Digital Image Processing (CSE/ECE 478)

Lecture # 12:Morphological operations

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Today's Lecture

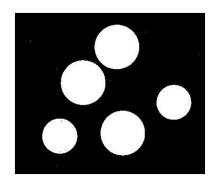
- Morphology is a branch of biology dealing with the study of the form and structure of organisms and their specific structural features (wikipedia)
- Shape, form, structure
 - Useful for extracting and describing image component regions
 - Usually applied to binary images
 - Based on set theory

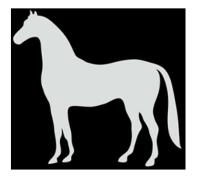
Today's Lecture

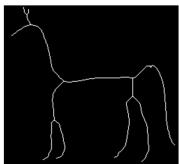
- Set theory
- Binary operations: dilation, erosion, opening, closing
- Connected components
- Morphological algorithms

Binary Images

- Thresholding (im2bw Matlab)
- Binary regions
 - Count number of binary regions
 - Measure shape
- Typical applications
 - Character and texts
 - Maps
 - Fingerprints







Set Theory Concepts

- 2D binary image as a set of points
 - A is unorderd set of pairs (x,y) such that the image value at (x,y) is equal to 1

$$A = \{(x, y) \mid I(x, y) = 1\}$$

- Union of two sets $(A \cup B)$
 - The set belonging to A,B, or both
- Intersection of two sets $(A \cap B)$
 - The set belonging to both A and B
- w "is an element of" set A
 - $w \in A$

Set Theory Concepts

- Complement (A^c)
 - The set elements that are not in A

$$A^c = \{ w \mid w \notin A \}$$

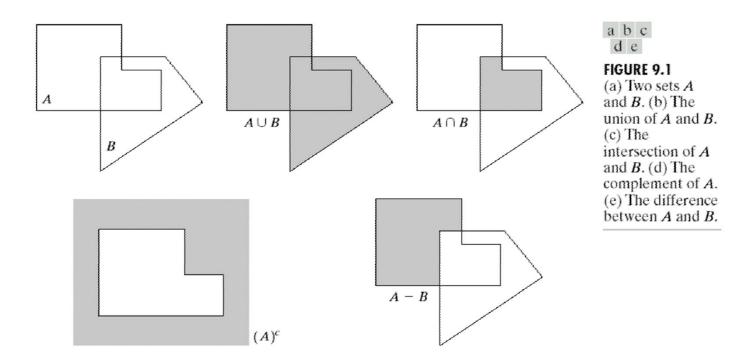
- Difference of two sets (A B)
 - The set belonging to A, but not to B

$$A - B = \{ w \mid w \in A, w \notin B \}$$

- Subset $(A \subseteq B)$
 - A is subset of B if every element of A is also in B
- Empty set {}
 - **-** φ

Set Operations

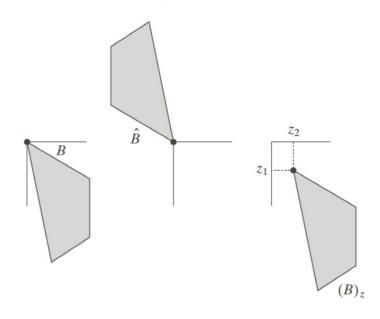
$$A = \{(x, y) \mid I_A(x, y) = 1\}, \quad B = \{(x, y) \mid I_B(x, y) = 1\}$$



Reflection and Translation

$$\hat{B} = \left\{ \vec{w} \middle| \vec{w} = -\vec{b}, \quad \text{for } \vec{b} \in B \right\}$$

$$(B)_z = \left\{ \vec{c} \middle| \vec{c} = \vec{b} + \vec{z}, \quad \text{for } \vec{b} \in B \right\}$$



a b c

FIGURE 9.1

- (a) A set, (b) its reflection, and (c) its translation
- by z.

