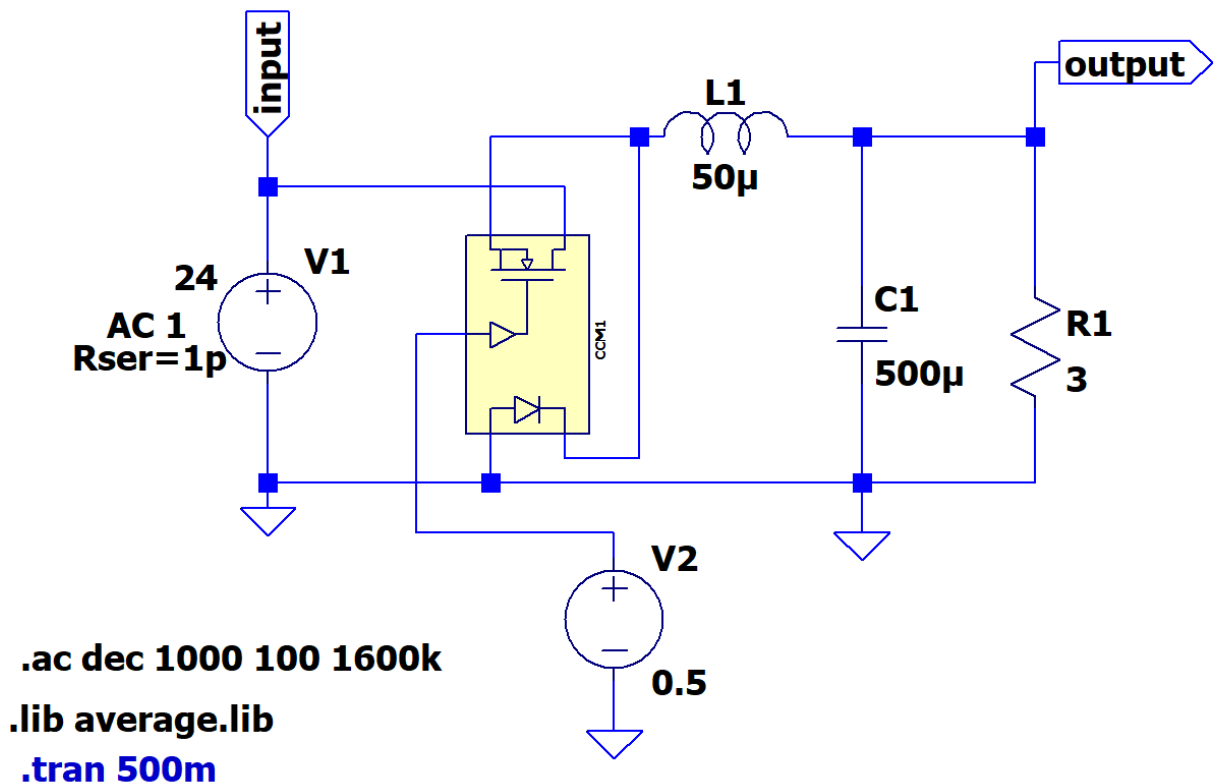


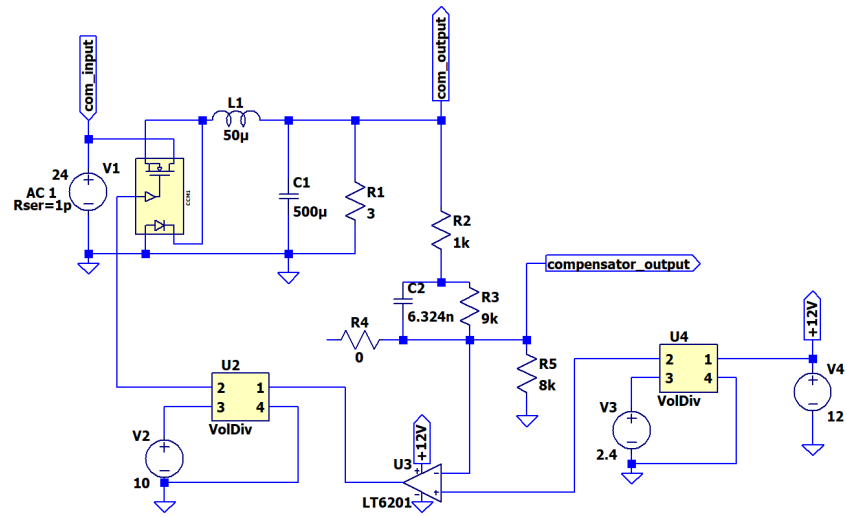
# Buck Converter Compensator