

In [185...]

```
%load_ext autoreload
%autoreload 2
from openscad2 import *
set_printoptions(suppress=True)
# from IPython.display import display, HTML
# display(HTML("<style>.container { width:100% !important; }</style>"))
```

The autoreload extension is already loaded. To reload it, use:
 %reload_ext autoreload

Table of Contents (alphabetic ordered)

- **3d-knots** : various interesting 3d knots
- **align_sol(sol,ang=10)** : same as align_sec but for solid with multiple slices
- **align_sol_1(sol)**: same a align_sec_1 but for a solid with multiple slices
- **ang(x,y)**: calculates the angle with base(x) and perpendicular(y) distances. if x<0 and y>0 the angle will be 90<x<180
- **ang_2lineccw(p0,p1,p2)** : ccw angle of the line p0p2 from base line p0p1
- **ang_2linecw(p0,p1,p2)** : cw angle of the line p0p2 from base line p0p1
- **arc(radius=0,start_angle=0,end_angle=0,cp=[0,0],s=20)**: function for calculating 2d arc. 'cp': center point of the arc. 's': number of segments in the arc
- **arc_2p(p1,p2,r,cw=1,s=20)**: calculates arc with 2 given points.cw or ccw will change the arc, also this generates the shortest distance arc
- **arc_2p_3d(n1,p0,p1,r,cw=1,s=20)** : draws an arc with 2 points and normal in 3d space
- **arc_2p_3d_cp(n1,p0,p1,r,cw=1)** : finds center point of the arc with 2 points and a normal
- **arc_2p_cp(p1,p2,r,cw=-1)** : calculates the center point of an arc based on 2 given points, cw or ccw dirctions are important to calculate the correct center point
- **arc_3d(v=[0,0,1],r=1,theta1=0,theta2=360,cw=-1,s=50)** : calculates the arc in 3d space w.r.t. plane defined by normal vector 'v1', radius 'r1', start and end angles, cw or ccw and number of segments 's'
- **arc_3p(p1,p2,p3,s=30)**: function to draw arc with 3 known points 'p1','p2','p3'. 's' is the number of segments of the arc
- **arc_3p_3d(points,s=20)** : draws an arc through the 3 points list. 's' is the number of segments of the circle
- **arc_long_2p(p1,p2,r,cw=1,s=20)**: long arc with 2 points 'p1,p2' with radius 'r' and with orientation clockwise (1) or counterclock wise(-1)
- **arc_long_2p_3d(n1,p0,p1,r,cw=1,s=20)** : draws a long arc with 2 points and normal
- **artifact** :
- **axis_rot(axis,solid,angle)**: rotate a solid around an axis
- **axis_rot_1(sol,ax1,loc1,theta)**: rotate a solid on any pivot point 'loc1' with axis of rotation 'ax1' by an angle 'theta'
- **axis_rot_o(axis,solid,angle)**: rotate a solid around an axis considering the solid is centered at origin
- **back-camera-clamp** :
- **ball-bearing** :
- **bb(prism)**: function to find the bounding box dimensions of a prism
- **bezier (p , s = 10)**: function to draw bezier curve with 'p' control points and 's' number of points on the resultant bezier curve)
- **bottle-with-cut-design** :
- **bspline_open(pl,deg,s=100)** : draws a bspline curve for the given control points 'pl' , 'deg' is the degree of curve that is quadratic, cubic or higher order 's' defines the number of points in a bspline curve
- **bspline_close(pl,deg,s=100)** : draws a bspline curve for the given control points 'pl' , 'deg' is the degree of curve that is quadratic, cubic or higher order 's' defines the number of points in a bspline curve
- **business-card-holder** :
- **c_hull(pnt)**: function to calculate convex hull for a list of points 'pnt'
- **c2ro(sol,s)** : change the orientation of points of a cylinder from circular to rectangular orientation. 'sol': is a cylindrical type 3d shape. 's': number of segments required between each straight line segments
- **c2t3(p)** : function to convert 2d to 3d, it just adds the z-coordinate to the points list
- **c3t2(a)**: function to convert 3d to 2d, it just removes the z-coordinate from the points list
- **cam-profile** :
- **Car Seat** :
- **chimney-panel-support** :
- **cir_2p(p1,p2,r,cw=1,s=20)** : circle with 2 points 'p1,p2' with radius 'r' and with orientation clockwise (1) or counterclock wise(-1)
- **cir_3p(p1,p2,p3,s=30)**: function to draw circle with 3 known points 'p1','p2','p3'. 's' is the number of segments of the circle
- **cir_3p_3d(points,s=20)**: draws a circle through the 3 points list. 's' is the number of segments of the circle
- **cir_p_t(cir,p)**: circle to point tangent line (point should be outside the circle)
- **circle(r,cp=[0,0],s=50)** : function for creating points in circle with radius "r", center point "cp" and number of segments "s"
- **coil-example** :
- **concave_hull(p_l,k=3)**:calculate the concave hull of a random list of points. larger number for 'k' will give smoother shape
- **convert_3lines2fillet(pnt1,pnt2,pnt3,f=1.9,s=10)** : Develops a fillet with 3 list of points (pnt1,pnt2,pnt3) in 3d space, f: is a factor which can be reduced to 1.5 in case of self intersection observed, s: number of segments in the fillet, increase the segments in case finer model is required
- **convert_3lines2fillet_closed(pnt1,pnt2,pnt3,f=1.9,s=10)** : Develops a fillet with 3 list of points (pnt1,pnt2,pnt3) in 3d space, f: is a factor which can be reduced to 1.5 in case of self intersection observed, s: number of segments in the fillet, increase the segments in case finer model is required
- **convert_secv(sec)** : function removes all the radii from the section 'sec' where points are ccw
- **convert_secv1(sec)** : function removes all the radii from the section 'sec'
- **convert_secv2(sec,d)** : function removes all the radii from the section 'sec' where points are cw. 'd' should be > the maximum radius at cw corner to give the right results
- **convex(sec)** : function to check whether a section is convex or not
- **convex_hull(pnts)**: calculates convex hull for a list of points 'pnts'
- **corner_radius(sec,s)** : function to create section with corner radiiuses)

- **cosinewave(l,n,a,p)** : creates a cosinewave with length 'l', number of cycles 'n' amplitude 'a' and number of points 'p'
- **cp_3p(p1,p2,p3)** : function to calculate center point of a circle created from 3 known points 'p1','p2','p3'
- **cp_arc(arc1)** : function returns the center point of a given circle or arc
- **cp_cir_3d(cir)** : center point of circle with atleast 3 known list of 'points' in 3d space
- **cpo(prism)** : function to change the orientation of the points of the prism
- **cs1(sec,d)**: creates a cleaning section for removing excess points for offsetting a section 'sec' with offset distance 'd'
- **cube(s,center=False)** : function to draw cube with size 's'
- **cut_plane(nv=[0,0,1],size=[5,5],thickness=10,trns1=0,trns2=0,trns3=0)** : function for defining a solid (cutting plane) oriented as per the defined normal vector, nv: normal vector for defining plane orientation of the section, thickness: thickness or height of the cutting plane, trns1: translate the solid in the direction of normal vector 'nv', trns2: translate the solid in the direction 'right' to the normal vector 'nv', trns3: translate the solid in the direction 'up' to the normal vector 'nv', '-ve' values given to the trns1,trns2,trns3 will translate the solid in the reverse direction
- **cw(sec)** : function to identify if an enclosed section is clockwise(cw) or counterclockwise(ccw). this returns 1 if section is clockwise and -1 if it is counterclockwise
- **cwv(sec)** : function to identify whether each point in a section is clockwise or counter clockwise.
- **cylinder(r1=1,r2=1,h=1,cp=[0,0],s=50,r=0,d=0,d2=0,center=False)** : function for creating cylinder, cone
- **cylinder-with-rectangular-pocket** :
- **cylinder-with-star-pocket** :
- **cytz(path)**: converts 'y' points to 'z' points in a 2d list of points
- **drill-bit** :
- **e_wave(l,a,w,t)** : create a graph of exponential function $a \cdot e^{-(wt)}$ where, w: omega, t: time steps, a: amplitude, l: length of time
- **end_cap(sol,r=1,s=10)** : function to draw radius at the ends of 'path_extrude_open' models. sol: path extruded solid, r: radius at the ends, s: segments of the radius
- **equidistant_path(path,s=10)** : divides a path in to equally spaced points
- **equidistant_pathc(path,s=10)** : divides a closed path in to equally spaced points
- **equivalent_rot_axis(r1=[])** : function returns an equivalent axis for rotation and angle of rotation for a sequence of rotations given by list 'r1'
- **example-of-rounding** :
- **exclude_points(list1,list_to_exclude)** : function to remove points from a list
- **f_prism(sec,path)** : creates a solid or prism with a 2d section and a 2d path. This is a much faster version of function prism, but may not work with few shapes correctly)
- **faces(l,m)** : calculate the faces for the vertices with shape l x m with first and the last end closed
- **faces_1(l,m)** : calculate the faces for the vertices with shape l x m with first and the last end open
- **fillet_2cir(r1,r2,c1,c2,r,s=50)** : fillet between 2 circles with radius 'r1' and 'r2' and center points 'c1' and 'c2' and 'r' is the radius of the fillet
- **fillet_3p_3d(p0,p1,p2,r,s)** : fillet with 3 known points 'p0,p1,p2' in 3d space
- **fillet_3p_3d_cp(p0,p1,p2,r)** : center point 'cp' of the fillet with 3 known points 'p0,p1,p2' in 3d space. 'r' is the radius of fillet
- **fillet_line_circle(l1,c1,r2,cw=-1,option=0,s=50)** : function to draw a fillet between a line and a circle, option can be '0' or '1' to flip the fillet from one side to another, 's' is the number of segments in the arc
- **fillet_2cir(r1,r2,c1,c2,r,s=50)** : fillet between 2 circles with radius 'r1' and 'r2' and center points 'c1' and 'c2' and 'r' is the radius of the fillet. This is an open fillet where first or the second fillet can be called based on requirement
- **flip(sec)** : flips the sequence of a list or list of points
- **gcd(a,b)** : calculates greatest common divisor for 2 numbers
- **glass-model** :
- **handling-trolley** :
- **helix(radius=10,pitch=10, number_of_coils=1, step_angle=1)** : creates helix
- **honeycomb(r,n1,n2)** : function to draw a honeycomb structure with radius 'r', n1: number of hexagons in 1 layer, n2: number of layers
- **i_line_fillet(sol1,sol2,ip,r1,r2,s=20,o=0)** : calculates a fillet at the intersection of 2 solids when the intersection points 'ip' are separately defined. r1 and r2 would be same in most of the cases, but the signs can be different depending on which side the fillet is required. r1 is the distance by which intersection line offsets on sol2 and similarly r2 is on sol1
- **i_line_planes(p1,p2)**: intersection line between 2 planes 'p1' and 'p2'
- **i_p_n(sol,i_p)** : calculates normal at the intersection points, sol: solid on which the normal is required, i_p: list of intersection points between 2 solids
- **i_p_p(sol,i_p,r)** : function to project the intersection point on the cutting lines based on the distance 'r'
- **i_p_t(path)** : function to calculate tangent vectors to a given path
- **intersections(segments)** : calculates the intersections of adjacent line segments only
- **ip(prism,prism1,side=-1)**: function to calculate intersection point between two 3d prisms. "prism" is the 3d object which is intersected with "prism1". side: when a ray intersects a solid it can intersect at 2 locations, if the ray is travelling from outside, in that case if '0' is given meaning only the first intersection point is considered, and in case '-1' is given meaning the last intersection point will be considered.)
- **ip_fillet(sol1,sol2,r1,r2,s=20,o=0)** : calculates a fillet at the intersection of 2 solids. r1 and r2 would be same in most of the cases, but the signs can be different depending on which side the fillet is required. r1 is the distance by which intersection line offsets on sol2 and similarly r2 is on sol1
- **ip_sol2line(sol,line)** : function to calculate intersection point between a 3d solid and a line. "sol" is the 3d object which is intersected with a "line". in case there are more than 1 intersections of the line with the solid/ prism ip(sol,line)[0] will give the first intersection point and ip(sol,line)[-1] will give the last intersection point
- **ip_sol2sol(sol,sol1,n=0)** : function to find the intersection point between 2 solids. this function is to be used where the cutting lines of sol1 are intersecting sol at more than 1 times.sol: solid which is intersected. sol1: this intersects the solid 'sol'. n: if the first intersection points of all the cutting lines are to be considered, value of n should be '0'. if the last intersection points of all the cutting lines are to be considered, value of 'n' should be set to '-1'
- **ip_triangle(sol1,p0)** : finds the triangle where the intersection point "p0" lies in a solid "sol1"
- **iterative-approach-towards-creating-fillets** :
- **I_cir_ip(line,cir)** : line circle intersection point
- **I_len(l)** : calculates length of a line 'l'
- **I_lenv(l)** : calculates sum of lengths of all the segments in a line 'l' considering the section is closed
- **I_lenv_o(l)** : calculates sum of lengths of all the segments in a line 'l' considering the section is open
- **I_sec_ip(line,sec)** : line and section intersection point

- **`I_sec_ip_3d(sec,line)`** : finds the intersection points between a section in 3d space and a line in 3d space
- **`I2I_intersection(l1,l2)`** : function to find the intersection point between 2 lines in 3d space
- **`lamp`** :
- **`lcm`** : calculates least common multiple for 2 numbers
- **`lexicographic_sort_xy(p)`** : function sorts the points list 'p' first with x and then with y smallest to largest
- **`lexicographic_sort_yx(p)`** : function sorts the points list 'p' first with y and then with x smallest to largest
- **`linear_extrude(sec,h=1,a=0,steps=1)`** : function to linear extrude a section where, se/users/sanjeevprabhakar section to extrude, h: height of the extrusion, a: angle of twist while extruding, steps: number of steps in each angular extrusion
- **`list_r(sec)`** : function list the corner radiiuses of a given section (only where the radius is specified)
- **`ls(line,n)`**: plots 'n' points in a straight line)
- **`m10`** :
- **`m35`** :
- **`m39`** :
- **`max_r(sec)`** : finds the maximum radius of a given closed section)
- **`mobile-phone-stand`** :
- **`multiple_sec_extrude(path_points=[],radiuses_list=[],sections_list=[],option=0,s=10)`**: path_points: are the points at which sections needs to be placed,radiuses: radius required at each path_point. this can be '0' in case no radius required in the path, sections_list= list of sections required at each path_points. same section can be provided for various path_points as well, option: can be '0' in case the number of points in each section do not match or '1' in case number of points for each section are same, s: in case value of radiuses is provided 's' is the number of segments in that path curve
- **`normals_along_path`** :
- **`nv(p)`** : finds the normal vector for a given points in a 3d plane
- **`o_3d(i_p,sol,r,o=0)`** : function to offset the intersection points 'i_p' on a solid 'sol' by distance 'r'. option 'o' can have values '0' or '1' and changes the direction of offset
- **`o_p_p(sol,i_p,d)`**: calculates projected points on the surface of a solid , sol: solid on which the points to be projected, i_p: list of points in 3d space near the solid, d: approximate distance of the points from the surface, specifying too big distance , may create multiple projection of the same point on the solid
- **`o_solid(nv=[0,0,1],sec=[],thickness=10,trns1=0,trns2=0,trns3=0, theta=[0,0,0])`** : function for defining a solid with any defined section. solid gets oriented as per the defined normal vector, nv: normal vector for defining plane orientation of the section, se/users/sanjeevprabhakar cross section of the solid, thickness: thickness or height of the solid, trns1: translate the solid in the direction of normal vector 'nv', trns2: translate the solid in the direction 'right' to the normal vector 'nv', trns3: translate the solid in the direction 'up' to the normal vector 'nv', '-ve' values given to the trns1,trns2,trns3 will translate the solid in the reverse direction , theta: rotate the section around axis fox example if nv is [1,0,0] or x-axis, the sequence of rotation will be x, y , z axis
- **`offset(sec,r)`** : calculates offset for a section 'sec' by amount 'r'
- **`offset_3d(sec,d)`** : offsets an enclosed section in 3d space, in case the section is in 1 plane, se/users/sanjeevprabhakar section in 3d space, d: offset distance -ve sign means inner offset and +ve sign is outer offset
- **`offset_points(sec,r)`** : function to calculate offset of a list of 2d points. in defining sections, providing corner radius is a must
- **`offset_points_ccw(sec,r)`**: function to offset only those points which are counter clockwise
- **`offset_points_cw(sec,r)`** : function to offset only those points which are clockwise
- **`offset_seg_cw(sec,r)`** : function offsets the segment only when the point is clockwise
- **`offset_segv(sec,d)`** : function makes the segments of the original section and offset each segment by a distance 'd'
- **`orthos_along_path(path,scale=1)`** :
- **`oset(sec,r)`** : function to draw offset of a section 'sec' with distance 'r'
- **`p_cir_t(p,cir)`** : point to circle tangent line (point should be outside the circle)
- **`p2p_interseccion_line(pa,pb)`** : function to calculate intersection line between 2 planes in 3d space
- **`path_extrude_closed(sec,path,twist=0)`** : function to extrude a closed section to a closed path. closed path means the path provided has it's first and the last point same example a circle
- **`path_extrude_open(sec,path,twist=0)`**: function to extrude a closed section to an open path. twist can be set either to '0' or '1' depending on the shape produced
- **`path_offset(path,d)`** : function to offset a 'path' by 'd' distance
- **`pies1(sec,pnts)`** : function to find points 'pnts' which are inside an enclosed section 'sec'
- **`plane(nv,size=[100,100])`** : plane defined by normal 'nv' and 'size'
- **`pntsnfaces(bead2)`** : function returns points and faces of a prism
- **`points_inside_offset_surround(sec,sec2,r)`** : function returns points in a list 'sec2' which are inside the offset surround of a section 'sec' with offset radius of 'r'
- **`ppesec(p0,sec)`**: point's projection on an enclosed 3d section
- **`ppplane(p0,v1,loc)`** : function to find projected points of a given list of points 'p0' on a plane defined by normal'v1' and location 'loc'
- **`prism(sec,path)`** : function to make a prism with combination of 2d section and 2d path
- **`prism2cpo(s1)`** : function to change the orientation of the surface
- **`psos(s2,s3,v1)`** : function to project a surface on to another
- **`pts(p)`** : calculates the cumulative sum of 2d list of points 'p'
- **`pts1(p)`**: 'p' is a list of points. function calculates the cumulative sum of x,y values in the list while z value remains the same. this is mainly used in function corner_radius(pl,s).
- **`q(vector=[1,0,0],point=[0,5,0],theta=0)`** : function to rotate a point around a vector(axis) with angle theta)
- **`q_rot(s,pl)`** : function to rotate a group of points "pl" around a series of axis with defined angles
- **`q_rot2d(theta,pl)`** : function to rotate a 2d point or 2d points list by an angle theta around z-axis
- **`r_sec(r1,r2,cp1,cp2)`** : creates a rounded section around a line defined by points 'cp1' and 'cp2'. radius around 'cp1' is 'r1' and radius around 'cp2' is 'r2'
- **`reorient_sec(sec)`** :re-orient section to create a better surface through 'prism' function
- **`rounding-various-rounded-cubes`** :
- **`rsz2d(sec,rsz)`** : function to resize a 2d section to dimensions 'rsz'. resized section will be placed on bottom center of the original section
- **`rsz2dc(sec,rsz)`** : function to resize a 2d section to dimensions 'rsz'. resized section will be placed in center of the original section
- **`rsz3d(prism,rsz)`** : function to resize a 'prism' to dimensions 'rsz'. bottom left corner of both the prisms would be same

- **rsz3dc(prism,rsz)** : function to resize a 'prism' to dimensions 'rsz'. resized prism will be placed in the center of the original prism or center point of both the prisms will be same
- **s_int(s)** : calculates the self intersection points of a list of line segments 's'. it also picks the points in case the 2 lines are just connected at 1 point and are not crossing
- **s_int1(s)**: calcutes the self intersecting segments such that there is a complete intersection and not only end points touching
- **samsung-tab-s6-holder** :
- **scl2d(sec,sl)**: scale a 2d section to a scaling factor 'sl')
- **scl2d_c(sec,sl)** : scale a 2d section such that the center of original and scaled section is same)
- **scl3d(p,s)** : scale any 3d prism to a scaling factor 's')
- **sec2vector(v1=[1,0,0],sec=[])** : function to align a section 'sec' with a vector 'v1'
- **sinewave(l,n,a,p)** : creates a sinewave with length 'l', number of cycles 'n' amplitude 'a' and number of points 'p'
- **sinwave-box** :
- **sl_int(sec,line)** : function to find intersection between an enclosed section in 3d space and a line
- **slice_sol(sol,n=10)**: function to slice a solid with 'n' intermediate steps
- **sol2path(sol,path)**: function to extrude a solid along a path
- **sol2vector(v1=[],sol=[],loc=[0,0,0])**: orients a solid as per a given vector
- **sort_points(sec,list1)** : function picks the nearest point of a section from a reference section and matches the length of points for the 2 compared sections
- **sphere(r=0,cp=[0,0,0],s=50)** : function to draw sphere with radius 'r' , center point 'cp' and number of segments 's'
- **sunflower** :
- **surf_base(surf,h=0)** : creates a solid from any surface, 'h' is the height of the base of the surface
- **surf_extrude(sec,path)** : extrudes an open section 'sec' to a 3d 'path' to create surface
- **surf_extrudef(surf,t=-.05)** : surface with a polyline 2d sketch and a 3d path. thickness of the surface can be set with parameter "t". positive and negative value creates thickness towards +z and -z directions respectively
- **surf_offset(sec,d)** : function to offset the surface 'sec' by a distance 'd'
- **surface_for_fillet(sol1=[],sol2=[],factor1=50,factor2=10,factor3=1,factor4=100,dia=40)**: sol1: Solid on which the surface needs to be created. sol2: Intersecting solid. factor1: number of segments in the circle. factor2: number of layers or slices of surface. factor3: decides the size of the surface lower value means bigger size. value can be set between 1 to any number. factor4: any high number should be ok like maybe 100 or greater, basically greater than the bounding box dimension of the "sol1". dia: diameter around the solid 2 where surfavce needs to be created
- **surface_offset(surf,d)** : offsets the surface by an amount 'd'
- **surface_thicken(surf,d)** : Thickens the surface by an amount 'd'
- **SurfaceFrom3LinesInDifferentPlanes(w1,w2,w3,o=1)** : create surface with 3 lines in different planes
- **swp_prism_h(prism_big,prism_small)** : creates a hollow prism with 2 similar prisms (1 big and 1 smaller)
- **t_cir_tarc(r1,r2,cp1,cp2,r,side=0,s=50)** : function draws a arc which is tangent to 2 circles defined by radiouses 'r1' and 'r2' and center points 'cp1' and 'cp2'. 's' is the number of segments of the tangent arc. 'r' is the radius of the tangent arc (it should be $\geq (r1+r2+\text{center distance of 2 circles})/2$). 'side' there are 2 sides of the circles where the arc could be created defined by '0' and '1'
- **tangents_along_path(path,scale=1)** :
- **tcct(r1,r2,cp1,cp2,cw=-1)** : two circle cross tangent
- **tctp(r1,r2,cp1,cp2)** : 2 circle tangent points (one side) r1 and r2 are the radius of 2 circles and cp1 and cp2 are the center points)
- **tctpf(r1,r2,cp1,cp2)** : 2 circle tangent point full (both the sides))
- **translate(p,sec)** : translates a prism or section by [x,y,z] distance
- **translate_2d(p,sec)** : function to translate a group of points "sec" by "p" distance defined in [x,y]
- **v_sec_extrude(sec,path,o)** : extrude a section 'sec' through a path 'path' . section will vary from start to end such that at the end the section will be offset by 'o' distance
- **wrap_around** : complex function see the example to understand

surf_extrude

```
In [2]: # example of surf_extrude
t0=time.time()

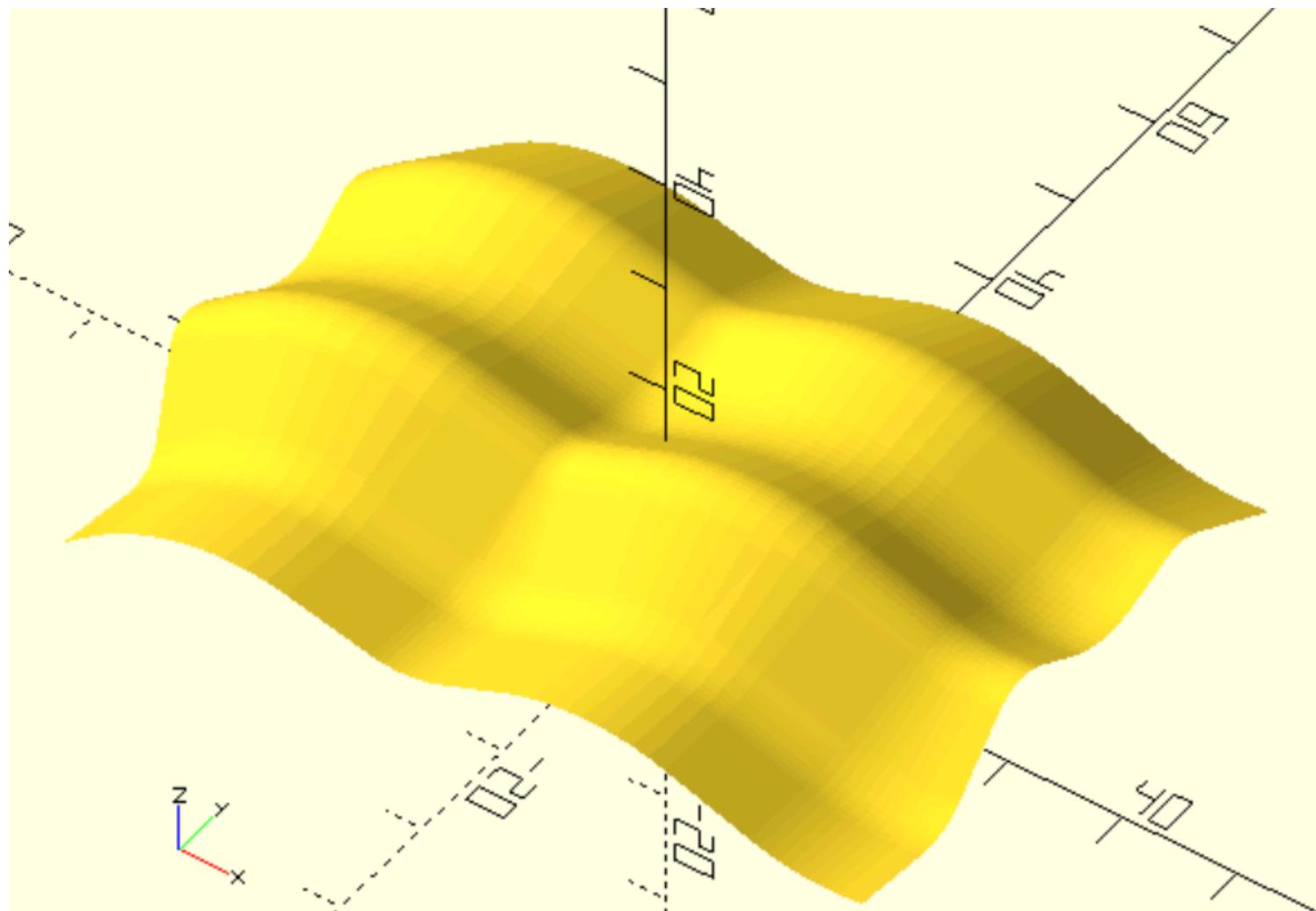
sec2=corner_radius(pts1([[-25,0],[10,5,5],[10,-3,10],[10,5,5],[10,-8,7],[10,1]]),10)
path2=cytz(corner_radius(pts1([-35,5,0],[10,8,20],[20,-5,10],[20,8,20],[10,-9,20],[10,1,0])),10)

surf2=surf_extrude(sec2,path2)
surf3=surface_offset(surf2,-1)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

{swp_surf(surf2)}
//color("grey"){swp_surf(surf3)}

'''')
t1=time.time()
total=t1-t0
total
```

Out [2]: 0.24101018905639648



surf_extrudef

surface_thicken

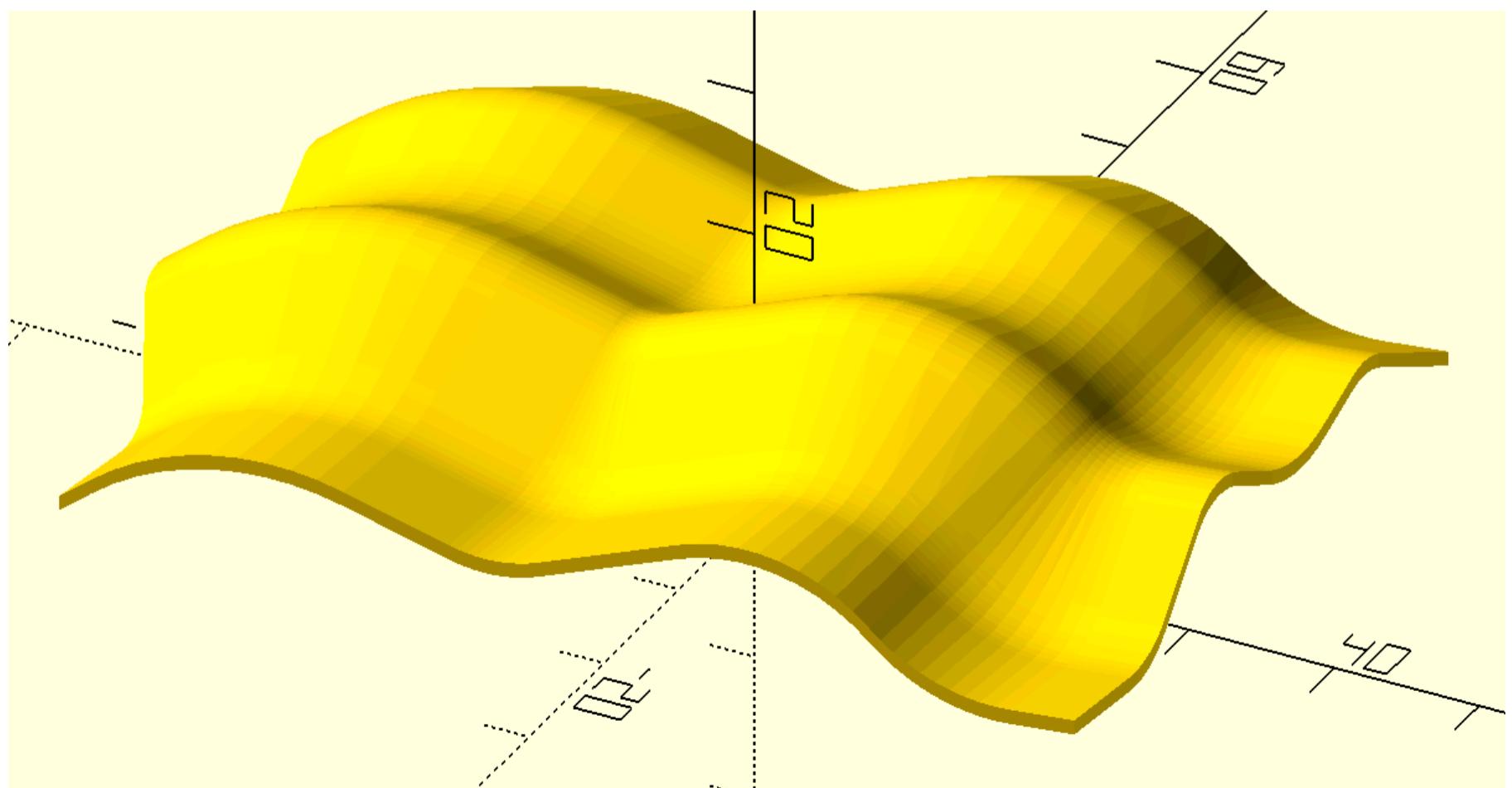
```
In [3]: # example of surf_extrudef
t0=time.time()

sec2=corner_radius(pts1([[-25,0],[10,5,5],[10,-3,10],[10,5,5],[10,-8,7],[10,1]]),10)
path2=cytz(corner_radius(pts1([[-35,5,0],[10,8,20],[20,-5,10],[20,8,20],[10,-9,20],[10,1,0]]),10))
surf2=surf_extrude(sec2,path2)
surf3=surf_extrudef(surf2,t==1)
surf3=surface_thicken(surf2,-1)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

{swp(surf3)}
//color("blue")for(p={surf3})p_line3dc(p,.1,rec=1);

''')
t1=time.time()
total=t1-t0
total
```

Out [3]: 0.2819671630859375

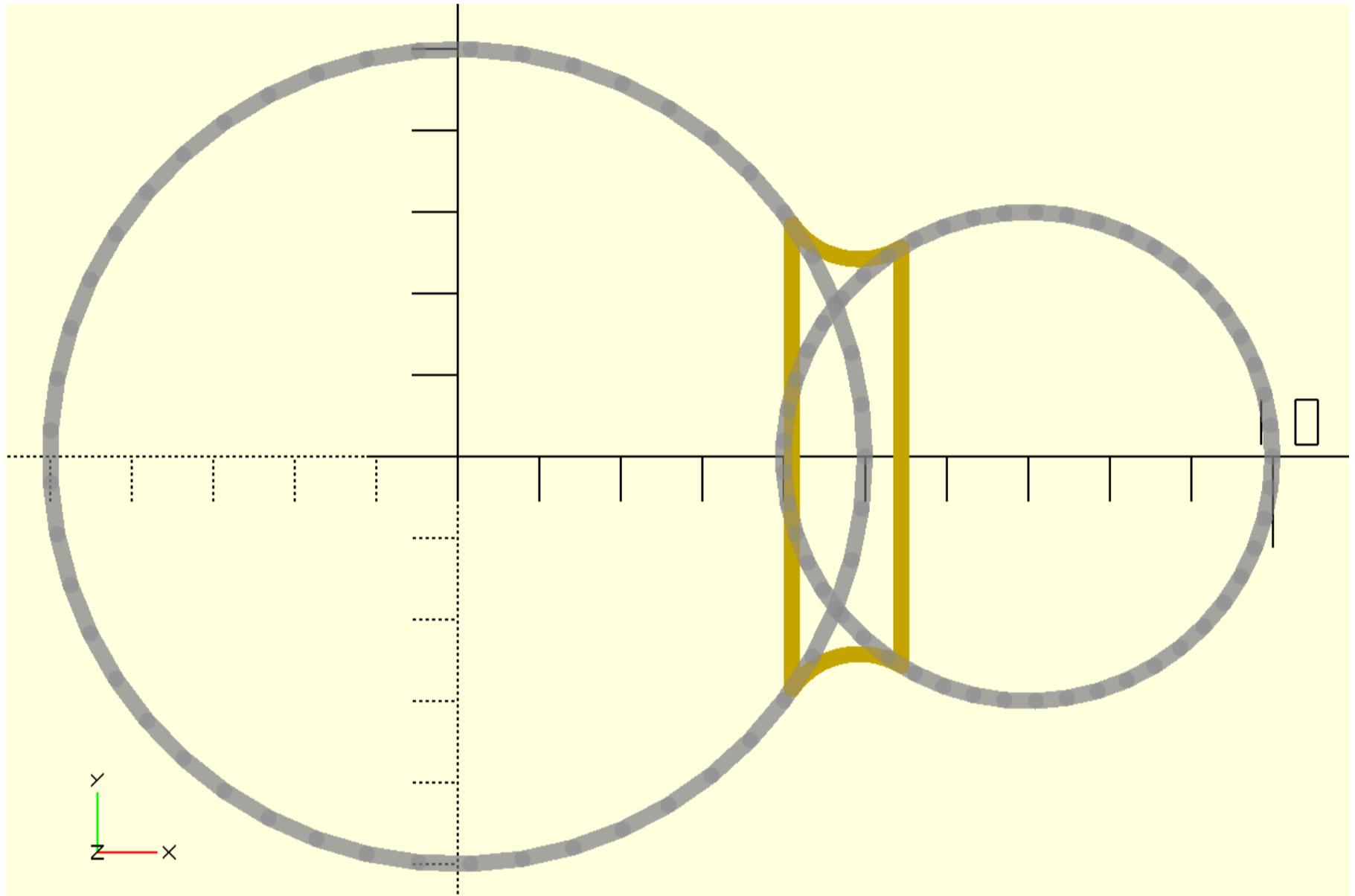


fillet_2cir

```
In [4]: # example of function fillet_2cir
t0=time.time()
fillet=fillet_2cir(r1=5,r2=3,c1=[0,0],c2=[7,0],r=1)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
%p_line({circle(5)},.2);
    %p_line({circle(3,[7,0])},.2);
    p_line({fillet},.2);

    ''')
t1=time.time()
t1-t0
```

Out[4]: 0.005474090576171875



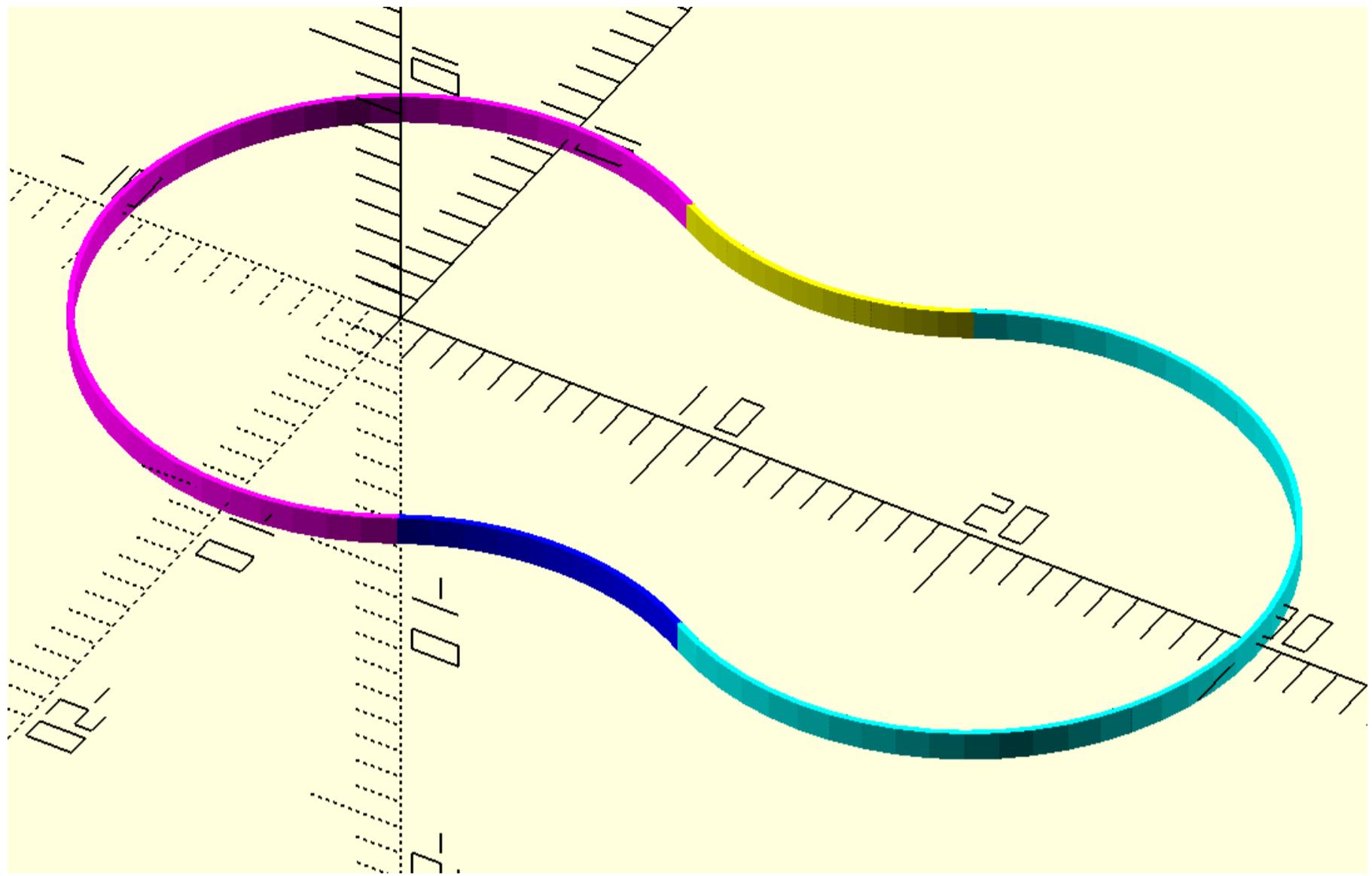
filleto_2cir

```
In [5]: # example of function filleto_2cir and arc_long_2p
t0=time.time()

fillet=filleto_2cir(r1=10,r2=10,c1=[0,0],c2=[20,0],r=10)
p0,p1,p2,p3=fillet[1][len(fillet[1])-1], fillet[0][0], fillet[0][len(fillet[0])-1], fillet[1][0]
cir1=arc_long_2p(p0,p1,10,-1,40)
cir2=arc_long_2p(p2,p3,10,-1,40)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
//%p_line({circle(10)},.2);
//%p_line({circle(10,[20,0])},.2);
color("blue")p_lineo({fillet[0]},.2);
color("yellow")p_lineo({fillet[1]},.2);
color("magenta")p_lineo({cir1},.2);
color("cyan")p_lineo({cir2},.2);

    ''')
t1=time.time()
t1-t0
```

Out[5]: 0.007096052169799805



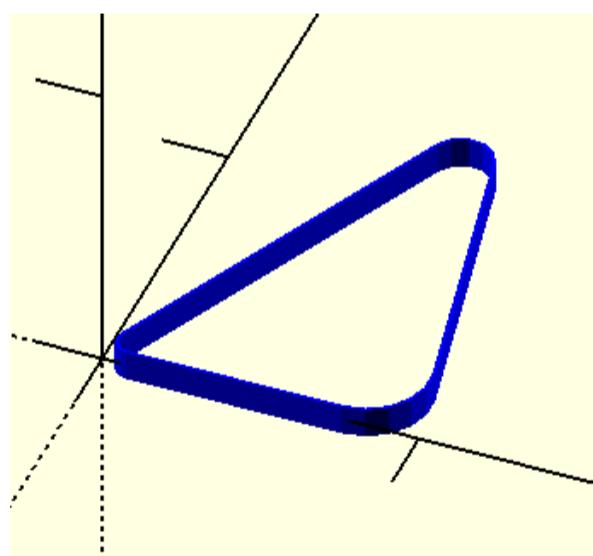
corner_radius(sec,s)

```
In [6]: # example of function corner_radius(pl,s)
t0=time.time()
sec=corner_radius(sec=[[0,0,.5],[10,0,2],[7,15,1]],s=5)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line({sec},.1);

''')
t1=time.time()
t1-t0
```

Out [6]: 0.006276845932006836



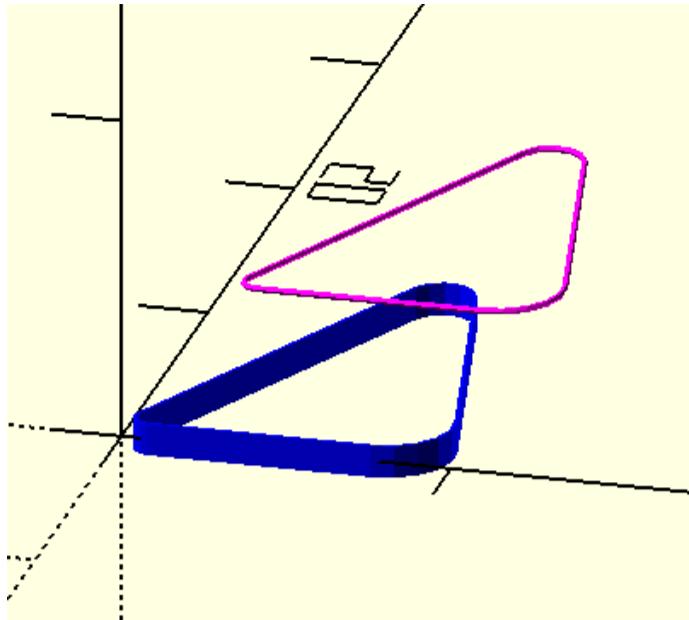
translate

```
In [7]: # example of function translate(p,sec)
t0=time.time()
sec=corner_radius([[0,0,.5],[10,0,2],[7,15,1]],5)
sec1=translate(p=[10,5,3],sec=sec)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line({sec},.1);
color("magenta")p_line3dc({sec1},.1);

''')
t1=time.time()
t1-t0
```

```
Out[7]: 0.007170200347900391
```

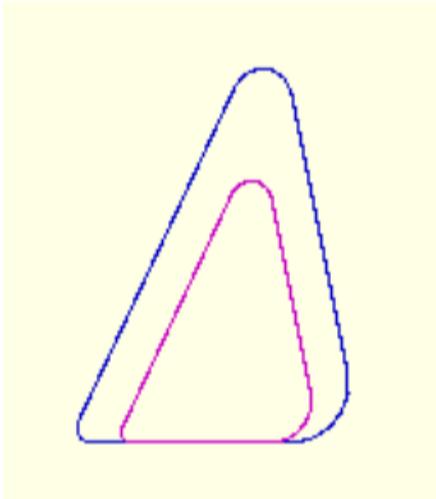


scl2d(sec,sl)

```
In [8]: # example of function scl2d(sec,sl)
t0=time.time()
sec=corner_radius([[0,0,.5],[10,0,2],[7,15,1]],5)
sec1=scl2d(sec,.7)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line({sec},.1);
color("magenta")p_line({sec1},.1);

''')
t1=time.time()
t1-t0
```

```
Out[8]: 0.007774829864501953
```



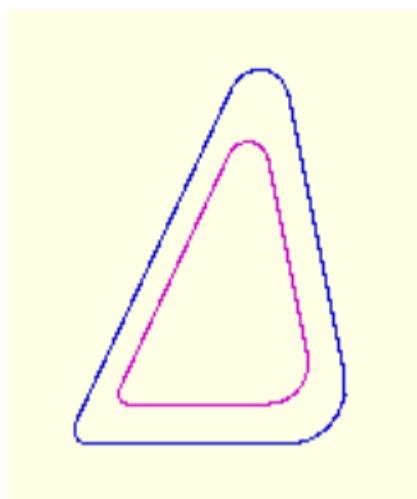
scl2d_c(sec,sl)

```
In [9]: # example of function scl2d_c(sec,sl)
t0=time.time()
sec=corner_radius([[0,0,.5],[10,0,2],[7,15,1]],5)
sec1=scl2d_c(sec,.7)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line({sec},.1);
color("magenta")p_line({sec1},.1);

''')
t1=time.time()
t1-t0
```

```
Out[9]: 0.007291078567504883
```



scl3d(p,s)

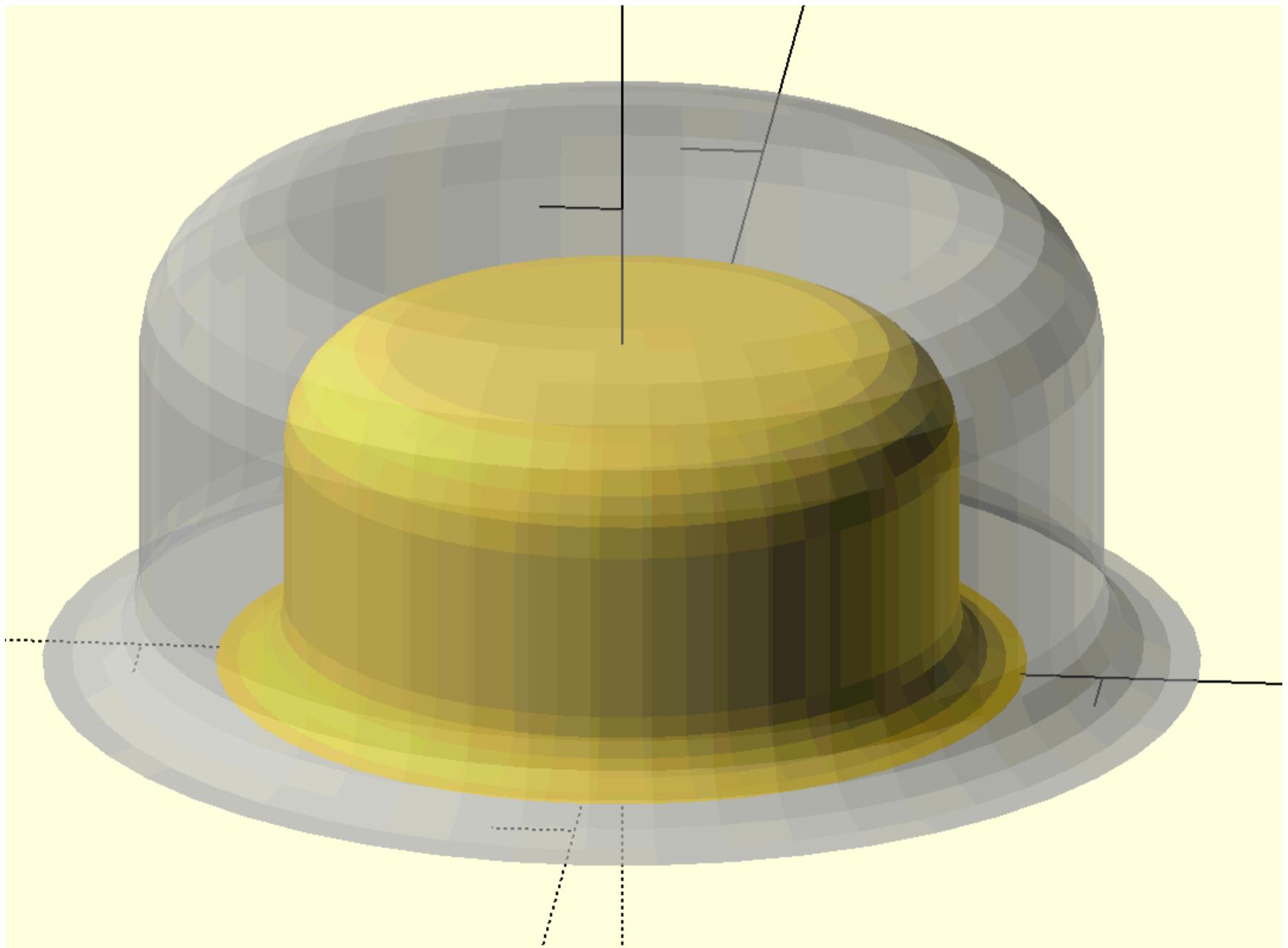
```
In [10]: # example of function scl3d(p,s)
t0=time.time()
sec=circle(10);
path=corner_radius(pts1([[2,0],[-2,0,2],[0,10,3],[-3,0]]),5)
sol=prism(sec,path)
sol1=scl3d(sol,.5)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
%{swp(sol)}
{swp(sol1)}

''')

t1=time.time()
t1-t0
```

Out[10]: 0.042694091796875



ip(prism,prism1)

```
In [11]: # example of function ip(prism,prism1)
t0=time.time()

sec=circle(10)
path=corner_radius(pts1([[2,0],[-2,0,2],[0,10,3],[-9.9,0]]),5)
p_0=prism(sec,path)
p_1=cylinder(r=3,h=15,s=30)
```

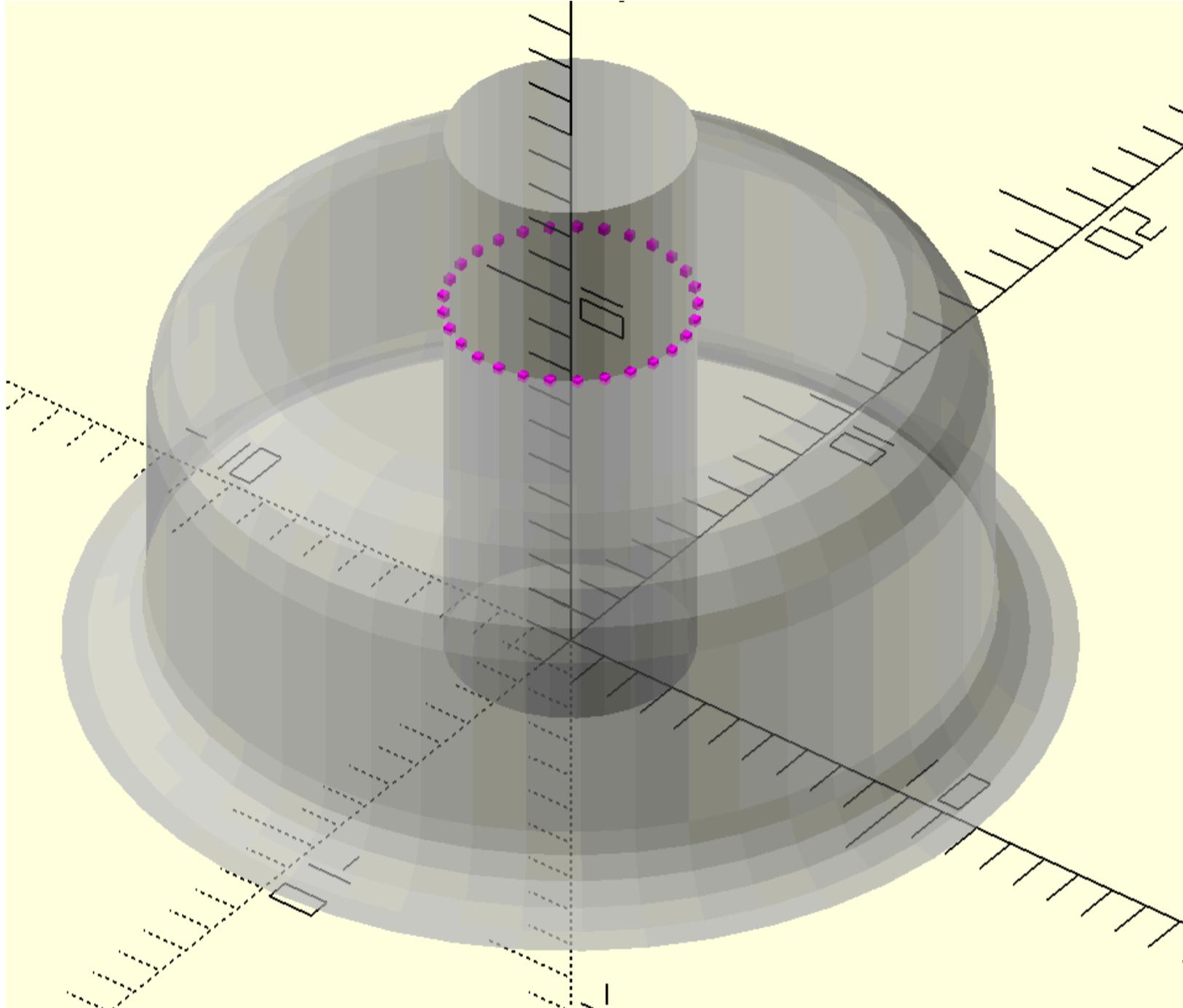
```

ip_1=ip(p_0,p_1)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
%{swp(p_0)}
%{swp(p_1)}
color("magenta")points({ip_1},.2);
//color("blue")for(p={cpo(p_0)})p_line3d(p,.05);
//color("blue")for(p={cpo(p_1)})p_line3d(p,.05);
''')
t1=time.time()
t1-t0

```

Out[11]: 0.05441617965698242



In [12]: t0=time.time()

```

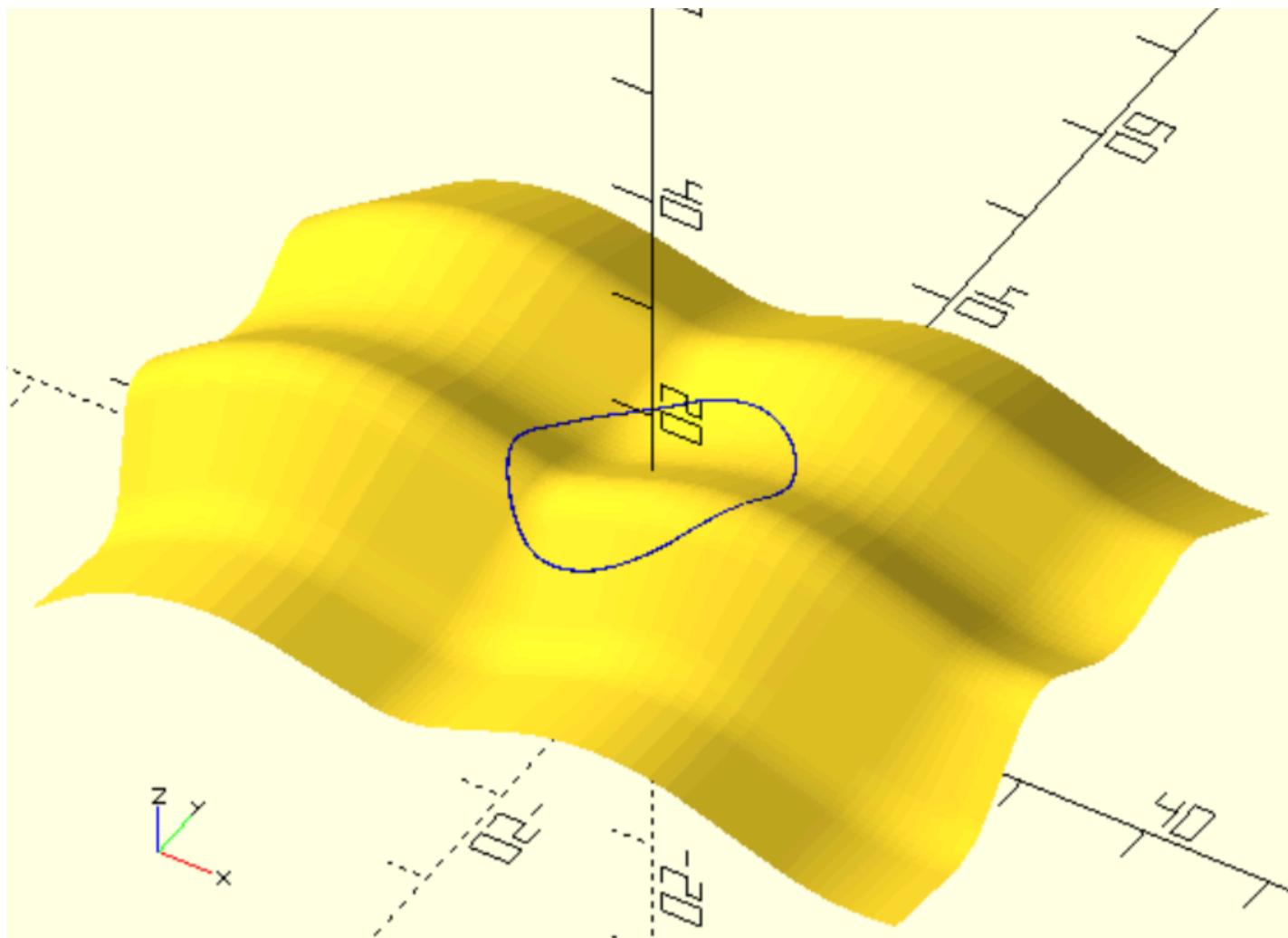
sec2=corner_radius(pts1([[-25,0],[10,5,5],[10,-3,10],[10,5,5],[10,-8,7],[10,1]]),10)
path2=cytz(corner_radius(pts1([[-35,5,0],[10,8,20],[20,-5,10],[20,8,20],[10,-9,20],[10,1,0]]),10))
surf2=surf_extrude(sec2,path2)
sol1=linear_extrude(circle(10),30)
# sol1=slice_sol(sol1,10)
i_p1=ip_surf(surf2,sol1)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("blue")p_line3dc({i_p1},.2);
{swp_surf(surf2)}
''')
t1=time.time()
total=t1-t0
total

```

Out[12]: 0.2083909511566162



tctp(r1,r2,cp1,cp2)

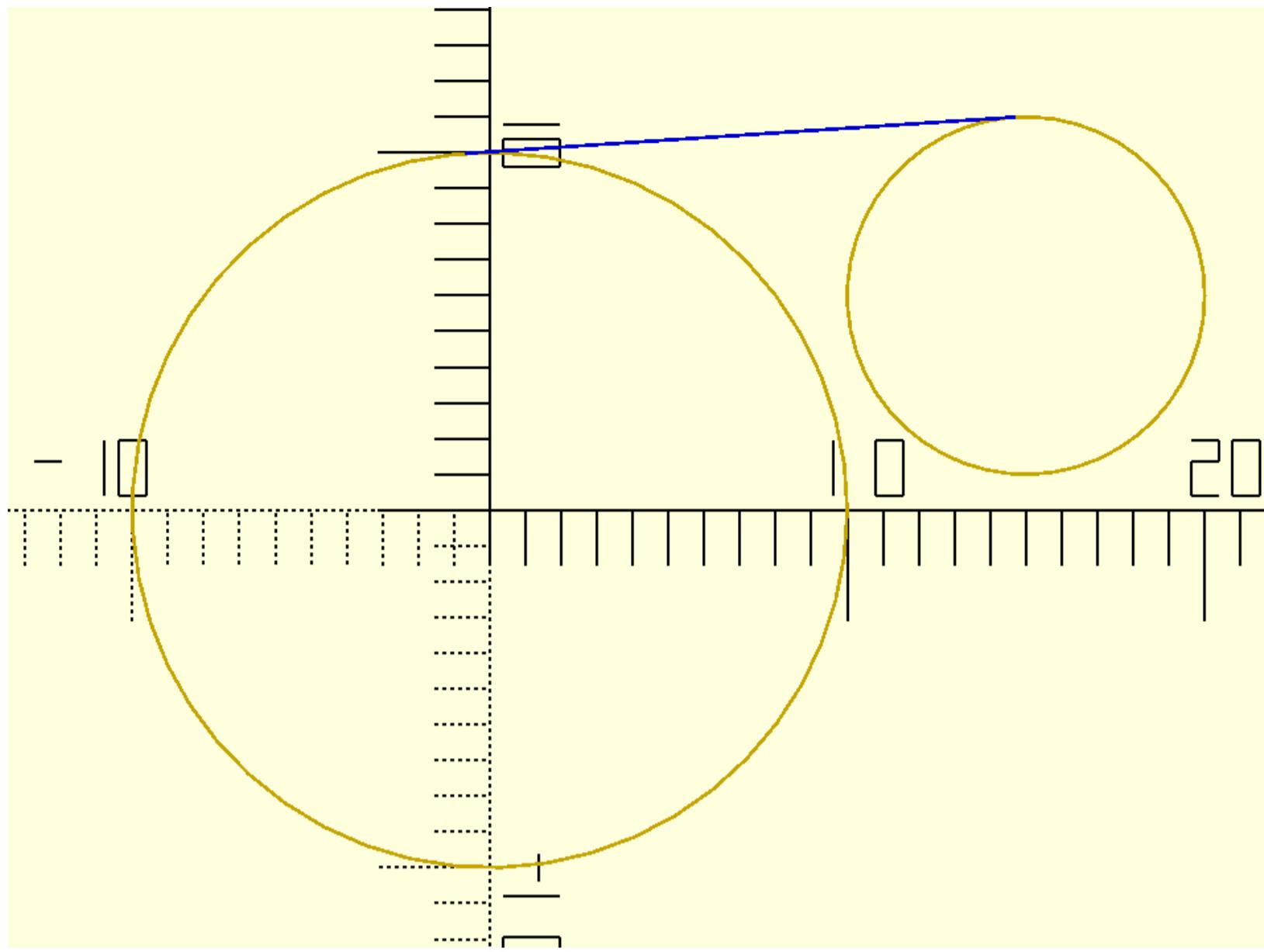
```
In [13]: # example of function tctp(r1,r2,cp1,cp2)
t0=time.time()
cir1=circle(10)
cir2=circle(5,[15,6])
sec=tctp(r1=10,r2=5,cp1=[0,0],cp2=[15,6]);

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
p_line({cir1},.1);
p_line({cir2},.1);

color("blue")p_line({sec},.1);
color("magenta")points({[sec[1]]},.5);

''')
t1=time.time()
t1-t0
```

Out[13]: 0.005353212356567383



tctpf(r1,r2,cp1,cp2)

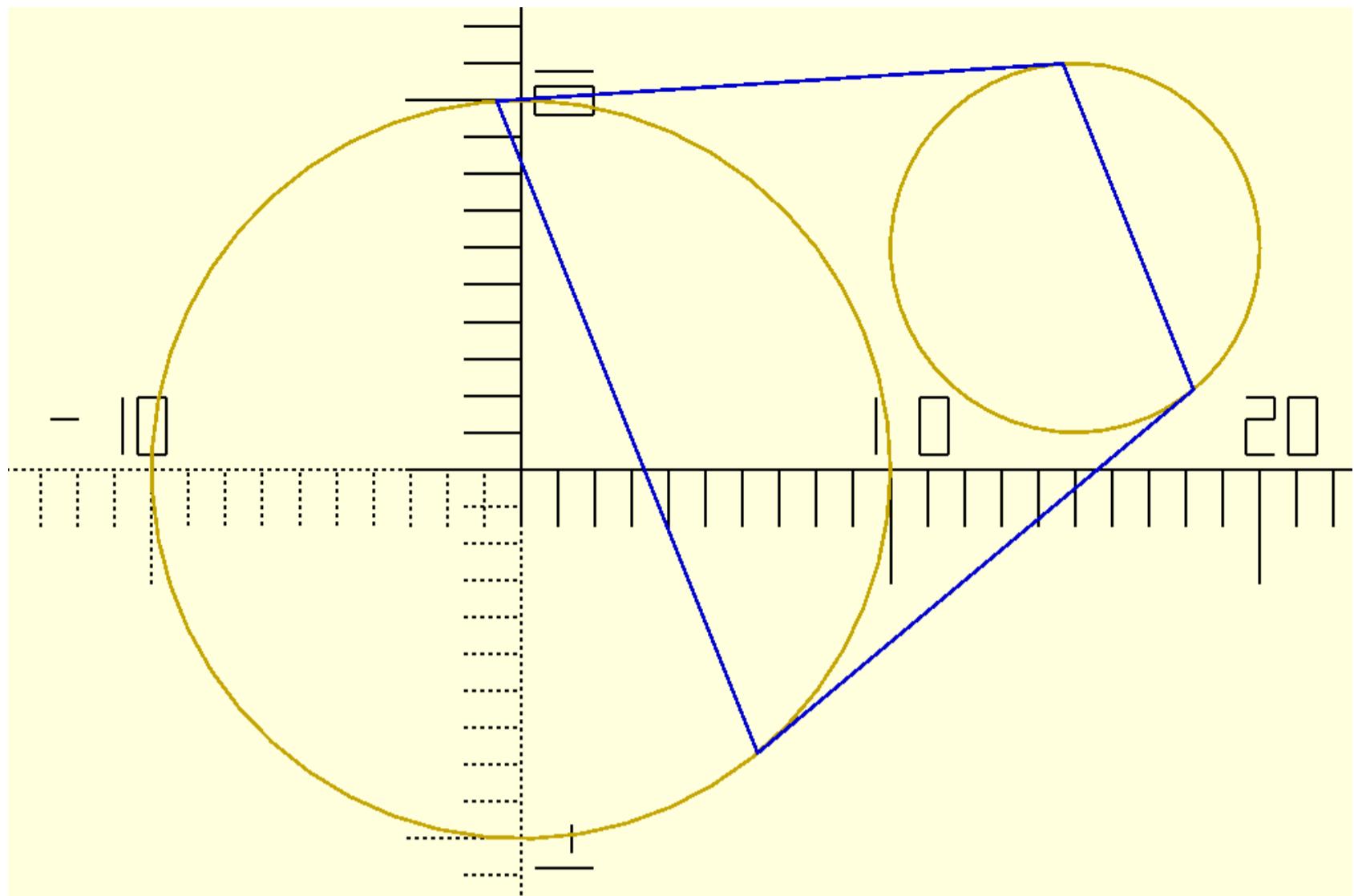
```
In [14]: # example of function tctpf(r1,r2,cp1,cp2)
t0=time.time()

cir1=circle(10)
cir2=circle(5,[15,6])
sec=tctpf(r1=5,r2=10,cp1=[15,6],cp2=[0,0])

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
p_line({{cir1}},.1);
p_line({{cir2}},.1);
color("blue")p_line({{sec}},.1);

''')
t1=time.time()
t1-t0
```

Out[14]: 0.003968954086303711



multiple_sec_extrude

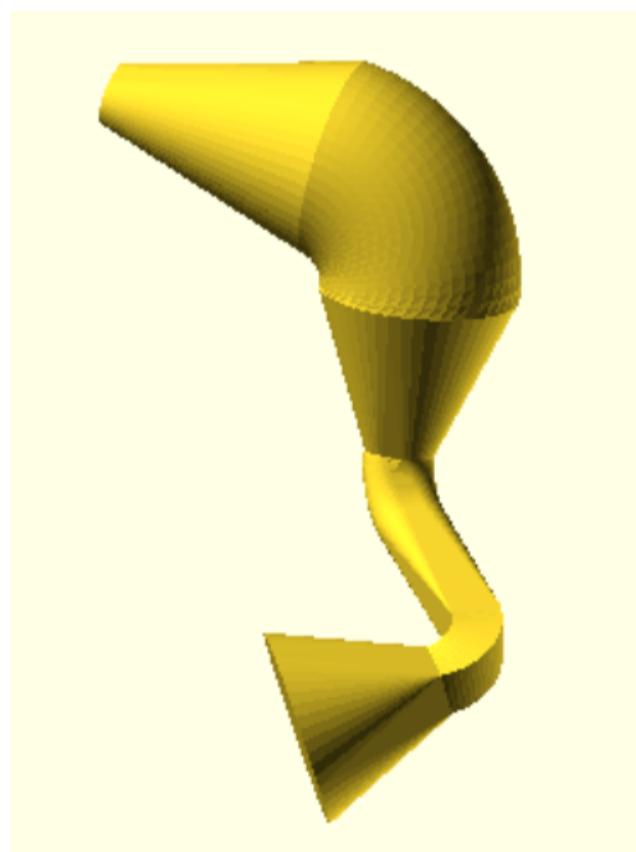
```
In [15]: # example of function multiple_sec_extrude(path_points=[],radiuses_list=[],sections_list=[],option=0,s=10)
t0=time.time()

sec1=circle(10)
sec2=square(5,True)
sec3=corner_radius(pts1([[-3.5,-2.5,2.49],[7,0,2.49],[0,5,2.49],[-7,0,2.49]]))
sections=[sec1,sec2,sec3,sec1,sec3]
path=array([[0,0,0],[20,2,5],[-7,25,3],[5,10,30],[-30,15,3]]).cumsum(0)
r=[0,5,7,12,0]

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
//color("blue")for(p={multiple_sec_extrude(path,r,sections,0,20)})p_line3dc(p,.1);
{swp(multiple_sec_extrude(path,r,sections,0,20))}

    ''')
t1=time.time()
t1-t0
```

Out[15]: 0.4314429759979248



path_extrude_open(sec,path)

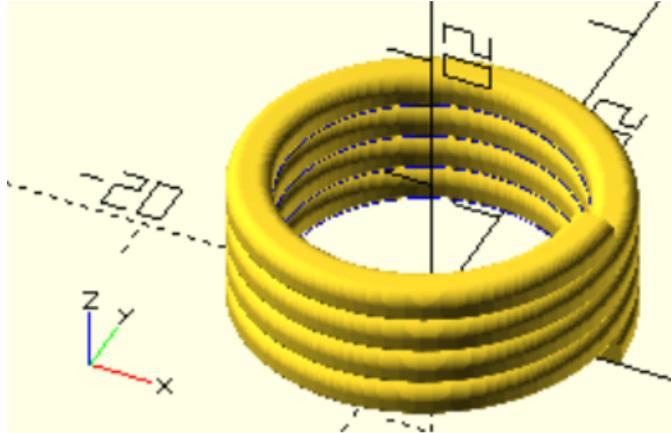
```
In [16]: # example of function path_extrude_open(sec,path)
t0=time.time()
```

```

sec=corner_radius(pts1([[0,0,.2],[3,0,.2],[0,2,1],[-3,0,1]]),10)
path=helix(10,2.5,4,5.01)
sol=path_extrude_open(sec,path)
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
{swp(sol)}
color("blue")p_line3d({path},.1);
    ''')
t1=time.time()
t1-t0

```

Out[16]: 0.1356360912322998



path_extrude_closed(sec,path)

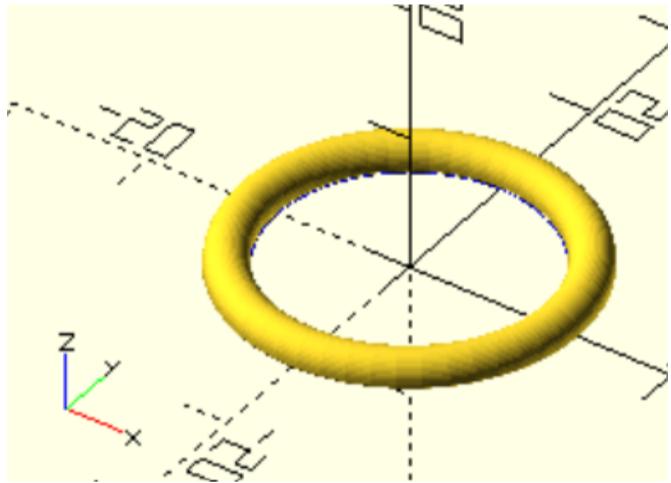
```

In [17]: # example of function path_extrude_closed(sec,path)
t0=time.time()
sec=corner_radius(pts1([[0,0,.2],[3,0,.2],[0,2,1.49],[-3,0,1.49]]),10)
path=c2t3(circle(10))
sol=path_extrude_closed(sec,path)
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
{swp_c(sol)}
color("blue")p_line3d({path},.1);
    ''')

t1=time.time()
t1-t0

```

Out[17]: 0.04159402847290039



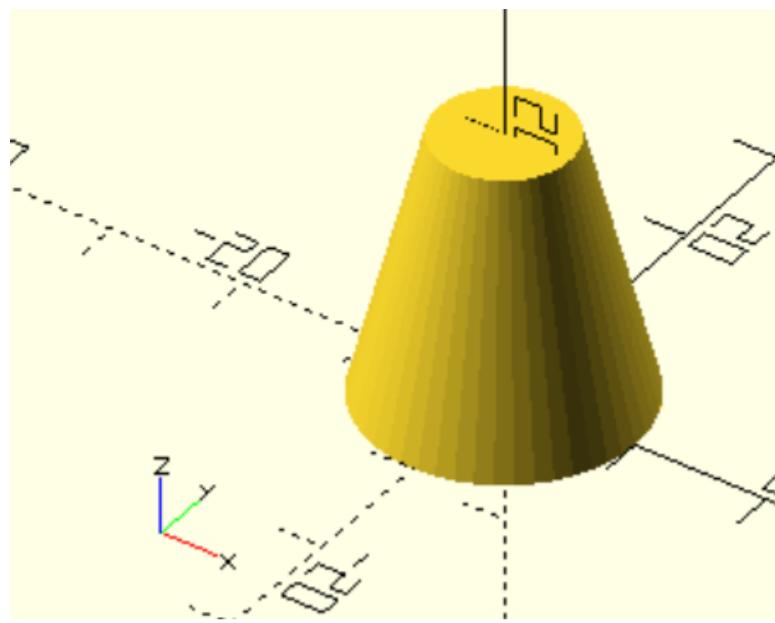
cylinder

```

In [18]: # example of function cylinder(r1=1, r2=1, h=1, s=50, r=0, d=0, d1=0, d2=0, center=False) and function swp
t0=time.time()
sol=cylinder(r1=10,r2=5,h=20)
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
{swp(sol)}
    ''')
t1=time.time()
t1-t0

```

Out[18]: 0.005438089370727539

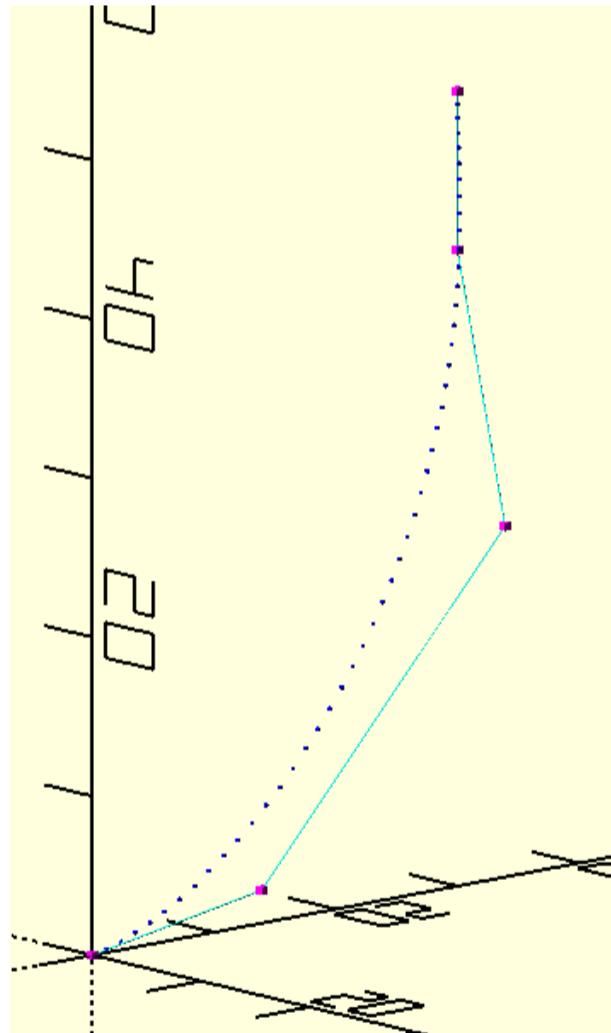


bezier(p,s=10)

```
In [19]: # example of function bezier(p,s=10)
t0=time.time()
control_points=array([[0,0,0],[10,5,5],[-10,10,20],[-10,5,15],[10,0,10]]).cumsum(0).tolist()
curve=bezier(control_points,50)

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line3d({curve},.1);
// control points
color("magenta")points({control_points},.5);
color("cyan")p_line3d({control_points},.05);
    ''')
t1=time.time()
t1-t0
```

Out[19]: 0.010961055755615234



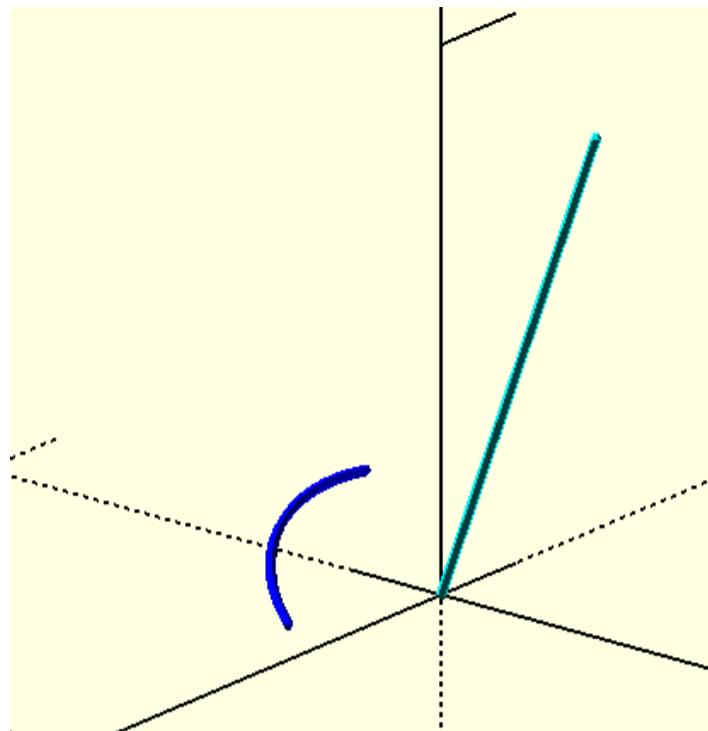
arc_3d

```
In [20]: # example of function arc_3d(v=[0,0,1],r=1,theta1=0,theta2=360,cw=-1,s=50)
t0=time.time()
vector=[[0,0,0],[1,0,1]]
arc1=arc_3d(v=[1,0,1],r=3,theta1=0,theta2=270,cw=-1,s=50)

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
//arc
color("blue")p_line3d({arc1},.1);
// vector
color("cyan")p_line3d({vector},.1);

    ''')
t1=time.time()
t1-t0
```

Out[20]: 0.012104034423828125



plane

```
In [21]: # example of function plane(nv, radius)
t0=time.time()
vector=[[0,0,0],[-3,0,2]]
plane1=plane(nv=[-3,0,2],size=[10,10])

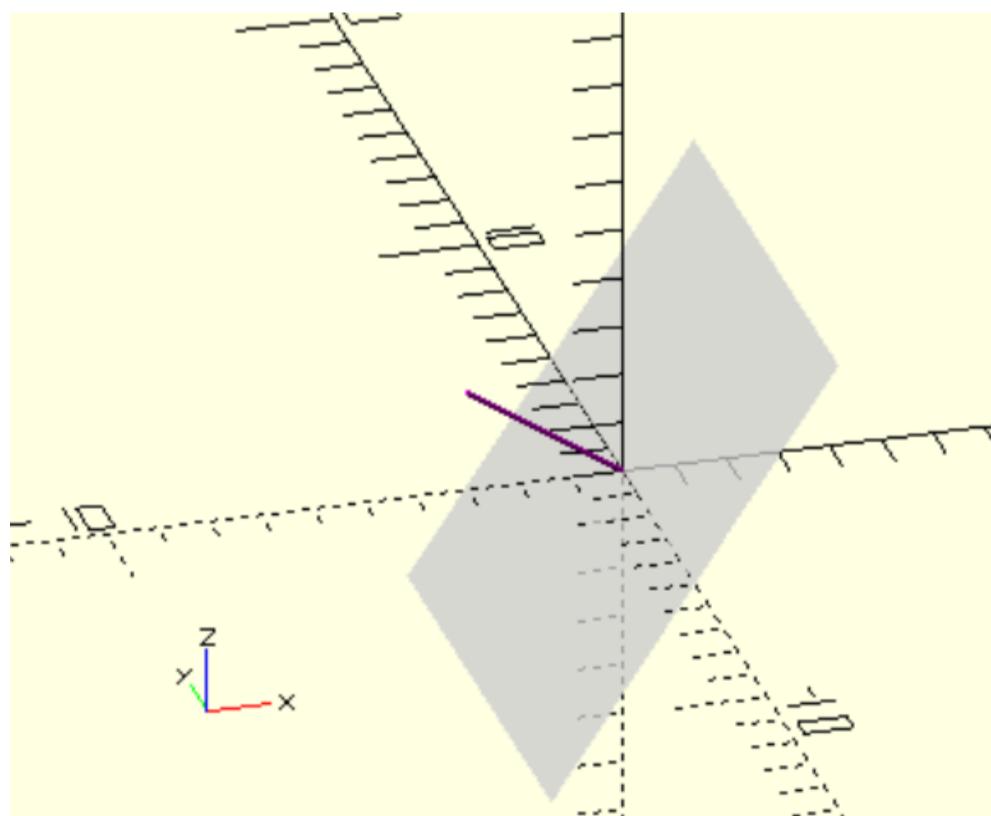
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

//plane
%{swp(plane1)}

// vector
color("magenta")p_line3d({vector},.1);

    ''')
t1=time.time()
t1-t0
```

Out[21]: 0.0031709671020507812



c_hull

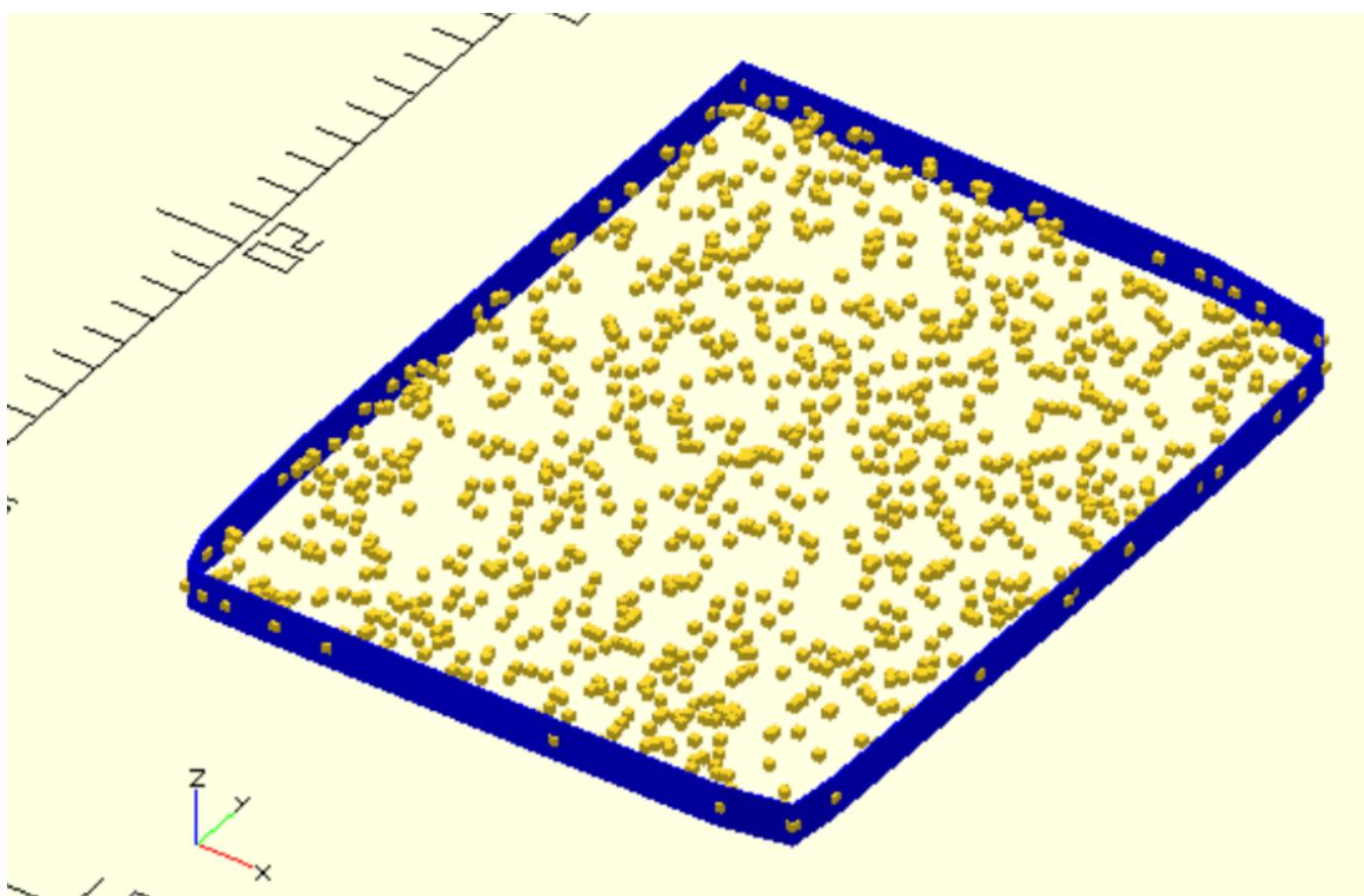
```
In [22]: # example of function c_hull(pnt)
t0=time.time()
a=random.random(1000)*(20-5)+5
b=random.random(1000)*(30-10)+10
points=array([a,b]).transpose(1,0).tolist()
sec=c_hull(points)
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

points({points},.2);
color("blue")p_line({sec},.05);

    ''')
```

```
t1=time.time()
t1-t0
```

Out[22]: 0.04491710662841797



convex

```
# example of function convex(sec)
t0=time.time()
sec1=corner_radius(pts1([[0,0,.2],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)
sec2=corner_radius(pts1([[0,0,1],[7,5,2],[5,7,3],[-5,7,2],[-7,5,3]]),20)

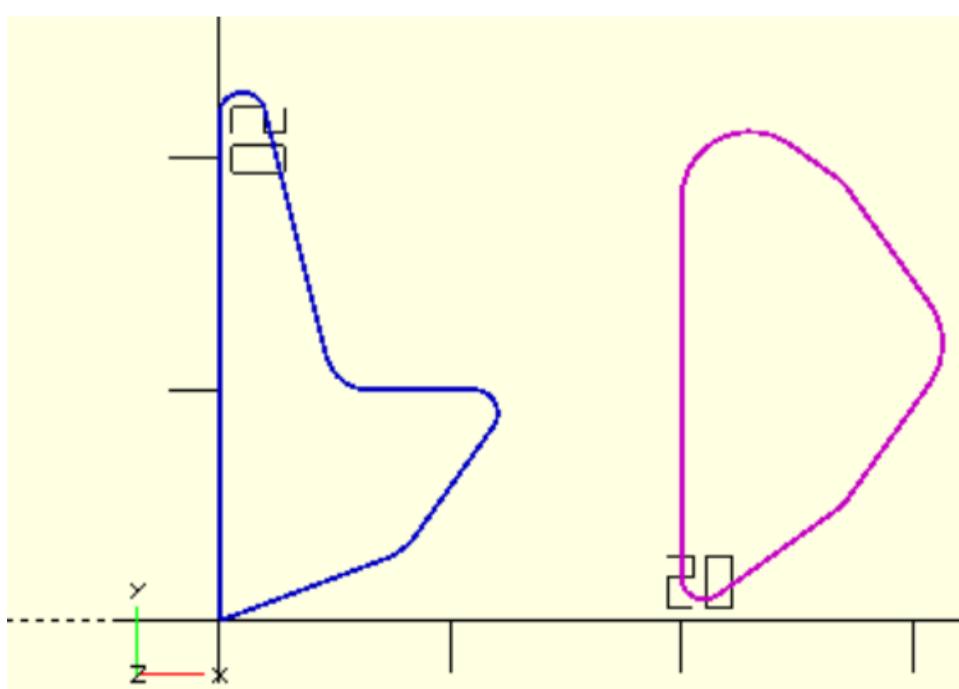
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

// not a convex section
color("blue")p_line({sec1},.2);

//convex section
color("magenta")translate([20,0,0])p_line({sec2},.2);

    ''')
t1=time.time()
convex(sec1,convex(sec2),t1-t0)
```

Out[23]: (False, True, 0.01895594596862793)



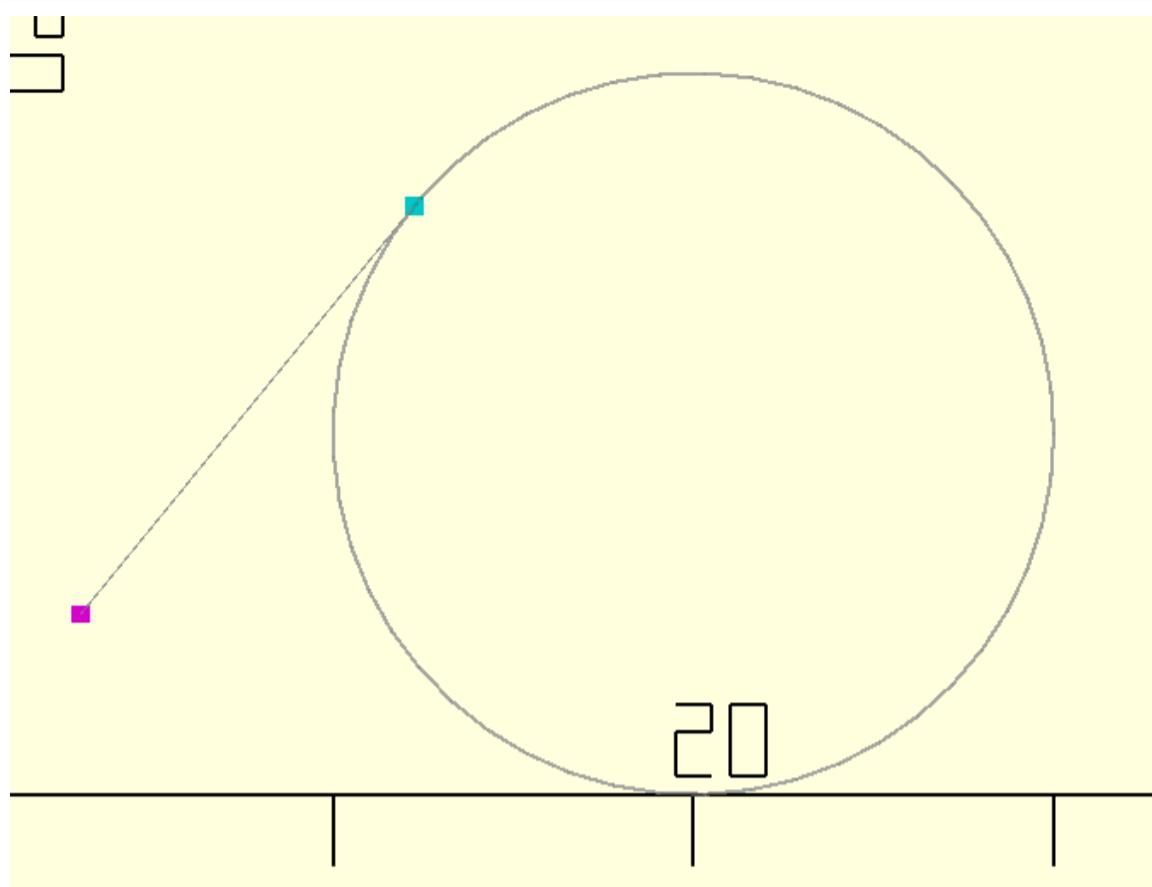
cir_p_t

```
# example of function cir_p_t(cir,pnt)
cir=c3t2(translate([20,10,0],circle(10)))
point=[1,30]
tangent_point=cir_p_t(cir,point)
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
// "cyan" is the tangent point from circle to some external point ("magenta color")
%p_line({cir},.1);
color("magenta")points({[point]},.5);
```

```

color("cyan")points({[tangent_point]},.5);
//color("blue")
%p_line({[point,tangent_point]},.05);
  ''')

```



concave_hull

```

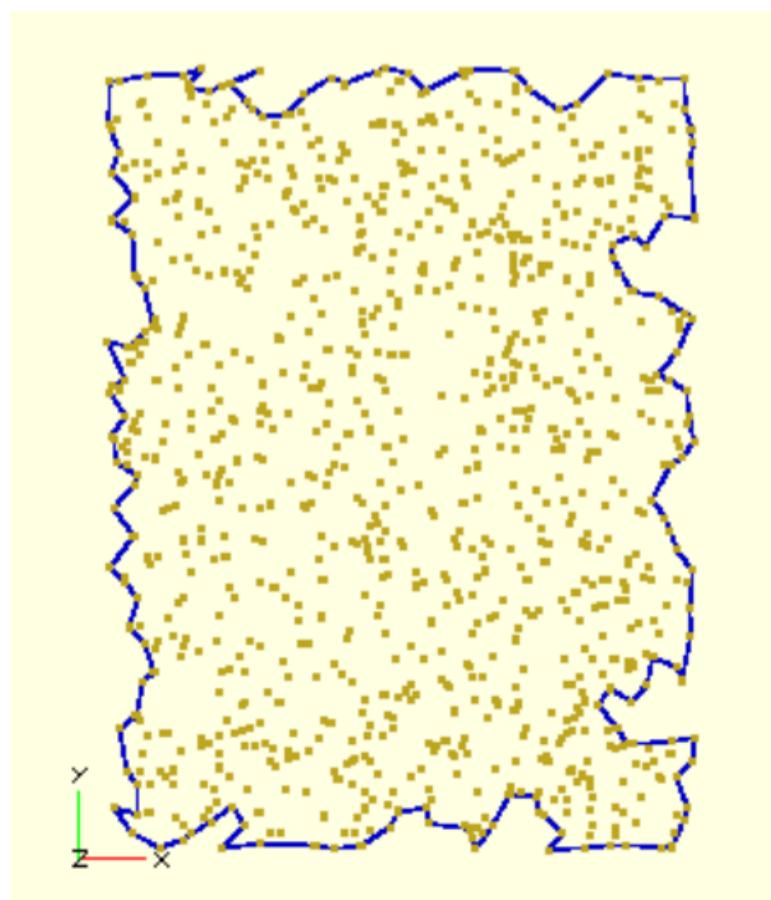
In [26]: # example of function concave_hull(pnts,x=1,loops=10)
t0=time.time()
a=random.random(1000)*(20-5)+5
b=random.random(1000)*(30-10)+10
points=remove_extra_points(array([a,b]).transpose(1,0))
conc_hull=concave_hull(points,3)
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

points({points},.2);
color("blue")p_line3d({conc_hull},.1,1);

  ''')
t1=time.time()
t1-t0

```

Out[26]: 1.3126389980316162



```

In [27]: # example of piesl(sec,pnts) and concave_hull
t0=time.time()

```

```

a=random.random(10000)*(10-0)+0
b=random.random(10000)*(20-0)+0
c=array([a,b]).transpose(1,0).tolist()

sec=corner_radius(pts1([[1.5,8,.9],[2,0,.9],[0,-3,1.4],[3,0,1.4],[0,4,1.9],[-5,0,2.5],[0,6,2.5],
[7,0,2.5],[0,-4,.9],[-2,0,.9],[0,3,1.4],[-3,0,1.4],[0,-4,1.9],

```

```

[5,0,2.5],[0,-6,2.5],[-7,0,2.5]]),20)

pnts=pies1(sec,c)

s1=concave_hull(pnts,20)

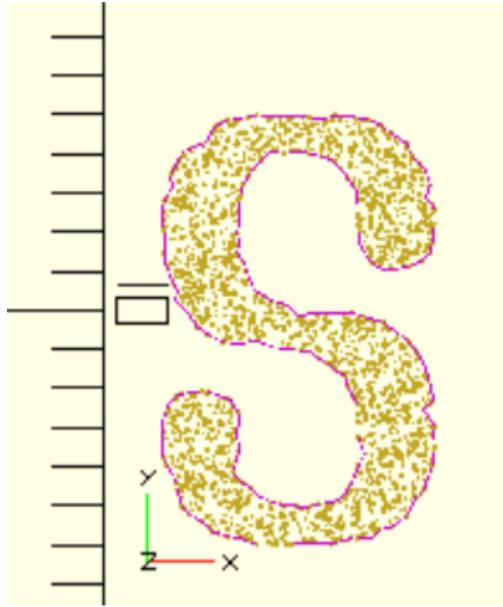
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

points({pnts},.1);
color("magenta")p_line({s1},.05);

'''')
t1=time.time()
t1-t0

```

Out[27]: 2.245518922805786



path_offset

```

In [28]: # example of function path_offset_n(path,d)

path=corner_radius(pts1([[-5,0],[5,0,2],[-1,10,2],[-5,0]]))
path1=path_offset_n(path,-1)
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
// orginal path
color("blue")p_line3d({path},.1,1);
//offset path
color("magenta")p_line3d({path1},.1,1);

'''')

```

```

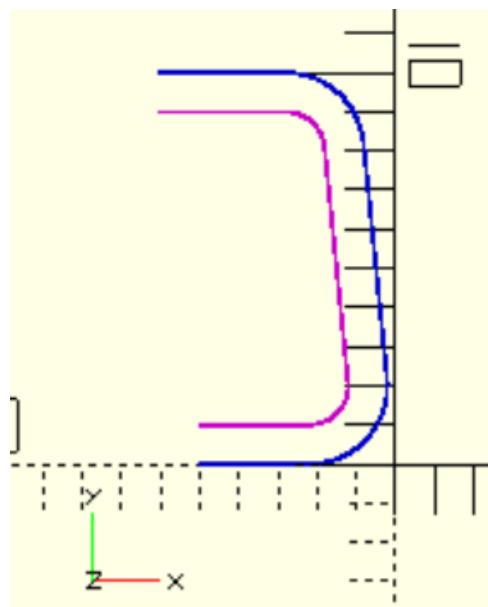
In [29]: # example of function path_offset(path,d)
r=-1
path=corner_radius(pts1([[-5,0],[5,0,2],[-1,10,2],[5,0]]),20)
# path=circle(10)
# path=corner_radius(pts1([[0,0],[10,0,.1],[-10,5,.1],[-10,-5]]),20)

path1=path_offset(path,r)

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
// orginal path
color("blue")p_lineo({path},.1);
//offset path
color("magenta")p_lineo({path1},.1);

'''')

```



pntsfnfaces

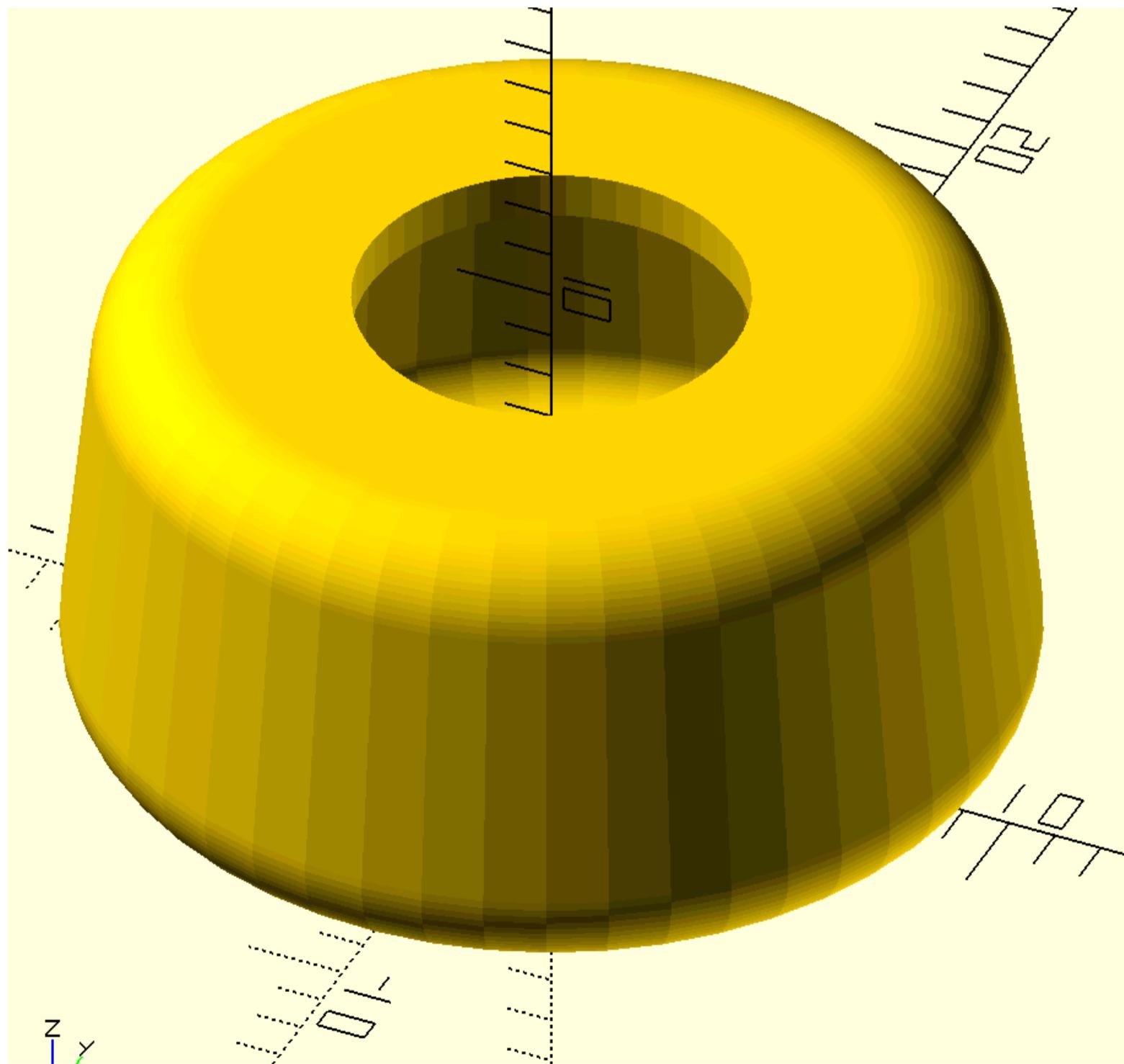
```
In [30]: # example of function pntsfnfaces(bead2)

path=corner_radius(pts1([[-5,0],[5,0,2],[-1,10,2],[-5,0]]))
path1=path_offset(path,-1)
final_path=path+flip(path1)
sec=circle(10)
sol=prism(sec,final_path)

points, faces=pntsfnfaces(sol)[0],pntsfnfaces(sol)[1]

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

polyhedron({points},{faces},convexity=10);
    ''')
```



offset_points

```
In [31]: # example of function offset_points(sec,r)
t0=time.time()
sec=corner_radius(pts1([[0,0,.1],[7,5,2],[5,7,3],[-5,7,2],[-7,5,3]]),20)
```

```

sec1=offset_points(sec,2)

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

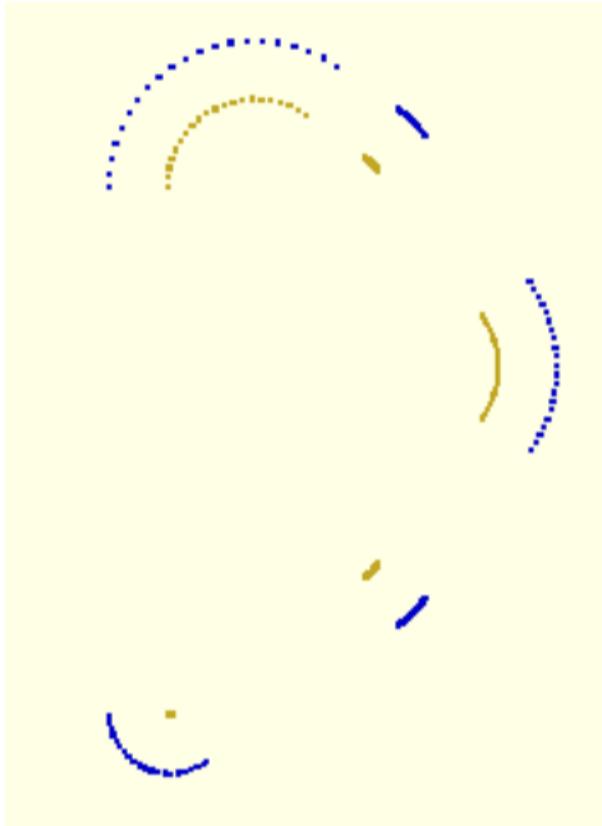
//original points
points({sec},.2);

// offset points
color("blue") points({sec1},.2);

    ''')
t1=time.time()
t1-t0

```

Out[31]: 0.011157035827636719



In []: set_printoptions(suppress=True)

s_int

```

# example of function s_int(s)
t0=time.time()
sec=corner_radius(pts1([[0,0,.1],[7,5,2],[-7,10,2]]),3)
sec1=offset_segv(sec,-1)
self_intersections=s_int(sec1)

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

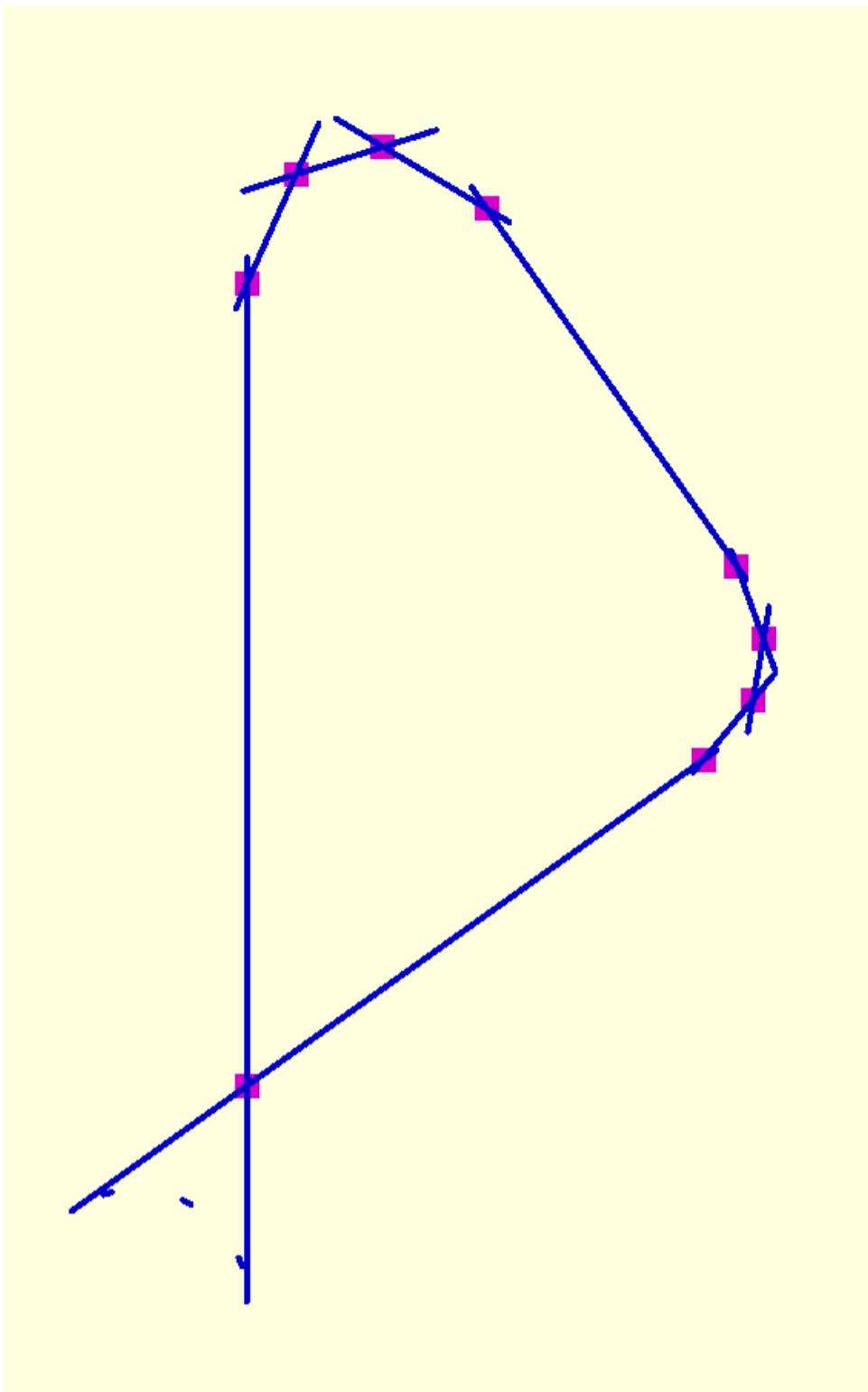
// line segments
color("blue") for (p={sec1}) p_line(p,.05);

// intersection points
color("magenta")points({self_intersections},.2);

    ''')
t1=time.time()
t1-t0

```

Out[32]: 0.012358903884887695



```
In [33]: # example of function s_int(s)
t0=time.time()
sec=corner_radius(pts1([[0,0,2],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),5)
sec=seg(sec)
s=s_int(sec)

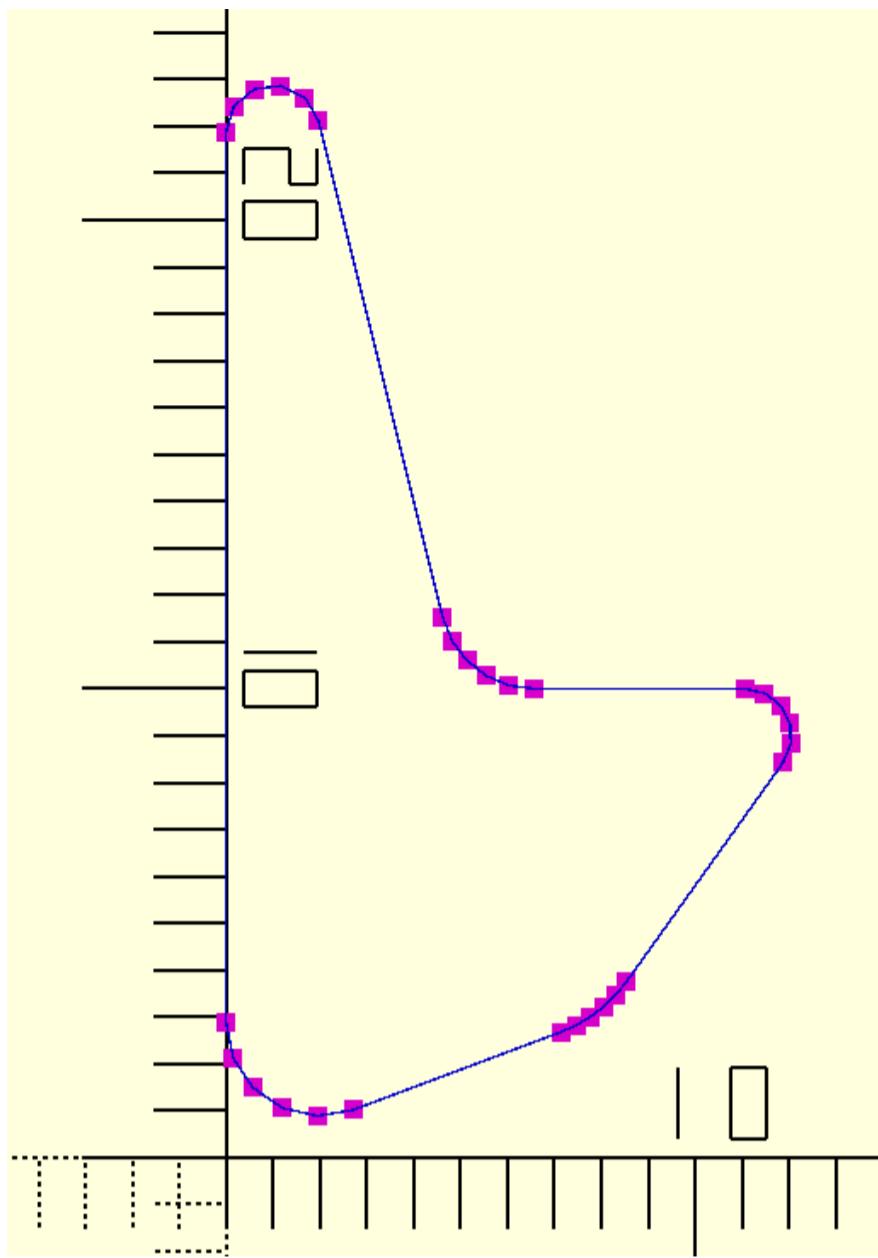
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

// line segments
color("blue") for (p={sec}) p_line(p,.05);

// intersection points
color("magenta")points({s},.4);

    ''')
t1=time.time()
t1-t0
```

Out[33]: 0.020062923431396484



s_int1

```
In [34]: # example of function s_int1(s)
t0=time.time()
sec=offset_segv([[0,0],[10,0],[15,7]],-1)
self_intersections=s_int1(sec)

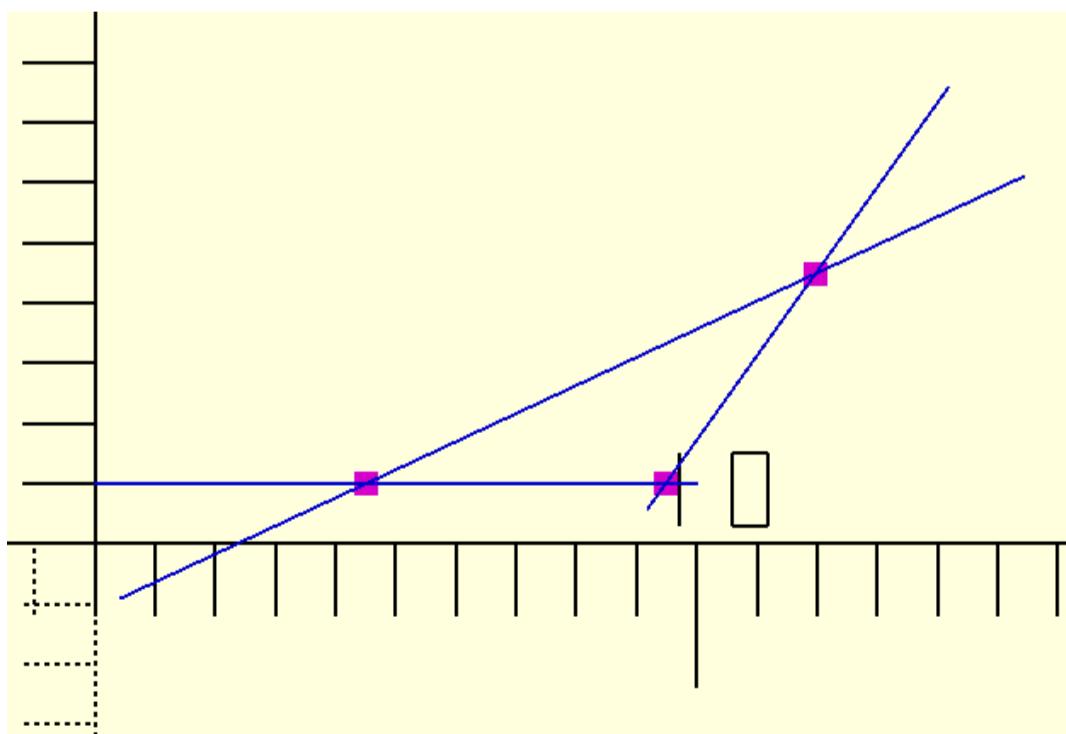
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

// line segments
color("blue") for (p={sec}) p_line(p,.05);

// intersection points
color("magenta")points({self_intersections},.4);

    ''')
t1=time.time()
t1-t0
```

Out[34]: 0.0030450820922851562



offset_seg_cw

```
In [35]: # example of function offset_seg_cw(sec,r)
t0=time.time()
```

```

sec=sec=corner_radius(pts1([[0,0,2],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),5)
sec1=offset_seg_cw(sec,-2)

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

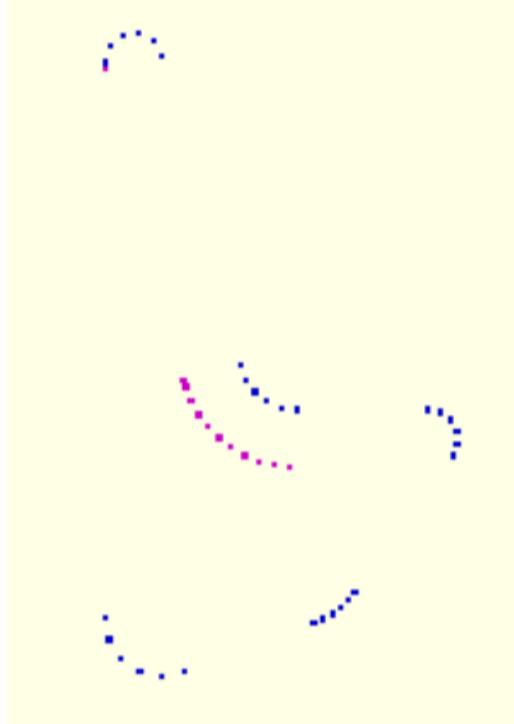
// original section
color("blue") points({sec},.2);

// offset segments
color("magenta")points({sec1},.2);

    ''')
t1=time.time()
t1-t0

```

Out[35]: 0.011030912399291992



offset_segv

```

In [36]: # example of function offset_segv(sec,r)
t0=time.time()
sec=sec=corner_radius(pts1([[0,0,2],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),5)
sec1=offset_segv(sec,-1)

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

// original section
color("blue") points({sec},.2);

// offset segments
color("magenta")for(p={sec1})points(p,.2);

    ''')
t1=time.time()
t1-t0

```

Out[36]: 0.008993864059448242

```

In [37]: # example of another method to offset segment where points are clockwise and example function cwv(sec)
t0=time.time()
sec=corner_radius(pts1([[0,0,2],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),5)
sec0=seg(sec)
decision=cwv(sec)
sec1=[path_offset(sec0[i],-2) for i in range(len(sec0)) if decision[i]==1]

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

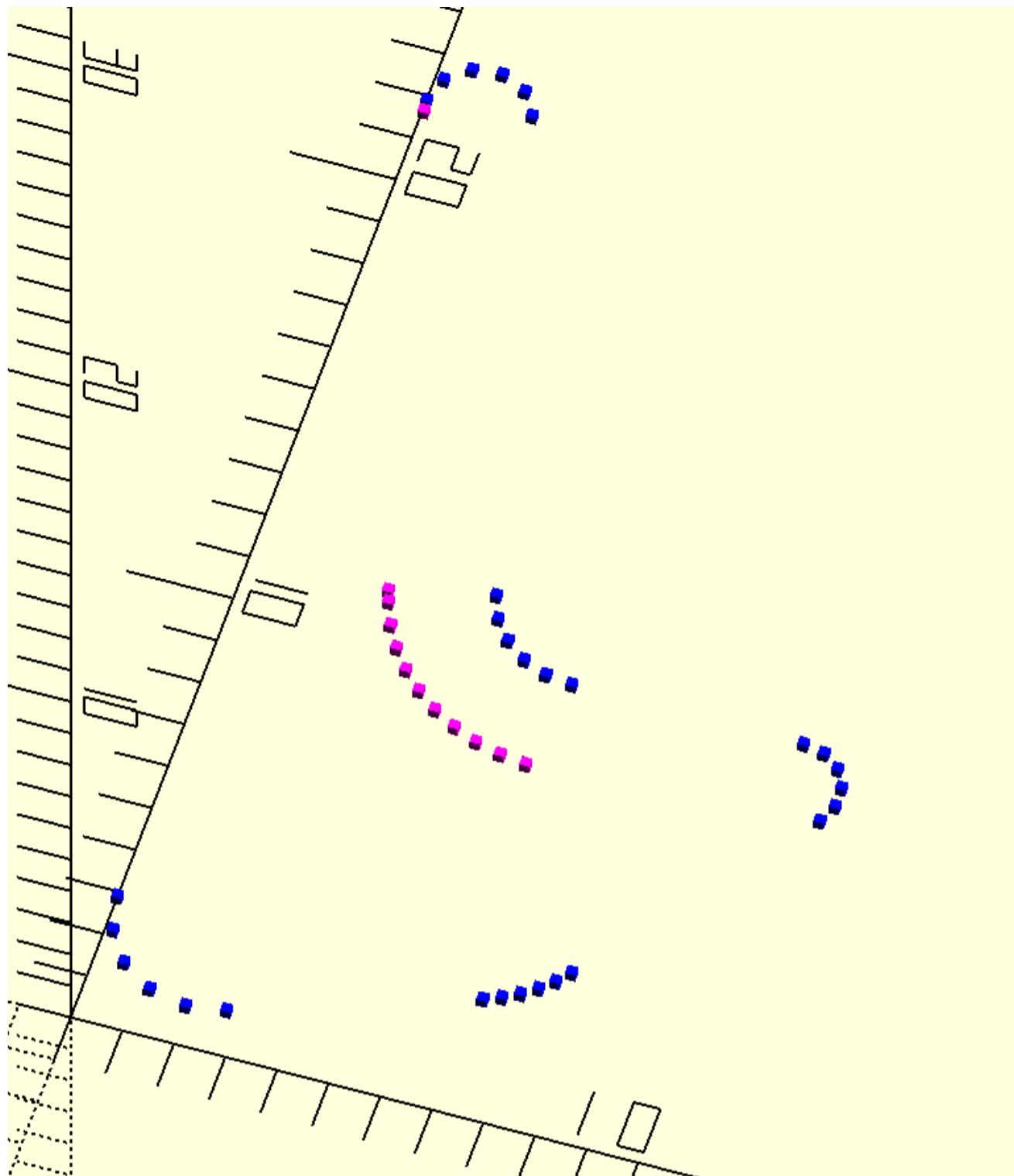
// original section
color("blue") points({sec},.2);

// offset segments
color("magenta")for(p={sec1})points(p,.2);

    ''')
t1=time.time()
t1-t0

```

Out[37]: 0.019224882125854492



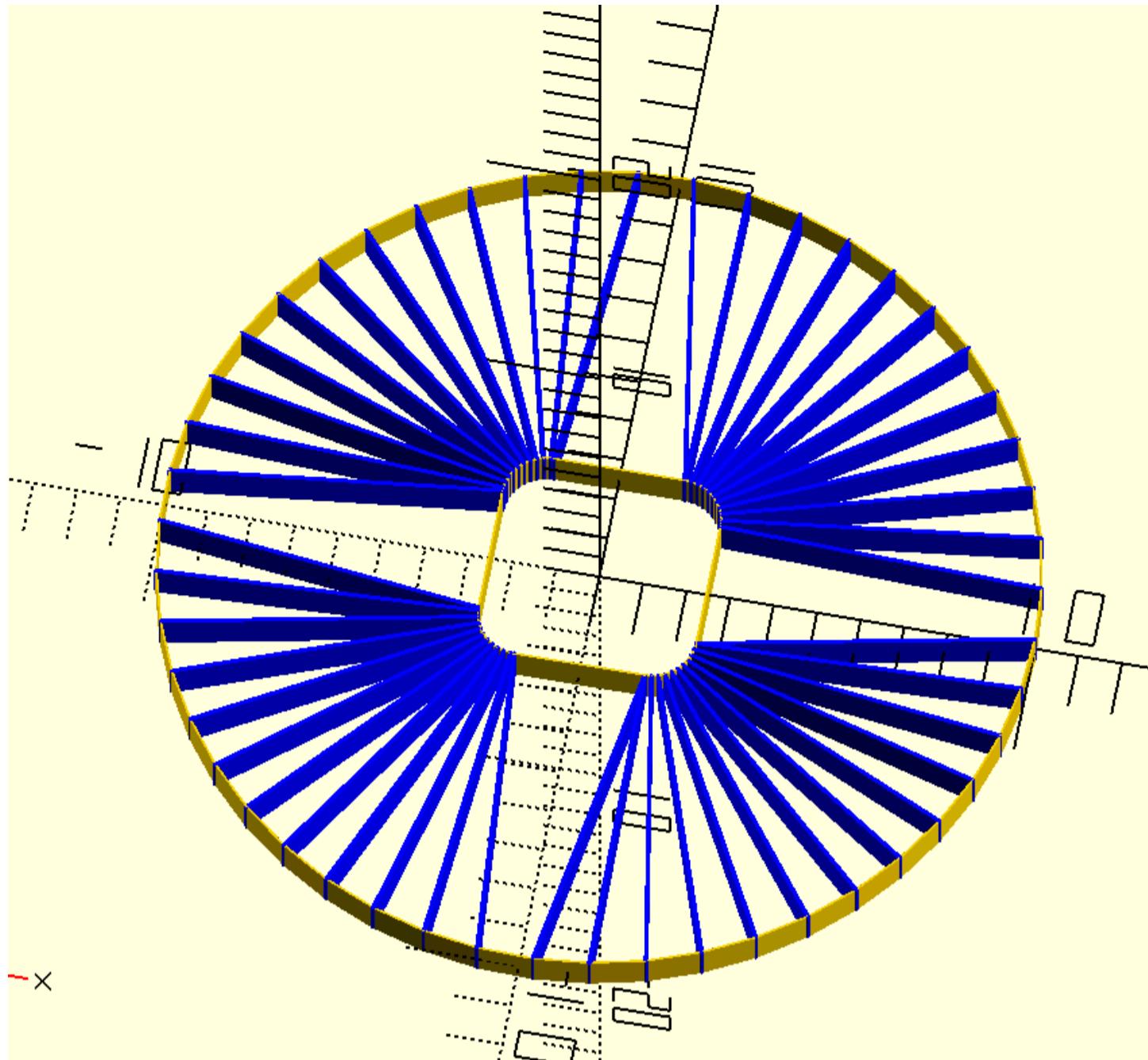
sort_points

```
In [38]: # example of function sort_points(sec,sec1)
t0=time.time()
sec=circle(10)
sec1=corner_radius(pts1([[-2.5,-2.5,1],[5,0,1],[0,5,1],[-5,0,1]]))
sec2=sort_points(sec,sec1)
sec3=cpo([sec2,sec])
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

p_line({{sec}},{.05});
p_line({{sec2}},{.05});
color("blue") for(p={{sec3}})p_line(p,{.1});

    ''')
t1=time.time()
t1-t0
```

