

电动力学条目

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1 一些数学

梯度、散度、旋度：

$$\begin{aligned}d\phi &\triangleq \nabla\phi \cdot d\vec{l} \\ \nabla \cdot \vec{F} &\triangleq \lim_{V \rightarrow 0} \frac{\oint_{\partial V} d\vec{\sigma} \cdot \vec{F}}{V} \\ \hat{n} \cdot (\nabla \times \vec{F}) &\triangleq \lim_{\Sigma \rightarrow 0} \frac{\oint_{\partial \Sigma} d\vec{l} \cdot \vec{F}}{\Sigma}\end{aligned}$$

迷向张量：

$$\begin{aligned}\epsilon_{ijk} &= \begin{vmatrix} \delta_{i1} & \delta_{i2} & \delta_{i3} \\ \delta_{j1} & \delta_{j2} & \delta_{j3} \\ \delta_{k1} & \delta_{k2} & \delta_{k3} \end{vmatrix} \\ \det(A) &= \epsilon_{ijk} A_{1i} A_{2j} A_{3k} \\ \epsilon_{lmn} \det(A) &= \epsilon_{ijk} A_{li} A_{mj} A_{nk} \\ \epsilon_{ijk} \epsilon_{mnk} &= \delta_{im} \delta_{jn} - \delta_{in} \delta_{jm} \\ \vec{a} \cdot (\vec{b} \times \vec{c}) &= \epsilon_{ijk} a_i b_j c_k\end{aligned}$$

张量：

$$\begin{aligned}T'_{i_1 \dots i_n} &= \lambda_{i_1 j_1} \dots \lambda_{i_n j_n} T_{j_1 \dots j_n} \\ I_{ij} &= \delta_{ij} = I'_{ij} \\ T_{ij} &= \frac{T_{ij} + T_{ji}}{2} + \frac{T_{ij} - T_{ji}}{2} \\ T_{ij} = T_{ji}, S_{ij} = -S_{ji} &\implies T_{ij} S_{ij} = 0 \\ \det(\vec{I} + \vec{f} \vec{g}) &= 1 + \vec{f} \cdot \vec{g} \\ \vec{T} : \vec{S} = T_{ij} S_{ji} = \text{tr}(TS) = \vec{S} : \vec{T} \\ \vec{T} : \vec{I} &= \text{tr}(T) \\ \vec{I} \times \vec{f} &= \vec{f} \times \vec{I} \\ T_{ij} = T_{ji} \implies (\nabla \cdot \vec{T}) \times \vec{r} &= \nabla \cdot (\vec{T} \times \vec{r}) \\ S_{ij} = S_{ji} \implies \text{tr}(S) &= 0\end{aligned}$$

泰勒展开：

$$\vec{f}(\vec{r} + \vec{\epsilon}) = e^{\vec{\epsilon} \cdot \nabla} \vec{f}(\vec{r})$$

积分公式：

$$\begin{aligned}\int_V dV \nabla &= \oint_{\partial V} d\vec{\sigma} \\ \int_{\Sigma} (d\vec{\sigma} \times \nabla) &= \oint_{\partial \Sigma} d\vec{l}\end{aligned}$$

正交曲线坐标系:

$$h_a \triangleq \left| \frac{\partial \vec{r}}{\partial u_a} \right|, H = h_1 h_2 h_3$$

$$d\vec{r} = \hat{r} dr + r \hat{\theta} d\theta + r \sin \theta \hat{\phi} d\phi$$

$$(h_r = 1, h_\theta = r, h_\phi = r \sin \theta, H = r^2 \sin \theta)$$

$$= \hat{s} ds + s \hat{\phi} d\phi + \hat{z} dz$$

$$(h_s = 1, h_\phi = s, h_z = 1, H = s)$$

$$\nabla \phi = \sum_a \frac{\hat{u}_a}{h_a} \frac{\partial \phi}{\partial u_a}$$

$$\begin{cases} \nabla u_a = \frac{\hat{u}_a}{h_a} \\ \nabla \times \frac{\hat{u}_a}{h_a} = 0 \\ \nabla \cdot \frac{h_a \hat{u}_a}{H} = 0 \end{cases}$$

$$\nabla^2 \phi = \nabla \cdot \nabla \phi = \sum_a \frac{1}{H} \frac{\partial}{\partial u_a} \left(\frac{H}{h_a^2} \frac{\partial \phi}{\partial u_a} \right)$$

$$\nabla \cdot \vec{f} = \frac{1}{H} \left[\frac{\partial}{\partial u_1} (h_2 h_3 f_1) + \frac{\partial}{\partial u_2} (h_1 h_3 f_2) + \frac{\partial}{\partial u_3} (h_1 h_2 f_3) \right]$$

$$\nabla \times \vec{f} = \frac{1}{H} \begin{vmatrix} h_1 \hat{u}_1 & h_2 \hat{u}_2 & h_3 \hat{u}_3 \\ \frac{\partial}{\partial u_1} & \frac{\partial}{\partial u_2} & \frac{\partial}{\partial u_3} \\ h_1 f_1 & h_2 f_2 & h_3 f_3 \end{vmatrix}$$

一些求导:

$$\nabla \times \frac{\hat{r}}{r^2} = 0, \nabla \cdot \frac{\hat{r}}{r^2} = 4\pi \delta(\vec{r})$$

$$\nabla \mathbb{R} = \hat{\mathbb{R}}, \nabla \frac{1}{\mathbb{R}} = -\frac{\hat{\mathbb{R}}}{\mathbb{R}}, \nabla^2 \frac{\hat{\mathbb{R}}}{\mathbb{R}^2} = 4\pi \delta(\mathbb{R}), \nabla \cdot \frac{\hat{\mathbb{R}}}{\mathbb{R}} = \frac{1}{\mathbb{R}^2}$$

$$\text{Helmholtz: } \vec{F} = -\nabla \phi + \nabla \times \vec{A}$$

$$= -\nabla \frac{1}{4\pi} \int dV' \frac{\nabla' \cdot \vec{F}(\vec{r}')}{\mathbb{R}} + \nabla \times \frac{1}{4\pi} \int dV' \frac{\nabla' \times \vec{F}(\vec{r}')}{\mathbb{R}}$$

一些积分:

$$\frac{1}{4\pi} \int_{r' \leq a} dV' \frac{\hat{\mathbb{R}}}{\mathbb{R}^2} = \frac{1}{4\pi} \int_{r' \leq a} dV' \frac{-\hat{\mathbb{R}}}{\mathbb{R}^2} = \begin{cases} r < a : \frac{\vec{r}}{3} \\ r > a : \frac{a^3 \vec{r}}{3r^3} \end{cases}$$

$$\int \hat{n} \hat{n} d\Omega = \frac{4\pi}{3} \vec{I}$$

$$\left(\int \hat{n} \hat{n} d\Omega : \hat{x}_i \hat{x}_j = \frac{4\pi}{3} \delta_{ij} \right)$$

$$\int d\Omega \alpha_i \alpha_j = \frac{4\pi}{3} \delta_{ij}$$

$$(\alpha_1 = \sin \theta \cos \phi, \quad \alpha_2 = \sin \theta \sin \phi, \quad \alpha_3 = \cos \theta)$$

$$\int d\Omega \alpha_i \alpha_k \alpha_m \alpha_l = \frac{4\pi}{15} (\delta_{ik} \delta_{ml} + \delta_{im} \delta_{kl} + \delta_{il} \delta_{km})$$

上式按照四个指标相同、三个指标相同、两个指标相同 (另两个不同)、两两相同来验证。

2 电磁场

麦克斯韦方程：

真空中：

$$\begin{cases} \nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0} & (EG) \\ \nabla \cdot \vec{B} = 0 & (BG) \\ \nabla \times \vec{E} = -\partial_t \vec{B} & (F) \\ \nabla \times \vec{B} = \mu_0 \vec{j} + \mu_0 \epsilon_0 \partial_t \vec{E} & (A/M) \end{cases}$$

$$\begin{cases} \hat{n} \cdot (\vec{E}_2 - \vec{E}_1) = \frac{\sigma}{\epsilon_0} \\ \hat{n} \cdot (\vec{B}_2 - \vec{B}_1) = 0 \\ \hat{n} \times (\vec{E}_2 - \vec{E}_1) = 0 \\ \hat{n} \times (\vec{B}_2 - \vec{B}_1) = \mu_0 \vec{K} \end{cases}$$

介质中：

$$\vec{D} \triangleq \epsilon_0 \vec{E} + \vec{P}$$

$$\vec{H} \triangleq \frac{\vec{B}}{\mu_0} - \vec{M}$$

$$\begin{cases} \nabla \cdot \vec{D} = \rho_0 & (EG) \\ \nabla \cdot \vec{B} = 0 & (BG) \\ \nabla \times \vec{E} = -\partial_t \vec{B} & (F) \\ \nabla \times \vec{H} = \vec{j}_0 + \partial_t \vec{D} & (A/M) \end{cases}$$

$$\begin{cases} \hat{n} \cdot (\vec{D}_2 - \vec{D}_1) = \sigma_0 \\ \hat{n} \cdot (\vec{B}_2 - \vec{B}_1) = 0 \\ \hat{n} \times (\vec{E}_2 - \vec{E}_1) = 0 \\ \hat{n} \times (\vec{H}_2 - \vec{H}_1) = \vec{K}_0 \end{cases}$$

电磁势：

$$\vec{E} = -\nabla \phi - \partial_t \vec{A}, \vec{B} = \nabla \times \vec{A}$$

规范变换:

$$\begin{cases} \phi' = \phi - \partial_t \psi \\ \vec{A}' = \vec{A} + \nabla \psi \end{cases}$$

$$\oint_C \vec{A}' \cdot d\vec{l} = \oint_C \vec{A} \cdot d\vec{l}$$

库伦规范: $\nabla \cdot \vec{A} = 0$

洛伦兹规范: $\nabla \cdot \vec{A} + \frac{1}{c^2} \partial_t \phi = 0$

势方程:

$$L \triangleq \nabla \cdot \vec{A} + \frac{1}{c^2} \partial_t \phi, \quad \square \triangleq \nabla^2 - \frac{1}{c^2} \partial_t^2 \text{ (d'Alembert 算子)}$$

$$\begin{cases} \square \phi + \partial_t L = -\frac{\rho}{\epsilon_0} \\ \square \vec{A} - \nabla L = -\mu_0 \vec{j} \end{cases}$$

真空中的守恒律:

能量守恒:

$$w \triangleq \frac{1}{2} \epsilon_0 E^2 + \frac{1}{2\mu_0} B^2 = \frac{1}{2} \epsilon_0 (E^2 + c^2 B^2)$$

$$\vec{S} \triangleq \frac{1}{\mu_0} \vec{E} \times \vec{B} = c^2 \epsilon_0 \vec{E} \times \vec{B}$$

$$\vec{E} \cdot \vec{j} = -\partial_t w - \nabla \cdot \vec{S}$$

动量守恒:

$$\vec{g} \triangleq \epsilon_0 \vec{E} \times \vec{B} = \frac{\vec{S}}{c^2}$$

$$\vec{T} \triangleq \frac{1}{2} \epsilon_0 (E^2 + c^2 B^2) \vec{I} - \epsilon_0 (\vec{E} \vec{E} + c^2 \vec{B} \vec{B})$$

$$-\partial_t \vec{g} = \nabla \cdot \vec{T} + \vec{f}$$

稳恒时, 受应力为 $\vec{f}_n = -\hat{n} \cdot \vec{T}$ 。

角动量守恒:

$$\vec{l}_{em} \triangleq \vec{r} \times \vec{g}$$

$$\vec{R} \triangleq -\vec{T} \times \vec{r}$$

$$-\partial_t \vec{l}_{em} = \nabla \cdot \vec{R} + \vec{r} \times \vec{f}$$

物质中的守恒律:

能量守恒 (线性无色散介质):

$$\begin{aligned}\vec{D}(\vec{r}, t) &= \vec{\epsilon}(\vec{r}) \cdot \vec{E}(\vec{r}, t) \\ w &\triangleq \frac{1}{2} \vec{D} \cdot \vec{E} + \frac{1}{2} \vec{B} \cdot \vec{H} \\ \vec{S} &\triangleq \vec{E} \times \vec{H} \\ \vec{E} \cdot \vec{j}_0 &= -\partial_t w - \nabla \cdot \vec{S}\end{aligned}$$

动量守恒 (线性均匀介质):

$$\begin{aligned}\vec{D}(\vec{r}, t) &= \vec{\epsilon}(t) \cdot \vec{E}(\vec{r}, t) \\ \vec{g} &\triangleq \vec{D} \times \vec{B} \\ \vec{T} &\triangleq \frac{1}{2} (\vec{D} \cdot \vec{E} + \vec{B} \cdot \vec{H}) \vec{I} - (\vec{D} \vec{E} + \vec{B} \vec{H}) \\ -\partial_t \vec{g} &= \nabla \cdot \vec{T} + \vec{f}_0\end{aligned}$$

动量守恒 (线性各向同性介质):

$$\begin{aligned}\vec{D}(\vec{r}, t) &= \epsilon(\vec{r}, t) \cdot \vec{E}(\vec{r}, t) \\ \vec{g} &\triangleq \vec{D} \times \vec{B} \\ \vec{T} &\triangleq \frac{1}{2} (\vec{D} \cdot \vec{E} + \vec{B} \cdot \vec{H}) \vec{I} - (\vec{D} \vec{E} + \vec{B} \vec{H}) \\ -\partial_t \vec{g} - \nabla \cdot \vec{T} &= \vec{f}_0 - \frac{1}{2} E^2 \nabla \epsilon - \frac{1}{2} H^2 \nabla \mu \triangleq \vec{f}_M\end{aligned}$$

角动量守恒 (线性均匀各向同性):

$$\begin{aligned}\vec{D}(\vec{r}, t) &= \epsilon(t) \cdot \vec{E}(\vec{r}, t) \\ \vec{l}_{em} &\triangleq \vec{r} \times \vec{g} \\ \vec{R} &\triangleq -\vec{T} \times \vec{r} \\ -\partial_t \vec{l}_{em} &= \nabla \cdot \vec{R} + \vec{r} \times \vec{f}_0\end{aligned}$$

3 静电场

真空中的基本方程:

$$\begin{cases} \nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0} \\ \nabla \times \vec{E} = 0 \end{cases}$$

$$\begin{cases} \hat{n} \cdot (\vec{E}_2 - \vec{E}_1) = \frac{\sigma}{\epsilon_0} \\ \hat{n} \times (\vec{E}_2 - \vec{E}_1) = 0 \end{cases}$$

$$\begin{aligned}\text{Helmholtz: } \vec{E}(\vec{r}) &= -\nabla \frac{1}{4\pi} \int dV' \frac{\nabla' \cdot \vec{E}}{\mathbb{R}} (= -\nabla \phi) \\ &= \frac{1}{4\pi\epsilon_0} \int dV' \frac{\rho(\vec{r}') \vec{R}}{\mathbb{R}^3} \\ \phi &= \frac{1}{4\pi\epsilon_0} \int dV' \frac{\rho(\vec{r}')}{\mathbb{R}}\end{aligned}$$

势方程:

$$\nabla^2 \phi = -\frac{\rho}{\epsilon_0}, \quad \begin{cases} \frac{\partial \phi_1}{\partial n} - \frac{\partial \phi_2}{\partial n} = \frac{\sigma}{\epsilon_0} \\ \phi_1 = \phi_2 \end{cases}$$

格林互易定理:

$$\int dV' \rho'(\vec{r}') \phi(\vec{r}') = \int dV \rho(\vec{r}) \phi'(\vec{r})$$

物质中的基本方程:

$$\begin{cases} \nabla \cdot \vec{D} = \rho_0 \\ \nabla \times \vec{E} = 0 \end{cases}$$

$$\begin{cases} \hat{n} \cdot (\vec{D}_2 - \vec{D}_1) = \sigma_0 \\ \hat{n} \times (\vec{E}_2 - \vec{E}_1) = 0 \end{cases}$$

势方程 (简单介质):

$$\epsilon = \epsilon(\vec{r})$$

$$\nabla(\epsilon \nabla \phi) = -\rho_0, \quad \begin{cases} \epsilon_1 \frac{\partial \phi_1}{\partial n} - \epsilon_2 \frac{\partial \phi_2}{\partial n} = \sigma_0 \\ \phi_1 = \phi_2 \end{cases}$$

静电能:

$$\delta A = \int dV \phi \delta \rho_0 = \dots = \int dV \vec{E} \cdot \delta \vec{D}$$

简单介质时, $\epsilon = \epsilon(\vec{r})$, 静电能为

$$\delta A = \int dV \delta \left(\frac{1}{2} \vec{D} \cdot \vec{E} \right)$$

$$W = \frac{1}{2} \int dV \vec{D} \cdot \vec{E} = \int dV \frac{1}{2} \epsilon_0 E^2 + \int dV \frac{1}{2} \vec{P} \cdot \vec{E} = \frac{1}{2} \int dV \vec{D} \cdot \vec{E}$$

$$= -\frac{1}{2} \int dV \vec{D} \cdot \nabla \phi = \frac{1}{2} \int dV \rho_0 \phi = \frac{1}{2} \int dV \vec{D} \cdot \vec{E} = \frac{1}{2} \sum_i Q_i \phi_i$$

移动简单介质 (从无穷远到给定位置) 做功:

$$\begin{aligned} A &= \frac{1}{2} \int dV (\vec{D} \cdot \vec{E} - \vec{D}_0 \cdot \vec{E}_0) \\ &= \frac{1}{2} \int dV [\vec{E} \cdot (\vec{D} - \vec{D}_0) + \vec{E}_0 \cdot (\vec{D} - \vec{D}_0)] + \frac{1}{2} \int dV (\vec{E} \cdot \vec{D}_0 - \vec{E}_0 \cdot \vec{D}) \\ &= \frac{1}{2} \int dV [\nabla \cdot (\phi(\vec{D} - \vec{D}_0)) - \phi \nabla \cdot (\vec{D} - \vec{D}_0)] \\ &\quad + \frac{1}{2} \int dV [\nabla \cdot (\phi_0(\vec{D} - \vec{D}_0)) - \phi_0 \nabla \cdot (\vec{D} - \vec{D}_0)] \\ &\quad + \frac{1}{2} \int dV (\epsilon_0 \vec{E} \cdot \vec{E}_0 - \vec{E}_0 \cdot (\epsilon_0 \vec{E} + \vec{P})) \\ &= -\frac{1}{2} \int dV \vec{P} \cdot \vec{E}_0 \end{aligned}$$

故介质会被吸入。

唯一性定理：

$$\phi_1 - \phi_2 = \Phi$$

$$\int dV \epsilon (\nabla \Phi)^2 = \int dV \epsilon [\epsilon (\nabla \Phi)^2 + \Phi \nabla \cdot (\epsilon \nabla \Phi)] = \oint_{\partial V} d\sigma \Phi \epsilon \frac{\partial \Phi}{\partial n}$$

Dirichlet 边界条件：

$$\phi(\vec{r}_s) = f(\vec{r}_s) \Rightarrow \text{unique } \vec{E}, \phi$$

Neumann 边界条件：

$$\frac{\partial \phi}{\partial n}|_{\partial V} = g(\vec{r}_s) \Rightarrow \text{unique } \vec{E}$$

导体电量：

$$Q_i = C_i \Rightarrow \text{unique } \vec{E}$$

拉普拉斯方程的求解 (泊松方程转化为拉普拉斯方程)：

分离变量法：

直角坐标系：

$$[\dots]$$

柱坐标一般解 ($\phi \in [0, 2\pi]$):

$$\phi = A_0 + B_0 \ln s + \sum_{m=1}^{\infty} \left(A_m s^m + \frac{B_m}{s^m} \right) (C_m \cos m\phi + D_m \sin m\phi)$$

球坐标一般解 ($\phi \in [0, 2\pi]$):

$$\begin{aligned} \phi &= \sum_{l=0}^{\infty} \sum_{m=0}^l \left(A_{lm} r^l + \frac{B_{lm}}{r^{l+1}} \right) P_l^m(\cos \theta) (C_{lm} \cos m\phi + D_{lm} \sin m\phi) \\ &= \sum_{l=0}^{\infty} \sum_{m=-l}^l \left(A_{lm} r^l + \frac{B_{lm}}{r^{l+1}} \right) Y_{lm} \end{aligned}$$

若有轴对称性，上式简化为

$$\phi = \sum_{l=0}^{\infty} \left(A_l r^l + \frac{B_l}{r^{l+1}} \right) P_l(\cos \theta)$$

本征函数展开：

$$[\dots]$$

格林函数法:

$$\begin{aligned}\phi(\vec{r}) = & \int_V dV' \rho(\vec{r}') G(\vec{r}'; \vec{r}) - \epsilon_0 \oint_{\partial V} d\sigma' \phi(\vec{r}') \frac{\partial G(\vec{r}'; \vec{r})}{\partial n'} \\ & + \epsilon_0 \oint_{\partial V} d\sigma' \frac{\phi(\vec{r}')}{\partial n'} G(\vec{r}'; \vec{r})\end{aligned}$$

