

PhysH308

Fluid Mechanics!

Ted Brzinski, Nov. 7, 2024



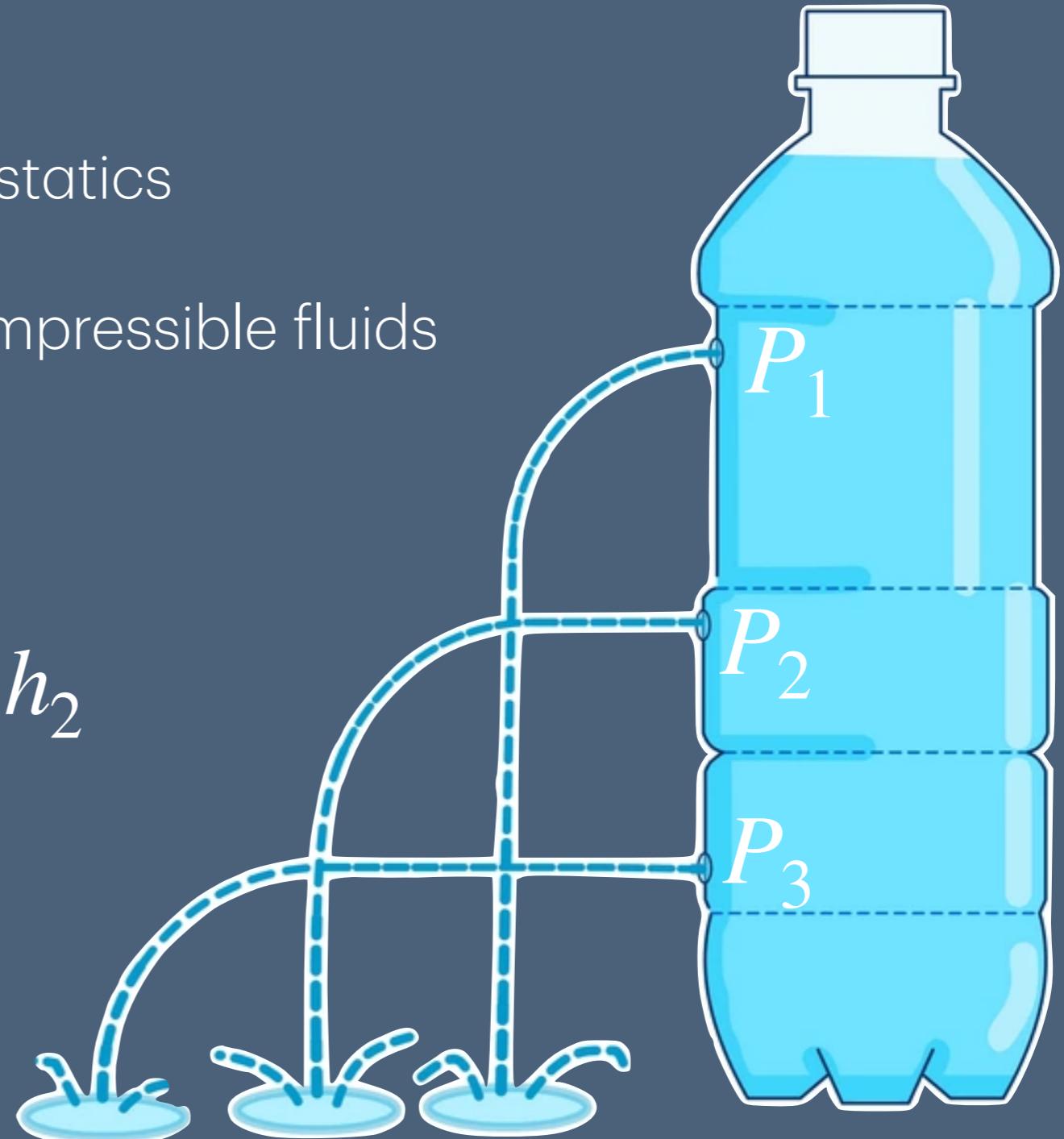
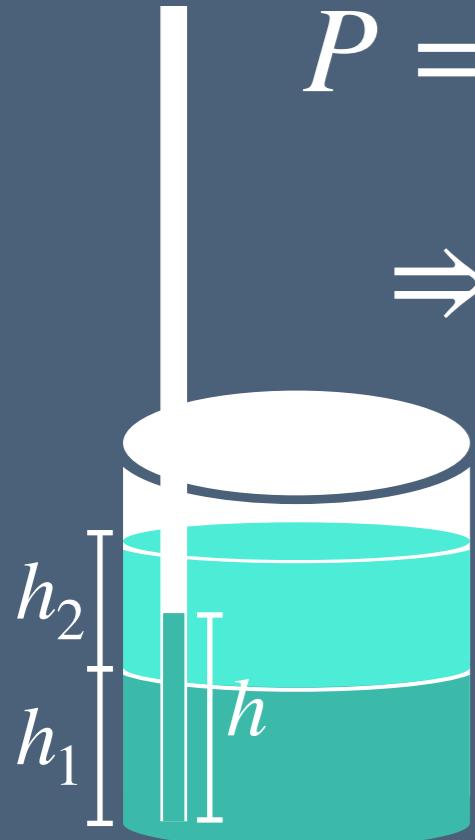
Last time!

Lautrup 2.5

- Pressure, stress/strain, hydrostatics
- Hydrostatic pressure in incompressible fluids

