



# *Effect of Satellite Formation Architectures and Imaging Modes on Albedo Estimation of major Biomes*

Sreeja Nag<sup>1,2</sup>, Charles Gatebe<sup>3</sup>, David Miller<sup>1,4</sup>, **Olivier de Weck**<sup>1</sup>

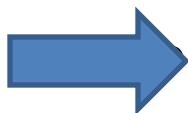
<sup>1</sup>Massachusetts Institute of Technology, Cambridge, MA

<sup>2</sup>NASA Ames Research Center, Moffet Field, CA

<sup>3</sup>NASA Goddard Space Flight Center, Greenbelt, MD

<sup>4</sup>NASA Headquarters, Washington DC

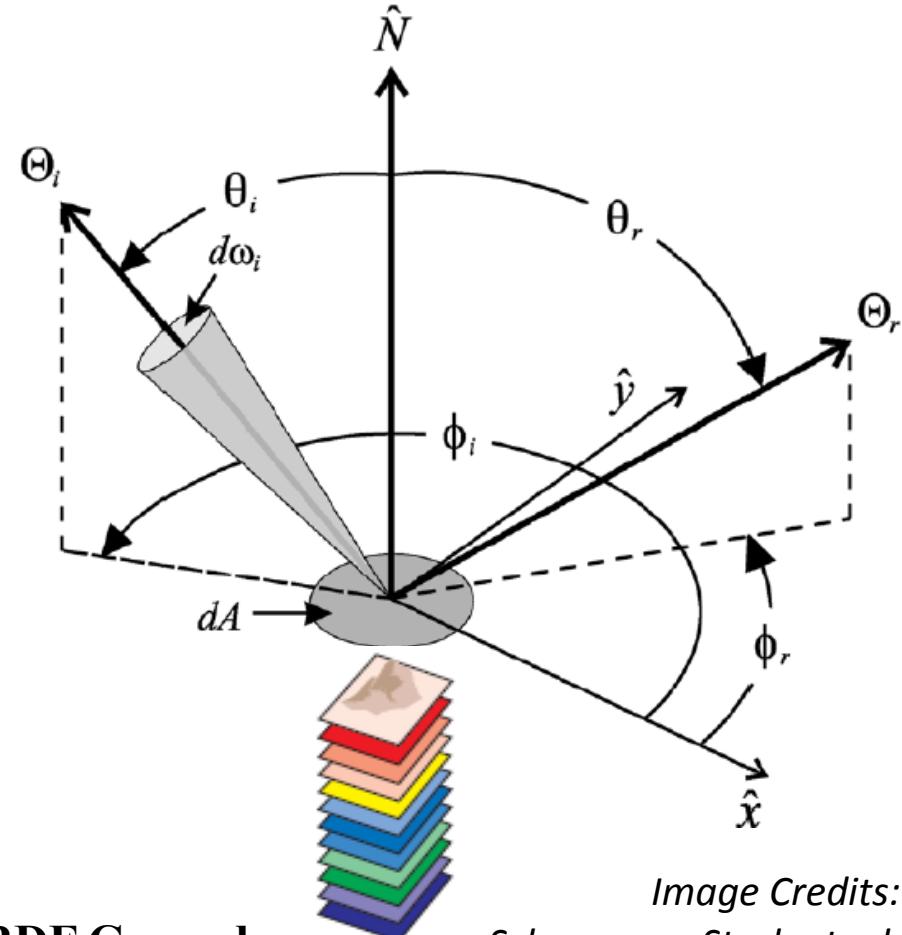
October 1, 2014



## The Angular Acquisition problem

- Example Application dependent on Angular Sampling
- Proposed Solution and Design Methodology
- Baseline Case Study using a few Formation Configurations
- Value of Imaging Modes
- Summary and Future Work

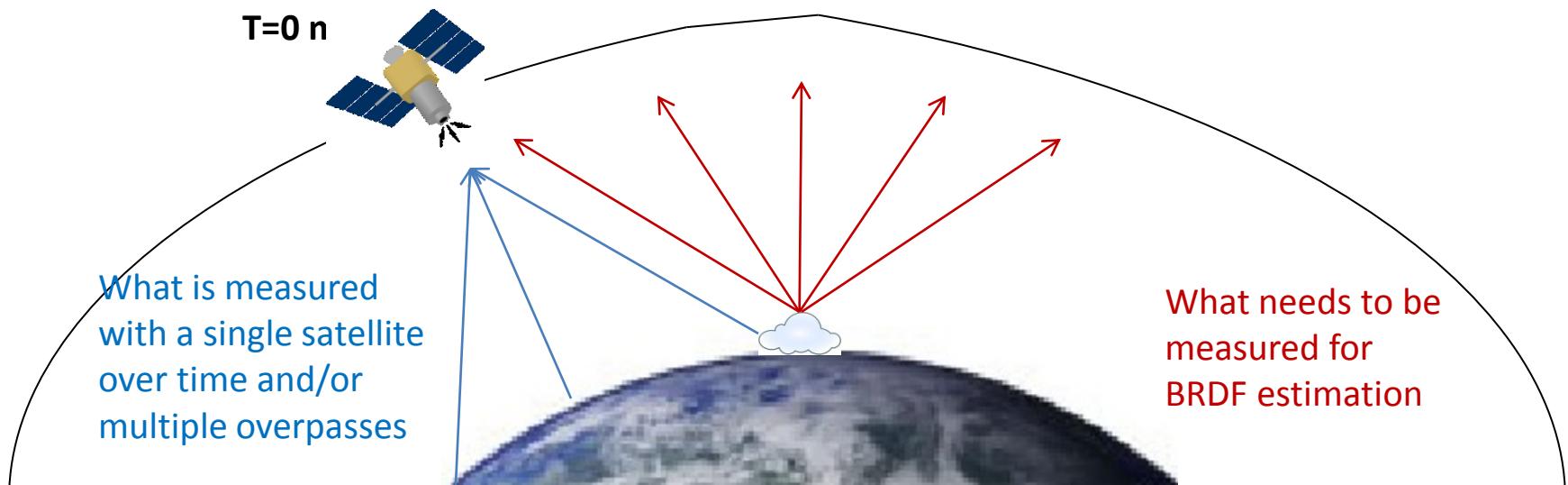
- Because reflectance values depend on the direction of solar illumination and direction of measured reflection
- Angular performance metric:  
Bi-directional reflectance distribution function (BRDF)
- Anisotropic (angle-dependent) and multispectral (near-solar spectrum) reflectance of clouds and ground surface
- Angular sampling is inadequate using monolithic spacecrafts presenting an angular challenge



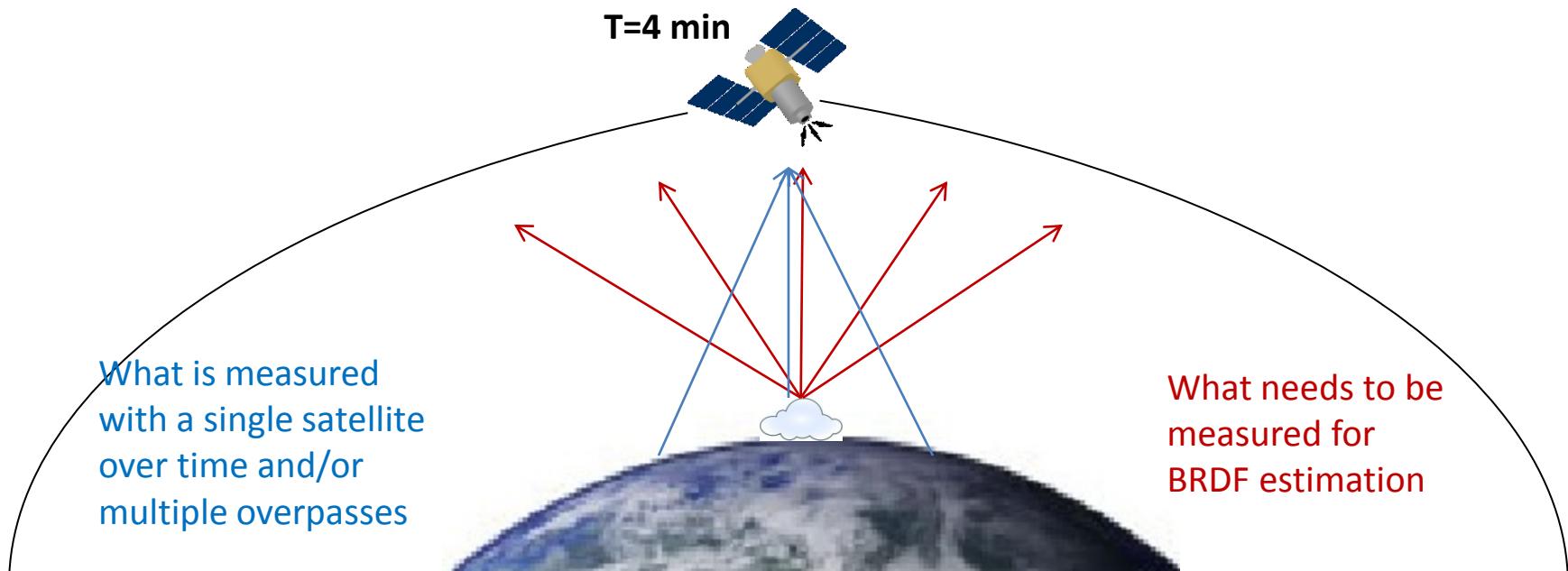
**BRDF Ground  
Spot spectrum**

*Image Credits:*  
Schaepman-Strub et. al,  
2006

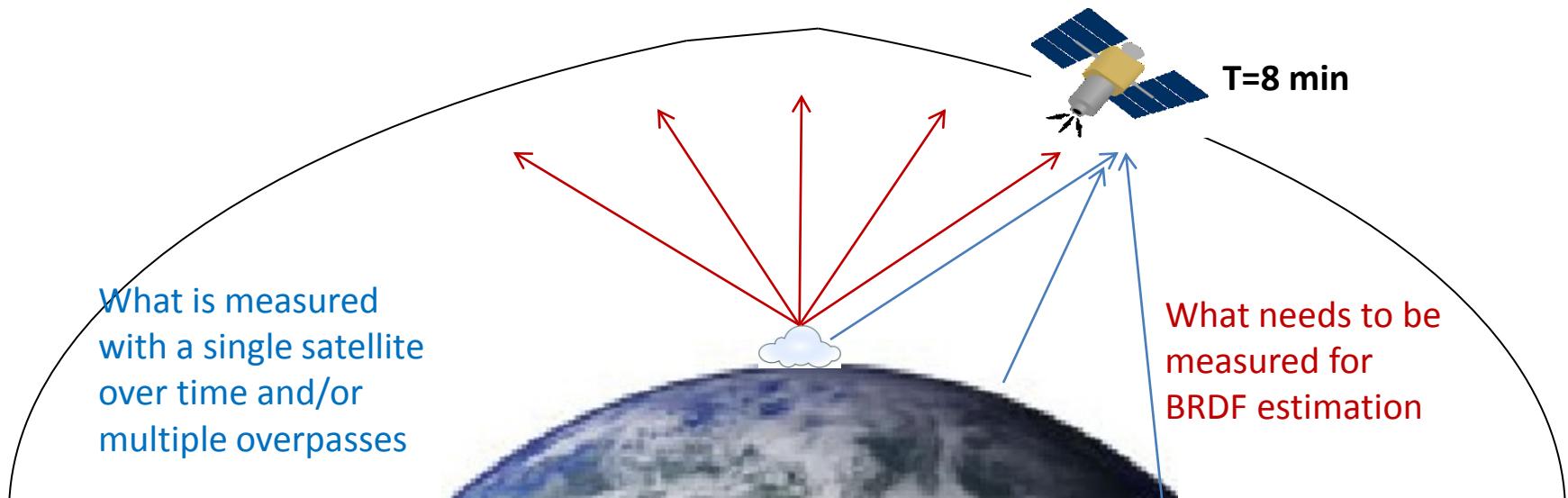
Measurements for BRDF Estimation using a single satellite with **forward aft sensors** – one angle at a time



Measurements for BRDF Estimation using a single satellite with **forward aft sensors** – one angle at a time

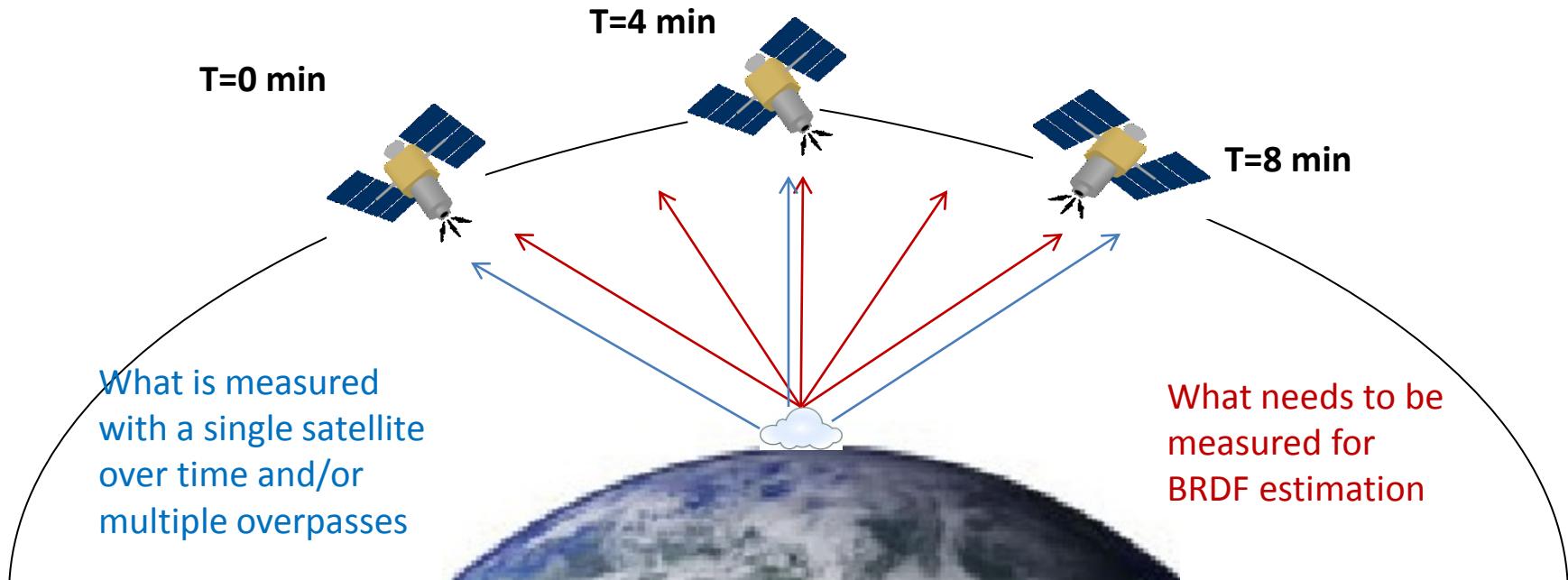


Measurements for BRDF Estimation using a single satellite with **forward aft sensors** – one angle at a time

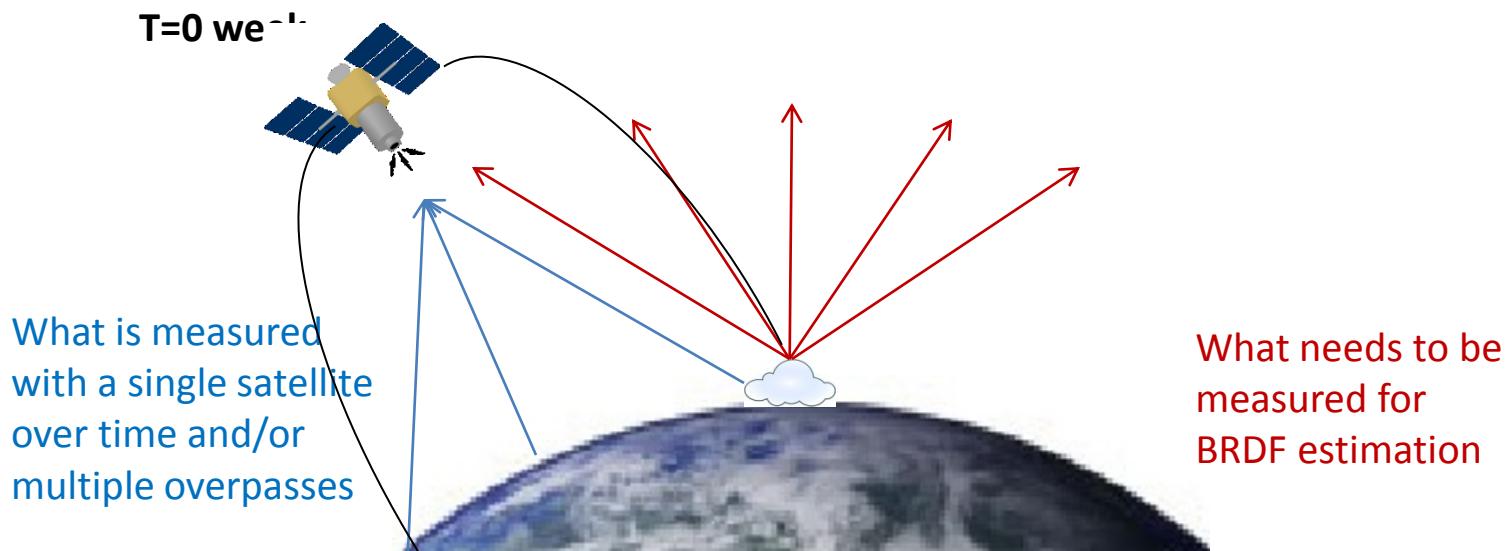


BRDF Estimation by combining the consecutive measurements

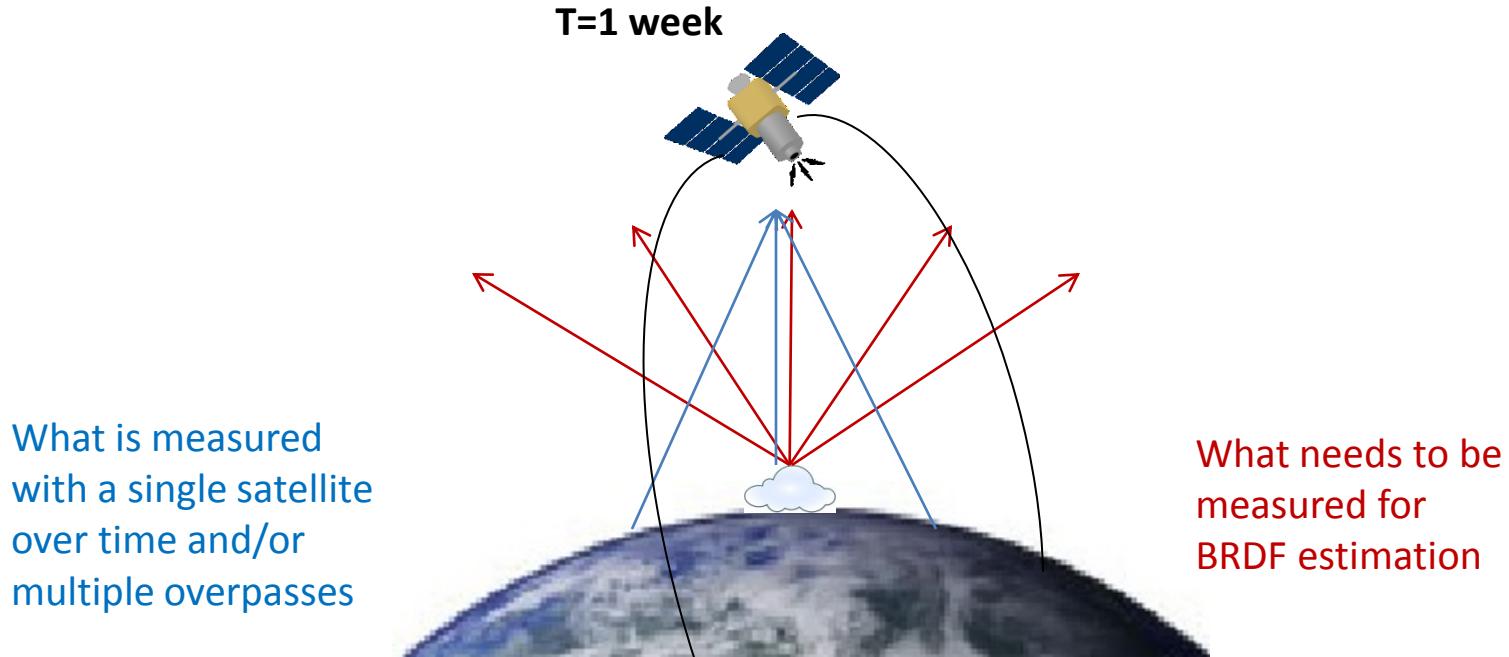
- Problem:**
1. Restrictive plane with respect to the sun
  2. Up to 10 minutes between measurements



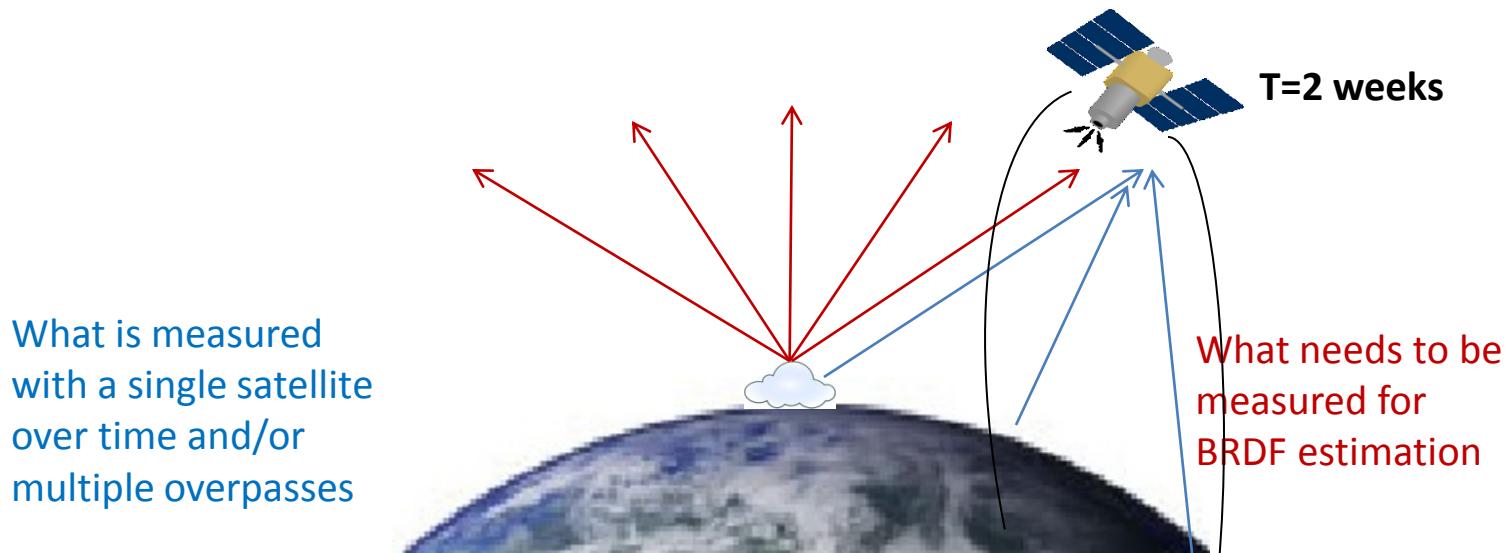
Measurements for BRDF Estimation using a single satellite with  
**large cross-track swath** – one angle at a time



Measurements for BRDF Estimation using a single satellite with  
**large cross-track swath** – one angle at a time

