Maximum Flow

Ford-Fulkerson Algorithm

Flow Networks

- A flow network G = (V, E)
 - directed graph in which each edge $(u, v) \in E$
 - has a nonnegative *capacity* $c(u, v) \ge 0$.
 - if E contains an edge (u, v), then there is no edge (v, u) in the reverse direction.
 - two vertices in a flow network:
 - a source s and a sink t.

Flows

- A *flow* in G is a real-valued function f: V X V → R
 that satisfies the following two properties:
 - Capacity constraint: For all $u, v \in V$, we require $0 \le f(u, v) \le c(u, v)$.
 - Flow conservation: For all $u \in V \{s, t\}$, we require

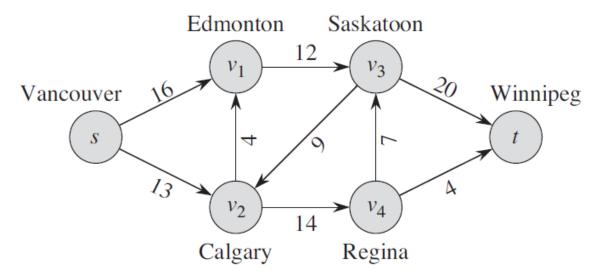
$$\sum_{v \in V} f(v, u) = \sum_{v \in V} f(u, v)$$

• The *value* |f| of a flow f is defined as

$$|f| = \sum_{v \in V} f(s, v) - \sum_{v \in V} f(v, s)$$

Applications

- Fluid in pipes
- Current in electrical circuits
- Traffic on roads
- Data flow in computer networks
- Money flow in economy



Ford-Fulkerson Method

 It is called "method" rather than an "algorithm" because it encompasses several implementations with differing running times.

FORD-FULKERSON-METHOD(G, s, t)

- 1. initialize flow f to 0
- 2. while there exists an augmenting path p in the residual network G_f
- 3. augment flow *f* along p
- 4. return *f*

Some Terms

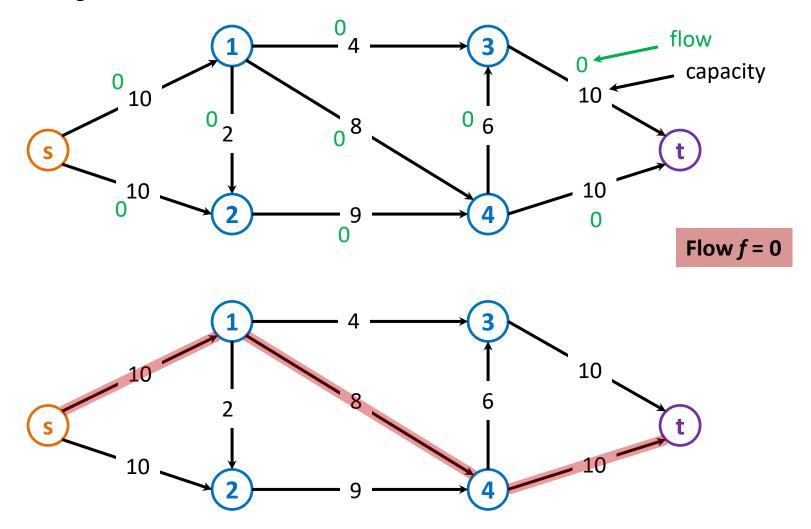
Residual Network:

- Only edges from G that can still have more flow.
- Considering a pair of vertices u, v ∈ V, the residual capacity c_f(u, v):

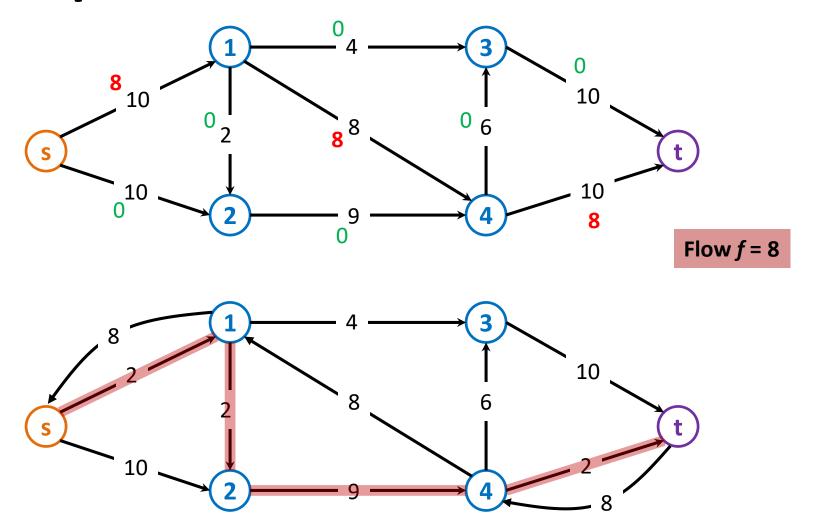
$$c_f(u, v) = \begin{cases} c(u, v) - f(u, v) & \text{if } (u, v) \in E, \\ f(v, u) & \text{if } (v, u) \in E, \\ 0 & \text{otherwise}. \end{cases}$$