Design

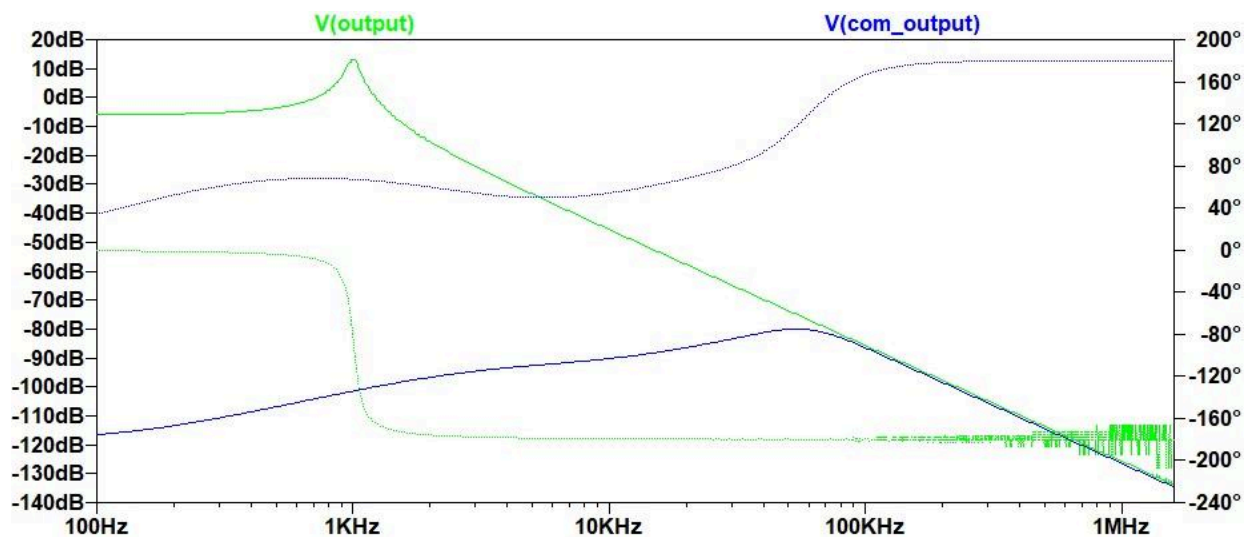
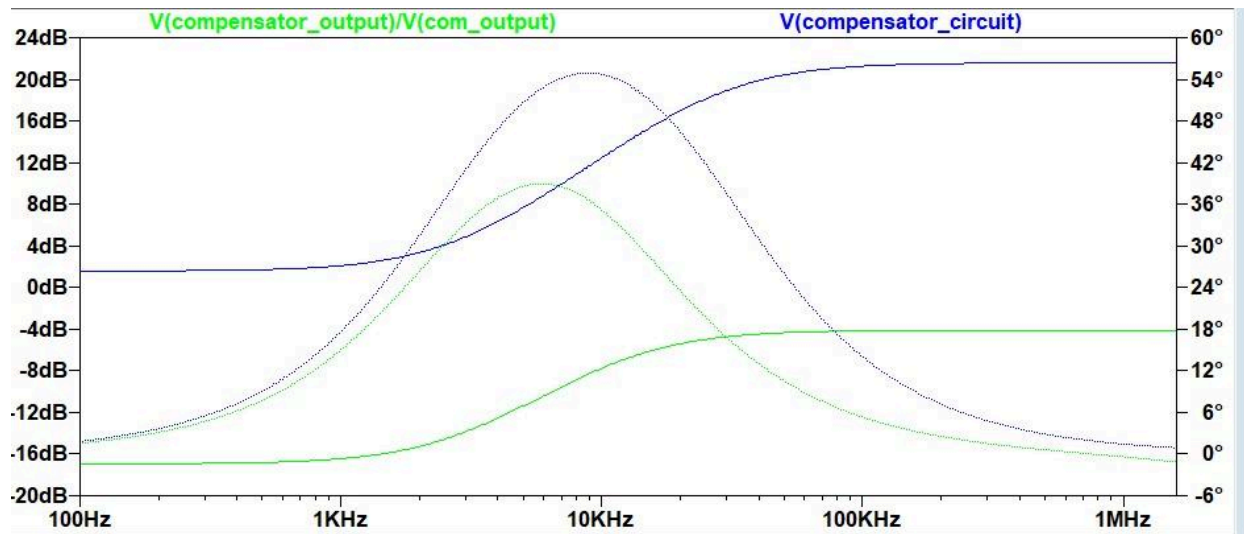
