



Advances in the Algebraic Factorization of Overconstrained Closed-Loop Linkages

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Unit of Geometry and Surveying

6R linkages

Kinematic image space

Via Study's kinematic mapping

$$\mathfrak{S} : \text{SE}(3) \hookrightarrow \mathcal{S} \subset \mathbb{P}^7$$

rigid body displacements are associated with points in 7-dimensional projective space \rightsquigarrow dual quaternion representation of $\text{SE}(3)$ in our work.

Overconstrained closed-loop linkages:

Their motions are described by curves on the Study quadric \mathcal{S} .

Factorization:

The process of computing the axes of a linkage from the curve in the kinematic image space.

Null quadric

Of particular interest are singular
displacements
 \rightsquigarrow dual quaternions with norm zero

Null quadric

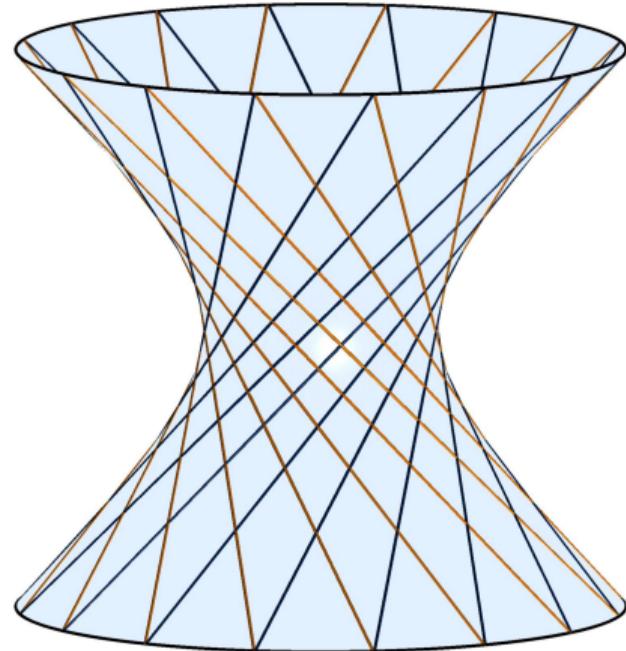
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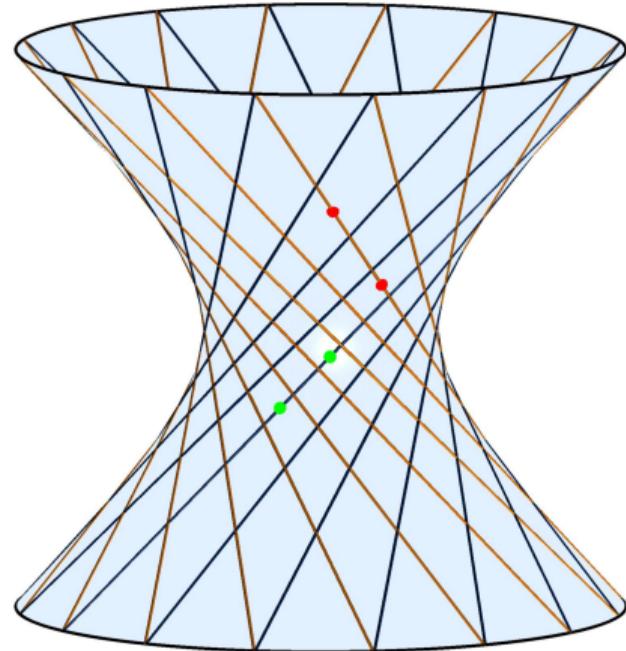
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State of the art

As outlined by Li et al. (2025), if some of the null points lie in the same linear subspaces of the null quadric $(n_i)^* n_j = 0$ or $n_i (n_j)^* = 0$, we can compute an axis.

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- ① Find a plane $a = a_1 \mathbf{i} + a_2 \mathbf{j} + a_3 \mathbf{k} + a_4 \varepsilon$ such that

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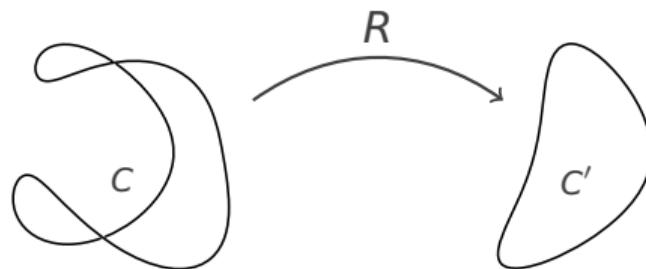
Research question: What are techniques and methods to factor a 6R linkage?

Riemann-Roch maps

Goal: The construction of a map R from a constraint curve C to a curve C' of lower degree.

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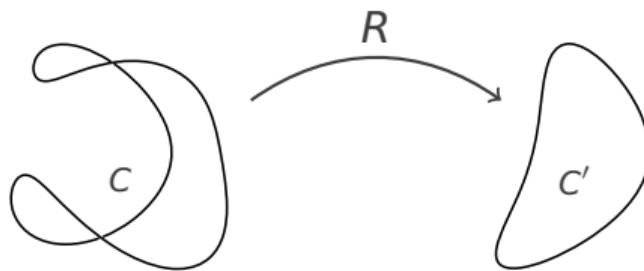
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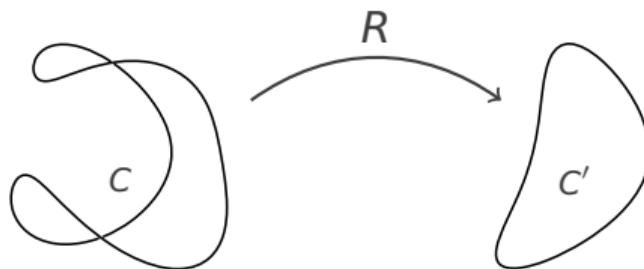


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is a rational map under certain constraints, namely

- vanish at certain null points,
- be of a given mapping degree,
- ...

Purpose: Eliminate some null points
 \rightsquigarrow lower degree.

Multiplication trick

Situation: Null points are not suited for the computation of the first and last axes via the standard method \rightsquigarrow Bricard plane-symmetric mechanism

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$$n'_i = (\varrho(n_i) - h)n_i$$

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Result: We get the first and last axes as well as the null points for the middle axis.

Outlook and conclusion

For certain linkage classes – plane-symmetric or line-symmetric Bricard – we have developed a method to factorize the axes of the linkage.

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Conclusion: Factorization can be done algebraically and most information about the mechanisms is contained in the null points.

**Thank you for
your attention!**