Augmenting Path:

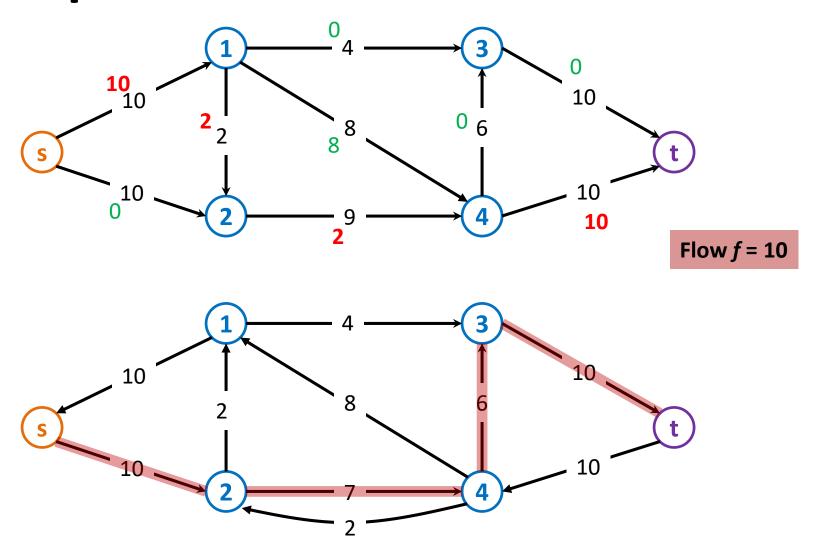
• Path from s to t in residual network, G_f



