# Lecture: An Assembly Language

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## 1 Language

### 1.1 Syntax

```
\begin{array}{c} \mathit{naturals} & \mathbf{n}, \mathbf{pc}, \mathbf{i}, \mathbf{j}, \mathbf{k} \\ \mathit{States} & \mathbf{s} ::= \langle \mathbf{m}, \mathbf{R}, \mathbf{f}, \mathbf{pc} \rangle \\ \mathit{Instructions} & \mathbf{i} ::= \mathbf{add} & \mathbf{r_i} & \mathbf{r_j} \mid \mathbf{const} & \mathbf{k} & \mathbf{r_i} \mid \mathbf{jmp} & \mathbf{r_i} \mid \mathbf{jz} & \mathbf{r_i} \\ & \mid \mathbf{load} & \mathbf{r_i} & \mathbf{r_j} \mid \mathbf{store} & \mathbf{r_i} & \mathbf{r_j} \mid \mathbf{cmp} & \mathbf{r_i} & \mathbf{r_j} \mid \mathbf{set} & \mathbf{r_i} & \mathbf{r_j} \\ \mathit{Register} & \mathbf{file} & \mathbf{R} ::= \mathbf{r_1} \mapsto \mathbf{n_1}, \mathbf{r_2} \mapsto \mathbf{n_2}, \cdots \\ \mathit{Registers} & \mathbf{r} & \mathbf{taken} & \mathbf{from} & \mathbf{an} & \mathbf{infinite}, & \mathbf{denumerable} & \mathbf{set} \\ \mathit{Flags} & \mathbf{f} ::= \mathbf{zf} = \mathbf{b} & \mathbf{b} = \mathbf{true} \mid \mathbf{false} \\ \mathit{Memories} & \mathbf{m} ::= \mathbf{n_1} \mapsto \mathbf{m_1}, \mathbf{n_2} \mapsto \mathbf{m_2}, \cdots \end{array}
```

Auxiliaries

$$(Memory\ Access) \\ \underline{pc \mapsto n \in m} \\ m(pc) = n \qquad \frac{r \mapsto n \in R}{R(r) = n}$$

$$(Memory\ Update) \\ \underline{m = n_1 \mapsto m_1, n_2 \mapsto m_2, \cdots, pc \mapsto n', \cdots} \\ \underline{m' = n_1 \mapsto m_1, n_2 \mapsto m_2, \cdots, pc \mapsto n', \cdots} \\ \underline{m[pc \mapsto n] = m'}$$

$$(Register\ Update) \\ R = r_1 \mapsto m_1, r_2 \mapsto m_2, \cdots, r \mapsto n', \cdots \\ \underline{R' = r_1 \mapsto m_1, r_2 \mapsto m_2, \cdots, r \mapsto n, \cdots}$$