$$P = P_0 + \rho g z$$

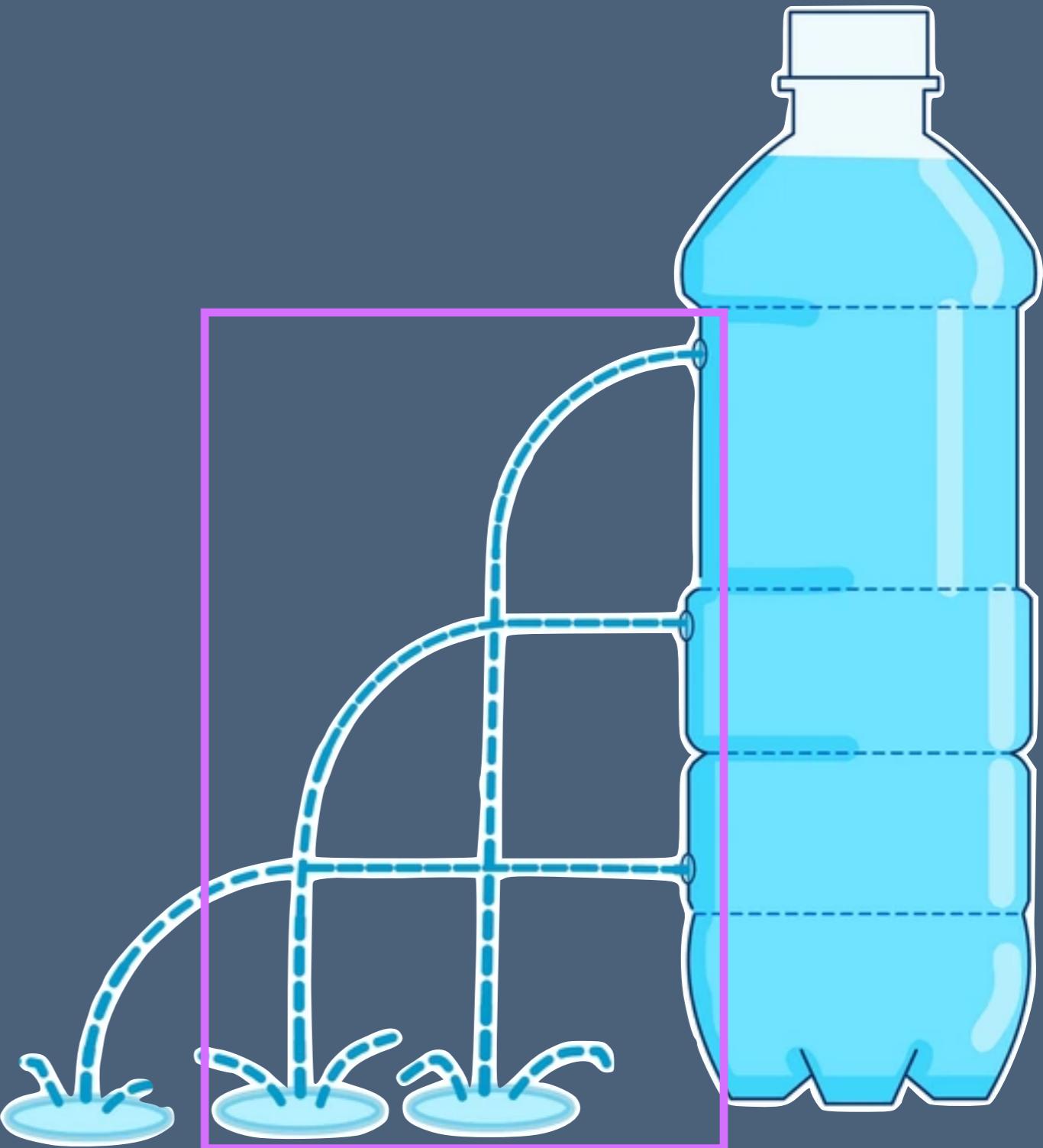
$$\Rightarrow h = h_1 + \frac{\rho_2}{\rho_1} h_2$$



This time:

Ideal Flow! (No viscosity)

- Discrete particles: $\vec{F} = \dot{\vec{p}},$
 $\vec{p} = m\vec{v}, T = \frac{1}{2m}\vec{p}^2,$
 $U = - \int \vec{F} \cdot d\vec{r}$ and
 $\mathcal{H} = T + U$
- All of this is still true for fluid particles! Only now the particle properties become fields...



This time:

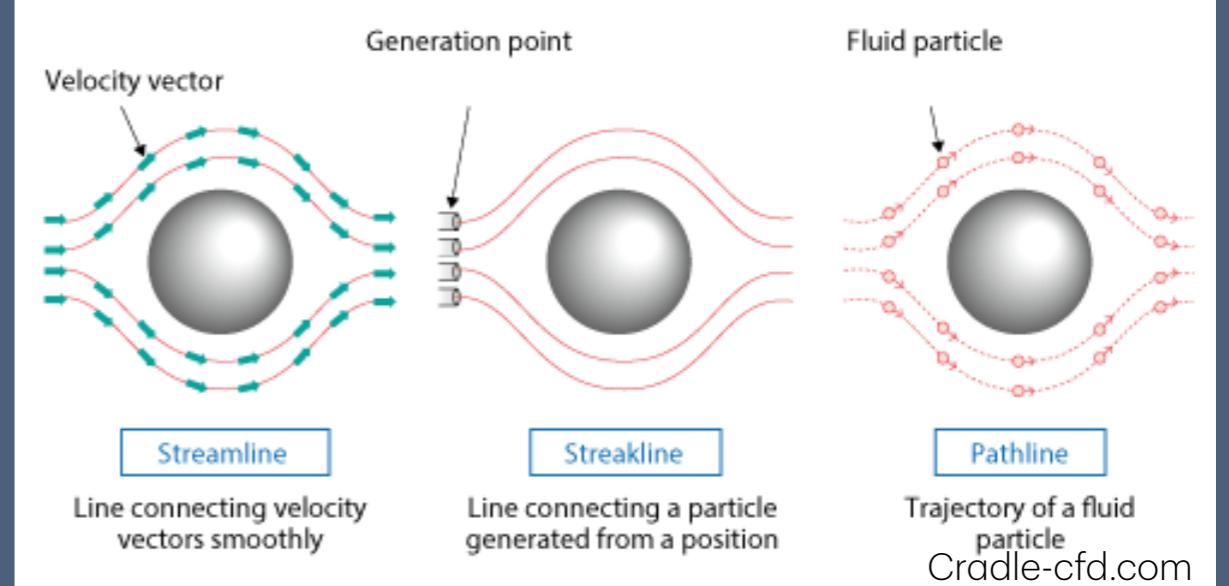
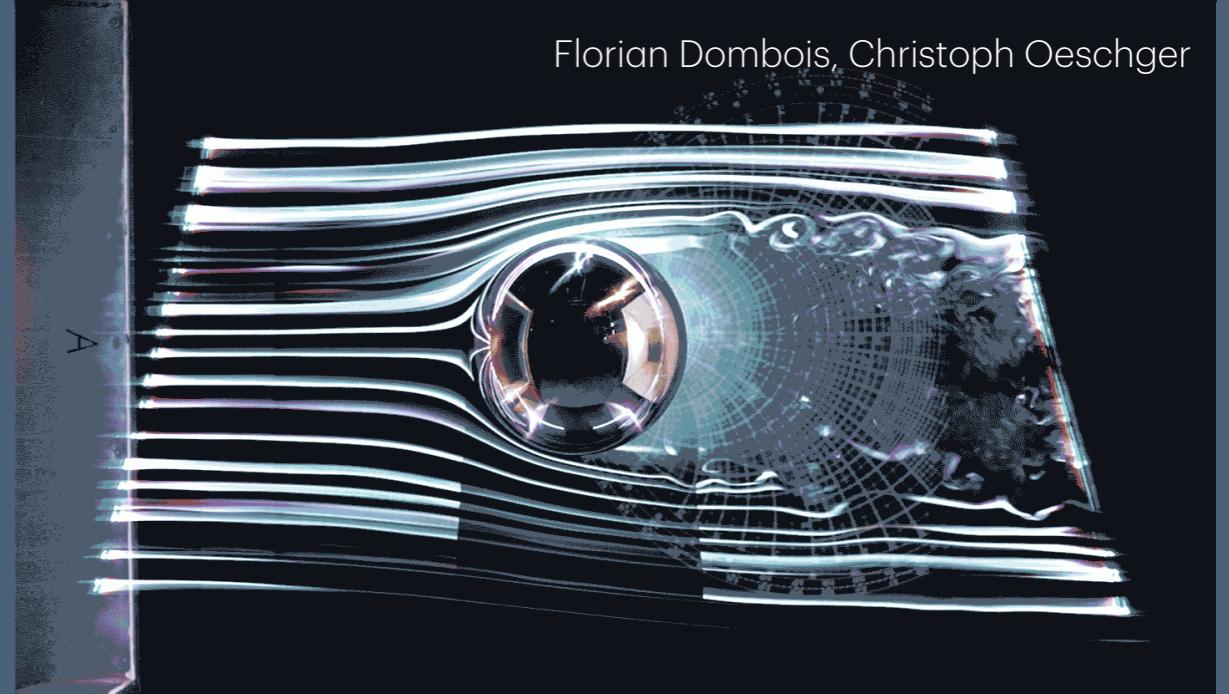
Ideal Flow! (No viscosity)

