

Discussion 5

137A

More... Spin-1/2 problems



1 Use matrix mechanics to compute:

$$[S_z, S_x]$$

You should find they don't commute. We say they are "incompatible". Their uncertainties w.r.t. any state $|\psi\rangle$ satisfy:

$$\Delta S_z \Delta S_x \geq \left| \frac{1}{2} \langle [S_z, S_x] \rangle \right|$$

Generalized uncertainty principle.

2 Is it possible that $\Delta S_z \Delta S_x = 0$?

3 Work out the matrix representation of the projection operators $P_+ = |+z\rangle\langle +z|$ and $P_- = |-z\rangle\langle -z|$ using the states $|+y\rangle$ and $|-y\rangle$ as a basis. Check that

$$P_+ + P_- = I \quad \text{Identity}$$

holds as a matrix equation.

Photon Polarization

4 A photon polarization for a photon travelling in the $+z$ direction is given by:

$$|\psi\rangle = \sqrt{\frac{2}{3}}|X\rangle + \frac{i}{\sqrt{3}}|Y\rangle$$

(a) What is the probability that the photon will pass through an ideal linear polarizer \rightarrow

with its transmission axis along the y-direction?

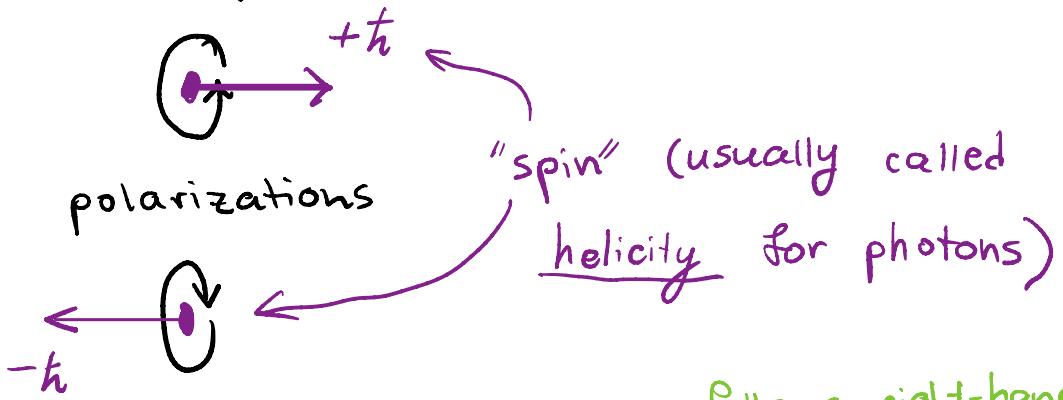
(b) What is the probability that the photon will pass through an ideal linear polarizer with its transmission axis making an angle ϕ with the y-axis?

(c) The states

$$|R\rangle = \frac{1}{\sqrt{2}}|X\rangle + \frac{i}{\sqrt{2}}|Y\rangle$$

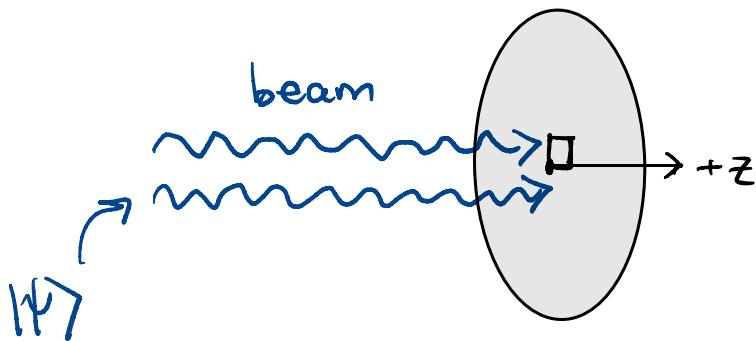
$$|L\rangle = \frac{1}{\sqrt{2}}|X\rangle - \frac{i}{\sqrt{2}}|Y\rangle$$

carry angular momentum $+\hbar$ and $-\hbar$, respectively, in the z-direction.



Angular momentum follows right-hand rule.

Suppose a beam carrying N photons per second, each in the state $|\psi\rangle$, is totally absorbed by a black surface with a surface normal in the z direction



How large is the torque exerted on the disk?
In which direction does the disk rotate?

→ This experiment was done in 1936
(R.A. Beth) confirming that photons carry helicity $\pm h$.

