Gaussian Flimination

S. Prancenkumor

AIE Ch. Cn. U/pie 220

Ch.en. uyaie22048

rearranging system of equation:

$$(4) \times 25 \rightarrow -1504 + 2007 = 440$$

$$(5) \times 6 \rightarrow -1504 + 1087 = -450$$

$$(4) \times 25 \rightarrow -1504 + 1087 = -450$$

$$(4) \times 25 \rightarrow -1504 + 2007 = 440$$

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$$(4) \times 25 \rightarrow -1504 + 2007 = 440$$

Sub
$$z = 0$$
 in (1)
 $-6y + 0 = -18$
 $+6y = +18$
 $y = 3$

Sub
$$x=0$$
 and $y=3$ in (1)
$$-x-4(3)+0=-9$$

$$-x=+3$$

$$x=-3$$

b)
$$x-y-x-y \to 0$$

 $2x-2y-2x=8 \to 0$
 $5x-5y-5x=20 \to 0$

so, maka free variables
y=s, z=t

solution of system equiation is 4+5+t solution to solution t

Try Sary War PA

Fre I was a great of

in a strained in 18th good by switch to

3

47=2

$$0 \rightarrow x + 6 + 7 = 0$$

$$3 \rightarrow -x - y - 7 = 0$$

$$0 \times + 0 + 0 \times 7 = 2$$

which is not possible

system of solution is no solution

the party of a category of a category

d)
$$3x+4y-7=-6 \rightarrow 1$$

 $-2y+10x=-8 \rightarrow 2$
 $4y-2x=-2 \rightarrow 3$

$$\cancel{5} \rightarrow 3x + x = -4$$

$$\cancel{(-)} \cancel{(-)} \cancel{(+)}$$

$$18z = -18$$

(5)

with the transfer of the facility

He wants to meet his friend at p(7,60)

: yes, he will meet his friend

LU De composition

$$A \Rightarrow \begin{bmatrix} 2 & 3 - 1 \\ 3 & 2 & 1 \\ 1 & -5 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 5 \\ 10 \\ 6 \end{bmatrix}$$

$$L = \begin{bmatrix} 1 & 0 & 0 \\ 1_{21} & 1 & 0 \\ 1_{31} & 1_{32} & 1_{33} \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 1_{21} & i & 0 \\ 1_{31} & 1_{32} & 1_{33} \end{bmatrix} \qquad U = \begin{bmatrix} U_{11} & U_{12} & U_{13} \\ 0 & U_{22} & U_{23} \\ 0 & 0 & U_{32} \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 1_{21} & 1 & 0 \\ 1_{31} & 1_{32} & 1 \end{bmatrix} \begin{bmatrix} 0_{11} & 0_{12} & 0_{13} \\ 0 & 0_{22} & 0_{23} \\ 0 & 0 & 0_{33} \end{bmatrix} = \begin{bmatrix} 2 & 3 & -1 \\ 3 & 2 & 1 \\ 1 & -5 & 3 \end{bmatrix}$$

$$\begin{bmatrix} u_{11} & u_{12} & u_{13} \\ u_{21}u_{11} & u_{21}u_{12}u_{22} & u_{21}u_{13}u_{23} \\ u_{31}u_{11} & u_{31}u_{12}u_{32}u_{32} & u_{31}u_{13}u_{13}u_{13}u_{13} \end{bmatrix} = \begin{bmatrix} 2 & 3 & -1 \\ 3 & 2 & 1 \\ 1 & -5 & 3 \end{bmatrix}$$

$$L = \begin{bmatrix} 1 & 0 & 0 \\ 3/2 & 1 & 0 \\ 1/2 & 13/5 \end{bmatrix} \qquad U = \begin{bmatrix} 2 & 3 & -1 \\ 0 & -5/2 & 5/2 \\ 0 & 0 & -3 \end{bmatrix}$$

$$Ly = 8$$

$$\begin{bmatrix} 3/2 & 0 & 0 \\ 3/2 & 0 & 0 \\ 1/2 & 13/5 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 5 \\ 10 \\ 0 \end{bmatrix}$$

$$y_1 = 5$$

$$y_2 = \frac{30 - 15}{2} = \frac{5}{2}$$

$$\frac{y_1}{2} + \frac{13}{6}y_2 + \frac{y_3}{6} = 0$$

$$\frac{5}{2} + \frac{13}{3} + \frac{13}{3} = 0$$
 $y = \begin{bmatrix} 5 \\ \frac{5}{2} \\ -9 \end{bmatrix}$

$$L = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 2\frac{1}{3} & 1 \end{bmatrix} \qquad U = \begin{bmatrix} 1 & 1 & 1 \\ 0 & -3 & -3 \\ 0 & 0 & 2 \end{bmatrix}$$

$$Lux = 8$$

$$Ux = y \qquad Ly = 8$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \\ 4 \end{bmatrix}$$