- All of this is still true for fluid particles! Only now the particle properties become fields....
- $\vec{p} = m\vec{v}$ becomes
 $d\vec{\mathcal{P}} = \vec{v}(\vec{x}, t) dM = \rho(\vec{x}, t) \vec{v}(\vec{x}, t) dV$
- $\vec{v}(\vec{x}, t)$ is a field, as is $\vec{a}(\vec{x}, t)$
(acceleration is \vec{w} , according to Lautrup)
- Newton's 2nd law thus becomes
 $d\vec{\mathcal{F}} = \vec{a}(\vec{x}, t) dM$



Visualizing flow

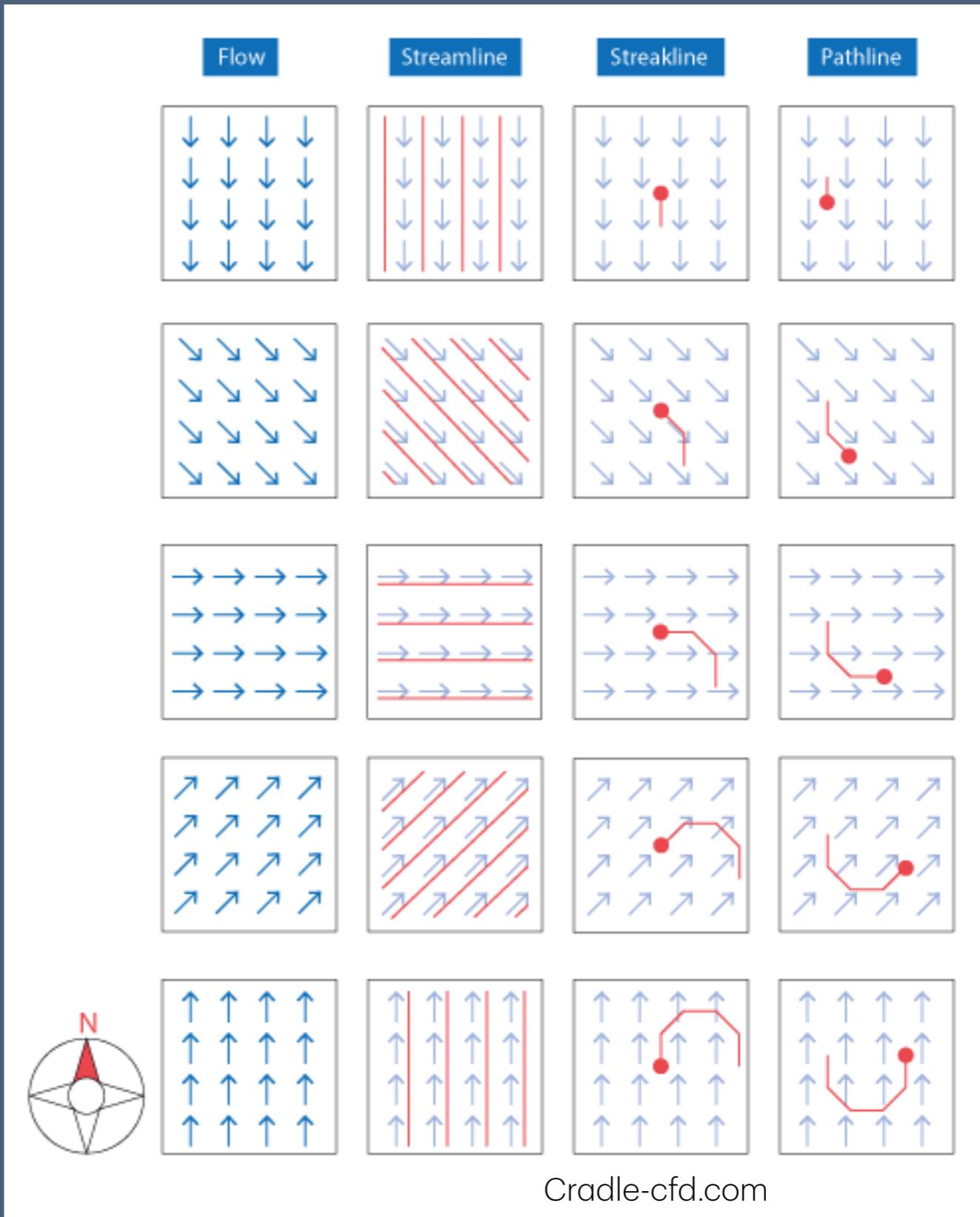
- $\vec{v}(\vec{x}, t)$ is the field we usually want to visualize:
 - Particle Orbits (individual particle paths)
 - Streaklines (lines of particles from a shared origin)
 - Streamlines (tangent to flow)



Visualizing flow

- Particle Orbits
(individual particle paths)
- Streaklines (lines of particles from a shared origin)
- Streamlines (tangent to flow)

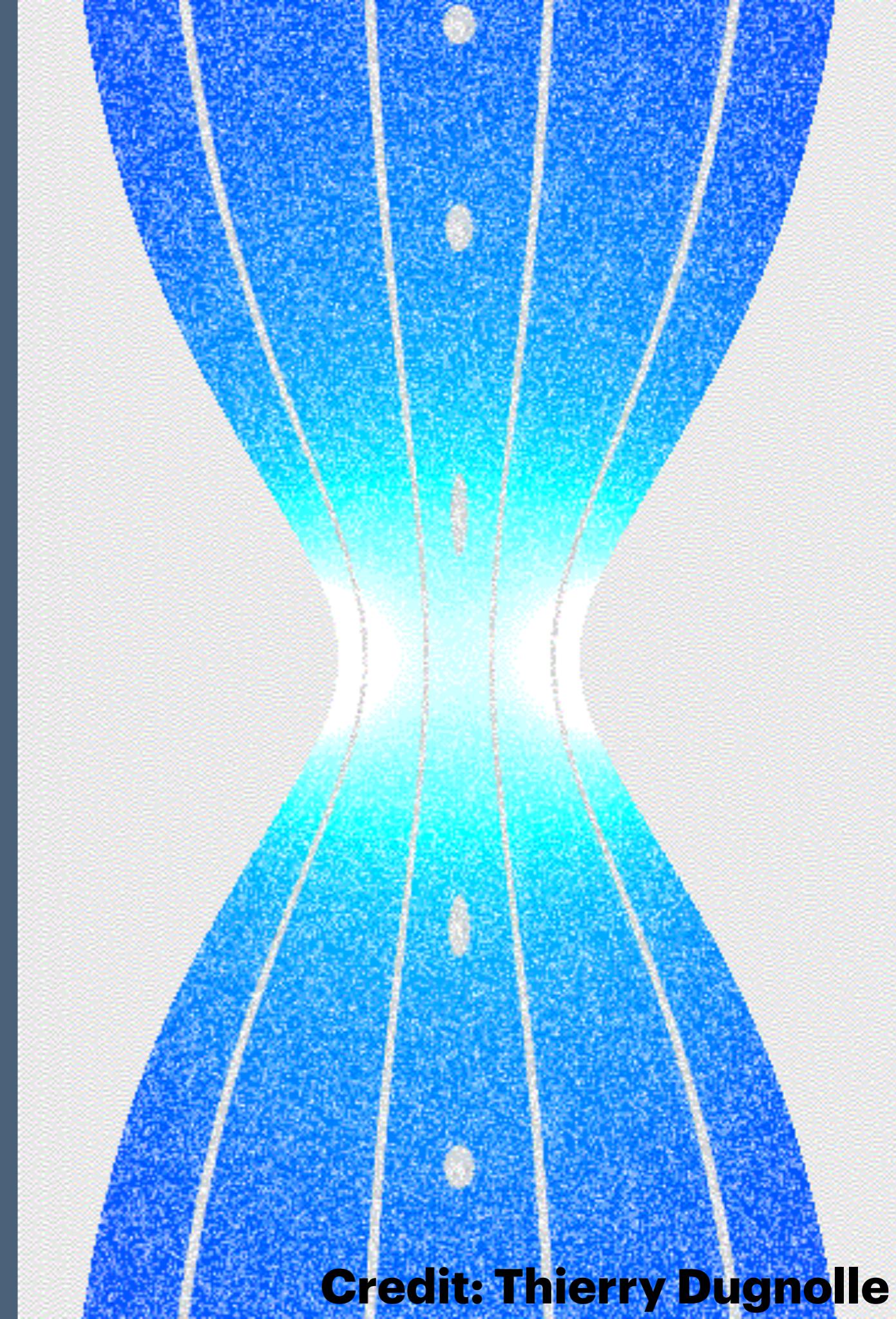
Same for steady flow, but not time-dependent flows!



