

SOAR: A Synthesis Approach for Open-Source API Refactoring

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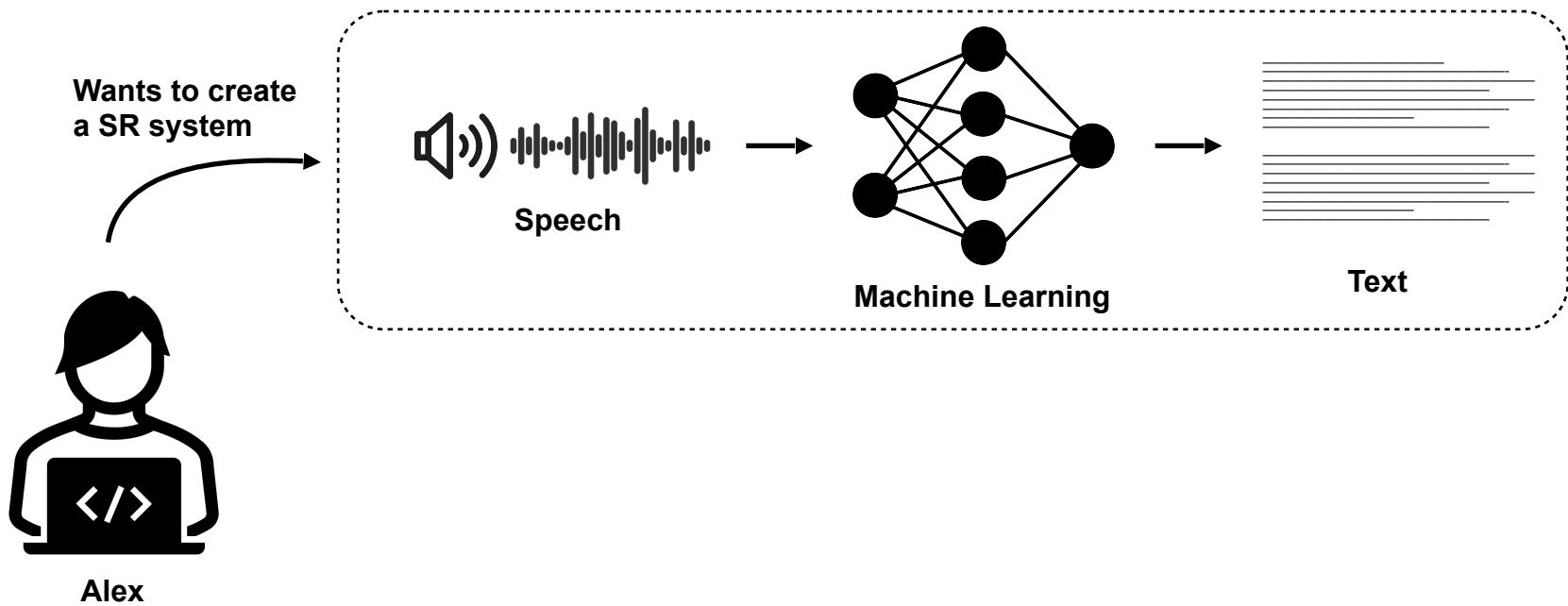