$G(\Delta G = -\delta)$ 满足齐次边界条件时, 有倒易性。 $G(\vec{r}; \vec{r}') = G(\vec{r}'; \vec{r})$

Dirichlet 边界条件:

$$\begin{aligned}\begin{cases} \nabla^2 G_D(\vec{r}; \vec{r}') = -\frac{\delta(\vec{r} - \vec{r}')}{\epsilon_0} \\ G_D(\vec{r}; \vec{r}') = 0 \end{cases} \\ G_D(\vec{r}; \vec{r}') = G_D(\vec{r}'; \vec{r}) \\ \phi(\vec{r}) = \int_V dV' \rho(\vec{r}') G_D(\vec{r}; \vec{r}') - \epsilon_0 \oint_{\partial V} d\sigma' \phi(\vec{r}') \frac{\partial G_D(\vec{r}; \vec{r}')}{\partial n'}\end{aligned}$$

Neumann 边界条件:

$$\begin{aligned}\begin{cases} \nabla^2 G_N(\vec{r}; \vec{r}') = -\frac{\delta(\vec{r} - \vec{r}')}{\epsilon_0} \\ G_N(\vec{r}; \vec{r}') = -\frac{1}{\epsilon_0 S} \end{cases} \\ \phi(\vec{r}) = \int_V dV' \rho(\vec{r}') G_N(\vec{r}; \vec{r}') + \epsilon_0 \oint_{\partial V} d\sigma' \frac{\partial \phi(\vec{r}')}{\partial n'} G_N(\vec{r}; \vec{r}') + \langle \phi \rangle_S\end{aligned}$$

也有其他修正方法, 但一般所得 G 没有倒易性。

G 的求法: 一般用电像法、保形变换 (某些二维)、类似电像猜解。由本征函数与 δ 函数的关系, G 也可以由本征函数表示出来。

多极展开:

$$\begin{aligned}\frac{1}{\mathbb{R}} &= \frac{1}{|\vec{r} - \vec{r}'|} = e^{-\vec{r}' \cdot \nabla} \frac{1}{r} \\ &= [1 - \vec{r}' \cdot \nabla + \frac{1}{2!} \vec{r}' \vec{r}' : \nabla \nabla - \dots] \frac{1}{r} \\ &= [1 - \vec{r}' \cdot \nabla + \frac{1}{6} (3 \vec{r}' \vec{r}' - (r')^2 \vec{I}) : \nabla \nabla - \dots] \frac{1}{r} \\ \nabla \frac{1}{r} &= -\frac{\vec{r}}{r^3}, \quad \nabla \nabla \frac{1}{r} = \frac{3 \hat{r} \hat{r} - \vec{I}}{r^3}\end{aligned}$$

多极矩:

$$\begin{aligned}Q &\triangleq \int dq \\ \vec{p} &\triangleq \int \vec{r}' dq \\ \vec{D}' &\triangleq \int \vec{r}' \vec{r}' dq \\ \vec{D} &\triangleq \int (3 \hat{r} \hat{r} - \vec{I}) dq, \quad (D_{ij} = D_{ji}, tr(D) = 0 = \vec{D} : \vec{I})\end{aligned}$$

偶极矩和场的体积分 (积分域为包含全部电荷的球):

$$\begin{aligned}
 \int dV \vec{E}(\vec{r}) &= \frac{1}{4\pi\epsilon_0} \int dV \int dV' \frac{\rho(\vec{r}') \hat{R}}{R^2} \\
 &= -\frac{1}{\epsilon_0} \int dV' \rho(\vec{r}') \frac{1}{4\pi} \int dV \frac{-\hat{R}}{R^2} \\
 &= -\frac{1}{\epsilon_0} \int dV' \rho(\vec{r}') \frac{\vec{r}'}{3} \\
 &= -\frac{\vec{p}}{3\epsilon_0}
 \end{aligned}$$

展开:

$$\begin{aligned}
 \phi(\vec{r}) &= \frac{1}{4\pi\epsilon_0} \int \frac{dq}{R} \\
 &= \frac{1}{4\pi\epsilon_0} \left[\frac{Q}{r} - \vec{p} \cdot \nabla \frac{1}{r} + \frac{1}{6} \vec{D} : \nabla \nabla \frac{1}{r} - \dots \right] \\
 &= \frac{Q}{4\pi\epsilon_0 r} + \frac{\vec{p} \cdot \hat{r}}{4\pi\epsilon_0 r^2} + \frac{\hat{r} \cdot \vec{D} \cdot \hat{r}}{8\pi\epsilon_0 r^3} + \dots
 \end{aligned}$$

外场中的小带电体:

电势能:

$$\begin{aligned}
 U &= \int \phi_e(\vec{r} + \vec{r}') dq = \int e^{\vec{r}' \cdot \nabla} \phi_e(\vec{r}) \\
 &= \int dq \left[1 + \vec{r}' \cdot \nabla + \frac{1}{6} (3\vec{r}' \cdot \vec{r}' - (r')^2 \vec{I} : \nabla \nabla) + \dots \right] \phi_e(\vec{r}) \\
 &= Q\phi_e(\vec{r}) - \vec{p} \cdot \vec{E}_e(\vec{r}) - \frac{1}{6} \vec{D} : \nabla \vec{E}_e(\vec{r}) + \dots \\
 &= U^{(0)} + U^{(1)} + U^{(2)} + \dots
 \end{aligned}$$

受力:

$$\begin{aligned}
 \vec{F} &= \int \vec{E}_e(\vec{r} + \vec{r}') dq \\
 &= \int dq \left[1 + \vec{r}' \cdot \nabla + \frac{1}{6} (3\vec{r}' \cdot \vec{r}' - (r')^2 \vec{I} : \nabla \nabla) + \dots \right] \vec{E}_e(\vec{r}) \\
 &= Q\vec{E}_e(\vec{r}) + \vec{p} \cdot \nabla \vec{E}_e(\vec{r}) + \frac{1}{6} (\vec{D} : \nabla \nabla) \vec{E}_e(\vec{r}) + \dots
 \end{aligned}$$

其中,

$$\begin{aligned}
 -\nabla U^{(0)} &= Q\vec{E}_e(\vec{r}) \\
 -\nabla U^{(1)} &= \vec{p} \cdot \nabla \vec{E}_e(\vec{r}) \\
 -\nabla U^{(2)} &= \frac{1}{6} \nabla (\vec{D} : \nabla \vec{E}_e(\vec{r})) \\
 &= \frac{1}{6} \nabla \nabla \vec{E}_e(\vec{r}) : \vec{D} \\
 &= \frac{1}{6} \vec{D} : \nabla \nabla \vec{E}_e(\vec{r})
 \end{aligned}$$

能换序因为 ∇E_e 为对称张量 (旋度为 0):

$$\begin{aligned}\nabla(\vec{D} : \nabla \vec{E}_e(\vec{r})) &= (\nabla)_a (\nabla)_b (E_e)_c (D)^{bc} \\ &= (\nabla)_b (D)^{bc} (\nabla)_a (E_e)_c = (\nabla)_b (D)^{bc} (\nabla)_c (E_e)_a \\ &= (D)^{bc} (\nabla)_b (\nabla)_c (E_e)_a = \vec{D} : \nabla \nabla \vec{E}_e(\vec{r})\end{aligned}$$

受力矩:

$$\begin{aligned}\vec{\tau} &= \int [\vec{r}' \times \vec{E}_e(\vec{r} + \vec{r}')] dq \\ &= \int [\vec{r}' \times \vec{E}_e(\vec{r})] dq + \int [\vec{r}' \times [(\vec{r}' \cdot \nabla) \vec{E}_e(\vec{r})]] dq + \dots \\ &= \vec{p} \times \vec{E}_e(\vec{r}) + [\int \vec{r}' \vec{r}' dq \cdot \nabla] \times \vec{E}_e(\vec{r}) + \dots \\ &= \vec{p} \times \vec{E}_e(\vec{r}) + \frac{1}{3} \int (3\vec{r}' \vec{r}' - (r')^2 \vec{I}) dq \cdot \nabla \times \vec{E}_e(\vec{r}) + \dots \\ &= \vec{p} \times \vec{E}_e(\vec{r}) + \frac{1}{3} (\vec{D} \cdot \nabla) \times \vec{E}_e(\vec{r}) + \dots\end{aligned}$$

球内球外展开:

$$\begin{aligned}\mathbb{R} = |\vec{r} - \vec{r}'| &= \sqrt{r^2 - 2rr'\hat{r} \cdot \hat{r}' + (r')^2} \\ \hat{r} \cdot \hat{r}' &= \cos \theta \cos \theta' + \sin \theta \sin \theta' \cos(\phi - \phi') \\ \frac{1}{\mathbb{R}} &= \frac{1}{\sqrt{r^2 - 2rr'\hat{r} \cdot \hat{r}' + (r')^2}} \\ &= \frac{1}{r_{>}} \sum_{l=0}^{\infty} \left(\frac{r_{\leq}}{r_{>}}\right)^l P_l(\hat{r} \cdot \hat{r}') \\ &= \frac{1}{r_{>}} \sum_{l=0}^{\infty} \left(\frac{r_{\leq}}{r_{>}}\right)^l \frac{4\pi}{2l+1} \sum_{m=-l}^{m=l} Y_{lm}^*(\Omega') Y_{lm}(\Omega)\end{aligned}$$

球内展开:

$$\phi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \sum_{l=0}^{\infty} \sum_{m=-l}^l A_{lm} r^l Y_{lm}(\Omega), \quad A_{lm} = \frac{4\pi}{2l+1} \int \frac{Y_{lm}^*(\Omega')}{(r')^{l+1}} dq$$

若 $\phi = \phi(r, \theta)$, 上式可以简化:

$$\phi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \sum_{l=0}^{\infty} A_l r^l P_l(\cos \theta), \quad A_l = \int \frac{P_l(\cos \theta')}{(r')^{l+1}} dq$$

球外展开:

$$\phi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \sum_{l=0}^{\infty} \sum_{m=-l}^l \frac{B_{lm}}{r^{l+1}} Y_{lm}(\Omega), \quad B_{lm} = \frac{4\pi}{2l+1} \int Y_{lm}^*(\Omega') (r')^l dq$$

若 $\phi = \phi(r, \theta)$, 上式可以简化:

$$\phi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \sum_{l=0}^{\infty} \frac{B_l}{r^{l+1}} P_l(\cos \theta), \quad B_l = \int P_l(\cos \theta') (r')^l dq$$

4 静磁场

真空中的基本方程：

$$\begin{cases} \nabla \cdot \vec{B}(\vec{r}) = 0 \\ \nabla \times \vec{B}(\vec{r}) = \mu_0 \vec{j}(\vec{r}) \end{cases}$$

$$\begin{cases} \hat{n} \cdot (\vec{B}_2 - \vec{B}_1) = 0 \\ \hat{n} \times (\vec{B}_2 - \vec{B}_1) = \mu_0 \vec{K} \end{cases}$$

$$\text{Helmholtz: } \vec{B}(\vec{r}) = \nabla \times \frac{1}{4\pi} \int dV' \frac{\nabla' \times \vec{B}(\vec{r}')}{\mathbb{R}} (= \nabla \times \vec{A})$$

$$= \frac{\mu_0}{4\pi} \int dV' \frac{\vec{j}(\vec{r}') \times \mathbb{R}}{\mathbb{R}^3}$$

从 \vec{B} 的表达式看出 \vec{B} 是一个轴矢量， $B'_i = \det(\lambda) \lambda_{ij} B_j$ 。(一般矢量应满足 $V'_i = \lambda_{ij} V_j$)

磁矢势：

$$\nabla \times \vec{A}(\vec{r}) = \vec{B}(\vec{r}), \quad \vec{A}' = \vec{A} + \nabla \psi(\vec{r})$$

库伦规范：

$$\nabla \cdot \vec{A} = 0$$

(分别可得切向分量连续和法向分量连续的边界条件。)

一个解：

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int dV' \frac{\vec{j}(\vec{r}')}{\mathbb{R}}, \quad \nabla \cdot \vec{A} = 0$$

按照这个解，同样有互易定理：

$$\int dV' \vec{j}'(\vec{r}') \vec{A}(\vec{r}') = \int dV \vec{j}(\vec{r}) \vec{A}'(\vec{r})$$

势方程 ($\nabla \cdot \vec{A} = 0$):

$$\nabla^2 \vec{A} = -\mu_0 \vec{j}, \quad \begin{cases} \vec{A}_1 = \vec{A}_2 \\ \hat{n} \times (\nabla \times \vec{A}_2 - \nabla \times \vec{A}_1) = \mu_0 \vec{K} \end{cases}$$

解出后需验证是否满足库伦规范。

物质中的基本方程：

$$\begin{cases} \nabla \cdot \vec{B}(\vec{r}) = 0 \\ \nabla \times \vec{H}(\vec{r}) = \vec{j}_0(\vec{r}) \end{cases}$$

$$\begin{cases} \hat{n} \cdot (\vec{B}_2 - \vec{B}_1) = 0 \\ \hat{n} \times (\vec{H}_2 - \vec{H}_1) = \vec{K}_0 \end{cases}$$

势方程 (简单介质; $\nabla \cdot \vec{A} = 0$):

$$\nabla \times \left(\frac{\nabla \times \vec{A}}{\mu(\vec{r})} \right) = \vec{j}_0, \quad \begin{cases} \vec{A}_1 = \vec{A}_2 \\ \hat{n} \times \left(\frac{\nabla \times \vec{A}_2}{\mu_2} - \frac{\nabla \times \vec{A}_1}{\mu_1} \right) = \vec{K}_0 \end{cases}$$

解出后需验证是否满足库伦规范。

磁能:

$$\begin{aligned} \delta A &= \int -dI_0 \cdot \epsilon \cdot \delta t = \int dI_0 \cdot \delta \Phi_B \\ &= \int \vec{j}_0 \cdot d\vec{\sigma}_\perp \int d\vec{\sigma} \cdot \delta \vec{B} = \int \vec{j}_0 \cdot d\vec{\sigma}_\perp \oint d\vec{l} \cdot \delta \vec{A} \\ &= \int dV \vec{j}_0 \cdot \delta \vec{A} \\ &= \dots = \int dV \vec{H} \cdot \delta \vec{B} \end{aligned}$$

简单介质时, $\mu = \mu(\vec{r})$, 磁能为

$$\begin{aligned} \delta A &= \int dV \delta \left(\frac{1}{2} \vec{B} \cdot \vec{H} \right) \\ W &= \frac{1}{2} \int dV \vec{B} \cdot \vec{H} = \int dV \frac{B^2}{2\mu_0} - \int dV \frac{1}{2} \vec{M} \cdot \vec{B} \\ &= \frac{1}{2} \int dV \vec{B} \cdot \vec{H} = \frac{1}{2} \int dV \vec{j}_0 \cdot \vec{A} \end{aligned}$$

移动简单介质 (从无穷远到给定位置) 做功:

$$\vec{A} = \frac{1}{2} \int dV [\vec{B} \cdot \vec{H} - \vec{B}_0 \cdot \vec{H}_0] = \dots = \frac{1}{2} \int dV \vec{M} \cdot \vec{B}_0$$

互能:

$$\begin{aligned} W[\vec{j}_1 + \vec{j}_2] &= \frac{1}{2} \int dV (\vec{j}_1 + \vec{j}_2) \cdot (\vec{A}_1 + \vec{A}_2) \\ &= W[\vec{j}_1] + W[\vec{j}_2] + \frac{1}{2} \int dV \vec{j}_1 \cdot \vec{A}_2 + \frac{1}{2} \int dV \vec{j}_2 \cdot \vec{A}_1 \\ &= W[\vec{j}_1] + W[\vec{j}_2] + \int dV \vec{j}_1 \cdot \vec{A}_2 \\ &\quad \left(\int dV \vec{j}_1 \cdot \vec{A}_2 = \int dV \vec{j}_2 \cdot \vec{A}_1 \right) \end{aligned}$$

(若将 \vec{j}_2 视为外场源 (\vec{A}_2 视为外场), 可以按照下式定义 $\vec{j}(\vec{r})$ 在外场中的磁能: $w_e \triangleq \int dV \vec{j}(\vec{r}) \cdot \vec{A}_e(\vec{r})$, 更进一步可以由此定义力学势能 (不考虑物体维持电流所需要的能量): $U \triangleq -w_e$)

线圈系统的能量:

$$\begin{aligned} W &= \frac{1}{2} \int dV \vec{j} \cdot \vec{A} = \frac{1}{2} \sum_i \int dV_i \vec{j}_i \cdot \vec{A} \\ &= \frac{1}{2} \sum_i I_i \oint_{C_i} d\vec{l}_i \cdot \vec{A} = \frac{1}{2} \sum_i I_i \Phi_i \end{aligned}$$

$$\begin{aligned}\Phi_i &= \oint_{C_i} d\vec{l}_i \cdot \vec{A} = \sum_k I_k \frac{\mu_0}{4\pi} \oint_{C_i} \oint_{C_k} \frac{d\vec{l}_i \cdot \vec{l}_k}{R_{ik}} = \sum_k L_{ik} I_k \\ L_{ik} &= \frac{\mu_0}{4\pi} \oint_{C_i} \oint_{C_k} \frac{d\vec{l}_i \cdot \vec{l}_k}{R_{ik}} = L_{ki} \\ W &= \frac{1}{2} \sum_{i,k} L_{ik} I_i I_k\end{aligned}$$

(两个线圈时, $W = \frac{1}{2} L_{11} I_1^2 + \frac{1}{2} L_{22} I_2^2 + L_{12} I_1 I_2$, 其中的系数即为自感和互感。)

磁多极子:

电流密度的积分:

$$\begin{aligned}\int dV \vec{j} &= \int dV (\nabla \cdot (\vec{j} \vec{r}) + \frac{\partial \rho}{\partial t} \vec{r}) = \dot{\vec{p}} \\ \int dV \vec{j} \vec{r} &= \frac{1}{2} \int dV (\vec{j} \vec{r} + \vec{r} \vec{j}) + \frac{1}{2} \int dV (\vec{j} \vec{r} - \vec{r} \vec{j}) \cdot \vec{I} \\ &= \frac{1}{2} \int dV [\nabla \cdot (\vec{j} \vec{r} \vec{r}) + \frac{\partial \rho}{\partial t} \vec{r} \vec{r}] + \frac{1}{2} \int dV (\vec{j} \vec{r} - \vec{r} \vec{j}) \cdot \vec{I} \\ &= \frac{1}{2} \int dV (\vec{r} \times \vec{j}) \times \vec{I} + \frac{1}{6} \dot{\vec{D}} + \frac{1}{6} \frac{d}{dt} \int dV \rho r^2 \vec{I} \\ &= \vec{m} \times \vec{I} + \frac{1}{6} \dot{\vec{D}} + \frac{1}{6} \frac{d}{dt} \int dV \rho r^2 \vec{I}\end{aligned}$$

磁偶极矩:

$$\vec{m} \triangleq \frac{1}{2} \int dV \vec{r} \times \vec{j}$$

对稳恒电流, $\int dV \vec{j} = 0$, $\int dV \vec{j} \vec{r} = \vec{m} \times \vec{I}$ 。对稳恒电流, \vec{m} 与原点的选择无关。

若为线圈上的稳恒电流,

$$\vec{m} = \frac{1}{2} I \oint \vec{r} \times d\vec{l} = -\frac{1}{2} I \int (d\vec{\sigma} \times \nabla) \times \vec{r} = I \int d\vec{\sigma}$$

偶极矩和场的体积分 (积分域为包含全部电流的球):

$$\begin{aligned}\int dV \vec{B}(\vec{r}) &= \frac{\mu_0}{4\pi} \int dV \int dV' \frac{\vec{j}(\vec{r}') \times \hat{\mathbb{R}}}{\mathbb{R}^2} \\ &= -\mu_0 \int dV' \vec{j}(\vec{r}') \times \frac{1}{4\pi} \int dV \frac{-\hat{\mathbb{R}}}{\mathbb{R}^2} \\ &= -\mu_0 \int dV' \vec{j}(\vec{r}') \times \frac{\vec{r}'}{3} \\ &= \frac{2\mu_0}{3} \frac{1}{2} \int dV \vec{r}' \times \vec{j}(\vec{r}') \\ &= \frac{2\mu_0}{3} \vec{m}\end{aligned}$$

磁矢势的多极展开

$$\begin{aligned}\vec{A}(\vec{r}) &= \frac{\mu_0}{4\pi} \int_{\mathbb{R}} dV' \frac{\vec{j}(\vec{r}')}{r^2} \\ &= \frac{\mu_0}{4\pi} \left[\frac{1}{r} \int dV' \vec{j}(\vec{r}') + \int dV' \vec{j}(\vec{r}') \cdot \frac{\vec{r}}{r^3} + \dots \right]\end{aligned}$$