Material derivatives

Time dependence plus continuity

- $\vec{v}(\vec{x}, t)$ is now a field, as is $\vec{a}(\vec{x}, t)$
- Only now $\vec{a}(\vec{x}, t) \neq \frac{d\vec{v}}{dt}$
- To see why, consider steady flow through a constriction. Conservation of mass requires flow to accelerate at the constriction.
- The velocity field is constant in time, but not space, which requires the same to be true of the acceleration!



Credit: Thierry Dugnolle

Material derivatives

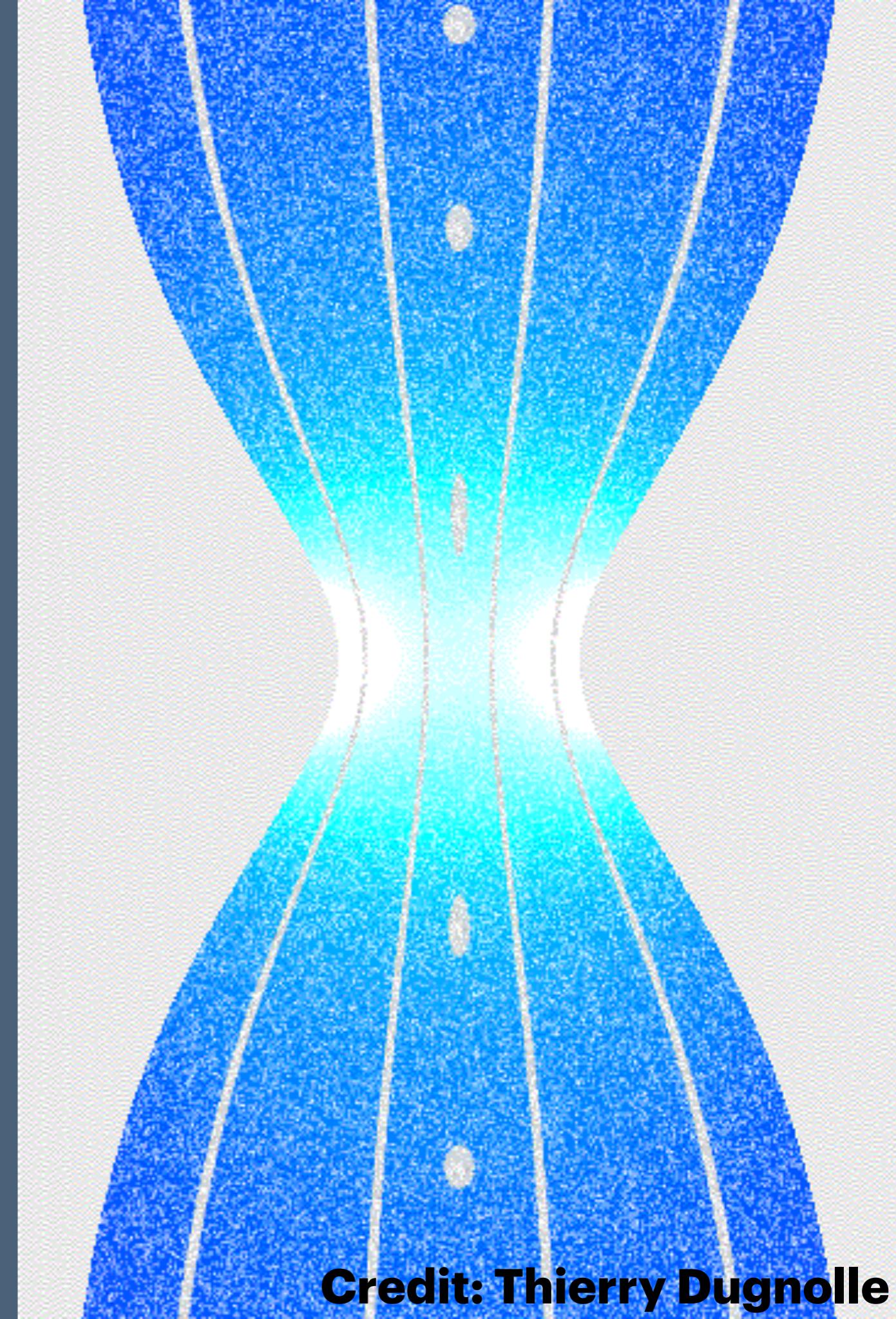
Time dependence plus continuity

- We define a “material derivative” or a “comoving derivative”:

$$\frac{D}{Dt} = \frac{\partial}{\partial t} + \vec{v} \cdot \nabla$$

- Thus

$$\vec{a} = \frac{D\vec{v}}{Dt} = \frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \nabla) \vec{v}$$