Out[38]: 0.011690855026245117



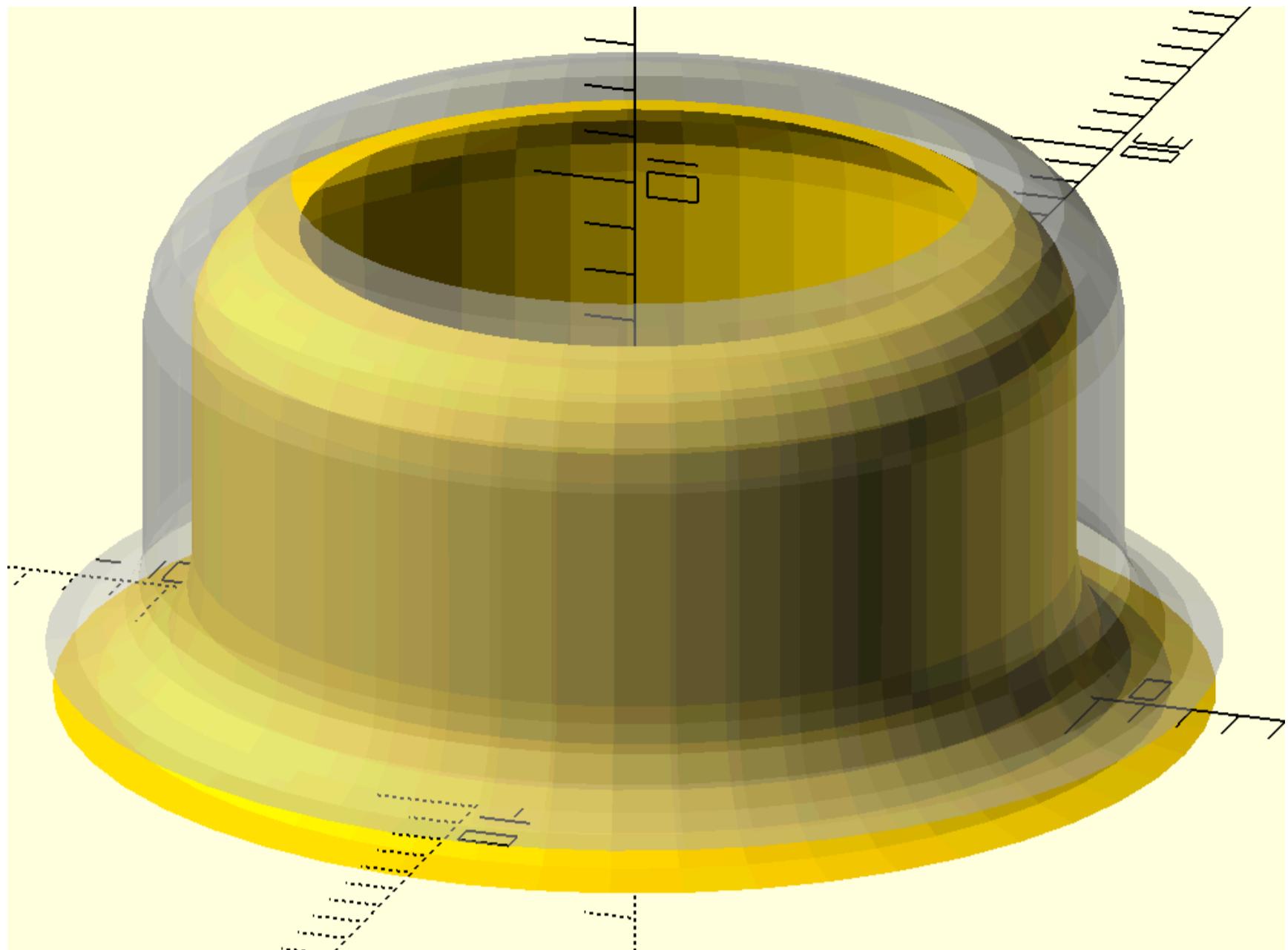
surf_offset

surface_offset:

Although surface_offset is more accurate function, it takes much longer to calculate the offset as compared to surf_offset

In [39]: # example of function surf_offset(surf,o)

```
sec=circle(10);
path=corner_radius(pts1([[2,0],[-2,0,2],[0,10,3],[-3,0]]),5)
sol=f_prism(sec,path)
sol1=surf_offset(sol,-1)
sol1=surface_offset(sol,1)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
%{swp_c(sol)}
{swp_c(sol1)}
''' )
```

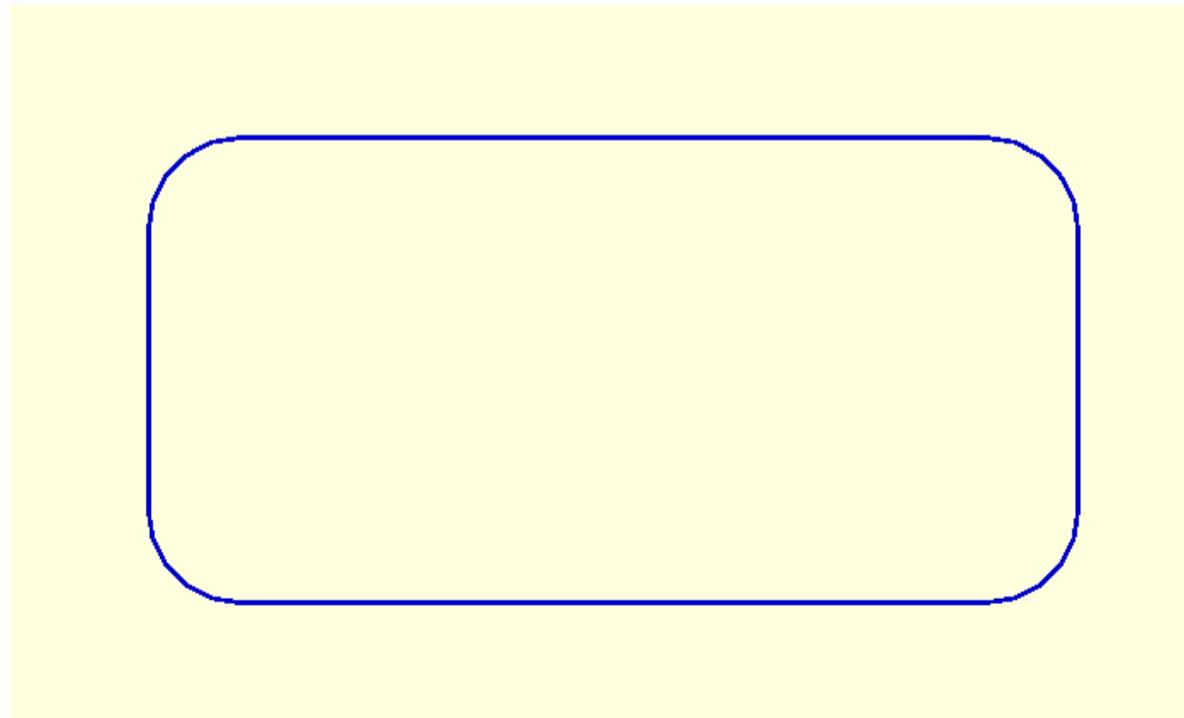


pts1

```
In [40]: # example of function pts1(p)
sec=corner_radius(pts1([[0,0,1],[10,0,1],[0,5,1],[-10,0,1]]),5)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line({sec},.05);

...)
```



arc_2p

```
In [41]: # example of function arc_2p(p1,p2,r,cw=1,s=20)

p1=[2,0]
p2=[0,2]
arc1=arc_2p(p1,p2,2,1,20)
arc2=arc_2p(p1,p2,2,-1,20)

with open('trial.scad','w+') as f:
```

```

f.write(f'''
include<dependencies2.scad>

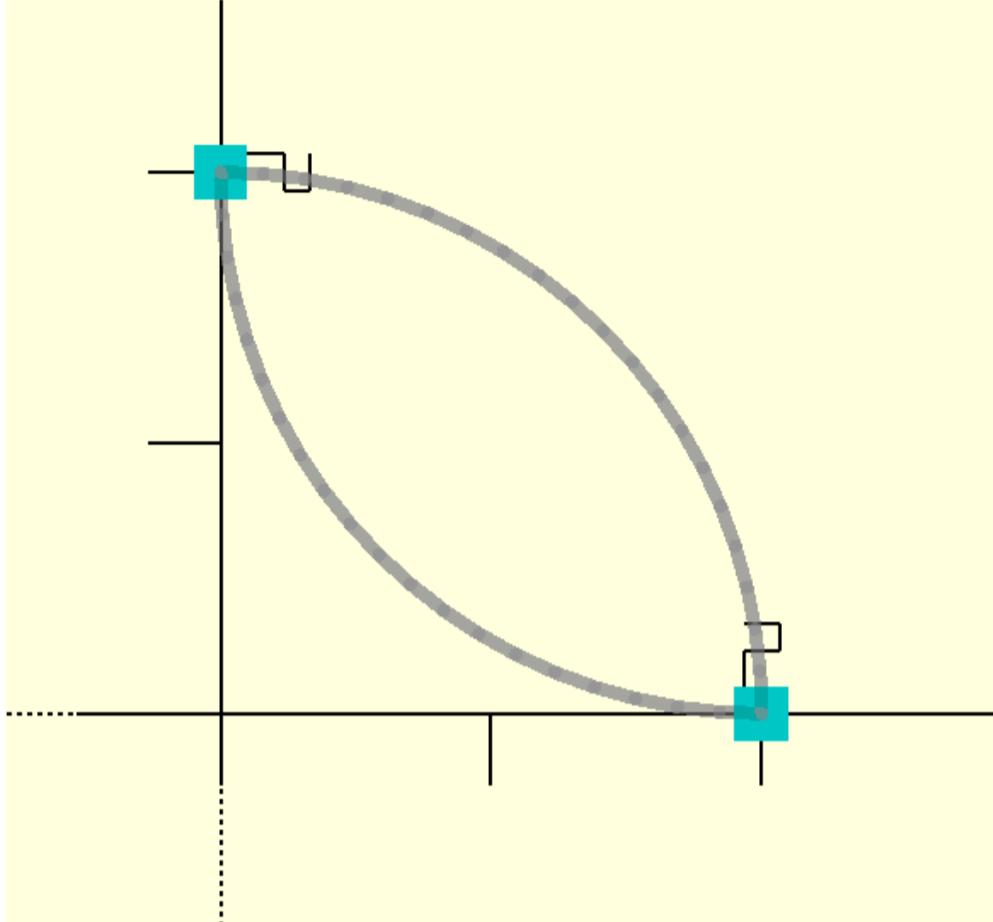
// arc clockwise
//color("blue")
%p_lineo({arc1},.05);

// arc counter clockwise
//color("magenta")
%p_lineo({arc2},.05);

color("cyan")points({[p1,p2]},.2);

''' )

```



arc_long_2p

```

In [42]: # example of function arc_long_2p(p1,p2,r,cw=1,s=20)

p1=[2,0]
p2=[0,2]
arc1=arc_long_2p(p1,p2,2,1,20)
arc2=arc_long_2p(p1,p2,2,-1,20)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

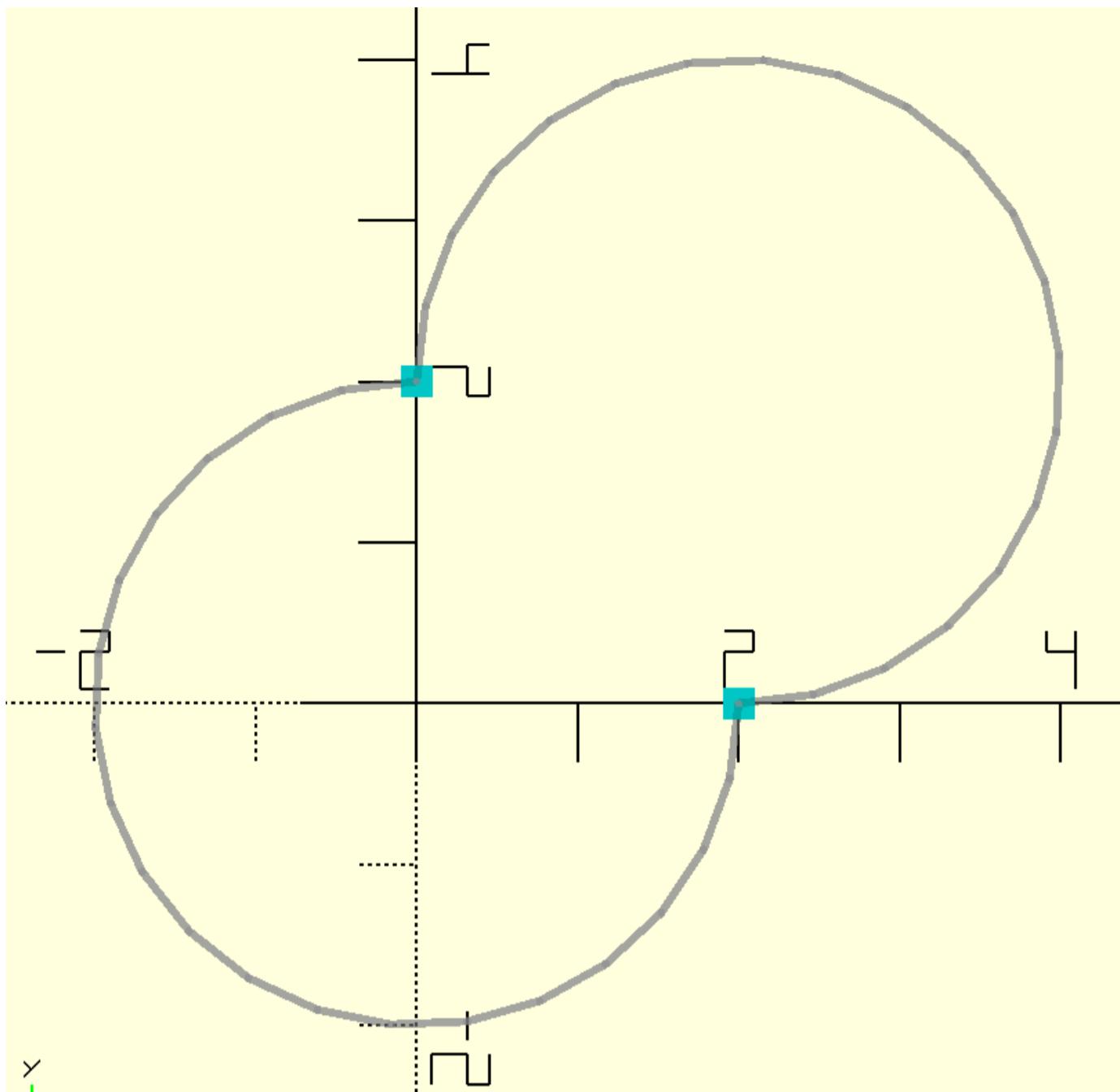
// arc clockwise
//color("blue")
%p_lineo({arc1},.05);

// arc counter clockwise
//color("magenta")
%p_lineo({arc2},.05);

color("cyan")points({[p1,p2]},.2);

''' )

```



arc_2p_cp

In [43]: # example of function arc_2p_cp(p1,p2,r,cw=-1)

```

p1=[2,0]
p2=[0,2]
arc1=arc_2p(p1,p2,2,1,5)
cp1=arc_2p_cp(p1,p2,2,1)

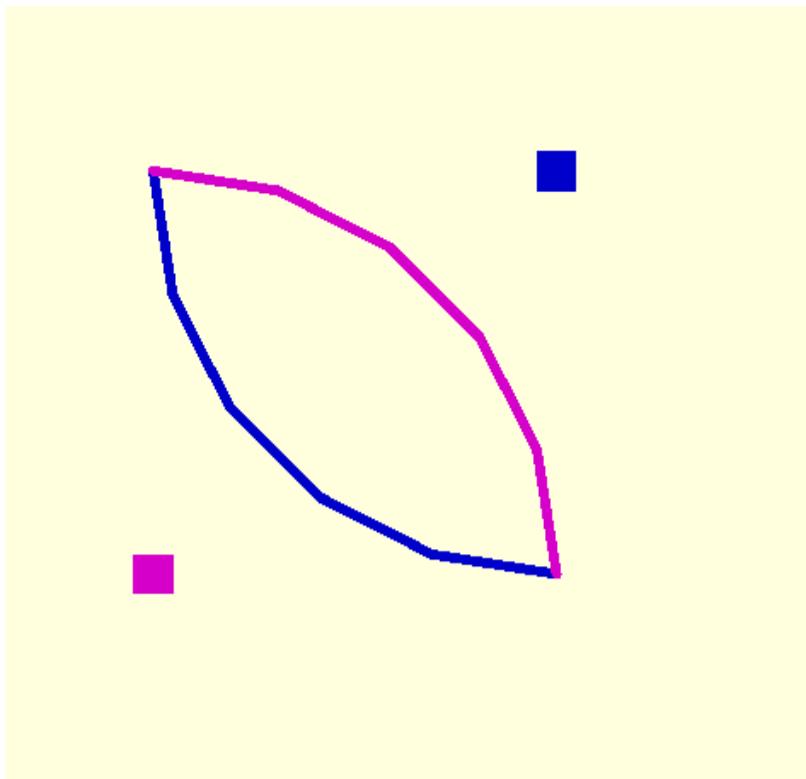
arc2=arc_2p(p1,p2,2,-1,5)
cp2=arc_2p_cp(p1,p2,2,-1)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

// arc clockwise with center point of the arc
color("blue")
{{p_lineo({arc1},.05);
points({[cp1]},.2);}}

// arc counter clockwise with center point of the arc
//color("magenta")
//{{p_lineo({arc2},.05);
//points({[cp2]},.2);}}
```

'''



offset

```
In [44]: # example of function offset(sec,r)

t0=time.time()

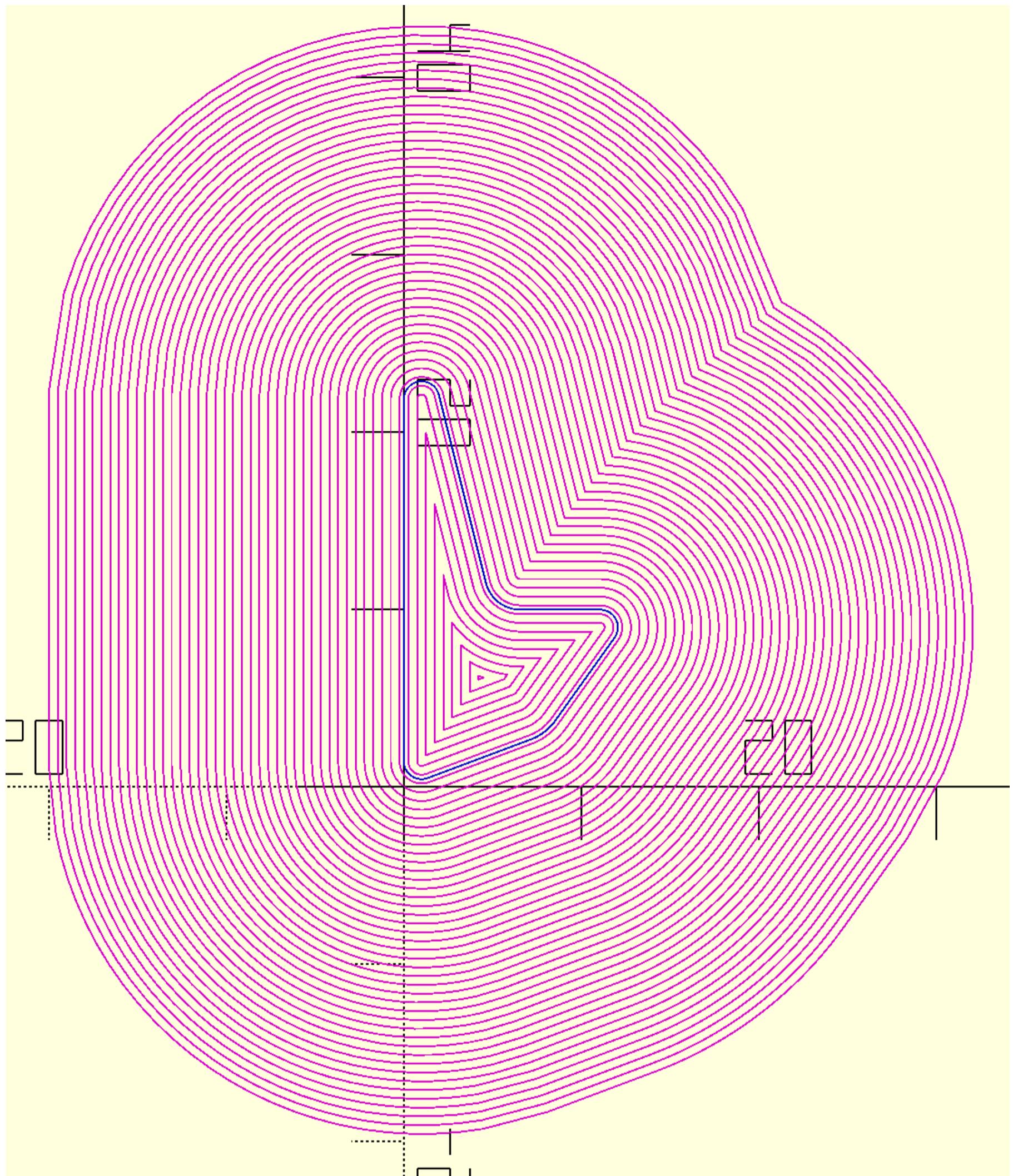
# sec=corner_radius(pts1([[0,0,.2],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)
# sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),10)
# sec=corner_radius(pts1([[0,0,1],[7,5,2],[5,7,3],[-5,7,2],[-7,5,3]]),10)
sec=corner_radius(pts1([-15,0,2.4],[0,15,3],[30,0,3],[0,-15,2.4],[5,0,2.4],[0,20,7],[-40,0,7],[0,-20,2.4])),15)
# sec=corner_radius(pts1([[0,0,1],[10,0,1],[0,5,1],[-10,0,1]]),10)
# sec=circle(10)
# sec=pts([[0,0],[10,0],[0,5],[-10,0]])

# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,4.2],[-4.2,0]]),40)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,5.3],[-5.3,0]]),40)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,2],[-2,0]]),20)
os=linspace(-2.5,20,50)
sec1=[offset(sec,i) for i in os] #
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("magenta")for(p={sec1})p_line(p,.1);
color("blue")p_line({sec},.1);

'''')
t1=time.time()
t1-t0
```

Out[44]: 9.080370903015137



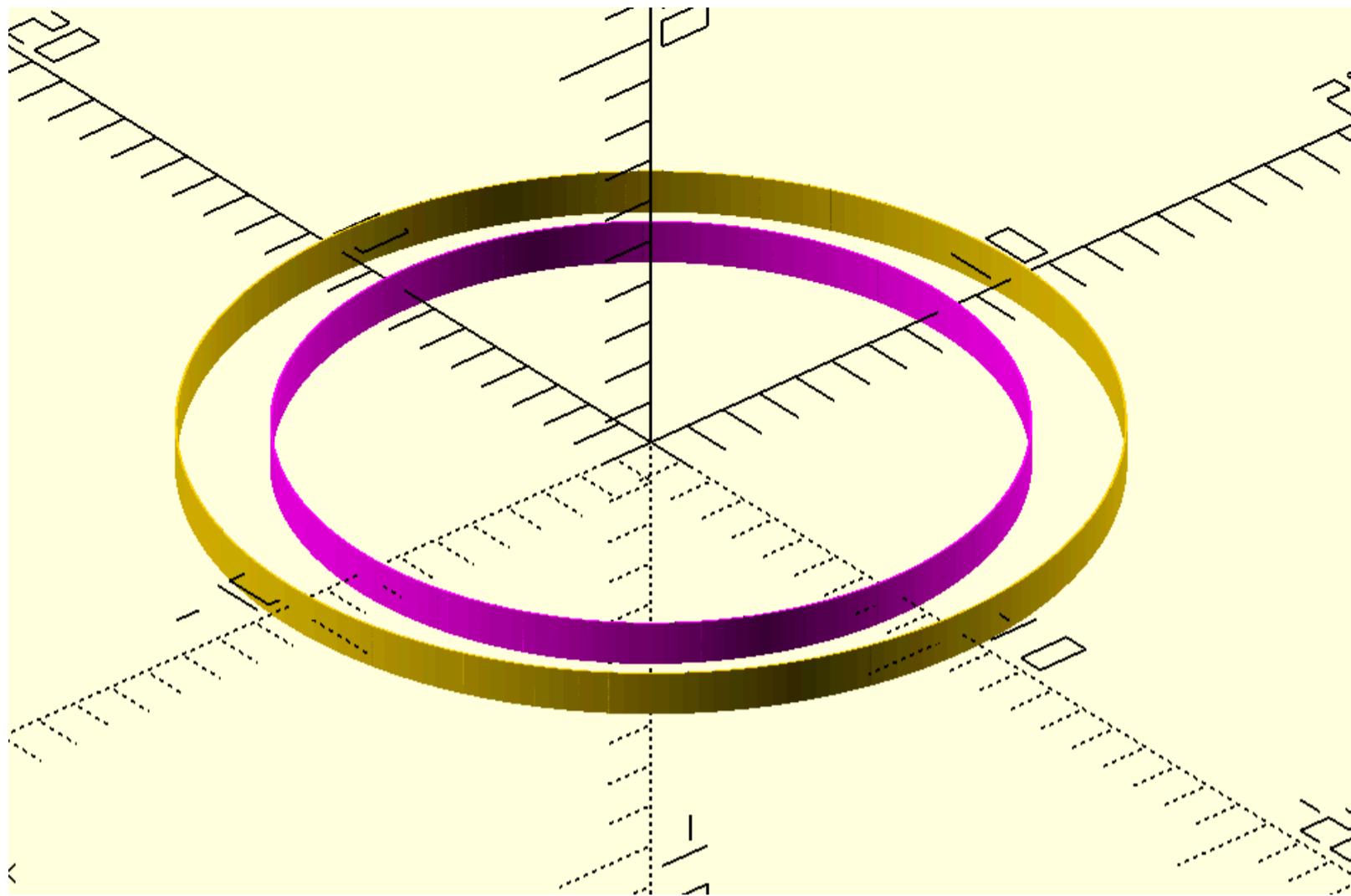
```
In [45]: t0=time.time()
r==2
# sec=corner_radius(pts1([[0,0,1],[7,5,2],[5,7,3],[-5,7,5],[-7,5,5]]),10)
sec=circle(10,s=200)
sec1=offset(sec,r)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
p_line({{sec}},.05);

color("magenta")p_line({{sec1}},.05);
''')

t1=time.time()
t1-t0
```

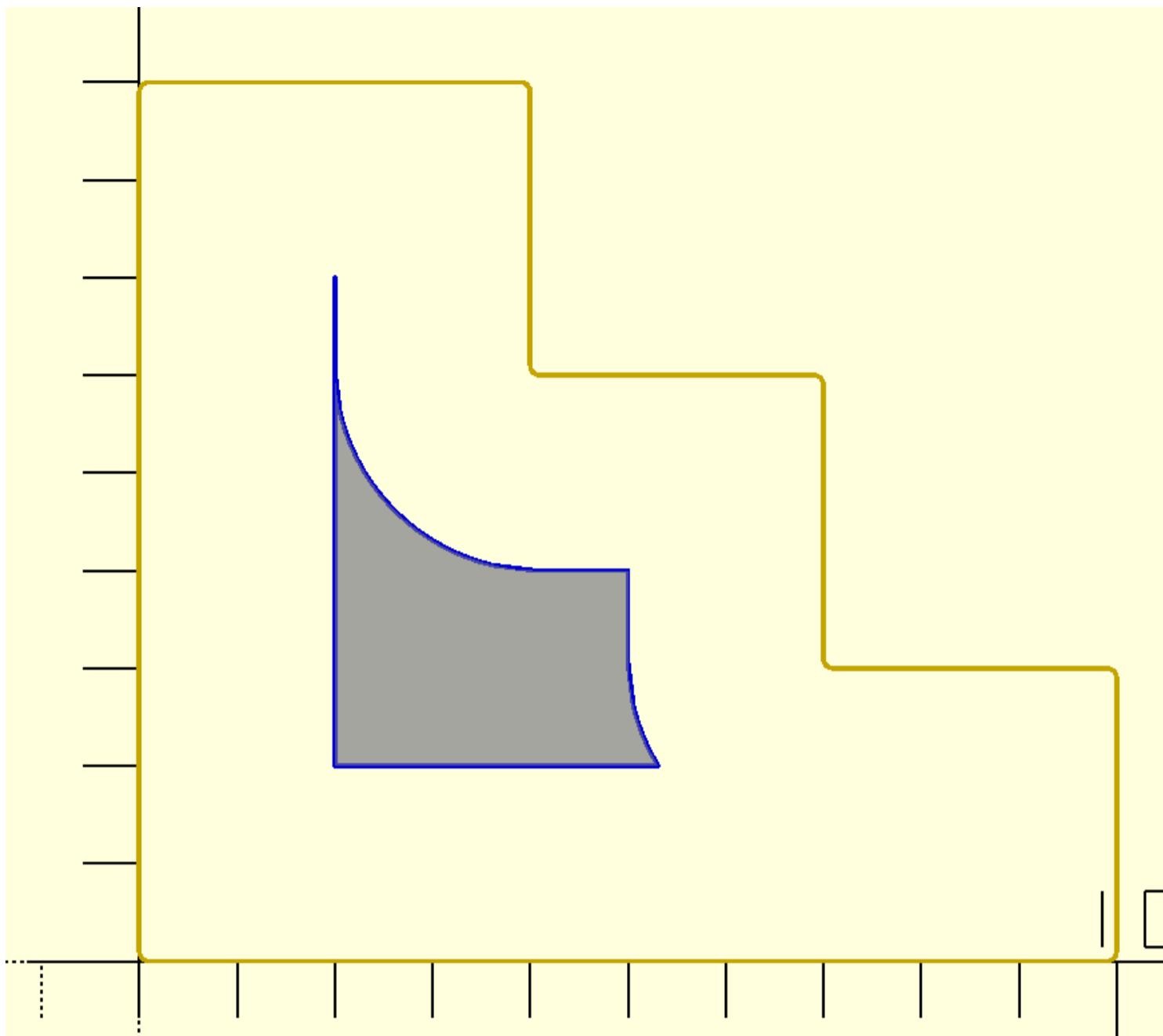
Out[45]: 0.03149914741516113



```
In [47]: sec=corner_radius(pts1([[0,0,.1],[10,0,.1],[0,3,.1],[-3,0,.1],[0,3,.1],[-3,0,.1],[0,3,.1],[-4,0,.1]]),20)
```

```
# sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),40)
# sec=sec=corner_radius(pts1([[0,0,1],[7,5,2],[5,7,3],[-5,7,5],[-7,5,5]]),20)
# sec=corner_radius(pts1([[-15,0,2.49],[0,15,3],[30,0,3],[0,-15,2.49],[5,0,2.49],[0,20,7],[-40,0,7],[0,-20,2.49]]),20)
# sec=circle(10)
d==2

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
p_line({{sec}},.05);
color("blue")p_line({{offset(sec,d)}},.05);
%offset({{d}})polygon({{sec}});
''' )
```



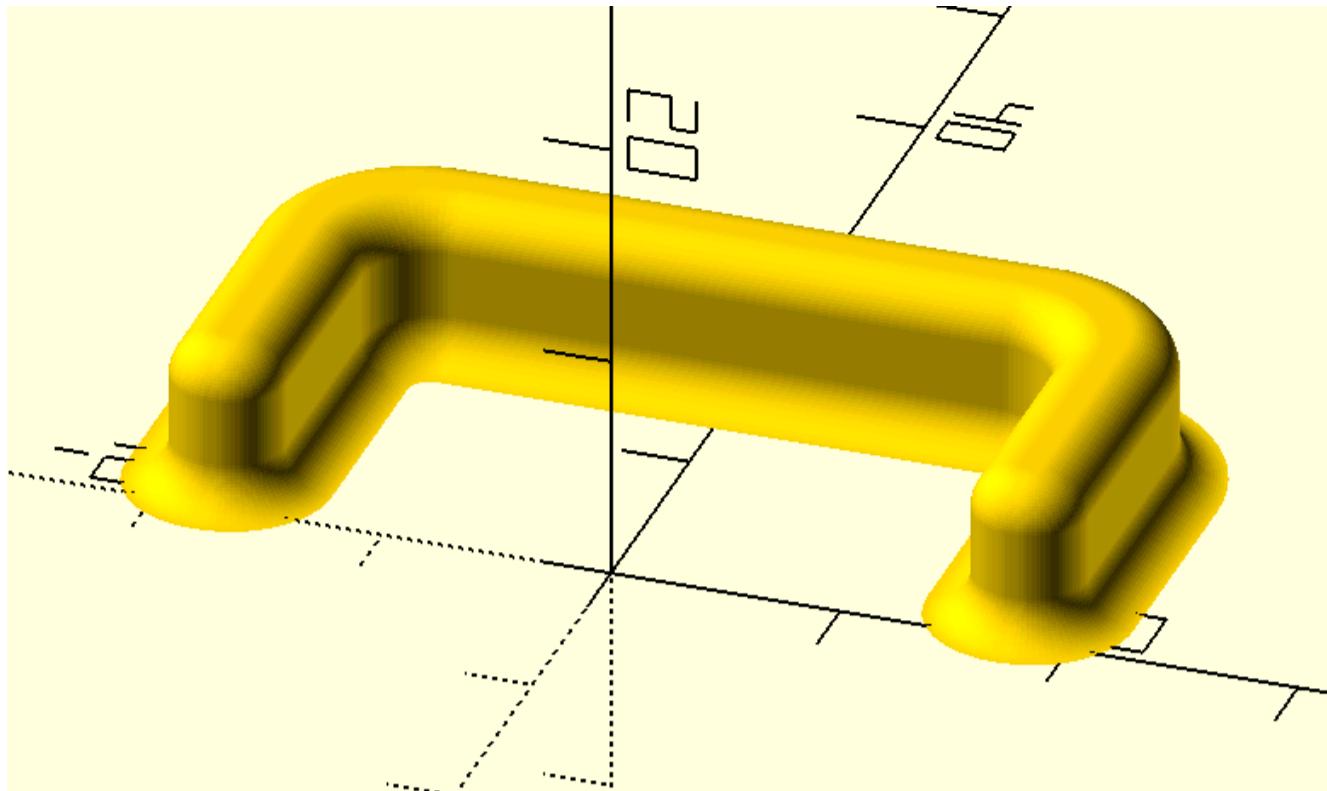
prism

```
In [48]: # example of function prism(sec,path) and function swp_prism_h(prism_big, prism_small)
t0=time.time()
# sec=corner_radius(pts1([[0,0,.2],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)
sec=corner_radius(pts1([[0,0,1],[7,5,2],[5,7,3],[-5,7,2],[-7,5,3]]),20)
sec=corner_radius(pts1([-15,0,2.4],[0,15,3],[30,0,3],[0,-15,2.4],[5,0,2.4],[0,20,7],[-40,0,7],[0,-20,2.4])),20)
# sec=pts([[0,0],[10,0],[0,5],[-10,0]])
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,4.2],[-4.2,0]]),20)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,5.2],[-5.2,0]]),20)
path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,2],[-2,0]]),20)

sol=prism(sec,path)
# sol1=prism(sec,path_offset(path,-.5))
# sol2=swp_prism_h(sol,sol1)

with open('trial.scad', 'w+') as f:
    f.write(f'''
        include<dependencies2.scad>
{swp(sol)}
    ''')
t1=time.time()
t1-t0
```

Out[48]: 0.5310509204864502



f_prism(sec,path)

```
In [49]: # example of function prism(sec,path) and function swp_prism_h(prism_big, prism_small)
t0=time.time()
# sec=corner_radius(pts1([[0,0,.2],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)
sec=corner_radius(pts1([[0,0,1],[7,5,2],[5,7,3],[-5,7,2],[-7,5,3]]),20)
# sec=corner_radius(pts1([[-15,0,2.4],[0,15,3],[30,0,3],[0,-15,2.4],[5,0,2.4],[0,20,7],[-40,0,7],[0,-20,2.4]]),20)
# sec=pts([[0,0],[10,0],[0,5],[-10,0]])
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,4.2],[-4.2,0]]),20)
path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,5.2],[-5.2,0]]),20)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,2],[-2,0]]),20)

sol=f_prism(sec,path)
# sol1=f_prism(sec,path_offset(path,-.5))
# sol2=f_swp_prism_h(sol,sol1)

with open('trial.scad','w+') as f:
    f.write(f'''  

{sdp(sol)}  

'''')

t1=time.time()
t1-t0
```

Out[49]: 0.5594003200531006

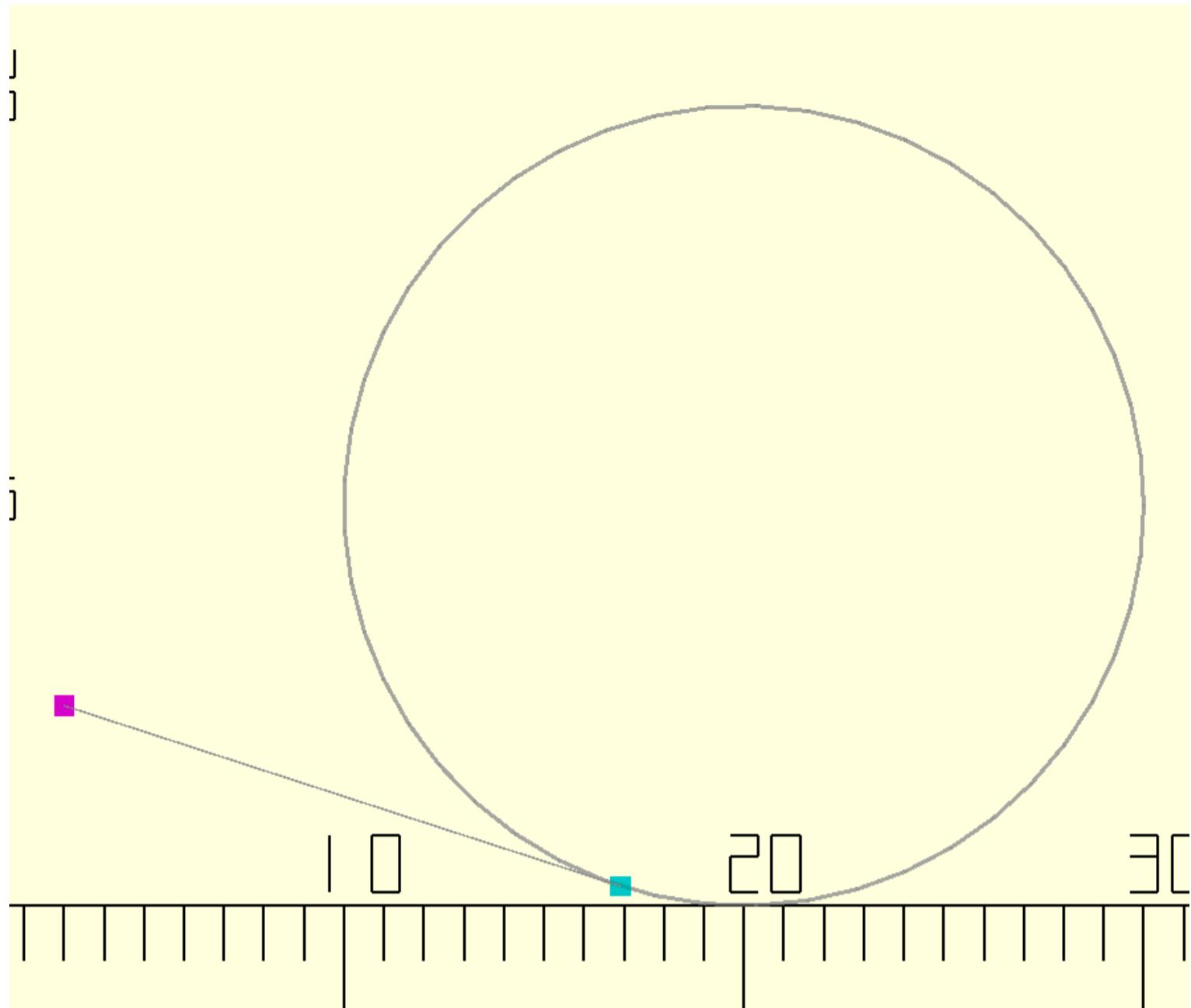
p_cir_t

```
In [50]: # example of function p_cir_t(pnt,cir)
cir=c3t2(translate([20,10,0],circle(10)))
point=[3,5]
tangent_point=p_cir_t(point,cir)
with open('trial.scad','w+')as f:
    f.write(f'''  

include<dependencies2.scad>  

%p_line({cir},.1);
color("magenta")points({[point]},.5);
color("cyan")points({[tangent_point]},.5);
%p_line({[point,tangent_point]},0.05);
'''')
```



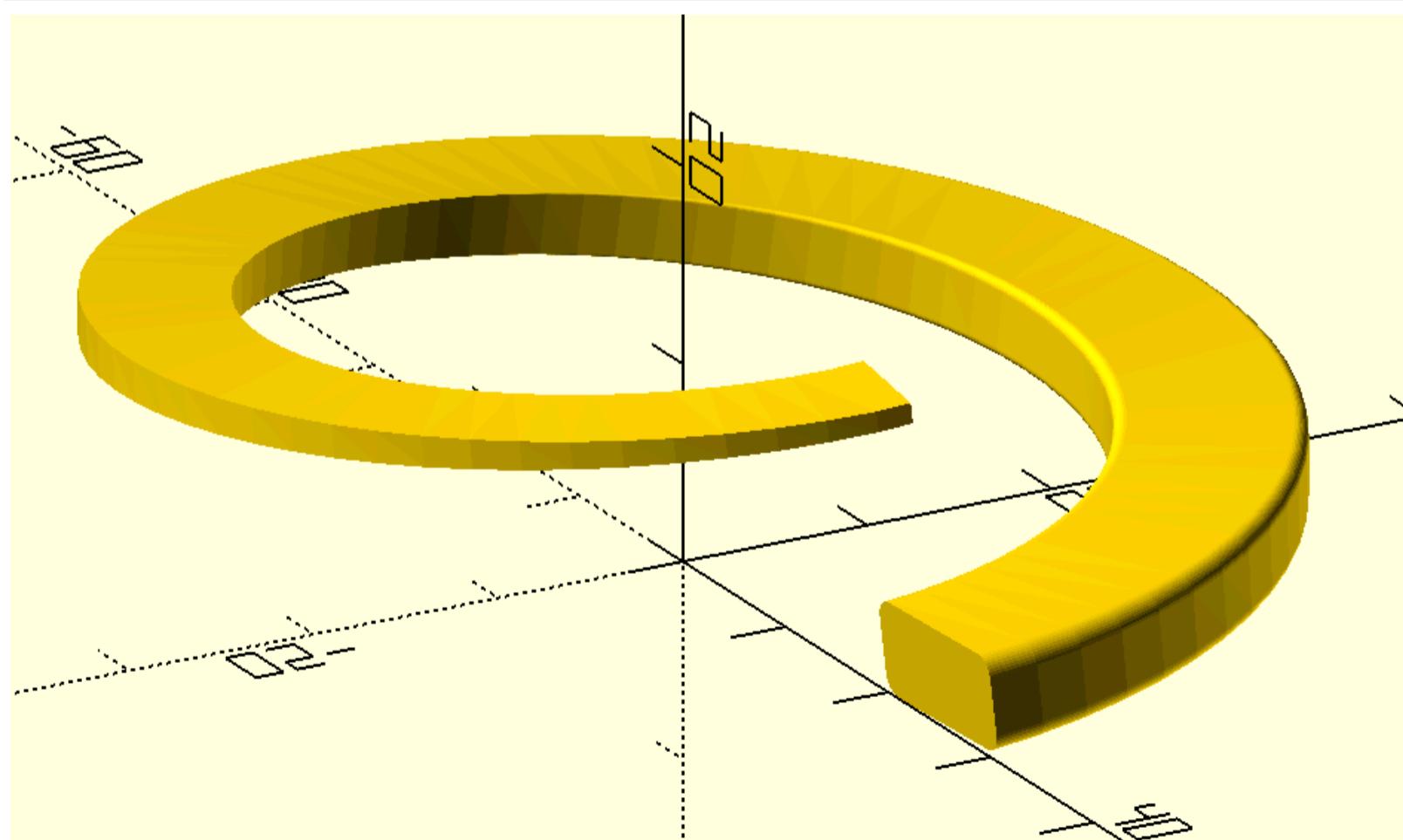
v_sec_extrude

```
In [51]: # example of function v_sec_extrude(sec,path,o)
sec=corner_radius(pts1([[0,0,1],[10,0,1],[0,5,1],[-10,0,1]]),10)
path=helix(20,15,1,5)

sol=v_sec_extrude(sec,path,-2)

with open('trial.scad','w+')as f:
    f.write(f''''
include<dependencies2.scad>

{swp(sol)}
    ''')
```



t_cir_tarc

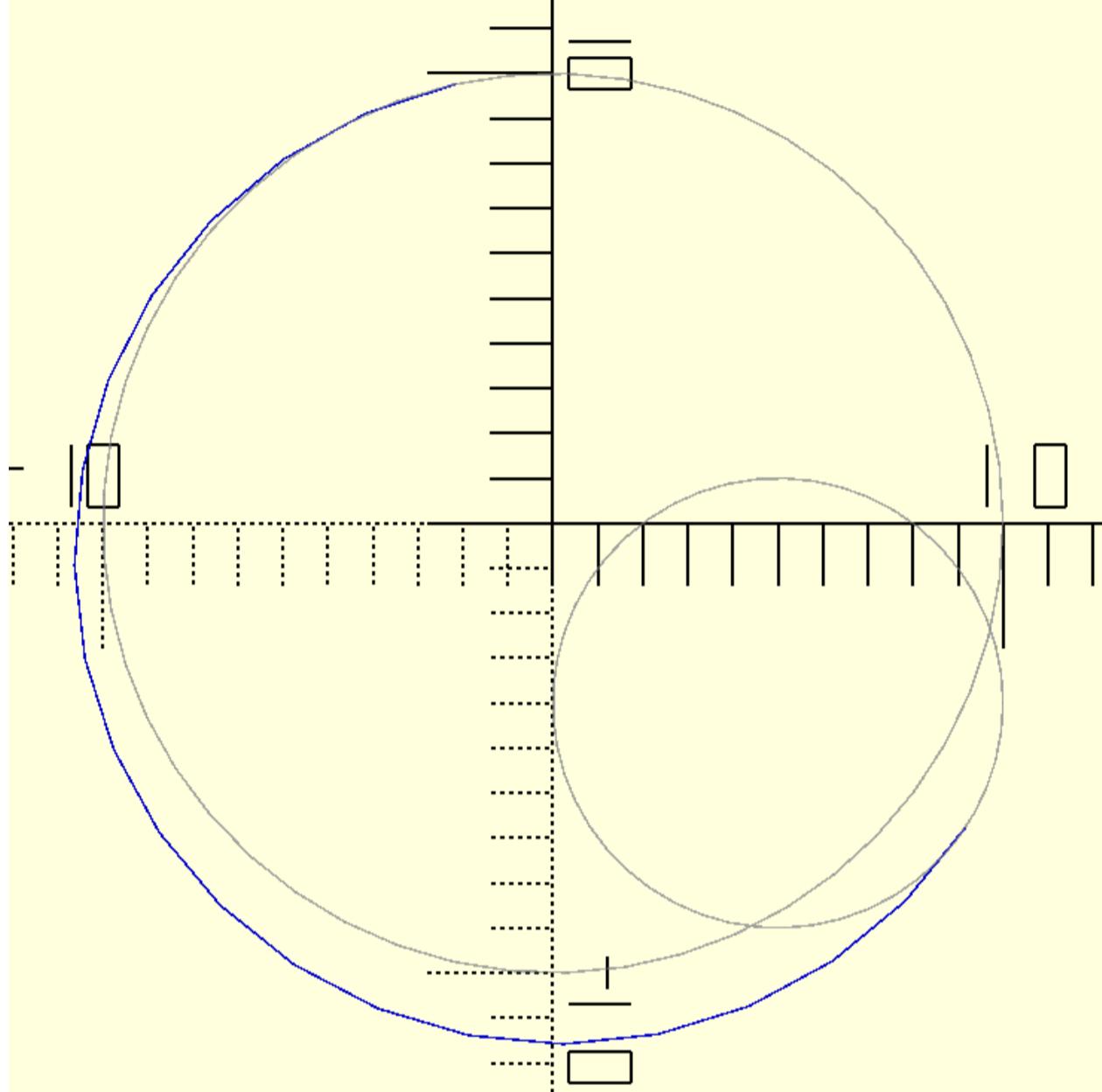
```
In [52]: # example of function t_cir_tarc(r1,r2,cp1,cp2,r,side=0,s=50)

r=17
arc1=t_cir_tarc(10,5,[0,0],[-15,10],r,0,20)

c1=circle(10)
c2=circle(5,[-15,10])
with open('trial.scad','w+')as f:
    f.write(f'''')
include<dependencies2.scad>

%p_line({c1},.05);
%p_line({c2},.05);
arc1={arc1};
color("blue") p_line3d(arc1,.1);
color("magenta")points({[arc1[0],arc1[-1]]},.2);

'''')
```



```
In [53]: # example of function t_cir_tarc

cir1=circle(20)
cir2=circle(10,[52.5*cos(d2r(30)),52.5*sin(d2r(30))])
cp1,cp2=[52.5*cos(d2r(30)),52.5*sin(d2r(30))],[0,0]

arc1=t_cir_tarc(10,20,cp1,cp2,45,0)
arc3=t_cir_tarc(10,20,cp1,cp2,18.75,1)
arc2=arc_long_2p(arc1[-1],arc3[0],20,-1)[1:-1]
arc4=arc_2p(arc3[-1],arc1[0],10,-1)[1:-1]

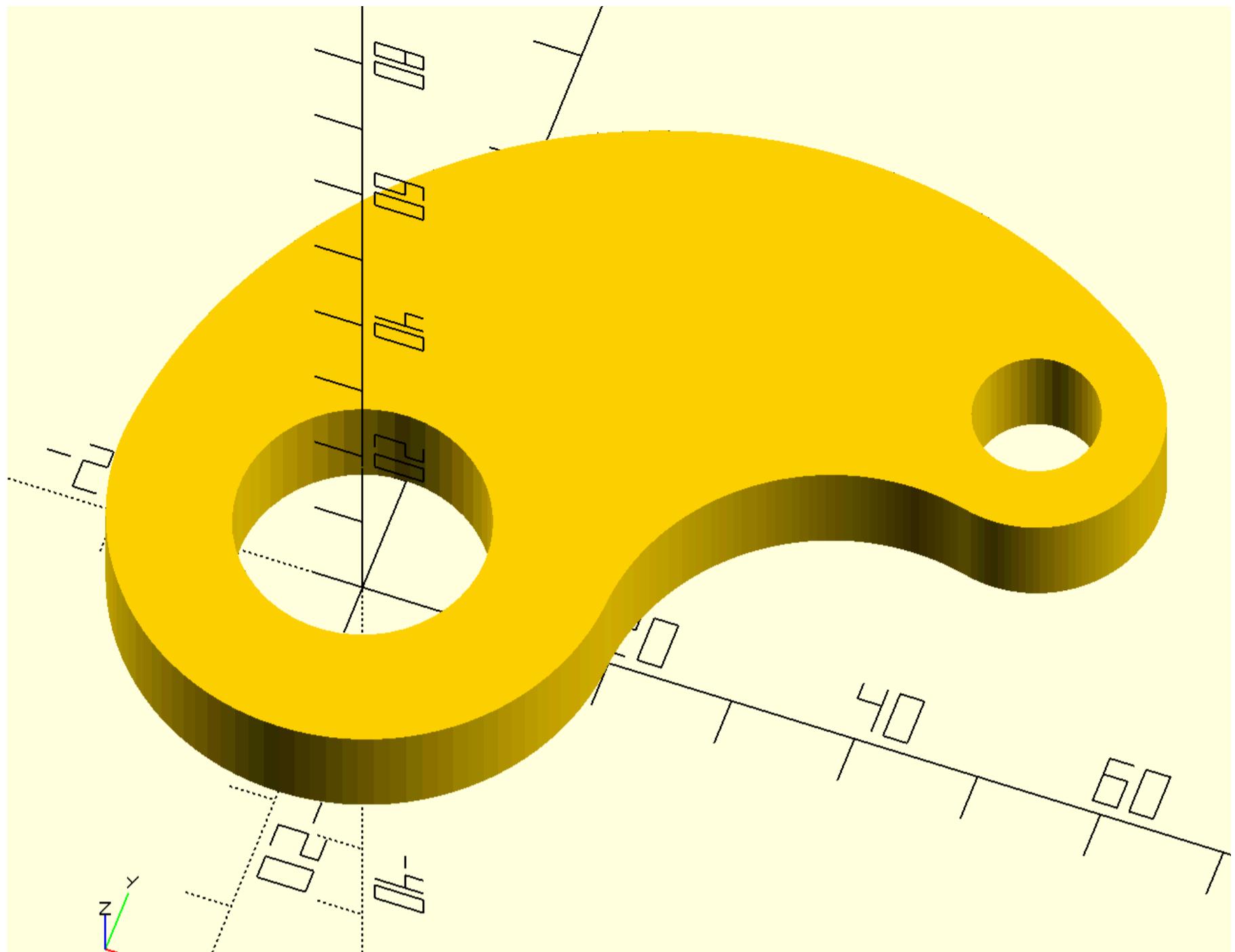
sec=arc1+arc2+arc3+arc4
sol=linear_extrude(sec,10)
sol1=translate([0,0,-.5],translate(c2t3(cp1),cylinder(r=5,h=11)))
sol2=translate([0,0,-.5],translate(c2t3(cp2),cylinder(r=10,h=11)))

with open('trial.scad','w+') as f:
    f.write(f'''')
include<dependencies2.scad>
//p_line3d({cir1},.1);
//p_line3d({cir2},.1);
//sec={sec};
//color("magenta")p_line3d(loop(sec,0,len(sec)*$t),.5);
difference(){{
{swp(sol)}
{swp(sol1)}
{swp(sol2)}

}}
'''')

arc1[-1]
```

Out[53]: [-19.93067428455553, 1.6637976328138104]



tcct

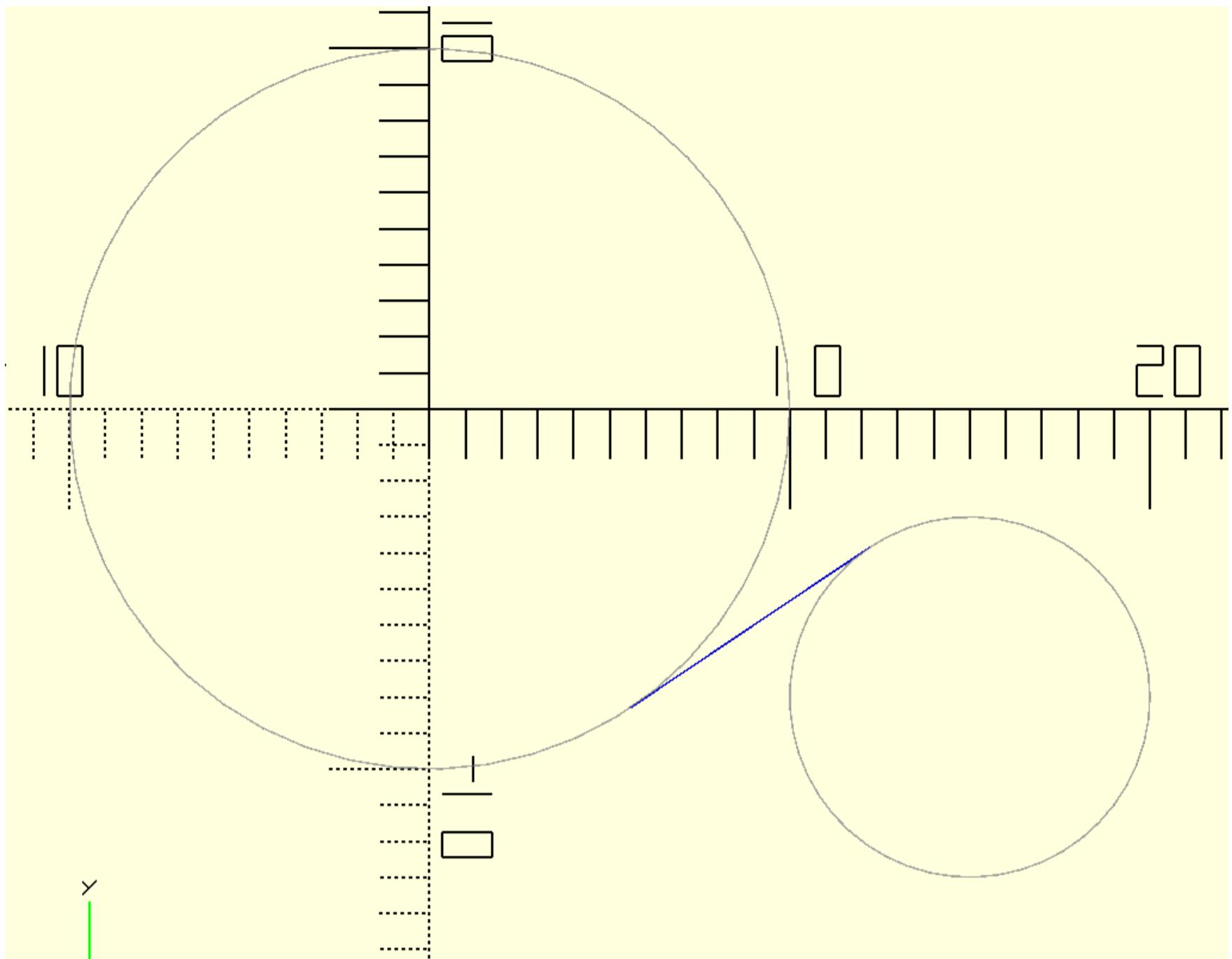
```
In [54]: # example of function tcct(r1,r2,cp1,cp2,cw=-1)
c1=circle(10)
c2=circle(5,[15,-8])

line= tcct(10,5,[0,0],[15,-8],cw=-1)

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

%p_line({{c1}},.05);
%p_line({{c2}},.05);
color("blue") p_lineo({{line}},.05);

    ''')
```

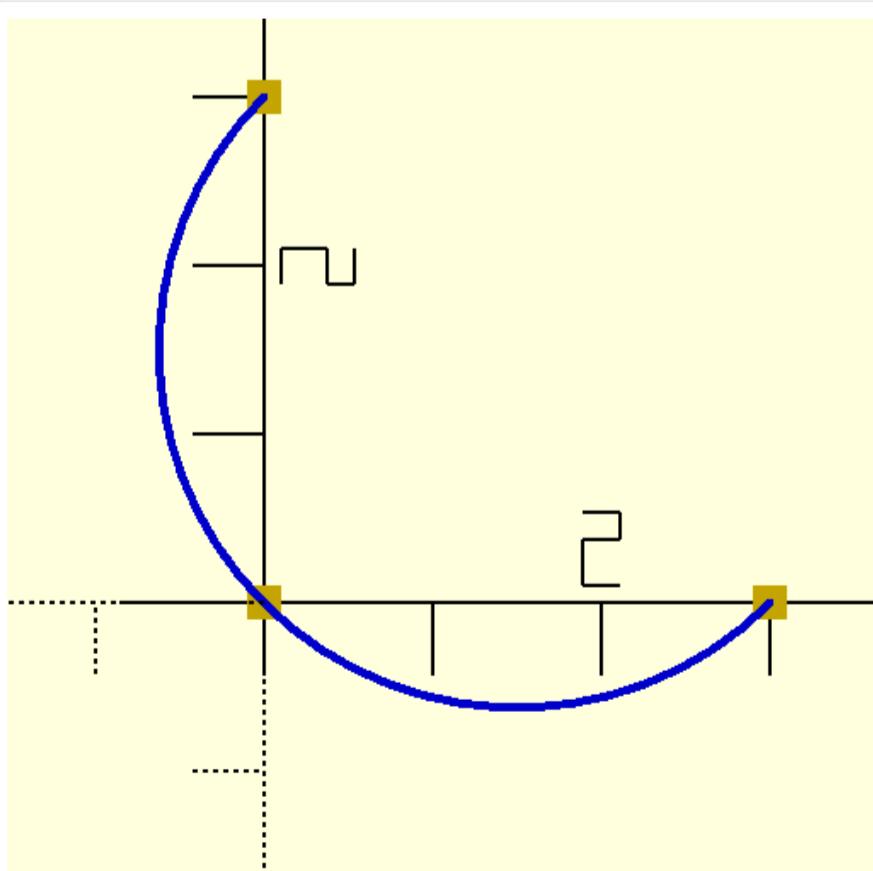


arc_3p

```
In [55]: # example of function arc_3p(p1,p2,p3,s=30)

p1,p2,p3=[3,0],[0,0],[0,3]
arc1=arc_3p(p1,p2,p3)
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

color("blue") p_lineo({arc1},.05);
points({[p1,p2,p3]},.2);
    ''')
```

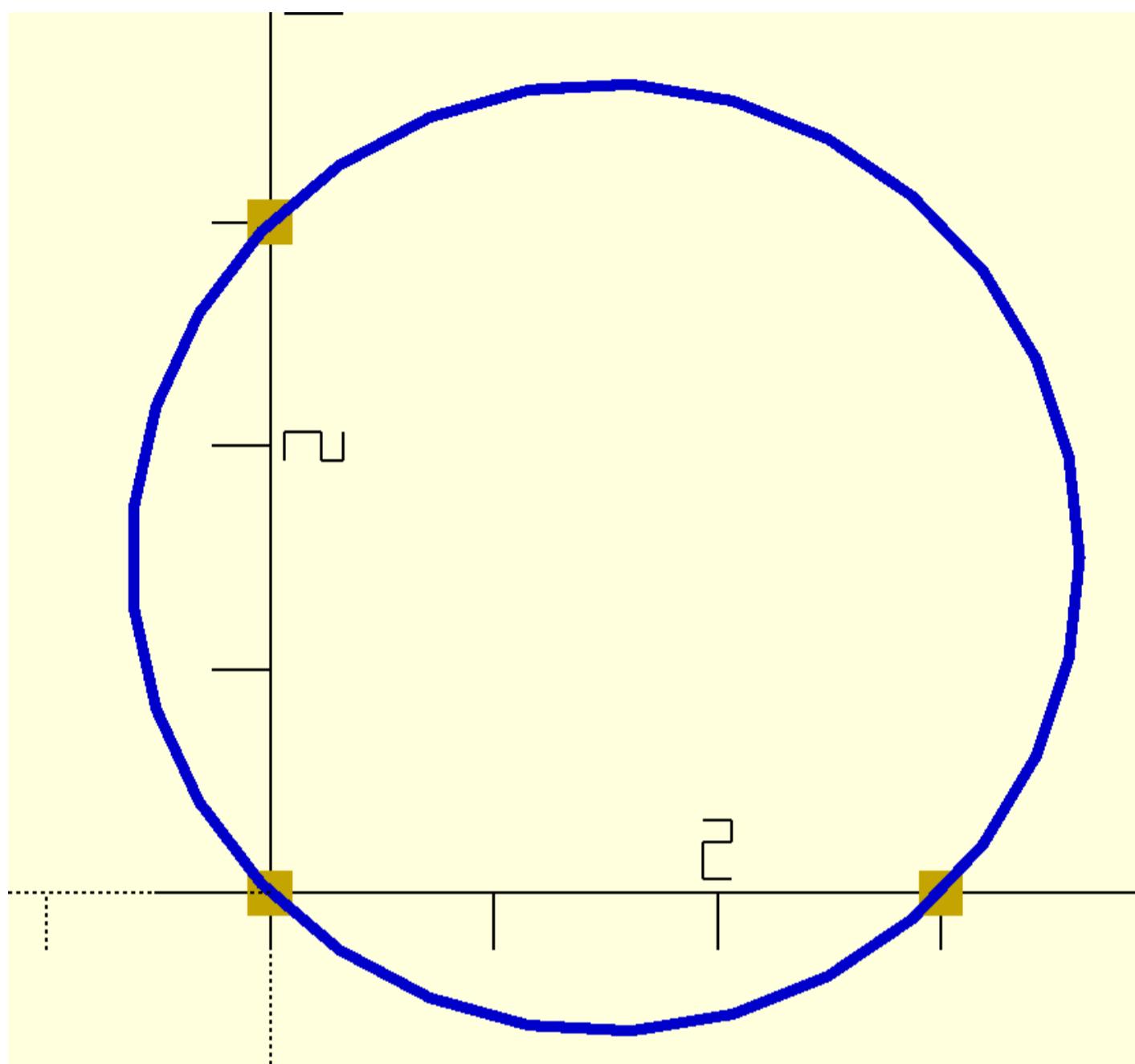


cir_3p

```
In [56]: # example of function cir_3p(p1,p2,p3,s=30)
```

```
p1,p2,p3=[3,0],[0,0],[0,3]
cir=cir_3p(p1,p2,p3,30)
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

color("blue") p_line({cir},.05);
points({[p1,p2,p3]},.2);
    ''')
```

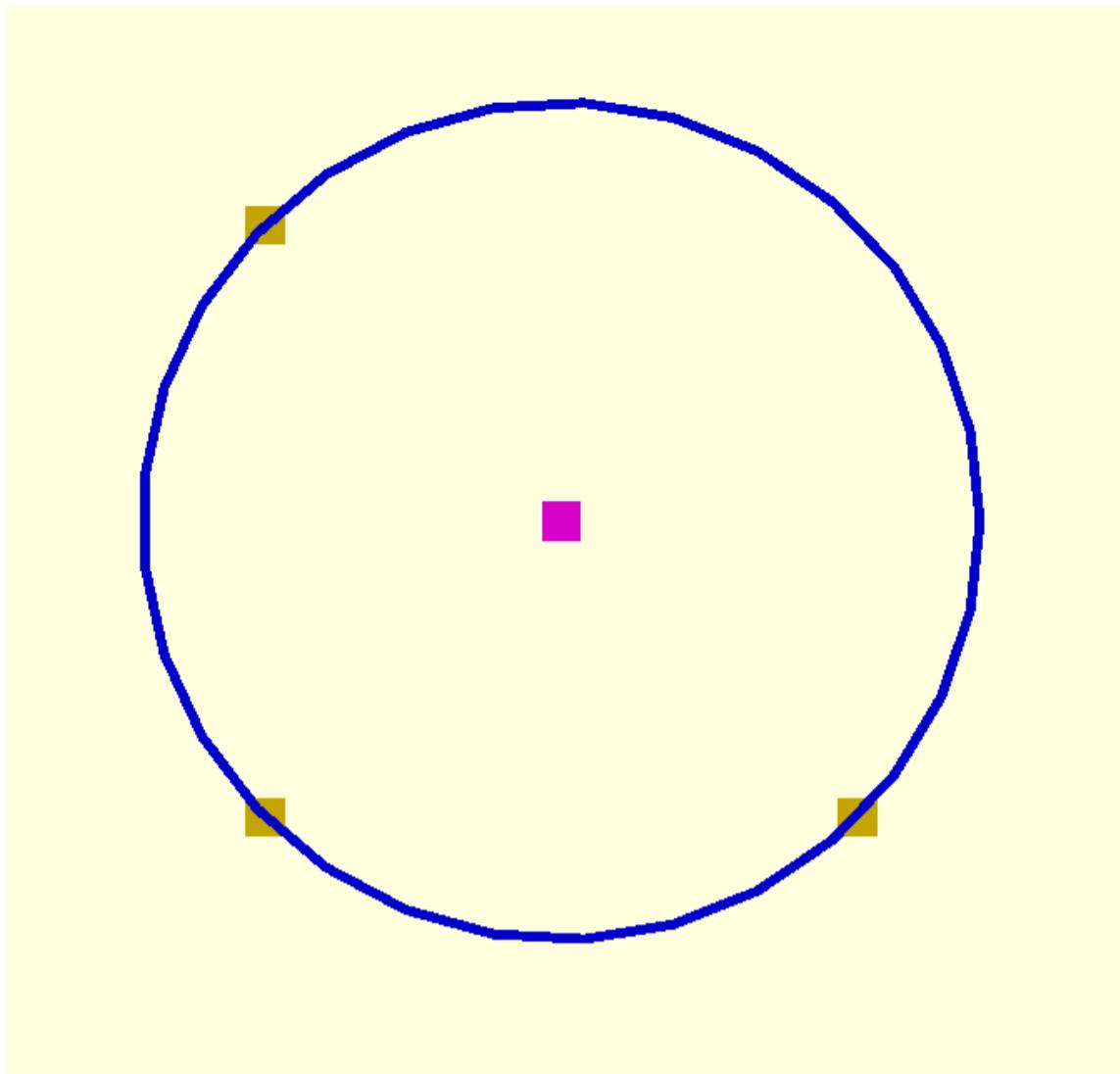


cp_3p

```
In [57]: # example of function cp_3p(p1,p2,p3)
```

```
p1,p2,p3=[3,0],[0,0],[0,3]
cir=cir_3p(p1,p2,p3,30)
center= cp_3p(p1,p2,p3)
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

color("blue") p_line({cir},.05);
points({[p1,p2,p3]},.2);
color("magenta")points({[center]},.2);
    ''')
```



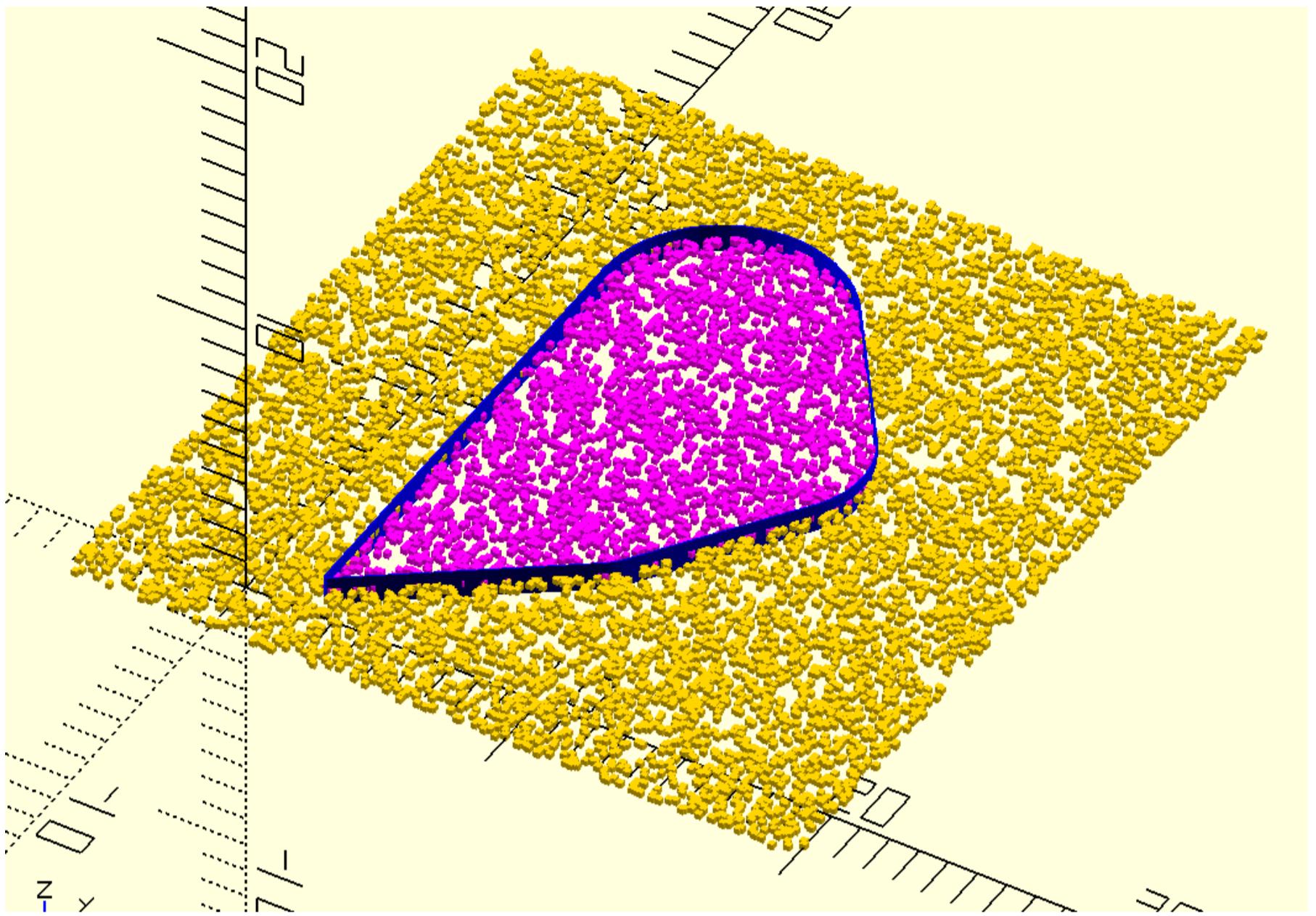
pies1

```
In [58]: # example of function pies1(sec,pnts)
# function points inside enclosed section
t0=time.time()
a=random.random(10000)*(20-(-5))+(-5)
b=random.random(10000)*(25-(-2))+(-2)
points=array([a,b]).transpose(1,0).tolist()
# sec=corner_radius(pts1([[2,1,.1],[7,5,2],[5,7,3],[-5,7,2],[-7,5,3]]),20)
sec=corner_radius(pts1([[8,0],[11,10,10],[0,10,5],[-10,0,5],[-1,-6,0.3],[-1,6,5],[-10,0,5],[0,-10,10]]))

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

color("blue") p_line({sec},.05);
points({points},.2);
color("magenta")points({pies1(sec,points)}),.2;
    ''')
t1=time.time()
t1-t0
```

Out[58]: 0.2869088649749756



```
In [59]: # example of pies1(sec,pnts)
t0=time.time()

a=random.random(10000)*(10-0)+0
b=random.random(10000)*(20-0)+0
c=array([a,b]).transpose(1,0).tolist()

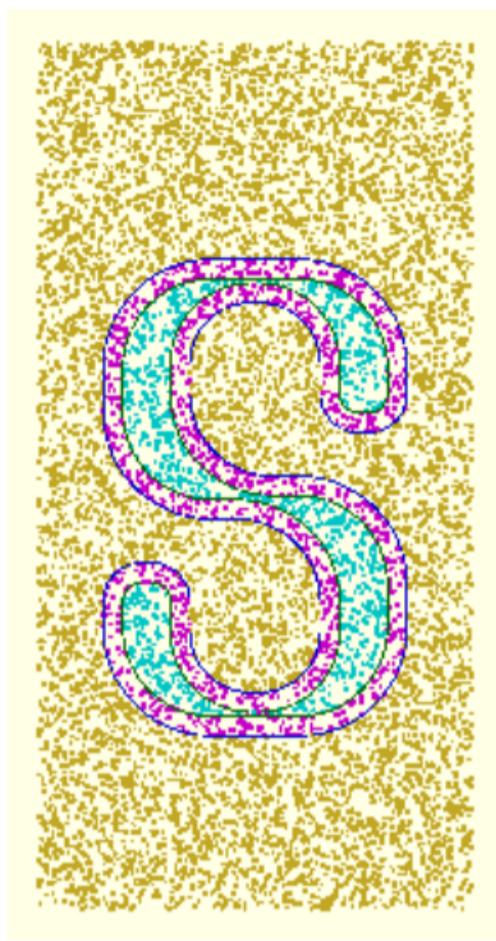
sec=corner_radius(pts1([[1.5,8,.9],[2,0,.9],[0,-3,1.4],[3,0,1.4],[0,4,1.9],[-5,0,2.5],[0,6,2.5],
[7,0,2.5],[0,-4,.9],[-2,0,.9],[0,3,1.4],[-3,0,1.4],[0,-4,1.9],
[5,0,2.5],[0,-6,2.5],[-7,0,2.5]]),20)

pnts=pies1(sec,c)
pnts1=pies1(offset(sec,-.45),pnts)

with open('trial.scad','w+')as f:
    f.write(f'''
    include<dependencies.scad>
    points({c},.1);
    color("magenta")points({pnts},.1);
    color("cyan")points({pnts1},.1);
    color("blue")p_line({sec},.05);
    color("green")p_line({offset(sec,-.45)},.05);

    ''')
t1=time.time()
t1-t0
```

Out[59]: 0.7498350143432617



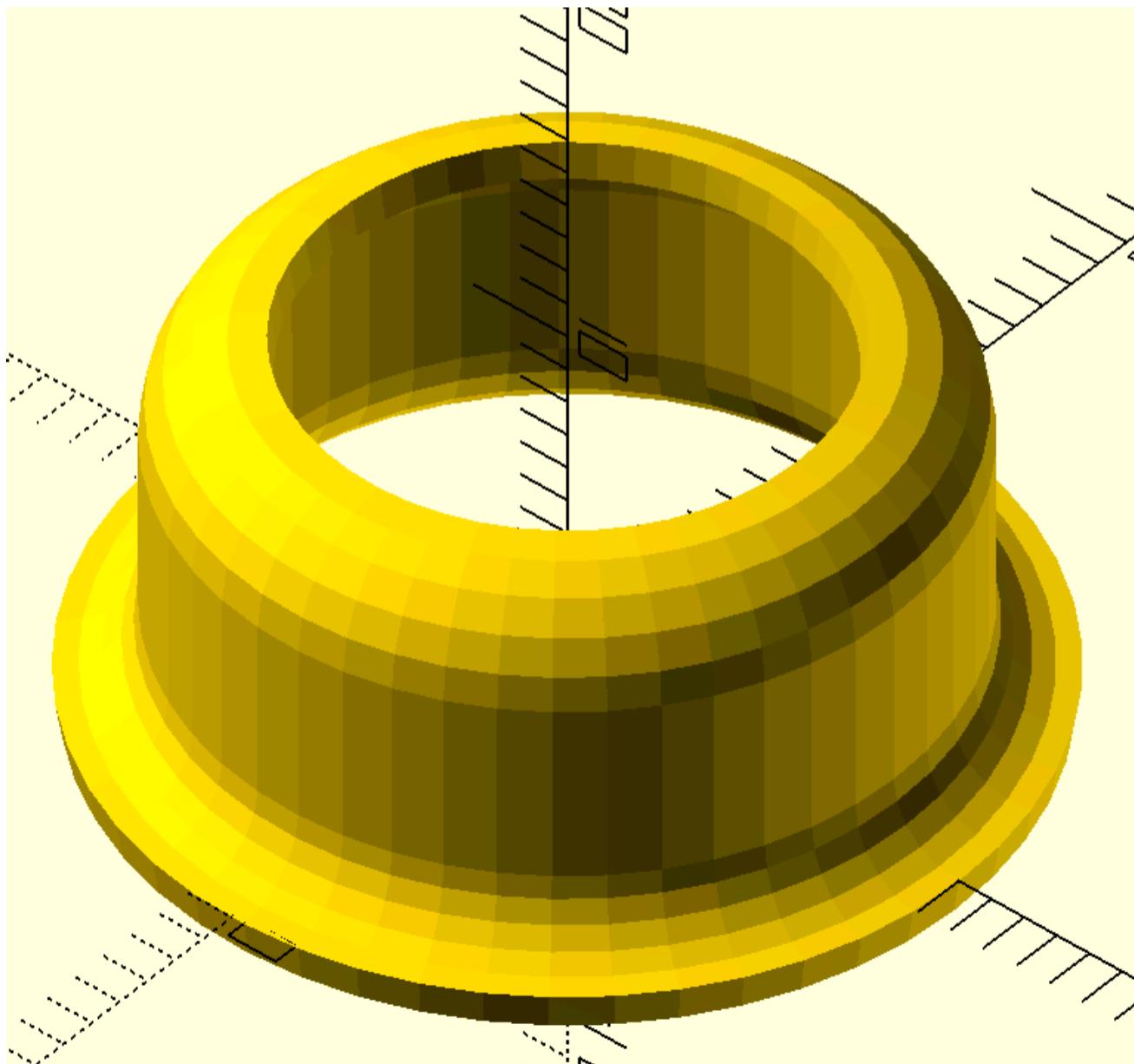
swp_prism_h

```
In [60]: # example of function swp_prism_h(prism_big,prism_small)

sec1=circle(10)
path=corner_radius(pts1([[2,0],[-2,0,2],[0,10,3],[-3,0]]),5)
sol=prism(sec1,path)
sol1=surf_offset(sol,-1)
sol2=swp_prism_h(sol,sol1)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
{swp_c(sol2)}

...''')
```



```
In [61]: # example of function prism(sec,path) and function swp_prism_h(prism_big, prism_small)
t0=time.time()
# sec=corner_radius(pts1([[0,0,.2],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)
# sec=corner_radius(pts1([[0,0,1],[7,5,2],[5,7,3],[-5,7,5],[-7,5,5]]),20)
```

```

sec=corner_radius(pts1([[-15,0,2.4],[0,15,3],[30,0,3],[0,-15,2.4],[5,0,2.4],[0,20,7],[-40,0,7],[0,-20,2.4]]),20)
# sec=pts([[0,0],[10,0],[0,5],[-10,0]])
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,4.2],[-4.2,0]]),20)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,5.2],[-5.2,0]]),20)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,2],[-2,0]]),20)

# sec=equidistant_pathc(sec,300)
sec1=offset(sec,.5)

sol=linear_extrude(sec,50)
sol1=linear_extrude(sec1,50)
sol2=swp_prism_h(sol1,sol)

with open('trial.scad','w+') as f:
    f.write(f'''

include<dependencies2.scad>
{swp_c(sol2)}

''')

t1=time.time()
t1-t0

```

Out[61]: 0.03553199768066406

```

In [62]: sec=corner_radius(pts1([[0,0,1],[25,0,1],[0,15,1],[-25,0,1]]),10)
sec1=offset(sec,2)
sol=linear_extrude(sec,10)
sol1=linear_extrude(sec1,10)
sol2=swp_prism_h(sol1,sol)

with open('trial.scad','w+') as f:
    f.write(f'''

include<dependencies2.scad>
{swp_c(sol2)}

''')



```

```

In [63]: sec=corner_radius(pts1([[0,0,1],[15,0,1],[0,10,1],[-15,0,1]]),10)
sec1=offset(sec,2)
sol=linear_extrude(sec,10)
sol1=linear_extrude(sec1,10)
sol2=swp_prism_h(sol1,sol)

with open('trial.scad','w+') as f:
    f.write(f'''

include<dependencies2.scad>
{swp_c(sol2)}

''')



```

surf_base

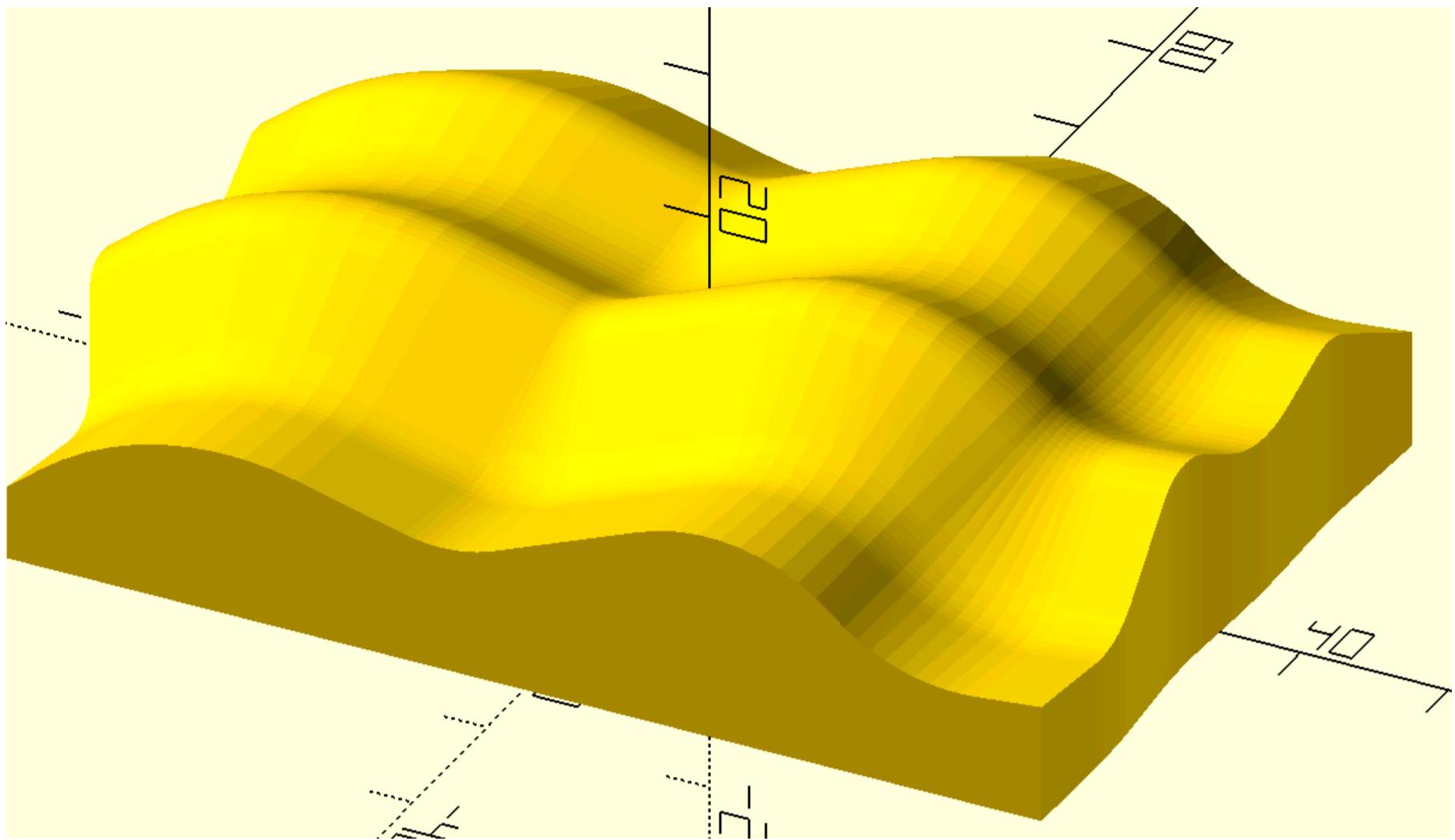
```

In [64]: # example of function surf_base(surf,h)
t0=time.time()

sec2=corner_radius(pts1([[-25,0],[10,5,5],[10,-3,10],[10,5,5],[10,-8,7],[10,1]]),10)
path2=cytz(corner_radius(pts1([[-35,5,0],[10,8,20],[20,-5,10],[20,8,20],[10,-9,20],[10,1,0]]),10))
surf2=surf_extrude(sec2,path2)
sol=surf_base(surf2,0)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
difference(){{{
{swp(sol)}
//{swp(cut_plane([0,0,1],[15,10],20,10))}}
}}}
t1=time.time()
total=t1-t0
total

```

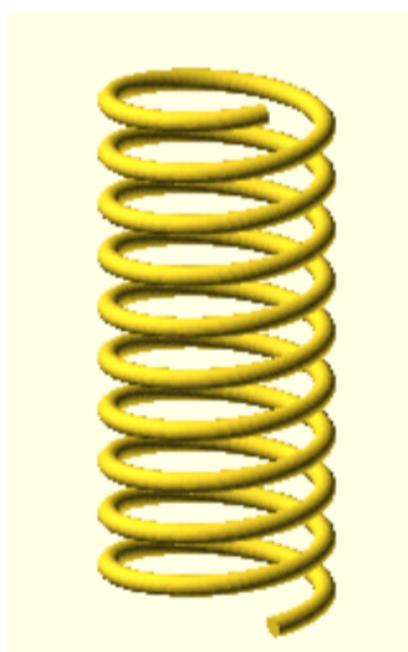
Out[64]: 0.0839698314666748



helix

```
In [65]: # example of function helix(radius=10,pitch=10, number_of_coils=1, step_angle=1)

path=helix(10,5,10,5)
sec=circle(1)
sol=path_extrude_open(sec,path)
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
//p_line3d({path},1,$fn=20);
{swp(sol)}
'''')
```



offset_points_cw

```
In [66]: # example of function offset_points_cw(sec,r)

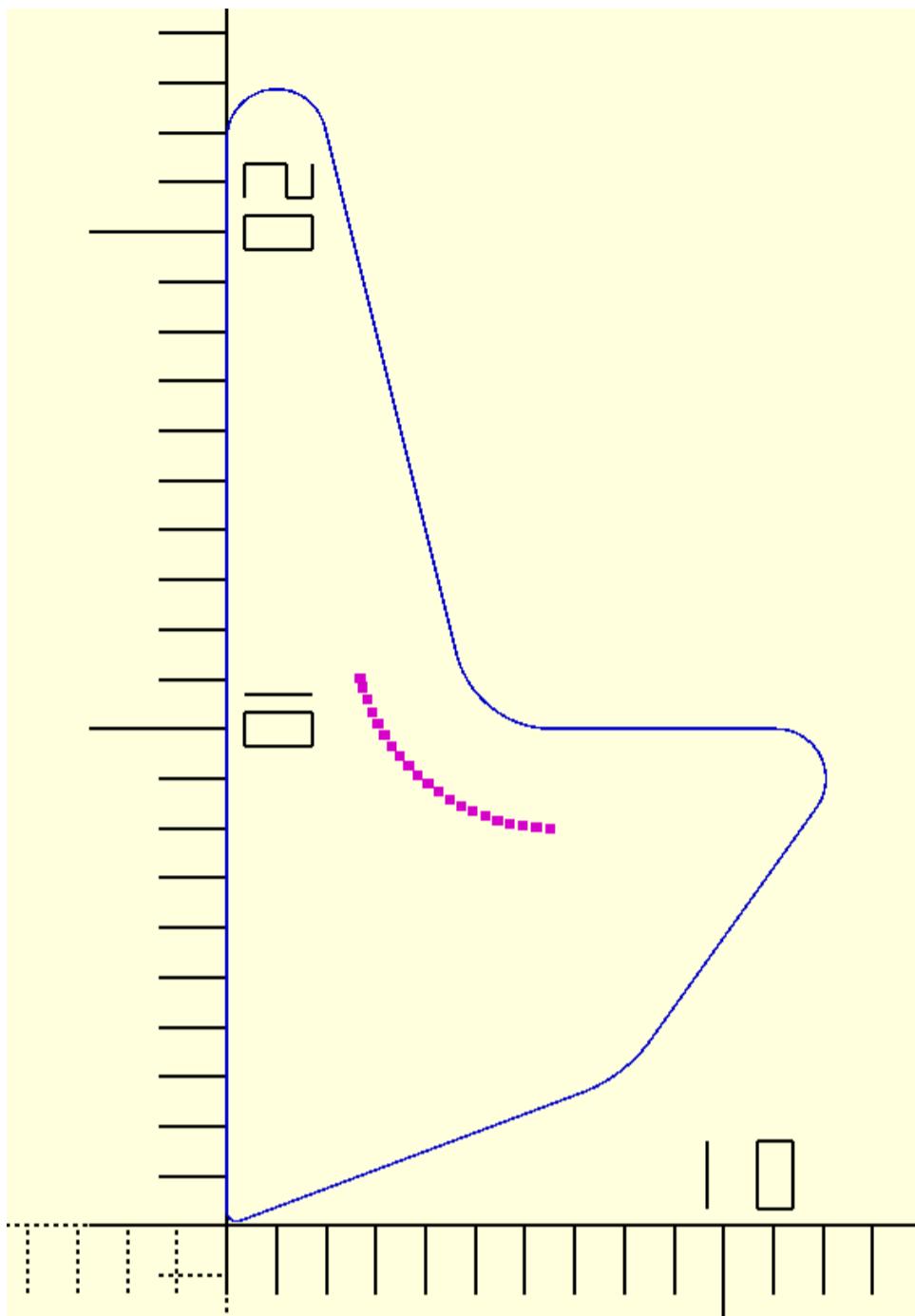
sec=corner_radius(pts1([[0,0,.2],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)
# sec=corner_radius(pts1([[0,0,.1],[7,5,2],[5,7,3],[-5,7,2],[-7,5,3]]),20)
# sec=corner_radius(pts1([[-15,0,2.4],[0,15,3],[30,0,3],[0,-15,2.4],[5,0,2.4],[0,20,7],[-40,0,7],[0,-20,2.4]]),20)

# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,4.2],[-4.2,0]]),40)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,5.3],[-5.3,0]]),40)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,2],[-2,0]]),20)

offsetPoints=offset_points_cw(sec,-2)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line({sec},.05);
color("magenta")points({offsetPoints},.2);

'''')
```



offset_points_ccw

```
In [67]: # example of function offset_points_ccw(sec,r)

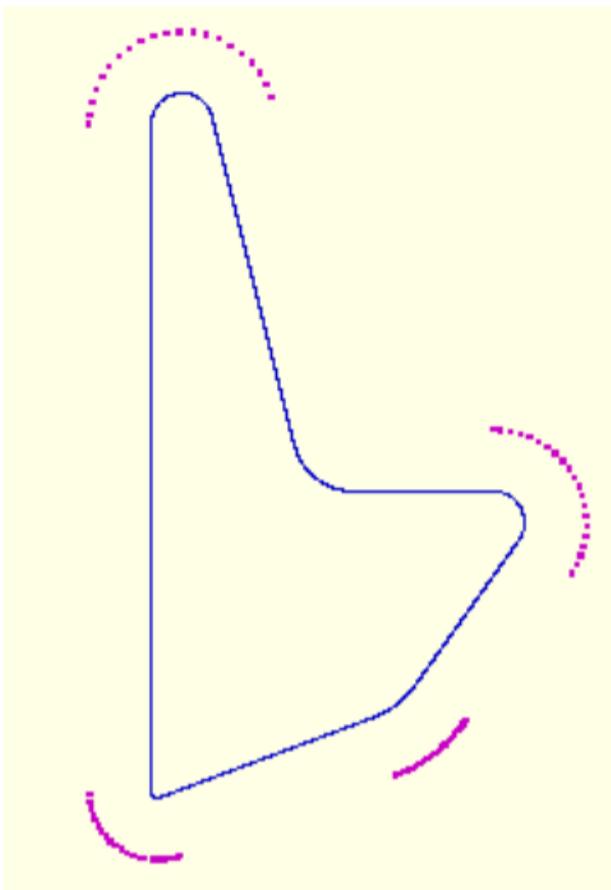
sec=corner_radius(pts1([[0,0,.2],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)
# sec=corner_radius(pts1([[0,0,.1],[7,5,2],[5,7,3],[-5,7,5],[-7,5,5]]),20)
# sec=corner_radius(pts1([[-15,0,2.4],[0,15,3],[30,0,3],[0,-15,2.4],[5,0,2.4],[0,20,7],[-40,0,7],[0,-20,2.4]]),20)

# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,4.2],[-4.2,0]]),40)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,5.3],[-5.3,0]]),40)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,2],[-2,0]]),20)

offsetPoints=offset_points_ccw(sec,2)

with open('trial.scad', 'w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line({sec},.1);
color("magenta")points({offsetPoints},.2);

''' )
```



cpo

```
In [68]: # example of function cpo(prism)

sec=corner_radius(pts1([[0,0,.2],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),10)
# sec=corner_radius(pts1([[0,0,.1],[7,5,2],[5,7,3],[-5,7,5],[-7,5,5]]),20)
# sec=corner_radius(pts1([[-15,0,2.4],[0,15,3],[30,0,3],[0,-15,2.4],[5,0,2.4],[0,20,7],[-40,0,7],[0,-20,2.4]]),20)

path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,4.2],[-4.2,0]]),10)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,5.3],[-5.3,0]]),40)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,2],[-2,0]]),20)

sp1=translate([0,50,0],sphere(10,s=20))
sp2=translate([30,0,0],cpo(sp1))

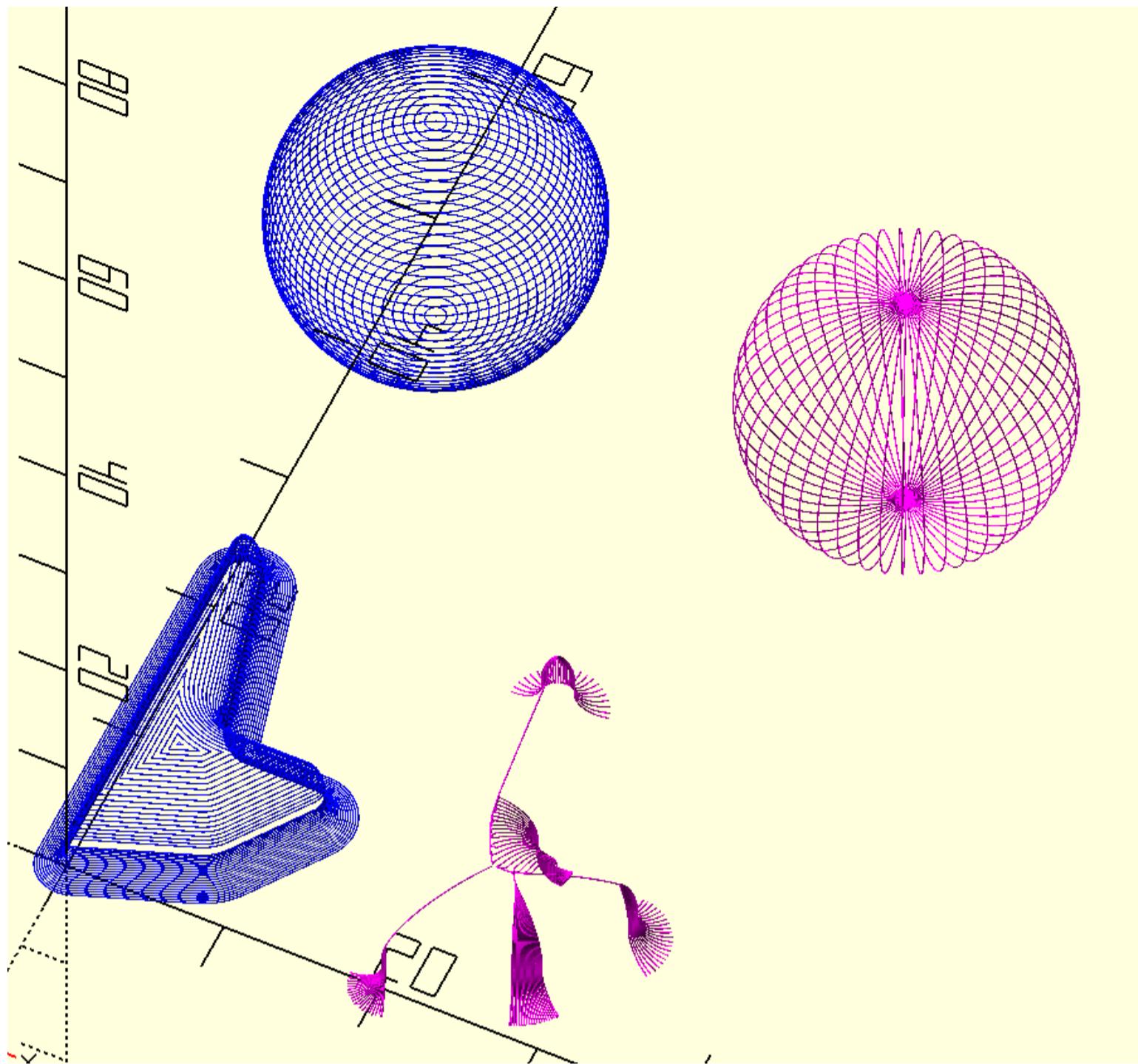
sol=prism(sec,path)
sol1=translate([20,0,0],cpo(sol))

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("blue")for(p={sol})p_line3dc(p,.1,1);
color("magenta")for(p={sol1})p_line3d(p,.1,1);

color("blue")for(p={sp1})p_line3dc(p,.1,1);
color("magenta")for(p={sp2})p_line3d(p,.1,1);

''' )
```



fillet_3p_3d

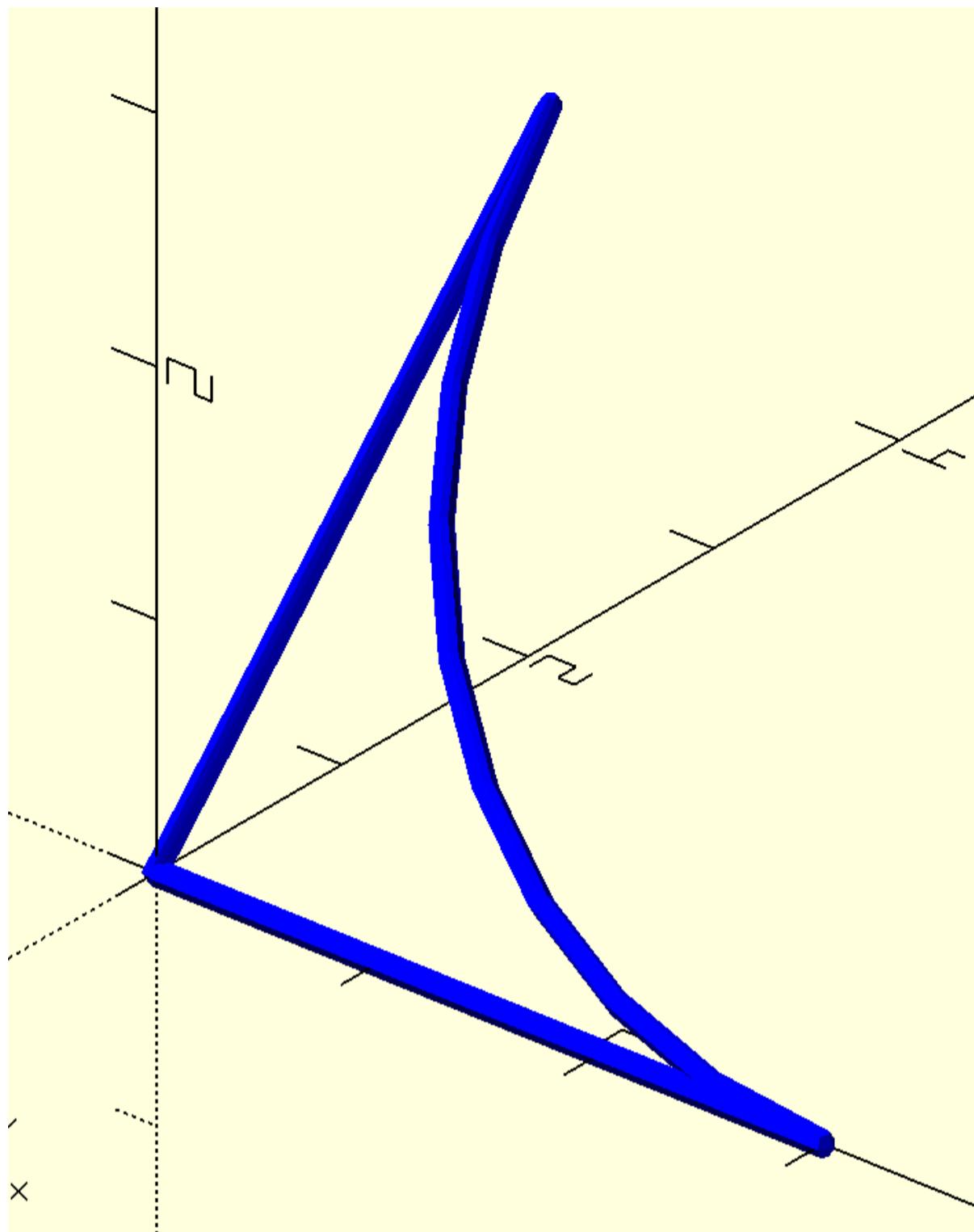
```
In [69]: # example of function fillet_3p_3d(p0,p1,p2,r,s)

p1,p2,p3=[[3,0,0],[0,0,0],[0,3,3]]
fillet=fillet_3p_3d(p1,p2,p3,3,10)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("blue")p_line3dc({fillet},.05);
color("cyan")points({[p1,p2,p3]},.2);

''' )
```



fillet_3p_3d_cp

```
In [70]: # example of function fillet_3p_3d_cp(p0,p1,p2,r)

p1,p2,p3=[[3,0,0],[0,0,0],[0,3,3]]
fillet=fillet_3p_3d(p1,p2,p3,3,10)
centerPoint=fillet_3p_3d_cp(p1,p2,p3,3)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("blue")p_line3dc({fillet},.05);
color("magenta")points({[centerPoint]}),.2);

''' )
```

arc_3p_3d

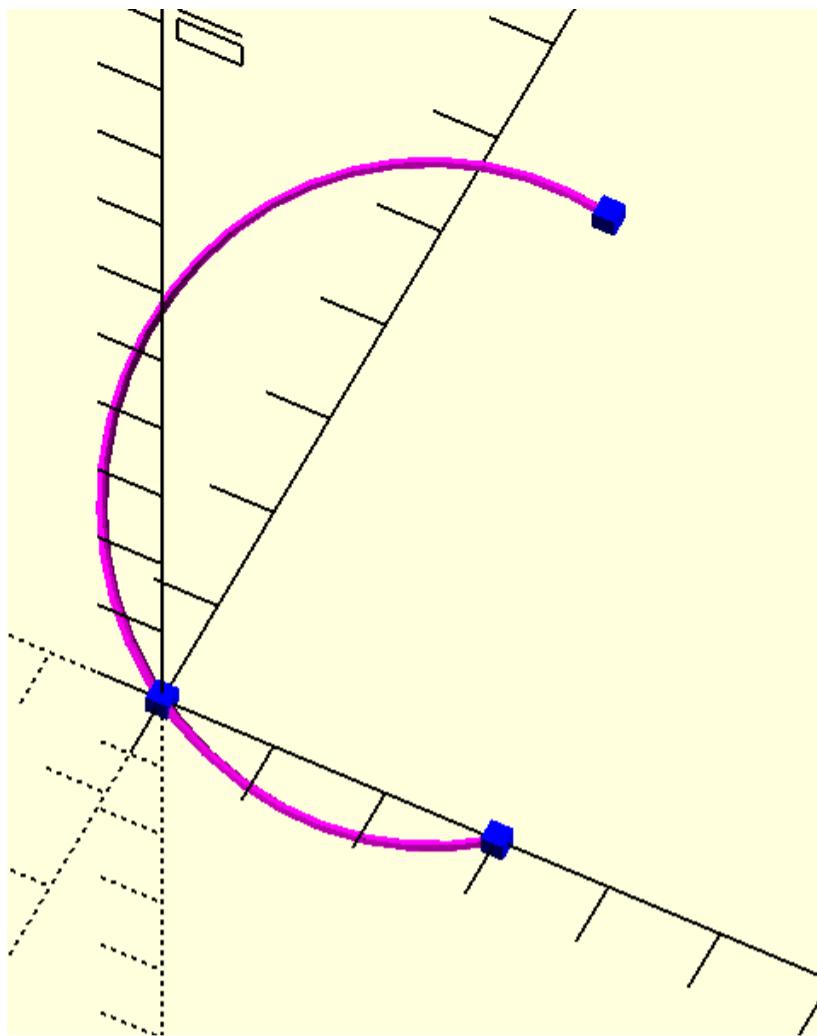
```
In [71]: # example of function arc_3p_3d(points,s)

p1,p2,p3=[[3,0,0],[0,1,0],[5,3,2]]
arc1=arc_3p_3d([p1,p2,p3],30)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("magenta")p_line3d({arc1},.05);
color("blue")points({[p1,p2,p3]}),.2);

''' )
```



cir_3p_3d

cp_cir_3d

```
In [72]: # example of function cir_3p_3d(points,s)

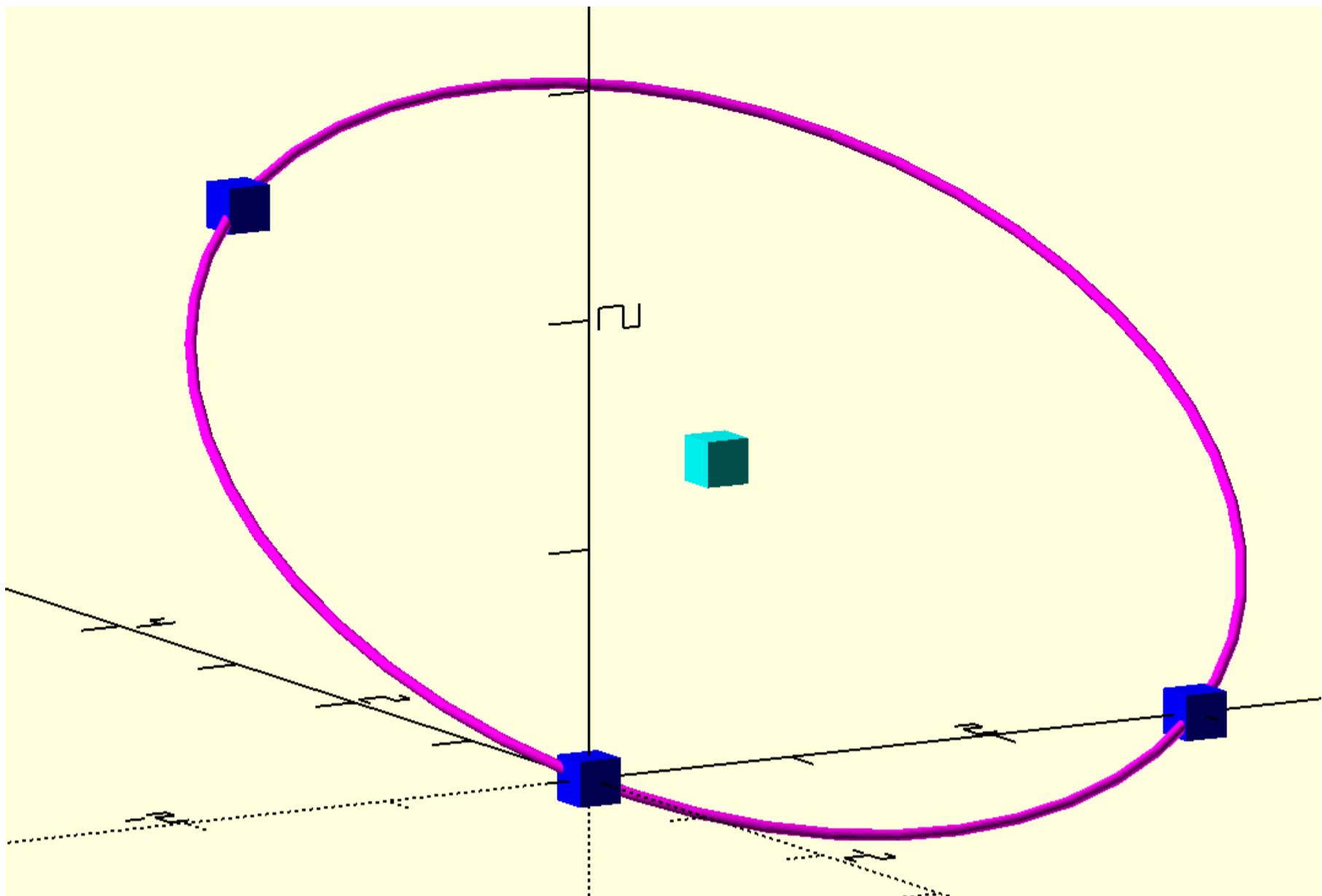
p1,p2,p3=[[3,0,0],[0,0,0],[0,3,2]]
cir=cir_3p_3d([p1,p2,p3],50)

cp1=cp_cir_3d(cir)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("magenta")p_line3dc({cir},.05);
color("blue")points({[p1,p2,p3]},.2);
color("cyan")points({[cp1]},.2);

''' )
```



linear_extrude

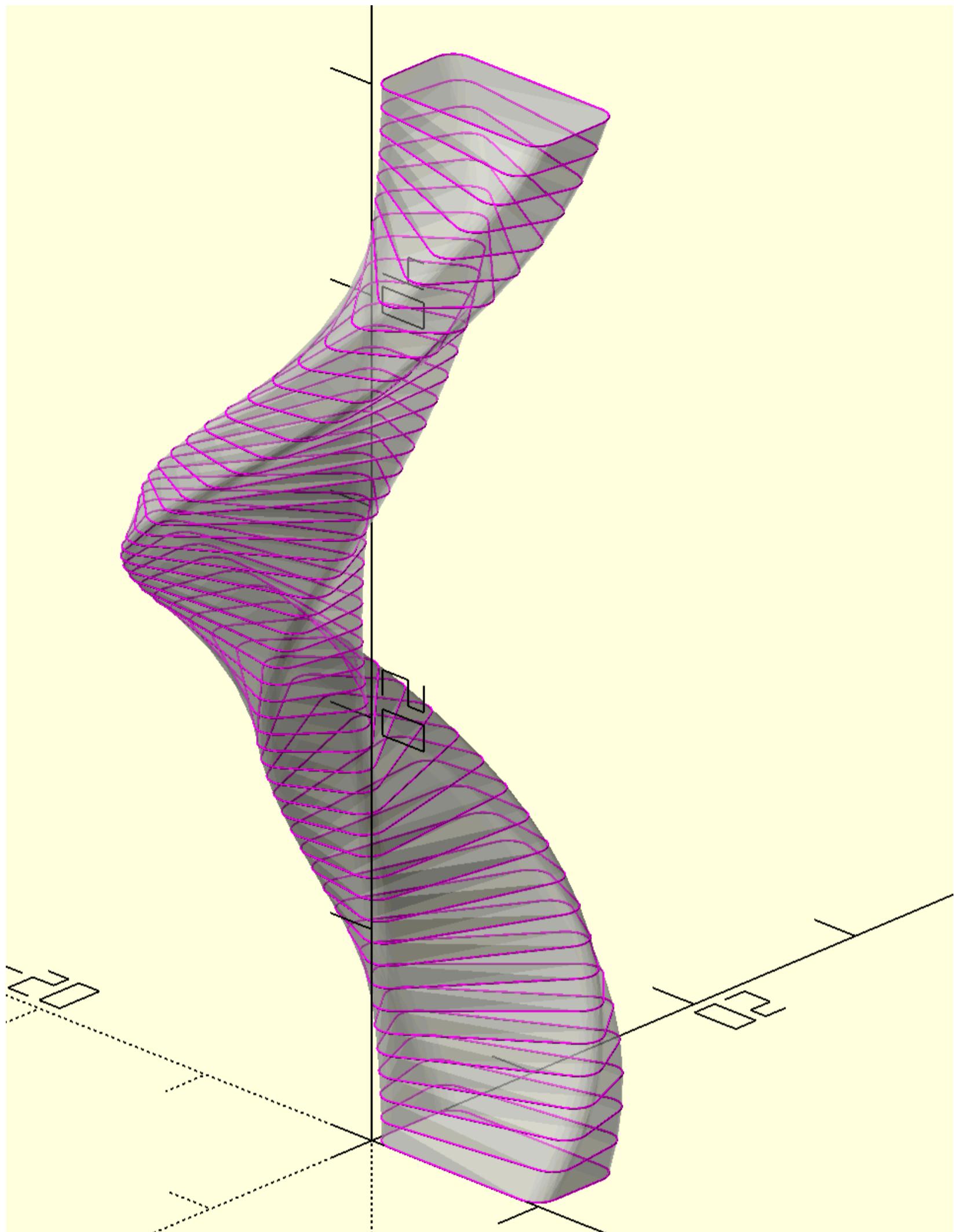
```
In [73]: # example of function linear_extrude(sec,h=1,a=0,steps=1)

sec=corner_radius(pts1([[0,0,1],[10,0,1],[0,5,1],[-10,0,1]]),5)
sol=linear_extrude(sec,50,360,50)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

//color("magenta") for(p={sol})p_line3dc(p,.05);
{swp(sol)}

''' )
```



rsz3d

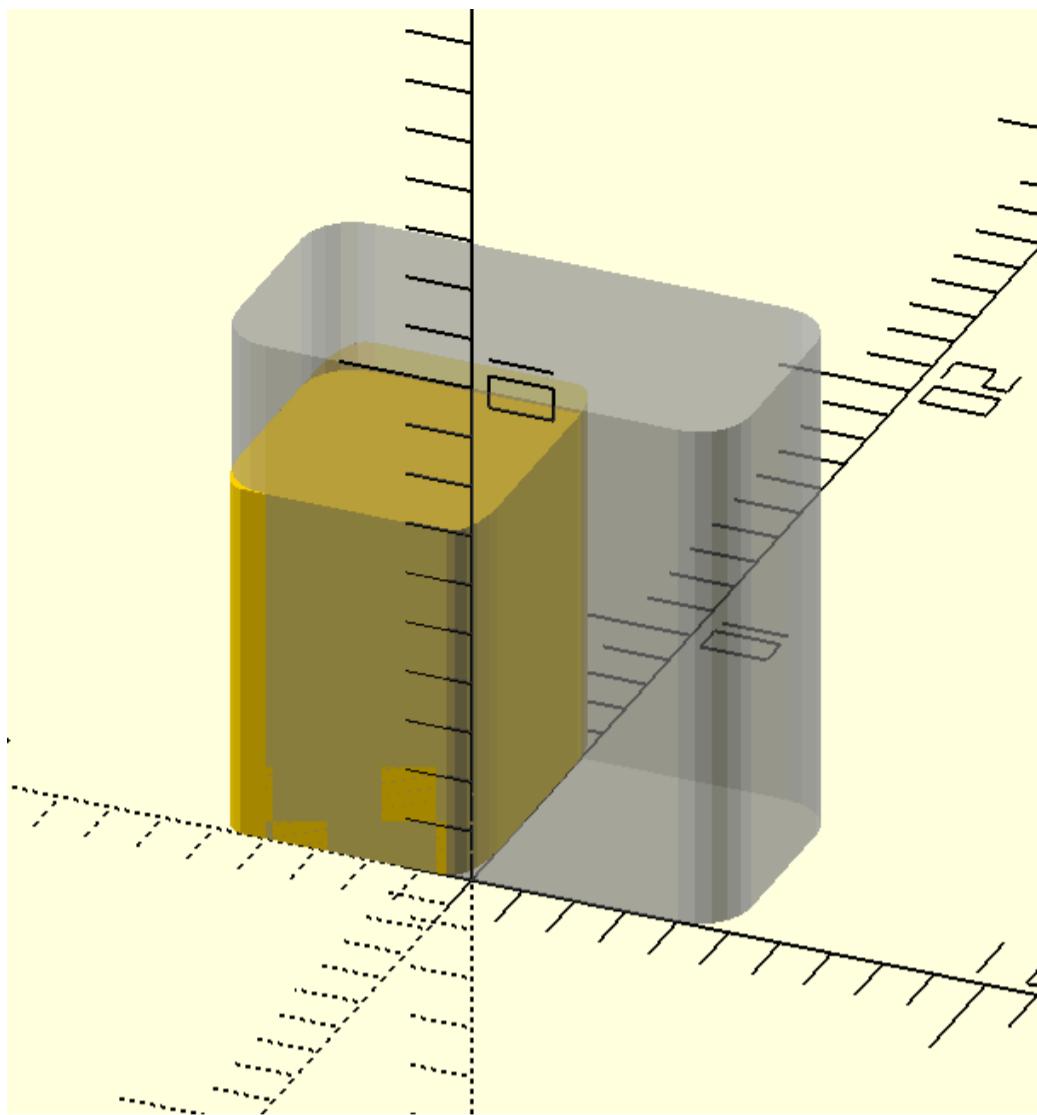
```
In [74]: # example of function rsz3d(prism,rsz)

sec=corner_radius(pts1([[0,0,1],[10,0,1],[0,5,1],[-10,0,1]]),5)
sol=translate([-5,0,0],linear_extrude(sec,10))
sol1=rsz3d(sol,[5,6,7])

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

%{swp(sol)}
{swp(sol1)}

'''')
```



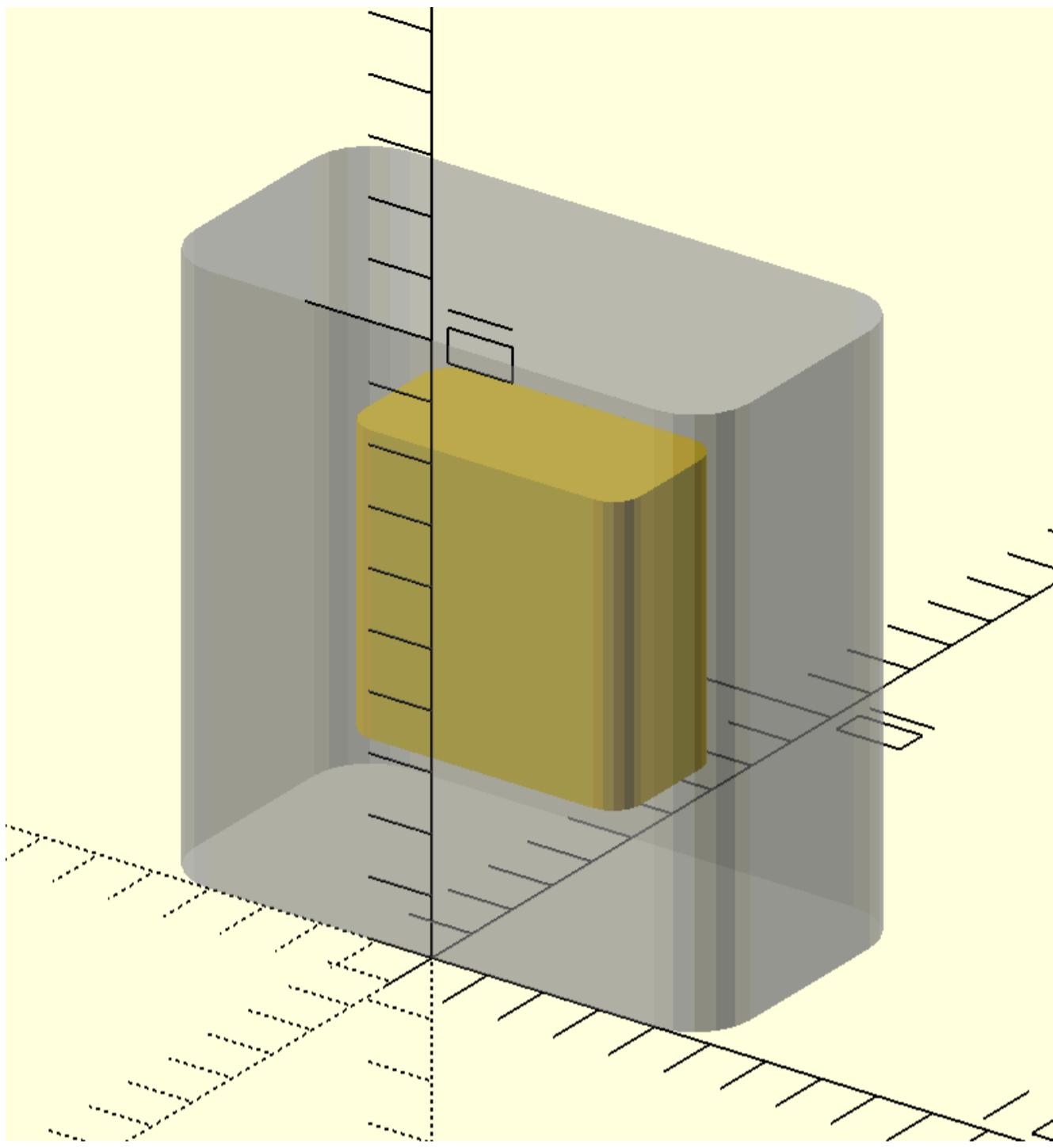
rsz3dc

```
In [75]: # example of function rsz3dc(prism,rsz)

sec=corner_radius(pts1([[0,0,1],[10,0,1],[0,5,1],[-10,0,1]]),5)
sol=translate([-5,0,0],linear_extrude(sec,10))
sol1=rsz3dc(sol,[5,2.5,5])

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

%{swp(sol)}
{swp(sol1)}
''' )
```

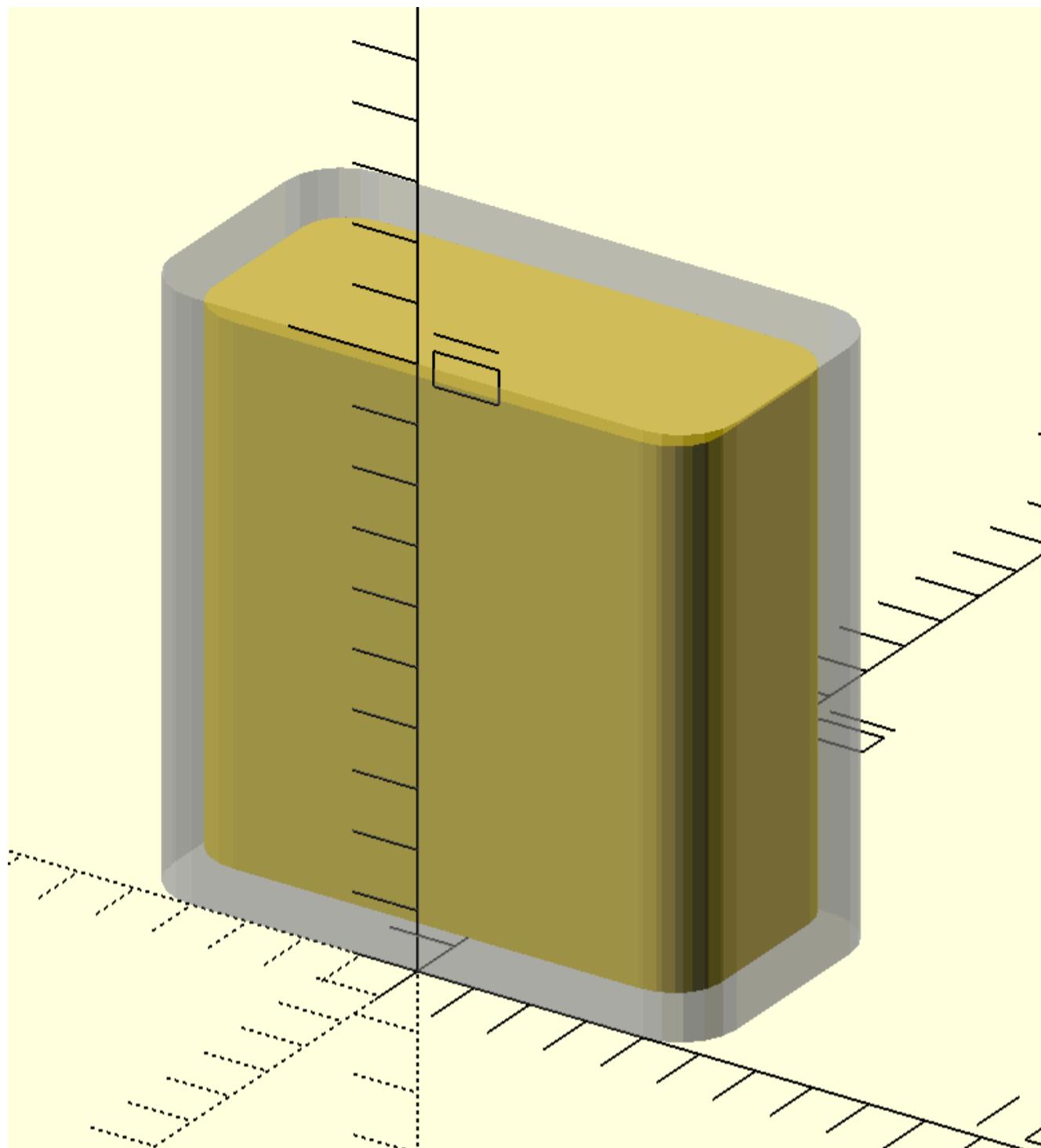


bb

```
In [76]: # example of function bb(prism)
sec=corner_radius(pts1([[0,0,1],[10,0,1],[0,5,1],[-10,0,1]]),5)
sol=translate([-5,0,0],linear_extrude(sec,10))
dim=bb(sol)
sol1=rsz3dc(sol,array(dim)-[2,2,2])

with open('trial.scad', 'w+') as f:
    f.write(f'''
include<dependencies2.scad>

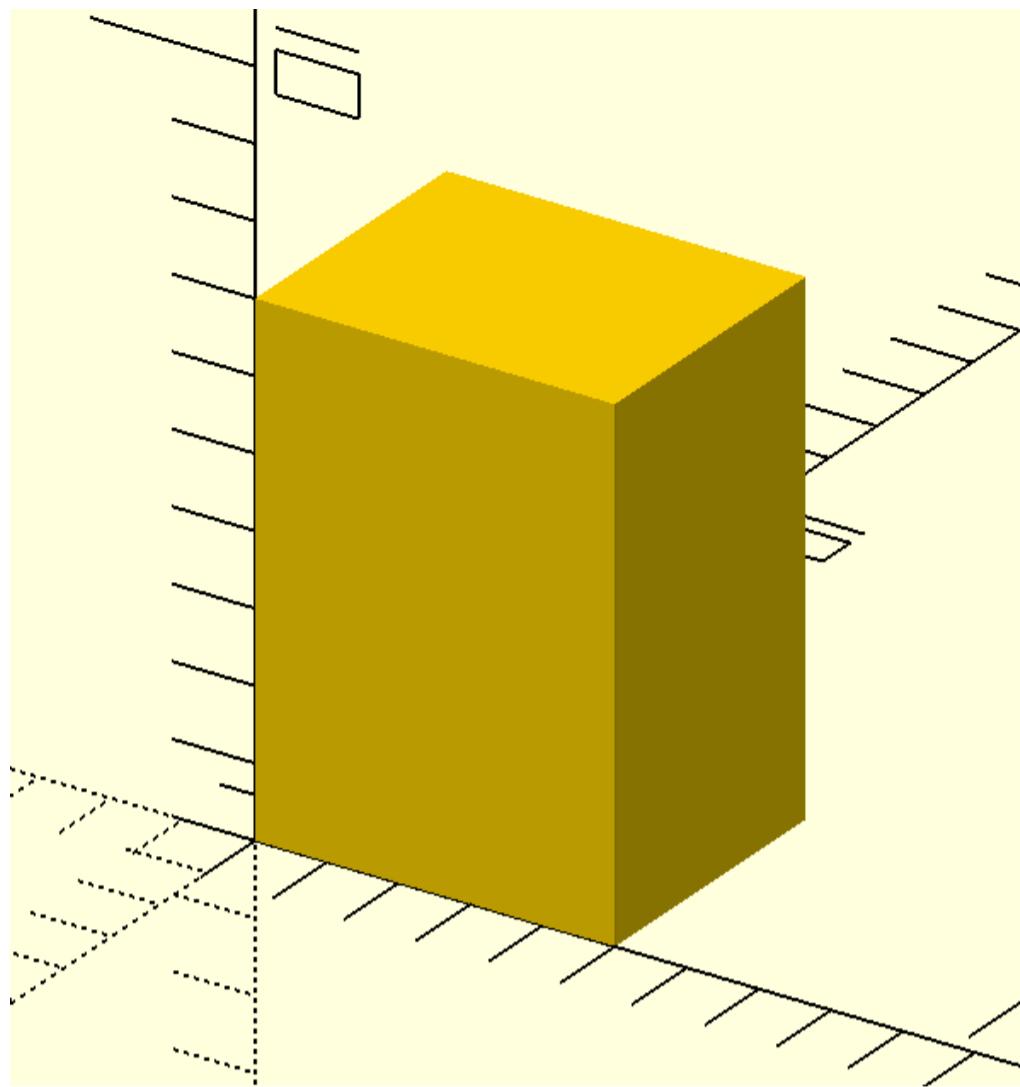
{sweepr(sol)}
{sweepr(sol1)}
...)
```



cube

```
In [77]: # example of function cube(s,center=False)
sol=cube([5,4,7],False)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
{swp(sol)}
''' )
```

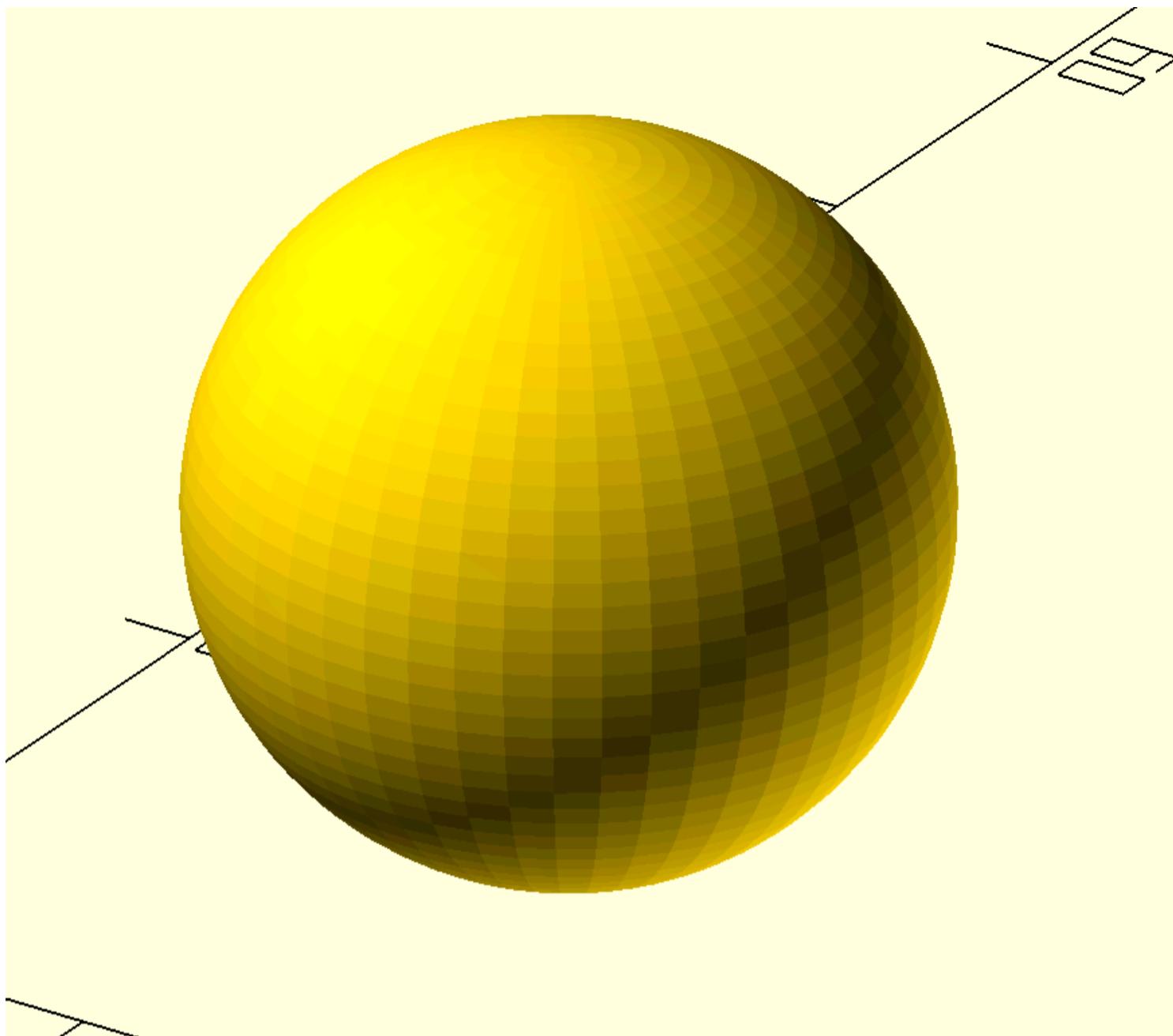


sphere

```
In [78]: # example of function sphere(r=0,c=[0,0,0],s=50)

sol=sphere(10,[15,15,10],30)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
difference(){{{
{swp(sol)}
//cube(10);
}}}
'''')
```

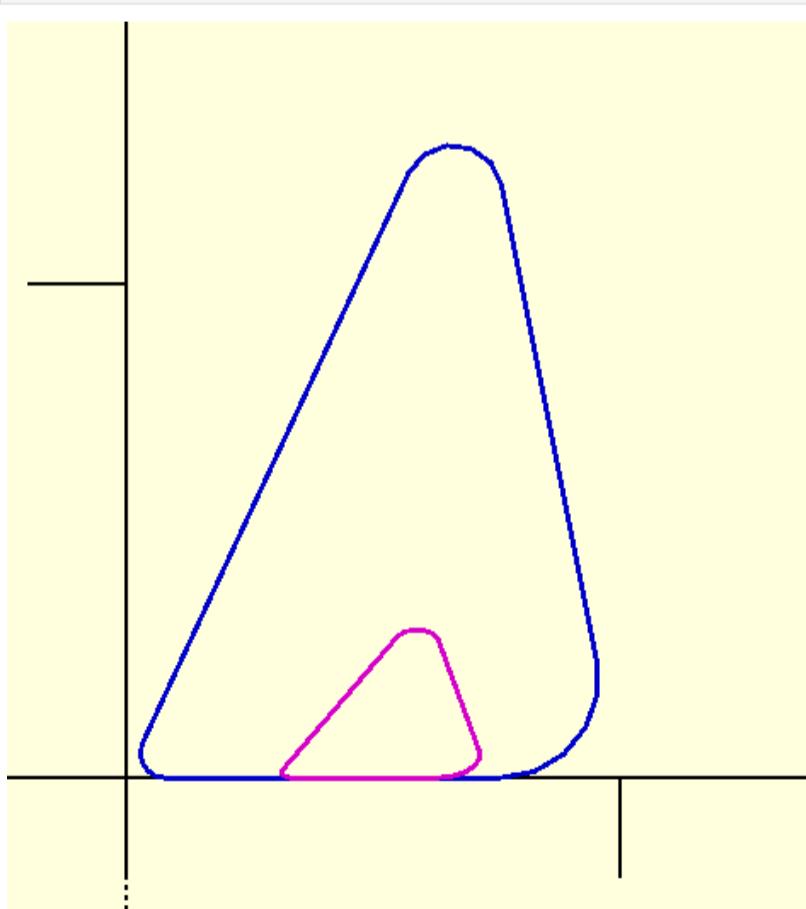


rsz2d

In [79]: # example of function rsz2d(sec,rsz)

```
sec=corner_radius([[0,0,.5],[10,0,2],[7,15,1]],5)
sec1=rsz2d(sec,[4,3])
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line({{sec}},{.1});
color("magenta")p_line({{sec1}},{.1});

'''')
```



rsz2dc

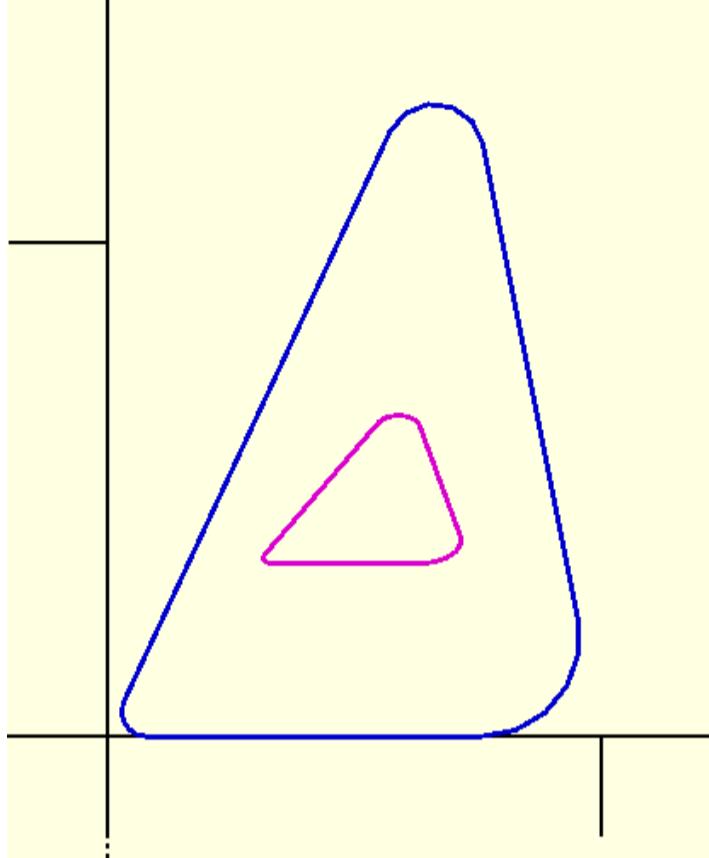
In [80]: # example of function rsz2dc(sec,rsz)

```

sec=corner_radius([[0,0,.5],[10,0,2],[7,15,1]],5)
sec1=rsz2dc(sec,[4,3])
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line({sec},.1);
color("magenta")p_line({sec1},.1);

''' )

```



cs1

```

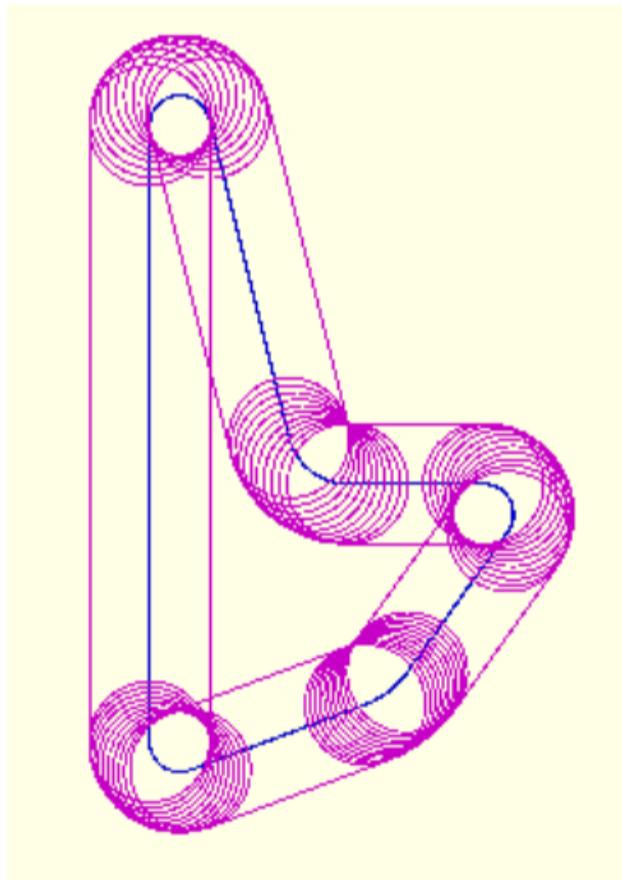
In [81]: # example of function cs1(sec,d) cs1 meaning cleaning section. This function is used in offset function for clearing extra points

sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),10)
# sec=corner_radius(pts1([[0,0,.1],[7,5,2],[5,7,3],[-5,7,5],[-7,5,5]]),20)
# sec=corner_radius(pts1([[-15,0,2.49],[0,15,3],[30,0,3],[0,-15,2.49],[5,0,2.49],[0,20,7],[-40,0,7],[0,-20,2.49]]),20)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line({sec},.1);
color("magenta")for(p={cs1(sec,-2)})p_line(p,.08);

''' )

```



convert_secv1

```

In [82]: # example of function convert_secv1(sec,d)

sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)
sec=sec=corner_radius(pts1([[0,0,1],[7,5,2],[5,7,3],[-5,7,2],[-7,5,3]]),20)
sec=corner_radius(pts1([[-15,0,2.49],[0,15,3],[30,0,3],[0,-15,2.49],[5,0,2.49],[0,20,7],[-40,0,7],[0,-20,2.49]]),20)

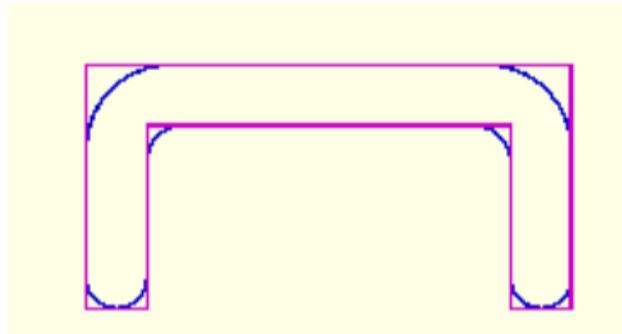
```

```

# sec=circle(10)
# sec=pts([[0,0],[10,0],[0,10],[-10,0]])
sec1=convert_secv1(sec)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line({sec},.3);
color("magenta")p_line({sec1},.3);
...