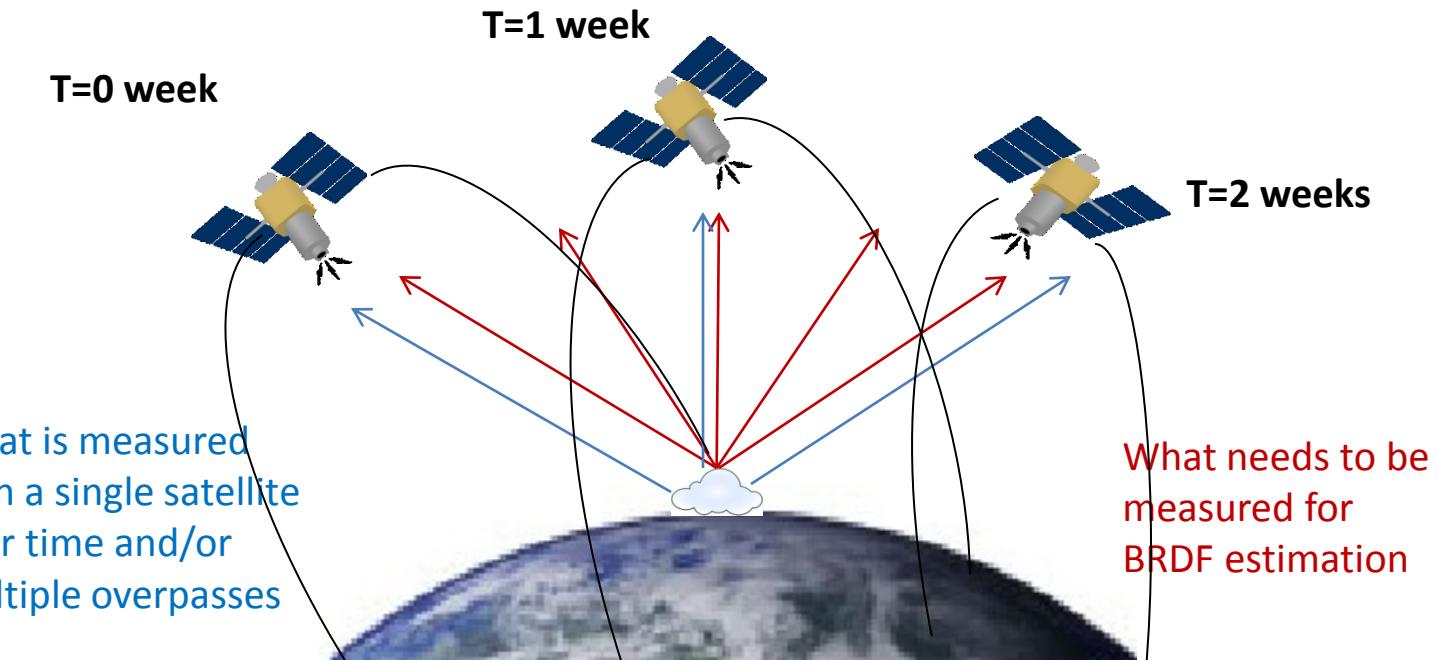


Measurements for BRDF Estimation using a single satellite with  
**large cross-track swath** – one angle at a time



BRDF Estimation by combining measurements over consecutive overpasses

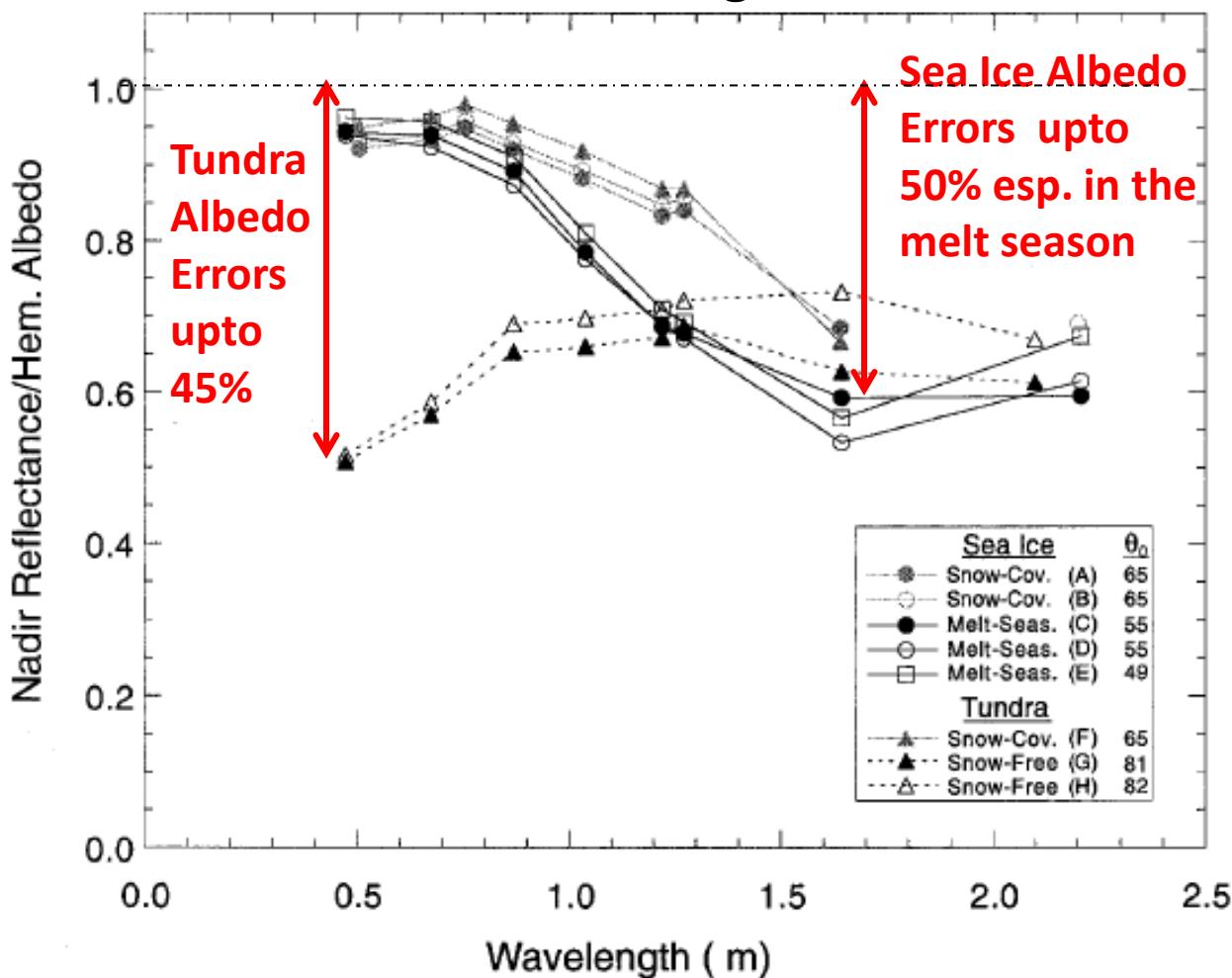
- Problem:**
1. Restrictive plane with respect to the sun
  2. Up 2 weeks between measurements



- The Angular Acquisition problem
- Example Application dependent on Angular Sampling
- Proposed Solution and Design Methodology
- Baseline Case Study using a few Formation Configurations
- Value of Imaging Modes
- Summary and Future Work

# Albedo Estimation

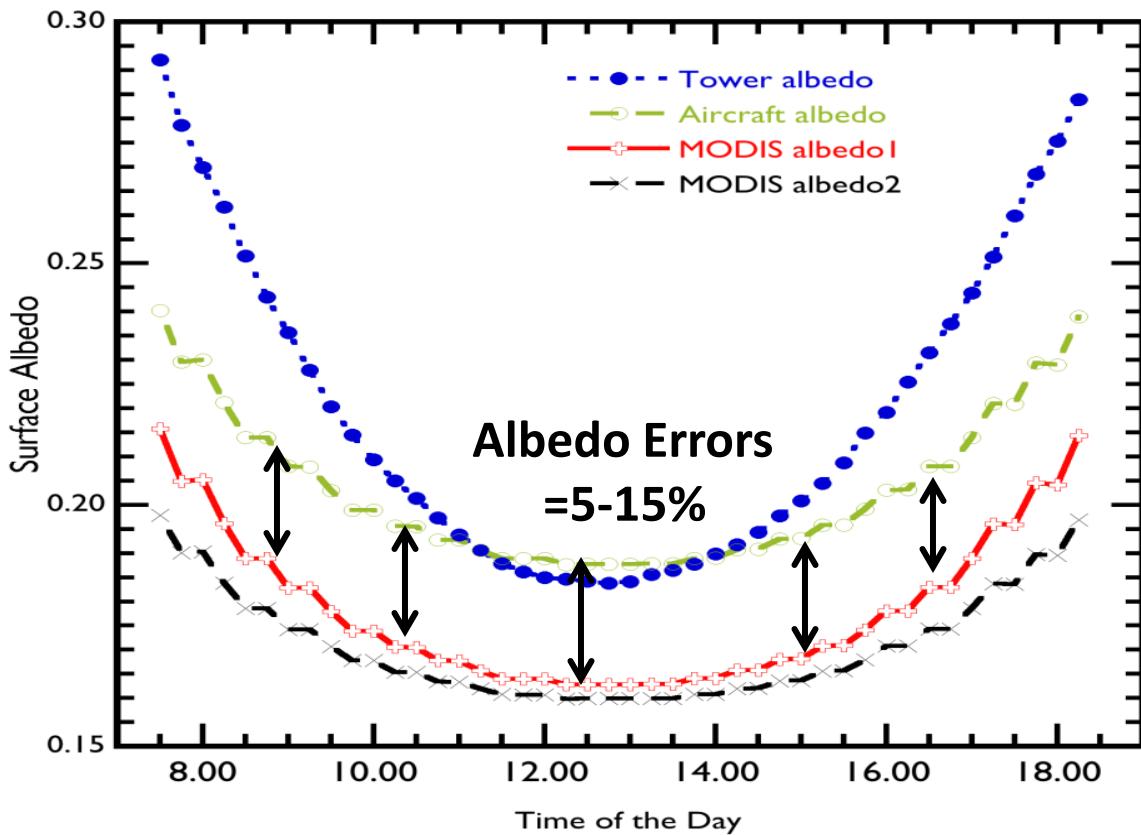
Albedo is the hemispheric integration of BRDF over all view zenith and azimuth angles. Can be estimated from nadir measurements BUT big errors in the Arctic...



*Image Credits: Arnold et. al, 2002*

*Figure uses thousands of angular measurement data from the airborne Cloud Absorption Radiometer taken during the ARM CAS campaign in 1998.*

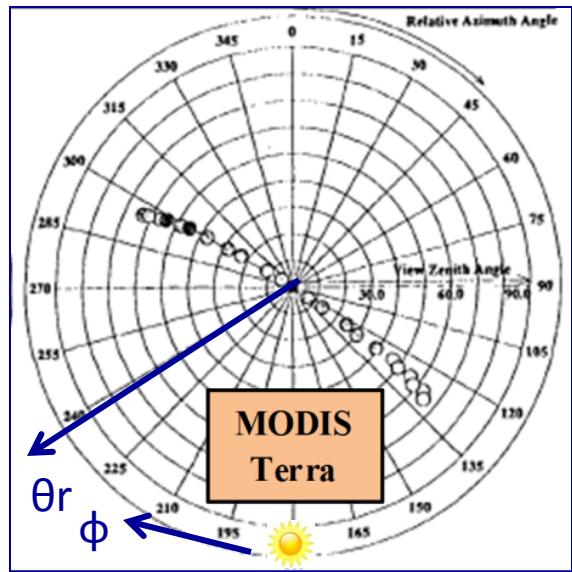
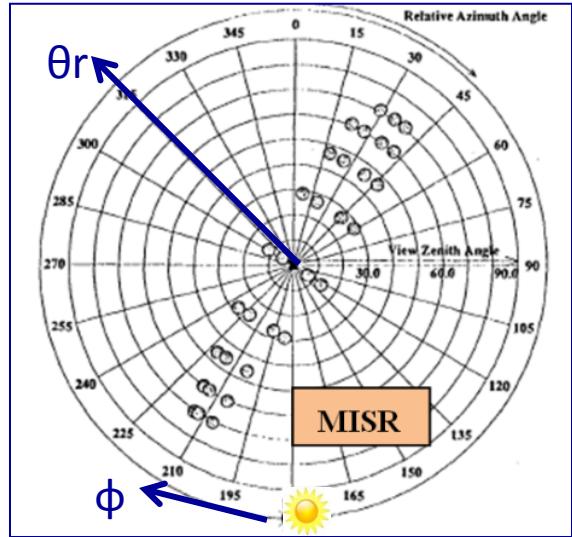
Albedo is the hemispheric integration of BRDF over all view zenith and azimuth angles. Can be estimated from multiple hemispheric measurements BUT big errors in the Savannas...



*BRDF Data (Image Credits:  
Gatebe et. al, 2012) from the  
airborne  
**Cloud Absorption Radiometer**  
vs.  
spaceborne **MODIS***

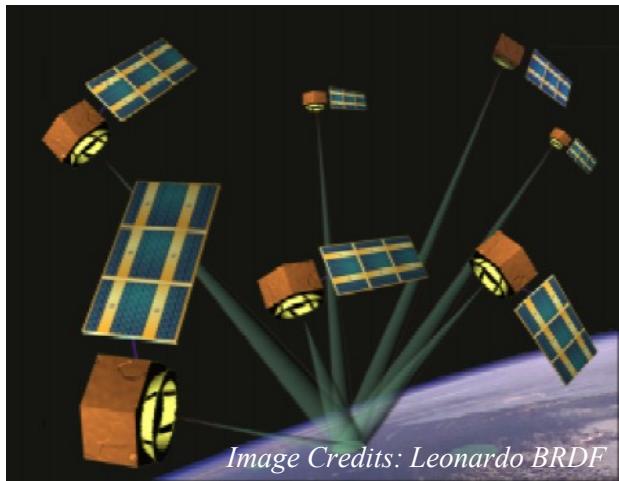
- The Angular Acquisition problem
  - Example Application dependent on Angular Sampling
- Proposed Solution and Design Methodology
- Baseline Case Study using a few Formation Configurations
  - Value of Imaging Modes
  - Summary and Future Work

Major Limitation: Angular undersampling



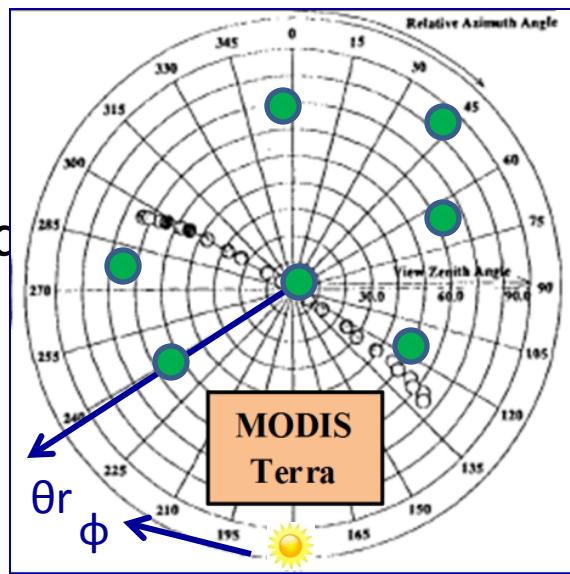
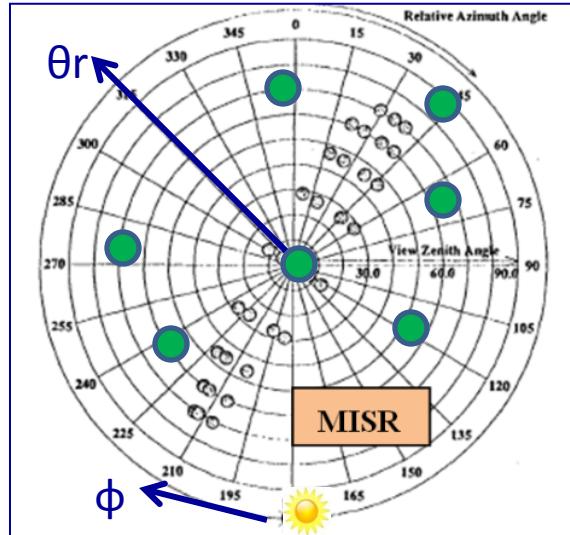
**Major Limitation:** Angular undersampling

**Potential Solution:** Clusters (NFOV) of nano-satellites in formation flight.

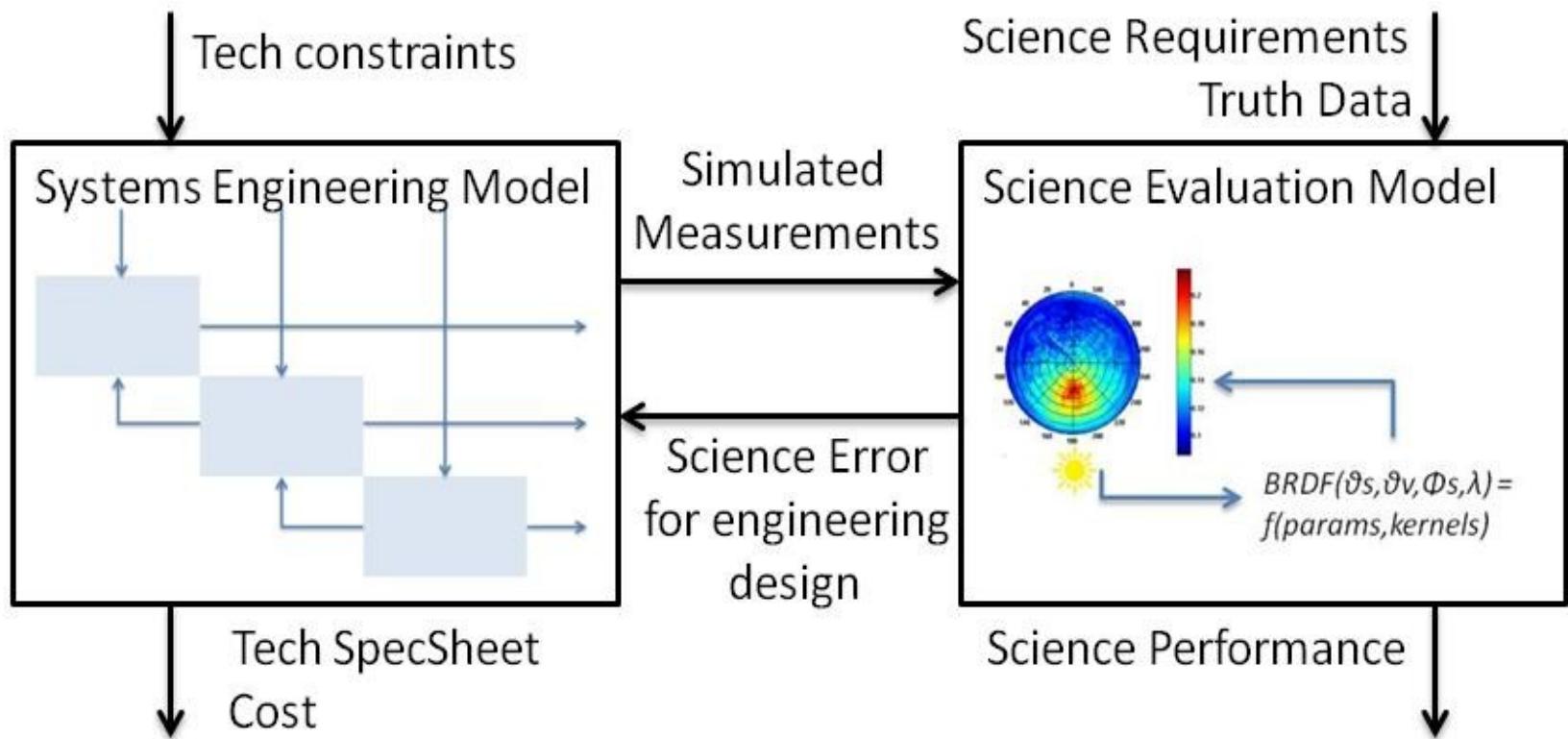


**Additional advantages**:- Small satellite design and development, Standard bus like 6U, Secondary payload launches, Cubesat GS network

**Disadvantages**:- Restrictive orbits, mass/volume constraints, limited propulsion and ADCS

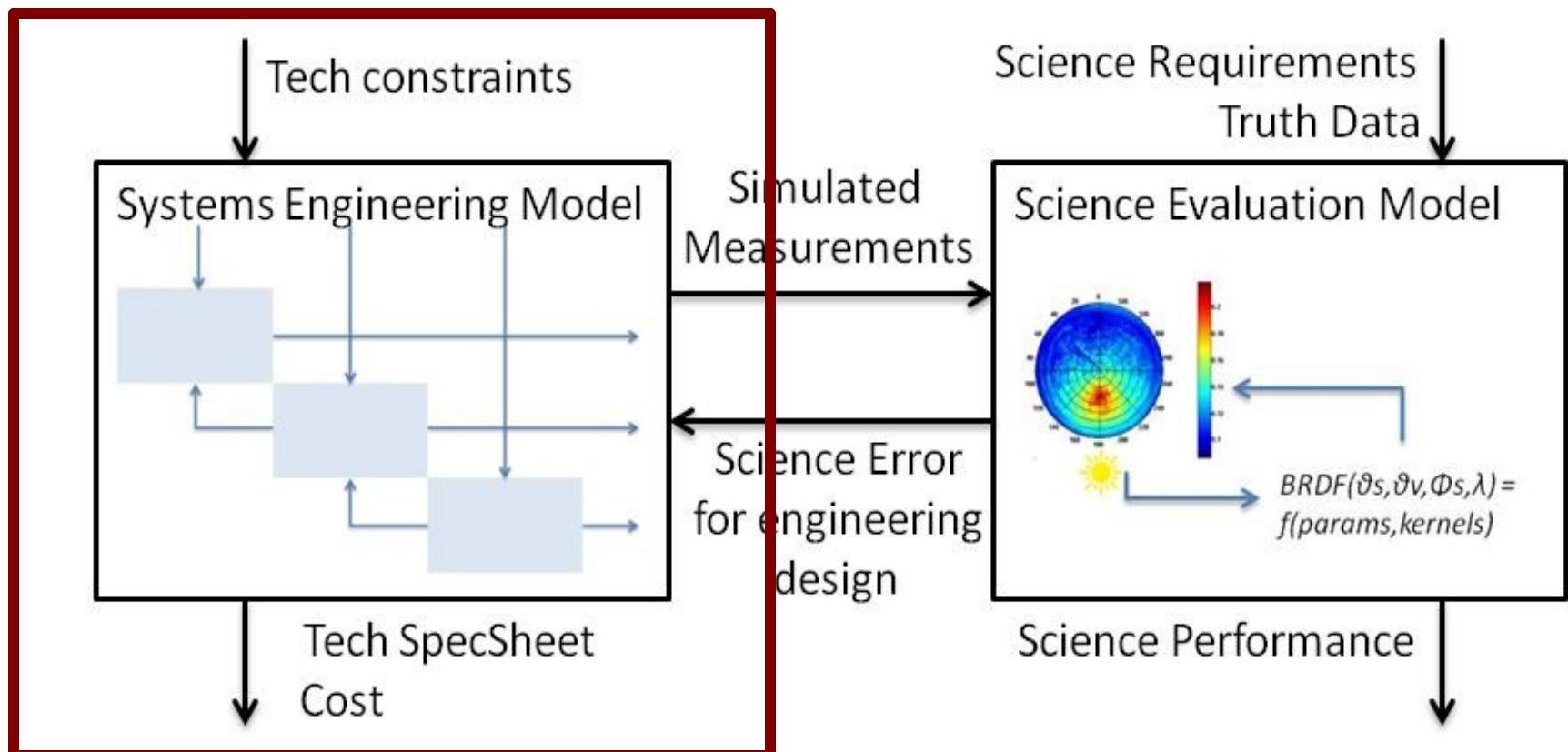


Build a Systems engineering (SE) model integrated with traditional BRDF Estimation models



