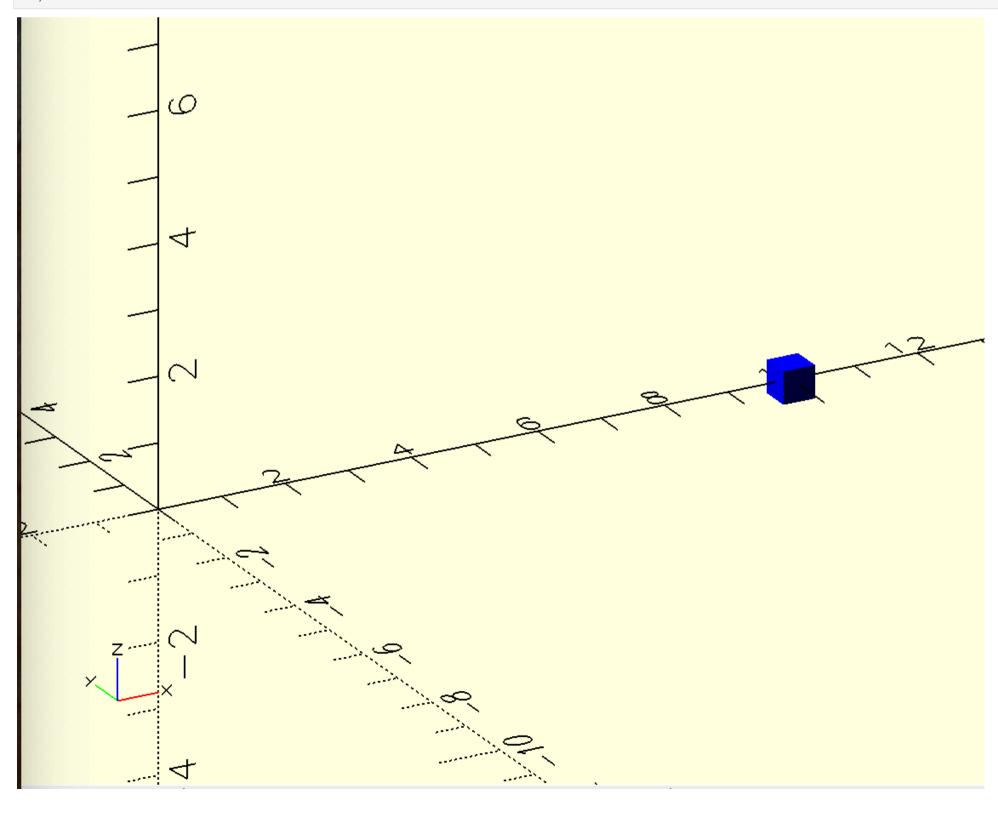
In []: %reload_ext autoreload
%autoreload 2
from openscad3 import *

Basic of Drawing and 3D modeling with library openscad3

Basic elements are:

- point: defined by 2d or 3d coordinates
- line: defined by 2 points (2d or 3d coordinates)
- polyline: defined by more than 2 points (2d or 3d coordinates)
- surface: defined by arrangement of 2 or more lines or polylines where there is no volume
- solid: defined by arrangement of 2 or more polylines with ends closed and has volume
- plane: defined by a normal vector
- extrude along path: defined by extruding a 2d section along a 3d path
- Sculpting along path: defined by sculpting a 2d section along a 2d path
- Rotate objects: Objects can be rotated along a defined axis
- translate objects: objects can be translated by a defined vector from their relative positions
- wrapping a polyline/ surface/ solids around a path
- Intersections: between line to line, polyline to polyline/ line (2d or 3d) or between surface to surface
- offset: offsetting a section outward or inward
- bspline curves: Can be open and closed loop
- bezier curves
- interpolation curves
- convex hull
- concave hul
- projection of a surface on to another surface
- projecting a line on a surface
- fillets in 2d
- fillets in 3d (few approaches)

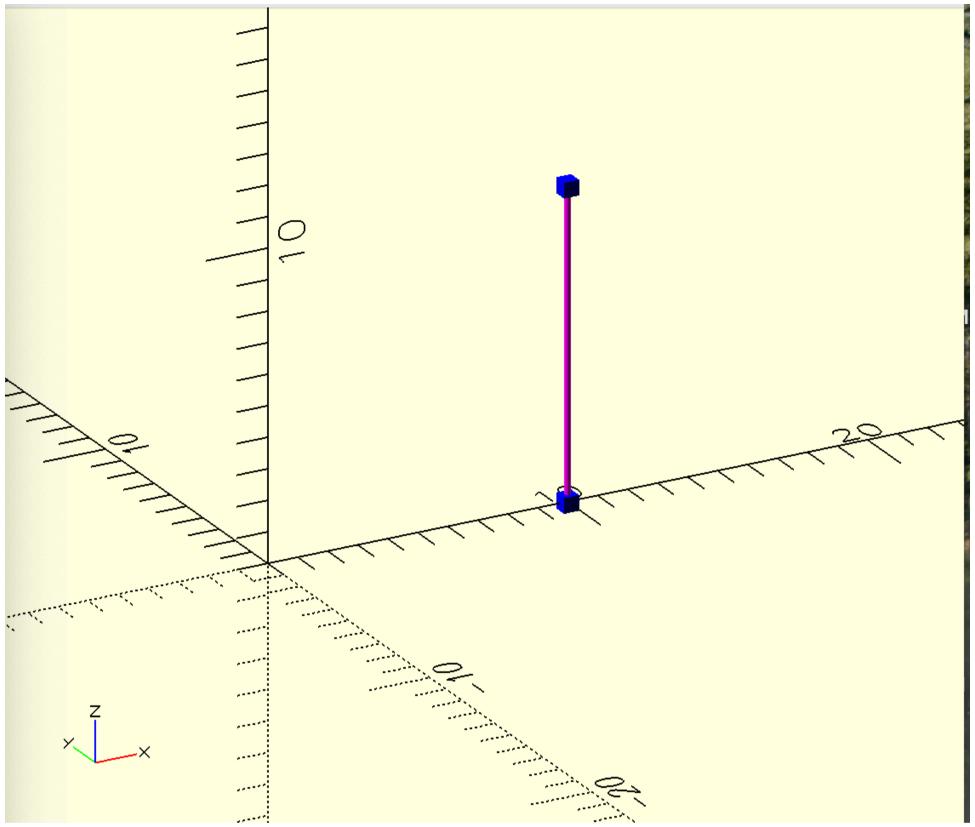
Points



```
In []: l1=[[10,0,0],[10,0,10]]
fo(f'''
color("blue") points({l1},.5);

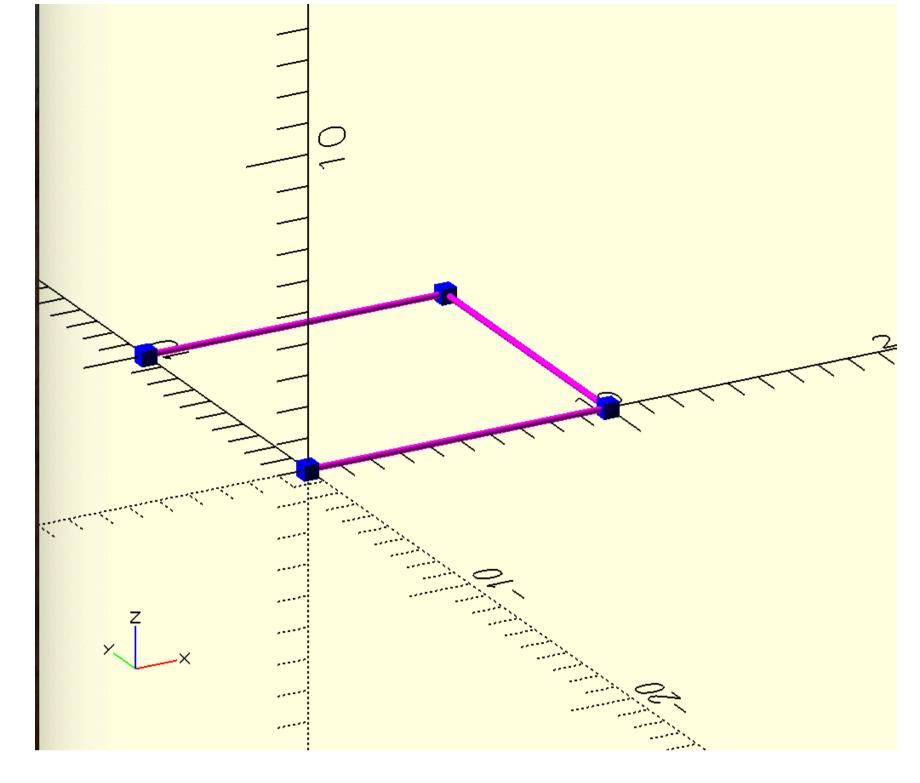
// p_line3d module is used for showing lines or polylines
// in this example line "l1" of diameter 0.2 mm is shown

color("magenta") p_line3d({l1},.2);
''')
```



Polylines

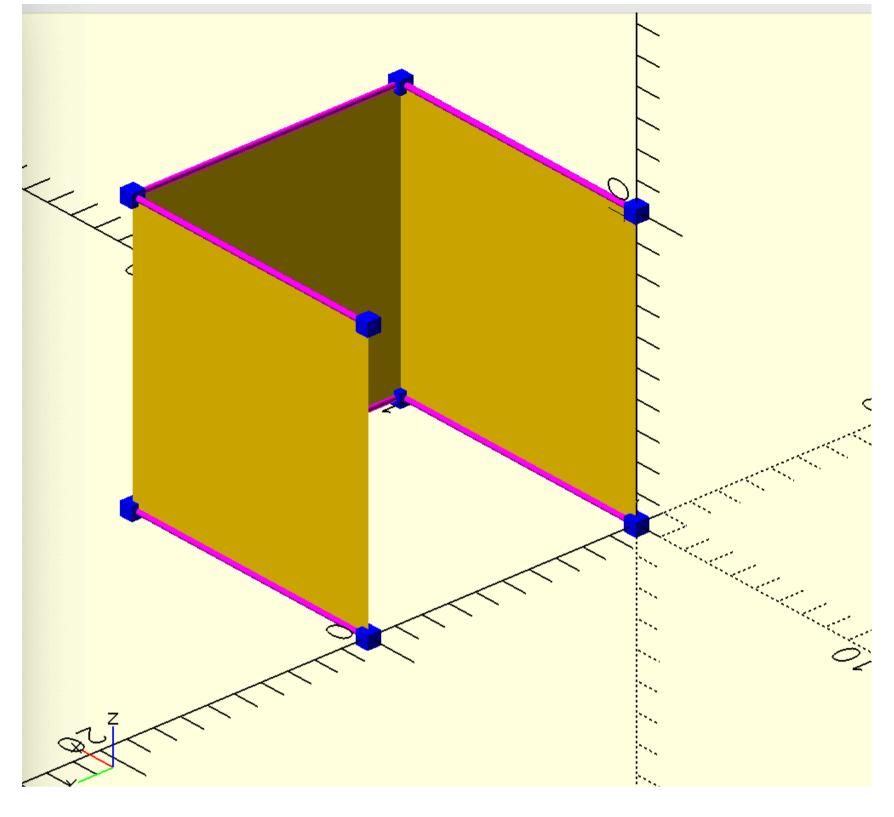
```
In []: l2=cr2dt([[0,0],[0,10],[-10,0]])
    fo(f'''
        color("blue") points({l2},.5);
        color("magenta") p_line3d({l2},.2);
```



Surface

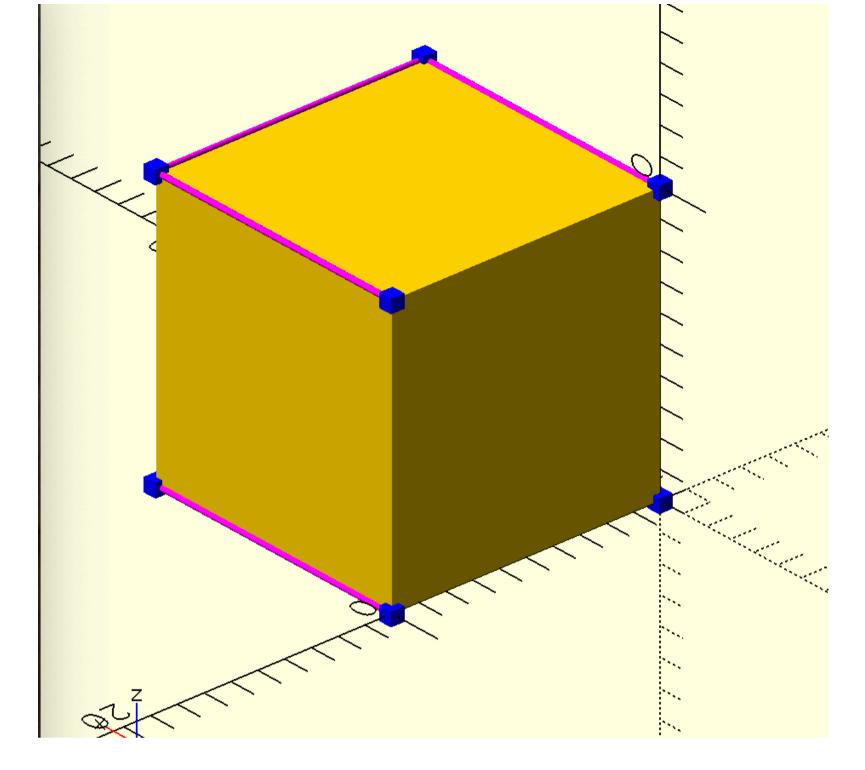
```
In []: l2=cr2dt([[0,0],[0,10],[-10,0]])
    s1=linear_extrude(l2,10)
    fo(f'''
    color("blue") for(p={s1}) points(p,.5);
    color("magenta")for(p={s1}) p_line3d(p,.2);

    // pay attention to the swp_surf module here
    // swp_surf shows the surface covered by the polylines and is very important
    // to understand as intersections are calculated based on intersecting surfaces
    {swp_surf(s1)}
    ''')
```



