

$$1) \begin{bmatrix} 4 & 1 & 2 \\ 2 & 4 & -1 \\ 1 & 1 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 9 \\ -5 \\ -9 \end{bmatrix}$$

normalized floating point representation

Using normalization of form

~~1.000 x 10^0~~

~~1.000 x 10^0~~

normalization doesn't change result

$$\begin{bmatrix} 4 \times 10^0 & 1 \times 10^0 & 2 \times 10^0 \\ 2 \times 10^0 & 4 \times 10^0 & -1 \times 10^0 \\ 1 \times 10^0 & 1 \times 10^0 & -3 \times 10^0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 9 \times 10^0 \\ -5 \times 10^0 \\ -9 \times 10^0 \end{bmatrix}$$

taking ~~R1/4~~ R1/4  $\Rightarrow$

We were normalizing as  $0.111 \times 10^0$  in class by the normalization should change answer - Wikipedia

$$\begin{bmatrix} 1 \times 10^0 & 2.5 \times 10^{-1} & 5 \times 10^{-1} \\ 2 \times 10^0 & 4 \times 10^0 & -1 \times 10^0 \\ 1 \times 10^0 & 1 \times 10^0 & -3 \times 10^0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2.3 \times 10^0 \\ -5 \times 10^0 \\ -9 \times 10^0 \end{bmatrix}$$

taking ~~R2 - 2R1~~ R2 - 2R1

$$\begin{bmatrix} 1 \times 10^0 & 2.5 \times 10^{-1} & 5 \times 10^{-1} \\ 0 & 3.5 \times 10^0 & -2 \times 10^0 \\ 1 \times 10^0 & 1 \times 10^0 & -3 \times 10^0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2.3 \times 10^0 \\ -9.6 \times 10^0 \\ -9 \times 10^0 \end{bmatrix}$$

taking R3 - R1

$$\begin{bmatrix} 1 \times 10^0 & 2.5 \times 10^{-1} & 5 \times 10^{-1} \\ 0 & 3.5 \times 10^0 & -2 \times 10^0 \\ 0 & 7.5 \times 10^{-1} & -3.5 \times 10^0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2.3 \times 10^0 \\ -9.6 \times 10^0 \\ -1.1 \times 10^1 \end{bmatrix}$$

taking R2/3.5  $\times 10^0$

$$\begin{bmatrix} 1 \times 10^0 & 2.5 \times 10^{-1} & 5 \times 10^{-1} \\ 0 & 1 \times 10^0 & -5.7 \times 10^{-1} \\ 0 & 7.5 \times 10^{-1} & -3.5 \times 10^0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2.3 \times 10^0 \\ -2.7 \times 10^0 \\ -1.1 \times 10^1 \end{bmatrix}$$



$$R_3 - (7.5 \times 10^{-1})(R_2)$$

$$\begin{bmatrix} 1 \times 10^0 & 2.5 \times 10^{-1} & 5 \times 10^{-1} \\ 0 & 1 \times 10^0 & -5.7 \times 10^{-1} \\ 0 & 0 & -3.1 \times 10^0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2.3 \times 10^0 \\ -2.7 \times 10^0 \\ -9.0 \times 10^0 \end{bmatrix}$$

$$R_3 / 3.1$$

$$\begin{bmatrix} 1 \times 10^0 & 2.5 \times 10^{-1} & 5 \times 10^{-1} \\ 0 & 1 \times 10^0 & -5.7 \times 10^{-1} \\ 0 & 0 & 1 \times 10^0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2.3 \times 10^0 \\ -2.7 \times 10^0 \\ 2.9 \times 10^0 \end{bmatrix}$$

from back substitution

$$x_3 = 2.9 \times 10^0$$

$$x_2 = -2.7 \times 10^0 + (5.7 \times 10^{-1} \times 2.9 \times 10^0)$$

$$= -2.7 \times 10^0 + 1.7 \times 10^0$$

$$= -1 \times 10^0$$

$$x_1 = 2.3 \times 10^0 - (5 \times 10^{-1} \times 2.9 \times 10^0) - (2.5 \times 10^{-1} \times -1 \times 10^0)$$