5 Since photon helicity is an observable, it is represented by an operator. Assuming the photon travels in the $+z$ direction, the relevant operator is the component of the angular momentum along the z -direction:

$$J_z |R\rangle = \hbar |R\rangle$$

$$J_z |L\rangle = -\hbar |L\rangle$$

Write the matrix-representation of J_z in the R-L basis, and in the X-Y basis.

6 Compute the matrix representation of the operator

$$R(\phi) = e^{-i J_z \phi / \hbar}$$

in the R-L basis and in the X-Y basis. This operator performs rotations about the z -axis by angle ϕ .

Solutions

1 $[\hat{S}_z, \hat{S}_x]$

$$\hat{S}_z \hat{S}_x \rightarrow \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \frac{\hbar^2}{4} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

$$\hat{S}_x \hat{S}_z \rightarrow \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{\hbar^2}{4} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

so

$$[S_z, S_x] \rightarrow -i \frac{\hbar}{2} \begin{pmatrix} 0 & -i\hbar/2 \\ i\hbar/2 & 0 \end{pmatrix} \rightarrow -i \frac{\hbar}{2} \hat{S}_y$$

2 Yes. For example: $|\psi\rangle = |+z\rangle$.

Then $\Delta S_z = 0$.

3 $P_+ = |+z\rangle \langle +z|$.

$$P_+ \xrightarrow{y} \begin{pmatrix} \langle +y | P_+ | +y \rangle & \langle +y | P_+ | -y \rangle \\ \langle -y | P_+ | +y \rangle & \langle -y | P_+ | -y \rangle \end{pmatrix}$$

$$= \begin{pmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{pmatrix}$$

$$P_- = |-\vec{z}\rangle\langle -\vec{z}|$$

$$P_- \longrightarrow \begin{pmatrix} \langle +y|P_+|+y\rangle & \langle +y|P_+|-y\rangle \\ \langle -y|P_+|+y\rangle & \langle -y|P_+|-y\rangle \end{pmatrix}$$

$$= \begin{pmatrix} 1/2 & -1/2 \\ -1/2 & 1/2 \end{pmatrix}$$

check:

$$\begin{pmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{pmatrix} + \begin{pmatrix} 1/2 & -1/2 \\ -1/2 & 1/2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \checkmark$$

4 $|\psi\rangle = \sqrt{\frac{2}{3}}|X\rangle + \frac{i}{\sqrt{3}}|Y\rangle$

(a) $|\langle Y|\psi\rangle|^2 = \boxed{1/3}$

(b) $|Y'\rangle = -\sin\phi|X\rangle + \cos\phi|Y\rangle$

C
 $\langle Y'|\psi\rangle = -\sin\phi\sqrt{\frac{2}{3}} + i\cos\phi\frac{1}{\sqrt{3}}$

↓
 $|\langle Y'|\psi\rangle|^2 = \frac{2}{3}\sin^2\phi + \frac{1}{3}\cos^2\phi$

$$= \boxed{\frac{1}{3} + \frac{1}{3}\sin^2\phi}$$

(c) Re-write this as a linear combination of $|R\rangle$ and $|L\rangle$:

$$\begin{cases} |X\rangle = \frac{1}{\sqrt{2}}|R\rangle + \frac{1}{\sqrt{2}}|L\rangle \\ |Y\rangle = \frac{1}{\sqrt{2}i}(|R\rangle - |L\rangle) \end{cases}$$



$$\begin{aligned}
 |\psi\rangle &= \sqrt{\frac{2}{3}} |X\rangle + \frac{i}{\sqrt{3}} |Y\rangle \\
 &= \left(\sqrt{\frac{2}{3}} \frac{1}{\sqrt{2}} |R\rangle + \sqrt{\frac{2}{3}} \frac{1}{\sqrt{2}} |L\rangle \right) \\
 &\quad + \left(\cancel{\frac{i}{\sqrt{3}}} \frac{1}{\sqrt{2}i} |R\rangle - \cancel{\frac{i}{\sqrt{3}}} \frac{1}{\sqrt{2}i} |L\rangle \right) \\
 &= \left(\frac{\sqrt{2}}{\sqrt{6}} + \frac{1}{\sqrt{6}} \right) |R\rangle + \left(\frac{1}{\sqrt{3}} - \frac{1}{\sqrt{6}} \right) |L\rangle \\
 &= \frac{1}{\sqrt{6}} (\sqrt{2} + 1) |R\rangle + \frac{1}{\sqrt{6}} (\sqrt{2} - 1) |L\rangle
 \end{aligned}$$

Then:

$$\begin{aligned}
 \langle J_z \rangle &= \hbar \left(\frac{5+\sqrt{2}}{6} \right) - \hbar \left(\frac{5-\sqrt{2}}{6} \right) \\
 &= \hbar \sqrt{2}/3
 \end{aligned}$$