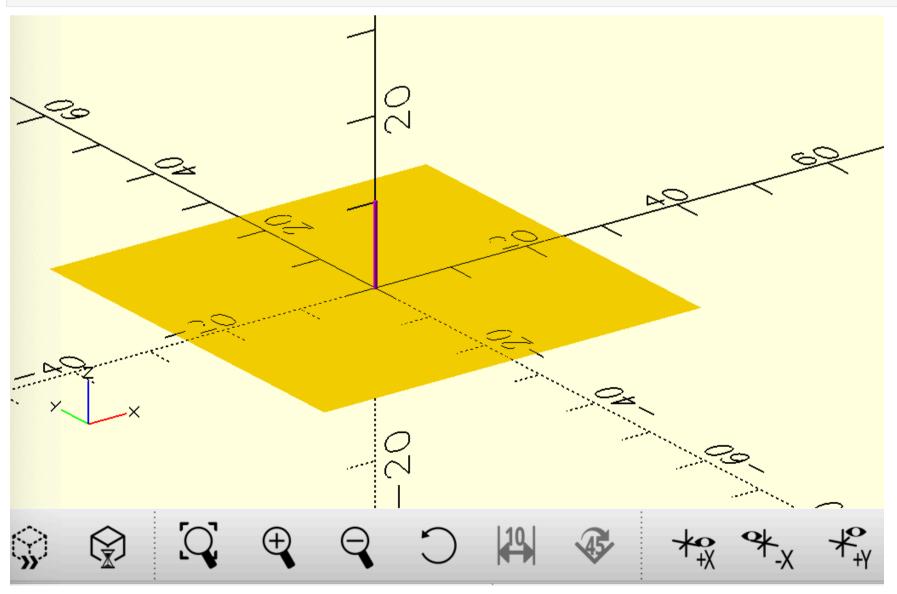
Solid

```
In []: l2=cr2dt([[0,0],[10,0],[-10,0]])
s1=linear_extrude(l2,10)
fo(f'''
color("blue") for(p={s1}) points(p,.5);
color("magenta")for(p={s1}) p_line3d(p,.2);
{swp(s1)}
```

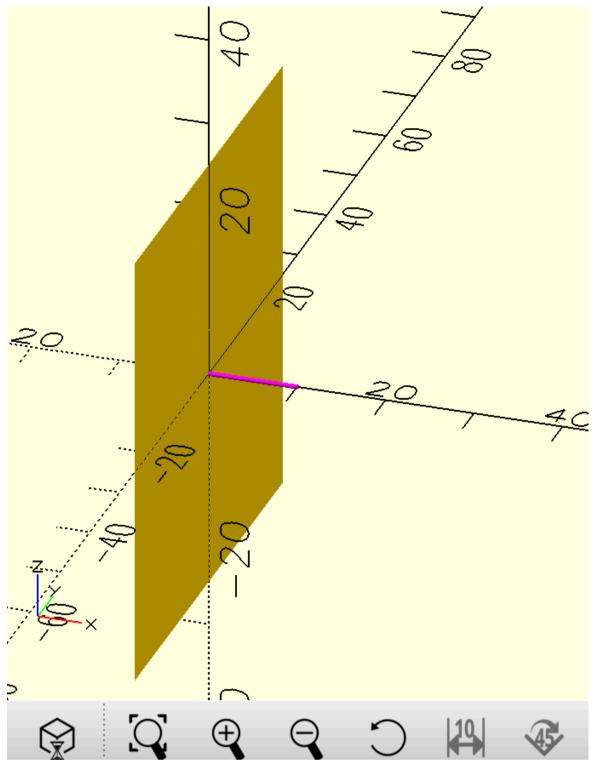


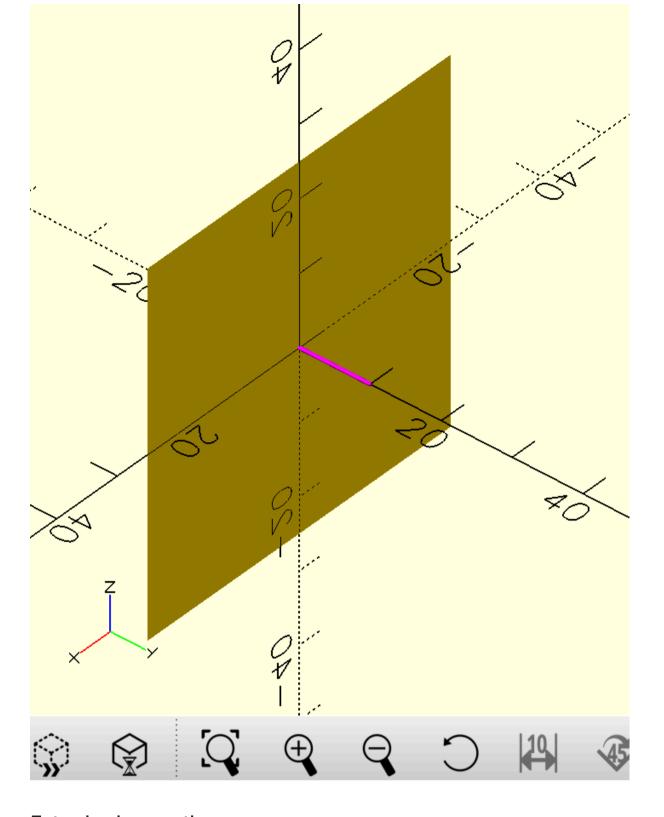
Planes

```
In []: n1=[0,0,1]
l1=[[0,0,0],[0,0,10]]
# x-y plane
pl1=plane(n1,size=[50,50], intercept=[0,0,0])
fo(f'''
color("magenta") p_line3d({l1},.5);
{swp_surf(pl1)}
'''')
```



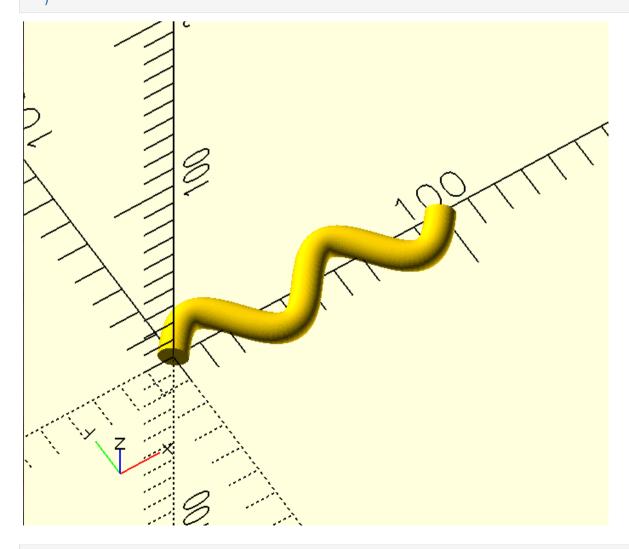
```
pl1=plane(n1,size=[50,50], intercept=[0,0,0])
fo(f'''
color("magenta") p_line3d({l1},.5);
{swp_surf(pl1)}
''')
```



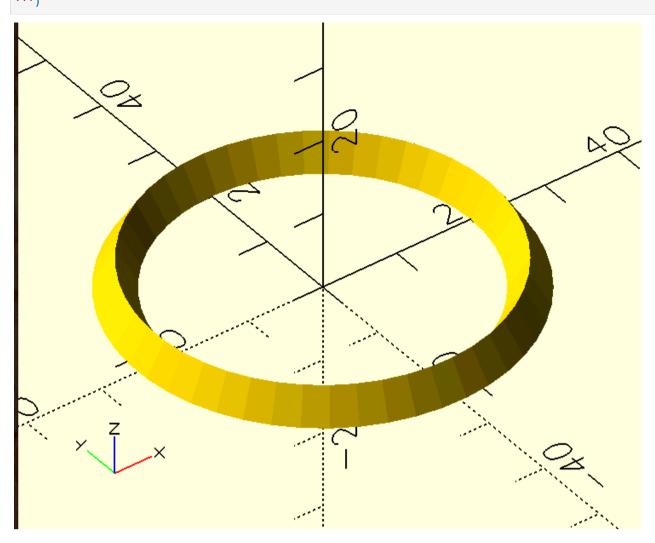


Extrude along path

```
In []: # circular section extruded along open path
    sec=circle(5)
    path=c23(sinewave(l=100,n=2,a=10,p=100))
    sol=path_extrude_open(sec,path)
    fo(f'''
    {swp(sol)}
    ''')
```

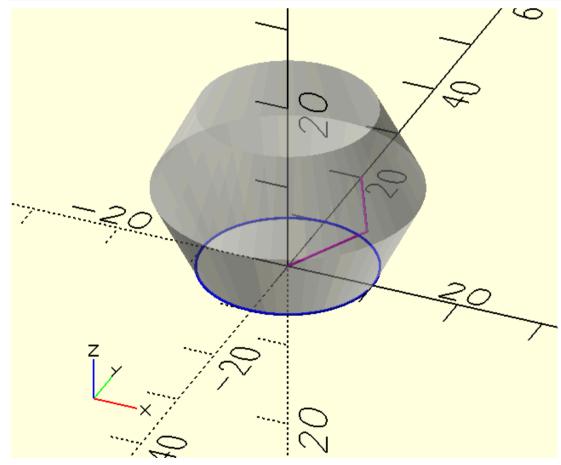


// swp_c is to be used where the loop is closing like the way here
{swp_c(sol)}
''')

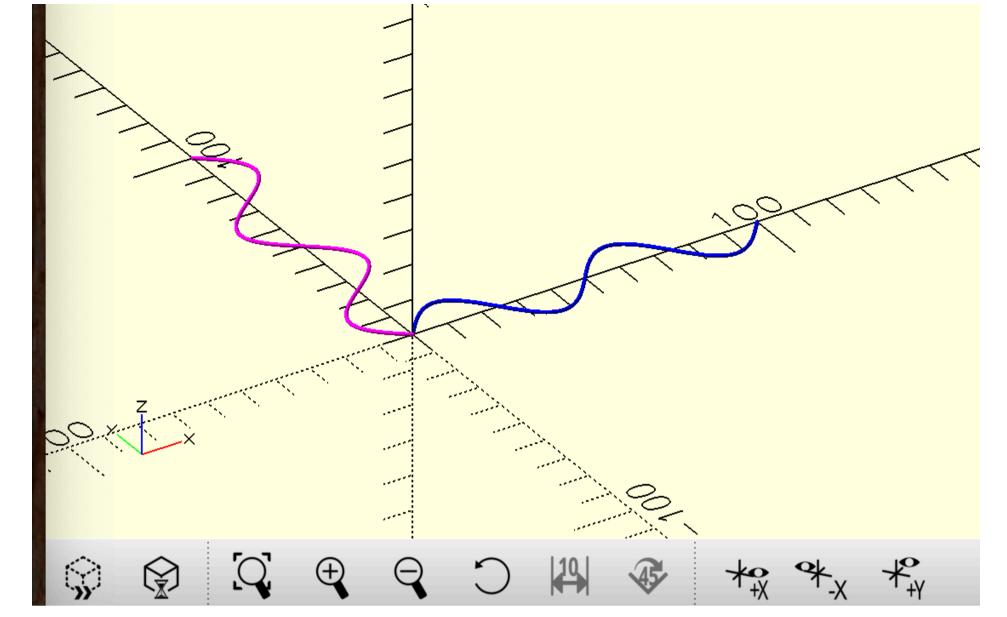


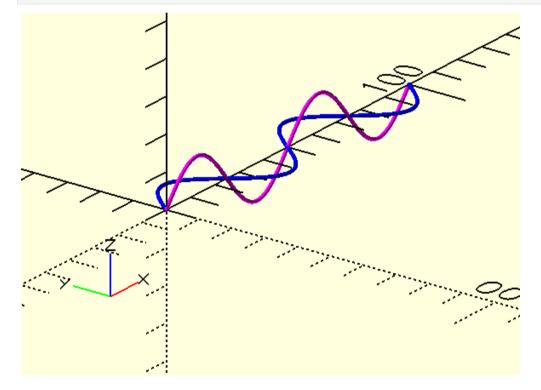
Sculpting along path

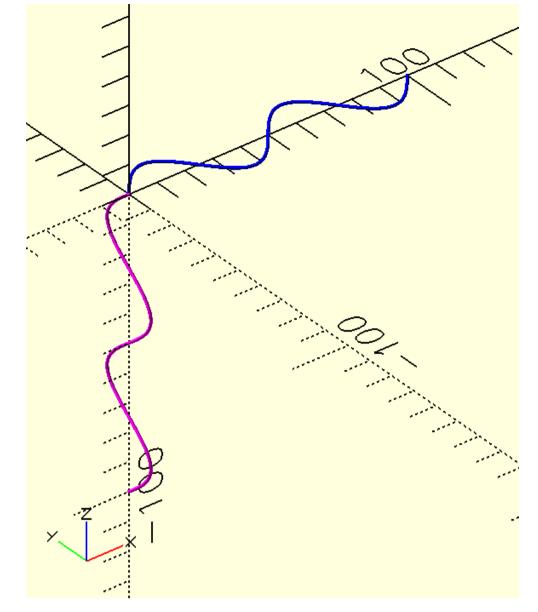
```
In []: sec=circle(10)
    path=[[0,0],[5,10],[0,20]] # x-coordinates work as offset and y-coordinates work as z-translate of sec
    sol=prism(sec,path)
    fo(f'''
        color("blue") p_line3d({sec},.3);
        color("magenta") p_line3d({path},.3);
    %{swp(sol)}
    '''')
```

