

Software Testing



Lecture 20

Covering Graphs

Graphs are the most commonly used structure for testing

Graphs can come from many sources

- Control flow graphs
- Design structure
- FSMs and statecharts
- Use cases

Tests usually are intended to “cover” the graph in some way

Definition of a Graph

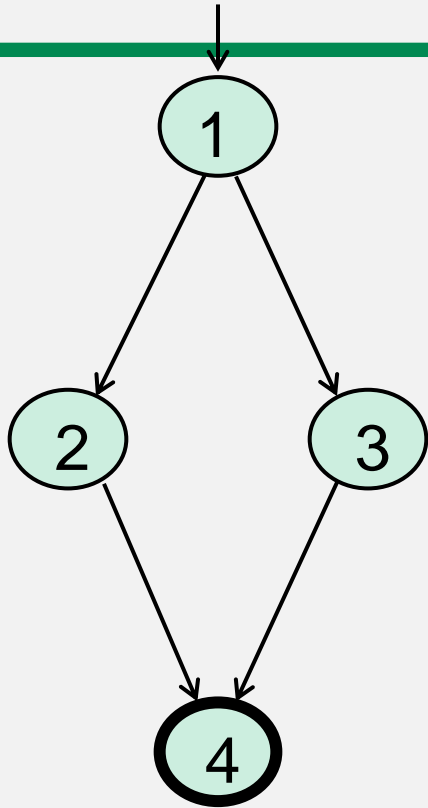
A set N of nodes, N is **not empty**

A set N_o of **initial** nodes, N_o is **not empty**

A set N_f of **final** nodes, N_f is **not empty**

A set E of edges, each edge from one node to another
(n_i, n_j), i is predecessor, j is successor

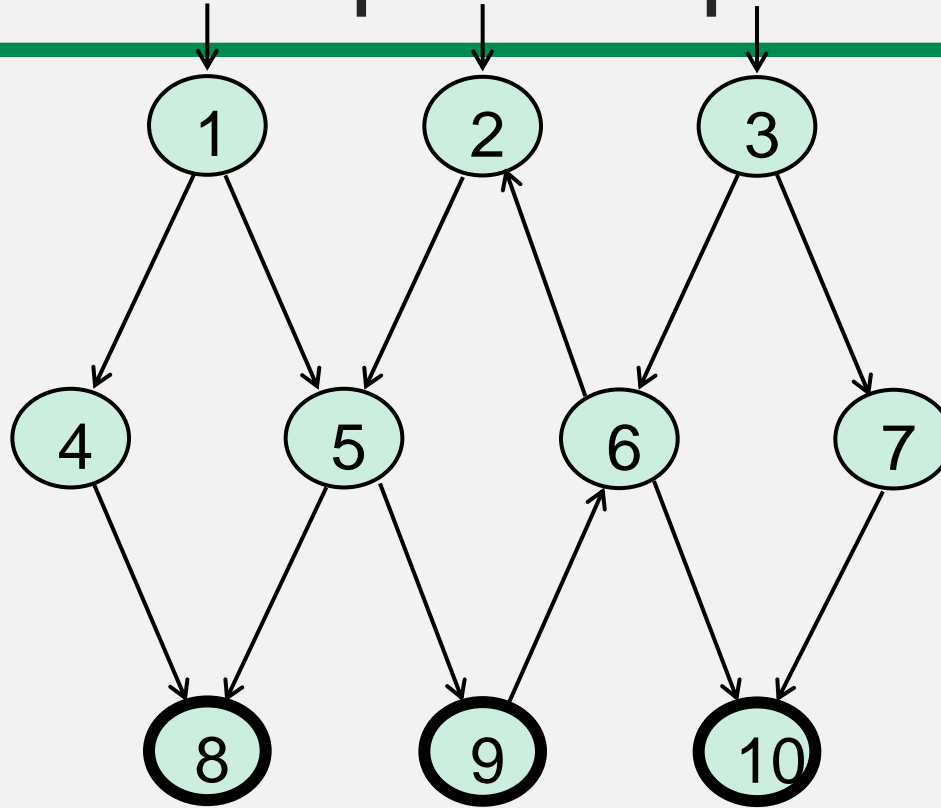
Example Graphs



$$N_0 = \{ 1 \}$$

$$N_f = \{ 4 \}$$

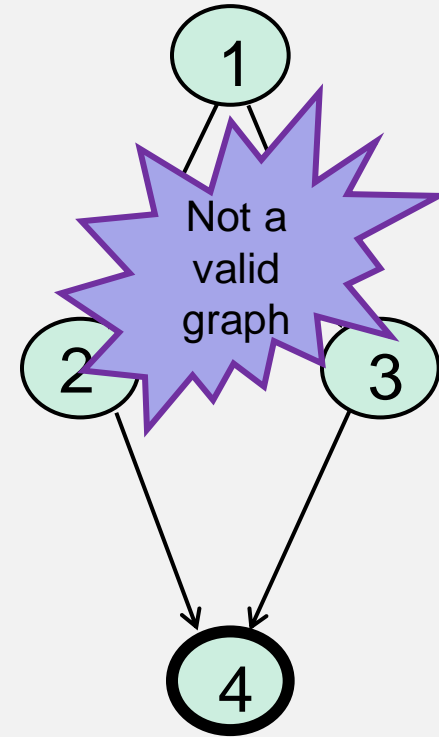
$$E = \{ (1,2), (1,3), (2,4), (3,4) \}$$