\*as a function of tech requirements,  
biomes of interest, science applications

Build a Systems engineering (SE) model integrated with traditional BRDF Estimation models



\*as a function of tech requirements,  
biomes of interest, science applications

# MIT Constellation vs. Formation Flight

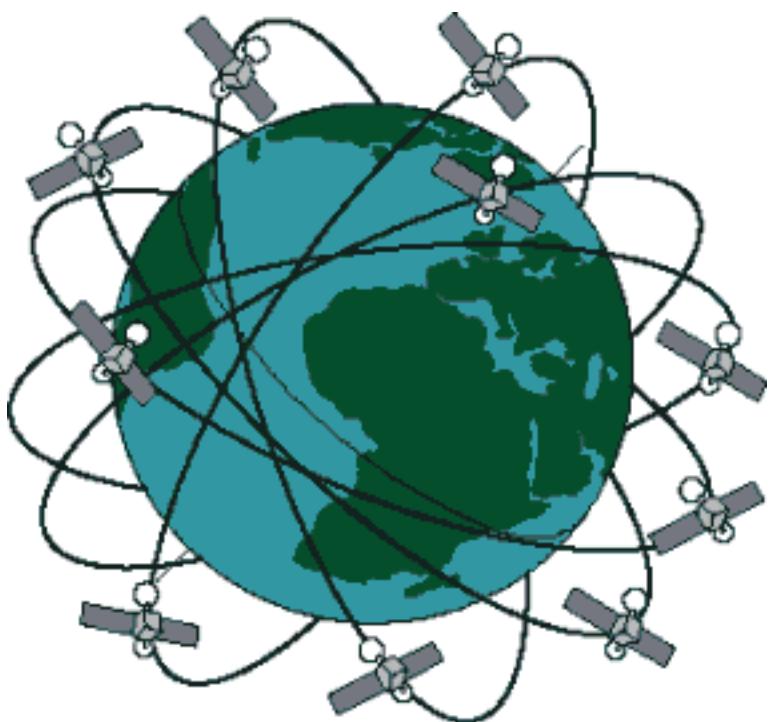
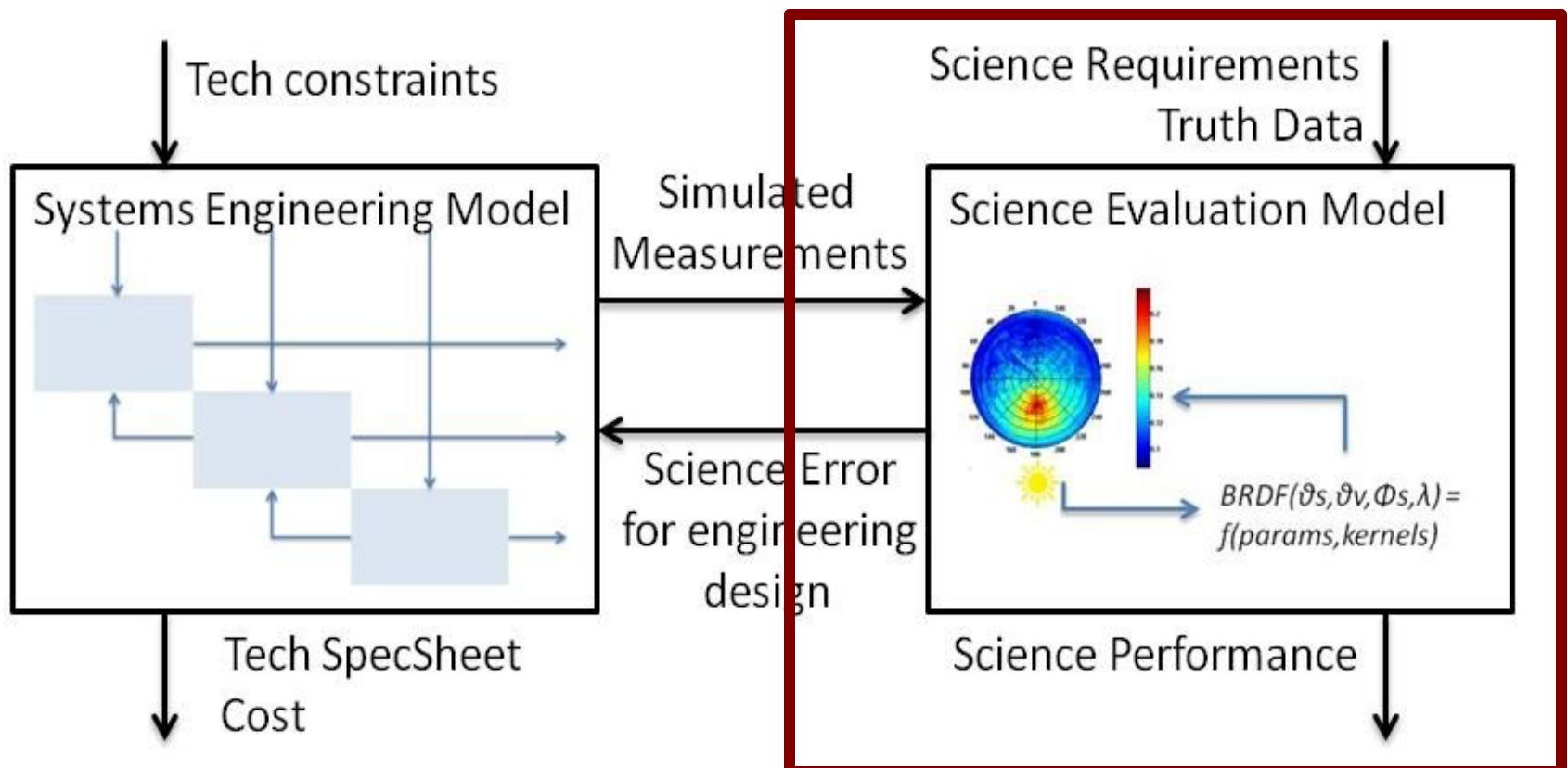


Image Credits: [www.cienciaviva.pt](http://www.cienciaviva.pt)

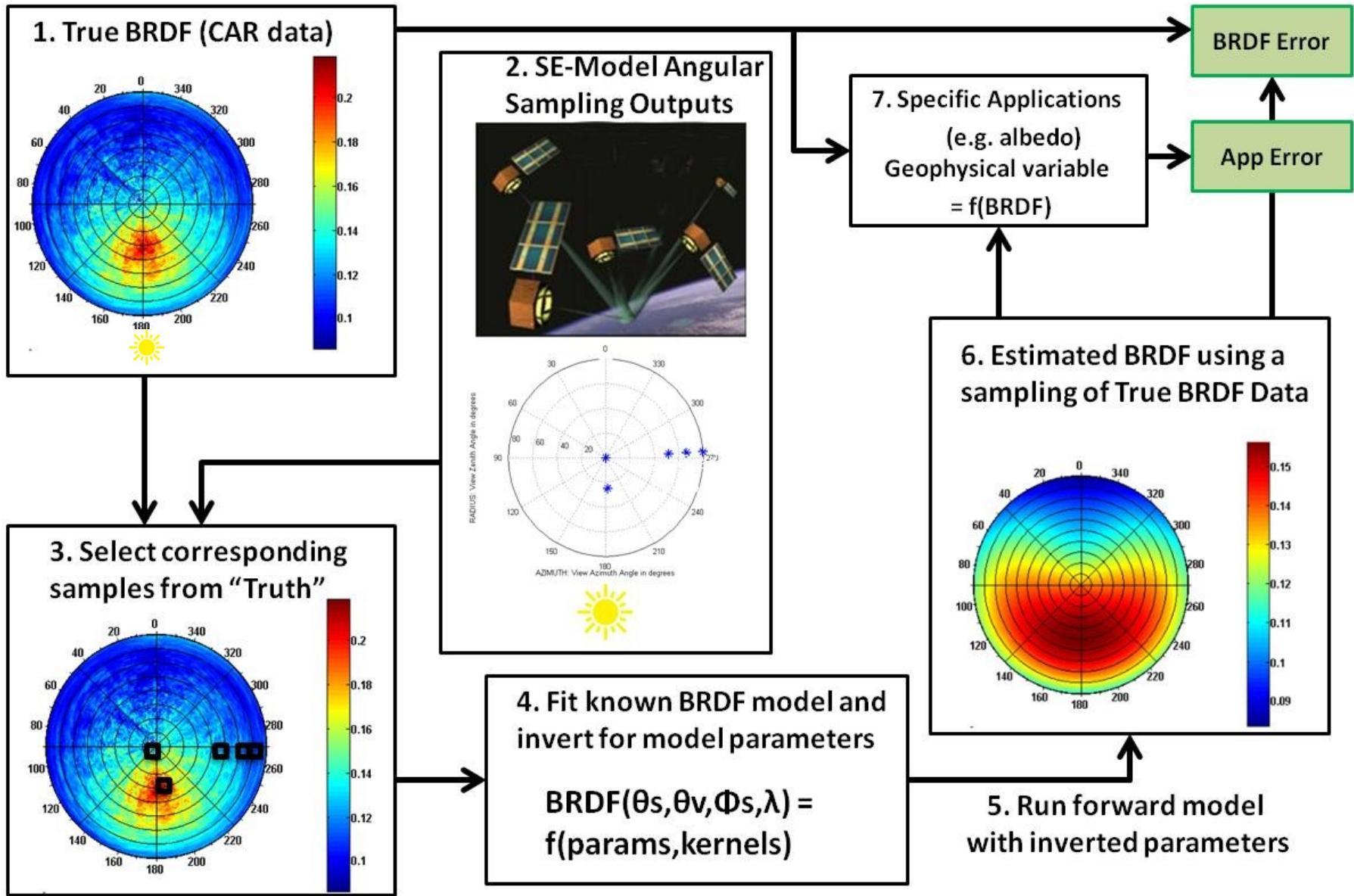
VS.



Build a Systems engineering (SE) model integrated with traditional BRDF Estimation models



\*as a function of tech requirements,  
biomes of interest, science applications

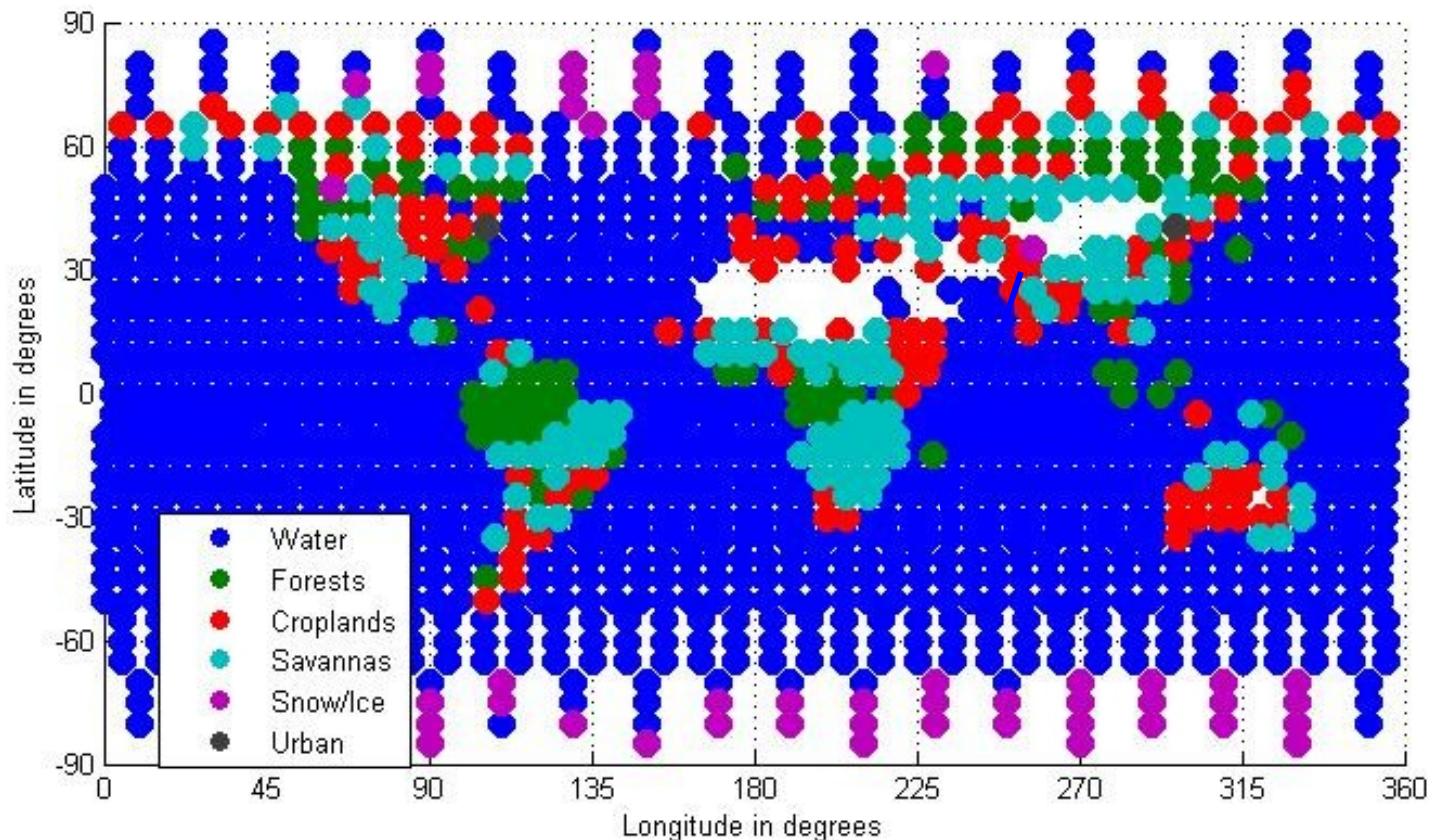


# Setting up the “Truth”

MODIS Land  
Cover Map:

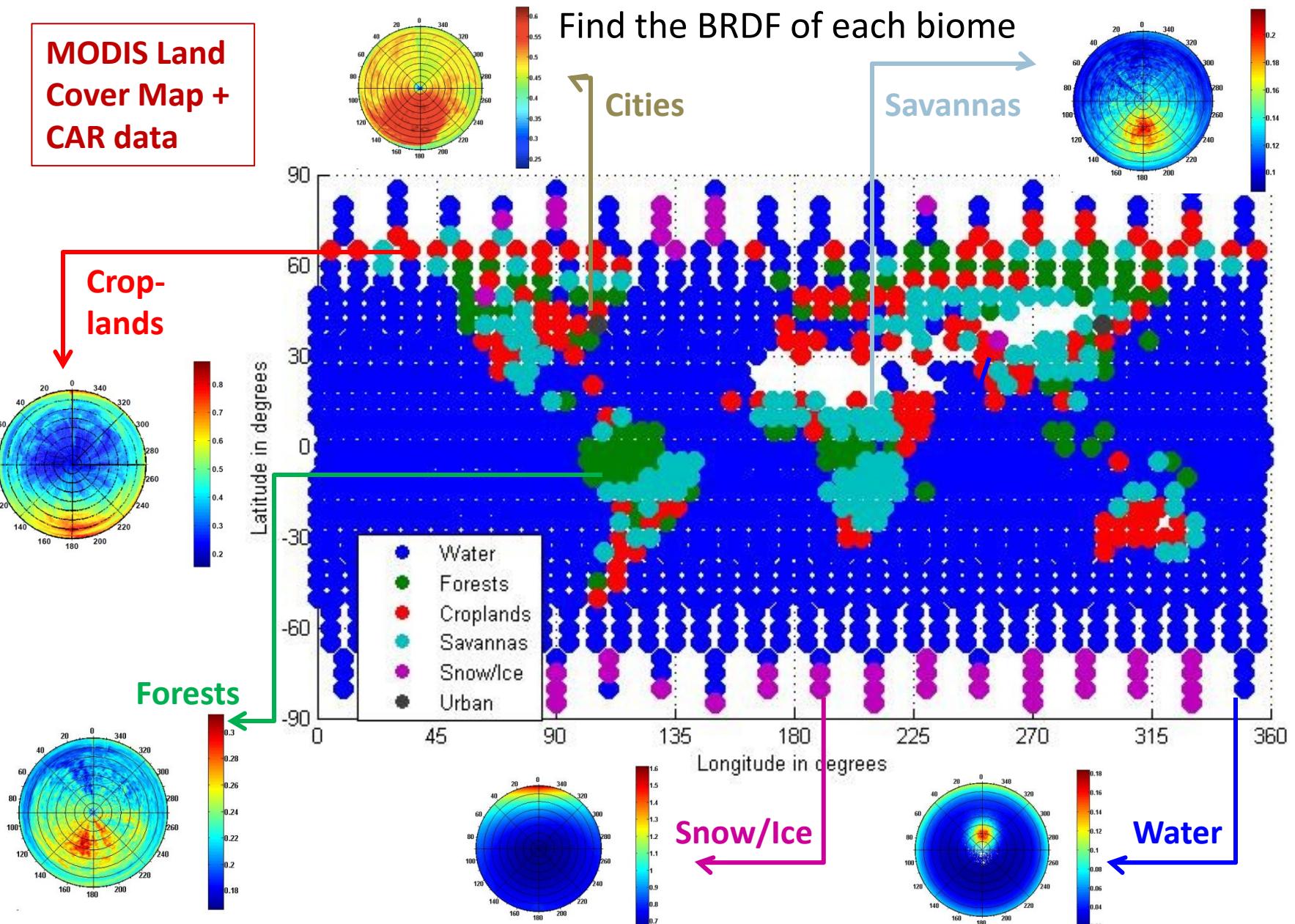
Find the global biome distribution

Because local & static BRDF data is available per biome



# Setting up the “Truth”

MODIS Land  
Cover Map +  
CAR data



- The Angular Acquisition problem
  - Example Application dependent on Angular Sampling
  - Proposed Solution and Design Methodology
-  Baseline Case Study using a few Formation Configurations
- Value of Imaging Modes
  - Summary and Future Work

**Simplest case considered** – 4 satellites, no propulsion but +/- 50deg of sensor slew, ISS inclination of 51.6 deg, 650 km.

**Biome considered** – Savanna vegetation considered for the baseline. Will be expanded to snow and others.

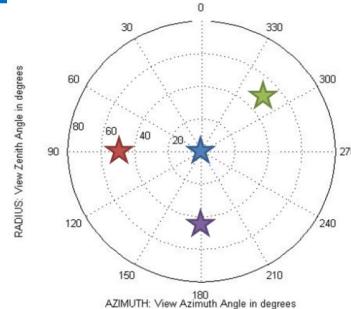
| Differential Keplerian variables |     |
|----------------------------------|-----|
| Semi Major Axis                  | No  |
| Inclination                      | No  |
| Arg. Of Perigee                  | No  |
| Eccentricity                     | No  |
| RAAN                             | Yes |
| True Anomaly                     | Yes |

Effect of configurations (few architectures) and modes will be shown. Mode #1 is the baseline mode.

| RAAN::TA of the following satellites in degrees |        |        |        |        |
|---|--------|--------|--------|--------|
|   | Sat #1 | Sat #2 | Sat #3 | Sat #4 |
| Config #1                                       | 0::0   | 0::-5  | -5::-1 | -5::-6 |
| Config #2                                       | 0::0   | 0::-5  | -5::-1 | 5::-4  |
| Config #3                                       | 0::0   | 0::-5  | -5::-6 | 5::-4  |
| Config #4                                       | 0::0   | 0::-5  | -5::-3 | 5::-4  |
| Config #5                                       | 0::0   | 0::-5  | -5::-3 | 3::-3  |
| Config #6                                       | 0::0   | 0::-3  | -3::0  | -3::-3 |

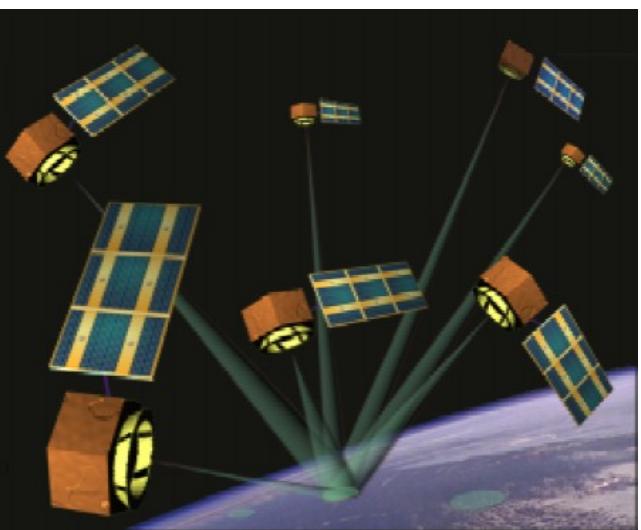
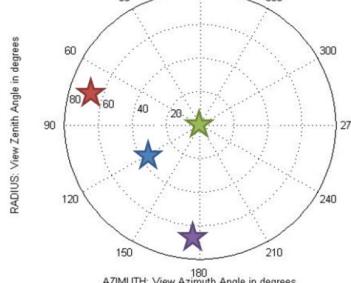
### ***MODE #1 – Same reference satellite***

One satellite in the cluster is the designated leader and always points nadir. Other sats point to the ground spot directly nadir to the leader satellite.



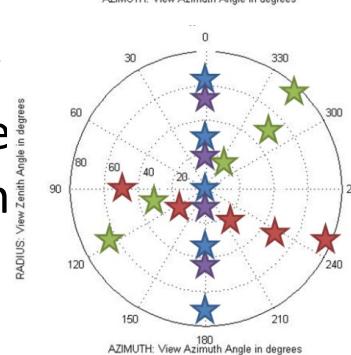
### ***MODE #2 – Change the reference satellite over the orbit***

Like Mode #1 but the leader satellite changes over the course of the orbit so as to optimize the angular coverage of the BRDF plane.



### ***MODE #3 – Tracking/Staring at a Spot***

All satellites such that they point to the same ground target/s as they approach over the horizon and recede into the horizon.

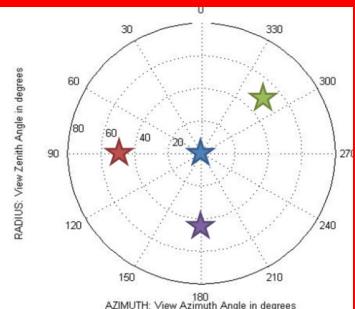


### ***MODE #4 – Multiple Payloads***

Each follows a different mode among the above or fractionate functionality.

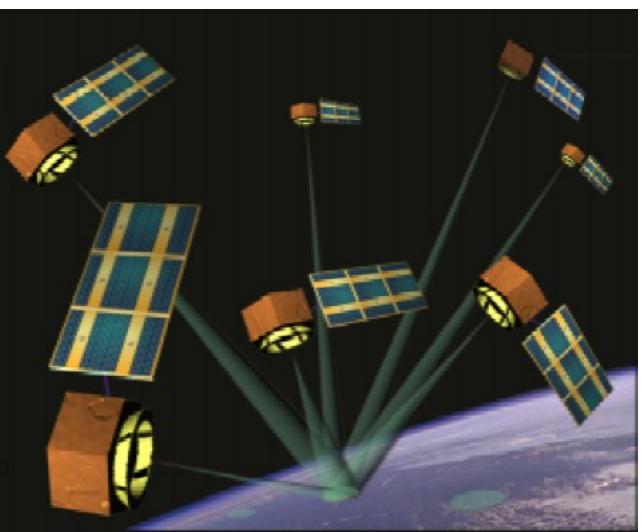
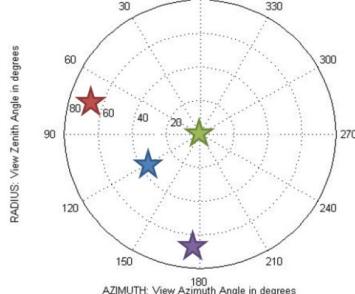
### ***MODE #1 – Same reference satellite***

One satellite in the cluster is the designated leader and always points nadir. Other sats point to the ground spot directly nadir to the leader satellite.