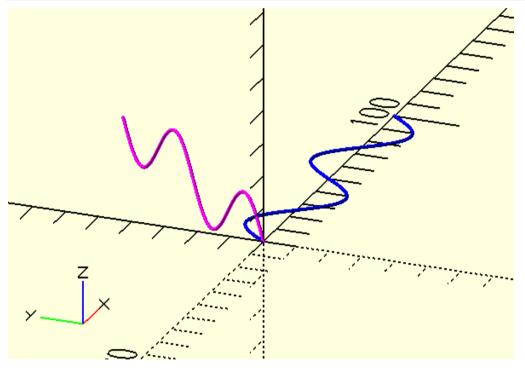


Rotation: Right hand thumb-rule (if thumb is pointed in the direction of axis, fingers curled in the direction of rotation)









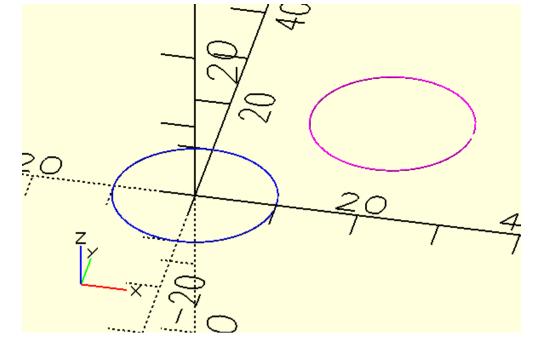
Translate: are of 2d and 3d type

```
In []: # example of translate in 2 d coordinates

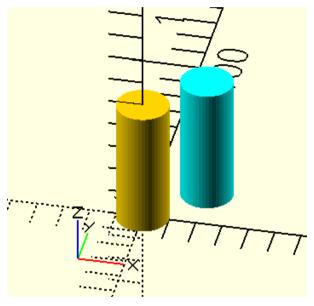
c1=circle(10)
c2=translate_2d([20,20],c1)
fo(f'''
    // original circle
color("blue") p_line3d({c1},.2);

// translated circle
color("magenta") p_line3d({c2},.2);

''')
```



```
In []: # example of translate in 3d coordinate
    c1=linear_extrude(circle(10),50)
    c2=translate([20,20,0],c1)
    fo(f'''
    // original cyclinder
    {swp(c1)}
    // translated cylinder by vector [20,20,0]
    color("cyan"){swp(c2)}
    '''')
```

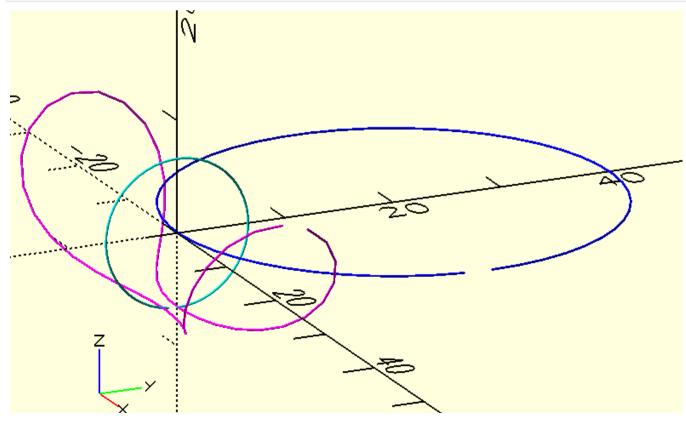


wrap around a section over a path

```
In []: c1=translate([0,20.1,0],circle(20))
    path=rot('y90',circle(40.2/(2*pi)+.2))
    c2=wrap_around(c1,path)

fo(f'''
    color("blue") p_line3d({c1},.2);
    color("cyan") p_line3d({path},.2);
    color("magenta") p_line3d({c2},.2);

'''')
```

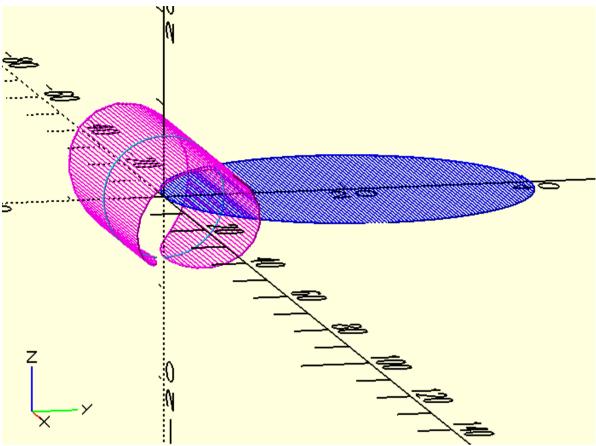


wrap around a surface over a path

```
In []: c1=translate_2d([0,20.1],circle(20))
    s1=h_lines_sec(c1,100)
    path=rot('y90',circle(40.2/(2*pi)+.2))
    c2=wrap_around(c1,path)
    s2=[wrap_around(p,path) for p in s1]
```

```
fo(f'''
color("blue") p_line3d({c1},.2);
color("cyan") p_line3d({path},.2);
color("magenta") p_line3d({c2},.2);

color("blue") for(p={s1}) p_line3d(p,.1,1);
color("magenta") for(p={s2}) p_line3d(p,.1,1);
''')
```

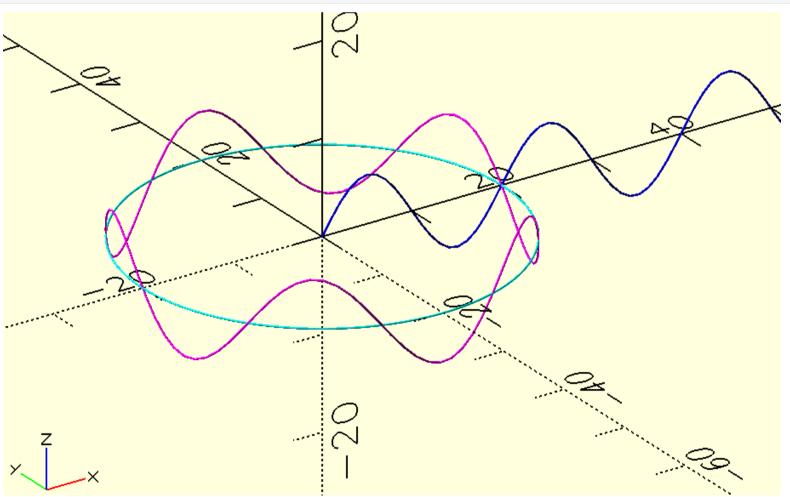


other methods of wrapping a polyline/ solid around a path

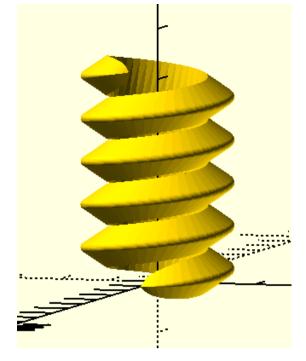
```
In []: c1=rot('x90', sinewave(100,5,5,100))
    path=c23(arc(20,0,360,s=99))
    c2=extrude_wave2path(c1,path)

fo(f'''
    color("blue") p_line3d({c1},.2);
    color("cyan") p_line3d({path},.2);
    color("magenta") p_line3dc({c2},.2);

''')
```

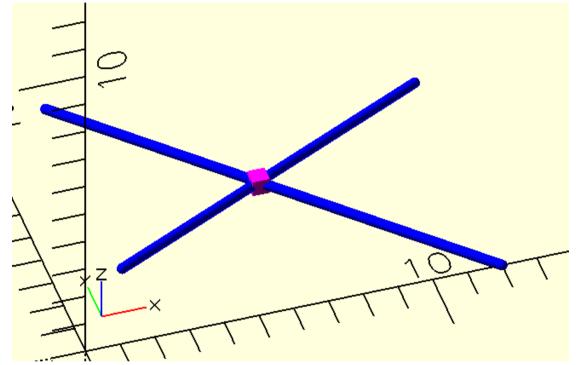


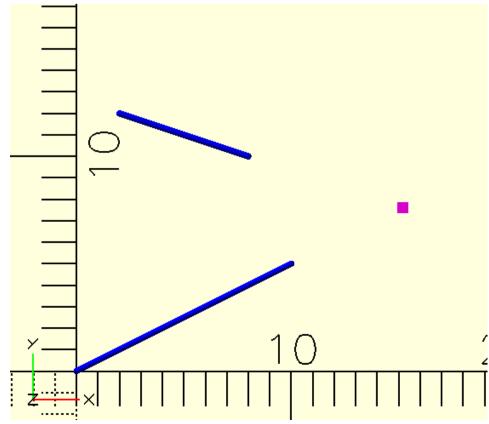
```
In []: c1=rot2d(-90,cr2dt([[-4,0],[8,0],[-4,6,1]],10))
    path=m_points1_o(cr2dt([[-2,0],[2,0.5,2],[0,50,2],[-2,0.5]],10),200,.01)
    sol=prism(c1,path)
    path1=helix(10,8.5,5,10)
    path1=path2path1(path,path1)
    # extruding sol to path1
    sol1=sol2path(sol,path1)
    fo(f'''
    {swp(sol1)}
    //color("blue") p_line3d({path},.5,1);
    ''')
```



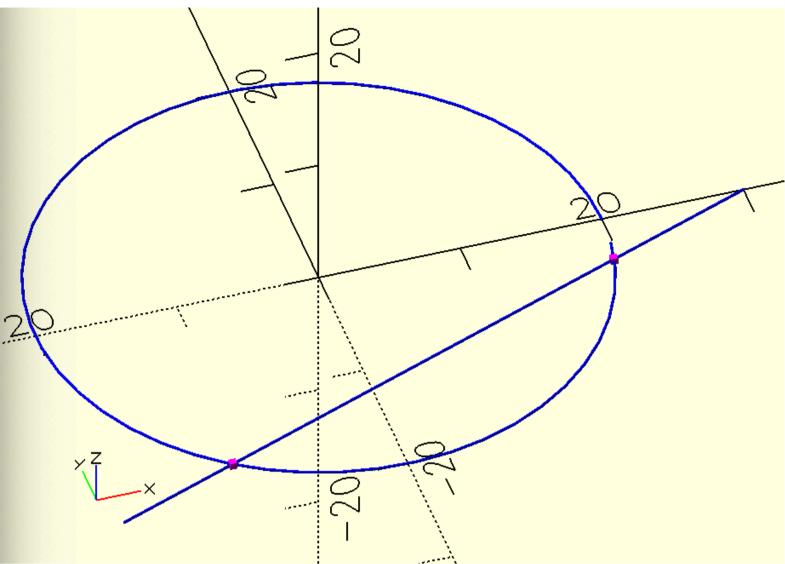
Intersections

intersection between line to line (2d)

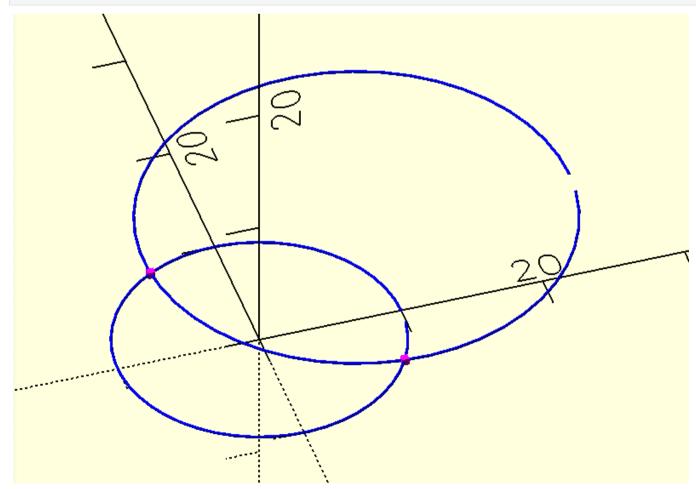




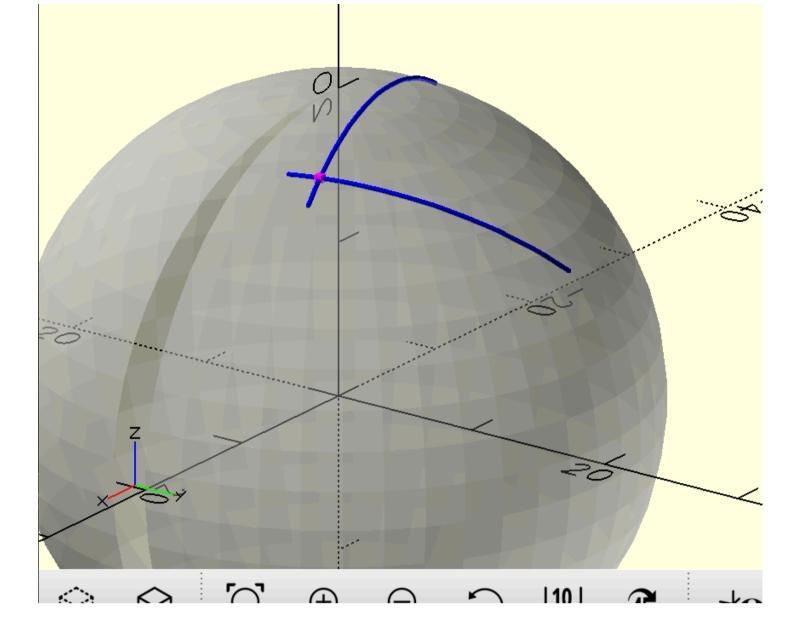
intersection between a polyline and line