$$N_0 = \{ 1, 2, 3 \}$$

$$N_f = \{ 8, 9, 10 \}$$

$$E = \{ (1,4), (1,5), (2,5), (3,6), (3,7), (4,8), (5,8), (5,9), (6,2), (6,10), (7,10), (9,6) \}$$



$$N_0 = \{ \}$$

$$N_f = \{ 4 \}$$

$$E = \{ (1,2), (1,3), (2,4), (3,4) \}$$

Paths in Graphs

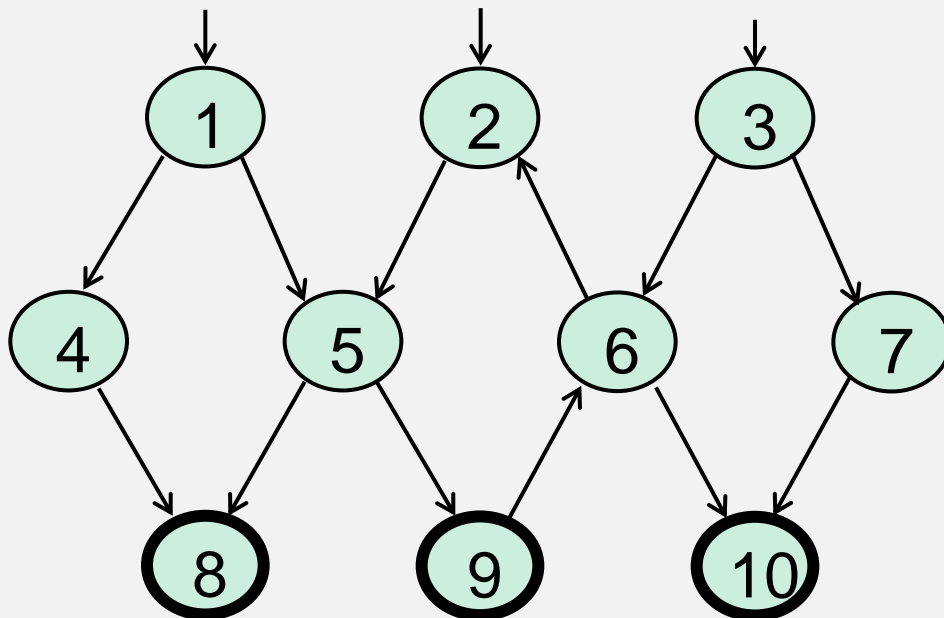
Path : A sequence of nodes – $[n_1, n_2, \dots, n_M]$

Each pair of nodes is an edge

Length : The number of edges

A single node is a path of length 0

Subpath : A subsequence of nodes in p is a subpath of p



A Few Paths

[1, 4, 8]

[2, 5, 9, 6, 2]

[3, 7, 10]

Test Paths and SESEs

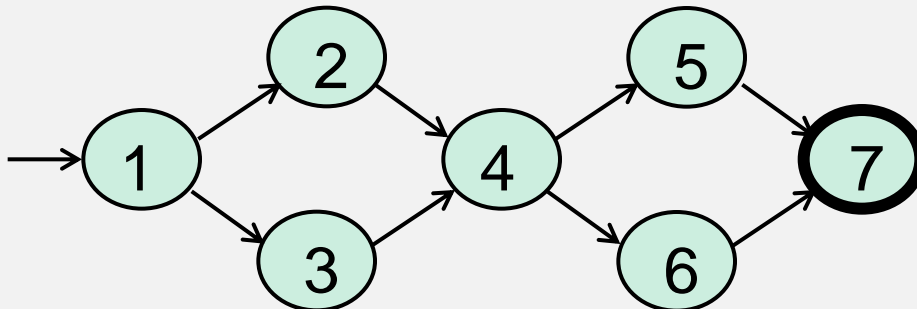
Test Path : A path that starts at an initial node and ends at a final node

Test paths represent execution of test cases

- Some test paths can be executed by many tests
- Some test paths cannot be executed by any tests

SESE graphs : All test paths start at a single node and end at another node

- Single-entry, single-exit
- N_0 and N_f have exactly one node



Double-diamond graph

Four test paths

[1, 2, 4, 5, 7]

[1, 2, 4, 6, 7]

[1, 3, 4, 5, 7]

[1, 3, 4, 6, 7]

Visiting and Touring

Visit : A test path p *visits* node n if n is in p

A test path p *visits* edge e if e is in p

Tour : A test path p *tours* subpath q if q is a subpath of p

Path [1, 2, 4, 5, 7]

Visits nodes 1, 2, 4, 5, 7

Visits edges (1, 2), (2, 4), (4, 5), (5, 7)

Tours subpaths [1, 2, 4], [2, 4, 5], [4, 5, 7], [1, 2, 4, 5], [2, 4, 5, 7], [1, 2, 4, 5, 7]

(Also, each edge is technically a subpath)