```



convert_secv

```

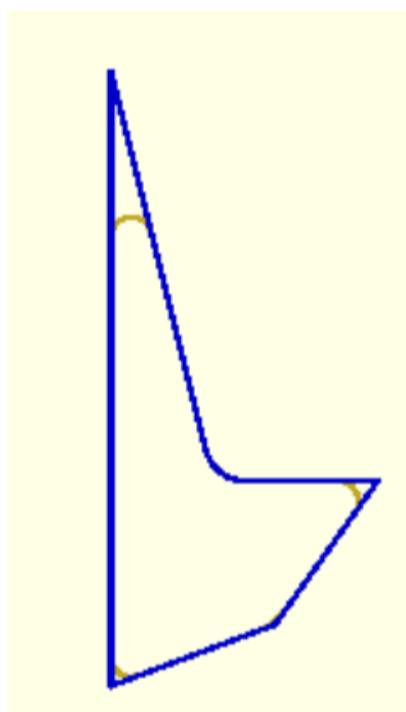
In [83]: # example of function convert_secv(sec)

sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),40)
# sec=sec=corner_radius(pts1([[0,0,.1],[7,5,2],[5,7,3],[-5,7,2],[-7,5,3]]),20)
# sec=corner_radius(pts1([[-15,0,2.49],[0,15,3],[30,0,3],[0,-15,2.49],[5,0,2.49],[0,20,7],[-40,0,7],[0,-20,2.49]]),20)
# sec=circle(10)
# sec=pts([[0,0],[10,0],[0,10],[-10,0]])
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,4.2],[-4.2,0]]),40)
# path=corner_radius(pts1([[2,0],[-2,0,2.2],[0,7,5.3],[-5.3,0]]),40)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,2],[-2,0]]),20)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

p_line({sec},.3);
color("blue")p_line({convert_secv(sec)},.3);
...

```



convert_secv2

```

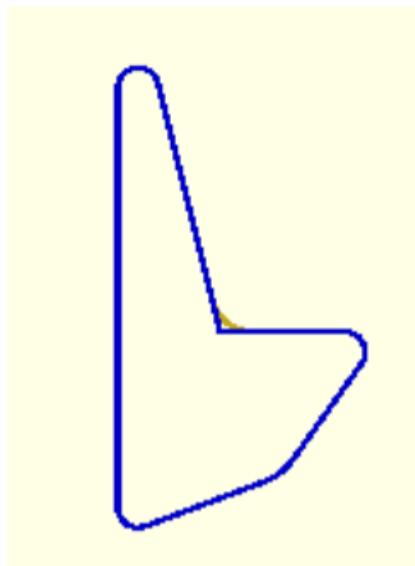
In [84]: # example of function convert_secv2(sec,d)

sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),40)
# sec=sec=corner_radius(pts1([[0,0,.1],[7,5,2],[5,7,3],[-5,7,2],[-7,5,3]]),20)
# sec=corner_radius(pts1([[-15,0,2.49],[0,15,3],[30,0,3],[0,-15,2.49],[5,0,2.49],[0,20,7],[-40,0,7],[0,-20,2.49]]),20)
# sec=circle(10)
# sec=pts([[0,0],[10,0],[0,10],[-10,0]])
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,4.2],[-4.2,0]]),40)
# path=corner_radius(pts1([[2,0],[-2,0,2.2],[0,7,5.3],[-5.3,0]]),40)
# path=corner_radius(pts1([[2,0],[-2,0,2],[0,7,2],[-2,0]]),20)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

p_line({sec},.3);
color("blue")p_line({convert_secv2(sec,5)},.3);
...

```



c2ro

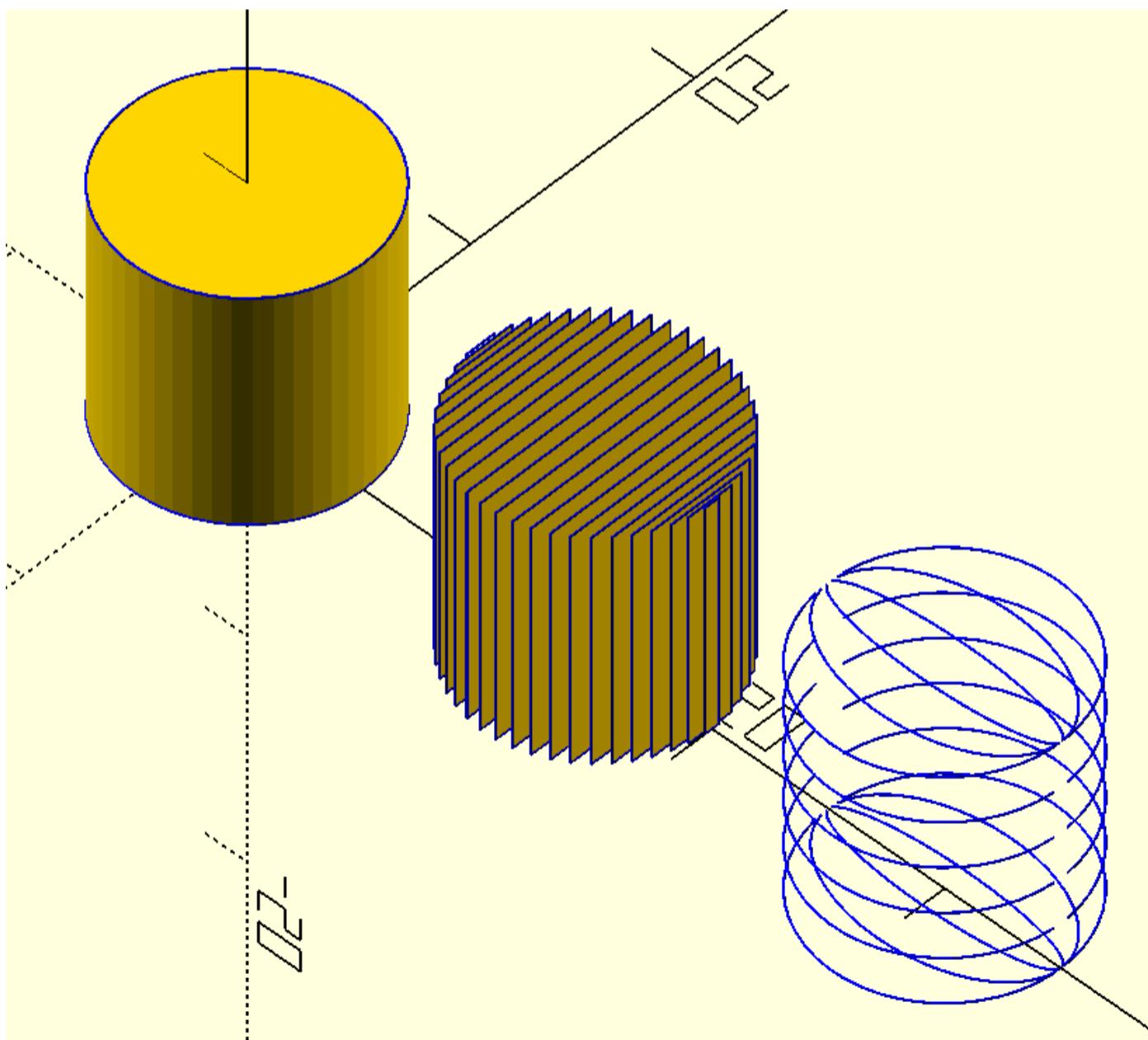
```
In [85]: # example of function c2ro(sol,s), 'c2ro' stands for circular to rectangular orientation
cyl=linear_extrude(circle(5,s=30),10)
cyl1=translate([15,0,0],c2ro(cyl,1))
cyl2=translate([30,0,0],cpo(c2ro(cyl,5)))

with open('trial.scad', 'w+') as f:
    f.write(f'''')
    include<dependencies2.scad>

color("blue")for(p={cyl})p_line3dc(p,.05);
color("blue")for(p={cyl1})p_line3dc(p,.05);
color("blue")for(p={cyl2})p_line3d(p,.05);
swp({cyl});

''')
# for i in range(14):
#     with open('trial.scad', 'a')as f:
#         f.write(f'''')
#         {swp(cyl1[i:i+1])}

#     {swp(cyl)}
#
# ''')
```



```
In [86]: # example of function c2ro(sol,s)
sp=sphere(5,s=21)
```

```

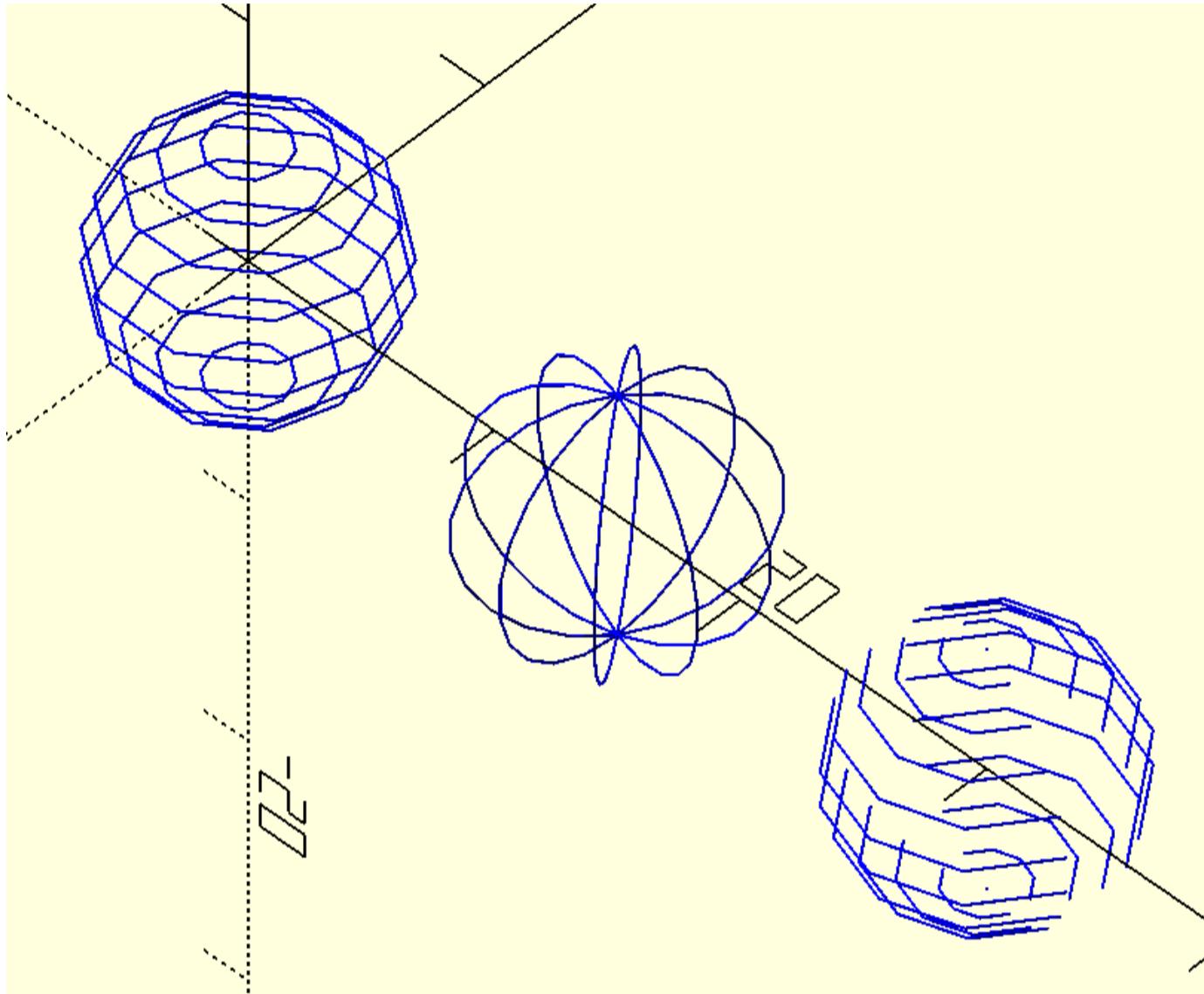
sp1=translate([15,0,0],c2ro(sp,3))
sp2=translate([30,0,0],cpo(c2ro(sp,3)))

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

color("blue")for(p={sp})p_line3dc(p,.1);
color("blue")for(p={sp1})p_line3dc(p,.1);
color("blue")for(p={sp2})p_line3d(p,.1);

    ''')

```



```

In [107... # application of function c2ro(sol, s) for creating fillet between 2 cylinders
sec=circle(5,s=50)
path=corner_radius(pts1([[-1,2],[1,0,1],[0,10,1],[-1,0]]),10)

sol1=linear_extrude(circle(10,s=100),14)

sol2=translate([10,0,0],c2ro(prism(sec,path),10))

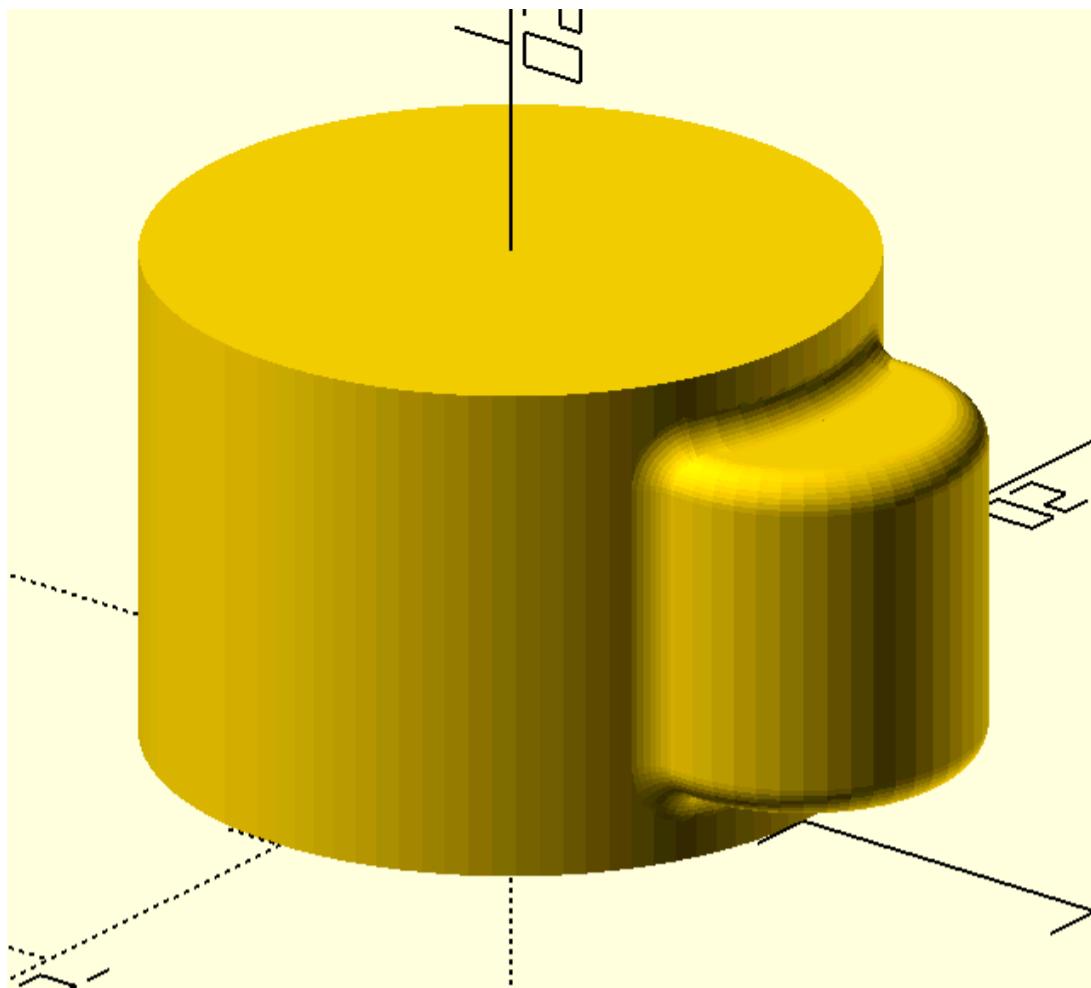
sol3=translate([10,0,0],prism(sec,path))

l1=ip_sol2sol(sol1,sol2)
l2=o_3d_rev(l1,sol1,1,o=1)
l3=o_3d_rev(l1,sol2,1,o=1)
f1=convert_3lines2fillet(l3,l2,l1)
f1=f1+[f1[0]]

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
{swp(sol3)}
{swp(sol1)}
{swp(f1)}
//color("magenta")for(p={[l1,l2,l3]})p_line3d(p,.1,1);

//color("blue")for(p={cpo(sol2)})p_line3d(p,.02);
//color("blue")for(p={f1})p_line3dc(p,.02);
    ''')

```



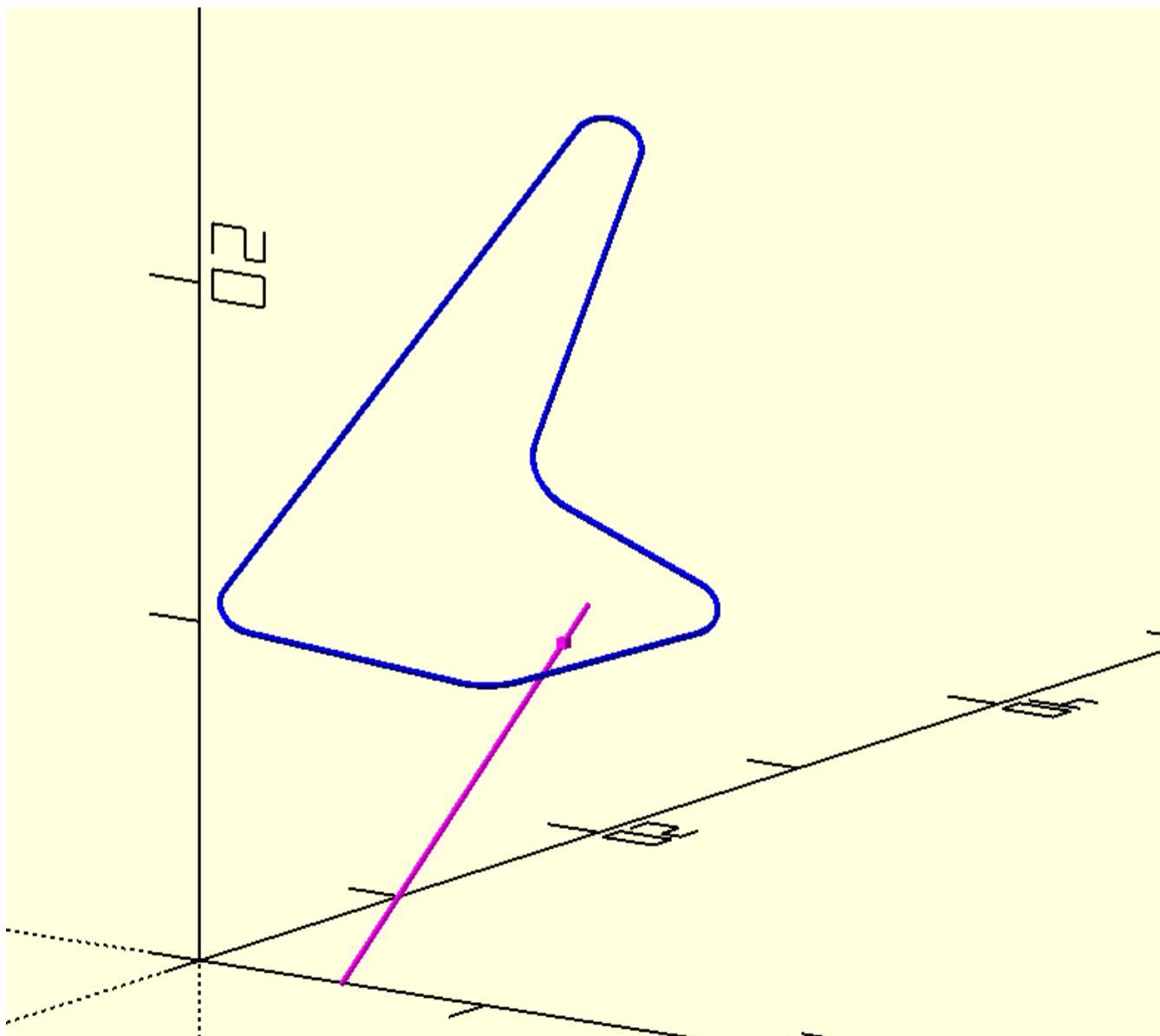
sl_int

```
In [108... # example of function sl_int(sec,line)

sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)
sec=translate([0,0,10],q_rot(['y30','x30'],sec))
line=[[5,0,0],[8,8,10]]
ip_1=sl_int(sec,line)

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line3dc({sec},.1);
color("magenta")p_line3d({line},.1);
color("magenta")points({ip_1},.3);

    ''')
```



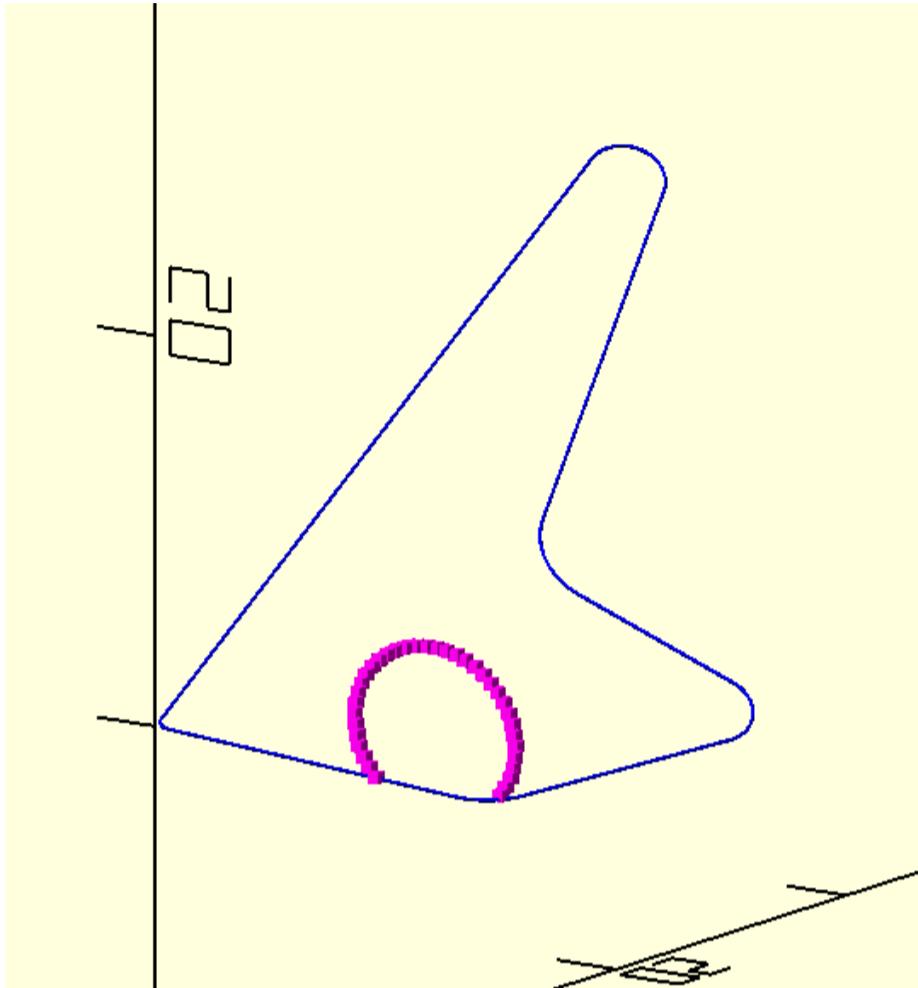
```
In [109... sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)
sec=translate([0,0,10],q_rot(['y30','x30'],sec))
sol=cpo(linear_extrude(circle(2,[5,9],s=50),20))
```

```

# lines=array(sol).reshape(-1,2,3)
ip_1=[sl_int(sec,line) for line in sol if sl_int(sec,line)!=[]]
ip_1=concatenate(ip_1).tolist()
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
polyhedron({sec},{{arange(len(sec)).tolist()}});
color("blue")p_line3dc({sec},.05);
color("magenta")points({ip_1},.1);
%{swp(cpo(sol))}

    ''')

```



axis_rot

```

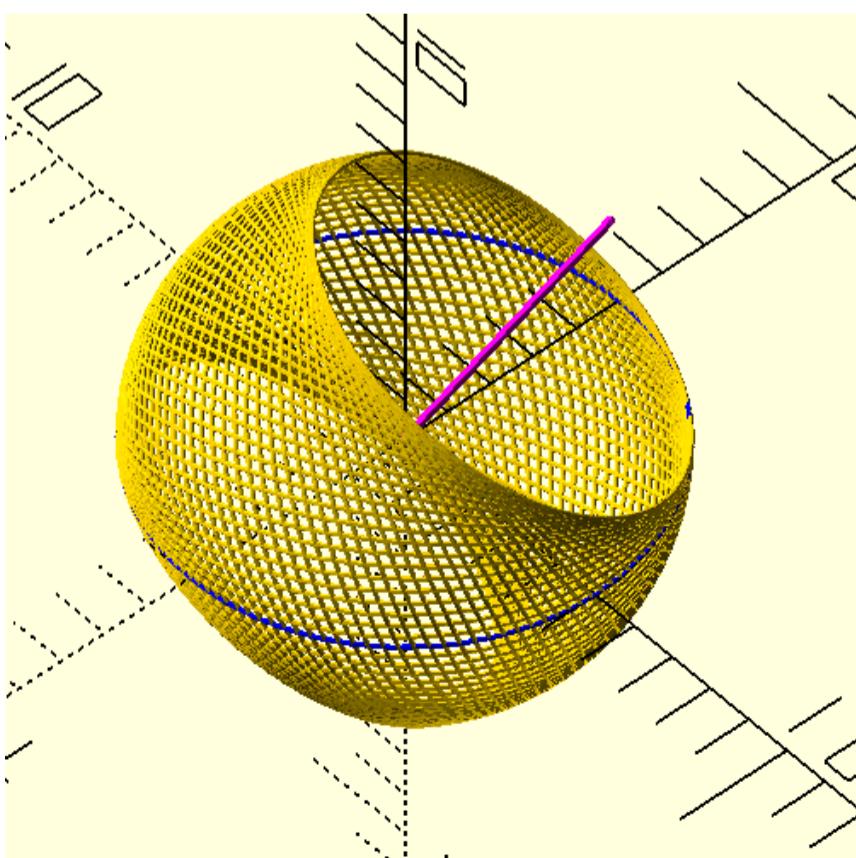
In [110]: # example of function axis_rot(axis,solid,angle)
vector=[2,3,5]
# sec=translate([-5,5,0],circle(5))
sec=path_extrude_closed(circle(.05),c2t3(circle(5)))
sec1=[path_extrude_closed(circle(.05),axis_rot(vector,circle(5),i)) for i in arange(0,360,20)]

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

for(p={sec1})swp(p);
//original section
color("blue"){swp(sec)}
// axis of rotation
color("magenta")p_line3d({[[0,0,0],vector]},.1);

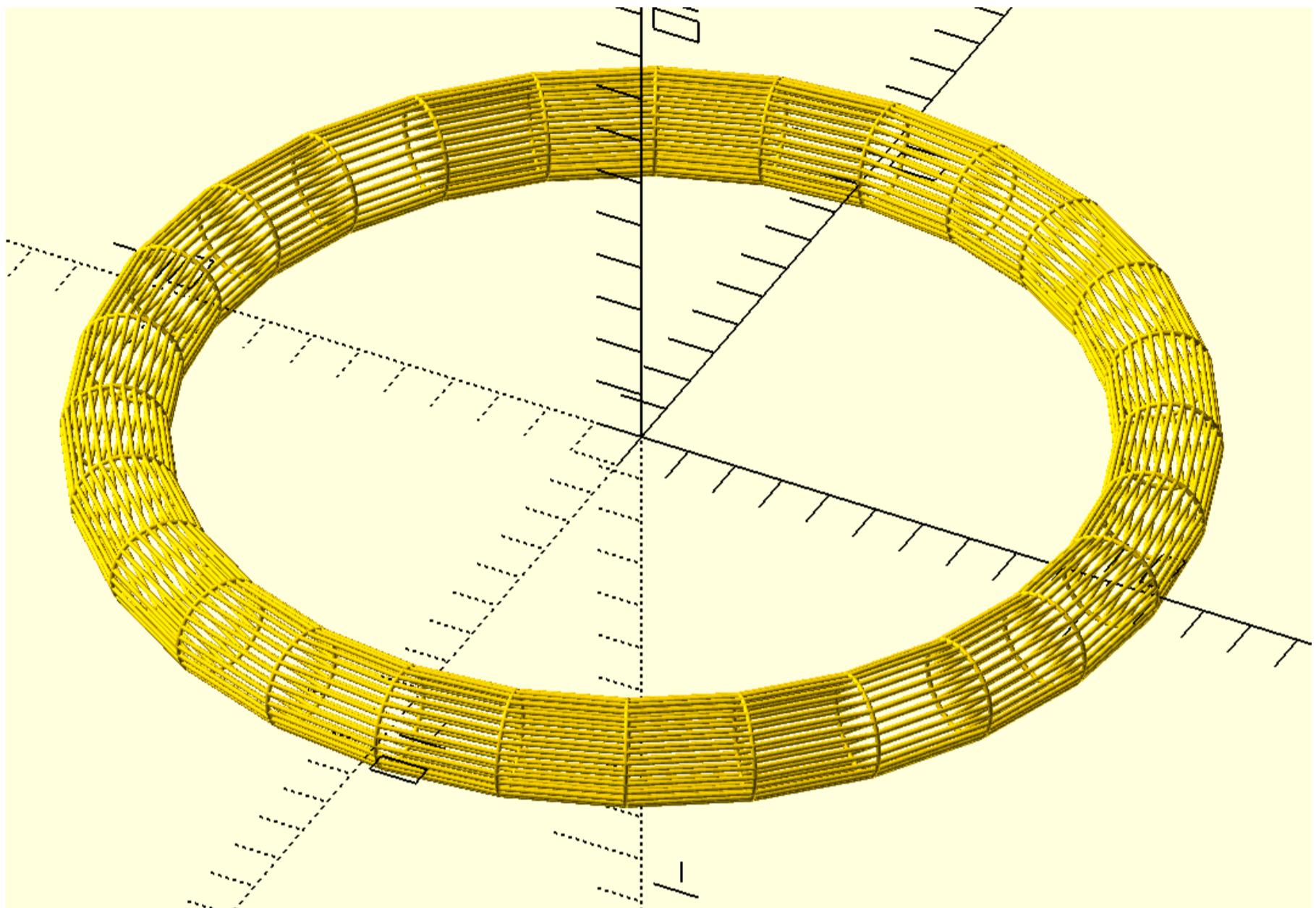
    ''')

```



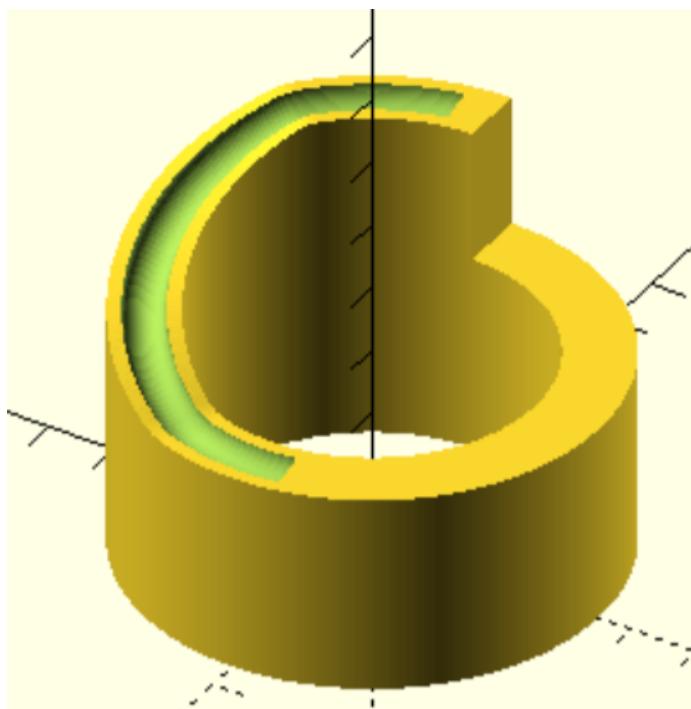
path_extrude_closed

```
In [111...]  
sec=circle(1,s=20)  
path=c2t3(circle(10,s=20))  
sol1=path_extrude_closed(sec,path)  
  
with open('trial.scad','w+')as f:  
    f.write(f'''  
include<dependencies2.scad>  
$fn=20;  
for(p={sol1})p_line3dc(p,.05);  
for(p={cpo(sol1)})p_line3dc(p,.05);  
    ''')
```



cam-profile

```
In [112...]  
# example of cam profile  
  
l_1=corner_radius(pts1([[0,50],[90,0,100],[180,-20,100],[360,0]]),30)  
l_1=q_rot(['x90'],equidistant_path(l_1,360))  
p1=c2t3(arc(30,0,362,s=360))  
l_2=extrude_wave2path(l_1,p1)  
l_3=[[-5,0],[5,0]]  
surf_1=path_extrude_open(l_3,l_2)  
surf_2=c2t3(c3t2(surf_1))  
sol_1=[surf_2[i]+flip(surf_1[i]) for i in range(len(surf_1))]  
c1=circle(3)  
sol_2=path_extrude_open(c1,l_2[10:190])  
  
with open('trial.scad','w+')as f:  
    f.write(f'''  
include<dependencies2.scad>  
  
difference(){  
{swp(sol_1)}  
{swp(sol_2)}  
}  
    ''')
```

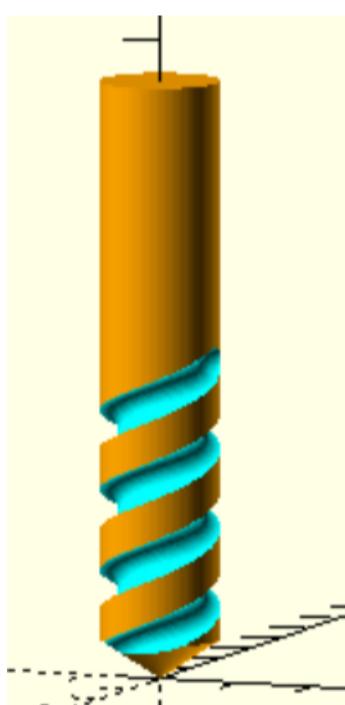


drill-bit

```
In [113... # drill bit
sec=circle(7.5,s=100)
path=pts([[-7.49*cos(360/200*pi/180),0],[7.5,5],[0,70]])
sol=prism(sec,path)
hx1=helix(7.5,20,2,5)
hx2=q_rot(['z180'],hx1)
with open('trial.scad','w+')as f:
    f.write(f'''
        include<dependencies2.scad>
//    render(){{

difference(){
    color("orange"){swp(sol)}
    color("cyan")p_line3d({hx1},4.5,$fn=70);
    color("cyan")p_line3d({hx2},4.5,$fn=70);

}
//  }}
...
''' )
```



bottle-with-cut-design

```
In [114... # bottle with cut design
i_t=time.time()
sec=circle(10,s=50)
path=corner_radius(pts1([[[-3,0,0],[3,0,3],[3,5,7],[-5,20,100],[8,30,20],[-11,10,5],[0,10,0]]]),50)
path=equidistant_path(path,100)
sol=prism(sec,path)

sec1=corner_radius(pts1([[[-7.5,10,3],[15,0,3],[0,20,30],[-3,20,30],[0,10,4.4],[-9,0,4.4],[0,-10,30],[-3,-20,30]]]),20)
sec1=equidistant_pathc(sec1,200)
path1=corner_radius(pts1([[1,0],[-1,0,1],[-1,1,2],[-2,0]]),10)
path1=equidistant_path(path1,10)
surf_1=f_prism(sec1,path1)

l1=equidistant_path([[0,15],[0,55]],10)
l1=equidistant_pathc(translate([0,0,1],surround(l1,.2,10)),200)
l1=align_sec_1(surf_1[-1],l1)[1]
# l1=sort_points(surf_1[-1],l1)
surf_1=surf_1[:-1]+slice_sol([surf_1[-1],l1],5)[1:]
# sol3=translate([0,0,-1.5],surf_1)
# sol2=flip(sol3)+surf_1#[flip(sol3)[0]]
sol2=surf_1
```

```

path=equidistant_path(q_rot(['y90'],path),100)
sol2=[wrap_around(p,path) for p in sol2]
sol2=translate([0,8.61,0],q_rot(['z90'],sol2))
path2=q_rot(['y90'],circle(10,s=200))
sol2=[wrap_around(p,path2) for p in sol2]
sol2=q_rot(['y90'],sol2)
sol3=translate(surface_normal(sol2[:2],2),sol2)
sol4=flip(sol3)+sol2

surf_2=surf_offset(sol2,.5)
surf_3=sol3=translate(surface_normal(sol2[:2],2),surf_2)
path=corner_radius(pts1([-3,0,0],[3,0,3],[3,5,7],[-5,20,100],[8,30,20],[-11,10,5],[0,10,0])),50)
path=equidistant_path(path,100)
sol_5=prism(sec,path_offset(path,-.5))
sol_6=flip(surf_3)+surf_2

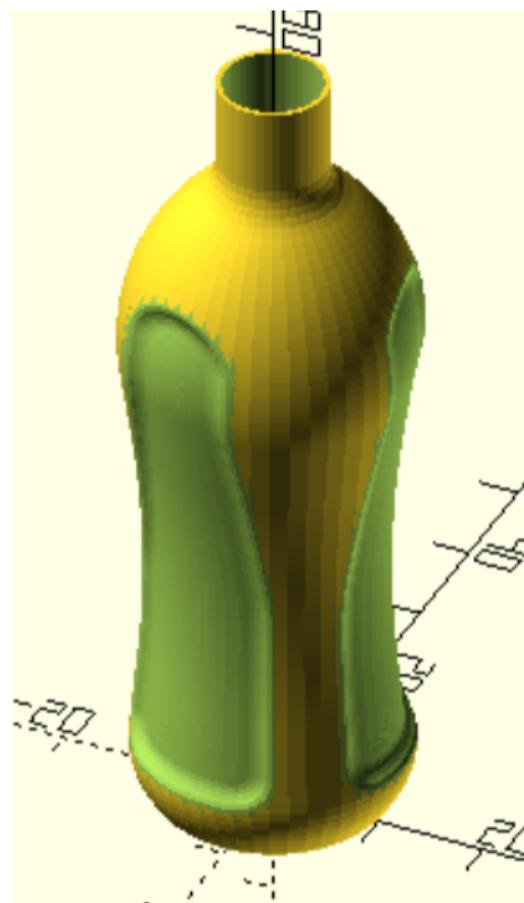
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>

        difference() {{
            union() {{
                difference() {{
                    difference() {{
                        {swp(sol)}
                        for(i=[0,120,240])rotate([0,0,i])
                    {swp(sol4)}
                }}
            translate([0,0,.01])
            difference() {{
                {swp(sol_5)}
                for(i=[0,120,240])rotate([0,0,i])
                {swp(sol_6)}
            }}
        }}
    }}
    //{{swp(cut_plane([0,-1,0],[300,300],100,theta=[0,0,20]))}}
}
    ''')

f_t=time.time()
f_t-i_t

```

Out[114... 1.321993112564087



psos

reorient_sec

prism2cpo

```

In [115... # example use of function psos (project a surface on to another without loosing the original points)
it=time.time()
# designing bottle with cut design
sec=circle(10,s=100)
path=corner_radius(pts1([-3,0],[3,0,3],[3,5,7],[-5,20,100],
                     [8,30,20],[-11,10,5],[0,10,0])),30)
path=equidistant_path(path,100)
sol=prism(sec,path)

sec1=corner_radius(pts1([-7.5,10,3],[15,0,3],[0,20,30],
                      [-3,20,30],[0,10,4.4],[-9,0,4.4],
                      [0,-10,30],[-3,-20,30])),10)

sec1=equidistant_pathc(sec1,100)

```

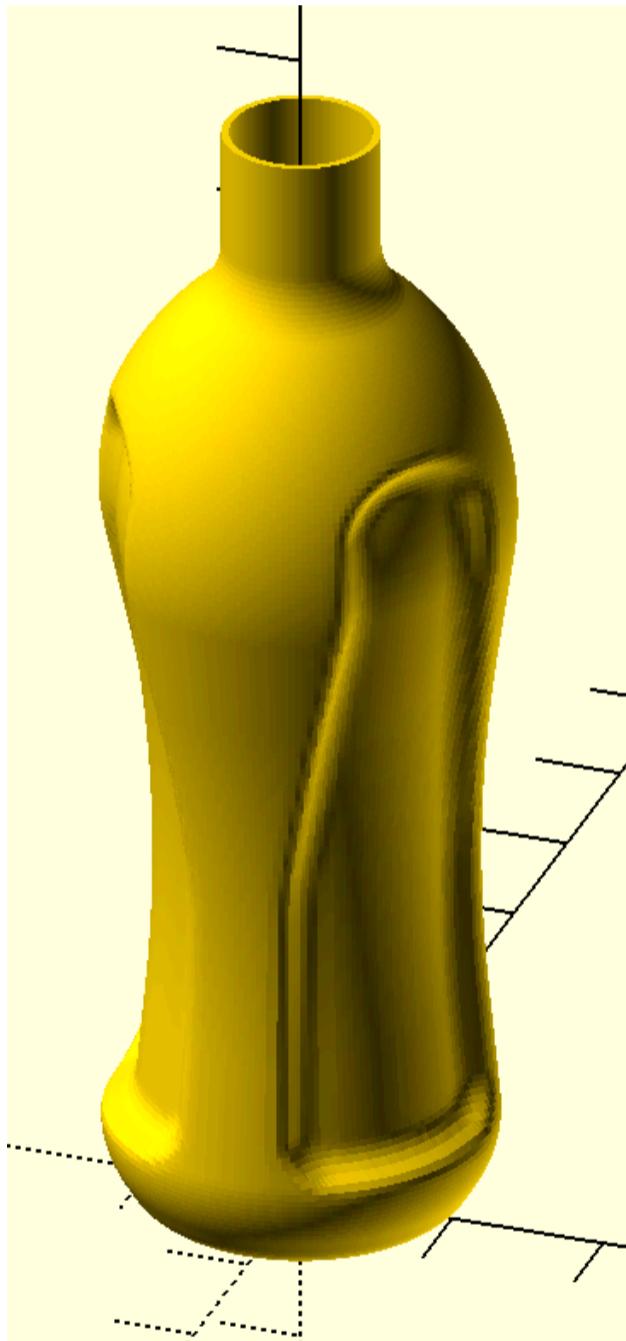
```

sec1=reorient_sec(sec1)
path1=corner_radius(pts1([[1,0],[-1,0,1],[-1,2,2],[-2,0]]),10)
path1=equidistant_path(path1,10)
surf1=prism2cpo(prism(sec1,path1))
s1=[equidistant_path(p,100) for p in surf1]
p1=q_rot(['y90'],path)
s1=[wrap_around(p,p1) for p in s1]
s1=translate([0,10,0],q_rot(['z-90'],s1))
p2=q_rot(['y90'],circle(10,s=200))
s1=[wrap_around(p,p2) for p in s1]
s1=q_rot(['y-90','z30'],s1)
sol=psos(s1,sol,[0,-1,0])
s1=q_rot(['z120'],s1)
v1=q_rot(['z120'],[0,-1,0])
sol=psos(s1,sol,v1)
s1=q_rot(['z120'],s1)
v1=q_rot(['z240'],[0,-1,0])
sol=psos(s1,sol,v1)
sol1=[offset_3d(p,-.5) for p in sol]
bottle=sol+flip(sol1)[:16]
with open('trial.scad','w+') as f:
    f.write(f'''
{s1}
    ''')

ft=time.time()
ft-it

```

Out[115... 18.741971969604492



example-of-rounding

```

In [116... # m37 rounded
i_t=time.time()
sec=[[i,3*sin(i*18*pi/180)] for i in arange(-20,20,.5)]
path=[[i,0,20+3*sin(i*12*pi/180)] for i in arange(-30,30,.5)]

surf=surf_extrude(sec,path)
surf1=surf_base(surf,0)
sec1=corner_radius(pts1([[0,0,2],[20,0,2],[0,20,2]]),40)
sec1=equidistant_pathc(sec1,200)
sol1=linear_extrude(sec1,40)
ip1=remove_extra_points(array(ip_surf(surf,sol1)).round(5))
fillet1=i_line_fillet(surf1,sol1,ip1,-1,1,s=10)
sol2=flip(solid_from_fillet_closed(fillet1,3))
with open('trial.scad','w+')as f:
    f.write(f'''
        include<dependencies2.scad>
difference(){{{
    intersection(){{{

```

```

{swp(surf_base(surf,0))}

{swp(sol1)}
}

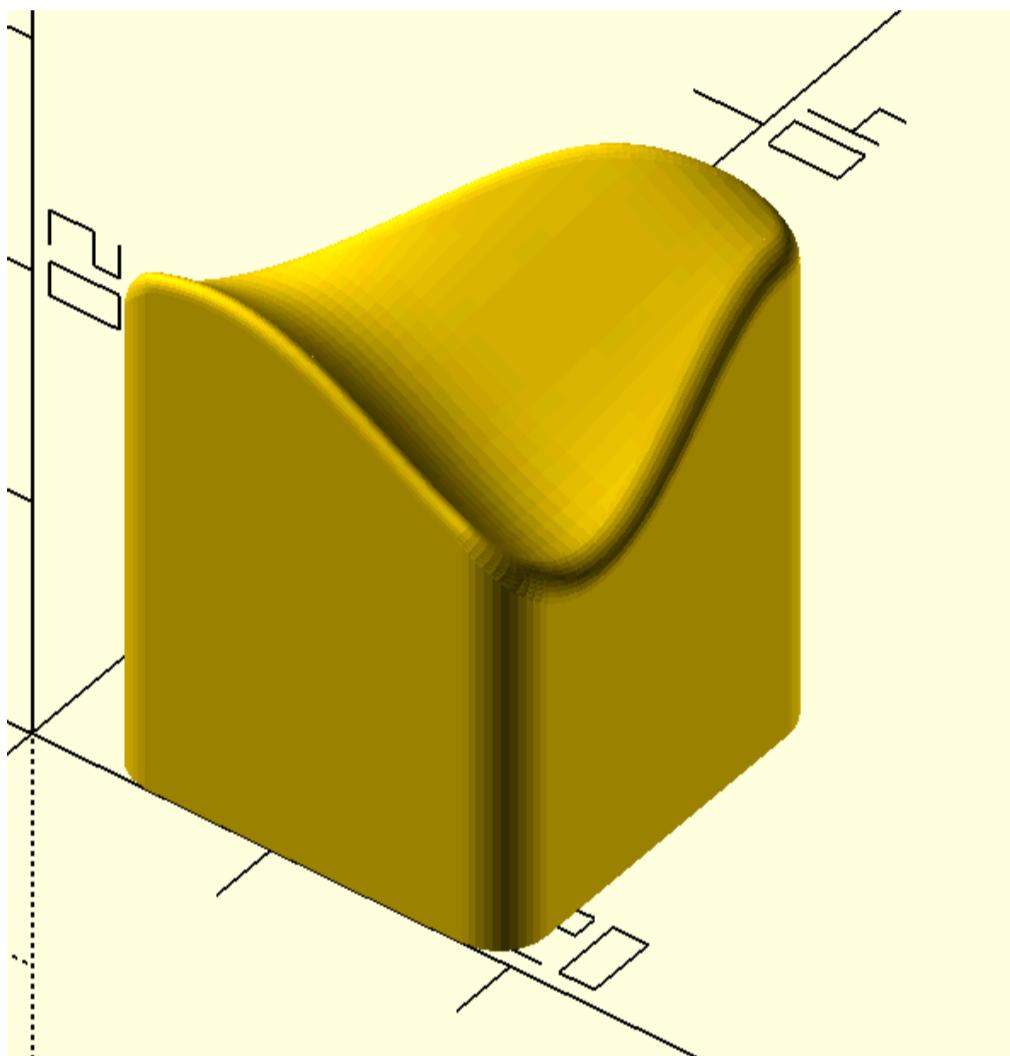
{swp_c(sol2)}
}

'''')
f_t=time.time()
f_t-i_t

/Users/sanjeevprabhakar/openscad/openscad2.py:4774: RuntimeWarning: divide by zero encountered in divide
    t=einsum('kl,ijkl->ijk',cross(p01,p02),la[:, :,None]-p0)/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad2.py:4775: RuntimeWarning: divide by zero encountered in divide
    u=einsum('ijkl,ijkl->ijk',cross(p02[None,None,:,:],(-lab)[[:,None,:]),(la[:, :,None,:]-p0[None,None,:,:]))/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad2.py:4776: RuntimeWarning: divide by zero encountered in divide
    v=einsum('ijkl,ijkl->ijk',cross((-lab)[[:,None,:],p01[None,None,:,:]),(la[:, :,None,:]-p0[None,None,:,:]))/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad2.py:4776: RuntimeWarning: invalid value encountered in divide
    v=einsum('ijkl,ijkl->ijk',cross((-lab)[[:,None,:],p01[None,None,:,:]),(la[:, :,None,:]-p0[None,None,:,:]))/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad2.py:4777: RuntimeWarning: invalid value encountered in add
    condition=(t>=0)&(t<=1)&(u>=0)&(u<=1)&(v>=0)&(v<=1)&(u+v<1)
/Users/sanjeevprabhakar/openscad/openscad2.py:4779: RuntimeWarning: invalid value encountered in multiply
    a=(la[:, :,None,:]+lab[:,None,:,None])*t[:,None,:,:None])

```

Out[116... 3.8964879512786865



m39

```

# m39
i_t=time.time()
p0=i_p2d(pts([[-45,0],[0,1]]),cir_theta_line(10,[-35,0],16.5,1))
p1=i_p2d(cir_theta_line(10,[-35,0],16.5,1),cir_theta_line(10,[35,0],-16.5,1))
p2=i_p2d(pts([[45,0],[0,1]]),cir_theta_line(10,[35,0],-16.5,1))
p3=[45,35]
p4=i_p2d([p3,p_cir_t(p3,circle(10,[0,44.06]))],[cir_p_t(circle(10,[0,44.06]),[-45,35]),[-45,35]])
p5=[-45,35]
p_l=array(c2t3([p0,p1,p2,p3,p4,p5]))
p_l=p_l+array([[0,0,i] for i in [10,32.5,10,10,10,10]])
sec1=corner_radius(p_l,20)

p0,p1,p2,p3,p4,p5=offset([p0,p1,p2,p3,p4,p5],-2.5)

c1,c2,c3=[circle(7.5,i) for i in [[-35,0],[35,0],[0,44.06]]]
a1=flip(fillet_l_cir([p0,p1],c1,2.5,10)[1])
a2=fillet_intersection_lines([p0,p1],[p2,p1],35,20)
a3=fillet_l_cir([p1,p2],c2,2.5,10)[0]
a4=flip(fillet_l_cir([p2,p3],c2,2.5,10)[1])
a3_1=arc_2p(a3[-1],a4[0],7.5,1,20)
a5=fillet_intersection_lines([p2,p3],[p4,p3],7.5,10)
a6=fillet_l_cir([p3,p4],c3,2.5,10)[0]
a7=flip(fillet_l_cir([p4,p5],c3,2.5,10)[1])
a6_1=arc_long_2p(a6[-1],a7[0],7.5,1,40)
a8=fillet_intersection_lines([p4,p5],[p0,p5],7.5,10)
a9=fillet_l_cir([p5,p0],c1,2.5,10)[0]
a10=arc_2p(a9[-1],a1[0],7.5,1,20)
sec2=a1+a2+a3+a3_1+a4+a5+a6+a6_1+a7+a8+a9+a10
sec2=remove_extra_points(array(sec2).round(4))

c4,c5,c6=[circle(5,i) for i in [[-35,0],[35,0],[0,44.06]]]
path1=corner_radius(pts1([[-1.25,0],[1.25,0,1.25],[0,10,1.25],[-1.25,0]]),10)

```

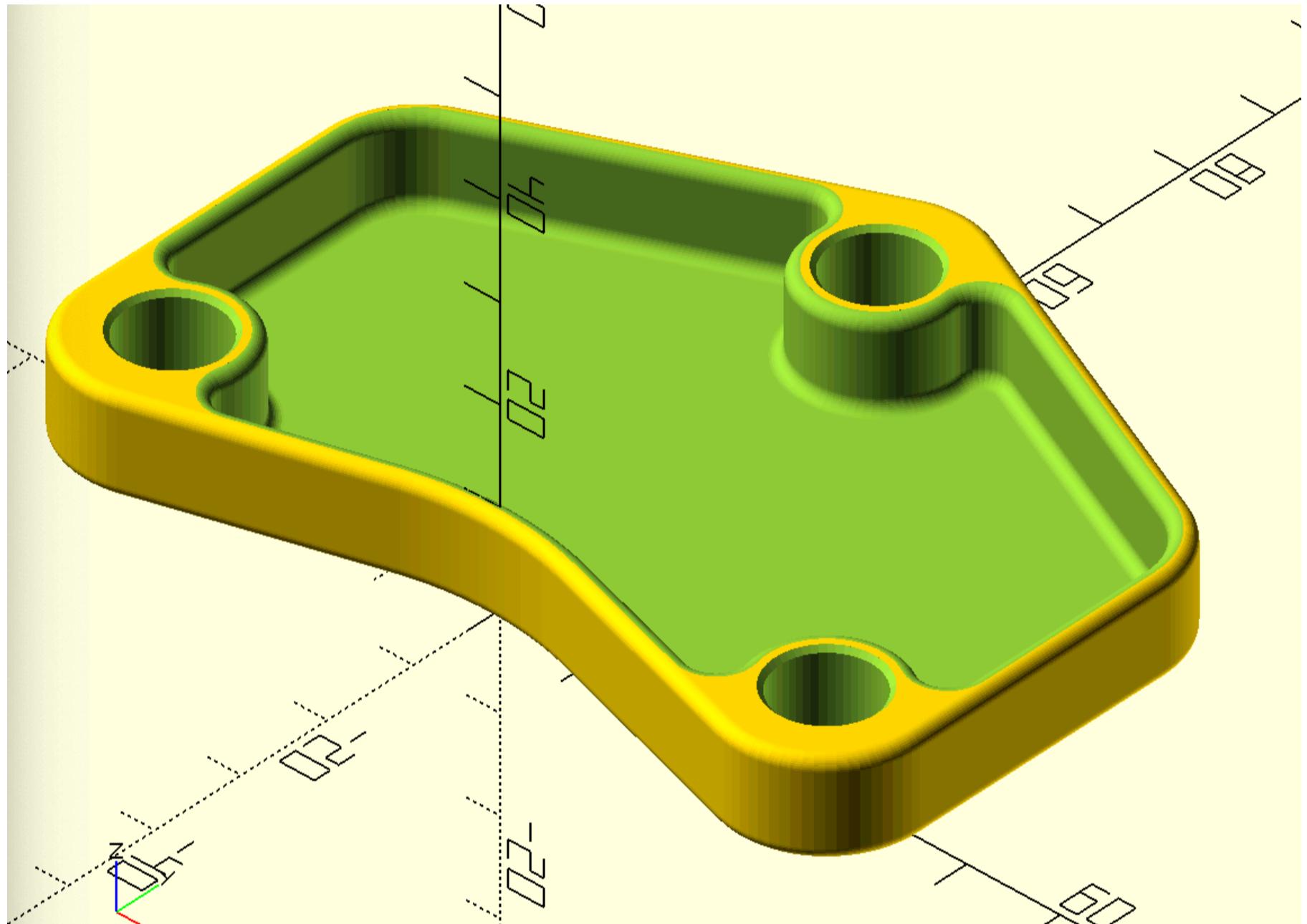
```

sol1=f_prism(sec1,path1)
path2=corner_radius(pts1([[-1.25,1.25],[1.25,0,1.25],[0,10-1.25,1.25],[1.25,0],[0,.2]]),10)
sol2=f_prism(sec2,path2)

path3=corner_radius(pts1([[0.5,-.2],[0,0.2],[-.5,.5],[0,9],[.5,.5],[0,.2]]),5)
sol3=[f_prism(s,path3) for s in [c4,c5,c6]]
with open('trial.scad','w+') as f:
    f.write(f'''')
include<dependencies2.scad>
difference() {{
    {swp(sol1)}
    {swp(sol2)}
    for(p={sol3}) swp(p);
}}
'''')
f_t=time.time()
f_t-i_t

```

Out[117...]: 1.0521118640899658



cylinder-with-rectangular-pocket

```

In [127...]: # cylinder with rectangular pocket
t=2 #thickness
n=100 # number of segments in the circle
s=[15,25] #size of the pocket
cir=circle(20,s=n)
path=corner_radius(pts1([[t/2,0,t/2],[0,80,t/2-.001],[-t,0,t/2-.001],[0,-80,t/2]]),20)
sol1=prism(cir,path)
sol1=sol1+[sol1[0]]

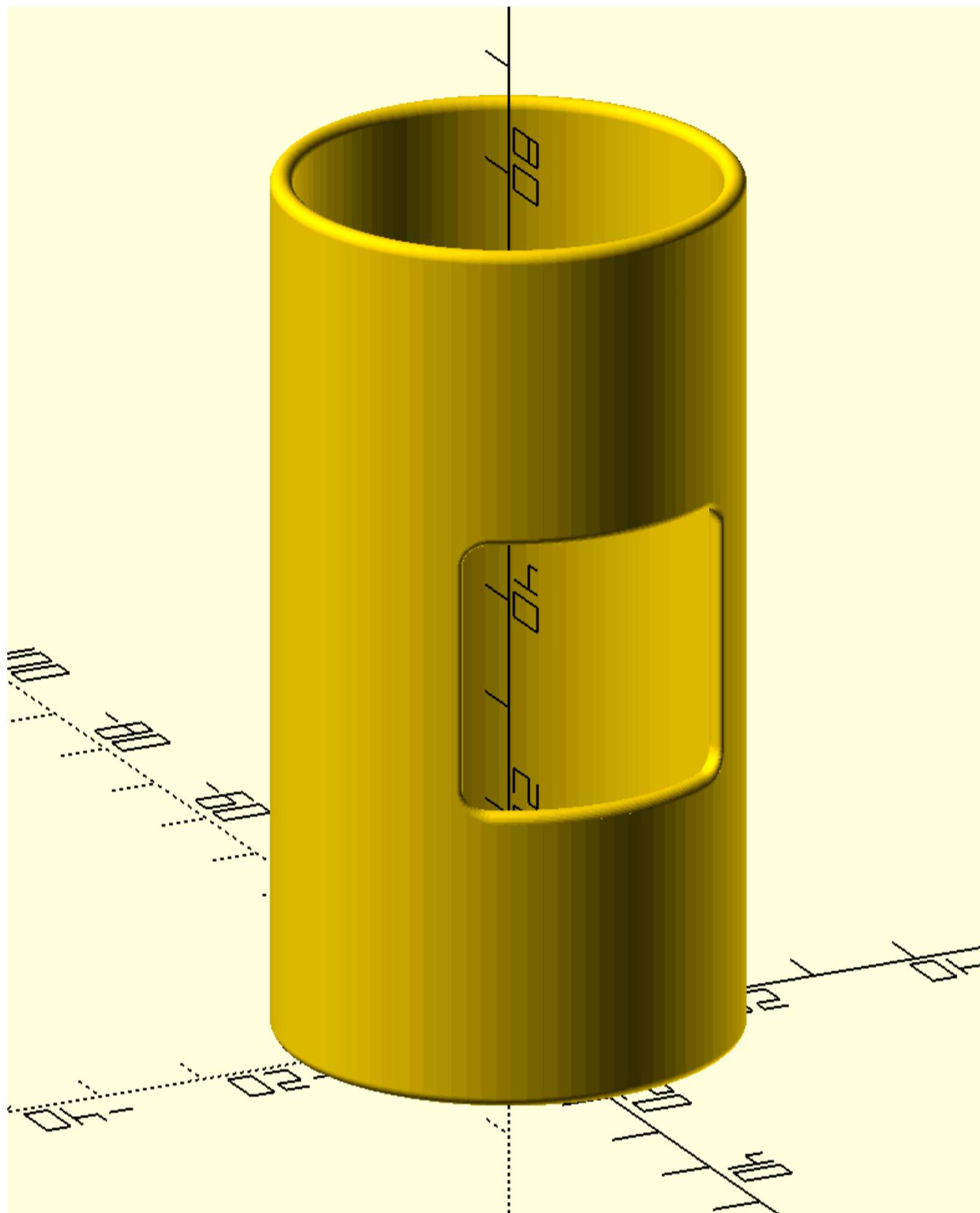
sec1=corner_radius(pts1([[-s[1]/2,-s[0]/2,t],[s[1],0,t],[0,s[0],t],[-s[1],0,t]]),10)
sol2=translate([0,0,40],q_rot(["y90"],linear_extrude(m_points(sec1,.51),40)))

fillet1=cpo(ip_fillet(sol1,flip(sol2),-t/2,t/2))[:-1]
fillet2=cpo(ip_fillet(flip(sol1),sol2,-t/2,t/2))[:-1]
sol3=flip([translate([5,0,0],fillet1[0])]+fillet1+flip(fillet2)+[translate([-5,0,0],fillet1[0])])

with open('trial.scad','w+') as f:
    f.write(f'''')
include<dependencies2.scad>

difference() {{
    {swp_c(sol1)}
    {swp(sol3)}
}}
'''')

```



cylinder-with-star-pocket

```
In [126]: # cylinder with star pocket

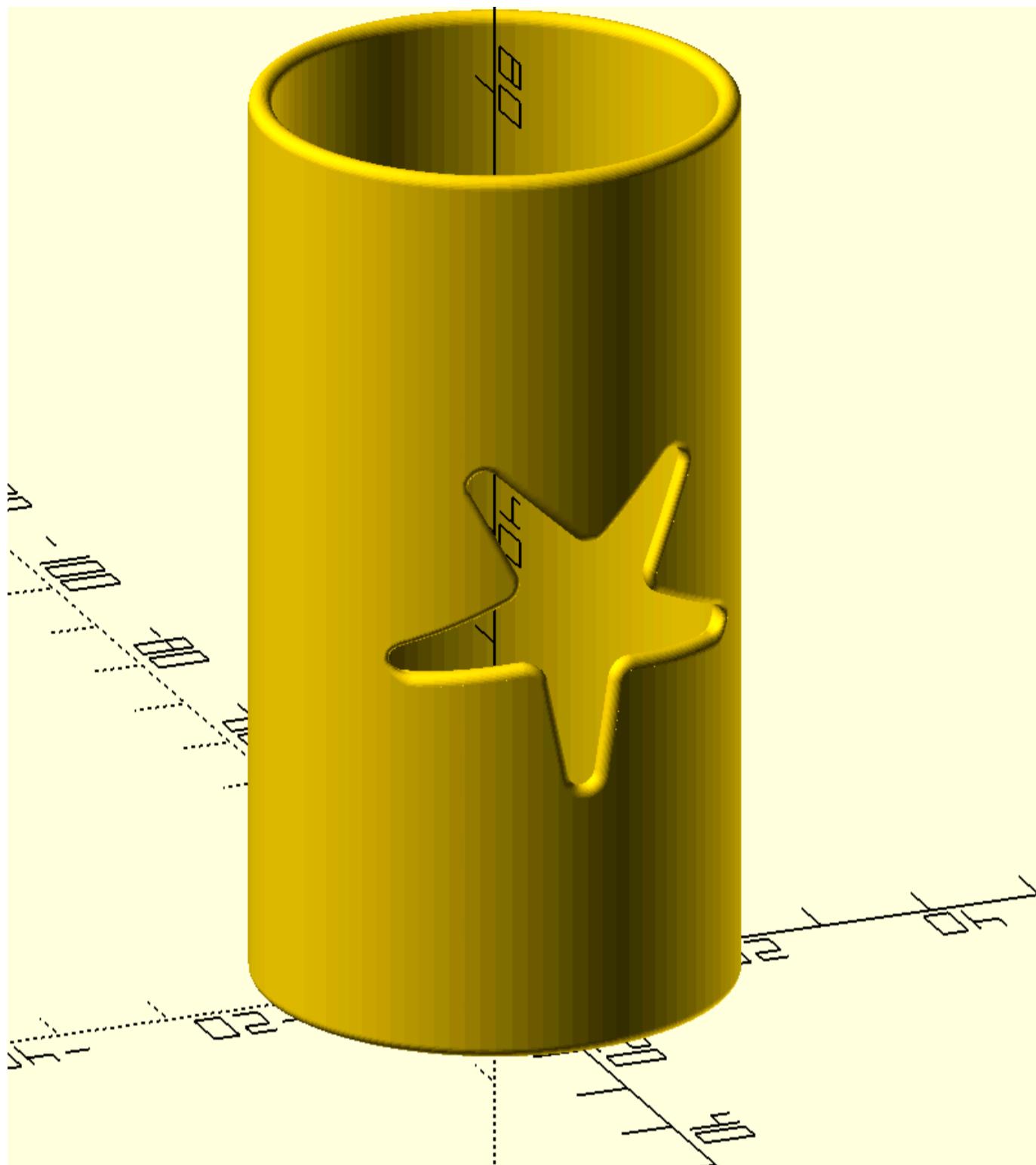
t=2 # thickness
n=100 # number of segments of circle
s=5 # number of sides of the star
d=20 # outer diameter of the star
h=50 # height of the star prism
cir1=circle(d,s=(s+1))
cir2=c3t2(q_rot(["z{360/(s+1)/2}"],circle(d/4,s=(s+1))))
sec1=array(c2t3([cir1,cir2]))
sec1=sec1.transpose(1,0,2).reshape(-1,3)
sec1=sec1
sec1=[(sec1[i]+[0,0,t/1.5]).tolist() if i%2==0 else (sec1[i]+[0,0,t]).tolist() for i in range(len(sec1)) ]
sec1=corner_radius(sec1,20)
sol1=translate([0,0,40],q_rot(["y90"],linear_extrude(m_points(sec1,1.1),h)))

cir=circle(20,s=n)
path=corner_radius(pts1([[t/2,0,t/2],[0,80,t/2-.001],[-t,0,t/2-.001],[0,-80,t/2]]),10)
sol2=prism(cir,path)
sol2=sol2+[sol2[0]]

fillet1=cpo(ip_fillet(sol2,flip(sol1),-t/2,t/2))[:-1]
fillet2=cpo(ip_fillet(flip(sol2),sol1,-t/2,t/2))[:-1]
sol3=flip([translate([5,0,0],fillet1[0])]+fillet1+flip(fillet2)+[translate([-5,0,0],fillet1[0])])

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

difference(){
{swp_c(sol2)}
{swp(sol3)}
}
''' )
```



lamp

```
In [120...]: # lamp

n=20 #number of strands in the lamp
t=5 # thickness of each strand
path=[[42,0],[62,50],[25,100],[25,180]]

path1=cytz(bezier(path,100))

path2=[q([0,0,1],path1[i],i/(len(path1)-1)*(180+1.8)) for i in range(len(path1)-1)]

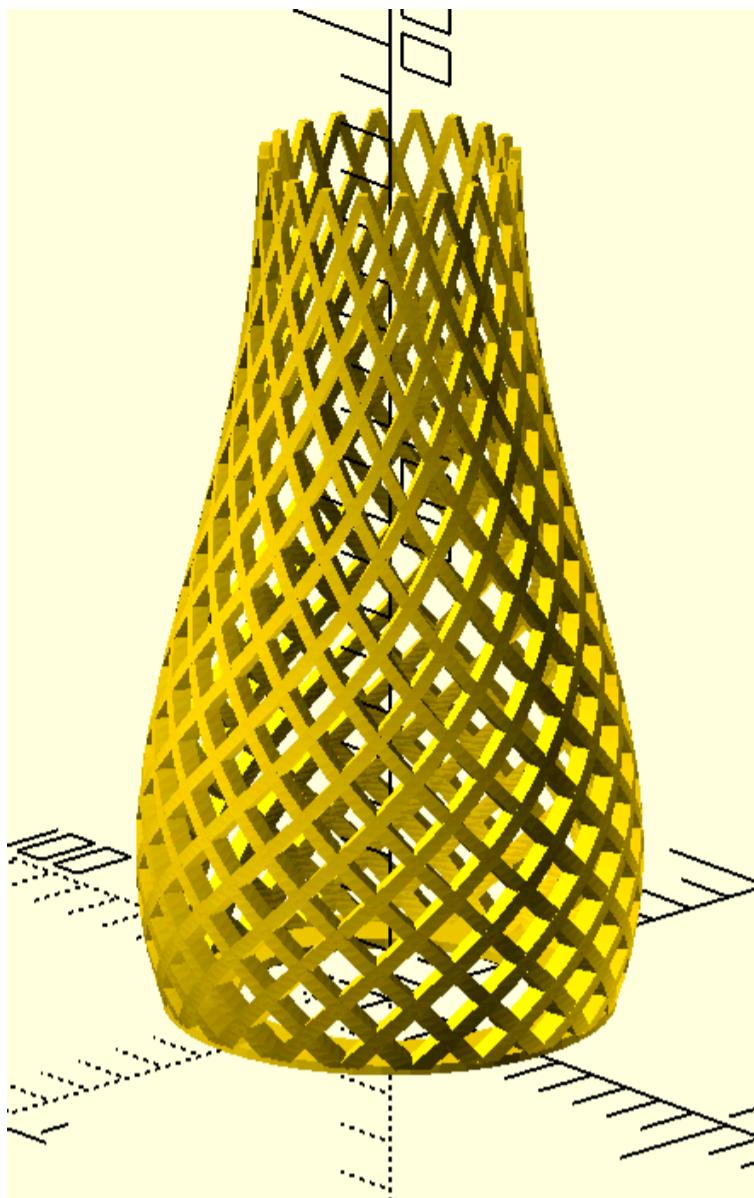
sol=[]
for i in range(len(path2)):
    theta=ang(path2[i][0],path2[i][1])
    sol.append(translate(path2[i],q_rot([f'z{theta}'], \
        offset(square(t,center=True),i/len(path2)*-1.5))))
sol=q_rot(['z0'],sol)

c1=circle(45)
c2=circle(30)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
for(i=[0:360/{n}:359])
rotate([0,0,i])
{{
{swp(sol)}
//p_line3d({path2},.5);
mirror([0,1,0])
{swp(sol)}
//p_line3d({path2},.5);

}}
linear_extrude(2)
difference()
{
polygon({c1});
polygon({c2});

}
''' )
```



samsung-tab-s6-holder

```
In [121...]: # samsung tab s6 holder to hang in car back seat

sec=corner_radius(pts1([[0,0,.1],[124,0,3],[27*cos(45*pi/180),27*sin(45*pi/180),1],
[15*cos(135*pi/180),15*sin(135*pi/180),1],
[5*cos((180+45)*pi/180),5*sin((180+45)*pi/180),1],
[10*cos(-45*pi/180),10*sin(-45*pi/180),1],
[17*cos((180+45)*pi/180),17*sin((180+45)*pi/180),1],
[10*cos(135*pi/180),10*sin(135*pi/180),1],
[8*cos(225*pi/180),8*sin(225*pi/180),1],[20*cos(135*pi/180),20*sin(135*pi/180),1],
[8*cos(45*pi/180),8*sin(45*pi/180),1],
[105*cos(135*pi/180),105*sin(135*pi/180),1],
[8*cos(225*pi/180),8*sin(225*pi/180),1],
[20*cos(135*pi/180),20*sin(135*pi/180),1],
[8*cos(45*pi/180),8*sin(45*pi/180),1],[10*cos(135*pi/180),10*sin(135*pi/180),1],
[17*cos(45*pi/180),17*sin(45*pi/180),1],[10*cos(-45*pi/180),10*sin(-45*pi/180),1],
[5*cos(45*pi/180),5*sin(45*pi/180),1],[15*cos(135*pi/180),15*sin(135*pi/180),1],
[21*cos(225*pi/180),21*sin(225*pi/180),1],[0,30,2],[-4,0,1]]),10)

sec1=corner_radius(pts1([[0,0,2],[17,0,2],[0,85,2],[-17,17,2]]),5)
path1=[[0,0],[0,6]]
sol=translate([123.5,7.7,30],q_rot(["x90","z45"],f_prism(sec1,path1)))

sol1=translate([5,129,130],q_rot(["x90","z45"],f_prism(sec1,path1)))

sec2=corner_radius(pts1([[0,0,4],[10,0,4],[0,40,4],[-10,0,4]]),5)
path2=[[0,0],[0,8]]
sol2=translate([-0.25,140,40],q_rot(["x90","z90"],f_prism(sec2,path2)))

sol3=translate([-0.25,140,170],q_rot(["x90","z90"],f_prism(sec2,path2)))

sec4=corner_radius(pts1([[0,0,0],[15,0,5],[0,90,5],[-15,0,0]]),5)
path4=[[0,0],[0,3]]
sol4=translate([90,35,0],q_rot(["z45"],f_prism(sec4,path4)))

sec5=corner_radius(pts1([[0,0],[120,0,0],[32*cos(135*pi/180),32*sin(135*pi/180),1],
[8*cos(45*pi/180),8*sin(45*pi/180),1],
[105*cos(135*pi/180),105*sin(135*pi/180),1],[8*cos(225*pi/180),8*sin(225*pi/180),1],
[33*cos(135*pi/180),33*sin(135*pi/180),0]]),5)

sec6=corner_radius(pts1([[0,0,5],[90,0,5],[0,110,5],[-90,90,5]]),5)
path6=[[0,0],[0,7]]

sol6=translate([15,6,25],q_rot(["x90"],f_prism(sec6,path6)));
sol7=translate([-1,15,25],q_rot(["x90","z90"],f_prism(sec6,path6)));
sol8=translate([94,30,25],q_rot(["x90","z135"],f_prism(sec6,path6)));

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
rotate([90,0,0])
{{}
difference(){{}
difference(){{}}
```

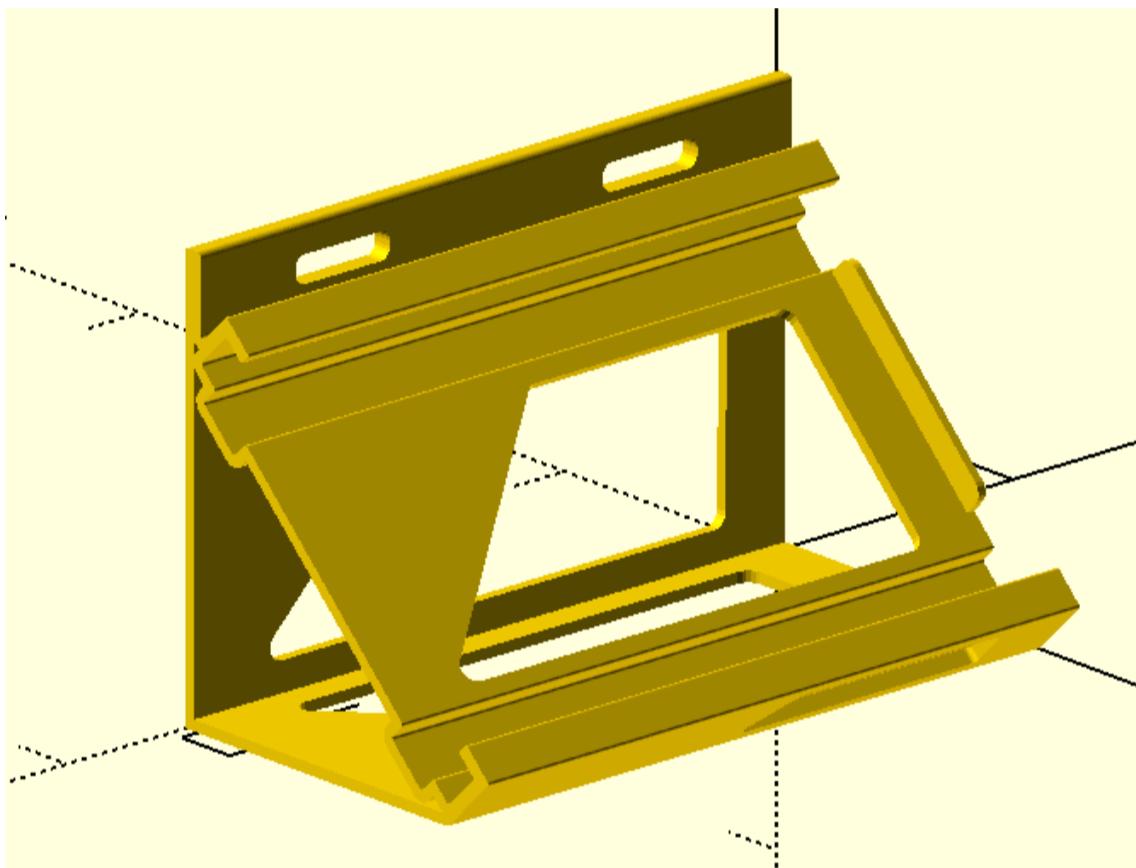
```

linear_extrude(250)
polygon({sec});

translate([0,0,-.05])
linear_extrude(250.1)
polygon({offset(sec,-4.5)});
}

//color("blue")
{swp(sol)}
//color("blue")
{swp(sol1)}
//color("blue")
{swp(sol2)}
//color("blue")
{swp(sol3)}
//color("blue")
{swp(sol6)}
//color("blue")
{swp(sol7)}
//color("blue")
{swp(sol8)}
}

//color("magenta")
{swp(sol4)}
}
'''
```



business-card-holder

```

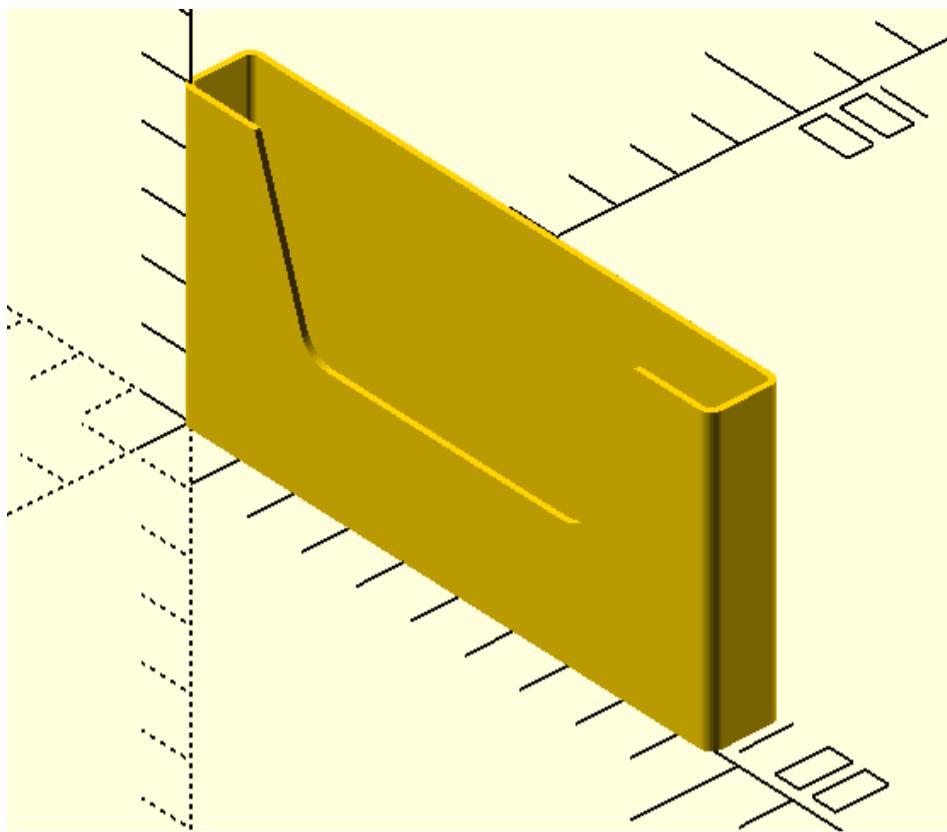
In [122... # business card holder

sec=corner_radius(pts1([[0,0,1],[95,0,1],[0,10,1],[-95,0,1]]),10)
sol2=linear_extrude(offset(sec,1),1);
sec1=corner_radius(pts1([[10,0,5],[50,0,5],[10,30],[-70,0]]),10);
sol3=translate([12.5,2,21],q_rot(["x90"],linear_extrude(sec1,5)));

# difference(){
# union(){
# sol4=swp_prism_h(prism1,prism)
# swp(prism2);
# swp(prism3);

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
render(){}
difference(){}
linear_extrude(50)
difference(){}
polygon({offset(sec,1)});
polygon({sec});
}

{swp(sol3)}
}
{swp(sol2)}
}
'''
```



m10

```
In [125...]
p0,p1,p6,p7=tctpf(7.5,17.5,[14.5,0],[0,0])
p2,p3,p4,p5=tctpf(17.5,7.5,[0,0],[-14.5,0])
sec1=arc_2p(p1,p2,17.5,-1)+arc_2p(p3,p4,7.5,-1)+arc_2p(p5,p6,17.5,-1)+arc_2p(p7,p0,7.5,-1)

path1=corner_radius(pts1([[[-17,0],[17,0],[0,5.5],[-17,0]]]))
sol1=f_prism(sec1,path1)

sec2=circle(10)
path2=cr_3d([[0,0,0.001,0],[0,0,29-.001,17.5],[-44+.001,0,0,0]],20)

sol2=align_sol_1(path_extrude_open(sec2,path2))

sec3=circle(39/2)
path3=corner_radius(pts1([[-39/2+.5,0],[39/2-.5,0],[0,4],[-39/2+.5,0]]),10)
sol3=f_prism(sec3,path3)
sol3=flip(sol2vector([1,0,0],sol3,[-44,0,29]))

fillet1=flip(ip_fillet(sol1,sol2,-1.5,1.5))
fillet1=fillet1+[fillet1[0]]
fillet2=ip_fillet(sol3,flip(sol2),1.5,1.5)
fillet2=fillet2+[fillet2[0]]
sol4=align_sol_1(path_extrude_open(circle(13/2),path2))
sol4=swp_prism_h(sol2,sol4)

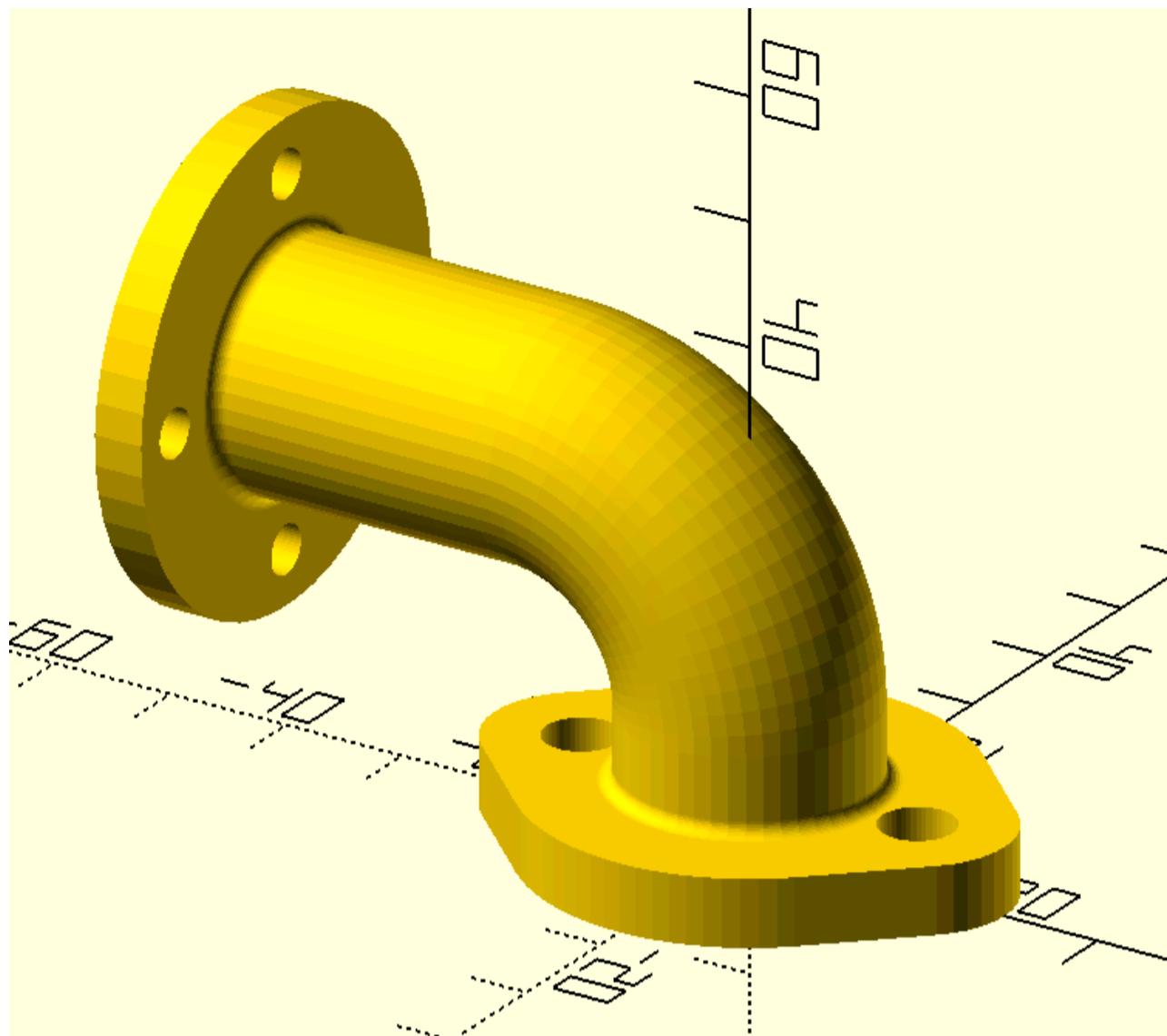
sol5=translate([0,0,-.25],linear_extrude(circle(10-.5),6))
sol6=flip(sol2vector([1,0,0],sol5,[-44,0,29]))
sol7=translate([0,0,-.25],linear_extrude(circle(2.5,[15,0]),5.5))
sol7=[q_rot([f'z{i}'],flip(sol7)) for i in [0,90,180,270]]
sol7=[sol2vector([1,0,0],p,[-44,0,29]) for p in sol7]

sol8=translate([0,0,-.25],linear_extrude(circle(3,[14.5,0]),6))
sol8=[q_rot([f'z{i}'],sol8) for i in [0,180]]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

//color("blue")p_line({sec1},.1);
sol8={sol8};
difference(){{
{swp(sol1)}
{swp(sol5)}
for(i=[0,1])swp(sol8[i]);
}}
{swp_c(fillet1)}
{swp_c(fillet2)}
'''')
```

```
/Users/sanjeevprabhakar/openscad/openscad2.py:4779: RuntimeWarning: invalid value encountered in divide
  u=einsum('ijkl,ijkl->ijk',cross(p02[None,None,:,:],(-lab)[::,None,:]),(la[:, :,None,:]-p0[None,None,:,:]))/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
```



m35

```
In [129... # m35
t0=time.time()

p0=[15,0]
p1=[15,45]
cir1=circle(7.5,[0,75-7.5])
p2=p_cir_t(p1,cir1)
p4=[-15,45]
p3=cir_p_t(cir1,p4)
arc1=arc_2p(p2,p3,7.5,-1,45)
p5=[-15,0]
p0,p1,arc1,p4,p5=[[15,0,0],[[15,45,20]],c2t3(arc1),[[[-15,45,20]],[[-15,0,0]]]
sec=corner_radius(p0+p1+arc1+p4+p5,10)
sec=translate([0,.1,0],sec)

path=corner_radius(pts1([[0,0],[45,0,7],[45*cos(d2r(30)),45*sin(d2r(30))]]),50)
path=q_rot(['x90','z90'],path)

surf1=wrap_around(sec,path)
surf1=sec2surface_1(surf1)
surf2=surface_offset(surf1,4)
sol=solid_from_2surfaces(surf1,surf2)
sol=translate([0,0,9],q_rot(['z-90'],sol))

sec2=translate([0,0,-2],linear_extrude(circle(3.75,[0,75-7.5]),10))
surf3=[ wrap_around(p,path) for p in sec2]

sol1=flip(translate([0,0,9],q_rot(['z-90'],surf3)))

path=cytz(pts([[0,9],[25.5+19.5,0],[(30-7.5)*cos(45*pi/180),(30-7.5)*sin(45*pi/180)]]))
# sec1=c2t3(m_points_o(pts([[-15,0],[30,0],[0,5],[-30,0]]),1))

sec3=[[-30,-15]]+arc_2p([0,-15],[0,15],15,-1,20)+[[-30,15]]
p6=l_cir_ip([-30,-15+10.5],[0,-15+10.5],circle(7.5))
p7=l_cir_ip([-30,15-10.5],[0,15-10.5],circle(7.5))
sec4=[[-30,-15+10.5]]+arc_long_2p(p6[0],p7[0],7.5,-1,30)+[[-30,15-10.5]]

sec5=circle(6)
path1=corner_radius(pts1([[0,-15.1],[0,4.6],[-3,0],[0,21],[3,0],[0,4.6]]),5)
sol2=translate([-30+12,0,11.25],q_rot(['x-90'],f_prism(sec5,path1)))

sec6=[[25.5+9,-15.1]]+arc_2p([25.5+9,0],[25.5,0],4.5,-1)+[[25.5,-15.1]]
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

difference(){{{
{swp(c2ro(sol,1))}}
linear_extrude(22.5)polygon({sec4});
{swp(flip(sol1))}}
linear_extrude(22.5)polygon({sec6});

}}}

difference(){{{
linear_extrude(22.5)
difference(){{{

}}}}}
```

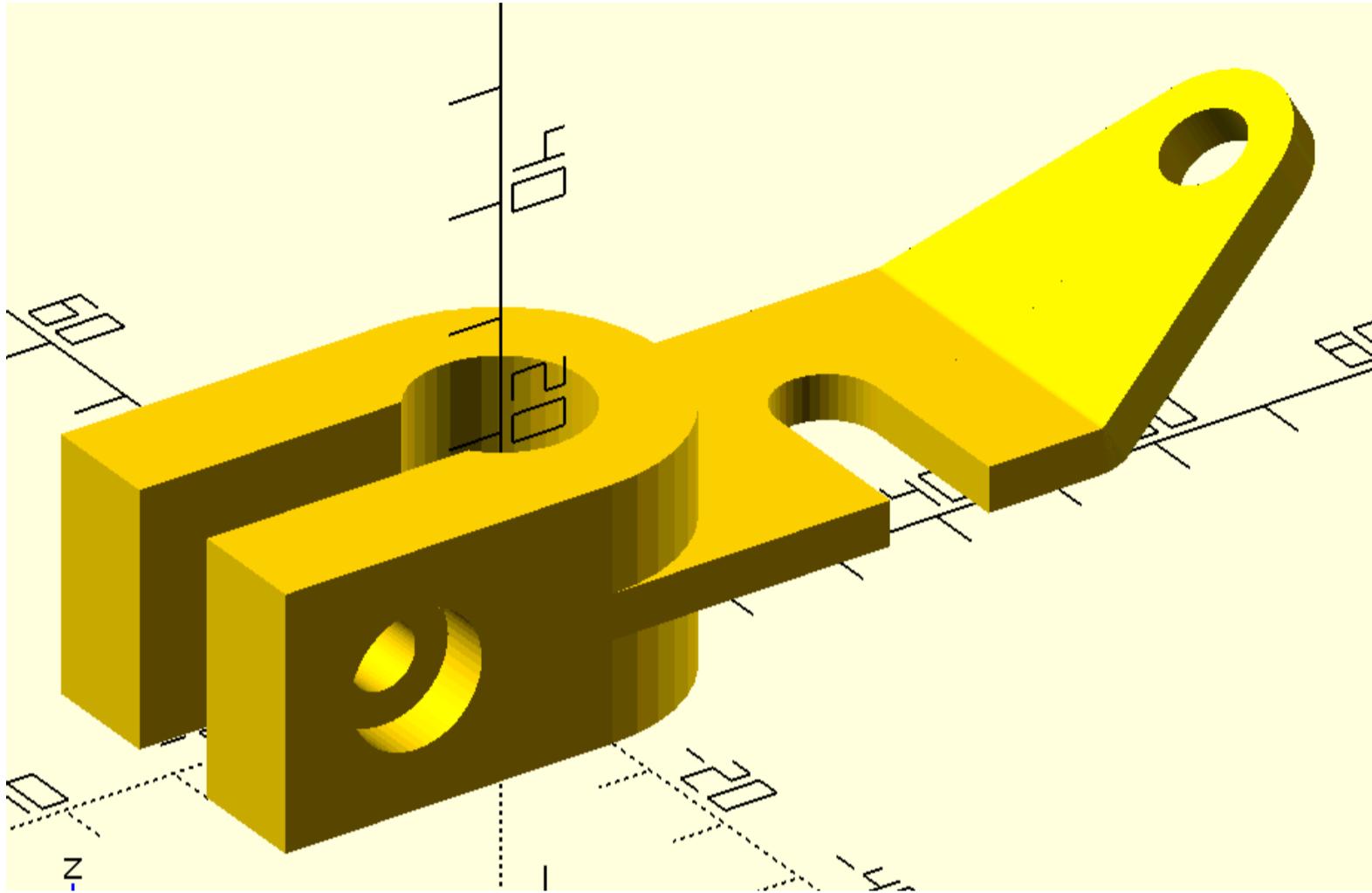
```

polygon({sec3});
polygon({sec4});
}
{swp(sol2)}
}

'''')
t1=time.time()
t1-t0

```

Out[129... 0.21127080917358398



l_cir_ip

```

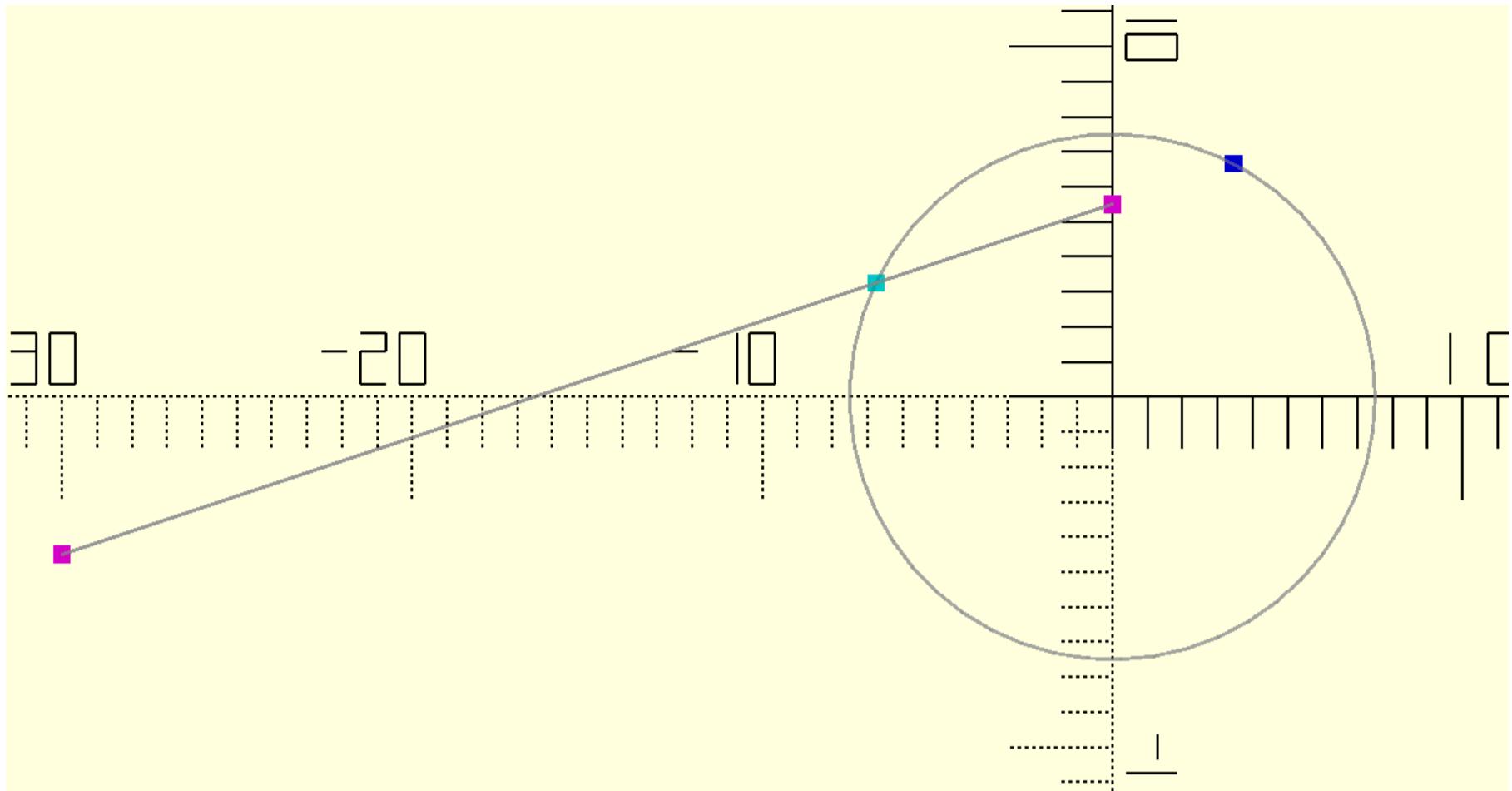
In [130... # example of function l_cir_ip(line, cir)
p0=[-30,-15+10.5]
p1=[0,-15+10.5+10]
line=[p0,p1]
cir=circle(7.5)
p2=l_cir_ip(line,cir)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

%p_line({cir},.1);
%p_line({[p0,p1]},.1);
color("magenta")points({[p0,p1]},.5);
color("cyan")points({[p2[0]]},.5);
color("blue")points({[p2[1]]},.5);

'''')

```



fillet_line_circle

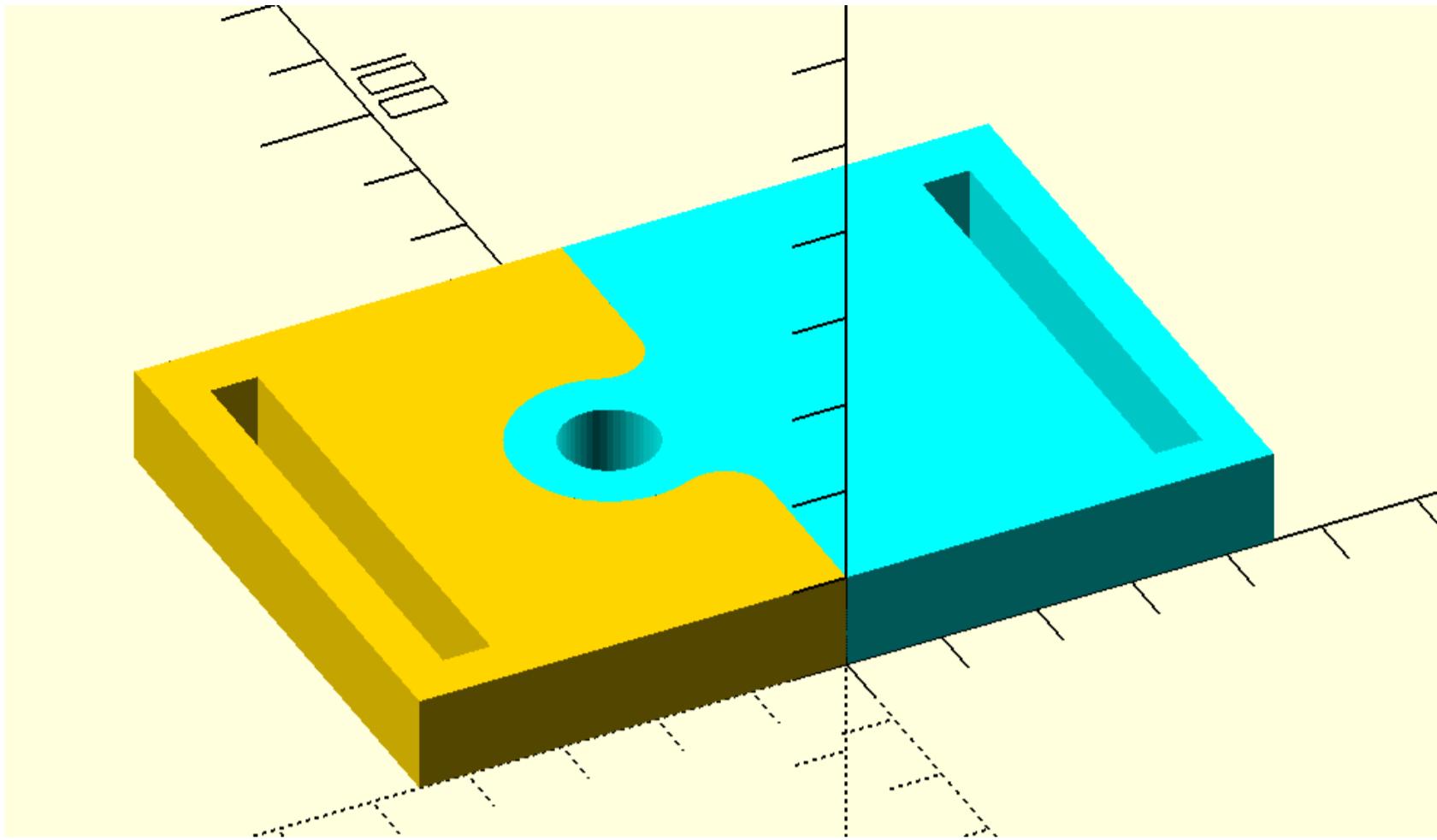
```
In [131...]: # example of fillet_line_circle(l1, c1, r2, cw=-1, option=0, s=50)

line=[[0,0],[0,60]]
cir1=circle(10,[-10,30])
cir2=circle(5,[-10,30])
fillet1=fillet_line_circle(line,cir1,4.5,-1,1,10)
fillet2=flip(fillet_line_circle(flip(line),cir1,4.5,1,1,10))
p0,p1,p2,p3,p4,p5,p6,p7,p8,p9=line[0],fillet1[0],fillet1[-1],fillet2[0],fillet2[-1],line[1],[-45,60],[-45,0],[45,60],[45,0]
sec1=[p0]+fillet1[:-1]+arc_long_2p(p2,p3,10,1,50)+fillet2[1:]+[p5]+[p6]+[p7]
sec2=[p0]+fillet1[:-1]+arc_long_2p(p2,p3,10,1,50)+fillet2[1:]+[p5]+[p8]+[p9]
sec3=c3t2(translate([-45+5,5,0],square([5,49])))
sec4=c3t2(translate([45-10,5,0],square([5,49])))

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

linear_extrude(10)
difference(){
    polygon({sec1});
    polygon({sec3});
}

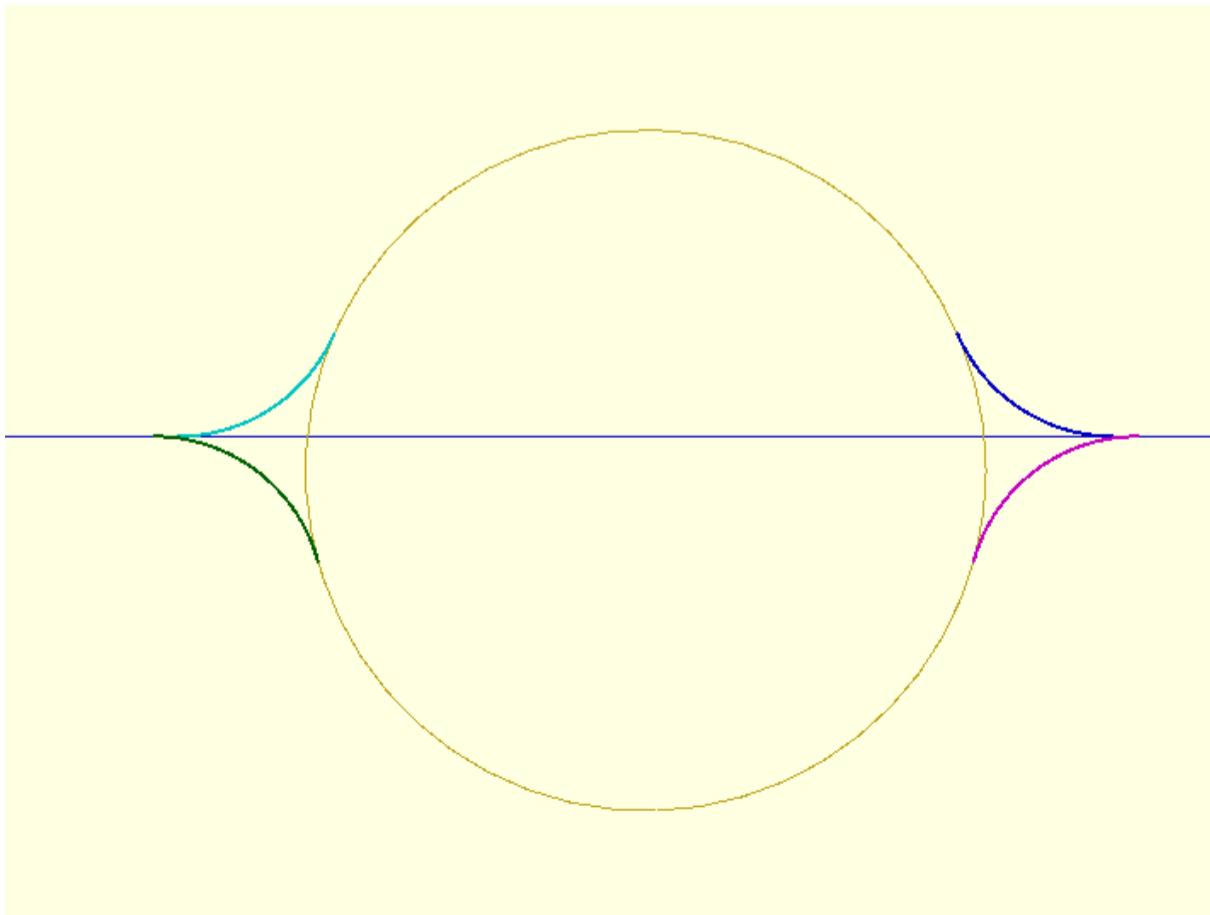
color("cyan")
linear_extrude(10)
difference(){
    polygon({sec2});
    polygon({cir2});
    polygon({sec4});
}
'''')
```



```
In [132]: # example of fillet_line_circle(l1, c1, r2, cw=-1, option=0, s=50)
```

```
line=[[-10,23],[30,13]]
cir1=circle(10,[10,12])
r2=5
s=20
fillet1=fillet_line_circle(line,cir1,r2,cw=-1)
fillet2=fillet_line_circle(flip(line),cir1,r2,cw=1)
fillet3=fillet_line_circle(flip(line),cir1,r2,cw=-1,option=1)
fillet4=fillet_line_circle(line,cir1,r2,cw=1,option=1)
fillet5=fillet_line_circle_internal(line,cir1,1,1,0,20)
fillet6=fillet_line_circle_internal(line,cir1,r2,-1,1,20)
fillet7=fillet_line_circle_internal(flip(line),cir1,1,-1,0,20)
fillet8=fillet_line_circle_internal(flip(line),cir1,r2,1,1,20)

with open('trial.scad','w+') as f:
    f.write(f'''
```



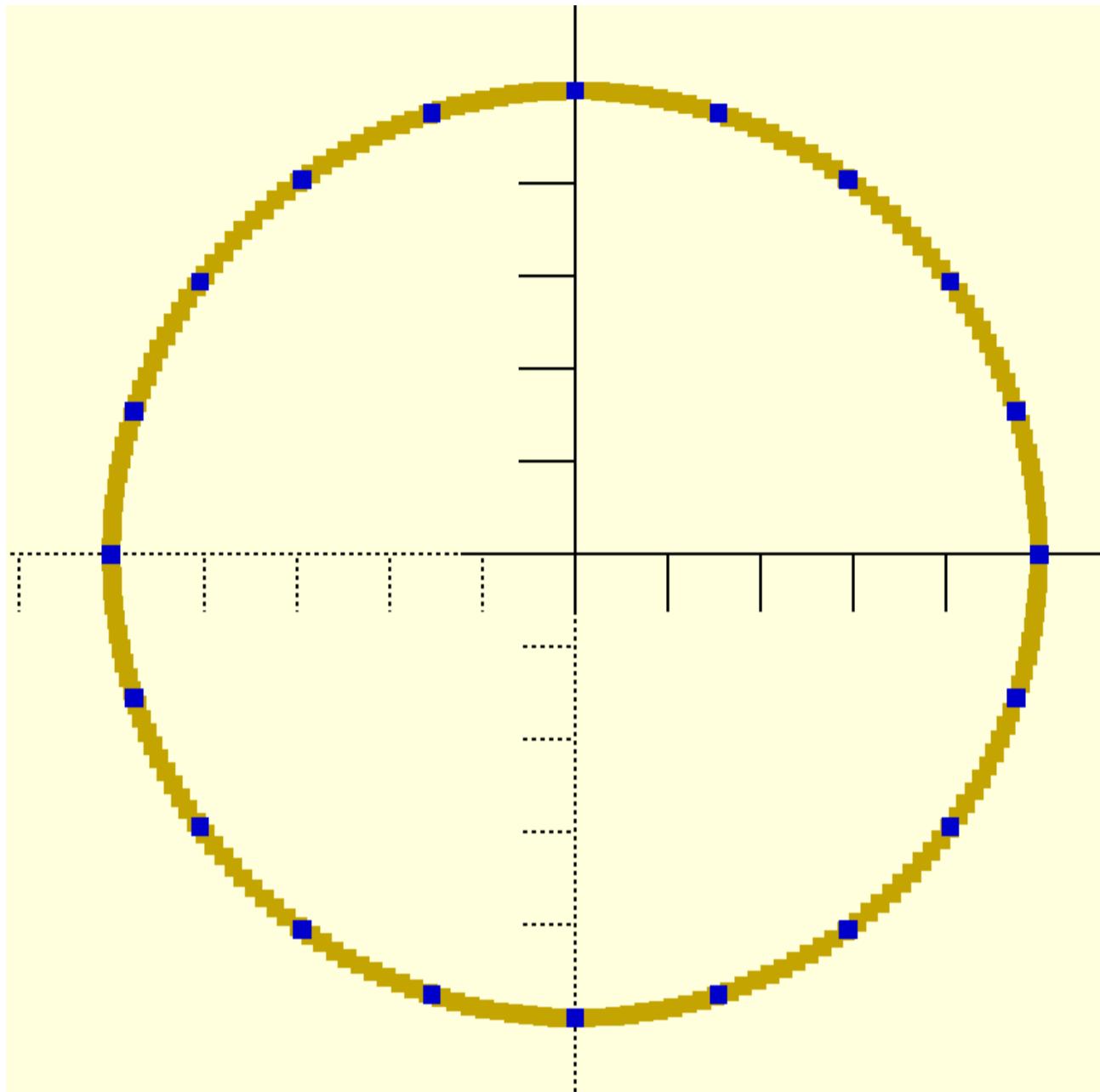
equidistant_pathc

In [133]:

```
a=circle(5,s=200)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
points({a},.2);
color("blue")points({equidistant_pathc(a,20)},.2);

'''')
```



artifact

oset

In [84]:

```
# it takes around 60 sec for calculations

t0=time.time()

stages =200
stage_height = 1.25
rad = 50
f1 = 25
f2 = 25
phase1 = 0
phase2 = 180
height_depth=5
depth1 = 20
depth2 = 20
thickness = 2
bottom_thickness = 3
myslices = 5
angle_step=.5
```

```

var=1

def pauw(x,p):
    return sign(x)*abs(x)**p

def f(i,stages):
    return sin(d2r(i/stages * 120))**2 * 7 + 1

def a(i,stages,var,height_depth):
    return (sin(d2r((i/stages*360*f(i,stages))%360)) * 0.5 + 0.5) * (var * height_depth)

# generate outer points

# points_base = [for (i = [0:1:stages])
#                 let(f = sin(i/stages * 120)^2 * 7 + 1, var = 1 , a=((sin((i/stages*360*f)%360) * 0.5 + 0.5) * (var * height_depth)))
#                 [for(j = [0:angle_step:360-angle_step])
#                  [sin(j) * (rad+a+(pauw(sin(j *f1+phase1),0.5)*0.5+0.5)*depth1*i/stages+(pauw(sin(j *f2+phase2),0.5)*0.5+0.5)*depth2*(1-i)
#                   cos(j) *(rad+a+(pauw(sin(j *f1+phase1),0.5)*0.5+0.5)*depth1*i/stages+(pauw(sin(j *f2+phase2),0.5)*0.5+0.5)*depth2*(1-i/
#                   i*stage_height)]]

points_base=[[

    [sin(d2r(j)) * (rad+a(i,stages,var,height_depth)+(pauw(sin(d2r(j *f1+phase1)),0.5)*0.5+0.5)*depth1*i/stages+(pauw(sin(d2r(j *f2+phase2)),0.5)*0.5+0.5)*depth2*(1-i)
     cos(d2r(j)) * (rad+a(i,stages,var,height_depth)+(pauw(sin(d2r(j *f1+phase1)),0.5)*0.5+0.5)*depth1*i/stages+(pauw(sin(d2r(j *f2+phase2)),0.5)*0.5+0.5)*depth2*(1-i/
     i*stage_height))

    ]
    for j in arange(0,360,angle_step)] for i in range(stages+1)]

p1,p2=[[],[]]
for i in range(stages):
    points_base1= flip(c3t2(points_base[i]))#flip(c3t2(points_base[i])) if cw(c3t2(points_base[i]))==1 else c3t2(points_base[i])
    points_base2=oset(points_base1,-thickness)
    p1.append(translate([0,0,i*stage_height],points_base1))
    p2.append(translate([0,0,i*stage_height],points_base2))

p2=flip(p2)
l1,l2=p2[-5],p2[-3]
l3=translate([0,0,2.5],offset(c3t2(p1[2]),-7))
f1=cpo(convert_3lines2fillet(l1,l3,l2))[:-1]
sol=p1+p2[:-6]+f1
with open('trial.scad','w+') as f:
    f.write(f'''

{swp(sol)}
''')

t1=time.time()
t1-t0

```

Out[84]: 81.73875188827515

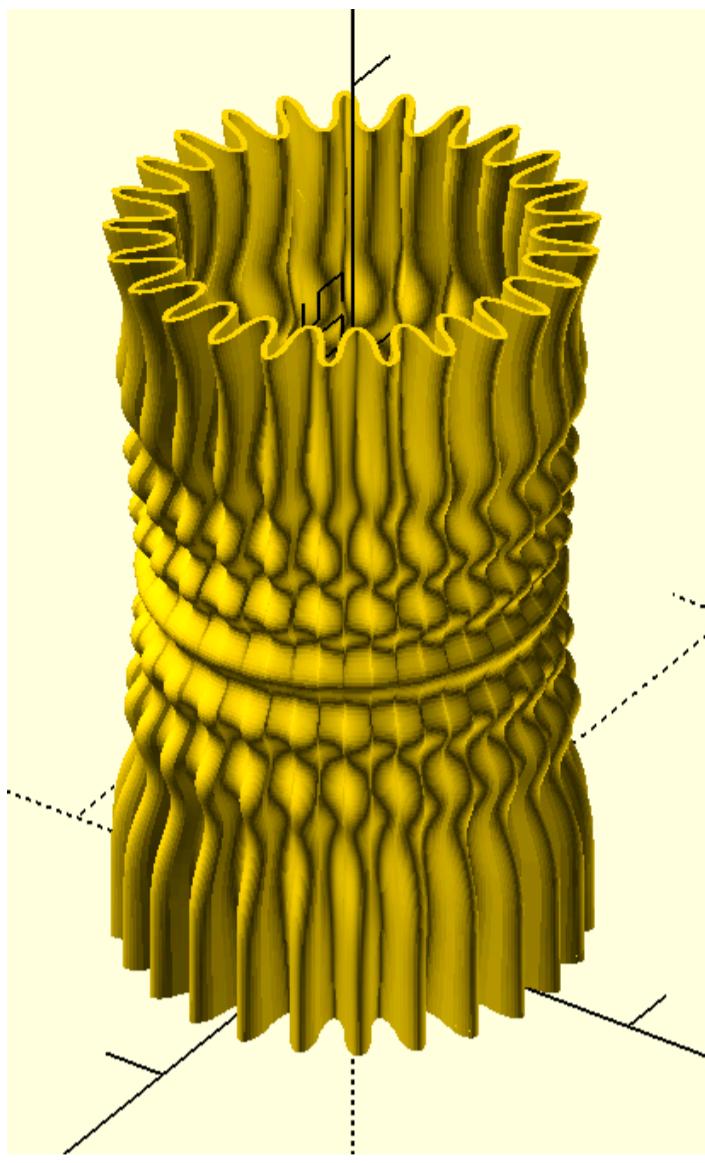
```

In [83]: p2=flip(p2)
l1,l2=p2[-5],p2[-3]
l3=translate([0,0,2.5],offset(c3t2(p1[2]),-7))
f1=cpo(convert_3lines2fillet(l1,l3,l2))[:-1]

with open('trial.scad','w+') as f:
    f.write(f'''

include<dependencies2.scad>
color("blue")p_line3d({l2},.2,1);
color("magenta")p_line3d({l3},.2,1);
{swp_c(f1)}
''')