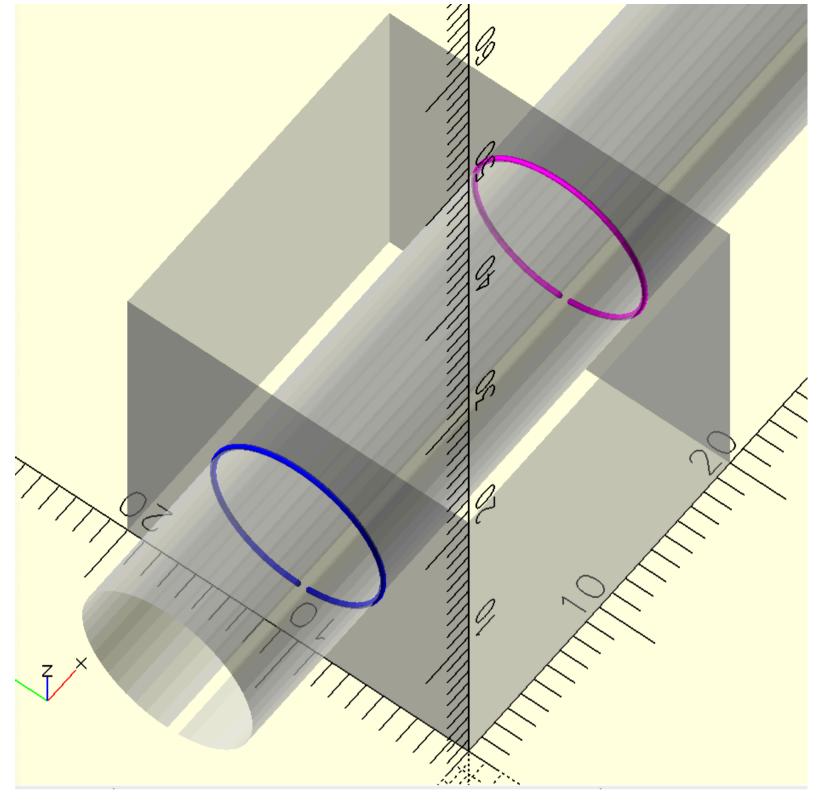
intersection between 2 polylines



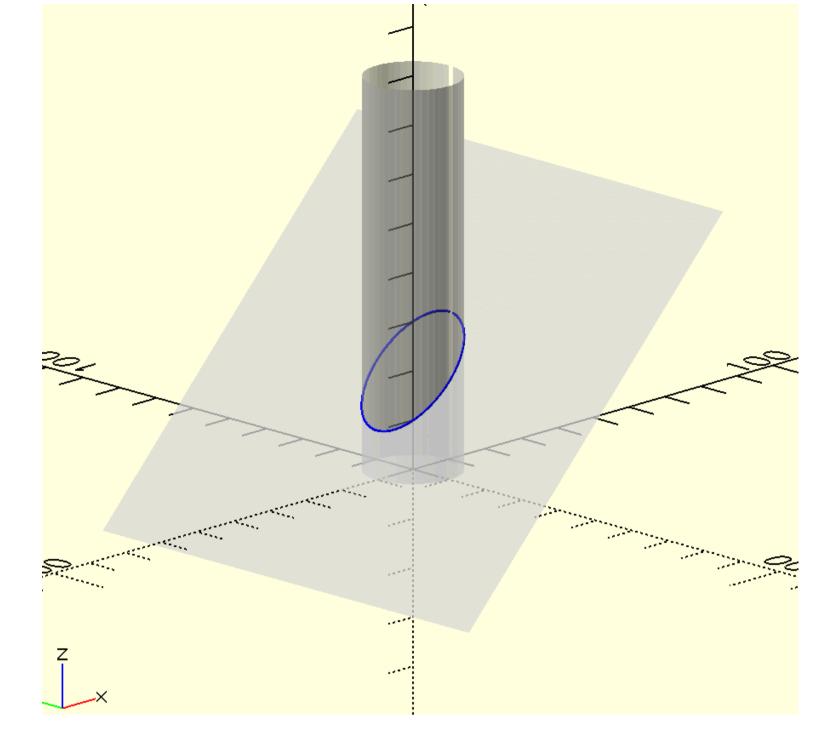
```
In []: # intersection between 2 polylines in 3d space
s1=sphere(20)
l1=c23(homogenise([[-10,0],[10,5]],1))
l1=plos(s1,l1,[0,0,1])
l2=c23(homogenise([[0,-15,0],[-7,5,0]],1))
l2=plos(s1,l2,[1,2,2])
p0=s_int1_3d(seg(l1)+seg(l2))[0]
fo(f'''
%{swp_surf(s1)}
color("blue") for(p={[l1,l2]}) p_line3d(p,.3);
color("magenta") points({[p0]},.5);
''')
```



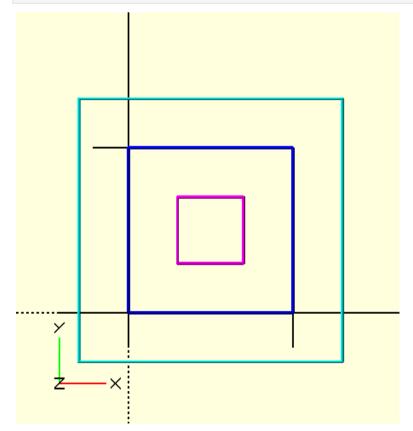
intersection between 2 surfaces



```
In []: pl1=plane([-1,0,1],[100,100],[0,0,20])
    c1=cylinder(r=10,h=80)
    p0=ip_sol2sol(pl1,c1)
    fo(f'''
    %{swp_c(pl1)}
    %{swp_surf(c1)}
    color("blue") p_line3d({p0},.5);
    ''')
```



offset

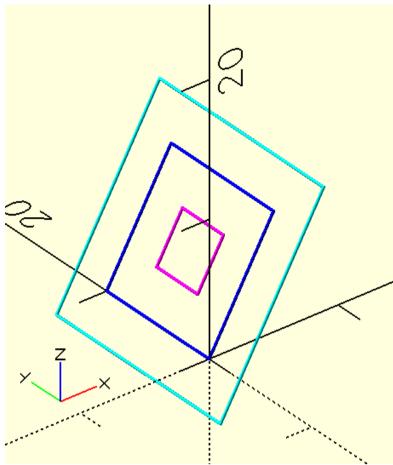


offset_3d

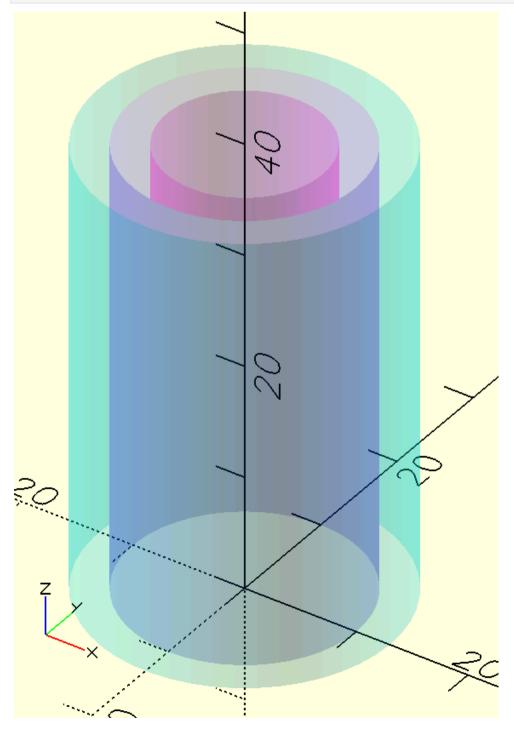
```
In []: sec=rot('y-60', square(10))
    sec1=offset_3d(sec,-3)
    sec2=offset_3d(sec,3)

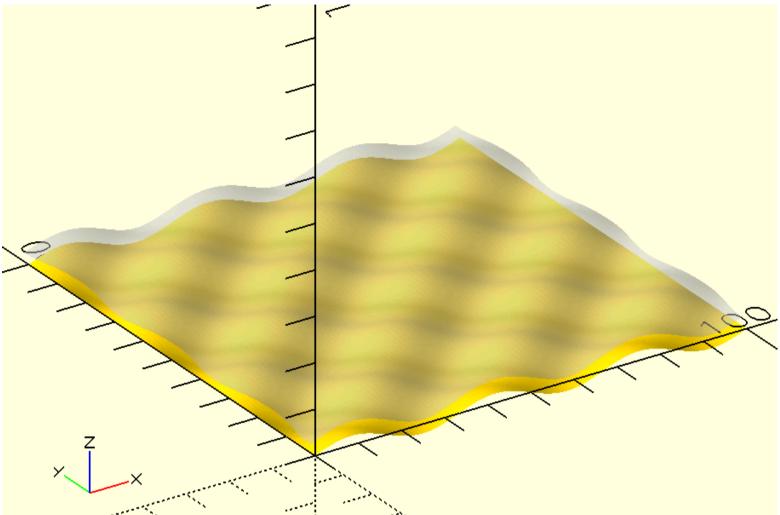
fo(f'''
    //original square
    color("blue") p_line3dc({sec},.2);
    // offset inwards by 3mm
```

```
color("magenta") p_line3dc({sec1},.2);
// offset outwards 3mm
color("cyan") p_line3dc({sec2},.2);
''')
```



offset solids



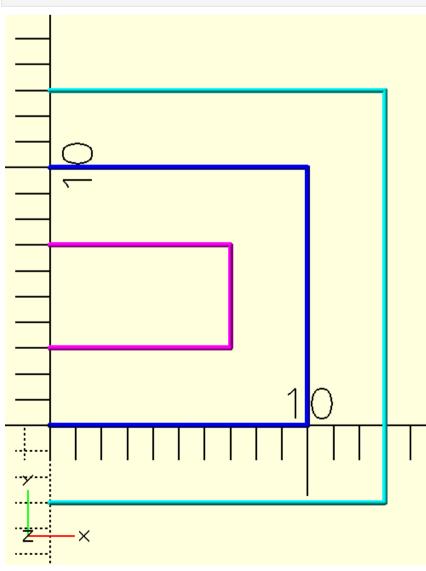


offset path or polylines

```
In []: s1=square(10)
    s2=path_offset(s1,-3)
    s3=path_offset(s1,3)

fo(f'''
    //original polyline
    color("blue") p_line3d({s1},.2);
    // offset inwards by 3mm
    color("magenta") p_line3d({s2},.2);
    // offset outwards 3mm
    color("cyan") p_line3d({s3},.2);

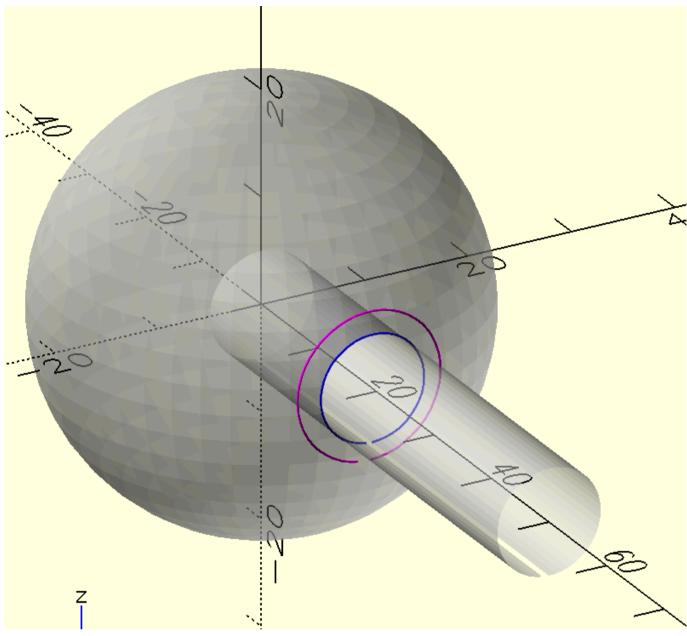
''')
```



