

```
/home/neofelis/VRX  
/drift/include/drift  
/kinematics/robots/mini  
_cheetah/Jwb_Body_to_FrontRight  
Foot.h
```



```
/home/neofelis/VRX  
/drift/src/kinematics  
/robots/mini_cheetah/Jwb  
_Body_to_FrontRightFoot.cpp
```