Structuring Elements (SEs)

- Morphological operations are defined based on "structuring elements (SEs)"
- SEs → small sets or sub images used to probe an image under study

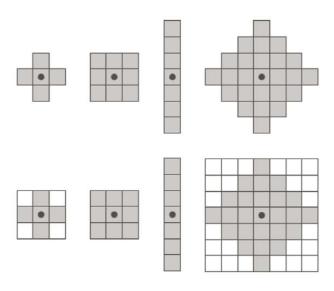
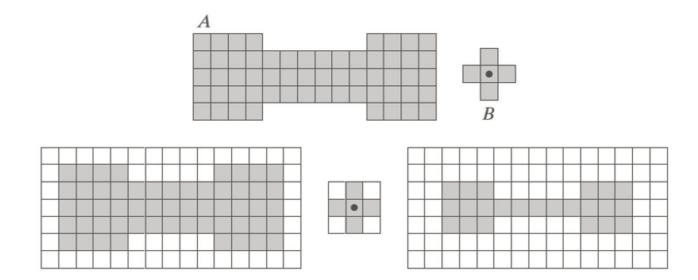


FIGURE 9.2 First row: Examples of structuring elements. Second row: Structuring elements converted to rectangular arrays. The dots denote the centers of the SEs.

The dots denote the centers of the SEs

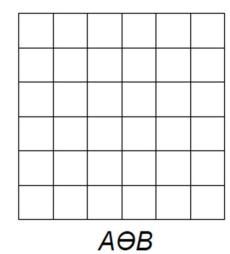
SE operation example

- Run B over A (origin of B visits every element of A)
- Mark if B is completely contained in A



The erosion of set A by set (structuring element) B is

$$A \ominus B = \{z | (B)_z \subseteq A\}$$



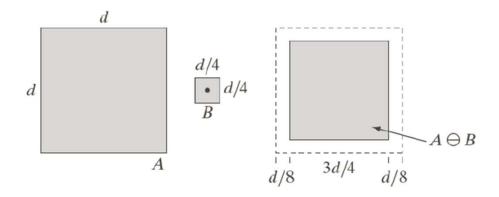
The erosion of set A by set (structuring element) B is

$$A \ominus B = \{z | (B)_z \subseteq A\}$$

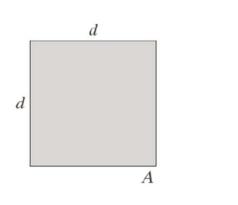
Completely contained is equivalent to not sharing any common elements with the background