稳恒电流时，磁矢势为

$$\vec{A} = \frac{\mu_0}{4\pi} \frac{\vec{m} \times \vec{r}}{r^3}$$

外场中的小载流体：

外场中的磁能：

$$\begin{aligned}W_e &= \int dV' \vec{j}(\vec{r}') \cdot \vec{A}_e(\vec{r} + \vec{r}') \\ &= \int dV' \vec{j}(\vec{r}') \cdot \vec{A}_e(\vec{r}) + \left[\int dV' \vec{j}(\vec{r}') \cdot \nabla \right] \cdot \vec{A}_e(\vec{r}) \\ &= [\vec{m} \times \vec{\nabla}] \cdot \vec{A}_e(\vec{r}) \\ &= \vec{m} \cdot \vec{B}_e = -U\end{aligned}$$

受力：

$$\begin{aligned}\vec{F} &= \int dV' \vec{j}(\vec{r}') \times \vec{B}_e(\vec{r} + \vec{r}') \\ &= \dots = (\vec{m} \times \nabla) \times \vec{B}_e(\vec{r}) \\ &= \nabla \vec{B}_e \cdot \vec{m} (= \nabla W_e = -\nabla U)\end{aligned}$$

磁能细究：考虑两个间隔无穷远的线圈，电流为 I_1, I_2 ，维持各自电流不变的情况下移动 I_2 到指定位置，做功详情为：

$$\begin{aligned}A_{2mot} &= MI_1 I_2, A_{2amp} = -MI_1 I_2 \\ A_{1ind} &= MI_1 I_2\end{aligned}$$

故磁力指向磁能增大的方向看似不合理，但这是电源也做功的结果。

受力矩：

$$\begin{aligned}\vec{\tau} &= \int dV' \vec{r}' \times [\vec{j}(\vec{r}') \times \vec{B}_e(\vec{r} + \vec{r}')] \\ &= \dots = \int dV' \vec{j}(\vec{r}') \vec{r}' \times \vec{B}_e(\vec{r}) - \int dV' \vec{r}' \cdot \vec{j}(\vec{r}') \vec{B}_e(\vec{r}) \\ &= \vec{m} \times \vec{B}_e(\vec{r}) + \frac{1}{2} \int dV' [(\nabla \cdot \vec{j}) r^2 - \nabla \cdot (\vec{j} r^2)] \vec{B}_e(\vec{r}) \\ &= \vec{m} \times \vec{B}_e(\vec{r})\end{aligned}$$

磁标势法：

在无传导电流的单连通区域 $\nabla \times \vec{H} = 0 \Rightarrow \vec{H} = -\nabla\phi$ ，一般情况下可模仿静电场求解关于 ψ 的方程。真空中传导电流已知时可以直接积分；磁化强度 \vec{M} 已知时可以用磁荷法类似库仑定律积分，磁荷的定义如下： $-\nabla \cdot \vec{M} = \rho^*$, $-\hat{n} \cdot (\vec{M}_2 - \vec{M}_1) = \sigma^*$ 。

5 电磁波

自由空间中的电磁波：

麦克斯韦方程：

$$\begin{cases} \nabla \cdot \vec{E} = 0 \\ \nabla \cdot \vec{B} = 0 \\ \nabla \times \vec{E} = -\partial_t \vec{B} \quad (*) \\ \nabla \times \vec{B} = \frac{1}{c^2} \partial_t \vec{E} \quad (*) \end{cases}$$

带 * 号的式子可以推出前两个以及相应的两个边界条件 $\begin{cases} \hat{n} \times (\vec{E}_2 - \vec{E}_1) = 0 \\ \hat{n} \times (\vec{B}_2 - \vec{B}_1) = 0 \end{cases}$

$$Maxwell + \{\vec{E}(\vec{r}, 0), \vec{B}(\vec{r}, 0)\} \Rightarrow \{\vec{E}(\vec{r}, t), \vec{B}(\vec{r}, t)\}$$

波动方程：

$$\begin{cases} \nabla^2 \vec{E} - \frac{1}{c^2} \partial_t^2 \vec{E} = 0 = \square \vec{E} \\ \nabla^2 \vec{B} - \frac{1}{c^2} \partial_t^2 \vec{B} = 0 = \square \vec{B} \end{cases}$$

场的求解：

$$\begin{cases} \square \vec{E} = 0 & \vec{E}(\vec{r}, 0) \xRightarrow{\quad} \vec{E}(\vec{r}, t) \\ \nabla \cdot \vec{E} = 0 \\ \partial_t \vec{B} = -\nabla \times \vec{E} & \vec{B}(\vec{r}, 0) \xRightarrow{\quad} \vec{B}(\vec{r}, t) \end{cases}$$

沿某方向传播的电磁波：

沿 z 方向：

$$\begin{aligned} \vec{E} &= \vec{E}(z, t), \vec{B} = \vec{B}(z, t) \\ \Rightarrow \begin{cases} \vec{E} = \vec{E}_-(z - ct) + (\vec{E}_+(z + ct) + \text{static field}) \\ \vec{B} = \frac{1}{c} \hat{z} \times \vec{E}_- + (-\frac{1}{c} \hat{z} \times \vec{E}_+ + \text{static field}) \\ (\vec{E}_- \cdot \hat{z} = 0) \end{cases} \end{aligned}$$

沿 \vec{k} 方向传播:

$$\begin{cases} \vec{E}(\vec{r}, t) = \vec{E}_\perp(\vec{k} \cdot \vec{r} - kct) = \vec{E}_\perp(\phi), & \vec{k} \cdot \vec{E} = 0 \\ \vec{B}(\vec{r}, t) = \frac{1}{c} \hat{k} \times \vec{E} \end{cases}$$

力学性质:

$$w = \frac{1}{2} \epsilon_0 (E^2 + c^2 B^2) = \epsilon_0 E^2 \quad (w_e = w_m)$$

$$\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B} = wc \hat{k}$$

$$\vec{g} = \epsilon_0 \vec{E} \times \vec{B} = \frac{w}{c} \hat{k}$$

$$\vec{T} = w \vec{I} - \vec{D} \vec{E} - \vec{B} \vec{H} = w \hat{k} \hat{k}$$

平面单色波:

偏振:

$$\hat{e}_1 \times \hat{e}_2 = \hat{k}$$

$$\vec{E} = E_1 \hat{e}_1 + E_2 \hat{e}_2 = A_1 \cos(\phi + \delta_1) \hat{e}_1 + A_2 \cos(\phi + \delta_2) \hat{e}_2$$

$$\delta \triangleq \delta_2 - \delta_1$$

转动方向与传播方向构成右手系时, 称为右旋。(与光学中相反)

复表示:

$$\vec{E} = \vec{E}_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)} = (E_{01} \hat{e}_1 + E_{02} \hat{e}_2) e^{i\phi}$$

$$= (A_1 e^{i\phi_1} \hat{e}_1 + A_2 e^{i\phi_2} \hat{e}_2) e^{i\phi}$$

$$\begin{cases} \nabla^2 \vec{E} = \frac{1}{c^2} \partial_t^2 \vec{E} \implies k = \frac{\omega}{c} \\ \nabla \cdot \vec{E} = 0 \implies \vec{k} \cdot \vec{E}_0 = 0 \\ \nabla \times \vec{E} = -\partial_t \vec{B} \implies \vec{B} = \frac{\vec{k} \times \vec{E}}{\omega} \end{cases}$$

复表示的实部为真实的物理场。

$$\begin{cases} Re \vec{F} \Leftrightarrow \vec{F} \\ \text{Linear Operator } L : L[Re \vec{F}] = 0 \iff L[\vec{F}] = 0 \\ \partial_t \longleftrightarrow -i\omega, \nabla \longleftrightarrow i\vec{k} \\ \langle Re f \cdot Re g \rangle = \left\langle \frac{f + f^*}{2} \cdot \frac{g + g^*}{2} \right\rangle = \frac{1}{2} Re(f^* g) \\ \langle Re \vec{f} \cdot Re \vec{g} \rangle = \frac{1}{2} Re \langle \vec{f}^* \cdot \vec{g} \rangle, \langle Re \vec{f} \times Re \vec{g} \rangle = \frac{1}{2} Re \langle \vec{f}^* \times \vec{g} \rangle \end{cases}$$

复表示的一些结果:

$$\begin{cases} f_0 e^{iax} = g_0 e^{ibx} \iff f_0 = g_0, a = b \\ f_0 e^{iax} + g_0 e^{ibx} = h_0 e^{icx} \iff f_0 + g_0 = h_0, a = b = c \\ \dots \end{cases}$$

f_i, a_i 均可为复数。

上式中 $[\dots]$ 可由恒等式求导, 结合系数非零解条件, 得到范德蒙德行列式, 证得其中两个 a_i, a_j 相等, 然后相等的项合并, 得到低一阶的范德蒙德行列式, 同理证明更多的 a_i 相等, 进而指数项都相等, 消去, 得到各项系数的关系。

偏振度:

$$\begin{aligned} \tilde{R} &\triangleq \frac{E_{02}}{E_{01}} = \frac{A_2}{A_1} e^{i\delta} \\ \text{Im} \tilde{R} &= 0 \Rightarrow LP \\ \text{Im} \tilde{R} \neq 0, \pm 1 &\Rightarrow \begin{cases} \text{Im} \tilde{R} > 0, & REP \\ \text{Im} \tilde{R} < 0, & LEP \end{cases} \\ \tilde{R} = \pm i &\Rightarrow \begin{cases} \tilde{R} = i, & RCP \\ \tilde{R} = -i, & LCP \end{cases} \end{aligned}$$

一般的 \vec{E}_0 由 \vec{e}_1, \vec{e}_2 的线性组合表示, 也可以由圆偏振基表示:

$$\begin{cases} RCP & \vec{e}_+ = \frac{\vec{e}_1 + i\vec{e}_2}{\sqrt{2}} \\ LCP & \vec{e}_- = \frac{\vec{e}_1 - i\vec{e}_2}{\sqrt{2}} \end{cases}$$

绝缘介质中的电磁波:

两个参数:

$$\begin{cases} n \triangleq c\sqrt{\mu\epsilon} \\ Z \triangleq \sqrt{\frac{\mu}{\epsilon}} \end{cases}$$

麦克斯韦方程:

$$\begin{cases} \nabla \cdot \vec{D} = 0 \\ \nabla \cdot \vec{B} = 0 \\ \nabla \times \vec{E} = -\partial_t \vec{B} & (*) \\ \nabla \times \vec{H} = \partial_t \vec{D} & (*) \end{cases}$$

带 * 号的式子可以推出前两个以及相应的两个边界条件 $\begin{cases} \hat{n} \times (\vec{E}_2 - \vec{E}_1) = 0 \\ \hat{n} \times (\vec{H}_2 - \vec{H}_1) = 0 \end{cases}$

时谐场 (均匀介质):

$$\begin{cases} \vec{E}(\vec{r}, t) = \vec{E}(\vec{r})e^{-i\omega t} \\ \vec{H}(\vec{r}, t) = \vec{H}(\vec{r})e^{-i\omega t} \end{cases}$$

$$\vec{D}(\vec{r}, t) = \epsilon(\omega)\vec{E}(\vec{r}, t), \quad \vec{B}(\vec{r}, t) = \mu(\omega)\vec{H}(\vec{r}, t)$$

场的求解:

$$\begin{cases} \nabla^2 \vec{E} + \omega^2 \mu \epsilon \vec{E} = \nabla^2 \vec{E} + k^2 \vec{E} = 0 \\ \nabla \cdot \vec{E} = 0 \\ \vec{H} = -\frac{i}{\omega \mu} \nabla \times \vec{E} \end{cases}$$

$$k = \omega \sqrt{\mu \epsilon} = \frac{\omega}{c} n$$

在无限大均匀介质中的解为

$$\nabla^2 \vec{E} + k^2 \vec{E} = 0 \implies$$

$$\begin{cases} \vec{E}(\vec{r}) = \sum_{k', k'', k'''} E_{01} e^{i\vec{k}' \cdot \vec{r}} \hat{x}_1 + E_{02} e^{i\vec{k}'' \cdot \vec{r}} \hat{x}_2 + E_{03} e^{i\vec{k}''' \cdot \vec{r}} \hat{x}_3 \\ (k')^2 = (k'')^2 = (k''')^2 = k^2 \end{cases}$$

$$\nabla \cdot \vec{E} = 0 \implies \begin{cases} \vec{k}' = \vec{k}'' = \vec{k}''' \triangleq \vec{k} \\ \vec{k} \cdot \vec{E}_0 = 0 \end{cases}, \quad \vec{E}(\vec{r}) = \vec{E}_0 e^{i\vec{k} \cdot \vec{r}}$$

$$\vec{H} = -\frac{i}{\omega \mu} \nabla \times \vec{E} \implies \vec{H}(\vec{r}) = \frac{\vec{k} \times \vec{E}(\vec{r})}{\omega \mu}$$

其中 \vec{k} 可以为复矢量。(但此时 $k^2 = \frac{\omega}{c} n$ 不代表复矢量模, 只是矢量分量平方和 $\vec{k} \cdot \vec{k}$.) 若 \vec{k} 为实矢量, 则解为平面电磁波。(真空中自然也是这样)

单色平面波:

$$\begin{cases} \vec{E}(\vec{r}, t) = \vec{E}_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}, \quad \vec{k} \cdot \vec{E}_0 = 0 \\ \vec{H} = \frac{\vec{k} \times \vec{E}}{\omega \mu} \quad (Z\vec{H} = \hat{k} \times \vec{E}) \end{cases}$$

相速度:

$$\vec{v}_p = \frac{\omega}{k} \hat{k} = \frac{c}{n} \hat{k}$$

力学性质:

$$\begin{aligned}
 w &= \epsilon |Re \vec{E}|^2, \quad \langle w \rangle = \frac{1}{2} \epsilon \vec{E}_0^* \cdot \vec{E}_0 \\
 \vec{S} &= Re \vec{E} \times Re \vec{H}, \quad \langle \vec{S} \rangle = \frac{1}{2} Re(\vec{E}_0^* \times \vec{H}_0) = \frac{\vec{E}_0^* \cdot \vec{E}_0}{2Z} \hat{k} = \langle w \rangle \vec{v}_p \\
 \vec{g} &= \epsilon \mu Re \vec{E} \times Re \vec{H} = \frac{\vec{S}}{v_p^2}, \quad \langle \vec{g} \rangle = \frac{\langle w \rangle}{v_p^2} \vec{v}_p \\
 \vec{T} &= w \vec{I} - Re \vec{D} Re \vec{E} - Re \vec{B} Re \vec{H} = w \hat{k} \hat{k}, \quad \langle \vec{T} \rangle = \langle w \rangle \hat{k} \hat{k}
 \end{aligned}$$

单色平面波在介质界面的折射和透射 (非全反射):

边界条件对波矢的限制: 沿界面方向分量相等: 入射反射折射波的波矢共面; 反射定律, 折射定律: p 波 (电矢量平行于入射面偏振)、s 波 (电矢量垂直于入射面偏振) 的反射折射波仍是 p 波、s 波。

边界条件对振幅的限制: 菲涅尔公式:

$$\begin{cases} r_p = \frac{Z_1 \cos \theta_1 - Z_2 \cos \theta_2}{Z_1 \cos \theta_1 + Z_2 \cos \theta_2} \\ t_p = \frac{2Z_2 \cos \theta_1}{Z_1 \cos \theta_1 + Z_2 \cos \theta_2} \end{cases}, \quad \begin{cases} r_s = \frac{Z_2 \cos \theta_1 - Z_1 \cos \theta_2}{Z_2 \cos \theta_1 + Z_1 \cos \theta_2} \\ t_s = \frac{2Z_2 \cos \theta_1}{Z_2 \cos \theta_1 + Z_1 \cos \theta_2} \end{cases}$$

对于弱磁性材料 $\mu_1 = \mu_2 = \mu_0$, 上式化为

$$\begin{cases} r_p = \frac{\tan(\theta_1 - \theta_2)}{\tan(\theta_1 + \theta_2)} \\ t_p = \frac{2 \cos \theta_1 \sin \theta_2}{\sin(\theta_1 + \theta_2) \cos(\theta_1 - \theta_2)} \end{cases}, \quad \begin{cases} r_s = -\frac{\sin(\theta_1 - \theta_2)}{\sin(\theta_1 + \theta_2)} \\ t_s = \frac{2 \cos \theta_1 \sin \theta_2}{\sin(\theta_1 + \theta_2)} \end{cases}$$

能量输运:

$$\begin{cases} R \triangleq \left| \frac{\hat{n} \cdot \langle \vec{S}_R \rangle}{\hat{n} \cdot \langle \vec{S}_I \rangle} \right| = \frac{|\vec{E}_{0R}|^2}{|\vec{E}_{0I}|^2} \\ T \triangleq \left| \frac{\hat{n} \cdot \langle \vec{S}_T \rangle}{\hat{n} \cdot \langle \vec{S}_I \rangle} \right| = \frac{Z_1 \cos \theta_2}{Z_2 \cos \theta_1} \frac{|\vec{E}_{0T}|^2}{|\vec{E}_{0I}|^2} \end{cases}$$

全反射:

$$\begin{aligned}
 \vec{E}_T &= \vec{E}_{0T} e^{-\kappa z} e^{i(k_1 \sin \theta_1 x - \omega t)} \\
 \vec{k}_T &= k_{Tx} \hat{x} + i\kappa \hat{z} \\
 \kappa &= k_1 \sqrt{\sin^2 \theta_1 - n_{21}^2}
 \end{aligned}$$

倏逝波的 \vec{E}, \vec{H} 不同相, 且不是横波。

若定义 $\begin{cases} k_{Tx} = k_1 \sin \theta_1 \triangleq k_2 \sin \theta_2 \\ k_{Tz} = \sqrt{k_2^2 - k_1^2 \sin^2 \theta_1} \triangleq k_2 \cos \theta_2 \end{cases}$, 则菲涅尔公式的反射部分仍成立 (因为无散条件和实矢量横波条件的分量等式是一样的), 只是此时 $\sin \theta_2 > 1, \cos \theta_2 \in C$ 。且此时 $|r_p|, |r_s| = 1$, 入射波反射波之间有相位差。

透射系数:

$$\begin{aligned}
 \hat{z} \cdot \langle \vec{S}_T \rangle &= \hat{z} \cdot \frac{1}{2} \text{Re}[\vec{E}_T^* \times \vec{H}_T] \\
 &= \hat{z} \cdot \frac{1}{2\omega\mu_2} \text{Re}[|\vec{E}_T|^2 \vec{k}_T - (\vec{k}_T \cdot \vec{E}_T^*) \vec{E}_T] \\
 &= \frac{1}{2\omega\mu_2} \text{Re}[|\vec{E}_T|^2 i\kappa - (\vec{k}_T \cdot \vec{E}_T^*) E_{Tz}] \\
 &= \frac{1}{2\omega\mu_2} \text{Re}[\vec{E}_T|^2 i\kappa - 2i\kappa E_{Tz}^* E_{Tz}] = 0 \\
 (0 &= (\vec{k}_T \cdot \vec{E}_T)^* = k_{Tx} E_{Tx}^* - i\kappa E_{Tz}^*) \\
 T &\triangleq \left| \frac{\hat{n} \cdot \langle \vec{S}_T \rangle}{\hat{n} \cdot \langle \vec{S}_I \rangle} \right| = \left| \frac{\hat{z} \cdot \langle \vec{S}_T \rangle}{\hat{z} \cdot \langle \vec{S}_I \rangle} \right| = 0
 \end{aligned}$$

导体对电磁波的影响:

$$\text{欧姆型导体 } (\sigma < \infty): \begin{cases} \text{interior: } \vec{j}_0 = \sigma \vec{E}, \rho_0 = 0 \\ \text{surface: } \vec{K}_0 = 0, \sigma_0 \end{cases}$$

$$\text{理想导体 } (\sigma \rightarrow \infty): \begin{cases} \text{interior: } \vec{j}_0 = 0, \rho_0 = 0 \\ \text{surface: } \vec{K}_0, \sigma_0 \end{cases}$$

麦克斯韦方程:

$$\begin{cases} \nabla \cdot \vec{D} = \rho_0 \\ \nabla \cdot \vec{B} = 0 \\ \nabla \times \vec{E} = -\partial_t \vec{B} \\ \nabla \times \vec{H} = \sigma \vec{E} + \partial_t \vec{D} \end{cases} \quad \begin{matrix} (*) \\ (**) \end{matrix}$$

其中 (**) 式可以推出 (*) 式。认为导体内自由电荷为 0 且导体为均匀导体, 后两式也可以推出第一式。

边界条件:

$$\begin{cases} \hat{n} \times (\vec{E}_2 - \vec{E}_1) = 0 \\ \hat{n} \times (\vec{H}_2 - \vec{H}_1) = 0 \\ \hat{n} \times (\vec{D}_2 - \vec{D}_1) = \sigma_0 \end{cases}$$