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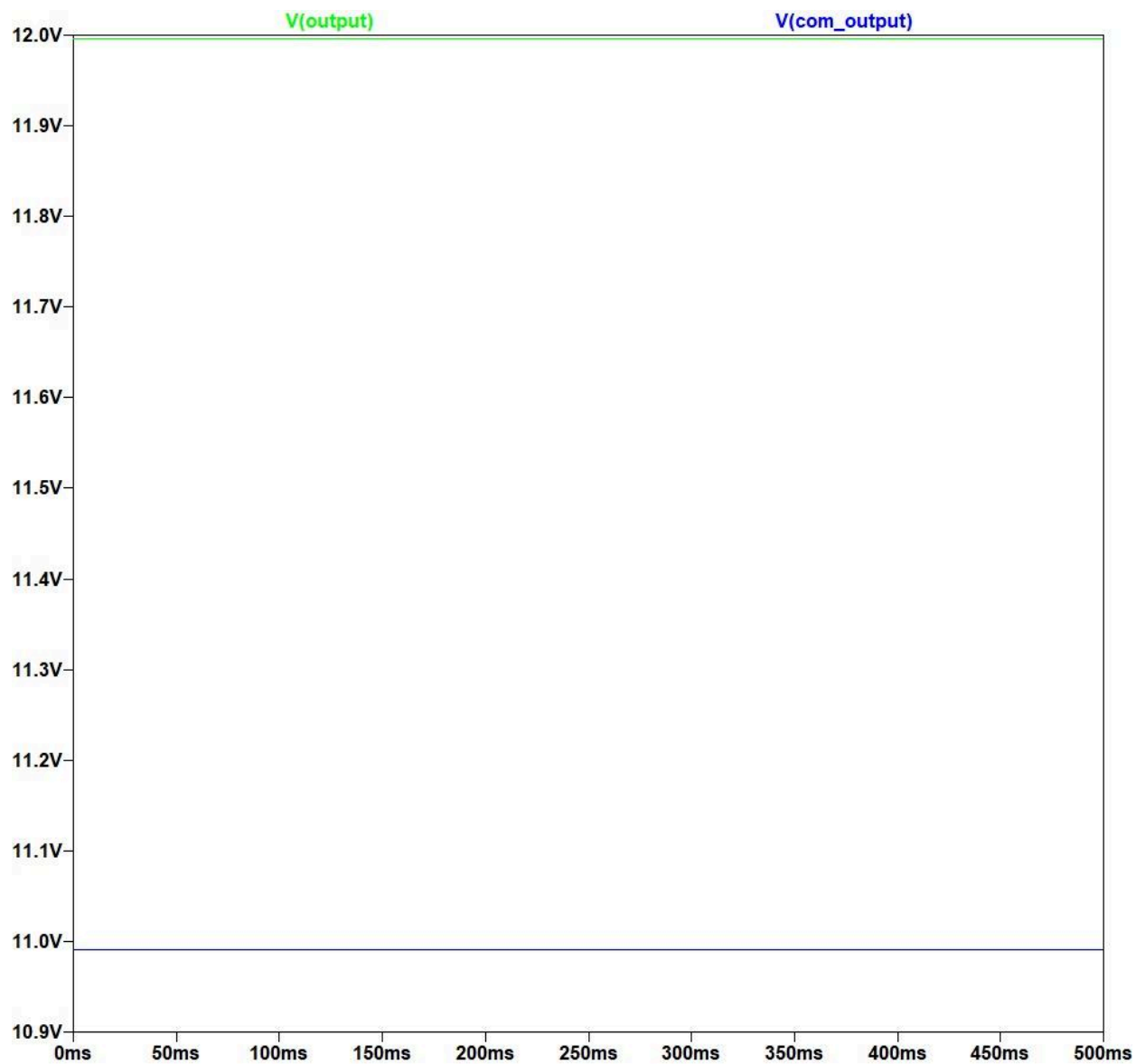
### Buck Converter Without Copensator



