

# PhysH308

Lagrangian Mechanics

Ted Brzinski, Oct 8, 2024

# Announcements

- Office hours today, tomorrow: zoom both days, only until 1:30 today
- Exam 2
- Last week's slides will go up this afternoon.

# Force on a particle

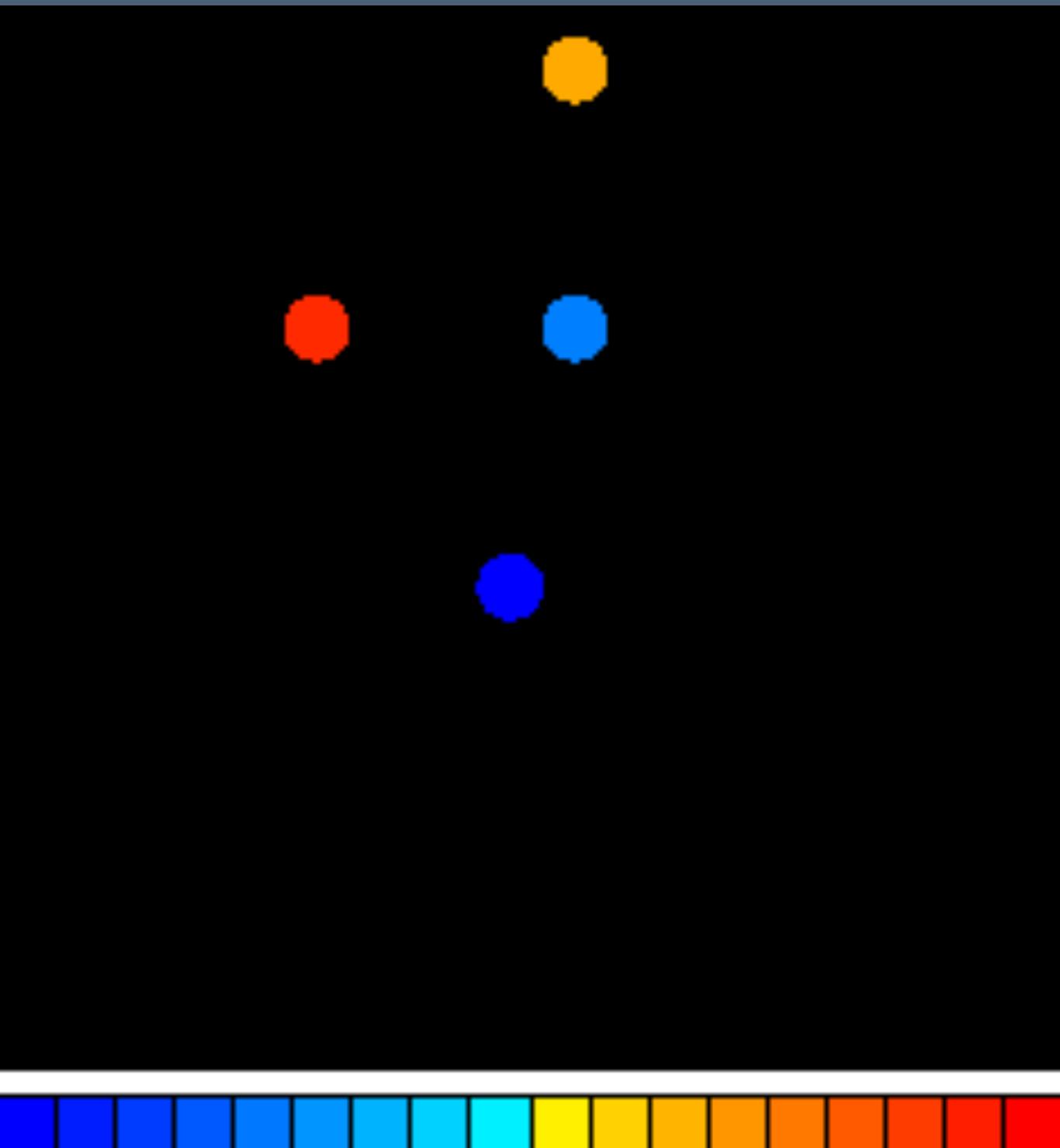
By Newton's 2nd:

$$\begin{aligned} F &= m\ddot{x} = m\dot{v} = \frac{d}{dt}mv \\ &= \frac{d}{dt}m\frac{\partial}{\partial v}\left(\frac{v^2}{2}\right) = \frac{d}{dt}\frac{\partial T}{\partial \dot{x}} \end{aligned}$$