$$R[r \mapsto n] = R'$$

$$(Instruction\ decoding) \\ \underline{\|i\| = n}$$

#### 1.2 Semantics

$$\begin{split} \mathbf{m}(\mathbf{pc}) &= \| \mathbf{add} \ \mathbf{r_i} \ \mathbf{r_j} \| \quad \mathbf{R}(\mathbf{r_i}) = \mathbf{n_i} \quad \mathbf{R}(\mathbf{r_j}) = \mathbf{n_j} \quad \mathbf{n_i} + \mathbf{n_j} = \mathbf{n_f} \\ & \langle \mathbf{m}, \mathbf{R}, \mathbf{f}, \mathbf{pc} \rangle \rightarrow \langle \mathbf{m}, \mathbf{R}[\mathbf{r_i} \mapsto \mathbf{n_f}], \mathbf{f}, \mathbf{pc} + \mathbf{1} \rangle \\ & \underbrace{\mathbf{m}(\mathbf{pc}) = \| \mathbf{const} \ \mathbf{j} \ \mathbf{r_i} \|}_{(\mathsf{Eval-const})} \\ & \underbrace{\mathbf{m}(\mathbf{pc}) = \| \mathbf{const} \ \mathbf{j} \ \mathbf{r_i} \|}_{(\mathsf{Eval-jmp})} \\ & \underbrace{\mathbf{m}(\mathbf{pc}) = \| \mathbf{jmp} \ \mathbf{r_i} \| \quad \mathbf{R}(\mathbf{r_i}) = \mathbf{n_i}}_{(\mathsf{Eval-jz-true})} \\ & \underbrace{\mathbf{m}(\mathbf{pc}) = \| \mathbf{jz} \ \mathbf{r_i} \| \quad \mathbf{R}(\mathbf{r_i}) = \mathbf{n_i}}_{(\mathsf{Eval-jz-true})} \\ & \underbrace{\mathbf{m}(\mathbf{pc}) = \| \mathbf{jz} \ \mathbf{r_i} \| \quad \mathbf{R}(\mathbf{r_i}) = \mathbf{n_i} \quad \mathbf{f} = \mathbf{zf} = \mathbf{true}}_{(\mathsf{m}, \mathbf{R}, \mathbf{f}, \mathbf{pc}) \rightarrow \langle \mathbf{m}, \mathbf{R}, \mathbf{f}, \mathbf{n_i} \rangle} \end{split}$$

The initial state runs execution from address 0 until it encounters an instruction that it cannot decode, the result value in that case is in  $\mathbf{r}_0$ .

## 2 Compiler from the Source to this Target

### 2.1 Compiler Definition

The compiler  $[\cdot]$  takes in input: a source expression  $\mathbf{e}$ , a list of registers  $\mathbf{K}$ , a list of bindings V, an address where to write the instructions. It returns: a list of instructions  $\mathbf{i}\mathbf{s}$ , a register where the output of that expression can be found  $\mathbf{r}$ , an updated list of registers  $\mathbf{K}'$ , an updated list of bindings V.

$$\begin{split} \mathbf{K} &::= \varnothing \mid \mathbf{K}, \mathbf{r} \\ V &::= \varnothing \mid V, \mathbf{x} : \mathbf{r} \\ \|\mathbf{K}\| &= n \qquad \text{where } \mathbf{K} = \mathbf{r_1}, \cdots, \mathbf{r_n} \\ \mathbf{is} &= \varnothing \mid \mathbf{is}, \mathbf{i} \\ \|\mathbf{is}\| &= n \qquad \text{where } \mathbf{is} = \mathbf{i_1}, \cdots, \mathbf{i_n} \end{split}$$

Compiler for whole programs (assuming no instruction decodes to  $\mathbf{0}$ ):

$$[f(x) \mapsto e] = is; set r_0 r_i; 0$$
 where  $[e, \emptyset, x : r_0, 0] = is, r_i, K, V$ 

Compiler for partial programs:

$$[f(x) \mapsto e] = is; set r_0 r_i$$
 where  $[e, \emptyset, x : r_0, 100] = is, r_i, K, V$ 