Tests and Test Paths

path (t) : The test path executed by test t

path (T) : The set of test paths executed by the set of tests T

Each test executes one and only one test path

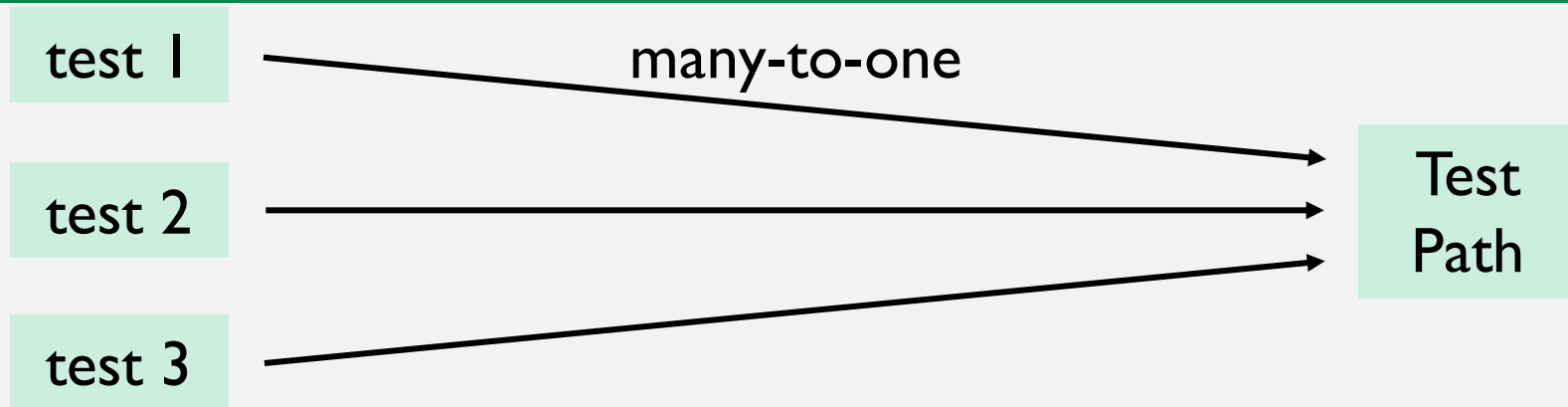
Complete execution from a start node to an final node

A location in a graph (node or edge) can be reached from another location if there is a sequence of edges from the first location to the second

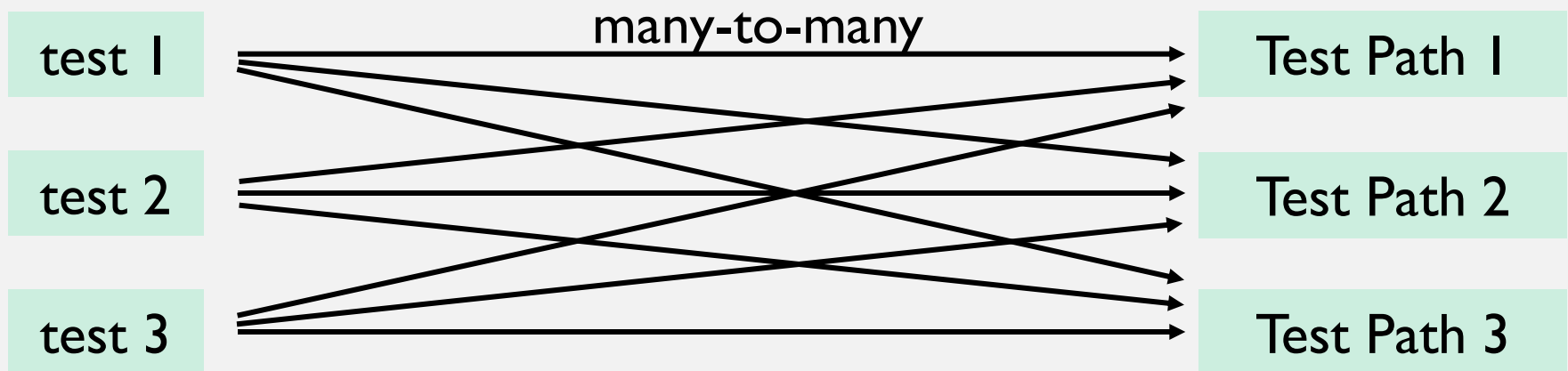
Syntactic reach : A subpath exists in the graph

Semantic reach : A test exists that can execute that subpath

Tests and Test Paths



Deterministic software—test always executes the same test path



Non-deterministic software—the same test can execute different test paths

Testing and Covering Graphs

We use graphs in testing as follows :

1. Develop a **model of the software as a graph**
2. **Require tests to visit or tour** specific sets of nodes, edges or subpaths

- **Test Requirements (TR)** : Describe properties of test paths
- **Test Criterion** : Rules that define test requirements
- **Satisfaction** : *Given a set TR of test requirements for a criterion C , a set of tests T satisfies C on a graph if and only if for **every test requirement in TR** , there is a test path in $path(T)$ that meets the test requirement TR*
- **Structural Coverage Criteria** : Defined on a graph just in terms of nodes and edges
- **Data Flow Coverage Criteria** : Requires a graph to be annotated with references to variables

Node and Edge Coverage

The first (and simplest) two criteria require that each node and edge in a graph be executed

Node Coverage (NC) : Test set T satisfies node coverage on graph G iff for every syntactically reachable node n in N , there is some path p in $path(T)$ such that p visits n .

- This statement is a bit cumbersome, so we abbreviate it in terms of the set of test requirements

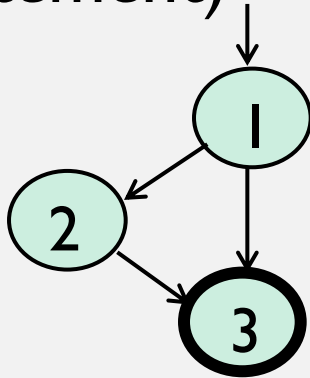
Node Coverage (NC) : TR contains each reachable node in G .

Node and Edge Coverage

Edge coverage is slightly stronger than node coverage

Edge Coverage (EC) : TR contains each reachable path of length up to l , inclusive, in G .