```



wrap_around

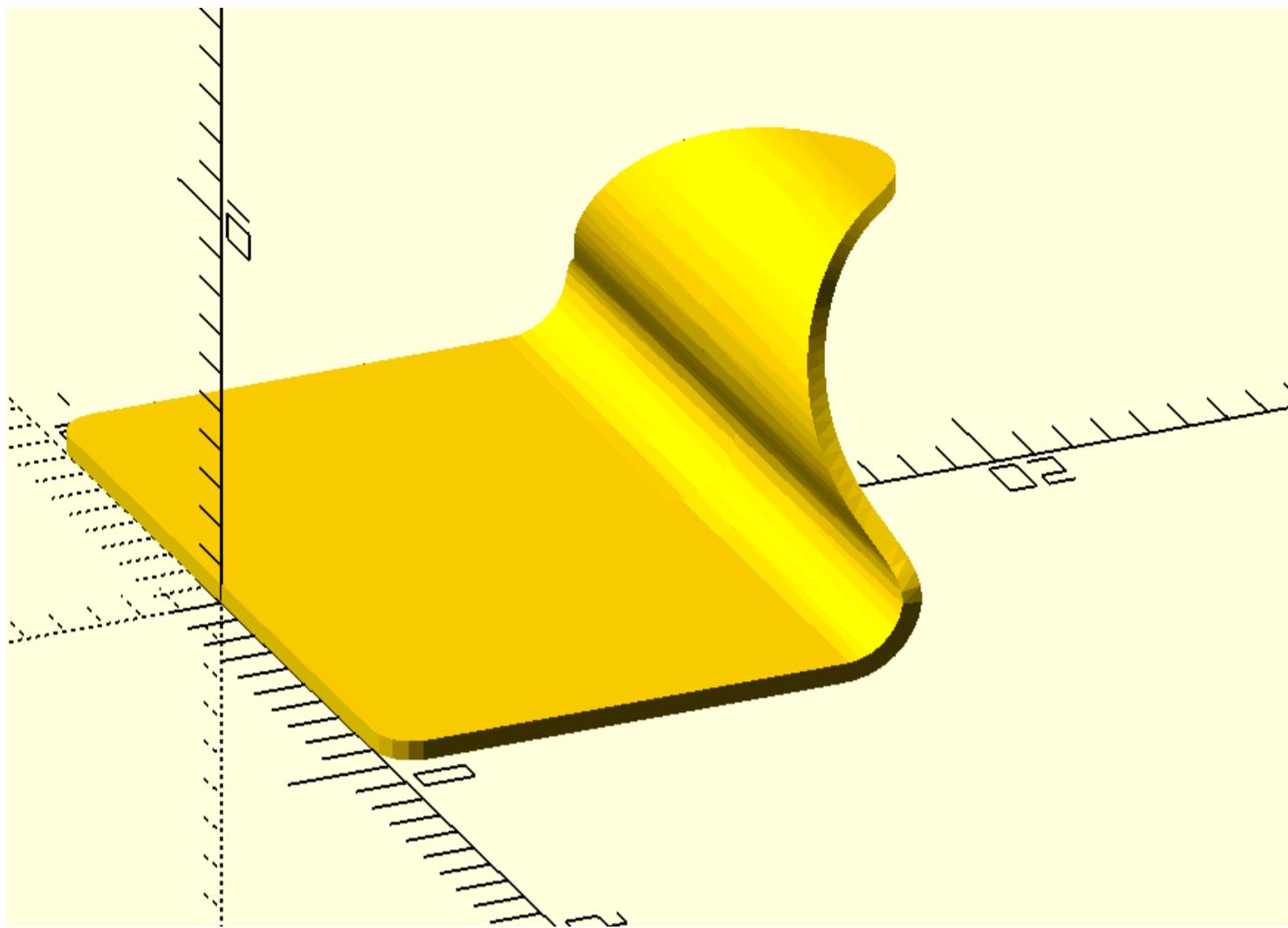
```
In [134... # example of function wrap_around(sec,path)
t0=time.time()

sec=equidistant_pathc(corner_radius(pts1([[-10,0,1],[20,0,1],[0,15,1],[-10,10,2],[-10,-10,1]]),20),200)
sec=equidistant_pathc(sec,200)
l1=equidistant_path([[0,2],[0,22]],10)
l1=equidistant_pathc(surround(l1,.001,10),200)
l1=align_sec_1(sec,l1)[1]
sol1=translate([0,.2,0],slice_sol([sec,l1],20))
path=cr_3d([[0,0,0,0],[0,15,0,2],[0,-4,8,3],[0,10,0,0]],20)
sol2=[wrap_around(p,path) for p in sol1]
sol3=surf_offset(sol2,.5)
sol4=flip(sol2)+sol3+[flip(sol2)[0]]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
{swp_c(sol4)}

'''')
t1=time.time()
t1-t0
```

Out[134... 0.5031750202178955



```
In [135...]: # example of function wrap_around(sec,path) work flow

sec=equidistant_pathc(corner_radius(pts1([[-10,0.1,1],[20,0,1],[0,15,1],[-10,10,2],[-10,-10,1]]),20),200)

path1=corner_radius(pts1([[0,0],[15,0,1],[-16,15]]),50)
path2=circle(5,s=200)
path3=corner_radius(pts1([[0,0],[5,0,1],[0,5,1],[3,0,1],[0,-5,1],[10,0]]),10)
path1=q_rot(['x90','z90'],path1)
path2=q_rot(['x90','z90'],path2)
path3=q_rot(['x90','z90'],path3)

sec1=wrap_around(sec,path1)
sec2=wrap_around(sec,path2)
sec3=wrap_around(sec,path3)

path4=corner_radius(pts1([[6,2],[-6,0,1],[0,-2.001,1],[25,0]]),10)
path4=q_rot(['x90','z90'],path4)

sec4=translate([0,9,0],q_rot(['z-45'],sec1))
sec4=wrap_around(sec4,path4)

sec5=translate([0,9,0],q_rot(['z90'],translate([0,-9,0],sec4)))
sec5=wrap_around(sec5,path4)

sec6=q_rot(['z-45'],translate([0,-9,0],sec5))

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

translate([30,40,0]){
p_line3d({path2},.1);
color("magenta")p_line3dc({sec2},.1);}

translate([30,60,0]){
p_line3d({path3},.1);
color("magenta")p_line3dc({sec3},.1);}

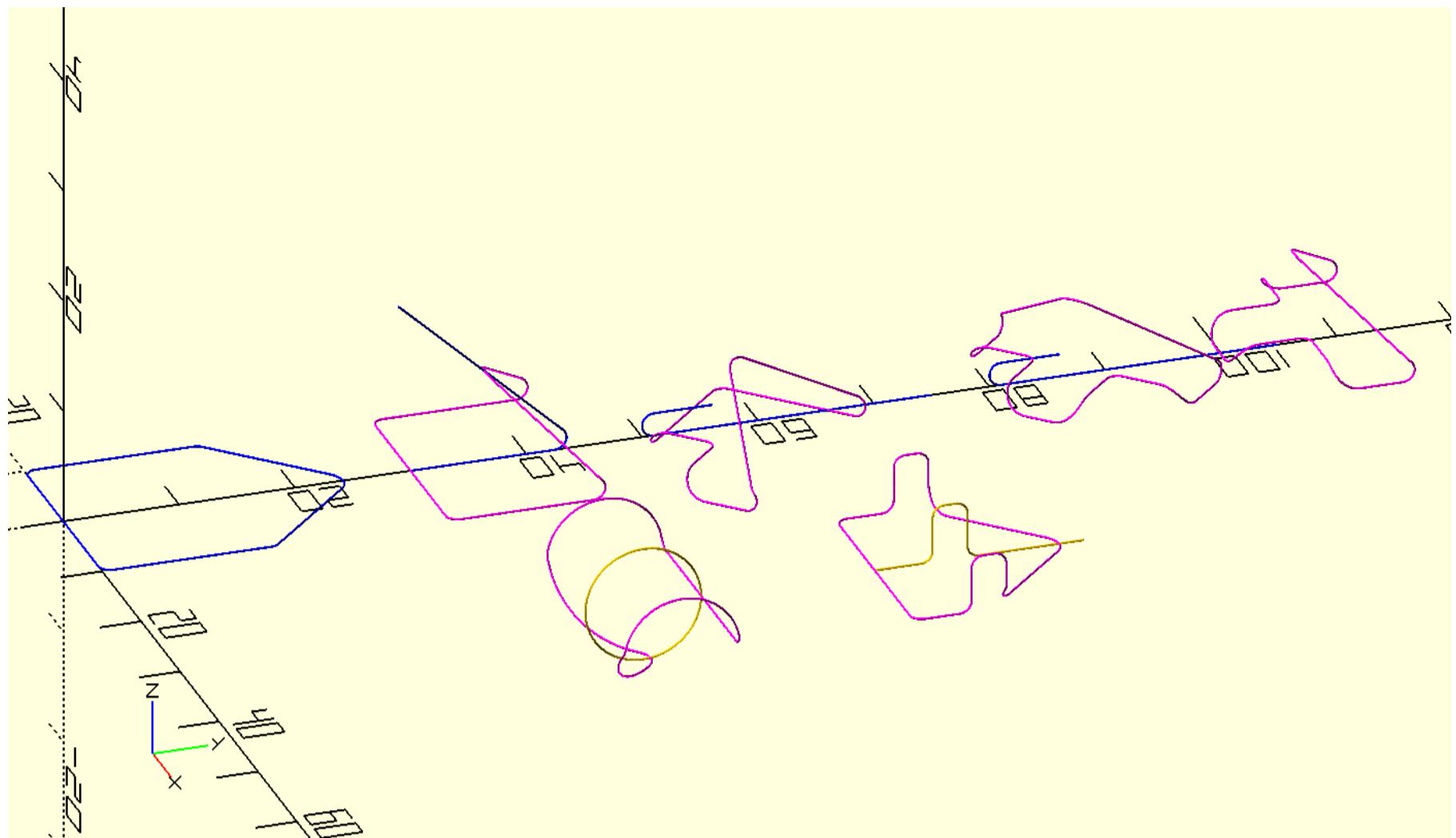
color("blue")p_line3dc({sec},.1);
translate([0,30,0]){
color("blue")p_line3d({path1},.1);
color("magenta")p_line3dc({sec1},.1);}

translate([0,50,0){
color("blue")p_line3d({path4},.1);
color("magenta")p_line3dc({sec4},.1);}

translate([0,80,0){
color("blue")p_line3d({path4},.1);
color("magenta")p_line3dc({sec5},.1);}

translate([0,110,0){
//p_line3d({path4},.1);
color("magenta")p_line3dc({sec6},.1);}

...
''' )
```



```
In [136]: # wrap_around example 4
t0=time.time()

sec0=corner_radius(pts1([[-10,0.1,1],[20,0,1],[0,15,1],[-10,10,2],[-10,-10,1]]),20)
cp=array(offset(sec0,-10)).mean(0).tolist()
sec=equidistant_pathc(corner_radius(pts1([[-10,0.1,1],[20,0,1],[0,15,1],[-10,10,2],[-10,-10,1]]),20),200)
sec1=cpo([sort_points(sec,[cp]),sec])
sec1=cpo([ls(p,50) for p in sec1]+[sec])

path1=corner_radius(pts1([[0,0],[15,0,1],[-16,15]]),50)
path1=q_rot(['x90','z90'],path1)

sec1=[wrap_around(p,path1) for p in sec1]

path4=corner_radius(pts1([[7,5],[-7,-5,1],[45,0]]),10)
path4=q_rot(['x90','z90'],path4)

sec2=translate([0,9,0],q_rot(['z-45'],sec1))
sec2=[wrap_around(p,path4) for p in sec2]

sec3=translate([0,9,0],q_rot(['z90'],translate([0,-9,0],sec2)))
sec3=[wrap_around(p,path4) for p in sec3]

sec3=q_rot(['z-45'],translate([0,-9,0],sec3))
sec4=surf_offset(flip(sec3),.5)
sol=sec3+sec4+[sec3[0]]
sol=translate([0,3,0],sol)

with open('trial.scad','w+') as f:
    f.write(f'''  

include<dependencies2.scad>  

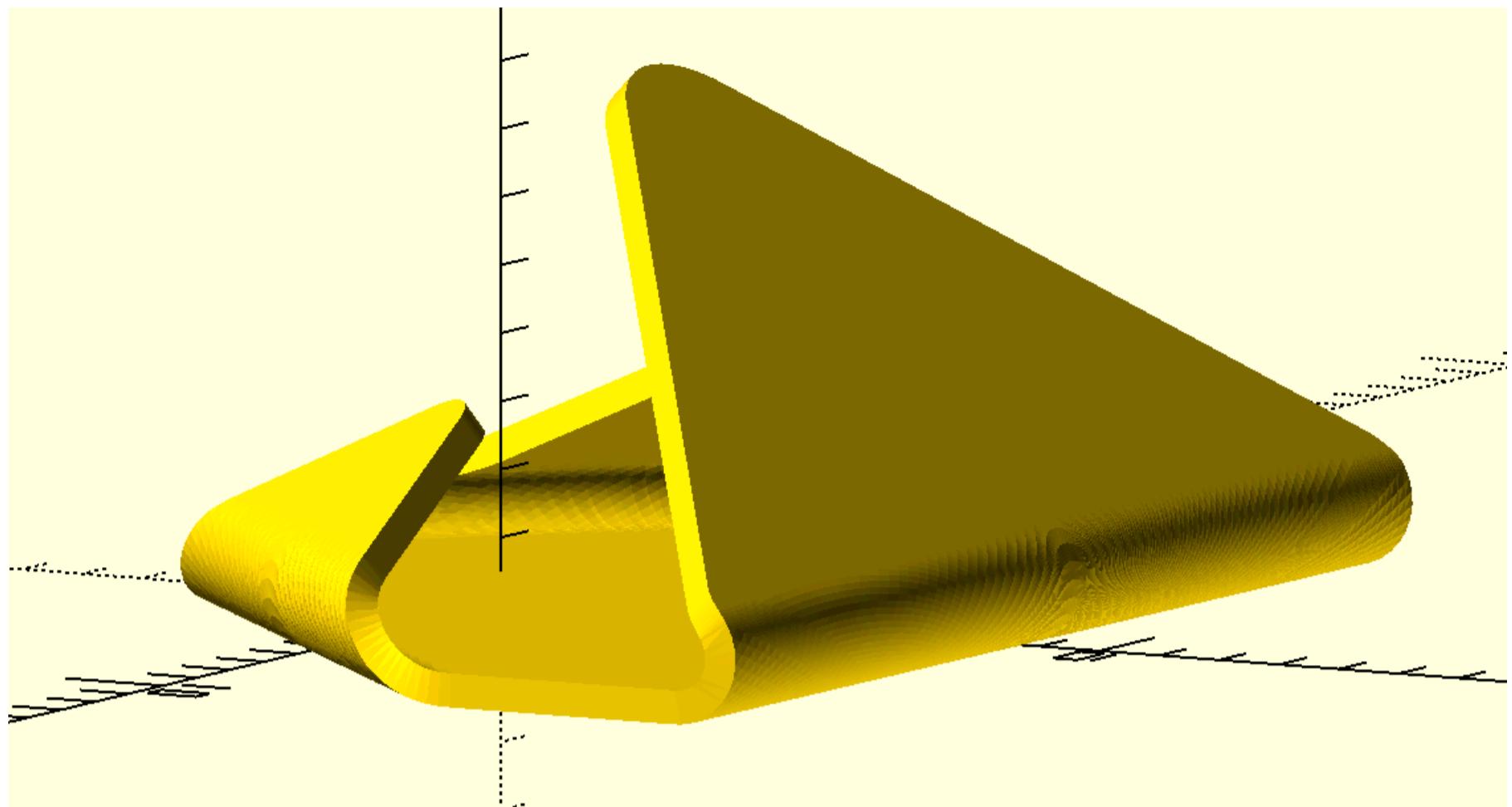
  

{swp(sol)}  

''')
t1=time.time()
t1-t0
```

Out[136]: 1.8647830486297607



ball-bearing

```
In [137]: # ball bearing

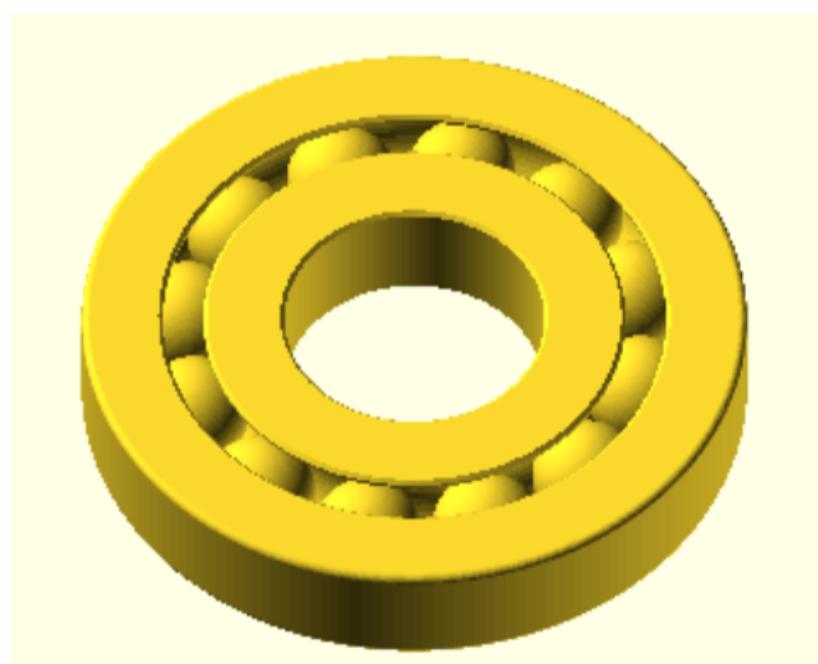
sec=corner_radius(pts1([[31,.5,0],[.5,-.5,0],[9.5,0,1],[0,15,1],[-9.5,0,0],[-.5,-.5,0]]),10)
sec1=corner_radius(pts1([[16,.5,0],[.5,-.5],[9,0,0],[0.5,.5,0],[0,14,0],[-.5,.5,0],[-9,0,0],[-.5,-.5,0]]),10)
sec2=circle(7,[28.5,7.5])

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

rotate_extrude($fn=200)
difference() {{
union() {{
polygon({sec});
polygon({sec1});
}}
polygon({sec2});
}}


for(i=[0:360/12:359])
rotate([0,0,i])
translate([28.5,0,7.5])
sphere(6.8,$fn=100);

''' )
```



mobile-phone-stand

```
In [138]: t0=time.time()
sec=pts([[0,0],[120,0],[0,4.1],q_rot2d(120,[7,0]),q_rot2d(210,[4.1,0]),
        q_rot2d(300,[4.7,0]),[-21.8,0],q_rot2d(120,[50,0]),
        q_rot2d(210,[4.1,0]),q_rot2d(300,[47.7,0]),[-88.7,0]])
r_l=[2,3,4,2,2,1,6,2,2,3,1.9]
sec1=corner_n_radius_list(sec,r_l,10)

p1=arc_2p([0,0],[150,0],350,s=20)
p2=q_rot(['x60','z90'],p1)
```

```

p3=q_rot(['z90'],p1)
s1=sec1[33:55]
t=array(s1[0])
s1=translate(cytz([t])[0],path_extrude_open(translate_2d(-t,s1),p2))
s2=sec1[77:99]
t=array(s2[0])
s2=translate(cytz([t])[0],path_extrude_open(translate_2d(-t,s2),p2))

s3=sec1[110:]+sec1[:11]
s3=path_extrude_open(s3,p3)
s4=q_rot(['x90'],sec1[11:33])
s4=slice_sol(flip(surface_line_vector(s4,[0,150,0])),20)

s5=q_rot(['x90'],sec1[55:77])
s5=slice_sol(flip(surface_line_vector(s5,[0,150,0])),20)

s6=q_rot(['x90'],sec1[99:110])
s6=slice_sol(flip(surface_line_vector(s6,[0,150,0])),20)

# now join all the surfaces together
# orientation of the surfaces needs to be changed
surf1=cpo(flip(cpo(s3))+cpo(s4)+flip(cpo(s1))+cpo(s5)+flip(cpo(s2))+cpo(s6))
l1=ppplane(surf1[0],[0,1,0],[0,0,0])
l2=offset_3d(l1,-1.8,1)
l3=i_p_p(surf1,surf1[0],2)
f1=cpo(convert_3lines2fillet(l2,l3,l1))[:-1]
f2=flip(mirror_surface(f1,[0,1,0],[0,75,0]))
# now create the solid with final shape
sol1=flip(f1+surf1[1:-1]+f2)
# radii can be now increased as desired
# That's it
with open('trial.scad','w+') as f:
    f.write(f'''

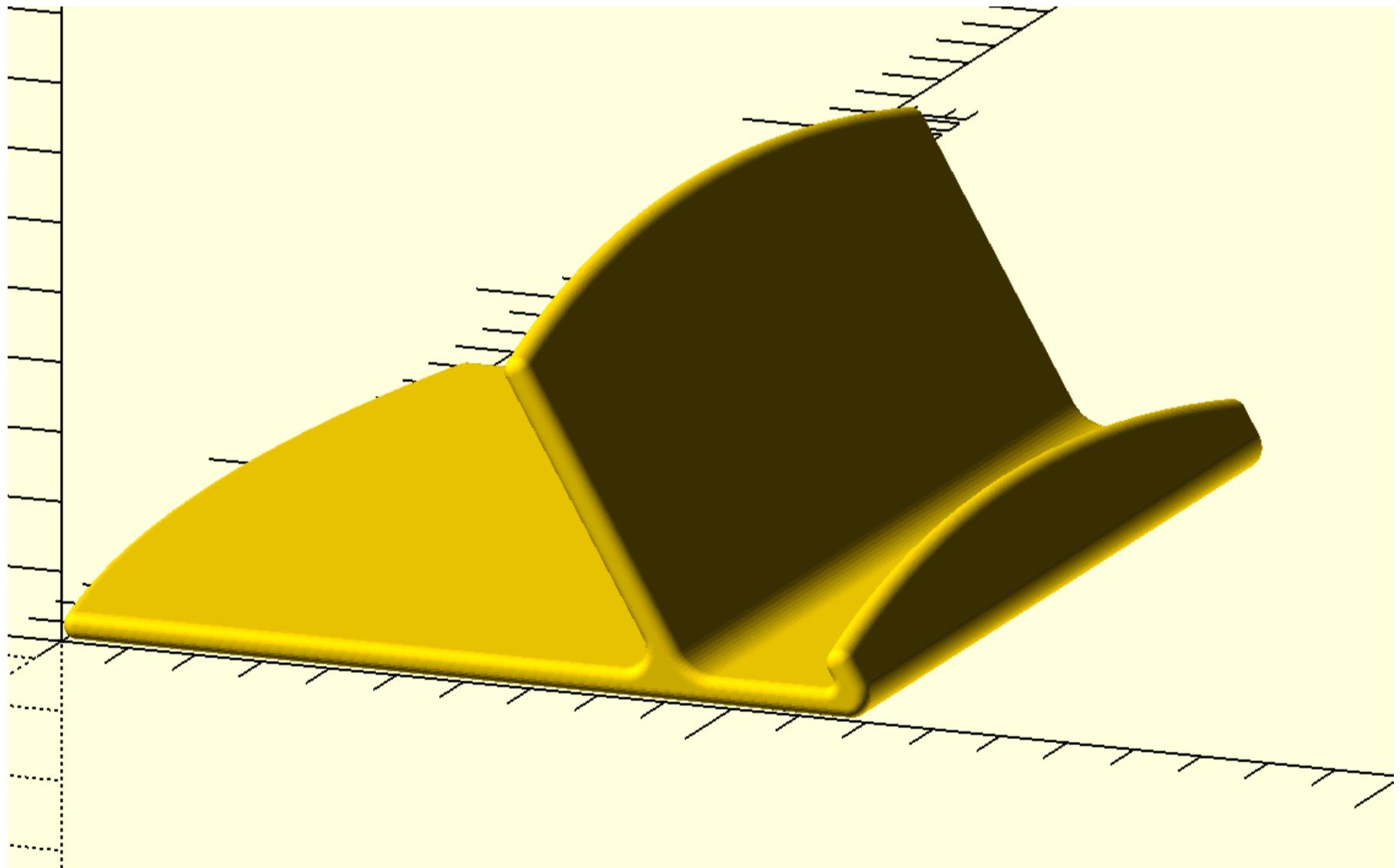
{swp(sol1)}
''')

t1=time.time()
t1-t0

```

/Users/sanjeevprabhakar/openscad/openscad2.py:8572: RuntimeWarning: invalid value encountered in divide
u4=(v4/norm(v4, axis=1).reshape(-1,1)).round(4)

Out[138... 1.4375531673431396



In [30]: # mobile phone stand with application of functions wrap_around and surf_offset

```

t0=time.time()
sec1=corner_radius(pts1([[-75,20,2],[75,-20,280],[75,20,2],[0,70,2],[-75,7,280],[-75,-7,2]]),30)
cp1=array(offset(sec1,-35)).mean(0)
sec1=m_points(sec1,.5)
sec2=cpo([sort_points(sec1,[cp1]),sec1])
sec2=cpo([ls(p,60) for p in sec2])+[sec1]
path1=corner_radius(pts1([[0,60*cos(d2r(60)),0],[60*cos(d2r(-60)),60*sin(d2r(-60)),5+1],[15+10,0,4+1],[50*cos(d2r(120)),50*sin(d2r(120))]]))
path1=path1
path1=q_rot(['x90','z90'],path1)

surf1=[wrap_around(p,path1) for p in sec2]
surf2=surf_offset(flip(surf1),3)
sol=surf1+surf2

sec1=corner_radius(pts1([[-70,20,2],[70,-20,200],[70,20,2],[0,80,2],[-140,0,2]]),30)

```

```

cp1=array(offset(sec1,-25)).mean(0)
sec1=m_points(sec1,.5)
sec2=cpo([sort_points(sec1,[cp1]),sec1])
sec2=cpo([ls(p,60) for p in sec2])+[sec1]

path2=corner_radius(pts1([[0,0],[95,0,4+1],[100*cos(d2r(120)),100*sin(d2r(120))]]),50)
path2=q_rot(['x90','z90'],path2)
surf1=[wrap_around(p,path2) for p in sec2]
surf2=surf_offset(flip(surf1),3)
sol1=surf1+surf2

sol2=[sol[57]]+slice_sol(sol[60:62],3)+[sol[63]]

p0,p1,p2,p3,p4,p5=sol2
fillet1=cpo(convert_3lines2fillet(p2,p0,p1))[:-1]
fillet2=cpo(convert_3lines2fillet(p5,p3,p4))[:-1]

sol3=flip(fillet1)+flip(fillet2)
sol4=sol[:57]+sol3+sol[64:]

sol2=[sol1[57]]+slice_sol(sol1[60:62],3)+[sol1[63]]

p0,p1,p2,p3,p4,p5=sol2
fillet1=cpo(convert_3lines2fillet(p2,p0,p1))[:-1]
fillet2=cpo(convert_3lines2fillet(p5,p3,p4))[:-1]

sol3=flip(fillet1)+flip(fillet2)
sol5=sol1[:57]+sol3+sol1[64:]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

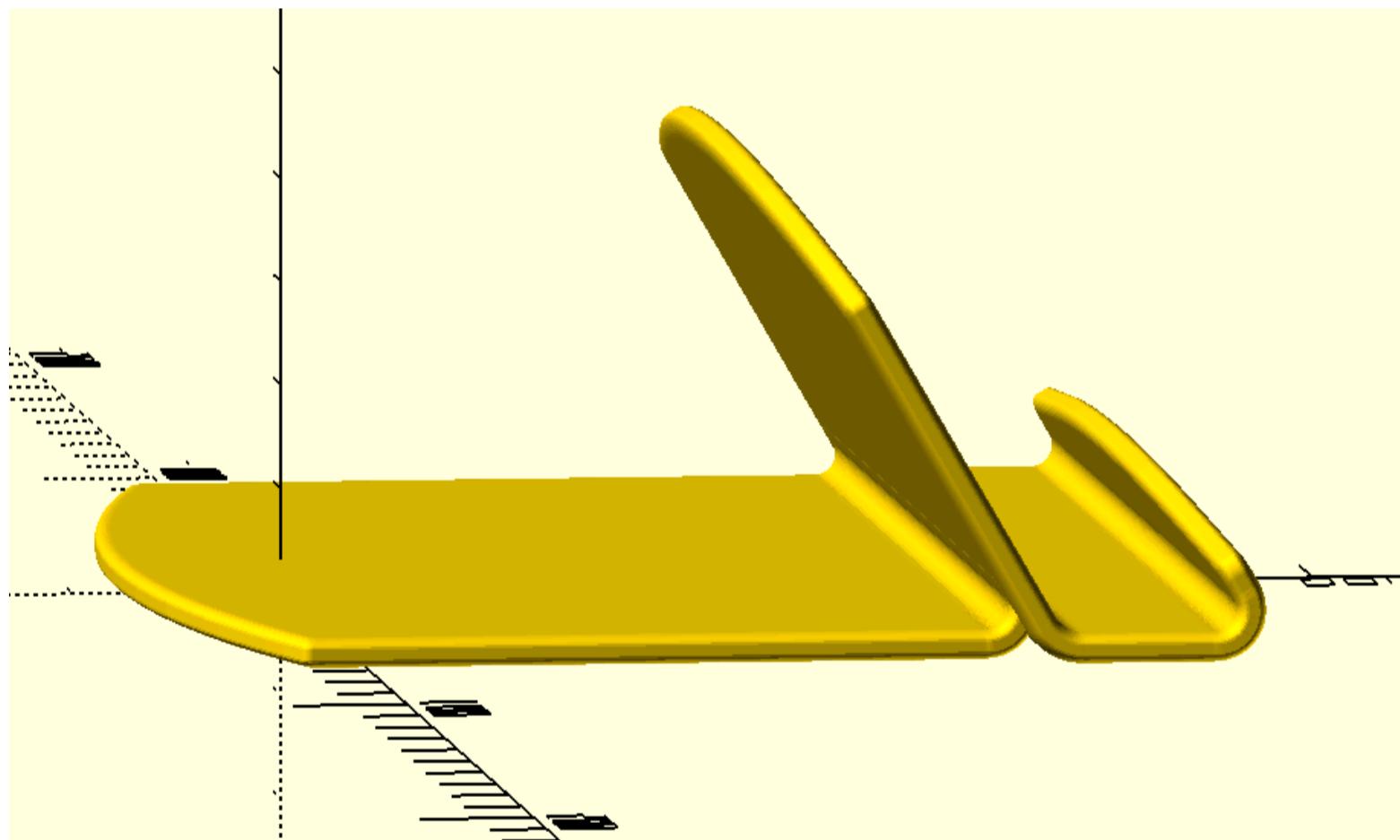
translate([0,40-4.625,0])
{swp(sol4)}
translate([0,-26.2,0])
{swp(sol5)}

''')

t1=time.time()
t1-t0

```

Out[30]: 18.951167821884155



```

In [139...]:
# car mobile stand
sec=corner_radius(pts1([-160/2-4,-15/2-4,23/2-.1],[160+2*4,0,23/2-.1],[0,15+2*4,23/2-.1],[-160-2*4,0,23/2-.1])),10)
sol=o_solid([0,1,sqrt(3)],sec,60)
sol1=surf_offset(sol,-4)
sol2=swp_prism_h(sol,sol1)
surf1=translate([0,0,10],plane([0,0,1],200))
ip1=ip_solid(sol1,surf1)
surf2=ip1[:22]+translate([0,100,0],ip1[22:44])
surf3=translate([0,0,-4],surf2)
sol3=[surf3]+[surf2]
sol4=o_solid([0,0,1],square(200,True),20,-10)

sec1=corner_radius(pts1([-130/2,0],[130,0],[5,60],[-130-2*5,0])),10)
sol5=o_solid([0,-sqrt(3),1],sec1,10,5,0,10)

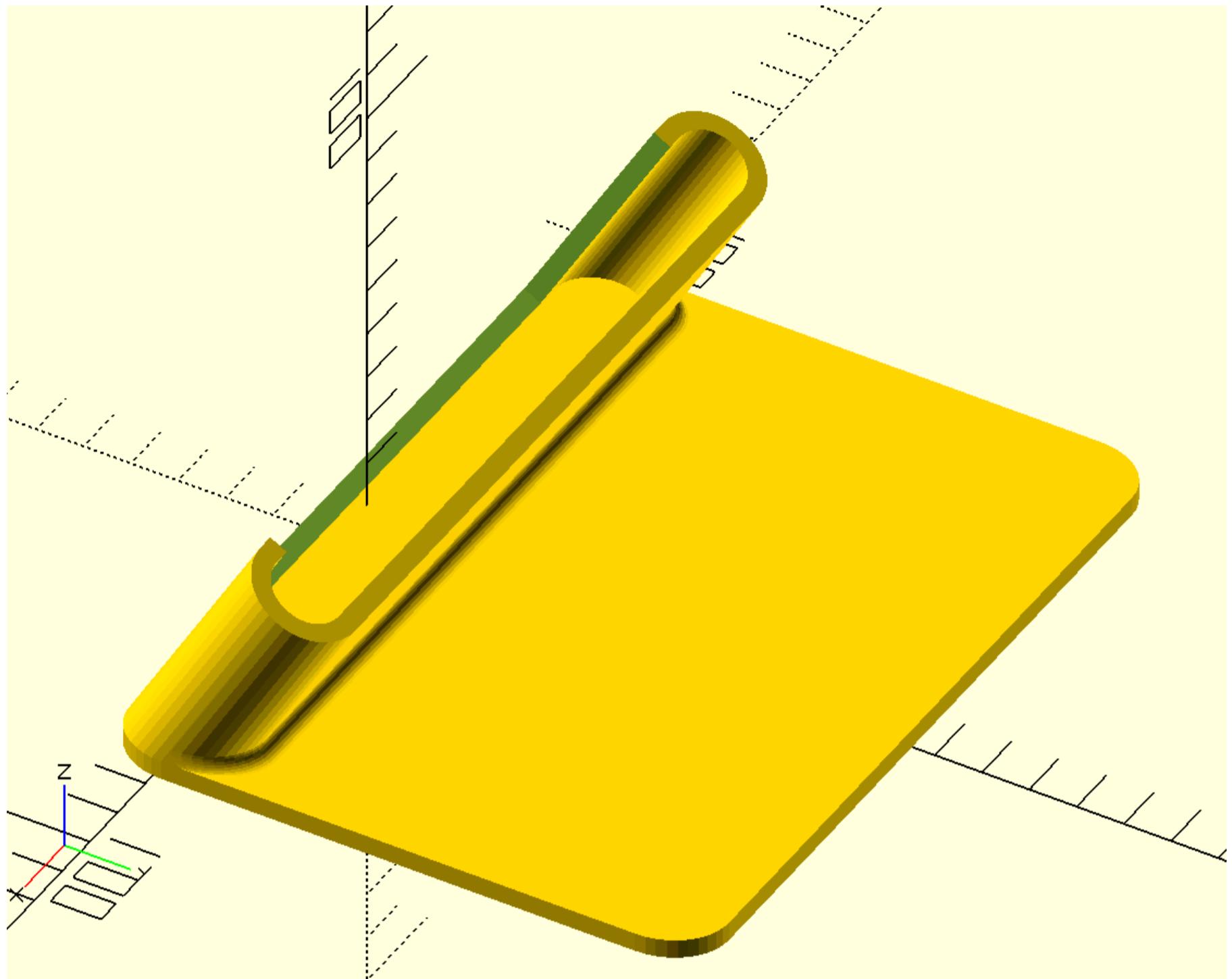
sol6=[ip1[22:]]+[translate([0,2,0],ip1[22:])] + [translate([0,1,sqrt(3)],ip1[22:])]
fillet1=convert_3lines2fillet(translate([0,5,0],ip1[22:]),translate([0,2.4,4.34],ip1[22:]),ip1[22:])
with open('trial.scad','w+') as f:
    f.write(f'''
difference(){
    {swp_c(sol2)}
    {swp(sol4)}
    {swp(sol5)}
}

```

```

}}
//%{swp(surf1)
//color("magenta")points({ip1[:22]},.5);
{swp(sol3)}
{swp(fillet1)}
...
}

```



back-camera-clamp

```

In [140...]: # back camera clamp

res=.5
sec=corner_radius(pts1([[-37/2,0.1,.5],[37,0,.5],[0,15,.5],[-5,24,13.5],[-27,0,13.5],[-5,-24,.5]]),20)
cp1=array(offset(sec,-17)).mean(0)
sec1=[sort_points(m_points(sec,res),[cp1])]+[m_points(sec,res)]
sec2=cpo([ls(p,20) for p in cpo(sec1)])+[m_points(sec,res)]

path=corner_radius(pts1([[0,0],[15,0,3.5],[15,41.21]]),10)
path=q_rot(['x90','z90'],path)

sec3=[wrap_around(p,path) for p in sec2]
sec4=surf_offset(flip(sec3),2)

sol=sec3+sec4

sec5=translate([0,0,-1],c2t3([circle(.1,[0,28])]+[circle(9,[0,28])]))
sec5=[wrap_around(p,path) for p in sec5]
sec6=surf_offset(flip(sec5),4)

sol1=sec5+sec6

cyl1=cylinder(d=4,h=5)

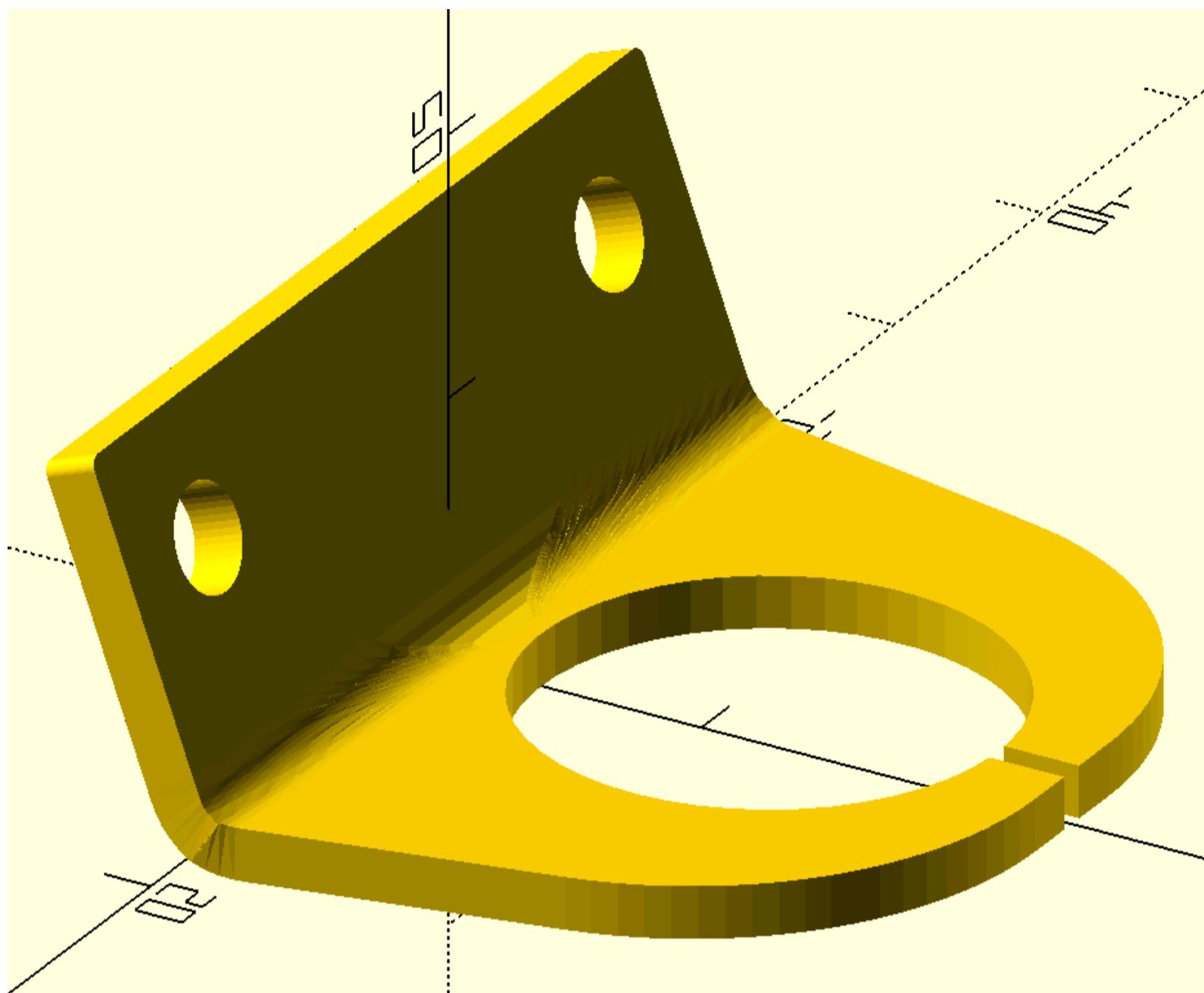
slit=q_rot(['x70'],translate([-5,15,-17],linear_extrude(square([1,20]),10)))

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
rotate([-70,0,0])
translate([0,-15,0])
difference(){
{swp(sol)}
{swp(sol1)}

for(i=[-27/2,27/2])
translate([i,5,-2])
{swp(cyl1)}''')

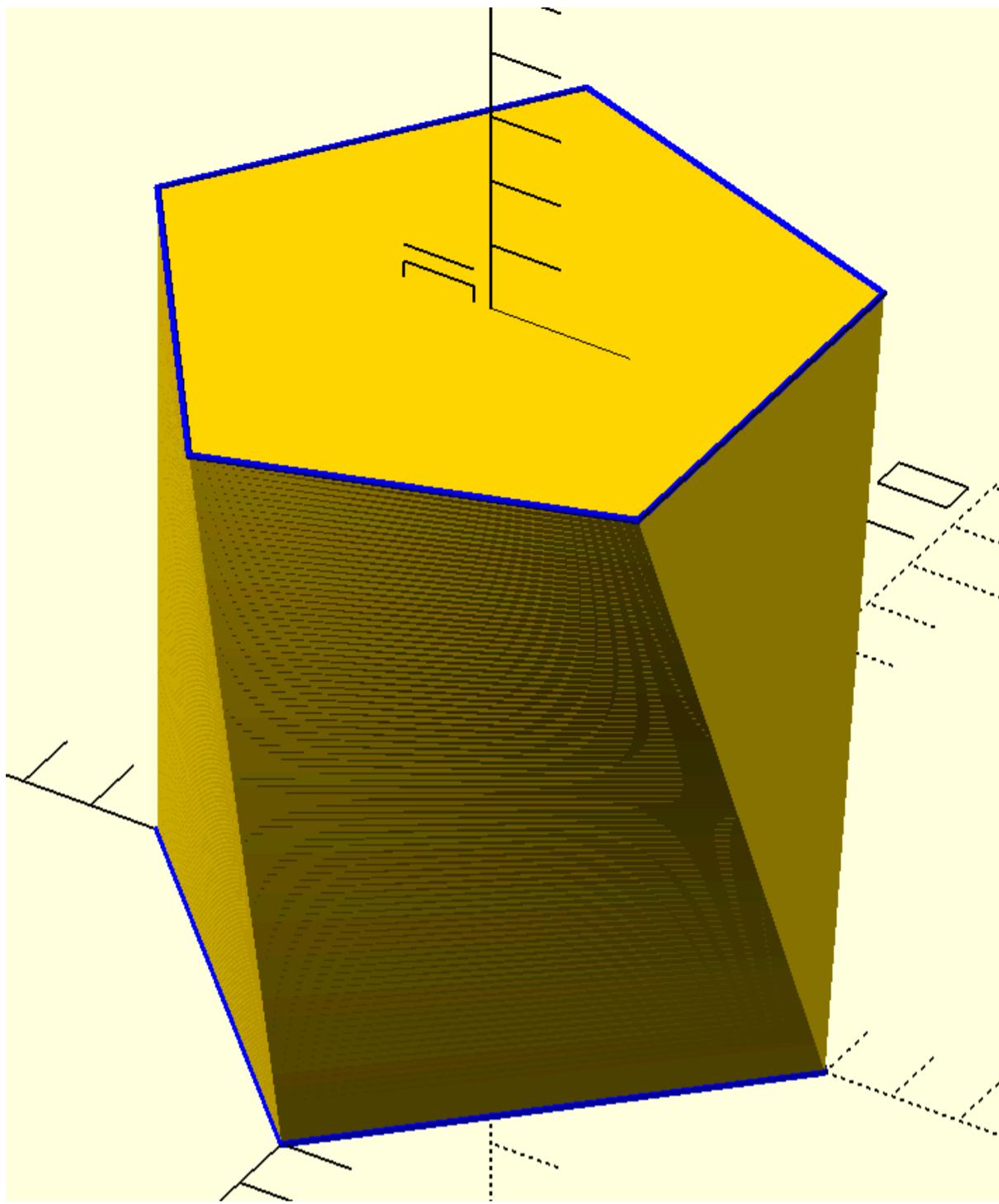
```

```
{swp(slit)}  
}}  
'''
```



align_sol

```
In [141]: # example of function align_sol(sol,angl)  
  
sqr1=circle(5,s=5)  
pent1=circle(5,s=6)  
  
sqr1=c2t3(sort_points(pent1,sqr1))  
pent1=translate([0,0,10],pent1)  
sol=[sqr1]+[pent1]  
sol=align_sol(sol,1)  
sol1=slice_sol(sol,100)  
  
with open('trial.scad','w+') as f:  
    f.write(f'  
include<dependencies2.scad>  
  
{swp(sol1)}  
color("blue")p_line3dc({sol[0]},.05);  
color("blue")p_line3dc({sol[1]},.05);  
'''
```

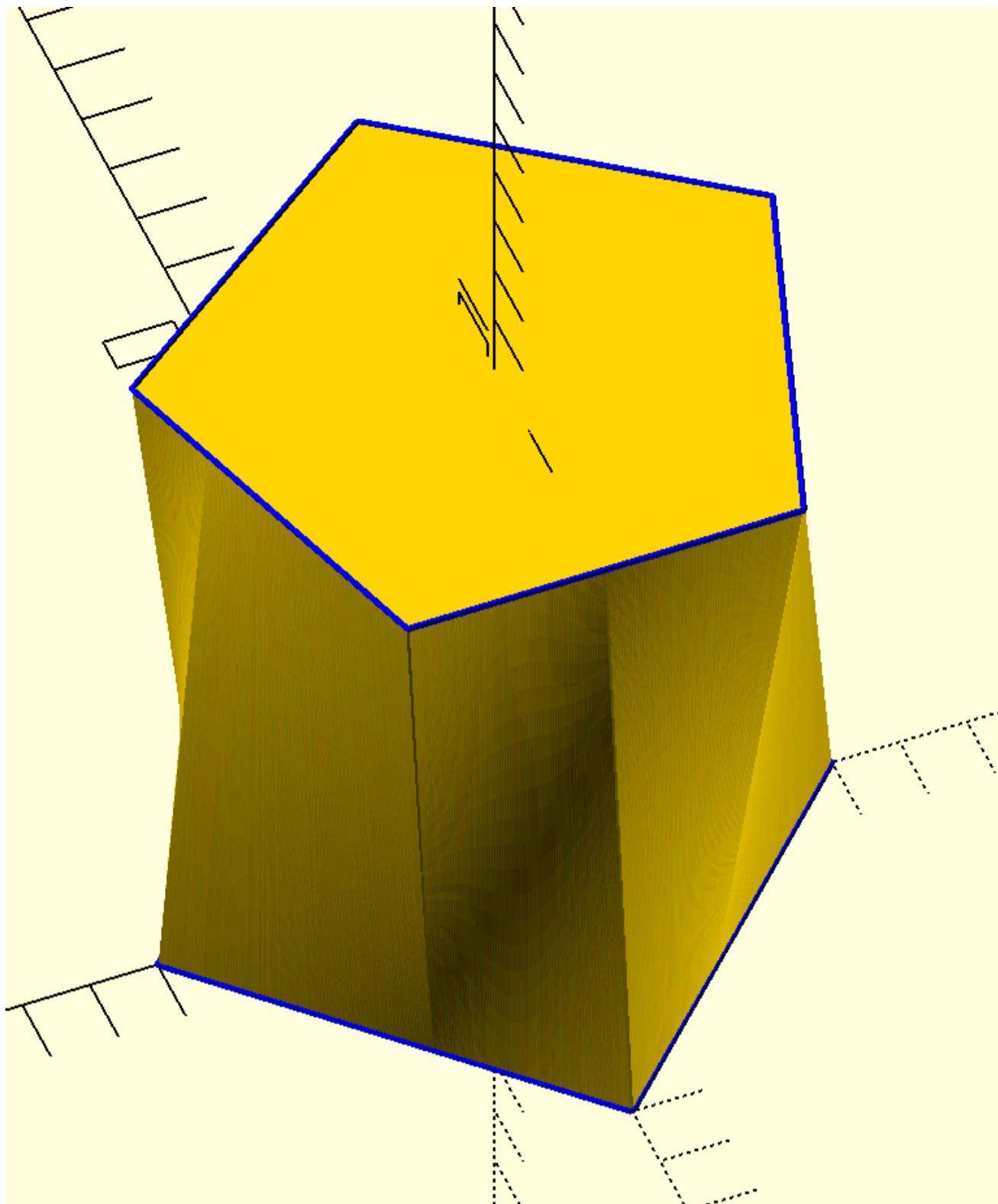


```
In [5]: # example of function align_sol(sol,angl)
```

```
sqr1=c2t3(equidistant_pathc(circle(5,s=5),200)[:200])
pent1=equidistant_pathc(circle(5,s=6),200)[:200]
pent1=translate([0,0,10],pent1)
sol=[sqr1]+[pent1]
sol=align_sol_1(sol)
sol1=slice_sol(sol,10)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

{swp(sol1)}
color("blue")p_line3dc({sol[0]},.05);
color("blue")p_line3dc({sol[1]},.05);
'''')
```



```
In [22]: sqr1=circle(5,s=5)
pent1=circle(5,s=6)

sqr1,pent1=c2t3(equate_points(sqr1,pent1))
pent1=translate([0,0,10],q_rot(['y-30'],pent1))
sol=[sqr1]+[pent1]
sol=align_sol(sol,.1)
sol1=slice_sol(sol,100)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

{swp(sol1)}
color("blue")p_line3dc({sol[0]},.05);
color("blue")p_line3dc({sol[1]},.05);
color("magenta")p_line3dc({pent1},.05);

'''')
```

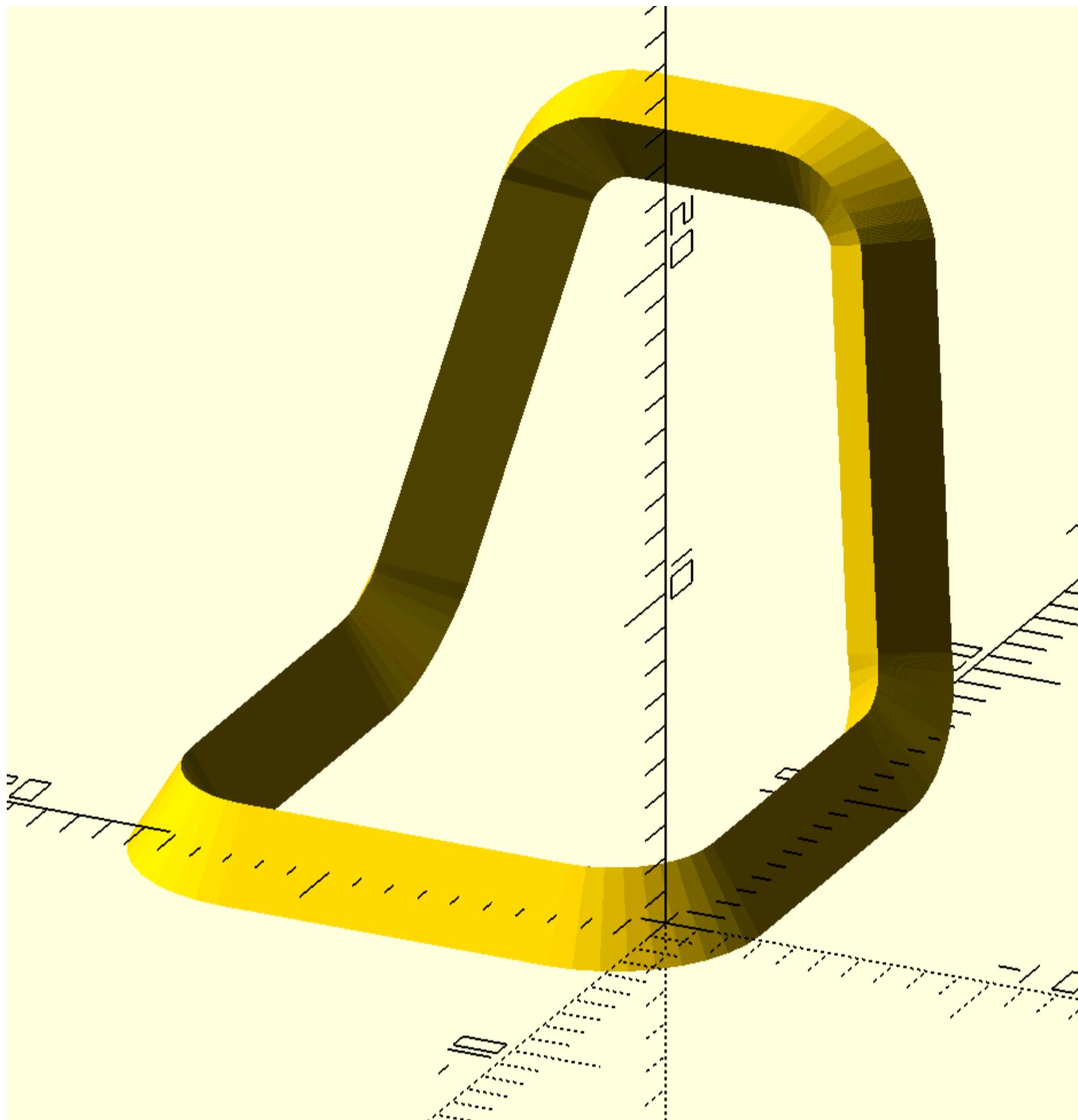
```
In [10]: # example of function align_sol(sol, ang=10)
t0=time.time()

path=cr_3d([[0,0,0,3],[15,0,0,4],[5,3,15,3],[0,10,0,3],[-5,3,-15,4],[-15,0,0,3]],10)
sec=pts([[1.5,-1.25],[3,0],[-1.5,2.5]])
sol=path_extrude_closed(sec,path,twist=1)
# sol=align_sol(sol,1)

sol=slice_sol_1(sol,200)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
//color("blue")for(p={sol})p_line3dc(p,.1,1);
{swp_c(sol)}

'''')
t1=time.time()
t1-t0
```

Out[10]: 0.8222799301147461



```
In [24]: # approach to align absolutely different shapes

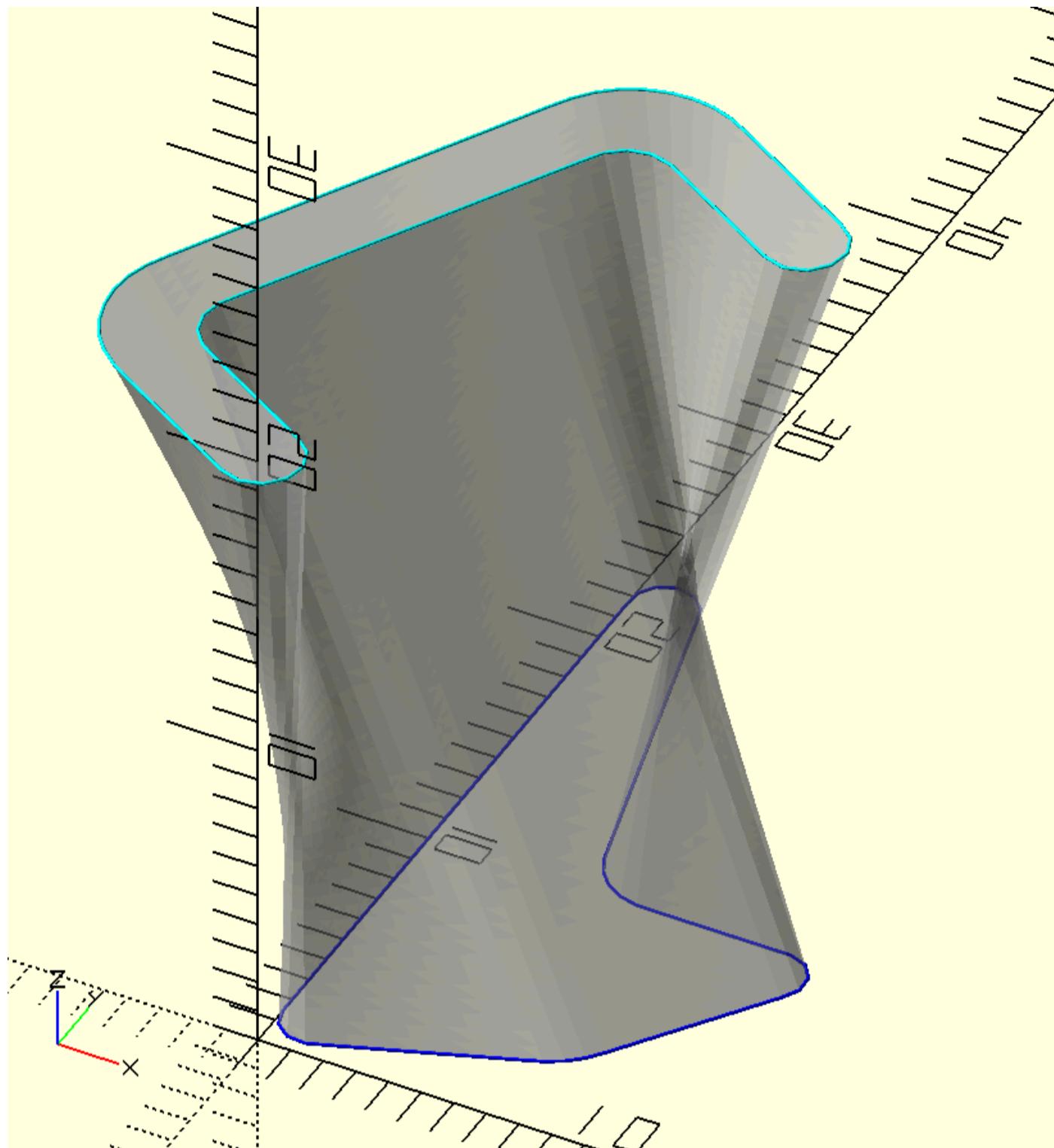
sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),30)
sec1=scl2d_c(corner_radius(pts1([[-15,0,2.4],[0,15,3],[30,0,3],[0,-15,2.4],[5,0,2.4],[0,20,7],[-40,0,7],[0,-20,2.4]]),10),.5)

sec2=c2t3(equidistant_pathc(sec,100))
sec3=translate([0,0,20],equidistant_pathc(sec1,100))
sol=[sec2,sec3]
sol=slice_sol(align_sol(sol),50)

t0=time.time()
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
difference() {{
    {swp(sol)}
    //cube(10);
}}
//color("blue")p_line3dc({sol[0]},.05);
//color("cyan")p_line3dc({sol[-1]},.05);

''')
t1=time.time()
t1-t0
```

Out[24]: 0.028511524200439453



align_sol_1

```
In [2]: # example of function align_sol_1(sol)

t0=time.time()

sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)
cp1=array(sec).mean(0)

pent1=circle(7,s=6)
pent2=c3t2(q_rot([f'z{360/5/2}'],circle(3.5,s=6)))
sec1=concatenate(cpo([pent1]+[pent2])).tolist()

sec=translate(-cp1,(equidistant_pathc(sec,200)))
sec1=translate([0,0,20],equidistant_pathc(sec1,200))
sol=slice_sol(align_sol_1([sec,sec1]),20)

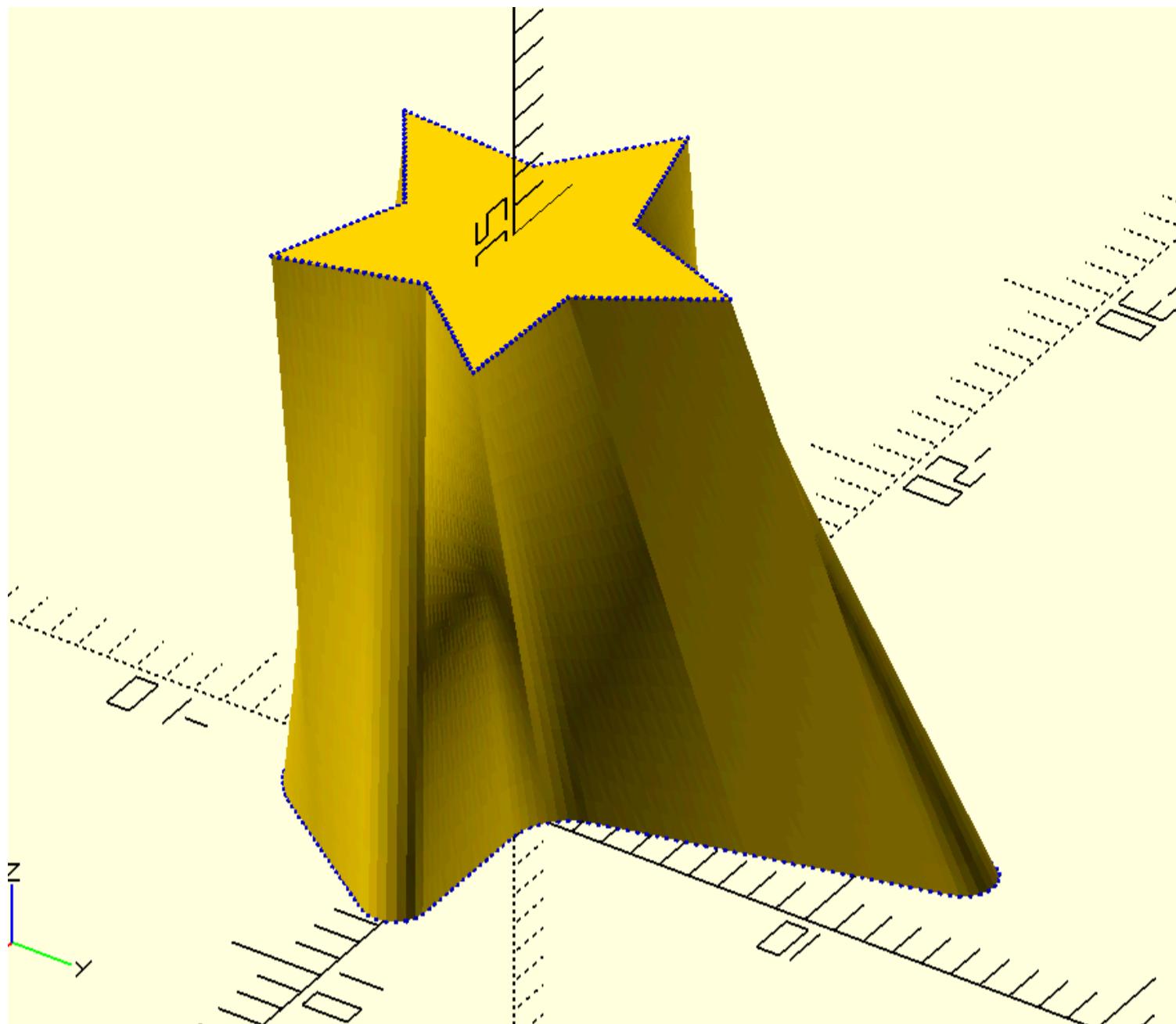
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

sec={sec};
sec1={sol[1]};
{swp(sol)}
color("blue")points({sol[-1]},.1);
color("blue")points({sol[0]},.1);
//for(i=0:len(sec)-1)translate(sec[i])linear_extrude(.1)text(str(i),.2);
//for(i=0:len(sec1)-1)translate(sec1[i])linear_extrude(.1)text(str(i),.2);

''')

t1=time.time()
t1-t0
```

Out [2]: 0.3692920207977295



```
In [125... # very fine merging of 2 very different shapes
t0=time.time()
sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)
sec1=corner_radius(pts1([[0,0,1],[7,5,2],[5,7,3],[-5,7,2],[-7,5,3]]),20)
sec1=corner_radius(pts1([[-15,0,2.4],[0,15,3],[30,0,3],[0,-15,2.4],[5,0,2.4],[0,20,7],[-40,0,7],[0,-20,2.4]]),30)

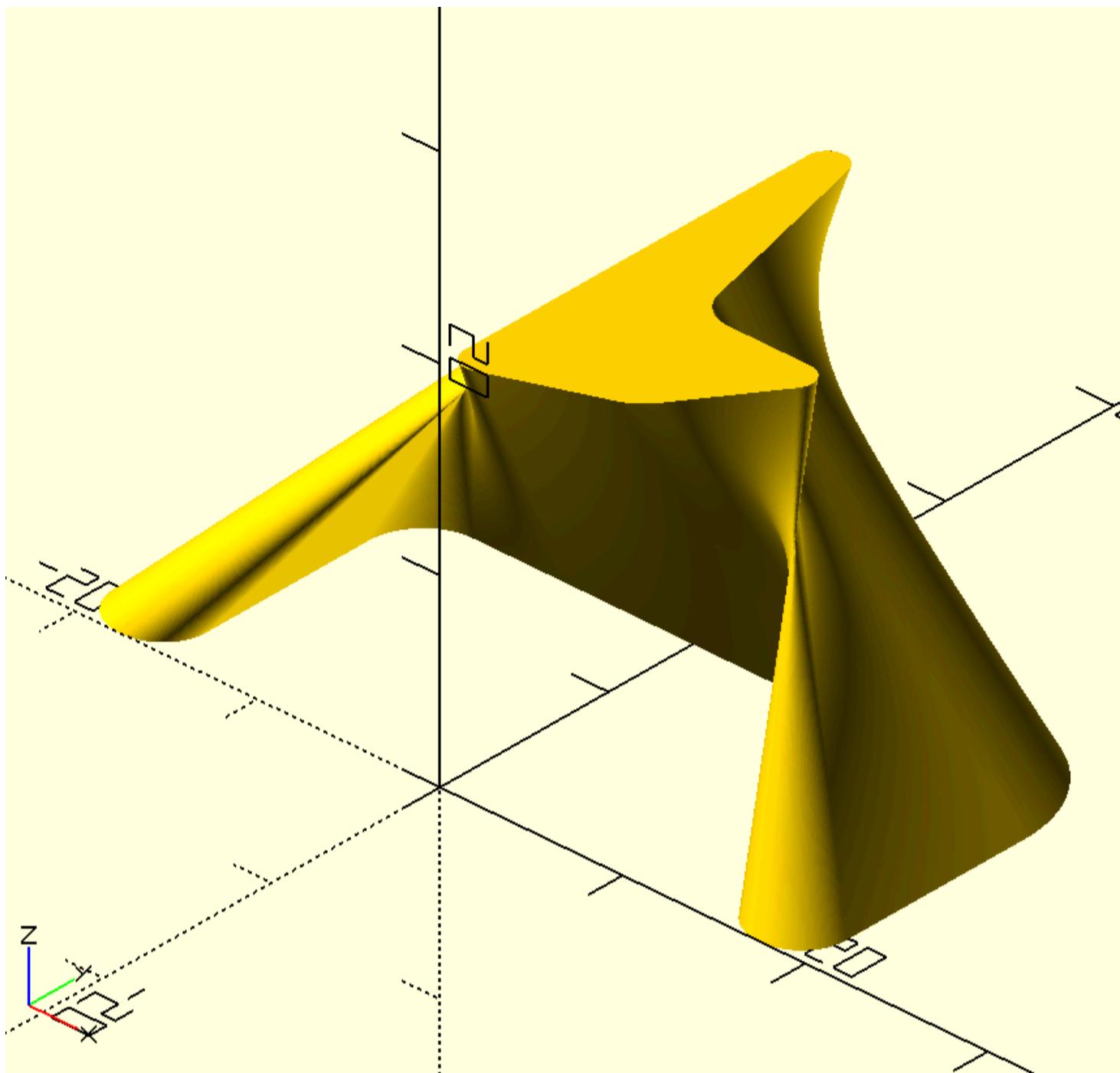
s1=translate([0,0,20],equidistant_pathc(sec,1000))
s2=c2t3(equidistant_pathc(sec1,1000))

s3=slice_sol(align_sol_1([s2]+[s1]),100)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
swp({s3});

''')
t1=time.time()
t1-t0
```

Out[125... 1.7837989330291748



end_cap

```
In [2]: # example of function path_extrude_open and end_cap

i_t=time.time()
sec=corner_radius(pts1([[-1.5,-1.5,.5],[3,0,.5],[0,3,1.49],[-3,0,1.49]]),10)
path=q_rot(['x-90'],cr_3d([[0,0,0,0],[3,5,10,5],[17,-2,5,6],[1,-10,10,0]],10))
sol=q_rot(['x90'],path_extrude_open(sec,path))
sol=align_sol_1(sol)
sol=slice_sol(sol,10)

e_cap=end_cap(sol,1)
f3=e_cap[0]
f4=e_cap[1]

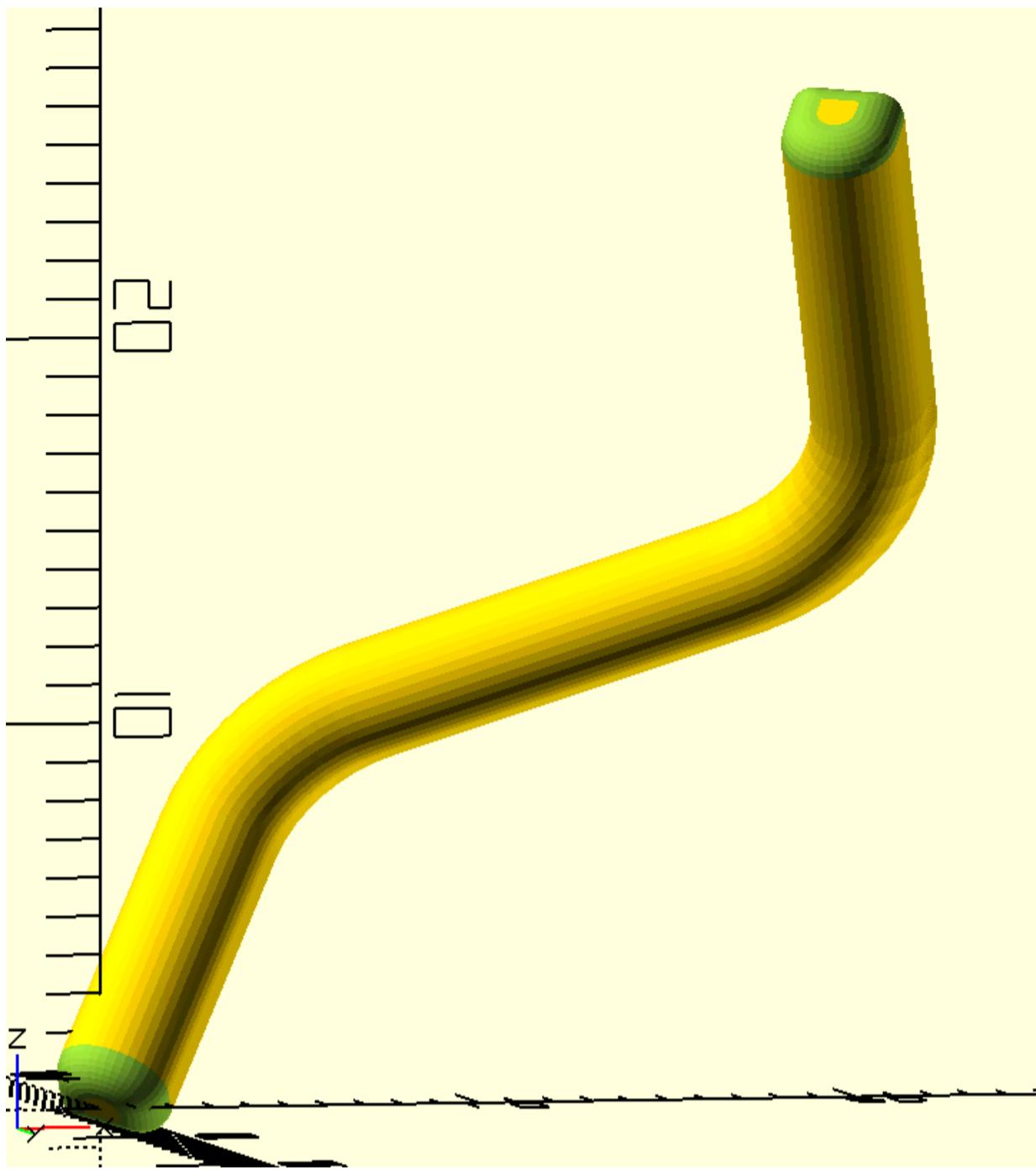
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

difference(){
{swp(sol)}
{swp_c(f3)}
{swp_c(f4)}

}
'''')
f_t=time.time()
f_t-i_t
```

c:\openscad\openSCAD-main\openscad1.py:5727: RuntimeWarning: invalid value encountered in divide
u1=v1/norm(v1)

Out [2]: 2.719264268875122



sec2vector

```
In [27]: # example of function sec2vector(v1,sec)
i_t=time.time()
sec=corner_radius(pts1([[-1.5,-1.5,.5],[3,0,.5],[0,3,.5],[-3,0,.5]]),10)
v1=[1,2,-1]
vector1=[[0,0,0],v1]
sec1=sec2vector(v1,sec)

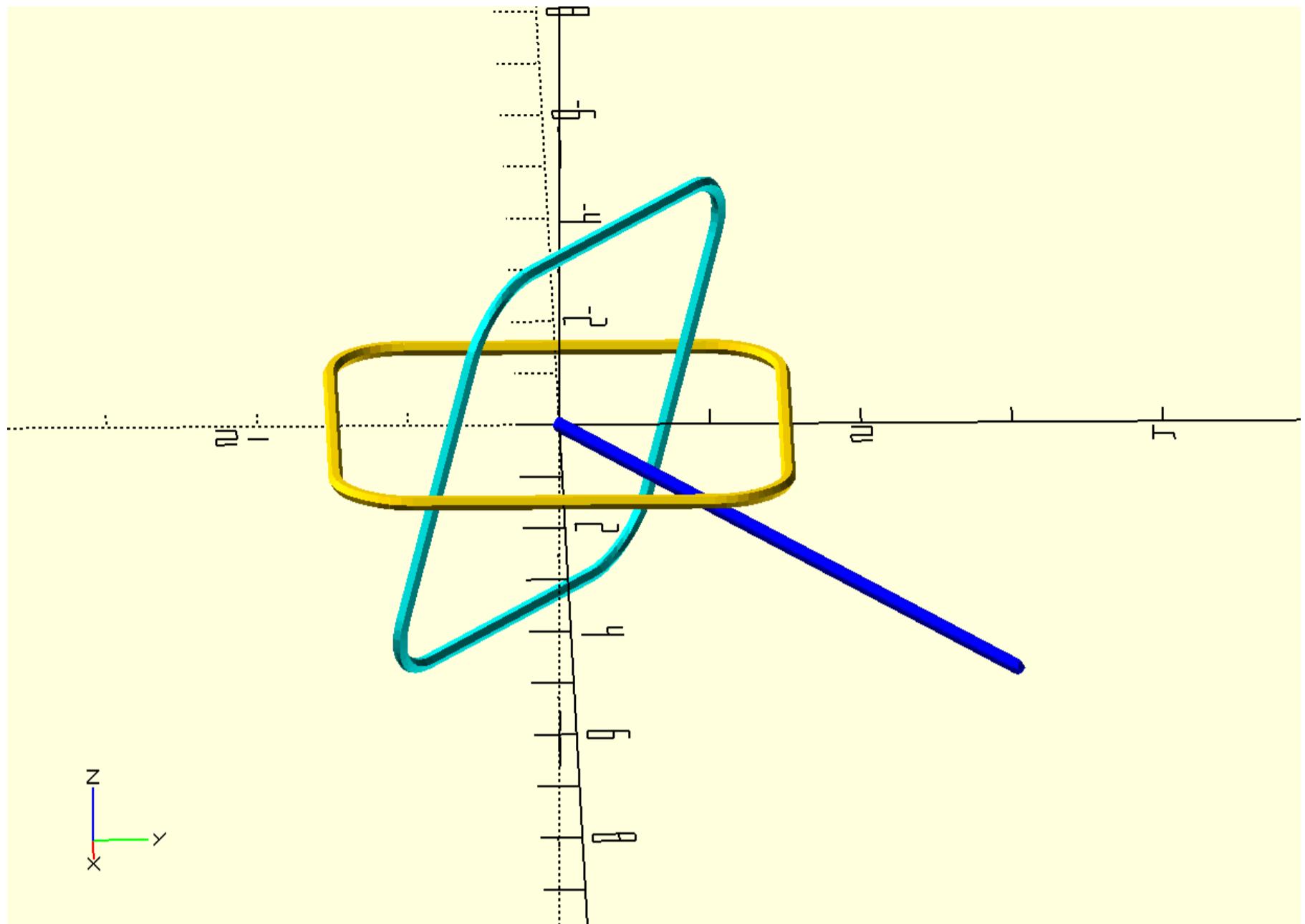
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
// original section
p_line3dc({sec},.05);

//aligned section in cyan color
color("cyan")p_line3dc({sec1},.05);

//vector with whom the section is expected to be aligned with in blue color
color("blue")p_line3d({vector1},.05);

''')
f_t=time.time()
f_t-i_t
```

Out[27]: 0.005366802215576172



cut_plane

```
In [28]: # example of function cut_plane(nv, radius, thickness, trns)
t0=time.time()

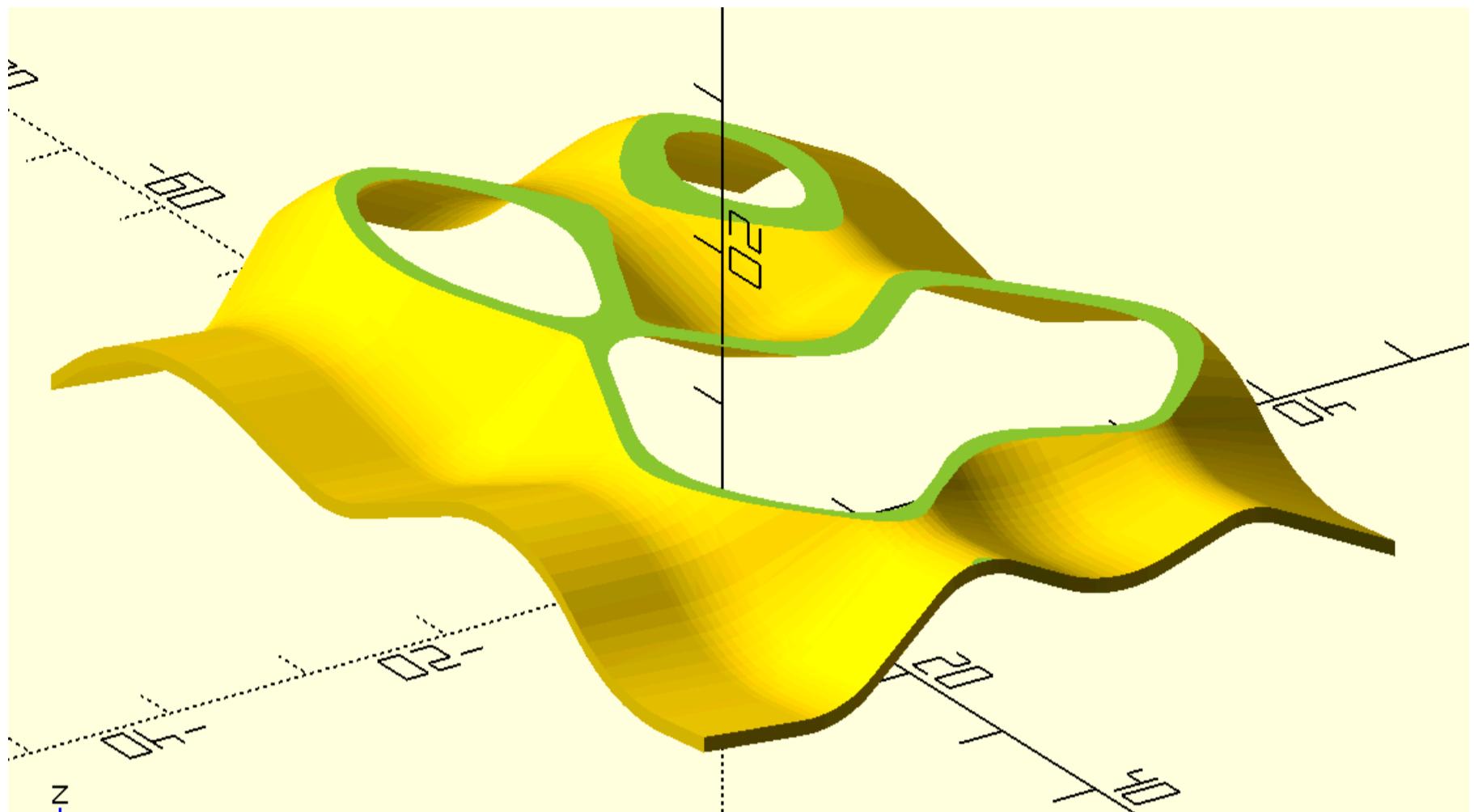
sec2=corner_radius(pts1([[-25,0],[10,5,5],[10,-3,10],[10,5,5],[10,-8,7],[10,1]]),10)
path2=cytz(corner_radius(pts1([-35,5,0],[10,8,20],[20,-5,10],[20,8,20],[10,-9,20],[10,1,0])),10))
surf2=surf_extrude(sec2,path2)
surf3=surf_extrude(surf2,t=-1)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

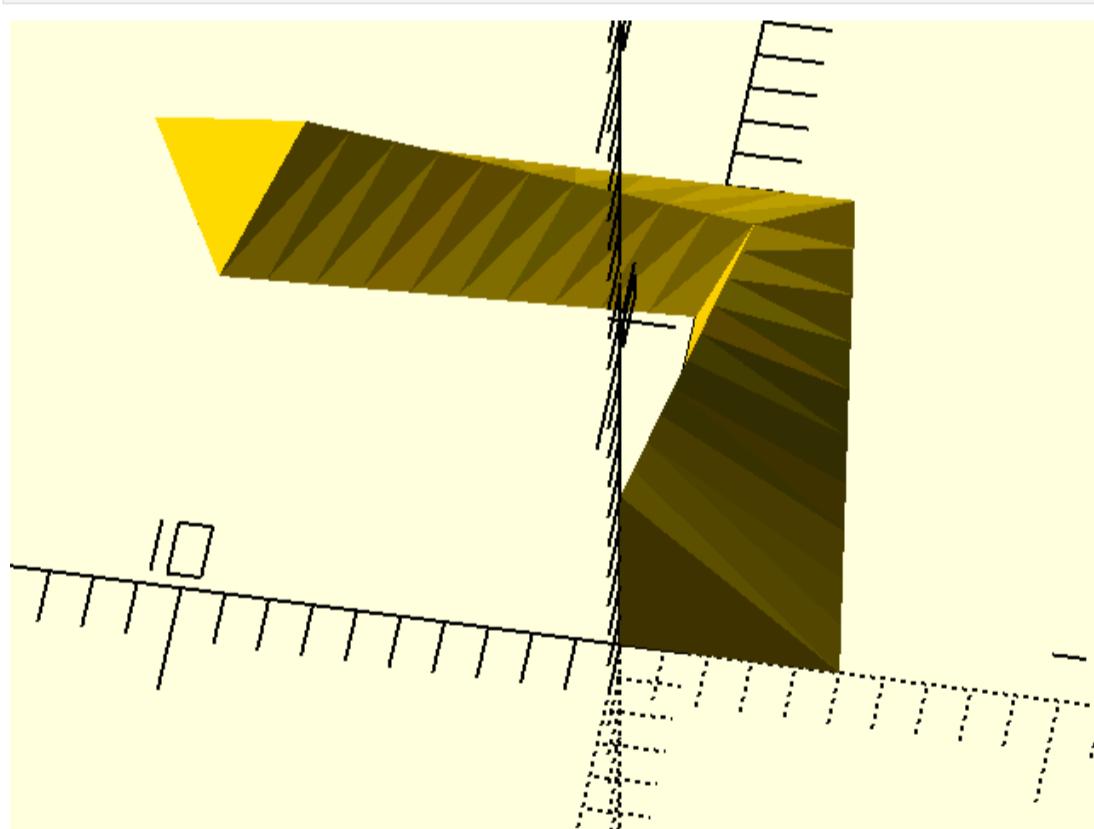
difference(){
{swp(surf3)}
{swp(cut_plane([0,0,1],[100,100],10,14))}

'''')
t1=time.time()
total=t1-t0
total
```

Out[28]: 0.07706761360168457

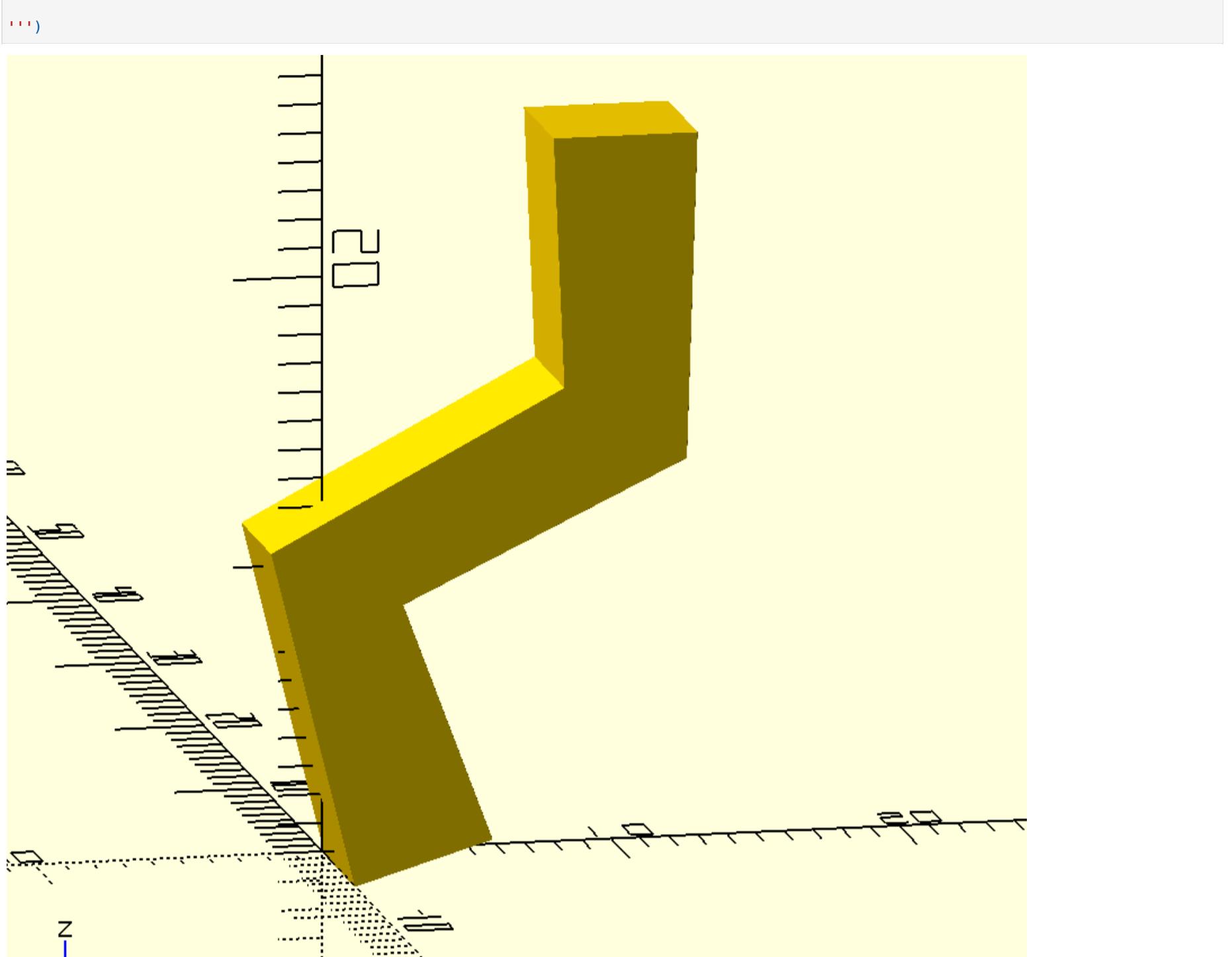


```
In [5]: sec=[[0,0],[5,0],[0,5]]
path=[[0,0,0],[10,0,0],[5,10,5]]
sol=path_extrude_open(sec,path)
sol=align_sol_1(sol)
sol2=slice_sol(sol,10)
with open('trial.scad','w+') as f:
    f.write(f'''  
include<dependencies2.scad>  
  
difference(){{  
{swp(sol2)}  
  
//{swp(cut_plane([1,1,1],30,7,-3))}  
}}  
'''')
```

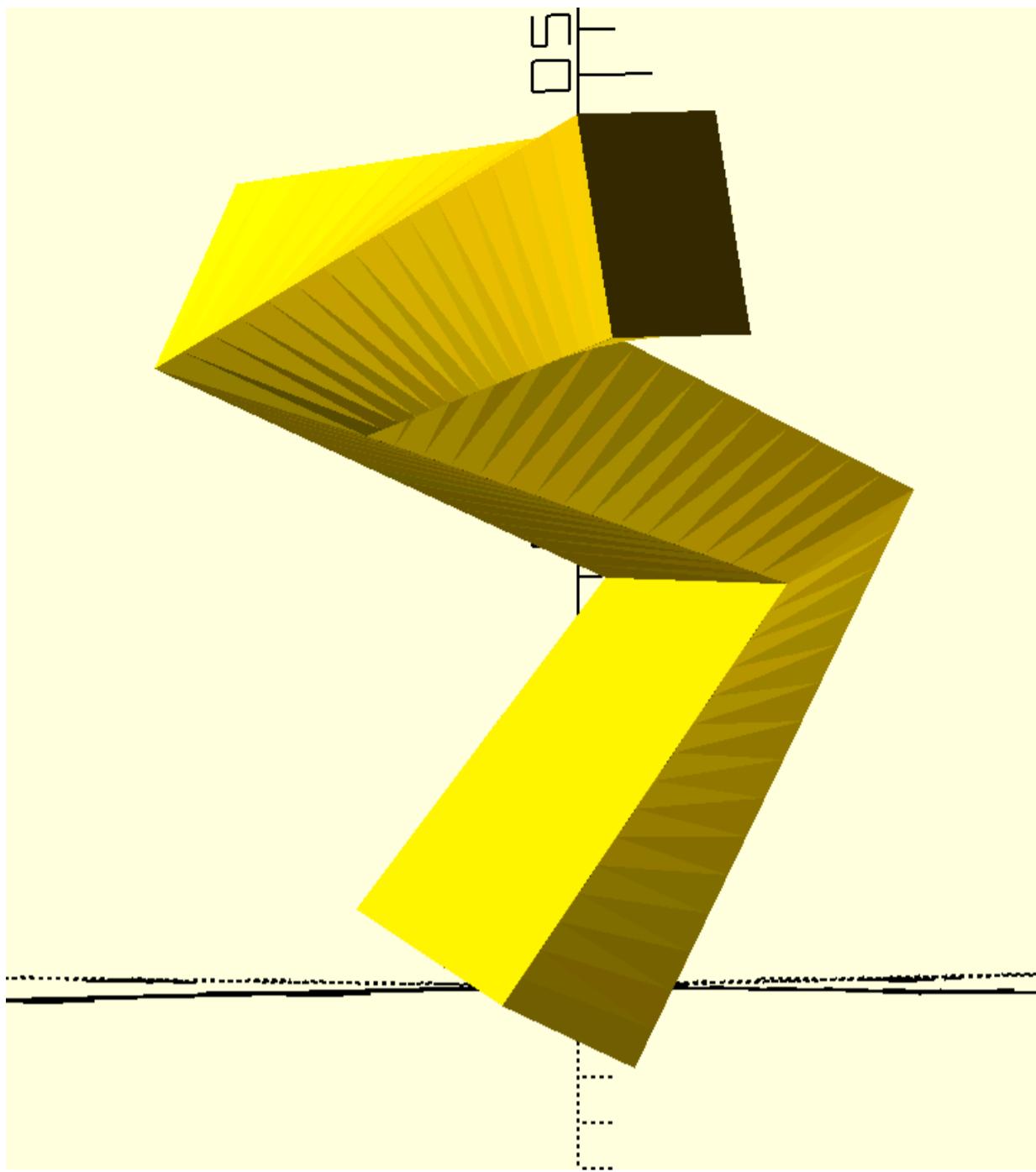


slice_sol

```
In [6]: sec=square(5,True)
path=q_rot(['x-90'],[[3,0,0],[0,0,10],[10,0,15],[10,0,25]])
sol=q_rot(['x90'],path_extrude_open(sec,path))
# sol=align_sol(sol)
sol2=slice_sol(sol,10)
with open('trial.scad','w+') as f:
    f.write(f'''  
include<dependencies2.scad>  
//color("blue")p_line3dc({sec},.1,1);
//color("blue")p_line3d({cytz(path)},.1,1);
//color("cyan")points({cytz(path)},.5);  
  
{swp(sol2)}
//color("magenta")for(p={sol2})p_line3dc(p,.1,1);
```



```
In [49]: sec=square(5,True)
path=q_rot(['x0'],pts2([[3,0,0],[-3,5,10],[10,-5,5],[0,10,2]]))
sol=path_extrude_open(sec,path)
sol=align_sol(sol,1)
sol2=slice_sol(sol,5)
sol3=offset_sol(sol2,.5,1)
sol4=swp_prism_h(sol3,sol2)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("magenta")p_line3d({{path}},.1,rec=1);
//color("cyan")for(p={{sol2}})p_line3dc(p,.1);
{{swp_c({sol4})}}
''' )
```



o_solid

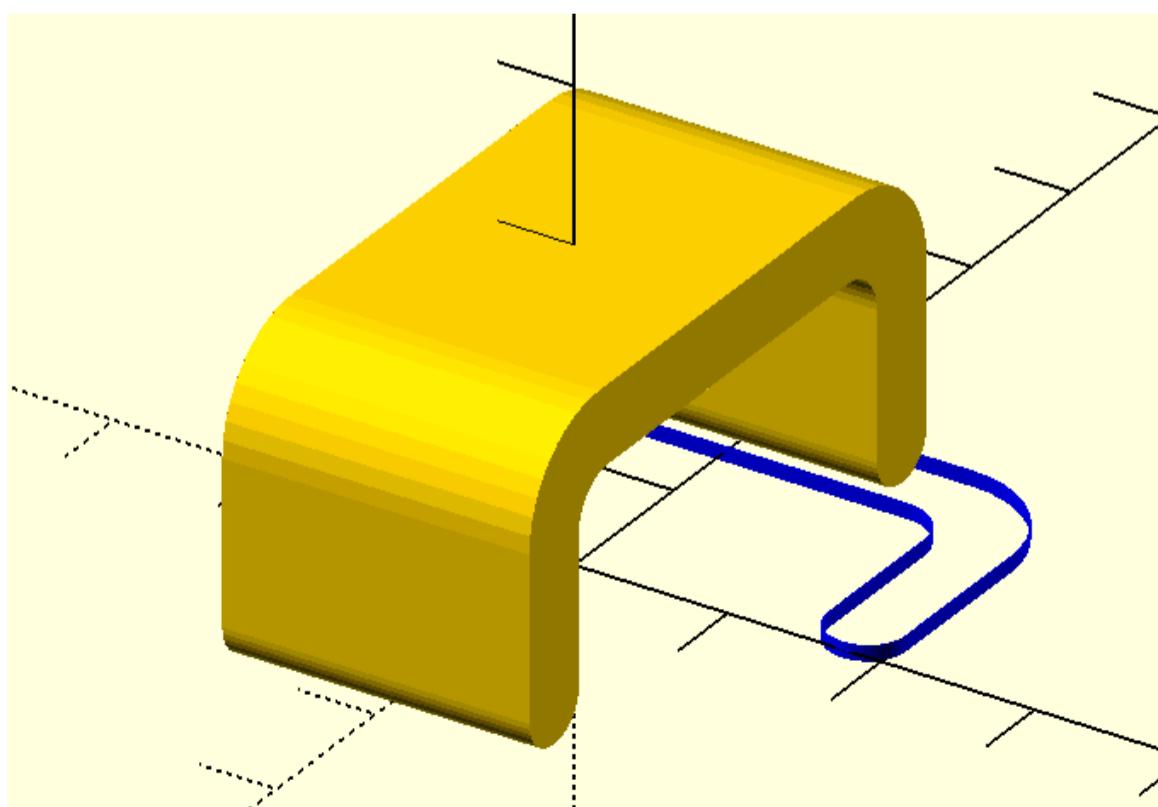
```
In [29]: # example of function o_solid(nv,sec,thickness,trns1,trns2,trns3)

# sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),30)
# sec=corner_radius(pts1([[0,0,1],[7,5,2],[5,7,3],[-5,7,5],[-7,5,5]]),10)
sec=corner_radius(pts1([[-15,0,2.4],[0,15,3],[30,0,3],[0,-15,2.4],[5,0,2.4],[0,20,7],[-40,0,7],[0,-20,2.4]]),10)
# sec=corner_radius(pts1([[0,0,1],[10,0,1],[0,5,1],[-10,0,1]]),10)
# sec=circle(10)

sol=o_solid([1,0,0],sec,20,-10,0,0,theta=[0,0,0])
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

{swp(sol)}
color("blue")p_line({sec},.05);

''' )
```



```
In [31]: t0=time.time()
sec=corner_radius(pts1([[-5,-5,1],[10,0,1],[0,10,1],[-10,0,1]]),5)
sec1=corner_radius(pts1([[-5,-5,1],[10,0,1],[0,10,1],[-10,0,1]]),5)

path=corner_radius(pts1([[-4,0],[4,0,1],[0,10,1],[-4,0]]),5)
# path=equidistant_path(path,100)
sol1=f_prism(sec,path)

sol2=o_solid([1,0,.1],circle(2,s=50),15,-7,0,10,[90,0,0])

with open('trial.scad','w+')as f:
    f.write(f'''
        include<dependencies.scad>

{swp(sol1)}
{swp(sol2)}

    ''')
t1=time.time()
t1-t0
```

Out[31]: 0.03232717514038086

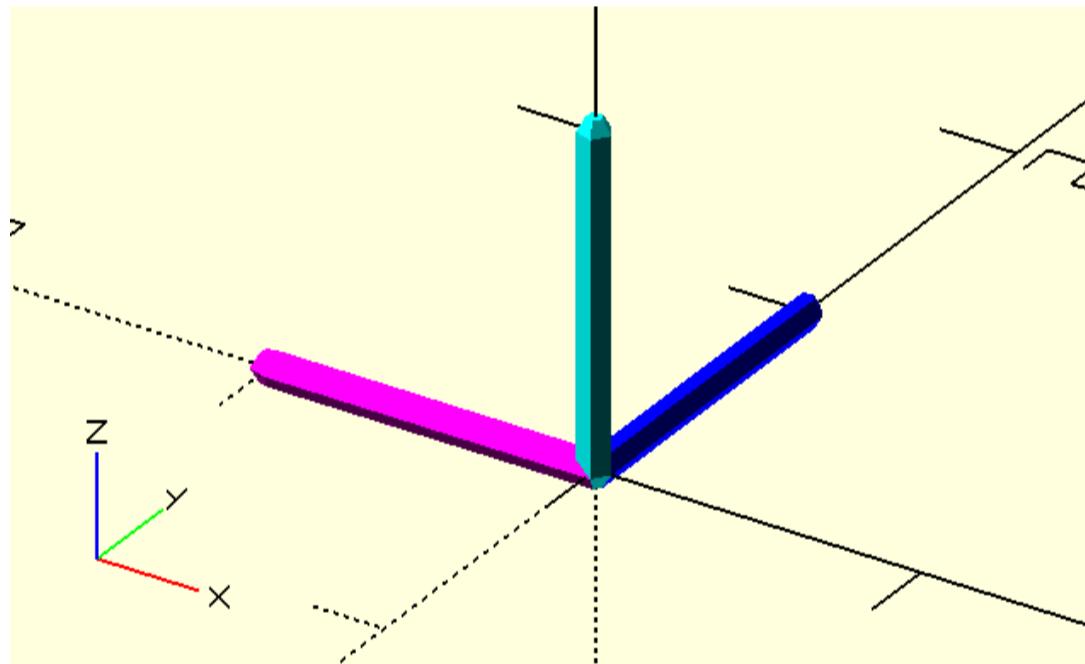
```
In [40]: # example of defining normal vectors to a given vector 'v1'

v1=[1,1,sqrt(2)]
u1=v1/norm(v1)
ua=array([0,0,-1]) if u1[2]==0 else array([0,-1,0]) if (u1==[0,0,1]).all() else array([-1,0,0]) if (u1==[0,0,-1]).all() else array([u1[0],
v2=cross(u1,ua)
u2=v2/norm(v2)
u3=array(q(u2,u1,-90))

u1,u2,u3=array([u1,u2,u3]).tolist()
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>

color("blue")p_line3d({[0,0,0],u1},.05);
color("magenta")p_line3d({[0,0,0],u2},.05);
color("cyan")p_line3d({[0,0,0],u3},.05);

    ''')
```



```
In [133... with open('trial.scad','w+') as f:
    f.write(f'''

cylinder (d=30,h=30); // hub.
linear_extrude (height=30, twist=100, $fn=100)
for (a=[0:120:359]) rotate (a) translate ([15,-1]) square ([45,2]);

    ''')
```

ppplane

```
In [135... # points projected on a plane
t0=time.time()

p0=random.random([10,3))*(20-(-20))+(-20)
loc=[0,10,1]
v1=[2,3,4]

sec=pts([[-50/2,-50/2],[50,0],[0,50],[-50,0]])
plane1=translate(loc,o_solid(v1,sec,.001))

ip1=ppplane(p0,v1,loc)
lines1=array([p0,ip1]).transpose(1,0,2).tolist()
```

```

with open('trial.scad','w+') as f:
    f.write(f'''

include<dependencies2.scad>
//p_line({sec},.05);

color("cyan")p_line3dc({plane1[0]},.1);
color("blue")points({p0.tolist()},.5);

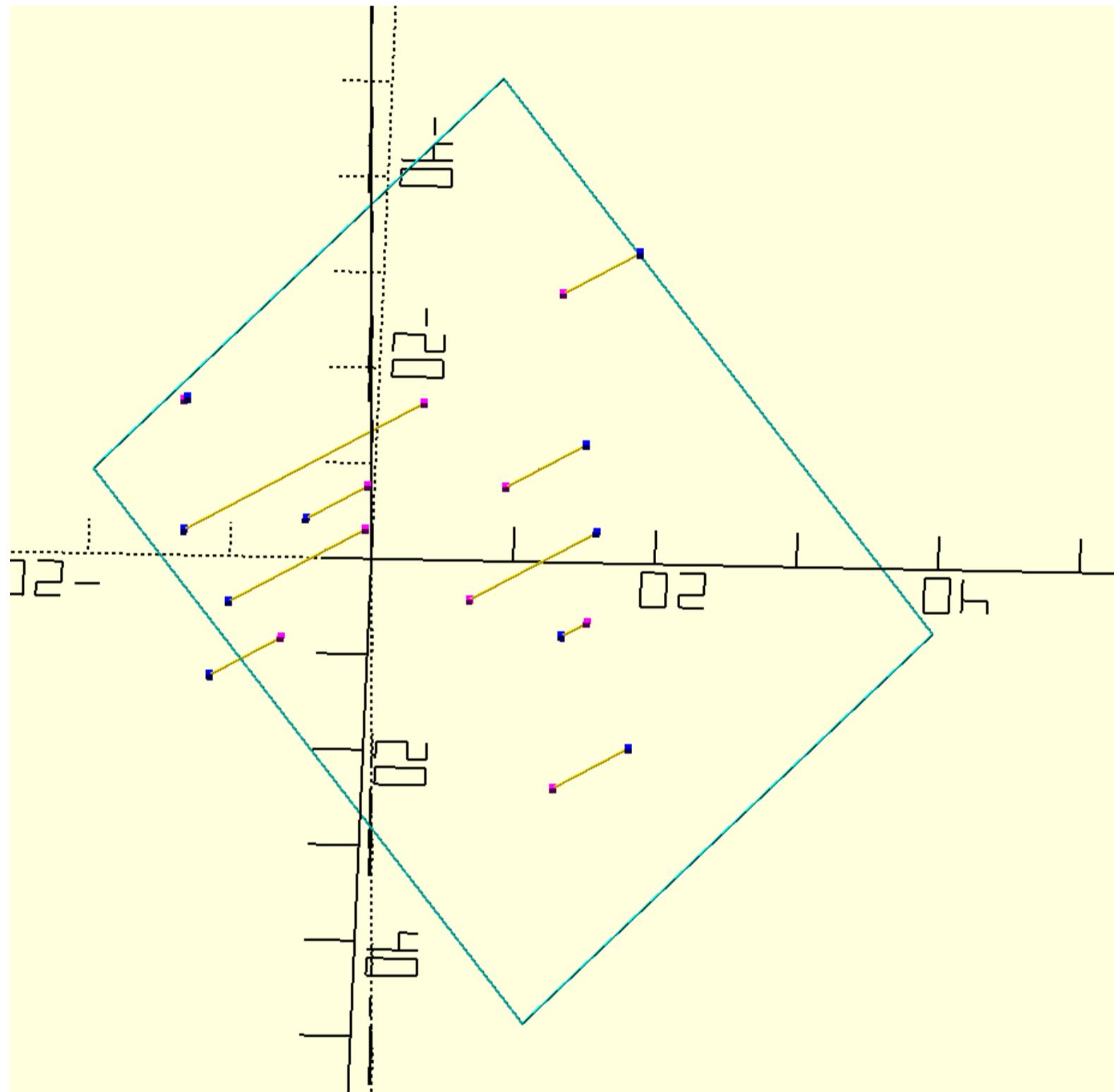
color("magenta")points({ip1},.5);

for(p={lines1})p_line3d(p,.1);

''')
t1=time.time()
t1-t0

```

Out[135]: 0.012294530868530273



ppesec

```

In [32]: # points projected on an enclosed section in 3d space
t0=time.time()

p0=random.random([10,3])*(20-(-20))+(-20)
loc=[0,10,1]
v1=[2,3,4]

sec=pts([[-50/2,-50/2],[50,0],[0,50],[-50,0]])
plane1=translate(loc,o_solid(v1,sec,.001))

ip1=ppesec(p0,plane1[0])[0]

lines1=array(ppesec(p0,plane1[0])).transpose(1,0,2).tolist()

with open('trial.scad','w+') as f:
    f.write(f'''

include<dependencies2.scad>
//p_line({sec},.05);

color("cyan")p_line3dc({plane1[0]},.1);
color("blue")points({p0.tolist()},.5);

color("magenta")points({ip1},.5);

for(p={lines1})p_line3d(p,.1);

''')
t1=time.time()
t1-t0

```

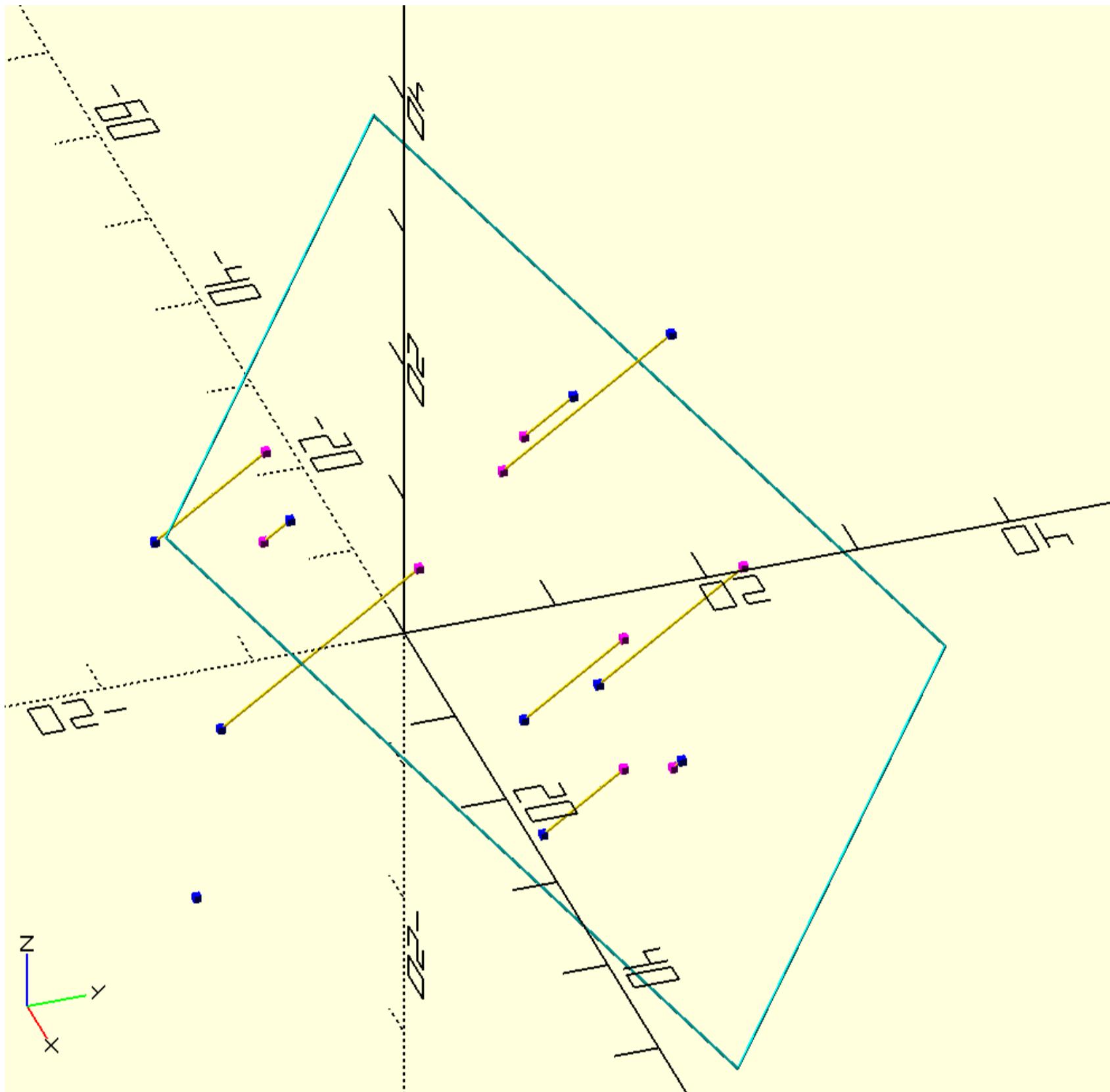
```

for(p={lines1})p_line3d(p,.1);

''')
t1=time.time()
t1-t0

```

Out[32]: 0.007561922073364258



In [33]: # another example of points projected on an enclosed section in 3d space
t0=time.time()

```

p0=random.random([10,3])*(20-(-20))+(-20)
v1=[2,3,4]
sec=circle(10)
loc=[0,10,0]
plane1=translate(loc,o_solid(v1,sec,.001))

ip1=ppesec(p0,plane1[0])[0]
lines1=cpo(ppesec(p0,plane1[0]))
with open('trial.scad','w+') as f:
    f.write('''
include<dependencies2.scad>
//p_line({sec},.05);

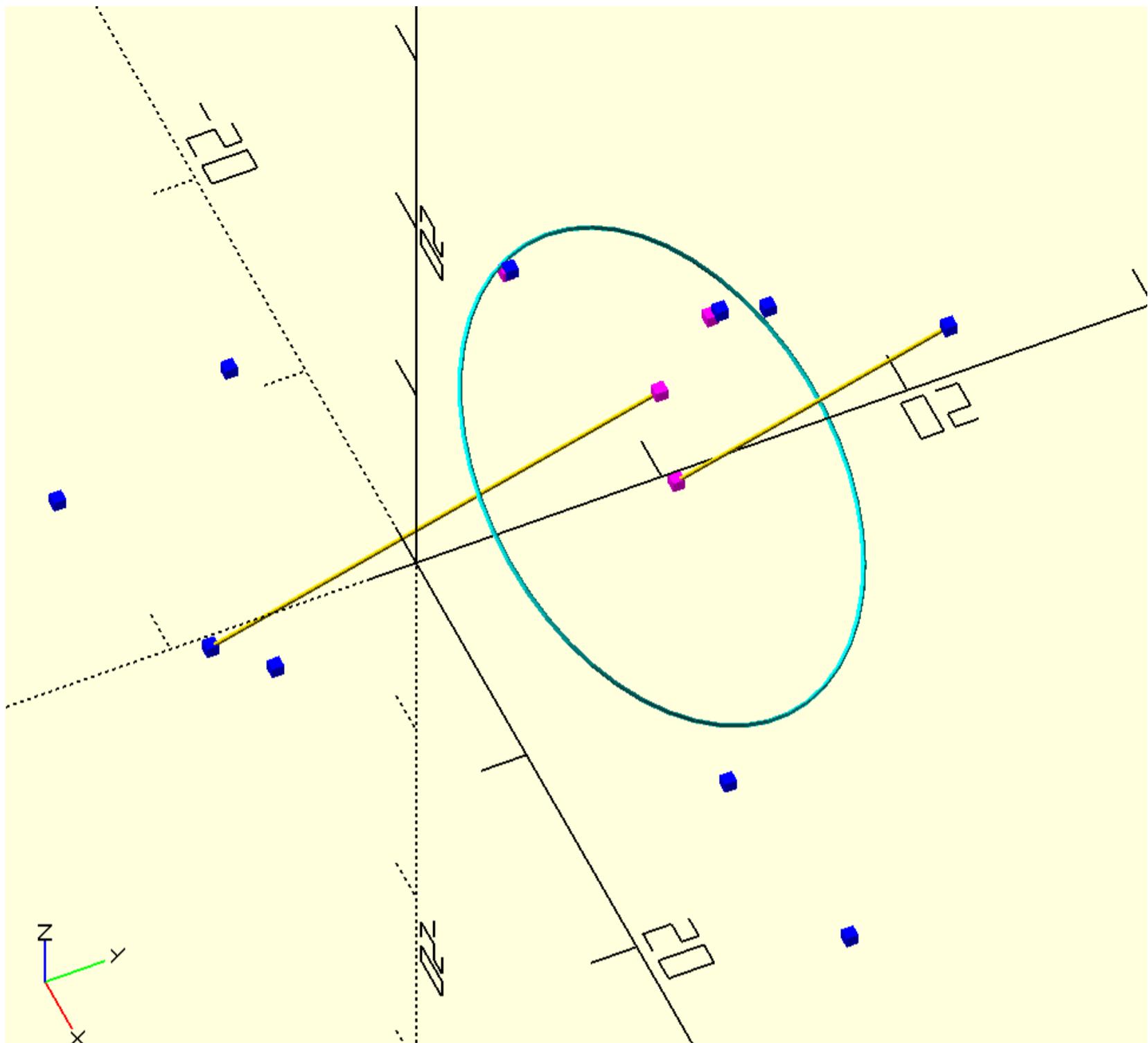
color("cyan")p_line3dc({plane1[0]},.1);
color("blue")points({p0.tolist()},.5);

color("magenta")points({ip1},.5);
for(p={lines1})p_line3d(p,.1);

'''')
t1=time.time()
t1-t0

```

Out[33]: 0.00796198844909668



honeycomb

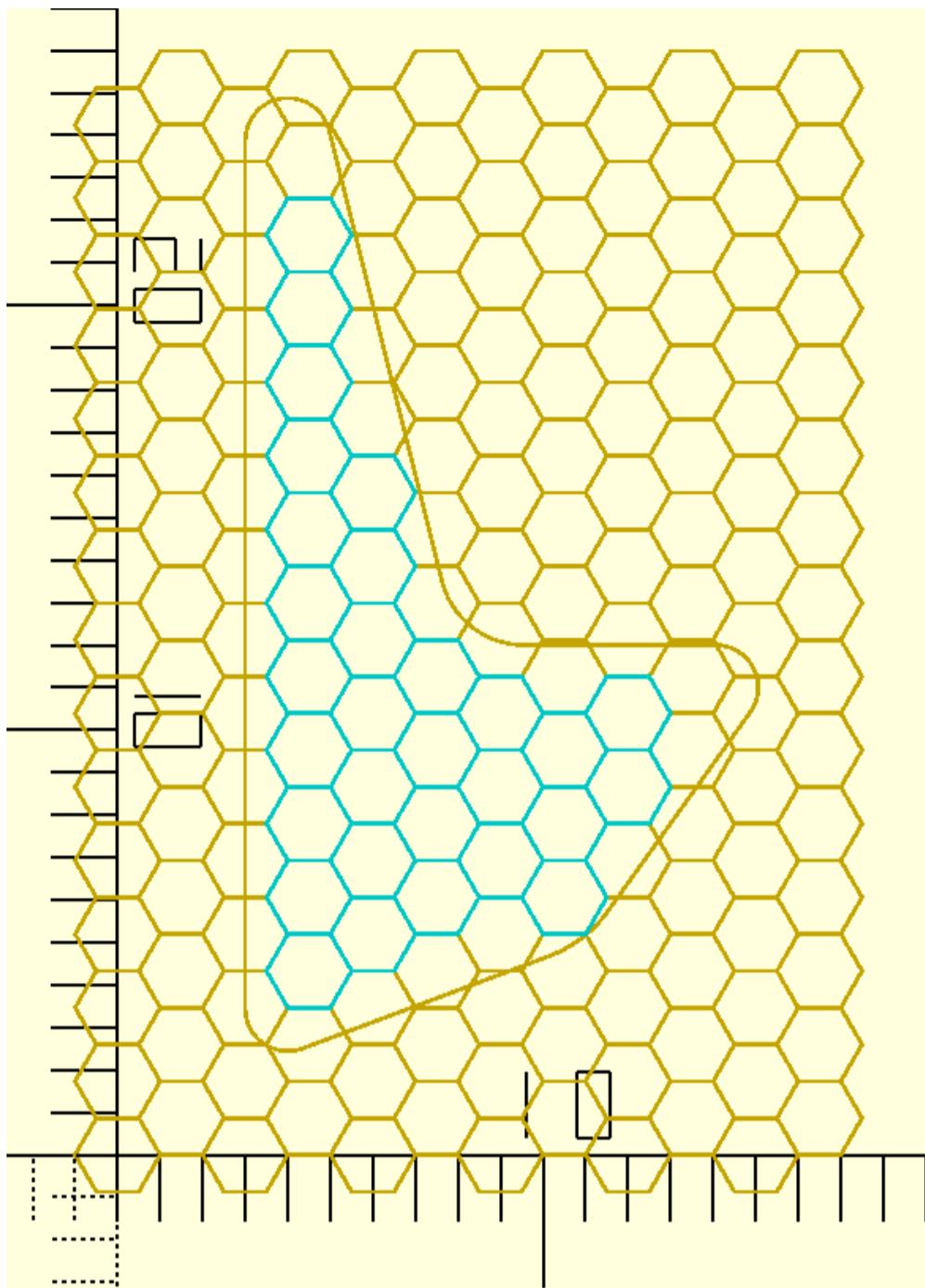
```
In [138]: # honeycomb structure

sec4=honeycomb(1,6,15)
sec=corner_radius(pts1([[3,2,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),30)
pnts1=[p for p in sec4 if len(pies1(sec,p))==6]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

for(p={sec4})p_line(p,.1);
color("blue")p_line({sec},.1);
color("cyan")for(p={pnts1})p_line(p,.1);

''' )
```



```
In [139... # honeycomb structure with intersection option
t0=time.time()

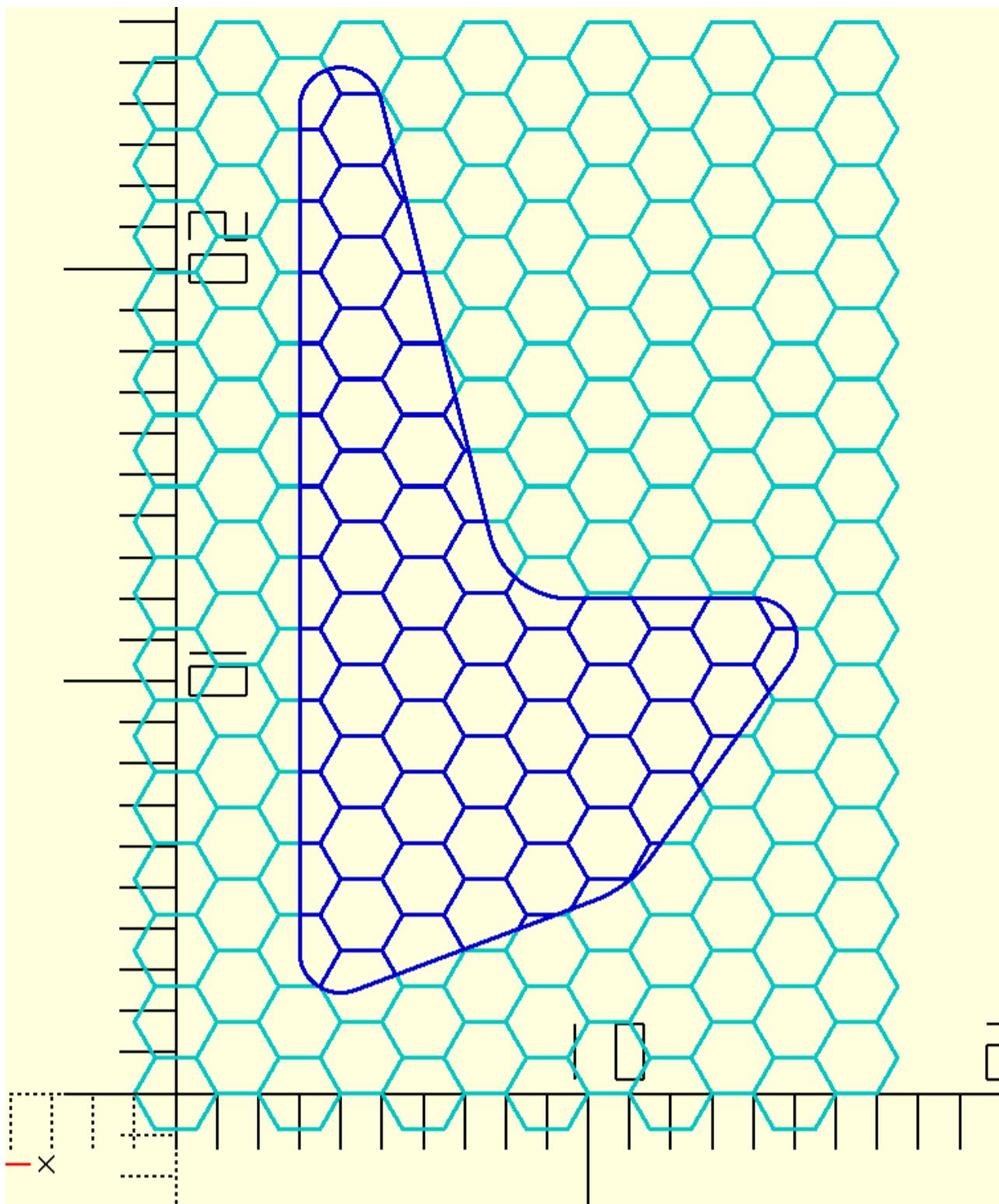
sec4=honeycomb(1,6,15)
sec=corner_radius(pts1([[3,2,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),30)
# pts1=[p for p in sec4 if len(pies1(sec,p))==6]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("cyan")linear_extrude(1)for(p={sec4})p_line(p,.1);

color("blue")
linear_extrude(1){{for(p={sec4})
intersection(){{p_line(p,.1);
polygon({sec});
}}}
p_line({sec},.1);
}};

''')
t1=time.time()
t1-t0
```

Out[139... 0.01912832260131836



chimney-panel-support

```
In [4]: # chimney panel support

sec=corner_radius(pts1([[0,5],[0,-5,3.5],[10,0,4],[2,1,1],[34,0,4],[1,3.5]]),10)
sec1=path_offset(sec,-3)
path=bezier([[-27.5,0,3]]+ arc_3p_3d([[-27,0,3],[0,0,0],[27,0,3]],100)+[[27.5,0,3]],100)
sol=path_extrude_open(sec,path)
sol1=path_extrude_open(sec1,path[1:-1])
sec2=corner_radius(pts1([[0,0],[25,0,.5],[0,4,.5],[-1,3,.5],[-1.5,0,.5],[-2,-3,1],[-20.5,0]]),10)
sol2=translate([0,-17,1],path_extrude_open(sec2,path[47:-47]))
sec3=corner_radius(pts1([[-6,-5,5],[12,0,5],[0,10.0001,5],[-12,0,5]]),10)
sol3=o_solid([0,0,1],sec3,5,0,0,-37)
sec4=corner_radius(pts1([[0,0],[5,0,10],[7,7,10],[14,0]]),20)
sec5=path_offset(sec4,-3)
sec6=sec4+flip(sec5)
sol4=translate([0,-25,1],path_extrude_open(sec6,path[16:30]))
sol5=translate([0,-25,1],path_extrude_open(sec6,path[-30:-16]))
sol6=translate([12,-25,2],q_rot(['x90','z-90']),linear_extrude(sec6[20:-20],39))

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
module chimeny_support(){
difference(){
{swp(sol)}
{swp(sol1)}
{swp(sol3)}
}

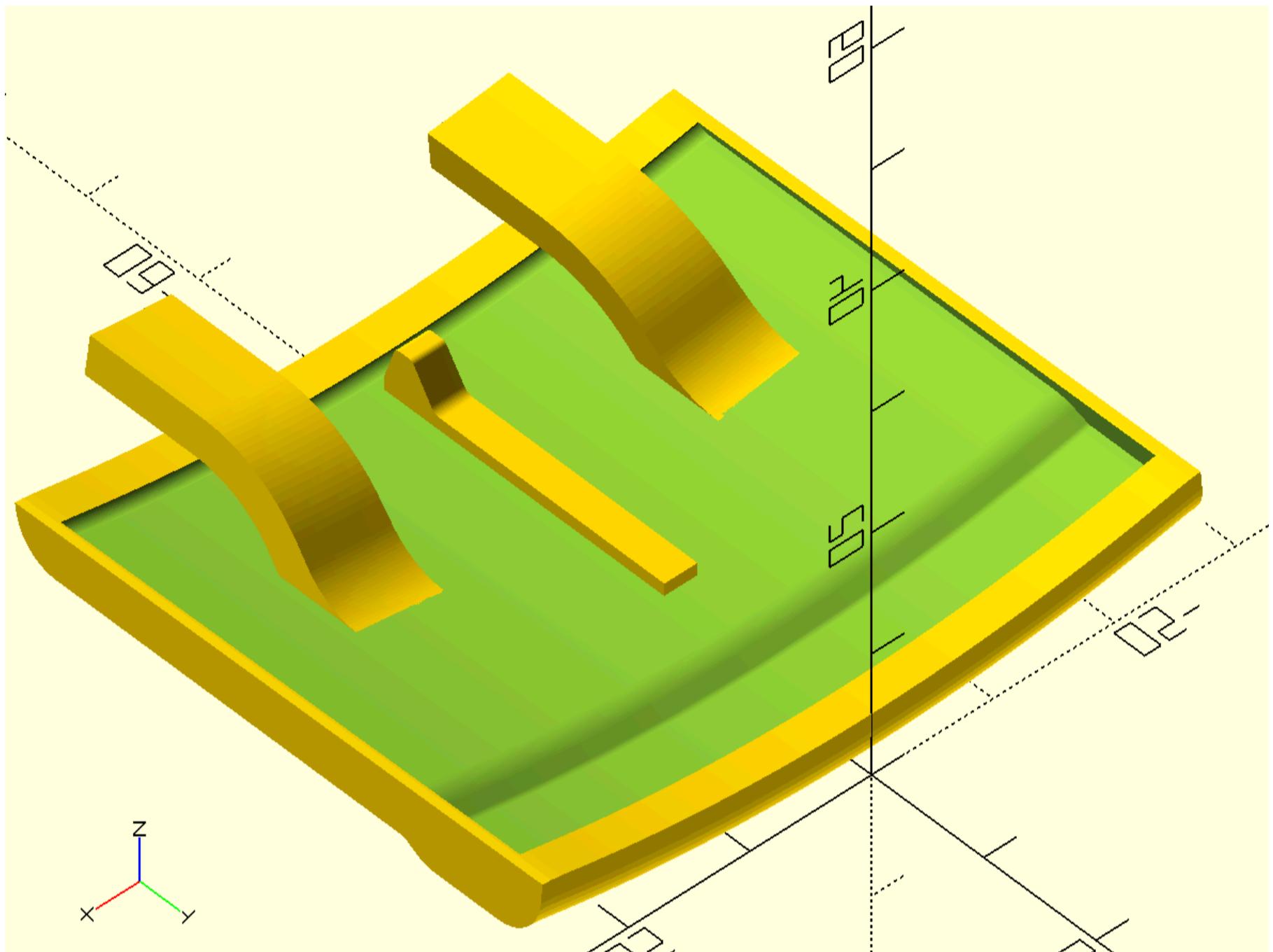
{swp(sol2)}

{swp(sol4)}
{swp(sol5)}

}

difference(){
translate([0,0,28])
rotate([0,-90,0])
chimney_support();
//{swp(cut_plane([0,0,1],60,50,12,0,22))}
}
//support for 3d printing the part
'''
```

```
//translate([-15,-55,0])
//cube([25,60,2]);
//translate([0,0,27])
//rotate([0,-90,0]){
///{swp(sol3)}
//{swp(sol6)}
//}}
'''
```