Assume the context fills the instruction before address 100 and after address  $100 + \|\mathbf{is}\|$ . We don't really model returns for simplicity

```
[\mathbf{z}, \mathbf{K}, V, \mathbf{a}] = \emptyset, \mathbf{r_i}, \mathbf{K}, V
                                                                                                                where \mathbf{z}: \mathbf{r_i} \in V
   [[true, \mathbf{K}, V, \mathbf{a}]] = \mathbf{const} \ \mathbf{0} \ \mathbf{r_i}, \mathbf{r_i}, \mathbf{K}, \mathbf{r_i}, V
                                                                                                                where \mathbf{i} = \|\mathbf{K}\| + 1
   [false, K, V, a] = const 1 r_i, r_i, K, r_i, V
                                                                                                                where \mathbf{i} = \|\mathbf{K}\| + 1
         [n, K, V, a] = const n r_i, r_i, K, r_i, V
                                                                                                                where \mathbf{i} = \|\mathbf{K}\| + 1
[e + e', K, V, a] = is; is'; add r_i r_i, r_i, K'', V''
                                                                                                                where [\mathbf{e}, \mathbf{K}, V, \mathbf{a}] = \mathbf{i}\mathbf{s}, \mathbf{r}_{\mathbf{i}}, \mathbf{K}', V'
                                                                                                                               [\mathbf{e}', \mathbf{K}', V', \mathbf{a} + \|\mathbf{is}\|] = \mathbf{is}', \mathbf{r_i}, \mathbf{K}'', V''
                                                                                                                               \mathbf{i} = \|\mathbf{K}\| + 1
                                                                                                                               \mathbf{j} = \|\mathbf{K}'\| + 1
             [e == e', K, V, a] = is; is'; cmp r_i r_i
                                                                                                                                           , \mathbf{r_i}, \mathbf{K''}, V''
                                                                const k r_{i+1}; jz r_{i+1}; const 0 r_i
                                             where [\mathbf{e}, \mathbf{K}, V, \mathbf{a}] = \mathbf{i}\mathbf{s}, \mathbf{r}_{\mathbf{i}}, \mathbf{K}', V'
                                                              [\mathbf{e}', \mathbf{K}', V', \mathbf{a} + \|\mathbf{is}\|] = \mathbf{is}', \mathbf{r_i}, \mathbf{K}'', V''
                                                             \mathbf{i} = \|\mathbf{K}\| + 1
                                                             \mathbf{j} = \|\mathbf{K}'\| + 1
                                                              k = a + ||is|| + ||is''|| + 5
                                                                         |is; const \ 0 \ r_{i+1}; cmp \ r_i \ r_{i+1}; const \ k_1 \ r_{i+1}; jz \ r_{i+1}
                                                                          is''; set r_i r_{i''}; const k_2 r_{i+1}; jmp r_{i+1}
                                                                                                                                                                                                      , \mathbf{r_i}, \mathbf{K''''}, V''''
[if e then e_1 else e_2, \mathbf{K}, V, \mathbf{a}] =
                                                                           is'; set r_i r_{i'};
                                                       where [\mathbf{e}, \mathbf{K}, V, \mathbf{a}] = \mathbf{i}\mathbf{s}, \mathbf{r}_{\mathbf{i}}, \mathbf{K}', V'
                                                                        [\mathbf{e_1}, \mathbf{K}', V', \mathbf{a_1}] = \mathbf{is}', \mathbf{r_{i'}}, \mathbf{K}'', V''
                                                                        [\mathbf{e}_2, \mathbf{K}', V', \mathbf{a}_2] = \mathbf{i}\mathbf{s}'', \mathbf{r}_{\mathbf{i}''}, \mathbf{K}''', V'''
                                                                        \mathbf{k_1} = \mathbf{a} + \|\mathbf{is}\| + 4 + \|\mathbf{is''}\| + 1
                                                                        \mathbf{k_2} = \mathbf{a} + \|\mathbf{is}\| + 4 + \|\mathbf{is''}\| + 3 + \|\mathbf{is'}\| + 1
                                                                        \mathbf{a_1} = \mathbf{a} + \|\mathbf{is}\| + 4 + \|\mathbf{is''}\| + 3
                                                                        \mathbf{a_2} = \mathbf{a} + \|\mathbf{is}\| + 4
                                                                        \mathbf{K}'''' = \max(\mathbf{K}'', \mathbf{K}''')
                                                                         V'''' = \max(V'', V''')
                [[\text{let } x = e \text{ in } e', \mathbf{K}, V, \mathbf{a}]] = \mathbf{is}; \mathbf{is}', \mathbf{r}_{\mathbf{i}'}, \mathbf{K}'', V''
                                                            where [\mathbf{e}, \mathbf{K}, V, \mathbf{a}] = \mathbf{i}\mathbf{s}, \mathbf{r}_{\mathbf{i}}, \mathbf{K}', V'
                                                                             [\mathbf{e}', \mathbf{K}', V', \mathbf{x} : \mathbf{r_i}, \mathbf{a_1}] = \mathbf{is}', \mathbf{r_{i'}}, \mathbf{K}'', V''
                                                                             \mathbf{a}_1 = \mathbf{a} + \|\mathbf{i}\mathbf{s}\|
```

#### 2.2 Compiler Correctness

Let  $\Gamma \vdash \gamma$  say that  $\gamma$  binds the same variables of  $\Gamma$  to values of the right type.