$$A \ominus B = \{z | (B)_z \cap A^c = \emptyset\}$$

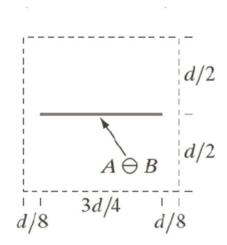
More examples



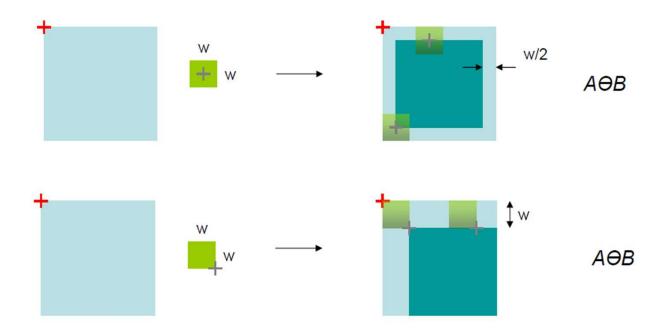
More examples





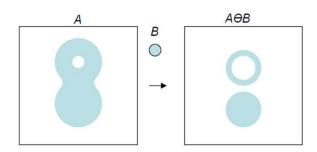


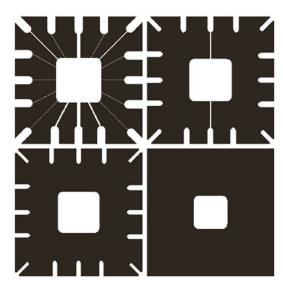
Changing the center



- Enlarges holes, breaks thin parts, shrinks object
- Not commutative

 $A\Theta B \neq B\Theta A$





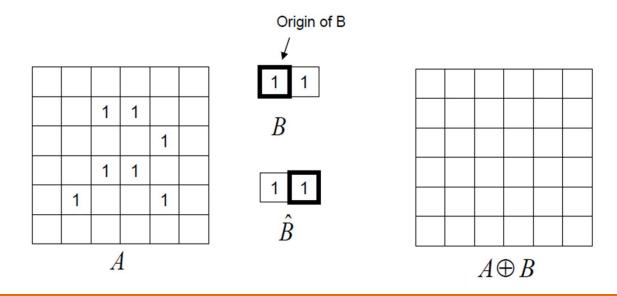
a b c d

FIGURE 9.5 Using erosion to remove image components. (a) A 486 × 486 binary image of a wirebond mask. (b)–(d) Image eroded using square structuring elements of sizes 11 × 11, 15 × 15, and 45 × 45, respectively. The elements of the SEs were all 1s.

The dilation of set A by set (structuring element) B is

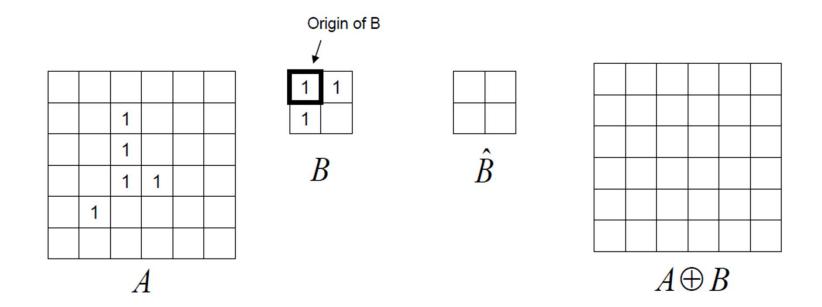
$$A \oplus B = \{z | (\hat{B})_z \cap A \neq \emptyset\}$$

• Interpretation: reflect B, shift by z, if it overlaps with even one element, output 1



The dilation of set A by set (structuring element) B is

$$A \oplus B = \{z | (\widehat{B})_z \cap A \neq \emptyset\}$$



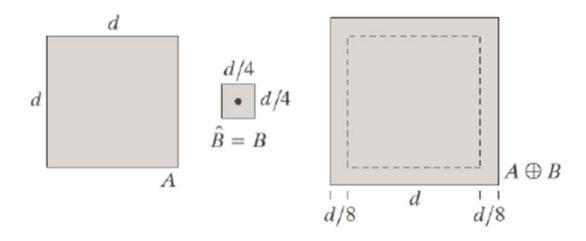
• The dilation of set A by set (structuring element) B is

$$A \oplus B = \{z | (\hat{B})_z \cap A \neq \emptyset\}$$

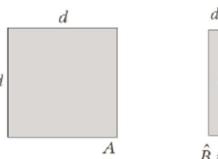
Can be equivalently written as:

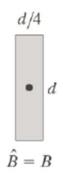
$$A \oplus B = \{z | [(\hat{B})_z \cap A] \subseteq A\}$$

