```
/home/neofelis/VRX
/drift/include/drift
/kinematics/robots/mini
_cheetah/Jws_Body_to_FrontRight
Foot.h
```

```
/home/neofelis/VRX
/drift/src/kinematics
/robots/mini_cheetah/Jws
_Body_to_FrontRightFoot.cpp
```