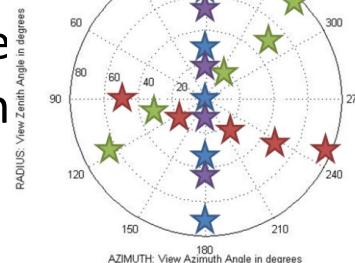
### ***MODE #2 – Change the reference satellite over the orbit***

Like Mode #1 but the leader satellite changes over the course of the orbit so as to optimize the angular coverage of the BRDF plane.



### ***MODE #3 – Tracking/Staring at a Spot***

All satellites such that they point to the same ground target/s as they approach over the horizon and recede into the horizon.

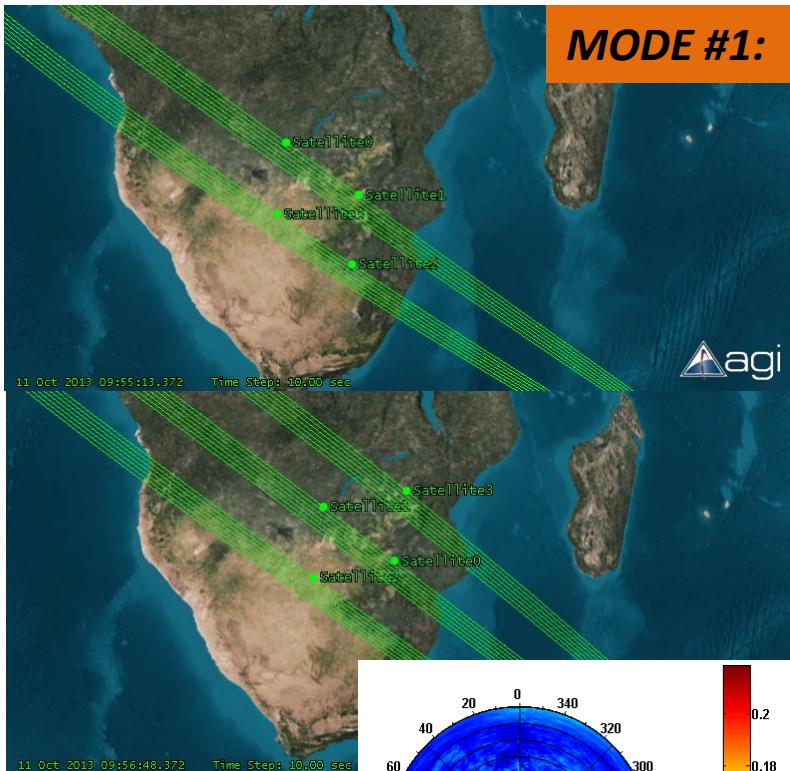


### ***MODE #4 – Multiple Payloads***

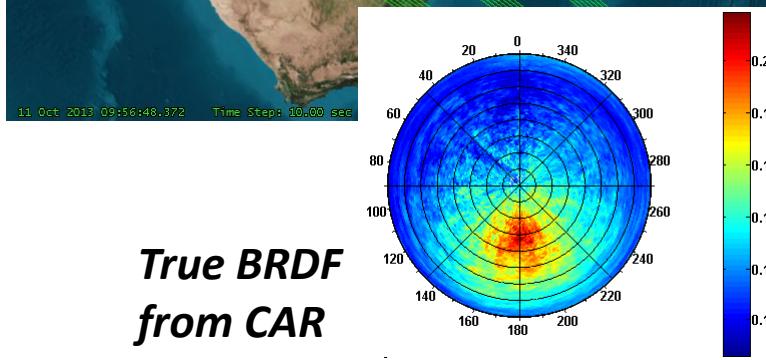
Each follows a different mode among the above or fractionate functionality.

# Albedo Errors by Configuration

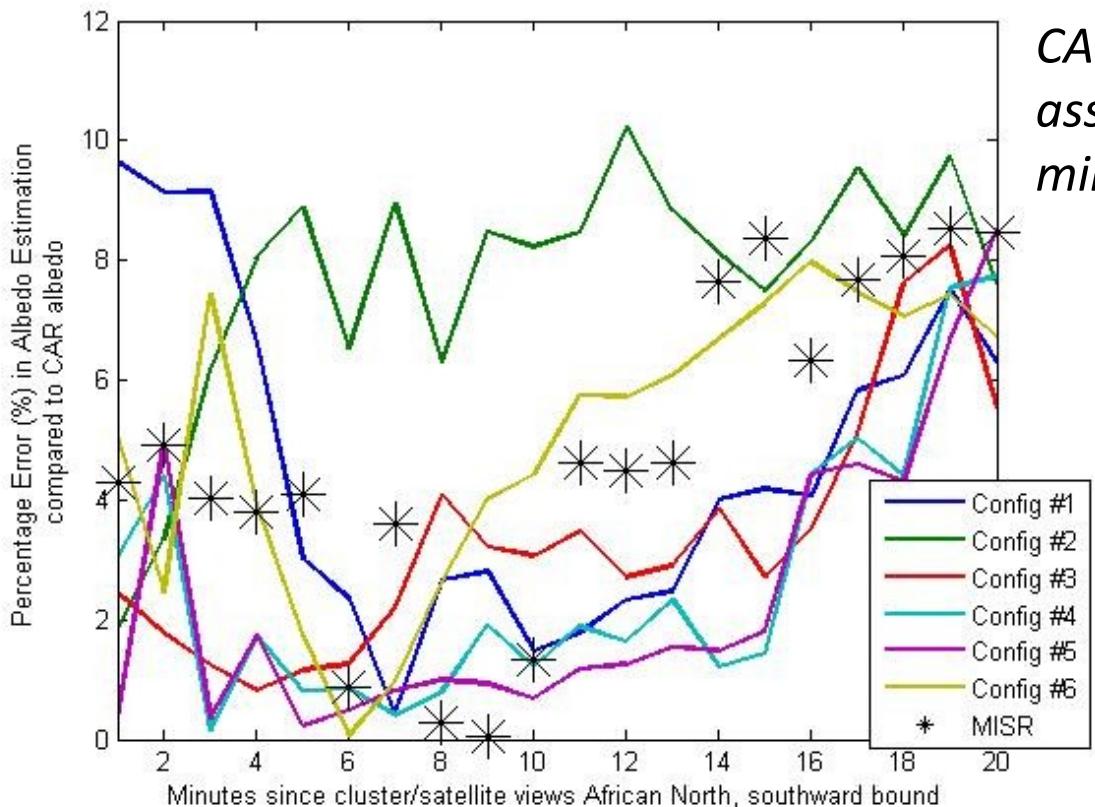
*Compared 6 diff. TA+RAAN orbits wrt CAR data (682 nm) from South Africa assuming same biome over a 20 minute pass over African Peninsula.*



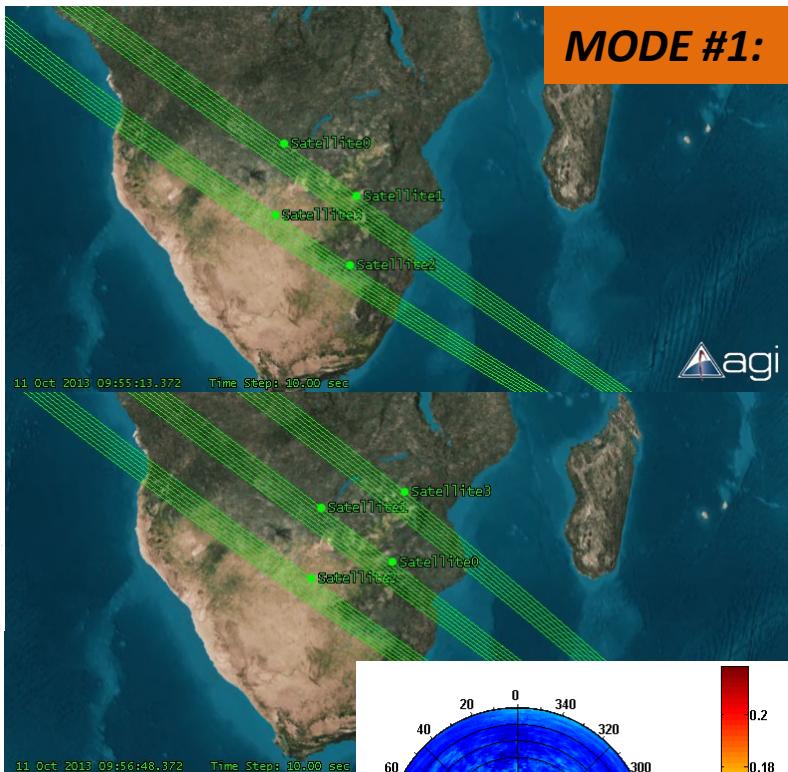
**True BRDF  
from CAR**



# Albedo Errors by Configuration



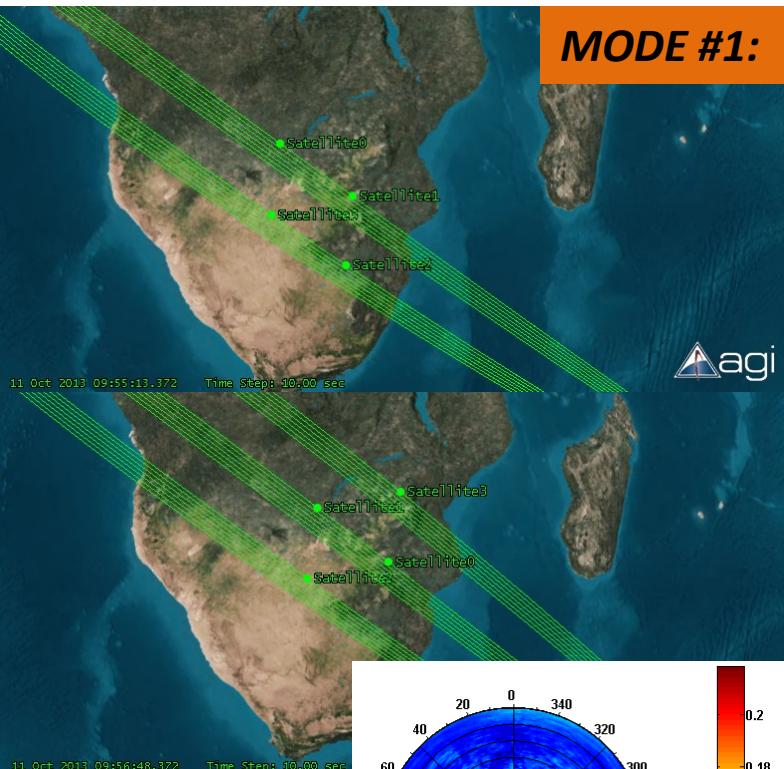
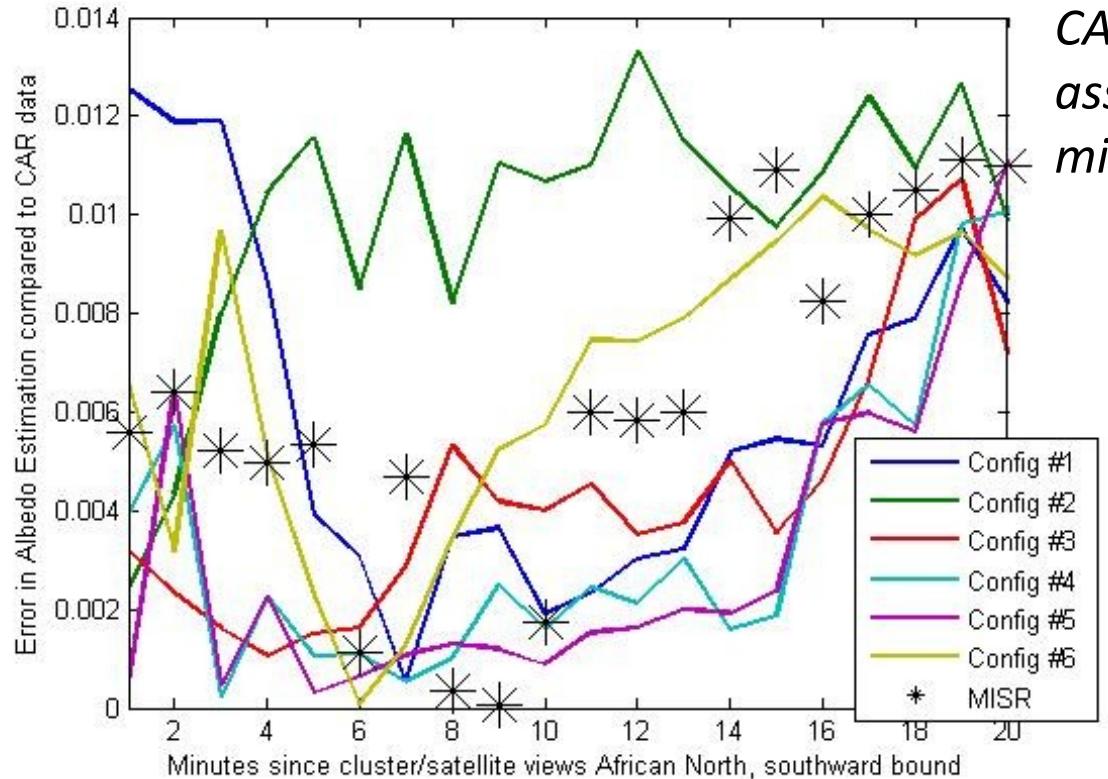
Compared 6 diff. TA+RAAN orbits wrt CAR data (682 nm) from South Africa assuming same biome over a 20 minute pass over African Peninsula.



True BRDF  
from CAR

# Albedo Errors by Configuration

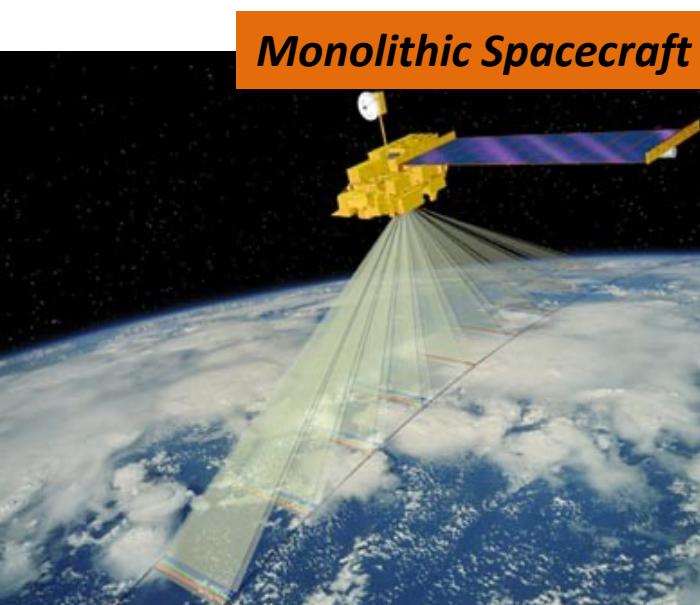
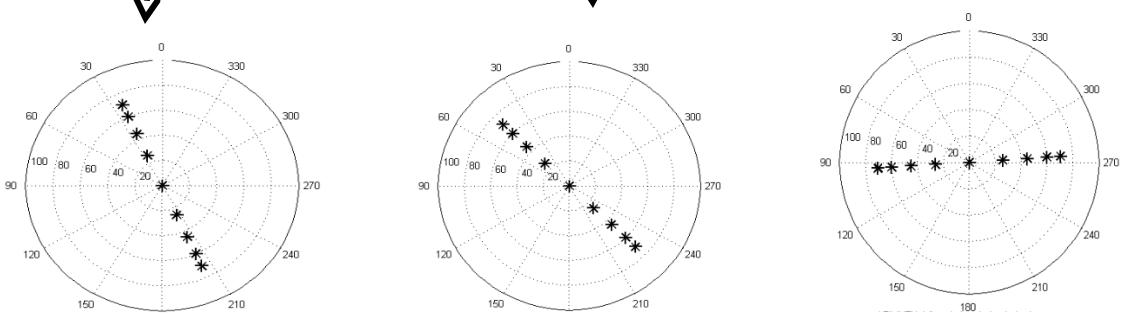
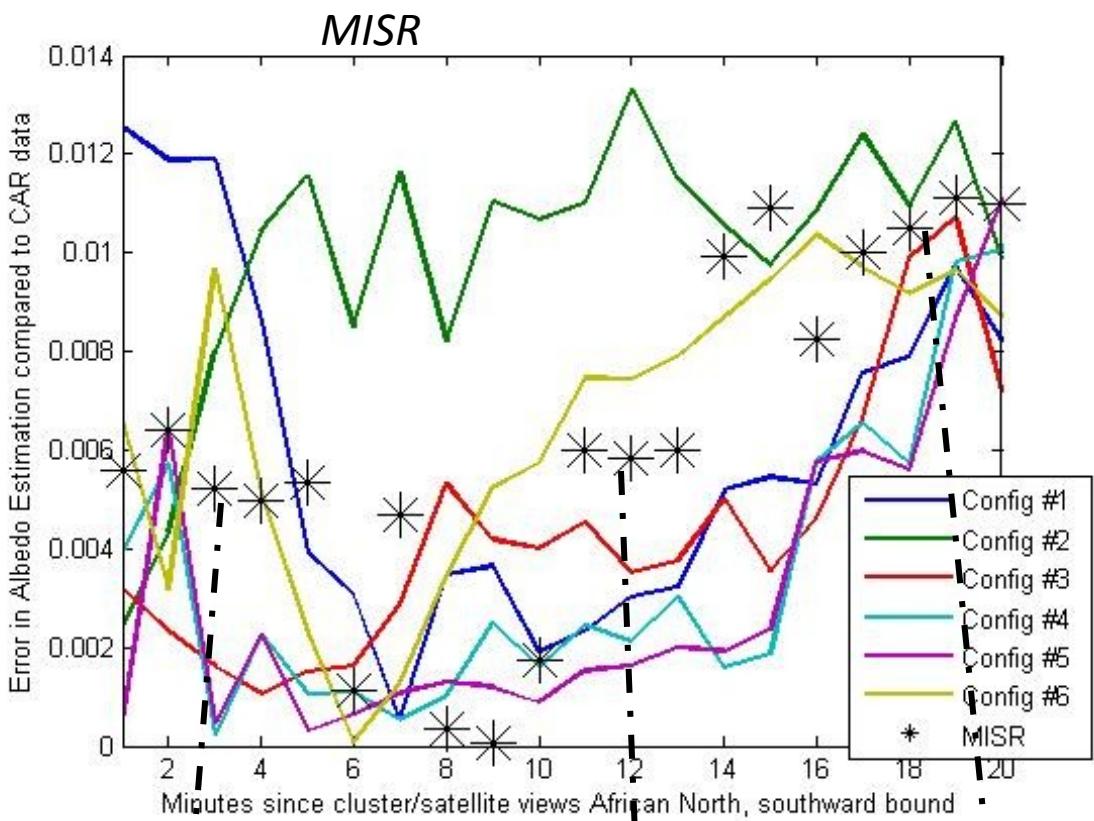
*Compared 6 diff. TA+RAAN orbits wrt CAR data (682 nm) from South Africa assuming same biome over a 20 minute pass over African Peninsula.*



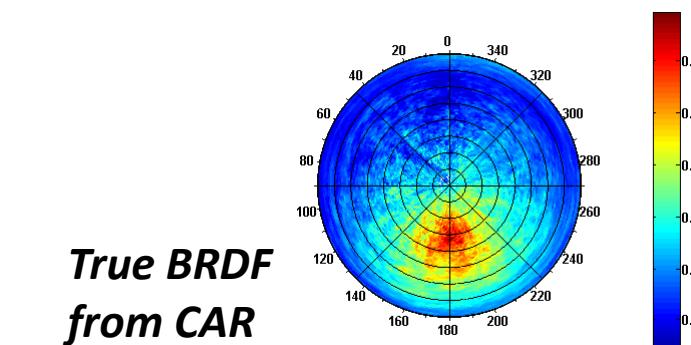
*True BRDF  
from CAR*

# Albedo Errors by Configuration

Compared 6 diff. TA+RAAN orbits wrt R data (682 nm) from South Africa assuming same biome over a 20 minute pass over African Peninsula.

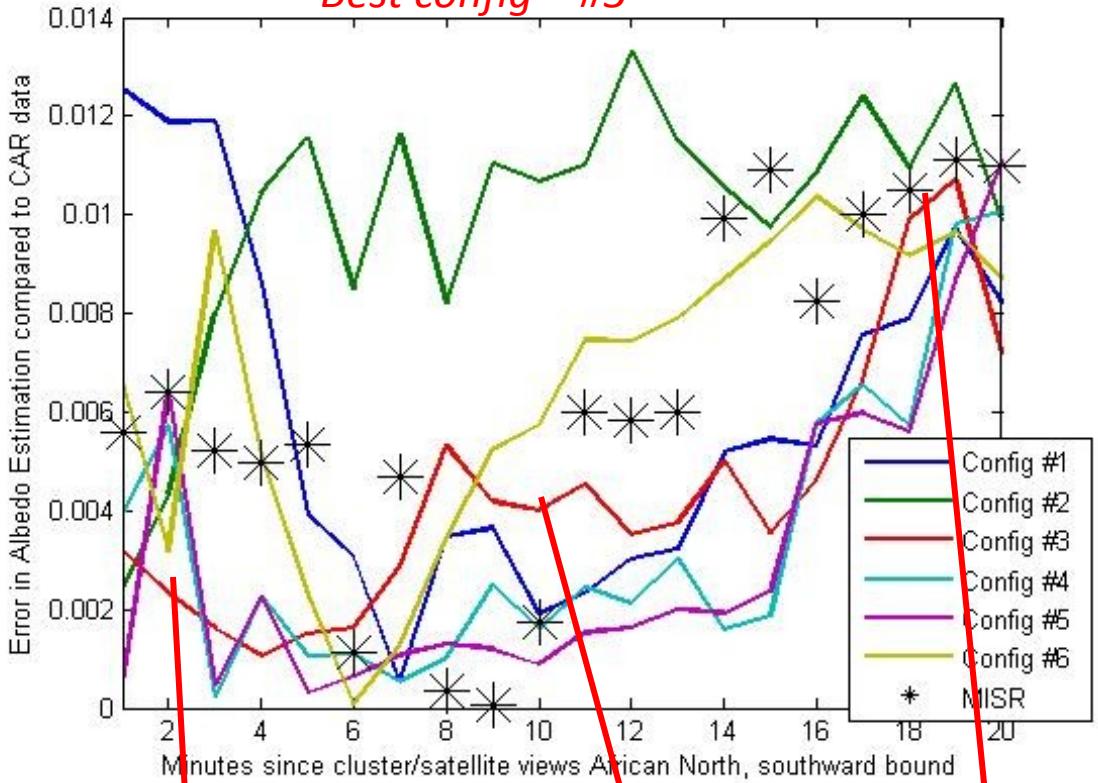


**True BRDF  
from CAR**



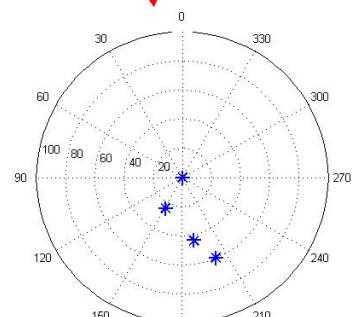
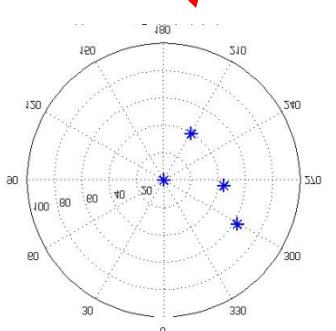
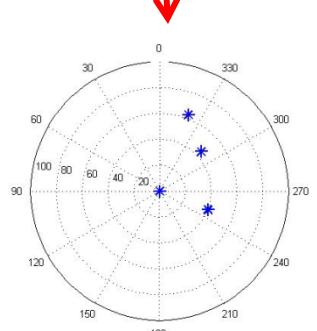
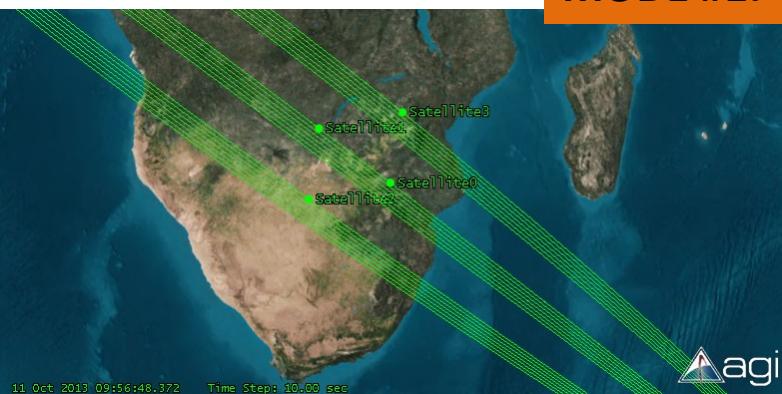
# Albedo Errors by Configuration

*Best config = #3*

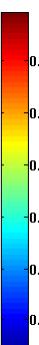
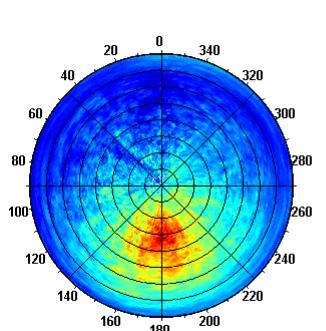


Compared 6 diff. TA+RAAN orbits wrt R data (682 nm) from South Africa assuming same biome over a 20 minute pass over African Peninsula.