- The phrase “*length up to l* ” allows for graphs with one node and no edges
- NC and EC are only different when there is an edge and another subpath between a pair of nodes (as in an “if-else” statement)



Node Coverage : $TR = \{ 1, 2, 3 \}$

Test Path = $[1, 2, 3]$

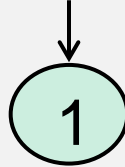
Edge Coverage : $TR = \{ (1, 2), (1, 3), (2, 3) \}$

Test Paths = $[1, 2, 3]$

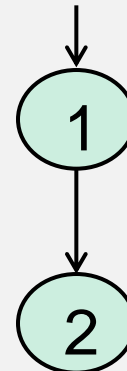
$[1, 3]$

Paths of Length 1 and 0

A graph with only one node will not have any edges



- It may seem trivial, but formally, Edge Coverage needs to require Node Coverage on this graph
- Otherwise, Edge Coverage will not subsume Node Coverage
 - So we define “length up to 1” instead of simply “length 1”
- We have the same issue with graphs that only have one edge – for Edge-Pair Coverage ...

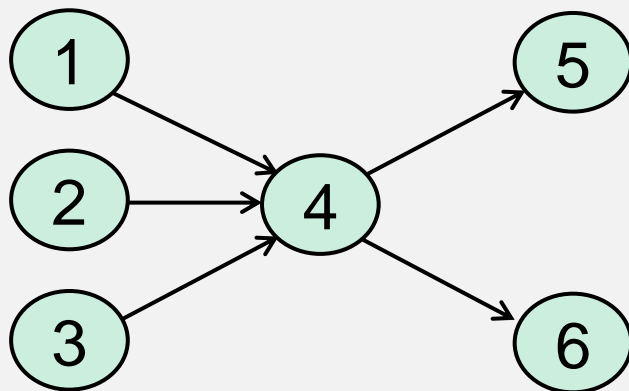


Covering Multiple Edges

Edge-pair coverage requires pairs of edges, or subpaths of length 2

Edge-Pair Coverage (EPC) : TR contains each reachable path of length up to 2, inclusive, in G.

- The phrase “length up to 2” is used to include graphs that have less than 2 edges



Edge-Pair Coverage :

TR = { [1,4,5], [1,4,6], [2,4,5], [2,4,6], [3,4,5], [3,4,6] }

- The logical extension is to require all paths ...

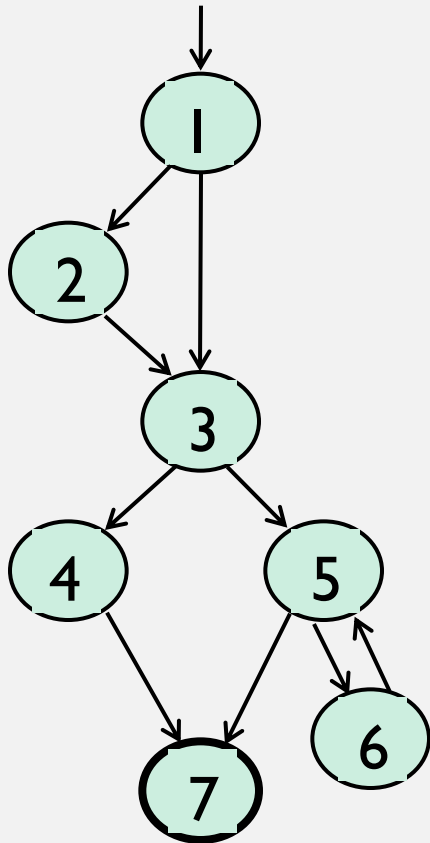
Covering Multiple Edges

Complete Path Coverage (CPC) : TR contains all paths in G.

Unfortunately, this is **impossible** if the graph has a **loop**, so a weak compromise makes the tester decide which paths:

Specified Path Coverage (SPC) : TR contains a set S of test paths, where S is supplied as a parameter.

Structural Coverage Example



Node Coverage

TR = { 1, 2, 3, 4, 5, 6, 7 }

Test Paths: [1, 2, 3, 4, 7] [1, 2, 3, 5, 6, 5, 7]

Edge Coverage

TR = { (1,2), (1, 3), (2, 3), (3, 4), (3, 5), (4, 7), (5, 6), (5, 7), (6, 5) }

Test Paths: [1, 2, 3, 4, 7] [1, 3, 5, 6, 5, 7]

Edge-Pair Coverage

TR = { [1,2,3], [1,3,4], [1,3,5], [2,3,4], [2,3,5], [3,4,7],
[3,5,6], [3,5,7], [5,6,5], [6,5,6], [6,5,7] }

Test Paths: [1, 2, 3, 4, 7] [1, 2, 3, 5, 7] [1, 3, 4, 7]
[1, 3, 5, 6, 5, 6, 5, 7]

Complete Path Coverage

Test Paths: [1, 2, 3, 4, 7] [1, 2, 3, 5, 7] [1, 2, 3, 5, 6, 5, 6] [1, 2, 3, 5, 6, 5, 6, 5, 6, 5, 7] [1, 2, 3, 5, 6, 5, 6, 5, 6, 5, 6, 5, 7] ...

Handling Loops in Graphs

If a graph contains a **loop**, it has an **infinite number of paths**

Thus, **CPC is not feasible**

SPC is not satisfactory because the results are subjective and vary with the tester

Attempts to “deal with” loops:

1970s : Execute cycles once ([4, 5, 4] in previous example, informal)

1980s : Execute each loop, exactly once (formalized)

1990s : Execute loops 0 times, once, more than once (informal description)

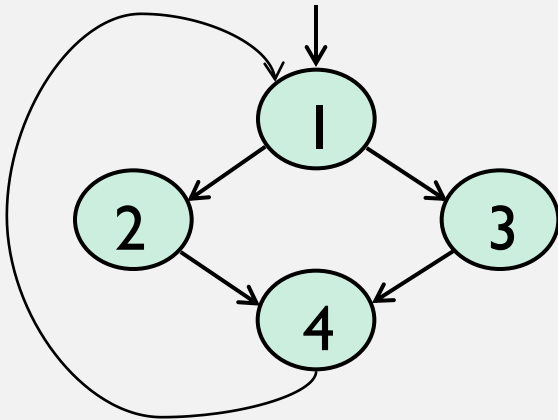
2000s : **Prime paths** (touring, sidetrips, and detours)

