EMG:

Shoulder Extension

Shoulder Flexion—

Rapid modification of an ongoing reach using touch

Sasha Reschechtko^{1,2}, J. Andrew Pruszynski^{1,3}

1. Western University, London ON N6A 3K7 Canada

2. sreschec@uwo.ca 🤟 @res_chetko

3. andrew.pruszynski@uwo.ca 🔰 @andpru



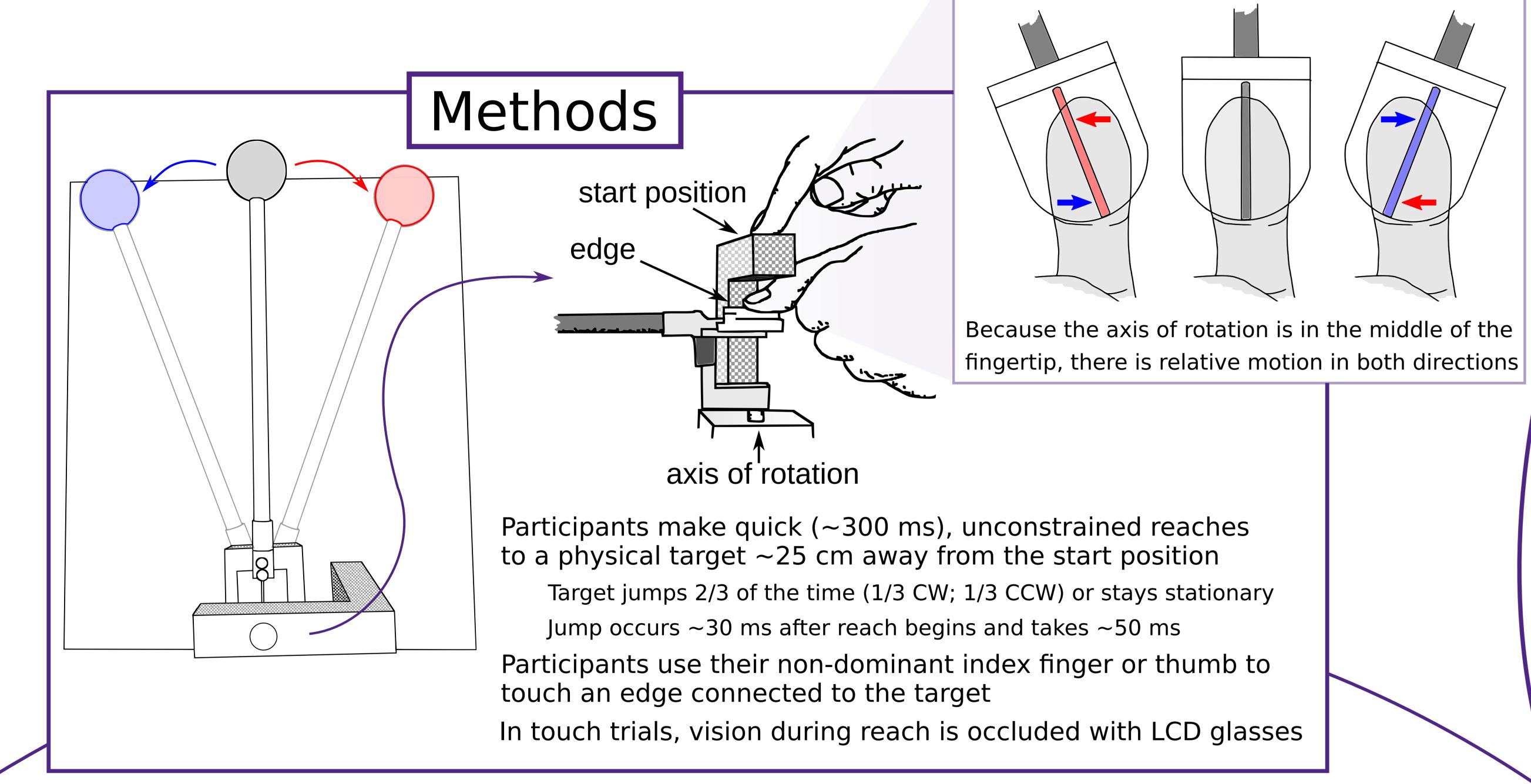
A hallmark of visually-guided reaching is the rapid correction of reach trajectory toward the target when it moves (Day & Lyon 2000) This early "pro-" response appears even when instructed to move in the opposite direction of target movement ("anti-reach")