By definition:

$$F = -\frac{\partial}{\partial x}U$$

$$\text{Thus: } -\frac{\partial}{\partial x}U = \frac{d}{dt}\frac{\partial T}{\partial \dot{x}}$$



# Force on a particle

$$-\frac{\partial}{\partial x}U = \frac{d}{dt}\frac{\partial T}{\partial \dot{x}}$$

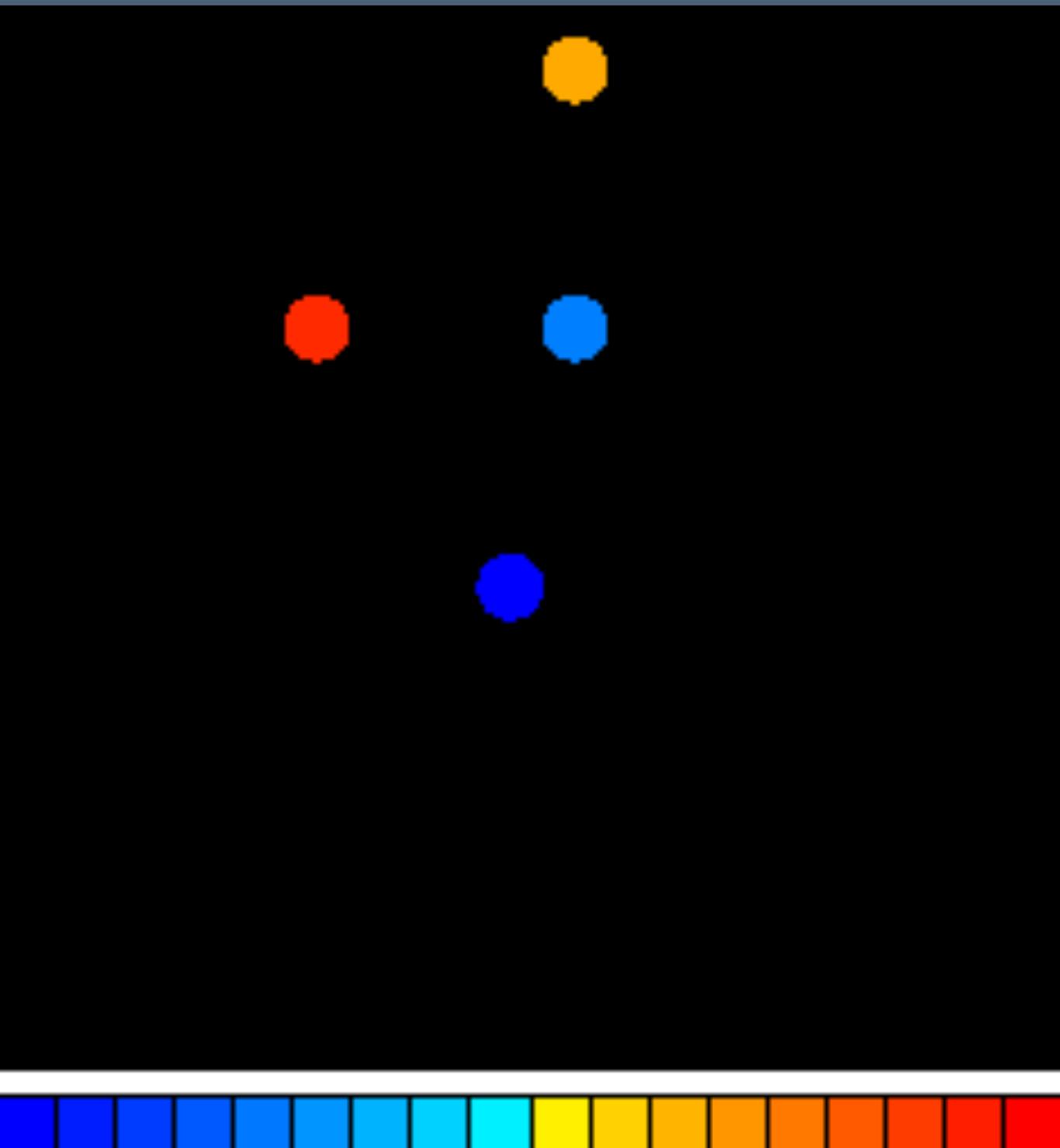
Also note that, in general,

$$\frac{\partial}{\partial x}T = 0 \text{ and } \frac{\partial U}{\partial \dot{x}} = 0$$

So  $\frac{\partial}{\partial x}\mathcal{L} = \frac{d}{dt}\frac{\partial \mathcal{L}}{\partial \dot{x}}$  where

$$\mathcal{L} = T - U$$

So what?



