METHODS GALORE

- TOPUP is widely used
- Physics based, no real error except a few simplifications





TOPUP, A GLICK AND A YUP

$$S(t) \propto \int_{x}^{\infty} \int_{y}^{\infty} \rho(x, y) e^{iy[\Delta B(x,y) + G_{f}(x,y,t) + G_{p}(x,y,t)]} dxdy$$

$$\underbrace{\mathbf{s}}_{m \times 1} = \underbrace{\mathbf{A}}_{m \times n_{x}n_{y}} \underbrace{\boldsymbol{\rho}}_{n_{x}n_{y} \times 1}$$

$$\mathbf{A} = \begin{bmatrix} e^{iy[\Delta B_0(x_1,y_1)t_1 + G_f(x_1,y_1,t_1) + G_p(x_1,y_1,t_1)]} & e^{iy[\Delta B_0(x_2,y_1)t_1 + G_f(x_2,y_1,t_1) + G_p(x_2,y_1,t_1)]} & \cdots & e^{iy[\Delta B_0(x_n,y_n,t_1) + G_f(x_n,y_n,t_1) + G_p(x_n,y_n,t_1)]} \\ e^{iy[\Delta B_0(x_1,y_1)t_2 + G_f(x_1,y_1,t_2) + G_p(x_1,y_1,t_2)]} & e^{iy[\Delta B_0(x_2,y_1)t_2 + G_f(x_2,y_1,t_2) + G_p(x_2,y_1,t_2)]} & \cdots & e^{iy[\Delta B_0(x_n,y_n,t_2) + G_f(x_n,y_n,t_2) + G_p(x_n,y_n,t_2)]} \\ \vdots & \vdots & \ddots & \vdots \\ e^{iy[\Delta B_0(x_1,y_1)t_m + G_f(x_1,y_1,t_m) + G_p(x_1,y_1,t_m)]} & e^{iy[\Delta B_0(x_2,y_1)t_m + G_f(x_2,y_1,t_m) + G_p(x_2,y_1,t_m)]} & \cdots & e^{iy[\Delta B_0(x_n,y_n,t_1) + G_f(x_n,y_n,t_1) + G_p(x_n,y_n,t_1) + G_p(x_n,y_n,t_1)]} \end{bmatrix}$$

$$\underbrace{\mathbf{f}}_{n^2 \times 1} = \underbrace{\mathbf{F}}^H \quad \underline{\mathbf{A}} \quad \underline{\boldsymbol{\rho}}_{} = \underbrace{\mathbf{K}}_{n^2 \times n^2} \quad \underline{\boldsymbol{\rho}}_{}^2 .$$

