Calculations by Trapezoidal Speed-Time Curve

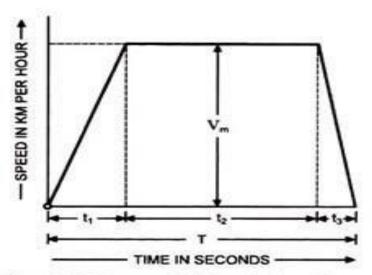


Fig. 11.5. Trapezoidal Speed-Time Curve

Let α = Acceleration in kmphps

 β = Retardation in kmphps

V_m = Crest speed in kmph T = Total time of run in seconds.

Time for acceleration in seconds, $t_1 = V_m/\alpha$ Time for retardation in seconds, $t_3 = V_m/\beta$ Time for free running in seconds, $t_2 = T - (t_1 + t_3) = T - (V_m/\alpha + V_m/\beta)$ Total distance of run in km,

S = Distance travelled during acceleration

- + distance travelled during free run
- + distance travelled during braking

$$= \frac{1}{2} V_m \frac{t_1}{3.600} + V_m \frac{t_2}{3.600} + \frac{1}{2} V_m \frac{t_3}{3.600}$$

Substituting $t_1 = \frac{V_m}{\alpha}$, $t_3 = \frac{V_m}{\beta}$ and $t_2 = T - \left(\frac{V_m}{\alpha} + \frac{V_m}{\beta}\right)$ we

have

$$S = \frac{V_m^2}{7,200\alpha} + \frac{V_m}{3,600} \left[T - \left(\frac{V_m}{\alpha} + \frac{V_m}{\beta} \right) \right] + \frac{V_m^2}{7,200\beta}$$
or
$$S = \frac{V_m^2}{7,200\alpha} + \frac{V_m}{3,600} T - \frac{V_m^2}{3,600\alpha} - \frac{V_m^2}{3,600\beta} + \frac{V_m^2}{7,200\beta}$$

$$= \frac{V_m T}{3,600} - \frac{V_m^2}{7,200\alpha} - \frac{V_m^2}{7,200\beta} \qquad ...(11.1)$$
or
$$\frac{V_m^2}{3,600} \left(\frac{1}{2\alpha} + \frac{1}{2\beta} \right) - \frac{V_m T}{3,600} + S = 0$$
or
$$V_m^2 \left(\frac{1}{2\alpha} + \frac{1}{2\beta} \right) - V_m T + 3,600S = 0$$

This is a quadratic equation for V_m . Substituting $\frac{1}{2\alpha} + \frac{1}{2\beta} = K$, we get

$$KV_m^2 - V_m T + 3,600 S = 0$$
or
$$V_m = \frac{T \pm \sqrt{T^2 - 4K \times 3,600S}}{2K}$$

$$= \frac{T}{2K} \pm \sqrt{\frac{T^2}{4K^2} - \frac{3,600 S}{K}}$$

The +ve sign cannot be adopted, as value of V_m obtained by using +ve sign will be much higher than that is possible in practice. Hence -ve sign will be used and, therefore, we have

$$V_m = \frac{T}{2K} - \sqrt{\frac{T^2}{4K^2} - \frac{3,600 \text{ S}}{K}}$$
 ...(11.2)

From the above equation unknown quantity can be determined by substituting the value of known quantities.

Calculation by Quadrilateral Speed-Time Curve

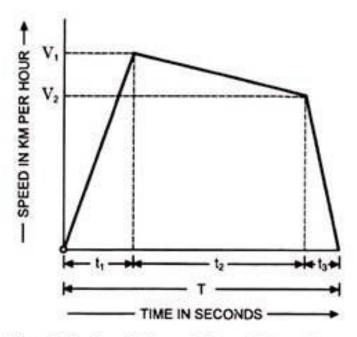


Fig. 11.6. Quadrilateral Speed-Time Curve

Let α = Acceleration in kmphps

 β_c = Coasting retardation in kmphps β = Braking retardation in kmphps

 V_1 = Maximum speed at the end of acceleration in kmph

 V_2 = Speed at the end of coasting in kmph

T = Total time of run in seconds

Time of acceleration in seconds, $t_1 = V_1/\alpha$ Time of coasting in seconds, $t_2 = (V_1 - V_2) / \beta_c$ Time of braking in seconds, $t_3 = V_2/\beta$ Total distance travelled in km, S = Distance travelled during acceleration + distance travelled during coasting + distance travelled during retardation

$$= \frac{1}{2}V_{1} \times \frac{t_{1}}{3,600} + \frac{V_{1} + V_{2}}{2} \times \frac{t_{2}}{3,600} + \frac{1}{2}V_{2} \times \frac{t_{3}}{3,600}$$

$$= \frac{V_{1}t_{1}}{7,200} + \frac{V_{1}t_{2}}{7,200} + \frac{V_{2}t_{2}}{7,200} + \frac{V_{2}t_{3}}{7,200}$$

$$= \frac{V_{1}}{7,200}(t_{1} + t_{2}) + \frac{V_{2}}{7,200}(t_{2} + t_{3})$$
or $S = \frac{V_{1}}{7,200}(T - t_{3}) + \frac{V_{2}}{7,200}(T - t_{1})$
Since $t_{1} + t_{2} + t_{3} = T$

or
$$S = \frac{T}{7,200}(V_1 + V_2) - \frac{V_1 t_3}{7,200} - \frac{V_2 t_1}{7,200}$$

or $S = \frac{T}{7,200}(V_1 + V_2) - \frac{V_1}{7,200} \times \frac{V_2}{\beta} - \frac{V_2}{7,200} \times \frac{V_1}{\alpha}$
 $= \frac{T}{7,200}(V_1 + V_2) - \frac{V_1 V_2}{7,200 \beta} - \frac{V_1 V_2}{7,200 \alpha}$
or $7,200S = T(V_1 + V_2) - V_1 V_2 \left(\frac{1}{\alpha} + \frac{1}{\beta}\right)$...(11.3)
We have $V_2 = V_1 - \beta_c t_2 = V_1 - \beta_c (T - t_1 - t_3)$
 $= V_1 - \beta_c \left(T - \frac{V_1}{\alpha} - \frac{V_2}{\beta}\right)$
or $\left(V_2 - \frac{\beta_c}{\beta} V_2\right) = V_1 - \beta_c \left(T - \frac{V_1}{\alpha}\right)$
or $V_2 = \frac{V_1 - \beta_c T + \frac{\beta_c}{\alpha} V_1}{1 - \frac{\beta_c}{\alpha}}$...(11.4)

Solving Eqs. (11.3) and (11.4) values of S, V_1 , V_2 etc. can be obtained.