**MODE #1:**

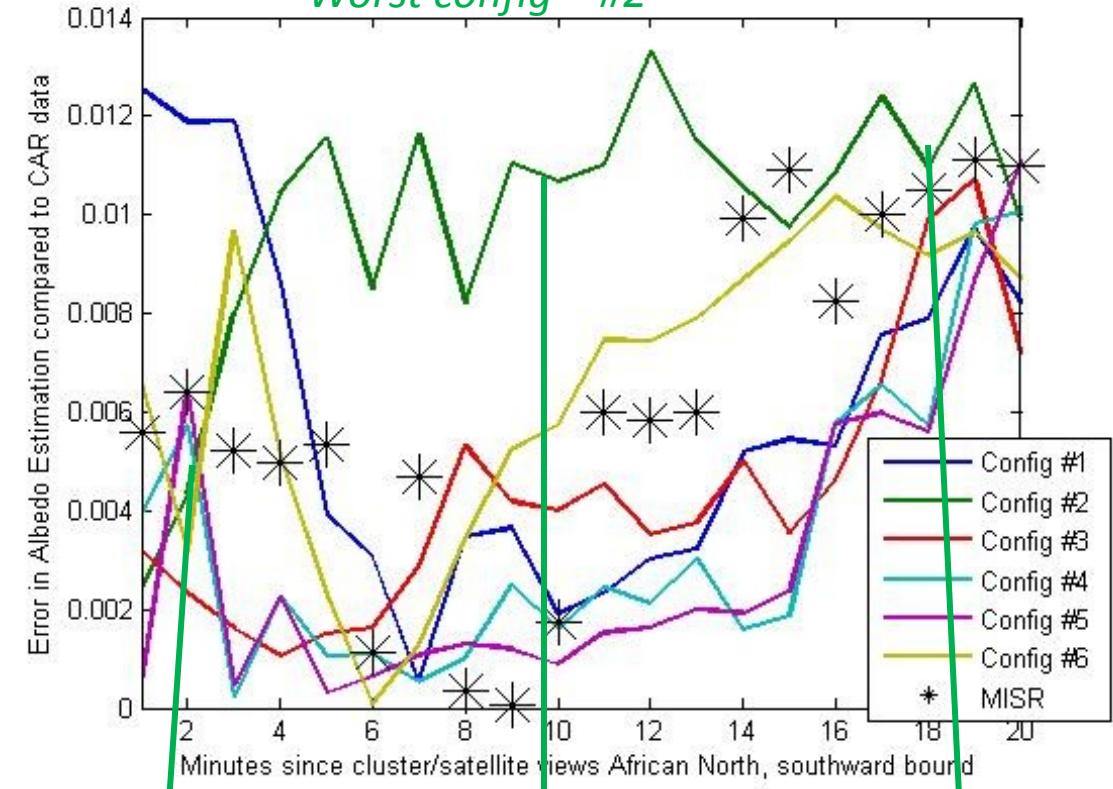


**True BRDF  
from CAR**



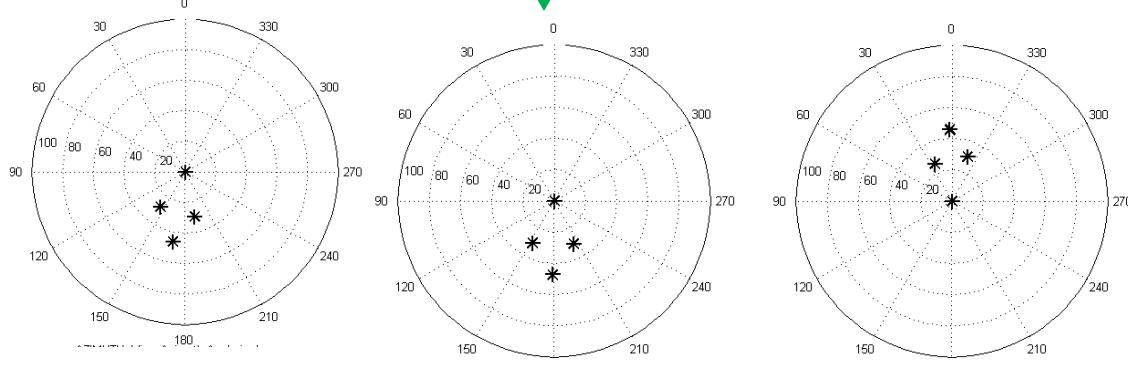
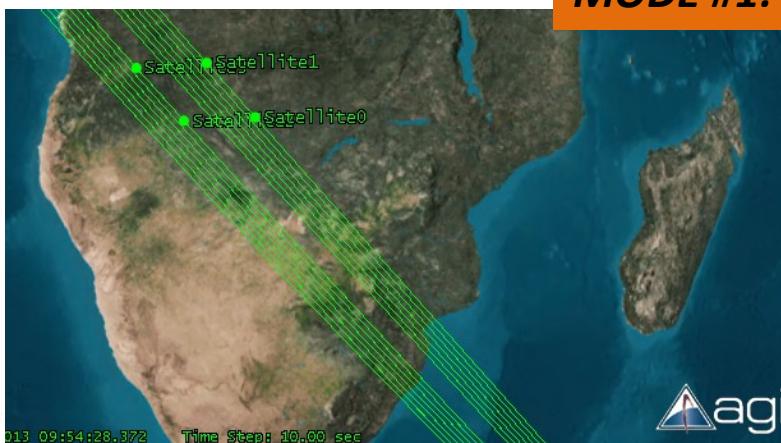
# Albedo Errors by Configuration

*Worst config = #2*

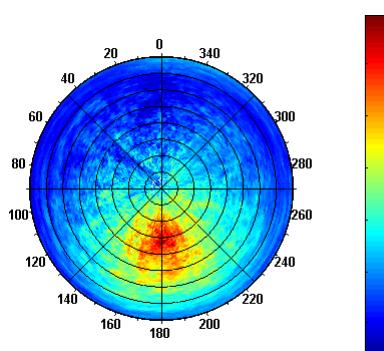


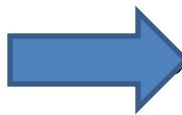
Compared 6 diff. TA+RAAN orbits wrt R data (682 nm) from South Africa assuming same biome over a 20 minute pass over African Peninsula.

**MODE #1:**



**True BRDF  
from CAR**



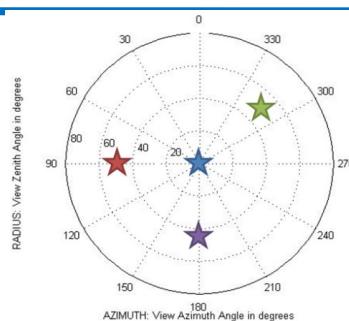
- The Angular Acquisition problem
  - Example Application dependent on Angular Sampling
  - Proposed Solution and Design Methodology
  - Baseline Case Study using a few Formation Configurations
-  Value of Imaging Modes
- Summary and Future Work

# Why use Imaging Modes?



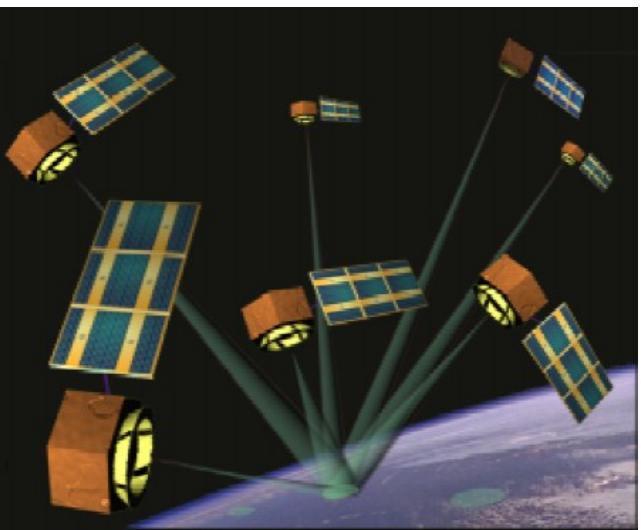
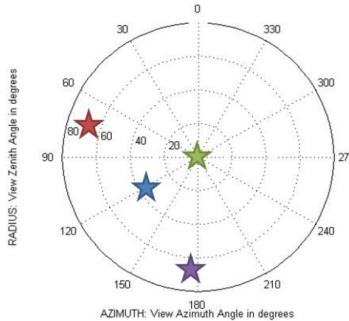
## ***MODE #1 – Same reference satellite***

Needs differential elements that are impossible to maintain with smallsat technologies to cover both hemispheres at all times (e.g. diff. inclination, diff. eccentricity)



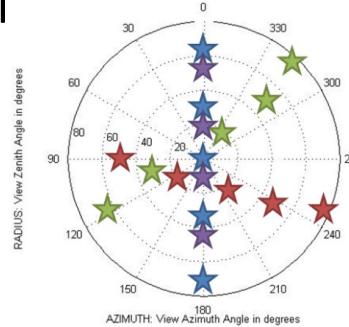
## ***MODE #2 – Change the reference satellite over the orbit***

An appropriately selected ref. satellite *allows both angular hemispheres to be covered using maintainable diff. elements.* Satellites drift apart over a year even in true anomaly.. This mode helps upto ~6 months.



## ***MODE #3 – Tracking/Staring at a Spot***

*More angular coverage and lesser local errors at the cost of spatial coverage. Polar + high latitude coverage only possible with this mode. Allows mission continuity beyond 6 months in spite of drifting satellites.*

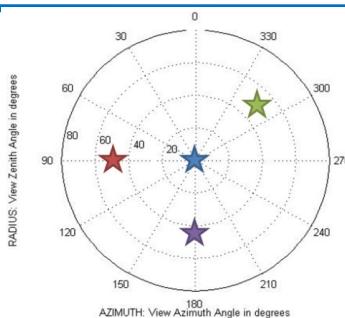


# Why use Imaging Modes?



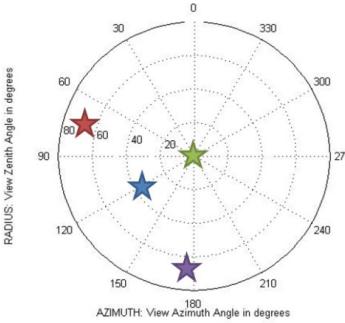
## ***MODE #1 – Same reference satellite***

Needs differential elements that are impossible to maintain with smallsat technologies to cover both hemispheres at all times (e.g. diff. inclination, diff. eccentricity)



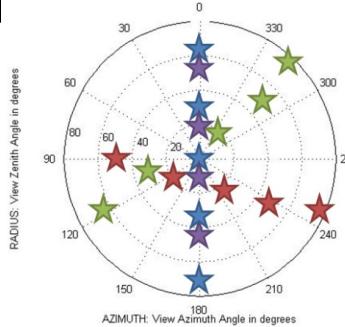
## ***MODE #2 – Change the reference satellite over the orbit***

An appropriately selected ref. satellite *allows both angular hemispheres to be covered using maintainable diff. elements.* Satellites drift apart over a year even in true anomaly.. This mode helps upto ~6 months.

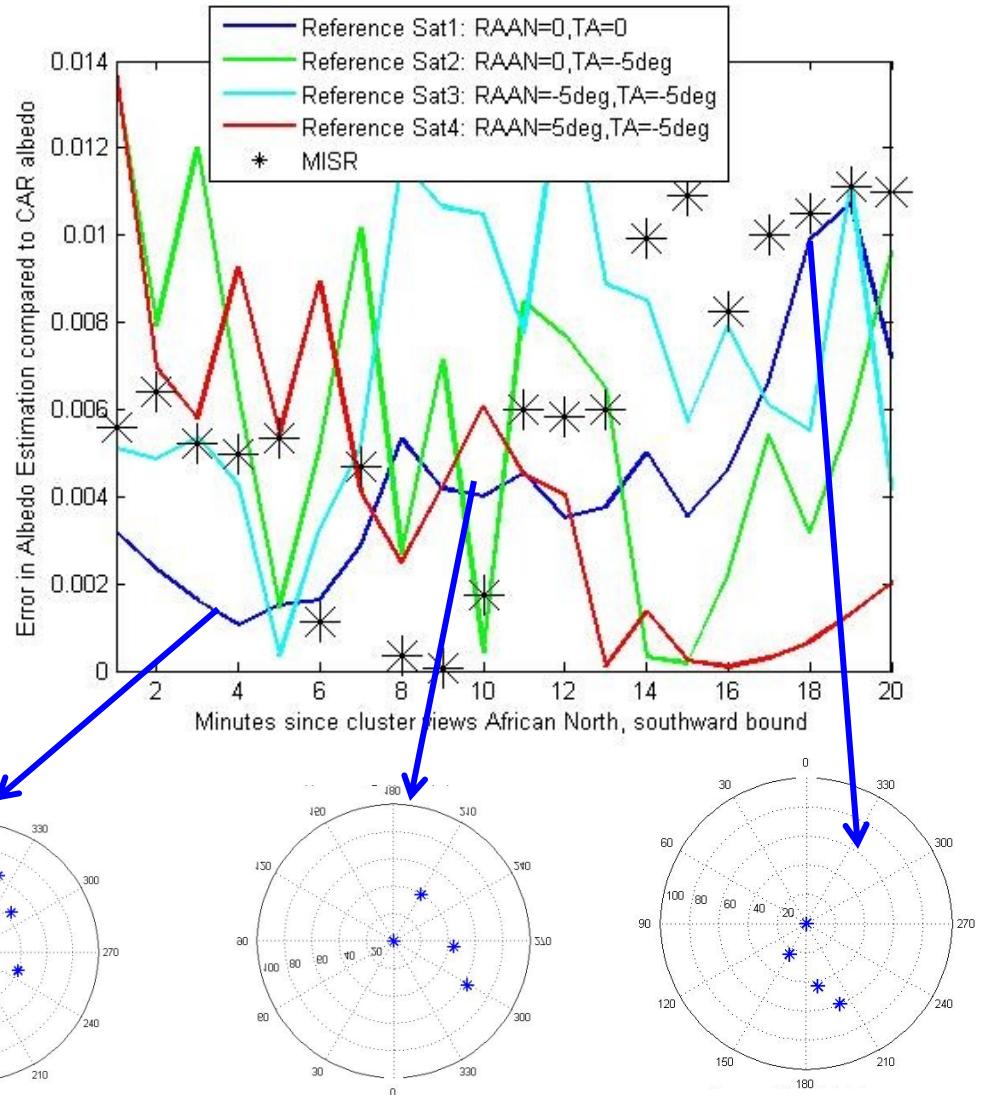


## ***MODE #3 – Tracking/Staring at a Spot***

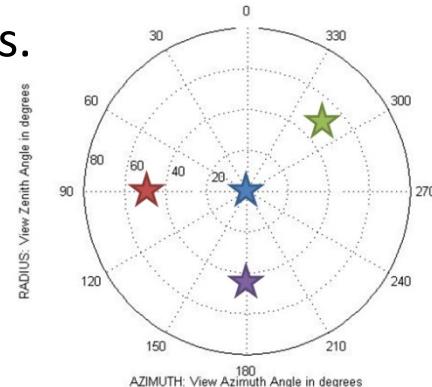
*More angular coverage and lesser local errors at the cost of spatial coverage. Polar + high latitude coverage only possible with this mode. Allows mission continuity beyond 6 months in spite of drifting satellites.*



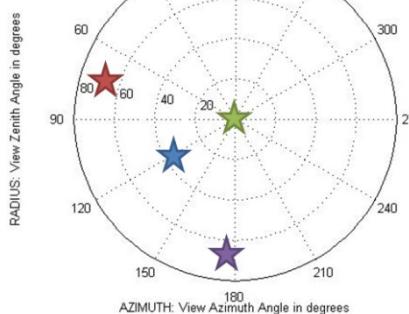
For the best configuration (#3), analyzed errors using different sats as reference.  
By changing the ref sat once in 20 mins, we can outdo monoliths.



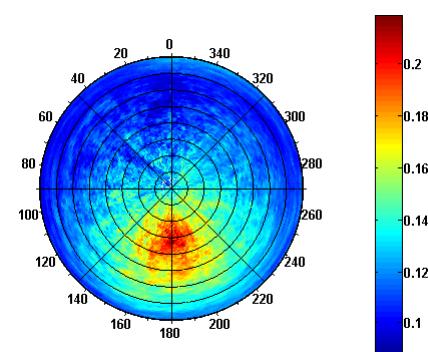
**MODE #1:**



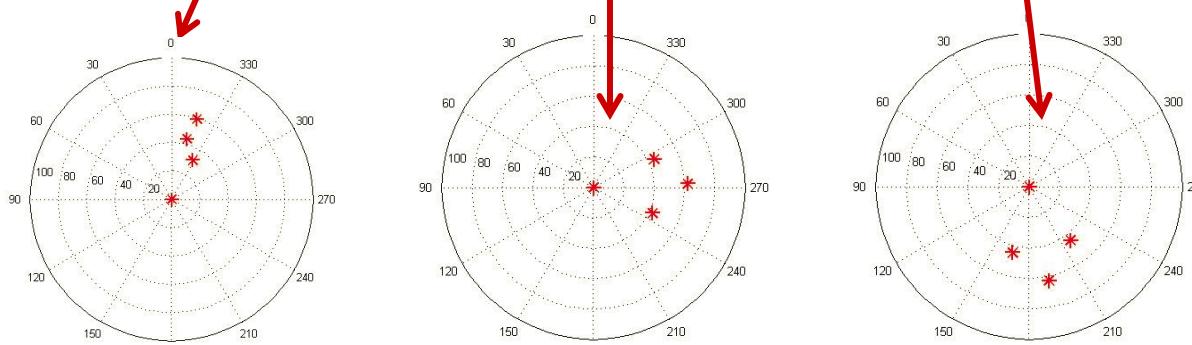
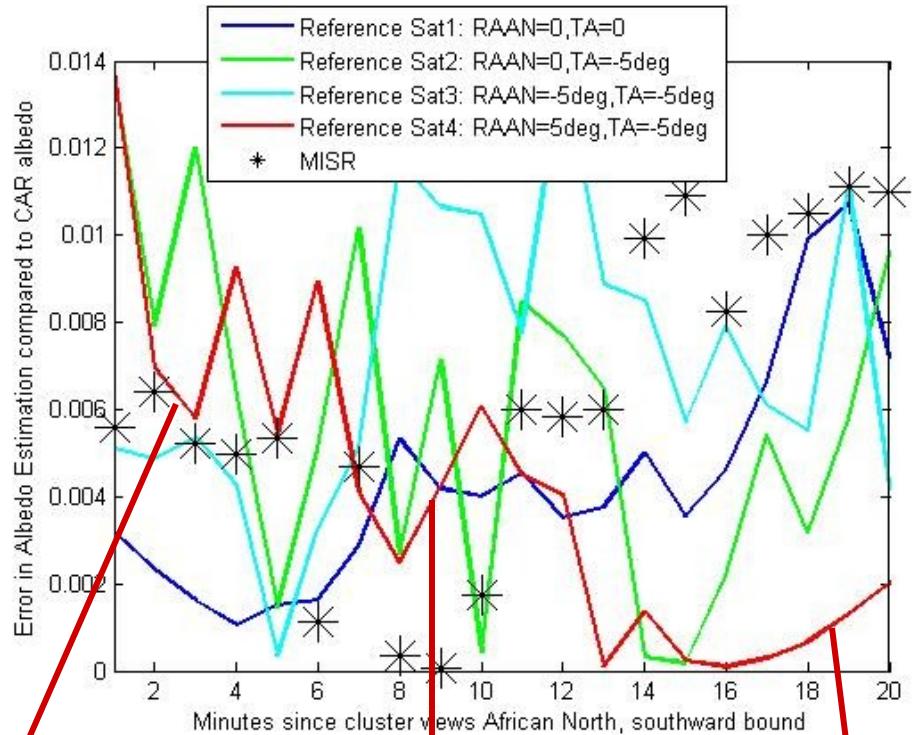
**MODE #2:**



**True BRDF  
from CAR:**



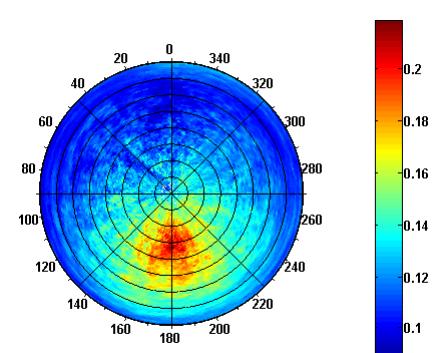
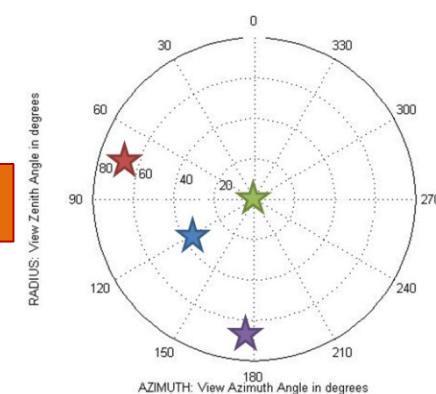
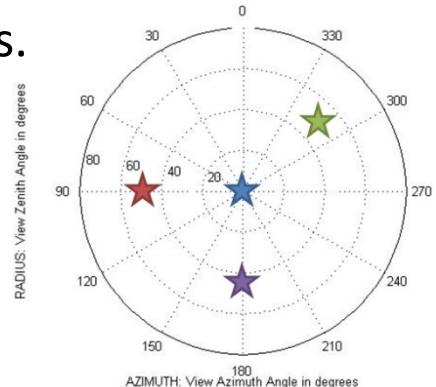
For the best configuration (#3), analyzed errors using different sats as reference.  
By changing the ref sat once in 20 mins, we can outdo monoliths.