Simple Paths and Prime Paths

Simple Path : A path from node n_i to n_j is simple if *no node appears more than once*, except possibly the first and last nodes are the same

- No internal loops
- A loop is a simple path

Prime Path : A simple path that *does not appear as a proper subpath* of any other simple path



Simple Paths : [1,2,4,1], [1,3,4,1], [2,4,1,2], [2,4,1,3], [3,4,1,2], [3,4,1,3], [4,1,2,4], [4,1,3,4], [1,2,4], [1,3,4], [2,4,1], [3,4,1], [4,1,2], [4,1,3], [1,2], [1,3], [2,4], [3,4], [4,1], [1], [2], [3], [4]

Prime Paths : [2,4,1,2], [2,4,1,3], [1,3,4,1], [1,2,4,1], [3,4,1,2], [4,1,3,4], [4,1,2,4], [3,4,1,3]

Prime Path Coverage

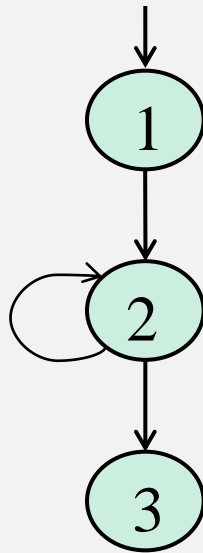
A simple, elegant and finite criterion that requires loops to be executed as well as skipped

Prime Path Coverage (PPC) : TR contains each prime path in G.

- Will tour all paths of length 0, 1, ...
- That is, it subsumes node and edge coverage
- PPC almost, but **not quite**, subsumes EPC ...

PPC Does Not Subsume EPC

- If a node n has an edge to itself (*self edge*), EPC requires $[n, n, m]$ and $[m, n, n]$
- $[n, n, m]$ is not prime
- Neither $[n, n, m]$ nor $[m, n, n]$ are simple paths (not prime)



EPC Requirements :

TR = { $[1,2,3]$, $[1,2,2]$, $[2,2,3]$, $[2,2,2]$ }

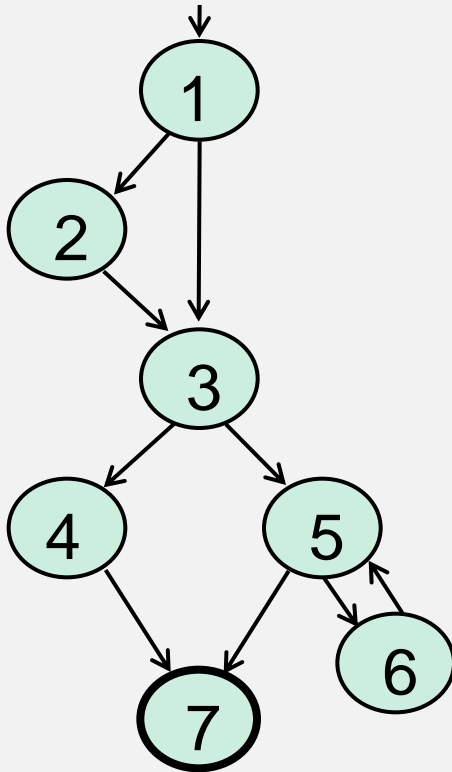
PPC Requirements :

TR = { $[1,2,3]$, $[2,2]$ }

Prime Path Example

The previous example has **38 simple** paths

Only **nine prime** paths



Prime Paths

[1, 2, 3, 4, 7]

[1, 2, 3, 5, 7]

[1, 2, 3, 5, 6]

[1, 3, 4, 7]

[1, 3, 5, 7]

[1, 3, 5, 6]

[6, 5, 7]

[6, 5, 6]

[5, 6, 5]