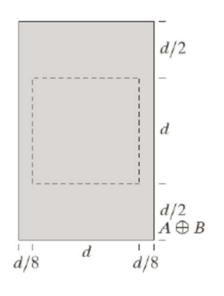
More examples



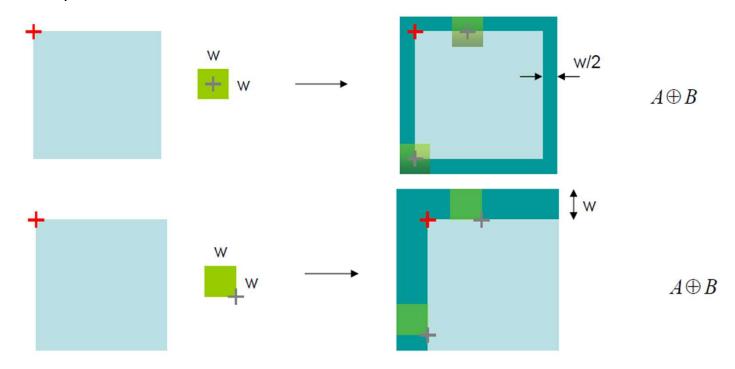
More examples



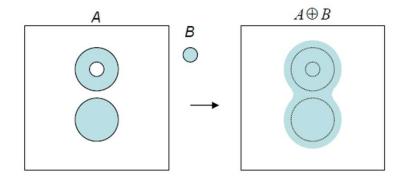




More examples



• Fills in holes, thickens thin parts, grows object



Historically, certain computer programs were written using only two digits rather than four to define the applicable year. Accordingly, the company's software may recognize a date using "00" as 1900 rather than the year 2000.

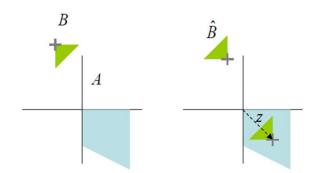
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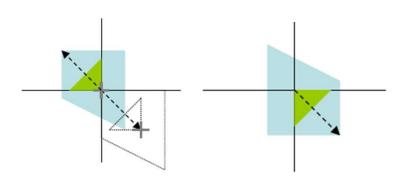
0	1	0
1	1	1
0	1	0

DILATION Properties

- Commutative $A \oplus B = B \oplus A$
- Associative $A \oplus (B \oplus C) = (A \oplus B) \oplus C$
- Proof

$$A \oplus B = \left\{ z \mid (\hat{B})_z \cap A \neq \varnothing \right\}$$
$$= \left\{ z \mid \hat{B} \cap (A)_{-z} \neq \varnothing \right\}$$
$$= \left\{ z \mid B \cap (\hat{A})_z \neq \varnothing \right\} = B \oplus A$$





DUALITY

$$(A \Theta B)^c = A^c \oplus \hat{B}$$

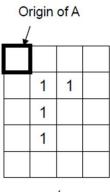
Proof

$$A\Theta B = \{z \mid (B)_z \subseteq A\} = \{z \mid (B)_z \cap A^c = \emptyset\}$$

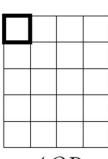
If set $(B)_z$ is contained in A, then the intersection of $(B)_z$ with the complement of A is empty

$$(A\Theta B)^{c} = \left\{ z \mid (B)_{z} \cap A^{c} = \varnothing \right\}^{c}$$
$$= \left\{ z \mid (B)_{z} \cap A^{c} \neq \varnothing \right\}$$
$$= A^{c} \oplus \hat{B}$$

