

# Initial report of 1976 U.S. Atmospheric Model methodology

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# 1 Background

“The USSA mathematical model divides the atmosphere into layers with an assumed linear distribution of absolute temperature  $T$  against geopotential altitude  $h$ . The other two values (pressure  $P$  and density  $\rho$ ) are computed by simultaneously solving the equations resulting from:

$$\frac{dP}{dh} = -\rho g \quad (1)$$

$$P = \rho R_{\text{specific}} T \quad (2)$$

where  $R_{\text{specific}}$  is the specific gas constant for dry air and  $g$  is the standard gravitational acceleration.” Equation (1) evaluates the vertical pressure variation with the mean sea level as a boundary condition ( $P_0 = 101,325$  Pa) and Equation (2) is the ideal gas law in molar form [1].

Combining equations (1) and (2) to find an expression for the pressure:

$$\ln P \Big|_{P_0}^{P_1} = -\frac{g}{R_{\text{specific}}} \int_{h_0}^{h_1} \frac{dh}{T(h)} \quad (3)$$

where the minimum geopotential altitude above sea level is set to  $h_0 = -1,524$  m. From [The Engineer ToolBox](#), various temperatures have been given for their corresponding geopotential altitudes in Table 1 [2].

Table 1: USSA1976 Temperature for Geopotential Altitude - Imperial (BG) Units

$h$ [ft]	$T$ [°F]
−5000	76.84
0	59
5000	41.17
10000	23.36
15000	5.55
20000	−12.26
25000	−30.05
30000	−47.83
35000	−65.61
40000	−69.70
45000	−69.70
50000	−69.70
60000	−69.70
70000	−67.42
80000	−61.98
90000	−56.54
100000	−51.10
150000	19.40
200000	−19.78
250000	−88.77

<sup>2</sup>It is interesting to note that if the maximum value of  $h$  is fed into (4) then the numerical value for the integral in the RHS becomes  $323.7972921077598 \pm 1.173024627261422 \times 10^{-10}$ .

where  $C_d$  is the drag coefficient and  $A$  is the cross-sectional area. The method which computes drag takes in ECEF position,<sup>3</sup> velocity, and ballistic parameters ( $C_d$ ,  $A$ ,  $m$ ) to output an acceleration due to force vector. The acceleration due to drag can be found using Newton's second law;  $\vec{a}_d = \vec{F}_d/m$ .

### 3 An Example

An object of mass  $m = 100\text{ kg}$  is traveling with a velocity of  $\vec{v} = (v_x, v_y, v_h) = (20, 100, 3000)\text{ m/s}$  at an ECEF position of  $(0, 0, 10000)\text{ m}$  where the latter component is the altitude. The drag coefficient is 1 and the cross-sectional area of the object is  $100\text{ m}^2$ . From the applied model for atmosphere here and the fourth degree polynomial for  $T(h)$  its temperature is  $226.956\text{ K}$  and it follows that its pressure is  $21846.097\text{ Pa}$  and the density of air at that altitude is  $0.335\text{ kg/m}^3$ . The applied drag force at that altitude would be  $\vec{F}_d = (1.677 \times 10^5, 1.509 \times 10^8, 6.707 \times 10^3)\text{ N}$ ; ergo, the length of the acceleration due to drag would be  $|\vec{a}_d| = 1508978.973\text{ m/s}^2$ .<sup>4</sup>

### Bibliography

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- [6] Ralph L. Carmichael, Public Domain Aeronautical Software, *Geopotential & Geometric Altitude*, retrieved on 01/22/2024 from <https://www.pdas.com/hydro.pdf>.
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<sup>3</sup>The altitude is the only relevant coordinate when it comes to this specific calculation as Equation (5)'s only parameter dependent on position is  $p$ .

<sup>4</sup>Although it does change with altitude,  $g = 9.81\text{ m/s}^2$  is used for all altitudes in this implementation.