Execute loop
0 times

Execute loop
once

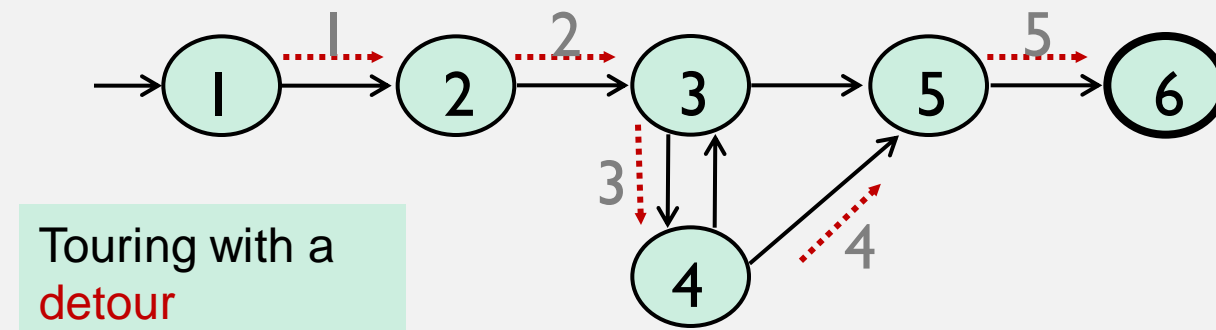
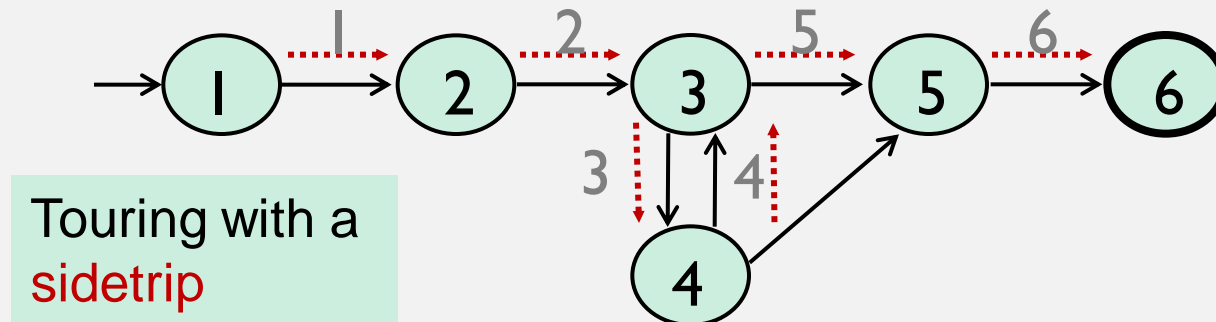
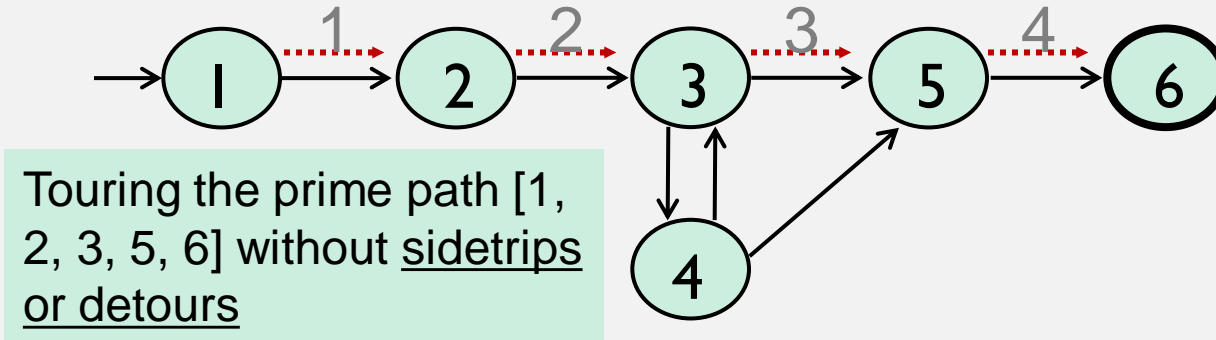
Execute loop
more than once

Touring, Sidetrips, and Detours

Prime paths do not have internal loops ... test paths **might**

- **Tour** : A test path p tours subpath q if q is a subpath of p
- **Tour With Sidetrips** : A test path p tours subpath q with sidetrips iff every edge in q is also in p in the same order
 - The **tour can include a sidetrip**, as long as it comes back to the same node
- **Tour With Detours** : A test path p tours subpath q with detours iff every node in q is also in p in the same order
 - The tour can include a detour from node n_i , as long as it comes back to the prime path at a successor of n_i

Sidetrips and Detours Example



Infeasible Test Requirements

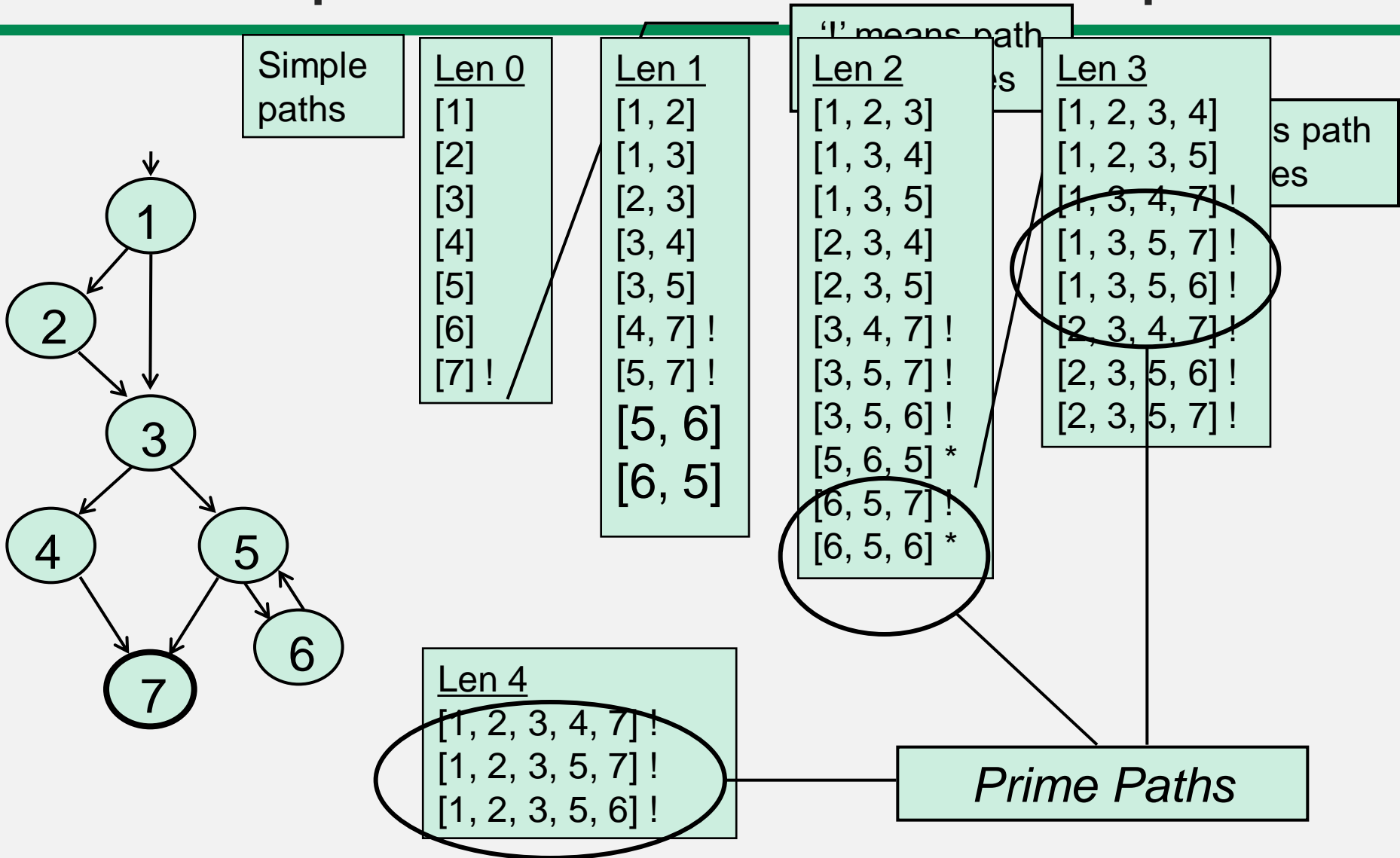
An infeasible test requirement **cannot be satisfied**