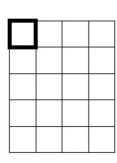
DUALITY



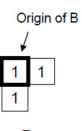
 \boldsymbol{A}



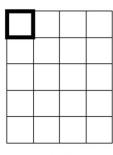
 $A\Theta B$



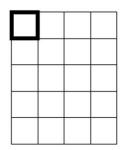
 A^c



B



 $(A\Theta B)^c$



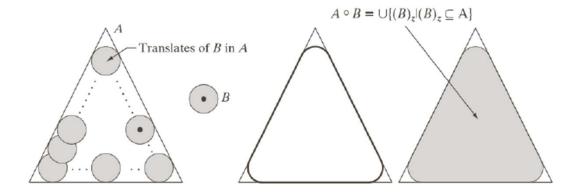
 $A^c \oplus \hat{B}$

OPENING

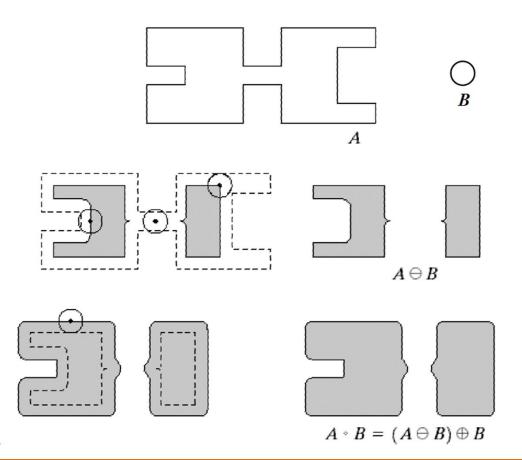
• Erosion followed by a dilation

$$A \circ B = (A \theta B) \oplus B$$

• Smoothes contour, breaks narrow isthmuses, and eliminate thin protrusions



Example OPENING

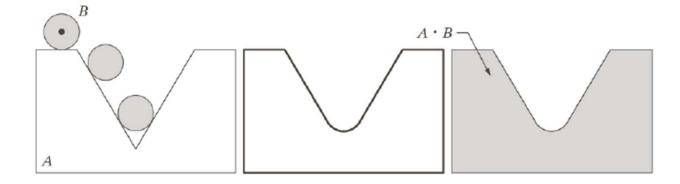


CLOSING

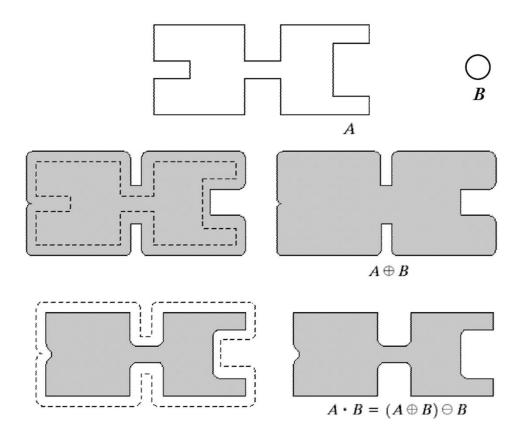
• Dilation followed by a erosion

$$A \bullet B = (A \oplus B)\theta B$$

• Fuses narrow bleaks and long thin gulfs, eliminates small holes, and fills gap in contour



Example CLOSING



Application



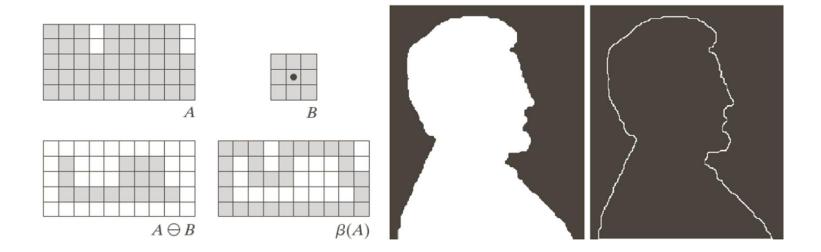
Morphological Algorithms

- Boundary Extraction
- Hit and Miss transform
- Region Filling
- Convex Hull
- Skeletonization

Boundary Extraction

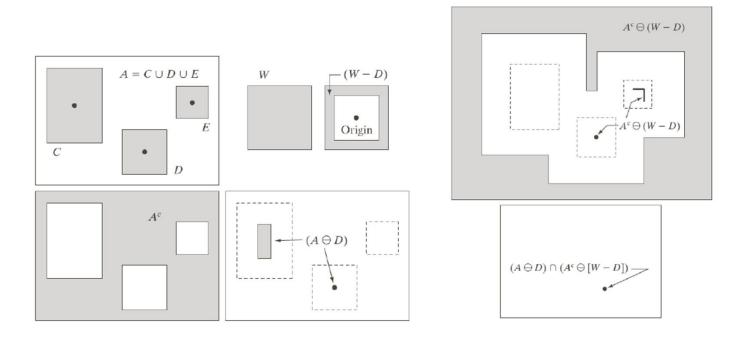
• Set difference between A and its erosion with B