# Force on a particle

$$\frac{\partial}{\partial x} \mathcal{L} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{x}} \text{ where}$$

$$\mathcal{L} = T - U$$

So what?

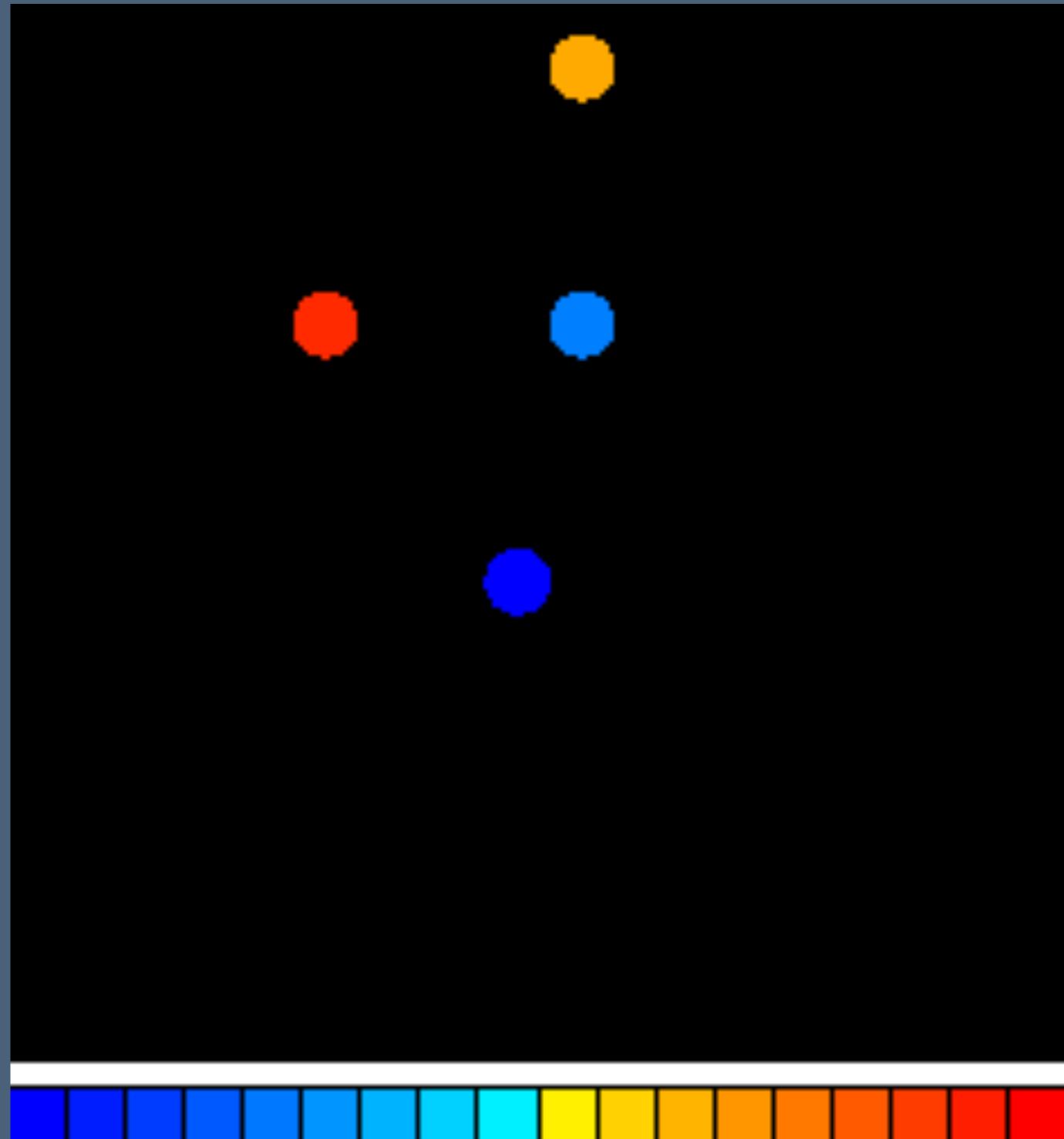
Well, that's E-L for...

$$S = \int_{t_1}^t \mathcal{L} dt$$

The “Action!!!”

What is “action”?

