

# Robust Federated Q-Learning with Almost No Communication

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## Abstract

This work studies *federated* reinforcement learning for discounted tabular Markov decision processes (MDPs) when a fraction of clients can be adversarial. There are  $M$  agents that each collect data from the same underlying MDP and communicate with a central server; however, an  $\varepsilon$ -fraction of agents may be Byzantine and can transmit arbitrary messages. The paper proposes an epoch-based federated  $Q$ -learning method, **Robust Fed-Q**, that (i) uses *variance-reduced* local Bellman backups computed from batched samples within each epoch, and (ii) aggregates client messages using a *robust* coordinate-wise median-of-means rule to tolerate Byzantine clients. The main results show that robust learning is possible with *almost no communication* (only one server round per epoch) while retaining a collaborative statistical gain: the clean part of the error scales as  $\tilde{\mathcal{O}}(1/\sqrt{MT})$ , and the unavoidable adversarial contribution scales as  $\tilde{\mathcal{O}}(\sqrt{\varepsilon}/\sqrt{T})$ . Experiments on a tabular gridworld validate that naive averaging can fail catastrophically under even mild Byzantine behavior, while **Robust Fed-Q** remains stable and improves with the number of honest agents.

## Theoretical Results

Using epoch-wise variance-reduced Bellman messages and coordinate-wise MoM aggregation, **Robust Fed-Q** learns  $Q^*$  reliably even when an  $\varepsilon$ -fraction of clients are adversarial.

- **Collaboration Gain + Diminishing Corruption Penalty.**

With high probability,

$$\|Q_K - Q^*\|_\infty \leq \tilde{\mathcal{O}}\left(\frac{1}{\sqrt{MT}}\right) + \tilde{\mathcal{O}}\left(\frac{\sqrt{\varepsilon}}{\sqrt{T}}\right),$$

so the clean term enjoys a  $1/\sqrt{M}$  federated speedup while the unavoidable corruptive term diminishes with  $T$ .

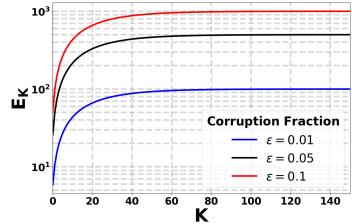
- **$\tilde{\mathcal{O}}(1)$  communication.** Each client uploads one message per epoch and the server broadcasts once per epoch, so the number of communication rounds is

$$K = \mathcal{O}(\log(MT)),$$

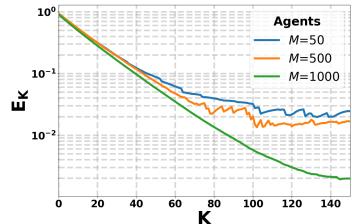
rather than  $\Theta(T)$ .

## Experiments

**Figure 1.**  $E_K = \|Q_K - Q^*\|_\infty$  for  $M = 1000$  and varying  $\varepsilon$  as a function of the number of epochs  $K$ , where the central server simply averages the agent updates.



**Figure 2.** Plots of  $E_K$  for Robust Fed-Q, with corruption fraction  $\varepsilon = 0.1$  and varying agent counts. Establishes **collaboration gain + robustness**.



## Overview

Federated reinforcement learning (FRL) aims to exploit many geographically distributed agents (devices, robots, simulators) that interact with *similar* environments, so that each agent can learn faster by sharing information rather than raw trajectories. In practice, large-scale federated deployments are vulnerable to unreliable participants: some clients may be faulty, noisy, or even malicious. This motivates a *Byzantine-robust* FRL formulation in which an adversary can corrupt an  $\varepsilon$ -fraction of clients and send arbitrary updates to the server.

The paper focuses on a tabular discounted MDP  $(\mathcal{S}, \mathcal{A}, \mathcal{P}, \mathcal{R}, \gamma)$  and asks:

- **Learnability under Byzantine clients:** Can one still obtain a vanishing  $\|Q - Q^*\|_\infty$  error as the number of samples grows?
- **Collaboration gain:** If learning is possible, can one achieve the same improvement as in clean federated learning, namely a  $1/\sqrt{M}$  reduction in statistical error due to  $M$  parallel data sources?
- **Communication efficiency:** Can this be done with *few* server rounds, instead of communicating after every environment step?