$$y_1 = 3 \qquad y_2 = -3 \qquad y_3 = 8$$

$$Ux = y \qquad Ux = y$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 2\frac{1}{3} & 3 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3 \\ -3 \\ 8 \end{bmatrix}$$

$$-3x_{2} - 3(4) = -3$$

$$-3x_{2} - 12 = -3$$

$$-3x_{3} = 9$$

$$\boxed{2x_{2} = -3}$$

$$x_1 - 3 + 4 = 3$$

$$x_1 + 1 = 3$$

$$x_1 = 2$$

$$x_1 = 2$$

$$x_1 = 2$$

$$x_1 = 3$$

$$x_1 = 3$$

$$x_1 = 3$$

$$x_1 = 3$$

$$x_2 = 3$$

$$x_3 = 4$$

```
%S.Praveeen Kumar
%AIE ch.en.u4aie22048
%Lab-1
%1)a)
% Ask user for matrix size
% Ask user for matrix size
n = input('Enter number of variables: ');
% Ask user for matrix coefficients
A = zeros(n);
for i = 1:n
    for j = 1:n
        A(i,j) = input(sprintf('Enter coefficient for A(%d,%d): ', i, j));
    end
end
% Ask user for right-hand side values
b = zeros(n,1);
for i = 1:n
    b(i) = input(sprintf('Enter value for b(%d): ', i));
end
% Gaussian elimination with partial pivoting
for k = 1:n-1
    % Partial pivoting
    [\sim,p] = \max(abs(A(k:n,k)));
    p = p + k - 1;
    if p \sim = k
        A([k,p],:) = A([p,k],:);
        b([k,p]) = b([p,k]);
    end
    % Elimination
    for i = k+1:n
        m = A(i,k) / A(k,k);
        A(i,k:n) = A(i,k:n) - m * A(k,k:n);
        b(i) = b(i) - m * b(k);
    end
end
% Back substitution
x = zeros(n,1);
x(n) = b(n) / A(n,n);
for i = n-1:-1:1
    x(i) = (b(i) - A(i,i+1:n) * x(i+1:n)) / A(i,i);
end
% Display solution
```

```
disp('Solution:');
Solution:
disp(x);

-3.0000
3.0000
0.0000
```

```
%1)b)
% Ask user for matrix size
n = input('Enter number of variables: ');
% Ask user for matrix coefficients
A = zeros(n);
for i = 1:n
    for j = 1:n
        A(i,j) = input(sprintf('Enter coefficient for A(%d,%d): ', i, j));
    end
end
% Ask user for right-hand side values
b = zeros(n,1);
for i = 1:n
    b(i) = input(sprintf('Enter value for b(%d): ', i));
end
% Gaussian elimination with partial pivoting
for k = 1:n-1
    % Partial pivoting
    [\sim,p] = \max(abs(A(k:n,k)));
    p = p + k - 1;
    if p ~= k
        A([k,p],:) = A([p,k],:);
        b([k,p]) = b([p,k]);
    end
    % Elimination
    for i = k+1:n
        m = A(i,k) / A(k,k);
        A(i,k:n) = A(i,k:n) - m * A(k,k:n);
        b(i) = b(i) - m * b(k);
    end
end
% Back substitution
x = zeros(n,1);
```

```
x(n) = b(n) / A(n,n);
for i = n-1:-1:1
    x(i) = (b(i) - A(i,i+1:n) * x(i+1:n)) / A(i,i);
end
% Display solution
disp('Solution:');
```

```
disp(x);
```

NaN NaN NaN

```
%1)c
% Ask user for matrix size
n = input('Enter number of variables: ');
% Ask user for matrix coefficients
A = zeros(n);
for i = 1:n
    for j = 1:n
        A(i,j) = input(sprintf('Enter coefficient for A(%d,%d): ', i, j));
    end
end
% Ask user for right-hand side values
b = zeros(n,1);
for i = 1:n
    b(i) = input(sprintf('Enter value for b(%d): ', i));
end
% Gaussian elimination with partial pivoting
for k = 1:n-1
    % Partial pivoting
    [\sim,p] = \max(abs(A(k:n,k)));
    p = p + k - 1;
    if p ~= k
        A([k,p],:) = A([p,k],:);
        b([k,p]) = b([p,k]);
    end
    % Elimination
    for i = k+1:n
        m = A(i,k) / A(k,k);
        A(i,k:n) = A(i,k:n) - m * A(k,k:n);
        b(i) = b(i) - m * b(k);
    end
```

```
% Back substitution
x = zeros(n,1);
x(n) = b(n) / A(n,n);
for i = n-1:-1:1
    x(i) = (b(i) - A(i,i+1:n) * x(i+1:n)) / A(i,i);
end
% Display solution
disp('Solution:');
```

```
disp(x);
```