$$\beta(A) = A - (A \ominus B)$$

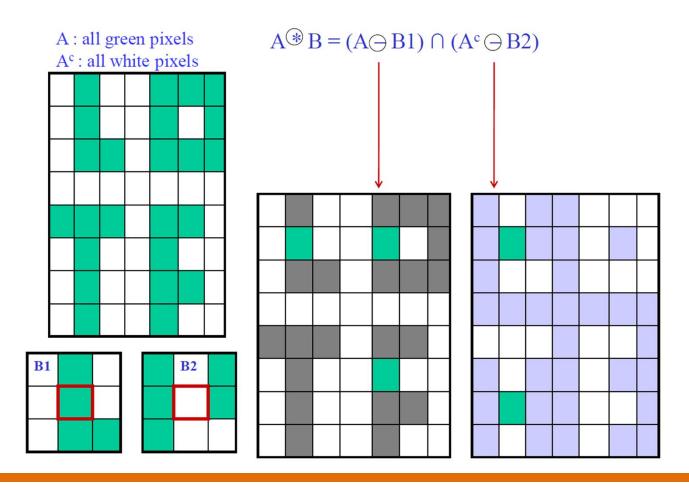


Hit and Miss Transform

$$A\circledast B=(A\ominus D)\cap [A^c\ominus (W-D)]$$



Hit and Miss Transform



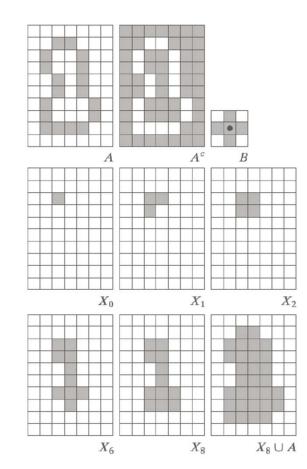
Source: J. Sivaswami

Region Filling

- Let A be a the set of 8-connected boundary points
- Start with a point inside the region
- Dilate
- Take intersection with compliment of A (repeat)

$$X_k = (X_{k-1} \oplus B) \cap A^c$$
, $k = 1,2,3...$

Stop when no more changes



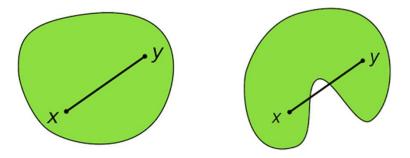
Region Filling

Example

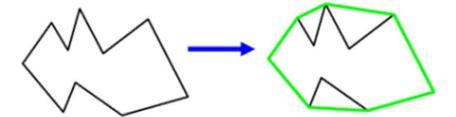


Convex Hull

Convex set

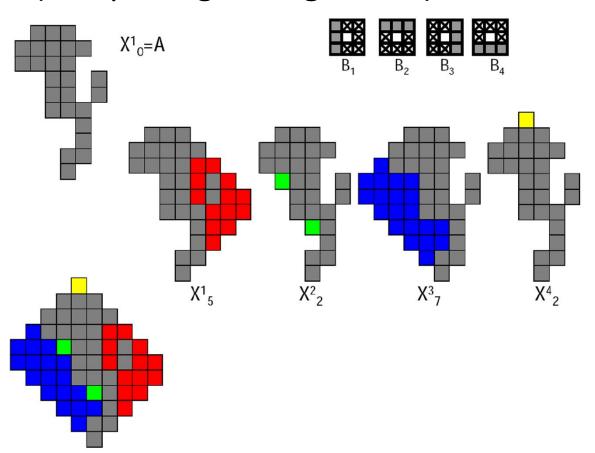


• Convex Hull : minimal envelope



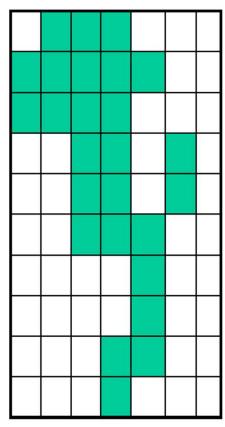
Convex Hull (Morphological Algorithm)