A key difficulty is that standard federated averaging is extremely fragile: a single adversarial client can inject large-magnitude messages that dominate the mean and derail learning. The central idea of this paper is to combine **epoching** (to form concentrated, low-variance client messages) with **robust aggregation** (to prevent Byzantine outliers from influencing the update).

## Main Results

■ **Setting.** There are  $M$  agents connected to a central server. Time is partitioned into  $K$  epochs of length  $H$ , so each agent collects  $T = KH$  samples. The goal is to return an estimate  $Q_K$  of the optimal action-value function  $Q^*$ , measured in  $\|\cdot\|_\infty$ :

$$e_K := \|Q_K - Q^*\|_\infty.$$

An  $\varepsilon$ -fraction of clients are Byzantine: they can observe the protocol and transmit arbitrary messages to the server in every epoch.

■ **Algorithm: Robust Fed-Q.** Each epoch consists of one *local computation + upload* step and one *server aggregation + broadcast* step.

(1) **Local variance-reduced Bellman message.** Within epoch  $k$ , each honest client  $i$  uses its  $H$  samples to form an empirical estimate of the Bellman backup at the current global iterate  $Q_k$ . Concretely, the client computes a message  $d_{i,k}$  intended to approximate  $(\mathcal{T}Q_k)(s, a)$  for every  $(s, a) \in \mathcal{S} \times \mathcal{A}$ , where

$$(\mathcal{T}Q)(s, a) = \mathcal{R}(s, a) + \gamma \mathbb{E}_{s' \sim \mathcal{P}(\cdot | s, a)} \left[ \max_{a'} Q(s', a') \right].$$

Using a batch of size  $H$  reduces the stochastic noise in  $d_{i,k}$  compared to a single-sample temporal-difference target.

**(2) Robust server aggregation across clients.** For each coordinate  $(s, a) \in \mathcal{S} \times \mathcal{A}$ , the server aggregates  $\{d_{i,k}(s, a)\}_{i=1}^M$  using a coordinate-wise median-of-means rule. MoM remains accurate even if an  $\varepsilon$ -fraction of inputs are arbitrarily corrupted, provided  $\varepsilon$  is below a constant and the honest inputs are sufficiently concentrated.

**(3) Global update and broadcast.** The server performs a convex combination update

$$Q_{k+1}(s, a) = (1 - \alpha) Q_k(s, a) + \alpha \tilde{d}_k(s, a),$$

where  $\tilde{d}_k$  is the robustly aggregated message, and broadcasts  $Q_{k+1}$  to all clients. Thus, the number of communication rounds is  $K$  (one per epoch), rather than  $T$  (one per interaction step).

■ **High-probability Error Bound.** With suitable choices of step size  $\alpha$  and epoch count  $K$  (typically logarithmic in  $T$  up to  $(1 - \gamma)$  factors), the paper proves that with high probability,

$$\|Q_K - Q^*\|_\infty \leq \underbrace{\tilde{\mathcal{O}}\left(\frac{1}{\sqrt{MT}}\right)}_{\text{Clean statistical term scaling with } M} + \underbrace{\tilde{\mathcal{O}}\left(\frac{\sqrt{\varepsilon}}{\sqrt{T}}\right)}_{\text{Byzantine penalty}}.$$

The two terms have complementary meanings:

- **Collaboration gain persists:** in the absence of Byzantine clients ( $\varepsilon = 0$ ), the error scales as  $\tilde{\mathcal{O}}(1/\sqrt{MT})$ , matching the intuition that  $M$  agents provide  $M$  times more data.
- **Robustness penalty is unavoidable:** when  $\varepsilon > 0$ , the additional  $\tilde{\mathcal{O}}(\sqrt{\varepsilon}/\sqrt{T})$  term captures the irreducible effect of adversarial participation. Importantly, this term does not vanish with  $M$  at the same rate as the clean term, reflecting that more agents also create more potential adversarial channels.
- **Communication is epoch-level:** the protocol needs only  $K$  server rounds, which can be far smaller than  $T$  in long-horizon learning.