$$2.3 \times 10^0 - 1.5 \times 10^0 + 0.25 \times 10^0$$

$$\begin{bmatrix} 1 \times 10^0 & 2.5 \times 10^{-1} & 5 \times 10^{-1} \\ 0 & 1 \times 10^0 & -5.7 \times 10^{-1} \\ 0 & 0 & 1 \times 10^0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2.3 \times 10^0 \\ -1 \times 10^0 \\ 2.9 \times 10^0 \end{bmatrix}$$

$$\therefore \text{Solution} = x_1 = 1.1$$

$$x_2 = -1$$

$$x_3 = 2.9$$



2)

library

a) C- FFTW Python - `numpy.fft` (module)  
function `fftw-plan-dft-1d` - `numpy.fft.fft`  
~~by~~ `fftw=execute`

b) library C- GSL Python - `scipy.linalg`  
function `gsl-linalg-QR-decomp()` - `scipy.linalg.qr()`

c) Python - `numpy.random.lognormal([mean, sigma, size])`

d) Python - `scipy.integrate.solve_ivp(..., method='DOP853')`  
by setting method to 'DOP853'

e) Python - `numpy.linalg.svd(a)`

f) Python - `emcee.EnsembleSampler`  
- ~~run-mcmc~~ `run-mcmc`

g) Python - `scipy.integrate.solve_ivp()`  
by Default has 'adaptive step-size control'

h) Python - `mcint` library  
function `mcint.integrate`

i) Python; `scipy.integrate.solve_bvp()`  
`solve-bvp` can solve any number of coupled ODEs

j) Python, `numpy.linalg.eig(a)`



$$3) \quad A \begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \\ \vdots & \vdots \\ a_n & b_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_n \end{bmatrix}$$

A Tridiagonal matrix is a band matrix that has non-zero elements on the main diagonal, the first diagonal below this, and the first diagonal above

Solving using Gaussian Elimination.

first we have to create a upper triangular matrix

① So so to ~~two~~ steps - first Divide  $R_1$  by  $a_1$  & it  
so 2 steps  $(a_1, b_1, d_1)$

② ~~Adding~~ & Subtracting  $R_2 - 4R_1$  - we have  
3-multiplications and 3-subtractions  
 $\therefore$  6-steps.

Repeating the steps for  $R_2$  - (dividing by  $a_{11}$ )

• Repeating the step ② from  $R_3 - R_2$  - 6-9 steps

$\therefore$  for total Recomposition - we have  $N$ -steps of type (1)  
an  $N-1$ -steps of type (2)

$\therefore$  Total number of steps =  $2N + 3(N-1)$   
 $= 5N - 3$  steps

③ for Back substitution - to find solutions. ( $b_1$  and  $d_n'$  are after decomposition)  
for finding  $x_{n-1}$  - we have  $d_n' = b_n'(x_{n-1})$   
which involves - 2-steps  
we have ~~A star~~  $n-1$  steps of the form ②



i. Total Number of steps in Back-substitution =  $2N-2$

∴ Total number of steps

$$= 5N-3 + 2N-2$$

$$= 7N-5 \text{ steps}$$

ii. Order (n)

solving a nxn tridiagonal matrix is of

Order (n) -  $O(n^2)$



5) The main factors to consider while choosing a library are

- 1) Computation time (speed): Different <sup>libraries</sup> ~~algorithms~~ may use different algorithms for computation. So some libraries are faster than others. If you are going to be using the function multiple times or is a very time intensive, it is better to choose faster library.
- 2) Required Accuracy: Some libraries might be fast but may not be able to provide the accuracy required <sup>for</sup> your physics. In that case it is required that we choose the slower but more accurate library. The accuracy depends on the algorithm and how it handles round-off errors.
- 3) Memory: Based on the memory (RAM) available to you, some libraries won't be able to work. So you have to choose the library which can work within your memory thresholds for the given physics problem.