- **Unreachable statement (dead code)**
- **Subpath that can only be executed with a contradiction ($X > 0$ and $X < 0$)**
- Most test criteria have some infeasible test requirements
- It is usually undecidable whether all test requirements are feasible
- When sidetrips are not allowed, many structural criteria have more infeasible test requirements
- However, always allowing sidetrips weakens the test criteria

Practical recommendation—Best Effort Touring

- Satisfy as many test requirements as possible without sidetrips
- Allow sidetrips to try to satisfy remaining test requirements

Simple & Prime Path Example



Round Trips

Round-Trip Path : *A prime path that starts and ends at the same node*

Simple Round Trip Coverage (SRTC) : TR contains at least one round-trip path for each reachable node in G that begins and ends a round-trip path.

Complete Round Trip Coverage (CRTC) : TR contains all round-trip paths for each reachable node in G .

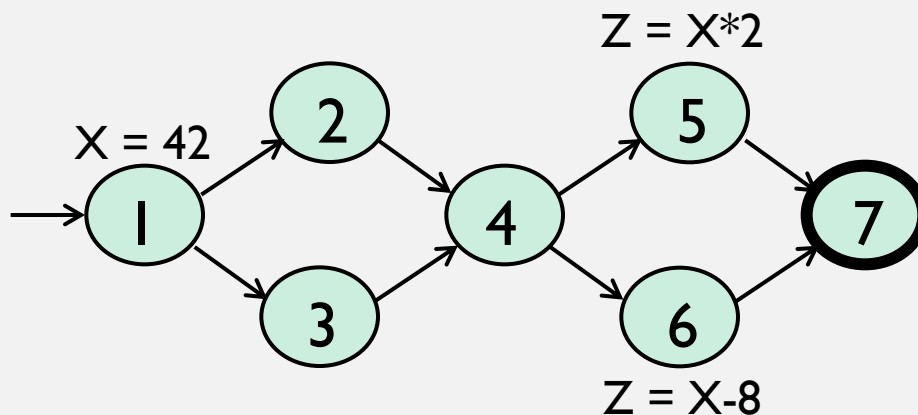
- These criteria omit nodes and edges that are not in round trips
- Thus, they do not subsume edge-pair, edge, or node coverage

Data Flow Criteria

Goal: Try to ensure that values are computed and used correctly

Definition (def) : A location where a value for a variable is stored into memory

Use : A location where a variable's value is accessed



Defs: $\text{def}(1) = \{X\}$

$\text{def}(5) = \{Z\}$

$\text{def}(6) = \{Z\}$

Uses: $\text{use}(5) = \{X\}$

$\text{use}(6) = \{X\}$

The values given in defs should reach at least one, some, or all possible uses

DU Pairs and DU Paths

- **def (n) or def (e)** : The set of variables that are defined by node n or edge e
- **use (n) or use (e)** : The set of variables that are used by node n or edge e

• **DU pair** : A pair of locations (l_i, l_j) such that a variable v is defined at l_i and used at l_j

• **Def-clear** : A path from l_i to l_j is *def-clear* with respect to variable v if v is not given another value on any of the nodes or edges in the path

• **Reach** : If there is a def-clear path from l_i to l_j with respect to v , the def of v at l_i reaches the use at l_j

• **du-path** : A simple subpath that is def-clear with respect to v from a def of v to a use of v

- **du** (n_i, n_j, v) – the set of du-paths from n_i to n_j
- **du** (n_i, v) – the set of du-paths that start at n_i

Touring DU-Paths

A test path p *du-tours* subpath d with respect to v if p tours d and the subpath taken is def-clear with respect to v

Sidetrips can be used, just as with previous touring

Three criteria

1. Use every def
2. Get to every use
3. Follow all du-paths

Data Flow Test Criteria

- First, we make sure every def reaches a use

All-defs coverage (ADC) : For each set of du-paths $S = du(n, v)$, TR contains at least one path d in S .

