/home/neofelis/VRX
/drift/include/drift
/kinematics/robots/mini
_cheetah/Jvb_Body_to_HindRight
Foot.h

/home/neofelis/VRX
/drift/src/kinematics
/robots/mini_cheetah/Jvb
_Body_to_HindRightFoot.cpp