

PCA :-

↳ Eigenvectors are vectors that just scale up/down on multiplication but never rotates.

↳ A matrix can be represented in dimensions of eigenvectors

$N \times N$   
Can have  $N$  eigenvectors.  
(orthogonal projections).

↳ Independent + somewhat interpretable.

↳ Influence of 1 dimension over others.

↳ Translation independence.

$$A = V \Lambda V^T$$

Eigendecomposition  
⇒ If eigenvalue = 0 → singular matrix (As one of the vector useless).

$$\Rightarrow \beta^T X^T X \beta + \frac{1}{2} (y - X\beta)^T (y - X\beta) \rightarrow \beta^T X^T X \beta - 2X^T y \beta + \frac{1}{2} y^T y$$

↳  $\frac{\partial L}{\partial \beta} \rightarrow -2X^T(y - X\beta)$  (Here at this  $\beta$  you will find a solution)

→ Quadratic Loss

↳ If we find eigendecomposition of  $X^T X$  i.e. covariance,  $\beta^T X (V \Lambda V^T) X \beta$  we will be able to speak something about the dist of  $\beta$  vectors (that are weights).

⇒ Additionally variability will be easily explained using eigenvalues of  $X^T X$ .



# Singular Value Decomposition

↳ Same as Eigendecomposition  
 ↳ Mapping from  $R^{n \times n}$  to  $R^{n \times n}$  space  
 (Two-way) ↳ predictor space (B)

$$A_{m \times n} = U \Sigma V^T$$

$m \times m$        $n \times n$

$$A A^T \subseteq I \quad \hookrightarrow A^T A$$

Symmetric Matrix  
 ↳ Eigenvectors are orthogonal

⇒ Eigenvector of a matrix  $A \rightarrow A \hat{x} = \lambda \hat{x}$

↳ There will be multiple projections of  $\hat{x}$  for  $A$   
 ↳ Max  $\rightarrow N$   
 ↳ Proof: Roots of  $x^n$

↳ can produce the same for  $x^T x$

↳ symmetric - orthogonal eigenvalues  
 $A x^T y = x^T A y$

⇒ New Story (NPTEL 6.1 IITM)

→ We have a vector  $V$ , A transformation  $A$   
 Properties of  $A \rightarrow$  column 1 or 1 row &  $\sum = 1$   
 ↳ symmetric

↳ Multiple times application of  $A$  will generate a vector in direction of dominant eigenvector of  $A$  (Theorem)

Idea  $\rightarrow A \sim \frac{X^T X}{N}$  (Keep in Mind) Variance (diagonal, diag)  $\rightarrow$  Covariance matrix

## Application

PCA  $\rightarrow$  Linear Transformation + Unsupervised Projections of given predictors vectors to a new space

$\hookrightarrow$  Reason or Objective Maximize Variability  $p \times p$

Data  $\rightarrow$  For this optimization  $\rightarrow X$

$x_1, x_2, \dots, x_{p-1}, x_p \rightarrow$  New projection  $\hookrightarrow p \times 1$   
(Find  $\alpha$ ) that maximize

dot product  $\alpha_i$   $\hookrightarrow \frac{(x_{01} - \text{Mean}(x_{01}))^2}{N}$  from the dataset  
with new  $\alpha$   $\hookrightarrow x_{01} + \alpha_1 x_1 + \dots$

Optimization is Non-Linear

See Vars  $\rightarrow \alpha$ 's (projections)  $\hookrightarrow$  Maybe Quadratic

$\hookrightarrow$  We will pass the dataset  $X$  as is to the objective function

$\hookrightarrow$  Define what to minimize  $\hookrightarrow$  maximize

$\Rightarrow$  Not done yet  $\rightarrow$  Subtract this projection from the dataset and find the repeat the process again on the new data

$\hookrightarrow$  This is  $\sim$  to finding eigenvalues of  $X^T X$  (covariance)



largest

Eigenvalues of a transformation must be  $\begin{matrix} \rightarrow E_x: \text{stretch } (x \rightarrow x) \\ \rightarrow E_y: \text{shrink } (y \rightarrow -y) \end{matrix}$

$\geq 1$  Good stability

$> 1 \rightarrow \text{Explode}$

$\rightarrow N$  components

$< 1 \rightarrow \text{Vanish}$

BASIS

$\rightarrow$  Projections of PCA are basis

$\hookrightarrow \therefore$  eigenvectors of cov. hgh.  $\hookrightarrow$  vectors are not expressed as some of others.