- Iteratively perform Hit or Miss transform with each SE, until convergence
- 2. Take union of the four results



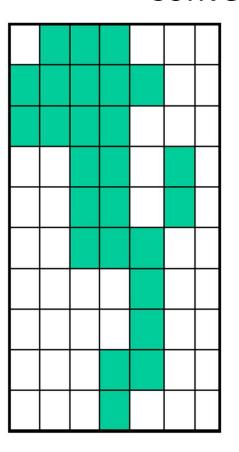
Convex Hull (alternate approach)

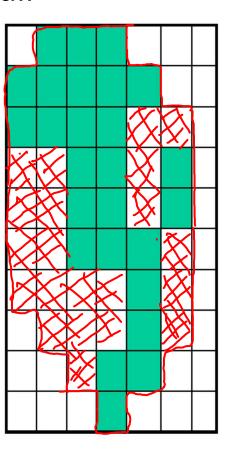
- 1. For every pixel i find the number n_i of its neighbours which belong to the object
- 2. If $n_i > 3$ then mark the object pixel I
- 3. Repeat 1 and 2 until there are no pixels with more than 3 neighbours



Source: J. Sivaswami

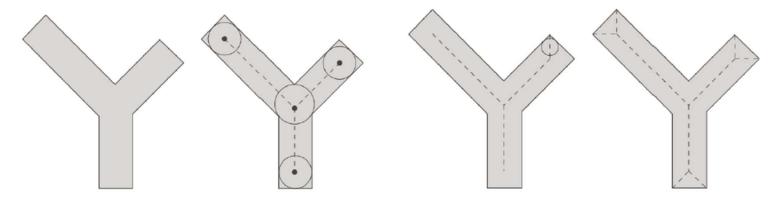
Convex Hull



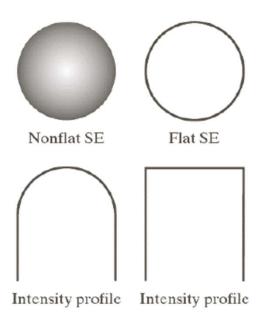


Skeletons

- Set of all points that are equally distant from two closest points of the object boundary
- A concise representation of a shape



- Analogy
 - start a fire at the boundary, let it burn inward
 - Points where fire is quenched are the skeleton

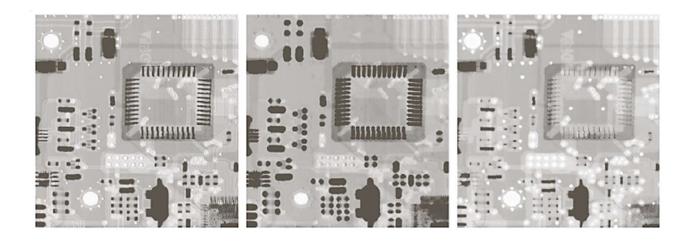


a b c d

FIGURE 9.34
Nonflat and flat structuring elements, and corresponding horizontal intensity profiles through their center. All examples in this section are based on flat SEs.

Erosion and Dilation

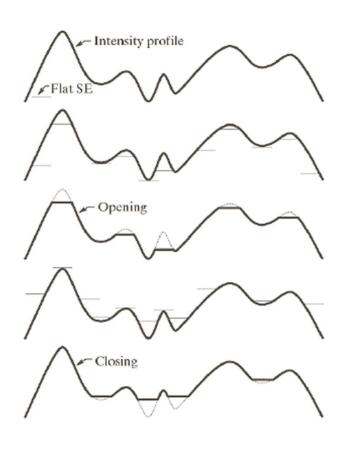
$$[f \ominus b](x,y) = \min_{(s,t) \in b} \{ f(x+s,y+t) \} \qquad [f \oplus b](x,y) = \max_{(s,t) \in b} \{ f(x-s,y-t) \}$$