Credit: Thierry Dugnolle

Material derivatives

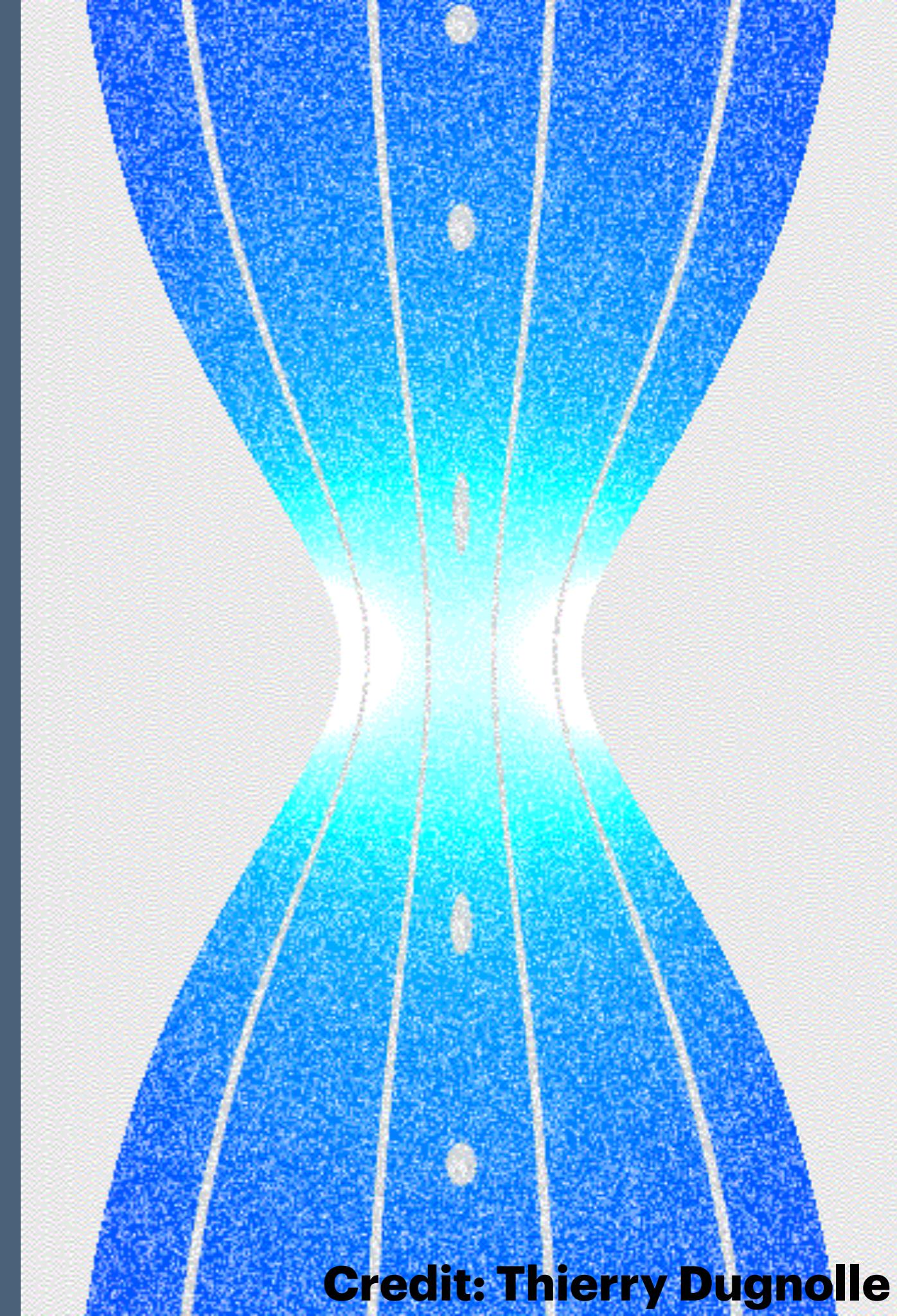
Time dependence plus continuity

- Now, let's return to Newton's 2nd law:

$$d\vec{\mathcal{F}} = \vec{a}dM = \rho\vec{a}dV$$

- $f^* \equiv \frac{d\vec{\mathcal{F}}}{dV} = \rho\vec{a} = \rho\frac{D\vec{v}}{Dt}$

(we call f^* a "force density")



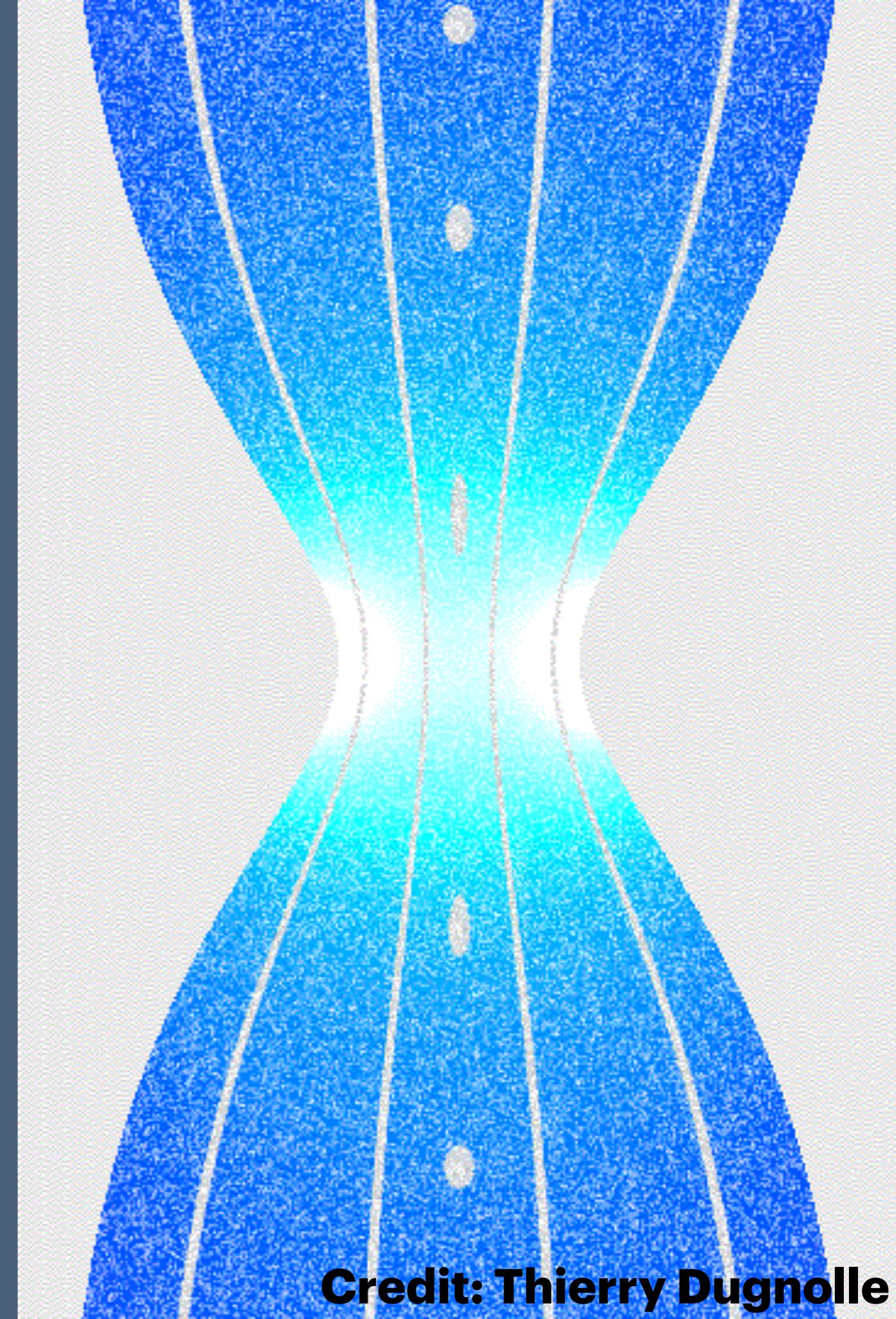
Credit: Thierry Dugnolle

Newton's 2nd Law

For continuous matter

$$\begin{aligned} \bullet f^* &\equiv \frac{d\vec{\mathcal{F}}}{dV} = \rho \vec{a} = \rho \frac{D\vec{v}}{Dt} \\ &= \rho \left(\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \nabla) \vec{v} \right) \end{aligned}$$

- This is “Cauchy’s Equation”, and is the final form of Newton’s 2nd for all continuous matter!