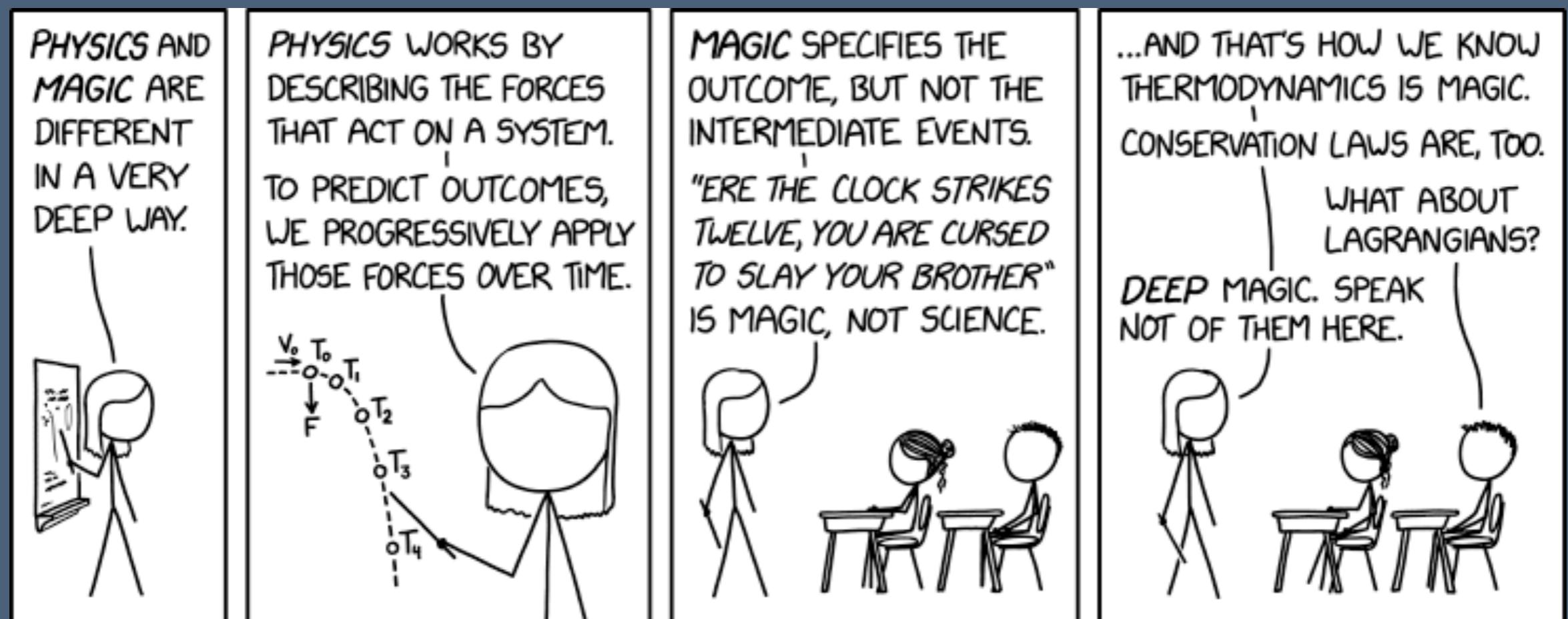
The thing minimized by paths described by Newton’s 2nd law.



# Okay Ted. Fine. But why would I do that?

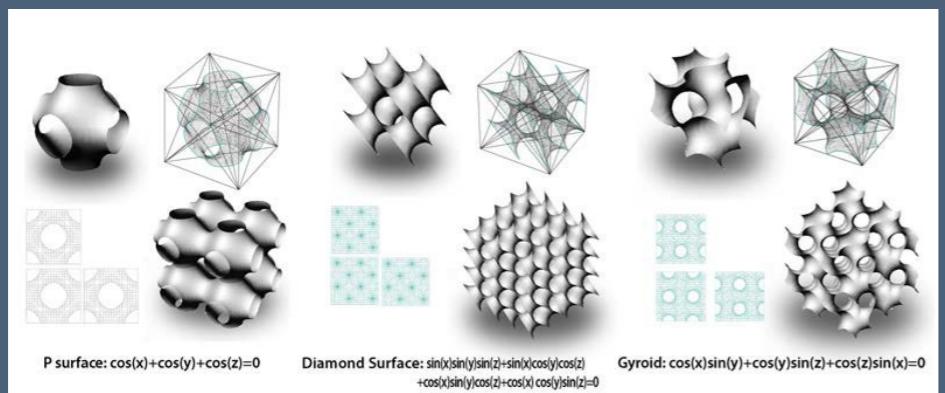
(Fair question)

- It's often easier to solve E-L for  $S$  than to solve a bunch of  $F = ma$ . Especially for coupled/constrained motion (we'll see that in practice tomorrow).
- We get the equation of motion from a statement that  $F = F$ , weird!



# Problems

- 6.19: our last problem from Chap. 6, finding a minimal surface! (Soap films, planar defects in LC, 3D printing)



- 7.2: Langrangian mech reproduces a familiar result!