NaN NaN NaN

```
%1)d
% Ask user for matrix size
n = input('Enter number of variables: ');
% Ask user for matrix coefficients
A = zeros(n);
for i = 1:n
    for j = 1:n
        A(i,j) = input(sprintf('Enter coefficient for A(%d,%d): ', i, j));
    end
end
% Ask user for right-hand side values
b = zeros(n,1);
for i = 1:n
    b(i) = input(sprintf('Enter value for b(%d): ', i));
end
% Gaussian elimination with partial pivoting
for k = 1:n-1
    % Partial pivoting
    [\sim,p] = \max(abs(A(k:n,k)));
    p = p + k - 1;
    if p ~= k
        A([k,p],:) = A([p,k],:);
        b([k,p]) = b([p,k]);
    end
    % Elimination
    for i = k+1:n
```

```
m = A(i,k) / A(k,k);
    A(i,k:n) = A(i,k:n) - m * A(k,k:n);
    b(i) = b(i) - m * b(k);
end
end

* Back substitution
x = zeros(n,1);
x(n) = b(n) / A(n,n);
for i = n-1:-1:1
    x(i) = (b(i) - A(i,i+1:n) * x(i+1:n)) / A(i,i);
end

* Display solution
disp('Solution:');
```

```
disp(x);
```

-1 -1

```
%2)
% Ask user for matrix size
n = input('Enter number of variables: ');
% Ask user for matrix coefficients
A = zeros(n);
for i = 1:n
    for j = 1:n
        A(i,j) = input(sprintf('Enter coefficient for A(%d,%d): ', i, j));
    end
end
% Ask user for right-hand side values
b = zeros(n,1);
for i = 1:n
    b(i) = input(sprintf('Enter value for b(%d): ', i));
end
% Gaussian elimination with partial pivoting
for k = 1:n-1
    % Partial pivoting
    [\sim,p] = \max(abs(A(k:n,k)));
    p = p + k - 1;
    if p ~= k
        A([k,p],:) = A([p,k],:);
        b([k,p]) = b([p,k]);
```

```
end
    % Elimination
    for i = k+1:n
        m = A(i,k) / A(k,k);
        A(i,k:n) = A(i,k:n) - m * A(k,k:n);
        b(i) = b(i) - m * b(k);
    end
end
% Back substitution
x = zeros(n,1);
x(n) = b(n) / A(n,n);
for i = n-1:-1:1
    x(i) = (b(i) - A(i,i+1:n) * x(i+1:n)) / A(i,i);
end
% Display solution
disp('Solution:');
```

```
disp(x);
```

1 3 -10

```
%3)a
A = [2 \ 3 \ -1 \ ; \ 3 \ 2 \ 1 \ ; \ 1 \ -5 \ 3]
b = [5 ; 10 ; 0]
n = size(A,1);
L = eye(n);
U = A;
for k = 1:n-1
 for i = k+1:n
L(i,k) = U(i,k)/U(k,k);
 U(i,k:n) = U(i,k:n) - L(i,k)*U(k,k:n);
 end
end
disp('L = ');
disp(L);
disp('U = ');
disp(U);
y = zeros(n,1);
y(1) = b(1);
for i = 2:n
y(i) = b(i) - L(i,1:i-1)*y(1:i-1);
end
x = zeros(n,1);
```

```
x(n) = y(n)/U(n,n);
for i = n-1:-1:1
x(i) = (y(i) - U(i,i+1:n)*x(i+1:n))/U(i,i);
disp('X = ');
disp(x);
L = 3 \times 3
    1
    0
         1 0
    0
         0
              1
U = 3 \times 3
        3 -1
    2
          2
    3
               1
    1
               3
Solution:
    1
    2
    3
%3)b
A = [1 \ 1 \ 1;2 \ -1 \ -1;1 \ -1 \ 1]
A = 3 \times 3
         1
              1
    1
        -1 -1
    2
    1
        -1
              - 1
b = [3; 3; 9]
b = 3 \times 1
    3
    3
    9
n = size(A,1);
L = eye(n);
U = A;
for k = 1:n-1
for i = k+1:n
L(i,k) = U(i,k)/U(k,k);
U(i,k:n) = U(i,k:n) - L(i,k)*U(k,k:n);
 end
end
disp('L = ');
L =
disp(L);
   1.0000
                 0
                          0
   2.0000
          1.0000
                          0
                    1.0000
   1.0000
          0.6667
disp('U = ');
```

U =

0

0

2

```
y = zeros(n,1);
y(1) = b(1);
for i = 2:n
    y(i) = b(i) - L(i,1:i-1)*y(1:i-1);
end
x = zeros(n,1);
x(n) = y(n)/U(n,n);
for i = n-1:-1:1
    x(i) = (y(i) - U(i,i+1:n)*x(i+1:n))/U(i,i);
end
disp('X = ');
```

X =

disp(x);

2 -3 4