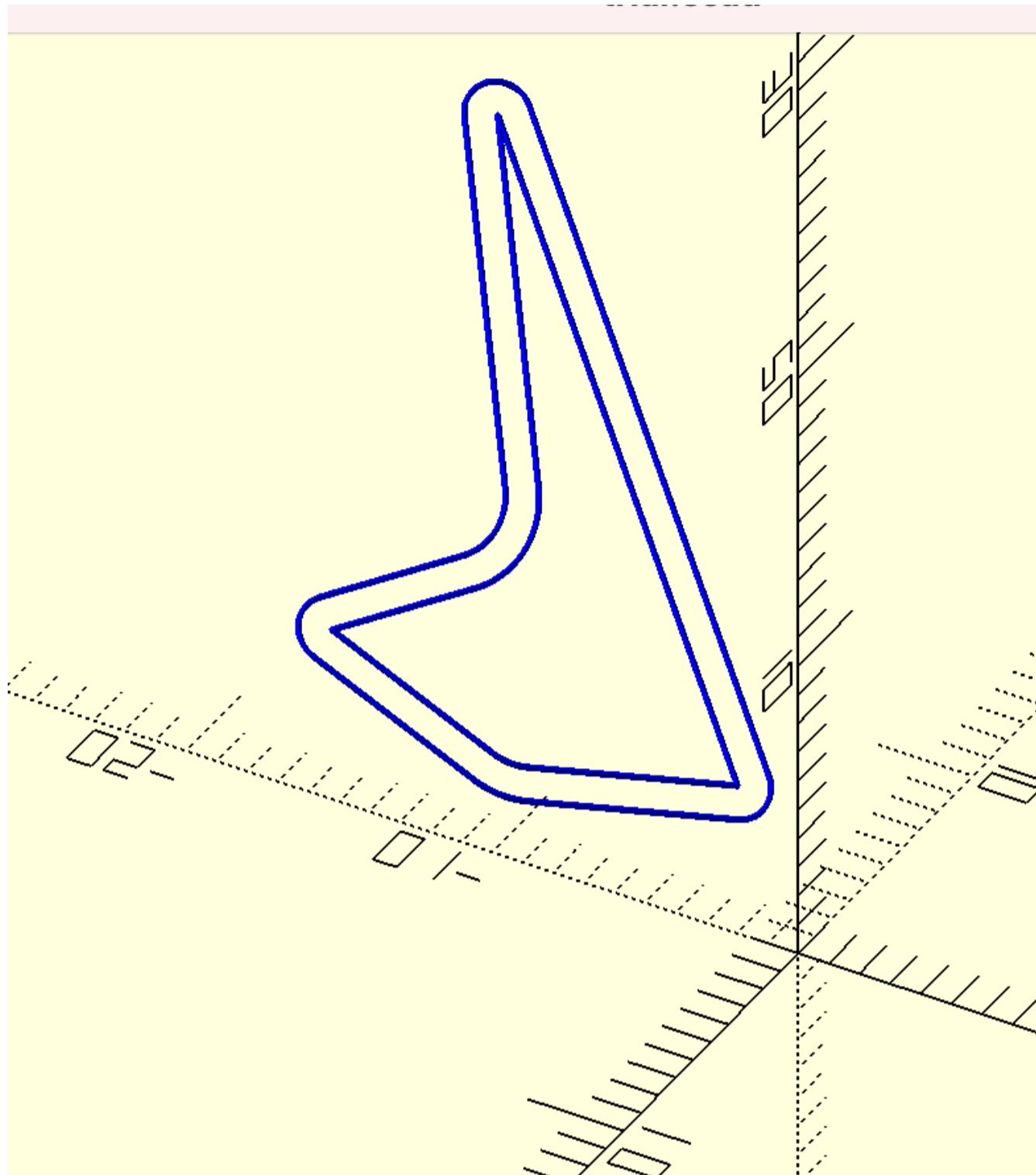


offset_3d

```
In [3]: # example of offset_3d(sec,d)
sec=corner_radius(pts1([[3,2,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),30)
sec1=o_solid([2,3,5],sec,1,10)[0]
sec2=offset_3d(sec1,-1)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("blue")p_line3dc({sec1},.1);
color("magenta")p_line3dc({sec2},.1);
'''')
```



convert_3lines2fillet

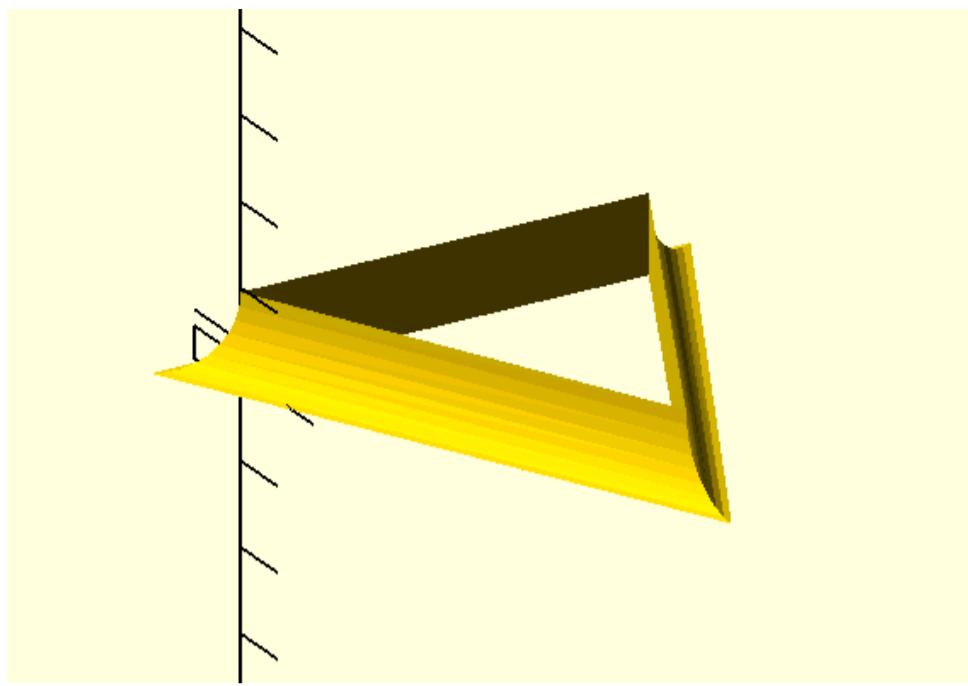
```
In [4]: # example of convert_3lines2fillet(pnt1,pnt2,pnt3,f=1.9,s=10)
t0=time.time()

sec=[[0,0],[5,0],[2.5,5]]
sol=o_solid([0,0,1],sec,1,10)
line1=sol[0]
line2=sol[1]
line3=offset_3d(line1,1)
fillet1=convert_3lines2fillet(line3,line2,line1)
fillet1=fillet1+[fillet1[0]]
# fillet1=flip(cpo(fillet1)[1:])
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("blue")p_line3dc({line1},.05);
color("cyan")p_line3dc({line2},.05);
color("magenta")p_line3dc({line3},.05);
{swp_c(fillet1)}

''')
t1=time.time()
t1-t0
```

Out [4]: 0.013554096221923828



sunflower

```
In [4]: # example of offset_3d when the section is not in 1 plane
# example of path_extrude2msec(sec_list, path)
t0=time.time()

t=1.1 # thickness
s=10 # number of sides of the star
d=20 # outer diameter of the star
h=50 # height of the star prism
cir1=circle(d,s=(s+1))
cir2=c3t2(q_rot([f"z{360/(s+1)/2}"],circle(d/4,s=(s+1))))
sec1=array(c2t3([cir1,cir2]))
sec1=sec1.transpose(1,0,2).reshape(-1,3)
sec1=sec1
sec1=[(sec1[i]+[0,0,1]).tolist() if i%2==0 else (sec1[i]+[0,0,t]).tolist() for i in range(len(sec1)) ]
sec1=m_points(corner_radius(sec1,20),1.1)
sol1=linear_extrude(sec1,h)

line1=corner_radius(pts1([-20,0],[20,15,30],[20,-15]),40)
line2=cytz(line1)
surf1=surf_extrude(line1,line2)

ip1=ip_surf(surf1,sol1)
ip2=offset_3d(ip1,-2.01)

surf4=[ip2,ip1,translate([0,0,-t],ip1),translate([0,0,-t],ip2),ip2]
avg2=array(surf4).mean(0).mean(0)

sec3=circle(5)
path3=m_points_o(corner_radius(pts1([-4,0],[0,15,2],[3.5,4,2],[0,1])),5),.5

sol3=f_prism(sec3,path3)

path4=q_rot(['z90','x90'],cytz([[i,3*sin(d2r(i*20))] for i in linspace(0,20,44)]))
sol4=sol2path(sol3,path4)
v1=array(nv(sol4[-1]))
avg1=array(sol4[-1]).mean(0)
surf4=translate([-avg2+[0,0,-.5],surf4)
surf4=sol2vector(v1,surf4,avg1)

arc1=arc_2p([0.01,0],[4.65,0],3,-1)
arc2=[q_rot([f'z{i}'],arc1) for i in arange(0,360,360/50)]
arc2p=translate([0,0,5],arc2)
arc2=array([arc2,arc2p]).transpose(1,0,2,3)

arc3=arc_2p([0.01,0],[4.65,0],3,1)
arc4=[q_rot([f'z{i}'],arc3) for i in arange(0,360,360/50)]
arc4p=translate([0,0,5],arc4)
arc4=array([arc4,arc4p]).transpose(1,0,2,3)

arc5=circle(4.5)
path5=arc_2p([0,0],[-4.5,2],10,-1)
sol5=f_prism(arc5,path5)

ip1=[ip_sol2sol(sol5,p,-1) for p in arc2]
ip2=[ip_sol2sol(sol5,p,-1) for p in arc4]

ip1=sol2vector(v1,ip1,avg1)
ip2=sol2vector(v1,ip2,avg1)
sol5=sol2vector(v1,sol5,avg1)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

{swp_c(flip(surf4))}
{swp(sol4)}
//color("blue")p_line3dc({sol4[-1]},.2);
//color("magenta")p_line3d({path4},.2);

difference(){{
```

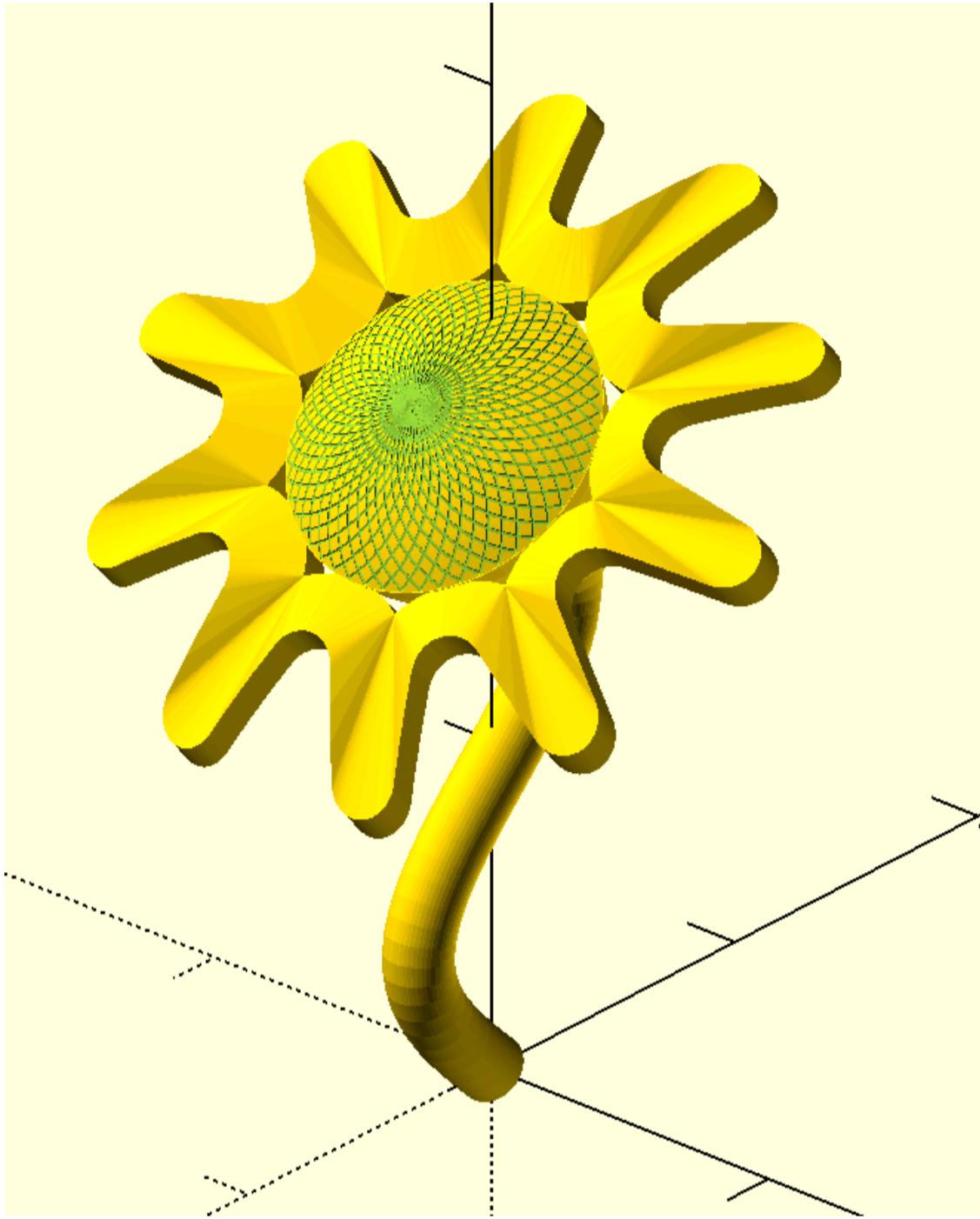
```

{swp(flip(sol5))}
for(p={ip1})p_line3d(p,.05,rec=1);
for(p={ip2})p_line3d(p,.05,rec=1);
}

'''')
t1=time.time()
t1-t0

```

Out[4]: 4.457535028457642



sol2vector

```

In [42]: # checking orientation of solid w.r.t. vector
t0=time.time()

sol=linear_extrude(circle(5),6)
v1=[2,3,4]
loc=[5,10,7.5]
sol1=sol2vector(v1,sol,loc)

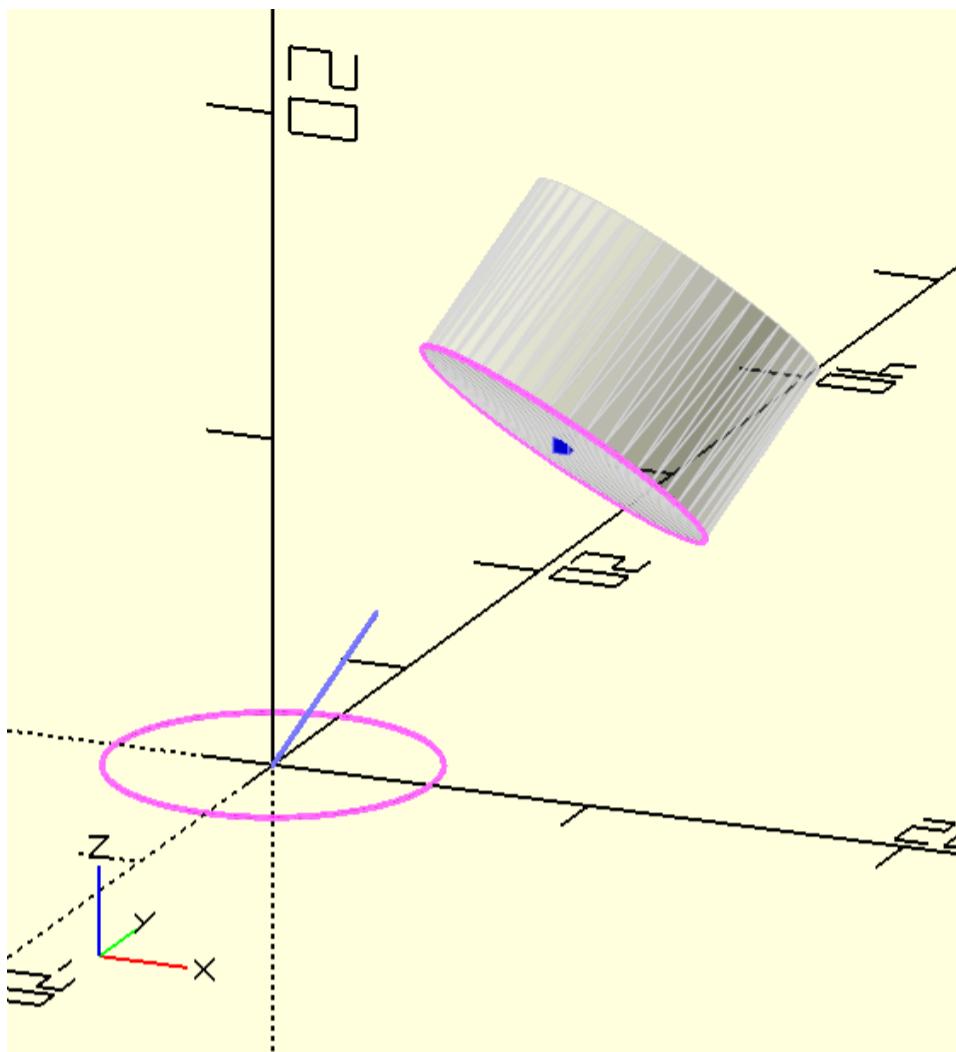
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
%{swp(sol1)}
color("blue")points({{loc}},.5);
color("magenta")p_line3dc({{sol[0]}},.1);
color("magenta")p_line3dc({{sol1[0]}},.1);
color("blue")p_line3d({{[0,0,0],v1}},.1);

'''')

t1=time.time()
t1-t0

```

Out[42]: 0.005764007568359375



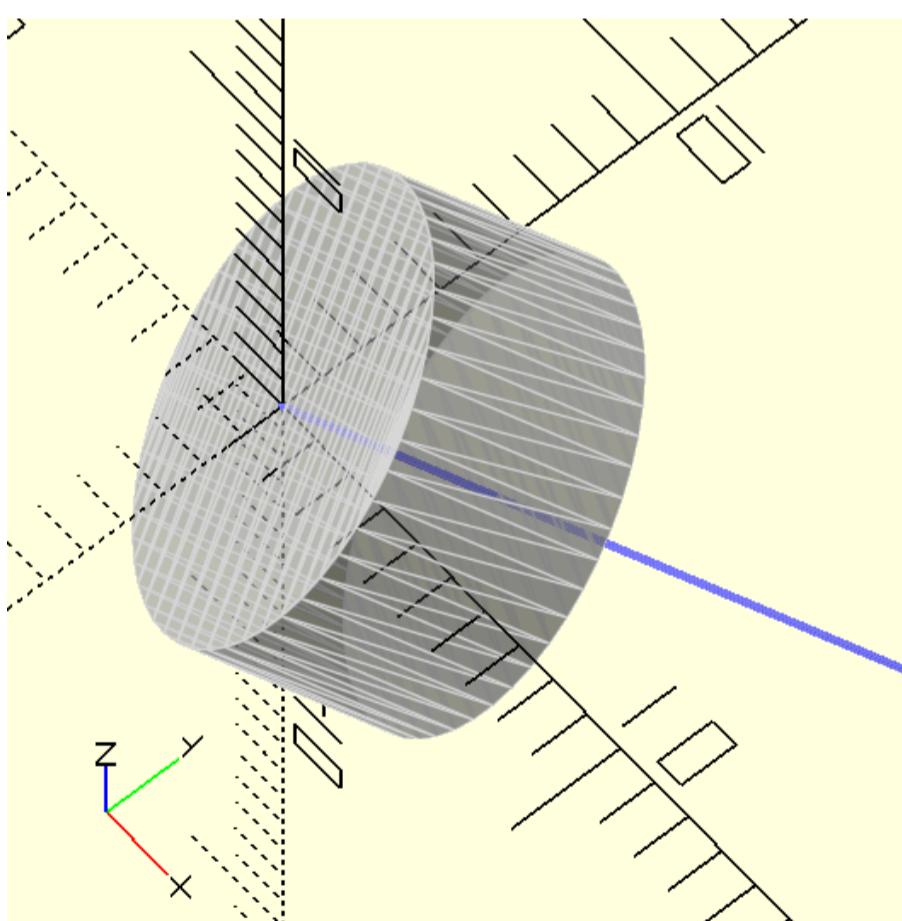
```
In [145]: # checking orientation of solid w.r.t. vector
t0=time.time()

sec=circle(5)
v1=(array([1,1,-1])*10).tolist()
sol=o_solid(v1,sec,5,0,0,0)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
%{swp(sol)}
color("blue")p_line3d({[[0,0,0],v1]},.1);

''')
t1=time.time()
t1-t0
```

Out[145]: 0.008459091186523438



```
In [4]: # difficult fillet
t0=time.time()

sec1=circle(10,s=6)
pent1=circle(7,s=6)
pent2=c3t2(q_rot([f'z{360/5/2}'],circle(3.5,s=6)))
sec2=concatenate(cpo([pent1]+[pent2])).tolist()

sec3=offset(sec2,-1.5)
sec4=offset(sec3,1)
path1=helix(20,30,1,5)
```

```

path2=[[0,0,10],[-30,20,13]]
sol=path_extrude_open(sec2,path1)
sol1=path_extrude_open(m_points1(sec3,50),path2)
sol2=path_extrude_open(m_points1(offset(sec3,.3),50),path2)
v1=array(path2[1])-array(path2[0])
u1=v1/norm(v1)
ip1=[ip_sol2line(sol,p)[-1] for p in cpo(sol1)]
ip2=translate(u1,ip1)
ip3=[ip_sol2line(sol,p)[-1] for p in cpo(sol2)]
fillet1=convert_3lines2fillet(ip3,ip2,ip1)
fillet1=fillet1+[fillet1[0]]
with open('trial.scad','w+') as f:
    f.write(f'''')
include<dependencies2.scad>

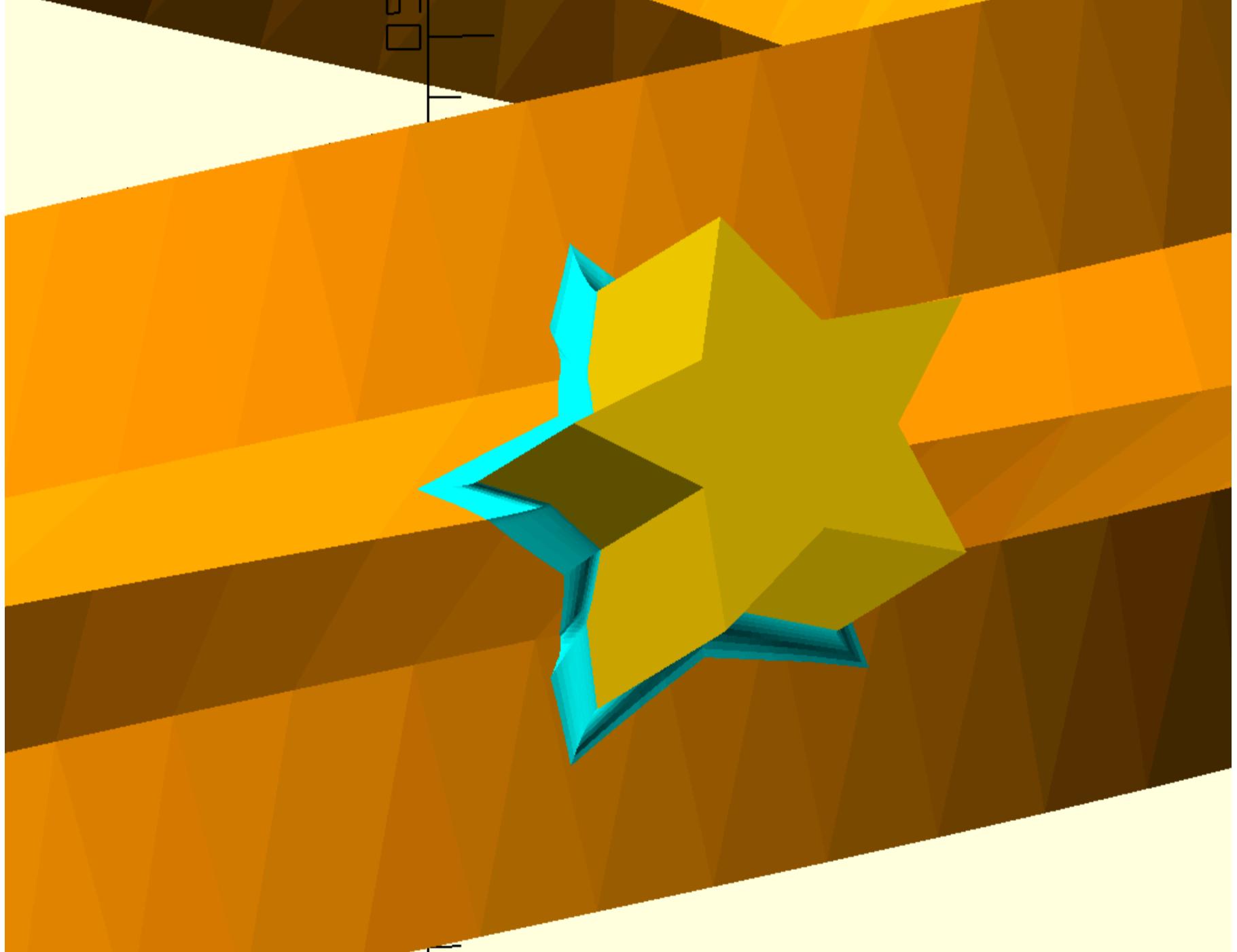
color("orange"){swp(sol)}
%{swp(sol1)}

//color("blue")p_line3dc({ip1},.05);
//color("blue")p_line3dc({ip2},.05);
//color("blue")p_line3dc({ip3},.05);
color("cyan"){swp(fillet1)}

''')
t1=time.time()
t1-t0

```

Out [4]: 5.0616841316223145



ip_sol2sol

```

In [36]: # example of function ip_sol2line(sol,line)
t0=time.time()

sec=circle(10)
path=corner_radius(pts1([[-10+.1,0],[12,0],[-2,0,2],[0,10,3],[-10,0]]),5)
sol=prism(sec,path)

sol1=o_solid([1,0,1],circle(3),20,-5)

ip1=ip_sol2sol(sol,sol1,-1)
ip2=ip_sol2sol(sol,sol1,0)

with open('trial.scad','w+') as f:
    f.write(f'''')
include<dependencies2.scad>

%{swp(sol)}

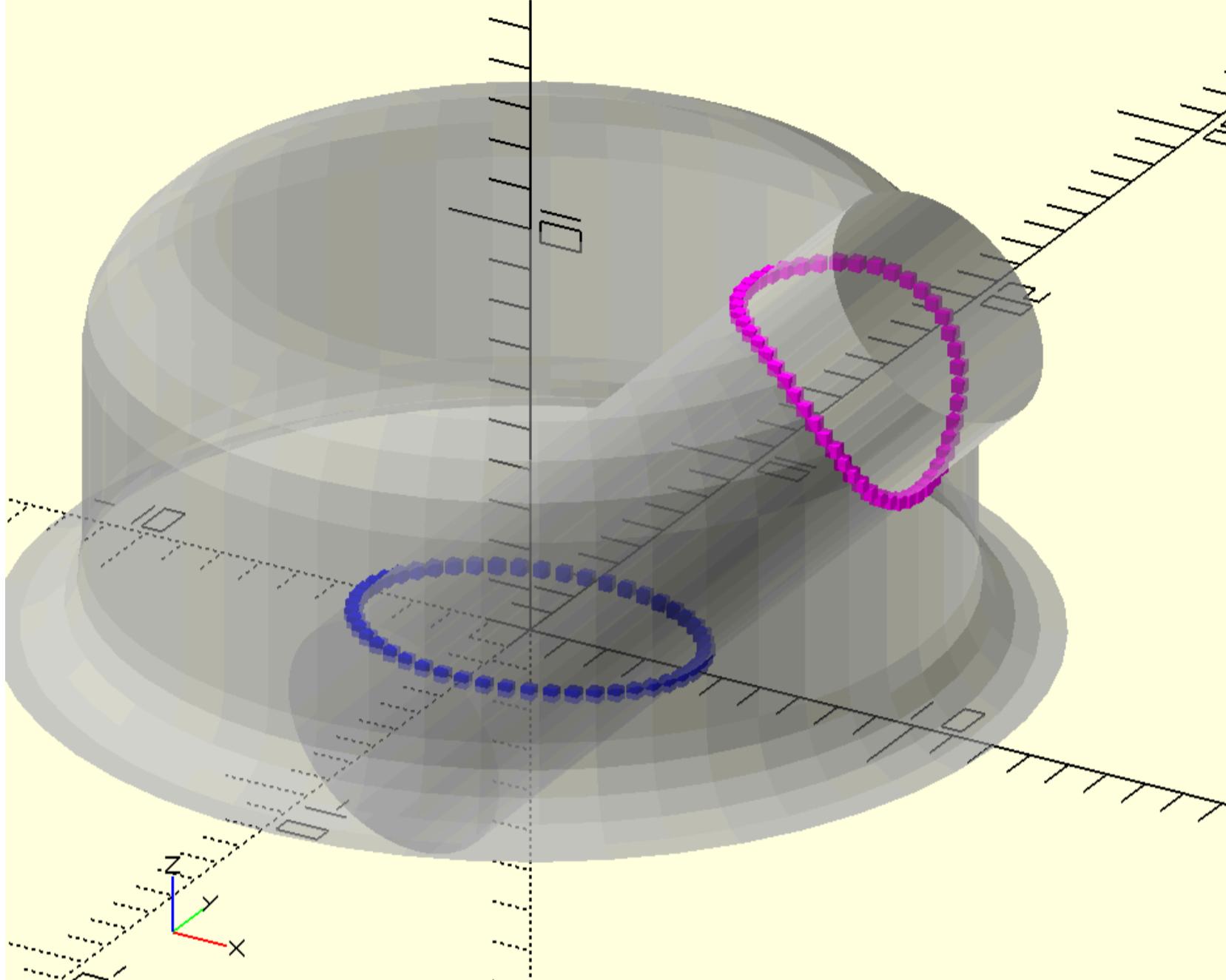
```

```
%{swp(sol1)}

color("magenta")points({ip1},.3);
color("blue")points({ip2},.3);

'''')
t1=time.time()
t1-t0
```

Out[36]: 0.0560760498046875



ip_sol2line

```
# example of function ip_sol2line(sol,line)
t0=time.time()

sec=circle(10)
path=corner_radius(pts1([[-10+.1,0],[12,0],[-2,0,2],[0,10,3],[-10,0]]),5)
sol=prism(sec,path)

line=ls([[0,0,-1],[20,20,10]],10)

ip1=ip_sol2line(sol,line)[-1]
ip2=ip_sol2line(sol,line)[0]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

%{swp(sol)}

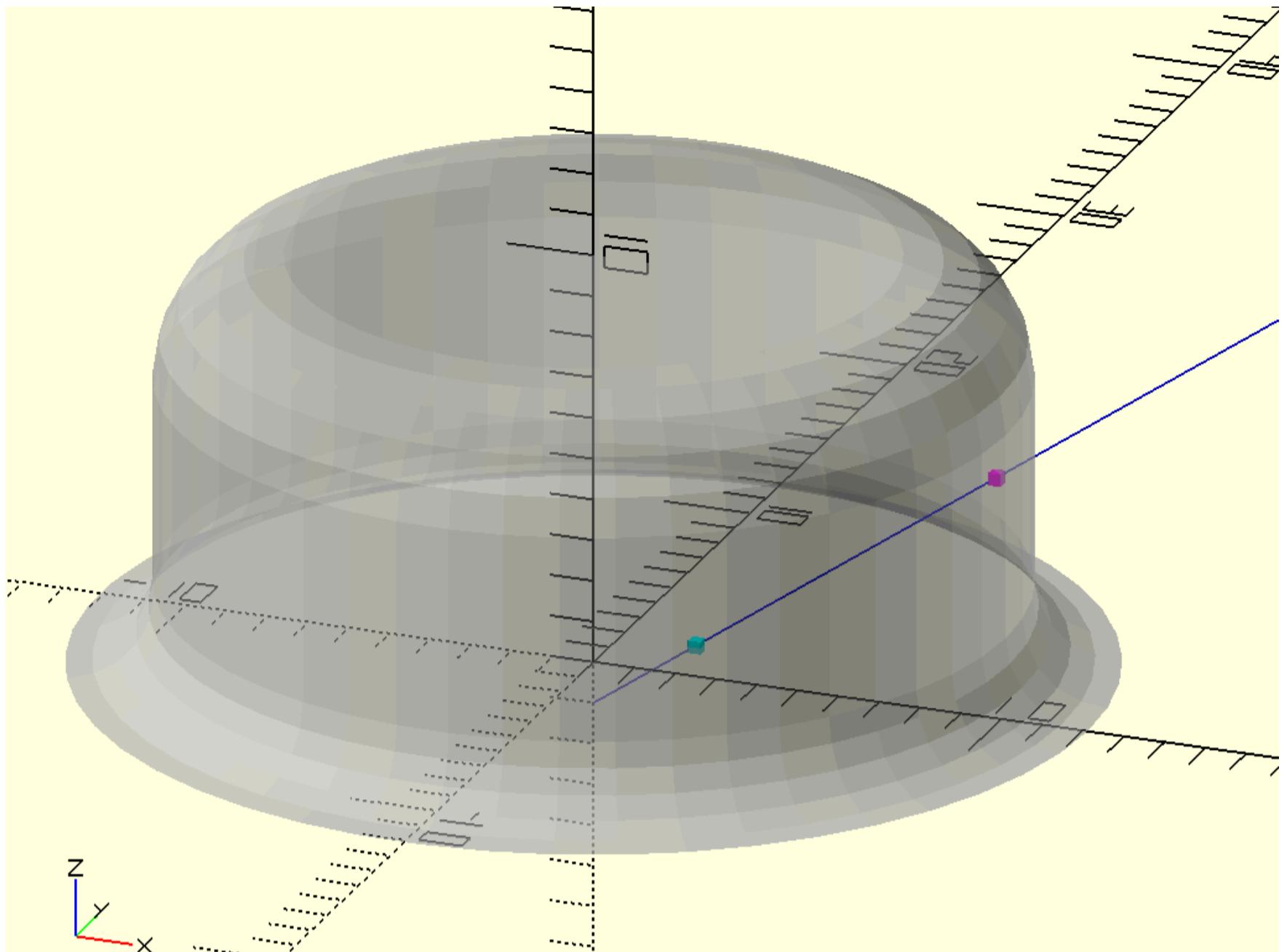
color("blue")p_line3dc({line},.05);

color("magenta")points({[ip1]},.3);
color("cyan")points({[ip2]},.3);

'''')
t1=time.time()
t1-t0

ip1
```

Out[148... [7.1354892496692255, 7.1354892496692255, 2.924519087318074]



```
In [5]: t0=time.time()

c1=l_cir_ip([[0,0],[0,5]],circle(2,[1,2.5]))
sec1=arc_long_2p(c1[0],c1[1],2,-1,50)
sol1=o_solid([0,0,1],sec1,5)

c1=l_cir_ip([[0,0],[0,5]],circle(2.3,[1,2.5]))
sec1=arc_long_2p(c1[0],c1[1],2.3,-1,50)
sol2=o_solid([0,0,1],sec1,5)

c1=l_cir_ip([[-0.3,0],[-0.3,5]],circle(2,[1,2.5]))
sec1=arc_long_2p(c1[0],c1[1],2,-1,50)
sol3=o_solid([0,0,1],sec1,5.6,-.3)
lines=array([sol1,sol3,sol2]).transpose(1,0,2,3)[1]
a,b,c=array([lines[0],lines[1],lines[2]]).tolist()
lines1=array([sol1,sol3,sol2]).transpose(1,0,2,3)[0]
h,i,j=array([lines1[0],lines1[1],lines1[2]]).tolist()
k,l,m=a+flip(h),b+flip(i),c+flip(j)

fillet1=convert_3lines2fillet(m,l,k)
fillet1=translate([0,5,0],q_rot(['z90']),fillet1+[fillet1[0]]))

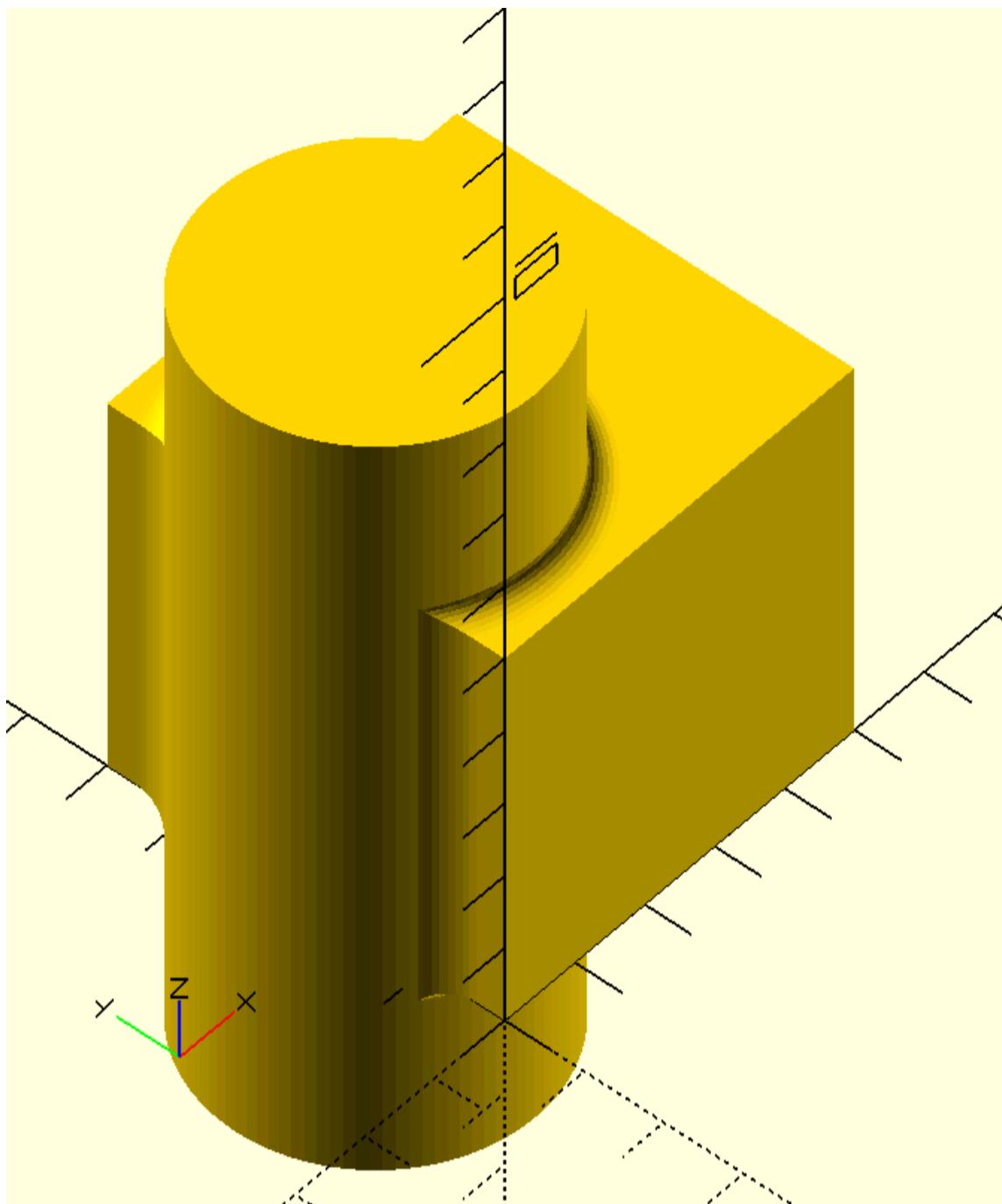
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

%cube(5);
%translate([1,2.5,-2.5])cylinder(r=2,h=10,$fn=100);

{swp(fillet1)}
translate([0,5,0])
rotate([0,0,90]){
color("magenta")p_line3dc({k},.02);
color("magenta")p_line3dc({l},.02);
color("magenta")p_line3dc({m},.02);
}
''')

t1=time.time()
t1-t0
```

Out [5]: 0.16157293319702148



```
In [5]: t0=time.time()
sec1=circle(10,s=6)
pent1=circle(7,s=6)
pent2=c3t2(q_rot([f'z{360/5/2}'],circle(3.5,s=6)))
sec2=concatenate(cpo([pent1]+[pent2])).tolist()
sec2=corner_radius(array(c2t3(sec2))+[0,0,.5],15)
sec3=concatenate(cpo([pent1]+[pent2])).tolist()
sec3=offset(sec3,-1)
sec3=corner_radius(array(c2t3(sec3))+[0,0,.2],10)
path1=helix(20,30,1,5)
path2=[[0,0,10],[-30,20,13]]
sol=path_extrude_open(sec2,path1)
sol1=path_extrude_open(equidistant_pathc(sec3,300),path2)

sol2=sol[22:33]
sol3=slice_sol(sol1,20)
sol4=path_extrude_open(equidistant_pathc(offset(sec3,1),300),path2)
sol4=slice_sol(sol4,20)

i_p1=ip_sol2sol(sol2,sol3[12:17],0)
i_p2=i_p_p(sol3,i_p1,1)
i_p3=ip_sol2sol(sol2,sol4[12:17],0)

i_p1,i_p2,i_p3=align_sol_1([i_p1,i_p2,i_p3])

fillet1=convert_3lines2fillet_closed(i_p3,i_p2,i_p1)
# fillet1=fillet_sol(sol2,sol3[12:16],1,s=20)

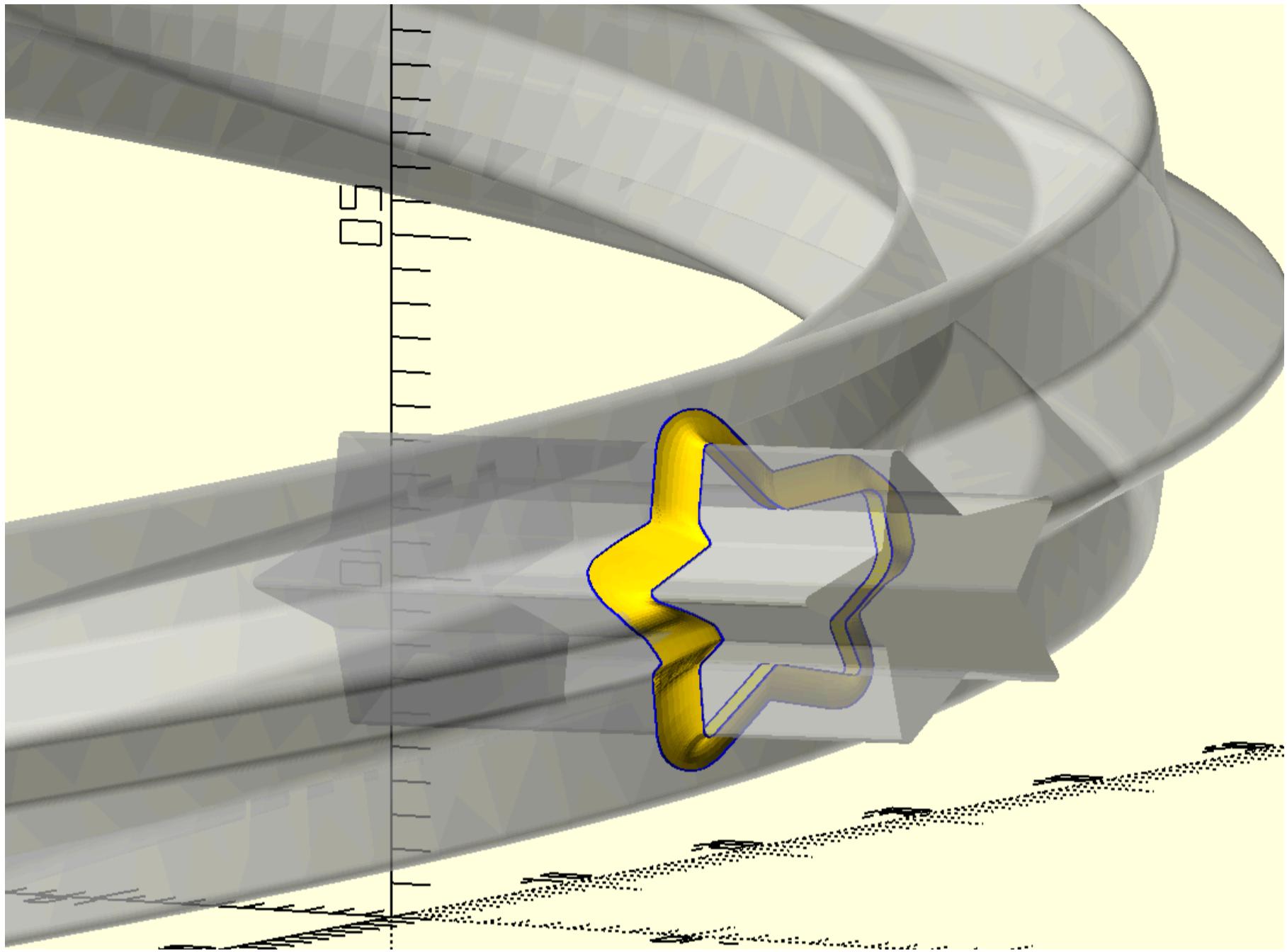
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
//color("blue")for(p={sol3[12:16]})points(p,.1);

{swp(sol)}
{swp(sol3)}
//color("blue")for(p={sol4[12:16]})p_line3dc(p,.1,rec=1);
color("blue")p_line3dc({i_p1},.05,rec=1);
color("blue")p_line3dc({i_p2},.05,rec=1);
color("blue")p_line3dc({i_p3},.05,rec=1);

{swp_c(fillet1)}

'''')
t1=time.time()
t1-t0
```

Out [5]: 2.1139259338378906



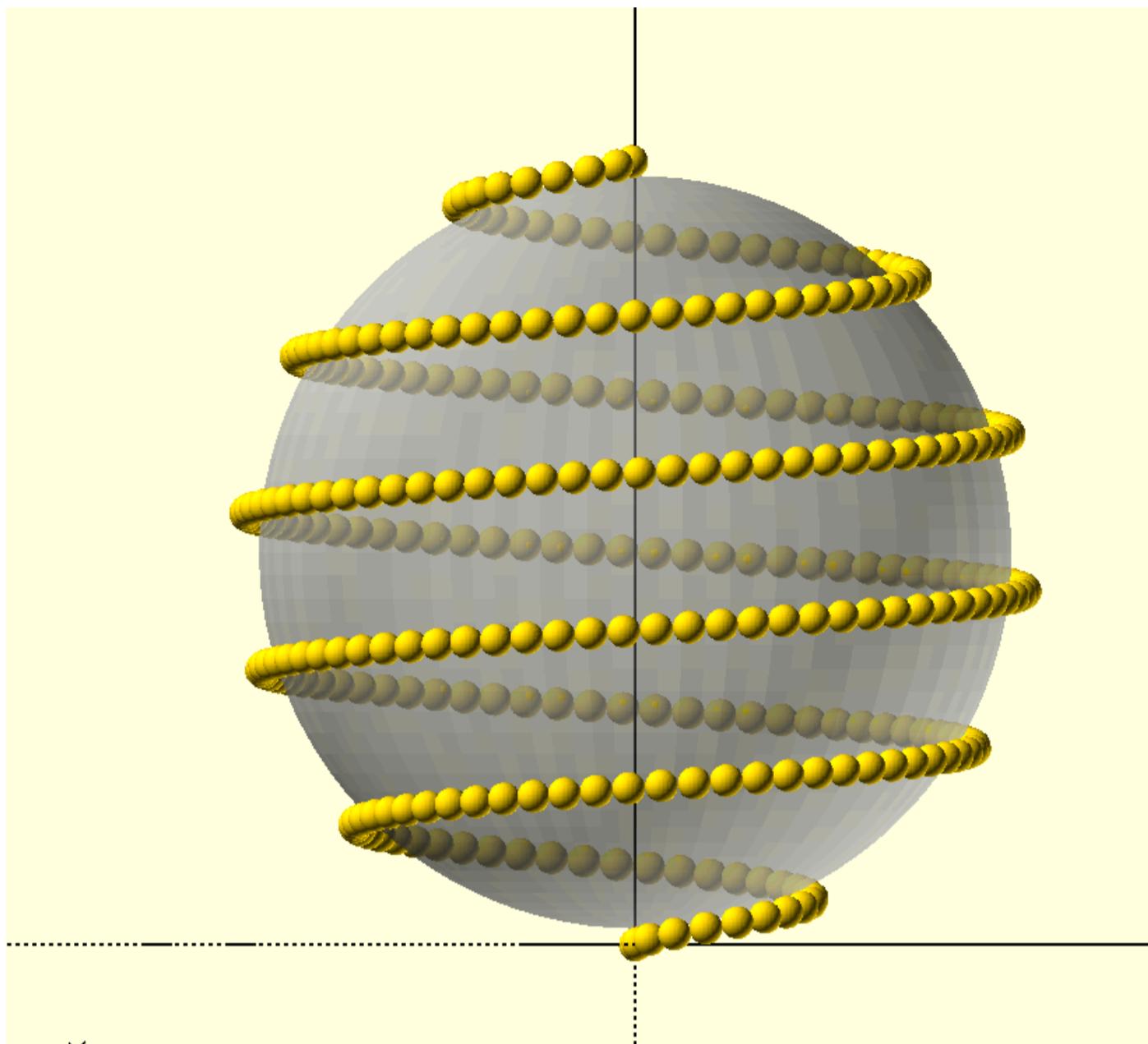
equidistant_path

```
In [7]: t0=time.time()
path=helix(15,20/10,10,5)
# path1=[[0,0,p[2]] for p in path]
path1=helix(0,20/10,10,5)
sec=circle(10)
path2=arc(10,-90,90,[-10+.1,10],50)
sp1=prism(sec,path2)
sol1=[path1,path]
i_p1=ip_sol2sol(sp1,sol1,0)
i_p1=equidistant_path(i_p1,500)
d=l_len([i_p1[0],i_p1[1]])
sp2=translate([0,0,10],sphere(10-d/2))
sp3=sphere(d/2)

with open('trial.scad','w+') as f:
    f.write(f'''
    include<dependencies2.scad>
    %{swp(sp2)}
    color("blue")p_line3d({i_p1},.05);
    for(p={i_p1})translate(p){swp(sp3)}

    ''')
t1=time.time()
t1-t0
```

Out[7]: 0.8852136135101318



iterative-approach-towards-creating-fillets

```
In [54]: # iterative approach towards creating fillets

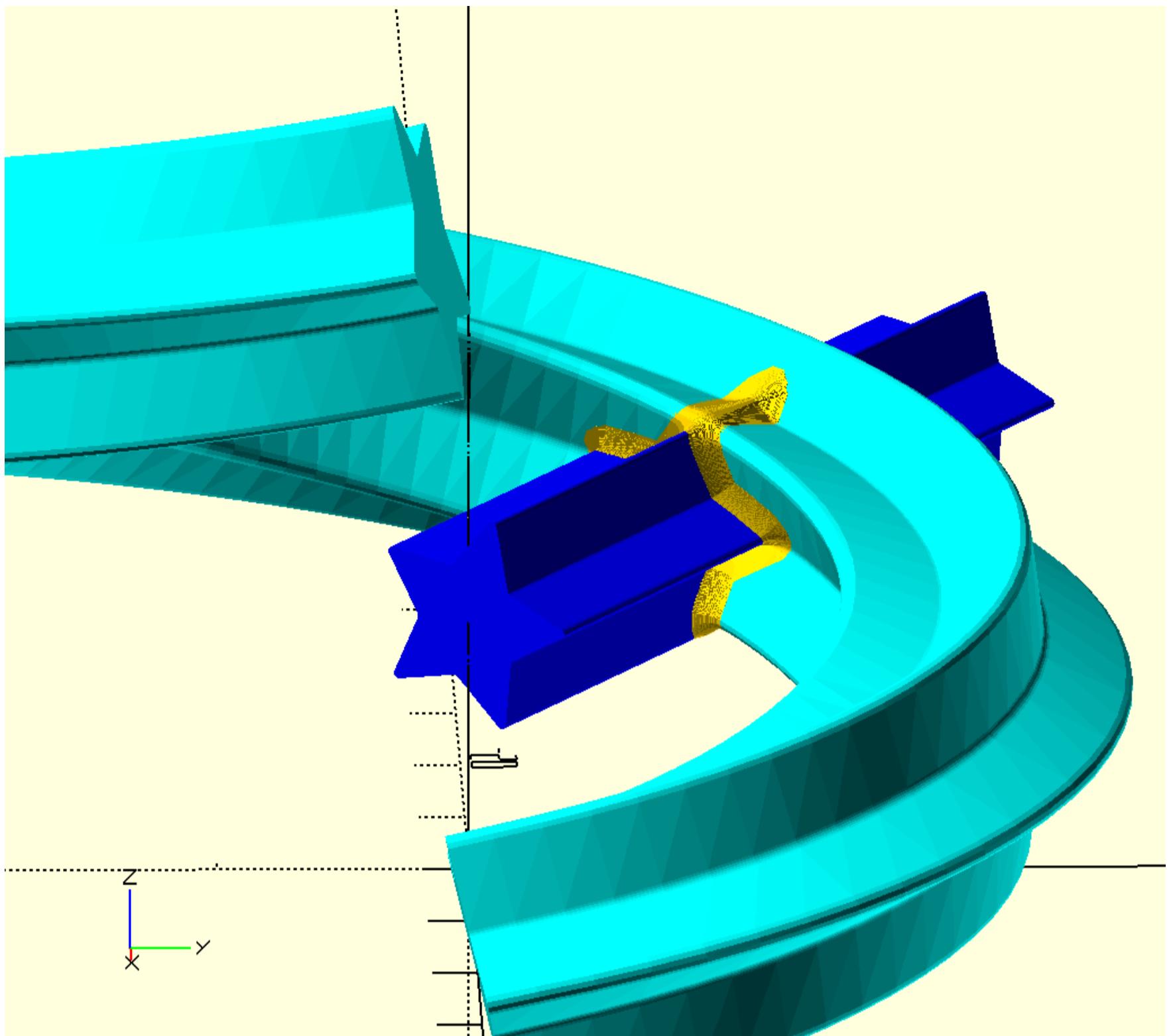
t0=time.time()
sec1=circle(10,s=6)
pent1=circle(7,s=6)
pent2=c3t2(q_rot([f'z{360/5/2}'],circle(3.5,s=6)))
sec2=concatenate(cpo([pent1]+[pent2])).tolist()
sec2=corner_radius(array(c2t3(sec2))+[0,0,.1],5)
sec3=concatenate(cpo([pent1]+[pent2])).tolist()
sec3=offset(sec3,-1)
sec3=corner_radius(array(c2t3(sec3))+[0,0,.1],5)
path1=helix(20,30,1,5)
path2=[[0,0,10],[-30,20,13]]
sol=path_extrude_open(sec2,path1)
sol1=path_extrude_open(sec3,path2)
sol2=sol[25:35]
a=array([[1-cos(d2r(i)),1-sin(d2r(i))] for i in linspace(0,90,90)])*1
b=[offset_sol(sol2,i,1) for i in a[:,0].round(2)]
c=[offset_sol(sol1,i) for i in a[:,1].round(2)]

with open('trial.scad','w+') as f:
    for i in range(len(b)):
        f.write(f'''
            intersection(){{{
                {swp(b[i])}
                {swp(c[i])}
            }}}

        ''')
    f.write(f'''
        include<dependencies2.scad>
        color("cyan")
        {swp(sol)}
        color("blue")
        {swp(sol1)}

    ''')
t1=time.time()
t1-t0
```

Out[54]: 61.24164652824402



```
In [153... # iterative approach for creating fillets, example-2

t0=time.time()
sec=circle(10)
path=corner_radius(pts1([[2,0],[-2,0,2],[-1,15,3],[-8,0]]),10)
sol1=q_rot(['z90'],prism(sec,path))

sec1=corner_radius(pts1([[0,0,1],[5,0,1],[0,7,2],[-5,0,2]]),10)
path1=corner_radius(pts1([[-2,0],[2,0,2],[0,5,.3],[-.5,0]]),10)
sol2=translate([6,0,12],q_rot(['x90','z90'],prism(sec1,path1)))
a=array([[1-cos(d2r(i)),1-sin(d2r(i))] for i in linspace(0,90,20)])*.75
b=[rsz3dc(sol1,array(bb(sol1))+i*2) for i in a[:,0]]
c=[rsz3dc(sol2,array(bb(sol2))+i*2) for i in a[:,1]]

with open('trial.scad','w+') as f:
    for i in range(len(a)-1):
        f.write(f'''')
include<dependencies2.scad>
hull(){{}
intersection(){{
{swp(b[i])}
{swp(c[i])}
}}}

intersection(){{
{swp(b[i+1])}
{swp(c[i+1])}
}}
}

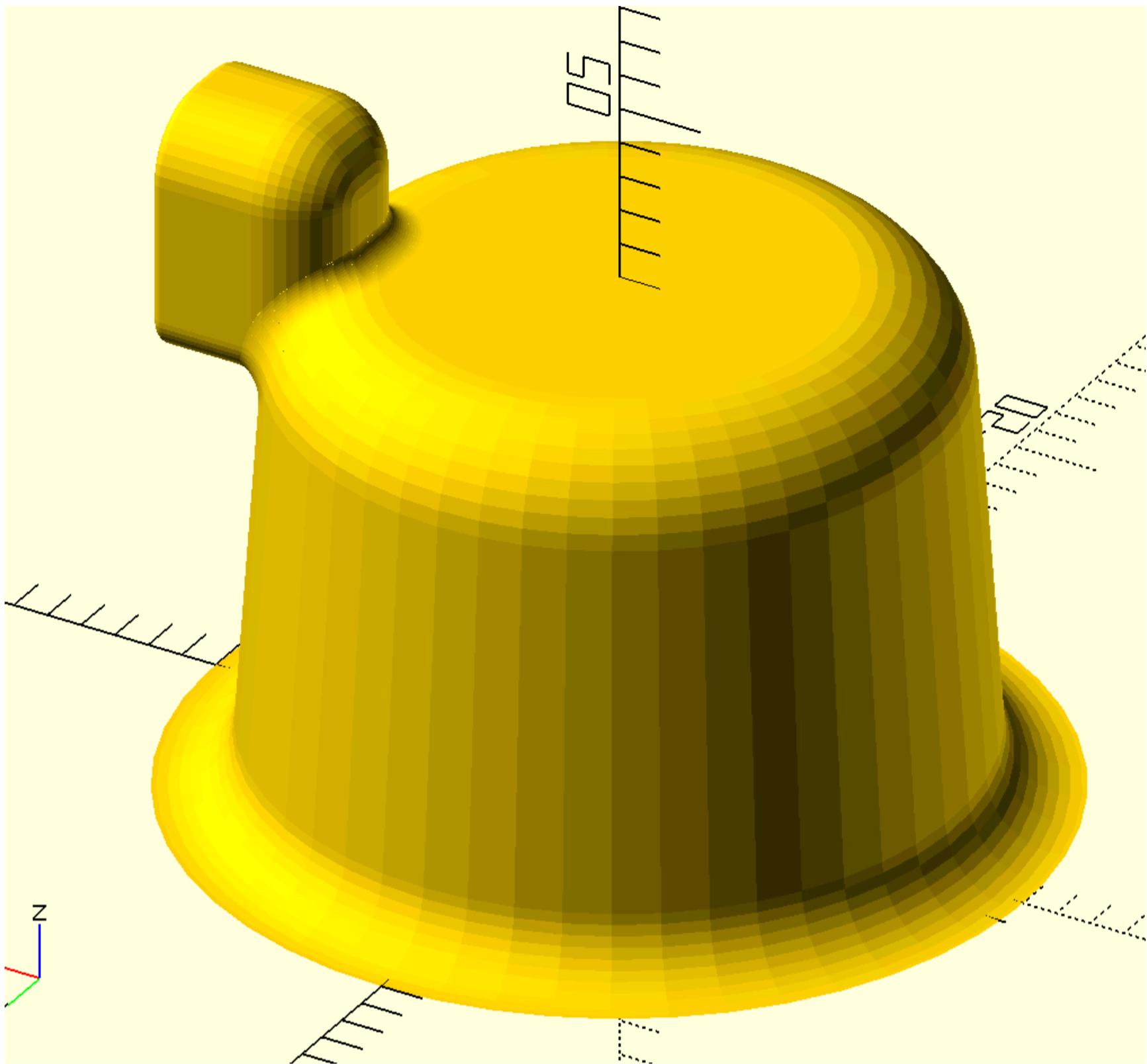
'''')
f.write(f'''

{swp(sol1)}
{swp(sol2)}

'''')

t1=time.time()
t1-t0
```

Out[153... 1.4294283390045166

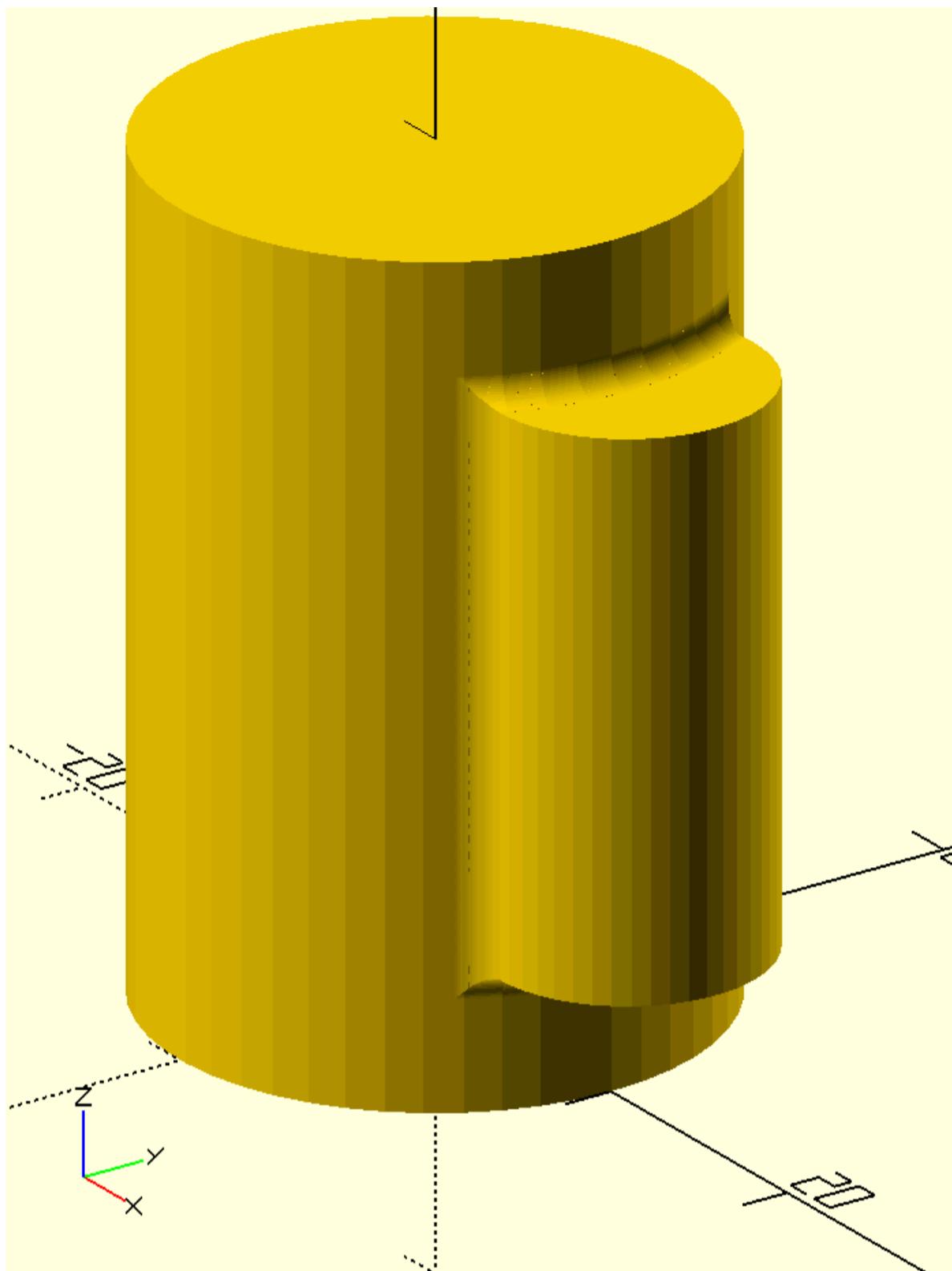


```
In [5]: cyl1=linear_extrude(circle(10,s=200),30)
cyl2=translate([10,0,5],linear_extrude(circle(5,s=100),20))
# cyl2=c2ro(cyl2,1)
a=array([[1-cos(d2r(i)),1-sin(d2r(i))] for i in linspace(0,90,20)])*1
b=[rsz3dc(cyl1,array(bb(cyl1))+i*2) for i in a[:,0]]
c=[rsz3dc(cyl2,array(bb(cyl2))+i*2) for i in a[:,1]]

with open('trial.scad','w+') as f:
    for i in range(len(a)-1):
        f.write(f'''')
include<dependencies2.scad>
hull(){}
intersection(){
{swp(b[i])}
{swp(c[i])}
}

intersection(){
{swp(b[i+1])}
{swp(c[i+1])}
}
}

'''')
    f.write(f'''
{swp(cyl1)}
{swp(cyl2)}
'''')
```



```
In [5]: # iterative approach to filleting example

t0=time.time()

sec=pts([[0,0],[5,0],[0,5],[-5,0]])
path=corner_radius(pts1([[-.4,0],[.4,0],0.2],[0,5,0.2],[-.4,0])),10)
sol=prism(sec,path)

sec1=circle(1.5,s=150)
# sol1=o_solid([0,0,1],sec1,10,-1.5,0,-2.5)
sol1=o_solid([1,0,10],sec1,10,-1.5,-2.5,0)

# sol1=slice_sol(sol1,20)

a=array([[1-cos(d2r(i)),1-sin(d2r(i))] for i in linspace(0,90,20)])*.5
b=[rsz3dc(sol,array(bb(sol))+i*2) for i in a[:,0]]
c=[offset_sol(sol1,i) for i in a[:,1]]

with open('trial.scad','w+') as f:
    for i in range(len(a)-1):
        f.write(f'''')
        hull(){{}
intersection(){{
{swp(b[i])}
{swp(c[i])}
}}}

intersection(){{
{swp(b[i+1])}
{swp(c[i+1])}
}}
}}
})

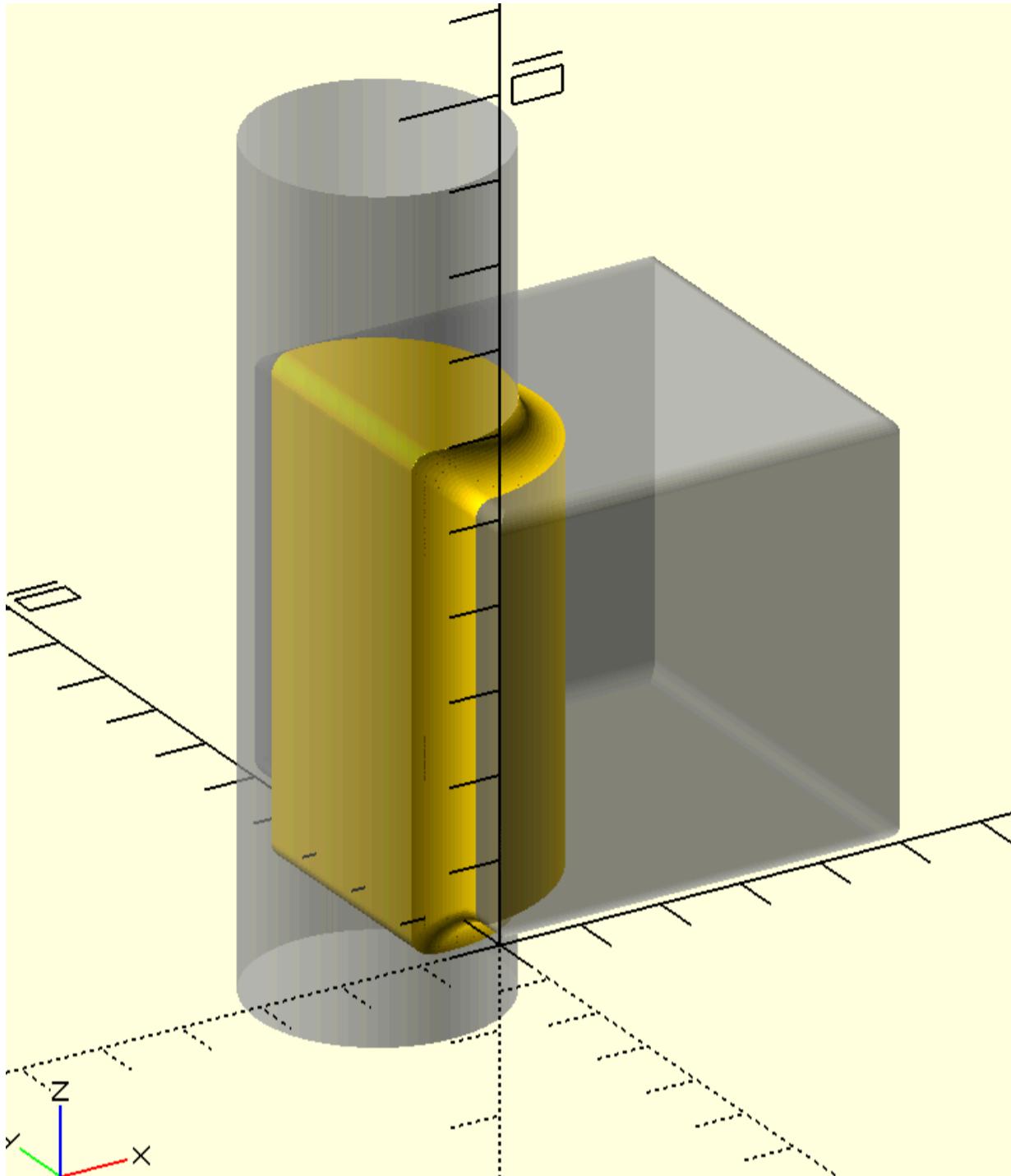
f.write(f'''')
include<dependencies2.scad>

{swp(sol)}
{swp(sol1)}

'''')

t1=time.time()
t1-t0
```

Out[5]: 0.46150994300842285



```
In [155... t0=time.time()

cyl1=o_solid([0,1,0],circle(5),70,-35)
cyl2=o_solid([1,0,0],circle(5),70,-35)

a=array([[1-cos(d2r(i)),1-sin(d2r(i))] for i in linspace(0,90,20)])*1.5
b=[rsz3dc(cyl1,array(bb(cyl1))+i*2) for i in a[:,0]]
c=[rsz3dc(cyl2,array(bb(cyl2))+i*2) for i in a[:,1]]

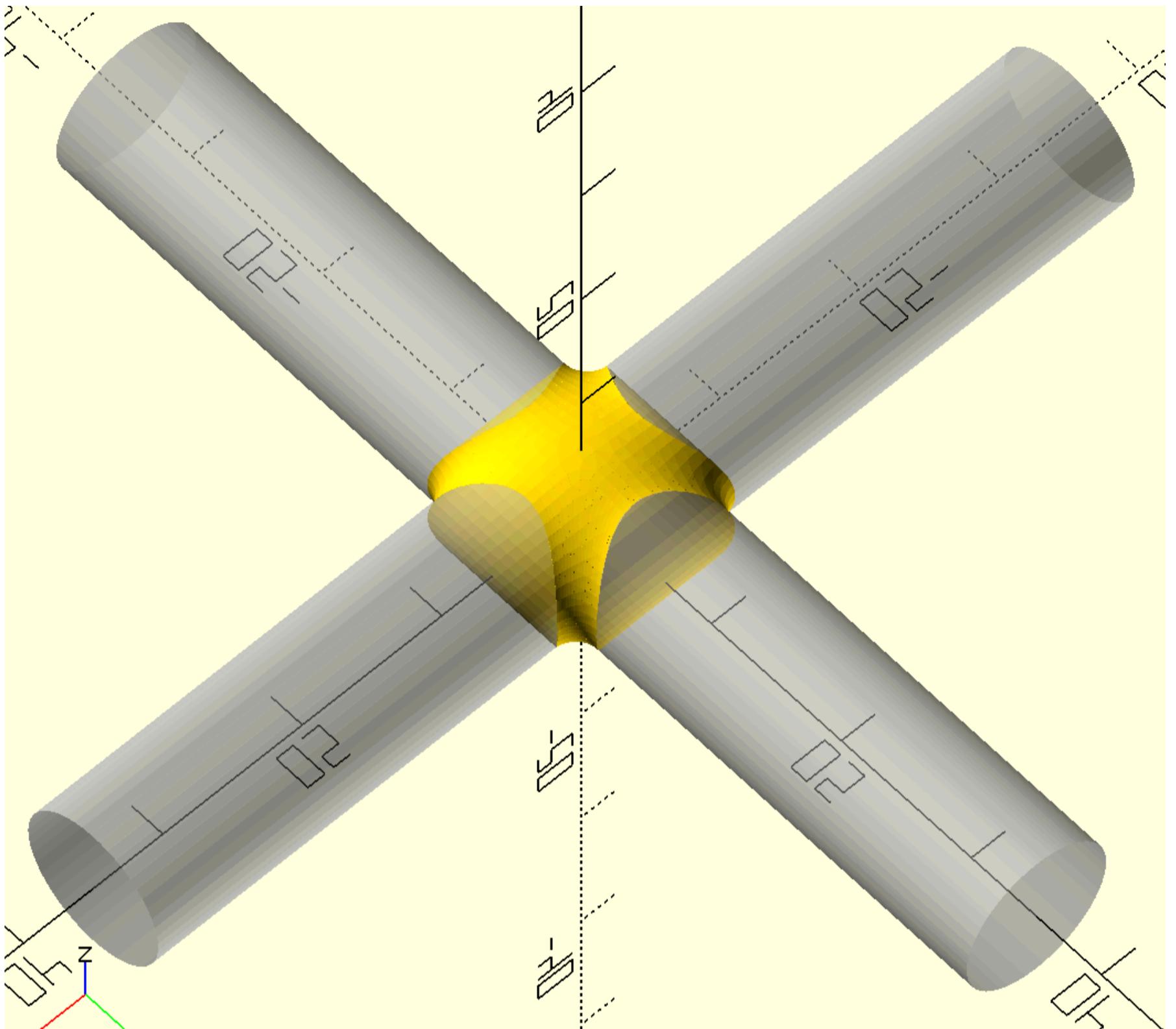
with open('trial.scad','w+') as f:
    for i in range(len(a)-1):
        f.write(f''''
            hull(){{{
                intersection(){{{
                    {swp(b[i])}
                    {swp(c[i])}
                }}}

                intersection(){{{
                    {swp(b[i+1])}
                    {swp(c[i+1])}
                }}}
            }}}
        ''')

    f.write(f'''
        include<dependencies2.scad>
        {swp(cyl1)}
        {swp(cyl2)}
    ''')

t1=time.time()
t1-t0
```

Out[155... 0.054795026779174805



```
In [156]: cyl1=linear_extrude(circle(5),20)
with open('trial.scad','w+') as f:
    f.write(f'''
{swp1(cyl1)}
'''')
```

```
In [157]: triangle=[[0,0],[5,0],[0,5]]
p=[0,3]
tx=triangulate_4p(triangle,p)

p0,p1,p2,p3=triangle+[p]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("blue")points({[p0,p1,p2,p3]},.2);
//p_line({tx},.05);
for(p={tx})p_line(p,.05);
color("magenta")p_line({cir_3p(tx[0][0],tx[0][1],tx[0][2],s=72)},.05);
color("cyan")p_line({cir_3p(tx[1][0],tx[1][1],tx[1][2],s=72)},.05);

''')
tx
```

```
Out[157]: [[[0, 5], [0, 3], [5, 0]], [[5, 0], [0, 3], [0, 0]]]
```

lexicographic_sort_xy

```
In [158]: # example of function lexicographic_sort_xy(p)
t0=time.time()
a=random.random(50)*(20-5)+5
b=random.random(50)*(30-10)+10
p=array([a.round(1),b.round(1)]).transpose(1,0)

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
p2={lexicographic_sort_xy(p)};
```

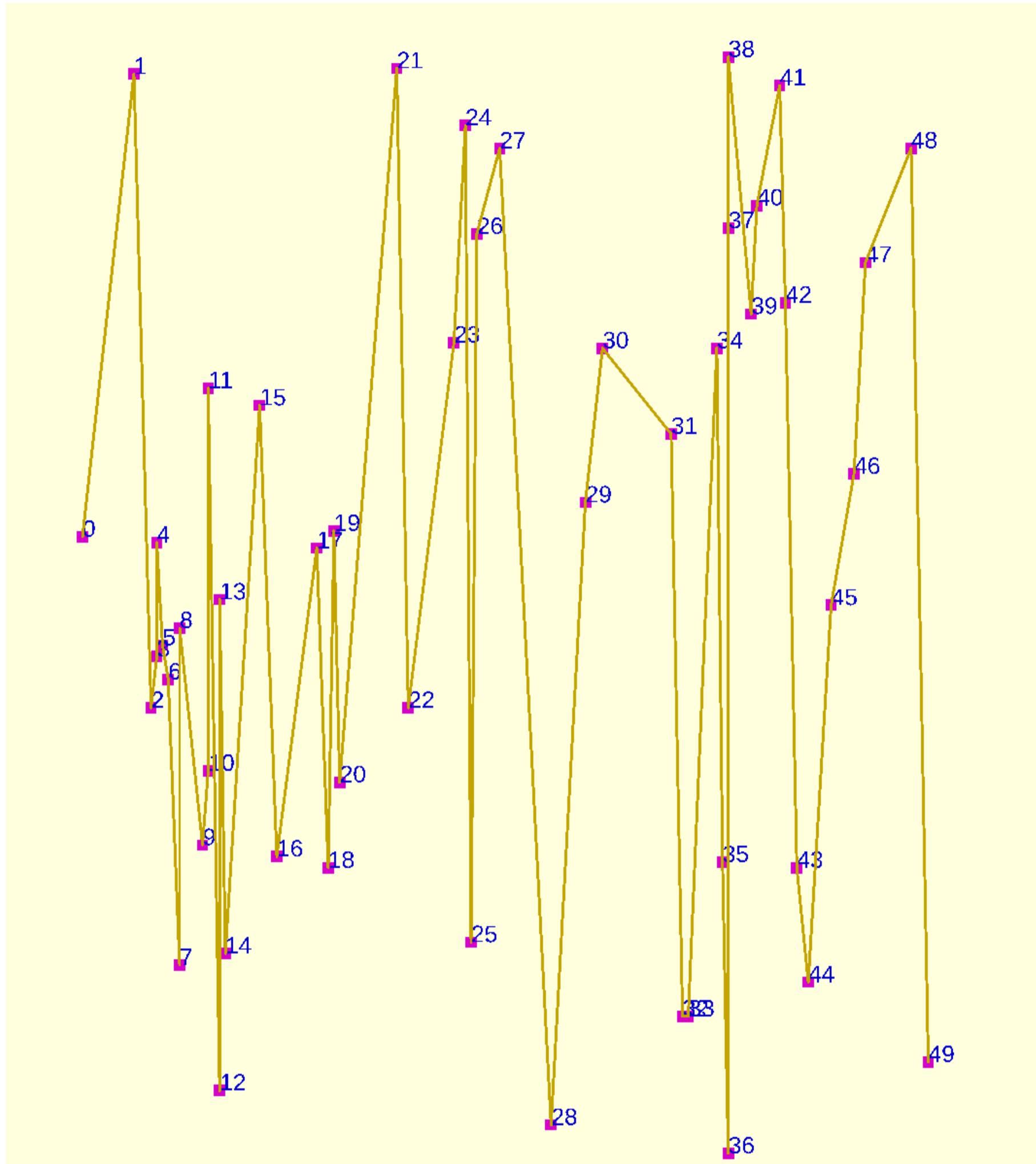
```

color("blue")for(i=0:len(p2)-1)translate(p2[i])text(str(i),.3);
p_lineo(p2,.05);
color("magenta")points(p2,.2);

    ''')
t1=time.time()
t1-t0

```

Out[158... 0.00671696662902832



lexicographic_sort_yx

```

In [159... # example of function lexicographic_sort_yx(p)
t0=time.time()
a=random.random(50)*(20-5)+5
b=random.random(50)*(30-10)+10
p=array([a.round(1),b.round(1)]).transpose(1,0)

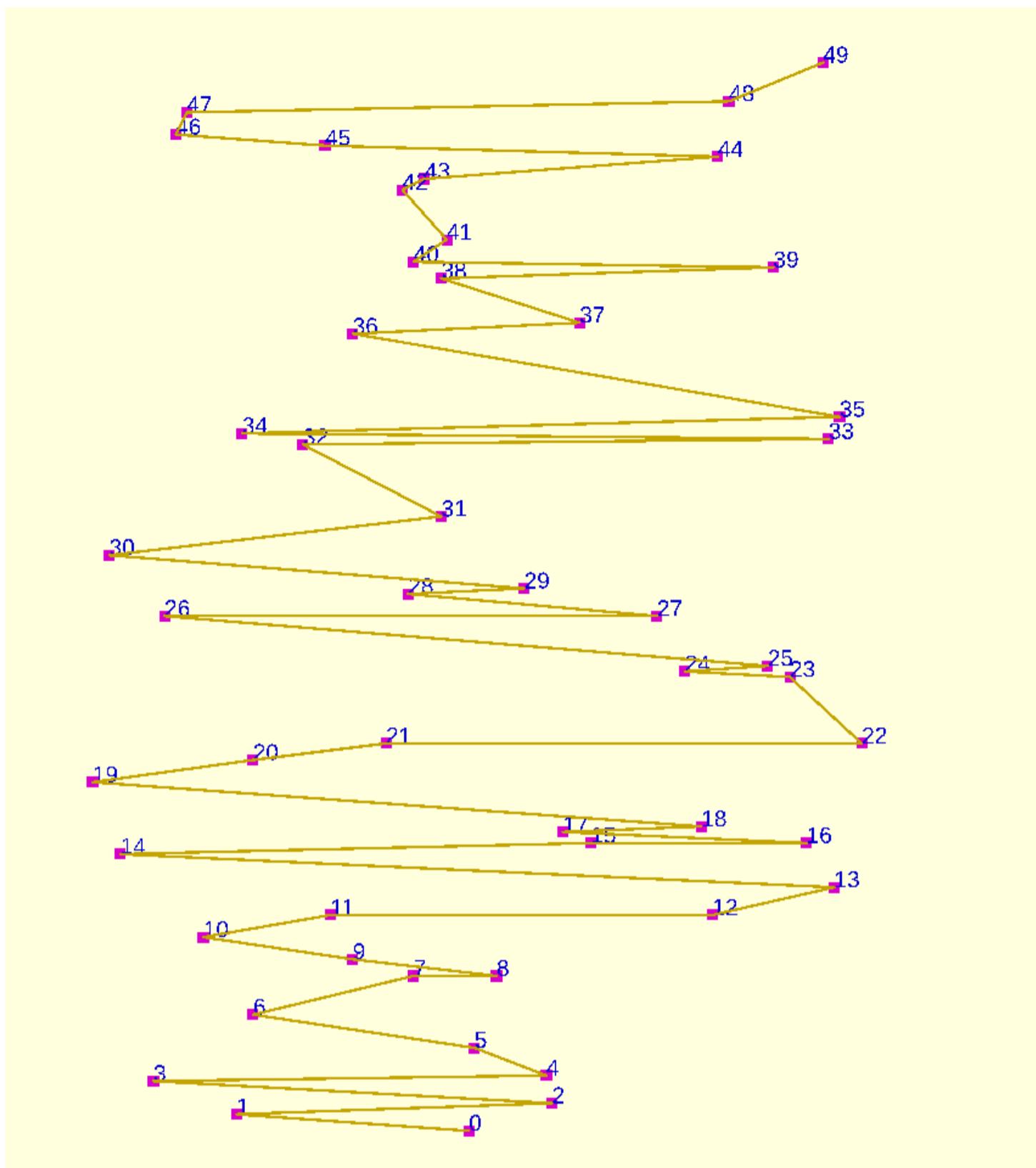
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
p2={lexicographic_sort_yx(p)};
color("blue")for(i=0:len(p2)-1)translate(p2[i])text(str(i),.3);
p_lineo(p2,.05);
color("magenta")points(p2,.2);

    ''')

```

```
t1=time.time()
t1-t0
```

Out[159]: 0.007342815399169922



convex_hull

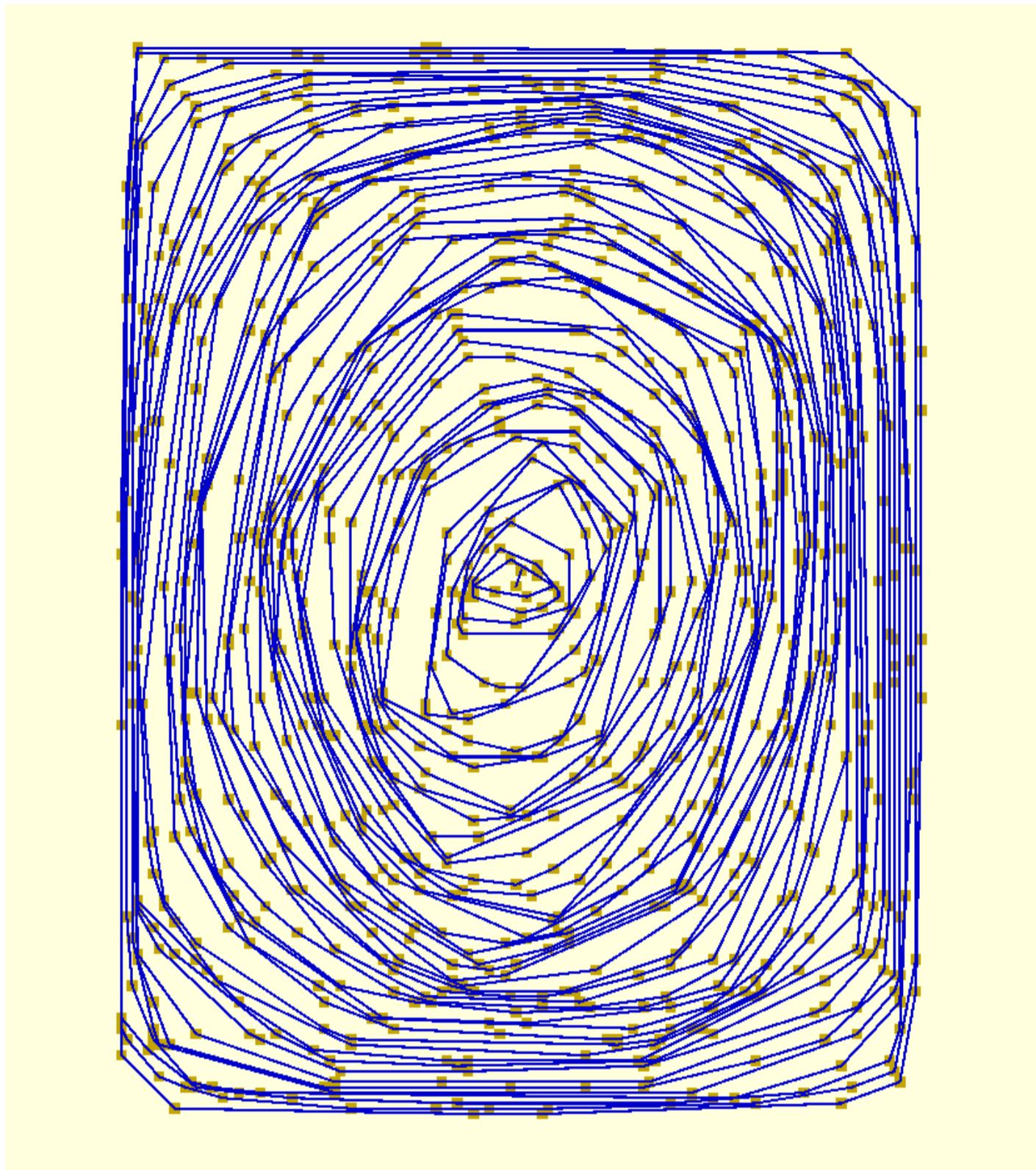
```
In [14]: t0=time.time()
a=random.random(1000)*(20-5)+5
b=random.random(1000)*(30-10)+10
px=array([a.round(1),b.round(1)]).transpose(1,0).tolist()
p=px
sec=[]
while(p!=[]):
    p1=convex_hull(p)
    sec.append(p1)
    p=exclude_points(p,p1)
    if p==[]:
        break

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
points({px},.2);

color("blue")for (p={sec})p_line(p,.05);

    ''')
t1=time.time()
t1-t0
```

Out[14]: 8.780018329620361



equivalent_rot_axis

```
In [161]: # example of function equivalent_rot_axis(r1=[])
a,b,c,d,e,f1,g,h=20,-20,70,40,50,-50,70,10
r1=[ f"x{a}",f"y{b}",f"z{c}",f"y{d}",f"x{e}",f"y{f1}",f"z{g}",f"y{h}"]
sol=cylinder(h=50)
v2,theta=equivalent_rot_axis(r1)
sol1=axis_rot(v2,sol,theta)
sol2=axis_rot(v2,sol1,-theta)

with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies.scad>

// pure openscad way of rotating the 3d object
color("magenta")
rotate({[0,h,0]})
```

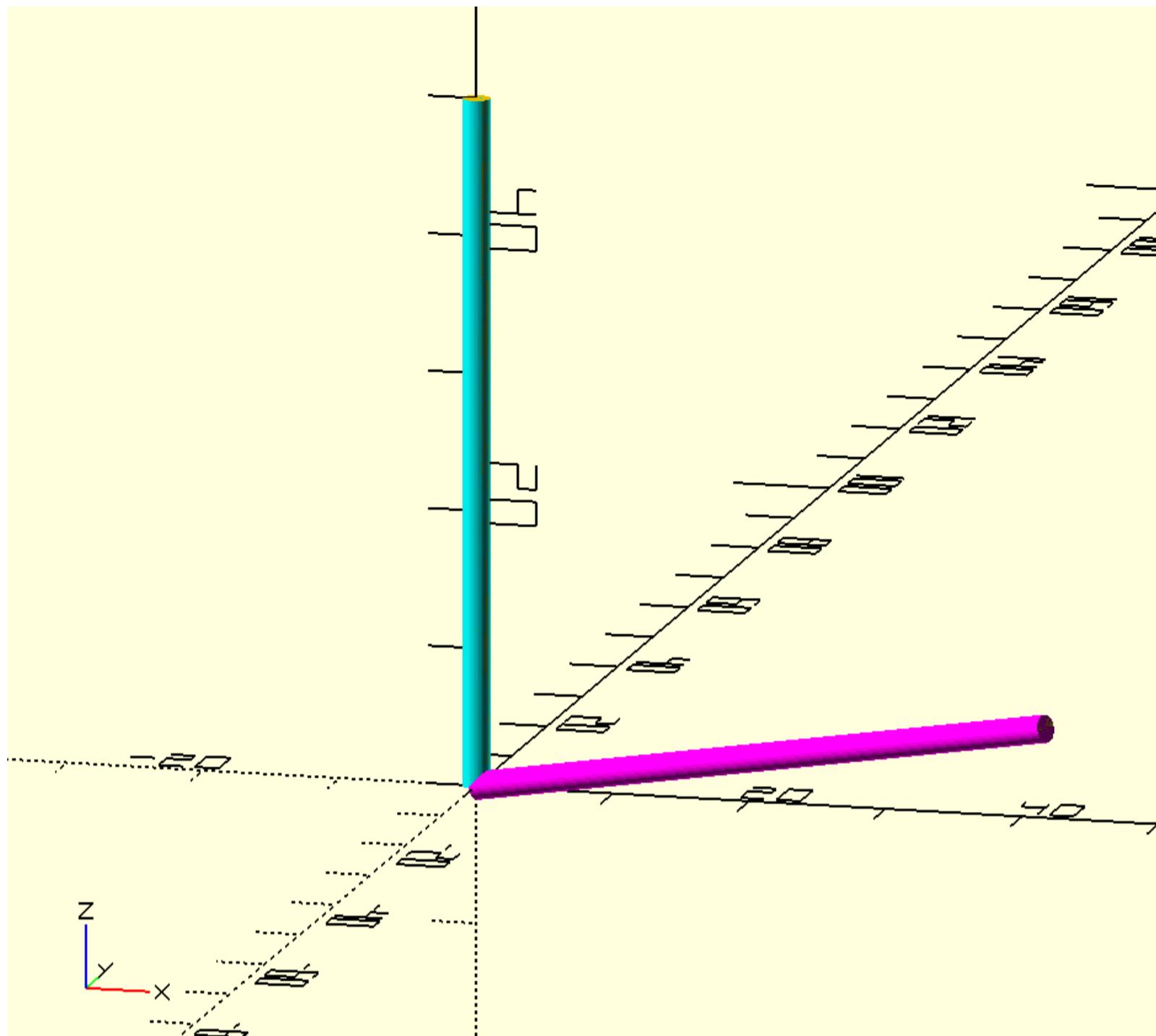
rotate([e,f1,g])
rotate([0,d,0])
rotate([a,b,c])
cylinder(r=1.01,h=50,\$fn=30);

```
// rotation by function equivalent_rot_axis
r1=[ "x{a}","y{b}","z{c}","y{d}","x{e}","y{f1}","z{g}","y{h}"];

theta=equivalent_rot_axis(r1)[0];
v2=equivalent_rot_axis(r1)[1];

rotate(-theta,v2)
rotate(theta,v2)
cylinder(r=1.01,h=50,$fn=30);

    ''')
```



```
In [16]: s_y=20+5/sin(d2r(45))
h_z=10/20*s_y
s_y1=(s_y**2-h_z**2)**0.5
sec=corner_radius(pts1([[20,s_y,5],[-20,20,5],[-20,-20,5],[20,-20,5]]),20)
sec1=offset(sec,5)

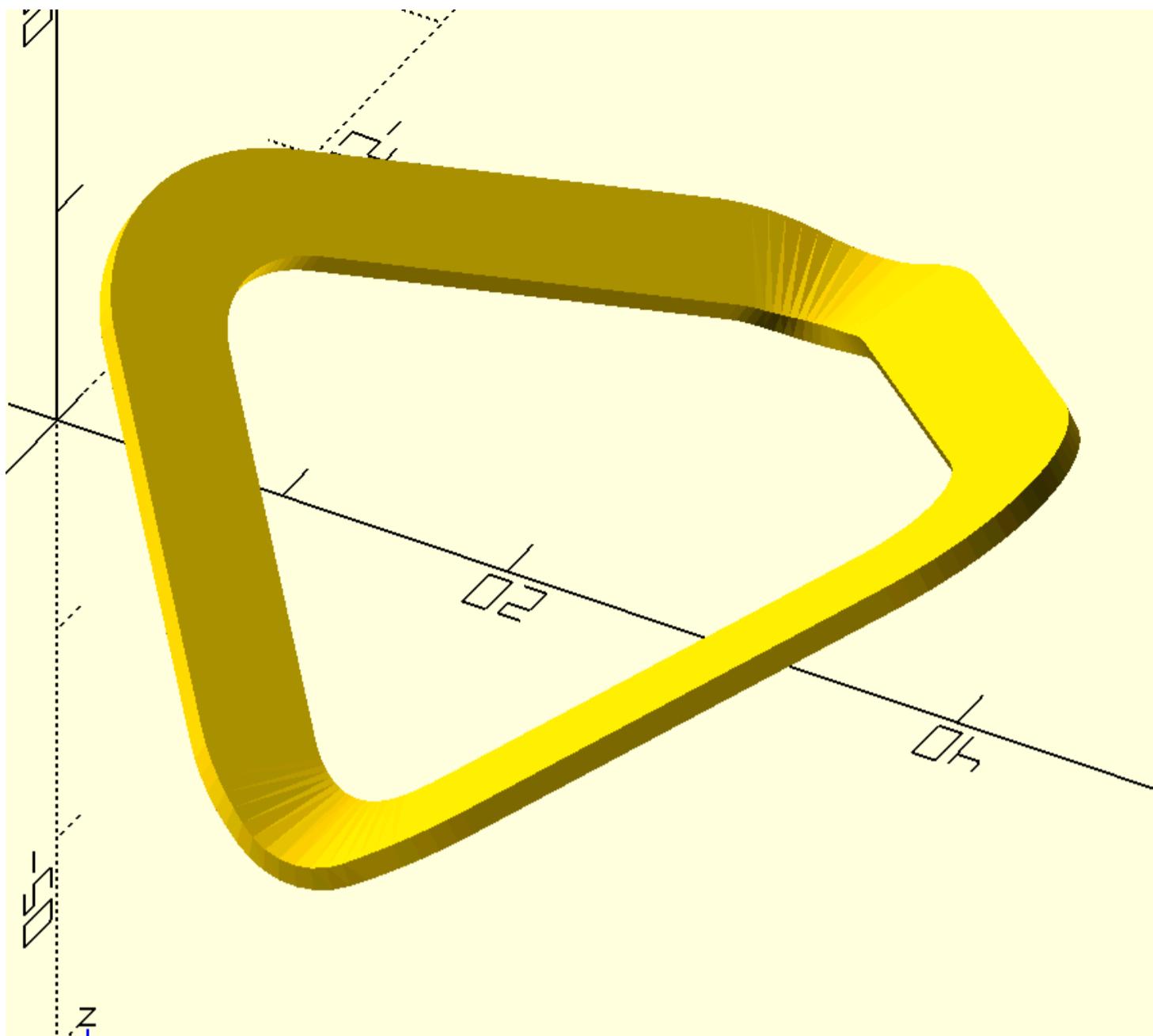
path=cr_3d([[0,0,h_z,0],[0,s_y1,-h_z,5],[0,s_y1,h_z,0]],20)

sec2=wrap_around(sec,path)
sec3=wrap_around(sec1,path)

surf1=[sec2,sec3]
surf2=surf_offset(surf1,-1)
sol=surf1+flip(surf2)+[surf1[0]]
d=s_y1/s_y*20
path2=cr_3d([[20,s_y1+.25,0,3.5],[-20,d,10,5],[-20,-d,-10,3.5],[20,-d,10,5]],20)

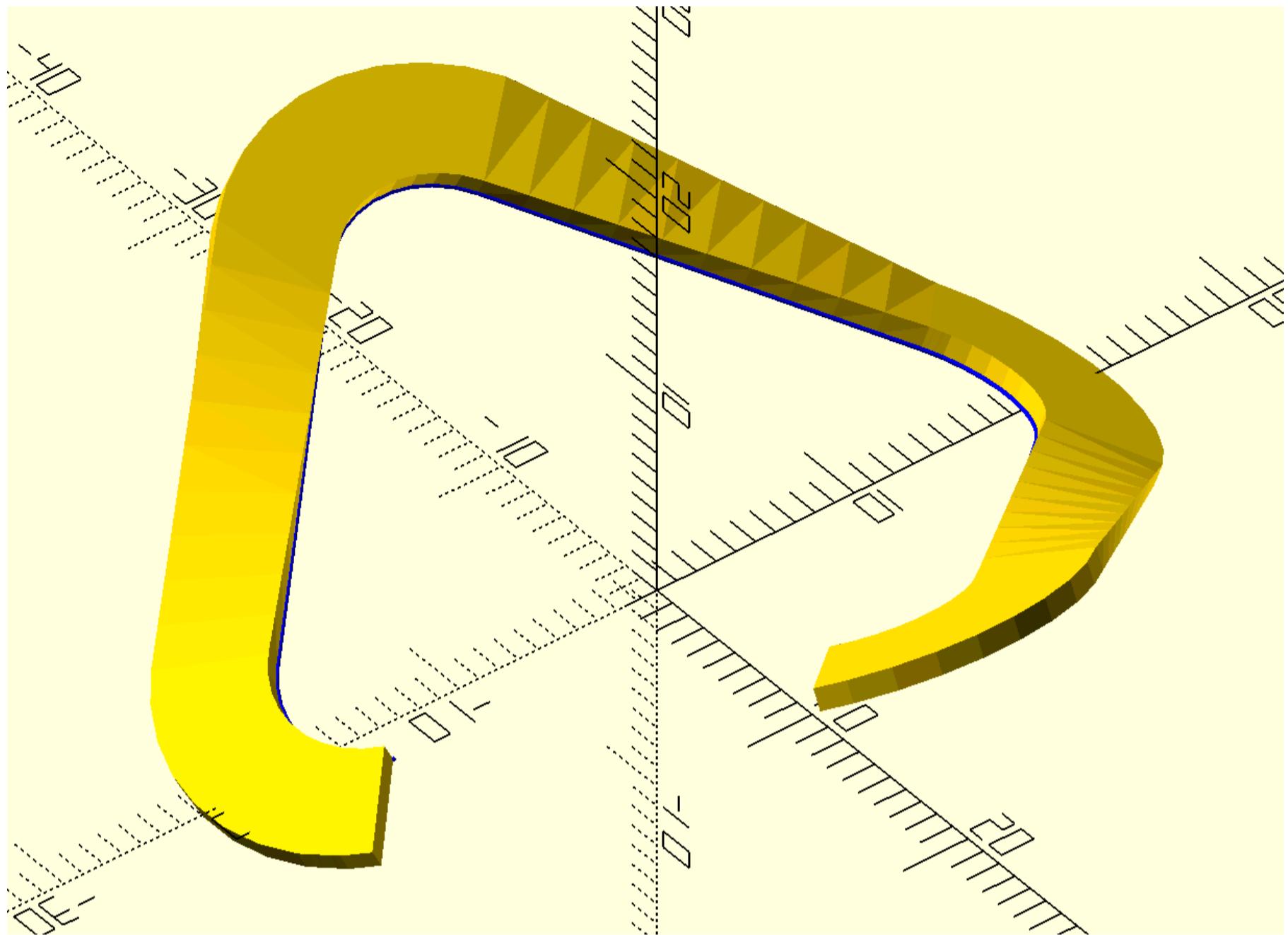
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

//color("blue")for(p={cpo(sol)})p_line3dc(p,.05);
//color("magenta")p_line3dc({path2},.05);
{swp_c(sol)}
    ''')
    
```



path_extrude_open

```
In [16]: # example of path_extrude_open(sec,path,twist=0) which adds a twist to the section
sec=pts([[0,0],[5,0],[0,1],[-5,0]])
path=cr_3d([[20,0,10,5],[-20,20,-10,5],[-20,-20,10,5],[20,-20,-10,5]],10)
# path=q_rot(['x30'],circle(20))
# path=helix(20,10,1,5.1)
sol=path_extrude_open(sec,path,1)
sol=slice_sol(sol,10)
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line3d({path},.1);
{swp(sol)}
...)
```



`tangents_along_path`

`normals_along_path`

`orthos_along_path`

```
In [2]: # path=q_rot(['x90.001'],circle(10))
# path=cr_3d([[0,0,0,3],[15,0,0,4],[5,3,15,3],[0,10,0,3],[-5,3,-15,4],[-15,0,0,3]],10)
path=cr_3d([[20,0,10,5],[-20,20,-10,5],[-20,-20,10,5],[20,-20,-10,5]],20)
# path=helix(10,5,3,5.001)

# sec=pts([[-1.5,-1.25],[3,0],[-1.5,2.5]])
# sec=pts([[0,0],[5,0],[0,1],[-5,0]])
sec=[[0,0],[1,0],[0,1]]
sol=path_extrude_open(sec,path)
# sol=slice_sol(sol,10)
# sol=align_sol(sol,1)

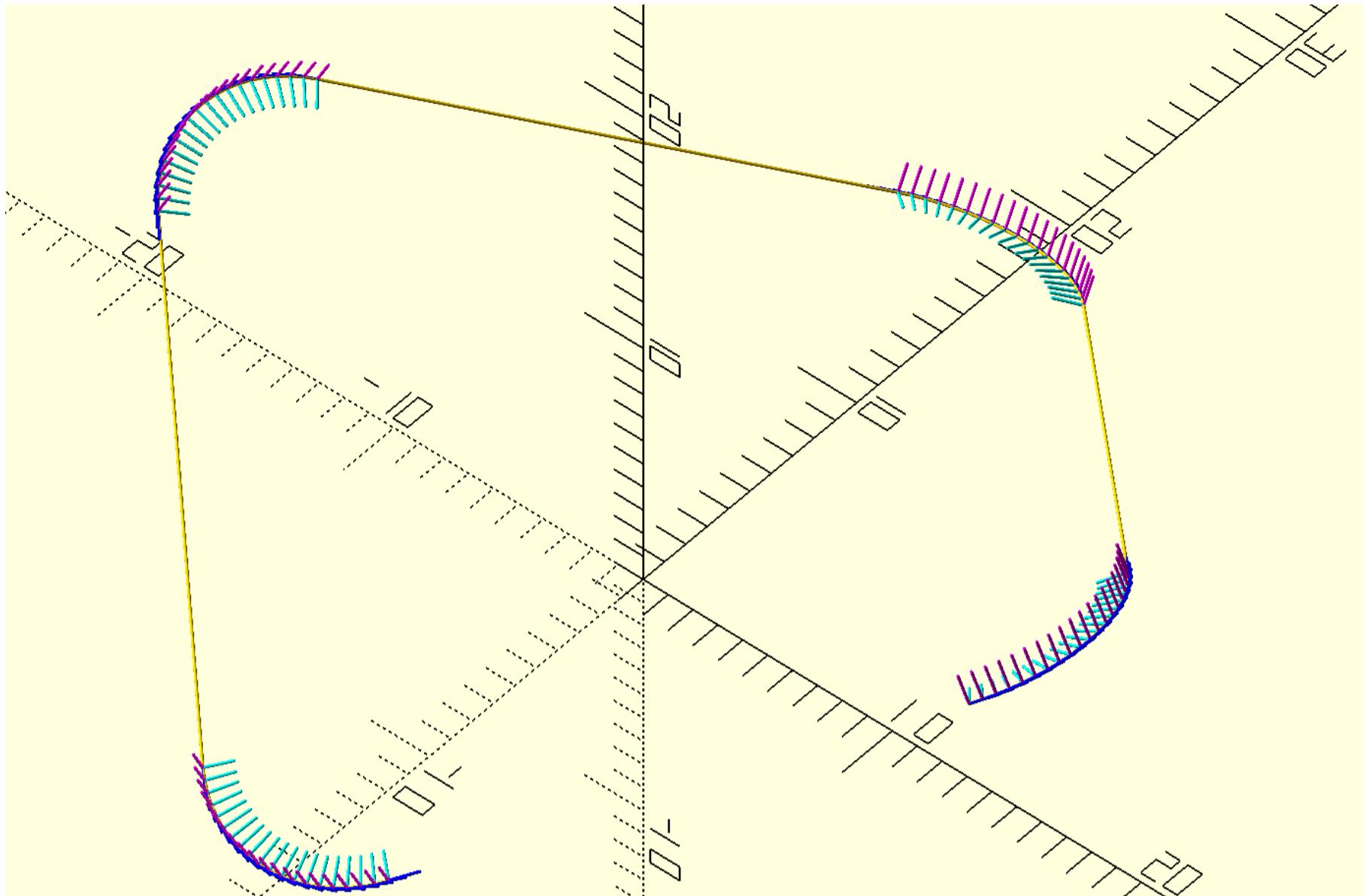
t_v1=tangents_along_path(path,1)
n_v1=normals_along_path(path,1)
o_v1=orthos_along_path(path,1)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

p_line3d({path},.05);
color("blue")for(p={t_v1})p_line3d(p,.05);
color("magenta")for(p={n_v1})p_line3d(p,.05);
color("cyan")for(p={o_v1})p_line3d(p,.05);

//{swp(sol)}

...)
```



```
In [165]: # sec2=[[0,0,0],[2,0,0],[0,0,2]]
sec2=[[0,1,0],[2,3,0],[0,3,2]]

cir1=cir_3p_3d(sec2,100)
cp=cp_cir_3d(sec2)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")points({sec2},.2);
p_line3dc({cir1},.05);

color("magenta")points({[cp]},.2);

''' )
```

cp_cir_3d

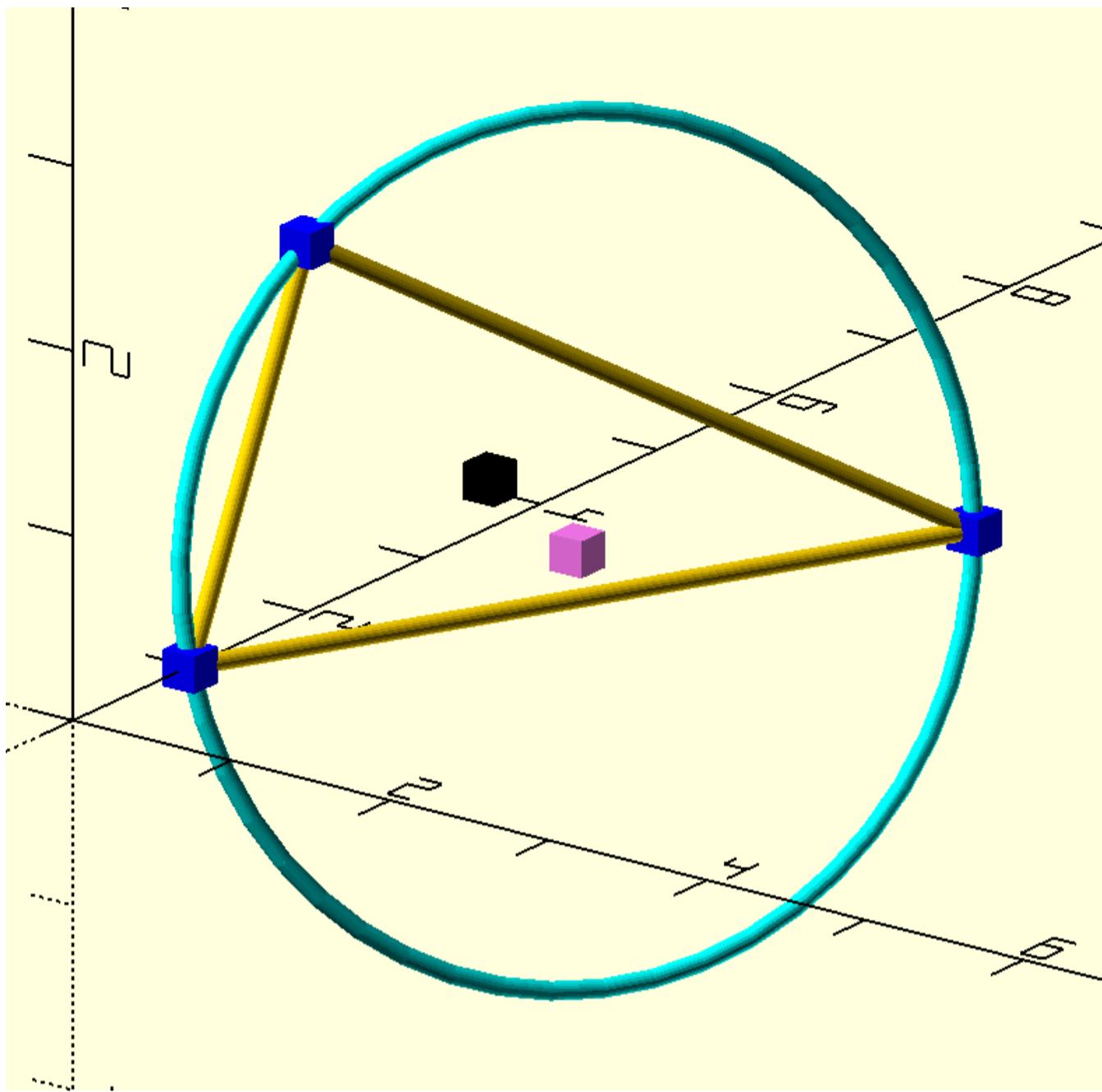
```
In [18]: # explanation of functions to draw circle from 3 points in 3d space
# function to get center of the circle drawn with 3 points. Note that the center of circle is different from the center of 3 points
# Also note that the centroid of the triangle is same as mean of the 3 points

sec=[[0,1,0],[2,5,0],[0,2,2]] # 3 points in 3d space

cir1=cir_3p_3d(sec,50) #function to draw circle from 3 points in 3d space
cp=cp_cir_3d(sec) # function calculates the center of the circle
cp1=centroid_3p_3d(sec)
cp2=array(sec).mean(0).tolist()
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")points({sec},.2);
p_line3dc({sec},.05);

color("cyan")p_line3dc({cir1},.05);// circle drawn by 3 points input
color("violet")points({[cp]},.2);// center point of the circle containing the 3 points as input
color("magenta")points({[cp1]},.2);// centroid of a triangle
color("black")points({[cp2]},.2);// mean is the centroid

''' )
```



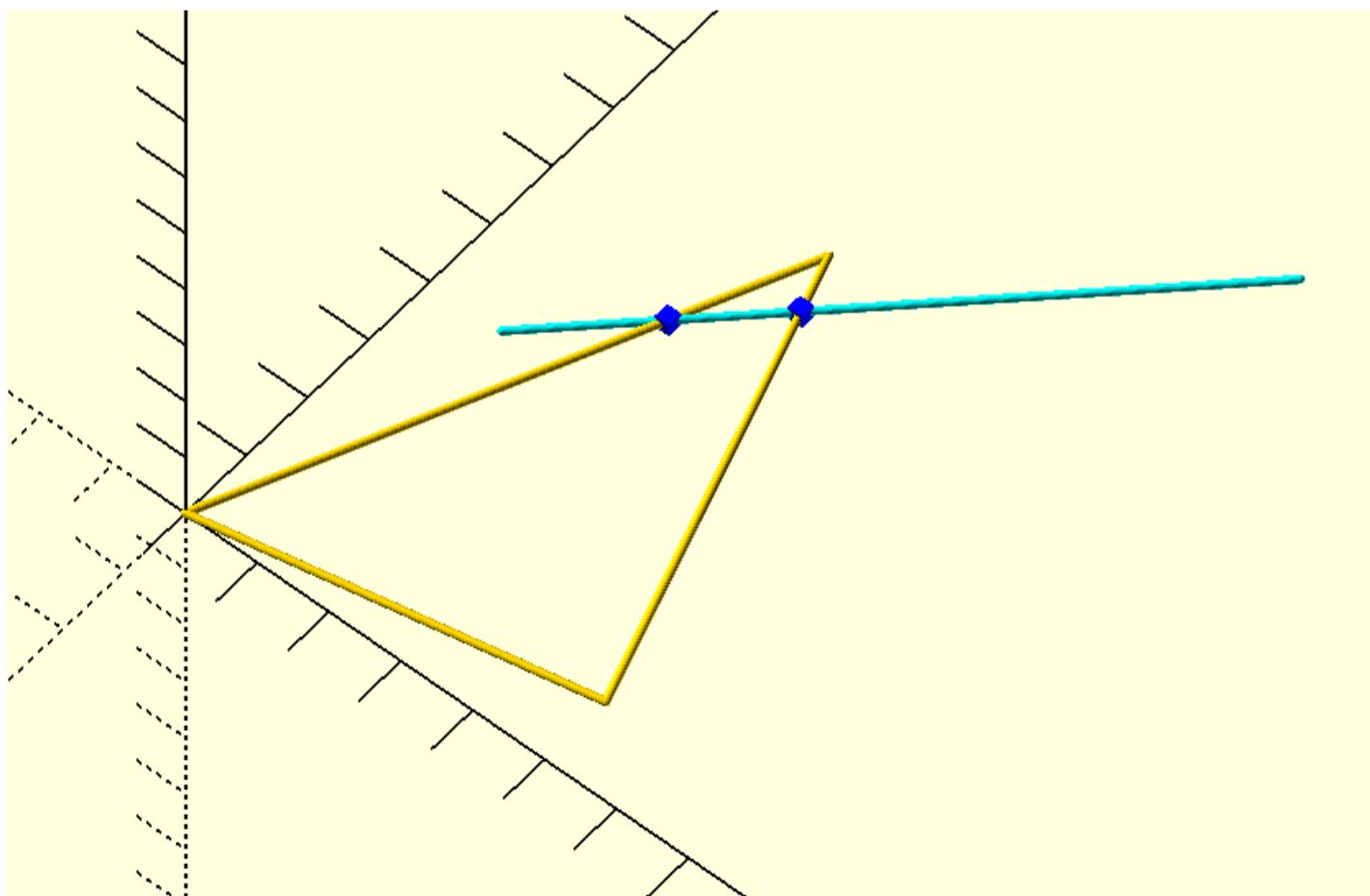
l_sec_ip

```
In [19]: # example of line to section intersection point function
line=[[1,4],[7,10]]
sec=[[0,0],[5,1],[3,7]]

i_p1=l_sec_ip(line,sec)
with open('trial.scad','w+') as f:
    f.write(f''''
include<dependencies2.scad>

p_line3dc({sec},.05);
color("cyan")p_line3dc({line},.05);
color("blue")points({i_p1},.2);

'''')
```



i_line_planes

```
In [20]: # example of intersection line between 2 planes
t0=time.time()

p1=translate([-2,0,-8.22],[[2,4,5],[7,9,15],[1,10,5]])
p2=translate([-3,0,-5],[[5,10,3],[5,-7,5],[-10,5,10]])

i_p1=i_line_planes(p2,p1)

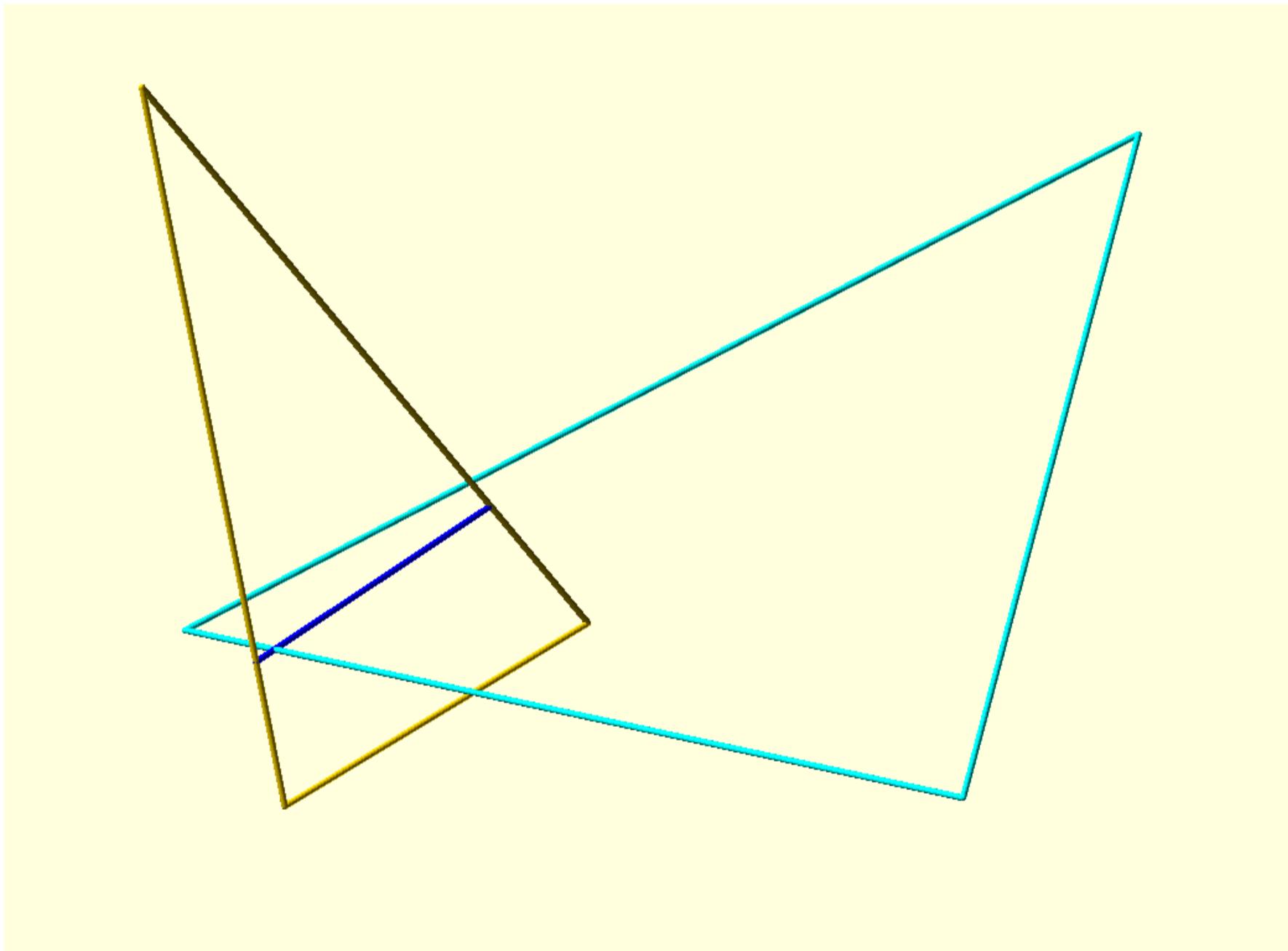
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

p_line3dc({p1},.05);
color("cyan")p_line3dc({p2},.05);

color("blue")p_line3d({i_p1},.05);

''')
t1=time.time()
t1-t0
```

Out [20]: 0.016494274139404297



surface_for_fillet

```
In [56]: # example of function surface_for_fillet(sol1=[],sol2=[],factor1=50,factor2=10,factor3=1,factor4=100,dia=40)
t0=time.time()

sec=circle(10)
path=corner_radius(pts1([[-8,0],[10,0],[-2,0,2],[-1,15,3],[-8.9,0]]),10)
path=equidistant_path(path,100)
sol1=q_rot(['z90'],prism(sec,path))

sec1=corner_radius(pts1([[0,0,1],[5,0,1],[0,7,2.3],[-5,0,2.3]]),10)
path1=corner_radius(pts1([[-2.4,0],[2.4,0,2],[0,5,.3],[-.5,0]]),10)
path1=equidistant_path(path1,30)
sol2=translate([6,0,12],q_rot(['x90','z90'],prism(sec1,path1)))

sol3=surface_for_fillet(sol1,sol2,100,20,4,23,8)
ip2=ip_sol2sol(sol2,sol3)

fillet1=i_line_fillet_closed(sol2,sol3,ip2,1,-1)
with open('trial.scad','w+') as f:
```

```

f.write(f'''
include<dependencies2.scad>
%{swp(sol1)}
%{swp(sol2)}
color("cyan")for(p={sol2})p_line3dc(p,.01,rec=1);
color("cyan")for(p={cpo(sol2)})p_line3d(p,.01,rec=1);

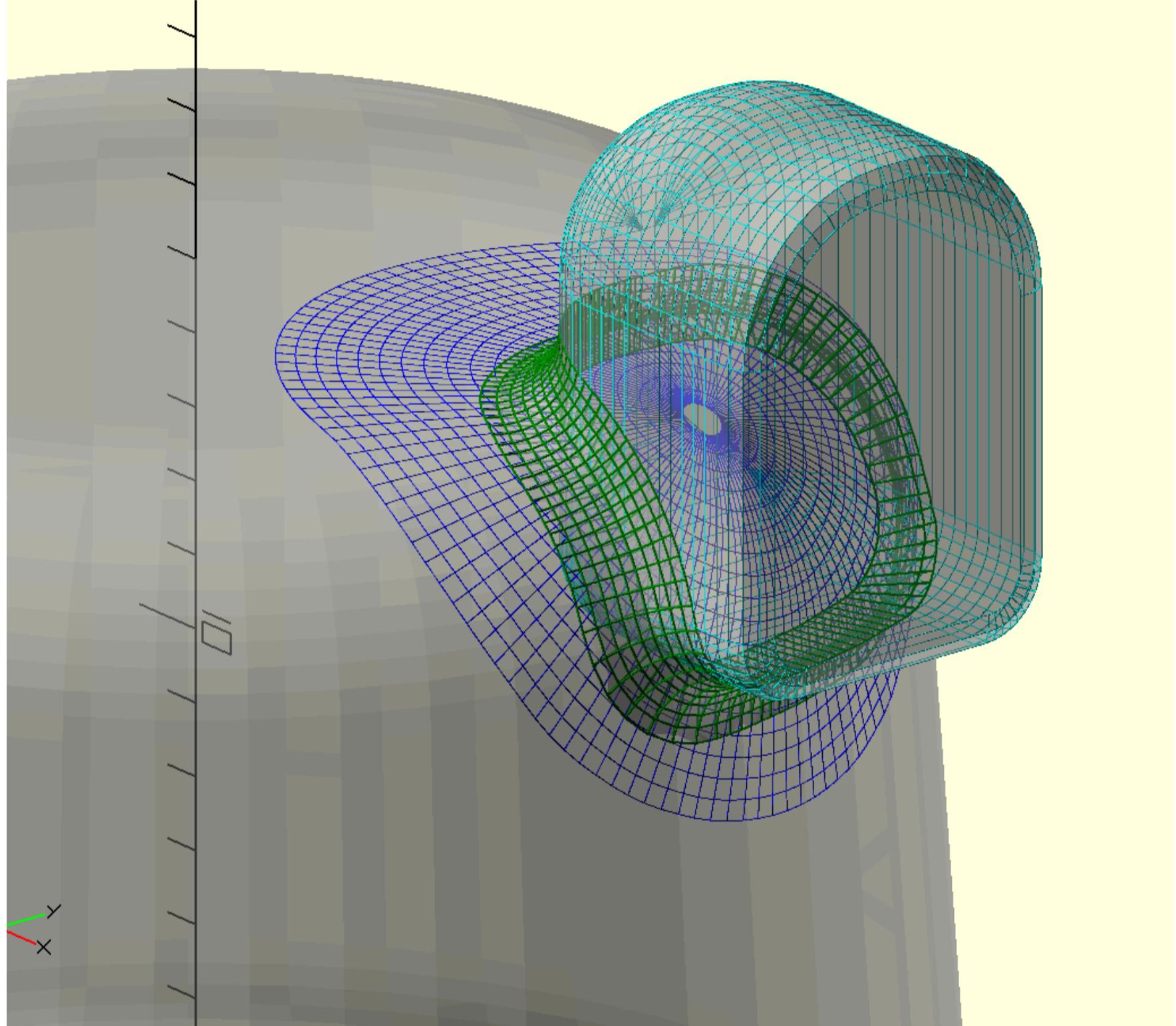
color("blue")for(p={sol3})p_line3dc(p,.01,rec=1);
color("blue")for(p={cpo(sol3)})p_line3d(p,.01,rec=1);
color("magenta")p_line3dc({ip2},.2,rec=1);

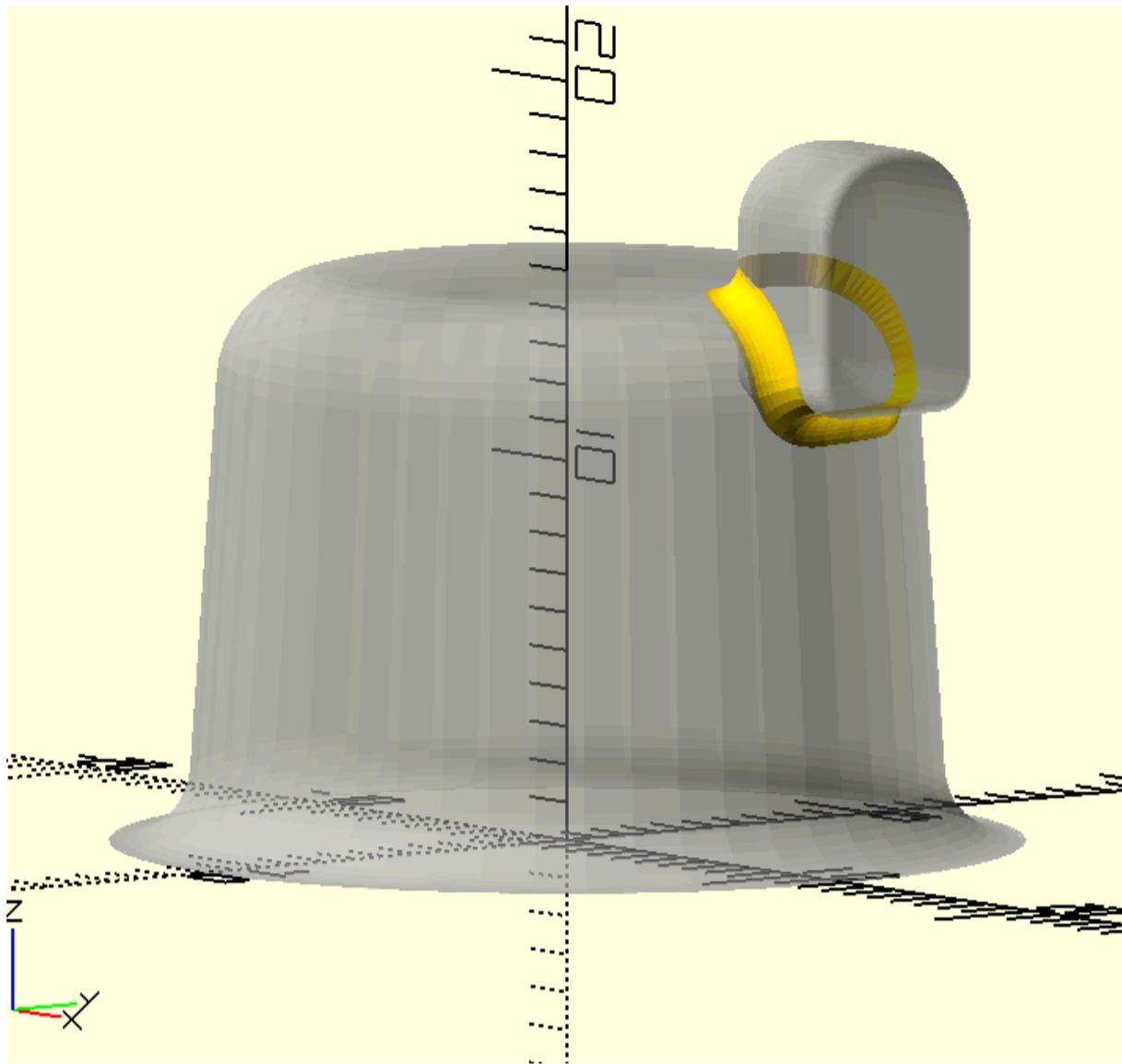
{swp_c(fillet1)}
color("green")for(p={fillet1})p_line3dc(p,.02,rec=1);
color("green")for(p={cpo(fillet1)})p_line3dc(p,.02,rec=1);

''' )