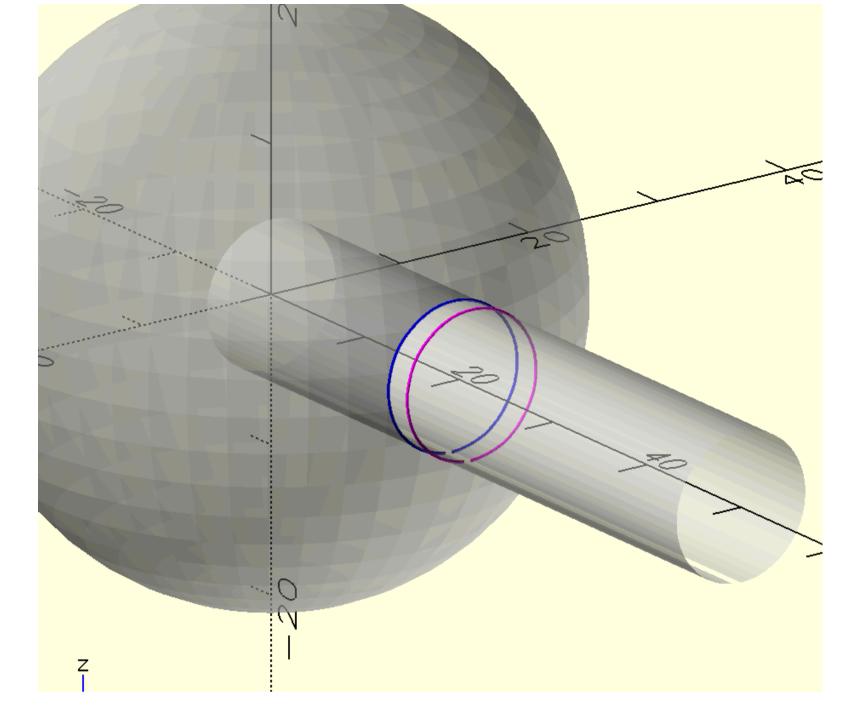
```
In []: s1=sphere(20)
    s2=rot('y90',cylinder(r=5,h=50))
    l1=ip_sol2sol(s1,s2)
    l2=o_3d(l1,s1,-2)

    fo(f'''
    %{swp_c(s1)}
    %{swp_surf(s2)}
    // original intersection line
    color("blue") p_line3d({l1},.2);

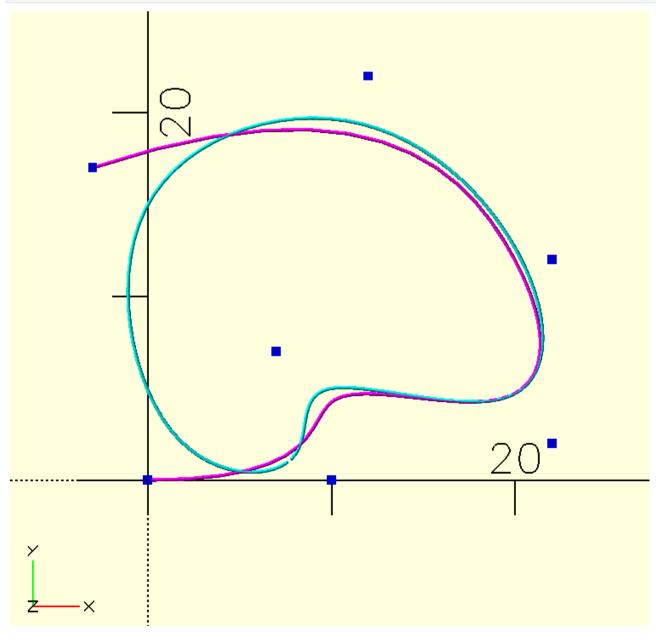
    // offset line on sphere
    color("magenta") p_line3d({l2},.2);
    ''')
```



move the intersection line on the intersecting surface



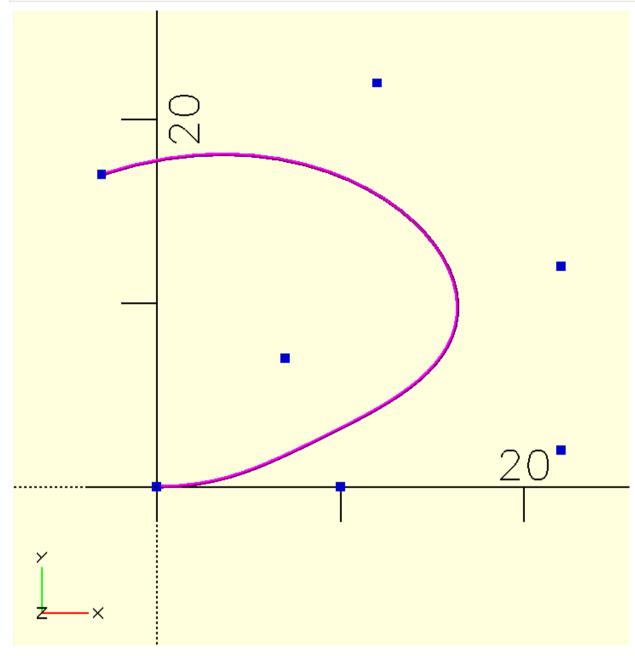
bspline curves



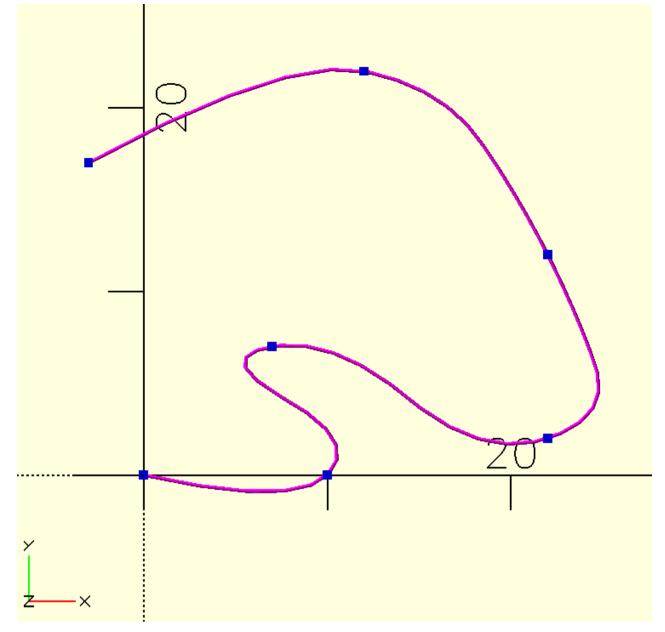
```
In []: l1=cr2dt([[0,0],[10,0],[-3,7],[15,-5],[0,10],[-10,10],[-15,-5]])
l2=bezier(l1,50)

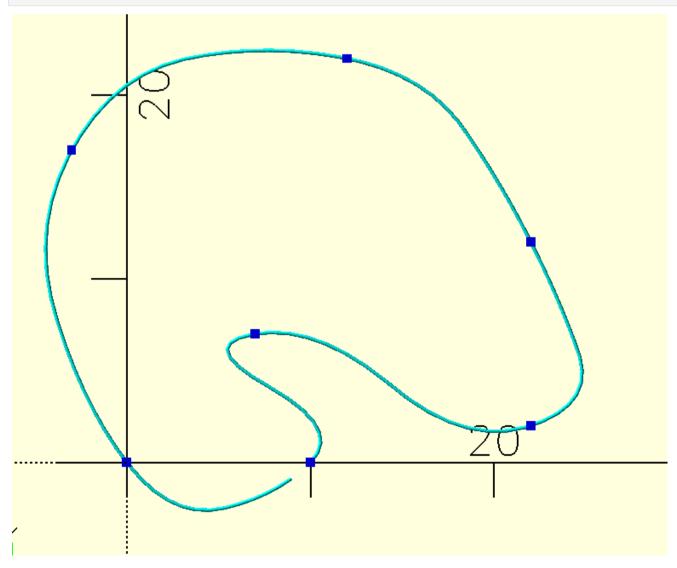
fo(f'''
    color("blue") points({l1},.5);
    color("magenta") p_line3d({l2},.2);

''')
```



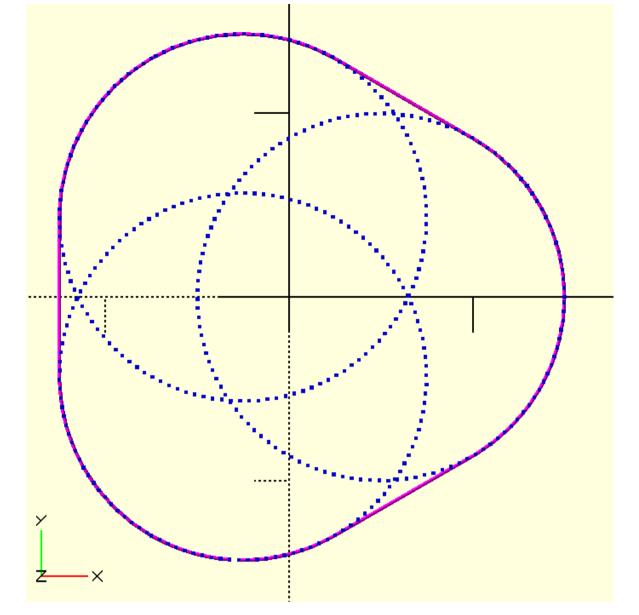
interpolation curves



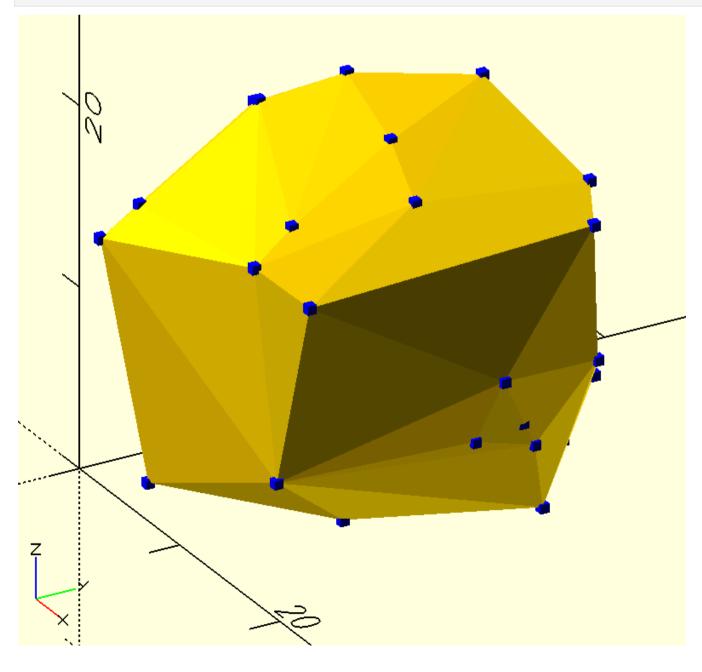


Convex hull

```
In []: c1=circle(10,[5,0])
    cx=[ rot2d(i,c1) for i in [0,120,240]]
    cx=homogenise(cx,.5,1)
    cy=convex_hull(cx)
    fo(f'''
    color("blue") points({cx},.2);
    color("magenta") p_line3d({cy},.2);
    ''')
```



```
In []: # convexhull in 3d
    a=random.random(100)*(20-0)+0
    b=random.random(100)*(20-0)+0
    c=random.random(100)*(20-0)+0
    p0=l_(a_([a,b,c]).transpose(1,0))
    sol=l_(a_(p0)[ConvexHull(p0).simplices])
    fo(f'''
    color("blue") points({p0},.5);
{swp_triangles(sol)}
'''')
```



concave hull

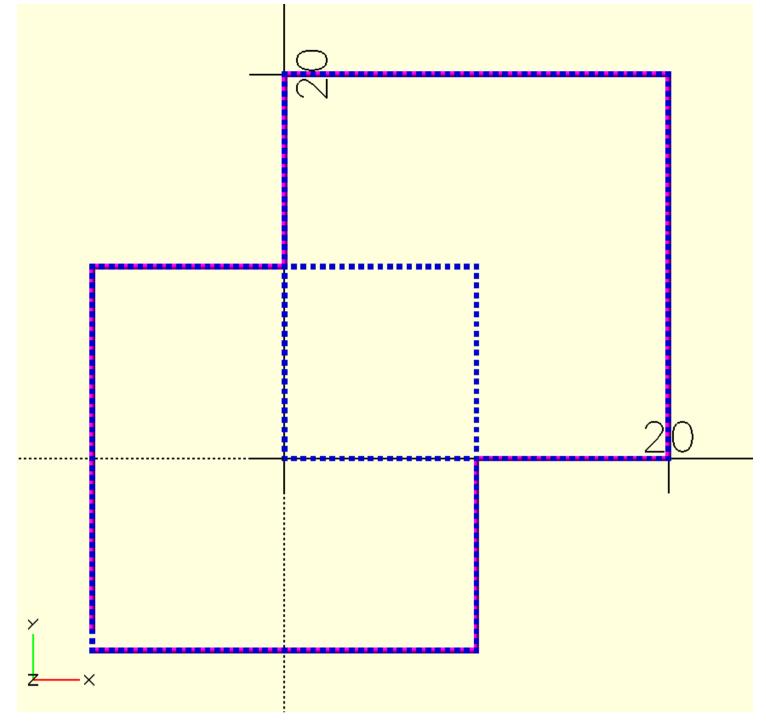
```
In []: # Draw a circle with radius 10 and centered at [5,0]
    c1=circle(10,[5,0])

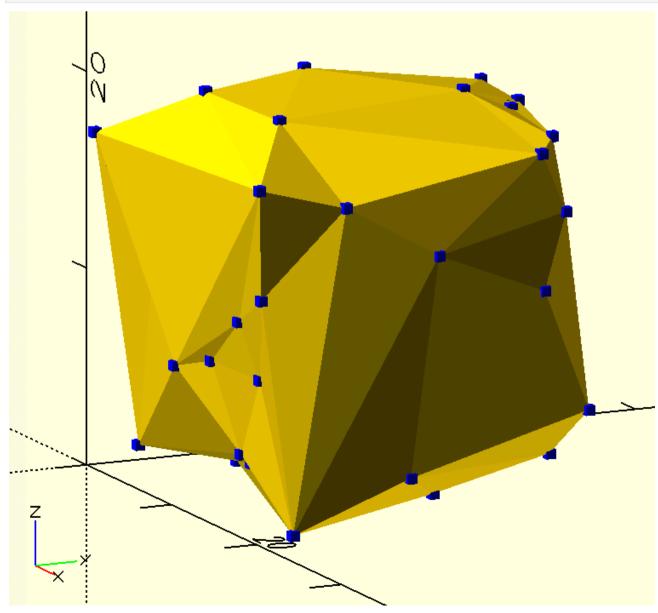
# Create 3 copies of the circle 'c1' rotated at 0, 120 and 240 deg from origin
    cx=[ rot2d(i,c1) for i in [0,120,240]]
```

```
# homogenise the 3 copies of circles created above, so that distance between
# each subsequent point of circle is 0.5 mm apart and these 3 circles are all
# closed loop sections individually as well
cx=homogenise(cx,pitch=.5,closed_loop=1)

# calculate the concave hull for these points
cy=concave_hull(cx)

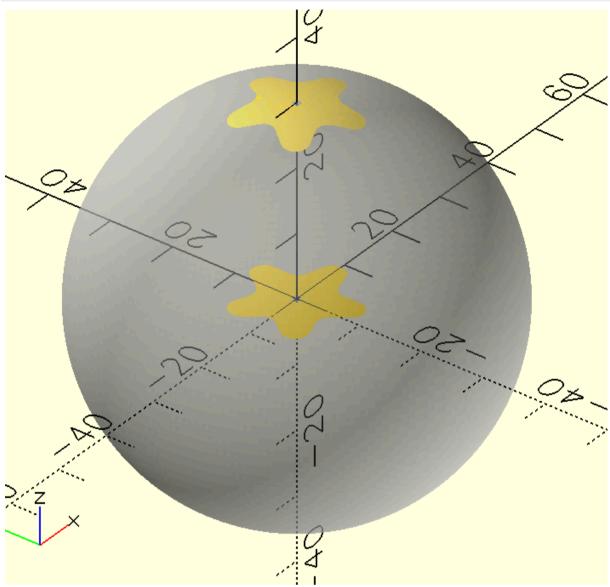
fo(f'''
color("blue") points({cx},.2);
color("magenta") p_line3d({cy},.2);
//polygon({cy});
''')
```