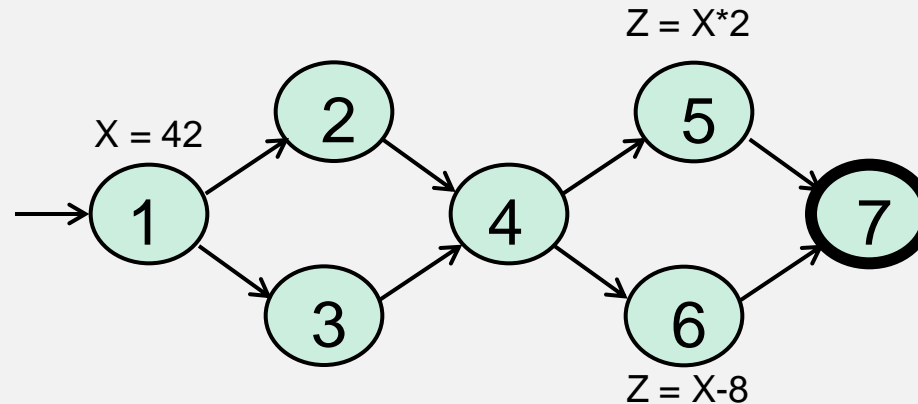
- Then we make sure that every def reaches all possible uses

All-uses coverage (AUC) : For each set of du-paths to uses $S = du(n_i, n_j, v)$, TR contains at least one path d in S .

- Finally, we cover all the paths between defs and uses

All-du-paths coverage (ADUPC) : For each set $S = du(n_i, n_j, v)$, TR contains every path d in S .

Data Flow Testing Example

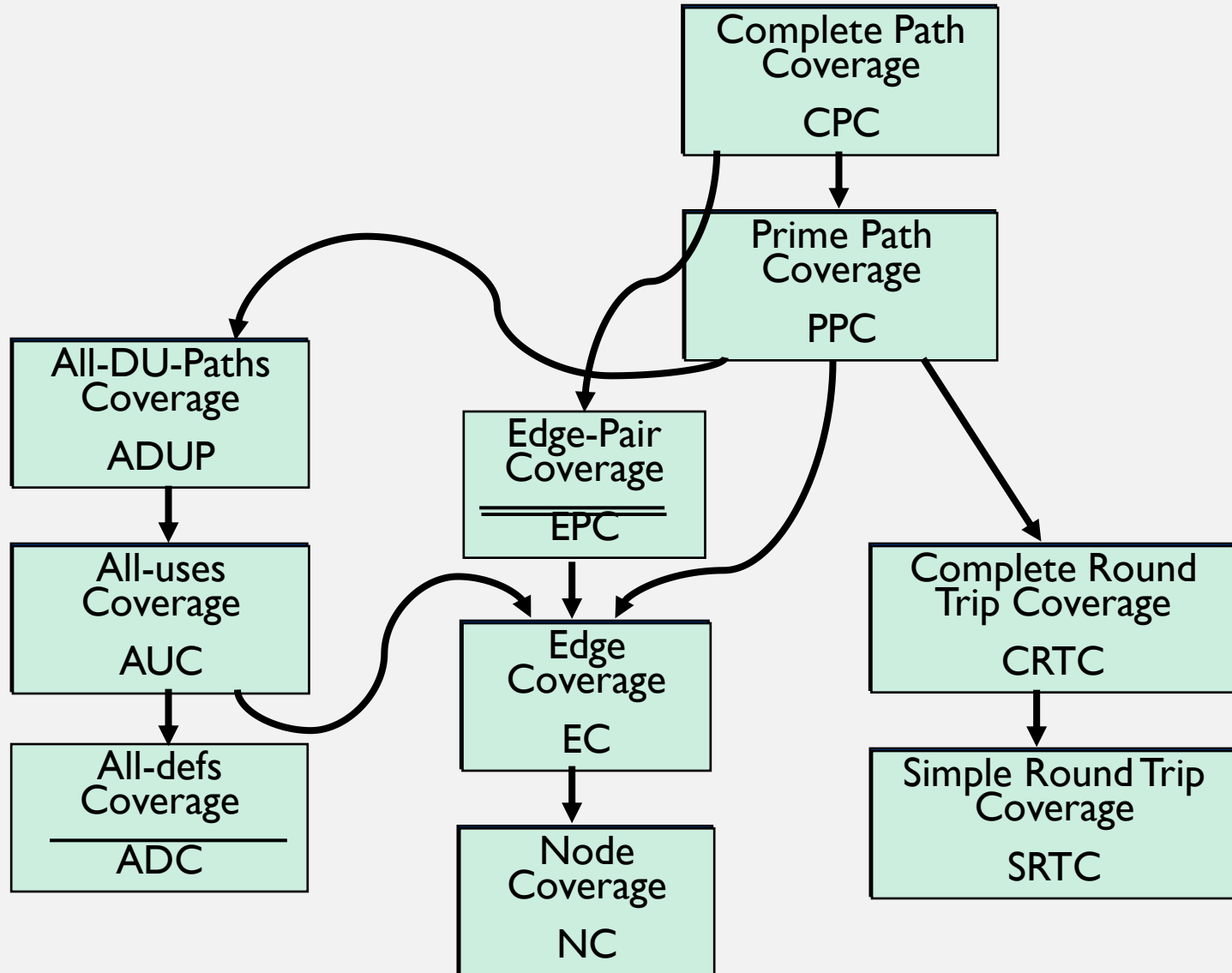


All-defs for X
[1, 2, 4, 5]

All-uses for X
[1, 2, 4, 5]
[1, 2, 4, 6]

All-du-paths for X
[1, 2, 4, 5]
[1, 3, 4, 5]
[1, 2, 4, 6]
[1, 3, 4, 6]

Graph Coverage Criteria Subsumption



Summary

Graphs are a very powerful abstraction for designing tests

The various criteria allow lots of cost / benefit tradeoffs

Thank You