

# 信号与系统第三次测试 (2021 年)

姓名:

学号:

1. 已知一因果连续 LTI 系统的微分方程为

$$y''(t) + 4y'(t) + 3y(t) = x'(t) + 2x(t)$$

试求:

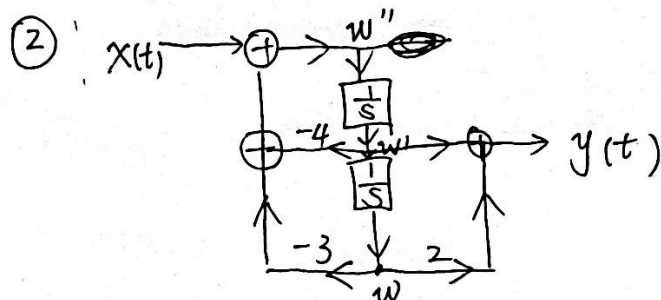
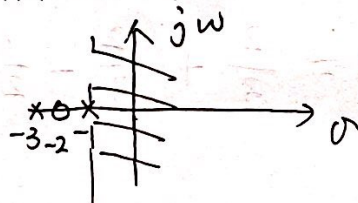
(1) 系统的  $H(s)$ , 画出  $H(s)$  零极图并判断系统的稳定性;

(2) 画出模拟框图;

(3)  $y(0^-) = -1, y'(0^-) = 1, x(t) = e^{-2t}u(t)$  时, 求  $y(t) (t > 0)$  的全响应、零输入响应和零状态响应。

(4) 当激励  $x(t) = u(-t) + 2u(t)$  时, 求  $y(t) (-\infty < t < \infty)$ 。

①  $H(s) = \frac{s+2}{(s+1)(s+3)}$



③ 
$$s^2 \widetilde{Y}(s) - sy(0) - y'(0) + 4[s\widetilde{Y}(s) - y(0)] + 3\widetilde{Y}(s) = (s+2) \cdot \frac{1}{s+2}$$

$$(s^2 + 4s + 3) \widetilde{Y}(s) = 1 + sy(0) + y'(0) + 4y(0)$$

$$= 1 + (-s + 1 - 4)$$

$$= 1 + (-s - 3)$$

$$\widetilde{Y}(s) = \frac{1}{(s+1)(s+3)} - \frac{s+3}{(s+1)(s+3)}$$

$$= \frac{\frac{1}{2}}{s+1} - \frac{\frac{1}{2}}{s+3} - \frac{1}{s+1}$$

$$y(t) = \underbrace{\frac{1}{2}(e^{-t} - e^{-3t})u(t)}_{y_{zs}(t)} - \underbrace{e^{-t}u(t)}_{y_{zi}(t)} = -\frac{1}{2}[e^{-t}u(t) + e^{-3t}u(t)]$$



$$(4) \quad x(t) = 1 + u(t)$$

$$1 = e^{0t} \xrightarrow{\text{LTZ}} H(0)e^{0t} = \frac{2}{3}$$

再求  $u(t)$  对应输出

$$(s^2 + 4s + 3)Y(s) = \frac{s+2}{s} \quad \operatorname{Re}\{s\} > 0$$

$$Y(s) = \frac{s+2}{s(s+1)(s+3)}$$

$$= \frac{\frac{2}{3}}{s} - \frac{\frac{1}{2}}{s+1} - \frac{\frac{1}{6}}{s+3}$$

$$y(t) = \frac{2}{3}u(t) - \frac{1}{2}e^{-t}u(t) - \frac{1}{6}e^{-3t}u(t)$$

因此:

$$y(t) = \frac{2}{3} + \left( \frac{2}{3} - \frac{1}{2}e^{-t} - \frac{1}{6}e^{-3t} \right)u(t)$$