时谐场 (均匀导体):

$$\begin{cases} \nabla \times \vec{E} = i\omega\mu\vec{H} \\ \nabla \times \vec{H} = -i\omega\epsilon\vec{E} \end{cases} \Rightarrow \begin{cases} \nabla^2 \vec{E} + k^2 \vec{E} = 0 \\ \nabla \cdot \vec{E} = 0 \\ \vec{H} = -\frac{i}{\omega\mu} \nabla \times \vec{E} \end{cases}$$

$$\begin{aligned}\tilde{\epsilon} &\triangleq \epsilon + i\frac{\sigma}{\omega}, & \tilde{k} &= \omega\sqrt{\mu\tilde{\epsilon}} \\ \tilde{n} &\triangleq c\sqrt{\mu\tilde{\epsilon}}, & \tilde{z} &\triangleq \sqrt{\frac{\mu}{\tilde{\epsilon}}}\end{aligned}$$

单色平面波:

$$\begin{aligned}\vec{E} &= \vec{E}_0 e^{i(\vec{k}\cdot\vec{r}-\omega t)}, & \vec{H} &= \vec{H}_0 e^{i(\vec{k}\cdot\vec{r}-\omega t)} \\ \vec{k}\cdot\vec{k} &= \tilde{k}^2 = \omega^2\mu\epsilon + i\omega\mu\sigma \\ \vec{k} &= \vec{\beta} + i\vec{\alpha}, & \beta^2 - \alpha^2 &= \omega^2\mu\epsilon, & 2\vec{\alpha}\cdot\vec{\beta} &= \omega\mu\sigma \\ \vec{E} &= \vec{E}_0 e^{-\vec{\alpha}\cdot\vec{r}} e^{i(\vec{\beta}\cdot\vec{r}-\omega t)}\end{aligned}$$

\vec{E}, \vec{H} 不同相, 且不是横波。

导体表面的反射和透射:

边界条件对波矢的限制: 在界面上的分量相等 $\beta_x = k_0 \sin \theta_1$; 入射、反射、透射波的波矢共面;
 $\vec{\alpha} = \alpha \hat{z}$;

$$\begin{aligned}\begin{cases} \beta^2 - \alpha^2 = \omega^2\mu\epsilon \\ 2\vec{\alpha}\cdot\vec{\beta} = \omega\mu\sigma \end{cases} &\implies \frac{\beta_z^2 - \alpha^2}{\alpha\beta_z} = \frac{2\omega\epsilon}{\sigma} \left(1 - \frac{\sin^2 \theta_1}{n^2}\right) \\ \xrightarrow{\sigma \rightarrow \infty} \alpha \approx \beta_z &\approx \sqrt{\frac{\omega\mu\sigma}{2}}, & \frac{\beta_x}{\beta_z} &= \frac{\sin \theta_1}{n} \sqrt{\frac{2\omega\epsilon}{\sigma}} \ll 1 \\ v_p = \frac{\omega}{\beta} \approx \frac{\omega}{\beta_z} &= \frac{c}{n} \sqrt{\frac{2\omega\epsilon}{\sigma}} \ll \frac{c}{n}\end{aligned}$$

趋肤效应: $d \triangleq \frac{1}{\alpha} \approx \sqrt{\frac{2}{\omega\mu\sigma}}$

良导体正入射:

$$\begin{cases} \vec{E}_1(\vec{r}, t) = E_{0I} e^{i(k_0 z - \omega t)} \hat{y} + E_{0R} e^{i(k_0 z + \omega t)} \hat{y} \\ \vec{E}_2(\vec{r}, t) = E_{0T} e^{i(\alpha(1+i)z - \omega t)} \hat{y} \\ \vec{H}_1(\vec{r}, t) = \frac{k_0}{\omega\mu_0} [E_{0I} e^{i(k_0 z - \omega t)} + E_{0R} e^{i(k_0 z + \omega t)}] \hat{x} \\ \vec{H}_2(\vec{r}, t) = -\frac{\alpha(1+i)}{\omega\mu} E_{0T} e^{i(\alpha(1+i)z - \omega t)} \hat{x} \end{cases}$$

$$\vec{H}_2 \text{ 比 } \vec{E}_2 \text{ 落后 } \frac{\pi}{4}; \quad \frac{\langle w_m \rangle}{\langle w_e \rangle} = \frac{\mu |\vec{H}_2|^2}{\epsilon |\vec{E}_2|^2} = \frac{\mu\sigma}{\epsilon\omega\mu} = \frac{\sigma}{\epsilon\omega} \gg 1$$

电流密度 $\vec{j} = \sigma \vec{E}_2$ 指数递减, 良导体情况下近似为表面电流:

$$\vec{K} = \int_0^\infty \vec{j}(z, t) dz = \frac{\sigma E_{0T}}{\sqrt{2}\alpha} e^{-i(\omega t - \pi/4)} \hat{y} = \vec{K}_0 e^{-i(\omega t - \pi/4)} \hat{y}$$

由热效应定义表面电阻 $R_s \triangleq \frac{1}{\sigma d} = \frac{\alpha}{\sigma}$

由边界条件确定正入射时的振幅关系，可有

$$R = |r|^2 = \frac{(1 - k_0 d)^2 + 1}{(1 + k_0 d)^2 + 1} \approx \frac{1 - k_0 d}{1 + k_0 d}$$

谐振腔与波导管：

理想导体边界下的时谐场：

$$\begin{cases} \nabla^2 \vec{E} + k^2 \vec{E} = 0 \\ \nabla \cdot \vec{E} = 0 \\ \vec{H} = -\frac{i}{\omega \mu_0} \nabla \times \vec{E} \end{cases}, \quad k = \frac{\omega}{c}$$

边界条件：

$$\begin{cases} \hat{n} \times \vec{E}|_{\vec{S}} = 0 \\ (\nabla \cdot \vec{E})|_{\vec{S}} = 0 \end{cases} \begin{cases} \frac{\partial E_n}{\partial n}|_{\vec{S}} = 0 \\ \frac{1}{E_s} \frac{\partial E_s}{\partial s}|_{s=R} = \frac{1}{R} \\ \frac{1}{E_r} \frac{\partial E_r}{\partial r}|_{r=R} = -\frac{2}{R} \end{cases}$$

得到解后计算其他物理量：

$$\sigma_0 = \hat{n} \cdot \vec{D}|_{\vec{S}}, \quad \vec{K}_0 = \hat{n} \times \vec{H}|_{\vec{S}}$$

谐振腔 (尺寸为 $a \times b \times d$)：

$$\nabla^2 \vec{E} + k^2 \vec{E} = 0 \Rightarrow \begin{cases} E_x = A_1 \cos k_1 x \sin k_2 y \sin k_3 z e^{-\omega t} \\ E_y = A_2 \sin k'_1 x \cos k'_2 y \sin k'_3 z e^{-\omega t} \\ E_z = A_3 \sin k''_1 x \sin k''_2 y \cos k''_3 z e^{-\omega t} \end{cases}$$

$$\nabla \cdot \vec{E} = 0 \Rightarrow \begin{cases} \vec{k} = \vec{k}' = \vec{k}'' \\ \vec{k} \cdot \vec{A} = 0 \end{cases}$$

$$k_1 = \frac{m\pi}{a}, \quad k_2 = \frac{n\pi}{b}, \quad k_3 = \frac{l\pi}{d}, \quad k = \sqrt{\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2 + \left(\frac{l\pi}{d}\right)^2}$$

由电场表达式， m, n, l 中最多一个为 0 才有非 0 解。每组 (m, n, l) 表示一种本征模式。 m, n, l 全部非 0 时，每个本征模式对应两个独立偏振模式 $A_1 : A_2 : A_3$ 。

$$\omega_{mnl} = kc = \pi c \sqrt{\left(\frac{m}{a}\right)^2 + \left(\frac{n}{b}\right)^2 + \left(\frac{l}{d}\right)^2}$$

频率只能取分立数值，称为本征频率。能在腔中激发的最低频率称为下截止频率 (m, n, l 中一个为 0)，具体取值由腔的尺寸决定。

矩形波导管 (尺寸 $a \times b$):

求行波形式的解:

$$\begin{cases} \vec{E}(\vec{r}, t) = \vec{E}(x, y) e^{i(k_3 z - \omega t)} \\ \vec{H}(\vec{r}, t) = \vec{H}(x, y) e^{i(k_3 z - \omega t)} \end{cases}$$

$$\nabla^2 \vec{E} + k^2 \vec{E} = 0 \Rightarrow \begin{cases} E_x = A_1 \cos k_1 x \sin k_2 y e^{i\phi} \\ E_y = A_2 \sin k'_1 x \cos k'_2 y e^{i\phi} \\ E_z = A_3 \sin k''_1 x \sin k''_2 y e^{i\phi} \end{cases}$$

$$\nabla \cdot \vec{E} = 0 \Rightarrow \begin{cases} \vec{k} = \vec{k}' = \vec{k}'' \\ k_1 A_1 + k_2 A_2 - i k_3 A_3 = 0 \end{cases}$$

$$k_1 = \frac{m\pi}{a}, \quad k_2 = \frac{n\pi}{b}, \quad k = \sqrt{\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2 + (k_3)^2}$$

由电场表达式, m, n 中最多一个为 0 才有非 0 解。每组 ($m \neq 0, n \neq 0$) 对应两个独立偏振模式。一个为 0 时, 对应一个偏振模式。

$$\omega = c \sqrt{\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2 + (k_3)^2} = \sqrt{\omega_{c,mn}^2 + k_3^2 c^2}$$

频率可以连续取值, 但存在下截止频率, 具体取值由尺寸决定。

磁场:

$$\vec{H} = -\frac{i}{\omega\mu_0} \nabla \times \vec{E} = \begin{cases} H_x = -\frac{i}{\omega\mu_0} (k_2 A_3 - i k_3 A_2) \sin k_1 x \cos k_2 y e^{i\phi} \\ H_y = -\frac{i}{\omega\mu_0} (i k_3 A_1 - k_1 A_3) \cos k_1 x \sin k_2 y e^{i\phi} \\ H_z = -\frac{i}{\omega\mu_0} (k_1 A_2 - k_2 A_1) \sin k_1 x \sin k_2 y e^{i\phi} \end{cases}$$

波导管的行波解不存在横电磁波 (TEM) ($A_3 = 0, k_1 A_2 - k_2 A_1 = 0, k_1 A_1 + k_2 A_2 - i k_3 A_3 = 0$ 在 m, n 至多一个为 0 的情况下无解)。当 $m \neq 0, n \neq 0$ 时, 存在 TE 波 ($A_3 = 0, k_1 A_1 + k_2 A_2 = 0$ 有解) 和 TM 波 ($k_1 A_2 - k_2 A_1 = 0, k_1 A_1 + k_2 A_2 - i k_3 A_3 = 0$ 有解); 当两个数有一个为 0 时, 只存在 TE 波 (此时电磁为横波, 故磁场不可能为横波)。

相速群速:

$$v_p = \frac{\omega}{k_3} = \frac{\omega c}{\sqrt{\omega^2 - \omega_{c,mn}^2}} > c, \quad v_g \frac{d\omega}{dk_3} = \frac{k_3 c^2}{\omega} = \frac{k_3 c^2}{\sqrt{\omega_{c,mn}^2 + k_3^2 c^2}} < c$$

$$v_p v_g = c^2$$

一般波导管:

分为垂直 (\perp) 和平行方向 (\hat{z})

$$\nabla = \nabla_{\perp} + \hat{z}\partial_z$$

行波形式的解:

$$\begin{cases} \vec{E}(\vec{r}, t) = [\vec{E}_{\perp}(\vec{r}_{\perp}) + E_z(\vec{r}_{\perp})\hat{z}]e^{i(k_3z - \omega t)} \\ \vec{H}(\vec{r}, t) = [\vec{H}_{\perp}(\vec{r}_{\perp}) + H_z(\vec{r}_{\perp})\hat{z}]e^{i(k_3z - \omega t)} \end{cases}$$

$$\nabla = \nabla_{\perp} + ik_3\hat{z}, \quad \partial_t = -i\omega$$

基本方程:

$$\begin{cases} \nabla \times \vec{E} = i\omega\mu\vec{H} \\ \nabla \times \vec{H} = -i\omega\epsilon\vec{E} \end{cases}$$

$$\Rightarrow \begin{cases} \nabla_{\perp} \times \vec{E}_{\perp} = i\omega\mu H_z \hat{z}, & k_3 \hat{z} \times \vec{E}_{\perp} - \omega\mu \vec{H}_{\perp} = -i\hat{z} \times \nabla_{\perp} E_z \\ \nabla_{\perp} \times \vec{H}_{\perp} = -i\omega\epsilon E_z \hat{z}, & k_3 \hat{z} \times \vec{H}_{\perp} + \omega\epsilon \vec{E}_{\perp} = -i\hat{z} \times \nabla_{\perp} H_z \end{cases}$$

不存在 TEM:

若 $E_z = H_z = 0$

$$\begin{cases} \nabla_{\perp} \times \vec{E}_{\perp} = 0, & k_3 \hat{z} \times \vec{E}_{\perp} - \omega\mu \vec{H}_{\perp} = 0 \\ \nabla_{\perp} \times \vec{H}_{\perp} = 0, & k_3 \hat{z} \times \vec{H}_{\perp} + \omega\epsilon \vec{E}_{\perp} = 0 \end{cases} \Rightarrow \begin{cases} \nabla_{\perp} \cdot \vec{E}_{\perp} = 0 \\ \nabla_{\perp} \cdot \vec{H}_{\perp} = 0 \end{cases}$$

$$\begin{cases} \nabla_{\perp} \cdot \vec{E}_{\perp} = 0 \\ \vec{E}_{\perp} = -\nabla_{\perp} \phi_{\perp}(\vec{r}_{\perp}) \end{cases} \Rightarrow \nabla_{\perp}^2 \phi_{\perp} = 0 \Rightarrow E_{\perp} = 0$$

$$\hat{n} \times \vec{E}_{\perp}|_{\mathcal{S}} = 0 \Rightarrow \phi_{\perp}(\vec{r})|_{\mathcal{S}} = \text{const}$$

$$\dots \Rightarrow H_{\perp} = 0$$

H_z 在截面上的积分为 0:

$$\hat{n} \times (\vec{E}_2 - \vec{E}_1) = 0 \Rightarrow \vec{E}_{\perp}|_{\mathcal{S}} / \hat{n}$$

$$\Rightarrow 0 = \oint_C d\vec{l} \cdot \vec{E}_{\perp} = \int_{\Sigma} d\vec{\sigma} \cdot (\nabla_{\perp} \times \vec{E}_{\perp}) = i\omega\mu \int_{\Sigma} d\sigma H_z$$

$$\Rightarrow \int_{\Sigma} d\sigma H_z = 0$$

同时可以看出 TE 波的 H_z 不为常数。(否则将存在 TEM)

基本方程的转化:

$$\begin{cases} \nabla_{\perp} \times \vec{E}_{\perp} = i\omega\mu H_z \hat{z} \\ \nabla_{\perp} \times \vec{H}_{\perp} = -i\omega\epsilon E_z \hat{z} \end{cases}, \quad \begin{cases} \gamma^2 \vec{E}_{\perp} = ik_3 \nabla_{\perp} E_z - i\omega\mu \hat{z} \times \nabla_{\perp} H_z \\ \gamma^2 \vec{H}_{\perp} = ik_3 \nabla_{\perp} H_z + i\omega\epsilon \hat{z} \times \nabla_{\perp} E_z \end{cases} \quad (*)$$

$$\gamma^2 \triangleq \omega^2 \mu \epsilon - k_3^2$$

$$\Rightarrow \begin{cases} \gamma^2 (\nabla_{\perp} \times \vec{E}_{\perp}) = -i\omega\mu \nabla_{\perp} (\hat{z} \times \nabla_{\perp} H_z) \Rightarrow \nabla_{\perp}^2 E_z = -\gamma^2 E_z \\ \gamma^2 (\nabla_{\perp} \times \vec{H}_{\perp}) = i\omega\mu \nabla_{\perp} (\hat{z} \times \nabla_{\perp} E_z) \Rightarrow \nabla_{\perp}^2 H_z = -\gamma^2 H_z \end{cases} \quad (*1)$$

$$\Rightarrow \begin{cases} \gamma^2 (\nabla_{\perp} \cdot \vec{E}_{\perp}) = ik_3 \nabla_{\perp}^2 E_z = -\gamma^2 \partial_z \hat{z} \cdot E_z \hat{z} \Rightarrow \nabla \cdot \vec{E} = 0 \\ \gamma^2 (\nabla_{\perp} \cdot \vec{H}_{\perp}) = ik_3 \nabla_{\perp}^2 H_z = -\gamma^2 \partial_z \hat{z} \cdot H_z \hat{z} \Rightarrow \nabla \cdot \vec{H} = 0 \end{cases} \quad (*2)$$

(*) 可以看出, 若 E_z, H_z 均为 0 或常数, 则只有 0 解。即 TE 波的 H_z 不为常数, TM 波的 E_z 不为常数。

(*1) 对于非 0 解, E_z, H_z 不能均为 0 或常数, 故此时必有 $\gamma^2 \neq 0$

(*2) 由于此时方程未耦合 ((*) 可以化回原来的方程), 故无散条件自动满足是显然的。

”Helmholtz 方程”:

$$\begin{cases} (\nabla_{\perp}^2 + \gamma^2) E_z = 0 \\ (\nabla_{\perp}^2 + \gamma^2) H_z = 0 \end{cases}$$

”亥姆霍兹方程”可以由 (*1) 式得到, 也可从 $\nabla^2 E_z + k^2 E_z = 0$ 和 γ^2 的定义直接得到。在矩形波导管中要解三个亥姆霍兹方程加上无散条件的限制, 这里只需解两个 (无散条件自动满足)。

方程求解:

$$\begin{aligned} TM : & \begin{cases} (\nabla_{\perp}^2 + \gamma^2) E_z = 0 \\ \hat{n} \times \vec{E}|_{\vec{S}} = 0 \Rightarrow E_z = 0|_{\vec{S}} \\ \vec{E}_{\perp} = \frac{ik_3}{\gamma^2} \nabla_{\perp} E_z, \quad \vec{H} = \vec{H}_{\perp} = \frac{i\omega\epsilon}{\gamma^2} \hat{z} \times \nabla_{\perp} E_z \end{cases} \\ TE : & \begin{cases} (\nabla_{\perp}^2 + \gamma^2) H_z = 0 \\ \hat{n} \times \vec{E}|_{\vec{S}} = 0 \Rightarrow \hat{n} \times (\hat{z} \times \nabla_{\perp} H_z)|_{\vec{S}} = 0 \Rightarrow \frac{\partial H_z}{\partial n}|_{\vec{S}} = 0 \\ \vec{H}_{\perp} = \frac{ik_3}{\gamma^2} \nabla_{\perp} H_z, \quad \vec{E} = \vec{E}_{\perp} = -\frac{i\omega\mu}{\gamma^2} \hat{z} \times \nabla_{\perp} H_z \end{cases} \end{aligned}$$

边界条件的取定是因为: 面电流密度未知, 不能用于求解; 无散条件已被自动保证满足, 不能用于求解。

$\gamma^2 > 0$:

$$\begin{aligned}
 \psi(\vec{r}_\perp) &\stackrel{\Delta}{=} E_z(\vec{r}_\perp) \quad (in TM) \quad or \quad H_z(\vec{r}_\perp) \quad (in TE) \\
 \nabla_\perp^2 \psi + \gamma^2 \psi &= 0 \implies \\
 \gamma^2 \int dV |\psi|^2 &= \int dV \psi^* \gamma^2 \psi = - \int dV \psi^* \nabla_\perp^2 \psi \\
 &= \dots = - \oint d\vec{\sigma} \cdot \psi^* \nabla_\perp \psi + \int dV |\nabla_\perp \psi|^2 \\
 &= - \oint d\sigma \psi^* \frac{\partial \psi}{\partial n} + \int dV |\nabla_\perp \psi|^2 \\
 &= \int dV |\nabla_\perp \psi|^2 > 0 \quad \left(E_z = 0|_{\vec{S}} = 0, \frac{\partial H_z}{\partial n}|_{\vec{S}} = 0 \right)
 \end{aligned}$$

6 电磁辐射

势方程:

$$L \stackrel{\Delta}{=} \nabla \cdot \vec{A} + \frac{1}{c^2} \partial_t \phi, \quad \square \stackrel{\Delta}{=} \nabla^2 - \frac{1}{c^2} \partial_t^2 \text{ (d'Alembert 算子)}$$

$$\begin{cases} \square \phi + \partial_t L = -\frac{\rho}{\epsilon_0} \\ \square \vec{A} - \nabla L = -\mu_0 \vec{j} \end{cases}$$

Coulomb 规范:

$$\begin{cases} \nabla \cdot \vec{A} = 0 & (I_c) \\ \nabla^2 \phi = -\frac{\rho}{\epsilon_0} & (I_a) \\ \square \vec{A} = -\mu_0 \vec{j} & (I_b) \end{cases}$$

Lorentz 规范:

$$\begin{cases} L = \nabla \cdot \vec{A} + \frac{1}{c^2} \partial_t \phi = 0 & (I_c) \\ \square \phi = -\frac{\rho}{\epsilon_0} & (I_a) \\ \square \vec{A} = -\mu_0 \vec{j} & (I_b) \end{cases}$$

自由空间单色平面波解:

$$\phi(\vec{r}, t) = \phi_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}, \quad \vec{A}(\vec{r}, t) = \vec{A}_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