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Ruben Martins
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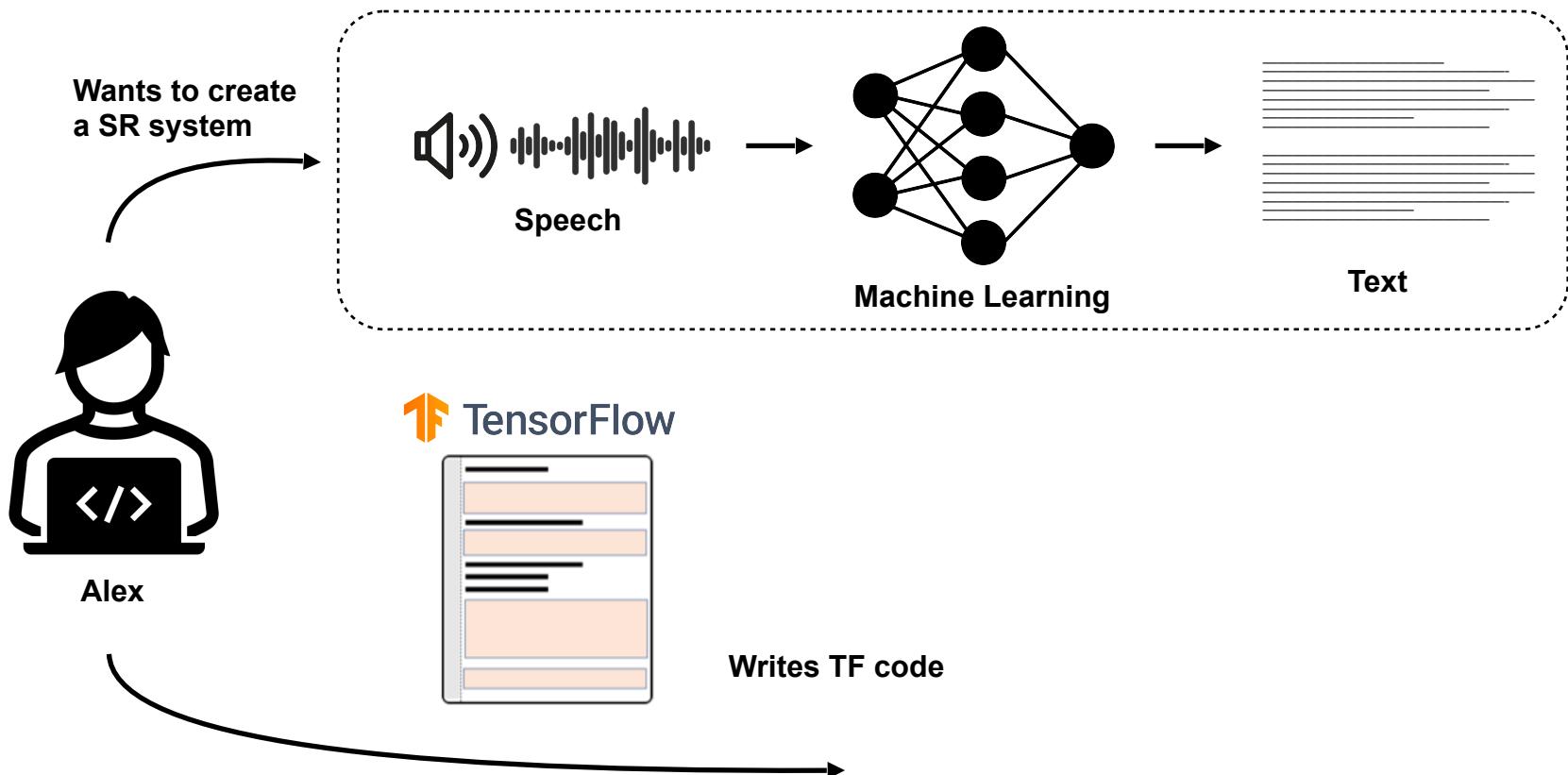
Claire Le Goues
CMU