Credit: Thierry Dugnolle

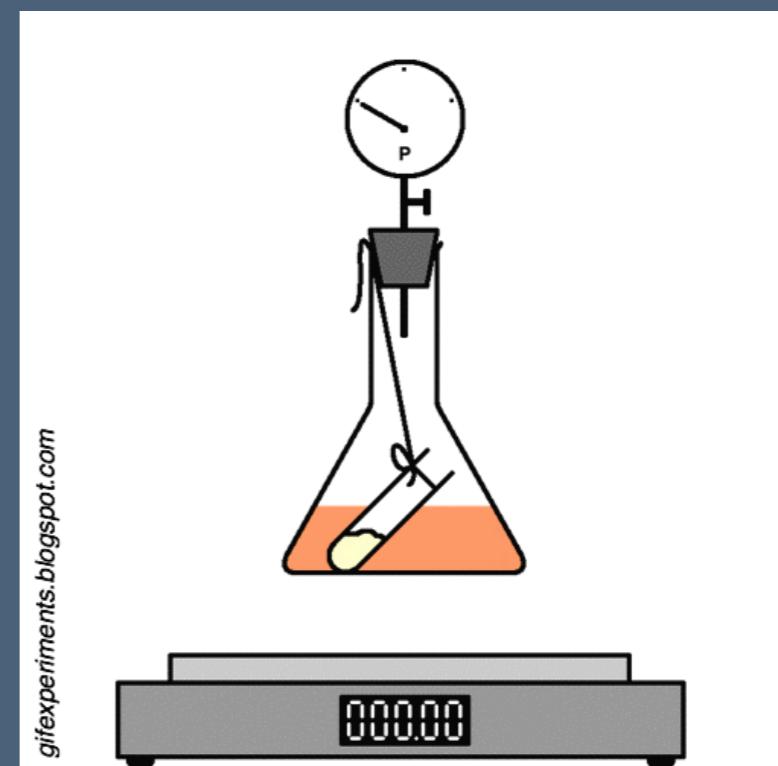
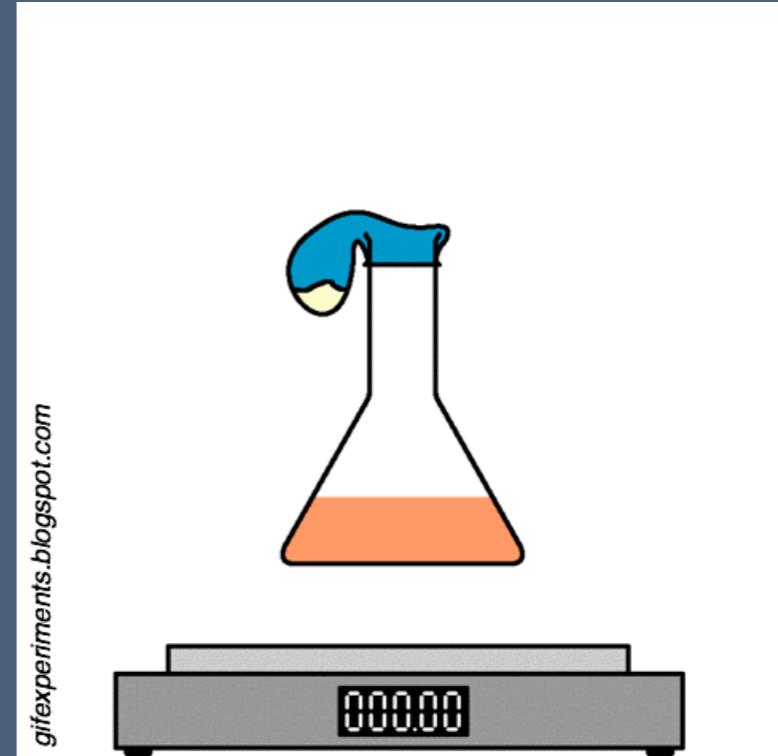
Conservation of mass

A 2nd constraint!

- Regardless of the density and pressure, the mass of a closed system must remain constant.

$$\frac{dM}{dt} = \boxed{\frac{d}{dt} \int_V \rho \, dV = - \oint_S \rho \vec{v} \cdot d\vec{S}}$$

The change in mass is due to the mass flux



Conservation of mass

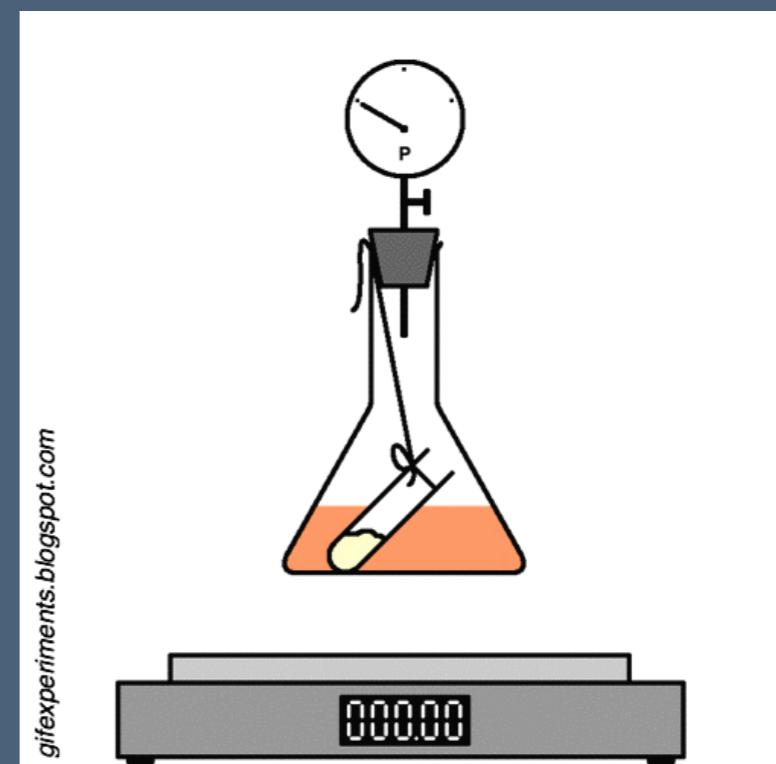
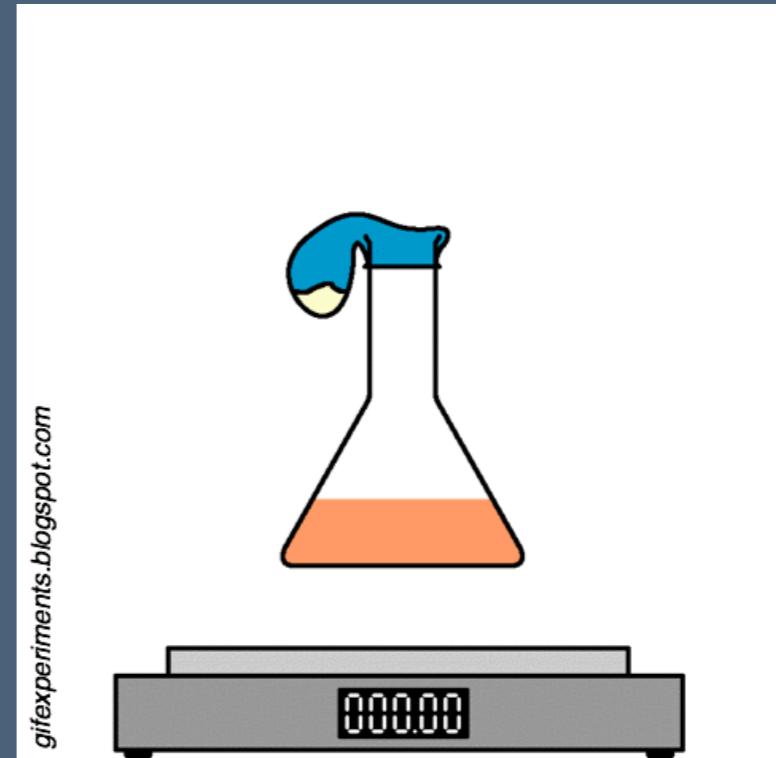
A 2nd constraint!