代入 Coulomb 规范:

$$\begin{aligned}
 I_a \implies \phi &= 0, I_b \implies \omega = kc, I_c \implies \vec{k} \cdot \vec{A} = 0 \\
 \vec{E} &= -\partial_t \vec{A} = i\omega \vec{A}, \vec{B} = \nabla \times \vec{A} = \frac{\vec{k} \times \vec{E}}{\omega}
 \end{aligned}$$

代入 Lorentz 规范:

$$I_a, I_b \implies \omega = kc, I_c \implies \vec{k} \cdot \vec{A} = \frac{\omega}{c^2} \phi$$

$$\vec{B} = \nabla \times \vec{A} = i\vec{k} \times \vec{A}, \vec{E} = -\nabla\phi - \partial_t \vec{A} = i\omega[\vec{A} - (\hat{k} \cdot \vec{A})\hat{k}] = c\vec{B} \times \hat{k}$$

推迟势:

$$\nabla^2 \phi - \frac{1}{c^2} \partial_t^2 \phi = -\frac{\rho(\vec{r}, t)}{\epsilon_0}$$

Green:

$$\nabla^2 \phi' - \frac{1}{c^2} \partial_t^2 \phi' = -\frac{\rho(\vec{r}', t) \delta(\vec{r} - \vec{r}')}{\epsilon_0}, \quad \rho(\vec{r}, t) = \int \rho(\vec{r}', t) \delta(\vec{r} - \vec{r}') dV'$$

$$\implies \begin{cases} \nabla^2 \phi' - \frac{1}{c^2} \partial_t^2 \phi' = 0 \\ \int dV (\nabla^2 \phi' - \frac{1}{c^2} \partial_t^2 \phi') = -\frac{\rho(\vec{r}', t)}{\epsilon_0} \end{cases}$$

$$\implies \begin{cases} \phi'(\mathbb{R}, t) = \frac{1}{\mathbb{R}} f(t - \frac{\mathbb{R}}{c}) \\ \int dV (f \nabla^2 \frac{1}{\mathbb{R}} + 2\nabla f \cdot \nabla \frac{1}{\mathbb{R}} + \frac{1}{\mathbb{R}} \nabla^2 f - \frac{1}{c^2 \mathbb{R}} \frac{\partial^2 f}{\partial t^2}) = -4\pi f(t) = -\frac{\rho(\vec{r}', t)}{\epsilon_0} \end{cases}$$

$$\phi'(\mathbb{R}, t) = \frac{1}{4\pi\epsilon_0} \frac{\rho(\vec{r}', t - \frac{\mathbb{R}}{c})}{\mathbb{R}}$$

$$\phi(\vec{r}, t) = \int dV' \phi'(\mathbb{R}, t) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}', t - \frac{\mathbb{R}}{c})}{\mathbb{R}} dV'$$

$$\dots \implies \vec{A}(\vec{r}, t) = \frac{\mu_0}{4\pi} \int \frac{\vec{j}(\vec{r}', t - \frac{\mathbb{R}}{c})}{\mathbb{R}} dV'$$

满足洛伦兹条件:

$$\begin{aligned} \nabla \cdot \vec{A} &= \frac{\mu_0}{4\pi} \int \nabla \cdot \frac{\vec{j}(\vec{r}', t - \frac{\mathbb{R}}{c})}{\mathbb{R}} dV' \\ &= \frac{\mu_0}{4\pi} \int dV' \left[-\nabla' \cdot \frac{\vec{j}(\vec{r}', t_r)}{\mathbb{R}} + \frac{[\nabla \cdot \vec{j}(\vec{r}', t_r)]_{t_r}}{\mathbb{R}} \right] \\ &= -\frac{1}{4\pi\epsilon_0 c^2} \int dV' \frac{\partial \rho(\vec{r}', t_r)}{\mathbb{R}} \\ &= -\frac{1}{c^2} \partial_t \phi \end{aligned}$$

电磁场:

$$\vec{B} = \nabla \times \vec{A} = \dots, \vec{E} = -\nabla\phi - \partial_t \vec{A} = \dots$$

在周期变换的电偶极子情况下计算坡印廷矢量可以发现在一个周期内流出去的能量和电偶极子二阶导数有关。

谐振电流的辐射场:

$$\begin{aligned}\vec{j}(\vec{r}, t) &= \vec{j}_0(\vec{r})e^{-i\omega t} \\ \frac{dP}{d\Omega} &= \lim_{r \rightarrow \infty} (\hat{r} \cdot \vec{S})r^2 = \frac{r^2}{\mu_0} \hat{r} \cdot (\vec{E}_{rad} \times \vec{B}_{rad}) \\ - \int_V dV \vec{E} \cdot \vec{j} &= \frac{dW}{dt} + \oint_{\partial V} d\vec{\sigma} \cdot \vec{S} \Rightarrow \langle P \rangle = -\frac{1}{2} Re \int_V dV \vec{E}^* \cdot \vec{j}\end{aligned}$$

势与场:

$$\begin{aligned}\begin{cases} \vec{j}(\vec{r}, t) = \vec{j}_0(\vec{r})e^{-i\omega t} \\ \nabla \cdot \vec{j} = -\partial_t \rho = i\omega \rho \Rightarrow \rho(\vec{r}, t) = \rho_0(\vec{r})e^{-i\omega t} = -\frac{i}{\omega} \nabla \cdot \vec{j}(\vec{r}, t) \end{cases} \\ \Rightarrow \begin{cases} \vec{A}(\vec{r}, t) = \vec{A}_0(\vec{r})e^{-i\omega t} = \frac{\mu_0}{4\pi} \int dV' \frac{\vec{j}_0(\vec{r}')e^{ikR}}{R} e^{-i\omega t} \\ \phi(\vec{r}, t) = \frac{1}{4\pi\epsilon_0} \int dV' \frac{\rho_0(\vec{r}')e^{ikR}}{R} e^{-i\omega t} \end{cases}\end{aligned}$$

洛伦兹条件的检验:

$$\begin{aligned}\phi(\vec{r}, t) &= \left(-\frac{ic^2}{\omega}\right) \frac{\mu_0}{4\pi} \int dV' \frac{\nabla' \cdot \vec{j}(\vec{r}', t)}{R} e^{ikR} \\ &= \left(-\frac{ic^2}{\omega}\right) \frac{\mu_0}{4\pi} \left[\oint d\vec{\sigma}' \cdot \frac{\vec{j} e^{ikR}}{R} + \nabla \cdot \int dV' \frac{\vec{j} e^{ikR}}{R} \right] \\ &= -i \frac{c^2}{\omega} \nabla \cdot \vec{A}(\vec{r}, t) \\ \Rightarrow \nabla \cdot \vec{A}(\vec{r}, t) + i\omega \frac{1}{c^2} \phi(\vec{r}, t) &= \nabla \cdot \vec{A}(\vec{r}, t) + \frac{1}{c^2} \partial_t^2 \phi(\vec{r}, t) = 0\end{aligned}$$

电磁场的计算:

$$\vec{B} = \nabla \times \vec{E}, \vec{E} = i \frac{c^2}{\omega} \nabla \times \vec{B}$$

(第二式是因为考虑场点没有源)

场区分:

近场区: $R \ll \lambda (kR \ll 1)$

感应区: $R \sim \lambda (kR \sim 1)$

辐射区: $R \gg \lambda (kR \gg 1)$

辐射场的提取:

由于球表面积 $S \sim r^2$, 故 \vec{E}, \vec{B} 只需保留到 $\frac{1}{r}$, 由 \vec{E}, \vec{B} 与 ϕ, \vec{A} 的关系可知, \vec{A} 只需保留到 $\frac{1}{r}$ 。
 $\left(\frac{d}{dr} \frac{e^{ikr}}{r} = ik \frac{e^{ikr}}{r} - \frac{e^{ikr}}{r^2}\right)$

approx.1: $r' \ll \mathbb{R}$

$$\frac{1}{\mathbb{R}} \approx \frac{1}{r}$$

$$k\mathbb{R} = k e^{-\vec{r}' \cdot \nabla} r = k \left[r - \vec{r}' \cdot \hat{r} + \frac{1}{2} \vec{r}' \vec{r}' : \frac{\vec{I}}{r} + \dots \right]$$

由于 λ, r' 的关系不明确, 故 $k\mathbb{R}$ 不能化简。

$$\vec{A}(\vec{r}, t) = \frac{\mu_0}{4\pi r} \int dV' \vec{j}(\vec{r}', t) e^{ik\mathbb{R}}$$

approx.2: $r' \ll \mathbb{R}, r' \lesssim \lambda$

$$\frac{1}{\mathbb{R}} \approx \frac{1}{r}$$

$$k\mathbb{R} = k e^{-\vec{r}' \cdot \nabla} r = k \left[r - \vec{r}' \cdot \hat{r} + \frac{1}{2} \vec{r}' \vec{r}' : \frac{\vec{I}}{r} + \dots \right]$$

$$= k [r - \vec{r}' \cdot \hat{r}] = \vec{k} \cdot \vec{\mathbb{R}}$$

$$\vec{A}(\vec{r}, t) = \frac{\mu_0}{4\pi r} e^{ikr} \int dV' \vec{j}(\vec{r}', t) e^{-i\vec{k} \cdot \vec{r}'}$$

此时有

$$\vec{B} = \nabla \times \vec{A} \sim \nabla \frac{e^{ikr} e^{-i\vec{k} \cdot \vec{r}'}}{r} \begin{cases} (\nabla \frac{1}{r}) e^{ikr} e^{-i\vec{k} \cdot \vec{r}'} \sim \frac{1}{r^2} & (*) \\ \frac{e^{-i\vec{k} \cdot \vec{r}'}}{r} \nabla (e^{ikr}) \sim \frac{k}{r} & (**) \\ \frac{e^{ikr} \nabla e^{-i\vec{k} \cdot \vec{r}'}}{r} \sim \frac{kr'}{r^2} & (***) \end{cases}$$

$$\frac{(***)}{(**)} \sim \frac{r'}{r} \ll 1$$

$$\frac{(*)}{(**)} \sim \frac{1}{kr}$$

从而 (**) 式可忽略, 但 r, λ 的关系不明确, 故 (*), (**) 的取舍不明。

approx.3: $r' \ll \mathbb{R}, r' \lesssim \lambda, \lambda \ll r$ (辐射区)

$$\frac{1}{\mathbb{R}} \approx \frac{1}{r}$$

$$k\mathbb{R} = \vec{k} \cdot \vec{\mathbb{R}}$$

$$\vec{A}(\vec{r}, t) = \frac{\mu_0}{4\pi r} e^{ikr} \int dV' \vec{j}(\vec{r}', t) e^{-i\vec{k} \cdot \vec{r}'}$$

而此时 $\frac{(*)}{(**)} \sim \frac{1}{kr} \ll 1$, 故

$$\begin{aligned} \vec{B} &= \nabla \times \vec{A} = i\vec{k} \times \vec{A} \\ \vec{E} &= i \frac{c^2}{\omega} \nabla \times \vec{B} = -\frac{c^2}{\omega} \vec{k} \times \vec{B} = c \vec{B} \times \hat{r} \\ \partial_t &\leftrightarrow -i\omega, \quad \nabla \leftrightarrow i\vec{k} = i \frac{\omega}{c} \hat{r} \leftrightarrow -\frac{\hat{r}}{c} \partial_r \end{aligned}$$

可见此时的辐射场是球面波且为横波。

$$\langle \vec{S} \rangle = \frac{1}{2\mu_0} \text{Re}(\vec{E}^* \times \vec{B}) = \frac{c}{2\mu_0} |\vec{B}|^2 \hat{r}$$

小场源辐射:

$$\begin{aligned} r' &<< \mathbb{R}, r' << \lambda, \lambda << r \\ \vec{A}(\vec{r}, t) &= \frac{\mu_0}{4\pi r} e^{ikr} \int dV' \vec{j}(\vec{r}', t) e^{-i\vec{k} \cdot \vec{r}'} \\ &= \frac{\mu_0}{4\pi r} e^{ikr} \int dV' \vec{j}(\vec{r}', t) (1 - i\vec{k} \cdot \vec{r}') \\ &= \frac{\mu_0}{4\pi r} e^{ikr} [\dot{\vec{p}}(t) - i\vec{m}(t) \times \vec{k} - i\frac{1}{6}\vec{D}(t) \cdot \vec{k} - i\frac{1}{6}\dot{g}(t)\vec{k}] \\ &= \frac{\mu_0}{4\pi r} e^{ikr} [\dot{\vec{p}}(t) + \frac{1}{c}\vec{m}(t) \times \hat{r} + \frac{1}{6c}\hat{r} \cdot \vec{D}(t) + \frac{1}{6c}\dot{g}(t)\hat{r}] \\ &= \frac{\mu_0}{4\pi r} [\dot{\vec{p}}(t - \frac{r}{c}) + \frac{1}{c}\vec{m}(t - \frac{r}{c}) \times \hat{r} + \frac{1}{6c}\hat{r} \cdot \vec{D}(t - \frac{r}{c}) + \frac{1}{6c}\dot{g}(t - \frac{r}{c})\hat{r}] \end{aligned}$$

式中的 g 并不影响, 因为 g 和 \hat{r} 一起出现, 在叉乘中消掉。也可以通过保洛伦兹规范规范变换消掉:

$$\begin{aligned} \vec{A}' &= \vec{A} + \nabla\psi = \vec{A} + i\vec{k}\psi = \vec{A} - \frac{\hat{r}}{c}\dot{\psi} \\ \frac{\dot{\psi}}{c} &= \frac{\mu_0}{4\pi r} \frac{1}{6c} \dot{g}(t - \frac{r}{c}) \implies \psi = \frac{\mu_0}{24\pi c} \frac{\dot{g}(t - \frac{r}{c})}{r} \end{aligned}$$

可以看出此时 ψ 是满足达朗贝尔方程的 (保洛伦兹规范)。

电偶极辐射:

$$\begin{aligned} \vec{A}(\vec{r}, t) &= \frac{\mu_0 e^{ikr}}{4\pi r} \dot{\vec{p}}(t) \\ \vec{B} &= \frac{1}{c} \dot{\vec{A}} \times \hat{r} = \frac{\mu_0 e^{ikr}}{4\pi cr} \ddot{\vec{p}} \times \hat{r} \\ \vec{E} &= c\vec{B} \times \hat{r} = \frac{\mu_0 e^{ikr}}{4\pi r} (\ddot{\vec{p}} \times \hat{r}) \times \hat{r} \\ \langle \vec{S} \rangle &= \frac{c}{2\mu_0} |\vec{B}|^2 \hat{r} = \frac{\mu_0}{32\pi^2 cr^2} |\ddot{\vec{p}} \times \hat{r}|^2 \hat{r} \\ \frac{d\langle P \rangle}{d\Omega} &= \frac{\mu_0}{32\pi^2 c} |\ddot{\vec{p}} \times \hat{r}|^2 \\ \langle P \rangle &= \frac{1}{32\pi^2 \epsilon_0 c^3} \int d\Omega (\ddot{\vec{p}}^* \times \hat{r}) \cdot (\ddot{\vec{p}} \times \hat{r}) \\ &= \frac{1}{32\pi^2 \epsilon_0 c^3} \int d\Omega [|\ddot{\vec{p}}|^2 - |\ddot{\vec{p}} \cdot \hat{r}|^2] \\ &= \frac{1}{32\pi^2 \epsilon_0 c^3} (4\pi |\ddot{\vec{p}}|^2 - \int d\Omega (\ddot{p}_i^* \alpha_i)(\ddot{p}_j \alpha_j)) \\ &= \frac{1}{32\pi^2 \epsilon_0 c^3} (4\pi |\ddot{\vec{p}}|^2 - \frac{4\pi}{3} \delta_{ij} \ddot{p}_i^* \ddot{p}_j) \\ &= \frac{|\ddot{\vec{p}}|^2}{12\pi \epsilon_0 c^3} \end{aligned}$$

匀速圆周运动点电荷:

$$\begin{aligned}
 \vec{p} &= eR(\hat{x} + i\hat{y})e^{-i\omega t} \\
 \vec{B} &= \frac{\mu_0 e^{ikr}}{4\pi cr} \ddot{\vec{p}} \times \hat{r} = \frac{e\omega^2 R}{4\pi\epsilon_0 c^3} \frac{-i\hat{\theta} + \cos\theta\hat{\phi}}{r} e^{i(kr-\omega t+\phi)} \\
 \vec{E} &= \frac{\mu_0 e^{ikr}}{4\pi r} (\ddot{\vec{p}} \times \hat{r}) \times \hat{r} = \frac{e\omega^2 R}{4\pi\epsilon_0 c^2} \frac{\cos\theta\hat{\theta} + i\hat{\phi}}{r} e^{i(kr-\omega t+\phi)} \\
 R &= \frac{E_\phi}{E_\theta} = \frac{i}{\cos\theta} \\
 \frac{d\langle P \rangle}{d\Omega} &= \frac{\mu_0}{32\pi^2 c} |\ddot{\vec{p}} \times \hat{r}|^2 = \frac{e^2 \omega^4 R^2}{32\pi^2 \epsilon_0 c^3} (1 + \cos^2 \theta) \\
 \langle P \rangle &= \frac{|\ddot{\vec{p}}|^2}{12\pi\epsilon_0 c^3} = \frac{e^2 \omega^4 R^2}{6\pi\epsilon_0 c^3}
 \end{aligned}$$

磁偶极辐射:

$$\begin{aligned}
 \vec{A}(\vec{r}, t) &= \frac{\mu_0 e^{ikr}}{4\pi cr} \dot{\vec{m}}(t) \\
 \vec{B} &= \frac{1}{c} \dot{\vec{A}} \times \hat{r} = \frac{\mu_0 e^{ikr}}{4\pi c^2 r} (\ddot{\vec{m}} \times \hat{r}) \times \hat{r} \\
 \vec{E} &= c\vec{B} \times \hat{r} = -\frac{\mu_0 e^{ikr}}{4\pi cr} \ddot{\vec{m}} \times \hat{r} \\
 \langle \vec{S} \rangle &= \frac{c}{2\mu_0} |\vec{B}|^2 \hat{r} = \frac{\mu_0}{32\pi^2 c^3 r^2} |\ddot{\vec{m}} \times \hat{r}|^2 \hat{r} \\
 \frac{d\langle P \rangle}{d\Omega} &= \frac{\mu_0}{32\pi^2 c^3} |\ddot{\vec{m}} \times \hat{r}|^2 \\
 \langle P \rangle &= \frac{\mu_0 |\ddot{\vec{m}}|^2}{12\pi c^3}
 \end{aligned}$$

电四极辐射:

$$\begin{aligned}
 \vec{A}(\vec{r}, t) &= \frac{\mu_0 e^{ikr}}{24\pi cr} \hat{r} \cdot \ddot{\vec{D}}(t) \\
 \vec{B} &= \frac{1}{c} \dot{\vec{A}} \times \hat{r} = \frac{\mu_0 e^{ikr}}{24\pi c^2 r} (\hat{r} \cdot \ddot{\vec{D}}) \times \hat{r} \\
 \vec{E} &= c\vec{B} \times \hat{r} = \frac{\mu_0 e^{ikr}}{24\pi cr} [(\hat{r} \cdot \ddot{\vec{D}}) \times \hat{r}] \times \hat{r} \\
 \langle \vec{S} \rangle &= \frac{c}{2\mu_0} |\vec{B}|^2 \hat{r} = \frac{\mu_0 \omega^6}{1152\pi^2 c^3 r^2} |(\hat{r} \cdot \ddot{\vec{D}}) \times \hat{r}|^2 \hat{r} \\
 \frac{d\langle P \rangle}{d\Omega} &= \frac{\mu_0 \omega^6}{1152\pi^2 c^3} |(\hat{r} \cdot \ddot{\vec{D}}) \times \hat{r}|^2 \\
 \langle P \rangle &= \frac{\mu_0 \omega^6}{1152\pi^2 c^3} \int d\Omega [(\hat{r} \cdot \ddot{\vec{D}}^*) \times \hat{r}] \cdot [(\hat{r} \cdot \ddot{\vec{D}}) \times \hat{r}] \\
 &= \frac{\mu_0 \omega^6}{1152\pi^2 c^3} \int d\Omega [\alpha_2^2 \alpha_3^2 (D_{22}^* - D_{33}^*)(D_{22} - D_{33}) \\
 &\quad + \alpha_3^2 \alpha_1^2 (D_{33}^* - D_{11}^*)(D_{33} - D_{11})]
 \end{aligned}$$

$$\begin{aligned}
& + \alpha_1^2 \alpha_2^2 (D_{11}^* - D_{22}^*)(D_{11} - D_{22})] \\
& (\alpha_1 = \sin \theta \cos \phi, \quad \alpha_2 = \sin \theta \sin \phi, \quad \alpha_3 = \cos \theta) \\
& = \frac{\mu_0 \omega^6}{1152 \pi^2 c^3} \frac{4\pi}{15} (D_{22}^* D_{22} + D_{33}^* D_{33} - D_{22}^* D_{33} - D_{33}^* D_{22} \\
& \quad + D_{33}^* D_{33} + D_{11}^* D_{11} - D_{33}^* D_{11} - D_{11}^* D_{33} \\
& \quad + D_{11}^* D_{11} + D_{22}^* D_{22} - D_{11}^* D_{22} - D_{22}^* D_{11}) \\
& = \frac{\mu_0 \omega^6}{1152 \pi^2 c^3} \frac{4\pi}{15} \{2(D_{11}^* D_{11} + D_{22}^* D_{22} + D_{33}^* D_{33}) \\
& \quad - [(D_{11}^* + D_{22}^* + D_{33}^*)(D_{11} + D_{22} + D_{33}) \\
& \quad - (D_{11}^* D_{11} + D_{22}^* D_{22} + D_{33}^* D_{33})]\} \\
& = \frac{\mu_0 \omega^6}{1152 \pi^2 c^3} \frac{4\pi}{5} \vec{D}^{\leftrightarrow *} : \vec{D} \\
& = \frac{\mu_0 \omega^6}{1440 \pi c^3} \vec{D}^{\leftrightarrow *} : \vec{D}
\end{aligned}$$