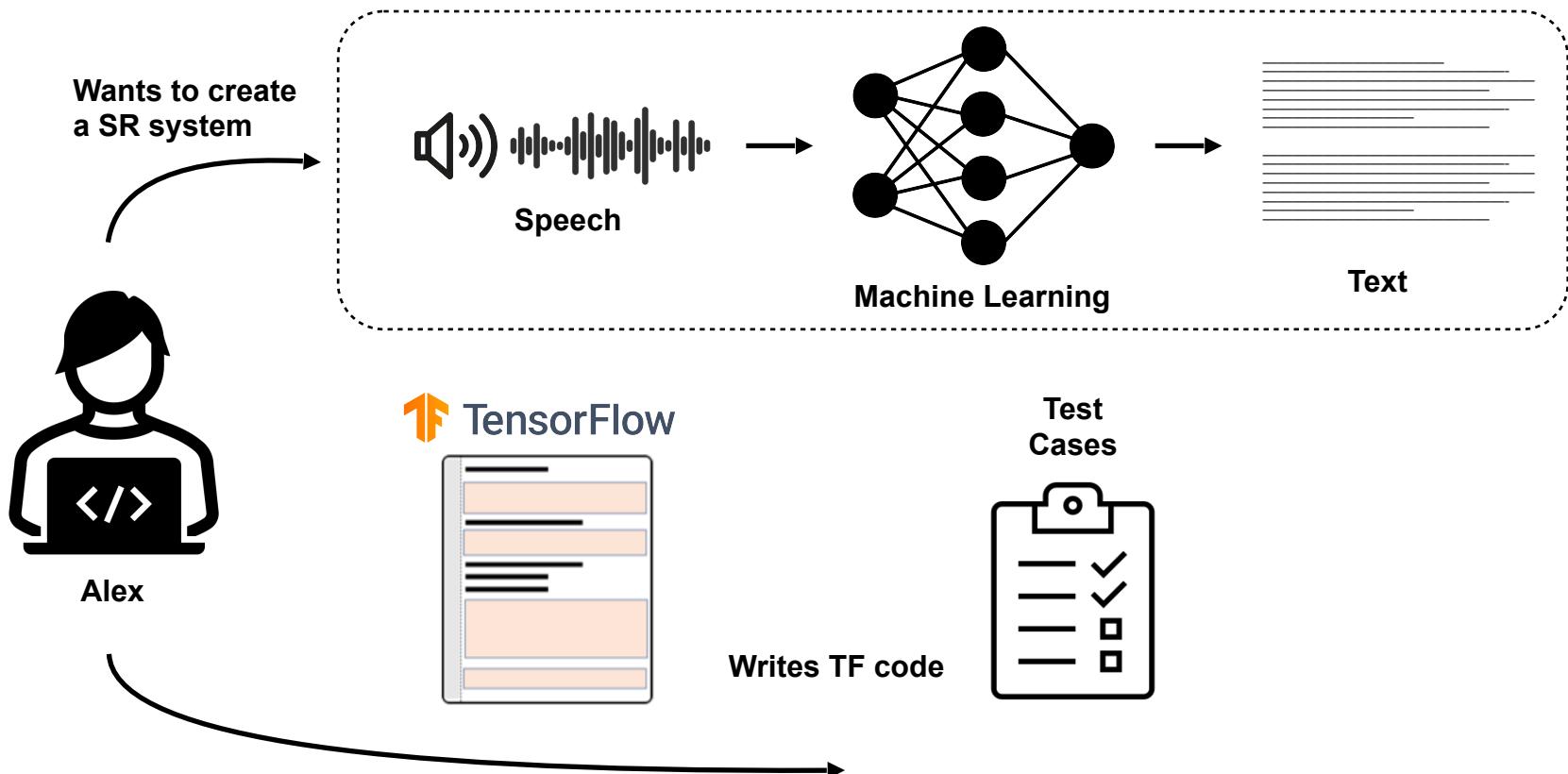
MOTIVATION



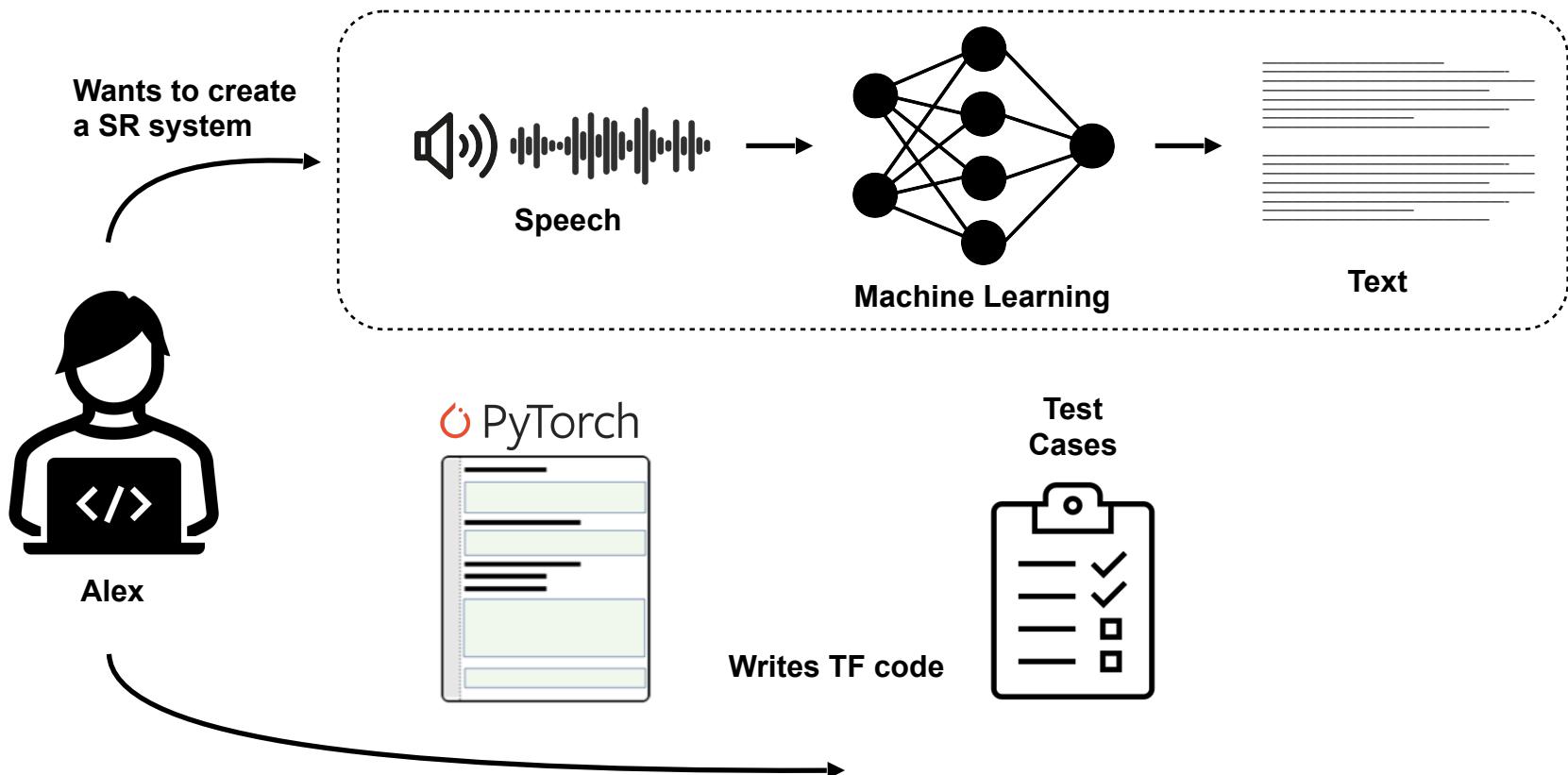
MOTIVATION