$\rightarrow$  In cases PCA's are the basis in which we try to project our data

$\rightarrow$  If basis, we need to find projections for this basis PCA's

If orthogonal basis then projection can be easily found.

$\rightarrow$  Eigenvectors are orthogonal  $\rightarrow$  of a symmetric.  $\hookrightarrow$  linearly independent

$\rightarrow$  Why we use this basis (multiple reasons)

$AU = A \begin{bmatrix} u_1 & u_2 & \dots & u_n \end{bmatrix} = \begin{bmatrix} Ae_1 & Ae_2 & \dots & Ae_n \end{bmatrix}$

$\begin{bmatrix} u_1 & u_2 & \dots & u_n \end{bmatrix} \begin{bmatrix} \tau_1 & \tau_2 & \dots & \tau_n \end{bmatrix} = U \tau$   
 $AU = U \tau$   
 $AU = U \tau \rightarrow A = U \tau U^{-1}$

$Q \Rightarrow U^T U$   
 $\hookrightarrow$  eigenvectors

are orthogonal.

$$= \begin{bmatrix} \leftarrow u_1 \\ \leftarrow u_2 \\ \leftarrow u_n \end{bmatrix} \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix} \quad \text{non}$$

$$U^T U = I$$

$$U^T U_{ij} \Rightarrow \langle u_1, u_2 \rangle = 0 \quad \langle u_i, u_j \rangle = 1 \text{ if } i=j$$

Any  $A = U \Lambda U^T$  if  $A$  is iteratively on  $x_0$   
 then final result  $\rightarrow$  stable if  $\lambda = 1$   
 Exploding if  $\lambda > 1$ .

Let  $A = N \times N$  matrix.

We wish to find max value of  $x^T A x$  st  $|x| = 1$ .

optimize:  $L = x^T A x - \frac{\lambda}{2} (x^T x - 1)$   
 $2Ax - \lambda x = 0 \quad \Rightarrow \quad Ax = \lambda x$   
 $\therefore x$  must be an eigenvector of  $A$  with value  $\lambda$

\* Why did we do this:-

So far  $\rightarrow$  • Different eigenvalues  $\Rightarrow$  diff eigenvectors  
 • Eigenvectors  $\rightarrow$  orthogonal.  $\therefore$  good basis

Unit Variance, centered  $\rightarrow$  helps in regularization

Right eigenvalues for variance  $\hookrightarrow$  Deep NN weights well regularized and applied - section (1.1, 1.2)



## Motivation of PCA :-

- ↳ Reduce dimensions in which the data is well explained
- ↳ project on new un-correlated dimensions

1. One data point  $x_i$  ( $\overset{p \rightarrow \# \text{ of predictors}}{m \times n}$  space)

$$x_i = x_{i1}p_1 + x_{i2}p_2 \dots x_{in}p_n$$

↳  $p_1$  is itself linear comb of  $p$  predictors

PCA is first optimization to find  $p_i$ 's. (1 to  $n$ )

Let there be  $M$  data points

Then we need to find a new set of  $\hat{p}_1, \hat{p}_2, \dots, \hat{p}_n$ .

$$\begin{matrix} x_1(1 \times N) \\ x_2 \\ \vdots \\ x_m \end{matrix} = \begin{matrix} \leftarrow x_1 \rightarrow \\ 1 \times N \end{matrix} \times \begin{bmatrix} \hat{p}_1 \\ \hat{p}_2 \\ \vdots \\ \hat{p}_n \end{bmatrix} \rightarrow 1 \times N$$

$$\leftarrow x_2 \rightarrow$$

$$\rightarrow 1 \times N$$

$$\leftarrow x_m \rightarrow$$

$$1 \times N$$

Stack these together to find new projection

$$\text{map: } \begin{matrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{matrix} \rightarrow M \times N = X P \rightarrow \text{Let it be } P \begin{matrix} \text{eigenvectors} \\ \text{(Basis)} \end{matrix}$$

$\Rightarrow X^T X \rightarrow$  is covariance if  $X$  is zero centered

Let say we have these. (Need to evaluate)

$$\hat{X} = X P$$

Covariance of the transformed data =  $\hat{X}^T \hat{X}$

$$\hat{X}^T \hat{X} = (XP)^T XP = P^T X^T X P = P^T \left( \sum \right) P$$

~ covariance of the original data

↳ covariance of the transformed data

↳ Want this to be diagonal.