其中用了主轴坐标系来简化运算。

天线辐射：

$$\begin{aligned}
I(z, t) &= I_0 \sin k \left(\frac{l}{2} - |z| \right) e^{-i\omega t} \quad (|z| \leq \frac{l}{2}) \\
m &\triangleq \frac{l}{\lambda}, \quad I(z, t) = I_0 \sin(m\pi - k|z|) e^{-i\omega t} \\
\vec{A}(\vec{r}, t) &= \frac{\mu_0}{4\pi r} e^{ikr} \int dV' \vec{j}(\vec{r}', t) e^{-i\vec{k} \cdot \vec{r}'} \\
&= \hat{z} \frac{\mu_0}{4\pi r} e^{i(kr - \omega t)} \int_{-\frac{l}{2}}^{\frac{l}{2}} dz' I_0 \sin(m\pi - k|z'|) e^{-ikz' \cos \theta} \\
&= \hat{z} \frac{\mu_0 I_0}{4\pi kr} e^{i(kr - \omega t)} \int_0^{m\pi} d\xi 2 \sin(m\pi - \xi) \cos(\xi \cos \theta) \\
&= \hat{z} \frac{\mu_0 I_0}{2\pi kr} e^{i(kr - \omega t)} \frac{\cos(m\pi \cos \theta) - \cos m\pi}{\sin^2 \theta} \\
\vec{B} = i\vec{k} \times \vec{A} &= -i \frac{\mu_0 I_0}{2\pi r} e^{i(kr - \omega t)} \frac{\cos(m\pi \cos \theta) - \cos m\pi}{\sin \theta} \hat{\phi} = -i \frac{\mu_0 I_0}{2\pi r} e^{i(kr - \omega t)} g(\theta) \hat{\phi} \\
\vec{E} = c\vec{B} \times \hat{r} &= -i \frac{\mu_0 c I_0}{2\pi r} e^{i(kr - \omega t)} \frac{\cos(m\pi \cos \theta) - \cos m\pi}{\sin \theta} \hat{\theta} = -i \frac{\mu_0 c I_0}{2\pi r} e^{i(kr - \omega t)} g(\theta) \hat{\theta} \\
\frac{d\langle P \rangle}{d\Omega} &= \frac{c}{2\mu_0} |\vec{B}|^2 r^2 = \frac{\mu_0 c I_0^2}{8\pi^2} g^2(\theta) \\
\langle P \rangle &= \frac{\mu_0 c I_0^2}{4\pi} \int_0^\pi g^2(\theta) \sin \theta d\theta \triangleq \frac{1}{2} I_0^2 R_0 \triangleq \frac{1}{2} I_{max}^2 R_r \\
R_0 &\triangleq \frac{\mu_0 c}{2\pi} \int_0^\pi g^2(\theta) \sin \theta d\theta \\
&= \frac{\mu_0 c}{2\pi} \int_{-1}^1 \frac{[\cos(m\pi u) - \cos(m\pi)]^2}{1 - u^2} du
\end{aligned}$$

由于 $I(z, t) = I_0 \sin(m\pi - k|z|)e^{-i\omega t}$, 故

$$\begin{aligned} m \geq \frac{1}{2} &\implies I_{\max} = I_0 \implies R_r = R_0 \\ m < \frac{1}{2} &\implies I_{\max} = I_0 \sin m\pi \implies R_r = \frac{R_0}{\sin^2 m\pi} \\ m \ll \frac{1}{2} &\implies I_{\max} = I_0 m\pi \implies R_r = \frac{R_0}{m^2 \pi^2} \end{aligned}$$

$$m \ll \frac{1}{2} \text{ 时, } R_r = \frac{R_0}{m^2 \pi^2} = \dots \approx 20 m^2 \pi^2 \approx 197 \left(\frac{l}{\lambda}\right) \Omega$$

7 运动电荷的辐射

$$\begin{aligned} \vec{r}(t) &= \vec{w}(t) \\ \phi(\vec{r}, t) &= e\delta(\vec{r} - \vec{w}(t)) \\ \vec{j}(\vec{r}, t) &= e\vec{v}(t)\delta(\vec{r} - \vec{w}(t)) \\ \phi(\vec{r}, t) &= \frac{1}{4\pi\epsilon_0} \int dV' \frac{\rho(\vec{r}', t_r)}{\mathbb{R}} = \frac{e}{4\pi\epsilon_0} \int dV' \frac{\delta(\vec{r}' - \vec{w}(t_r))}{\mathbb{R}} \\ \vec{A}(\vec{r}, t) &= \frac{\mu_0}{4\pi} \int dV' \frac{\vec{j}(\vec{r}', t_r)}{\mathbb{R}} = \frac{e}{4\pi\epsilon_0 c^2} \int dV' \frac{\vec{v}(t_r)\delta(\vec{r}' - \vec{w}(t_r))}{\mathbb{R}} \end{aligned}$$

坐标变换:

$$\begin{aligned} \vec{r}' &\rightarrow \vec{r}'' = \vec{r}' - \vec{w}(t_r) \\ J &\triangleq \frac{\partial(x'_1, x'_2, x'_3)}{\partial(x''_1, x''_2, x''_3)} = \det(\nabla' \vec{r}'') \\ &= \det[\nabla'(\vec{r}' - \vec{w}(t_r))] \\ &= \det(\vec{I} - \frac{\hat{\mathbb{R}}}{c} \vec{v}(t_r)) \\ &= 1 - \hat{\mathbb{R}} \cdot \vec{\beta} > 0 \end{aligned}$$

Lienard-Wechert 势:

$$\begin{aligned} \phi(\vec{r}, t) &= \frac{1}{4\pi\epsilon_0} \int dV' \frac{\rho(\vec{r}', t_r)}{\mathbb{R}} = \frac{e}{4\pi\epsilon_0} \int dV'' \frac{\delta(\vec{r}'')}{|J|\mathbb{R}} \\ &= \frac{e}{4\pi\epsilon_0 \mathbb{R}} \frac{1}{1 - \hat{\mathbb{R}} \cdot \vec{\beta}} \Big|_{\vec{r}''=0} \\ &= \frac{e}{4\pi\epsilon_0 \mathbb{R}^*} \frac{1}{1 - \hat{\mathbb{R}}^* \cdot \vec{\beta}^*} \\ \vec{A}(\vec{r}, t) &= \frac{\vec{v}^*}{c^2} \phi(\vec{r}, t) = \frac{\vec{\beta}^*}{c} \phi(\vec{r}, t) \end{aligned}$$

* 号满足:

$$|\vec{r} - \vec{w}(t^*)| = c(t - t^*) = c\Delta t > 0 \implies t^* = t^*(\vec{r}, t)$$

有时把 Δt 看作未知量取正解比较方便。

$$\vec{\mathbb{R}}^* = \vec{r} - \vec{w}(t^*) = \vec{\mathbb{R}}^*(\vec{r}, t)$$

$$\mathbb{R}^* = c(t - t^*) = \mathbb{R}^*(\vec{r}, t)$$

\vec{n}^* :

$$\vec{n}^* \triangleq \hat{\mathbb{R}}^* - \vec{\beta}^*$$

$$\phi(\vec{r}, t) = \frac{e}{4\pi\epsilon_0} \frac{1}{\vec{\mathbb{R}}^* \cdot \vec{n}^*}$$

$$\vec{\mathbb{R}}^* \cdot \vec{n}^* = \hat{\mathbb{R}}^* \cdot (\mathbb{R}^* \hat{\mathbb{R}}^* - \mathbb{R}^* \vec{\beta}^*) = \hat{\mathbb{R}}^* \cdot (c\Delta t \hat{\mathbb{R}}^* - \vec{v}^* \Delta t)$$

从中可以看出 $\mathbb{R}^* \vec{n}^*$ 表示这样一个矢量：由推迟时刻做匀速运动在 t 时刻到达的点指向场点。

t^* 只有一个解：

$$\begin{cases} c(t - t_1^*) = \mathbb{R}_1^* \\ c(t - t_2^*) = \mathbb{R}_2^* \end{cases}$$

$$\Rightarrow c|t_1^* - t_2^*| = |\mathbb{R}_1^* - \mathbb{R}_2^*| \leq |\vec{\mathbb{R}}_1^* - \vec{\mathbb{R}}_2^*| \leq \Delta s = \langle v \rangle |t_1^* - t_2^*| < c|t_1^* - t_2^*|$$

匀速运动点电荷：

$$\phi(\vec{r}, t) = \frac{e}{4\pi\epsilon_0 R} \frac{1}{\sqrt{1 - \beta^2 \sin^2 \theta}}$$

$$\vec{A}(\vec{r}, t) = \frac{\vec{\beta}}{c} \phi(\vec{r}, t)$$

其中 R 为 t 时刻的相对位矢的模长。

电磁场的计算：

t^* 的导数：

$$\begin{cases} \partial_t(\mathbb{R}^{*2}) = 2\mathbb{R}^* \partial_t \mathbb{R}^* = 2\mathbb{R}^* c(1 - \partial_t t^*) \\ \partial_t(\vec{\mathbb{R}}^* \cdot \vec{\mathbb{R}}^*) = 2\vec{\mathbb{R}}^* \cdot \partial_t \vec{\mathbb{R}}^* = -2\vec{\mathbb{R}}^* \cdot \vec{v}^* \partial_t t^* \end{cases} \Rightarrow \partial_t t^* = \frac{\mathbb{R}^*}{\vec{\mathbb{R}}^* \cdot \vec{n}^*}$$

$$\begin{cases} \nabla(\mathbb{R}^{*2}) = \dots \\ \nabla(\vec{\mathbb{R}}^* \cdot \vec{\mathbb{R}}^*) = \dots \end{cases} \Rightarrow \nabla t^* = -\frac{\vec{\mathbb{R}}^*}{c \vec{\mathbb{R}}^* \cdot \vec{n}^*}$$

$$\nabla t^* = -\frac{\hat{\mathbb{R}}^*}{c} \partial_t t^*$$

$\vec{\mathbb{R}}^* \cdot \vec{n}^*$ 的导数:

$$\begin{aligned}\partial_t(\vec{\mathbb{R}}^* \cdot \vec{n}^*) &= \partial_t(\mathbb{R}^* - \vec{\mathbb{R}}^* \cdot \vec{\beta}^*) = \dots = c - (1 - \beta^{*2} + \frac{\vec{\mathbb{R}}^* \cdot \vec{a}^*}{c^2})c\partial_t t^* \\ \nabla(\vec{\mathbb{R}}^* \cdot \vec{n}^*) &= \dots = -\vec{\beta}^* - (1 - \beta^{*2} + \frac{\vec{\mathbb{R}}^* \cdot \vec{a}^*}{c^2})c\nabla t^* \\ &= -\vec{\beta}^* + (1 - \beta^{*2} + \frac{\vec{\mathbb{R}}^* \cdot \vec{a}^*}{c^2})\hat{\mathbb{R}}^*\partial_t t^* \\ &= \vec{n}^* - \frac{\hat{\mathbb{R}}^*}{c}\partial_t(\vec{\mathbb{R}}^* \cdot \vec{n}^*)\end{aligned}$$

Lienard-Wiechert 场;

$$\begin{aligned}\vec{E} &= -\nabla\phi - \partial_t\vec{A} = -\nabla\phi - \frac{\vec{\beta}^*}{c}\partial_t\phi - \frac{\phi}{c}\partial_t\vec{\beta}^* \\ &= \dots = \frac{e}{4\pi\epsilon_0} \frac{1}{(\vec{\mathbb{R}}^* \cdot \vec{n}^*)^2} \left[(1 - \beta^{*2} + \frac{\vec{\mathbb{R}}^* \cdot \vec{a}^*}{c^2})\vec{n}^* - \frac{\vec{\mathbb{R}}^* \cdot \vec{n}^*}{c^2}\vec{a}^* \right] \partial_t t^* \\ &= \frac{e}{4\pi\epsilon_0} \frac{\mathbb{R}^*}{(\vec{\mathbb{R}}^* \cdot \vec{n}^*)^3} \left[(1 - \beta^{*2})\vec{n}^* + \frac{\vec{\mathbb{R}}^* \times (\vec{n}^* \times \vec{a}^*)}{c^2} \right] \\ c\vec{B} &= \nabla \times (c\vec{A}) = \nabla \times (\vec{\beta}^* \phi) \\ &= \dots = \frac{e}{4\pi\epsilon_0(\vec{\mathbb{R}}^* \cdot \vec{n}^*)^2} \left[-\nabla(\vec{\mathbb{R}}^* \cdot \vec{n}^*) \times \vec{\beta}^* + \frac{\vec{\mathbb{R}}^* \cdot \vec{n}^*}{c} \nabla t^* \times \vec{a}^* \right] \\ &= \hat{\mathbb{R}}^* \times \frac{e}{4\pi\epsilon_0} \frac{1}{(\vec{\mathbb{R}}^* \cdot \vec{n}^*)^2} \left[(1 - \beta^{*2} + \frac{\vec{\mathbb{R}}^* \cdot \vec{a}^*}{c^2})(\vec{n}^* - \hat{\mathbb{R}}^*) - \frac{\vec{\mathbb{R}}^* \cdot \vec{n}^*}{c^2}\vec{a}^* \right] \partial_t t^* \\ &= \hat{\mathbb{R}}^* \times \frac{e}{4\pi\epsilon_0} \frac{1}{(\vec{\mathbb{R}}^* \cdot \vec{n}^*)^2} \left[(1 - \beta^{*2} + \frac{\vec{\mathbb{R}}^* \cdot \vec{a}^*}{c^2})\vec{n}^* - \frac{\vec{\mathbb{R}}^* \cdot \vec{n}^*}{c^2}\vec{a}^* \right] \partial_t t^* \\ &= \hat{\mathbb{R}}^* \times \vec{E}(\vec{r}, t)\end{aligned}$$

可见 $\vec{E} \cdot \vec{B} = 0, \hat{\mathbb{R}}^* \cdot \vec{B} = 0$, 但一般 $\vec{E} \cdot \hat{\mathbb{R}}^* \neq 0$ 。 $c|\vec{B}| \leq \vec{E}$, 从而 $w_B \leq w_E$ 。

速度场与加速度场:

$$\begin{aligned}\vec{E}_v &= \frac{e}{4\pi\epsilon_0} \frac{\mathbb{R}^*}{(\vec{\mathbb{R}}^* \cdot \vec{n}^*)^3} (1 - \beta^{*2})\vec{n}^* \\ \vec{E}_a &= \frac{e}{4\pi\epsilon_0} \frac{\mathbb{R}^*}{(\vec{\mathbb{R}}^* \cdot \vec{n}^*)^3} \frac{\vec{\mathbb{R}}^* \times (\vec{n}^* \times \vec{a}^*)}{c^2} \\ c\vec{B}_v &= \hat{\mathbb{R}}^* \times \vec{E}_v, \quad c\vec{B}_a = \hat{\mathbb{R}}^* \times \vec{E}_a\end{aligned}$$

可见 $\vec{E}_v, \vec{B}_v \sim \frac{1}{\mathbb{R}^{*2}}$, 而 $\vec{E}_a, \vec{B}_a \sim \frac{1}{\mathbb{R}^*}$, 从而辐射场是加速度场。

和之前相比, 此时 $\vec{E}_a \cdot \vec{B}_a = 0, \hat{\mathbb{R}}^* \cdot \vec{B}_a = 0, \hat{\mathbb{R}}^* \cdot \vec{E}_a = 0$, 同时 $c|\vec{B}_a| = \vec{E}_a, w_B = w_E$ 。

点电荷的辐射:

$$\begin{aligned}\vec{E} &= \frac{e}{4\pi\epsilon_0 c^2 \mathbb{R}^*} \frac{\hat{\mathbb{R}}^* \times (\vec{n}^* \times \vec{a}^*)}{(\hat{\mathbb{R}}^* \cdot \vec{n}^*)^3} \\ c\vec{B} &= \hat{\mathbb{R}} \times \vec{E} \\ w = \epsilon_0 E^2 &= \frac{e^2}{16\pi^2 \epsilon_0 c^4 \mathbb{R}^{*2}} \frac{|\hat{\mathbb{R}}^* \times (\vec{n}^* \times \vec{a}^*)|^2}{(\hat{\mathbb{R}}^* \cdot \vec{n}^*)^6} \\ \vec{S} &= \frac{1}{\mu_0} \vec{E} \times \vec{B} = wc\hat{\mathbb{R}}^*\end{aligned}$$

功率计算:

接收者:

$$\begin{aligned}\frac{dP}{d\Omega}|_{receiver} &= \frac{dW}{dt d\Omega} = \frac{S \mathbb{R}^{*2} d\Omega dt}{dt d\Omega} \\ &= S \mathbb{R}^{*2} = \frac{e^2}{16\pi^2 \epsilon_0 c^3} \frac{|\hat{\mathbb{R}}^* \times (\vec{n}^* \times \vec{a}^*)|^2}{(\hat{\mathbb{R}}^* \cdot \vec{n}^*)^6}\end{aligned}$$

发射者:

$$\begin{aligned}\frac{dP}{d\Omega}|_{launcher} &= \frac{dW}{dt^* d\Omega} = \frac{w \mathbb{R}^{*2} d\Omega (\mathbb{R}^* - \mathbb{R}^{*'} - v^* dt^* \cos \theta)}{dt^* d\Omega} \\ &= \frac{w \mathbb{R}^{*2} d\Omega (dt^* - v^* dt^* \cos \theta)}{dt^* d\Omega} \\ &= \frac{w \mathbb{R}^{*2} d\Omega c dt^* \hat{\mathbb{R}}^* \cdot \vec{n}^*}{dt^* d\Omega} \\ &= wc \mathbb{R}^{*2} (\hat{\mathbb{R}}^* \cdot \vec{n}^*) \\ &= \frac{dP}{d\Omega}|_{receiver} (\hat{\mathbb{R}}^* \cdot \vec{n}^*) = \frac{dt}{dt^*} \frac{dP}{d\Omega}|_{receiver}\end{aligned}$$

低速运动粒子的辐射:

$$\begin{aligned}\beta &<< 1 \\ \vec{n} &= \hat{\mathbb{R}}^* - \vec{\beta}^* \approx \hat{\mathbb{R}}^*, \hat{\mathbb{R}}^* \cdot \vec{n}^* \approx 1 \\ \hat{\mathbb{R}}^* \times (\vec{n}^* \times \vec{a}^*) &\approx \hat{\mathbb{R}}^* \times (\hat{\mathbb{R}}^* \times \vec{a}^*) = a^* \sin \theta \hat{\theta} \\ (\theta &= \angle(\hat{\mathbb{R}}^*, \vec{a}^*)) \\ \frac{dP}{d\Omega}|_{launcher} &\approx \frac{dP}{d\Omega}|_{receiver} = \frac{e^2 a^{*2} \sin^2 \theta}{16\pi^2 \epsilon_0 c^3} = \frac{e_s^2 a^{*2} \sin^2 \theta}{4\pi c^3} \\ P &= \int d\Omega \frac{dP}{d\Omega} = \frac{2e_s^2 a^{*2}}{3c^3}\end{aligned}$$

相对论性粒子的辐射:

$$\begin{aligned}\hat{\mathbb{R}}^* \cdot \vec{n}^* &= 1 - \beta^* \cos \theta \\ (\theta &= \angle(\hat{\mathbb{R}}^*, \vec{\beta}^*))\end{aligned}$$

速度与加速度平行:

$$\begin{aligned}\hat{\mathbf{R}}^* \times (\vec{\mathbf{n}}^* \times \vec{\mathbf{a}}_{//}^*) &= \hat{\mathbf{R}}^* \times (\hat{\mathbf{R}}^* \times \vec{\mathbf{a}}_{//}^*) = a_{//}^* \sin \theta \hat{\boldsymbol{\theta}} \\ \frac{dP_{//}}{d\Omega}|_{\text{launcher}} &= \frac{e^2}{16\pi^2\epsilon_0 c^3} \frac{|\hat{\mathbf{R}}^* \times (\vec{\mathbf{n}}^* \times \vec{\mathbf{a}}_{//}^*)|^2}{(\hat{\mathbf{R}}^* \cdot \vec{\mathbf{n}}^*)^5} = \frac{e_S^2 a_{//}^{*2}}{4\pi c^3} \frac{\sin^2 \theta}{(1 - \beta \cos \theta)^5}\end{aligned}$$