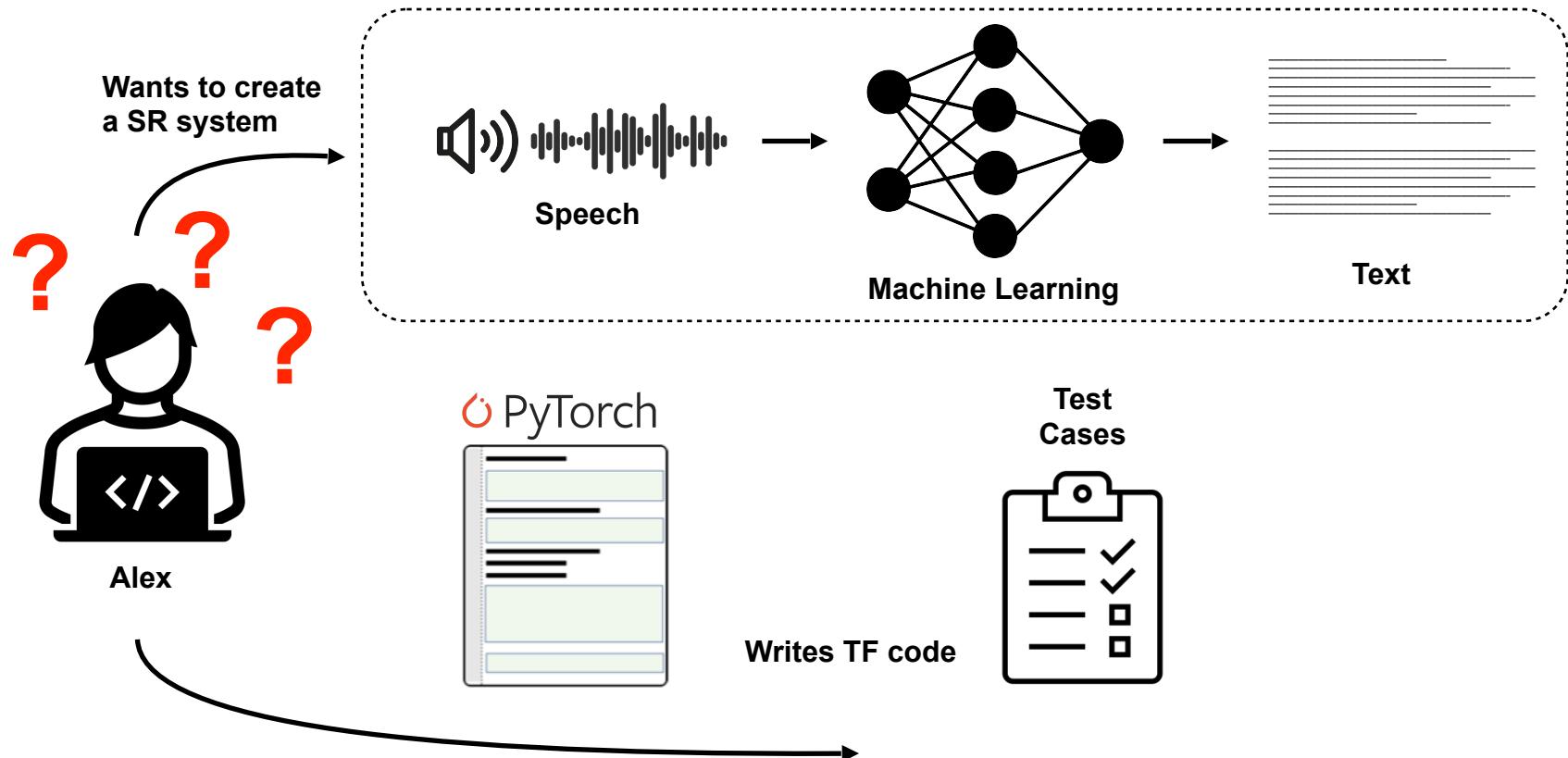
MOTIVATION



MOTIVATION

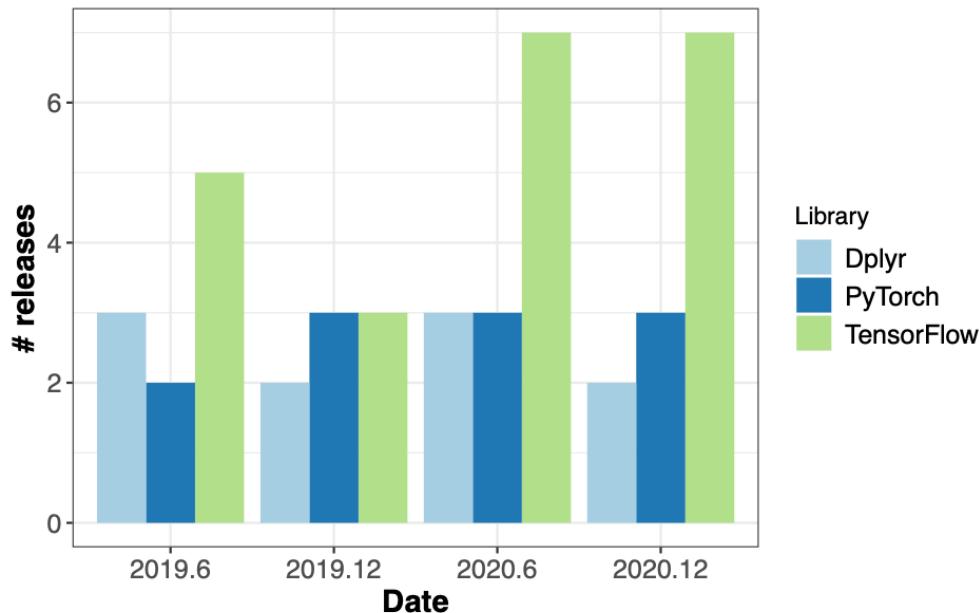


MOTIVATION



API REFACTORYING PROBLEM

- This is an API refactoring / migration problem
- Libraries no longer supported, new alternatives, updates, etc.