#### Lemma 2.1 (Forward simulation).

```
\begin{split} &\text{if } \Gamma \vdash \mathbf{e} : \tau \text{ and } \Gamma \vdash \gamma \text{ and } \mathbf{e} \gamma \hookrightarrow^* \mathbf{v} \text{ and } \mathsf{dom}\left(\mathbf{K}\right) = \mathsf{img}\left(V\right) \\ &\text{and } \llbracket \mathbf{e}, \mathbf{K}, V, \mathbf{pc} \rrbracket = \mathbf{is}, \mathbf{r_i}, \_, \_ \text{ and } \mathbf{e} \gamma \sim_V \langle \mathbf{m}, \mathbf{R}, \mathbf{f}, \mathbf{pc} \rangle \\ &\text{then } \langle \mathbf{m}, \mathbf{R}, \mathbf{f}, \mathbf{pc} \rangle \rightarrow^{\lVert \mathbf{is} \rVert} \langle \mathbf{m}', \mathbf{R}', \mathbf{f}', \mathbf{pc}' \rangle \text{ and } \mathbf{v} \sim_{\mathbf{r_i}} \langle \mathbf{m}', \mathbf{R}', \mathbf{f}', \mathbf{pc}' \rangle \end{split}
```

*Proof.* By induction on the typing derivation of e.

#### 2.2.1 Relations for this Proof

We need a set of cross-language relations.

$$(State \ \mathsf{Relation} \ (\mathsf{closed}))$$

$$[\![\mathbf{e},\varnothing,\mathbf{x}:\mathbf{r_0},\mathbf{pc}]\!] = \mathbf{i_0},\cdots,\mathbf{i_j},\_,\_,\_$$

$$\forall k \in 0..j \ \mathbf{m}(\mathbf{pc}+\mathbf{k}) \mapsto \mathbf{i_k}$$

$$\mathbf{e} \sim^c \langle \mathbf{m},\mathbf{R},\mathbf{f},\mathbf{pc} \rangle$$

A source closed expression is related to a target state if:

• in the memory, starting at address **pc**, there is the list of instructions that result of the compilation of **e**;

$$\begin{array}{c} \text{(Value Relation)} \\ \text{v} \sim^0 \mathbf{R}(\mathbf{r}) \\ \hline \text{v} \sim_{\mathbf{r}} \langle \mathbf{m}', \mathbf{R}', \mathbf{f}', \mathbf{pc}' \rangle \\ \hline \end{array} \qquad \begin{array}{c} \text{(Base Value Relation - true)} \\ \hline \text{true} \sim^0 \mathbf{0} \\ \hline \text{(Base Value Relation - n)} \\ \hline \\ \hline \text{n} \sim^0 \mathbf{n} \\ \end{array}$$

A source value is related to a target state at a certain register if:

 in the target state, at the register, there is a number that is in the base relation for values.

```
(\text{State Relation (ope)}) \\ e \sim^{c} \langle \mathbf{m}, \mathbf{R}, \mathbf{f}, \mathbf{pc} \rangle \\ V \vdash \gamma \sim \mathbf{R} \\ \hline e \gamma \sim_{V} \langle \mathbf{m}, \mathbf{R}, \mathbf{f}, \mathbf{pc} \rangle \\ (\text{Substitution Relation - subst}) \\ V(\mathbf{x}) = \mathbf{r} \\ v \sim^{0} \mathbf{R}(\mathbf{r}) \\ \hline V \vdash \gamma; [\mathbf{v} \mid \mathbf{x}] \sim \mathbf{R}
```

An open source expression is related to a target state if:

- the expression is related according to the closed expression relation;
- the list of substitutions  $\gamma$  is accounted for in the registers **R**.