$$\cdot \frac{dM}{dt} = \frac{d}{dt} \int_V \rho \, dV = - \oint_S \rho \vec{v} \cdot d\vec{S}$$

$$\cdot = \int_V \frac{d\rho}{dt} \, dV = - \int_V \nabla \cdot \rho \vec{v} \, dV$$

$$\cdot \Rightarrow \boxed{\frac{d\rho}{dt} + \nabla \cdot \rho \vec{v} = 0}$$

**Mass is conserved
everywhere!**



Conservation of mass

A 2nd constraint!

- $\Rightarrow \frac{d\rho}{dt} + \nabla \cdot \rho \vec{v} = 0$

- Now consider

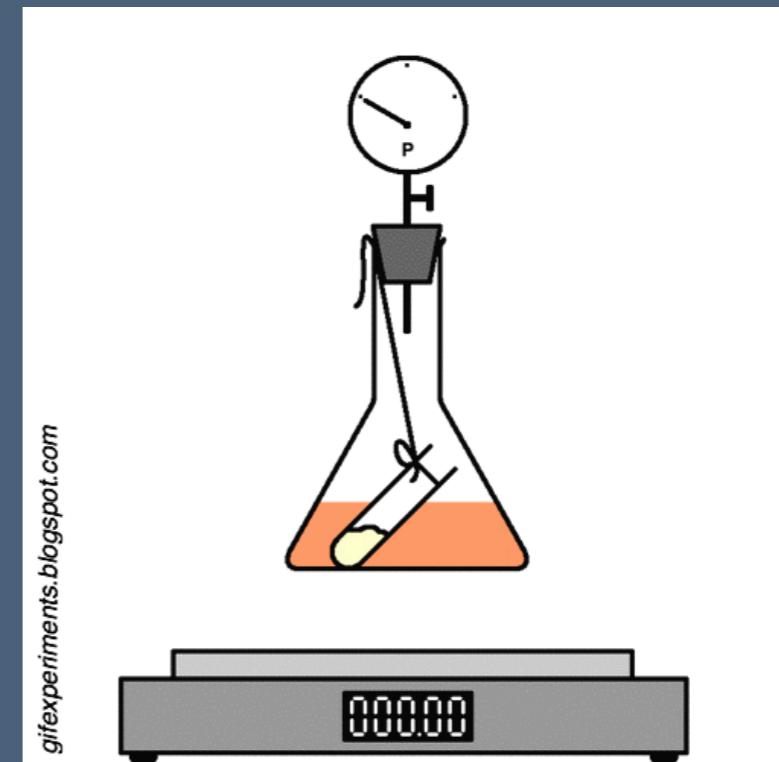
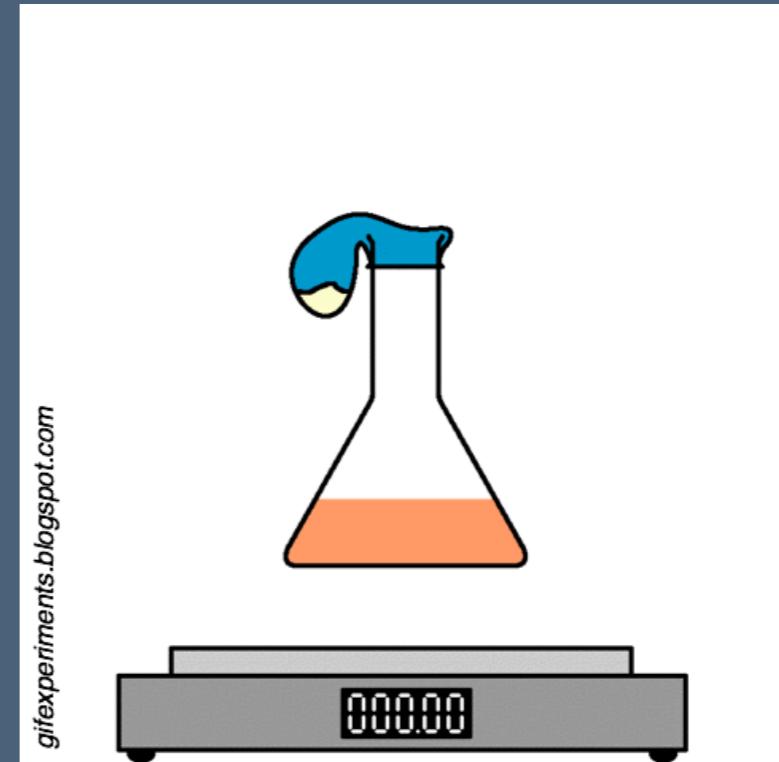
$$\frac{D\rho}{Dt} = \frac{\partial \rho}{\partial t} + (\vec{v} \cdot \nabla) \rho$$

- $= \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) - \rho \nabla \cdot \vec{v}$