\Rightarrow on avg. each photon deposits $\frac{\sqrt{2}}{3}\hbar$ of angular momentum onto the disk.

$$\Rightarrow \text{torque} = \frac{\sqrt{2}}{3}\hbar N$$

\Rightarrow In the CCW direction abt Z -axis.

$$5 \quad J_z = \hbar |R\rangle\langle R| - \hbar |L\rangle\langle L| \quad \text{so:}$$

$$J_z \xrightarrow{R,L} \hbar \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Now, since

$$\begin{cases} |R\rangle = \frac{1}{\sqrt{2}} |X\rangle + \frac{i}{\sqrt{2}} |Y\rangle \\ |L\rangle = \frac{1}{\sqrt{2}} |X\rangle - \frac{i}{\sqrt{2}} |Y\rangle \end{cases}$$

We can write:

$$\begin{aligned} J_z &= \hbar \left(\frac{1}{\sqrt{2}} |X\rangle + \frac{i}{\sqrt{2}} |Y\rangle \right) \left(\frac{1}{\sqrt{2}} \langle X| - \frac{i}{\sqrt{2}} \langle Y| \right) \\ &\quad - \hbar \left(\frac{1}{\sqrt{2}} |X\rangle - \frac{i}{\sqrt{2}} |Y\rangle \right) \left(\frac{1}{\sqrt{2}} \langle X| + \frac{i}{\sqrt{2}} \langle Y| \right) \\ &= \hbar \left(\frac{1}{2} |X\rangle \langle X| - \frac{i}{2} |X\rangle \langle Y| + \frac{i}{2} |Y\rangle \langle X| \right. \\ &\quad \left. + \frac{1}{2} |Y\rangle \langle Y| \right) \\ &\quad - \hbar \left(\frac{1}{2} |X\rangle \langle X| + \frac{i}{2} |X\rangle \langle Y| - \frac{i}{2} |Y\rangle \langle X| \right. \\ &\quad \left. + \frac{1}{2} |Y\rangle \langle Y| \right) \end{aligned}$$

$$= \hbar (i |Y\rangle\langle X| - i |X\rangle\langle Y|)$$

so:

$$J_z \xrightarrow{X,Y} \boxed{\hbar \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}}$$

6 $R_z(\phi) = e^{-i J_z \phi / \hbar}$

First, in the R/L basis. Then:

$$\begin{aligned} R_z(\phi) |R\rangle &= e^{-i J_z \phi / \hbar} |R\rangle \\ &= e^{-i \phi} |R\rangle \quad \text{---} \quad = \hbar |R\rangle \end{aligned}$$

$$\begin{aligned} R_z(\phi) |L\rangle &= e^{-i J_z \phi / \hbar} |L\rangle \\ &= e^{i \phi} |L\rangle \end{aligned}$$

$$\Rightarrow R_z(\phi) = e^{-i \phi} |R\rangle\langle R| + e^{i \phi} |L\rangle\langle L|$$

$$\rightarrow R_z(\phi) \xrightarrow{R/L} \begin{pmatrix} e^{-i\phi} & 0 \\ 0 & e^{i\phi} \end{pmatrix}$$

Now just perform a change of basis with

$$U = \begin{pmatrix} 1/\sqrt{2} & i/\sqrt{2} \\ 1/\sqrt{2} & -i/\sqrt{2} \end{pmatrix}$$

so

$$\begin{aligned}
 R_z(\phi) &\xrightarrow{X,Y} \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{-i}{\sqrt{2}} & \frac{i}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} e^{-i\phi} & 0 \\ 0 & e^{i\phi} \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{i}{\sqrt{2}} \\ \frac{-i}{\sqrt{2}} & \frac{-i}{\sqrt{2}} \end{pmatrix} \\
 &= \frac{1}{2} \begin{pmatrix} 1 & i \\ -i & i \end{pmatrix} \begin{pmatrix} e^{-i\phi} & ie^{-i\phi} \\ e^{i\phi} & -ie^{i\phi} \end{pmatrix} \\
 &= \frac{1}{2} \begin{pmatrix} e^{-i\phi} + e^{i\phi} & ie^{-i\phi} - ie^{i\phi} \\ -ie^{-i\phi} + ie^{i\phi} & e^{-i\phi} + e^{i\phi} \end{pmatrix} \\
 &= \boxed{\begin{pmatrix} \cos\phi & \sin\phi \\ -\sin\phi & \cos\phi \end{pmatrix}}
 \end{aligned}$$