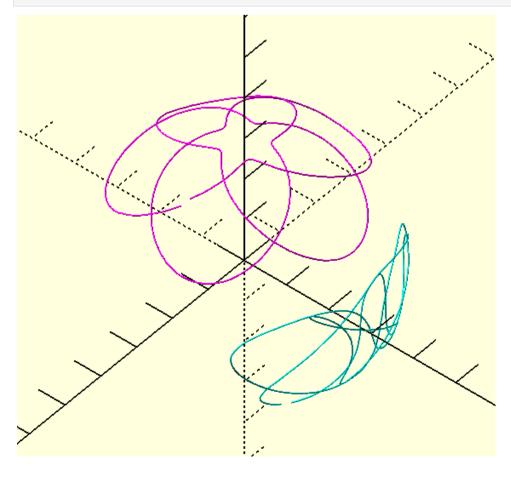


projection of surface on to another surface

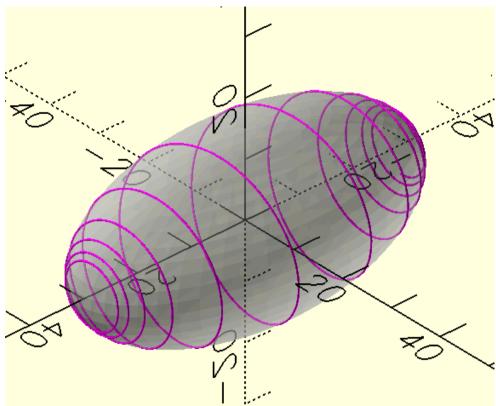
```
In []: s1=sphere(30,s=200)
    c1=circle(15,s=6)
    c2=rot2d(360/5/2,circle(5,s=6))
    s2=a_(c23(concatenate(cpo([c1,c2]))))+[0,0,2]
    s2=cr2d(s2,10)
    s3=c23([s2,offset(s2,-2.5),offset(s2,-4),offset(s2,-5)])
    s3=bspline_surface(s3,3,3,100,10,[1,0])
    s4=psos(c_(s1),s3,[0,0,1])
    fo(f'''
    //color("blue") for(p={s4})p_line3dc(p,.03);
    %{swp(s1)}
    {swp_c(s3)}
    {swp_c(s4)}
    ''')
```

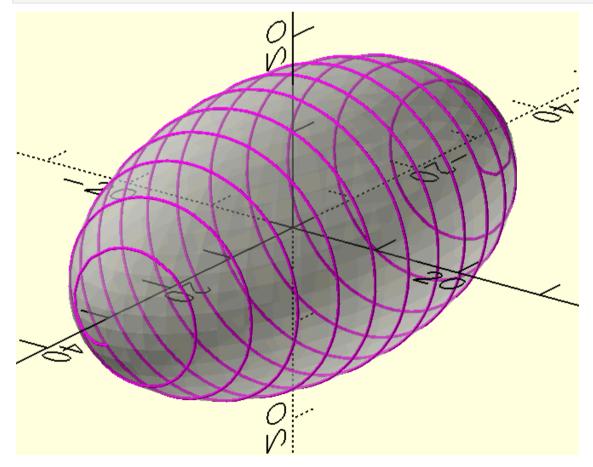


projecting a line on a surface

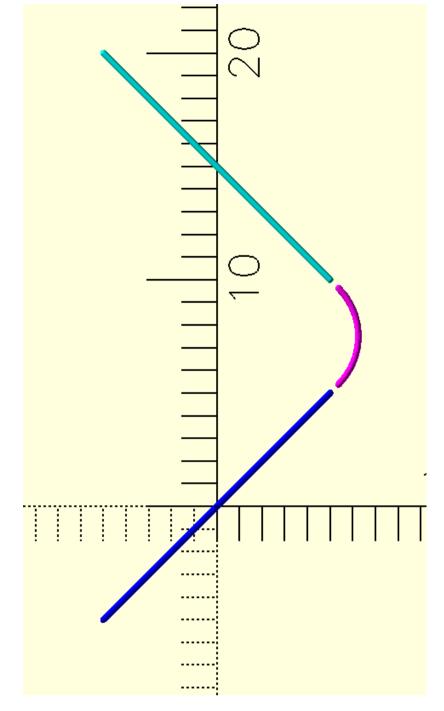


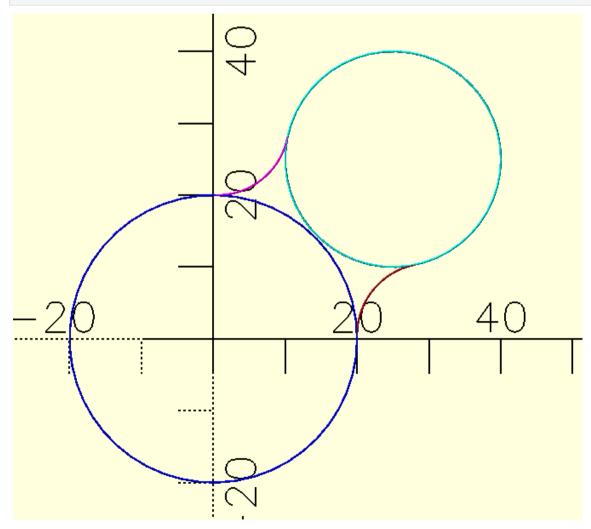
```
In []: l1=translate([-5*12/2,0,0],rot('y90',helix(5,5,12,5)))
    s1=rsz3dc(sphere(30),[61,30,30])
    l2=plos_v(c_(s1),l1,[0,0,0])
    fo(f'''
    //color("blue") p_line3d({l1},.3);
    color("magenta") p_line3d({l2},.3);
%{swp(s1)}
'''')
```



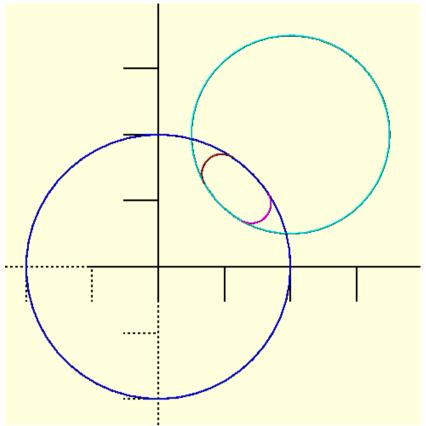


Fillets in 2d

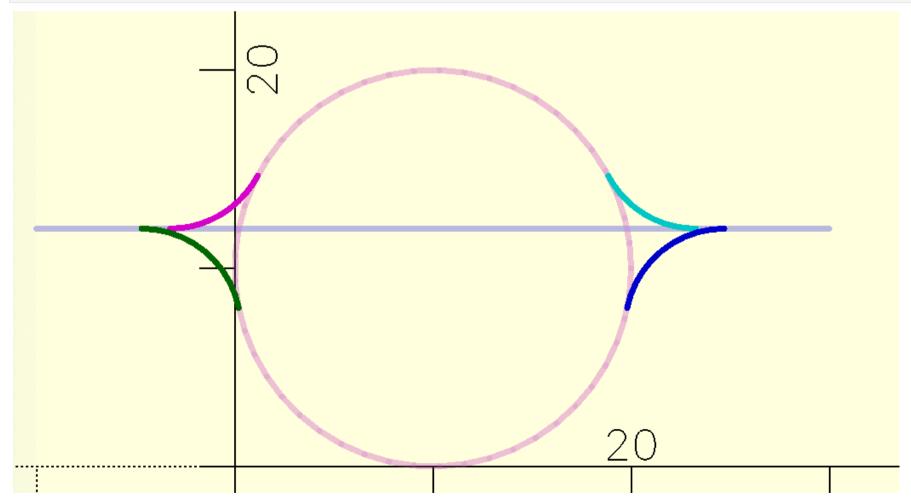




```
In []: # fillet between 2 arcs
    c1=circle(20)
    c2=circle(15,[20,20])
    f1=two_cir_tarc_internal(c2,c1,r=3)
    f2=two_cir_tarc_internal(c1,c2,r=3)
    fo(f'''
        color("blue") p_line3dc({c1},.3);
        color("cyan") p_line3dc({c2},.3);
        color("magenta") p_line3d({f1},.3);
        color("brown") p_line3d({f2},.3);
        ''')
```

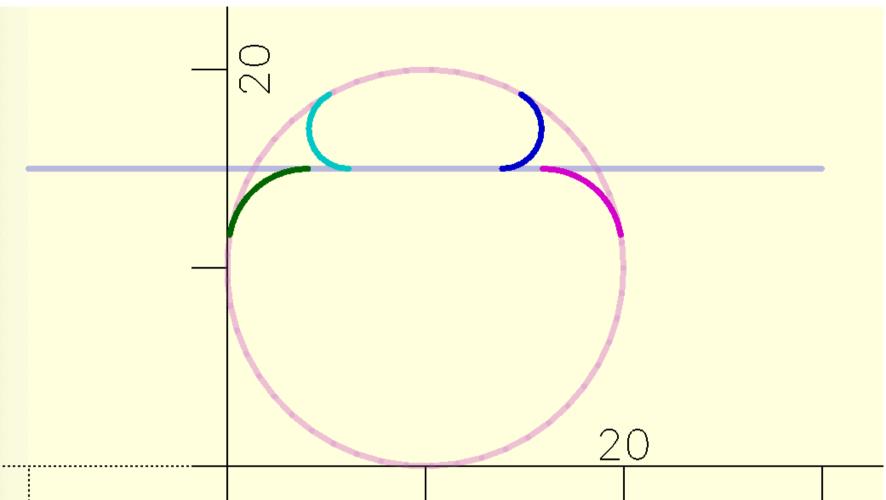


```
In [ ]: # fillet between line and circle (outside)
         h=12
         line=[[-10,h],[30,h]]
         cir1=circle(10,[10,10])
         r2=5
         s=20
         fillet1=fillet_line_circle(line,cir1,r2,1)
         fillet2=fillet_line_circle(line,cir1,r2,2)
         fillet3=fillet_line_circle(line,cir1,r2,3)
         fillet4=fillet_line_circle(line,cir1,r2,4)
         fo(f'''
         color("blue",.1)p_line({line},.3);
        color("violet",.2)p_line({cir1},.3);
color("cyan")p_lineo({fillet1},.3);
         color("blue")p_lineo({fillet2},.3);
         color("magenta")p_lineo({fillet3},.3);
         color("green")p_lineo({fillet4},.3);
```



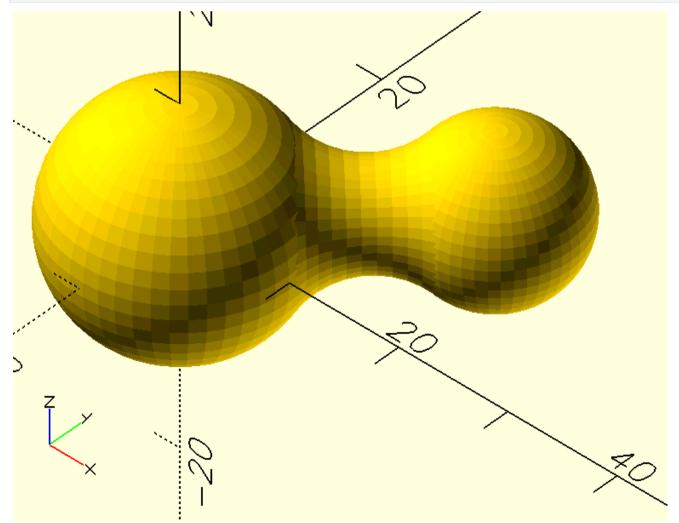
```
In []: # fillet between line and circle (inside)
h=15
line=[[-10,h],[30,h]]
cir1=circle(10,[10,10])
s=20
fillet5=fillet_line_circle_internal(line,cir1,2,1)
fillet6=fillet_line_circle_internal(line,cir1,4,2)
fillet7=fillet_line_circle_internal(line,cir1,2,3)
fillet8=fillet_line_circle_internal(line,cir1,4,4)
fo(f'''
color("blue",.1)p_line({line},.3);
color("violet",.2)p_line({cir1},.3);
```

```
color("blue")p_lineo({fillet5},.3);
color("magenta")p_lineo({fillet6},.3);
color("cyan")p_lineo({fillet7},.3);
color("green")p_lineo({fillet8},.3);
''')
```