**MODE #1:**

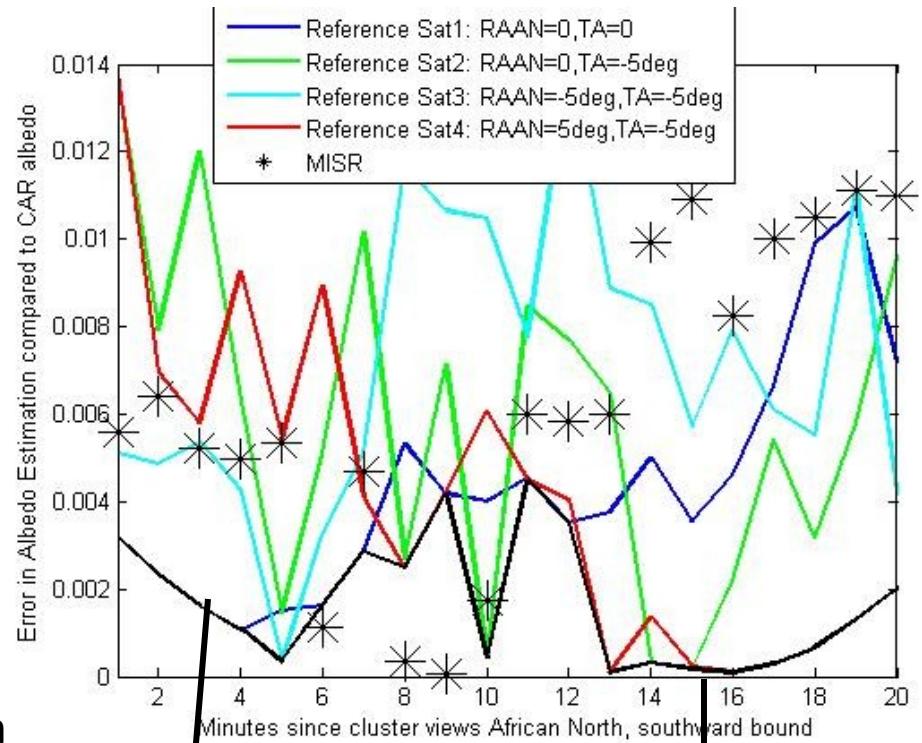
**MODE #2:**

**True BRDF from CAR:**

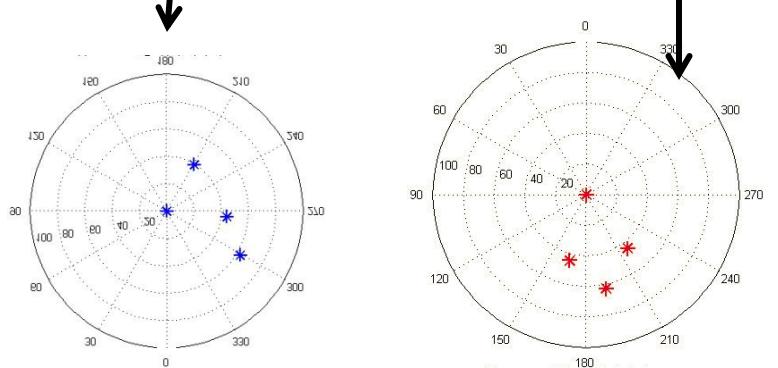


For the best configuration (#3), analyzed errors using different sats as reference.

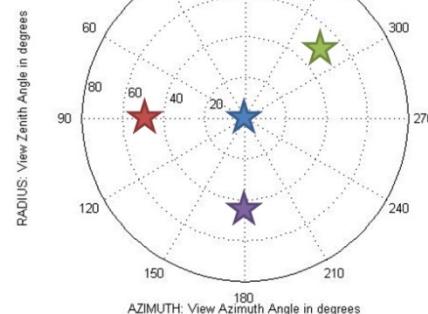
By changing the ref sat once in 20 mins, we can outdo monoliths



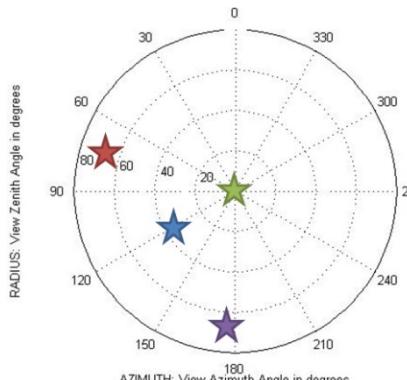
Minimum Estimation Error:



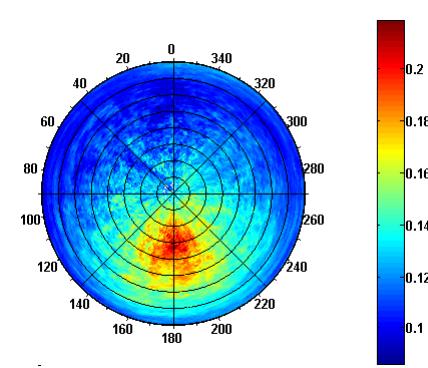
**MODE #1:**



**MODE #2:**



**True BRDF from CAR:**

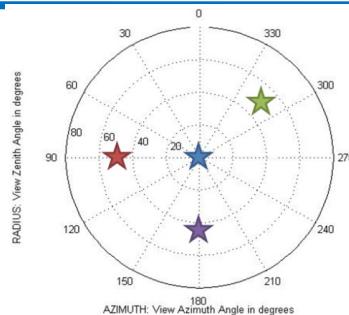


# Why use Imaging Modes?



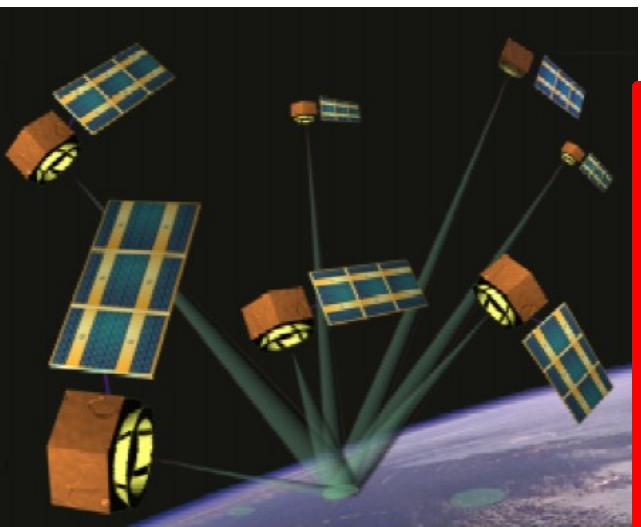
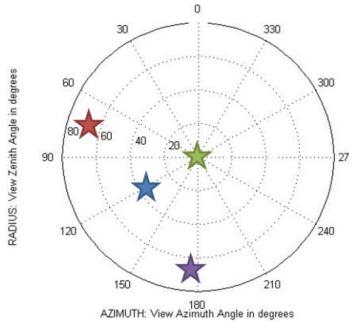
## ***MODE #1 – Same reference satellite***

Needs differential elements that are impossible to maintain with smallsat technologies to cover both hemispheres at all times (e.g. diff. inclination, diff. eccentricity)



## ***MODE #2 – Change the reference satellite over the orbit***

An appropriately selected ref. satellite *allows both angular hemispheres to be covered using maintainable diff. elements.* Satellites drift apart over a year even in true anomaly.. This mode helps upto ~6 months.

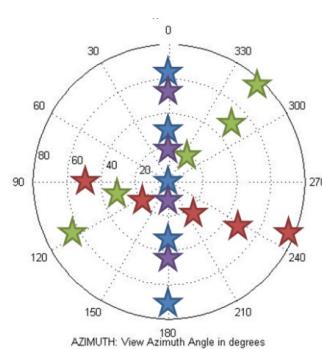


## ***MODE #3 – Tracking/Staring at a Spot***

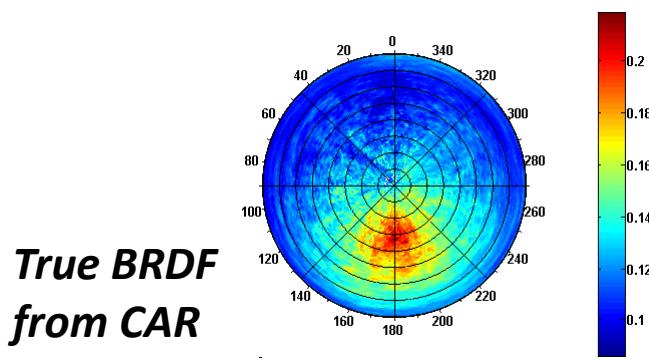
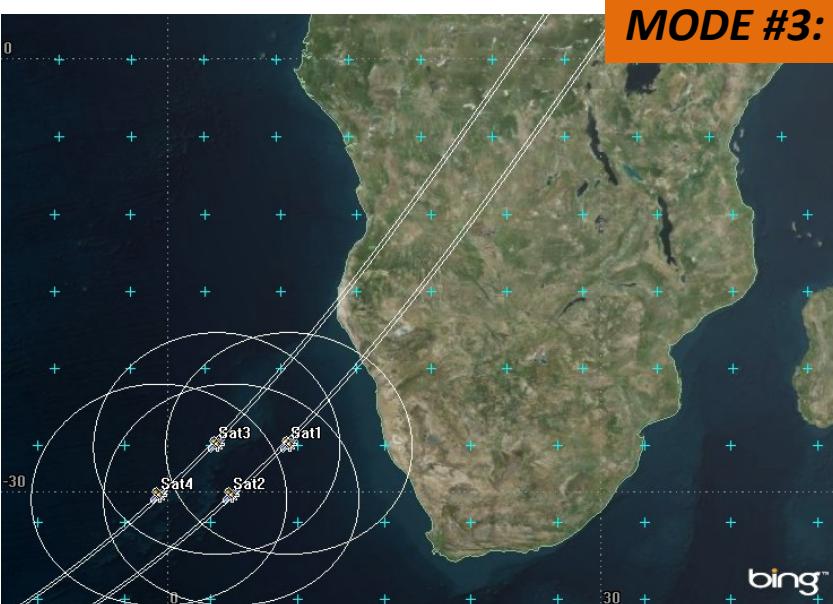
*More angular coverage and lesser local errors at the cost of spatial coverage.*

*Polar + high latitude coverage only possible with this mode.*

*Allows mission continuity beyond 6 months in spite of drifting satellites.*

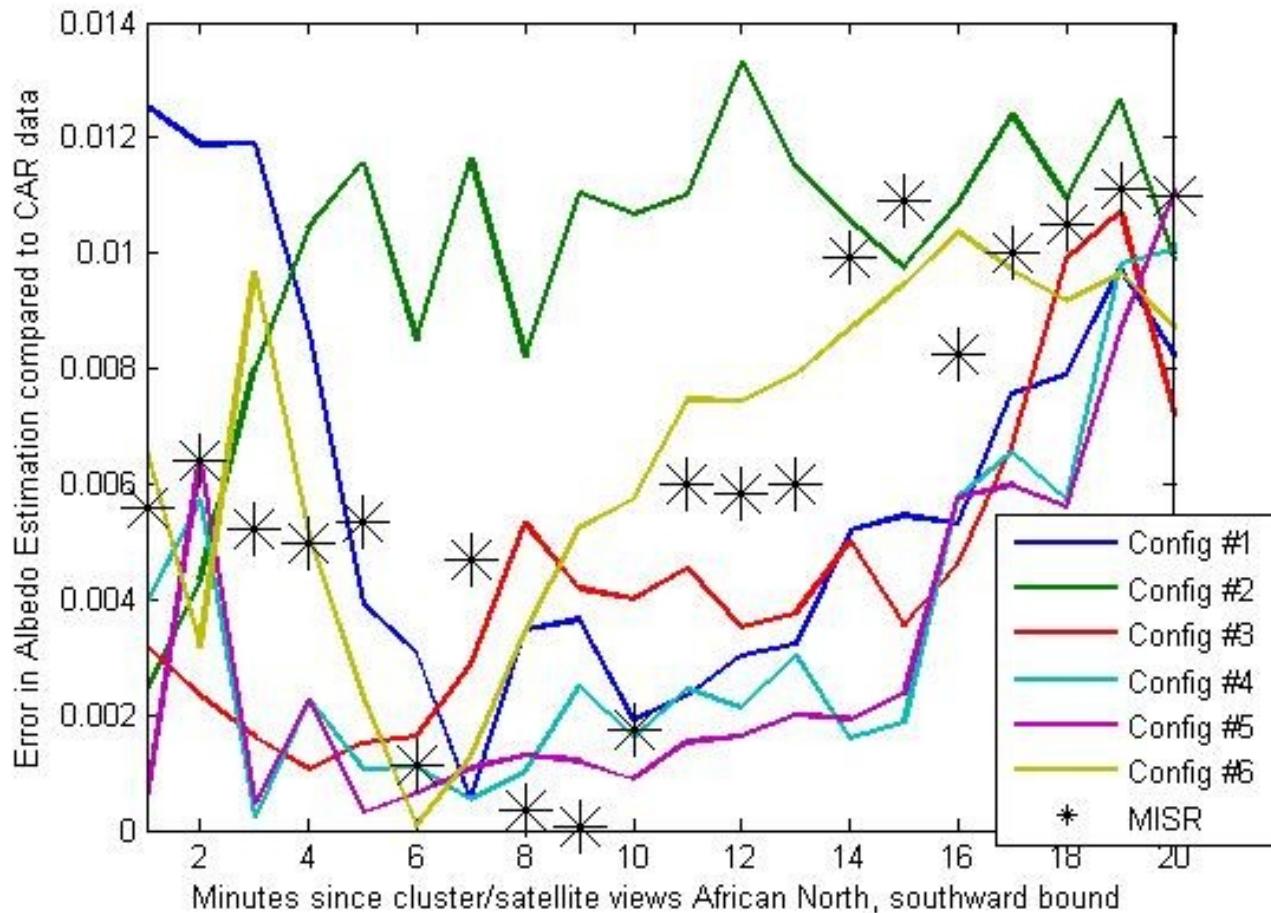


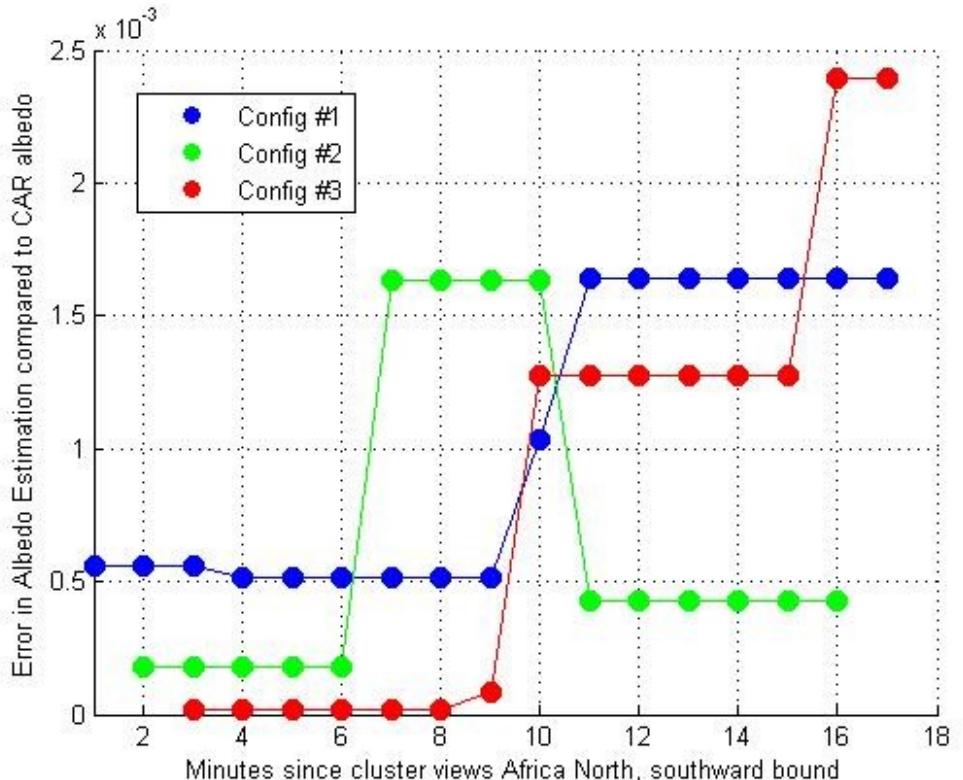
*Compared 6 diff. TA+RAAN orbits wrt CAR data (682 nm) from South Africa assuming same biome over a 20 minute pass over African Peninsula.*



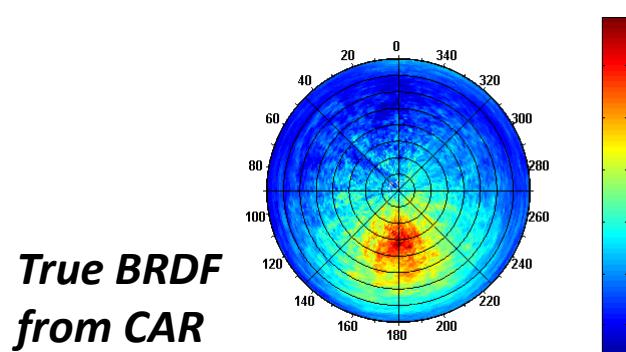
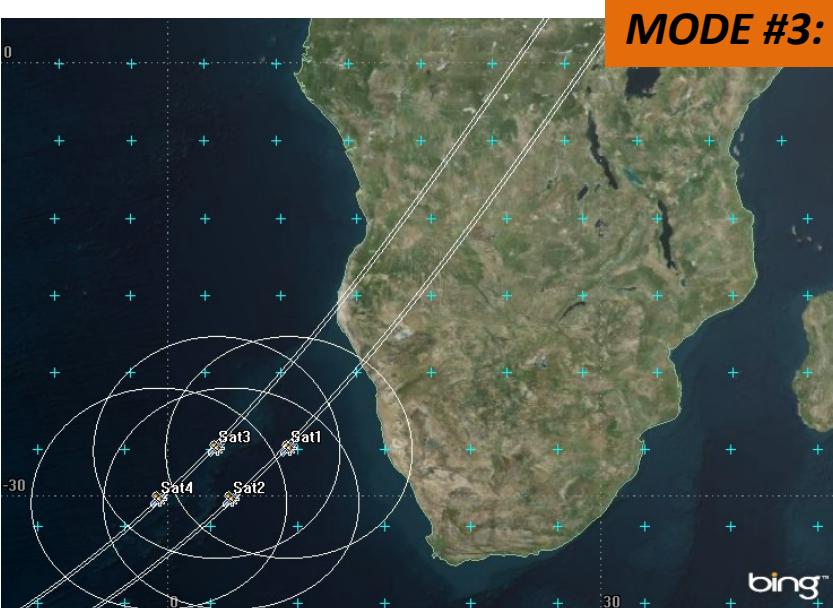
## RECAP -

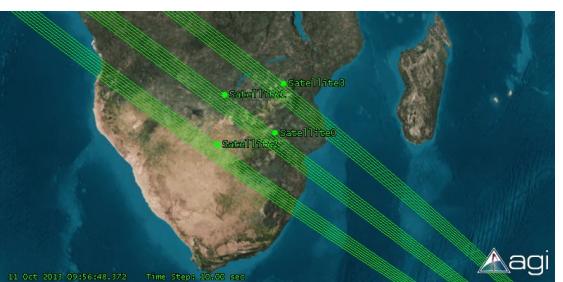
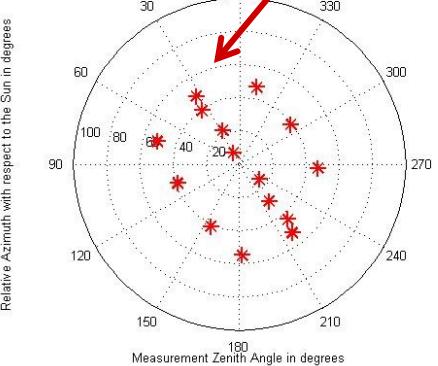
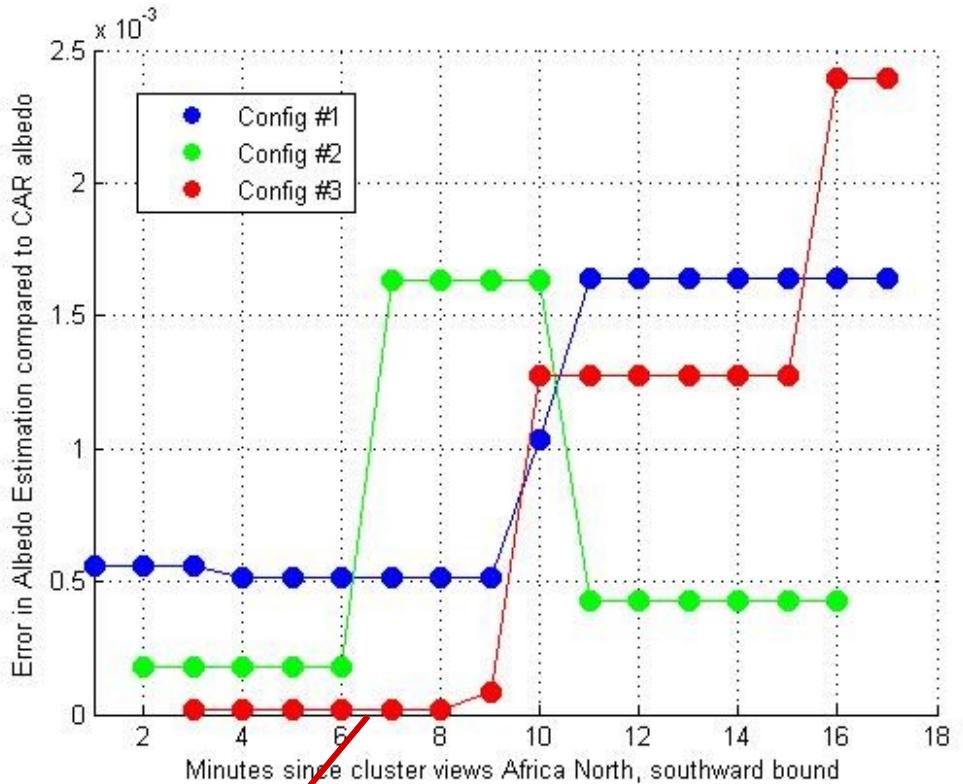
Config #1 : Mode #1 Worst but Improved by Mode#2  
Config #2 : Mode #1 Worse, NOT improved by Mode #2  
Config #3 : Best for Mode#1 and Mode#2



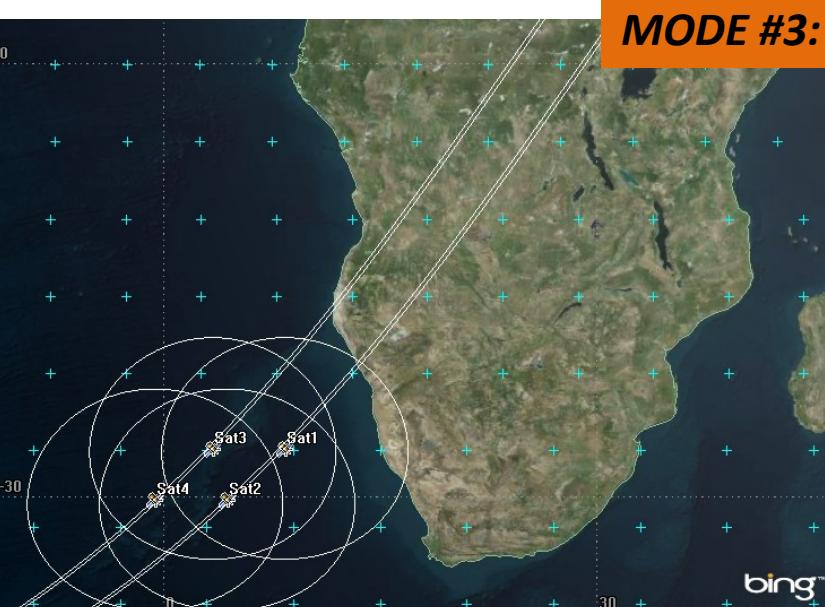


Compared 6 diff. TA+RAAN orbits wrt CAR data (682 nm) from South Africa assuming same biome over a 20 minute pass over African Peninsula.