```

Out[56]: 2.5321803092956543





```
In [36]: t0=time.time()
sec1=circle(55,s=70)
path1=corner_radius(pts1([[-50,30],[56,0],[0,8,5],[-4,3,5],[0,18,10],[8,5,10],[0,12],[-50,0]]),10)
sol1=q_rot(['z0'],f_prism(sec1,path1))

sec2=circle(7.5)
path2=corner_radius(pts1([[-5,0],[5,0,5],[0,35,3],[-4,0]]),10)
sol2=translate([58,0,35],f_prism(sec2,path2))

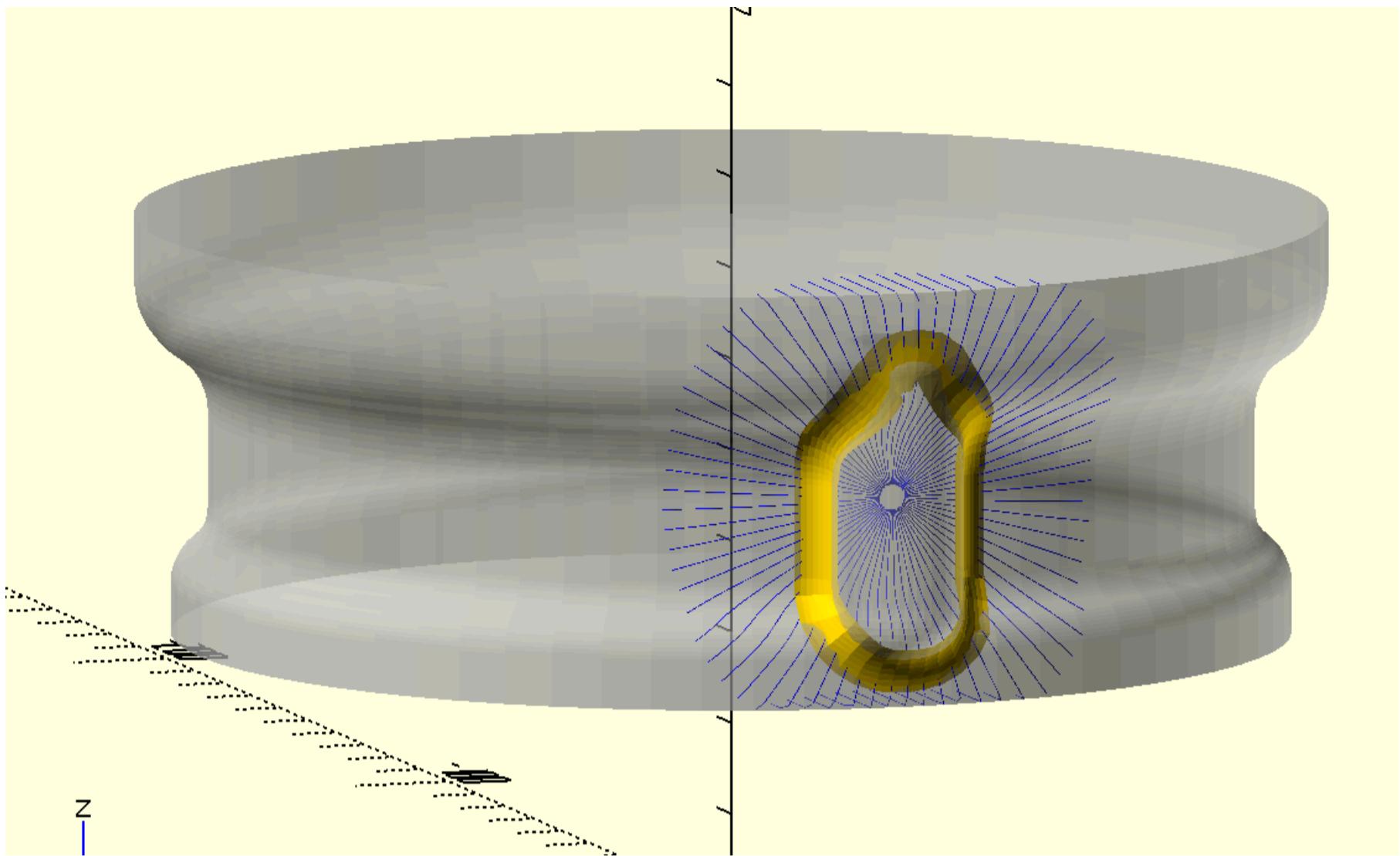
surf1=surface_for_fillet(sol1,sol2,70,20,5,200,50)

fillet1=fillet_sol2sol(sol2,surf1,4)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
%{swp(sol1)}
%{swp(sol2)}

color("blue")for(p={cpo(surf1)})p_line3d(p,.05);
{swp_c(fillet1)}
''')
t1=time.time()
total=t1-t0
total
```

C:\openscad\openscad-main\openscad1.py:2454: RuntimeWarning: invalid value encountered in arcsin
a=arcsin(r1/d1)*180/pi

Out[36]: 1.6076035499572754



i_line_fillet

```
In [37]: i_t=time.time()
sec1=circle(55)
path1=corner_radius(pts1([[-50,0],[50,0,.2],[0,30,3],[6,1,3],[0,6,3],[-4,2,3],[0,22,6],[8,2,6],[0,10,.2],[-50,0]]),10)
# path1=equidistant_path(path1,200)
sec2=circle(7.5)
path2=corner_radius(pts1([[-5,0],[5,0,5],[0,35,2],[-5,0]]),10)
path2=equidistant_path(path2,50)
sol1=f_prism(sec1,path1)
sol2=translate([57.5,0,37],f_prism(sec2,path2))
sol2=axis_rot_o([0,0,1],sol2,180)
p1=ip_sol2sol(sol1,cpo(sol2))
p2=ip_sol2sol(sol1,cpo(sol2),-1)

p3=flip(p1)+p2

fillet1=i_line_fillet_closed(sol1,sol2,p3,3,-3)

with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>

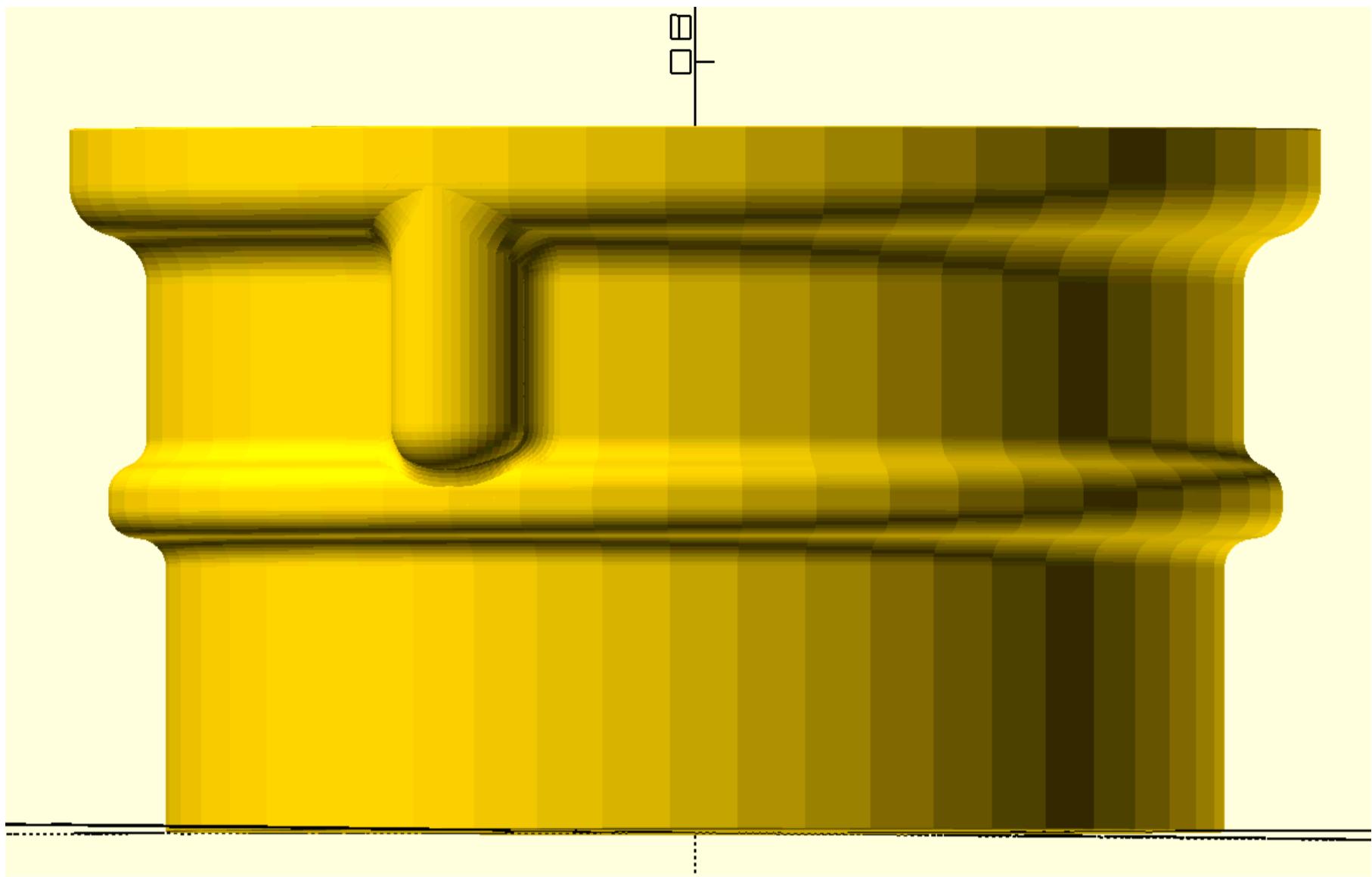
        %{swp(sol1)}
        %{swp(sol2)}

        //color("blue")for(p={cpo(sol2)})p_line3d(p,.1,rec=1);
        color("magenta")points({p1},.3);
        color("magenta")points({p2},.3);
        color("cyan")p_line3dc({p3},.1,rec=1);
        {swp_c(fillet1)}


    ''')

f_t=time.time()
f_t-i_t
# len(p1),len(p2),len(p3)
```

Out[37]: 7.604323863983154



```
In [6]: i_t=time.time()
sec=corner_radius(pts1([[-5,-5,1],[10,0,1],[0,10,1],[-10,0,1]]),10)
path=corner_radius(pts1([[-4,0],[4,0,1],[0,10,1],[-4,0]]),10)
sol1=prism(sec,path)
sol2=o_solid([1,0,.1],circle(2,s=100),15,-7,0,10,[-90,0,0])
sol2=slice_sol(sol2,2)
p1=ip_sol2sol(sol1,sol2)
p2=ip_sol2sol(sol1,sol2,-1)

p3=flip(p1)+p2
# p4=o_3d(p3,sol2,-1)
# p5=o_3d(p3,sol1,1)
# fillet1=convert_3lines2fillet_closed(p3,p5,p4)
fillet1=i_line_fillet_closed(sol1,sol2,p3,1,-1)

with open('trial.scad','w+')as f:
    f.write(f'''
        include<dependencies2.scad>

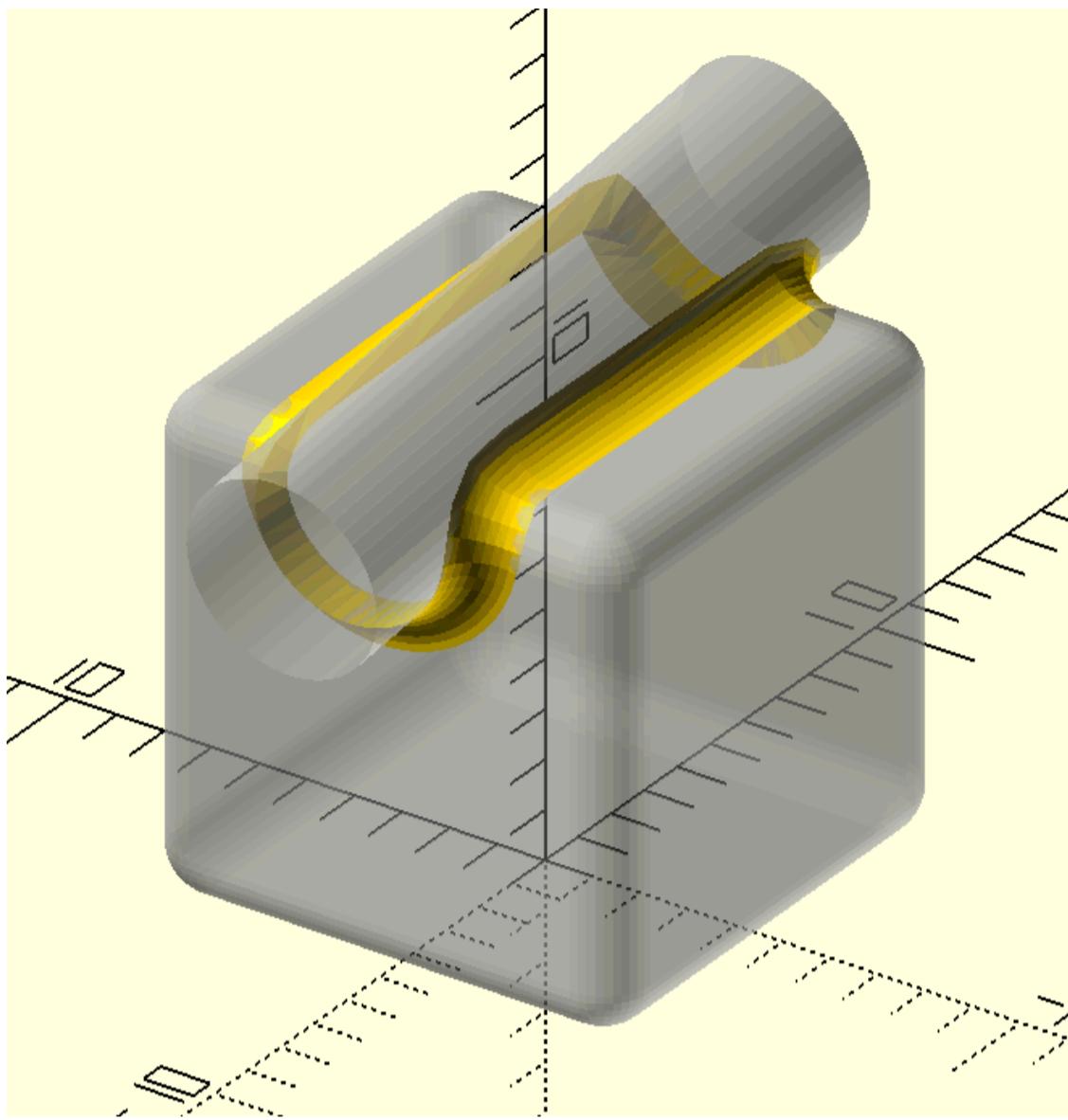
        %{swp(sol1)}
        %{swp(sol2)}
        color("blue")p_line3d({p1},.04,rec=1);
        color("magenta")p_line3d({p2},.04,rec=1);

        {swp_c(fillet1)}

        ''')
f_t=time.time()
f_t-i_t
# len(p3),len(p4),len(p5)

/Users/sanjeevprabhakar/openscad/openscad1.py:4750: RuntimeWarning: divide by zero encountered in divide
    t=einsum('kl,ijkl->ijk',cross(p01,p02),la[:, :,None]-p0)/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad1.py:4750: RuntimeWarning: invalid value encountered in divide
    t=einsum('kl,ijkl->ijk',cross(p01,p02),la[:, :,None]-p0)/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad1.py:4751: RuntimeWarning: divide by zero encountered in divide
    u=einsum('ijkl,ijkl->ijk',cross(p02[None,None,:,:],(-lab)[:, :,None,:]),(la[:, :,None,:]-p0[None,None,:,:]))/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad1.py:4752: RuntimeWarning: divide by zero encountered in divide
    v=einsum('ijkl,ijkl->ijk',cross((-lab)[:, :,None,:],p01[None,None,:,:]),(la[:, :,None,:]-p0[None,None,:,:]))/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad1.py:4752: RuntimeWarning: invalid value encountered in divide
    v=einsum('ijkl,ijkl->ijk',cross((-lab)[:, :,None,:],p01[None,None,:,:]),(la[:, :,None,:]-p0[None,None,:,:]))/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad1.py:4753: RuntimeWarning: invalid value encountered in add
    condition=(t>=0)&(t<=1)&(u>=0)&(u<=1)&(v>=0)&(v<=1)&(u+v<1)
/Users/sanjeevprabhakar/openscad/openscad1.py:4755: RuntimeWarning: invalid value encountered in multiply
    a=(la[:, :,None,:]+lab[:, :,None,:])*t[:, :,None,:]
/Users/sanjeevprabhakar/openscad/openscad1.py:4751: RuntimeWarning: invalid value encountered in divide
    u=einsum('ijkl,ijkl->ijk',cross(p02[None,None,:,:],(-lab)[:, :,None,:]),(la[:, :,None,:]-p0[None,None,:,:]))/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)

Out[6]: 0.685377836227417
```



```
In [8]: i_t=time.time()

sec=pts([[0,0],[5,0],[0,5],[-5,0]])
path=corner_radius(pts1([[-2.49,0],[2.49,0,0.25],[0,5,0.25],[-2.49,0]]),10)
sol1=prism(sec,path)
v1=[2,0,8]
sec1=axis_rot([0,0,1],circle(1.5,s=100),90)
sol2=o_solid(v1,sec1,10,-1.5,-2.5,0)
p1=ip_sol2sol(sol1,sol2)
p2=ip_sol2sol(sol1,sol2,-1)

p3=flip(p1)+p2
# p4=equidistant_pathc(o_3d(p3,sol1,.5),200)
# p4=sort_points(p3,p4)
# # p4=path2path1(p3,p4)
# p5=equidistant_pathc(o_3d(p3,sol2,-.5),200)
# p5=sort_points(p3,p5)
# # p5=path2path1(p3,p5)
# p3,p4,p5=align_sol_1([p3,p4,p5])
# fillet1=convert_3lines2fillet_closed(p3,p5,p4)

fillet1=i_line_fillet_closed(sol1,sol2,p3,.5,-.5)

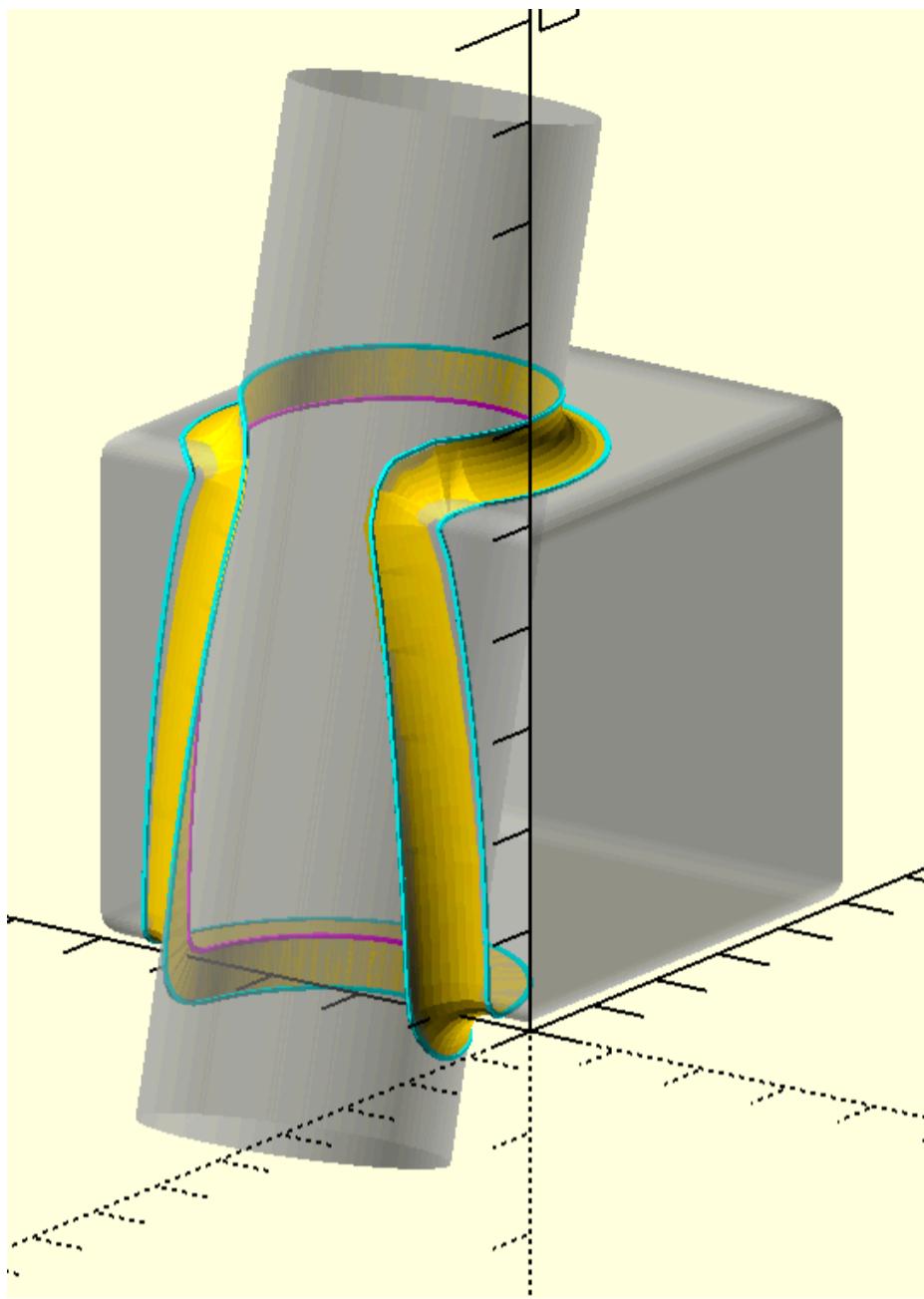
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

{swp(sol1)}
{swp(sol2)}
{swp_c(fillet1)}
''')

f_t=time.time()
f_t-i_t

# len(p3),len(p4),len(p5)
```

Out[8]: 0.36285901069641113

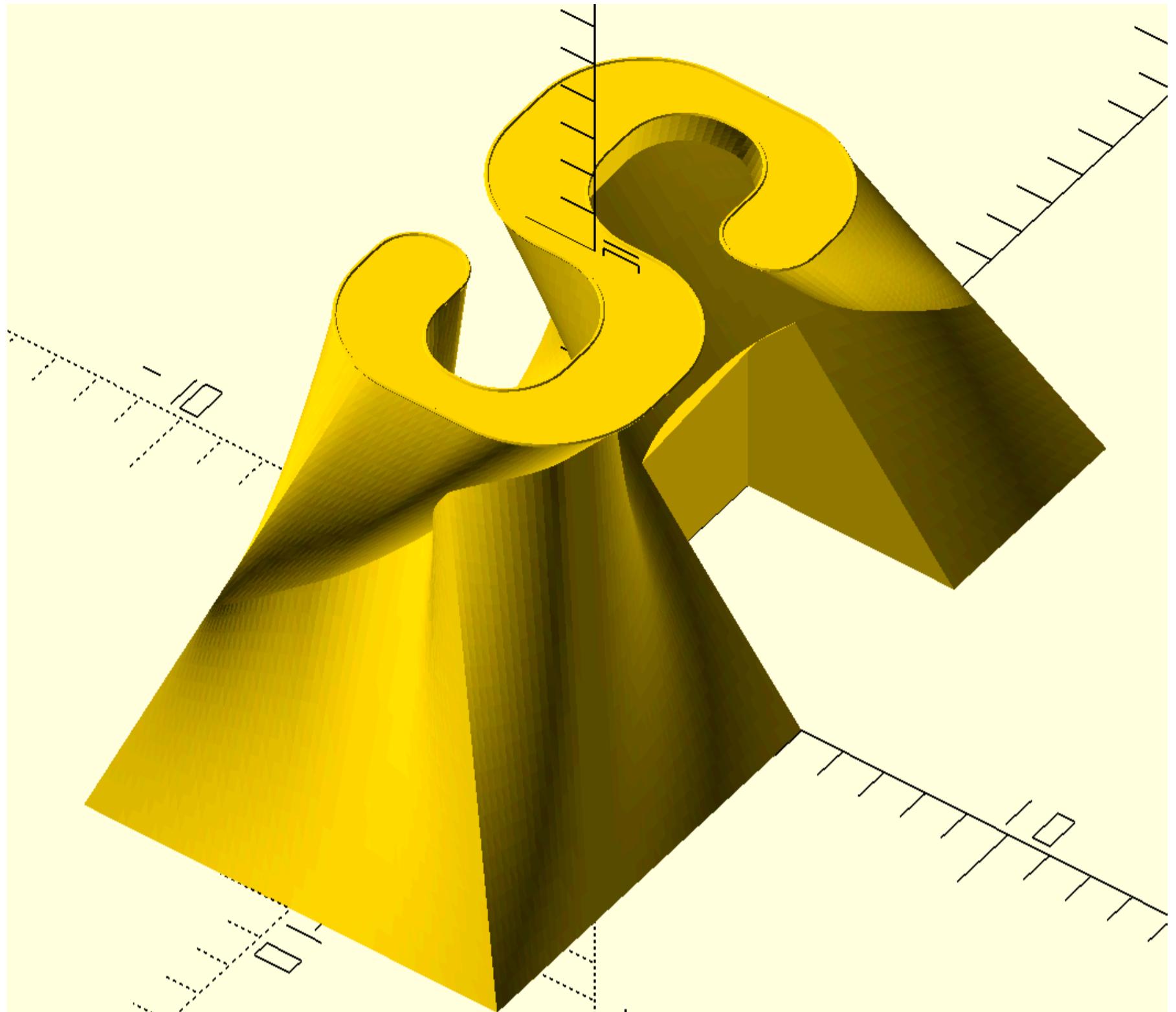


```
In [214... import sys  
set_printoptions(threshold=sys.maxsize)
```

align_sol_1

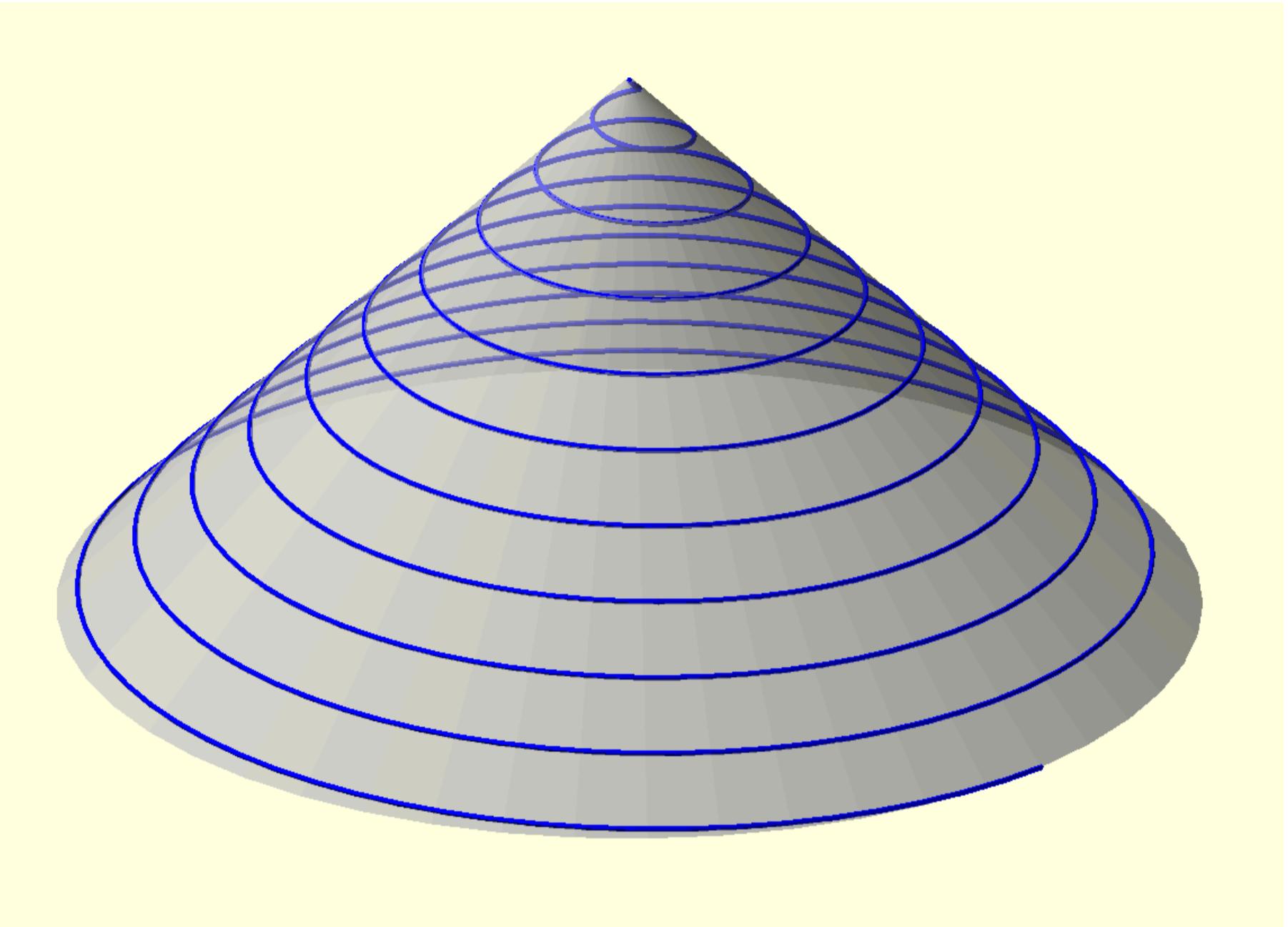
```
In [174... # merging 2 different shapes  
t0=time.time()  
  
sec=corner_radius(pts1([[1.5,8,.9],[2,0,.9],[0,-3,1.4],[3,0,1.4],[0,4,1.9],[-5,0,2.5],[0,6,2.5],  
[7,0,2.5],[0,-4,.9],[-2,0,.9],[0,3,1.4],[-3,0,1.4],[0,-4,1.9],  
[5,0,2.5],[0,-6,2.5],[-7,0,2.5]]),20)  
  
cp1=array(c2t3(sec)).mean(0)+[0,0,10]  
sec=translate(cp1,sec)  
sec1=c2t3(pts([-5,-10],[10,0],[0,20],[-10,0]))  
  
sec=equidistant_pathc(sec,300)  
sec1=equidistant_pathc(sec1,300)  
  
sol=align_sol_1([sec1,sec])  
sol=slice_sol(sol,30)  
sol1=array(sol).reshape(-1,3)  
  
with open('trial.scad','w+')as f:  
    f.write(f'''  
    include<dependencies.scad>  
  
difference(){  
    {swp(sol)}  
    translate([0,0,-.01])cube(5);  
}  
  
color("blue")p_line3dc({sol[-1]},.05);  
'''')  
  
t1=time.time()  
t1-t0
```

```
Out[174... 0.2719290256500244
```



coil-example

```
In [175]: coil=array([i/360*array([cos(d2r(i)),sin(d2r(i)),-1]) for i in linspace(0,3600,720)]).tolist()
cyl1=translate([0,0,-10],cylinder(r1=10,r2=0.1,h=10))
with open('trial.scad','w+')as f:
    f.write(f'''
        include<dependencies.scad>
translate([0,0,10]){{{
color("blue")p_line3d({coil},.05);
%{swp(cyl1)}
}}}
    ''')
```



In [178]:

```
x,y=sym.symbols('x y')
f1=sym.lambdify(x,10*sym.cos(x),'numpy')
f2=sym.lambdify(x,10*sym.sin(x),'numpy')
a=linspace(0,2*pi,100)
cir1=array([f1(a),f2(a)]).transpose(1,0).tolist()
with open('trial.scad','w+')as f:
    f.write(f'''
        include<dependencies.scad>
        color("blue")p_line({cir1},.05);
    ''')
```

In [44]:

```
v1x,v1y,v2x,v2y,p0x,p0y,p1x,p1y,t1,t2=sym.symbols('v1x,v1y,v2x,v2y,p0x,p0y,p1x,p1y,t1,t2')
p0,v1=array([[2,3],[4,5]])
p1,v2=array([[10,7],[-3,7]])

# p0+v1*t1=p1+v2*t2
# v1*t1-v2*t2=p1-p0
# v1x*t1-v2x*t2=(p1-p0)x
# v1.y*t1-v2.y*t2=(p1-p0).y

sp.linsolve([v1x*t1-v2x*t2-(p1x-p0x),v1y*t1-v2y*t2-(p1y-p0y)],t1,t2)
```

Out[44]:

$$\frac{p_0 + v_1 t_1 - p_1 - v_2 t_2}{v_1 x - v_2 x} = \frac{p_0 y + v_1 y + p_1 x - p_1 y - v_1 x}{v_1 x - v_2 x}$$

In [50]:

```
# p0+v1*t1=p2+v2*t2+v3*t3
# v1*t1-v2*t2-v3*t3=p2-p0

v1x,v1y,v1z,v2x,v2y,v2z,v3x,v3y,v3z,p0x,p0y,p0z,p2x,p2y,p2z,t1,t2,t3=
sp.symbols('v1x,v1y,v1z,v2x,v2y,v2z,v3x,v3y,v3z,p0x,p0y,p0z,p2x,p2y,p2z,t1,t2,t3')

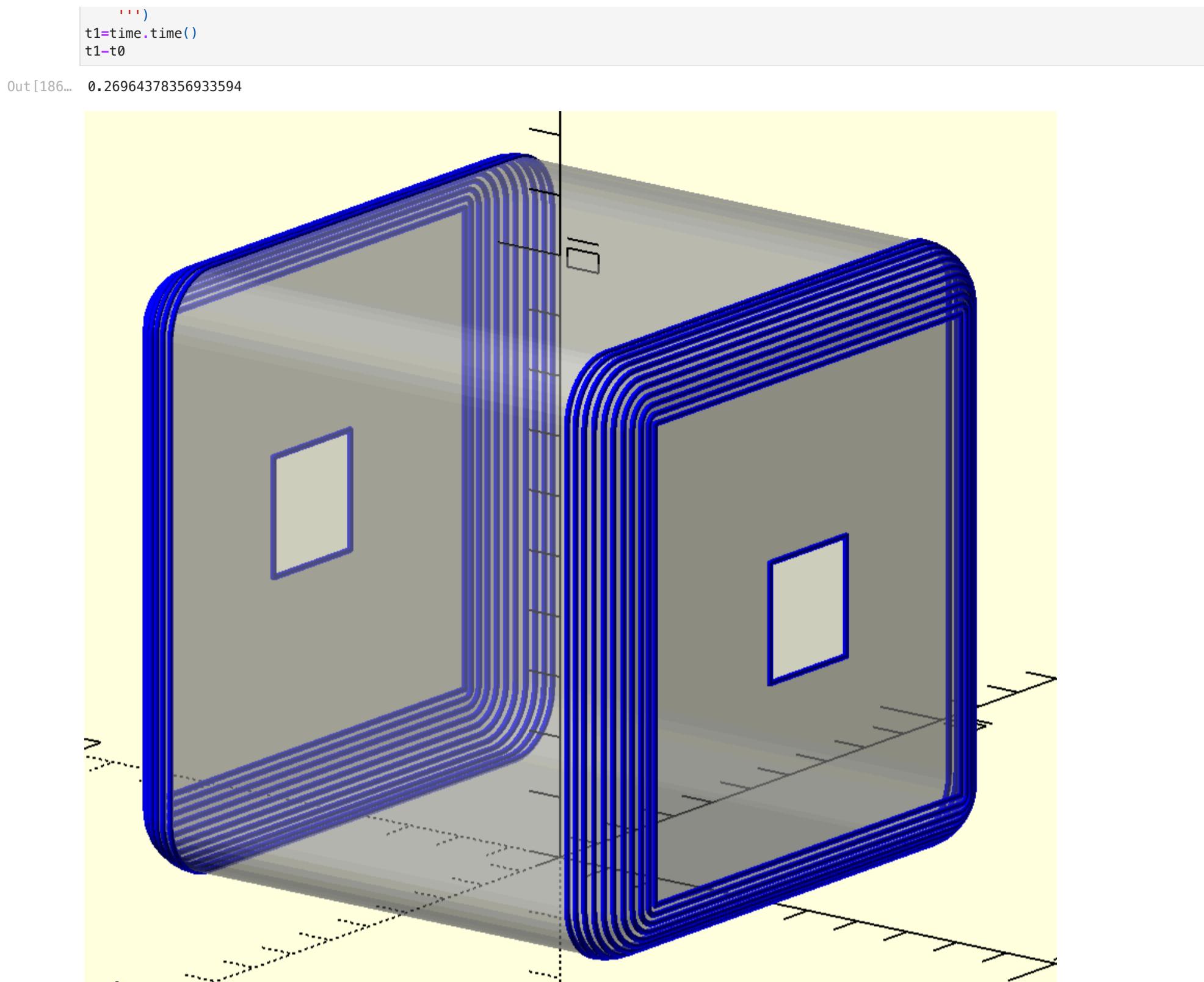
f=sp.linsolve([v1x*t1-v2x*t2-v3x*t3-(p2x-p0x),v1y*t1-v2y*t2-v3y*t3-(p2y-p0y),v1z*t1-v2z*t2-v3z*t3-(p2z-p0z)],t1,t2,t3)
```

axis_rot_o

In [186]:

```
t0=time.time()
sec=corner_radius(pts1([-5,-5,1],[10,0,1],[0,10,1],[-10,0,1]),10)
path=corner_radius(pts1([[-4,0],[4,0,1],[0,10,1],[-4,0]]),10)
sol1=axis_rot_o([0,1,0],prism(sec,path),90)

with open('trial.scad','w+')as f:
    f.write(f'''
        include<dependencies.scad>
        %{swp_c(sol1)}
        color("blue")for(p={sol1})p_line3dc(p,.1);
```



```
In [180... a=random.random(1000)*(10-1)+1
b=random.random(1000)*(10-3)+3
```

```
In [ ]: a=random.random(1000)*(10-1)+1
b=random.random(1000)*(10-3)+3
px=array([a,b]).transpose(1,0)
p_l=array([a,b]).transpose(1,0)
p_l=p_l.tolist()
```

```
In [403... k,n=3,10
s1=ch1(pnts,k)
py=exclude_points(pnts,s1)
pz=exclude_points(py,pies1(s1,py))

while (pz!=[] and k<=n):
    k=k+1
    s1=ch1(pnts,k)
    py=exclude_points(pnts,s1)
    x=pies1(s1,py)
    pz=exclude_points(py,x) if x!=[] else py
```

```
In [227... # for x in arange(10):
#     for y in arange(10):
#         for z in arange(10):
#             print (x,y,z)
#             if x*y*z == 30:
#                 break
#             else:
#                 continue
#             break
#         else:
#             continue
#         break
```

handling-trolley

```
In [17]: # frame
sec1=circle(12.5)
path1=c2t3(corner_radius(pts1([[0,0,5],[900,0,5],[0,600,5],[-900,0,5]]),10))

sol1=path_extrude_closed(sec1,path1)

path2=cr_3d([[600,0,0,5],[0,600,0,5],[0,0,500,5],[0,-600,0,5]],10)
```

```

sol2=align_sol_1(path_extrude_closed(sec1,path2))

sol3=translate([-100,0,0],sol2)

# hinge supports
fillet1=fillet_l_cir([[0,75],[200,75]],circle(40,[100,120]),20)[1]
fillet2=flip(fillet_l_cir([[0,75],[200,75]],circle(40,[100,120]),20)[0])
arc1=arc_long_2p(fillet1[-1],fillet2[0],40,-1)
sec2=[[0,0],[200,0],[200,75]]+fillet1+arc1+fillet2+[[0,75]]
sol4=translate([450,250,465],q_rot(['x90'],linear_extrude(sec2,20)))
sol5=translate([450,350,465],q_rot(['x90'],linear_extrude(sec2,20)))

# long arm
x1=o_solid([-1,0,0],circle(30),1800,-900,290,590,[0,0,0])
x2=o_solid([-1,0,0],circle(25),1800,-900,290,590,[0,0,0])
sol6=swp_prism_h(x1,x2)
# sol6=axis_rot_1(sol6,[0,1,0],[550,290,590],10)

# frame
sol7=o_solid([0,1,0],circle(12.5),600,0,100)
sol8=o_solid([0,1,0],circle(12.5),600,0,200)

# cylinder body
x3=o_solid([0,0,1],circle(40),300,135,150,-290)
x4=o_solid([0,0,1],circle(35),300,135,150,-290)
sol9=swp_prism_h(x3,x4)
# sol9=axis_rot_1(sol9,[0,1,0],[150,290,100],1)

# cylinder bottom cover
x5=o_solid([0,0,1],circle(40),20,135,150,-290)
# x5=axis_rot_1(x5,[0,1,0],[150,290,100],1)

# hinge of cylinder
sec1=corner_radius(pts1([[-20,-35,20],[40,0,20],[0,70],[-40,0]]))
sol10=o_solid([0,1,0],sec1,20,-10+290,150,125-20)
# sol10=axis_rot_1(sol10,[0,1,0],[150,290,100],2)

# piston
x6=o_solid([0,0,1],circle(35),20,175,150,-290)
# x6=axis_rot_1(x6,[0,1,0],[150,290,100],1)

# piston rod
x7=o_solid([0,0,1],circle(15),350,175,150,-290)
# x7=axis_rot_1(x7,[0,1,0],[150,290,100],1)

# cylinder top cover
x8=o_solid([0,0,1],circle(40),20,425,150,-290)
# x8=axis_rot_1(x8,[0,1,0],[150,290,100],1)

# c-clamp for hinge support
sec1=corner_radius(pts1([[-20,0,20],[40,0,20],[0,260,20],[-40,0,20]]),10)
sec1=equidistant_pathc(sec1,300)
sec2=offset(sec1,-19)

path1=corner_radius(pts1([[0,100],[0,-100,10],[70,0,10],[0,120]]),10)
path1=equidistant_path(path1,300)
path1=translate([0,0,0],q_rot(['x90','z90'],path1))
fold1=wrap_around(sec1,path1)

fold2=wrap_around(sec2,path1)
surf1=[fold1]+[fold2]
surf2=surf_offset(surf1,-5)
sol11=[surf1[1]]+[surf1[0]]+[surf2[0]]+[surf2[1]]
sol11=translate([150,255,520],sol11)
# sol11=axis_rot_1(sol11,[0,1,0],[550,290,590],10)
# sol11=axis_rot_1(sol11,[0,1,0],[170,290,670],-9)

# c-clamp for counterweight
x9=[surf1[1]]+[surf1[0]]+[surf2[0]]+[surf2[1]]
x9=translate([850,255,520],x9)

# catcher
arc1=c2t3(arc(200,-90,90,s=100))

sol12=path_extrude_open(circle(10),arc1)
sol12=translate([-1090,290,590],sol12)
# sol12=axis_rot_1(sol12,[0,1,0],[550,290,590],10)

# hinge pin c-clamp
sol13=o_solid([0,1,0],circle(5),100,240,150,590)
# sol13=axis_rot_1(sol13,[0,1,0],[550,290,590],10)

# hinge pin cylinder mounting
sol14=o_solid([0,1,0],circle(5),100,240,150,90)

# hinge pin long arm
sol15=o_solid([0,1,0],circle(5),140,220,550,590)

# hinge pin counterweight
x10=o_solid([0,1,0],circle(5),100,240,850,590)

# rod for counterweight
x11=o_solid([0,0,1],circle(15),300,225,850,-290)

# counterweight
s1=corner_radius(pts1([[100,20],[-120,0,19],[0,-40,19],[120,0]]),10)+arc_long_2p([100,-20],[100,20],100,1,50)

x12=o_solid([0,0,1],s1,100,235,850,-290,[90,0,0])

# support for counterweight

```

```

x13=o_solid([0,0,1],circle(100),10,225,850,-290)

# trolley wheel
s1=circle(15)
p1=q_rot(['x90'],circle(50))
wh=path_extrude_closed(s1,p1)
wh=align_sol_1(wh)
s2=circle(4)
p2=[[-50,0,0],[50,0,0]]
spk=[axis_rot([0,1,0],path_extrude_open(s2,p2),i) for i in linspace(0,360,6)[-1]]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
// frame
swp_c({sol1});
swp_c({sol2});
swp_c({sol3});
swp({sol7});
swp({sol8});

// hinge supports
swp({sol4});
swp({sol5});

for(i=[20,80])
translate([-400,i,-500])
swp({sol4});
swp_c({sol6});

//cylinder body
sol9={sol9};
%swp_c(sol9);
//cylinder bottom cover
x5={x5};
swp(x5);

//hinge for cylinder
swp({sol10});

//piston
x6={x6};
swp(x6);

color("cyan")
union(){
//piston rod
x7={x7};
swp(x7);

//cylinder top cover
x8={x8};
swp(x8);
}

// c-clamp for pivot point hinge support
sol11={sol11};
swp(sol11);

// catcher
sol12={sol12};
swp(sol12);

//hinge pin
sol13={sol13};
color("cyan")swp(sol13);

//hinge pin cylinder
sol14={sol14};
color("cyan")swp(sol14);

//hinge pin long arm
sol15={sol15};
color("cyan")swp(sol15);

//c-clamp for counterweight
x9={x9};
swp(x9);

// hinge pin counterweight
x10={x10};
color("cyan")swp(x10);

// rod for counterweight
x11={x11};
color("cyan")swp(x11);

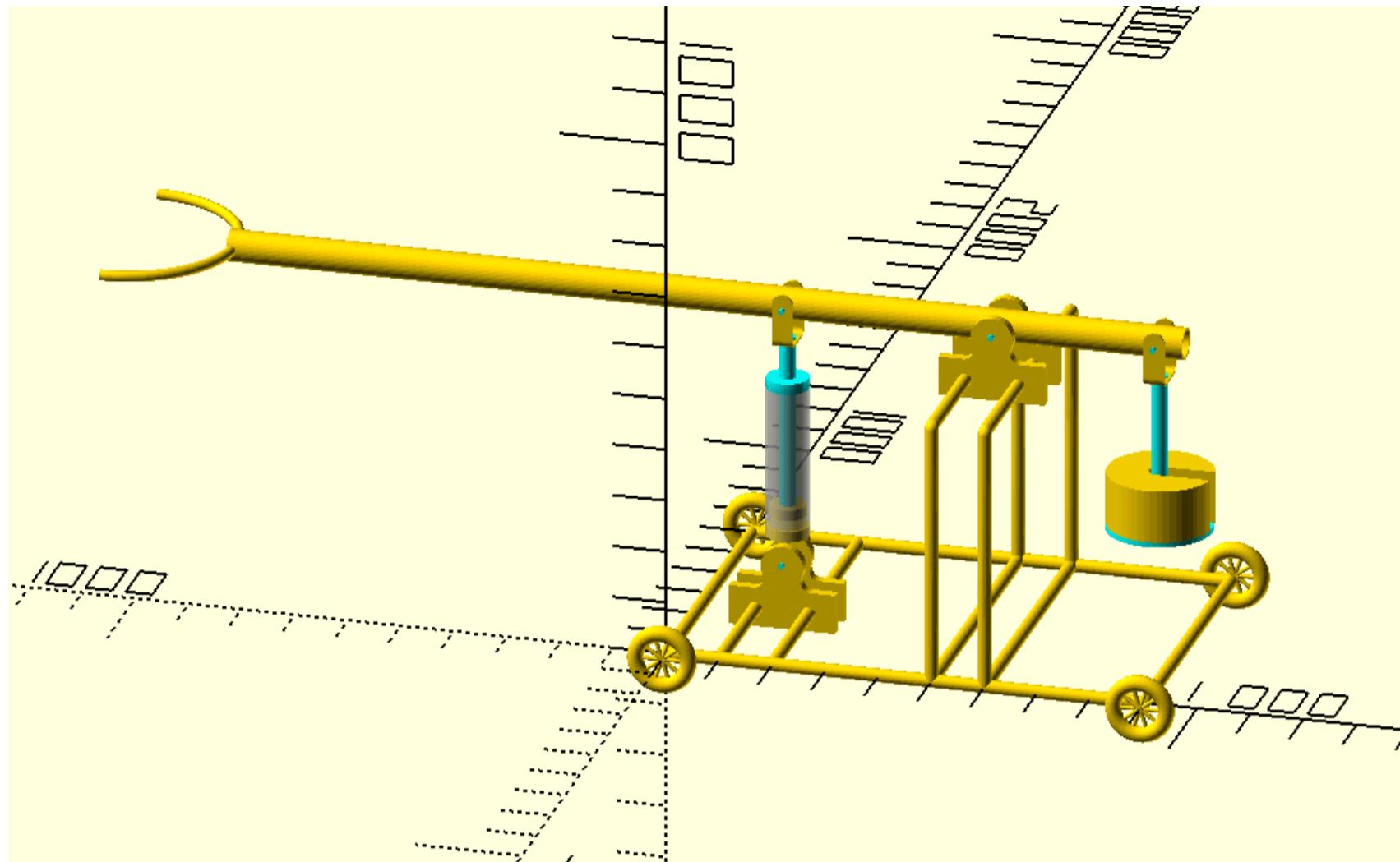
//counterweight
x12={x12};
swp(x12);

//counterweight
x13={x13};
color("cyan")swp(x13);

//trolley wheels
for(j=[0,900])
for(i=[-30,630])
translate([j,i,0]){


```

```
swp_c({wh});
for(p={spk})swp(p);
}
'''
```



r_sec

```
In [189... # example of function r_sec(r1,r2,cp1,cp2)
t0=time.time()

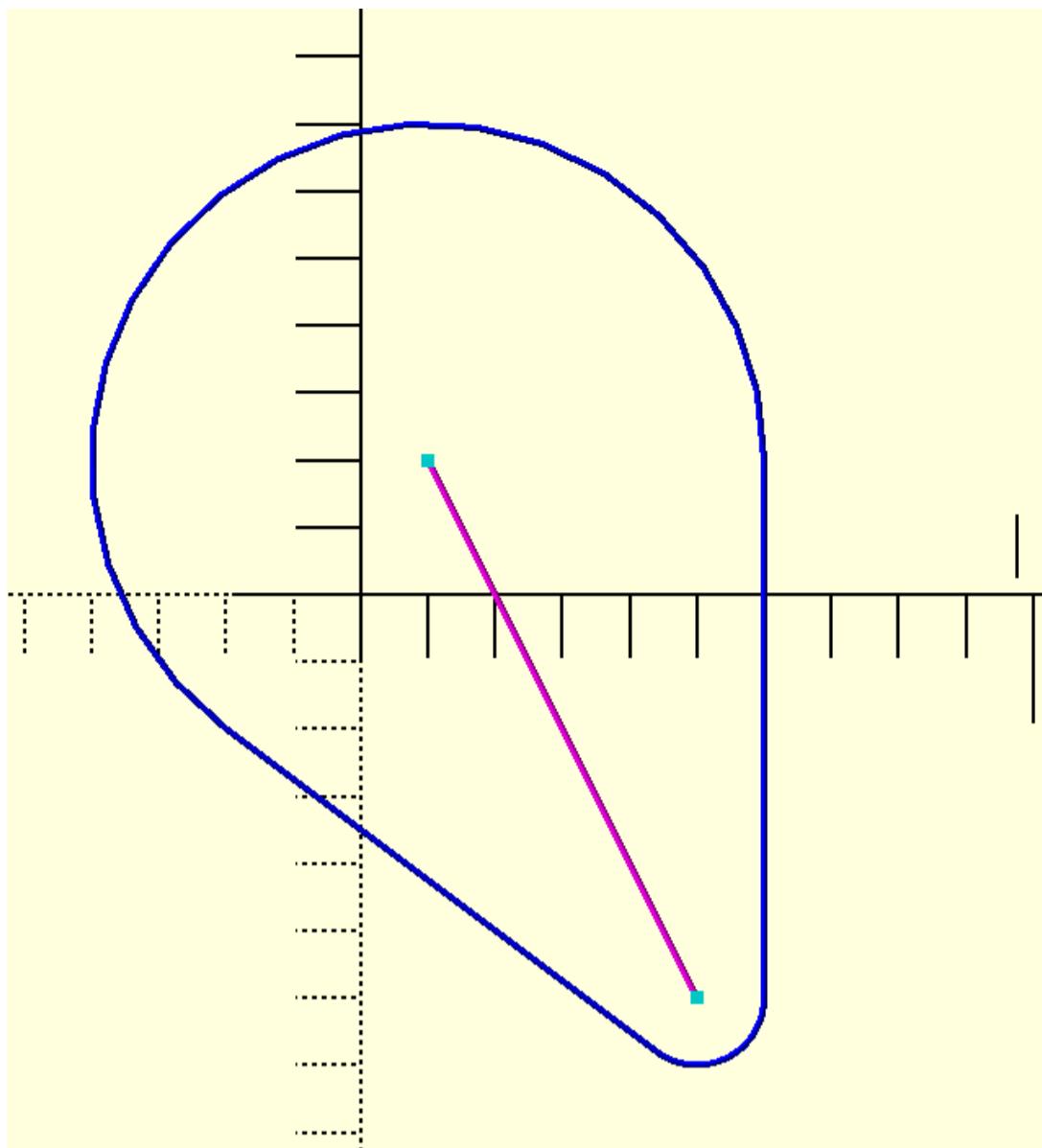
line=[[1,2],[5,-6]]
r1,r2=5,1

sec1=r_sec(r1,r2,line[0],line[1])

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line3dc({sec1},.1);
color("magenta")p_line3d({line},.1);
color("cyan")points({line},.2);

''')
t1=time.time()
t1-t0
```

```
Out[189... 0.004086017608642578
```



3d-knots

```
In [18]: # 3d knots various types
t0=time.time()
# trefoil knot

path=[[10*(sin(t)+2*sin(2*t)),
      10*(cos(t)-2*cos(2*t)),
      -10*sin(3*t)] for t in d2r(arange(0,360))]

# circular sin theta knot

# path=[[60*(cos(t)),
#        60*(sin(t)),
#        20*sin(4*t)*cos(4*t)] for t in d2r(arange(0,360))]

# random knot

# path=[[20*(-0.22*cos(t) - 1.28*sin(t) - 0.44*cos(3*t) - 0.78*sin(3*t)),
#        20*(-0.1*cos(2*t) - 0.27*sin(2*t) + 0.38*cos(4*t) + 0.46*sin(4*t)),
#        20*(0.7*cos(3*t) - 0.4*sin(3*t))] for t in d2r(arange(0,360))]

# torus knots

# path=[[10*cos(3*t)*(3+cos(4*t)),
#        10*sin(3*t)*(3+cos(4*t)),
#        10*sin(4*t)] for t in d2r(arange(0,360))]

# cinquefoil torus knots
a,p,q=3,11,12
d=10

# explanation
# radius of the torus = a*d
# section radius of the torus = d
# p in number of cycles of the wrapping coil over torus
# q in the number of turns of the wrapping coil over torus

path=[[d*cos(p*t)*(a+cos(q*t)),
      d*sin(p*t)*(a+cos(q*t)),
      -d*sin(q*t)] for t in d2r(arange(0,360,.25))]

# Lissajous knots

# path=[[10*cos(3*t+5),
#        10*cos(3*t+10),
#        10*cos(3*t+2)] for t in d2r(arange(0,360))]
r=2
sec=circle(r)
sol=align_sol_1(path_extrude_closed(sec,path))

sec1=circle(d-r)
path1=c2t3(circle(a*d))
sol1=path_extrude_closed(sec1,path1)
```

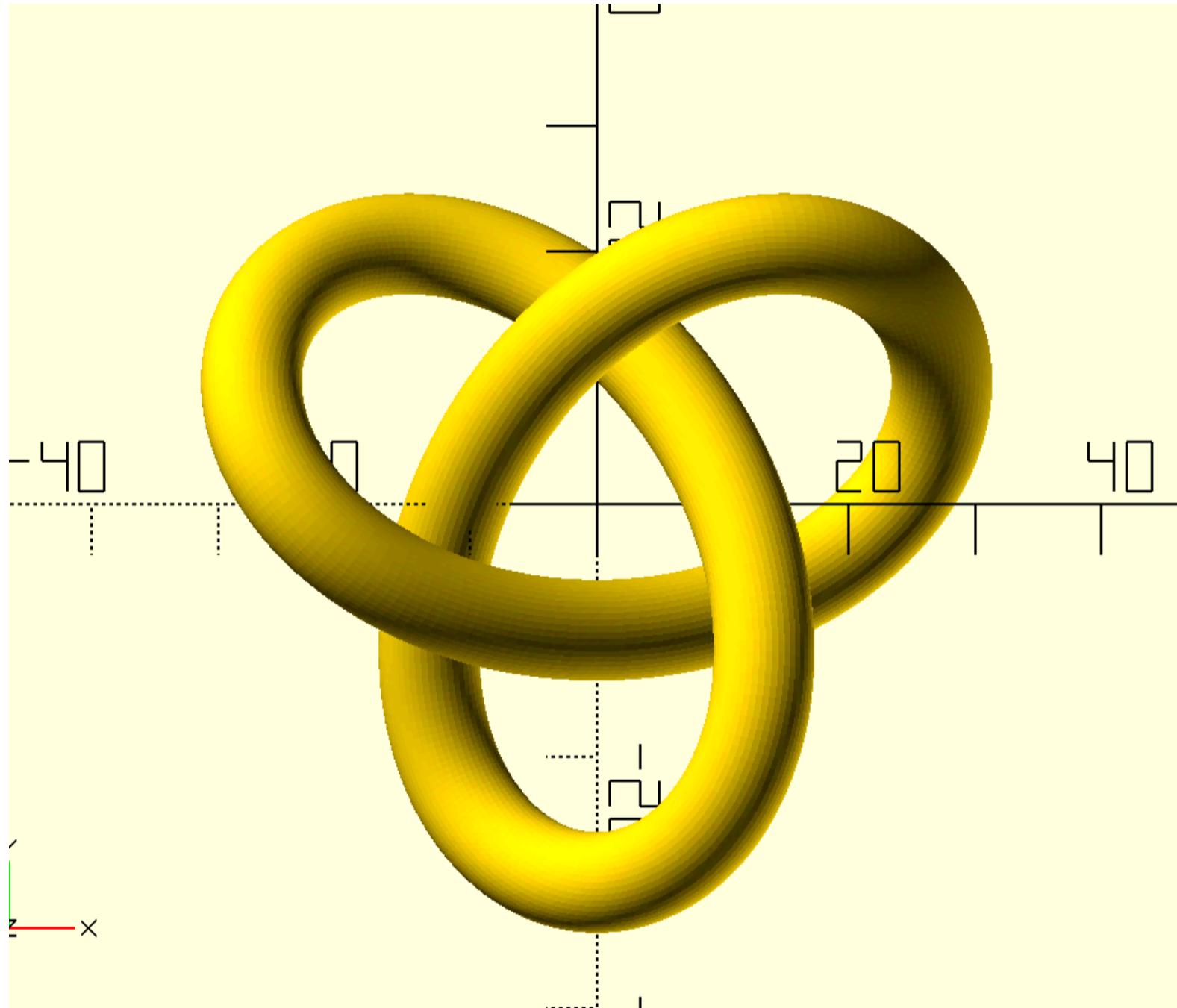
```
# sol2=o_solid([0,0,-1],circle(38),2,10)
# sol3=o_solid([0,0,-1],circle(20),2,10)
# sol2=swp_prism_h(sol2,sol3)

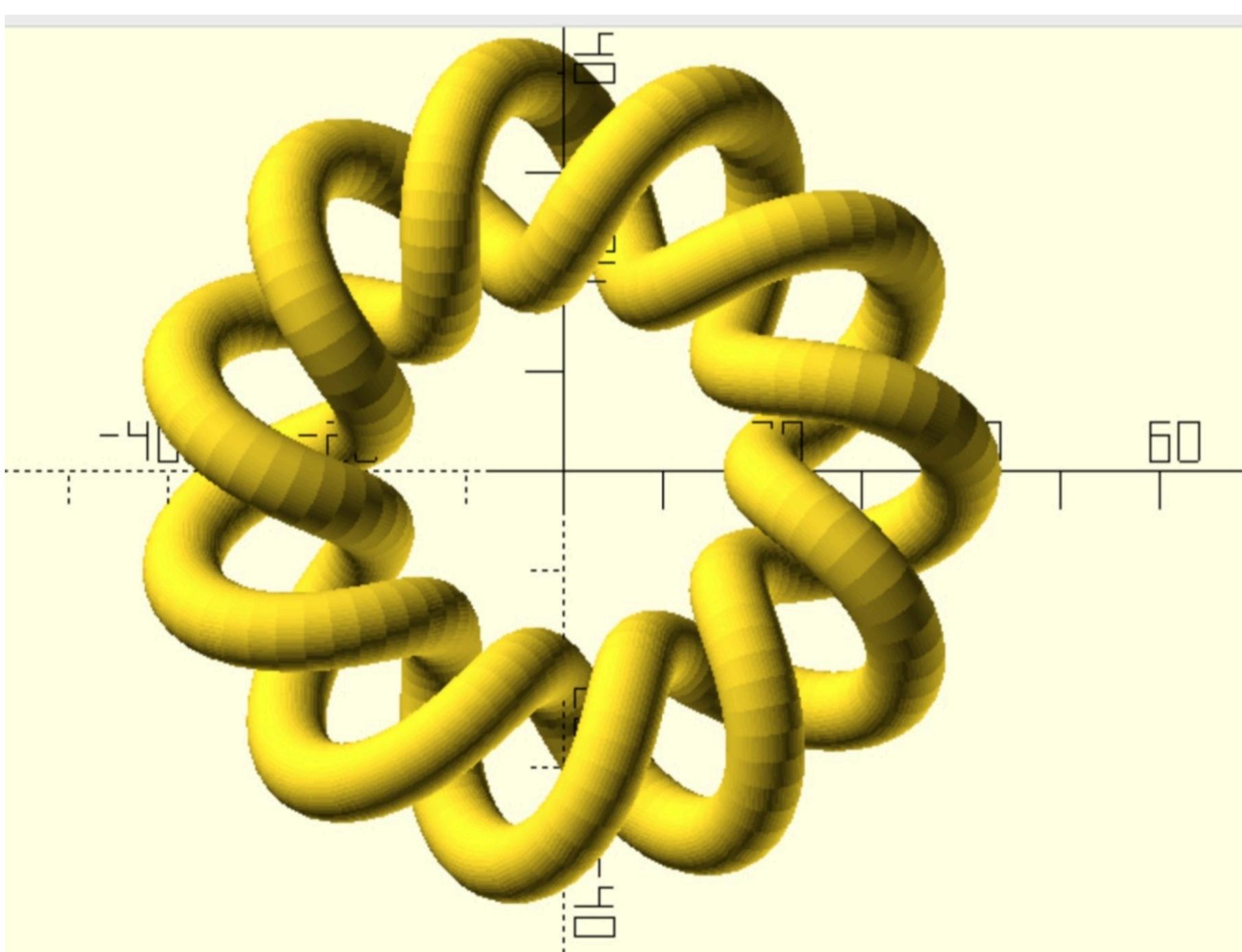
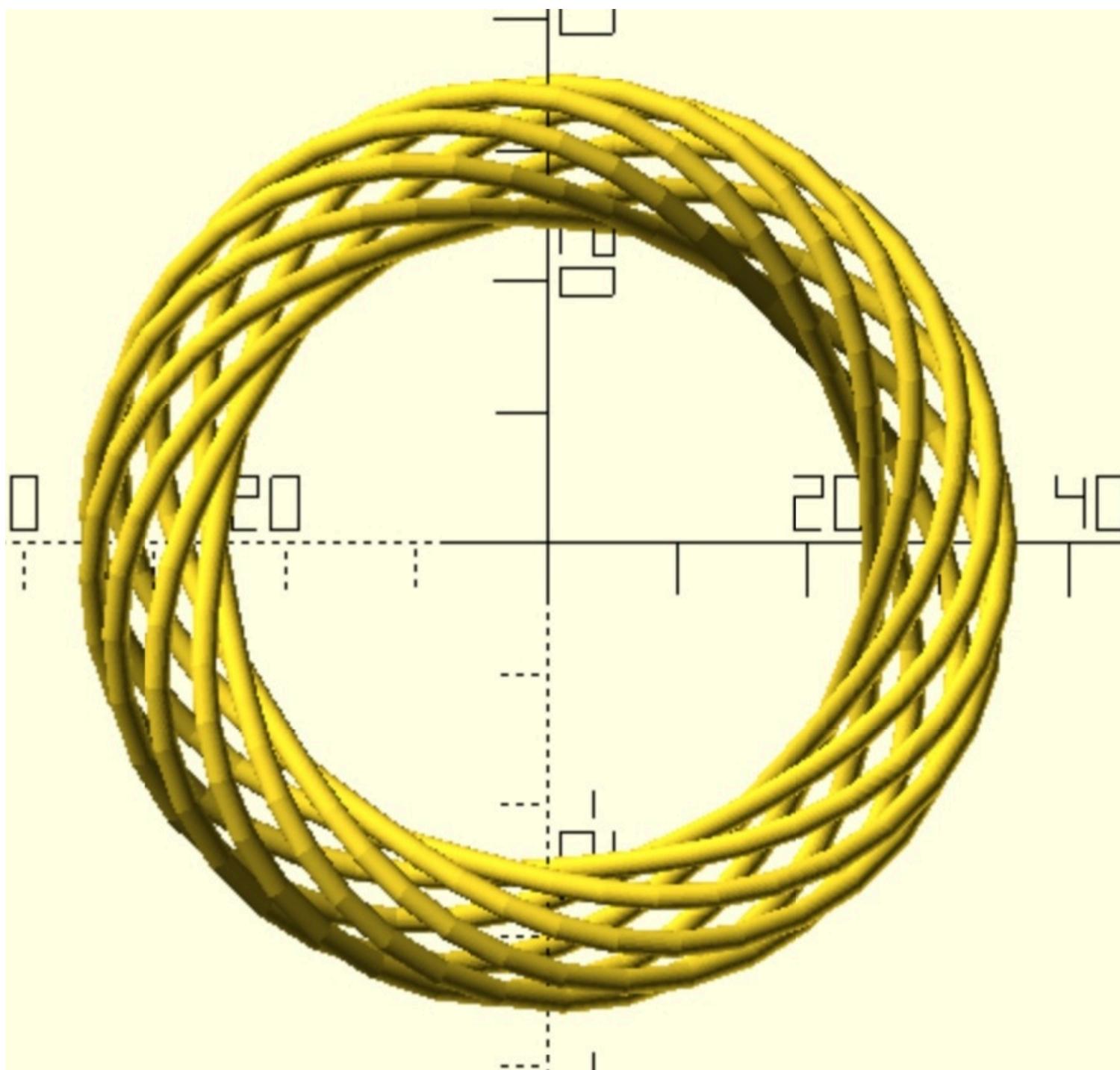
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
difference(){{{
{swp(sol)}
//{swp(cut_plane([0,-1,0],[100,100],100))}

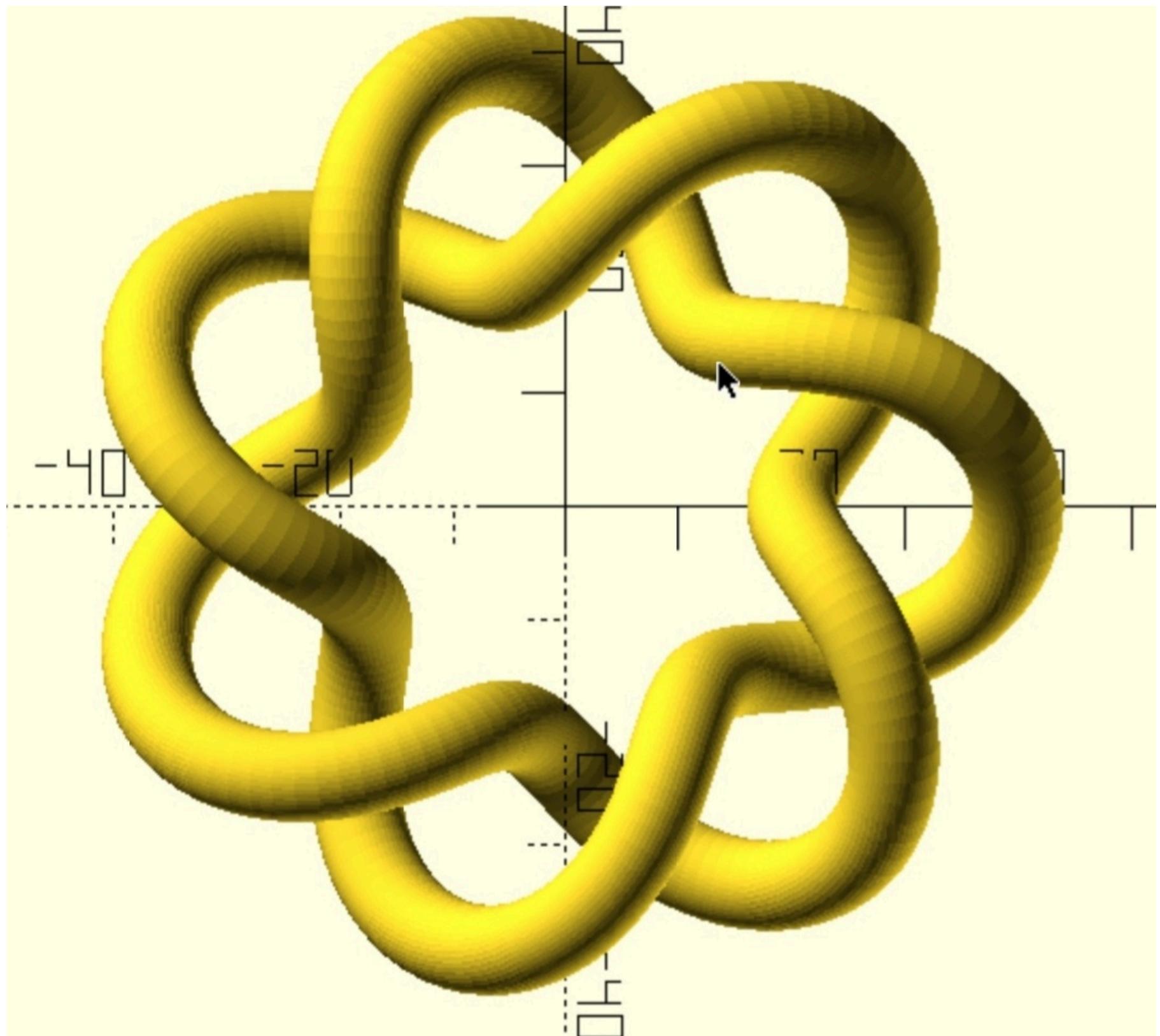
}}}

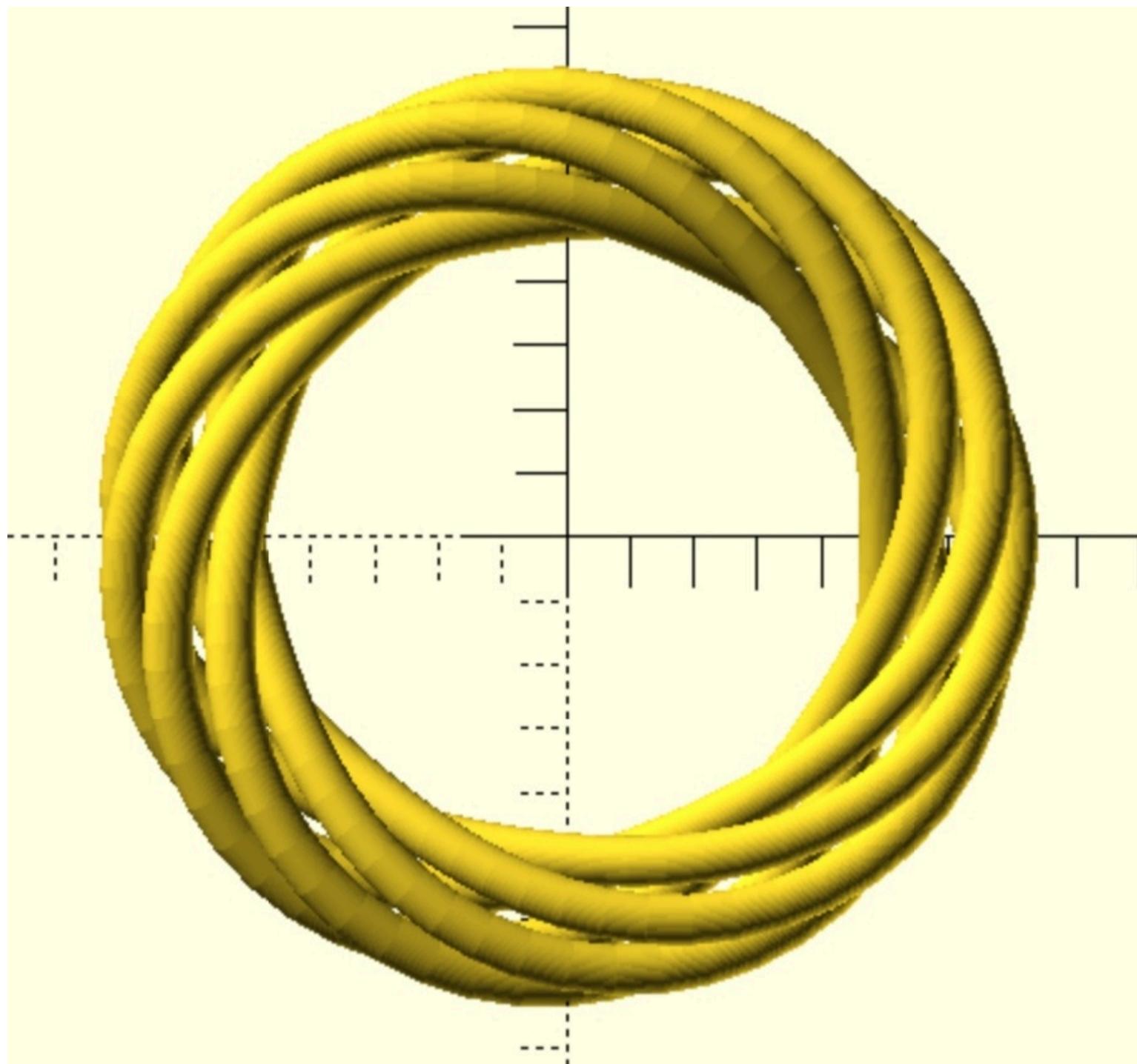
...)
t1=time()
t1-t0
```

Out[18]: 3.011662006378174





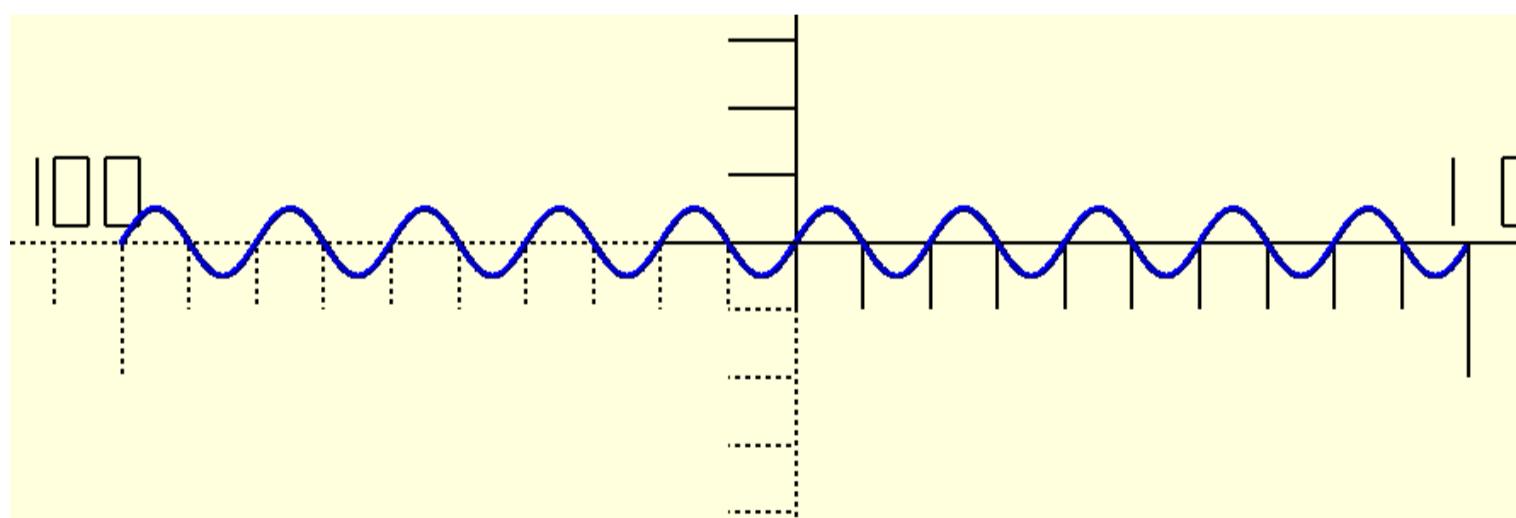




```
In [179... # sinwave
length=200
starting_point=-100
number_of_waves=10
amplitude=5
a=[[r2d(i)/360*length+starting_point,amplitude*sin(number_of_waves*i)] for i in d2r(arange(0,360))]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line3d({a},1);

...)
```



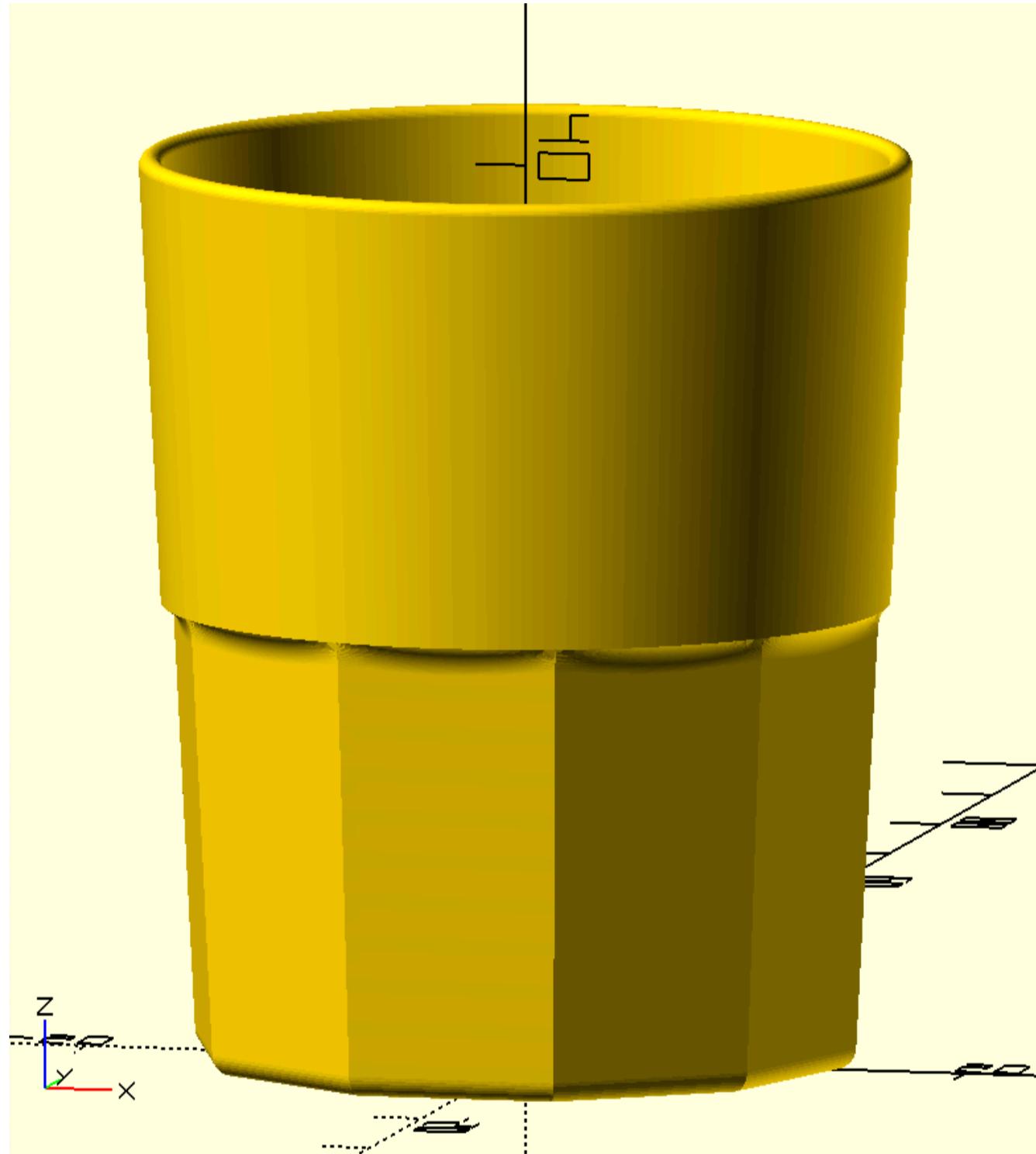
glass-model

```
In [9]: # glass model
r=15
a1=1/20 #taper of the glass
h1=20
h2=20
s1=10
cir1=circle(r,s=s1+1)
path1=corner_radius(pts1([[-1,0],[1,0,1],[a1*h1,h1]]),10)
sol1=prism(cir1,path1)
sol1=align_sol_1([equidistant_path(p,200) for p in sol1])
sol1=slice_sol(sol1,30)
cir2=circle((r+a1*h1)/cos(d2r(360/(s1+1)/4)),s=201)
```

```

path2=corner_radius(pts1([[0,h1+.25],[a1*h2,h2,.49],[-1,0,.49],[-a1*h2,-h2,.5],[-.5,-.5,.5],[-a1*(h1-3),-(h1-3),1],[-2,0]]),10)
sol2=prism(cir2,path2)
sol3=sol1+sol2
p0=sol1[-1]
p1=sol2[0]
p2=sol1[-2]
fill=convert_3lines2fillet(p2,p1,p0,s=30)
fill=fill+[fill[0]]
sec=square(100,center=True)
cut1=o_solid([0,-1,0],sec,100,theta=[0,0,10])
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
difference() {{
union() {{
{swp(sol3)}
{swp_c(fill)}
}}
{swp(cut1)}
}}
''' )

```



`q(vector=[1,0,0],point=[0,5,0],theta=0)`

In [2]: `q(vector=[1,0,0],point=[0,5,0],theta=90)`

Out [2]: [0.0, 8.881784197001252e-16, 5.0]

`q_rot`

```

In [10]: line=[[0,0,0],[10,0,0]]
line1=q_rot(['z30','x90'],line)

pnt=[20,0]
pnt1=q_rot(['z45'],pnt)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

p_line3d({line},1);
color("blue")p_line3d({line1},1);
color("magenta")points({{pnt}},1);
color("magenta")points({{pnt1}},1);

```

```
'''
```

ang(x,y)

```
In [196... # example of function ang(x,y)
pnt=[20,0]
pnt1=q_rot(['z125'],pnt)
ang(pnt1[0],pnt1[1])
```

```
Out[196... 125.0
```

l_len

```
In [197... l_len([[0,0,0],[10,0,0]])
```

```
Out[197... 10.0
```

l_lenv

```
In [198... l_lenv([[0,0,0],[10,0,0],[10,5,0],[0,5,0]])
```

```
Out[198... 30.0
```

l_lenv_o

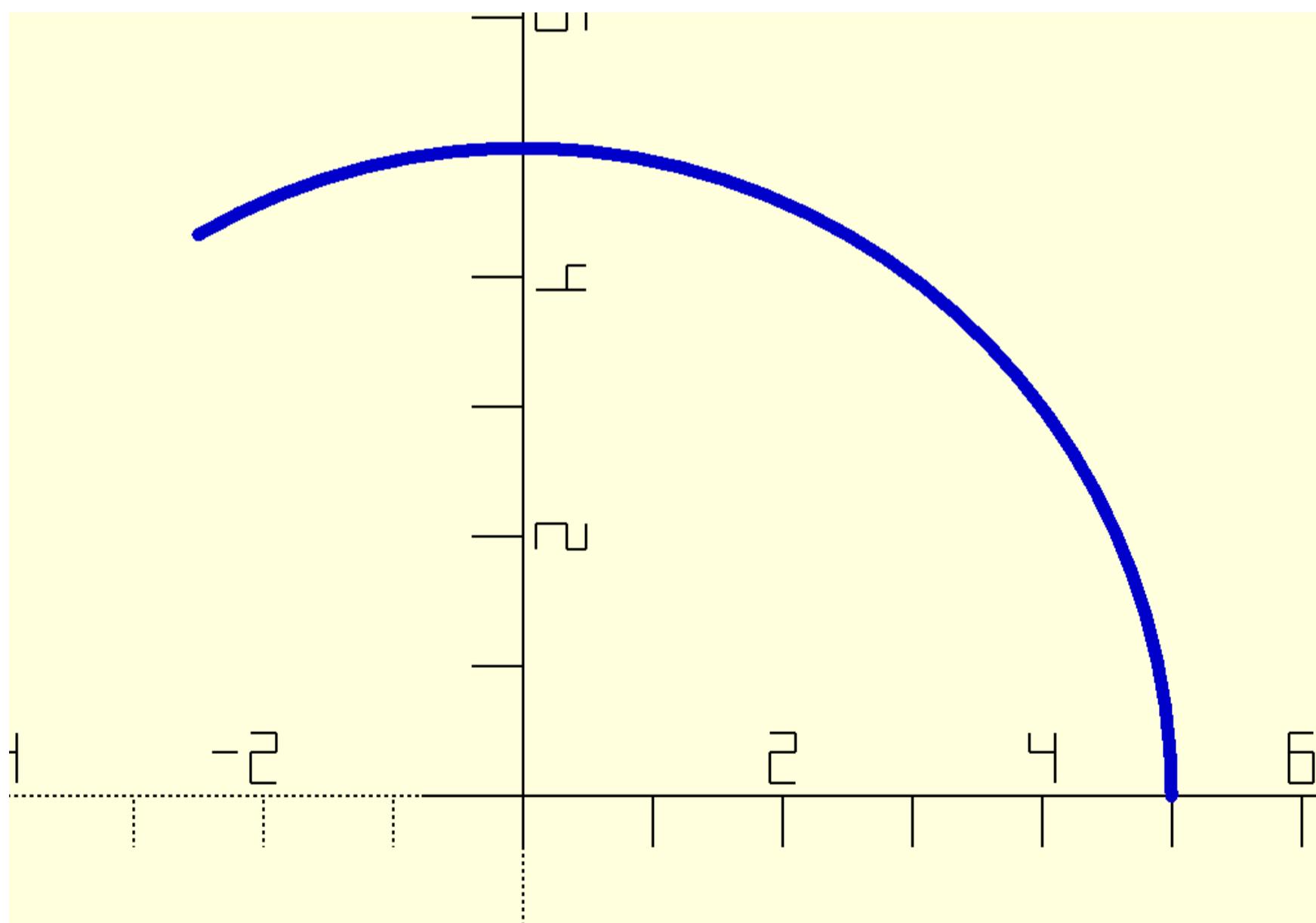
```
In [199... l_lenv_o([[0,0,0],[10,0,0],[10,5,0],[0,5,0]])
```

```
Out[199... 25.0
```

arc

```
In [200... arc1=arc(radius=5,start_angle=0,end_angle=120,cp=[0,0],s=30)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("blue")p_lineo({arc1},.1);
'''')
```



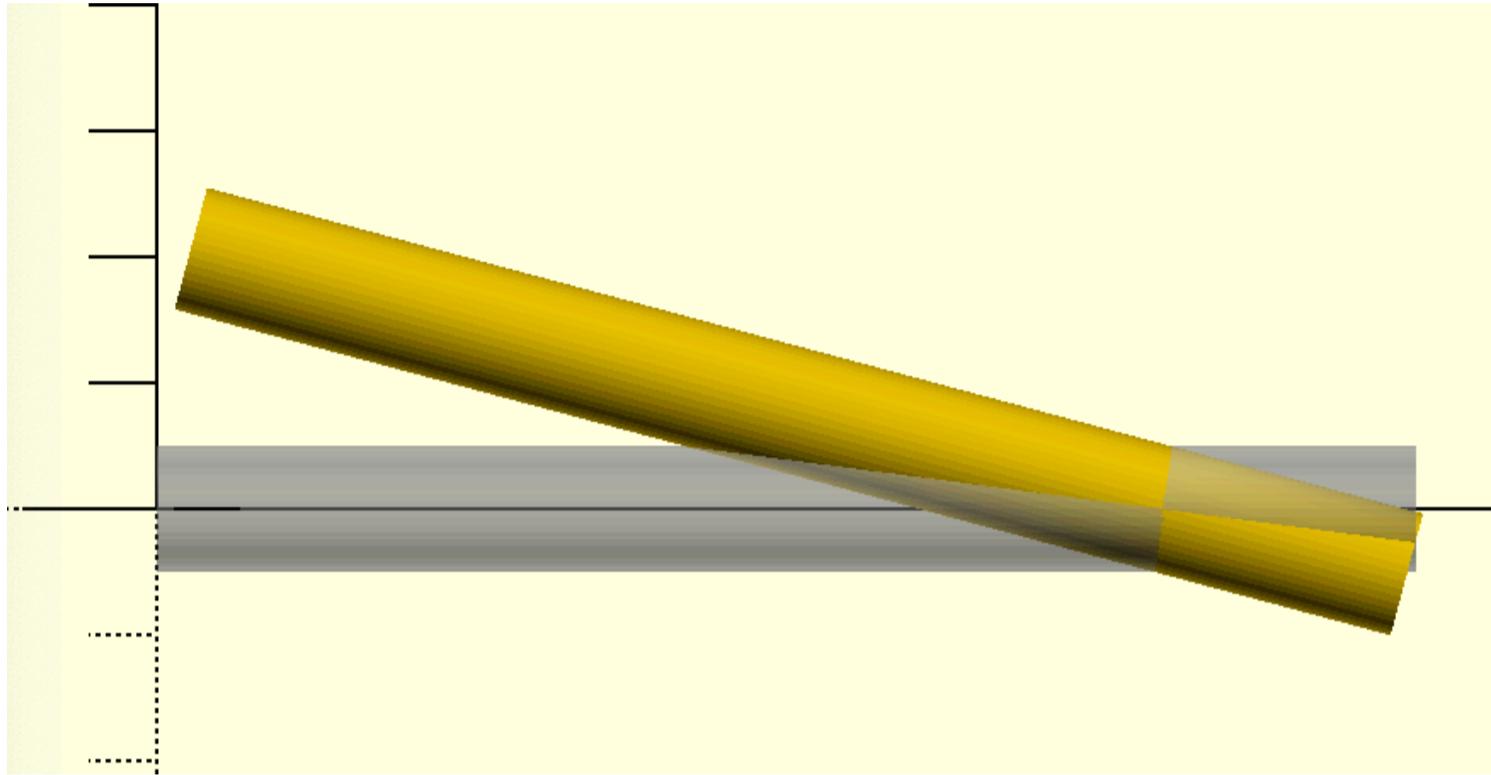
pts

```
In [201... # calculates the cumulative sum of points
pts([[0,0],[4,0],[2,3],[5,-8]])
```

```
Out[201]: [[0, 0], [4, 0], [6, 3], [11, -5]]
```

axis_rot_1

```
In [11]: sol=o_solid([1,0,0],circle(5),100)
sol1=axis_rot_1(sol,[0,1,0],[80,0,0],15)
with open('trial.scad','w+') as f:
    f.write(f'''  
include<dependencies2.scad>  
  
%{swp(sol)}  
{swp(sol1)}  
'''')
```

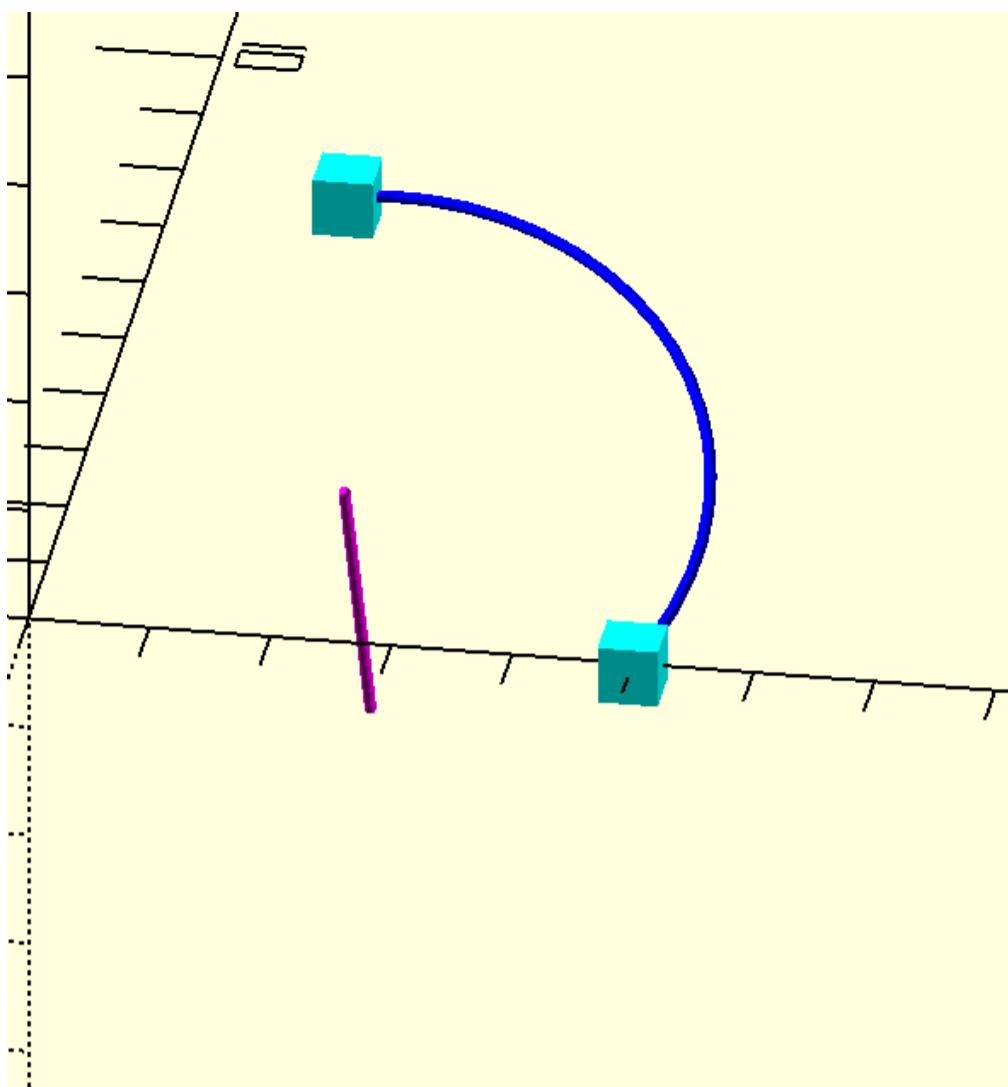


arc_2p_3d

arc_2p_3p_cp

```
In [9]: '''
    draws an arc through 2 points
    n1: normal vector to define plane on which the arc will be drawn
    r: radius of the arc
    cw: '1' stands for clockwise and '-1' stands for counter-clockwise
    's' is the number of segments of the circle
'''  
  
p0=[5,0,0]
p1=[2,4,2]
p2=[0,0,0]
n1=nv([p0,p1,p2])
n2=(array(n1)*3).tolist()
arc1=arc_2p_3d(n1,p0,p1,3,-1)
cp=arc_2p_3d_cp(n1,p0,p1,3,-1)
n_line=[cp,(array(cp)+array(n2)).tolist()]
  
  
with open('trial.scad','w+') as f:
    f.write(f'''  
include<dependencies2.scad>
color("blue")p_line3d({arc1},.1);
color("magenta")p_line3dc({n_line},.1);
color("cyan")points({[p0,p1]},.5);
'''')
n1
```

```
Out[9]: [0.0, 0.4472135954999579, -0.8944271909999159]
```



c2t3

```
In [10]: # function to convert 2d to 3d, it just adds the z-coordinate to the points list
#     example:
list=c2t3([[1,2],[3,4],[6,7]])
list
```

```
Out[10]: [[1, 2, 0], [3, 4, 0], [6, 7, 0]]
```

c3t2

```
In [187... # function to convert 3d to 2d, it just removes the z-coordinate from the points list
#     example:
list=c3t2([[1,2,3],[3,4,5],[6,7,8]])
list
```

```
Out[187... [[1, 2], [3, 4], [6, 7]]]
```

nv

```
In [188... # given 3 points ['p1','p2',p3] function calculates unit normal vector
#     example:
p1,p2,p3=[1,0,0],[0,10,0],[-5,0,0]
nv([p1,p2,p3]) #=> [0.0, 0.0, -1.0]

```

```
Out[188... [0.0, 0.0, -1.0]]
```

cytz

```
In [189... #     function to convert the y co-ordinates to z co-ordinates e.g. [x,y]>[x,0,y]. 2d to 3d coordinate system
list=cytz([[1,2],[3,4],[6,7]])
list
```

```
Out[189... [[1, 0, 2], [3, 0, 4], [6, 0, 7]]]
```

d2r

```
In [190... # function to convert from degrees to radians
d2r(90)
```

```
Out[190... 1.5707963267948966]
```

r2d

```
In [191... # function to convert from radians to degrees
r2d(1.57079)
```

```
Out[191... 89.99963750135457]
```

flip

```
In [11]: # function to flip the sequence of a list or a list of points
#     example:
list=[1,2,3,4,5]
flipped_list1=flip(list) #=> [5, 4, 3, 2, 1]

list=[[1,2,3],[4,5,6],[7,8,9]]
flipped_list2=flip(list) #=> [[7, 8, 9], [4, 5, 6], [1, 2, 3]]
flipped_list1, flipped_list2
```

```
Out[11]: ([5, 4, 3, 2, 1], [[7, 8, 9], [4, 5, 6], [1, 2, 3]])
```

gcd

```
In [212...]: # calculates the greatest common divisor of 2 numbers 'a','b'
gcd(12,15)
```

```
Out[212...]: 3
```

lcm

```
In [213...]: # calculates the least common multiple of 2 numbers 'a','b'
lcm(12,15)
```

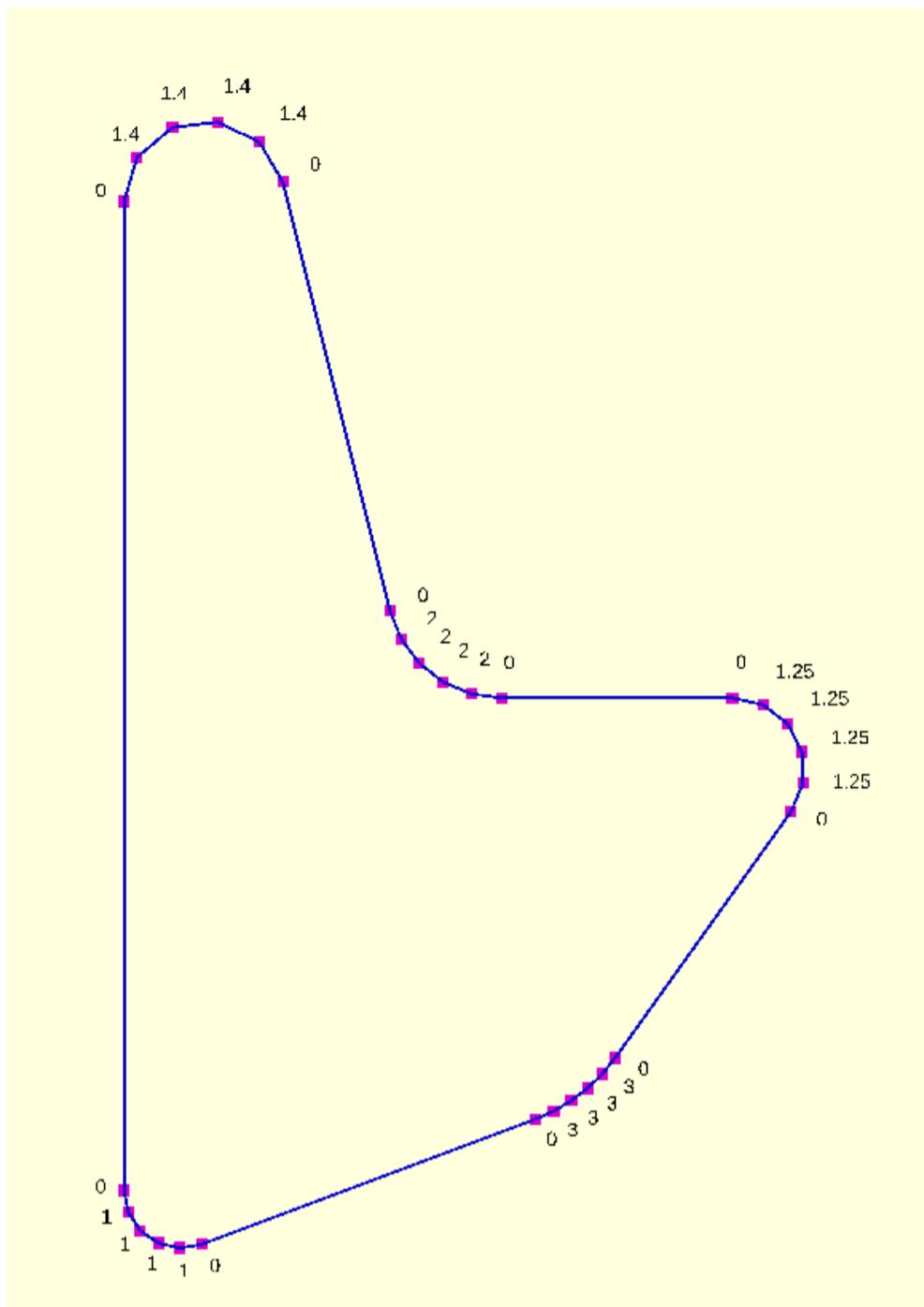
```
Out[213...]: 60.0
```

list_r

```
In [57]: #     function list the corner radiiuses of a given section (only where the radius is specified)
#     example:
sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1.25],[-8,0,2],[-5,20,1.4]]),5)
r1=list_r(sec)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
sec={sec};
r1={r1.tolist()};
color("blue")p_line({sec},.05);
color("magenta")points({sec},.2);
color("black")for(i=[0:len(sec)-1])translate({offset(sec,.5)}[i])text(str(r1[i]),.25);

''' )
r1
```

```
Out[57]: array([0. , 1. , 1. , 1. , 1. , 0. , 0. , 3. , 3. , 3. , 3. ,
 0. , 0. , 1.25, 1.25, 1.25, 1.25, 0. , 0. , 2. , 2. , 2. ,
 2. , 0. , 0. , 1.4 , 1.4 , 1.4 , 1.4 , 0. ])
```



ls(line,n)

```
In [194...]: # function to draw number of points 'n' in a line 'line'
#   example:
line=[[0,0],[10,0]]
line1=ls(line,5) #=> [[0.0, 0.0], [2.0, 0.0], [4.0, 0.0], [6.0, 0.0], [8.0, 0.0], [10.0, 0.0]]
line1
```

```
Out[194...]: [[0.0, 0.0], [2.0, 0.0], [4.0, 0.0], [6.0, 0.0], [8.0, 0.0]]
```

max_r(sec)

```
In [195...]: # function calculates the maximum radius in a given closed section
#   example:
sec=cr_c(pts1([[0,0,.2],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)
max_r(sec) #=> 3.0
```

```
Out[195...]: 3.0
```

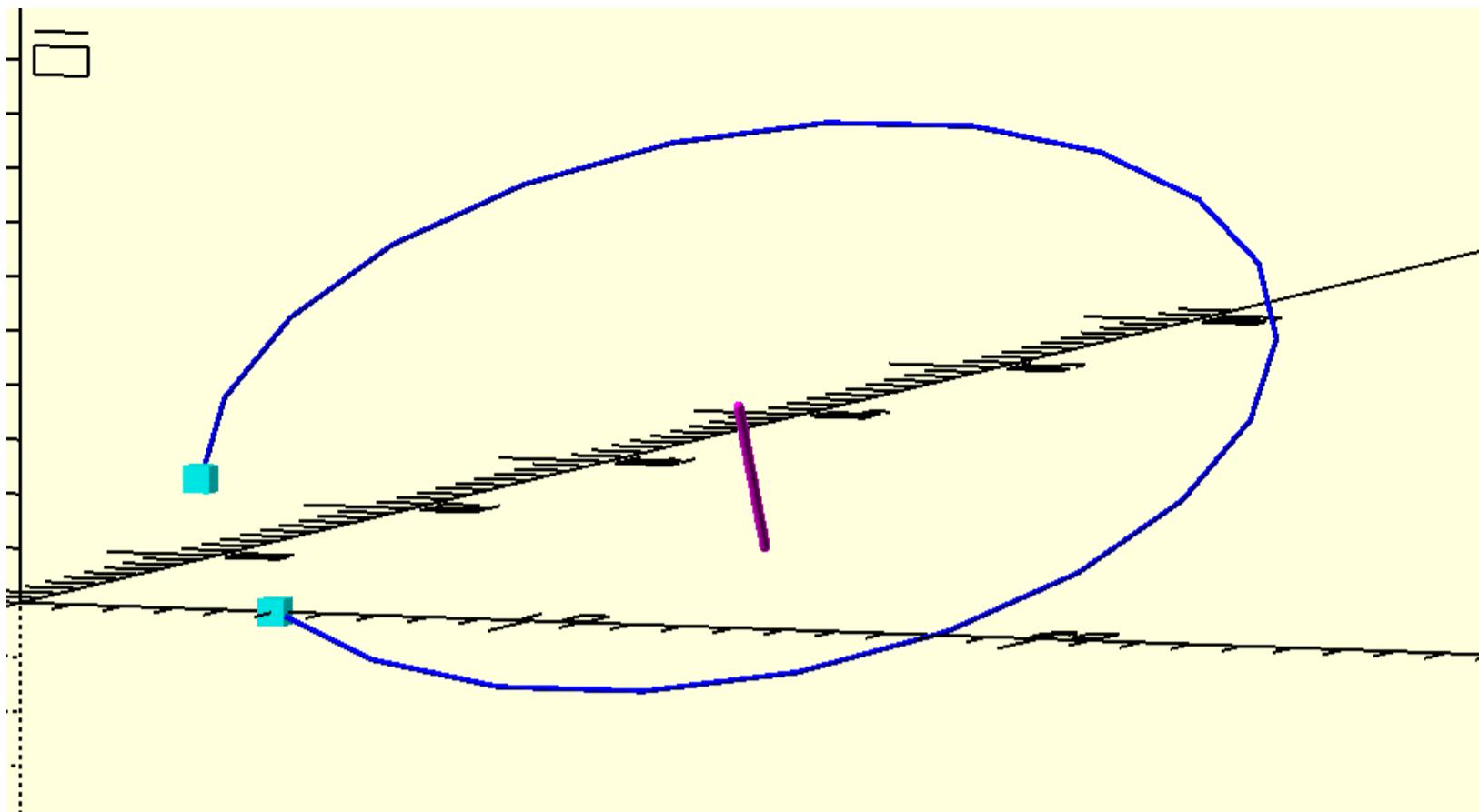
arc_long_2p_3d

```
In [14]: # draws a long arc through 2 points
#   n1: normal vector to define plane on which the arc will be drawn
#   r: radius of the arc
#   cw: '1' stands for clockwise and '-1' stands for counter-clockwise
#   's' is the number of segments of the circle

p0=[5,0,0]
p1=[2,4,2]
p2=[0,0,0]
n1=inv([p0,p1,p2])
n2=(array(n1)*3).tolist()
arc1=arc_long_2p_3d(n1,p0,p1,10,-1)

cp=arc_2p_3d_cp(n1,p0,p1,10,1)
n_line=[cp,(array(cp)+array(n2)).tolist()]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line3d({arc1},.1);
color("magenta")p_line3dc({n_line},.2);
color("cyan")points({[p0,p1]}),.5;
''' )
```



```
In [41]: t0=time.time()

sec=pts([[0,0],[5,0],[0,5],[-5,0]])
path=corner_radius(pts1([[-2.5,0],[2.5,0,0.25],[0,5.01,0.25],[-2.5,0]]),10)
sol=f_prism(sec,path)

v1=[2,0,7]
sec1=axis_rot([0,0,1],circle(1.5,s=100),90)
sol1=o_solid(v1,sec1,10,-1.5,-2.5,0)
sol2=[ip_sol2line(sol,p)[0] if ip_sol2line(sol,p)!=[] else p[1] for p in cpo(sol1) ]

sol2=translate([.01,0,0.01],[sol1[0]]+[sol2])
fillet1=fillet_sol2sol(sol,sol2,.3,o=1)[:;-2]
fillet1=flip(fillet1)

sol3=[ip_sol2line(sol,p)[0] if ip_sol2line(sol,p)!=[] else p[1] for p in cpo(flip(sol1)) ]
sol3=[flip(sol1)[0]]+[sol3]
sol3=translate([0.01,0,-.01],sol3)
fillet2=fillet_sol2sol(sol,sol3,.3)[1:-2]

fillet3=fillet1+fillet2+[fillet1[0]]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

{swp(sol)}
{swp(sol1)}
{swp_c(fillet3)}
//{swp_c(fillet2)}
//color("blue")p_line3dc({fillet1[0]},.05);
//color("blue")p_line3dc({fillet2[0]},.05);

'''')
t1=time.time()
t1-t0
```

Out[41]: 0.5353126525878906

ang_2lineccw

```
In [16]: p0=[0,0]
p1=[5,2]
p2=[7,8]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

// case 1: counter-clockwise angle between line p1p0 and p1p2 is 229.76 degrees
color("blue")points({[p0,p1,p2]},.2);
color("cyan")p_line3d({[p0,p1,p2]},.1);
color("magenta")translate([0,-.5]){{translate({p0})text("p0",.5);
translate({p1})text("p1",.5);
translate({p2})text("p2",.5);
}};

// case 2: counter-clockwise angle between line p0p1 and p0p2 is 27.01 degrees
translate([10,0,0]){{color("blue")points({[p0,p1,p2]},.2);
color("cyan")p_line3d({[p1,p0,p2]},.1);

color("magenta")translate([0,-.5]){{translate({p0})text("p0",.5);
translate({p1})text("p1",.5);}};
```

```

translate({p2})text("p2",.5);
}
}

'''')
ang_2lineccw(p1,p0,p2),ang_2lineccw(p0,p1,p2)

```

Out[16]: (229.76364169072616, 27.012665347938547)

ang_2linecw

```

In [17]: p0=[0,0]
p1=[5,2]
p2=[7,8]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

// case 1: clockwise angle between line p1p0 and p1p2 is 130.23 degrees
color("blue")points({[p0,p1,p2]},.2);
color("cyan")p_line3d({[p0,p1,p2]},.1);
color("magenta")translate([0,-.5]){
    translate({p0})text("p0",.5);
    translate({p1})text("p1",.5);
    translate({p2})text("p2",.5);
}

// case 2: clockwise angle between line p0p1 and p0p2 is 332.98 degrees

translate([10,0,0]){
    color("blue")points({[p0,p1,p2]},.2);
    color("cyan")p_line3d({[p1,p0,p2]},.1);

    color("magenta")translate([0,-.5]){
        translate({p0})text("p0",.5);
        translate({p1})text("p1",.5);
        translate({p2})text("p2",.5);
    }
}

'''')
ang_2linecw(p1,p0,p2),ang_2linecw(p0,p1,p2)

```

Out[17]: (130.23635830927384, 332.98733465206146)

cir_2p

cp_arc

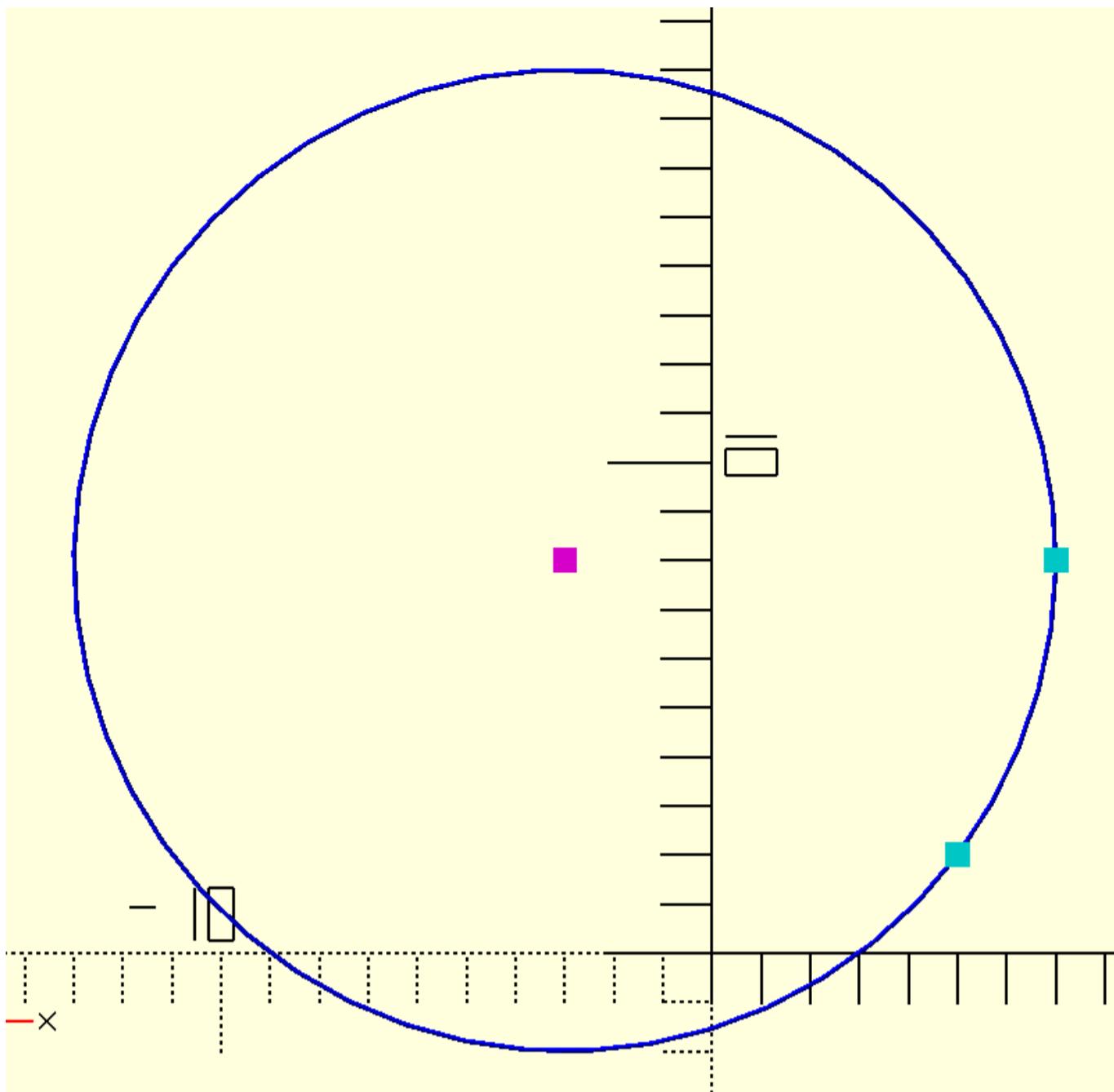
```

In [18]: p1=[5,2]
p2=[7,8]
r=10
c1=cir_2p(p1,p2,r,cw=-1,s=50)
cp1=cp_arc(c1)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("cyan")points({[p1,p2]},.5);
color("blue")p_line3dc({c1},.1);
color("magenta")points({[cp1]},.5);

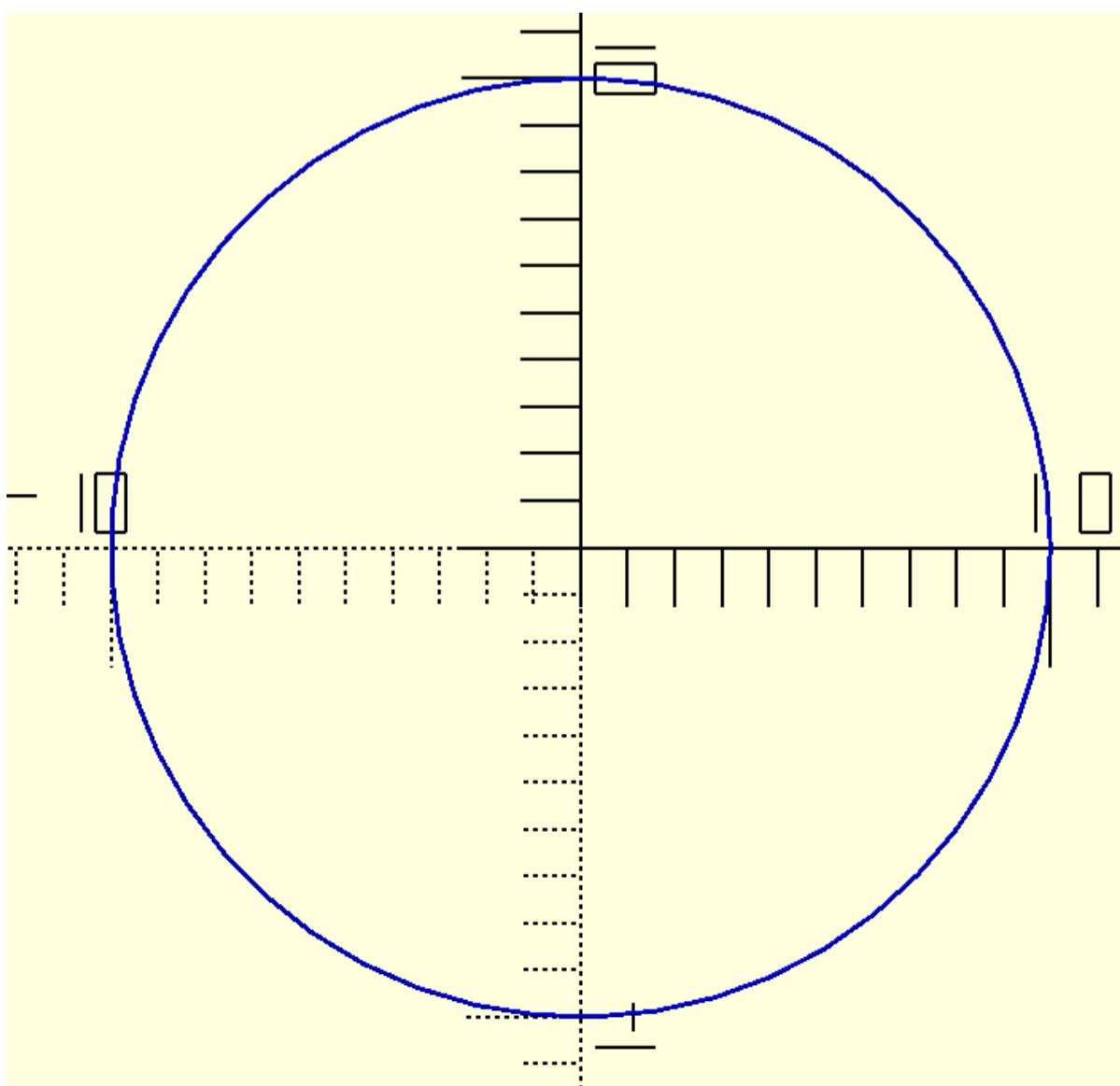
'''')

```



circle

```
In [201]: c1=circle(r=10,cp=[0,0],s=50)
with open('trial.scad','w+') as f:
    f.write(f'''')
include<dependencies2.scad>
color("blue")p_line3dc({c1},.1);
'''')
```



CW

```
In [202]: sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)  
cw(sec)
```

Out[202... -1

CWV

```
In [112]: sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),20)  
array(cwv(sec))
```

exclude_points

```
In [204]: p0=[[ 0,  1,  2],[ 3,  4,  5],[ 6,  7,  8],[ 9, 10, 11],[12, 13, 14],[15, 16, 17],  
[18, 19, 20], [21, 22, 23],[24, 25, 26], [27, 28, 29]]  
  
p1=[[0,1,2],[9,10,11]]  
  
p2=exclude_points(p0,p1)  
p2
```

```
Out[204...]: [[3, 4, 5],  
 [6, 7, 8],  
 [12, 13, 14],  
 [15, 16, 17],  
 [18, 19, 20],  
 [21, 22, 23],  
 [24, 25, 26],  
 [27, 28, 29]]
```