角度因子 $g_{//}(\theta) = \frac{\sin^2 \theta}{(1 - \beta \cos \theta)^5}$, $\beta \rightarrow 1$ 时, 辐射主要集中在 θ 较小的方向。

$$P_{//} = \int d\Omega \frac{dP_{//}}{d\Omega} = \dots = \frac{2e_S^2 a_{//}^{*2}}{3c^3} \gamma^6$$

速度与加速度垂直:

$$\begin{aligned}\vec{\mathbf{a}}_{\perp}^* &= a_{\perp}^* \hat{\mathbf{x}}, \vec{\boldsymbol{\beta}}^* = \beta^* \hat{\mathbf{z}} \\ \hat{\mathbf{R}}^* \times (\vec{\mathbf{n}}^* \times \vec{\mathbf{a}}_{\perp}^*) &= (\hat{\mathbf{R}}^* \cdot \vec{\mathbf{a}}_{\perp}^*) \hat{\mathbf{R}}^* - a_{\perp}^* \hat{\mathbf{x}} - \beta a_{\perp}^* \hat{\mathbf{R}}^* \times \hat{\mathbf{y}} \\ &= \dots \\ &= (-a_{\perp}^* \cos \theta \cos \phi + \beta^* a_{\perp}^* \cos \phi) \hat{\boldsymbol{\theta}} \\ &\quad + (a_{\perp}^* \sin \phi - \beta^* a_{\perp}^* \cos \theta \sin \phi) \hat{\boldsymbol{\phi}} \\ |\hat{\mathbf{R}}^* \times (\vec{\mathbf{n}}^* \times \vec{\mathbf{a}}_{\perp}^*)|^2 &= \dots = a_{\perp}^{*2} [(1 - \beta^* \cos \theta)^2 - (1 - \beta^{*2}) \sin^2 \theta \cos^2 \phi] \\ \frac{dP_{\perp}}{d\Omega}|_{\text{launcher}} &= \frac{e_S^2 a_{\perp}^{*2}}{4\pi c^3} \frac{(1 - \beta^* \cos \theta)^2 - (1 - \beta^{*2}) \sin^2 \theta \cos^2 \phi}{(1 - \beta^* \cos \theta)^5}\end{aligned}$$

角度因子 $g_{\perp}(\theta, \phi) = \frac{(1 - \beta^* \cos \theta)^2 - (1 - \beta^{*2}) \sin^2 \theta \cos^2 \phi}{(1 - \beta^* \cos \theta)^5}$, $\theta = 0$ 时辐射最强:

$$g_{\perp}(\theta, \phi) \leq g_{\perp}(\theta, \frac{\pi}{2}) = g_{\perp}(\theta, \frac{3\pi}{2}) \leq g_{\perp}(0, \phi)$$

$$P_{\perp} = \int d\Omega \frac{dP_{\perp}}{d\Omega} = \dots = \frac{2e_S^2 a_{\perp}^{*2}}{3c^3} \gamma^4$$

一般情形的加速度:

$$\begin{aligned}\hat{\mathbf{R}}^* \times (\vec{\mathbf{n}}^* \times \vec{\mathbf{a}}^*) &= a_{//}^* \sin \theta \hat{\boldsymbol{\theta}} \\ &\quad + (-a_{\perp}^* \cos \theta \cos \phi + \beta^* a_{\perp}^* \cos \phi) \hat{\boldsymbol{\theta}} \\ &\quad + (a_{\perp}^* \sin \phi - \beta^* a_{\perp}^* \cos \theta \sin \phi) \hat{\boldsymbol{\phi}} \\ \frac{dP}{d\Omega}|_{\text{launcher}} &= \frac{dP_{//}}{d\Omega}|_{\text{launcher}} + \frac{dP_{\perp}}{d\Omega}|_{\text{launcher}} + \frac{e^2 a_{//}^* a_{\perp}^* (\beta - \cos \theta) \sin \theta \cos \phi}{2\pi c^3 (1 - \beta \cos \theta)^5}\end{aligned}$$

交叉项有 $\cos \phi$, 积分后为 0:

$$\begin{aligned}P &= \int d\Omega \frac{dP}{d\Omega} = P_{//} + P_{\perp} = \frac{2e_S^2}{3c^3} \gamma^6 [a_{//}^{*2} + \frac{a_{\perp}^{*2}}{\gamma^2}] \\ &= \frac{2e_S^2}{3c^3} \gamma^6 [a^{*2} - |\vec{\boldsymbol{\beta}}^* \times \vec{\mathbf{a}}^*|^2] \\ &= \frac{2e_S^2 a^{*2}}{3c^3} \gamma^6 [1 - |\vec{\boldsymbol{\beta}}^* \times \hat{\mathbf{a}}^*|^2] \\ &\quad (\text{Lienard formula})\end{aligned}$$

8 狭义相对论

Einstein 假设:

相对性原理: 物理定律在所有惯性系中具有相同的形式。

光速普适原理: 真空中光速对所有惯性系具有相同的数值。

洛伦兹变换:

4-位矢:

$$x^\alpha \triangleq (x^0, x^1, x^2, x^3) = (ct, x, y, z) = (ct, \vec{r})$$

洛伦兹度规 $g_{\alpha\beta}$ 及其逆 $g^{\alpha\beta}$:

$$g_{\alpha\beta} = g^{\alpha\beta} = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

$$g^{\alpha\gamma} g_{\gamma\beta} = \delta^\alpha_\beta$$

$$g_{\alpha\rho} T^{\dots\rho\dots} = T^{\dots\alpha\dots}, \quad g^{\alpha\rho} T_{\dots\rho\dots} = T_{\dots\alpha\dots}$$

$$\text{时空间隔: } \Delta s^2 \triangleq g_{\alpha\beta} \Delta x^\alpha \Delta x^\beta$$

坐标变换的性质:

$$\text{时空均匀性} \implies \text{变换是线性的: } x'^\alpha = \Lambda^\alpha_\beta x^\beta + a^\alpha$$

光速普适; 空间各向同性; 变换回本参考系连续性 \implies 时空间隔不变

$$g_{\alpha\beta} \Lambda^\alpha_\rho \Lambda^\beta_\sigma = g_{\rho\sigma} \quad (\Lambda^T g \Lambda = g)$$

(1) 由于 $g_{\alpha\beta}$ 的对称性, 分量方程有 10 个是独立的。 Λ^α_β 有 6 个独立参数。

$$(2) \Lambda^T g \Lambda = g \implies \det(\Lambda) = \pm 1$$

庞加莱变换: $x'^\alpha = \Lambda^\alpha_\beta x^\beta + a^\alpha$ (10 个参数)

洛伦兹变换: $x'^\alpha = \Lambda^\alpha_\beta x^\beta$ (6 个参数)

(在洛伦兹变换下, 由于时空间隔不变可得到标量积 ($\triangleq g_{\alpha\beta} x^\alpha y^\beta$) 为一不变量。)

几个坐标变换:

$$\begin{aligned}x'^{\alpha} &= \Lambda^{\alpha}_{\beta} x^{\beta}, & x^{\alpha} &= \Lambda^{\alpha}_{\beta} x'^{\beta} \\x'_{\alpha} &= \Lambda^{\beta}_{\alpha} x_{\beta}, & x_{\alpha} &= \Lambda^{\beta}_{\alpha} x'_{\beta} \\(x^{\alpha} &= \Lambda^{\alpha}_{\beta} x'^{\beta}, & ds^2 = ds'^2 &\implies \Lambda g \Lambda^T = g)\end{aligned}$$

(这没有增加独立方程的个数, 因为 $\Lambda^T g \Lambda = g$ 已经蕴含了这点: $\Lambda^T g \Lambda = g \implies g \Lambda = (\Lambda^T)^{-1} g \implies \Lambda g = g (\Lambda^T)^{-1} \implies g \Lambda^T = \Lambda^{-1} g \implies \Lambda g \Lambda^T = g$)

无穷小洛伦兹变换:

$$\begin{aligned}\Lambda^{\alpha}_{\beta} &= \delta^{\alpha}_{\beta} + \Omega^{\alpha}_{\beta} \\g_{\rho\sigma} &= g_{\alpha\beta} \Lambda^{\alpha}_{\rho} \Lambda^{\beta}_{\sigma} = g_{\alpha\beta} (\delta^{\alpha}_{\rho} + \Omega^{\alpha}_{\rho}) (\delta^{\beta}_{\sigma} + \Omega^{\beta}_{\sigma}) \approx g_{\rho\sigma} + g_{\rho\beta} \Omega^{\beta}_{\sigma} + g_{\alpha\sigma} \Omega^{\alpha}_{\rho} \\&\implies \begin{cases} \Omega_{\rho\sigma} = -\Omega_{\sigma\rho} \\ \Omega^T = -g \Omega g \quad (\Omega = (\Omega^{\alpha}_{\beta})) \end{cases} \\ \Lambda^{\alpha}_{\beta} &= \delta^{\alpha}_{\beta} + g^{\alpha\rho} \Omega_{\rho\beta}\end{aligned}$$

两个推论:

(1)

$$\Omega_{\rho\sigma} = -\Omega_{\sigma\rho} \implies \Lambda = \begin{pmatrix} 1 & -\xi_1 & -\xi_2 & -\xi_3 \\ -\xi_1 & 1 & -\theta n_3 & \theta n_2 \\ -\xi_2 & \theta n_3 & 1 & -\theta n_1 \\ -\xi_3 & -\theta n_2 & \theta n_1 & 1 \end{pmatrix}$$

其中 $\xi_1, \xi_2, \xi_3, \theta, n_1, n_2, n_3 (n_1^2 + n_2^2 + n_3^2 = 1)$ 为 6 个参数。

$$\begin{pmatrix} ct' \\ \vec{r}' \end{pmatrix} = \Lambda \begin{pmatrix} ct \\ \vec{r} \end{pmatrix} = \begin{pmatrix} ct - \vec{\xi} \cdot \vec{r} \\ \vec{r} - \vec{\xi} ct + \theta \hat{n} \times \vec{r} \end{pmatrix}$$

$\vec{\xi} = 0$: 转动; $\theta = 0$: 推动。

(2)

$$\begin{aligned}\Omega^T &= -g \Omega g \implies e^{\Omega^T} = e^{-g \Omega g} = \sum_{n=0}^{\infty} \frac{(-1)^n}{n!} (g \Omega g)^n = g e^{-\Omega} g \\&\implies e^{\Omega^T} g e^{\Omega} = g, \quad e^{\Omega} \in \{\Lambda | \Lambda^T g \Lambda = g\}\end{aligned}$$

事实上, $\forall \Lambda \in \{\Lambda | \Lambda^T g \Lambda = g\}$, 可以写为 e^Ω 的形式。粗糙理解: 同被 6 个参数描述, 存在一个对应, 由参数连续性, 一一对应。

$$\Omega = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \theta \Rightarrow e^\Omega = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \theta & \sin \theta & 0 \\ 0 & -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\Omega = \begin{pmatrix} 0 & -1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \xi \Rightarrow e^\Omega = \begin{pmatrix} \cosh \xi & -\sinh \xi & 0 & 0 \\ -\sinh \xi & \cosh \xi & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

沿 x 方向运动的洛伦兹变换及反变换:

$$\begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \gamma & -\beta\gamma & 0 & 0 \\ -\beta\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$$

$$\begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \gamma & \beta\gamma & 0 & 0 \\ \beta\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix}$$

写为矢量形式:

$$\begin{pmatrix} ct' \\ \vec{r}'_{//} \\ \vec{r}'_{\perp} \end{pmatrix} = \begin{pmatrix} \gamma(ct - \vec{\beta} \cdot \vec{r}) \\ \gamma(\vec{r}_{//} - \vec{\beta}ct) \\ \vec{r}_{\perp} \end{pmatrix}$$

$$\begin{pmatrix} ct \\ \vec{r}_{//} \\ \vec{r}_{\perp} \end{pmatrix} = \begin{pmatrix} \gamma(ct' + \vec{\beta} \cdot \vec{r}') \\ \gamma(\vec{r}'_{//} + \vec{\beta}ct') \\ \vec{r}'_{\perp} \end{pmatrix}$$

速度变换:

$$\begin{cases} \beta_x = \frac{dx}{cdt} = \frac{\beta'_x + \beta_0}{1 + \beta_0\beta'_x} \\ \beta_{y,z} = \frac{dy,z}{cdt} = \frac{\beta'_{y,z}}{\gamma_0(1 + \beta_0\beta'_x)} \end{cases} \quad \begin{cases} \beta'_x = \frac{dx}{cdt} = \frac{\beta_x - \beta_0}{1 - \beta_0\beta'_x} \\ \beta'_{y,z} = \frac{dy,z}{cdt} = \frac{\beta_{y,z}}{\gamma_0(1 - \beta_0\beta'_x)} \end{cases}$$

加速度变换:

$$\begin{cases} a_x = \frac{1}{\gamma_0(1 + \beta_0\beta'_x)} \left[\frac{a'_x}{1 + \beta_0\beta'_x} - \frac{(\beta'_x + \beta_0)\beta_0 a'_x}{(1 + \beta_0\beta'_x)^2} \right] \\ a_{y,z} = \frac{1}{\gamma_0^2(1 + \beta_0\beta'_x)} \left[\frac{a'_y}{1 + \beta_0\beta'_x} - \frac{\beta'_y\beta_0 a'_x}{(1 + \beta_0\beta'_x)^2} \right] \end{cases} \quad \begin{cases} a'_x = \dots \\ a'_y = \dots \end{cases}$$

瞬时惯性系 (MCRF):

在这个参考系中 $\beta' = 0$, 有时便于计算一些参考系无关量。加速度变换在 MCRF 里有较简单的形式:

$$a_x = \frac{a'_x}{\gamma_0^3}, \quad a_y = \frac{a'_y}{\gamma_0^2}, \quad a_z = \frac{a'_z}{\gamma_0^2}$$

事件分类:

$\Delta s^2 < 0$: 类时间隔, 可找到标架使两者同地发生。

$\Delta s^2 = 0$: 类光间隔

$\Delta s^2 > 0$: 类空间隔, 可找到标架使两者同时发生。

原时 $d\tau$:

物体自身系中时钟走时, 又称固有时。

$$ds^2 = 0 - (cd\tau)^2, \quad d\tau = \frac{\sqrt{-ds^2}}{c}$$

由时空间隔不变性, 质点在时空图上轨迹的长度 $\int \sqrt{-ds^2} = c\Delta\tau$

一些 4-矢量:

导数算符:

$$\begin{aligned} \partial_\alpha &\triangleq \left(\frac{1}{c} \frac{\partial}{\partial t}, \nabla \right) \\ \partial'_\alpha &= \Lambda_\alpha^\rho \partial_\rho \\ \square &= \partial_\alpha \partial^\alpha = -\frac{1}{c^2} \partial^2 t + \nabla^2 \end{aligned}$$

标量积为 4 不变量, 故达朗贝尔算子是 4 维不变的。

4-速度:

$$\begin{aligned} U^\alpha &\triangleq \frac{dx^\alpha}{d\tau} = \gamma(c, \vec{u}) \\ U'^\alpha &= \Lambda^\alpha_\beta U^\beta \\ U^\alpha U_\alpha &= -c^2 \end{aligned}$$

4-加速度:

$$\begin{aligned} A^\alpha &\triangleq \frac{dU^\alpha}{d\tau} = \gamma^4 (\vec{\beta} \cdot \vec{a}, \frac{\vec{a}}{\gamma^2} + (\vec{\beta} \cdot \vec{a}) \vec{\beta}) \\ A'^\alpha &= \Lambda^\alpha_\beta A^\beta \\ A^\alpha A_\alpha &= A^\alpha A_\alpha \text{ in MCRF} = a'^2 \\ 0 &= \frac{d(U^\alpha U_\alpha)}{d\tau} = \frac{dU_\alpha}{d\tau} U^\alpha + \frac{dU^\alpha}{d\tau} U_\alpha = 2U_\alpha \frac{dU^\alpha}{d\tau} = 2U_\alpha A^\alpha \end{aligned}$$

4-动量:

$$P^\alpha \triangleq mU^\alpha = (\gamma mc, \gamma m \vec{u}) = \left(\frac{\epsilon}{c}, \vec{p}\right)$$

$$P'^\alpha = \Lambda^\alpha_\beta P^\beta$$

$$P^\alpha P_\alpha = p^2 - \frac{\epsilon^2}{c^2} = P^\alpha P_\alpha \text{ in MCRF} = -m^2 c^2$$

对于无质量粒子, $P^\alpha = \hbar\left(\frac{\omega}{c}, \vec{k}\right) = \hbar k^\alpha$ 。

4-张量:

$$T'^{\alpha_1 \cdots \alpha_n}_{\beta_1 \cdots \beta_n} = \Lambda^{\alpha_1}_{\rho_1} \cdots \Lambda^{\alpha_n}_{\rho_n} \Lambda^{\sigma_1}_{\beta_1} \cdots \Lambda^{\sigma_n}_{\beta_n} T^{\rho_1 \cdots \rho_n}_{\sigma_1 \cdots \sigma_n}$$

二阶张量可以写为:

$$\begin{pmatrix} \phi & \vec{p} \\ \vec{q} & T \end{pmatrix}$$

Leci-Civita 符号:

$$\epsilon^{\alpha\beta\mu\nu} = \begin{vmatrix} \delta^\alpha_0 & \delta^\alpha_1 & \delta^\alpha_2 & \delta^\alpha_3 \\ \delta^\beta_0 & \delta^\beta_1 & \delta^\beta_2 & \delta^\beta_3 \\ \delta^\mu_0 & \delta^\mu_1 & \delta^\mu_2 & \delta^\mu_3 \\ \delta^\nu_0 & \delta^\nu_1 & \delta^\nu_2 & \delta^\nu_3 \end{vmatrix}$$

反对称张量 $A^{\alpha\beta}$ 的对偶张量:

$$A^{*\alpha\beta} \triangleq \frac{1}{2!} \epsilon^{\alpha\beta\mu\nu} A_{\mu\nu}$$

$$(A^{\alpha\beta}) = \begin{pmatrix} 0 & p_1 & p_2 & p_3 \\ -p_1 & 0 & a_3 & -a_2 \\ -p_2 & -a_3 & 0 & a_1 \\ -p_3 & a_2 & -a_1 & 0 \end{pmatrix} \triangleq \{\vec{p}, \vec{a}\}$$

$$(A_{\alpha\beta}) = \begin{pmatrix} 0 & -p_1 & -p_2 & -p_3 \\ p_1 & 0 & a_3 & -a_2 \\ p_2 & -a_3 & 0 & a_1 \\ p_3 & a_2 & -a_1 & 0 \end{pmatrix} = \{-\vec{p}, \vec{a}\}$$

$$(A^{*\alpha\beta}) = \begin{pmatrix} 0 & a_1 & a_2 & a_3 \\ -a_1 & 0 & -p_3 & p_2 \\ -a_2 & p_3 & 0 & -p_1 \\ -a_3 & -p_2 & p_1 & 0 \end{pmatrix} = \{\vec{a}, -\vec{p}\}$$

二阶张量场的导数:

$$(T^{\alpha\beta}) = \begin{pmatrix} \phi & \vec{p} \\ \vec{q} & \vec{T} \end{pmatrix} \Rightarrow \begin{cases} \partial_\beta T^{0\beta} = \partial_0 \phi + \nabla \cdot \vec{p} \\ \partial_\beta T^{i\beta} = \partial_0 \phi + \partial_j T^{ij} \end{cases}$$

$$(T^{\alpha\beta}) = (T^{\beta\alpha}) = \begin{pmatrix} \phi & \vec{p} \\ \vec{p} & \vec{T} \end{pmatrix} \Rightarrow (\partial_\beta T^{\alpha\beta}) = \begin{pmatrix} \partial_0 \phi + \nabla \cdot \vec{p} \\ \partial_0 \vec{p} + \nabla \cdot \vec{T} \end{pmatrix}$$

$$(T^{\alpha\beta}) = (-T^{\beta\alpha}) = \{\vec{p}, \vec{a}\} \Rightarrow \partial_\beta T^{\alpha\beta} = \begin{pmatrix} \nabla \cdot \vec{p} \\ -\partial_0 \vec{p} + \nabla \times \vec{a} \end{pmatrix}$$

电磁规律的相对论协变性:

4-电流密度:

$$\text{电荷守恒: } \rho dV = \rho_0 dV_0 \xrightarrow{dV_0 = \gamma dV} \begin{cases} \rho = \gamma \rho_0 \\ \vec{j} = \gamma \rho_0 \vec{u} \end{cases}$$

$$j^\alpha \triangleq \rho_0 U^\alpha = \rho_0 \gamma (c, \vec{u}) = (\rho c, \vec{j})$$

$$\text{连续性方程: } \partial_t \rho + \nabla \cdot \vec{j} = 0 \iff \partial_\alpha j^\alpha = 0$$