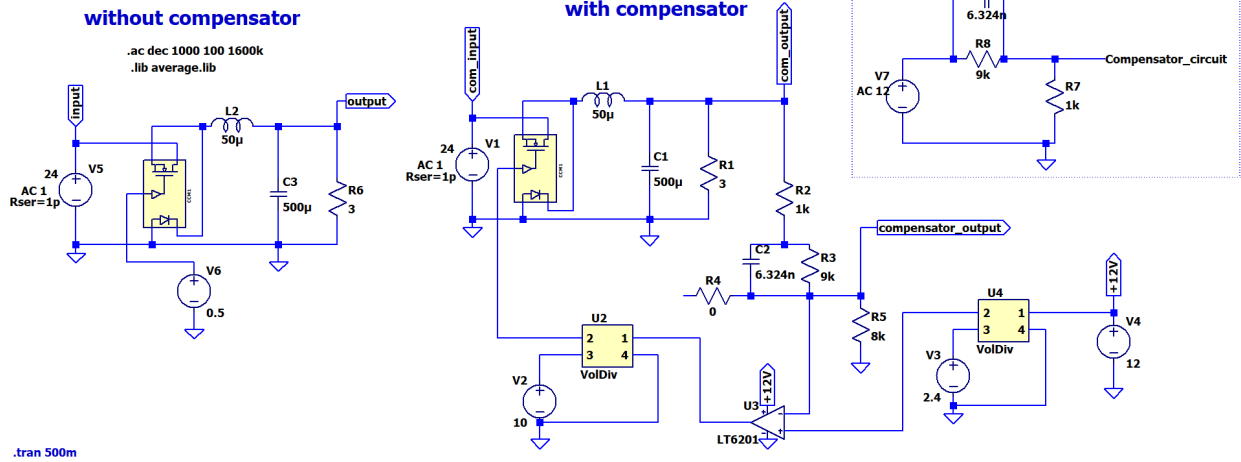
## Buck Converter with Lead compensator







# Buck Converter whole circuit



## Lead compensator / Components calculation

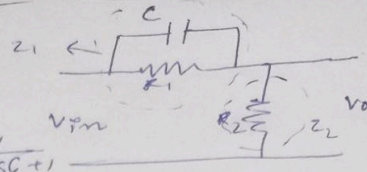
Roll. Back Converter

the converter freq. is 100 kHz

$$\frac{V_o}{V_{in}} = \frac{Z_2}{Z_1 + Z_2}$$

$$Z_2 = R_2$$

$$Z_1 = R_1 \parallel \frac{1}{sC} = \frac{R_1}{sR_1C + 1}$$



$$\frac{V_o}{V_{in}} = \frac{R_2}{R_2 + \frac{R_1}{sR_1C + 1}} = \frac{R_2(1 + sR_1C)}{R_1R_2sC + R_2 + R_1} = \frac{R_2}{R_1 + R_2} \left[ \frac{1 + \frac{s}{1/R_1C}}{1 + \frac{s}{\frac{R_1 + R_2}{R_2}} \left( \frac{1}{R_1C} \right)} \right]$$

putting it in lead compensator form

$$\frac{V_o}{V_{in}} = \alpha \left( \frac{1 + \frac{s}{1/T}}{1 + \frac{s}{\frac{1}{\alpha T}}} \right), \quad T = R_1C, \quad \alpha = \frac{R_2}{R_1 + R_2}$$

comparing with lead compensator - standard form

$$G(s) = G_c(s) \left( \frac{1 + \frac{s}{\omega_z}}{1 + \frac{s}{\omega_p}} \right) \quad \text{where} \quad G_c(s) = \alpha \rightarrow \text{DC gain}$$

$$\omega_z = \frac{1}{T}, \quad \omega_p = \frac{1}{\alpha T}$$

Let DC gain  $\alpha = 0.1$ ,  $\alpha = \frac{R_2}{R_1 + R_2} = \frac{1}{10} \Rightarrow R_1 = 9R_2$

Let  $R_2 = 1k, R_1 = 9k$

freq. at which phase margin is maximum

$$\omega_m = \sqrt{\omega_z \omega_p} = \frac{1}{T\sqrt{\alpha}} \quad \omega_m = 500 \text{ kHz} \Rightarrow 5 \times 10^5 = \frac{\sqrt{10}}{T}$$

$$\therefore T = 10\sqrt{\frac{2}{5}} \times 10^{-6}, \quad C = 6.324 \mu\text{F}$$

$$\omega_z = 158 \text{ kHz}, \quad \omega_p = 1.58 \text{ MHz}$$