SOAR: A SYNTHESIS APPROACH FOR API REFACTORING

- SOAR's an end-to-end technique for API migration

```
import tensorflow as tf

class TensorLin(tf.keras.Model):
    def __init__(self, **kwargs):
        super(TensorLin, self).__init__()
        self.fc1 = tf.keras.layers.Dense(128)
        self.fc2 = tf.keras.layers.Dense(256)
        self.out = tf.keras.layers.Dense(10)

    def call(self, x):
        x = self.fc1(x)
        x = self.fc2(x)
        x = self.out(x)
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Source (TF)

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```

Source (TF)

```
import torch

class TorchLin(torch.nn.Module):
    def __init__(self, **kwargs):
        super(TorchLin, self).__init__()
        self.fc1 = torch.nn.Linear(50, 128)
        self.fc2 = torch.nn.Linear(128, 256)
        self.out = torch.nn.Linear(256, 10)

    def forward(self, x):
        x = self.fc1(x)
        x = self.fc2(x)
        x = self.out(x)
        return x
```

Target

SOAR: A SYNTHESIS APPROACH FOR API REFACTORING

- SOAR is built upon three key observations:
 - 1. Data science APIs are well documented**

tf.keras.layers.Dense

Table of contents

Used in the notebooks

Arguments

✓ See Stable

See Nightly



TensorFlow 1 version



View source on GitHub

Just your regular densely-connected NN layer.

Inherits From: [Layer](#), [Module](#)

+ View aliases

Used in the notebooks

Used in the guide

- Save and load Keras models
- The Sequential model
- Training and evaluation with the built-in methods
- The Functional API
- Making new Layers and Models via subclassing

Used in the tutorials

- Overfit and underfit
- Time series forecasting
- Intro to Autoencoders
- Transformer model for language understanding
- Load CSV data

`Dense` implements the operation: `output = activation(dot(input, kernel) + bias)` where `activation` is the element-wise activation function passed as the `activation` argument, `kernel` is a weights matrix created by the layer, and `bias` is a bias vector created by the layer (only applicable if `use_bias` is `True`).



Note: If the input to the layer has a rank greater than 2, then `Dense` computes the dot product between the `inputs` and the `kernel` along the last axis of the `inputs` and axis 1 of the `kernel` (using `tf.tensordot`). For example, if input has dimensions (batch_size, 10, 10), then the output has 50 units (10 * 10 * 5) and the `kernel` has dimensions (10, 5).

Arguments

units

Positive integer, dimensionality of the output space.

activation

Activation function to use. If you don't specify anything, no activation is applied (ie. "linear" activation: $a(x) = x$).

use_bias

Boolean, whether the layer uses a bias vector.

kernel_initializer

Initializer for the `kernel` weights matrix.

bias_initializer

Initializer for the bias vector.

kernel_regularizer

Regularizer function applied to the `kernel` weights matrix.

Table of Contents



LINEAR

CLASS `torch.nn.Linear(in_features, out_features, bias=True)`[\[SOURCE\]](#)

Applies a linear transformation to the incoming data: $y = xA^T + b$

This module supports [TensorFloat32](#).

Parameters

- **in_features** – size of each input sample
- **out_features** – size of each output sample
- **bias** – If set to `False`, the layer will not learn an additive bias. Default: `True`

LINEAR

CLASS `torch.nn.Linear(in_features, out_features, bias=True)`

[SOURCE]

Applies a linear transformation to the incoming data: $y = xA^T + b$

This module supports `TensorFloat32`.

Parameters

- **in_features** – size of each input sample
- **out_features** – size of each output sample
- **bias** – If set to `False`, the layer will not learn an additive bias. Default: `True`

Shape:

- Input: $(N, *, H_{in})$ where * means any number of additional dimensions and $H_{in} = \text{in_features}$
- Output: $(N, *, H_{out})$ where all but the last dimension are the same shape as the input and $H_{out} = \text{out_features}$.

SOAR: API MAPPINGS

- Using the mappings we can replace the source APIs

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import tensorflow as tf

class TensorLin(tf.keras.Model):
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    def call(self, x):
        x = self.fc1(x)
        x = self.fc2(x)
        x = self.out(x)
        return x

import torch

class TorchLin(torch.nn.Module):
    def __init__(self, **kwargs):
        super(TorchLin, self).__init__()
        self.fc1 = torch.nn.Linear(?, ?)
        self.fc2 = torch.nn.Linear(?, ?)
        self.out = torch.nn.Linear(?, ?)

    def forward(self, x):
        x = self.fc1(x)
        x = self.fc2(x)
        x = self.out(x)
        return x
```

PROBLEM

- How can we compute the new arguments?