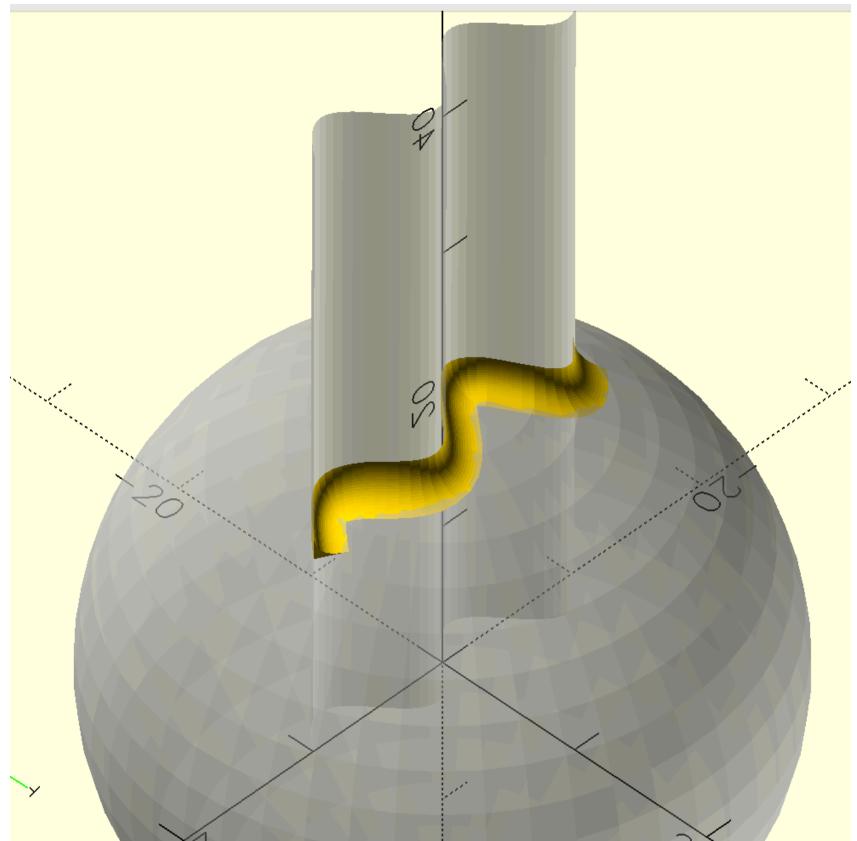


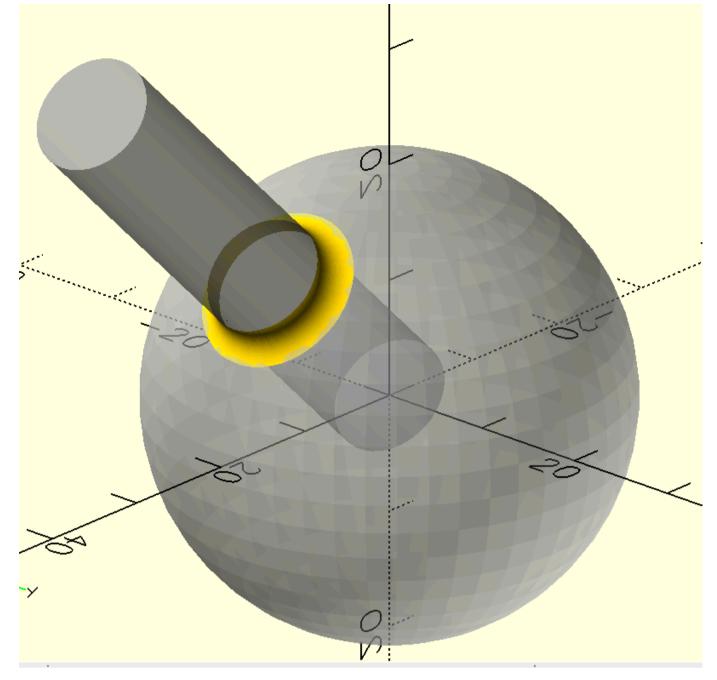
Fillets in 3d

```
In []: # fillet between 2 spheres
    s1=sphere(10)
    s2=sphere(7,[15,15,0])
    f1=fillet_2spheres(s1,s2,7,s1=10,s2=40)
    fo(f'''
    {swp(s1)}
    {swp(s2)}
    {swp(f1)}
    '''')
```

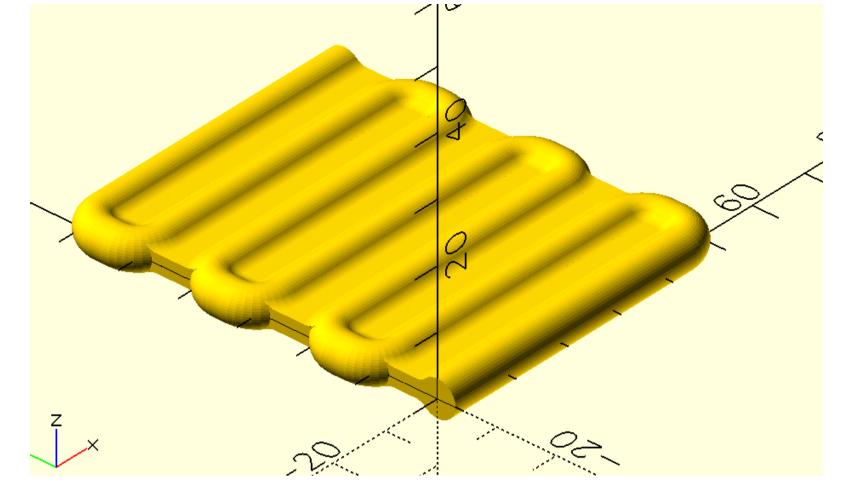


```
In []: # fillet at the intersection of a solid and a surface
    s1=sphere(20)
    l1=translate([-10,0,0],sinewave(20,2,2,50))
    s2=surface_line_vector(l1,[5,5,50])
    f1=ip_fillet(s1,s2,2,2)
    fo(f'''
    %{swp(s1)}
    %{swp_surf(s2)}
    {swp(f1)}
    ''')
```

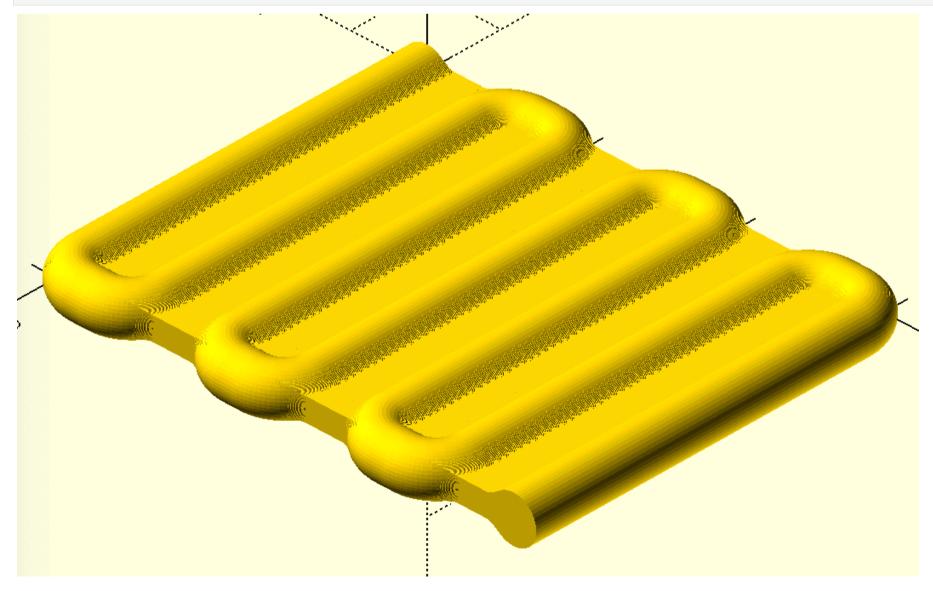




```
In [ ]: # Complex fillets
          s1=square([50,60])
           c1=circle(3)
           sol1=path_extrude_open(c1,l1)
          p1=cr2dt([[-3,-1.5],[3,0],[0,3],[-3,0]],10)
p2=cr2dt([[-3,-3],[3,0,1],[0,6,1],[-3,0]],10)
          sol2=prism(s1,p1)
sol3=prism(s1,p2)
           l2=point_vector([-5,1.5],[5,0])
          l3=point_vector([-5,-1.5],[5,0])
f1=fillet_line_circle(l2,c1,2.5,3,s=21)
           p0=s_int1([l2]+seg(c1))[0]
          f2=c32(flip(mirror_line(c23(f1),[0,1,0],[0,0,0])))
f3=c32(flip(mirror_line(c23(f1),[1,0,0],[0,0,0])))
f4=c32(flip(mirror_line(c23(f3),[0,1,0],[0,0,0])))
           s2=path_extrude_open(f1,l1)
          s3=path_extrude_open(f2,l1)
s4=path_extrude_open(f3,l1)
           s5=path_extrude_open(f4,l1)
           fo(f'''
           {swp(sol1)}
           {swp(sol2)}
           intersection(){{
           {swp(sol3)}
           for(p={[s2,s3,s4,s5]})swp(p);
          }}
           111)
```



```
In [ ]: t0=time.time()
         s1=square([50,60])
c1=circle(3)
         sol1=path_extrude_open(c1,l1)
         p1=cr2dt([[-3,-1.5],[3,0],[0,3],[-3,0]],10)
p2=cr2dt([[-3,-3],[3,0,1],[0,6,1],[-3,0]],10)
         sol2=prism(s1,p1)
sol3=prism(s1,p2)
          r=1
         a1=cr2dt([[r,0],[-r,0,r],[0,r]],20)
a=l_(a_([prism(s1,path_offset(p1,x)) for (x,y) in a1]).round(3))
         b=l_(a_([path_extrude_open(offset(c1,y,2),l1) for (x,y) in al]).round(3))
fo(f'''
          {swp(sol1)}
         {swp(sol2)}
         for(i=[0:{len(a1)-1}])
         intersection(){{
         swp({a}[i]);
         swp({b}[i]);
         }}
''')
         t1=time.time()
         t1<u>-</u>t0
```



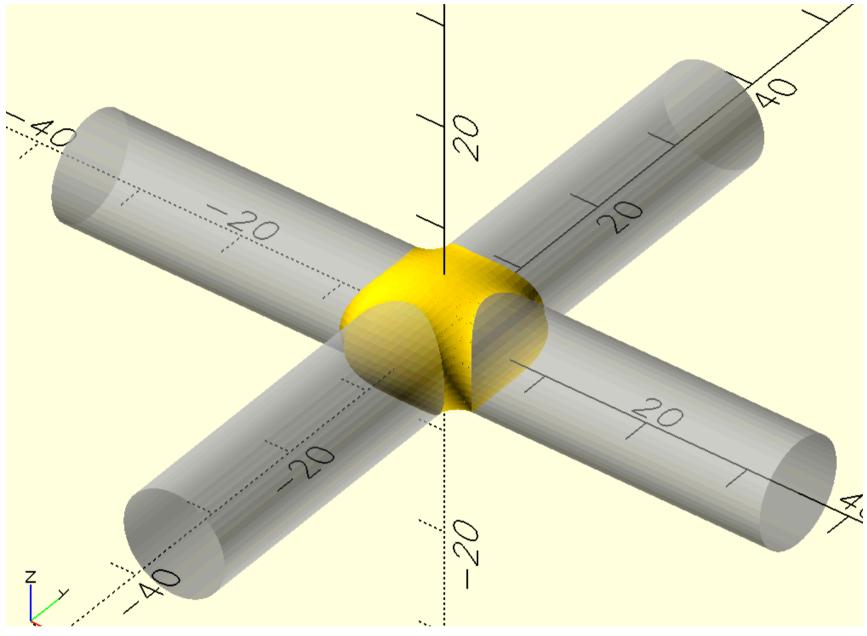
```
In []: # another approach to create fillets

s2=translate([0,35,0],rot('x90',cylinder(r=5,h=70)))
s3=translate([-35,0,0],rot('y90',cylinder(r=5,h=70)))

p1=corner_radius_with_turtle([[1.5,0],[-1.5,0,1.5],[0,1.5]],20)
```

```
s4=[translate([0,35,0],rot('x90',cylinder(r=(5+x),h=70))) for (x,y) in p1]
s5=[translate([-35,0,0],rot('y90',cylinder(r=(5+y),h=70))) for (x,y) in p1]

fo(f'''
%(swp(s2))
%(swp(s3))
for(i=[0:19])
hull(){{
    intersection(){{
        swp({s4}{ii});
        swp({s5}{ii});
        }
     intersection(){{
        swp(s4}{ii-1});
        swp({s5}{ii-1});
        }
}
intersection(){{
        swp(s5}{ii-1});
        }
}
```