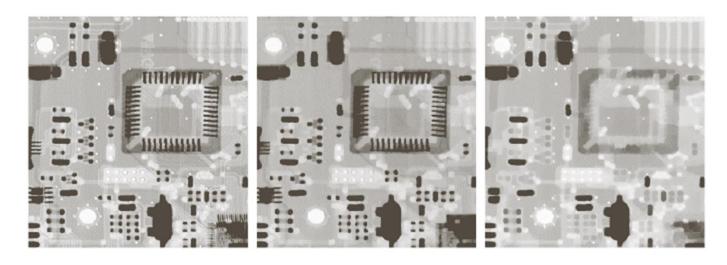
Opening and Closing

$$[f \circ b] = (f \ominus b) \oplus b$$

$$[f \cdot b] = (f \oplus b) \ominus b$$



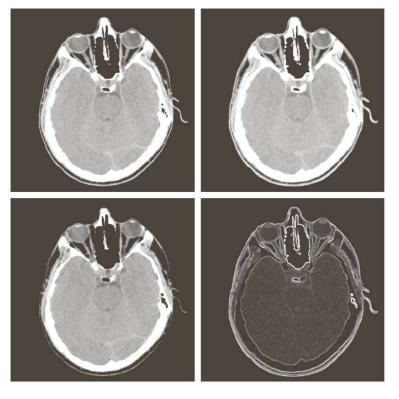
Opening and Closing



a b c

FIGURE 9.37 (a) A gray-scale X-ray image of size 448×425 pixels. (b) Opening using a disk SE with a radius of 3 pixels. (c) Closing using an SE of radius 5.

Morphological Gradient



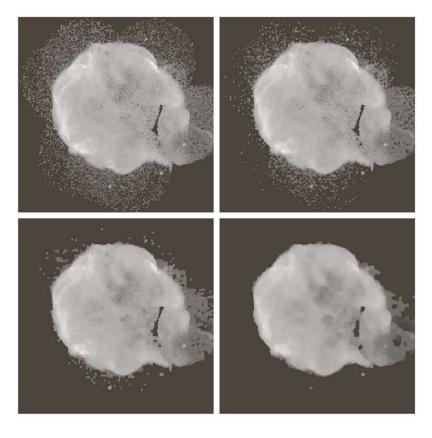
a b c d

FIGURE 9.39

- (a) 512×512 image of a head CT scan.
- (b) Dilation.
- (c) Erosion.
- (d) Morphological gradient, computed as the difference between (b) and (c). (Original image courtesy of Dr. David R. Pickens, Vanderbilt University.)

Dialation - Erosion

Smoothing



a b c d

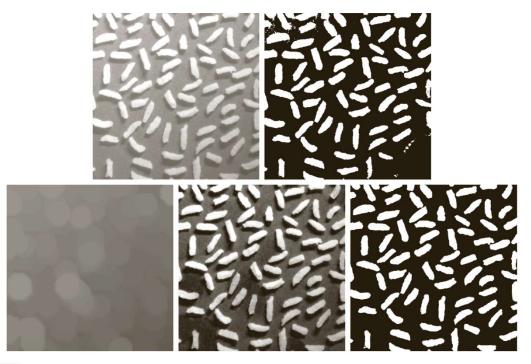
FIGURE 9.38
(a) 566 × 566
image of the
Cygnus Loop
supernova, taken
in the X-ray band
by NASA's
Hubble Telescope.
(b)–(d) Results of
performing
opening and
closing sequences
on the original
image with disk
structuring
elements of radii,
1, 3, and 5,
respectively.
(Original image
courtesy of
NASA.)

Applications: Top hat transform

- Open the image with an structuring element, subtract it from original
- Leaves only details smaller than the structuring element

$$T_{hat}(f) = f - (f \circ b)$$

Top hat transform



a b c d e

FIGURE 9.40 Using the top-hat transformation for *shading correction*. (a) Original image of size 600×600 pixels. (b) Thresholded image. (c) Image opened using a disk SE of radius 40. (d) Top-hat transformation (the image minus its opening). (e) Thresholded top-hat image.