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SOAR: A SYNTHESIS APPROACH FOR API REFACTORING

- SOAR is built upon three key observations:
 1. Data science APIs are really well documented
 - 2. Computing arguments is a great fit for program synthesis**

SOAR: PROGRAM SYNTHESIS

- Documentation has information about argument types, constraints
- Enumerate possible values and validate

```
import torch

class TorchLin(torch.nn.Module):
    def __init__(self, **kwargs):
        super(TorchLin, self).__init__()
        self.fc1 = torch.nn.Linear(int: x1, int: x2)
        self.fc2 = torch.nn.Linear(int: x3, int: x4)
        self.out = torch.nn.Linear(int: x5, int: x5)

    def forward(self, x):
        x = self.fc1(x)
        x = self.fc2(x)
        x = self.out(x)
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```

SOAR: PROGRAM SYNTHESIS

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        x = self.out(x)
        return x
```

<code>x1 = -1 & x2 = 256</code>	
<code>x1 = 50 & x2 = -1</code>	
<code>x1 = 50 & x2 = 128</code>	

SOAR: A SYNTHESIS APPROACH FOR API REFACTORING

- SOAR is built upon three key observations:
 1. Data science APIs are really well documented
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SOAR uses documentation to guide the synthesis

SOAR: A SYNTHESIS APPROACH FOR API REFACTORING

- SOAR is built upon three key observations:
 1. Data science APIs are really well documented
 2. Computing arguments is a great fit for program synthesis
 - 3. Well-documented APIs have informative error messages**

SOAR: ERROR MESSAGE UNDERSTANDING

- SOAR uses error messages to speed-up the synthesis process
- Generates constraints from the errors to prune the search space

`torch.nn.Linear(-1, 50)` \longrightarrow $x_1 \geq 0$

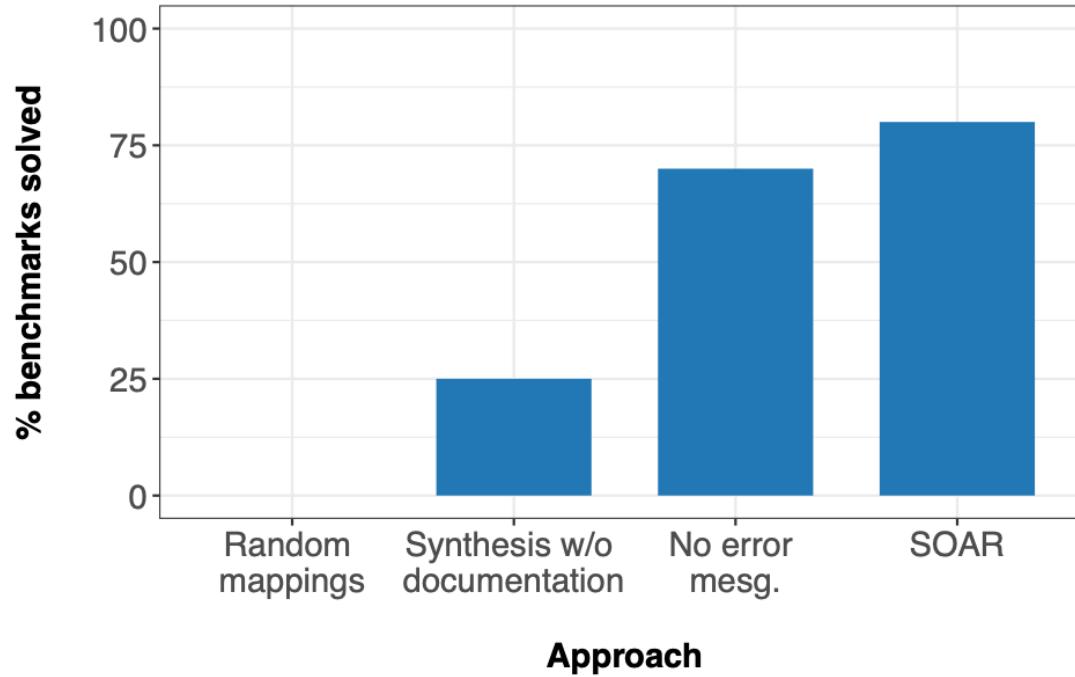
Trying to create tensor with negative dimension -1: [-1, -1]