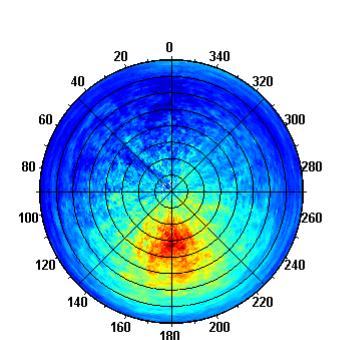


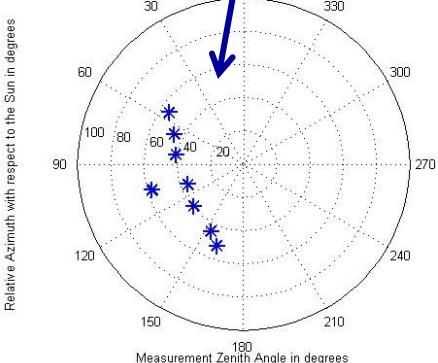
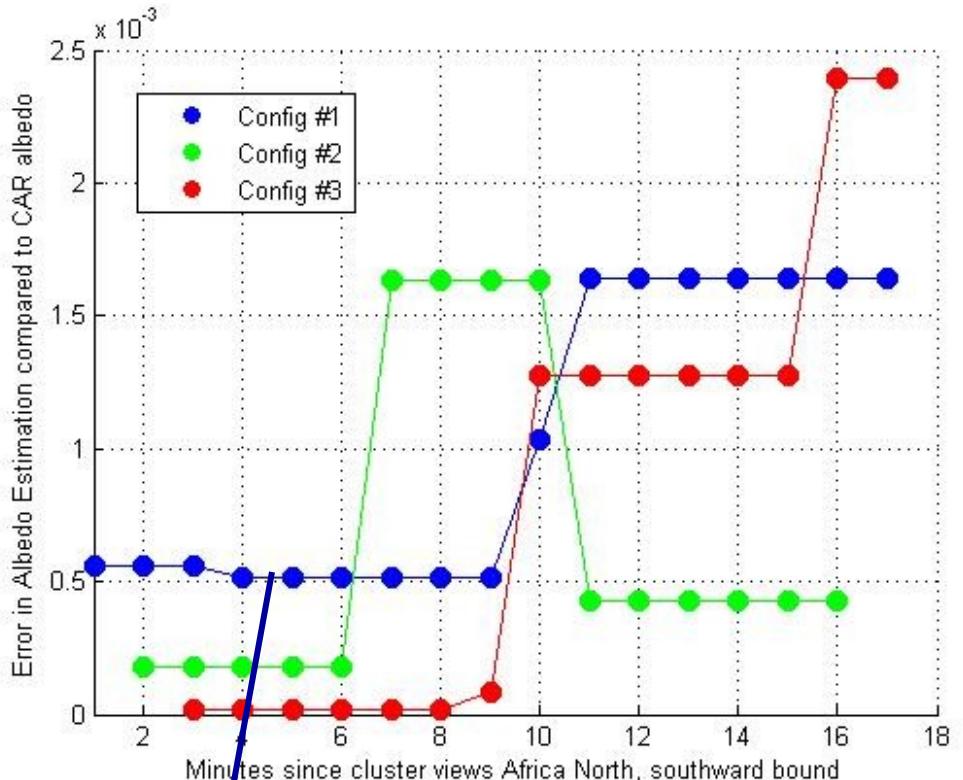


Compared 6 diff. TA+RAAN orbits wrt CAR data (682 nm) from South Africa assuming same biome over a 20 minute pass over African Peninsula.

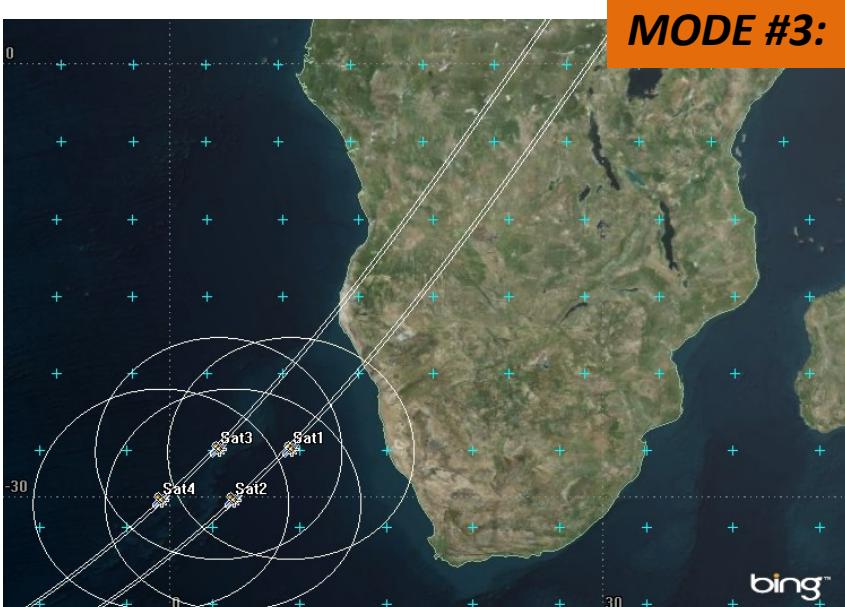


True BRDF  
from CAR

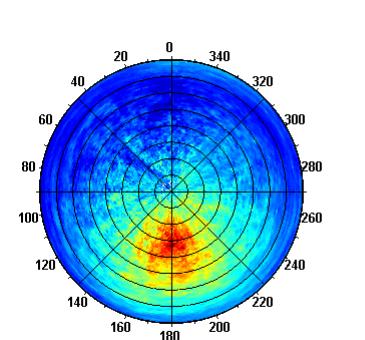


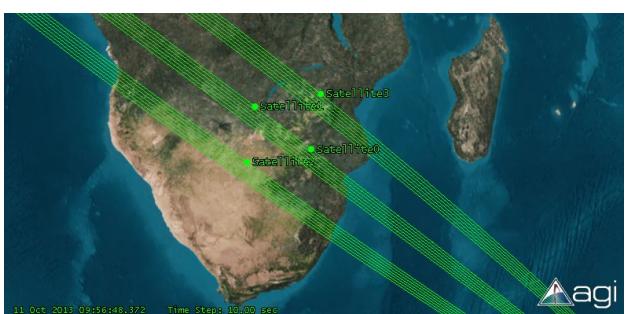
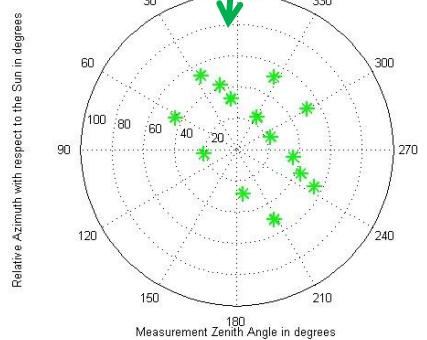
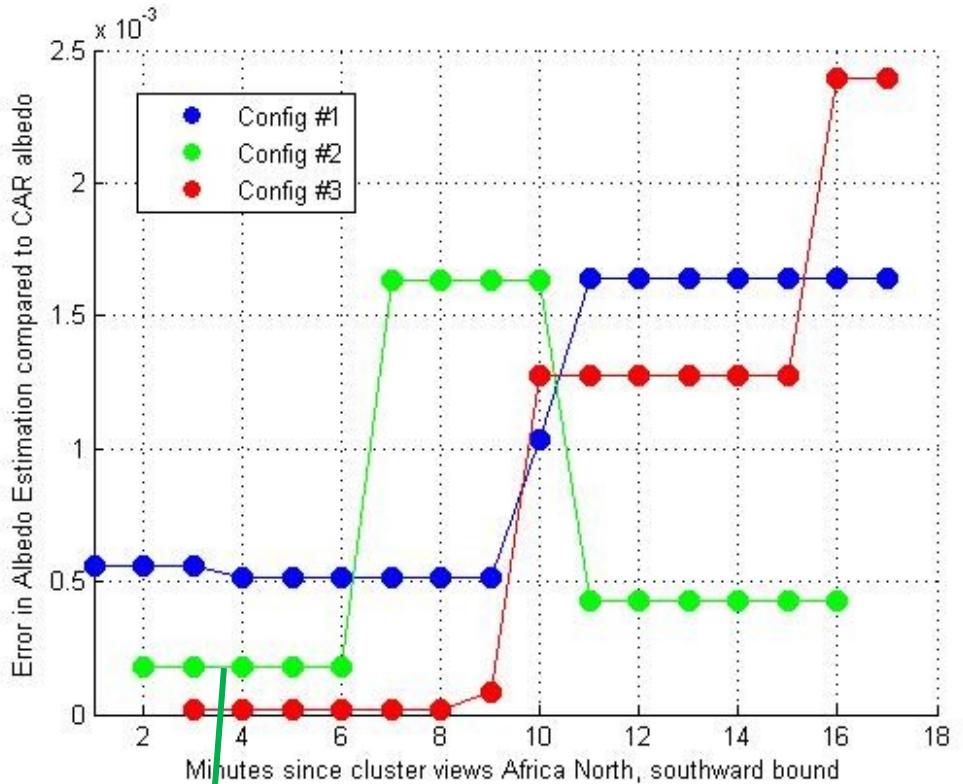


Compared 6 diff. TA+RAAN orbits wrt CAR data (682 nm) from South Africa assuming same biome over a 20 minute pass over African Peninsula.

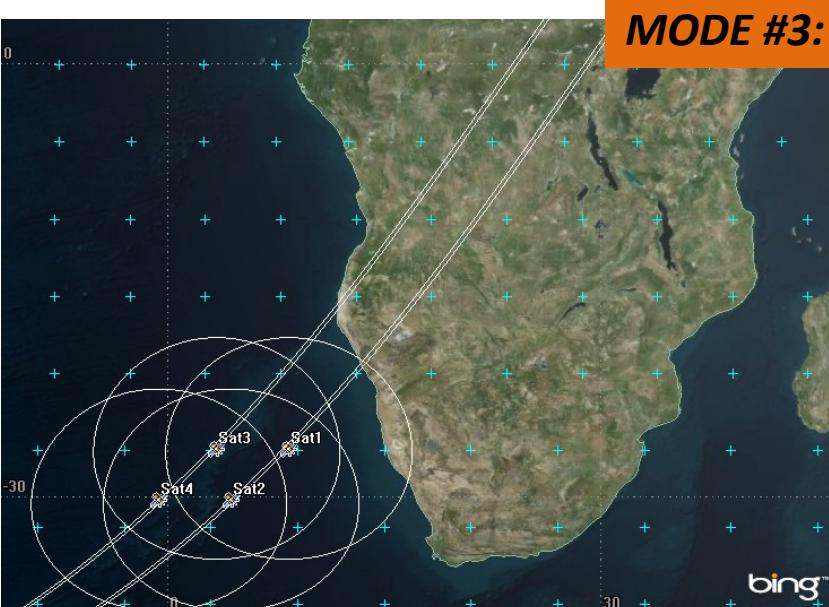


True BRDF  
from CAR

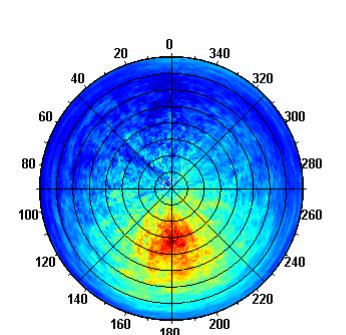




Compared 6 diff. TA+RAAN orbits wrt CAR data (682 nm) from South Africa assuming same biome over a 20 minute pass over African Peninsula.



True BRDF  
from CAR

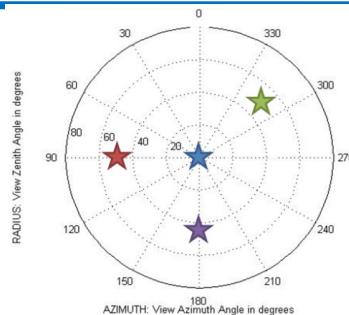


# Why use Imaging Modes?



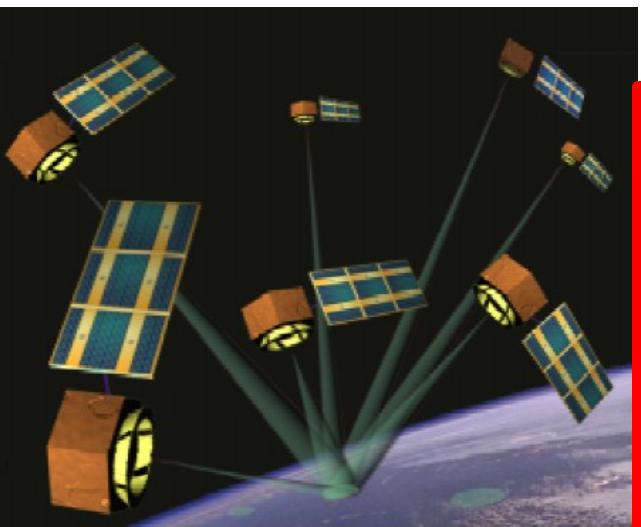
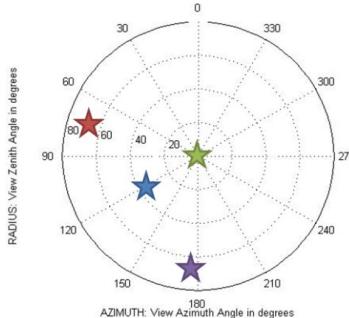
## ***MODE #1 – Same reference satellite***

Needs differential elements that are impossible to maintain with smallsat technologies to cover both hemispheres at all times (e.g. diff. inclination, diff. eccentricity)



## ***MODE #2 – Change the reference satellite over the orbit***

An appropriately selected ref. satellite *allows both angular hemispheres to be covered using maintainable diff. elements.* Satellites drift apart over a year even in true anomaly.. This mode helps upto ~6 months.

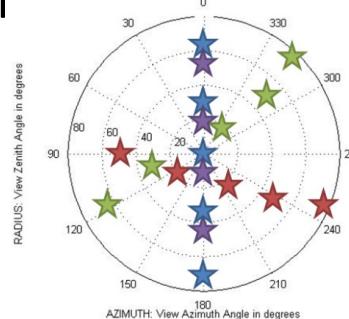


## ***MODE #3 – Tracking/Staring at a Spot***

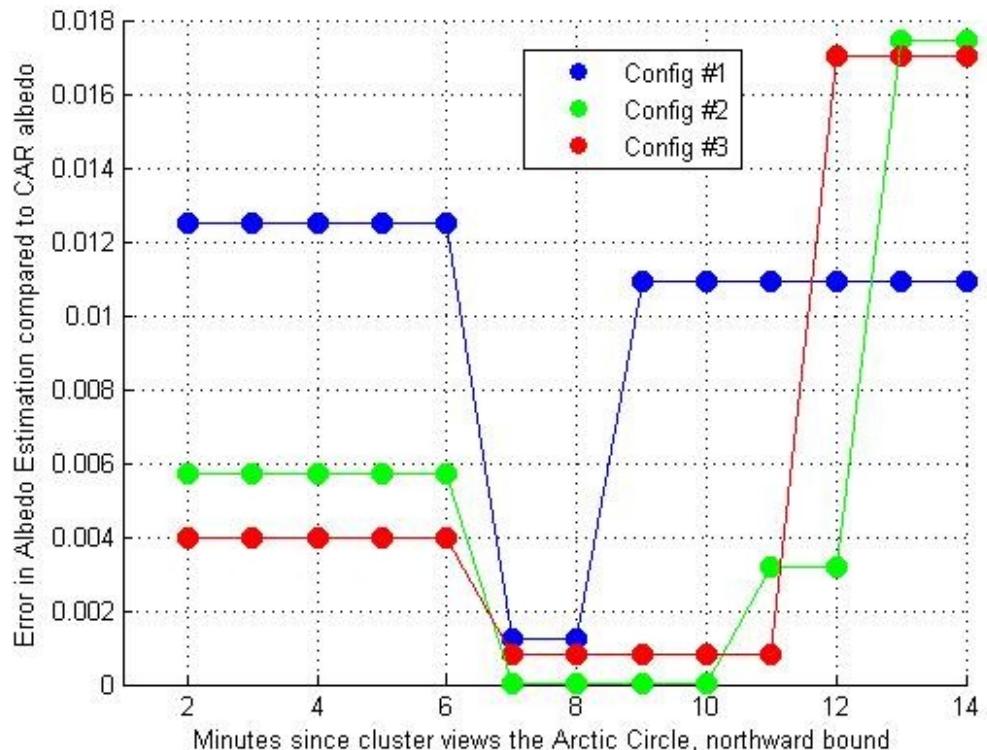
*More angular coverage and lesser local errors at the cost of spatial coverage.*

*Polar + high latitude coverage only possible with this mode.*

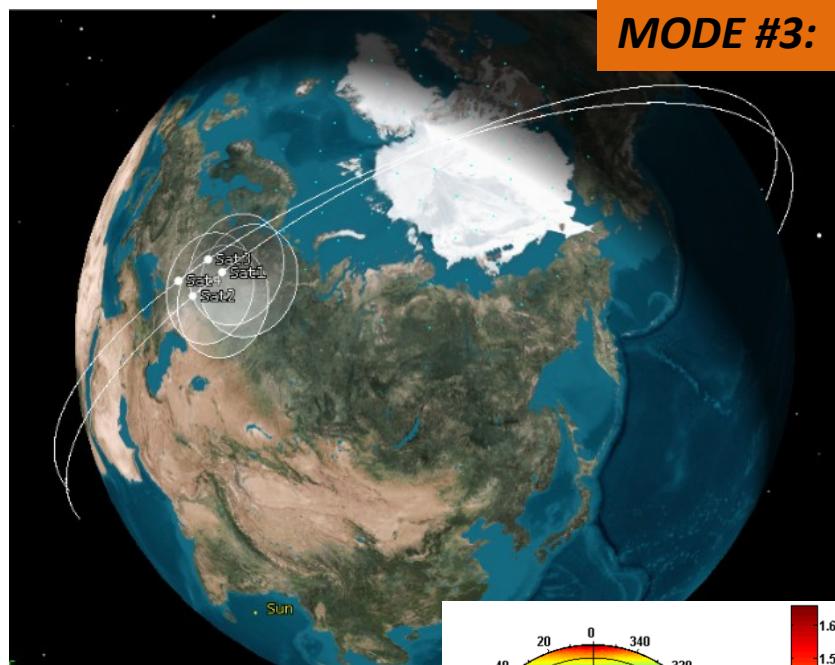
*Allows mission continuity beyond 6 months in spite of drifting satellites.*



# Polar Albedo Estimation



Compared 3 of the previous TA+RAAN orbits wrt CAR data (1031 nm) from Alaska assuming same biome over a 12 minute pass over the Arctic Circle.

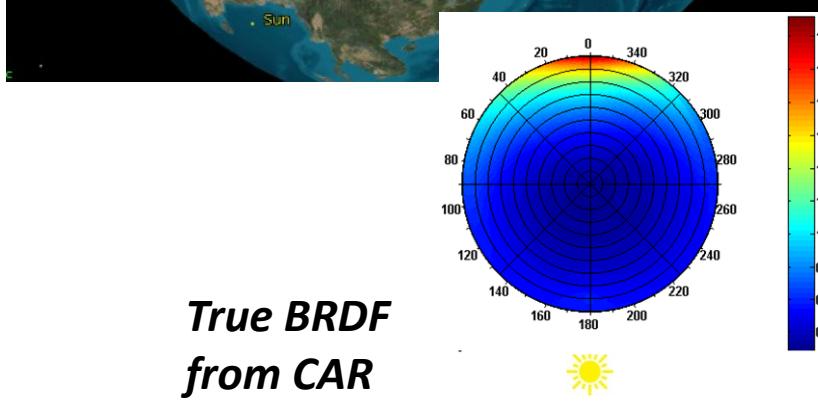
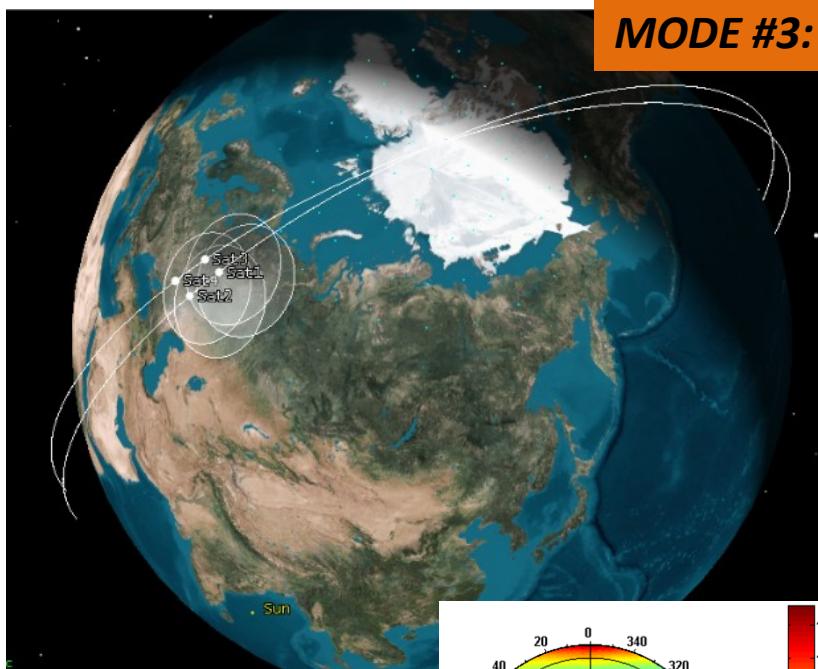
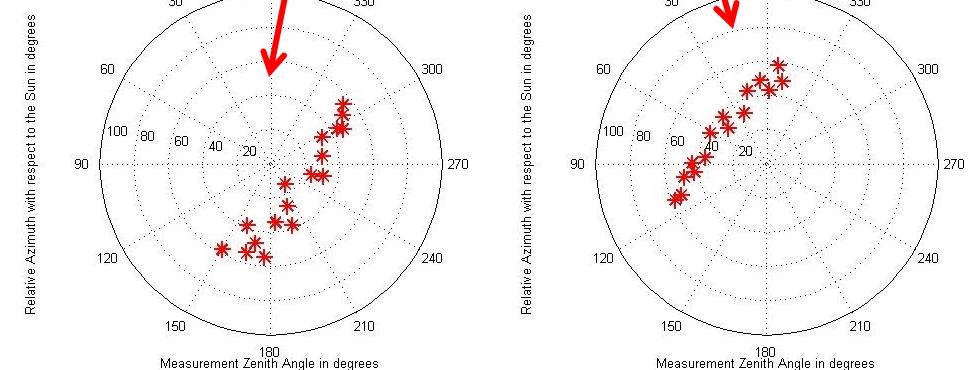
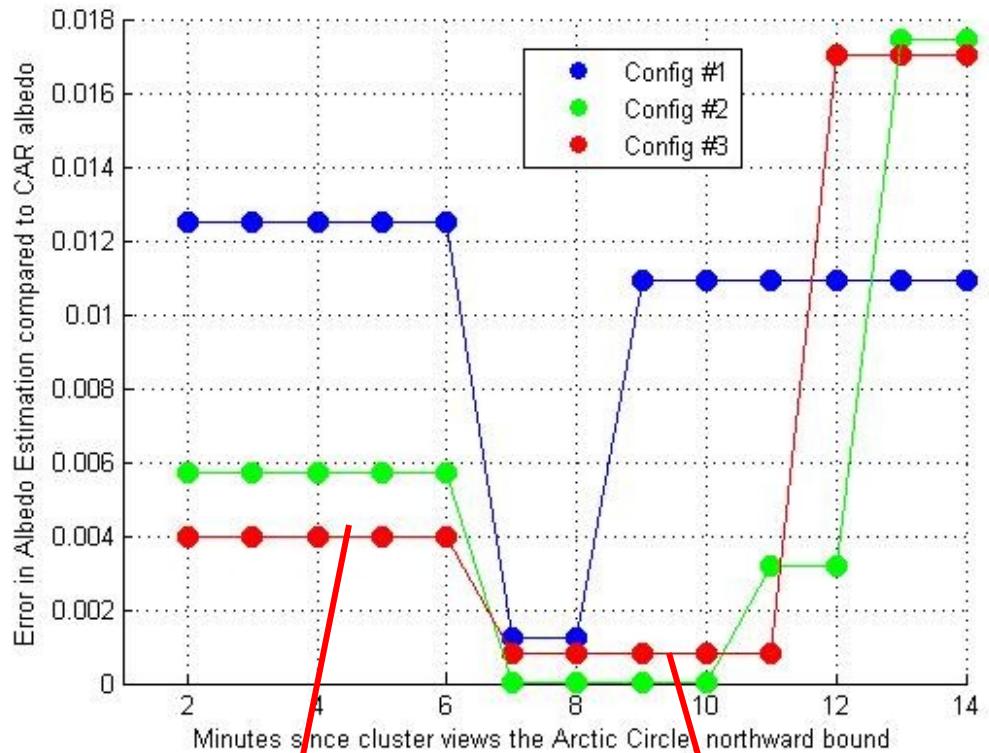