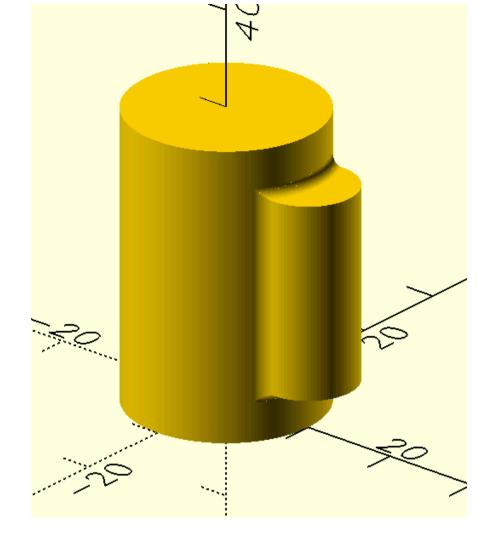


```
In []: s2=linear_extrude(circle(10,s=200),30)
    s3=translate([10,0,5],linear_extrude(circle(5,s=100),20))
    p1=corner_radius_with_turtle([[1,0],[-1,0,1],[0,1]],20)
    s4=[ translate([10,0,5-x],linear_extrude(offset(circle(5,s=100),x),20+2*x))    for (x,y) in p1]
    s5=[linear_extrude( offset(circle(10,s=200),y),30)    for(x,y) in p1]

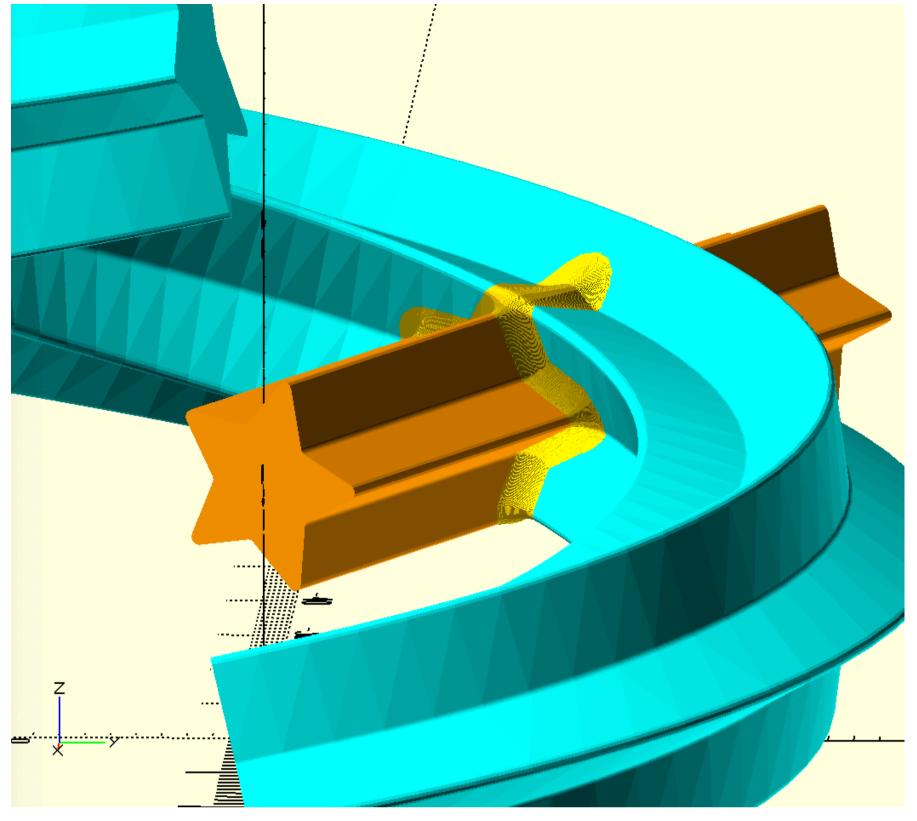
    fo(f'''
    {swp(s2)}
    {swp(s3)}
    for(i=[0:19])
    hull(){{
        intersection(){{
        swp({s4}[i]);
        swp({s4}[i]);
        swp({s4}[i+1]);
        swp({s4}[i+1]);
        swp({s5}[i+1]);
    }
}

    intersection(){{
        swp({s4}[i+1]);
        swp({s5}[i+1]);
    }
}

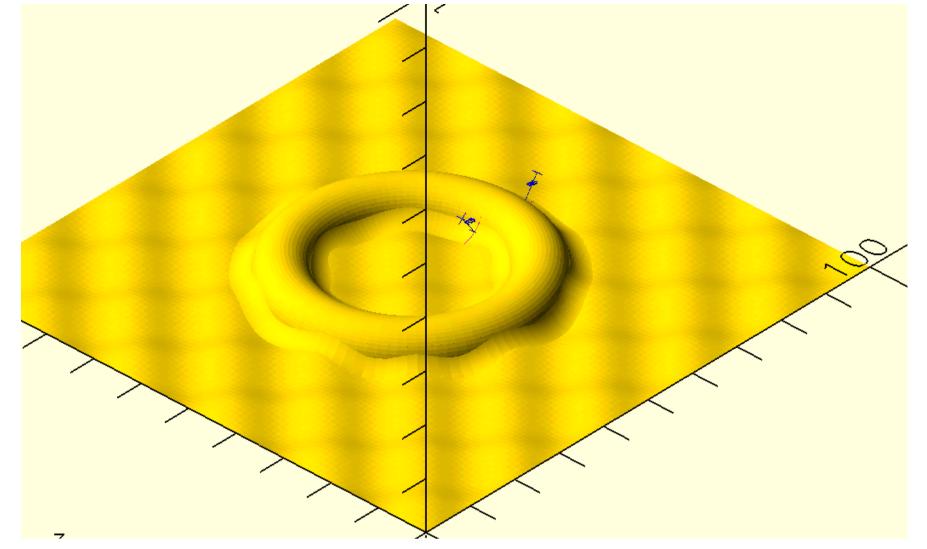
    ''')
```



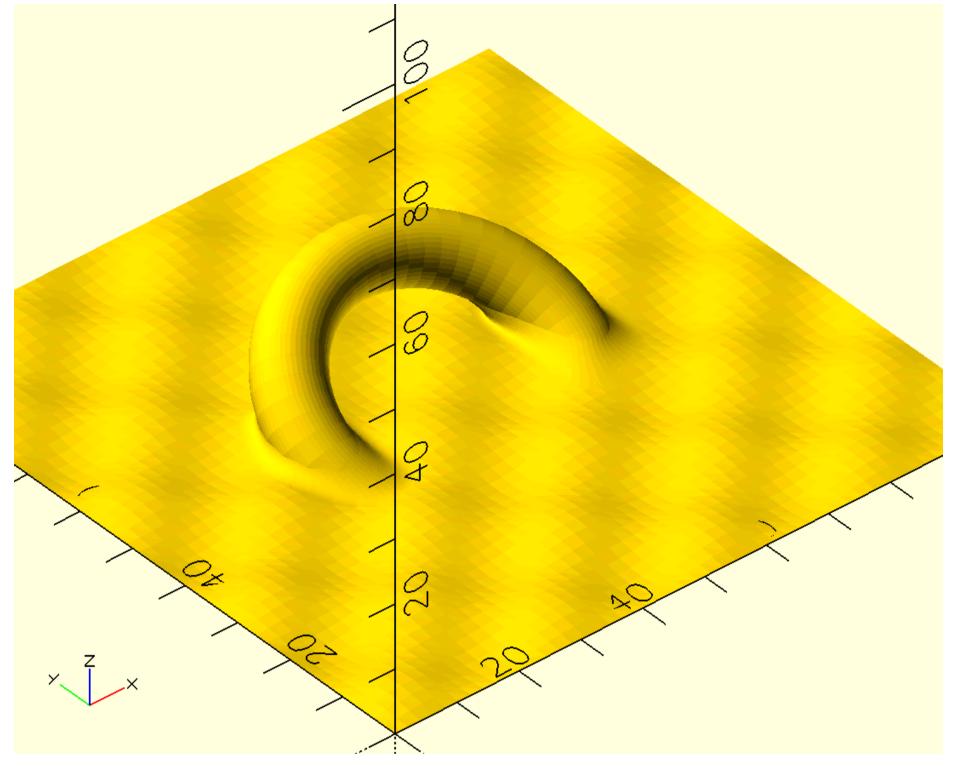
```
In [ ]: t0=time.time()
          sec1=circle(10,s=6)
          pent1=circle(7,s=6)
         pent2=c3t2(rot(f'z{360/5/2}',circle(3.5,s=6)))
sec2=concatenate(cpo([pent1]+[pent2])).tolist()
          sec2=corner_radius(array(c2t3(sec2))+[0,0,.3],5)
          sec3=concatenate(cpo([pent1]+[pent2])).tolist()
          sec3=offset(sec3,-1)
          sec3=corner_radius(array(c2t3(sec3))+[0,0,.3],5)
          path1=helix(20,30,1,5)
         path2=[[0,0,10],[-30,20,13]]
          sol=path_extrude_open(sec2,path1)
          sol1=path_extrude_open(sec3,path2)
          sol2=sol[20:40]
         a1=cr2dt([[1.1,0],[-1.1,0,1.1],[0,1.1]],90)
a=l_(a_([path_extrude_open(offset(sec3,x,2),path2) for (x,y) in a1]).round(3))
         b=l_(a_([path_extrude_open(offset(sec2,y,2),path1[25:35]) for (x,y) in a1]).round(3))
          fo(f'''
          for(i=[0:{len(a1)-1}])
          intersection(){{
          swp({a}[i]);
          swp({b}[i]);
         }}
         color("cyan"){swp(sol)}
color("orange"){swp(sol1)}
          t1=time.time()
         t1-t0
```



```
In [ ]: i_t=time.time()
          l1=rot('x90',sinewave(100,5,2,100))
l2=rot('x90z90',sinewave(100,5,2,100))
           s1=surface_from_2_waves(l1,l2,1)
          c1=sec_start_pos( circle(5),12)
          c2=circle(20,[50,50],s=100)
          sol1=prism(c2,c1)
           sol1=sol1+[sol1[0]]
          l1=c23(circle(15,[50,50],s=100))
l2=c23(circle(15-3,[50,50],s=100))
          l3=c23(circle(15+1,[50,50],s=100))
           l2=plos(s1,l2,[0,0,1],unidirection=0)
l3=plos(c_(sol1),l3,[0,0,1],unidirection=1)
           fillet1=convert_3lines2fillet_closed(l2,l3,l1,s=20,r=5,style=1)
          l1=c23(circle(25,[50,50],s=100))
          l2=c23(circle(25+3,[50,50],s=100))
l3=c23(circle(25-1,[50,50],s=100))
           l2=plos(s1,l2,[0,0,1],unidirection=0)
          l3=plos(c_(sol1),l3,[0,0,1],unidirection=1)
fillet2=convert_3lines2fillet_closed(l2,l3,l1,s=20,r=5,style=1)
          txt1=dim_radial(fillet1[0][:-1])
          txt2=dim_radial(fillet2[0][:-1])
           fo(f'''
           {swp_surf(s1)}
           {swp_c(sol1)}
{swp_c(fillet1)}
           {swp_c(fillet2)}
           {txt1}{txt2}
          f_t=time.time()
           f_t-i_t
```



```
In [ ]: t0=time.time()
          # another strategy for filleting
s1=rot('x90',sinewave(100,4,1,50))
           s2=rot('x90z90',sinewave(100,4,1,50))
           surf1=surface_from_2_waves(s1,s2,1)
           c1=circle(5)
           p1=c23(sec_start_pos(circle(20),35))
           theta=30
          o=5
          sol1=translate([50,50,0],rot(f'x\{theta\}',path\_extrude\_closed(c1,p1)))\\ surf2=plane([0,0,1],[200,200])
           l1=ip_surf2sol(surf2,sol1)
           l2=offset_3d(l1,o*.6)
           l3=i_p_p(sol1,l1,o)
           l1=plos(surf1,l1,rot(f'x{theta}',[0,1,0]),0)
l2=plos(surf1,l2,rot(f'x{theta}',[0,1,0]),0)
           f1=convert_3lines2fillet_closed(l2,l3,l1,s=20)
           l1=ip_surf2sol(surf2,sol1,-1)
           l2=offset_3d(l1,o*.6)
           l3=i_p_s(sol1,l1,-o)
          l1=plos(surf1,l1,rot(f'x{theta}',[0,1,0]),0)
l2=plos(surf1,l2,rot(f'x{theta}',[0,1,0]),0)
f2=convert_3lines2fillet_closed(l2,l3,l1,s=20)
           txt1=dim_radial(sol1[20][20:],cross_hair_size=.5,outside=1)
           fo(f'''
           //color("blue") for(p={[l1,l2,l3]}) p_line3d(p,.3);
           {swp_surf(surf1)}
{swp_c(sol1)}
           {swp_c(f1)}
           {swp_c(f2)}
           {txt1}
           t1=time.time()
           t1-t0
```



```
In [ ]: t0=time.time()
           # another strategy for filleting
           c1=circle(5)
           p1=sec_start_pos(c23(circle(20)),35)
sol1=path_extrude_closed(c1,p1)
sol2=rot('x90',sol1)
            r=2
           a1=cr2dt([[r,0],[-r,0,r],[0,r]],50)
           a=l_(a_([path_extrude_open(offset(c1,x,2),p1[10:19]) for (x,y) in a1]).round(3))
b=l_(a_([rot('x90',path_extrude_open(offset(c1,y,2),p1[10:19])) for (x,y) in a1]).round(3))
fo(f'''
            {swp_c(sol1)}
           {swp_c(sol2)}
            for(i=[0,180]) rotate([0,0,i])
            for(i=[0:{len(a1)-1}])
           intersection(){{
swp({a}[i]);
           swp({b}[i]);
           }}
           111)
           t1=time.time()
           t1-t0
```