# 3 Examples

Compiling this program:

```
[\![f(x)\mapsto let\ z=true\ in\ let\ y=2\ in\ if\ z\ then\ 0\ else\ y+3]\!]
```

results in this assembly:

```
100 \text{ const } 0 r_1
                                                                       z = true
101 \text{ const } 2 r_2
                                                                          y = 2
102 \text{ const } 0 r_3
                                                                 if loads true
                                                       if checks z == true
103 \text{ cmp } r_1 r_3
104 const 111 r<sub>3</sub>
                                                           distance to then
105 jz r_3
106 const 3 r<sub>4</sub>
                                                                         else: 3
107 add r_2 r_4
                                                                           y + 3
108 \; \mathrm{set} \; \mathrm{r}_3 \; \mathrm{r}_2
                                                  set to if-result register
109 const 113 r<sub>4</sub>
                                                                    end offset
110 \text{ jmp } r_4
                                                                      goto end
111 \text{ const } 0 \text{ } r_4
                                                                       then: 0
112 \text{ set } r_3 r_4
                                                  set to if-result register
113 \ set \ r_0 \ r_3
                                        set to program result register
```

Compiling this program:

$$\llbracket f(x) \mapsto x \rrbracket$$

results in this assembly:

```
100 \operatorname{set} \mathbf{r}_0 \mathbf{r}_0 x
```

Compiling this program:

```
[f(x) \mapsto if \times then \ 0 \ else \ 1]
```

results in this assembly:

```
100 \text{ const } 0 r_1
                                                                if loads true
                                                     if checks x == true
101 \text{ cmp } r_0 r_1
102 const 108 r<sub>1</sub>
                                                          distance to then
103 jz r_1
                                                                               if
104 \text{ const } 1 \text{ r}_2
                                                                        else: 1
105 \text{ set } r_0 r_2
                                                  set to if-result register
106 \text{ const } 110 \text{ r}_1
                                                                   end offset
107 \text{ jmp } r_1
                                                                     goto end
```

# 4 Supporting Fully-Abstract Compilation

In order to support fully-abstract compilation we extend the language with a primitive that zeroes-out all registers except one.

```
Instructions i ::= \cdots \mid zero r
```

```
\frac{\mathbf{m}(\mathbf{pc}) = \|\mathbf{zero}\ \mathbf{r}\|}{\mathbf{R}(\mathbf{r}) = \mathbf{n}} \quad \forall i \geq 0.\ \mathbf{R}' = \mathbf{r_i} \mapsto \mathbf{0}\langle \mathbf{m}, \mathbf{R}, \mathbf{f}, \mathbf{pc} \rangle \rightarrow \langle \mathbf{m}, \mathbf{R}'[\mathbf{r} \mapsto \mathbf{n}], \mathbf{f}, \mathbf{pc} + \mathbf{1} \rangle
```

Fully-abstract compiler for partial programs:

```
[\![\mathsf{f}(\mathsf{x}) \mapsto \mathsf{e}]\!] = \mathbf{i}\mathbf{s}; \mathbf{set} \ \mathbf{r_0} \ \mathbf{r_i}; \mathbf{zero} \ \mathbf{r_0} \quad \text{where} \ [\![\mathsf{e},\varnothing,\mathsf{x}:\mathbf{r_0},\mathbf{100}]\!] = \mathbf{i}\mathbf{s},\mathbf{r_i},\mathbf{K},\mathit{V}
```

Note that we avoid many issues by insisting that all source functions are typed at  $Nat \rightarrow Nat$ . Any change in any of those types would require the introduction of a typecheck in order for the compiler to be fully-abstract.