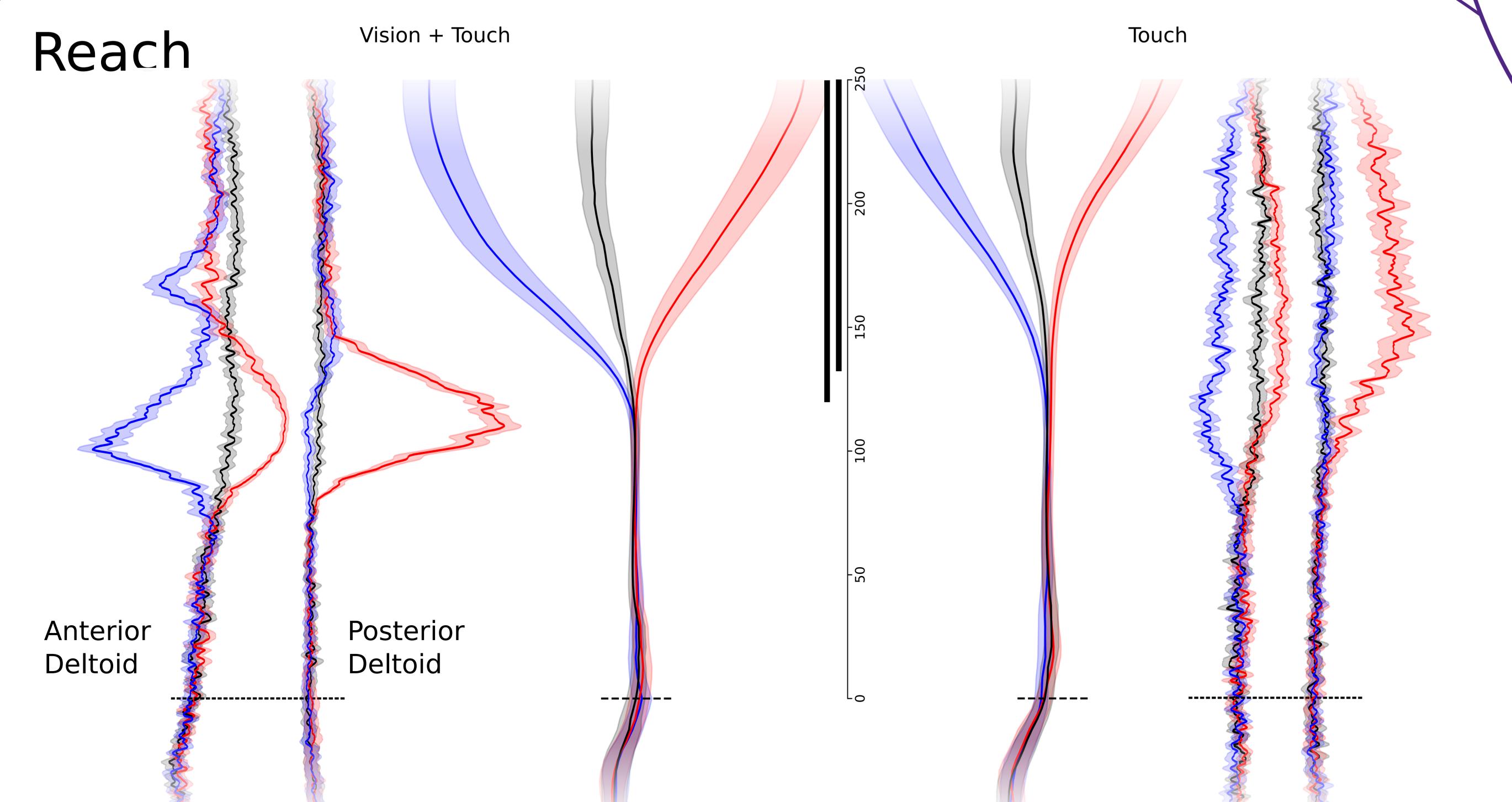
Here we investigate whether this pro- response occurs during an anti-reach paradigm under tactile guidance

This tight spatial stimulus-locking might not occur under tactile guidance because:

-We can manipulate non-rigid objects, for which the association between relative motion on the skin and object orientation varies