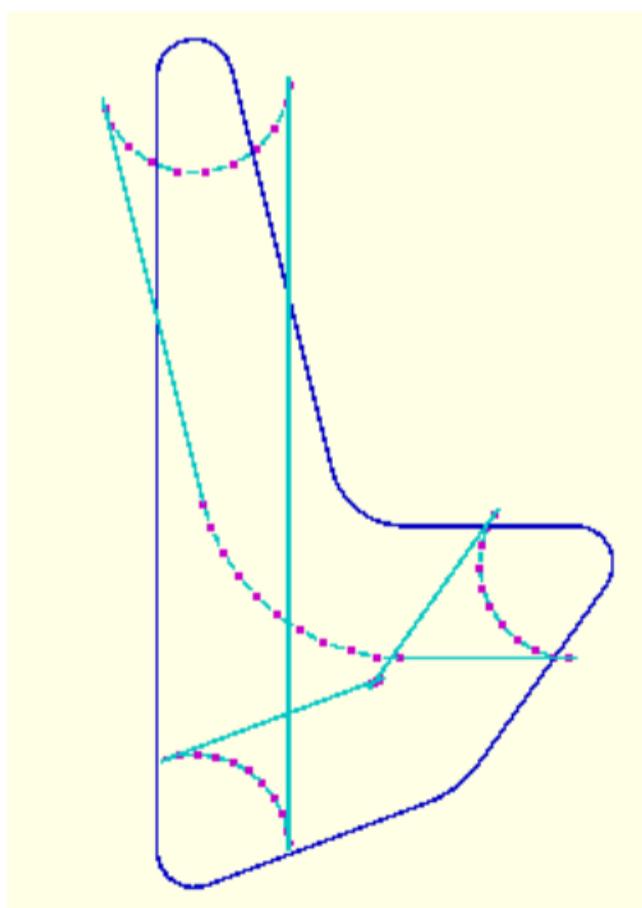
intersections

```
In [44]: sec=corner_radius(pts1([[0,0,1],[8,3,3],[5,7,1],[-8,0,2],[-5,20,1]]),10)
# sec=sec=corner_radius(pts1([[0,0,.1],[7,5,2],[5,7,2],[-5,7,2],[-7,5,3]]),20)
# sec=corner_radius(pts1([-15,0,2.49],[0,15,3],[30,0,3],[0,-15,2.49],[5,0,2.49],[0,20,7],[-40,0,7],[0,-20,2.49])),20)
# sec=circle(10)
# sec=pts([[0,0],[10,0],[0,10],[-10,0]])

offset_line_segments=offset_segv(sec,-3.5)
intersection_points=intersections(offset_line_segments)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")p_line({sec},.1);
color("cyan")for(p={offset_line_segments})p_line(p,.1);
color("magenta")points({intersection_points},.2);

''' )
```



```
In [12]: c1=c2t3(circle(10))
c2=translate([0,0,10],circle(5,s=70))

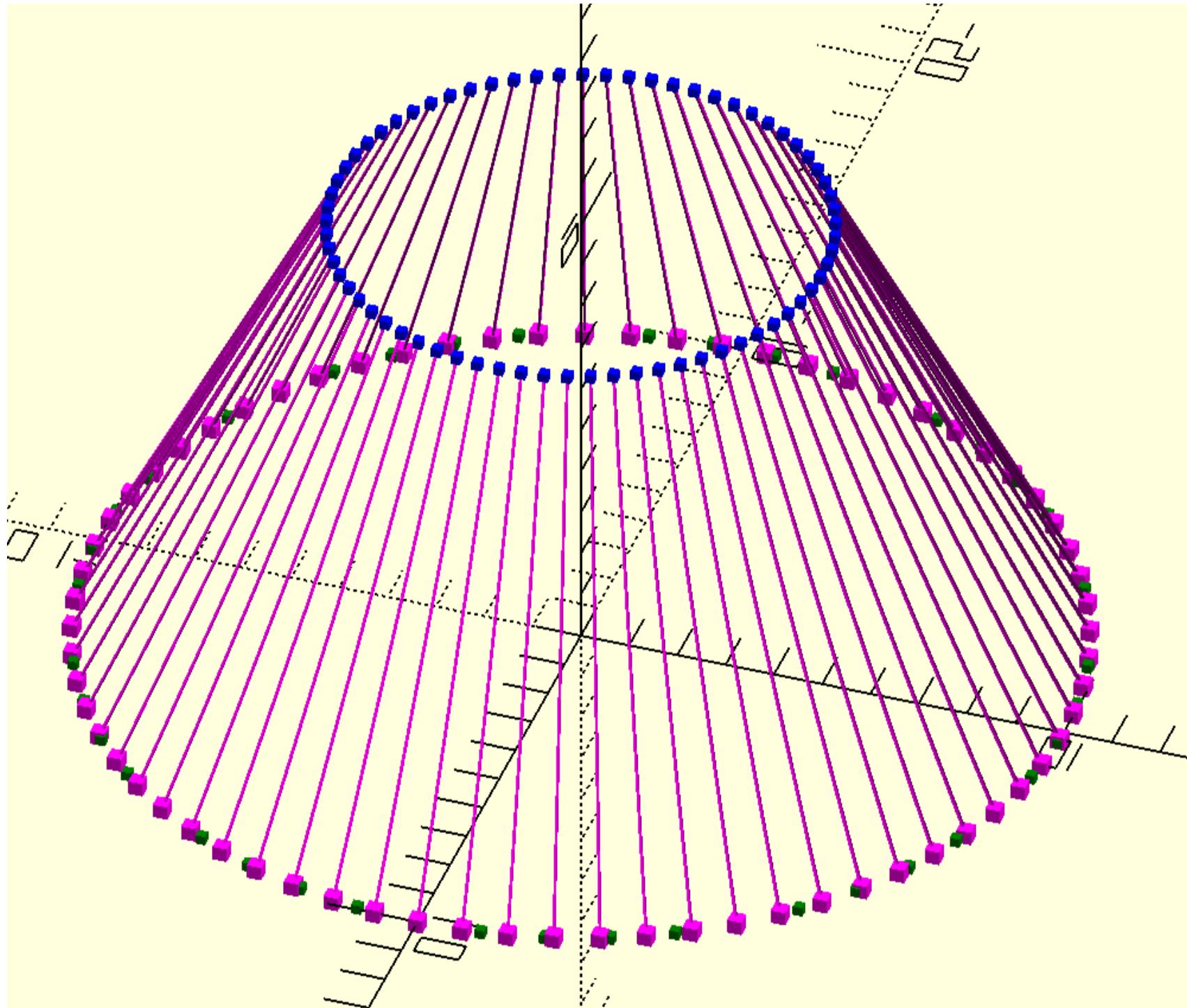
c3=path2path1_closed(c2,c1)
sol=cpo(align_sol_1([c3,c2]))

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("blue")points({c2},.2);
color("cyan")points({c3},.2);
color("green")points({c1},.2);
color("magenta")points({circle(10,s=70)},.3);

color("magenta")for(p={sol})p_line3d(p,.05,rec=1);

''' )
```



sol2path

```
In [5]: # example to extrude a solid along a path

# profile of the fan blade
t0=time.time()

p0=corner_radius(pts1([[0,0,.5],[20,-2,300],[20,-5,5],[5,5,4],[-5,5,5],[-20,0,300],[-20,-2,.5]]),20)

# blade profile smoothed with bezier
# sec=bezier(p0,300)
sec=equidistant_pathc(p0,300)

sol=linear_extrude(sec,45)
sol1=translate([45,0,0],q_rot(['y-90'],sol))
sol1=c2ro(sol1,1)
# zval=[p[0][2] for p in sol1]
# sol1=c3t2(sol1)

# generating helical path to extrude the profile
arc1=c2t3(arc(30,-10,0,s=2))
path=arc1+helix(30,120,.25,5)[3:]
path=bezier(path,100)

# code to extrude the solid along the given path
sol2=sol2path(sol1,path)
sol2=slice_sol_1(sol2,200)
```

```

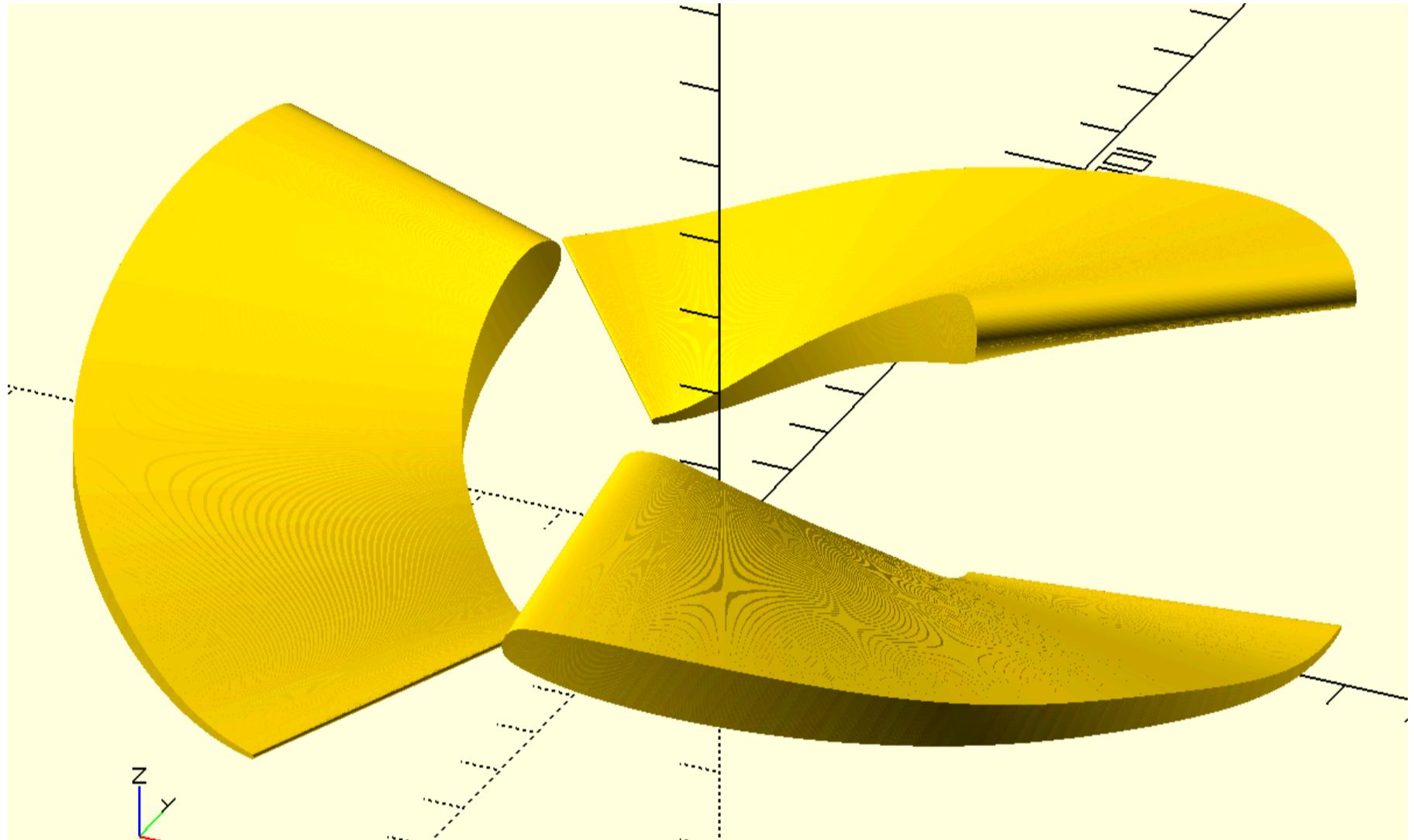
# file path needs to be modified
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>
difference(){{}
union(){{}
for(i=[0:360/3:359])
rotate([0,0,i])
mirror([0,1,0]){{swp(sol2)}}
}

//{swp(cut_plane([0,0,1],[1000,1000],100,20))}

color("blue")p_line3d({path},1,1);
'''')
t1=time.time()
t1-t0

```

Out [5]: 0.2892270088195801



```

In [36]: # profile of the fan blade
t0=time.time()

p0=corner_radius(pts1([[0,0,.5],[20,-2,300],[20,-5,5],[5,5,4],[-5,5,5],[-20,0,300],[-20,-2,.5]]),20)

# blade profile smoothed with bezier
sec=bezier(p0,200)
# sec=equidistant_pathc(p0,300)

sol=linear_extrude(sec,45)
sol1=translate([45,0,0],q_rot(['y-90'],sol))
sol1=c2ro(sol1,1)
zval=[p[0][2] for p in sol]
solx=c3t2(sol1)

sol2=[]
for p in solx:
    r1=array([l_len(p1) for p1 in seg(p)]).min()/5
    s1=corner_radius([[p[0][0],p[0][1],r1],[p[1][0],p[1][1],r1],[p[2][0],p[2][1],r1],[p[3][0],p[3][1],r1]],10)
    sol2.append(s1)

sol2=[translate([0,0,zval[i]],sol2[i]) for i in range(len(sol2))]

# generating helical path to extrude the profile
arc1=c2t3(arc(30,-10,0,s=3)[-1])
path=arc1+helix(30,120,.25,5)
path=bezier(pa2pb(path,zval),len(zval))
# path=bezier(path,len(zval))

# extrude a solid to a different path

sol3=sol2path(sol2,path)
sol3=slice_sol_1(sol3,200)

with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>

```

```

difference(){{union(){{for(i=[0:360/3:359])rotate([0,0,i])mirror([0,1,0]){swp(sol3)}}}}}

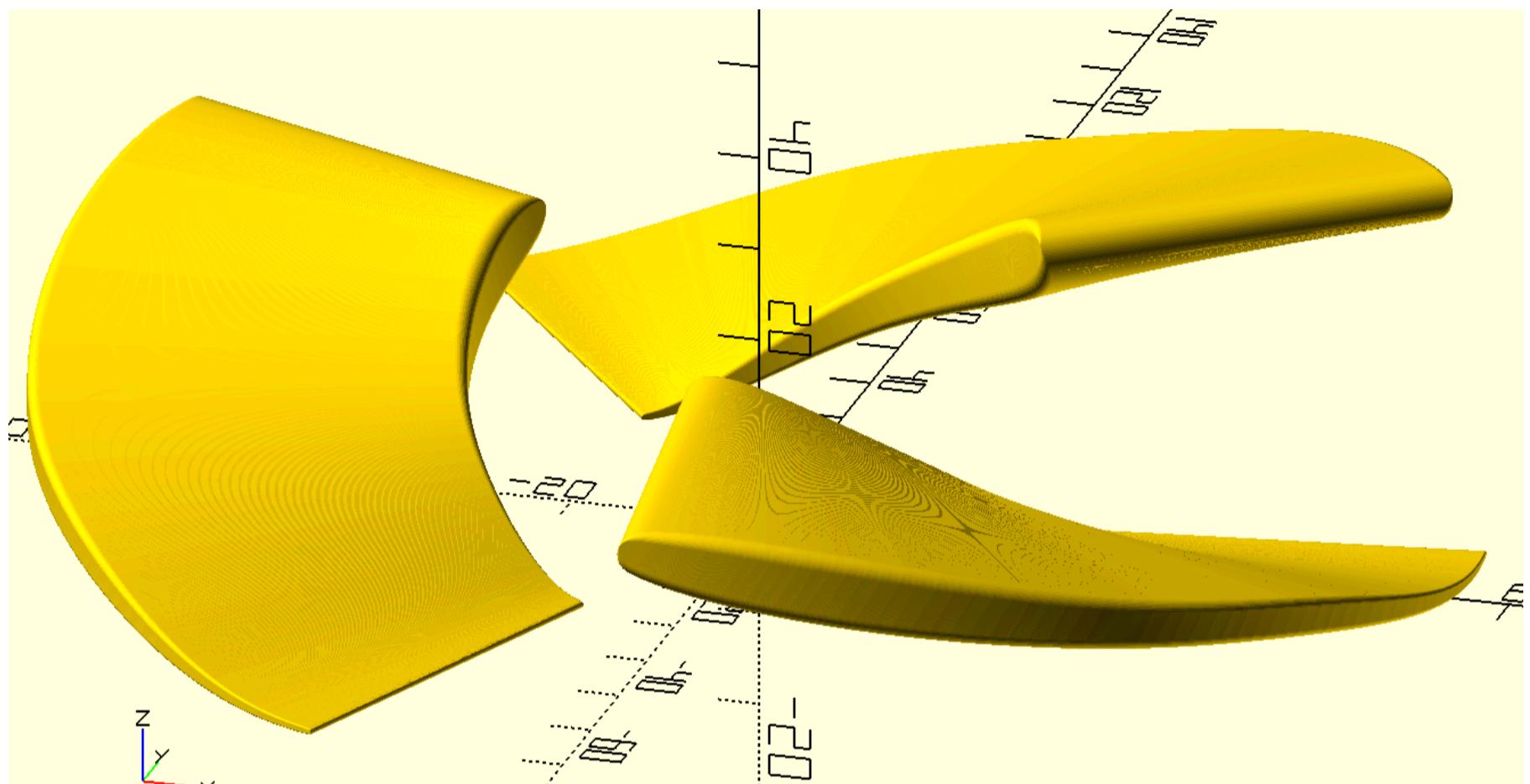
//{swp(cut_plane([0,0,1],[1000,1000],100,20))}

t1=time.time()
t1-t0

len(path)

```

Out[36]: 100



```

In [20]: t0=time.time()

sec=circle(5)
path1=corner_radius(pts1([[-3,0],[3,0,3],[0,15,2],[-2,5,3],[2,5,2],[0,20,3],[-3,0]]),10)
path1=equidistant_path(path1,200)
sol=prism(sec,path1)
path=bspline(cr_3d([[10,0,0,0],[10,15,10,8],[0,0,15,6],[20,0,0,0]]),20),2,50)
sol2=sol2path(sol,path)

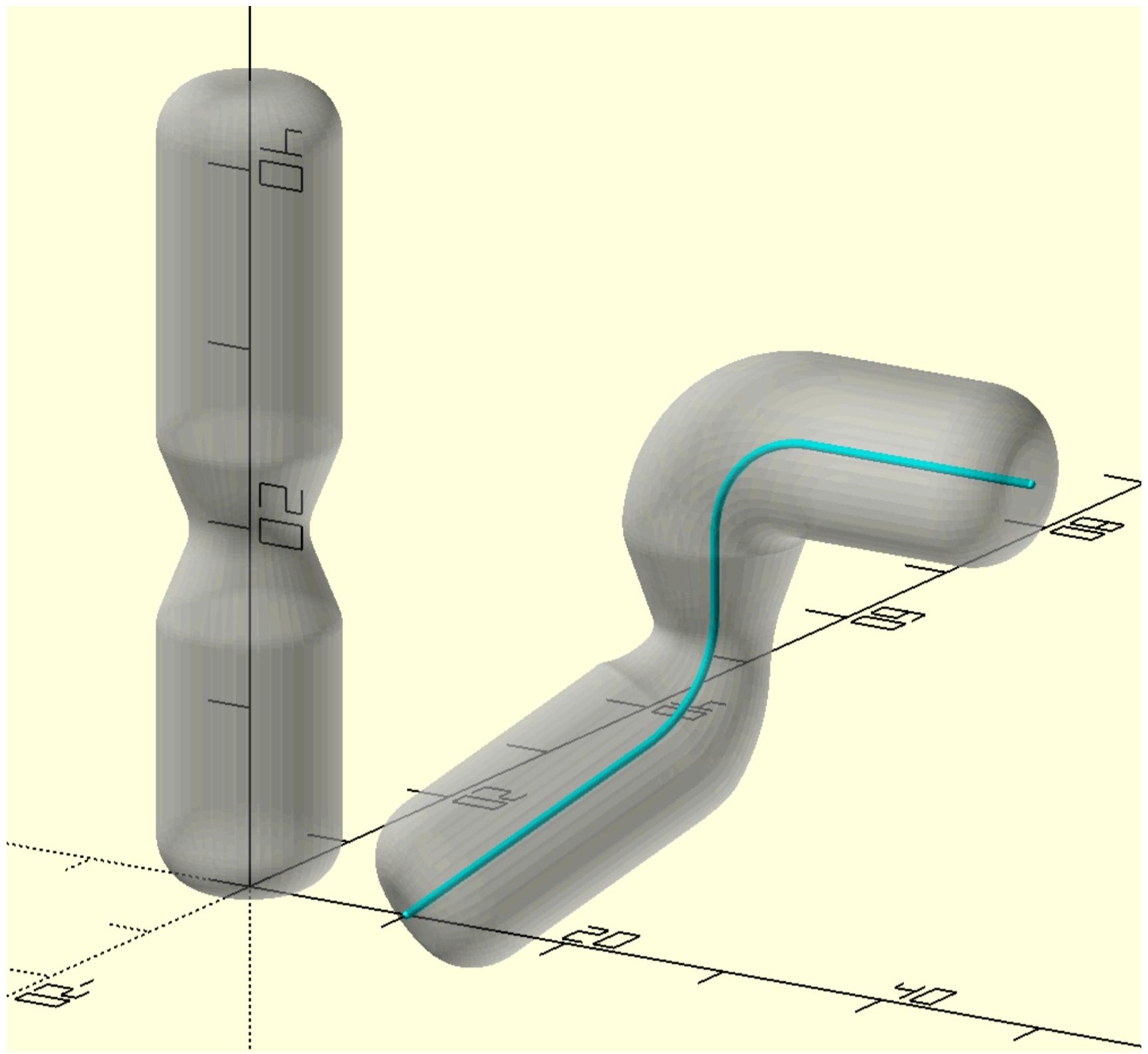
with open('trial.scad','w+') as f:
    f.write(f'''include<dependencies2.scad>

#{swp(sol)}
#{swp(sol2)}
color("cyan")p_line3d({path},.5);
''')

t1=time.time()
t1-t0

```

Out[20]: 0.9831128120422363



```
In [7]: sec=circle(5)
path=bezier(pts([[5,0],[15,10],[-26,10],[0,10],[5,6],[5,15],[4,4]]),50)
path1=q_rot(['x90'],corner_radius(pts1([[0,0],[0,45,15],[30,0]]),10))
sol=prism(sec,path)
sol1=sol2path(sol,path1)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

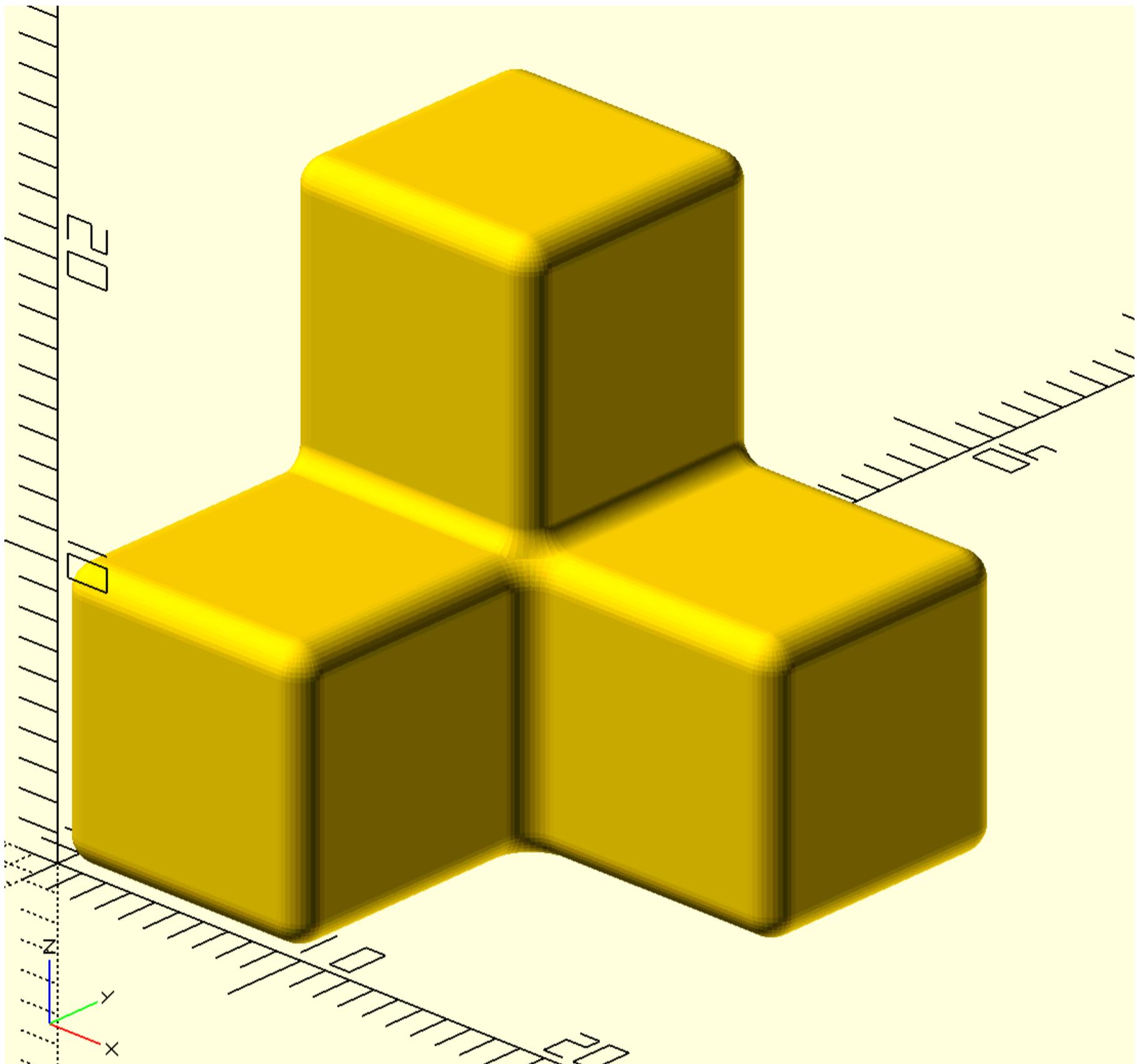
color("blue")p_line3d({path1},1);
{swp(sol1)}
'''')
```

rounding-various-rounded-cubes

```
In [128... t0=time.time()
p0=corner_radius(pts1([[0,0,1],[10,0,1],[0,10,1],[10,0,1],[0,10,1],[-20,0,1]]),10)
p1=corner_radius(pts1([[3,0],[3,0,1],[0,10,1],[-3,0]]),10)
sol=prism(p0,p1)

p2=corner_radius(pts1([[0,10,1],[10,0,1],[0,10,1],[-10,0,1]]),10)
p2=offset(p2,-.001)
p3=corner_radius(pts1([[0,8],[0,12,1],[-3,0]]),10)
sol1=prism(p2,p3)
f1=ip_fillet(sol,sol1,-.7,.7)
with open('trial.scad','w+') as f:
    f.write(f'''
    include<dependencies2.scad>
    {swp(sol)}
    {swp(sol1)}
    {swp(f1)}
    ''')
t1=time.time()
t1-t0
```

Out [128... 1.4244892597198486



ip_triangle

```
In [7]: t0=time.time()

sec=pts([[0,0],[5,0],[0,5],[-5,0]])
sec=equidistant_pathc(sec,50)
path=corner_radius(pts1([[-2.49,0],[2.49,0,0.25],[0,5,0.25],[-2.49,0]]),10)
sol1=prism(sec,path)
v1=[2,0,8]
sec1=axis_rot([0,0,1],circle(1.5,s=100),90)
sol2=o_solid(v1,sec1,10,-1.5,-2.5,0)
p1=ip_sol2sol(sol1,sol2)
p2=ip_sol2sol(sol1,sol2,-1)

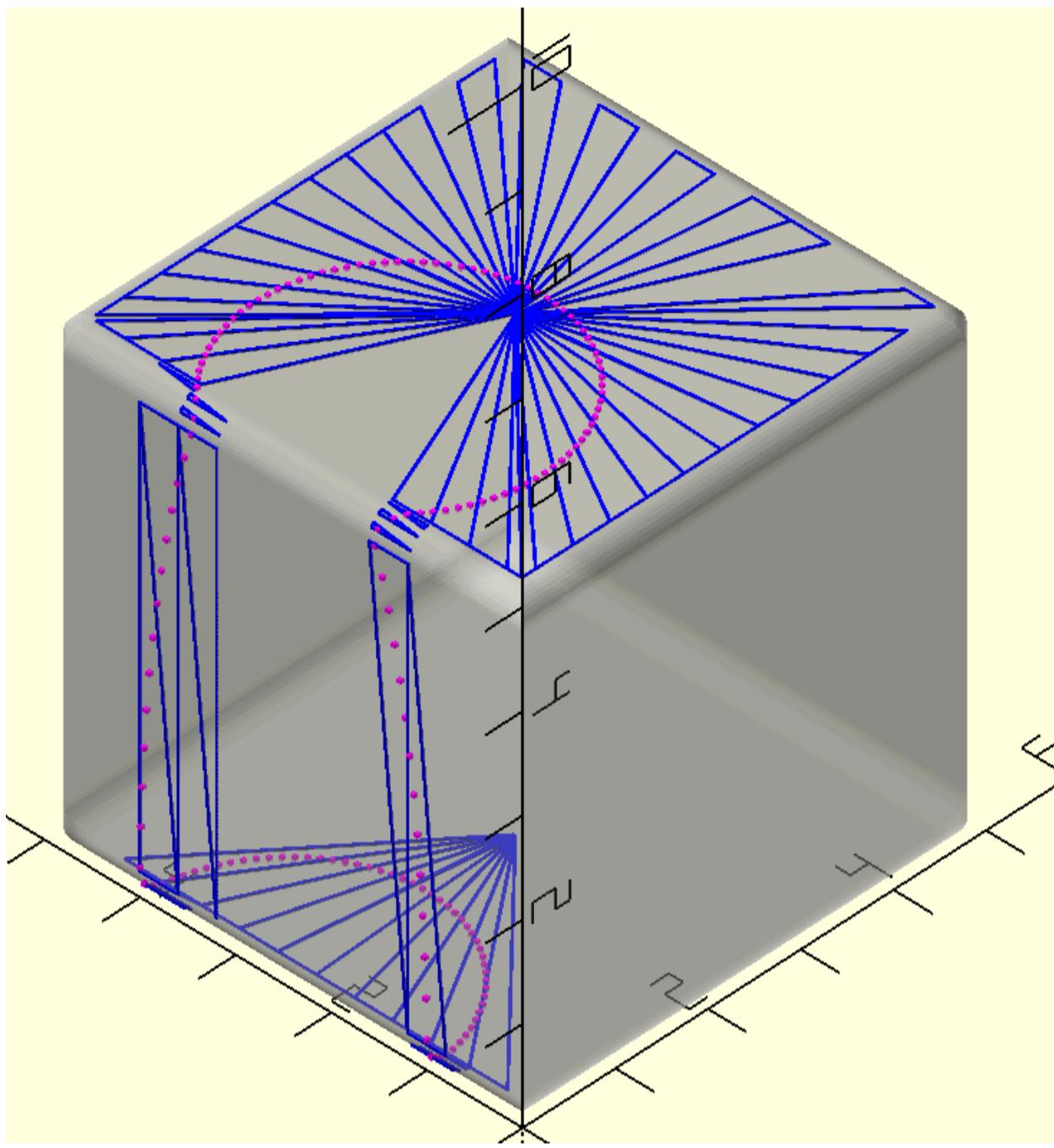
p3=flip(p1)+p2

tri_1=ip_triangle(p3,sol1)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

%{swp(sol1)}
//%{swp(sol2)}

color("magenta")points({p3},.05);
color("blue")for(p={tri_1})p_line3dc(p,.04,rec=1);
''')
t1=time.time()
t1-t0
```

Out[7]: 0.3002438545227051

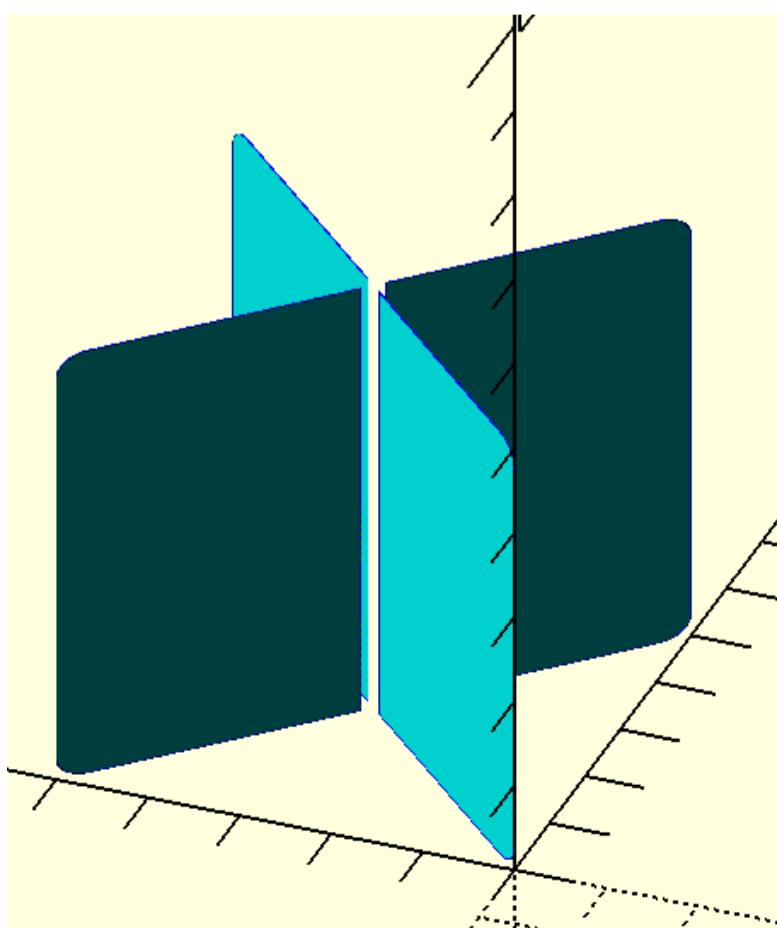


$$p_0 + v_0 t_0 = p_a + v_1 t_1 + v_2 t_2$$

$$v_0 t_0 - v_1 t_1 - v_2 t_2 = p_a - p_0$$

$$[v_0, -v_1, -v_2] * [t_0, t_1, t_2] = [p_a - p_0]$$

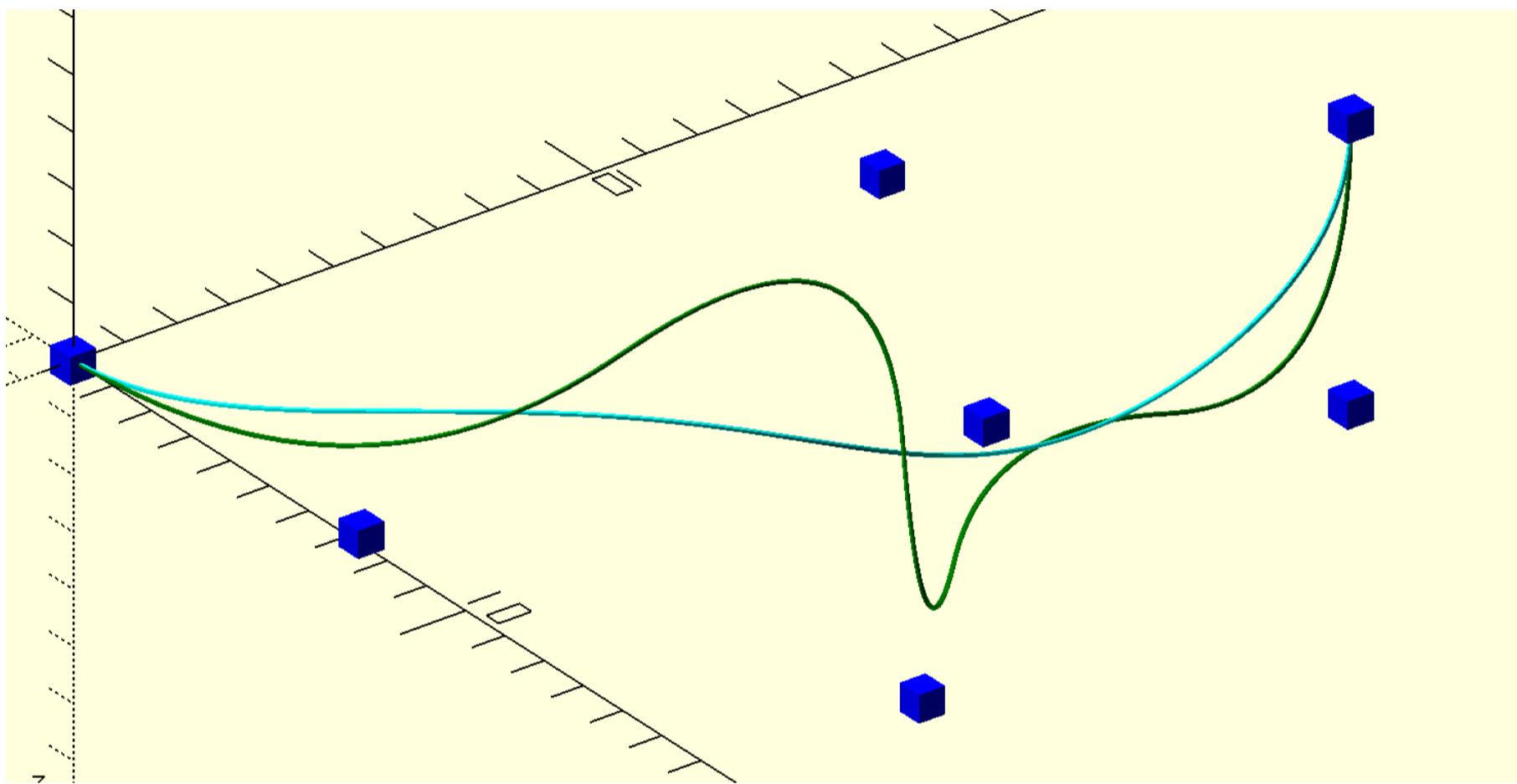
```
In [28]: sec=pts([[0,0],[5,0],[0,5],[-5,0]])
path=corner_radius(pts1([[-2.4,0],[2.4,0,0.25],[0,5,0.25],[-2.4,0]]),10)
sol1=prism(sec,path)
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
color("blue")for(p={cpo(sol1)})p_line3dc(p,.01,rec=1);
color("cyan")for(p={cpo(sol1)})polyhedron(p,[{range(len(cpo(sol1)[0])).tolist()}]);
''' )
```



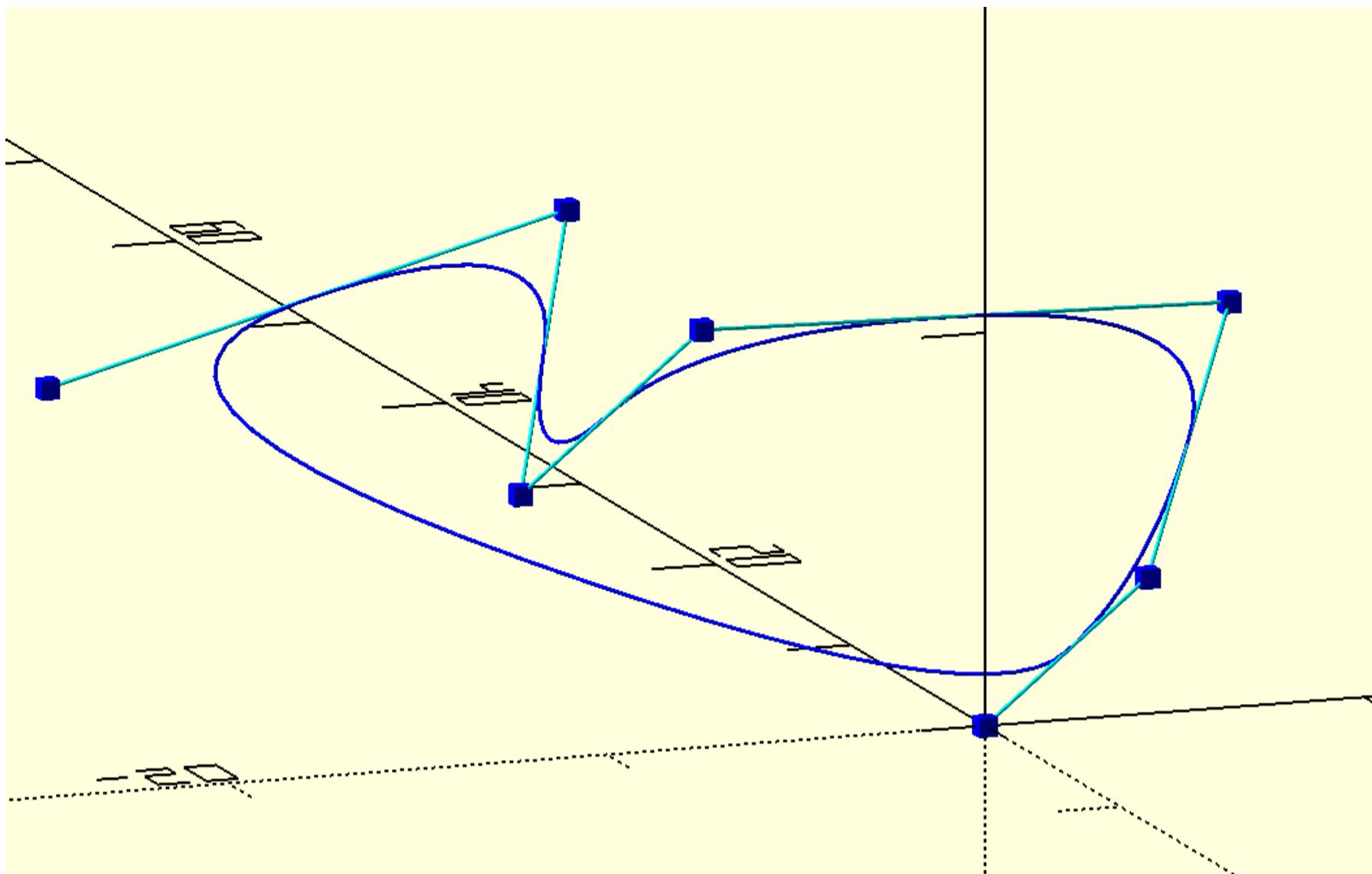
bspline

```
In [31]: p0=pts2([[0,0,0],[10,-2,2],[0,10,3],[5,-3,-6],[-5,5,1],[0,7,-2],[0,0,5]])  
p1=m_points1_o(p0,10)  
c1=bezier(p0,100)  
  
s1=bspline_open(p0,2,100)  
  
with open('trial.scad','w+') as f:  
    f.write(f'''  
include<dependencies2.scad>  
  
color("blue")points({p0},.5);  
//color("magenta")points({p1},.4);  
color("cyan")p_line3d({c1},.05,rec=1);  
  
color("green")p_line3d({s1},.05,rec=1);  
  
...)  
  
(len(p0)-2)*20,len(s1),l_lenv_o(p0)/10
```

Out[31]: (100, 100, 4.862074993748794)



```
In [32]: # bspline_closed function  
px=pts2([[0,0,0],[5,2,3],[5,8,5],[-15,-3,1],[-3,5,-5],[3,5,6],[-13,-10,10]])  
  
# b=bspline_open(px,2,100)  
c=bezier(px,100)  
d=bspline_closed(px,2,100)  
with open('trial.scad','w+') as f:  
    f.write(f'''  
include<dependencies2.scad>  
color("blue")points({px},.5);  
color("cyan")p_line3d({px},.1);  
color("blue")p_line3d({d},.1);  
  
...)
```



```
In [33]: px=pts2([[0,0,0],[5,2,3],[5,8,5],[-15,-3,-2],[0,10,0],[7,0,6],[-3,5,-4]])
px=helix(10,5,1,5)
b=bspline_open(px,4,100)
c=bezier(px,100)

with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>
color("blue")points({px},.5);
color("magenta")p_line3d({b},.1,rec=1);
//color("cyan")p_line3d({c},.1,rec=1);

    ''')
len(b)
```

Out[33]: 100

faces

```
In [32]: sec=pts([[0,0],[5,0],[0,5],[-5,0]])
# sec=equidistant_pathc(sec,50)
path=corner_radius(pts1([[-1,0],[1,0,0.25],[0,5,0.25],[-1,0]]),10)
sol1=prism(sec,path)
l,m,_=array(sol1).shape
v=array(sol1).reshape(-1,3).tolist()
f1=faces(l,m)

with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>

polyhedron({v},{f1});

    ''')
```

faces_1

```
In [33]: sec=pts([[0,0],[5,0],[0,5],[-5,0]])
# sec=equidistant_pathc(sec,50)
path=corner_radius(pts1([[-1,0],[1,0,0.25],[0,5,0.25],[-1,0]]),10)
sol1=prism(sec,path)
l,m,_=array(sol1).shape
v=array(sol1).reshape(-1,3).tolist()
f1=faces_1(l,m)

with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>

polyhedron({v},{f1});

    ''')
```

```
In [34]: p0=[10,0,0]
p1=[5,2,3]
```

```

p2=[10,1,1]
l1,p2=array([p0,p1]),array(p2)

v1=l1[1]-l1[0]
u1=v1/norm(v1)
v2=p2-l1[0]

v2sint=norm(cross(v1,v2))/norm(v1)
v2cost=(v1@v2)/norm(v1)
t1=v2cost/norm(v1)
p3=l1[0]+v1*t1
p2=p2.tolist()
p3=p3.tolist()

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("blue")points({[p0,p1,p2,p3]},.3);
color("cyan")p_line3d({[p0,p1]},.1);
color("magenta")p_line3d({[p2,p3]},.1);

''')

t1

```

Out[34]: 0.13157894736842107

p2p_intersection_line

l_sec_ip_3d

|2|_intersection

```

In [2]: i_t=time.time()
p0=[[1,2,1],[5,4,3],[2,8,5]]

p1=[[10,2,1],[5,1,3],[12,8,-5]]
line=p2p_intersection_line(p0,p1)
line1=l_sec_ip_3d(p0,line)
line2=l_sec_ip_3d(p1,line)

p2=l2l_intersection(line1,line2)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("blue")p_line3dc({p0},.1,rec=1);
color("magenta")p_line3dc({p1},.1,rec=1);
color("cyan")p_line3d({line1},.1,rec=1);
color("green")p_line3d({line2},.1,rec=1);
color("magenta")points({[p2]},.5);

''')

f_t=time.time()
f_t-i_t

```

Out[2]: 0.41835975646972656

```

In [3]: i_t=time.time()

# p0=translate([-2,0,-8.22],[[2,4,5],[7,9,15],[1,10,5]])
# p1=translate([-3,0,-5],[[5,10,3],[5,-7,5],[-10,5,10]])

p0=[[-2,5,0],[-5,0,0],[0,5,10]]
p1=[[0,-5,0],[0,10,0],[5,3,15]]

line=p2p_intersection_line(p0,p1)
line1=l_sec_ip_3d(p0,line)
line2=l_sec_ip_3d(p1,line)

line3=[mean(p0,0).tolist(),add(mean(p0,0),multiply(nv(p0),10)).tolist()]
line4=[mean(p1,0).tolist(),add(mean(p1,0),multiply(nv(p1),10)).tolist()]
line5=array([array(p0).mean(0)-cross(nv(p0),nv(p1)),array(p0).mean(0)+cross(nv(p0),nv(p1))]).tolist()
line6=array([array(p1).mean(0)-cross(nv(p0),nv(p1)),array(p1).mean(0)+cross(nv(p0),nv(p1))]).tolist()
line7=array([array(p0).mean(0),array(p0).mean(0)+cross(nv(p0),cross(nv(p0),nv(p1))*15)]).tolist()
line8=array([array(sl_int1(p1,line3)[0]),array(sl_int1(p1,line3)[0])-cross(nv(p1),cross(nv(p0),nv(p1))*20)]).tolist()
p2=sl_int1(p1,line3)[0]
p3=l2l_intersection(line7,line8)
p4=array(p0).mean(0).tolist()
p5=sl_int1(p0,line4)[0]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

color("blue")p_line3dc({p0},.1,rec=1);
color("magenta")p_line3dc({p1},.1,rec=1);
//color("cyan")p_line3d({line},.1,rec=1);
//color("cyan")p_line3d({line1},.1,rec=1);
color("green")p_line3d({line2},.1,rec=1);

```

```

color("green")p_line3d({line3},.1,rec=1);
color("magenta")p_line3d({line4},.1,rec=1);
color("magenta")p_line3d({line5},.1,rec=1);
color([.2,.3,.7,.2])p_line3d({line6},.1,rec=1);
color([.1,.3,.9,1])p_line3d({line7},.1,rec=1);
color([.1,.3,.2,1])p_line3d({line8},.1,rec=1);
color([.3,.2,.6,1])points({[p2]},.3);
color([.3,.2,.1,1])points({[p3]},.3);
color([.1,.2,.9,1])points({[p4]},.3);
color([.5,.5,1,1])points({[p5]},.3);

polyhedron({p0},[[0,1,2]]);
polyhedron({p1},[[0,1,2]]);

'''')
f_t=time.time()
f_t-i_t

```

Out [3]: 0.1726062297821045

i_p_p

i_p_n

i_p_t

o_3d

ip_fillet

```

In [188... i_t=time.time()
sol=o_solid([1,0,0],circle(5),30,-15)
sol1=o_solid([0,1,0],circle(4.8),30,-15)
sol1=slice_sol(sol1,2)
fillet1=ip_fillet(sol,flip(sol1),1,1,o=-1,style=2)
fillet1=fillet1+[fillet1[0]]
fillet2=ip_fillet(flip(sol),sol1,1,1,o=-1,style=2)
fillet2=fillet2+[fillet2[0]]
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>

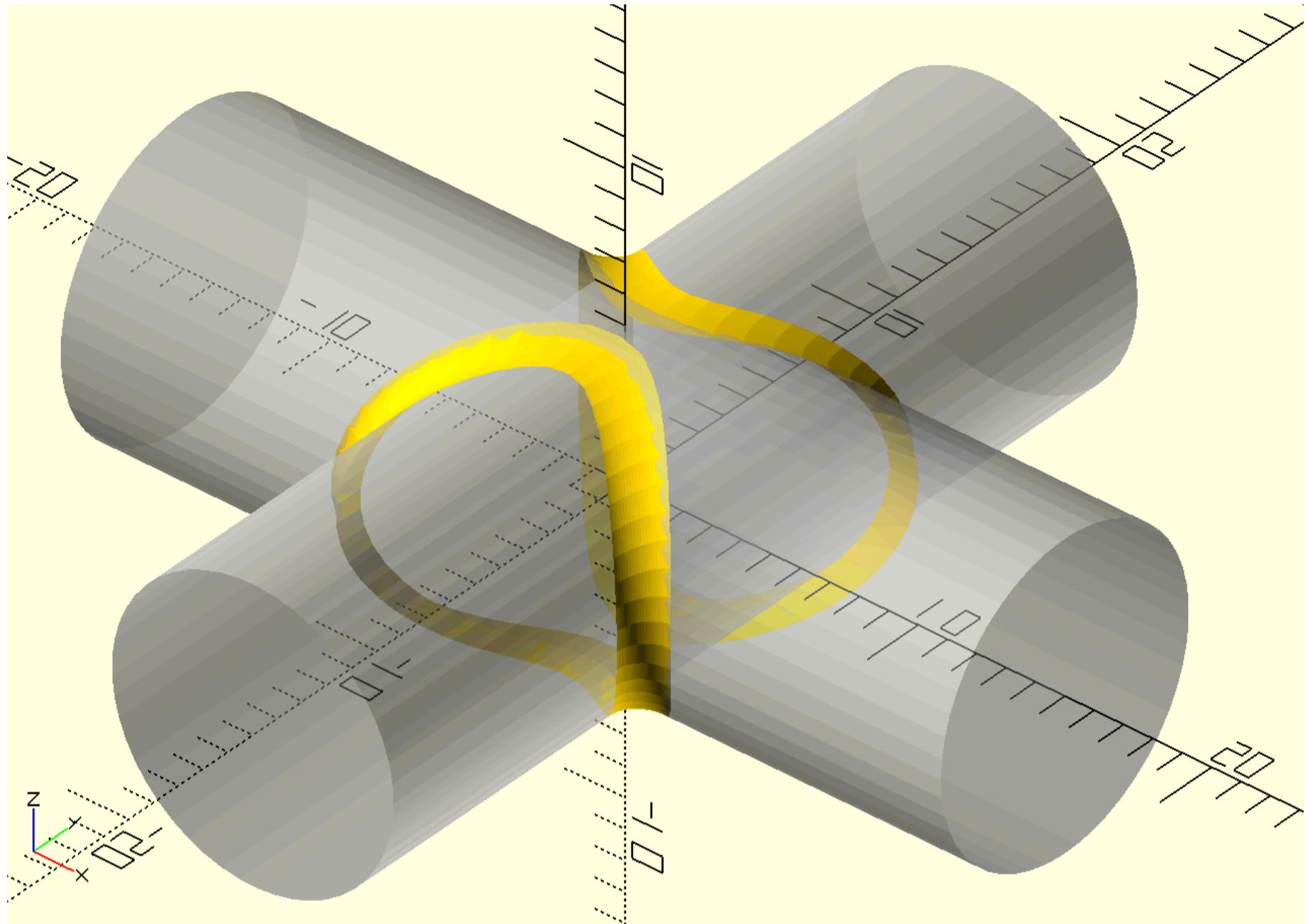
{swo_swp(sol)}
{swo_swp(sol1)}

{swp_c(fillet1)}
{swp_c(fillet2)}

'''')
f_t=time.time()
f_t-i_t
# len(i_p),len(i_p1),len(i_p2)

```

Out [188... 0.43102312088012695



```
In [59]: i_t=time.time()
sec=corner_radius(pts1([[-5,-10,1],[10,0,1],[0,15,1],[-10,0,1]]),10)
path=corner_radius(pts1([[5,0],[5,0,1],[0,20,1],[-5,0]]),10)
sol=prism(sec,path)
sec1=circle(2,s=100)
path1=bezier(pts2([[0,-4,2],[0,5,10],[10,1,20]]),20)
sol1=path_extrude_open(sec1,path1)
fillet1=ip_fillet(sol,sol1,-1,1,style=2)
fillet1=fillet1+[fillet1[0]]
# p1=ip_sol2sol(sol,sol1,-1)

# p2=i_p_p(sol1,p1,1)
# p3=o_3d(p1,sol,-1)

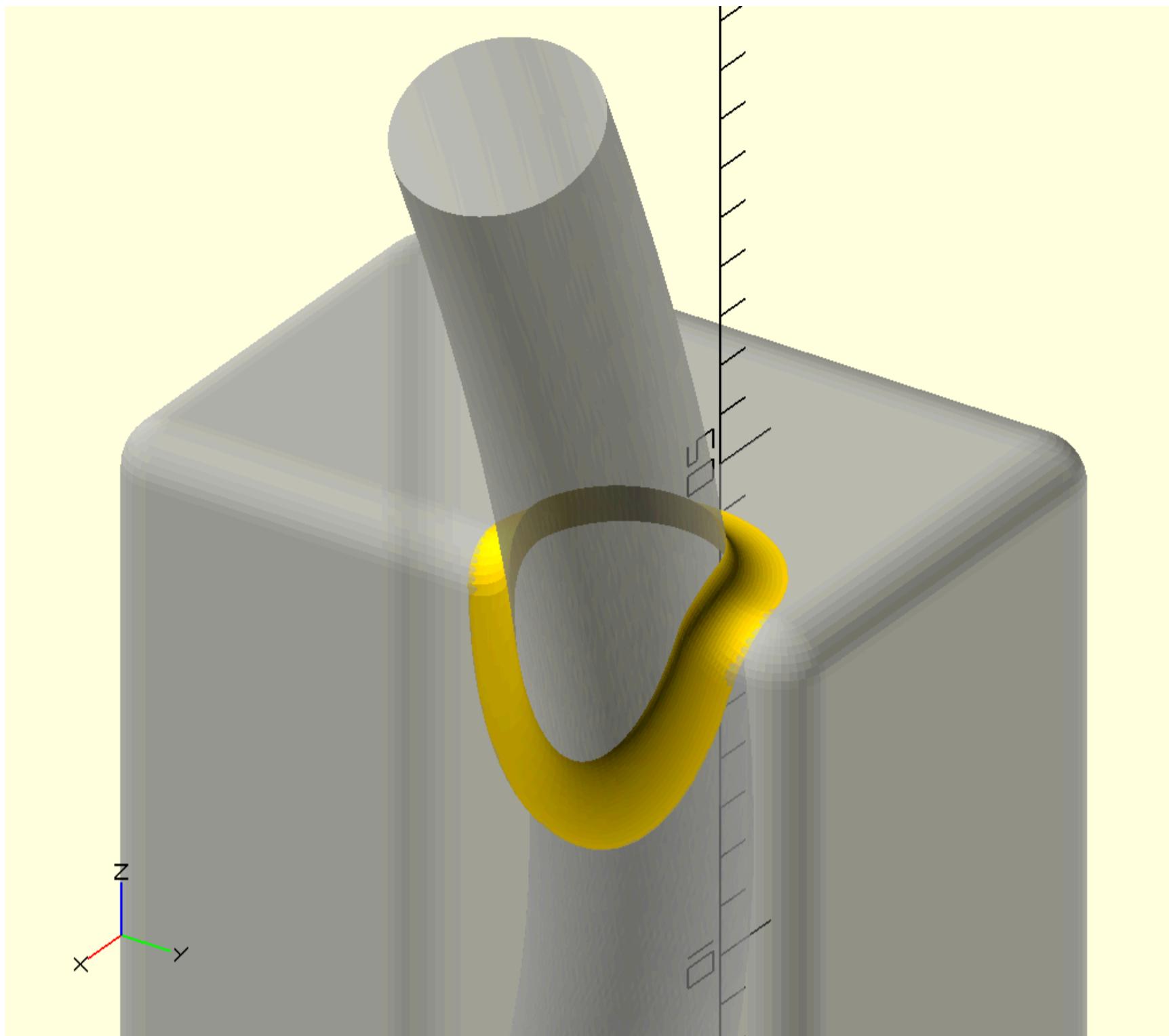
# fillet1=convert_3lines2fillet_closed(p3,p2,p1)

with open('trial.scad','w+')as f:
    f.write(f'''include<dependencies2.scad>

{sweep(sol)}
{sweep(sol1)}
{sweep_c(fillet1)}

''')
f_t=time.time()
f_t-i_t
```

Out[59]: 2.056248903274536



```
In [189... i_t=time.time()
p1=[[0,-31],[21-5,0,.2],[2,10,4],[35,0,10],
[5,22,5],[-5,22,10],[-35,0,4],[-2,10,.2],[-21+5,0]]

path1=corner_radius(pts1(p1),10)
sec1=circle(5,s=72)
sol1=f_prism(sec1,path1)

sec5=corner_radius(pts1([[-20,-7.5,2.45],[5,0,2.45],[0,10,3],[15,2,70],[15,-2,3],[0,-10,2.45],
[5,0,2.45],[1,7.5,5],[-1,7.5,7],[-20,3,90],[-20,-3,7],[-1,-7.5,5]]),10)

sec5=equidistant_pathc(sec5,201)
sec6=scl2d_c(sec5,.6)
sol2=[c2t3(sec5)]+[translate([0,0,120],sec6)]
sol2=translate([0,41,0],q_rot(['x90','z190'],sol2))

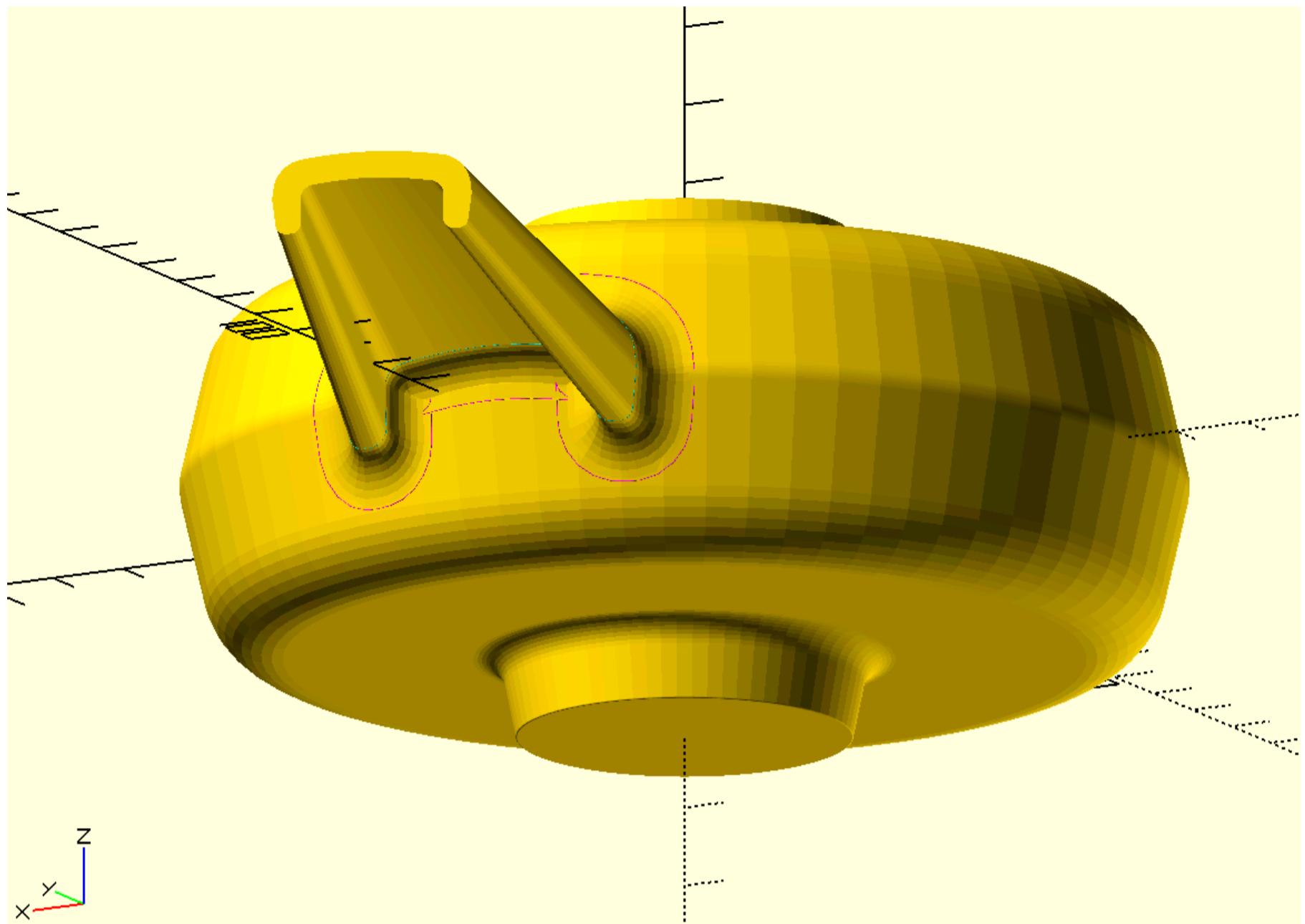
# p1=ip_surf(sol1,sol2)
# p2=i_p_p(sol2,p1,6)
# p3=o_3d(p1,sol1,6)
# fillet1=convert_3lines2fillet_closed(p1,p2,p3)
fillet1=ip_fillet(sol1,sol2,-6,6,style=2)
fillet1=fillet1+[fillet1[0]]
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

%{swp(sol1)}
%{swp(sol2)}
{swp_c(fillet1)}

''')

f_t=time.time()
f_t-i_t
# len(p1),len(p2),len(p3)
```

Out [189... 7.536956071853638



```
In [65]: i_t=time.time()

p1=[[0,-31],[21-5,0,.2],[2,10,4],[35,0,10],
    [5,22,5],[-5,22,10],[-35,0,4],[-2,10,.2],[-21+5,0]]

path1=corner_radius(pts1(p1),10)
sec1=circle(5,s=72)
sol1=prism(sec1,path1)

sec5=corner_radius(pts1([[20,-7.5,2.49],[5,0,2.49],[0,10,3],[15,2,70],[15,-2,3],[0,-10,2.49],
    [5,0,2.49],[1,7.5,5],[-1,7.5,7],[-20,3,90],[-20,-3,7],[-1,-7.5,5]]),10)

sec5=equidistant_pathc(sec5,200)
sec6=scl2d_c(sec5,.6)
sol2=[c2t3(sec5)]+[translate([0,0,120],sec6)]
sol2=translate([0,41,0],q_rot(['x90','z190'],sol2))
p1=ip(sol1,sol2)

p2=ip(sol1,offset_sol(sol2,8,1))
# p2=sort_points(p1,p2)
# p2=sort_points(p1,p2)
p3=i_p_p(sol2,p1,8)
# p3=sort_points(p1,p3)

fillet1=convert_3lines2fillet_closed(p2,p3,p1,style=2)

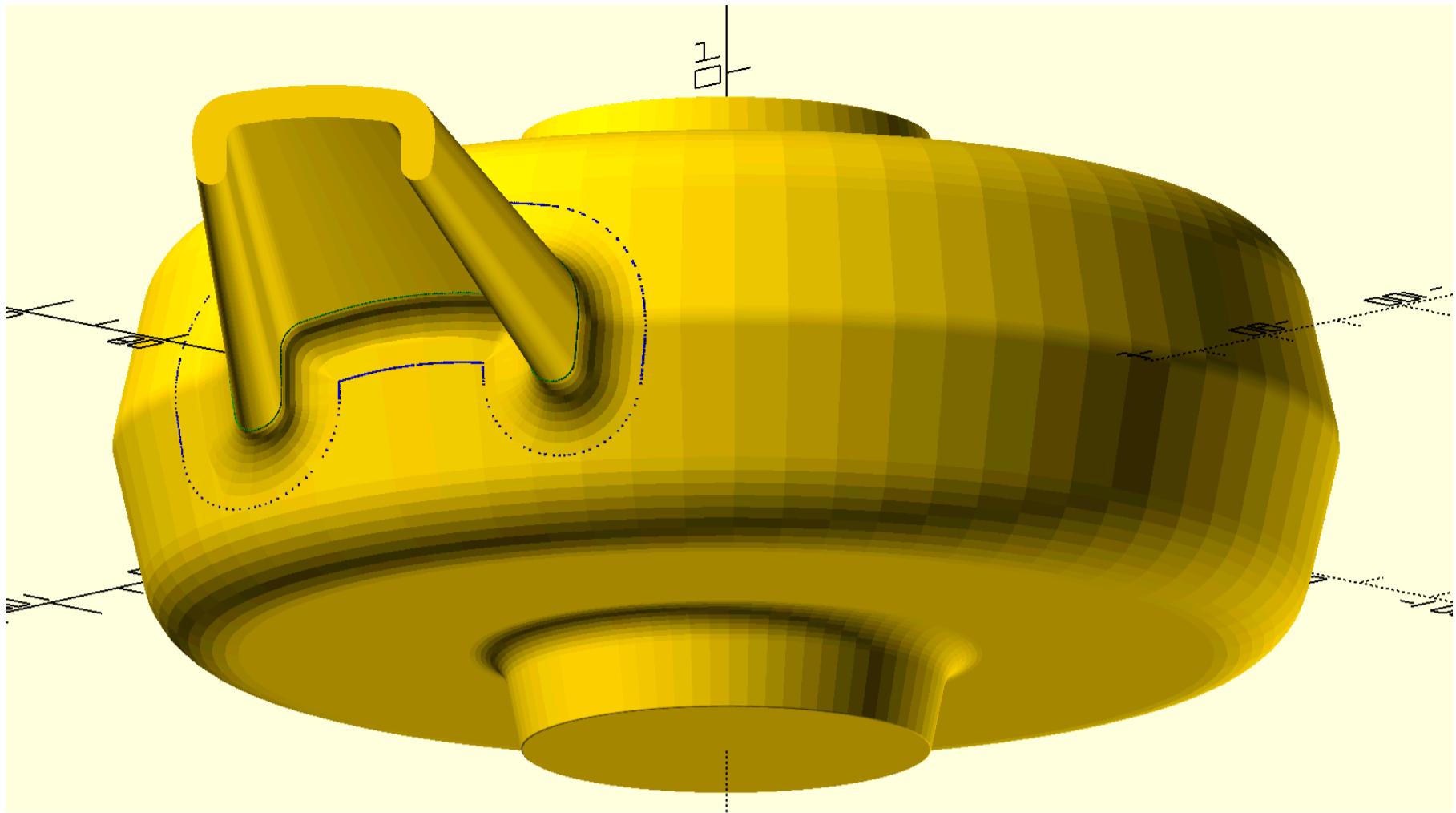
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>

{swp(sol1)}
{swp(sol2)}
//%{swp(offset_sol(sol2,6,1))}
{swp_c(fillet1)}
color("blue")p_line3dc({p2},.2,rec=1);
color("green")p_line3dc({p3},.2,rec=1);

color("magenta")p_line3dc({p1},.2,rec=1);

''')
len(p1),len(p2),len(p3)
f_t=time.time()
f_t-i_t
```

Out[65]: 4.440587997436523



```
In [70]: # m10
t0=time.time()

sec1=arc(20,0,359,s=150)
path1=[[0,0],[-5,25]]

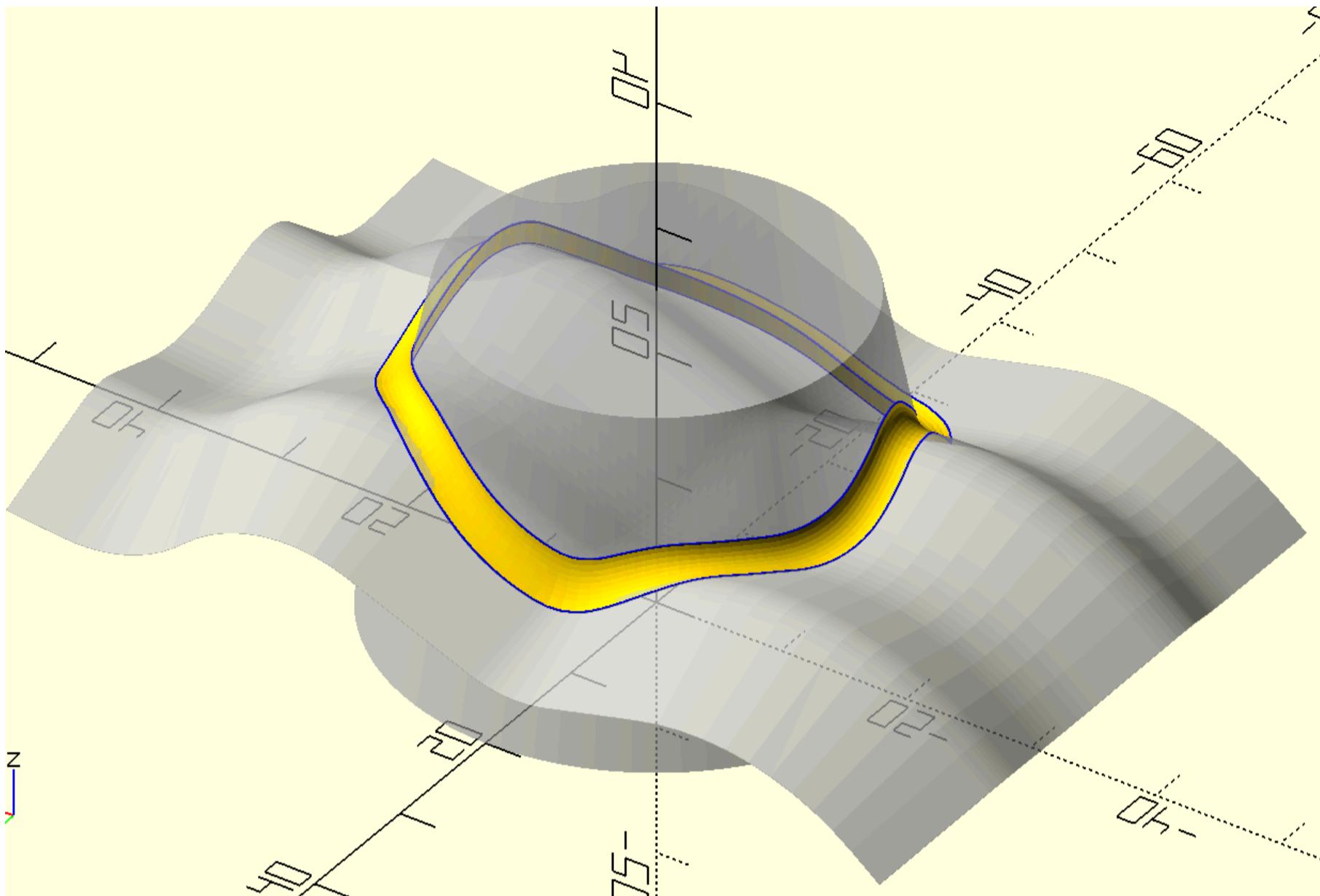
surf1=prism(sec1,path1)

sec2=corner_radius(pts1([[-25,0],[10,5,5],[10,-3,10],[10,5,5],[10,-8,7],[10,1]]),10)
path2=cytz(corner_radius(pts1([-35,5,0],[10,8,20],[20,-5,10],[20,8,20],[10,-9,20],[10,1,0])),10))
surf2=surf_extrude(sec2,path2)
surf3=surf_extrude(surf2)
# p1=ip_surf(surf2,surf1)
# p2=o_3d_surf(p1,surf2,2)
# p3=i_p_p(surf1,p1,2)
# # # p=fillet_surf2sol(surf2,surf1,2,10,0)
# fillet1=convert_3lines2fillet_closed(p1,p3,p2)

fillet1=ip_fillet_surf(surf2,surf1,-2,2,style=2)
fillet1=fillet1+[fillet1[0]]
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies.scad>
{swp(surf1)}
{swp_c(surf3)}
{swp_c(fillet1)}

'''')
t1=time.time()
total=t1-t0
total
```

Out[70]: 2.3320670127868652



```
In [73]: t1=time.time()

p1=[[0,-15,.5],[6,0,.3],[0,-16,.1],[1,-1,.1],[4,0,.2],[2,10,4],[35,0,10],
     [5,22,5],[-5,22,10],[-35,0,4],[-2,10,.2],[-4,0,.1],[-1,-1,.1],[0,-16,.3],
     [-6,0,.5]]
sec1=corner_radius(pts1(p1),10)
path1=c2t3(circle(10,s=72))
sol1=path_extrude_closed(sec1,path1)

sec3=circle(7,s=50)
path2=corner_radius(pts1([[2,0],[-2,31]]),10)

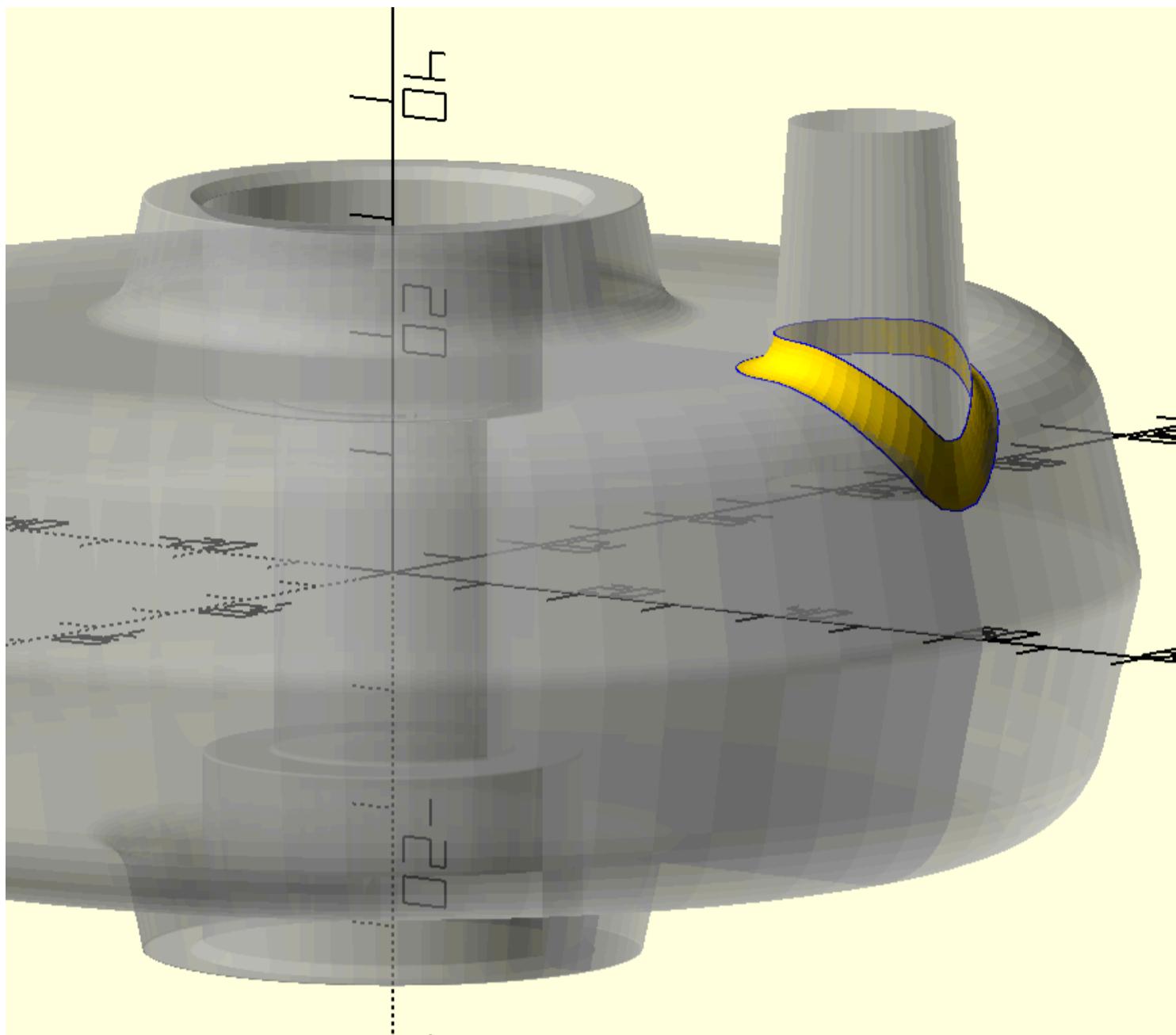
sol3=translate([51.2,0,12],prism(sec3,path2))
# px=ip_surf(sol1,sol3)
# py=i_p_p(sol3,px,3)
# pz=o_3d_surf(px,sol1,3)
fillet1=convert_3lines2fillet_closed(px,py,pz)
fillet1=ip_fillet(sol1,sol3,-3,3,style=2)
fillet1=fillet1+[fillet1[0]]
f3=end_cap(sol3,2)[1]
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

{swp_c(sol1)}
difference(){
{swp(sol3)}
{swp_c(f3)}
}
{swp_c(fillet1)}

//color("blue")for(p={cpo(fillet1)[0],cpo(fillet1)[-2]})p_line3dc(p,.2);
    ''')

t2=time.time()
t2-t1
# len(p1),len(p2),len(p3)
```

```
Out[73]: 3.7424118518829346
```



```
In [12]: line=[[0,0],[10,0]]
pnts=[[10,15]]
d=1e-10

perp_points_d(line,pnts,d),perp_distance_within_line(line,pnts)
```

```
Out[12]: ([], [15.0])
```

```
In [155...]: t0=time.time()
sec=corner_radius(pts1([[0,0],[40,0],[0,40],[-40,0]]),10)
path=corner_radius(pts1([[-20,0],[20,0],[0,10],[-20,0]]),10)

sol1=prism(sec,path)

sec1=circle(7.5,s=100)
path1=corner_radius(pts1([[-7,0],[7,0],[-7.49,40]]),10)
sol2=prism(sec1,path1)
sol2=axis_rot_o([1,0,0],translate([-0.01,20,12],q_rot(['y90'],sol2)),180)

a=array([[1-cos(d2r(i)),1-sin(d2r(i))] for i in linspace(0,90,100)])*5
b=[rsz3dc(sol1,array(bb(sol1))+i*2) for i in a[:,0]]
c=[rsz3dc(sol2,array(bb(sol2))+i*2) for i in a[:,1]]

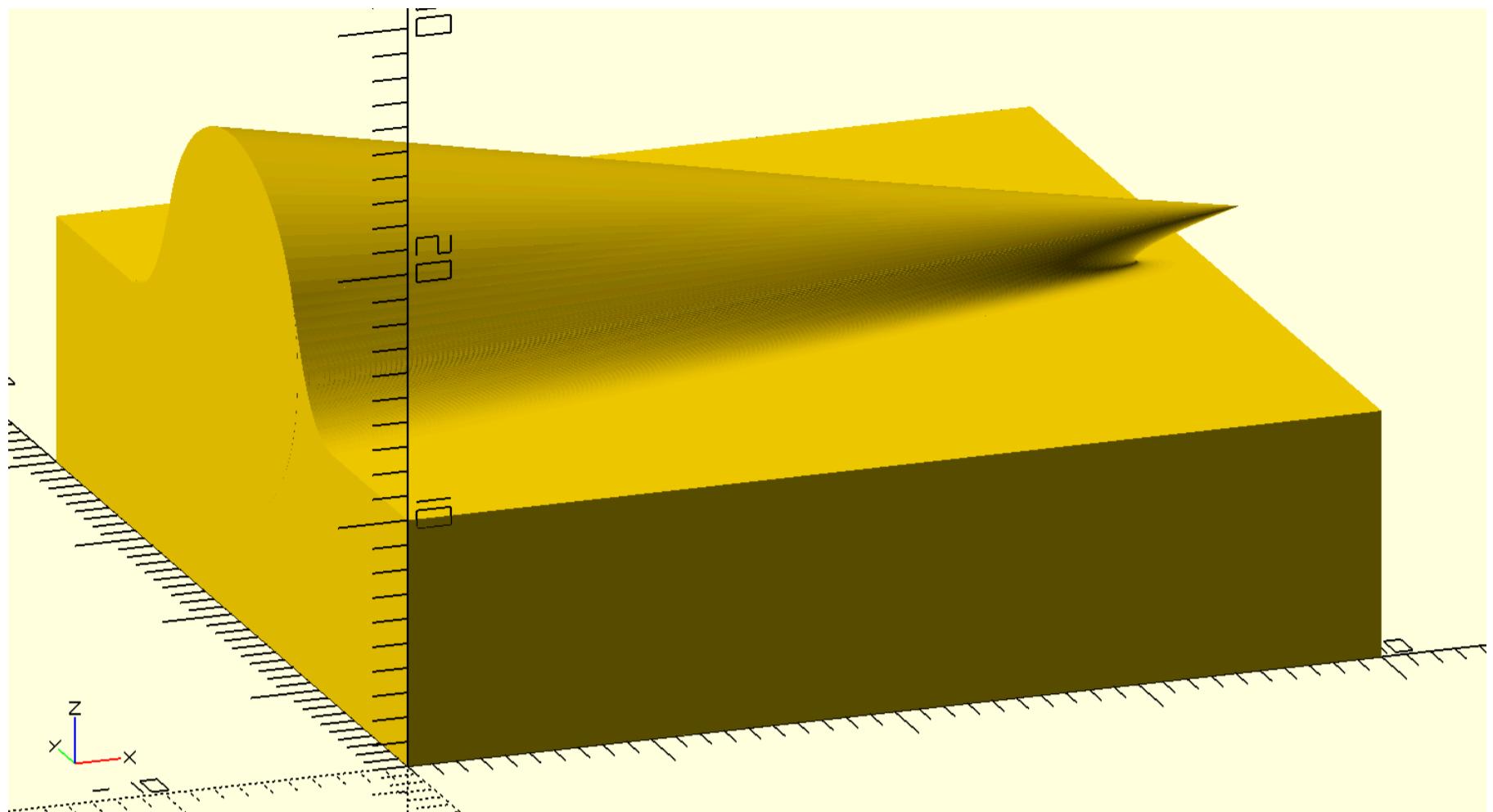
with open('trial.scad','w+') as f:
    f.write(f'''')
    difference(){{}
        union(){{
            ''
        }}
        for i in range(len(a)-1):
            f.write(f'''')
    //include<dependencies2.scad>
    hull(){{}}
    intersection(){{
        {swp(b[i])}
        {swp(c[i])}
    }}

    intersection(){{
        {swp(b[i+1])}
        {swp(c[i+1])}
    }}
    ''
    })
    f.write(f'''')

    })
    translate([-10,-5,-2])cube([10,50,30]);
    })
    {swp(sol1)}
    {swp(sol2)}
    ''')
```

```
t1=time.time()
t1-t0
```

Out[155]: 0.38067102432250977



partial_surface

shield

```
In [44]: i_t=time.time()
sec1=circle(55)
path1=corner_radius(pts1([[-50,0],[50,0,.2],[0,30,3],[6,1,3],[0,6,3],[-4,2,3],[0,22,6],[8,2,6],[0,10,.2],[-50,0]]),10)
# path1=equidistant_path(path1,200)
sec2=circle(7.5)
path2=corner_radius(pts1([[5,0],[5,0,5],[0,35,2],[-5,0]]),10)
path2=equidistant_path(path2,50)
sol1=prism(sec1,path1)
sol2=translate([57.5,0,37],prism(sec2,path2))
sol2=axis_rot_o([0,0,1],sol2,180)

s1=shield(sol1,sol2,50,10,4,135)
v,f1=partial_surface(sol1,prism_center(sol2),50)

with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>

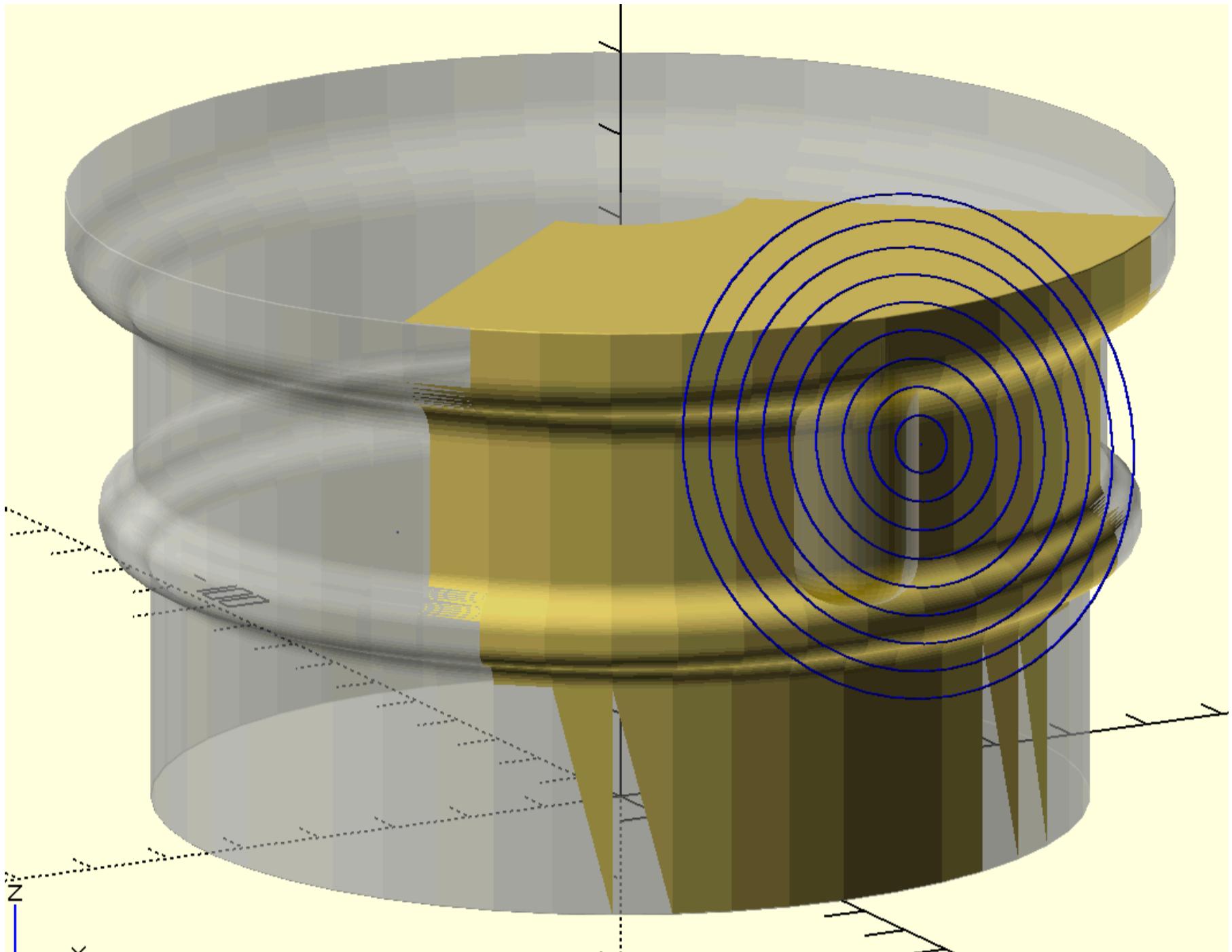
        %{{swp(sol1)}}
        %{{swp(sol2)}}

        color("blue")for(p={s1})for(p1=p)p_line3dc(p1,.2,rec=1);
        polyhedron({v},{f1});

    ''')

f_t=time.time()
f_t-i_t
# len(p1),len(p2),len(p3)
```

Out[44]: 0.5128381252288818



```
In [45]: # example of function surface_for_fillet(sol1=[],sol2=[],factor1=50,factor2=10,factor3=1,factor4=100,dia=40)
t0=time.time()

sec=circle(10)
path=corner_radius(pts1([[-8,0],[10,0],[-2,0,2],[-1,15,3],[-8.9,0]]),10)
path=equidistant_path(path,100)
sol1=q_rot(['z90'],prism(sec,path))

sec1=corner_radius(pts1([[0,0,1],[5,0,1],[0,7,2.3],[-5,0,2.3]]),10)
path1=corner_radius(pts1([[-2.4,0],[2.4,0,2],[0,5,.3],[-.5,0]]),10)
path1=equidistant_path(path1,30)
sol2=translate([6,0,12],q_rot(['x90','z90'],prism(sec1,path1)))

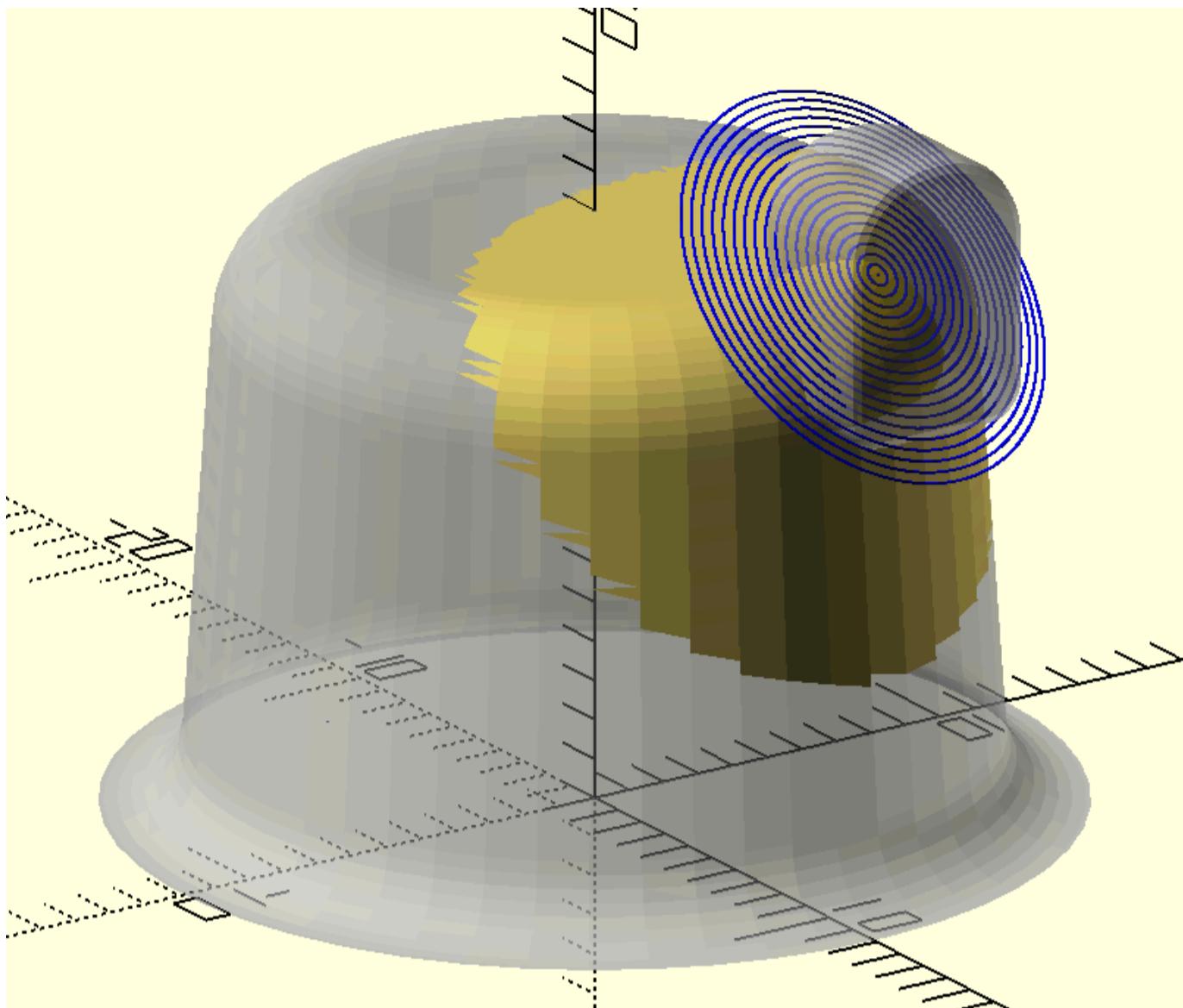
i_p1=shield(sol1,sol2,100,20,4,23)
v,f1=partial_surface(sol1,prism_center(sol2),10)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
%{swp(sol1)}
%{swp(sol2)}
color("blue") for(p={i_p1})for(p1=p)p_line3dc(p1,.05,rec=1);
polyhedron({v},{f1});

    ''')
t1=time.time()
t1-t0

# len(ip2),len(ip3),len(ip4)
```

Out[45]: 0.8456509113311768



```
In [32]: i_t=time.time()
sec1=circle(55)
path1=corner_radius(pts1([[-50,0],[50,0,.2],[0,30,3],[6,1,3],[0,6,3],[-4,2,3],[0,22,6],[8,2,6],[0,10,.2],[-50,0]]),10)
# path1=equidistant_path(path1,200)
sec2=circle(7.5)
path2=corner_radius(pts1([[-5,0],[5,0,5],[0,35,2],[-5,0]]),10)
path2=equidistant_path(path2,100)
sol1=prism(sec1,path1)
sol2=translate([57.5,0,37],prism(sec2,path2))
sol2=axis_rot_o([0,0,1],sol2,180)

v,f1=partial_surface(sol1,prism_center(sol2),30)

i_p1=ip_tri2sol(v,f1,cpo(sol2))
p1=[p[0] for p in i_p1]
p2=[p[-1] for p in i_p1]
p3=flip(p1)+p2

fillet1=i_line_tri_fillet(v,f1,sol2,p3,3,-3,s=20)

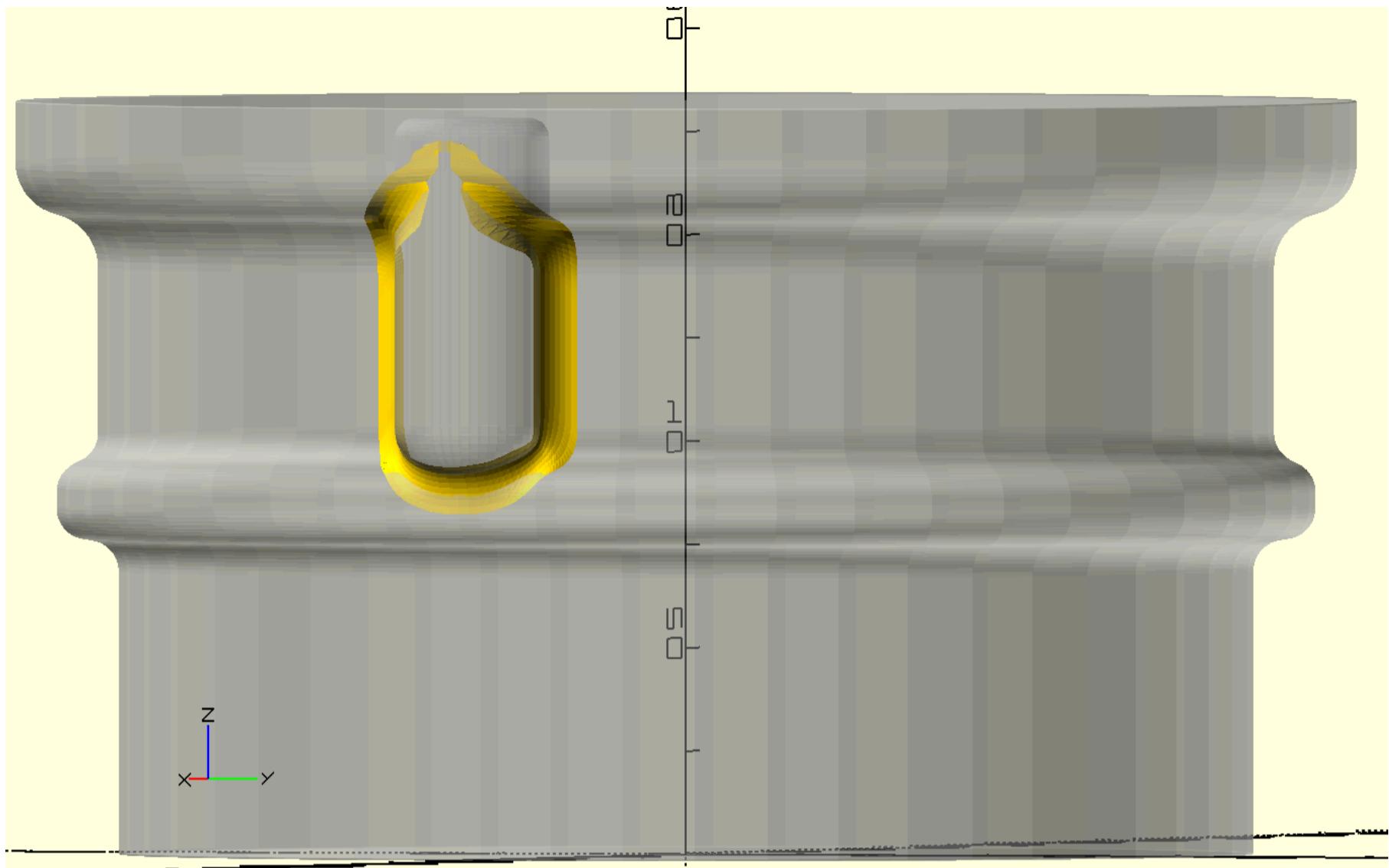
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>

        %swp(sol1)
        %swp(sol2)
        //polyhedron({v},{f1});

        {swp_c(fillet1)}
    ''')

f_t=time.time()
f_t-i_t
# len(p3),len(p4),len(p5)
```

Out[32]: 2.132855176925659



```
In [31]: t1=time.time()

p1=[[0,-15,.5],[6,0,.3],[0,-16,.1],[1,-1,.1],[4,0,.2],[2,10,4],[35,0,10],
     [5,22,5],[-5,22,10],[-35,0,4],[-2,10,.2],[-4,0,.1],[-1,-1,.1],[0,-16,.3],
     [-6,0,.5]]
sec1=corner_radius(pts1(p1),10)
path1=c2t3(circle(10,s=72))
sol1=path_extrude_closed(sec1,path1)

sec3=circle(7,s=100)
path2=corner_radius(pts1([[2,0],[-2,31]]),10)

sol3=translate([51,0,12],prism(sec3,path2))
v,f1=partial_surface(sol1,prism_center(sol3),30)
p2=ip_tri2sol(v,f1,sol3)
p2=[p[0] for p in p2]
fillet1=i_line_tri_fillet(v,f1,sol3,p2,3,-3)

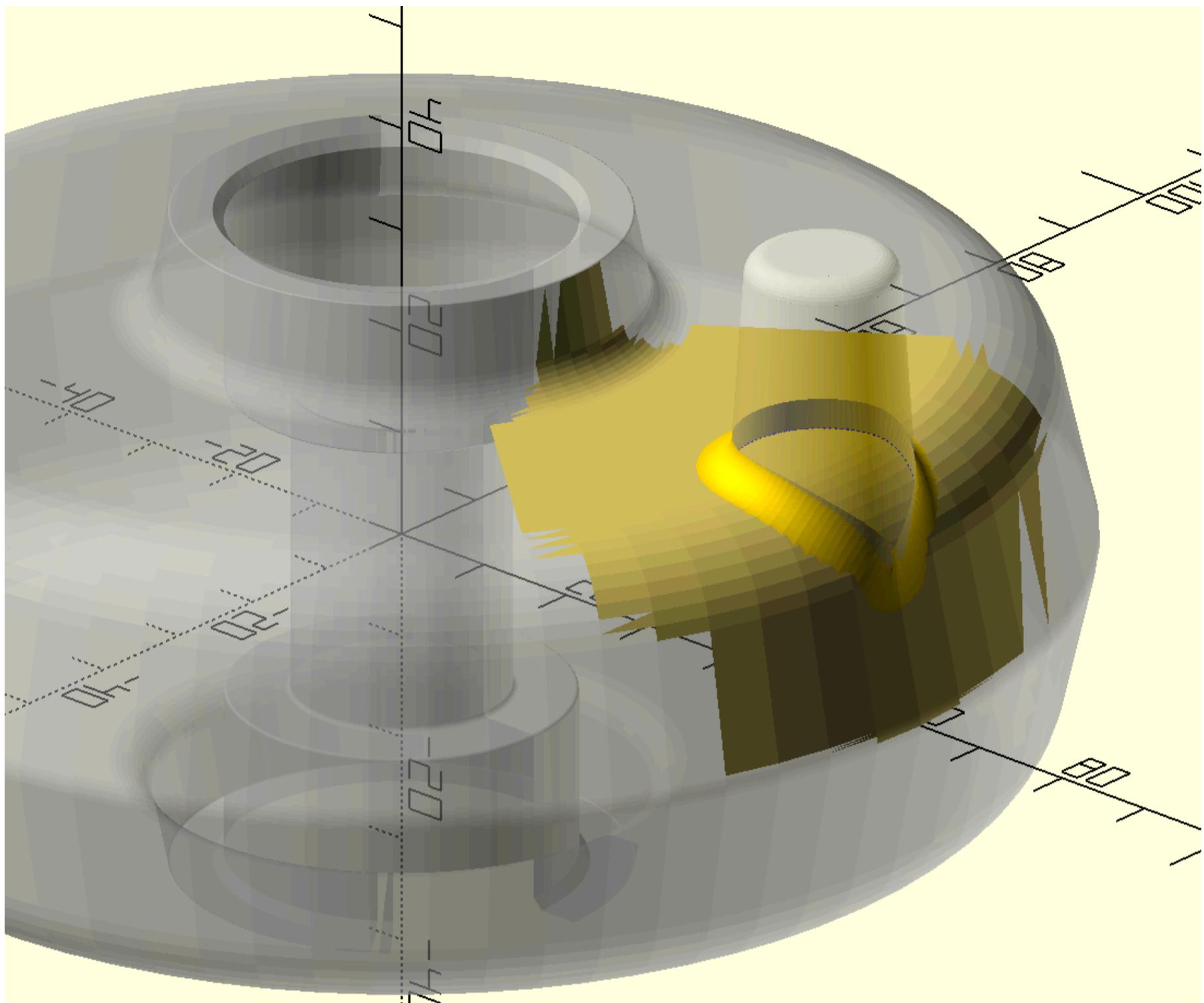
f3=end_cap(sol3,2)[1]
with open('trial.scad','w+')as f:
    f.write(f'''
include<dependencies2.scad>

%{swp_c(sol1)}
%difference(){
{swp(sol3)}
{swp_c(f3)}
}
{swp_c(fillet1)}
polyhedron({v},{f1});
color("blue")points({p2},.2);

    ''')

t2=time.time()
t2-t1
# len(p1),len(p2),len(p3)
```

Out[31]: 0.47414708137512207



```
In [130]: i_t=time.time()

r=26.27
cp1,cp2,cp3,cp4=[0,0],[0,r],[r*cos(d2r(90+120)),r*sin(d2r(90+120))],[r*cos(d2r(90+240)),r*sin(d2r(90+240))]
r1,r2=22.5,6
a1=t_cir_tarc(r1,r2,cp1,cp2,7.5,0)
a2=t_cir_tarc(r1,r2,cp1,cp2,7.5,1)
a3=t_cir_tarc(r1,r2,cp1,cp3,7.5,0)
a4=t_cir_tarc(r1,r2,cp1,cp3,7.5,1)
a5=t_cir_tarc(r2,r1,cp4,cp1,7.5,1)
a6=t_cir_tarc(r2,r1,cp4,cp1,7.5,0)

a12=arc_2p(a1[-1],a2[0],r2,-1)[1:-1]
a23=arc_2p(a2[-1],a3[0],r1,-1)[1:-1]

a34=arc_2p(a3[-1],a4[0],r2,-1)[1:-1]
a45=arc_2p(a4[-1],a5[0],r1,-1)[1:-1]

a56=arc_2p(a5[-1],a6[0],r2,-1)[1:-1]
a61=arc_2p(a6[-1],a1[0],r1,-1)[1:-1]

sec1=a1+a12+a2+a23+a3+a34+a4+a45+a5+a56+a6+a61

path1=corner_radius(pts1([[-22,0],[22,0],[0,3],[-22,0]]),10)
sol1=prism(sec1,path1)

sec2=circle(33.75/2,s=100)
path2=corner_radius(pts1([[0,0.001],[0,8.63],[-1.125,0],[0,3.75],[1.125,0],[0,7.5],[-1.125,0],[0,3.75],[1.125,0],[0,5.63]]),10)
sol2=prism(sec2,path2)

fillet1=ip_fillet_closed(sol1,sol2,-1.88,1.88)

sol3=translate([0,0,-.1],linear_extrude(circle(14.06,s=100),30))

sol4=translate([0,0,-.1],linear_extrude(circle(2.81,[0,26.27]),4))
sol4=[q_rot([f'z{i}'],sol4) for i in [0,120,240]]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
//color("magenta")p_line({sec1},.1);

difference(){
union(){{
```

```

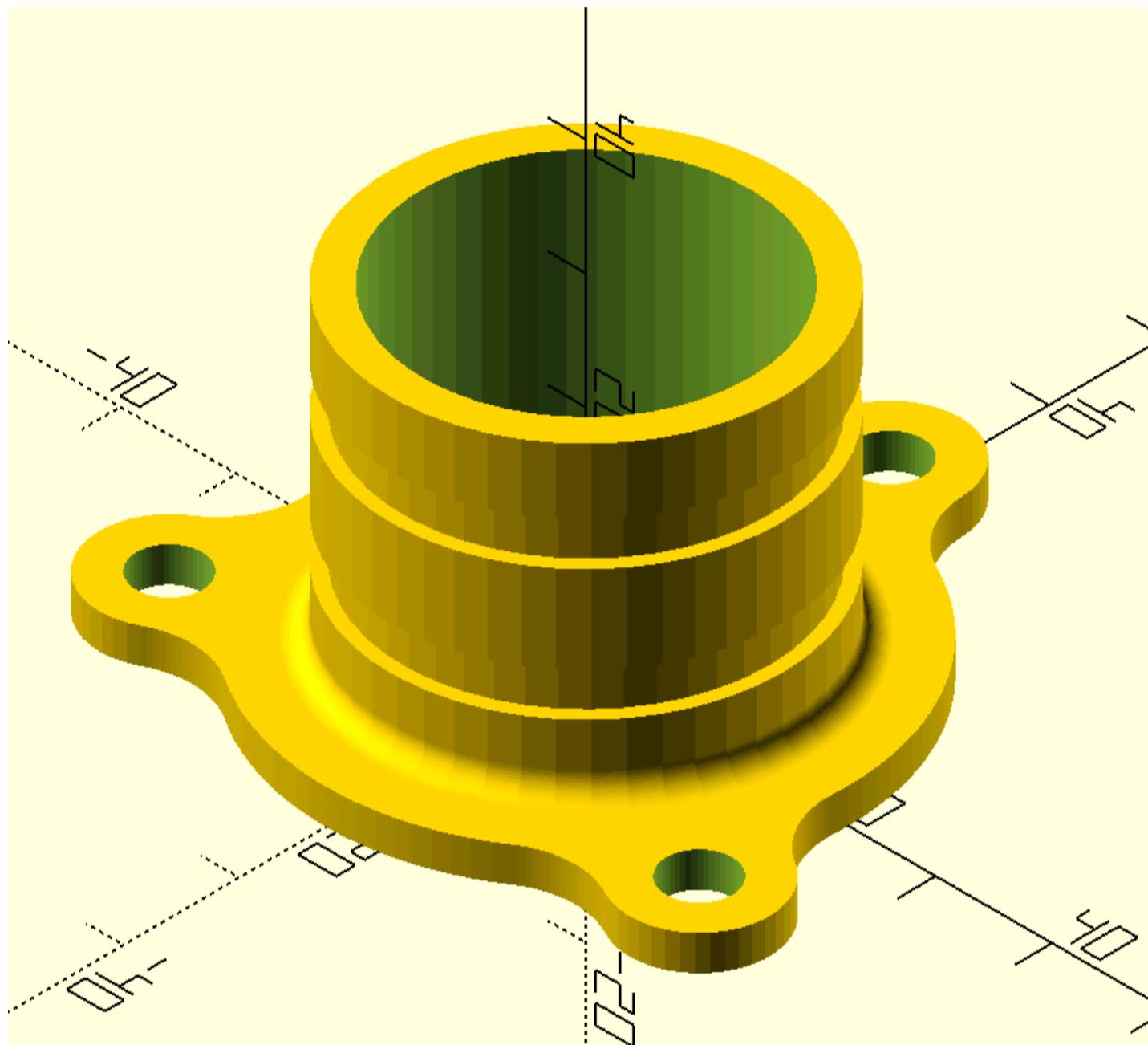
{swp(sol1)}
{swp(sol2)}
}
{swp(sol3)}
for(p={sol4})swp(p);

}
{swp_c(fillet1)
'''}

f_t=time.time()
f_t-i_t

```

Out[130]: 5.693842887878418



```

In [76]: i_t=time.time()

sec1=r_sec(60,60,[-55/2,0],[55/2,0],s=50)[:-1]
path1=corner_radius(pts1([[0,0],[0,8],[-14.5,0,2],[0,24,20],[-25,0]]),10)

sol1=prism(sec1,path1)
sol1=sol1+[sort_points(sol1[-1],[[0,0,24+8]])]
sec2=offset(sec1,-22.5)
path2=corner_radius(pts1([[0,-0.01],[0,24.01,12],[-12-25.5,0]]),10)
sol2=prism(sec2,path2)
sol2=sol2+[sort_points(sol2[-1],[[0,0,24]])]

sec3=circle(8)
path3=corner_radius(pts1([[0,16],[0,27,2],[7,0,2],[0,5]]),10)
sol3=prism(sec3,path3)

fillet1=ip_fillet_closed(sol1,sol3,-2,2,style=2)
fillet2=ip_fillet_closed(sol2,flip(sol3),-2,2,style=2)

sol4=translate([34.75,0,28],linear_extrude(circle(9),8))
fillet3=ip_fillet_closed(sol1,sol4,-2,2,style=2)

sol5=translate([0,0,16-.5],linear_extrude(circle(4),33))
sol6=translate([34.75,0,24-.5],linear_extrude(circle(5),13))

sol7=translate([0,52.5,-.1],linear_extrude(circle(4),9))
sol8=[translate([-55/2,0,0],q_rot([f'z{i}'],sol7)) for i in [0,60,120,180]]
sol9=[translate([55/2,0,0],q_rot([f'z{i}'],sol7)) for i in [0,-60,-120,-180]]

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
//color("blue")p_line({sec1},.05);
//color("blue")p_lineo({path1},.2);
sol8={sol8};
sol9={sol9};
difference(){{
union(){{
difference(){{
{swp(sol1)}}

```

```

{swp(sol2)}
for(i=[0,1,2,3])swp(sol8[i]);
for(i=[0,1,2,3])swp(sol9[i]);
}
{swp(sol3)}
{swp(sol4)}
}
{swp(sol5)}
{swp(sol6)}
}

{swp_c(fillet1)}
{swp_c(fillet2)}
{swp_c(fillet3)}

//color("blue")for(p={sol1})p_line3dc(p,.2,rec=1);
'''

f_t=time.time()
f_t-i_t

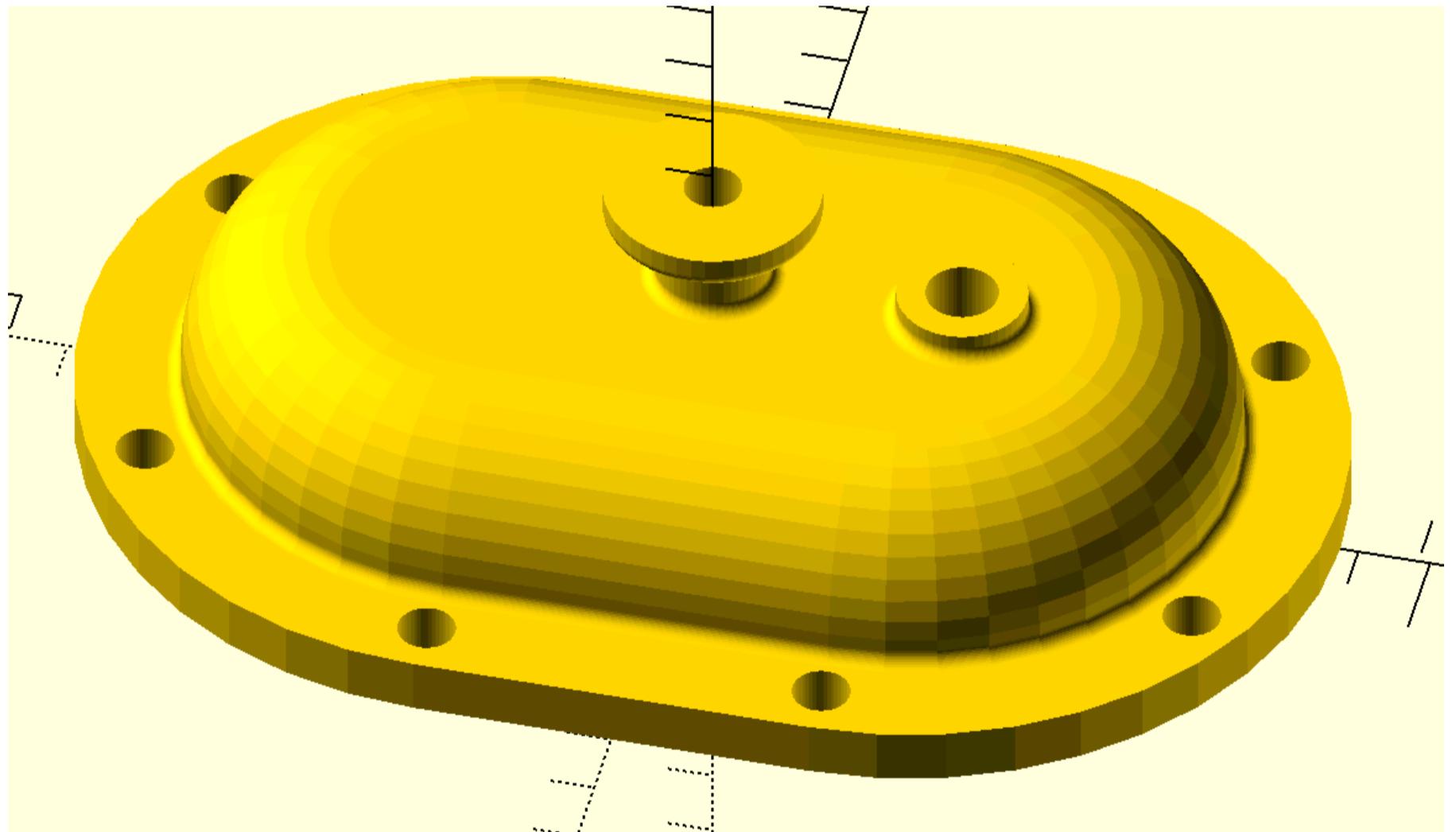
```

```

/Users/sanjeevprabhakar/openscad/openscad2.py:4778: RuntimeWarning: invalid value encountered in divide
    t=einsum('kl,ijkl->ijk',cross(p01,p02),la[:, :,None]-p0)/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad2.py:4779: RuntimeWarning: divide by zero encountered in divide
    u=einsum('ijkl,ijkl->ijk',cross(p02[None,None,:,:],(-lab)[:, :,None,:]),(la[:, :,None,:]-p0[None,None,:,:]))/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad2.py:4780: RuntimeWarning: divide by zero encountered in divide
    v=einsum('ijkl,ijkl->ijk',cross((-lab)[:, :,None,:],p01[None,None,:,:]),(la[:, :,None,:]-p0[None,None,:,:]))/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad2.py:4781: RuntimeWarning: invalid value encountered in add
    condition=(t>=0)&(t<=1)&(u>=0)&(u<=1)&(v>=0)&(v<=1)&(u+v<1)
/Users/sanjeevprabhakar/openscad/openscad2.py:4778: RuntimeWarning: divide by zero encountered in divide
    t=einsum('kl,ijkl->ijk',cross(p01,p02),la[:, :,None]-p0)/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad2.py:4779: RuntimeWarning: invalid value encountered in divide
    u=einsum('ijkl,ijkl->ijk',cross(p02[None,None,:,:],(-lab)[:, :,None,:]),(la[:, :,None,:]-p0[None,None,:,:]))/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad2.py:4783: RuntimeWarning: invalid value encountered in multiply
    a=(la[:, :,None,:]+lab[:, :,None,:])*t[:, :,None,:]

```

Out[76]: 4.0440778732299805



```

In [116]: i_t=time.time()

a1=c2t3(arc_2p([0,0],[5,28],58,-1))
a2=flip(c2t3(arc_2p([-1,2],[3,28],56,-1)))

a3=[[-5,0,0],[0,0,3]]+a1[2:-1]+[[5,28,.9],[3,28,.9]]+a2[1:-1]+[[-1,2,2],[-5,2,0]]
path1=corner_radius(a3,10)
sec1=circle(43/2,s=100)
sol1=prism(sec1,path1)

c1=circle(7.75,[10,18])
p0=[0,8]
p1=p_cir_t(p0,c1)
p2=c1[19]
a4=arc_long_2p(p1,p2,7.75,-1,s=50)
path2=cytz([p0]+a4)
sec2=circle(2,s=60)
sol2=translate([18.7,0,-3],align_sol_1(path_extrude_open(sec2,path2)))

a5=[[-5,0,0],[0,0,5]]+a1[1:-1]+[[5,28,1],[3,28,0]]
path3=corner_radius(a5,10)
sol3=prism(sec1,path3)
fillet1=ip_fillet(sol1,sol2[:-10],-2,2,style=2)
fillet2=ip_fillet_closed(sol3,flip(sol2[30:]),2,2,style=2)

```

```

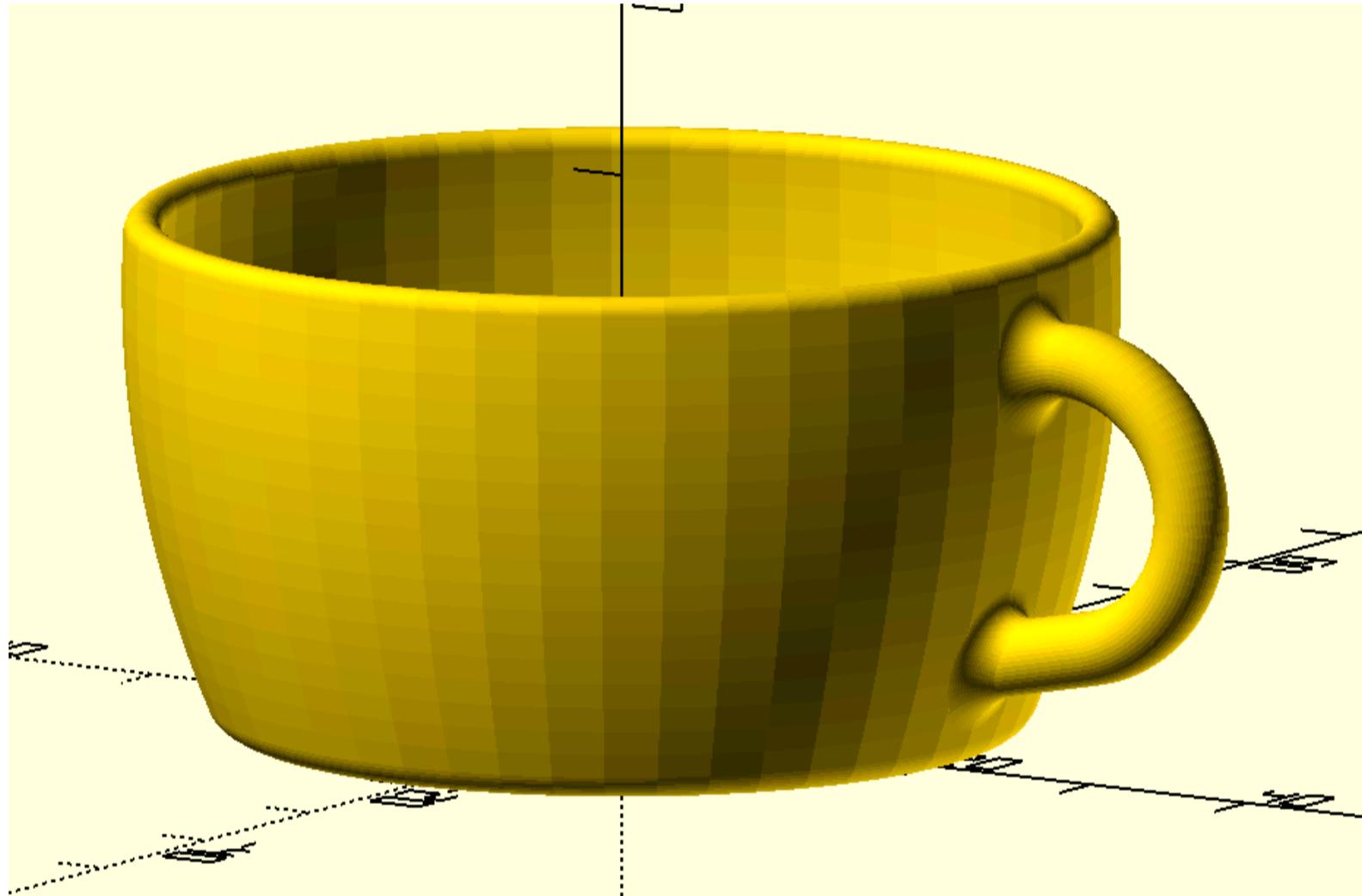
l1=ip_sol2sol(sol1,sol2[:-10])
l2=i_p_p(sol2,l1,2)
l3=o_3d_rev(l1,sol1,-2,edges_closed=1)
sol4=cut_plane([0,-1,0],[100,100],100)
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>

difference() {{
union() {{
{swp(sol1)}
difference() {{
{swp(sol2[:-10])}
{swp(sol3)}
}}
{swp(cpo(fillet1)[:-1])}
{swp(cpo(fillet2)[:-1])}
}}
//{swp(sol4)}
}}
''')

f_t=time.time()
f_t-i_t

```

Out[116]: 24.877924919128418



```

In [53]: sec=corner_radius(pts1([[-2.5,-2.5,0],[5,0,2.5],[0,2.5,0.5],[5,0,0]]),10)

with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>
        color("blue")p_lineo({sec},.05);
    ''')

```

```

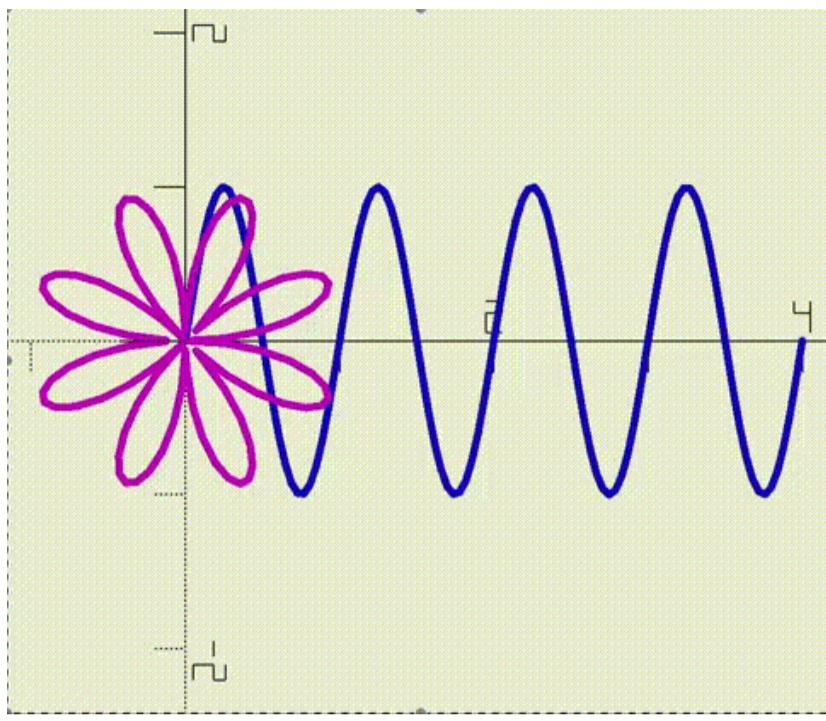
In [23]: s=100
x=2
a=linspace(0,4,s)
b=sin(d2r(720/x*a))

theta=720/x*a
c=cos(d2r(theta))
d=sin(d2r(theta))
e=array([[cos(d2r(i)),sin(d2r(i))] for i in linspace(0,360,s)])
e=einsum('ij,i->ij',e,abs(b).tolist())
sw=array([a,b]).transpose(1,0).tolist()

with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies.scad>
        e={e};
        sw={sw};
        color("blue")p_lineo(loop(sw,0,100*$t),.05);
        color("magenta")p_lineo(loop(e,0,100*$t),.05);

    ''')

```



```
In [10]: s=200
x=2
a=linspace(0,4,s)
b=sin(d2r(270/x*a))

theta=270/x*a
c=cos(d2r(theta))
d=sin(d2r(theta))
e=array([[cos(d2r(i)),sin(d2r(i))] for i in linspace(0,360,s)])
e=einsum('ij,i->ij',e,abs(b)).tolist()
sw=array([a,b]).transpose(1,0).tolist()

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies.scad>
e={e};
sw={sw};
color("blue")p_lineo(loop(sw,0,200*$t),.05);
color("magenta")p_lineo(loop(e,0,200*$t),.05);

''' )
```

```
In [20]: # 3d knots various types
t0=time.time()
# trefoil knot

# path=[[10*(sin(t)+2*sin(2*t)),
#        10*(cos(t)-2*cos(2*t)),
#        -10*sin(3*t)] for t in d2r(arange(0,360))]

# circular sin theta knot

# path=[[60*(cos(t)),
#        60*(sin(t)),
#        20*sin(4*t)*cos(4*t)] for t in d2r(arange(0,360))]

# random knot

# path=[[20*(-0.22*cos(t) - 1.28*sin(t) - 0.44*cos(3*t) - 0.78*sin(3*t)),
#        20*(-0.1*cos(2*t) - 0.27*sin(2*t) + 0.38*cos(4*t) + 0.46*sin(4*t)),
#        20*(0.7*cos(3*t) - 0.4*sin(3*t))] for t in d2r(arange(0,360))]

# torus knots

# path=[[10*cos(3*t)*(3+cos(4*t)),
#        10*sin(3*t)*(3+cos(4*t)),
#        10*sin(4*t)] for t in d2r(arange(0,360))]

# cinquefoil torus knots
# a,p,q=3,3,16
# d=10

# explanation
# radius of the torus = a*d
# section radius of the torus = d
# p in number of cycles of the wrapping coil over torus
# q in the number of turns of the wrapping coil over torus

# path=[[d*cos(p*t)*(a+cos(q*t)),
#        d*sin(p*t)*(a+cos(q*t)),
#        -d*sin(q*t)] for t in d2r(arange(0,360,1))]

# Lissajous knots

path=[[10*cos(3*t+5),
       10*cos(3*t+10),
       10*cos(3*t+2)] for t in d2r(arange(0,360))]
r=2
sec=circle(r)
sol=align_sol_1(path_extrude_closed(sec,path))
```

```

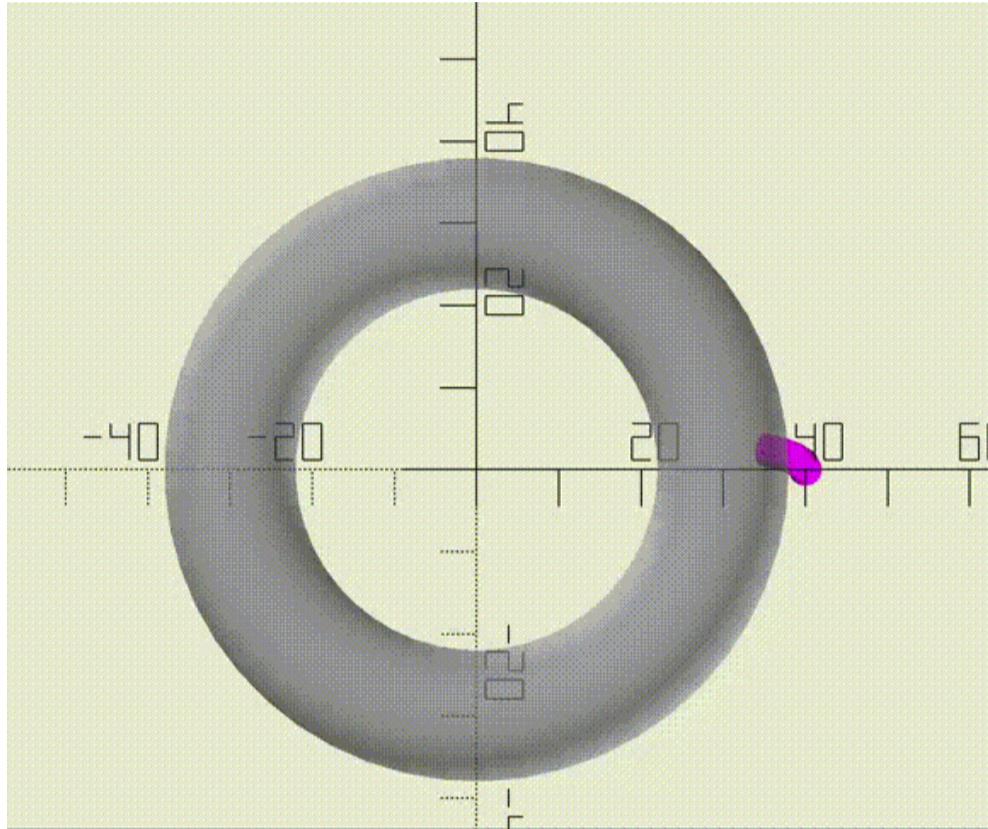
# sec1=circle(d-r)
# path1=c2t3(circle(a*d))
# sol1=path_extrude_closed(sec1,path1)

with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies.scad>
//color("blue")p_line3d({path},4);
sol={sol};
//color("magenta")swp_c(loop(sol,0,360*$t));
//color([.2,.5,.7,.3])
{swp_c(sol)}

//%{swp_c(sol1)}
'''')
t1=time.time()
t1-t0

```

Out[20]: 2.4420342445373535



```

In [143...]:
sec=circle(25)
path=corner_radius(pts1([[0,0,0],[0,15,1],[-6,50,1],[0,18,0]]),10)
sol=prism(sec,path)
sol1=prism(circle(24),path)
sol0=swp_prism_h(sol,sol1)
sec2=circle(15)
path2=cr_3d([[0,0,15,0],[-60,0,40,20],[0,0,30,0]],10)
sol2=path_extrude_open(sec2,path2,twist=1)
sol3=path_extrude_open(offset(sec2,-1),path2,twist=1)
sol02=swp_prism_h(sol2,sol3)
fillet1=ip_fillet_closed(sol,sol2,-5,5,style=2)

sec3=corner_radius(pts1([[0,0],[-2,1,.2],[2,1]]),10)
path3=helix(14,2.5,6,5)
sol4=path_extrude_open(sec3,path3)

sol4=sol2vector([0,0,1],sol4,[-60,0,70])
with open('trial.scad','w+') as f:
    f.write(f'''
difference(){
{swp_c(sol0)}
{swp_c(sol3)}
}
difference(){
{swp_c(sol2)}
{swp_c(sol)}
}
{swp_c(fillet1)}
intersection(){
color("blue"){swp(sol4)}
{swp_c(sol3)}
}
'''')
'''')

```

sinwave-box

```

In [7]: i_t=time.time()
# sinwave glass
height=125
dia=100
width=pi*dia
factor=round(width/height,0)
sec=[[i,j,1*sin(d2r(i*360/height*3))*sin(d2r(j*360/width*3*factor))] for j in linspace(0,width,150) for i in linspace(0,height,100)]
# path=translate([0,100/pi/2,100/pi/2],q_rot(['y90'],arc(100/pi/2,0,400,s=200)))
path=q_rot(['y90'],arc(dia/2,0,400,s=200))

surf1=[wrap_around(p,path)[:-1] for p in sec]