- So $\frac{D\rho}{Dt} = -\rho \nabla \cdot \vec{v}$

- We see that in incompressible flow,

$$\frac{D\rho}{Dt} = 0, \text{ then we have } \nabla \cdot \vec{v} = 0$$



Equations of motion

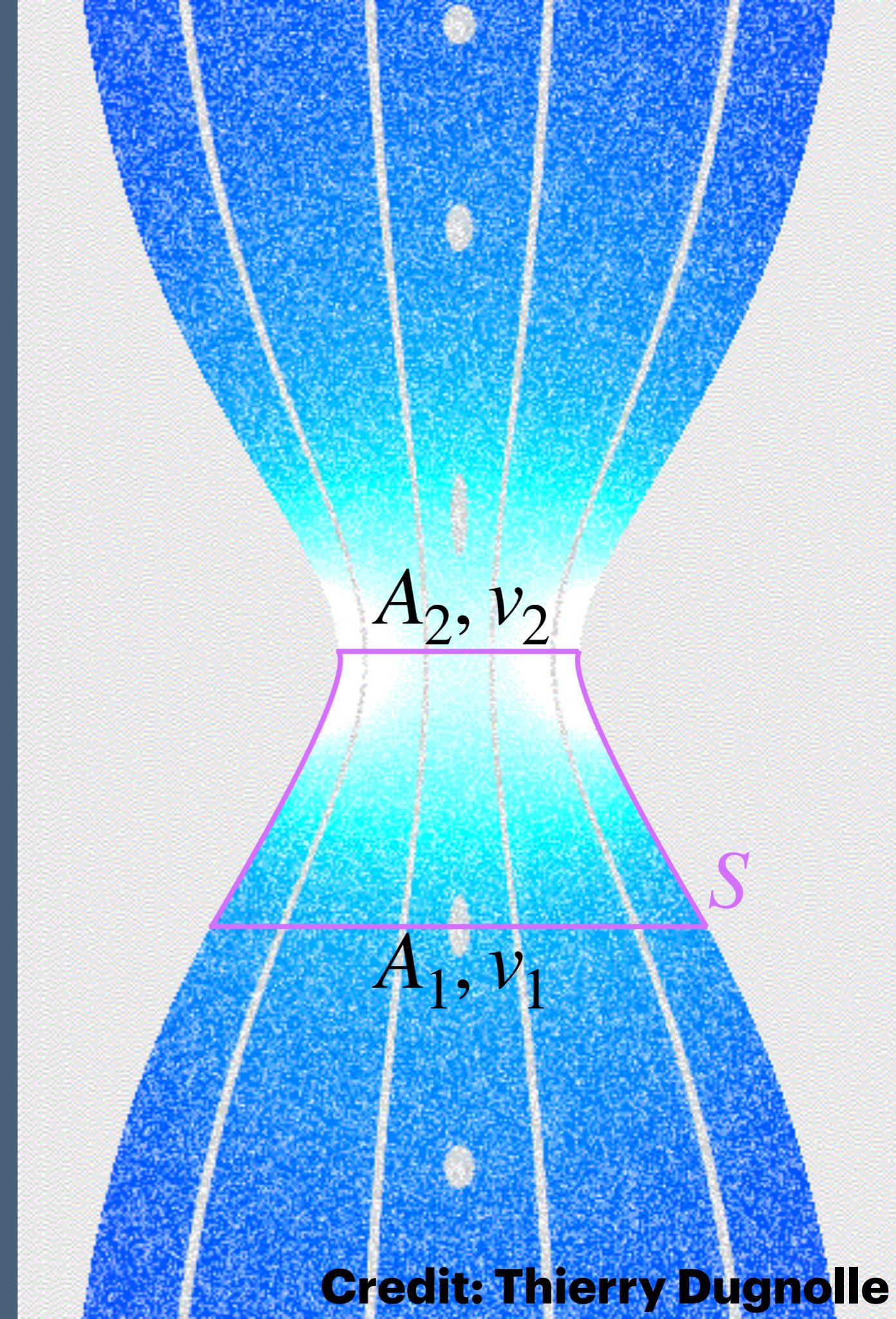
- Cauchy's equation gives us $\frac{\partial \vec{v}}{\partial t} = - (\vec{v} \cdot \nabla) \vec{v} + \rho^{-1} f^*$
- Conservation of mass gives $\frac{\partial \rho}{\partial t} = - (\vec{v} \cdot \nabla) \rho - \rho \nabla \cdot \vec{v}$
- All we need is $f^* = f^* [\rho, \vec{v}] (\vec{x}, t)$ to solve the system of equations!

(Gross, but you've developed these skills already!)

A simple case

Incompressible fluid, steady flow

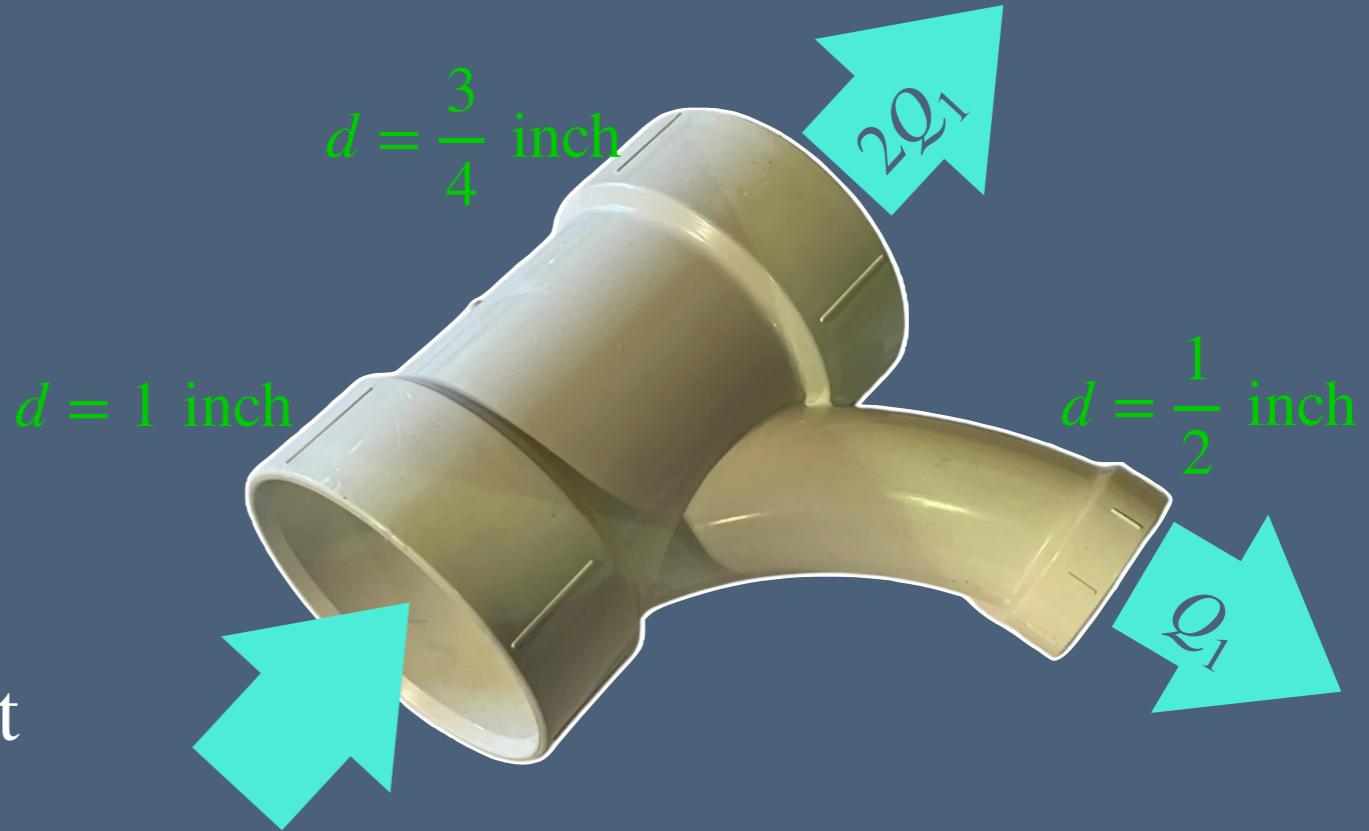
- For an incompressible fluid, we found $\nabla \cdot \vec{v} = 0$
- By Gauss' Law, this is equivalent to $\oint_S \vec{v} \cdot d\vec{S} = 0$
- $\oint_S \vec{v} \cdot d\vec{S} = -A_1 v_1 + A_2 v_2 = 0$
- Leonardo's Law (const. flux):
$$Q = \vec{A} \cdot \vec{v} = \text{constant}$$



Credit: Thierry Dugnolle

Problems

Ideal, incompressible flow



- Leonardo's Law: $Q = Av = \text{constant}$

12.4 A water pipe with diameter 1 inch branches into two pipes with diameters $3/4$ inch and $1/2$ inch. Water is tapped from the largest branch at double the rate as from the other. What is the ratio of velocities in the pipes?

- **2nd problem (conceptual):** A pipe reduces diameter by 50% at a conical constriction. (Hint, recall the holey bottle demo from Tuesday)
 - How does the velocity change across the constriction?
 - How does the pressure change? In particular, on which side of the constriction is the pressure higher? Why? (This is a preview of Bernoulli's effect!)