麦克斯韦方程组:

电磁场强张量:

$$F^{\alpha\beta} = \begin{pmatrix} 0 & \frac{E_1}{c} & \frac{E_2}{c} & \frac{E_3}{c} \\ -\frac{E_1}{c} & 0 & B_3 & -B_2 \\ -\frac{E_2}{c} & -B_3 & 0 & B_1 \\ -\frac{E_3}{c} & B_2 & -B_1 & 0 \end{pmatrix} = \left\{ \frac{\vec{E}}{c}, \vec{B} \right\}$$

$$F_{\alpha\beta} = \left\{ -\frac{\vec{E}}{c}, \vec{B} \right\}$$

$$G^{\alpha\beta} \triangleq F^{*\alpha\beta} = \frac{1}{2!} \epsilon^{\alpha\beta\mu\nu} F_{\mu\nu} = \left\{ \vec{B}, -\frac{\vec{E}}{c} \right\}$$

场的导数:

$$(\partial_\beta F^{\alpha\beta}) = \begin{pmatrix} \frac{1}{c} \nabla \cdot \vec{E} \\ \nabla \times \vec{B} - \frac{1}{c^2} \partial_t \vec{E} \end{pmatrix}$$

$$(\partial_\beta G^{\alpha\beta}) = \begin{pmatrix} \nabla \cdot \vec{B} \\ -\frac{1}{c} \nabla \times \vec{E} - \frac{1}{c} \partial_t \vec{B} \end{pmatrix}$$

麦克斯韦方程组:

$$\begin{cases} \partial_\beta F^{\alpha\beta} = \mu_0 j^\alpha \\ \partial_\beta G^{\alpha\beta} = 0 \end{cases}$$

其中 $\partial_\beta G^{\alpha\beta} = 0 \iff \partial_\alpha F_{\beta\gamma} + \partial_\beta F_{\gamma\alpha} + \partial_\gamma F_{\alpha\beta} = 0$:

$\implies: \partial_\beta G^{\alpha\beta} = 0 \implies \epsilon^{\alpha\beta\mu\nu} \partial_\beta F_{\mu\nu} = 0 \implies$ 由 $F_{\alpha\beta}$ 的反对称性, 可得三个数不同时, 成立等式。而三个数有两个相同时, 可直接得等式成立。三个数都相同时, 由于对角线为 0, 故也成立。所以对任意 α, β, γ 均成立。

$$\iff: \partial_\alpha F_{\beta\gamma} + \partial_\beta F_{\gamma\alpha} + \partial_\gamma F_{\alpha\beta} = 0, F_{\alpha\beta} = -F_{\beta\alpha}$$

$$\implies \epsilon^{\alpha\beta\mu\nu} \partial_\beta F_{\mu\nu} = 0 \implies \partial_\beta G^{\alpha\beta} = 0$$

验证电磁场强张量确实为张量:

$$\begin{aligned} \partial'_\beta F'^{\alpha\beta} &= \mu_0 j'^\alpha \\ \Lambda_\beta^\gamma \partial_\nu F'^{\alpha\beta} &= \mu_0 \Lambda_\gamma^\alpha j^\gamma \\ \Lambda_\alpha^\mu \Lambda_\beta^\gamma \partial_\nu F'^{\alpha\beta} &= \mu_0 \Lambda_\alpha^\mu \Lambda_\gamma^\alpha j^\gamma \\ \partial_\nu (\Lambda_\alpha^\mu \Lambda_\beta^\gamma F'^{\alpha\beta}) &= \mu_0 \delta^\mu_\gamma j^\gamma = \mu_0 j^\mu = \partial_\nu F^{\mu\nu} \\ \implies \begin{pmatrix} \nabla \cdot \vec{Y} \\ -\frac{1}{c} \partial_t \vec{Y} + \nabla \times \vec{Z} \end{pmatrix} &= \begin{pmatrix} \nabla \cdot \vec{E} \\ -\frac{1}{c} \partial_t \vec{E} + \nabla \times \vec{B} \end{pmatrix} \end{aligned}$$

其中

$$\begin{aligned} \vec{Y} &\triangleq E'_1 \hat{x}_1 + \gamma_0 (E'_2 + \beta_0 c B'_3) \hat{x}_2 + \gamma_0 (E'_3 - \beta_0 c B'_2) \hat{x}_3 \\ \vec{Z} &\triangleq B'_1 \hat{x}_1 + \gamma_0 (B'_2 - \beta_0 \frac{E'_3}{c}) \hat{x}_2 + \gamma_0 (B'_3 + \beta_0 \frac{E'_2}{c}) \hat{x}_3 \\ (\Lambda_\alpha^\mu \Lambda_\beta^\gamma F'^{\alpha\beta}) &= \{ \frac{\vec{Y}}{c}, \vec{Z} \} \end{aligned}$$

假设电磁场变换是线性齐次的, 则可得 $\Lambda_\alpha^\mu \Lambda_\beta^\gamma F'^{\alpha\beta} = F^{\mu\nu}$ 。

(在线性齐次的情况下, 由散度相等可得 $\vec{E} - \vec{Y} = \vec{W}$ 。 \vec{W} 满足 $\nabla \cdot \vec{W} = 0, \vec{W} = \vec{W}(E'_1, \dots, B'_3)$, 是 E'_1, \dots, B'_3 的齐次线性函数。代入特殊电磁场 (平面电磁波, 叠加无限大场源使得只有某个场分量变化, ...) 可以得到 $\vec{W} = 0, \vec{E} = \vec{Y}$ 。类似可得 $\vec{B} = \vec{Z}$)

(设 $F'^{\mu\nu} = M[F^{\mu\nu}]$, 不同参考系中的场应该满足各自参考系的叠加原理 $F'^{\mu\nu} = (F'^{\mu\nu})_1 + (F'^{\mu\nu})_2 = M[(F^{\mu\nu})_1] + M[(F^{\mu\nu})_2] = M[F^{\mu\nu}] = M[(F^{\mu\nu})_1 + (F^{\mu\nu})_2]$, 故 $M[F^{\mu\nu}]$ 的泰勒展开中应当只包含电磁场分量的一次项, 即变换应为线性齐次变换。)

电磁场的变换:

$$\Lambda_{\alpha}^{\mu} \Lambda_{\beta}^{\nu} F'^{\alpha\beta} = F^{\mu\nu}$$

$$\begin{cases} \vec{E}'_{//} = \vec{E}_{//}, & \vec{E}'_{\perp} = \gamma_0(\vec{E}_{\perp} + \vec{\beta}_0 \times c\vec{B}) \\ \vec{B}'_{//} = \vec{B}_{//}, & c\vec{B}'_{\perp} = \gamma_0(c\vec{B}_{\perp} - \vec{\beta}_0 \times \vec{E}) \end{cases}$$

$$\begin{cases} \vec{E}_{//} = \vec{E}'_{//}, & \vec{E}_{\perp} = \gamma_0(\vec{E}'_{\perp} - \vec{\beta}_0 \times c\vec{B}') \\ \vec{B}_{//} = \vec{B}'_{//}, & c\vec{B}_{\perp} = \gamma_0(c\vec{B}'_{\perp} + \vec{\beta}_0 \times \vec{E}') \end{cases}$$

低速时:

$$\vec{E}' = \vec{E} + \vec{v}_0 \times \vec{B}, \quad \vec{B}' = \vec{B} - \frac{\vec{v}_0 \times \vec{E}}{c^2}$$

(保留到 β_0 的一级小量)

张量缩并带来的不变量:

$$\mathcal{L}_0 \triangleq -\frac{1}{4\mu_0} F_{\alpha\beta} F^{\alpha\beta} = \frac{1}{2} \epsilon_0 (E^2 - c^2 B^2)$$

$$-\frac{c}{4} F_{\alpha\beta} G^{\alpha\beta} = \vec{E} \cdot \vec{B}$$

根据 \mathcal{L}_0 的取值将电磁场分类: $E > cB$: 类电; $E < cB$: 类磁; $E = cB$: 电磁波。若 $\vec{E} \cdot \vec{B} = 0$, 且 $E > cB$, 则存在标架使得在其中为纯电场 (取 $\vec{\beta}_0 = \frac{\vec{E} \times c\vec{B}}{E^2}$; 若 $\vec{E} \cdot \vec{B} = 0$, 且 $E < cB$, 则存在标架使得在其中为纯磁场 (取 $\vec{\beta}_0 = \frac{\vec{E} \times c\vec{B}}{(cB)^2}$)。若 $\vec{E} \cdot \vec{B} \neq 0$, 则可找到标架使得 $\vec{E}' // \vec{B}'$ (取 $\vec{\beta}_0$ 满足 $\frac{\vec{\beta}_0}{1 + \beta_0^2} = \frac{\vec{E} \times c\vec{B}}{E^2 + c^2 B^2}$)。

4-波矢:

$$k^{\alpha} = \left(\frac{\omega}{c}, \vec{k} \right) = \frac{\omega}{c} (1, \hat{k}) = \frac{2\pi}{c} f(1, \hat{k})$$

k^{α} 是 4-矢量:

单色平面波:

$$\begin{cases} \vec{E}(\vec{r}, t) = \vec{E}_0 e^{ik^{\alpha} x_{\alpha}} \\ \vec{B}(\vec{r}, t) = \vec{B}_0 e^{ik^{\alpha} x_{\alpha}} \end{cases}$$

$k^{\alpha} x_{\alpha} = \text{Const} + 2n\pi$ 时电磁场都相等, 且 $k^{\alpha} x_{\alpha} = \text{Const} + 2n\pi$ 确定一族等间隔“平面”, 又由于 $x^{\alpha} \rightarrow x'^{\alpha}$ 为齐次线性变换, 从而在动系中也对应一族等间隔“平面”, 故动系电磁场也应为单色平面波。

$$\vec{E}' = \vec{E}_0 e^{i(k'^{\alpha} x'_{\alpha})} = [\dots] e^{i(k^{\alpha} x_{\alpha})}$$

$$\implies k'^{\alpha} x'_{\alpha} = k^{\alpha} x_{\alpha}$$

$$\implies k'^{\alpha} = \Lambda^{\alpha}_{\beta} k^{\beta}$$

光行差效应和多普勒效应:

$$k^\alpha = \frac{2\pi}{c} f(1, \hat{\mathbf{k}})$$

$$\text{观察者: } k^\alpha = \frac{2\pi}{c} f \begin{pmatrix} 1 \\ \cos \theta \\ \sin \theta \cos \phi \\ \sin \theta \sin \phi \end{pmatrix}, \quad \text{光源: } k^\alpha = \frac{2\pi}{c} f_0 \begin{pmatrix} 1 \\ \cos \theta_0 \\ \sin \theta_0 \cos \phi_0 \\ \sin \theta_0 \sin \phi_0 \end{pmatrix}$$

$$k'^\alpha = \Lambda^\alpha_\beta k^\beta$$

$$\Rightarrow \begin{cases} f = f_0 \frac{\sqrt{1-\beta^2}}{1-\beta \cos \theta} \\ \cos \theta_0 = \frac{\cos \theta - \beta}{1-\beta \cos \theta} \\ \phi_0 = \phi \end{cases} \quad \begin{cases} f = f_0 \frac{1+\beta \cos \theta_0}{\sqrt{1-\beta^2}} \\ \cos \theta = \frac{\cos \theta_0 + \beta}{1+\beta \cos \theta_0} \\ \phi = \phi_0 \end{cases}$$

能动量守恒:

4-力密度:

$$f^\mu \triangleq F^{\mu\alpha} j_\alpha = \left(\frac{\vec{E} \cdot \vec{j}}{c}, \rho \vec{E} + \vec{j} \times \vec{B} \right)$$

$$\begin{aligned} f^\mu &= \frac{1}{\mu_0} F^{\mu\alpha} \mu_0 j_\alpha \\ &= \frac{1}{\mu_0} F^{\mu\alpha} \partial^\beta F_{\alpha\beta} \\ &= \frac{1}{\mu_0} \partial^\beta (F^{\mu\alpha} F_{\alpha\beta}) - \frac{1}{\mu_0} F_{\alpha\beta} \partial^\beta F^{\mu\alpha} \\ &= \frac{1}{\mu_0} \partial^\beta (F^{\mu\alpha} F_{\alpha\beta}) + \frac{1}{\mu_0} F_{\alpha\beta} \partial^\mu F^{\alpha\beta} + \frac{1}{\mu_0} F_{\alpha\beta} \partial^\alpha F^{\beta\mu} \\ &\quad (\partial_\alpha F_{\beta\gamma} + \partial_\beta F_{\gamma\alpha} + \partial_\gamma F_{\alpha\beta} = 0) \\ &= \frac{1}{\mu_0} \partial^\beta (F^{\mu\alpha} F_{\alpha\beta}) + 2\partial^\mu \mathcal{L}_0 + \frac{1}{\mu_0} F_{\alpha\beta} \partial^\beta F^{\mu\alpha} \\ &= \frac{1}{\mu_0} \partial^\beta (F^{\mu\alpha} F_{\alpha\beta}) + 2\partial^\mu \mathcal{L}_0 + \frac{1}{\mu_0} \partial^\beta (F^{\mu\alpha} F_{\alpha\beta}) - f^\mu \\ &\Rightarrow f^\mu = \partial_\nu \left(\frac{1}{\mu_0} F^{\mu\alpha} F_\alpha{}^\nu \right) - \partial_\nu (g^{\mu\nu} \mathcal{L}_0) \triangleq -\partial_\nu T^{\mu\nu} \end{aligned}$$

能动量张量:

$$T^{\mu\nu} = g^{\mu\nu} \mathcal{L}_0 - \frac{1}{\mu_0} F^{\mu\alpha} F_\alpha{}^\nu \Rightarrow T^{\mu\nu} = T^{\nu\mu}$$

$$(T^{\mu\nu}) = \begin{pmatrix} w & \frac{\vec{S}}{c} \\ \frac{\vec{S}}{c} & \vec{T} \end{pmatrix}$$

$$(-\partial_\nu T^{\mu\nu}) = - \begin{pmatrix} \partial_0 w + \nabla \cdot \frac{\vec{S}}{c} \\ \frac{\vec{S}}{\partial_0 c} + \nabla \cdot \vec{T} \end{pmatrix} = f^\mu = \begin{pmatrix} \frac{\vec{E} \cdot \vec{j}}{c} \\ \rho \vec{E} + \vec{j} \times \vec{B} \end{pmatrix}$$

规范势:

$$(1) F_{\alpha\beta} = -F_{\beta\alpha} \implies F_{ab} \text{ 是 2-形式}$$

$$(2) \partial_\alpha F_{\beta\gamma} + \partial_\beta F_{\gamma\alpha} + \partial_\gamma F_{\alpha\beta} = 0, F_{\alpha\beta} = -F_{\beta\alpha} \implies \partial_{[\alpha} F_{\beta\gamma]} = 0 \\ \implies (dF)_{abc} = 0 \implies F_{ab} = (dA)_{ab}$$

$$(3) F_{ab} = (dA)_{ab} \text{ 显然也可以推出}$$

$$\partial_\alpha F_{\beta\gamma} + \partial_\beta F_{\gamma\alpha} + \partial_\gamma F_{\alpha\beta} = 0, F_{\alpha\beta} = -F_{\beta\alpha}$$

从而有如下等价关系:

$$\partial_\beta G^{\alpha\beta} = 0 \iff F_{ab} = (dA)_{ab} \\ \iff \partial_\alpha F_{\beta\gamma} + \partial_\beta F_{\gamma\alpha} + \partial_\gamma F_{\alpha\beta} = 0, F_{\alpha\beta} = -F_{\beta\alpha}$$

规范势 A^α :

$$A^\alpha = \left(\frac{\phi}{c}, \vec{A} \right) \\ F^{\alpha\beta} = \partial^\alpha A^\beta - \partial^\beta A^\alpha \\ \begin{cases} \vec{E} = -\nabla\phi - \partial_t \vec{A} \\ \vec{B} = \nabla \times \vec{A} \end{cases}$$

规范变换:

$$\partial^\alpha A^\beta - \partial^\beta A^\alpha = \partial^\alpha A'^\beta - \partial^\beta A'^\alpha \\ \implies \partial_\alpha K_\beta - \partial_\beta K_\alpha = 0 \\ (K^\alpha = A'^\alpha - A^\alpha) \\ \implies (dK)_{ab} = 0 \implies K_a = (d\psi)_a \\ A'^\alpha = A^\alpha + \partial^\alpha \psi$$

势方程:

$$\mu_0 j^\alpha = \partial_\beta F^{\alpha\beta} = \partial_\beta (\partial^\alpha A^\beta - \partial^\beta A^\alpha) \\ = \partial^\alpha (\partial_\beta A^\beta) - \partial_\beta \partial^\beta A^\alpha \\ = \partial^\alpha L - \square A^\alpha \\ \square A^\alpha - \partial^\alpha L = -\mu_0 j^\alpha$$

(另外的方程已经被规范势表示自动满足。)

洛伦兹规范:

$$L = 0$$

$$\square A^\alpha = -\mu_0 j^\alpha$$

介质中的麦克斯韦方程:

$$\begin{aligned}
 \nabla \cdot \frac{\vec{E}}{c} &= \mu_0 \rho c, \nabla \times \vec{B} - \frac{1}{c^2} \partial_t \vec{E} = \mu_0 \vec{j} \iff \partial_\beta F^{\alpha\beta} = \mu_0 j^\alpha \\
 \nabla \cdot &= \rho_0 c, \nabla \times \vec{H} - \partial_t \vec{D} = \vec{j}_0 \iff \partial_\beta H^{\alpha\beta} = j_0^\alpha \\
 (H^{\alpha\beta}) &= \begin{pmatrix} 0 & cD_1 & cD_2 & cD_3 \\ -cD_1 & 0 & H_3 & -H_2 \\ -cD_2 & -H_3 & 0 & H_1 \\ -cD_3 & H_2 & -H_1 & 0 \end{pmatrix} = \{c\vec{D}, \vec{H}\} \\
 &\begin{cases} \vec{D} = \epsilon_0 \vec{E} + \vec{P} \\ \vec{H} = \frac{\vec{B}}{\mu_0} - \vec{M} \end{cases} \\
 (M^{\alpha\beta}) &= \left(\frac{1}{\mu_0} F^{\alpha\beta} - H^{\alpha\beta} \right) = \begin{pmatrix} 0 & -cP_1 & -cP_2 & -cP_3 \\ cP_1 & 0 & M_3 & -M_2 \\ cP_2 & -M_3 & 0 & M_1 \\ cP_3 & M_2 & -M_1 & 0 \end{pmatrix}
 \end{aligned}$$

运动介质 ($\beta_0 \ll 1$) 中的 $\vec{D} = \vec{D}(\vec{E}, \vec{H}), \vec{B} = \vec{B}(\vec{E}, \vec{H})$:

$$\begin{cases} \vec{D} = \epsilon \vec{E} + (\epsilon\mu - \frac{1}{c^2}) \vec{v}_0 \times \vec{H} \\ \vec{B} = \mu \vec{H} - (\epsilon\mu - \frac{1}{c^2}) \vec{v}_0 \times \vec{E} \end{cases}$$

粒子动力学:

$$\begin{aligned}
 \epsilon &\triangleq \gamma mc^2 = \frac{mc^2}{\sqrt{1 - \frac{u^2}{c^2}}} \\
 \vec{p} &\triangleq \gamma m \vec{u} = \frac{m \vec{u}}{\sqrt{1 - \frac{u^2}{c^2}}} \\
 \implies \vec{u} &= \frac{c^2 \vec{p}}{\epsilon} \\
 P^\alpha &= \left(\frac{\epsilon}{c}, \vec{p} \right) \\
 P^\alpha P_\alpha &= -mc^2 \implies \epsilon^2 = p^2 c^2 + m^2 c^4
 \end{aligned}$$

动力学方程:

假设 MCRF 中, 牛二定律成立: $\vec{F}' = m \vec{a}'$

电磁作用有

$$\begin{aligned}
 ma'_x &= eE'_x, ma'_{y,z} = eE'_{y,z} \\
 a'_x &= \gamma^3 a_x, a'_{y,z} = \gamma^2 a_{y,z} \\
 E'_x &= E_x, E'_{y,z} = \gamma(\vec{E} + \vec{\beta} \times c\vec{B})_{y,z} \\
 \Rightarrow &\begin{cases} \gamma^3 ma_x = eE_x \\ \gamma ma_{y,z} = e(\vec{E} + \vec{u} \times \vec{B})_{y,z} \end{cases} \\
 \Rightarrow &\vec{F} = e\vec{E} + e\vec{u} \times \vec{B} = \frac{d\vec{p}}{dt}
 \end{aligned}$$

写为 4-矢量:

$$\frac{dP^\alpha}{d\tau} = K^\alpha, \quad K^\alpha \triangleq \gamma(\vec{F} \cdot \vec{\beta}, \vec{F})$$