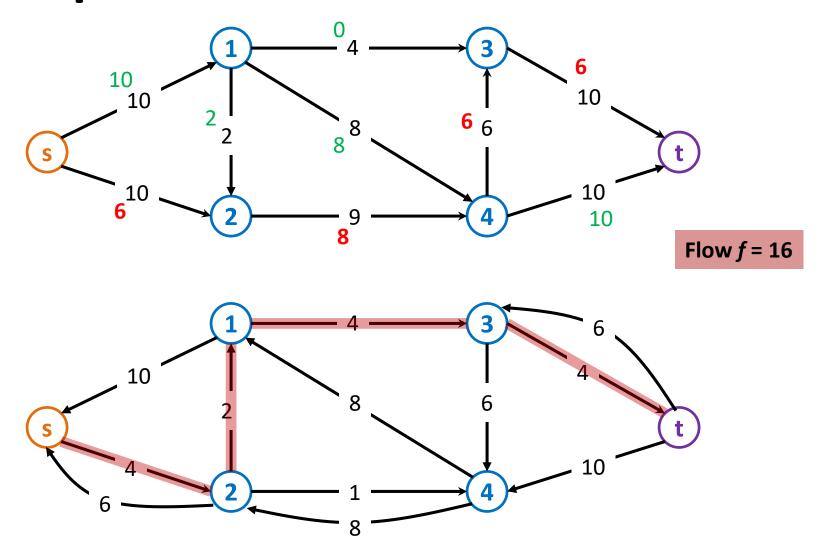
Residual Network



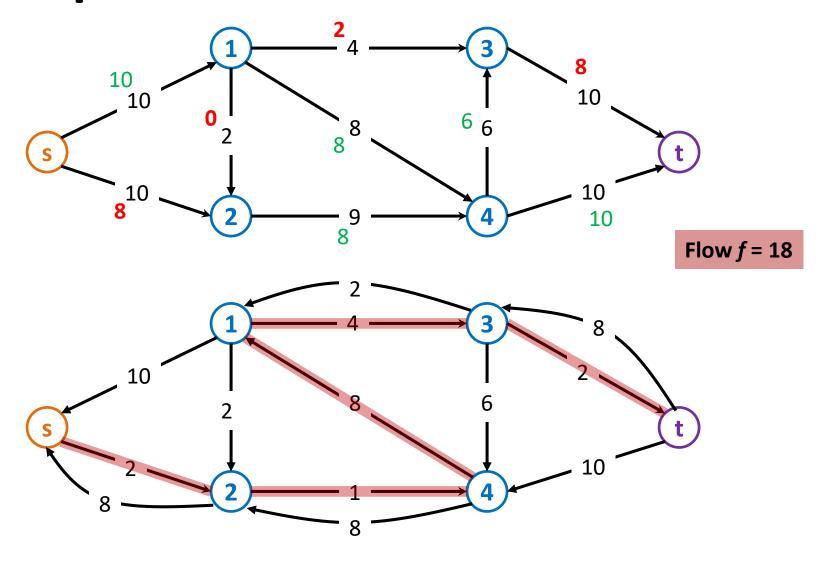
Residual Network



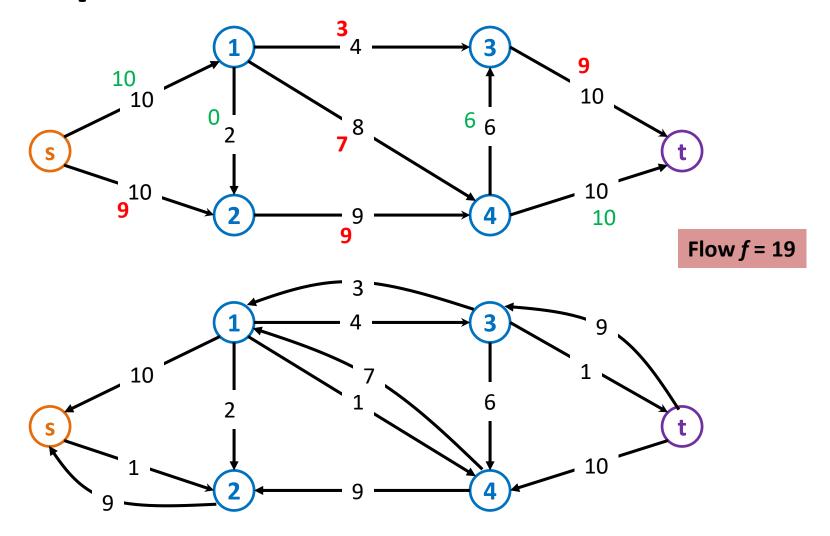
Residual Network



Residual Network



Residual Network



Residual Network

Ford-Fulkerson Algorithm

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FORD-FULKERSON(G, s, t)

1 for each edge (u, v) \in G.E

2 (u, v).f = 0

3 while there exists a path p from s to t in the residual network G_f

4 c_f(p) = \min\{c_f(u, v) : (u, v) \text{ is in } p\}

5 for each edge (u, v) in p

6 if (u, v) \in E

7 (u, v).f = (u, v).f + c_f(p)

8 else (v, u).f = (v, u).f - c_f(p)
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Analysis

- If f *denotes a maximum flow in the transformed network, then a straightforward implementation of FORD-FULKERSON executes
 - the while loop of lines 3–8 at most $|f^*|$ times, since the flow value increases by at least one unit in each iteration.
- The time to find a path in a residual network is O(V + E') =
 O(E) if we use either depth-first search or breadth-first search.
- Each iteration of the **while** loop thus takes O(E) time, as does the initialization in lines 1–2, making the total running time of the FORD-FULKERSON algorithm $O(E \mid f^* \mid)$.

Cuts of Flow Networks

- A cut (S, T) of flow network G = (V, E) is a partition of V into S and T = V S such that s ∈ S and t ∈ T.
- If f is a flow, then the net flow f (S, T) across the cut (S, T) is defined to be

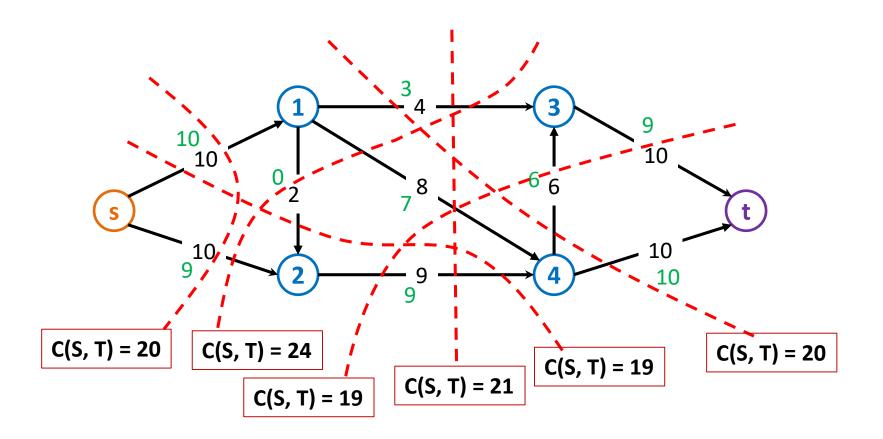
$$f(S,T) = \sum_{u \in S} \sum_{v \in T} f(u,v) - \sum_{u \in S} \sum_{v \in T} f(v,u)$$

• The *capacity* of the cut (S, T) is

$$c(S,T) = \sum_{u \in S} \sum_{v \in T} c(u,v)$$

Minimum Cut

• A *minimum cut* of a network is a cut whose capacity is minimum over all cuts of the network.



Max-flow Min-cut Theorem

If f is a flow in a flow network G = (V, E) with source s and sink t, then the following conditions are equivalent:

- 1. f is a maximum flow in G.
- 2. The residual network G_f contains no augmenting paths.
- 3. |f| = c(S, T) for some cut (S, T) of G.

Proof: Self-study