Generally you have to choose a <sup>best</sup> compromise between speed, accuracy and memory. ~~as increasing memory we~~ ~~will be able to get better~~

Other factors while choosing libraries are:

- a) licensing- some libraries are open-source - while others are paid.
- b) Exception - handling - how the libraries handle exceptions. If they are coded well to handle exceptions.
- c) Documentation:- A well documented library will help you considerably when you use it.
- d) Community- Number of people using and working on the library.



## 7) Linear Congruential Method

$$X_{i+1} = (aX_i + c) \bmod m$$

$a$  = multiplier

$c$  = increment

$m$  = modulus

$x_0$  = seed

The selection of values of  $a$ ,  $c$ ,  $m$  and  $x_0$  drastically affects cycle length (length after which the cycle repeats)

~~Example~~  $x_0 = 4$

Repeating sequence.

Take  $a=13$ ,  $c=0$ ,  $m=64$  and  $x_0=4$

$$x_0 = 4 \quad x_1 = (13 \times 4 + 0) \% 64 = 52 \% 64 = 52$$

$$x_2 = (52 \times 13 + 0) \% 64 = 676 \% 64 = 36$$

$$x_3 = (36 \times 13 + 0) \% 64 = 468 \% 64 = 20$$

$$x_4 = (20 \times 13 + 0) \% 64 = 260 \% 64 = 4$$

$\therefore$  Series = 4, 52, 36, 20, 4

a much easier choice of repeating LCG would be to choose

$$a=1, c=0, m=2, x_0=1$$

$$\therefore x_0 = 1$$

$$x_1 = 1 \% 2 = 1$$

$$x_2 = 1 \% 2 = 1$$

~~Example~~

It repeats immediately. We can see that maximum length without repeating is  $m$  (as after that we will have no more integers and we will repeat)



Seed never appears

One simple example would be to

choose  $m=16, a=2, c=0, x_0=8$

$$\therefore x_0 = 8$$

$$x_1 = (2x_0 + 0) \% 16 = 0$$

$$x_2 = 0$$

$$x_3 = 0$$

$\vdots$

$\therefore$  The seed doesn't appear again, but the sequence is also not random.

~~The maximum number of random numbers occurs when the seed repeats after m iterations or seed occurs~~

The maximum cycle length without any repeat repetition or large period is  $m$

to get the maximum period we have to choose

$m = \text{as large as possible} \Rightarrow 2^b = 2^{32}$  (maximum = 32 bit number)

$c = \text{relative prime to } m \Rightarrow \text{odd number}$

$a = 144k - (k \text{ is any integer})$



4) b) The maximum frequency is given by nyquist extension frequency -

$$= \text{extended } \cancel{\text{max}} \frac{\pi}{\Delta} \times \cancel{\Delta}$$

$$\cancel{\text{which is } \frac{\pi}{\Delta} \times \Delta}$$

$$f_{\max} = \frac{n-1}{n} 2\pi \left( \frac{1}{2\Delta} \right) = \frac{n-1}{n} \frac{\pi}{\Delta} \quad \text{for our case} = 3.13$$

$$f_{\min} = -2\pi \left( \frac{1}{2\Delta} \right) = -\frac{\pi}{\Delta} \quad \text{for our case} = -3.14$$

We are assuming a sampling rate of 1Hz as it is not specified in the problem, based on our experiment we will know the sampling rate from which we can find  $\Delta$  as  $(1/\text{sampling rate})$ . It doesn't depend on  $n$ .

e) As our input is a uniform distributed - the power spectrum that we expect is a fourier transform of uniform function - we know that the fourier transform of a uniform function is a Delta function - so ~~we can~~ our result for power spectrum which is in form of Delta-function should be correct.