~  $AU = U\Lambda = U\Gamma$   
~  $U^T AU = \Gamma = \text{diagonal}$

We want  $P^T \Sigma P = \text{Diag}$  ∴  $P$  must be stack of eigenvectors of  $\Sigma$

PCA → Linear transformation to the new basis where 1<sup>st</sup> variance is high and 2<sup>nd</sup> cov is 0. Iteratively optimize

↳ diagonalise the  $\Sigma$

↳ This will give stack of eigenvectors as answer.

Any transformed data point

$$\hat{x}_i = \sum_{j=1}^N x_{ij} p_j$$

(We can remove some dimensions)

↳ Pure construction

$$L = \sum_{i=1}^m (\hat{x}_i - \bar{\hat{x}})^T (\hat{x}_i - \bar{\hat{x}})$$

Data points

$$\sum_{i=1}^m \left( \sum_{j=1}^N x_{ij} p_j - \sum_{j=1}^p x_{ij} p_j \right)^T \times ( )$$

p Reduced dimension

$$\sum_{i=1}^m \left( \sum_{j=p+1}^N (x_{ij} p_j)^T ( ) \right)$$

$$p_i p_j = p_j p_i = 0 \text{ if } i \neq j$$

Same

$$\sum_{i=1}^m [x_{i,p+1} p_{p+1} + x_{i,p+2} p_{p+2} \dots x_{i,N} p_N]^T ( )$$



$$= \sum_{i=1}^M \sum_{j=R+1}^N (x_{ij})^2$$

$$= \sum_{i=1}^M \sum_{j=R+1}^N (\mathbf{x}_i^T \mathbf{p}_j)^2$$

$$= \mathbf{P}_j^T \sum_{i=1}^M x_i x_i^T \mathbf{p}_j$$

↳ covariance

Minimize  $\mathbf{p}_j^T \Sigma \mathbf{p}_j$

↳ Find smallest eigenvalues of  $\Sigma$

↳ Throw away these dimensions

PCA - Orthogonal basis (so that the projections are easily found)

Covariance  $\rightarrow$  Eigenvectors of covariance

Property -  
Is of transform  
= diagonal.

Stack of these evs

gives

Eigenvalues

can also be  
used for  
dimensionality  
reduction.

~~eigenvectors~~ orthogonal  
basis.

↳ Transformed projection  
can be easily  
computed

Take dot product  
of dot point with  
basis / eigenvectors.



Because eigenvectors are orthogonal.

↳ as  $X^T X$  is symmetric

$$P = [e_1, e_2, \dots]$$

$$X_{\text{transformed}} = X \cdot P = \langle X, P \rangle$$

$$X_{\text{transformed}} = X \cdot P_i = \langle X, P_i \rangle$$

$$\text{Variance} = X_{\text{tra}}^T X_{\text{transformed}} \rightarrow \text{eigenvector}$$

$$= (X P_i)^T (X P_i) = P_i^T (X^T X P_i)$$

$$= P_i^T X^T X P_i = P_i^T P_i = I_i$$

To maximize variance select the largest

$P_i$

Example :-

↳ Image (100 x 100) → 10K dimensions

50-200 dimensions. Need to compress the data

$$X \rightarrow M \times 10K.$$

↳  $X^T X$  → Then compute the eigendecomposition of the same

↳ Each eigenvector is represented in 10K dimensions

↳ Linear combination of original features

We have 10000 eigenvectors

Each eigenvector  $\rightarrow$  1 map of  $100 \times 100$  pixel

Original Image (100x100)  $\rightarrow$  1st Map

The difference between  $(x_i - x_{ip1})^2 \rightarrow$  Reconstruct error.

Only 20-50 basis  $n_i$ 's (top ones) will help us explain the image

$\Rightarrow$  Originally 8 ~~1000~~ images  $\rightarrow$  100  $\times$  100 pixel each.

$\Rightarrow$  We stored 10k features for 8 images  $[8 \times (10k)]$  Each represented in 10k dims.

Now we only need 20 eigenvectors (basis)

$\hookrightarrow$  If we have 20 for 20 basis.

$\hookrightarrow [20 \times (10k)] \rightarrow$  This is transformation issue.

But we can now explain 8 images in just 20 dimensions

(Transformation and  $\overline{x_i}$  dimensions will reduce)



PCA  $\rightarrow$  Deals with data Augmentation

$\hookrightarrow$  Remove less significant dimensions  
explainability (Noise)

Data Augmentation

$\hookrightarrow$  Lighting, Rotation, Translation

$\hookrightarrow$  Creates noise base variation

$\hookrightarrow$  can be removed.