True BRDF  
from CAR



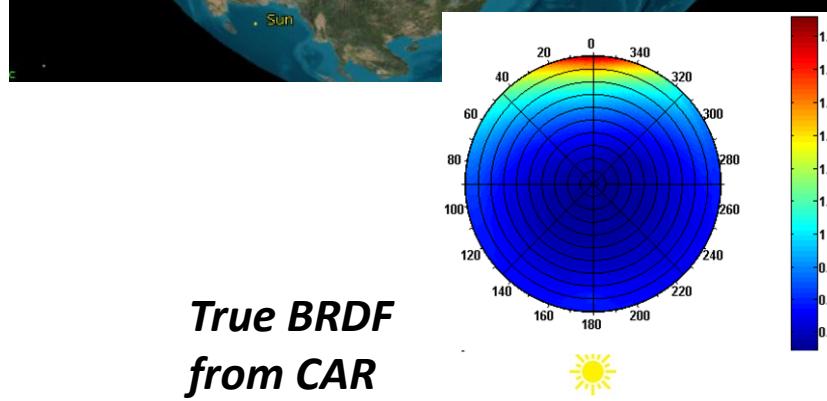
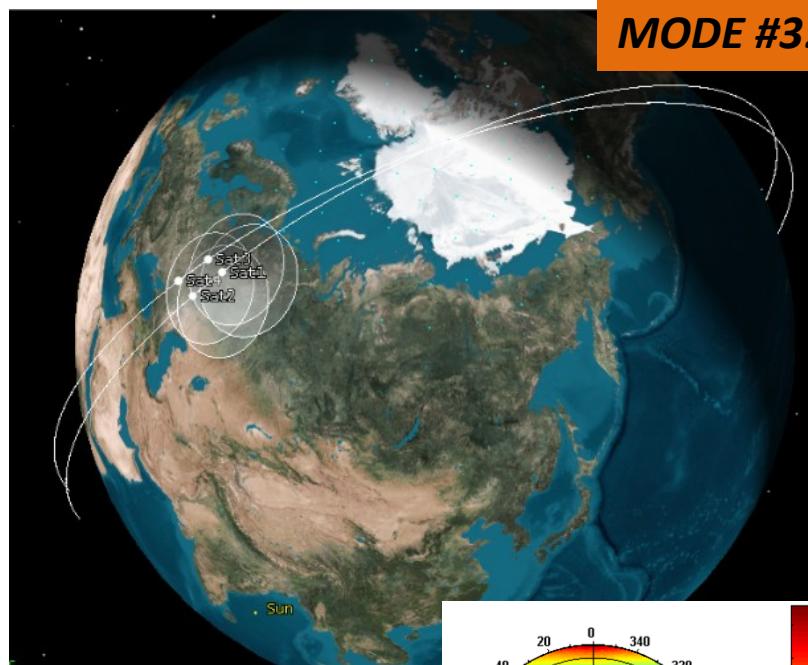
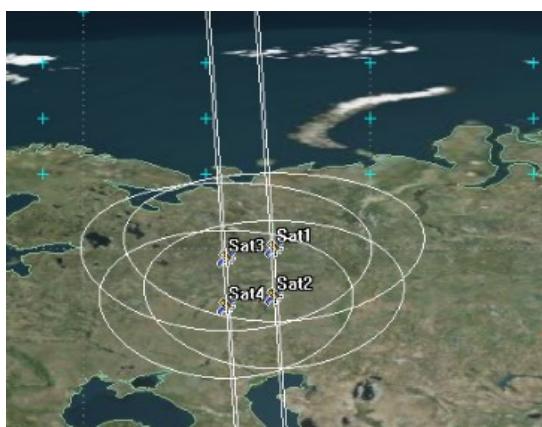
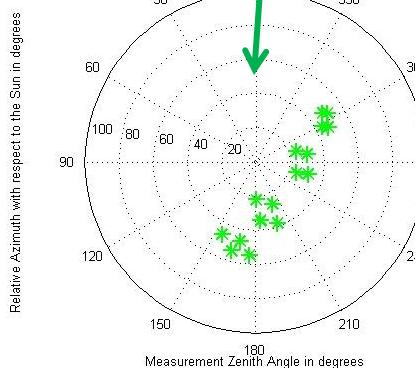
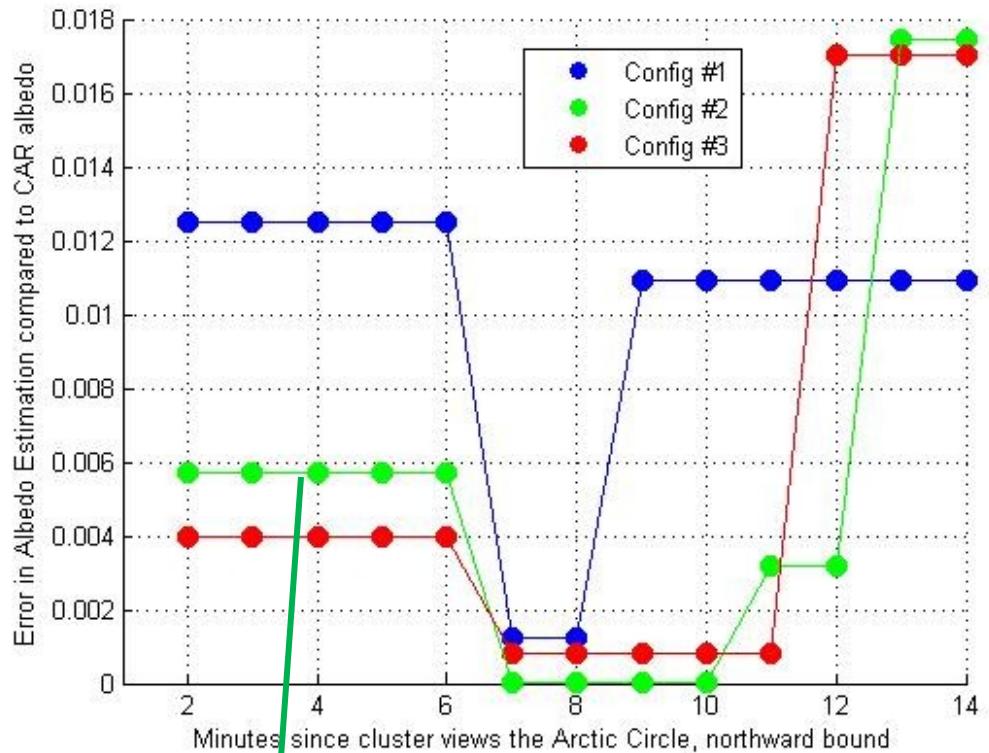
# Polar Albedo Estimation

*Compared 3 of the previous TA+RAAN orbits wrt CAR data (1031 nm) from Alaska assuming same biome over a 12 minute pass over the Arctic Circle.*



# Polar Albedo Estimation

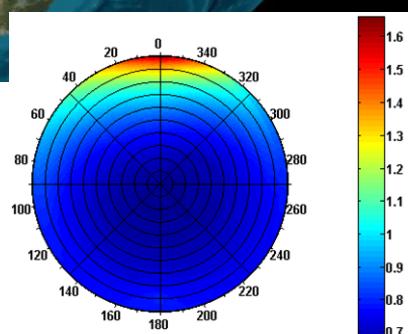
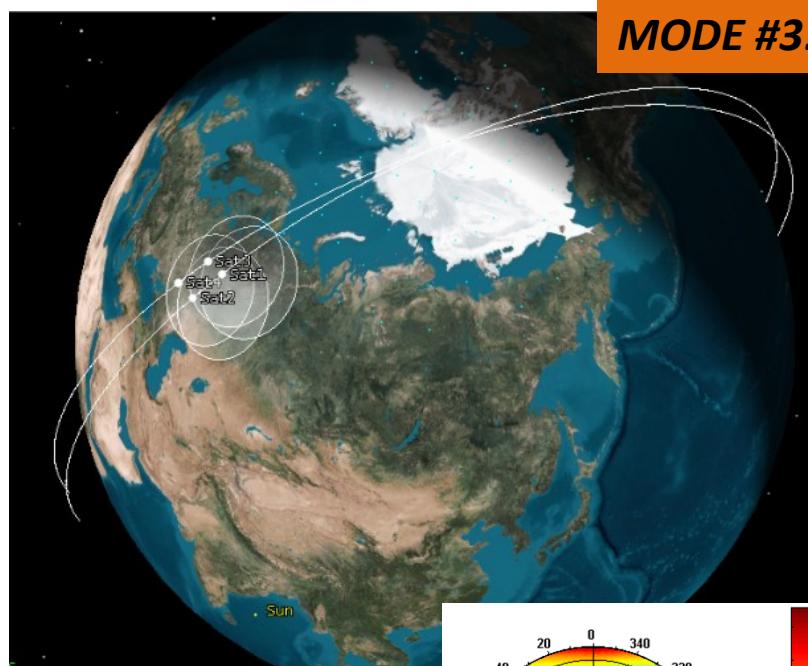
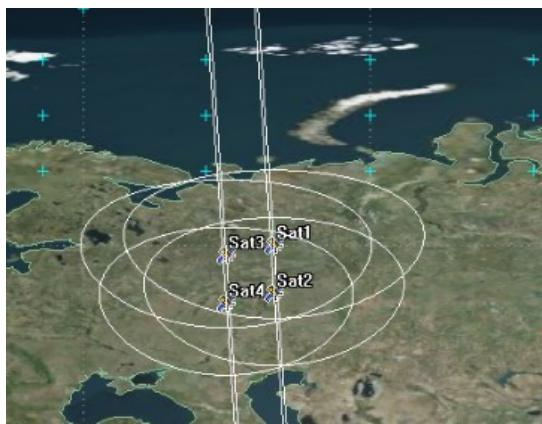
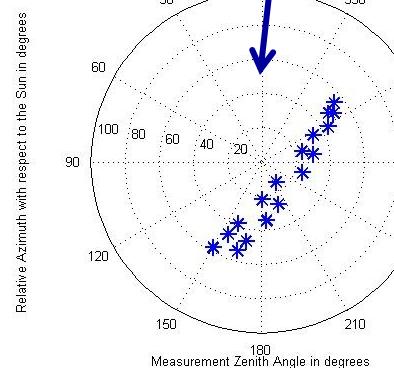
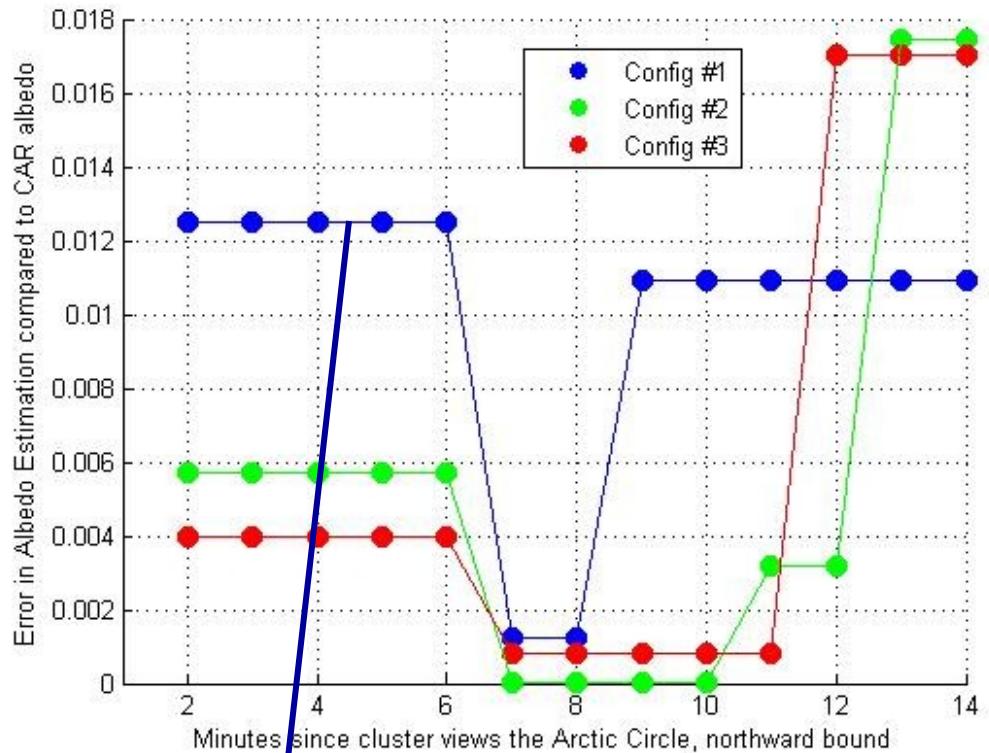
*Compared 3 of the previous TA+RAAN orbits wrt CAR data (1031 nm) from Alaska assuming same biome over a 12 minute pass over the Arctic Circle.*



**True BRDF  
from CAR**

# Polar Albedo Estimation

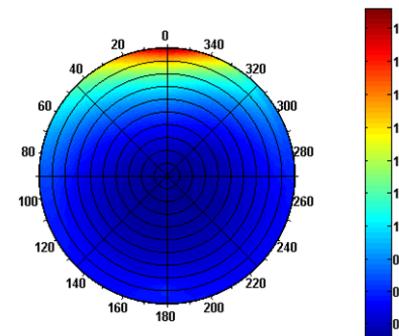
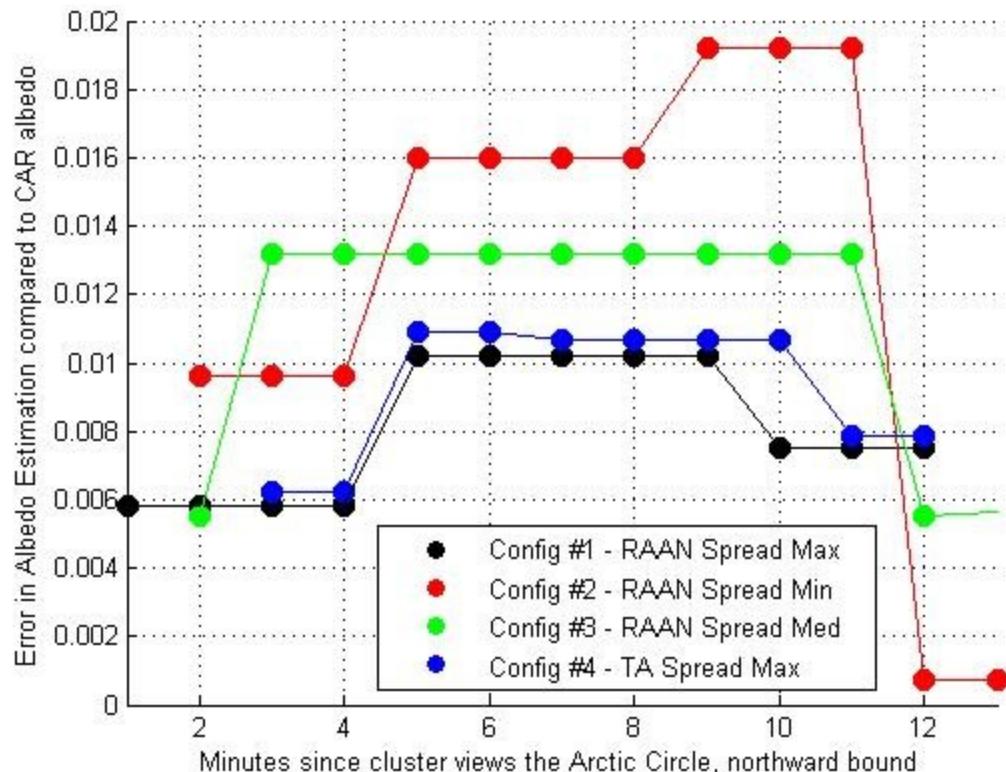
*Compared 3 of the previous TA+RAAN orbits wrt CAR data (1031 nm) from Alaska assuming same biome over a 12 minute pass over the Arctic Circle.*



**True BRDF  
from CAR**

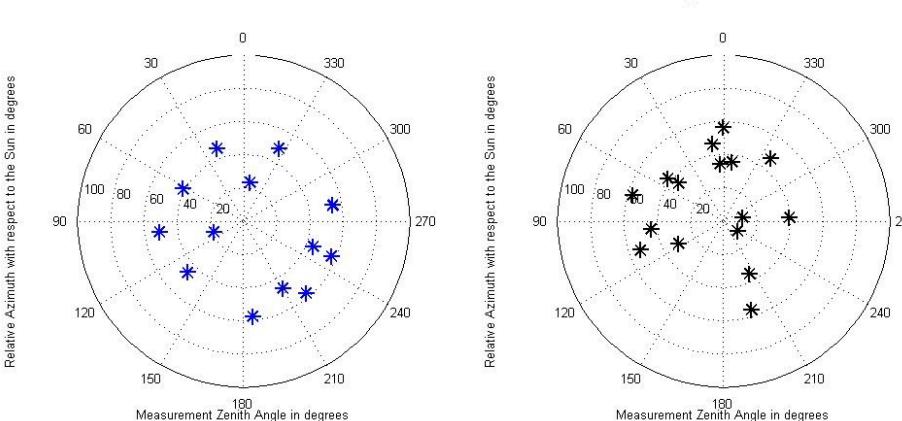
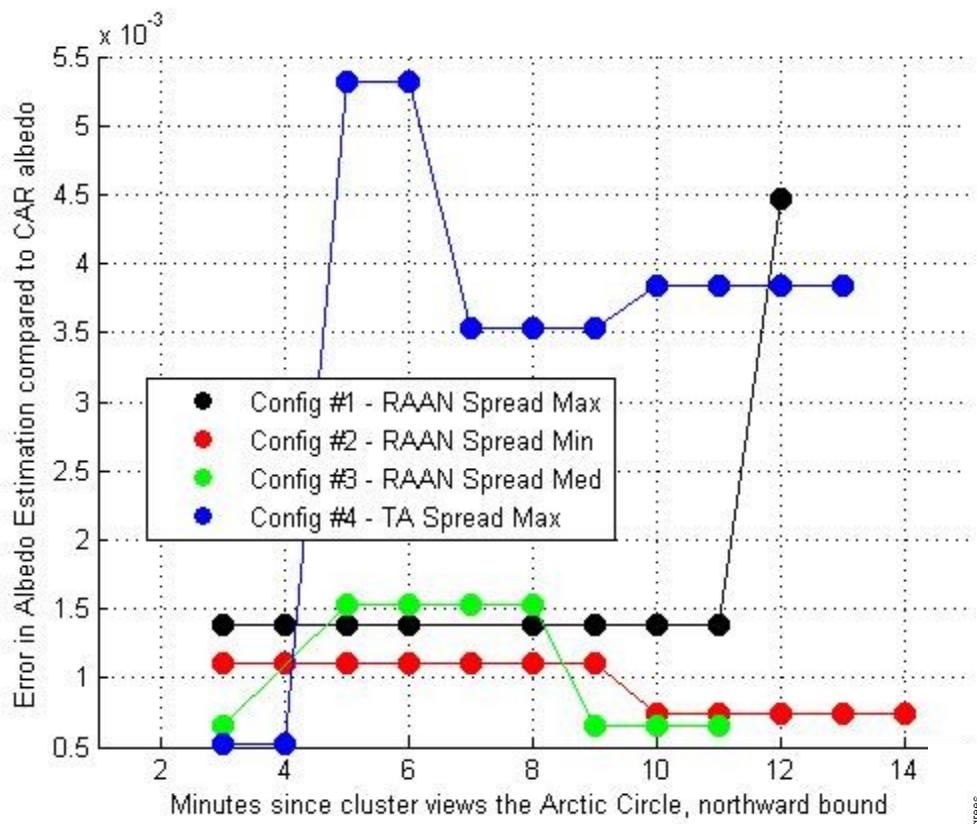
Instead, by spreading out the RAAN and TA, we may get lower errors. However, BRDF near the equator would need a clustellation (more spatio temporal coverage)

**MODE #3:**



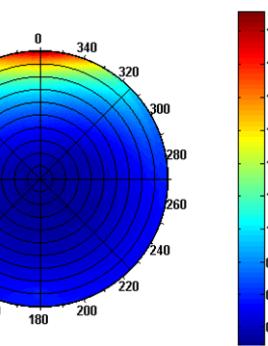
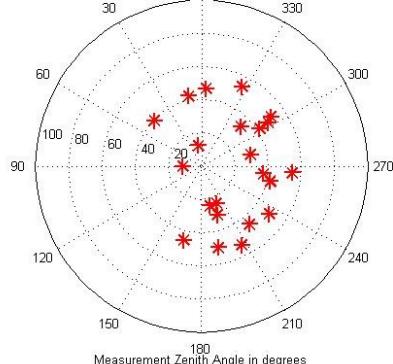
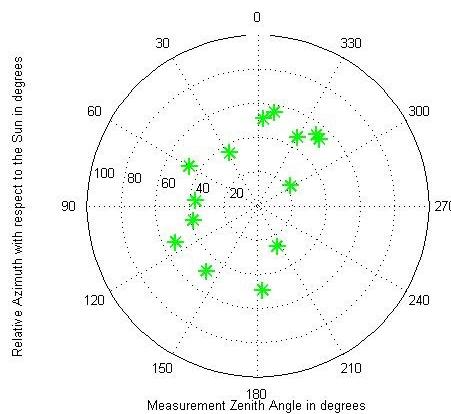
 **True BRDF  
from CAR**

# Polar Albedo Estimation



*Instead, by spreading out the RAAN and TA, we may get lower errors. However, BRDF near the equator would need a clustellation (more spatio temporal coverage)*

**MODE #3:**



**True BRDF  
from CAR**

- Distributed Space Missions for the Angular Acquisition problem
- Example Application dependent on Angular Sampling
- Proposed Solution and Design Methodology
- Baseline Case Study using a few Formation Configurations
- Value of Imaging Modes
- Summary and Future Work

- The angular acquisition problem for more accurate albedo estimation can be solved using small satellite formation flight
- Coupled science (BRDF estimation) and engineering (differential Keplerian) models proposed to validate the performance of a baseline formation design
- Simple formations with 4 satellites and no propulsion (only RAAN, TA variation) can achieve better performance than monoliths over few months, especially when different imaging modes are used
- Imaging modes are indispensable for albedo retrievals at the poles and for when the TA spread becomes too large because of unpredictable J2 effects
- Future work – Assess effect on major variables like chief orbit altitude/inclination+satellites and minor variables like their differential variation in RAAN, TA, eccentricity
- The same cluster designs are applicable for 3D mapping and biomass estimation from space

***Thank you!***

Questions?

For more info, please email:

[sreejanag@alum.mit.edu](mailto:sreejanag@alum.mit.edu)

or

[sreeja.nag@nasa.gov](mailto:sreeja.nag@nasa.gov)