BENCHMARKS

- Evaluated SOAR on 40 benchmarks from two domains:
 - 20 tasks from TensorFlow to PyTorch
 - 20 tasks from dplyr (R) to pandas (Python)
- Migrations tasks from TensorFlow to PyTorch correspond to migrating a network with 3 to 44 layers, including:
 - Auto-encoders
 - VGG
 - AlexNet
 - LeNet

SOAR TRANSLATES 80% OF THE BENCHMARKS

- Benchmarks solved for the TensorFlow to PyTorch task (1h timeout)



SOAR: MIGRATION EXAMPLE

```
1 from tensorflow import keras
2
3 class AutoEncoder(keras.Model):
4     def __init__(self, **kwargs):
5         super(AutoEncoder, self).__init__()
6         self.conv1 = keras.layers.Conv2D(filters=32,
7                                         kernel_size=3,
8                                         strides=(2,2))
9
10        self.relu1 = keras.layers.ReLU()
11        self.conv2 = keras.layers.Conv2D(filters=64,
12                                         kernel_size=3,
13                                         strides=(2,2))
14
15        self.relu2 = keras.layers.ReLU()
16        self.flatt = keras.layers.Flatten()
17        self.dense = keras.layers.Dense(10)
18        self.dense = keras.layers.Dense(units=1568)
19        self.relu3 = keras.layers.ReLU()
20        self.resha = keras.layers.Reshape(
21                                         target_shape=(7, 7, 32))
22        self.conv3 = keras.layers.Conv2DTranspose(
23                                         filters=64,
24                                         kernel_size=3,
```

```
1 import torch
2
3 class AutoEncoder(torch.nn.Module):
4     def __init__(self, **kwargs):
5         super(AutoEncoder, self).__init__()
6         self.many_0 = lambda x: x.permute(0, 3, 1, 2)
7         self.var816 = torch.nn.Conv2d(32, 32, (3, 3),
8                                     stride=(2, 2),
9                                     padding=(0, 0))
10        self.var817 = torch.nn.ReLU()
11        self.many_1 = lambda x: x.permute(0, 1, 3, 2)
12        self.var1528 = torch.nn.Conv2d(32, 64, (3, 3),
13                                     stride=(2, 2),
14                                     padding=(0, 0))
15        self.var1529 = torch.nn.ReLU()
16        self.var1530 = lambda x: torch.flatten(x, 1)
17        self.var1710 = torch.nn.Linear(64, 10)
18        self.var1801 = torch.nn.Linear(10, 1568)
19        self.var1802 = torch.nn.ReLU()
20        self.many_2 = lambda x: x.view(10, 7, 7, 32)
21
22        self.many_3 = lambda x: x.permute(0, 3, 1, 2)
23        self.var5089 = torch.nn.ConvTranspose2d(32, 64,
24                                             (3, 3),
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SOAR: MIGRATION EXAMPLE

LIMITATIONS

- Automatic Testing - Decomposability
Intermediate outputs must be tested independently
- Error message understanding model is library specific
Different libraries have different stylings for error presentation
- Synthesis doesn't support many-to-many mappings
SOAR only supports one-to-one and one-to-many mappings

FINAL REMARKS



- Novel approach for automatic API refactoring:
 - Requires no training data
 - Leverages API documentation and error messages
 - Guarantees that migrated code passes all test cases
 - Language agnostic
- All code is open-source: <https://github.com/danieltrt/SOAR/>
- Replication package: <https://zenodo.org/record/4452730>

KEY TAKEAWAY

Documentation can help automating API refactoring tasks

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