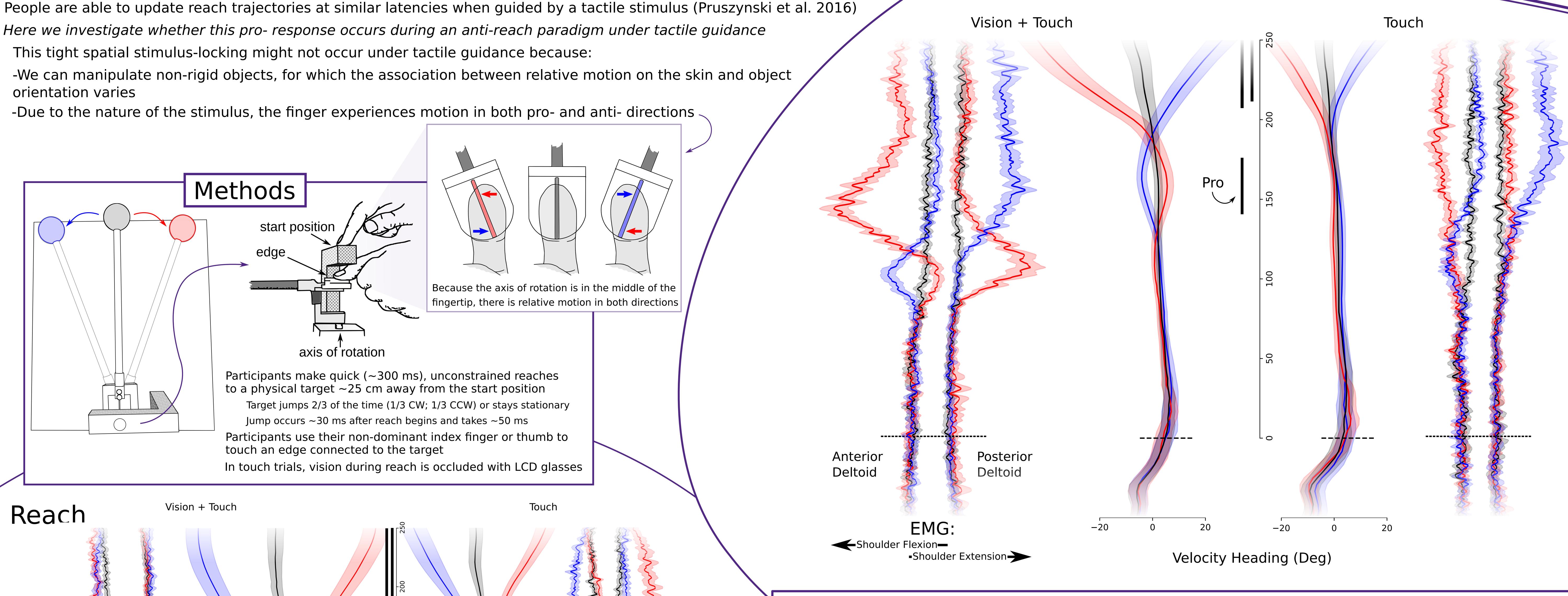
-Due to the nature of the stimulus, the finger experiences motion in both pro- and anti- directions <

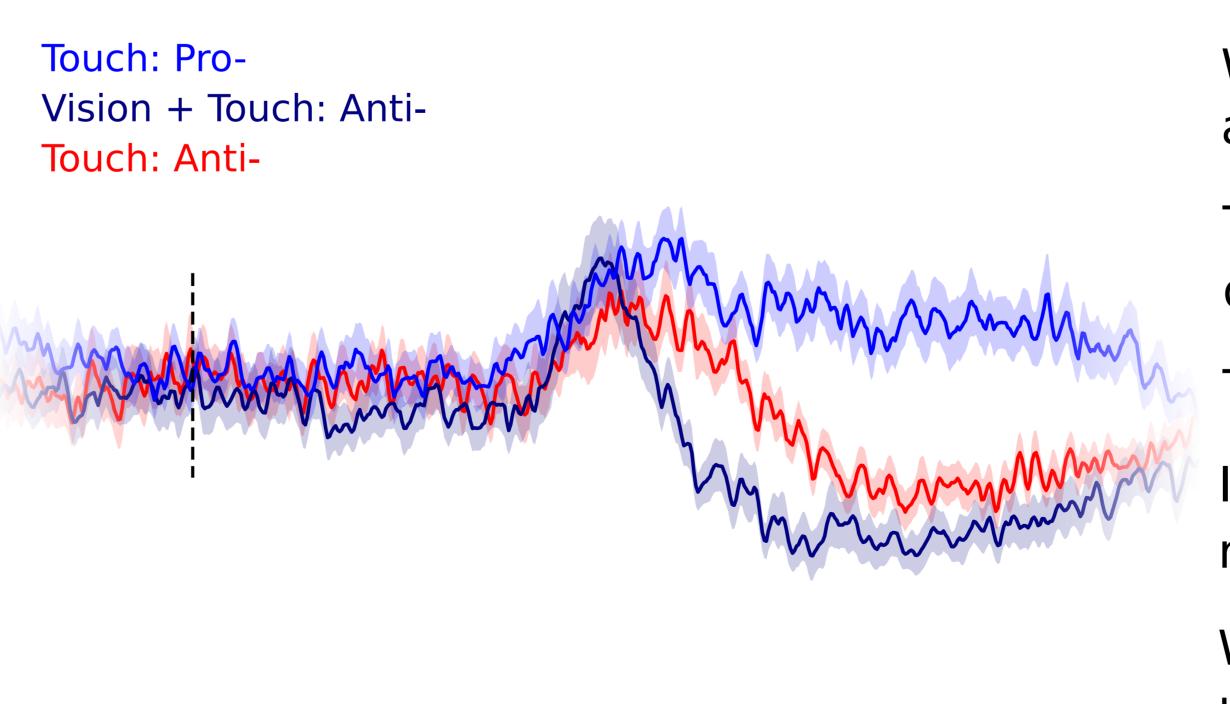




Velocity Heading (Deg)

Anti-Reach





While there is no kinematic pro- component, non-direction-specific EMG activity is evident in Touch at similar latency to the pro-component in vision

This occurs despite participants' ability to react at similar latency in a direction-specific way

The non-direction specific response does not appear to be large co-contraction

Is tactile guidance more amenable to arbitrary remapping, or do these responses result from mixed relative motion on the fingertip?

We will use a partial edge (stimulus moves in only one direction) to try to tease apart this question