```

```

surf2=offset_sol(surf1,-2)

sol1=q_rot(['y-90'],swp_prism_h(surf2,surf1))
sol2=q_rot(['y-90'],surf1[:2])

p0=sol1[2][:-1]
p1=sol1[15][:-1]
p2=offset_3d(p0,-15)
fillet1=convert_3lines2fillet_closed(p2,p1,p0,s=30)

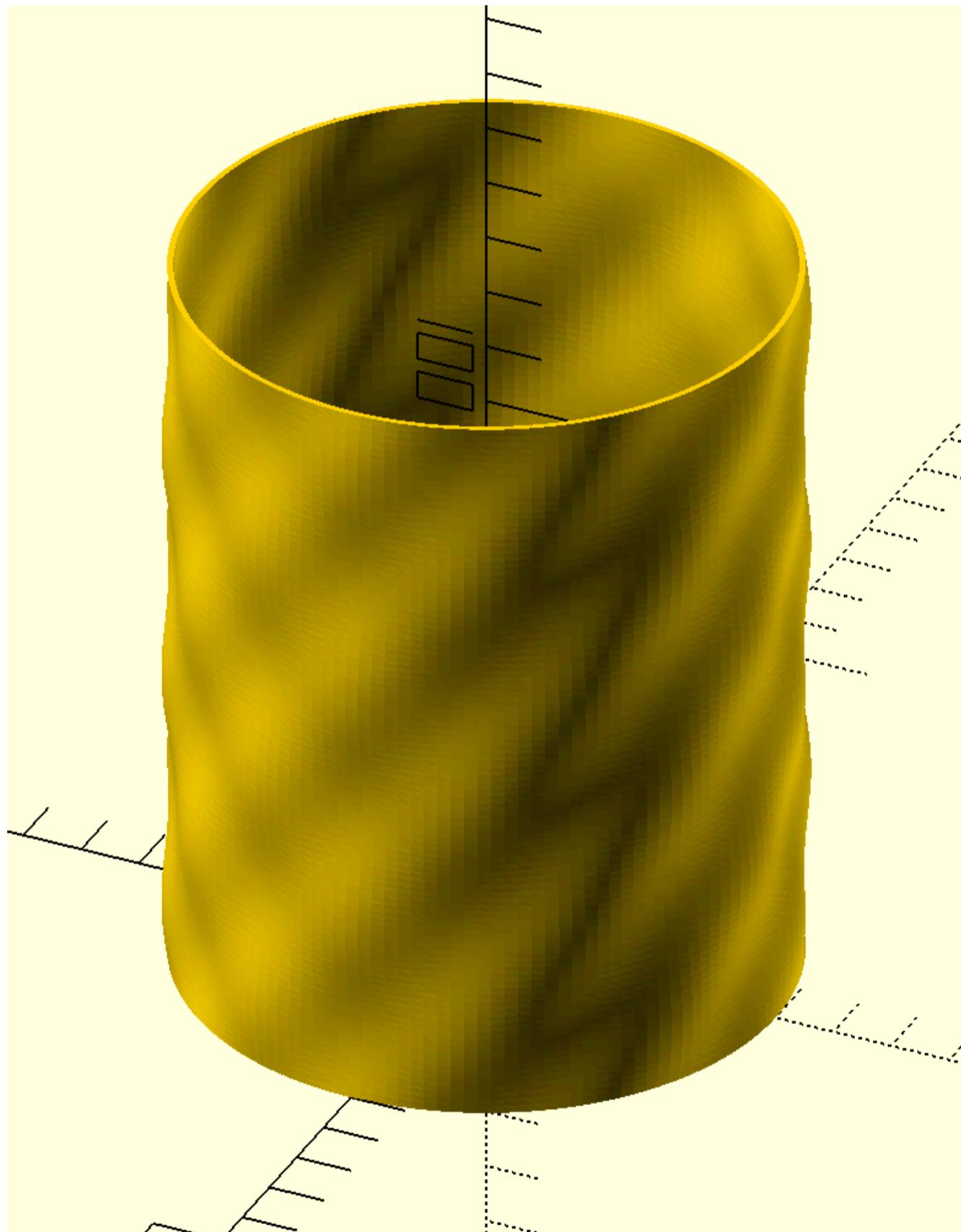
sol3=flip(sol1)[-15:]+flip(cpo(fillet1)[1:-1])

sol4=cut_plane([-1,0,0],[300,300],300,0,0,0)
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>
        difference(){
            {swp(sol3)}
            //{{swp(sol4)}}

        }
    ''')
f_t=time.time()
f_t-i_t

```

Out [7]: 2.3556830883026123



```

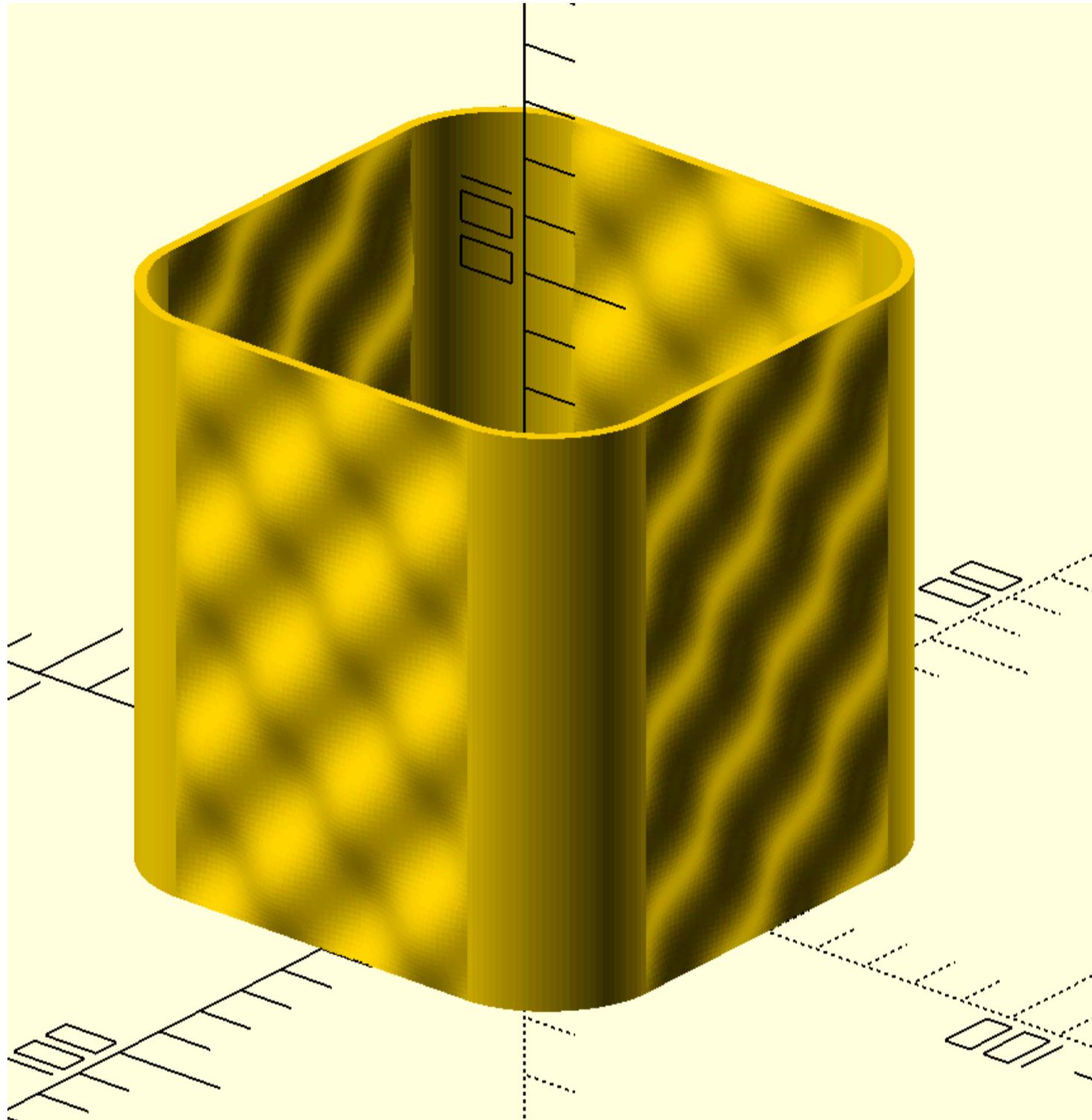
In [8]: i_t=time.time()
# sinwave_box
w1=q_rot(['x90'],sinewave(100,3,2,100))
w2=q_rot(['x90','z90'],sinewave(60,1,2,60))
s1=translate([50,-30,0],q_rot(['y-90'],surface_from_2_waves(w1,w2,1.5)))
s2=[cpo(q_rot(['f'z{i}'],s1)) for i in [0,90,180,270]]
l1=s2[0][-1]
l2=s2[1][0]
l3=translate([0,20,0],l1)
f1=cpo(convert_3lines2fillet(l1,l2,l3,s=30))[:-1]
f2=[q_rot(['f'z{i}'],f1[1:-1]) for i in [0,90,180,270]]
s3=cpo(s2[0]+f2[0]+s2[1]+f2[1]+s2[2]+f2[2]+s2[3]+f2[3])
s4=offset_sol(s3,-2)
sol=s3+flip(s4)[-2]
l1=flip(s4)[-6]

```

```

l2=flip(s4)[-3]
l3=offset_3d(l2,-3)
f3=convert_3lines2fillet_closed(l3,l1,l2,s=20)
with open('trial.scad','w+') as f:
    f.write(f'''
        union(){{}
{swp(sol)}
{swp_c(f3)}
}}
```

Out [8]: 5.954119920730591



q_rot2d

translate_2d

```

In [4]: c1=circle(22.5)
c2=translate_2d([26.25,0],circle(6))
c3=[q_rot2d(i,c2) for i in [0,120,240]]

a1=t_cir_tarc(22.5,6,[0,0],[26.25,0],7.5)
p0,p1=a1[0],a1[-1]

a2=t_cir_tarc(22.5,6,[0,0],[26.25,0],7.5,side=1)
p2,p3=a2[0],a2[-1]
p4=q_rot2d(120,p0)

sec=arc_2p(p0,p1,7.5,cw=1)+arc_2p(p1,p2,6,cw=-1)+ \
arc_2p(p2,p3,7.5,cw=1)+arc_2p(p3,p4,22.5,cw=-1)

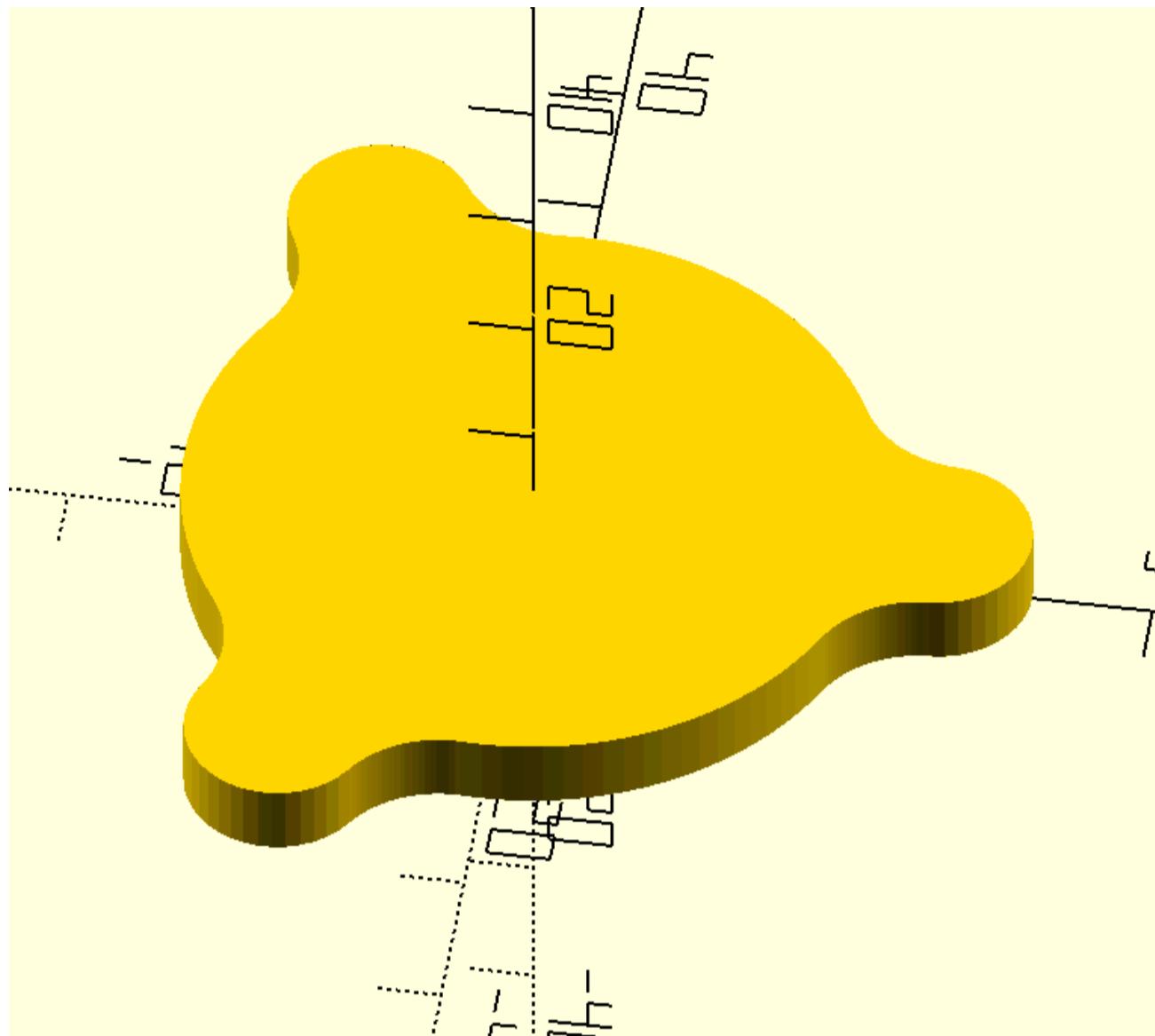
sec=[q_rot2d(i,sec) for i in [0,120,240]]

sec=remove_extra_points(concatenate(sec).round(5))

sol=linear_extrude(sec,5)

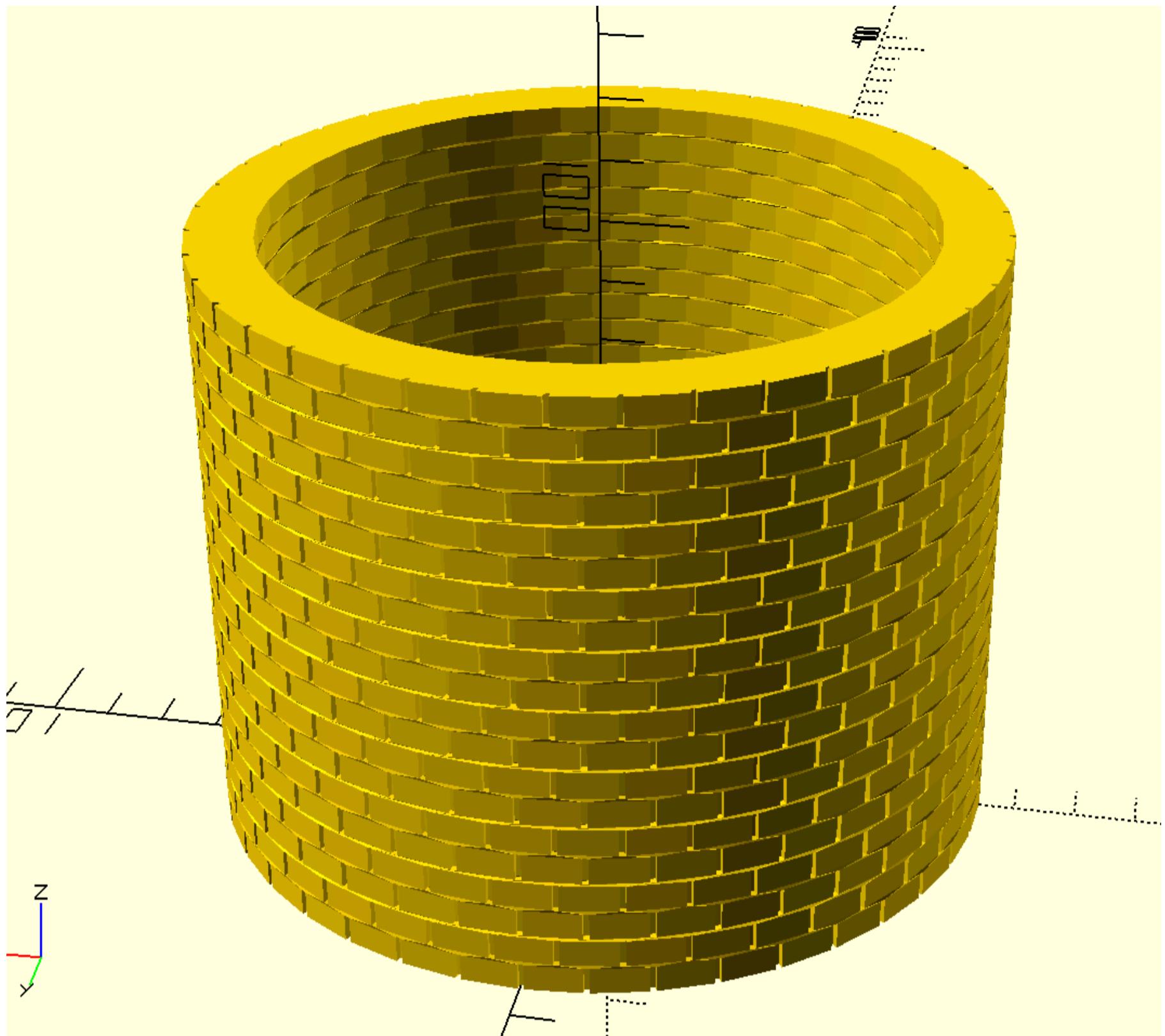
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>
//color("blue",.2)p_line3dc({c1},.3);
```

```
//color("magenta",.2)for(p={c3})p_line3dc(p,.3);
//color("cyan")p_line3dc({sec},.5);
//color("blue")points({[p4]},1);
{swp(sol)}
...
)
```



```
In [190... peri=400
height=100
sec=corner_radius(pts1([[0,0],[9,0],[0,1],[1,0]]),10)
sec=concatenate([translate_2d([i,0],sec) for i in arange(0,peri,10)]).tolist()
sec=translate([0,1,0],q_rot(['x90','z90'],sec))
path=q_rot(['y90'],arc(401.07/(2*pi),0,360,s=100))
sec=q_rot(['y-90'],wrap_around(sec,path))
sec1=translate([0,0,5],sec)
sec2=offset_3d(sec1,-.5,2)
sec3=q_rot(['z5'],translate([0,0,5.5],sec))
sec4=offset_3d(sec3,-.5,2)
sec5=translate([0,0,5],sec3)
sec6=translate([0,0,5],sec4)
sec7=translate([0,0,11],offset_3d(sec,-.5,2))
sec8=translate([0,0,11],sec)

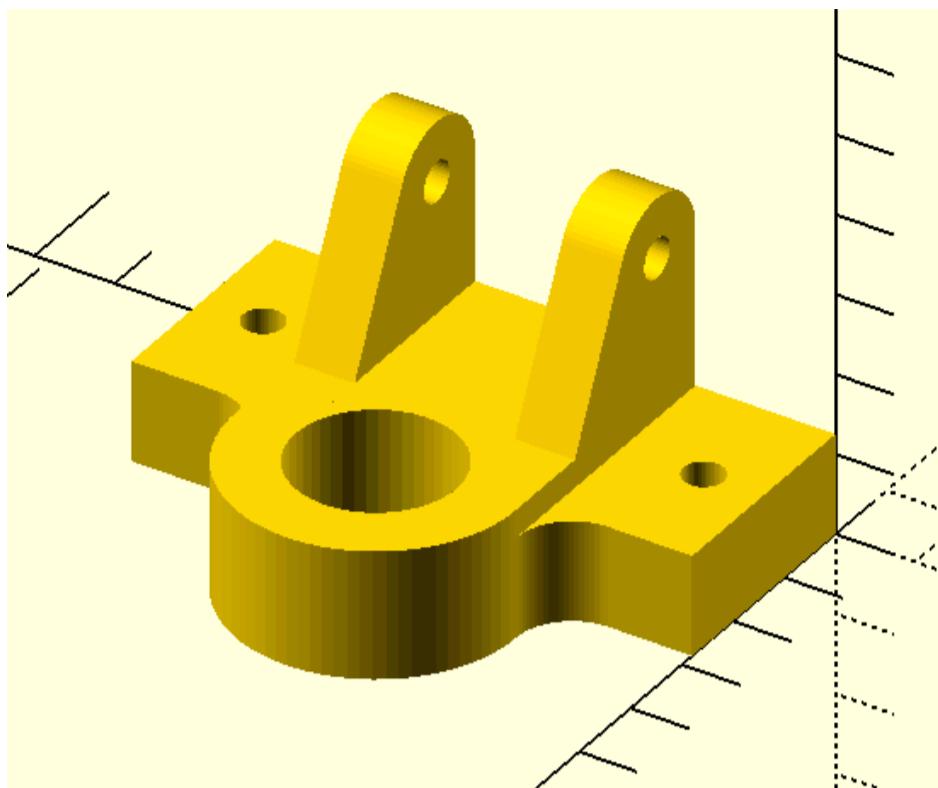
sol=[sec,sec1,sec2,sec4,sec3,sec5,sec6,sec7,sec8]
sol1=concatenate([ translate([0,0,i],sol) for i in range(0,110,11)]).tolist()
a=[0,5,5.5,5.5,10.5,10.5,11,11]
b=[10,10,9,9,10,10,9,9,10]
sol2=[translate([0,0,a[i]],offset(c3t2(sol[i]),-b[i],2)) for i in range(len(a))]
sol2=concatenate([ translate([0,0,i],sol2) for i in range(0,110,11)]).tolist()
sol3=swp_prism_h(sol1[:-2],sol2[:-2])
with open('trial.scad','w+') as f:
    f.write(f'''
include<dependencies2.scad>
{swp_c(sol3)}
...
)
```



```
In [5]: sec=corner_radius(pts1([[0,0],[70,0],[0,28],[-17.5,0,7],[0,24.5,17.5],  
[-35.01,0,17.5],[0,-24.5,7],[-17.5,0]]),20)  
  
cp_1=cp_arc(sec[26:30])  
c1=circle(10,cp_1)  
c2=circle(2.5,[7.5,14])  
c3=circle(2.5,[62.5,14])  
sol1=linear_extrude(sec,16)  
sol2=[translate([0,0,-.5],linear_extrude(p,17)) for p in [c1,c2,c3]]  
sol3=translate([-52.5+29,16],cube([18,40,20]))  
sol4=translate([70-17.5,-5,12.5],cube([18,40,20]))  
c4=circle(7.5,[-7.5,32.5])  
p0=[0,0]  
p1=p_cir_t(p0,c4)  
p3=[-52.5+29,16]  
p2=cir_p_t(c4,p3)  
p4=[-52.5+17.5,16]  
p5=[-52.5+17.5,0]  
c5=circle(2.5,[-7.5,32.5])  
sec1=[p0]+arc_2p(p1,p2,7.5,-1,30)+[p3,p4,p5]  
  
sol5=linear_extrude(sec1,7.5)  
sol6=translate([0,0,-.5],linear_extrude(c5,9))  
with open('trial.scad','w+') as f:  
    f.write(f'''  
        include<dependencies2.scad>  
        //color("blue")p_line3d({sec},.2,1);  
        //color("magenta")p_line3d({c1},.2,1);  
        //color("magenta")p_line3d({c2},.2,1);  
        //color("magenta")p_line3d({c3},.2,1);  
        //color("blue")points({[p0,p1,p2,p3,p4,p5]},.5);  
        //color("magenta")p_line3dc({sec1},.2,1);  
        for(i=[17.5,17.5+35-7.5])  
            translate([i+7.5,0,0])  
            rotate([90,0,-90])  
            difference(){  
                {swp(sol5)}  
                {swp(sol6)}  
            }  
  
            difference(){  
                {swp(sol1)}  
                for(p={sol2})swp(p);  
                {swp(sol3)}  
                {swp(sol4)}  
            }  
    ''')
```

```
}}
```

```
...)
```



sinewave

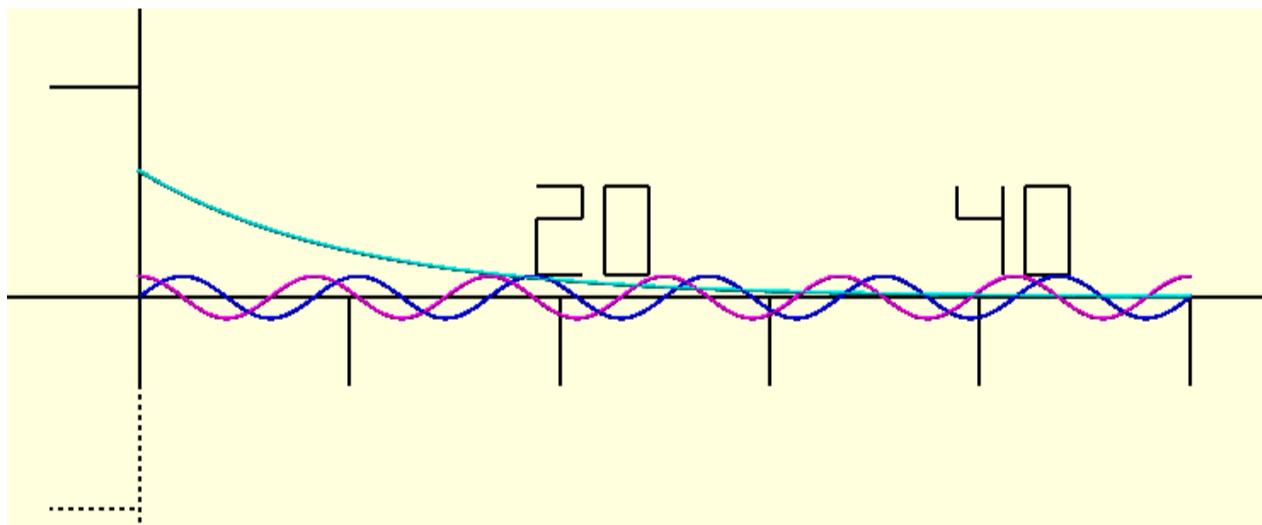
cosinewave

e_wave

```
In [9]: wav1=sinewave(50,6,1,200)
wav2=cosinewave(50,6,1,200)
wav3=e_wave(50,6,.1,200)
```

```
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>
color("blue") p_line3d({wav1},.2);
color("magenta") p_line3d({wav2},.2);
color("cyan") p_line3d({wav3},.2);
```

```
...)
```



```
In [10]: wav1=sinewave(50,6,1,200)
wav2=sinewave(50,9,1,200)
```

```
a=[[wav1[i][0] , wav1[i][1]*wav2[i][1] ] for i in range(len(wav1))]
# b=[[wav1[i][0] , wav1[i][1]*wav2[i][1] ] for i in range(len(wav1))]

b=q_rot(['x90'],a)
c=q_rot(['x90','z90'],a)

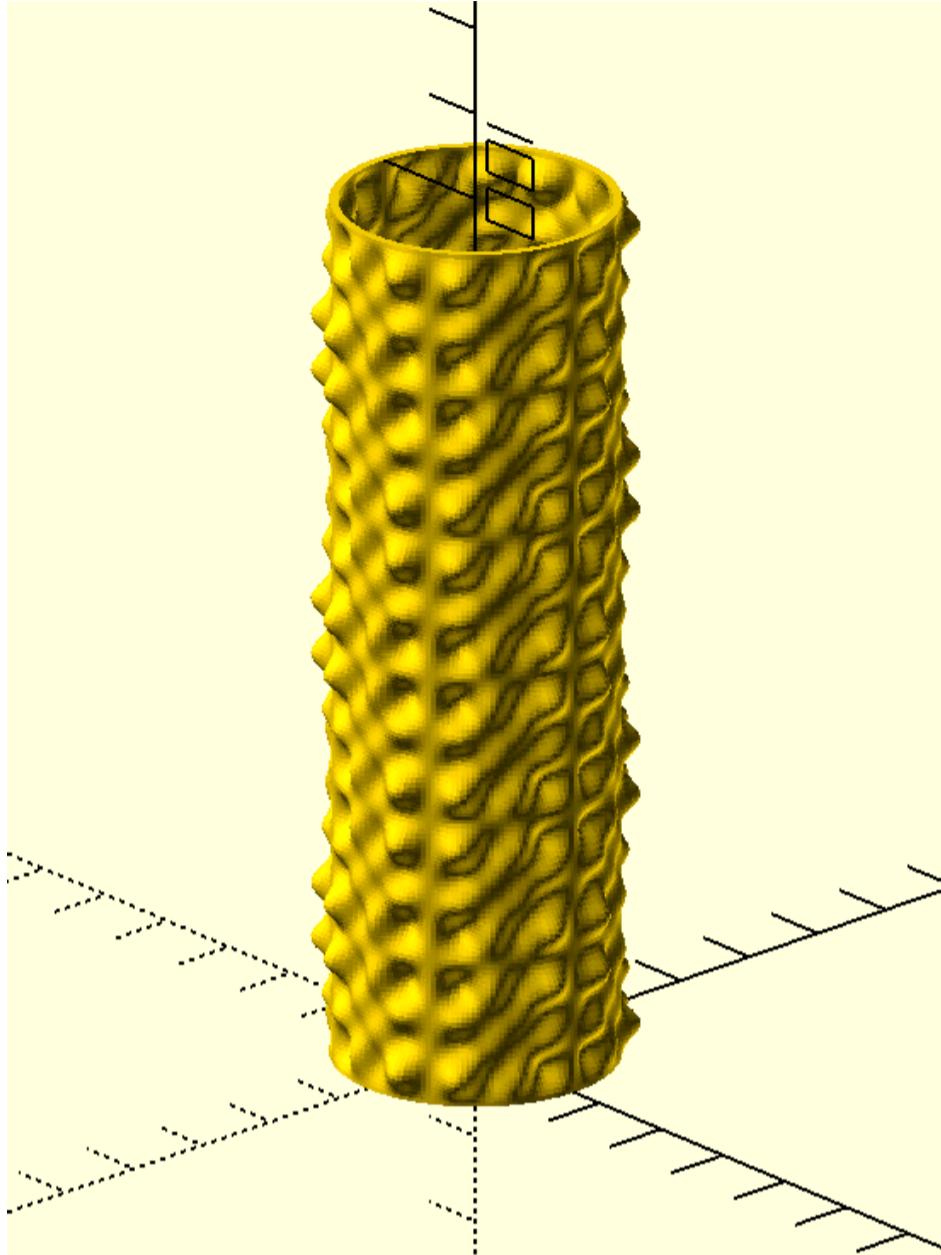
surf_1=surface_from_2_waves(b,c,1)
surf_2=surf_extrudef(surf_1,-.1)

path=circle(50/2/pi+.01,s=100)
path=path+path[:3]
path=q_rot(['y90'],path)
sol=[wrap_around(p,path) for p in surf_1]
sol=q_rot(['y-90'],sol)
h=[[0,0,p[0][2]] for p in sol]
s=c3t2(sol)
s1=[offset(p,-.5) for p in s]
sol1=[translate(h[i],s1[i]) for i in range(len(s1))]
sol2=swp_prism_h(sol,sol1)
```

```

sol2=scl3d(sol2,2)
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>
{swp_c(sol2)}
    ''')

```



SurfaceFrom3LinesInDifferentPlanes

```

In [3]: i_t=time.time()
w1=arc_3p_3d([[0,0,0],[5,20,0],[0,40,0]])
w2=arc_3p_3d([[0,0,0],[-4,0,20],[0,0,40]])
w3=arc_3p_3d([[0,0,40],[2,15,40],[0,30,45]])

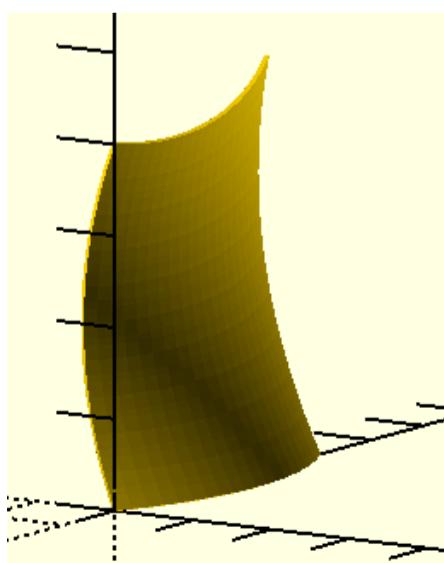
surf_1=SurfaceFrom3LinesInDifferentPlanes(w1,w2,w3)
surf_2=surface_offset(surf_1,-1)
sol=solid_from_2surfaces(surf_1,surf_2)
sol1=[ surf_1[i]+flip(surf_2[i]) for i in range(len(surf_1))]
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>

color("blue")for(p={sol})p_line3dc(p,.1,1);
color("magenta")for(p={sol1})p_line3dc(p,.1,1);
{swp(sol)}

    ''')
f_t=time.time()
f_t-i_t

```

Out[3]: 0.2523980140686035



```
In [4]: # complex part with fillet
i_t=time.time()

c1=circle(20)
c2=circle(5,[25,0])
f_1=two_cir_tarc(c1,c2,10,0)
f_2=two_cir_tarc(c1,c2,10,1)
p0,p1,p2,p3,p4,p5=f_1[0],f_1[-1],[70,-5],[70,5],f_2[0],f_2[-1]

sec=[p3]+arc_2p(p4,p5,10,1)+arc_long_2p(p5,p0,20,-1,s=50)+ \
arc_2p(p0,p1,10,1)+[p2]

sec=remove_extra_points(array(sec).round(5))
sec=equidistant_path(sec,1000)
sol=translate([0,0,-25],linear_extrude(sec,50))
sol1=translate([40,0,0],q_rot(['x90','z180'],sol))

ipa=ip_sol2sol(sol1,sol)
ipb=ip_sol2sol(sol1,sol,-1)

ipc=remove_extra_points(array(ipa+flip(ipb)).round(5))
fillet1=i_line_fillet_closed(sol,sol1,ipc,2,-2,10,n=300)
fillet2=solid_from_fillet_closed(fillet1,-4)
with open('trial.scad','w+') as f:
    f.write(f'''  

        include<dependencies2.scad>  

        difference(){{
            intersection(){{
                {swp(sol)}
                {swp(sol1)}
            }}
        }}  

{swp_c(fillet2)}
{swp(o_solid([0,0,1],circle(15),40,-20))}  

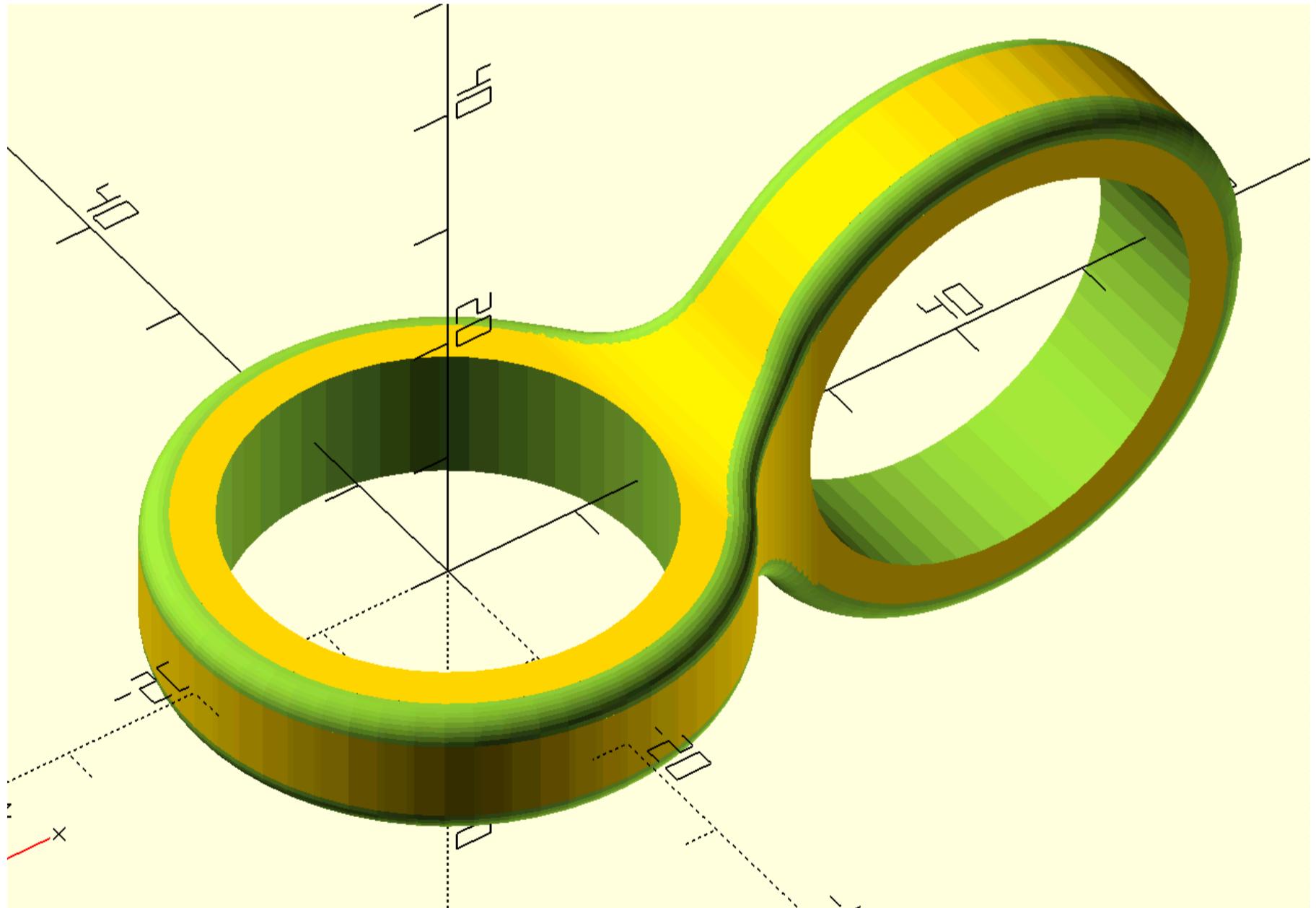
{swp(o_solid([0,1,0],circle(15),40,-20,40))}  

}}  

    ''')

f_t=time.time()
f_t-i_t
```

Out[4]: 3.631418228149414



```
In [144...]: # mobile stand revised version
i_t=time.time()
sec=round_corners(pts1([[0,0,1.9],[150,0,1.9],[0,4,1.9],[-150,0,1.9]]),10)
path=round_corners(pts1([[1.9,0],[1.9,0,1.9],[0,120,1.9],[-1.9,0]]),10)

sol=prism(sec,path)
sol=q_rot(['z90'],sol)
sol=[equidistant_pathc(p,400) for p in sol]
path1=arc_2p([0,0],[150,0],500,1,150)
path1=translate([0,0,120],q_rot(['x90','z90'],path1))

sol1=translate([0,0,-120+1.9],sol[-10:])
sol1=[wrap_around(p,path1) for p in sol1]
```

```

path2=arc_2p([0,0],[150,0],500,-1,150)
path2=translate([0,0,0],q_rot(['x90','z90'],path2))
sol2=sol[:10]
sol2=[wrap_around(p,path2) for p in sol2]

sol3=[sol2[-1]]+[sol1[0]]
sol3=slice_sol(sol3,100)
sol4=sol2+sol3+sol1
sol4=translate([0,10,0],q_rot(['y90','z90'],sol4))

path3=round_corners(pts1([[0,0],[127,0,6],[-50*cos(d2r(60)),50*sin(d2r(60))]]),10)
path3=q_rot(['x90','z90'],path3)

sol5=[wrap_around(p,path3) for p in sol4]

sec=round_corners(pts1([[6,0,1.9],[150-12,0,1.9],[0,4,1.9],[-150+12,0,1.9]]),10)
path=round_corners(pts1([[0,0],[0,1.9,1.9],[-1.9,0]]),10)

sol=prism(sec,path)
sol=q_rot(['z90'],sol)
path=arc_2p([0,0],[150,0],300,1,150)
path=translate([0,0,50],q_rot(['x90','z90'],path))

sol1=[wrap_around(equidistant_pathc(p,400),path) for p in sol]
sol2=translate([0,0,-50],equidistant_pathc(wrap_around(sol[0]),path),400)
sol2=[sol2]+sol1
sol2=translate([0,100,1],q_rot(['z90','x30']),sol2)

sol6=[sol5[10]]+[sol5[90]]
sol7=[sol2[0]]+[sol2[1]]
fillet1=flip(ip_fillet_closed(sol6,sol7,-4,3.8,style=2))

with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>
        {swp(sol5)}
        {swp(sol2)}
        {swp_c(fillet1)}
    ''')

f_t=time.time()
f_t-i_t

```

Out[144... 8.871129274368286

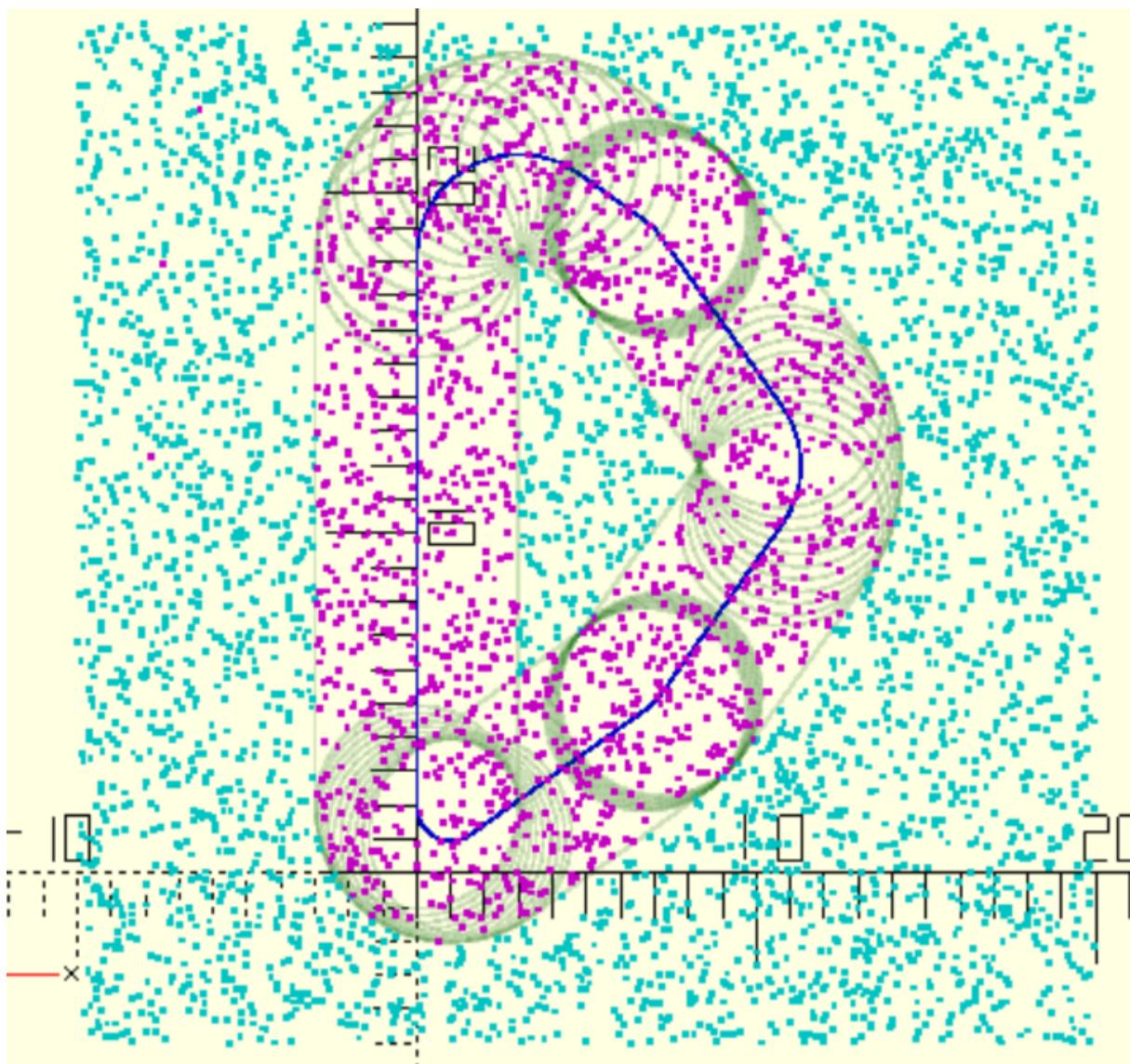
points_inside_offset_surround

```

In [151... i_t=time.time()
sec=corner_radius(pts1([[0,0,1],[7,5,2],[5,7,3],[-5,7,2],[-7,5,3]]),10)
a=(random.random(5000)*(30-0)+(-10))
b=(random.random(5000)*(30-0)+(-5))
c=array([a,b]).transpose(1,0).tolist()
r=3
sec2=cs1(sec,r-.01)
p_0=points_inside_offset_surround(sec,c,r-.01)
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>
        color("blue")p_line3dc({sec},.1,1);
        color("cyan")points({c},.2);
        color("green",.1)for(p={sec2})p_line3dc(p,.1,1);
        color("magenta")points({p_0},.2);
    ''')
f_t=time.time()
f_t-i_t

```

Out[151... 1.3581559658050537



```
In [150...]
od=150
id=75
n=16
t=3
sl_ang=50
sl_h=(od/2-id/2)*tan(d2r(sl_ang))
a=c2t3(circle(od/2,s=n+1))
b=q_rot([f'z{360/len(a)/2}'],c2t3(circle(od/2,s=n+1)))
h=l_len(a[:2])/2

sol_1=[translate([0,0,i*h],a) if i%2==0
      else translate([0,0,i*h],b)
      for i in range(5)]
a=flip(c2t3(circle(od/2,s=n+1)))
b=flip(q_rot([f'z{-360/len(a)/2}'],c2t3(circle(od/2,s=n+1))))
h=l_len(a[:2])/2
sol_2=[translate([0,0,i*h],a) if i%2==0
      else translate([0,0,i*h],b)
      for i in range(5)]

a=c2t3(circle(id/2,s=n+1))
b=q_rot([f'z{360/len(a)/2}'],c2t3(circle(id/2,s=n+1)))
# h=l_len(a[:2])/2

sol_3=[translate([0,0,i*h],a) if i%2==0
      else translate([0,0,i*h],b)
      for i in range(5)]

a=flip(c2t3(circle(id/2,s=n+1)))
b=flip(q_rot([f'z{-360/len(a)/2}'],c2t3(circle(id/2,s=n+1))))
# h=l_len(a[:2])/2
sol_4=[translate([0,0,i*h],a) if i%2==0
      else translate([0,0,i*h],b)
      for i in range(5)]

a=[seg(p)[:-1] for p in cpo(sol_1)]
b=[seg(p)[:-1] for p in translate([0,0,sl_h],cpo(sol_3))]

sol_5=array([a,b]).transpose(1,2,0,3,4).tolist()

a=[seg(p)[:-1] for p in cpo(sol_2)]
b=[seg(p)[:-1] for p in translate([0,0,sl_h],cpo(sol_4))]

sol_6=array([a,b]).transpose(1,2,0,3,4).tolist()

with open('trial.scad','w+') as f:
    f.write(f'''
    include<dependencies2.scad>

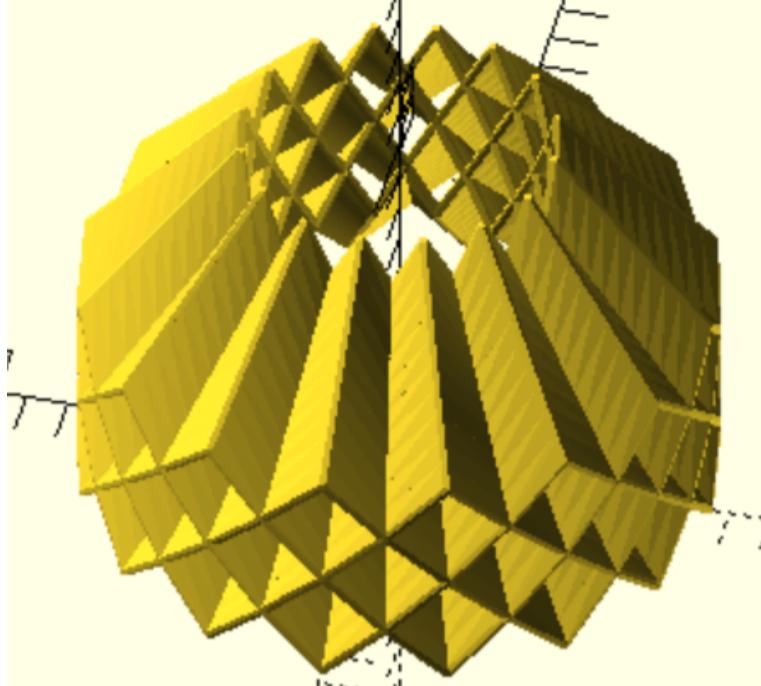
    for(p={sol_5})for(p1=p)
        let(
            a=slice_sol(p1,10)
            )
        for(i=[1:len(a)-1])
            hull(){{
                p_line3d(a[i-1],{t/2},1);
                p_line3d(a[i],{t/2},1);
            }}

    for(p={sol_6})for(p1=p)
```

```

let(
    a=slice_sol(p1,10)
)
for(i=[1:len(a)-1])
hull(){{
p_line3d(a[i-1],{t/2},1);
p_line3d(a[i],{t/2},1);
}}
...
)

```



```

In [5]: a=ellipse(20,15,s=101)[:51]
sol1=[q_rot([f'x{i}'],a) for i in linspace(0,180,100)]
sol1=translate([0,20,0],q_rot(['z90'],sol1))
sec=corner_radius(pts1([[20,-15,0],[-8,10,10],[-15,2.5,2.8],[0,5,2.8],[15,2,10],[8,10]]),10)
sec=translate_2d([0,20],q_rot2d(90,sec))
sec=equidistant_path(sec,100)
l1=project_points_on_surface(c2t3(sec),cpo(sol1),[0,0,1],1)
l2=equidistant_path([[0,17,0],[0,40,0]],50)
l2=project_points_on_surface(l2,cpo(sol1),[0,0,1],1)
l3=path_offset_3d(l2,-2)
l4=flip([[0,0,3],[0,40,3]])
a1=flip(fillet_line_circle_internal_3d(l4,l3,4,0,option=0,s=20))
l5=l3[:31]+a1+[[0,0,3]]
l6=wrap_around(translate([0,-17,0],sec),l5)
l7=c3t2(l6)+[-15,0],[15,0]
sol2=slice_sol(linear_extrude(l7,30),30)[7:]
sol3=surface_line_vector(l5+[[0,0,12]],[20,0,0],1)
l1=o_3d(l6[:-2],sol3,-1)[1:-1]
l2=l6[:-2][1:-1]
l3=translate([0,0,1],l2)
f1=convert_3lines2fillet(l1,l3,l2)
f2=flip(solid_from_fillet(f1,1))
l1=project_points_on_surface(c2t3(c3t2(l6)),cpo(sol1),[0,0,1],1)[5:-5]
l2=o_3d(l1,cpo(sol1),1)
l3=translate([0,0,-1],l1)
l1,l2,l3=[p[1:-1] for p in [l1,l2,l3]]
f3=convert_3lines2fillet(l3,l2,l1)
f3=flip(solid_from_fillet(f3,1))
l1=ip_sol2sol(sol3,cpo(sol1))
l2=o_3d(l1,cpo(sol1),-1)
l3=o_3d(l1,sol3,1)
l1,l2,l3=[p[1:-1] for p in [l1,l2,l3]]
f4=convert_3lines2fillet(l3,l2,l1)
f4=solid_from_fillet(f4,-1)

l1=ip_sol2sol(sol3,sol1,-1)
l1=l1+flip(mirror(l1,[1,0,0],[0,0,0]))
l2=o_3d(l1,sol3,1)
l3=o_3d(l1,sol1,1)
f5=convert_3lines2fillet(l3,l2,l1)
f5=flip(solid_from_fillet(f5,1))
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>

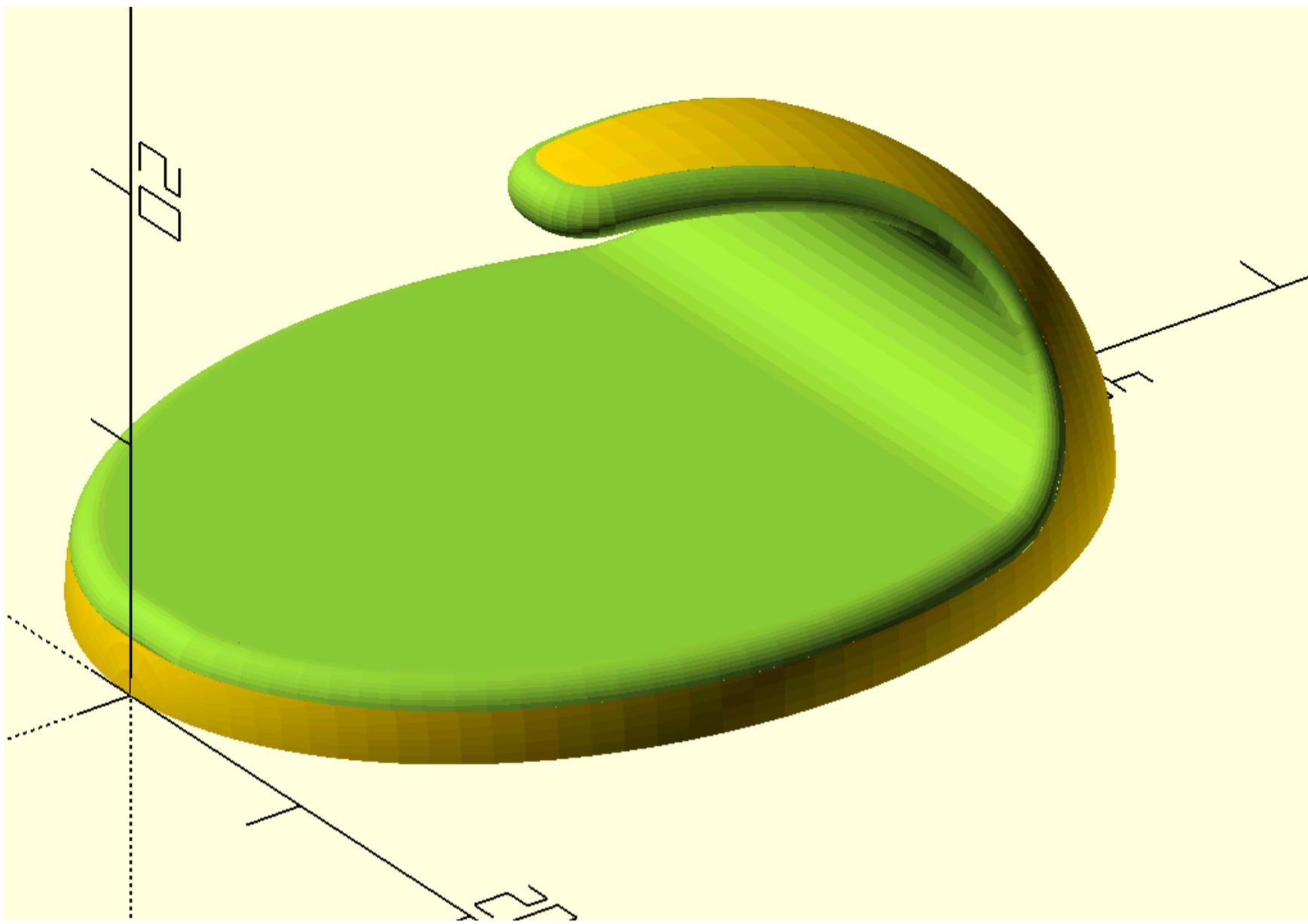
difference() {{
    {swp(sol1)}
    {swp(sol2)}
    {swp(sol3)}
    {swp(f2)}
    {swp(f3)}
    {swp(f4)}
    {swp(f5)}
}}
...
)

```

```

/Users/sanjeevprabhakar/openscad/openscad1.py:4750: RuntimeWarning: invalid value encountered in divide
    t=einsum('kl,ijkl->ijk',cross(p01,p02),la[:, :,None]-p0)/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)
/Users/sanjeevprabhakar/openscad/openscad1.py:4751: RuntimeWarning: invalid value encountered in divide
    u=einsum('ijkl,ijkl->ijk',cross(p02[None,None,:,:],(-lab)[:, :,None,:]),(la[:, :,None,:]-p0[None,None,:,:]))/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)

```



```
In [148...]: sec=corner_radius(pts1([[-15,0],[0,-3,3],[30,0,3],[0,6.1,3],[-30,0,3]]),10)
cir1=circle(8,s=51)
cir1=c2t3(cir1)
cir2=translate([0,0,5],circle(10,s=51))
cir3=translate([0,0,10],circle(9,s=51))

sec=q_rot(['z0'],translate([0,0,50],equidistant_pathc(sec,50)))
sec=align_sec_1(cir1,sec)[1]
# sol_1=cpo([equidistant_path(p,50) for p in cpo([cir1,cir2,cir3,sec])])
sol_1=slice_sol_1([cir1,cir2,cir3,sec],50)
path1=corner_radius(pts1([[0,0,0],[1,25,10],q_rot2d(5,[40,0])]),20)
path1=q_rot(['x90'],equidistant_path(path1,50))
sol_1=sol2path(sol_1,path1)

sol_2=translate([0,0,-1],cylinder(r1=6,r2=12,h=50))
path2=corner_radius(pts1([[-15,10],[17,0,10],[3,18.5,8],q_rot(['z5'],[36,0]))],10)
path2=q_rot(['x90'],path2)
surf_1=surface_line_vector(path2,[0,20,0],1)
surf_2=translate([-10,0,10],surf_1)
sol_3=solid_from_2surfaces(surf_2,surf_1)

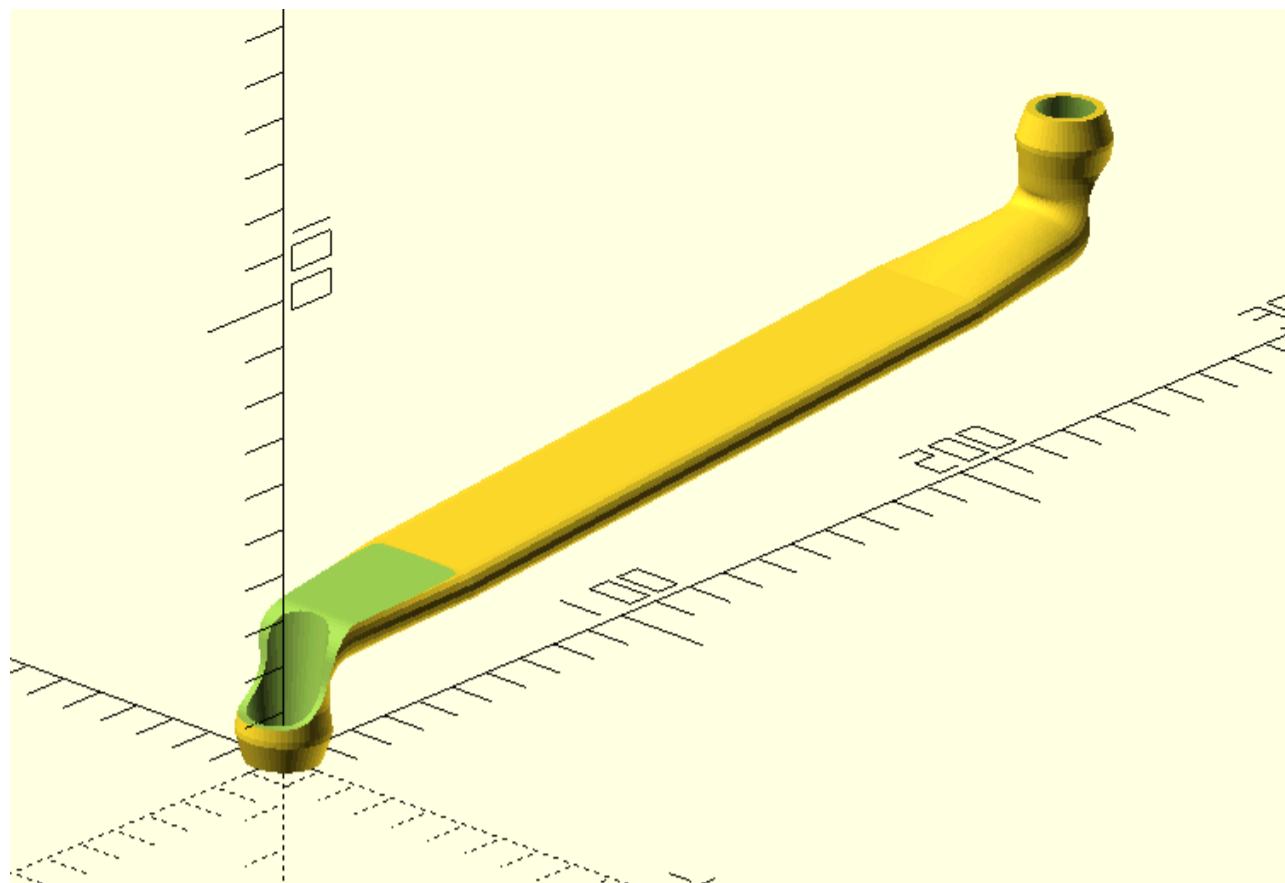
l_1=[path1[-1],(array(path1[-1])+array(q_rot(['y-5'],[150,0,0]))).tolist()]
p0=mid_point(l_1)

sol_1_1=axis_rot_1(sol_1,[0,1,0],p0,180)
sol_2_1=axis_rot_1(sol_2,[0,1,0],p0,180)
sol_3_1=axis_rot_1(sol_3,[0,1,0],p0,180)

sol_4=align_sol_1([sol_1[-1],flip(sol_1_1[-1])])
with open('trial.scad','w+') as f:
    f.write('''
        include<dependencies2.scad>
//color("blue")p_line3d({path1},.2,1);
//color("blue")p_line3d({path2},.2,1);

        union(){
difference(){
    {swp(sol_1)}
    {swp(sol_2)}
    {swp(sol_3)}
}
difference(){
    {swp(sol_1_1)}
    {swp(sol_2_1)}
    {swp(sol_3_1)}
}

{swp(sol_4)}
}
'''')
```



```
In [151... from openscad2 import *
it=time.time()
sec1=corner_radius(pts1([[-27.5,-2],[0,2,2],[6,0,.9],[0,-2,.9],
[14.5,0,.9],[0,2,.9],[6,0,.9],[0,-2],[2,0],[0,2,.9],
[6,0,.9],[0,-2,.9],[14.5,0,.9],[0,2,.9],[6,0,2],[0,-2]]),10)

path1=cr_3d([[0,0,20,0],[0,30,0,2],[0,0,30,0]],20)
s1=path_extrude_open(sec1,path1,twist=1)

sec2=corner_radius(pts1([[-27.5,6],[0,-6,2.4],[6,0,2.4],[0,6,2.4],[14.5,0,2.4],[0,-6,2.4],
[6,0,2.4],[0,6],[2,0],[0,-6,2.4],[6,0,2.4],[0,6,2.4],[14.5,0,2.4],
[0,-6,2.4],[6,0,2.4],[0,6]]))
path2=cr_3d([[0,0,0,0],[0,50,0,20],[0,0,50,0]],20)
s2=path_extrude_open(sec2,path2,twist=1)

sol1=[ equidistant_pathc(s1[i]+flip(s2[i]),300)+[s1[i][0]] for i in range(len(s1))]

sec3=corner_radius(pts1([[-27.5,-2],[0,2,2],[6,0,.9],[0,-2,.9],[19,0,.9],[0,2,.9],
[5,0,.9],[0,-2,.9],[19,0,.9],[0,2,.9],[6,0,2],[0,-2]]))

path3=cr_3d([[0,0,0,0],[0,0,30,2],[-30+2,0,0,0]],20)
s3=translate([0,30,50],q_rot(['z90'],path_extrude_open(sec3,path3,1)))

sec4=corner_radius(pts1([[-27.5,13],[0,-13,2.4],[6,0,2.4],[0,13,2.4],[19,0,2.4],
[0,-13,2.4],[5,0,2.4],[0,13,2.4],[19,0,2.4],[0,-13,2.4],[6,0,2.4],[0,13]]))

path4=cr_3d([[0,0,0,0],[0,0,50,20],[-50+2,0,0,0]],20)
s4=translate([0,50,50],q_rot(['z90'],path_extrude_open(sec4,path4,1)))

sol2=[ equidistant_pathc(s3[i]+flip(s4[i]),300)+[s3[i][0]] for i in range(len(s3))]

sec5=circle(27.5,s=100)
path5=corner_radius(pts1([[-15,-2],[15,0,2],[0,24,2],[-15,0]]),20)
sol3=prism(sec5,path5)
sol4=translate([0,50,50],q_rot(['x90'],sol3))
sec5=circle(15)
l1=[[-21.5,3],[21.5,3]]
a1=fillet_line_circle(l1,sec5,3)
a2=fillet_line_circle(flip(l1),sec5,3,1)
sec5=corner_radius(pts1([[-21.5,3,3],[0,5],[-6,0],[0,-8,5],[10,-15,3],
[35,0,3],[10,15,5],[0,8],[-6,0],[0,-5,3]]),10)
sec6=sec5+a2+arc_2p(a2[-1],a1[-1],15,-1,50)[1:-1]+flip(a1)

path5=corner_radius(pts1([[-5,0],[5,0,2],[0,20,2.4],[-5,0]]),20)
sol5=translate([0,0,80],prism(sec6,path5))
sol5=[p+[p[0]] for p in sol5]
sol6=o_solid([0,0,1],circle(45/2,s=100),30,-5)
sol7=o_solid([0,1,0],circle(45/2,s=100),30,25,0,50)
sol8=o_solid([0,0,1],circle(5),30,75)
sol9=o_solid([1,0,0],pts([[-25,-25],[50,0],[0,50],[-50,0]]),2,-1,-40,10)

f1=ip_fillet_closed(sol3,sol1,2,2,type=0,style=2)
f2=ip_fillet_closed(sol4,flip(sol1),-2,2,style=2)
f3=ip_fillet_closed(sol4,sol2,2,2,style=2)

s5=cpo(cpo(s3)[60:-60])
s6=cpo(cpo(s4)[60:-60])
sol10=[ equidistant_pathc(s5[i]+flip(s6[i]),200)+[s5[i][0]] for i in range(len(s5))]

l1=ip_sol2sol(sol5,sol10)
l2=o_3d_rev(l1,sol5,2,o=1,type=2,vx=[1,0,0],dist=10)
l3=translate([0,2,0],l1)
f4=convert_3lines2fillet(l3,l2,l1,style=2)
with open('trial.scad','w+') as f:
    f.write(f'''
    include<dependencies2.scad>
```

```

difference(){{  
union(){{  
{swp(sol5)}  
{swp(flip(sol1))}  
{swp(flip(sol2))}  
{swp(sol3)}  
{swp(sol4)}  
{swp(f1)}  
{swp(flip(f2))}  
{swp(f3)}  
{swp(f4)}  
}}  
{swp(sol6)}  
{swp(sol7)}  
{swp(sol8)}  
{swp(sol9)}  
}}  
  
})

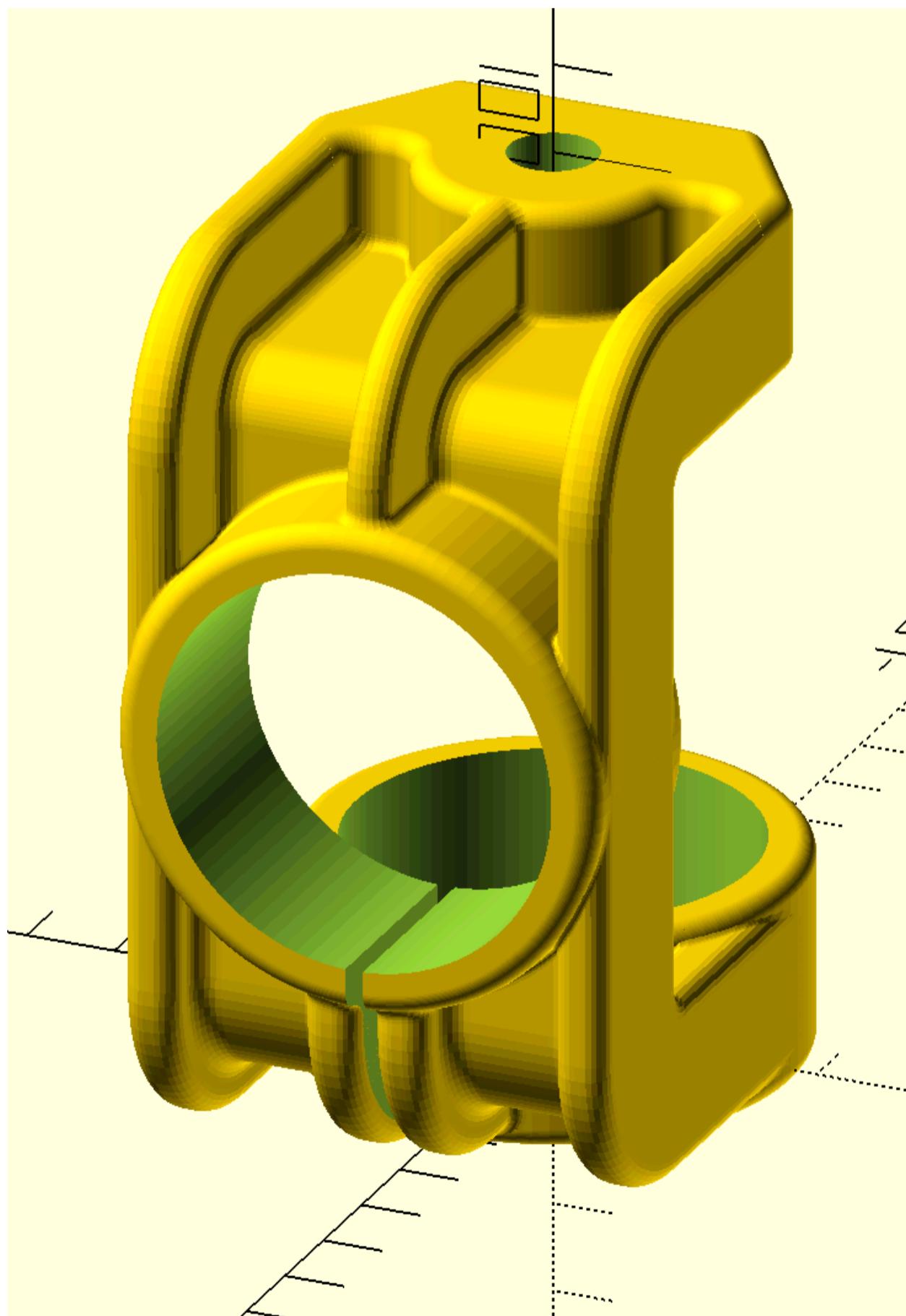
```

```

ft=time.time()  
ft-it  
  
/Users/sanjeevprabhakar/openscad/openscad2.py:4778: RuntimeWarning: divide by zero encountered in divide  
t=einsum('kl,ijkl->ijk',cross(p01,p02),la[:, :,None]-p0)/(einsum('ijl,kl->ijk',(-lab),cross(p01,p02))+.00000)  
/Users/sanjeevprabhakar/openscad/openscad2.py:4783: RuntimeWarning: invalid value encountered in multiply  
a=(la[:,None,:,:]+lab[:,None,:,:]*t[:,None,:,:,:None])

```

Out[151... 30.4185528755188



car_seat

```

In [152... p0=c2t3(pts([[0,780],[0,-300],[280,-480],[420,0],q_rot2d(30,[100,0]),  
q_rot2d(120,[75,0])))  
l1=arc_2p_3d([1,0,0],translate([0,0,100],p0[0]),translate([0,0,180],p0[1]),800,1,10)  
l2=arc_2p_3d(q_rot(['z30'],[1,0]),translate([0,0,180],p0[1]),translate([0,0,120],p0[2]),750,1,10)

```

```

l3=arc_2p_3d([0,1,0],translate([0,0,120],p0[2]),translate([0,0,200],p0[3]),840,1,10)
l4=c2t3(bezier([[240,0],[150,100],[150,170],[0,450]],20))
l5=fillet_line_circle_internal_3d([l1[0],p0[0]],l1,150,option=1,s=10)
r1=r_3p_3d([l1[-1],l4[-1],mirror(l1,[0,0,1],[0,0,0])[-1]])
l6=arc_2p_3d([1,0,0],l1[-1],l4[-1],r1,1,s=10)
l5=flip(l5)[:-1]+mirror(l5,[0,0,1],[0,0,0])
l6=l6[:-1]+flip(mirror(l6,[0,0,1],[0,0,0]))
s1=surface_4_lines_enclosed(extend_arc3d(l1,10,10,1),
                           mirror(extend_arc3d(l1,10,10,1),[0,0,1],[0,0,0]),
                           l5,l6,[100,0,0],[0,0,1],10)
s2=convert_3lines2surface(l2,flip(l4),mirror(l2,[0,0,1],[0,0,0]),20)
l7=c2t3(bezier(pts[[0,0],[30,0],[50,-50],[50,0],[50,50],[70,0]]),20)
l7=flip(mirror(l7,[1,0,0],[0,0,0]))[:-1]+l7
l7=translate(q_rot2d(120,[50,0]),translate(p0[4],q_rot(['y90','z30']),l7)))

ts1=[l3,mirror(l3,[0,0,1],[0,0,0])]
l8=project_line_on_surface(l7,ts1,q_rot(['z30'],[1,0,0]))
ts2=surface_line_vector(p0[4:6],[0,0,183],1)
l9=project_line_on_surface(l7,ts2,q_rot(['z30'],[1,0,0]))
l8=equidistant_path(l8,20)
l9=equidistant_path(l9,20)
l10=arc_2p_3d([0,0,-1],p0[-1],p0[2],420,-1,20)
l11=arc_2p_3d([0,0,-1],p0[2],p0[1],350,-1,20)
l12=c2t3(two_cir_tarc(c3t2(l10),c3t2(l11),75,0,10))
l13=c2t3(flip(fillet_line_circle([[30,780],[30,480]],c3t2(l11),100,-1,0,10)))
p1=arc_2p_3d([0,0,-1],p0[-1],l12[0],420,-1,10)[:-1] \
+arc_2p_3d([0,0,-1],l12[0],l12[-1],75,1,10) \
+arc_2p_3d([0,0,-1],l12[-1],l13[0],350,-1,10)[1:-1] \
+l13
ts3=SurfaceFrom3LinesInDifferentPlanes(extend_arc3d(l3,15,20),bezier(equidistant_path(flip(l2),50),50),extend_arc3d(flip(l1),10,20))
p1=project_line_on_surface(p1,ts3,[0,0,1])+[translate([30,0,0],s1[0][0])]
l14=equidistant_path([l8[0],l9[0]],5)
l14=project_line_on_surface(l14,ts3,[0,0,1])
s3=surface_4_lines_enclosed(extend_arc3d(l3,10,20,1),
                           mirror(extend_arc3d(l3,10,20,1),[0,0,1],[0,0,0]),
                           s2[-1],l8,[0,100,0],[0,0,1])
s4=surface_4_lines_enclosed(extend_arc3d(l14,10,10,1),
                           mirror(extend_arc3d(l14,10,10,1),[0,0,1],[0,0,0]),
                           l8,l9,q_rot(['z120'],[100,0,0]),[0,0,1],10)
surf1=s1+s2+s3+s4
surf1=cpo([bezier(p,100) for p in cpo(surf1)])
l15=cpo(surf1)[0]
l16=path2path1(l15,flip(p1))
ts4=cpo(slice_sol([l16,l15],10))
ts4=[project_line_on_surface(p[:-1],translate([-5,-5,0],ts3),[0,0,1]) for p in ts4]
surf2=cpo(ts4)+cpo(surf1)+flip(mirror_surface(cpo(ts4),[0,0,1],[0,0,0]))
surf2=[bezier(p,50) for p in cpo(surf2)]
surf3=surface_offset(surf2,30)
sol1=solid_from_surfaces(surf2,surf3)
l17=[mid_point(p) for p in cpo([surf2[0],surf3[0]])][12:-12]
l18=[mid_point(p) for p in cpo([surf2[-1],surf3[-1]])][2:-2]
l19=[mid_point(p) for p in cpo([cpo(surf2)[-1],cpo(surf3)[-1]])]
l20=[mid_point(p) for p in cpo([cpo(surf2)[0],cpo(surf3)[0]])]
l21=flip(l19)[:-13]+flip(l17)+l20[13:]+l18

l22=flip(cpo(s4)[2])
l23=s4[0][2:-3]
l24=cpo(s4)[-3]
l25=flip(s4[-1])[3:-2]
l26=l22+l23+l24+l25
l26=ppplane(l26,q_rot(['z120'],[1,0,0]),l23[-1])
l26=bezier_c(l26,5,-21,25)
l26=offset_3d(l26,-20)
l26=project_line_on_surface(l26,surf3,q_rot(['z120'],[1,0,0]))
l27=offset_3d(l26,-20)
l27=project_line_on_surface(l27,surf3,q_rot(['z120'],[1,0,0]))
l27=translate(q_rot(['z120'],[10,0,0]),l27)
l28=translate(q_rot(['z120'],[10,0,0]),l26)
f1=cpo(convert_3lines2fillet_closed(l26,l27,l28))[:-1]

l22=flip(cpo(s3)[2])
l23=s3[0][2:-3]
l24=cpo(s3)[-3]
l25=flip(s3[-1])[3:-2]
l26=l22+l23+l24+l25
l26=ppplane(l26,[0,1,0],l23[-1])
l26=bezier_c(l26,5,-21,25)
l26=offset_3d(l26,-20)
l26=project_line_on_surface(l26,surf3,[0,1,0])
l27=offset_3d(l26,-20)
l27=project_line_on_surface(l27,surf3,[0,1,0])
l27=translate([0,10,0],l27)
l28=translate([0,10,0],l26)
f2=cpo(convert_3lines2fillet_closed(l26,l27,l28))[:-1]

l22=flip(cpo(s2)[2])
l23=s2[0][2:-3]
l24=cpo(s2)[-3]
l25=flip(s2[-1])[3:-2]
l26=l22+l23+l24+l25
l26=ppplane(l26,q_rot(['z30'],[1,0,0]),l23[-1])
l26=bezier_c(l26,10,-26,25)
l26=offset_3d(l26,-50)
l26=project_line_on_surface(l26,surf3,q_rot(['z30'],[1,0,0]))
l27=ppplane(l26,q_rot(['z30'],[1,0,0]),l23[-1])
l27=offset_3d(l26,-20)
l27=project_line_on_surface(l27,surf3,q_rot(['z30'],[1,0,0]))
l27=translate(q_rot(['z30'],[10,0,0]),l27)
l28=translate(q_rot(['z30'],[10,0,0]),l26)
f3=cpo(convert_3lines2fillet_closed(l26,l27,l28))[:-1]

l22=flip(cpo(s1)[2])[:-1]

```

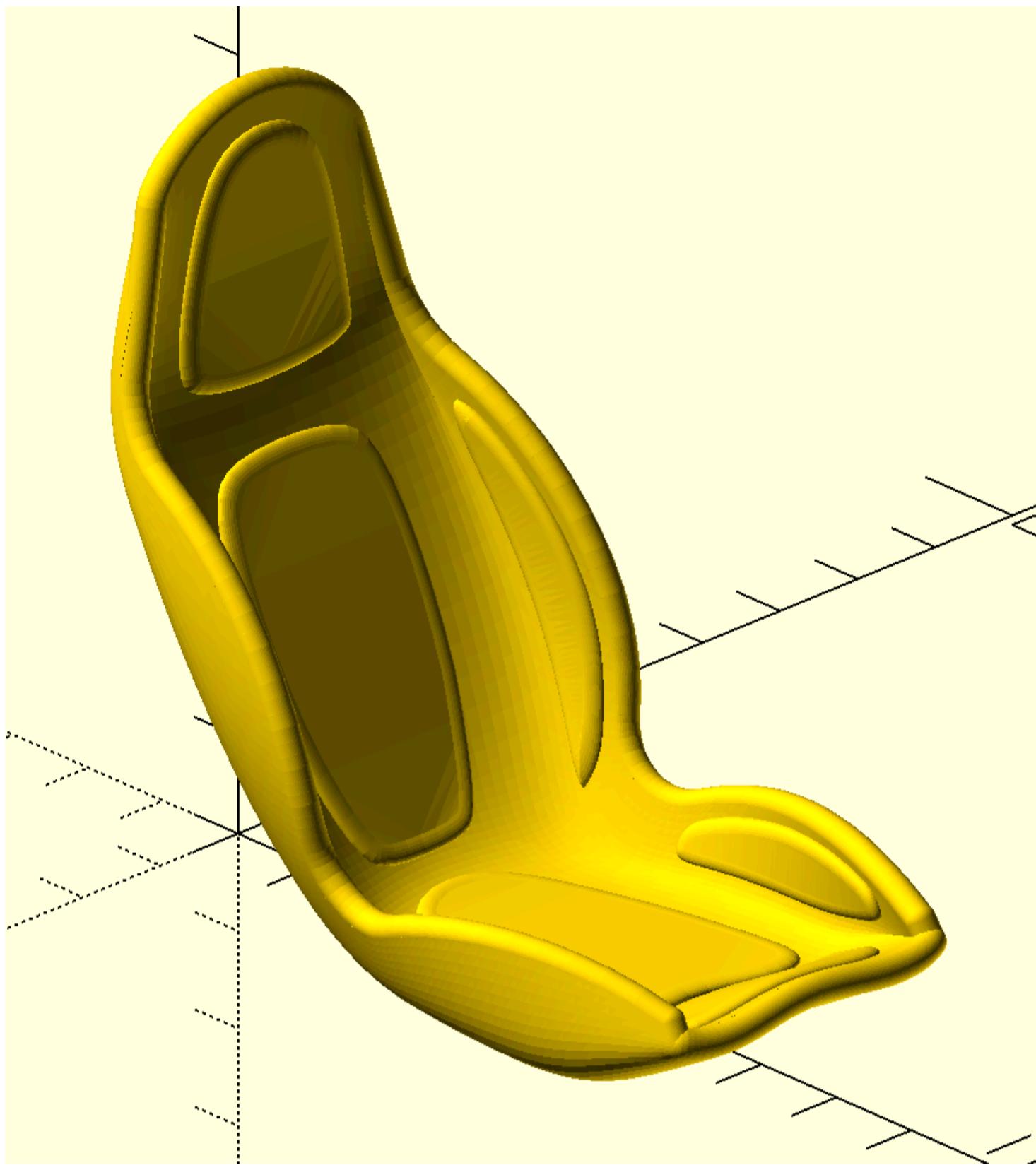
```

l23=s1[0][5:-5]
l24=cpo(s1)[-3][1:]
l25=flip(s1[-1])[3:-2]
l26=l22+l23+l24+l25
l26=ppplane(l26,[1,0,0],l23[-1])
l26=bezier_c(l26,5,-20,25)
l26=offset_3d(l26,-30)
l26=project_line_on_surface(l26,surf3,[1,0,0])
l27=ppplane(l26,[1,0,0],l23[-1])
l27=offset_3d(l26,-20)
l27=project_line_on_surface(l27,surf3,[1,0,0])
l27=translate([10,0,0],l27)
l28=translate([10,0,0],l26)
f4=cpo(convert_3lines2fillet_closed(l26,l27,l28))[:-1]

l22=l21[5:40]
l23=flip(cpo(surf3)[-10])[5:40]
l24=l23+flip(l22)
l24=ppplane(l24,[0,0,1],[0,0,-300])
l24=bezier_c(l24,17,-17,70)
l24=translate([0,0,-300],offset(c3t2(l24),-10))
l25=translate([0,0,-300],offset(c3t2(l24),-15))
l24=project_line_on_surface(l24,cpo(surf3)[20:], [0,0,1])
l25=project_line_on_surface(l25,cpo(surf3)[20:], [0,0,1])
l25=translate([0,0,10],l25)
l26=translate([0,0,10],l24)
f5=cpo(convert_3lines2fillet_closed(l24,l25,l26))[:-1]
f6=mirror_surface(f5,[0,0,1],[0,0,0])

l22=l21[50:80]
l23=flip(cpo(surf3)[-10])[50:80]
l24=l23+flip(l22)
l24=ppplane(l24,[0,0,1],[0,0,-300])
l24=bezier_c(l24,15,-15,60)
l24=translate([0,0,-300],offset(c3t2(l24),-10))
l25=c2t3(offset(equidistant_path(c3t2(l24),60),-15))
l24=project_line_on_surface(l24,cpo(surf3)[20:], [0,0,1])
l25=project_line_on_surface(l25,cpo(surf3)[20:], [0,0,1])
l25=translate([0,0,10],l25)
l25=path2path1(l24,l25)
l26=translate([0,0,10],l24)
f7=cpo(convert_3lines2fillet_closed(l24,l25,l26))[:-1]
f8=mirror_surface(f7,[0,0,1],[0,0,0])
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>
        rotate([90,0,0]){{{
{swp(sol1)}
p_line3dc({l21},30,$fn=50);
{swp(f1)}
{swp(f2)}
{swp(f3)}
{swp(f4)}
{swp(f5)}
{swp(f6)}
{swp(f7)}
{swp(f8)}
}}}
    ''')

```

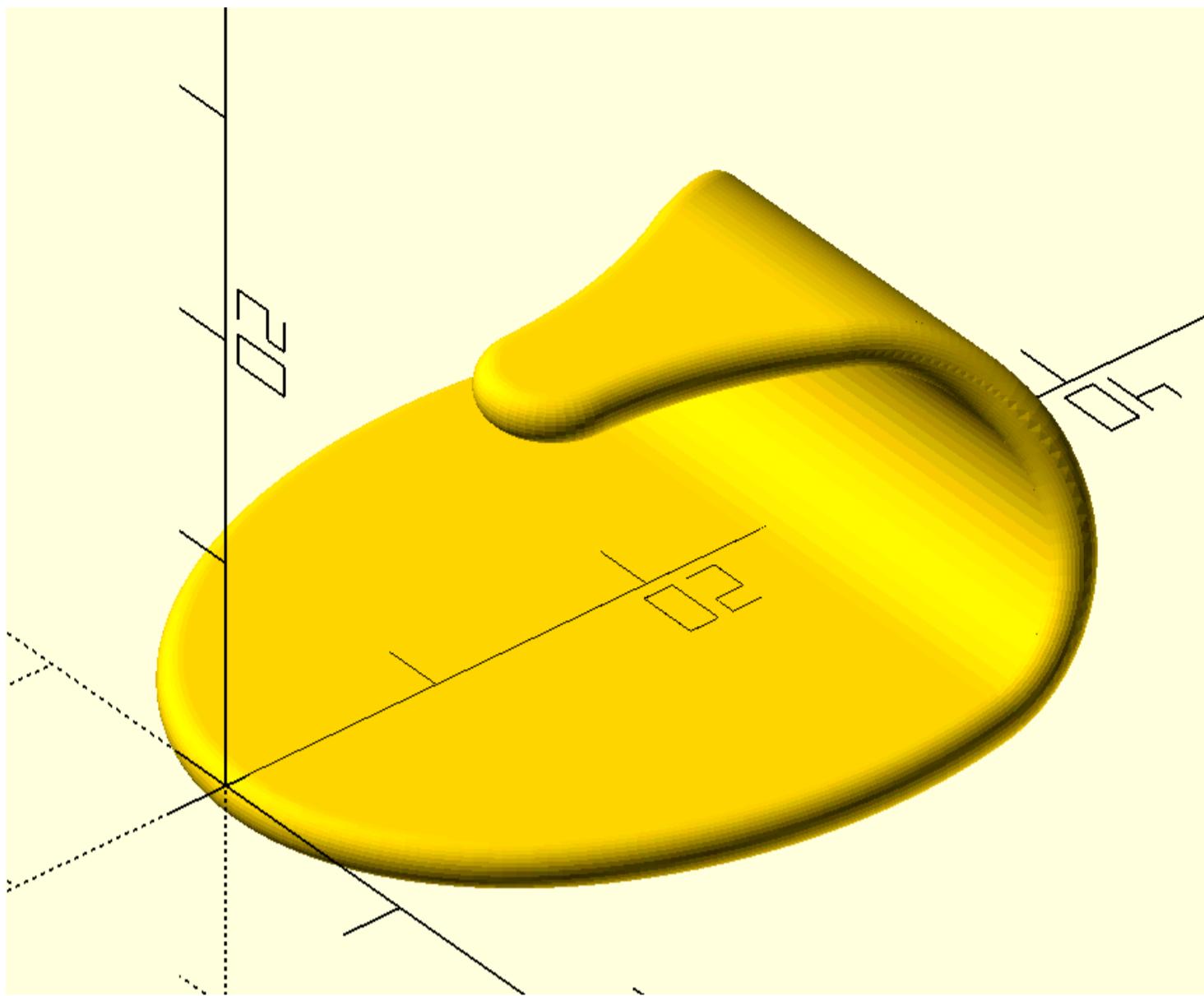


align_sec_2

```
In [155]: # application of c2ro
a=ellipse(20,15,s=200)
b=circle(3,[30,0])
c=two_cir_tarc(b,a[16:28],20)
d=a[21:-20]+flip(c3t2(mirror(c2t3(c),[0,1,0],[0,0,0])))+b[-12:]+b[:12]+c
d=translate_2d([0,20.2],q_rot2d(90,d))
d1=sec2surface_1(d)
p2=cr_3d([[0,0,0],[0,30,0,4.9],[0,0,10,4.9],[0,-30,0,0]],30)
e=[wrap_around(p,p2) for p in d1]
f1=surface_offset(e,-2)
sol=solid_from_2surfaces(f1,e)
l1=surface2sec(f1)[0]
l2=surface2sec(e)[0]
l3=[mid_point(p) for p in cpo([l1,l2])]
s1=surface_line_vector(path_offset_3d(p2,2),[20,0,0],1)
s2=surface_line_vector(p2,[20,0,0],1)
l4=o_3d(l1,s1,1)
l5=o_3d(l2,s2,1)
f1=convert_3lines2fillet(l4,l3,l1)
f1=solid_from_fillet_closed(f1,-1)
f2=convert_3lines2fillet(l3,l5,l2)
f2=solid_from_fillet_closed(f2,-1)
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>

difference(){{{
{swp(c2ro(sol,1))}

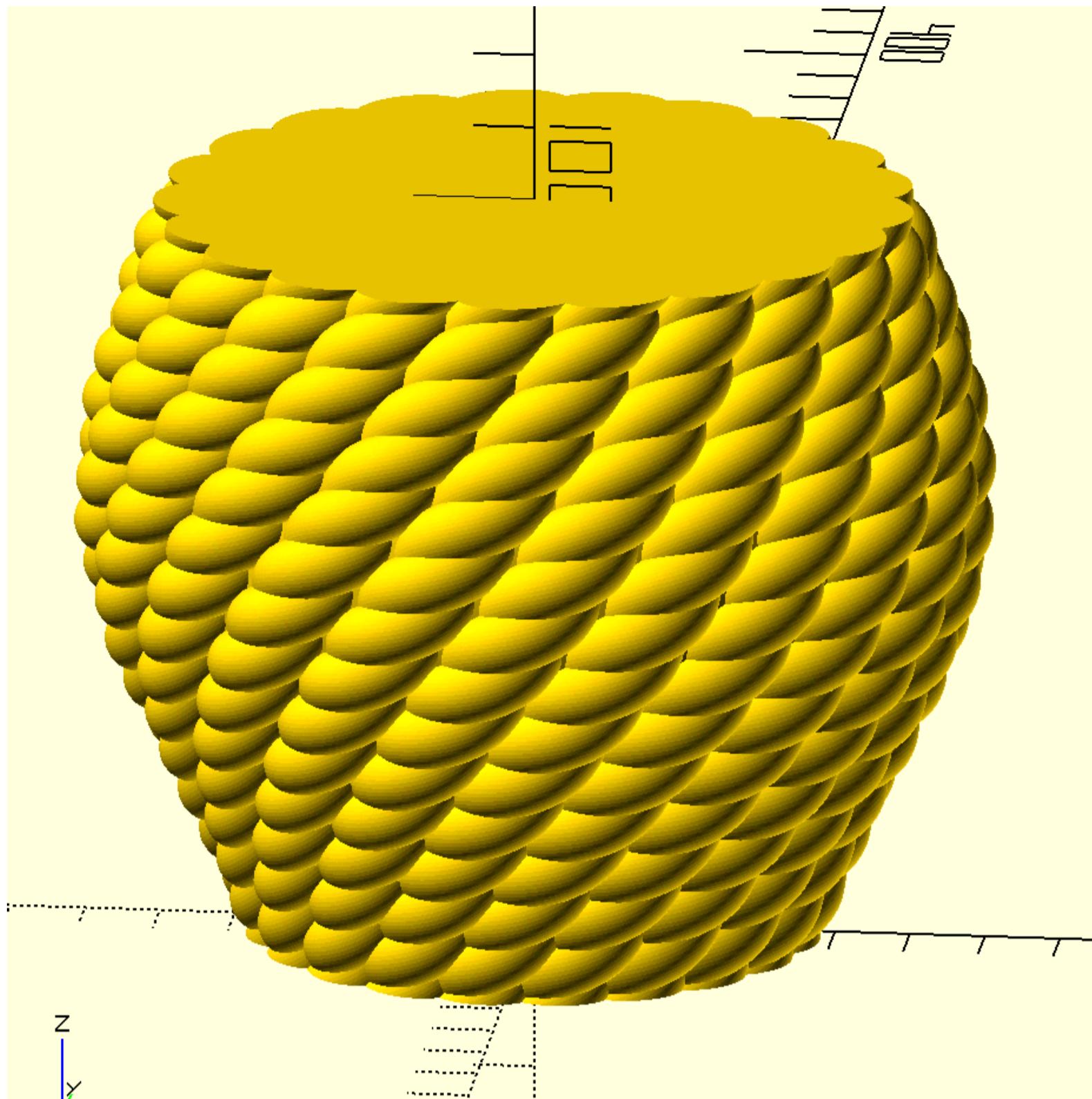
{swp_c(f1)}
{swp_c(f2)}
}}}
    ''')
```



```
In [13]: i_t=time.time()
a=q_rot(['y90'],helix(3,35,5,360*5/300))
a_1=q_rot(['z120','y90'],helix(3,35,5,360*5/300))
a_2=q_rot(['z240','y90'],helix(3,35,5,360*5/300))

a2=bezier([[30,-5],[40,30],[60,50],[60,60],[40,107]],300)
b=equidistant_path(axis_rot_1(c2t3(a2),[1,0,0],[0,0,0],90),299)
ba=[i for i in linspace(0,90,300)]
b=[q_rot([f'z{ba[i]}'],b[i]) for i in range(len(b))]
c=extrude_wave2path(a,b)
c1=extrude_wave2path(a_1,b)
c2=extrude_wave2path(a_2,b)
d=align_sol_1(path_extrude_open(circle(4.5),c))
d1=align_sol_1(path_extrude_open(circle(4.5),c1))
d2=align_sol_1(path_extrude_open(circle(4.5),c2))
g=cylinder(r=200,h=100)
h=prism(circle(2),a2)
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>
        intersection() {{
            union() {{
                for(i=[0:17.25:360])
                    rotate([0,0,i])
                    {{
                        {swp(d)}
                        {swp(d1)}
                        {swp(d2)}
                    }}
                    {swp(h)}
                }
                {swp(g)}
            }}
        }}''')
f_t=time.time()
f_t-i_t
```

Out[13]: 2.587597131729126



```
In [156]: i_t=time.time()

h=[100,180,120,200]
r=[800,750,840]
r1=[420,75,350,100]
s=[780,300,tan(d2r(30))*480,420,100,75]
sec=pts([[0,780],[0,-300],[s[2],-480],[420,0],q_rot2d(30,[100,0]),
         ,q_rot2d(120,[75,0]))]

arcs1=[arc_2p(p1,p2,r,-1,20) for (p1,p2,r) in [[sec[-1],sec[2],420],[sec[2],sec[1],350]]]
arc2=two_cir_tarc(arcs1[0],arcs1[1],75,s=10)
arc3=flip(fillet_line_circle(sec[:2],arcs1[1],100,-1,0,s=10))
sec1=arc_2p(sec[-1],arc2[0],420,-1,20)+arc2[1:-1]+ \
arc_2p(arc2[-1],arc3[0],350,-1,s=20)+arc3[1:]
curve1=bezier([[210,0],[125,100],[150,150],[0,450]],20)
curve1=flip(equidistant_path(curve1,20))
p0=[translate([0,0,h[i]],sec[i]) for i in range(4)]
arcs1=[ arc_2p_3d(n1,p1,p2,r)for (n1,p1,p2,r) in [[[1,0,0],p0[0],p0[1],r[0]],
[q_rot(['z30']),[1,0,0]),p0[1],p0[2],r[1]],
[[0,1,0],p0[2],p0[3],r[2]]]]

l1=[p0[0],c2t3(sec[0])]
arc1=fillet_line_circle_internal_3d(l1,arcs1[0],150,option=1,s=10)
surf1=SurfaceFrom3LinesInDifferentPlanes(
    extend_arc3d(arcs1[2],15),flip(arcs1[1]),extend_arc3d(flip(arcs1[0]),10))

arc1=flip(arc1)+mirror(arc1,[0,0,1],[0,0,0])[1:]
arc2=arc_3p_3d([p0[1],c2t3(curve1[0]),mirror([p0[1]],[0,0,1],[0,0,0])[0]])
s1=surface_4_lines_enclosed(arcs1[0],
    mirror(arcs1[0],[0,0,1],[0,0,0]),
    arc1,arc2,[1,0,0],[0,0,1])
s2=convert_3lines2surface(arcs1[1],c2t3(curve1),mirror(arcs1[1],[0,0,1],[0,0,0]),s=20)
temp_1=surface_line_vector(sec[2:4],[0,0,200],1)
temp_2=surface_line_vector(sec[4:6],[0,0,185],1)
l1=c2t3(bezier(pts([[0,0],[30,0],[50,-50],[50,0],[50,50],[70,0]]),20))
l2=mirror(l1,[1,0,0],[0,0,0])
l1=translate(q_rot2d(120,[50,0]),translate(sec[4],q_rot(['y90','z30'],flip(l2)+l1)))
l1,l2=[project_points_on_surface(l1,p,q_rot(['z30'],[1,0,0])) for p in [temp_1,temp_2]]
l1,l2=[equidistant_path(p,20) for p in [l1,l2]]
s3=surface_4_lines_enclosed(arcs1[-1],
    mirror(arcs1[-1],[0,0,1],[0,0,0]),s2[-1],l1,[0,10,0],[0,0,1],s=20)
l3=equidistant_path([l1[0],l2[0]],10)
l3=project_points_on_surface(l3,surf1,[0,0,1])
l4=mirror(l3,[0,0,1],[0,0,0])
s4=surface_4_lines_enclosed(l3,l4,l1,l2,c2t3(q_rot2d(120,[10,0])),[0,0,1],s=10)
l1=flip(project_points_on_surface(c2t3(sec1),surf1,[0,0,1]))
```

```

surf2=s1[13:]+s2+s3+s4
surf2=cpo([bezier(p,70) for p in cpo(surf2)])
l1=path2path1(cpo(surf2)[0],l1)
s5=slice_sol([l1,cpy(surf2)[0]],10)
s5=[project_points_on_surface(p,surf1,[0,0,1]) for p in s5][:-1]
s6=flip(mirror_surface(s5,[0,0,1],[0,0,0]))
surf3=s5+cpo(surf2)+s6
surf3=[bezier(p,50) for p in cpo(surf3)]
surf4=surface_offset(surf3,30)
sol=solid_from_2surfaces(surf3,surf4)
l1=cpy(surf3)[0]
l2=cpy(surf4)[0]
l3=[mid_point(p) for p in cpo([l1,l2])[5:]]
l4=mirror(l3,[0,0,1],[0,0,0])
l1=surf3[-1]
l2=surf4[-1]
l5=[mid_point(p) for p in cpo([l1,l2])]
surf5=s1[:13]+[equidistant_path(surf3[0],20)]
surf6=translate([30,0,0],surf5)
sol1=solid_from_2surfaces(surf5,surf6)
l1=arcs1[0][7:-4]
l2=arc1
l6=mirror(l1,[0,0,1],[0,0,0])
l6=translate([15,0,0],flip(l1)+l2+l6)
l7=[l3[0],l6[0]]
l8=mirror(l7,[0,0,1],[0,0,0])
pipe=l3+l5+flip(l4)
# pipe=min_d_points(pipe,5)
# pipe1=align_sol_1(path_extrude_closed(circle(15),pipe))
l1=cpy(surf3)[0]
l2=cpy(surf3)[10]
l3=equidistant_pathc(c3t2(l1[15:-5]+flip(l2[15:-5])),150)
l3=bezier_c(l3,50,-50,75)
l3_1=offset(l3,-20,2)
l3_2=offset(l3,-30,2)

l4=project_points_on_surface(c2t3(l3_1),surf4,[0,0,1],1)
l5=translate([0,0,-10],l4)
l6=project_points_on_surface(c2t3(l3_2),surf4,[0,0,1],1)
l6=translate([0,0,-12],l6)
sol2=cpo(convert_3lines2fillet(l4,l6,l5))[:-1]
sol3=mirror_surface(sol2,[0,0,1],[0,0,0])
l1=s3[0]+cpo(s3)[-1]+flip(s3[-1])+flip(cpo(s3)[0])
l1=bezier_c(l1,30,-10,50)
l2_1=offset_3d(l1,-50)
l2_2=offset_3d(l1,-70)

l3=project_points_on_surface(l2_1,surf4,[0,1,0],1)
l4=translate([0,10,0],l3)
l5=project_points_on_surface(l2_2,surf4,[0,1,0],1)
l5=translate([0,12,0],l5)
sol4=cpo(convert_3lines2fillet(l3,l5,l4))[:-1]

l1=s4[0]
l2=cpo(s4)[-1][1:-1]
l3=flip(s4[-1])
l4=flip(cpo(s4)[0])[1:-1]
l5=l1+l2+l3+l4
l5=ppplane(l5,q_rot(['z120'],[1,0,0]),l5[10])
l6=bezier_c(offset_3d(l5,-35),5,-20,60)
l6=project_points_on_surface(l6,surf4,q_rot(['z120'],[1,0,0]))
l7=translate(q_rot(['z120'],[10,0,0]),l6)
l8=bezier_c(offset_3d(l5,-50),5,-20,60)
l8=project_points_on_surface(l8,surf4,q_rot(['z120'],[1,0,0]))
l8=translate(q_rot(['z120'],[12,0,0]),l8)
sol5=cpo(convert_3lines2fillet(l6,l8,l7))[:-1]

l1=s2[0]
l2=cpo(s2)[-1][1:-1]
l3=flip(s2[-1])
l4=flip(cpo(s2)[0])[1:-1]
l5=l1+l2+l3+l4
l5=ppplane(l5,q_rot(['z30'],[1,0,0]),l5[10])
l6=offset_3d(l5,-50)
l6=bezier_c(l6,10,-30,s=60)
l6=project_points_on_surface(l6,surf4,q_rot(['z30'],[1,0,0]))
l7=translate(q_rot(['z30'],[10,0,0]),l6)

l8=[offset_3d(l5,-p) for p in linspace(70,200,20)]
l8=[bezier_c(p,10,-30,s=60) for p in l8]
l8=[project_points_on_surface(p,surf4,q_rot(['z30'],[1,0,0])) for p in l8]
l9=[translate(q_rot(['z30'],[12,0,0]),p) for p in l8]
sol6=cpo(convert_3lines2fillet(l6,l9[0],l7))[:-1]
sol6=flip(l8)+sol6+l9[1:]

s7=translate([30,0,0],s1)
l1=s7[0]
l2=cpo(s7)[-1][1:-1]
l3=flip(s7[-1])
l4=flip(cpo(s7)[0])[1:-1]
l5=l1+l2+l3+l4
l6=offset_3d(l5,-50)
l7=bezier_c(l6,11,-30,s=50)
l8=translate([10,0,0],l7)
l9=offset_3d(l5,-70)
l9=bezier_c(l9,11,-30,s=50)
l9=translate([12,0,0],l9)
sol7=cpo(convert_3lines2fillet(l7,l9,l8))[:-1]

s7=translate([30,0,0],s1)
l1=s7[0]
l2=cpo(s7)[-1][1:-1]
l3=flip(s7[-1])

```

```

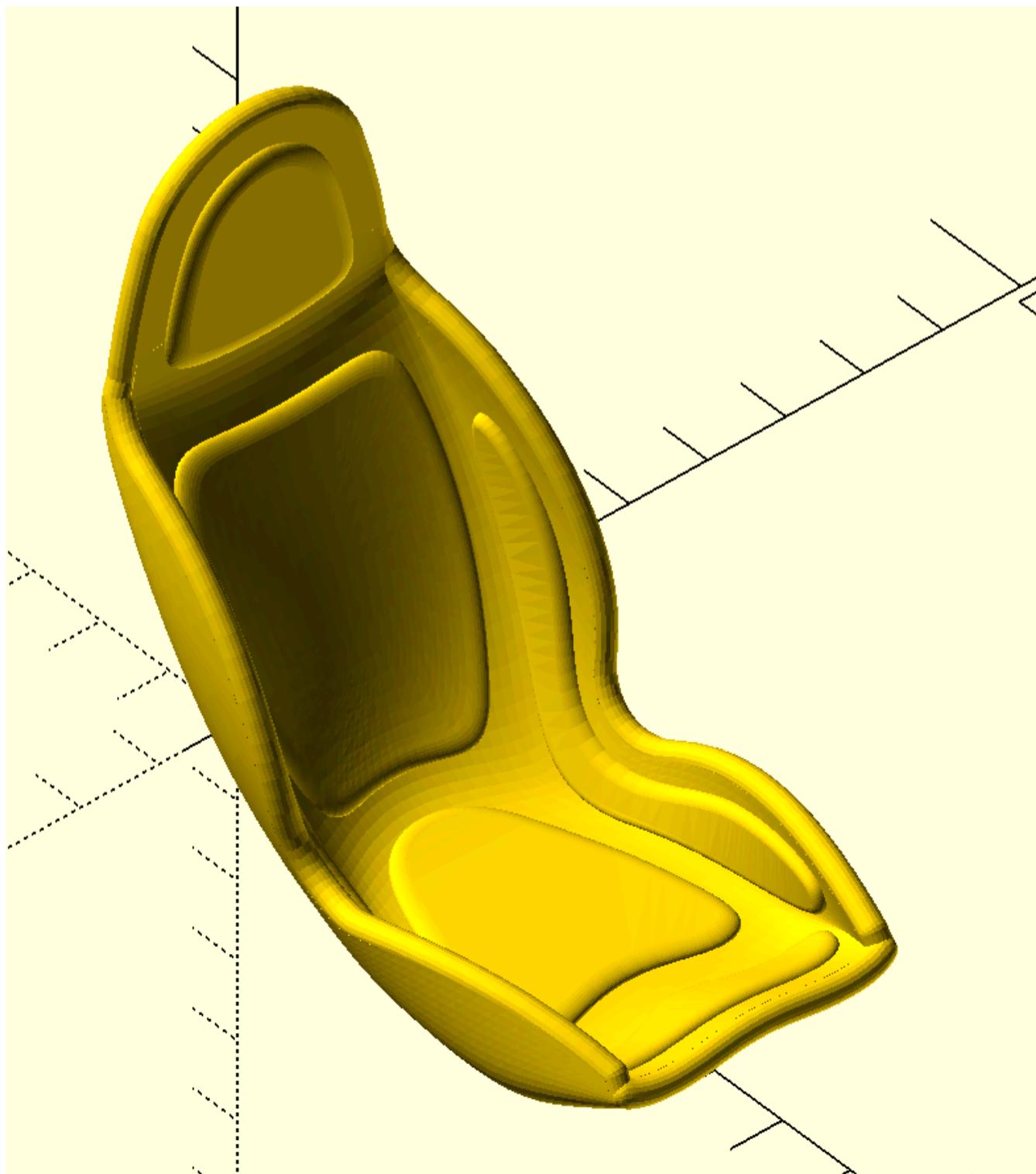
l4=flip(cpo(s7)[0])[1:-1]
l5=l1+l2+l3+l4
l6=offset_3d(l5,-15)
l7=translate([-30,0,0],l6)
sol8=[l7,l6]
l8=[mid_point(p) for p in cpo(sol8)]
l8=l8[-15:]+l8[:35]
pipe=pipe+flip(l8)
solx=o_solid([0,1,0],pts([[0,0],[50,0],[0,50],[-50,0]]),80,515,-10,215,theta=[90,15,0])
soly=flip(mirror_surface(solx,[0,0,1],[0,0,0]))
with open('trial.scad','w+')as f:
    f.write(f'''
        include<dependencies2.scad>
//color("blue")p_line3d(arcs1[0][7:-2],30);
//color("magenta")p_line3d(arc1,30);
//color("green")points(pipe,5);
//color("violet")p_line3d(sol[0],1);
//color("green")for(p=s6)p_line3d(p,1,1);
//color("indigo")p_line3d(l1,1,1);
//color("indigo")p_line3d(cpo(surf2)[0],1,1);
//p_line3d(l3,30);
//p_line3d(l4,30);
//p_line3d(l5[10:-10],30);
//p_line3d(l6,30);
//p_line3d(l7,30);
//p_line3d(l8,30);

rotate([90,0,0]){
difference(){
{swp(sol)}
{swp(solx)}
{swp(soly)}

}}
//{swp(sol8)}
p_line3dc({pipe},30);
{swp(sol2)}
{swp(sol3)}
{swp(sol4)}
{swp(sol5)}
{swp(sol6)}
{swp(sol7)}
hull(){p_line3d({l8},30);}
}
    ''')
f_t=time.time()
f_t-i_t

```

Out [156]: 34.628093004226685



```

In [157...]
a=ellipse(20,15,s=101)
b=a[:33]
c=path_offset(b,-2)
c=[[-21,0],[-21,4]]+bspline_open(equidistant_path([[5,4],[10,4]]+c[11:],5),3,50)

b=b+arc_2p(b[-1],c[-1],1,-1,s=10)+flip(c)
b=q_rot(['x90'],equidistant_path(b,500))
c=bspline_open([a[-14],[10,-5],[-7,-3],[-7,3],[10,5],a[14]],2,50)
c=c[1:-1]+a[14:-13]
sol1=[ q_rot(f'x{i}'),a[:51]) for i in linspace(0,180,50)]
sol2=surface_line_vector(b,[0,20,0],1)
sol3=slice_sol(flip(surface_line_vector(c23(c),[0,0,21])),20)[8:]

l1=psos(sol1,[b],[0,-1,0])[0][220:-30]
l2=o_3d(l1,sol2,-1.5)
l3=o_3d(l1,sol1,1.5)
f1=convert_3lines2fillet(l3,l2,l1)
f1=solid_from_fillet(f1,1.5)
f1=flip(f1+flip(mirror_surface(f1,[0,1,0],[0,0,0])))
l1=psos(sol1,[c23(c)],[0,0,1])[0][3:45]
l2=ip_sol2sol(sol2,flip(sol3),-1)[3:45]
l3=[mid_point(p) for p in cpo([l1,l2])]
l4=o_3d(l2,sol2,1)
l5=o_3d(l1,sol1,-1)
f2=[bspline_open(p,4,20) for p in cpo([l4,l2,l3,l1,l5])]
f21=surface_offset(f2,-1.5)
f2=solid_from_2surfaces(f2,f21)
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>
//      color("blue",.2)p_line3d({l1},.2,1);
//      color("magenta")p_line3d({l2},.2,1);
//      color("green")p_line3d({l3},.2,1);
//      color("orange")p_line3d({l4},.2,1);
//      color("grey")p_line3d({l5},.2,1);

        difference() {{
            difference() {{
                intersection() {{
{swp(sol1)}
{swp(sol2)}
    }}
{swp(sol3)}
{swp(f1)}
    }}
{swp(f2)}
    }}
    ''')

```

/Users/sanjeevprabhakar/openscad/openscad2.py:4779: RuntimeWarning: invalid value encountered in divide
 $u=\text{einsum}('ijkl,ijkl\rightarrow ijk', \text{cross}(p02[\text{None},\text{None},:,:],(-\text{lab})[:, :, \text{None}, :]), (\text{la}[:, :, \text{None}, :] - p0[\text{None},\text{None},:,:])) / (\text{einsum}('ijl,kl\rightarrow ijk', (-\text{lab}), \text{cross}(p01,p02)) + .00000)$

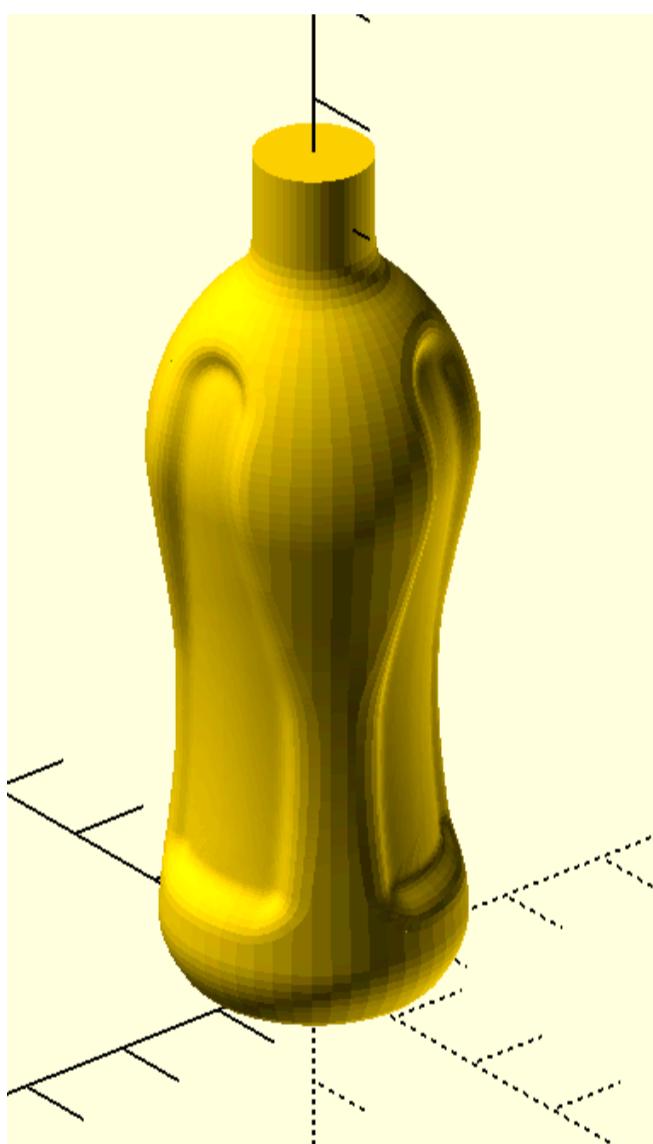
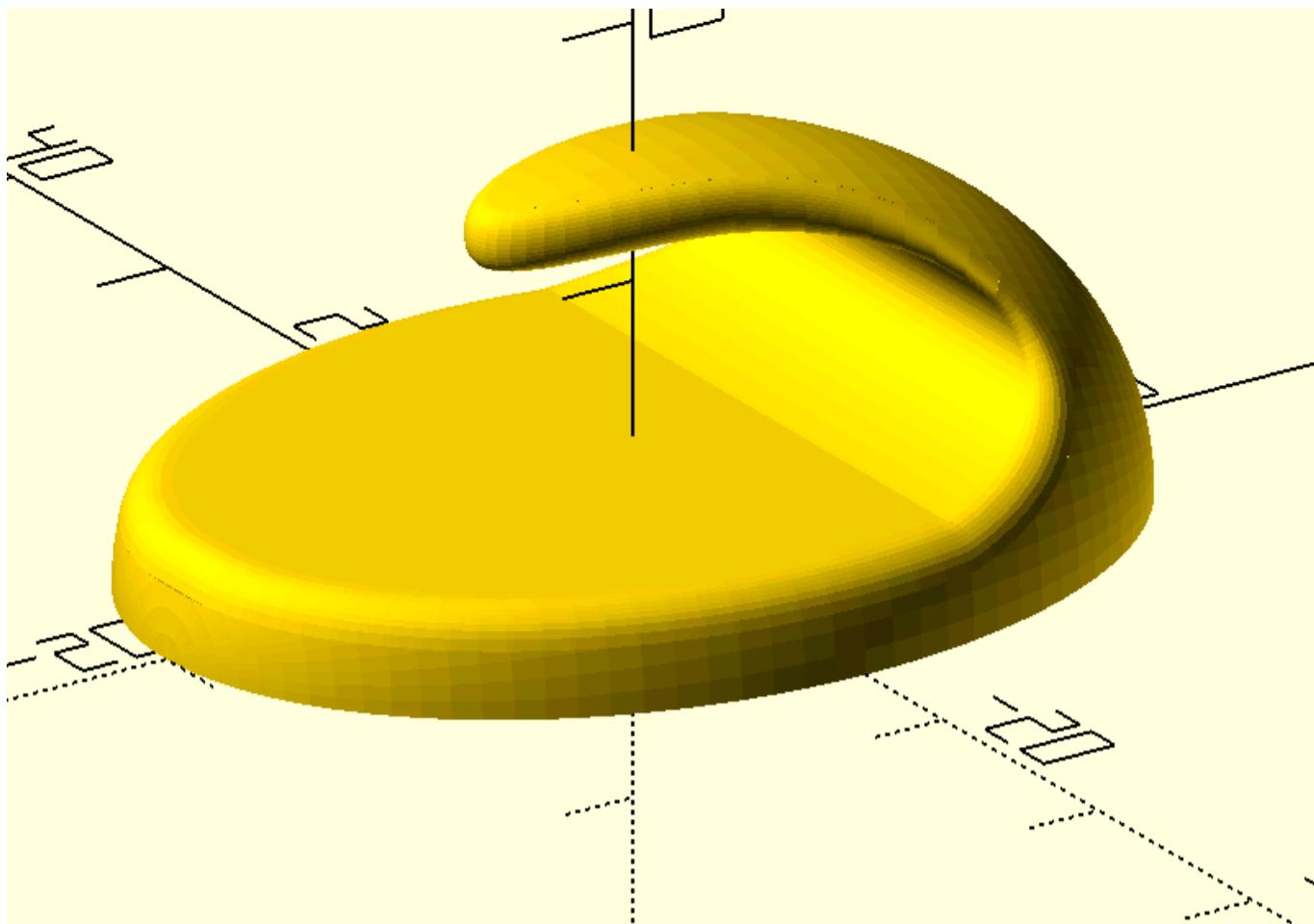
```

In [158...]
sec=circle(10,s=50)
path=corner_radius(pts1([[-3,0,0],[3,0,3],[3,5,7],[-5,20,100],[8,30,20],[-11,10,5],[0,10,0]]),50)
path=equidistant_path(path,100)
sol=prism(sec,path)

sec1=corner_radius(pts1([[-7.5,10,3],[15,0,3],[0,20,30],[-3,20,30],[0,10,4.4],[-9,0,4.4],[0,-10,30],[-3,-20,30]]),20)
sec1=equidistant_pathc(sec1,200)
a=q_rot(['x90'],sec1)
b=q_rot(['x90'],offset(sec1,1.5))
c=q_rot(['x90'],offset(sec1,-1.5))
d=q_rot(['x90'],offset(sec1,-3))
e=surround(equidistant_path([[0,15],[0,55]]),5,.1,10)
e=q_rot(['x90'],equidistant_pathc(e,200))
e=align_sec_1(d,e)[-1]
e=slice_sol([d,e],5)[2:]
a=project_points_on_surface(a,sol,[0,1,0],1)
b=project_points_on_surface(b,sol,[0,1,0],1)
c=translate([0,-2,0],project_points_on_surface(c,sol,[0,1,0],1))
d=translate([0,-2,0],project_points_on_surface(d,sol,[0,1,0],1))
e=[translate([0,-2,0],project_points_on_surface(p,sol,[0,1,0],1)) for p in e]

s1=cpo([bspline_open(p,3,30) for p in cpo([b,a,c,d]+e)])
s2=translate([0,2.5,0],s1)
sol1=flip(flip(s1)+s2)
with open('trial.scad','w+') as f:
    f.write(f'''
        include<dependencies2.scad>
//color("magenta")for(p={s1})p_line3d(p,.2,1);
difference() {{
{swp(sol)}
for(i=[0,120,240])rotate([0,0,i])
{swp(sol1)}
}}
    ''')

```



```
In [160]: from openscad2 import *
i_t=time()

sec=pts([[-155/2,-101/2],[155,0],[0,101],[-155,0]])
rl=[15,15,15,15]
sec=corner_n_radius_list(sec,rl,10)
l1=norm(cp_arc(sec[:10]))
a=cp_arc(sec[:10])
theta=r2d(arctan(a[1]/a[0]))
l2=[q_rot2d(i,[0,0],[l1,0]) for i in [theta,180-theta,180+theta,-theta]]
l3=[surround(p,15) for p in l2]
c1=circle(55/2,s=100)
la,lb,lc=seg(l3[0])[-1],seg(l3[-1])[20],seg(l3[-2])[-1]
a1=fillet_intersection_lines(flip(la),lb,15)
a2=c32(mirror(c23(a1),[1,0,0],[0,0,0]))
a3=fillet_line_circle(lc,c1,15,1)
a4=c32(mirror(c23(a3),[1,0,0],[0,0,0]))
a5=c32(mirror(c23(a3),[0,1,0],[0,0,0]))
a6=c32(mirror(c23(a4),[0,1,0],[0,0,0]))
sec1=flip(a1)+l3[0][:21]+a6+arc_2p(a6[-1],a5[-1],55/2,-1)[1:-1]+flip(a5)+l3[1][21:]+a2 \
+l3[2][21:]+a3+arc_2p(a3[-1],a4[-1],55/2,-1)[1:-1]+flip(a4)+l3[-1][:21]
sec1=equidistant_pathc(sec1,300)
path1=corner_radius(pts1([[-3,0],[2.9,0,3],[0,18,3],[-3,0]]),10)
sol1=prism(sec1,path1)
path2=corner_radius(pts1([[-3,0],[3,0,3],[0,12,3],[-3,0]]),10)
sol2=prism(sec1,path2)+[translate([0,0,12],circle(.2,s=len(sec)+1))]
sol3=linear_extrude(circle(55/2,s=100),45)
```

```

sol3_1=translate([0,0,-1],linear_extrude(circle(42/2,s=100),47))

csnk=translate([0,0,10],linear_extrude(circle(22/2,a),11))
csnk1=mirror_surface(csnk,[0,1,0],[0,0,0])
csnk2=mirror_surface(csnk,[1,0,0],[0,0,0])
csnk3=mirror_surface(csnk1,[1,0,0],[0,0,0])

td=translate([0,0,-1],linear_extrude(circle(14/2,a),20))
td1=mirror_surface(td,[0,1,0],[0,0,0])
td2=mirror_surface(td,[1,0,0],[0,0,0])
td3=mirror_surface(td1,[1,0,0],[0,0,0])

slot=o_solid([0,1,0],pts([-30,0],[60,0],[0,20],[-60,0])),8,-4,0,32)

l1=ip_sol2sol(prism2cpo(sol1),translate([0,0,4],offset_sol(sol3,-.1)))
l2=o_3d_rev(l1,prism2cpo(sol1),3)
l3=translate([0,0,3],l1)
f2=convert_3lines2fillet_closed(l3,l2,l1,style=2)

l1=ip_sol2sol(sol2,sol1,-1)
l2=o_3d_rev(l1,sol2,-3,dist=6)
l2=psos_v(prism2cpo(sol2),[l2],[0,0,-10],dist=3)[0]
l3=o_3d_rev(l1,sol1,3)
f1=convert_3lines2fillet_closed(l3,l2,l1,style=2)

path3=corner_radius(pts1([[5,12],[-5,0,3],[0,33]]),10)
s2=prism(circle(55/2,s=301),path3)
path4=corner_radius(pts1([[0,9],[0,3,3],[-5,0]]),10)
s3=prism(sec1,path4)
s2=align_sol_1(s3+s2)

v1=q_rot(['y45','z-90'],[100,0,0])
sec2=corner_radius(pts1([[-4,0],[0,45,3],[8,0,3],[0,-45]]),10)
sec2=equidistant_path(sec2,200)
sec2=translate([0,-55/2+.5,0],q_rot(['x90'],sec2))
s3=surface_line_vector(sec2,v1)

path3=corner_radius(pts1([[5,12],[-5,0,3],[0,35]]),10)
s4=prism(circle(55/2,s=45),path3)
path4=corner_radius(pts1([[0,9],[0,3,3],[-5,0]]),10)
s5=prism(sec1,path4)
s4=align_sol_1(s5+s4)
l1=psos_n(s4,sec2surface(sec2,1)[19:-1],-1)
l2=[p[0] for p in l1]+flip([p[-1] for p in l1])
l2=equidistant_path(l2,200)
l1=psos(s4,[l2],[0,0,-1])[0]
l1=psos_v(s4,[l1],[0,0,0])[0]
l2=o_3d_rev(l1,s3,-2,type=1)
l3=o_3d_rev(l1,s4,2)
f3=convert_3lines2fillet(l2,l3,l1,style=2)
sol4=translate([0,0,4],linear_extrude(sec,45-4))
with open('trial.scad','w+') as f:
    f.write(f'''')
include<dependencies2.scad>

difference(){{

union(){{

{swp(sol1)}
{swp(sol2)}
{swp(sol3)}

{swp_c(f1)}
{swp_c(f2)}


}}}

for(p=[[csnk,flip(csnk1),flip(csnk2),csnk3]])swp(p);
for(p=[[td,flip(td1),flip(td2),td3]])swp(p);
{swp(slot)}
{swp(sol3_1)}
}}


intersection(){{

{swp(flip(f3))}

{swp(sol4)}


}}


intersection(){{

{swp(s3)}
{swp(sol4)}


}}


mirror([0,1,0])
{{ intersection(){{

{swp(flip(f3))}

{swp(sol4)}


}}}

intersection(){{

{swp(s3)}
{swp(sol4)}


}}}

intersection(){{

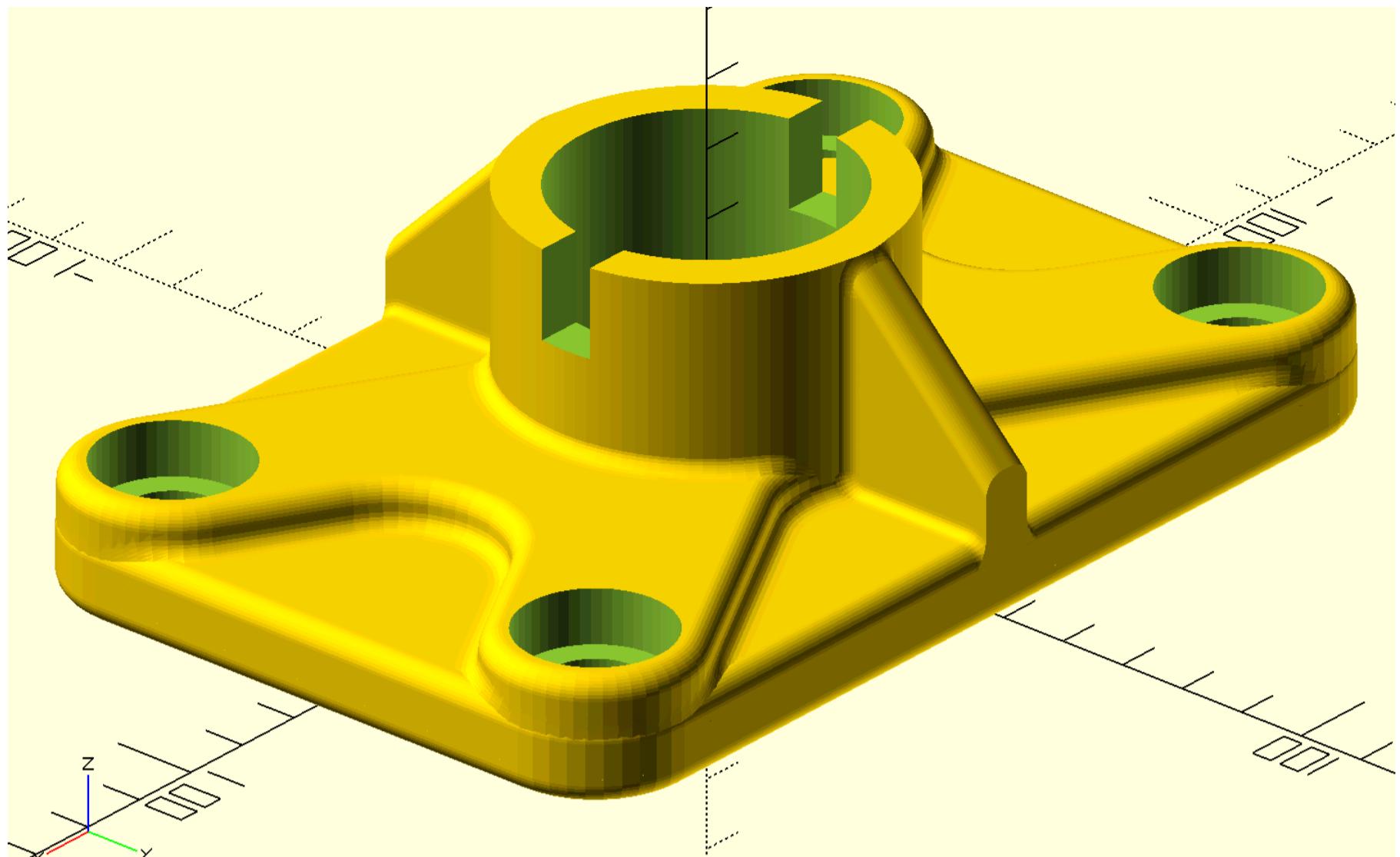
{swp(s3)}
{swp(sol4)}


}}}

...}

f_t=time.time()
f_t-i_t

```



In []: