

# Comparison of Triangular, Cell-Centered Strand, and Node-Centered Strand Grid methods

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## I. Introduction

Three separate algorithms for computing a flat plate and a bump case are shown and compared. A triangular grid case with flux correction is explained and a flat plate case and bump case are analyzed. A cell-centered strand grid and a node-centered strand grid are also explained, and similar cases are run and analyzed. The node-centered strand grid was also run at transonic speeds with a limiter inclusion on a bump case. The resulting shock is shown and analyzed.

## II. Numerical Methods

### A. Triangular Grid

Shauns stuff that talks about Figure 1

### B. Cell-Centered Grid

Shauns stuff [3]

869	901	933
868	900	932
867	899	931
866	898	930
865	897	929
864	896	928

Figure 1. Cell-Centered Grid configuration displaying identification numbers for the cells.

### C. Node-Centered Grid

stuff and talk about Figure 2

#### 1. Limiter Inclusion

Stuff again, discuss equations related to the limiter. Reference the appendix V

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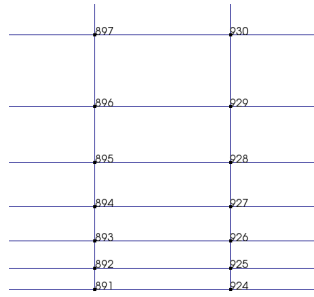


Figure 2. Node-Centered Grid configuration displaying identification numbers for the nodes.

### III. Results

We will compare the results from the plate and bump cases from each of the grid codes.

#### A. Flat Plate

comparison of the flat plate stuff against blasius solutions

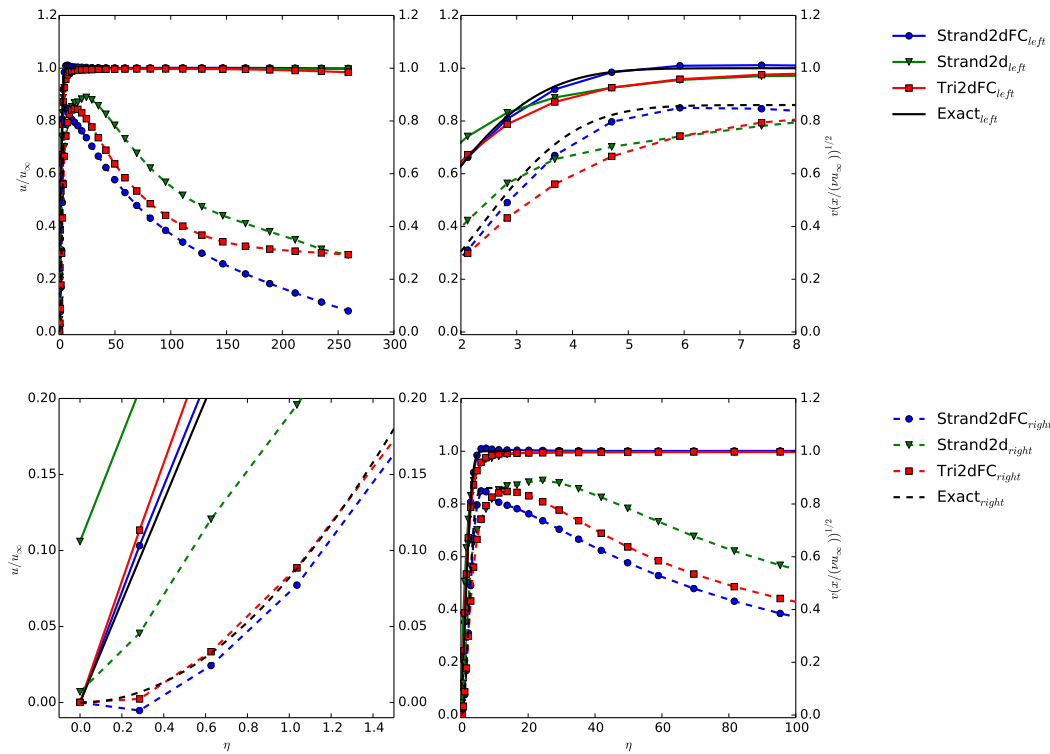


Figure 3. Blasius Solution comparison of all three grids

#### B. Bump

The general bump is outlined by NASA stuff

### 1. *Subsonic*

This is what it looks like

### 2. *Transonic Inviscid with Limiter Inclusion*

and what it looks like when you run it a bit faster inviscid

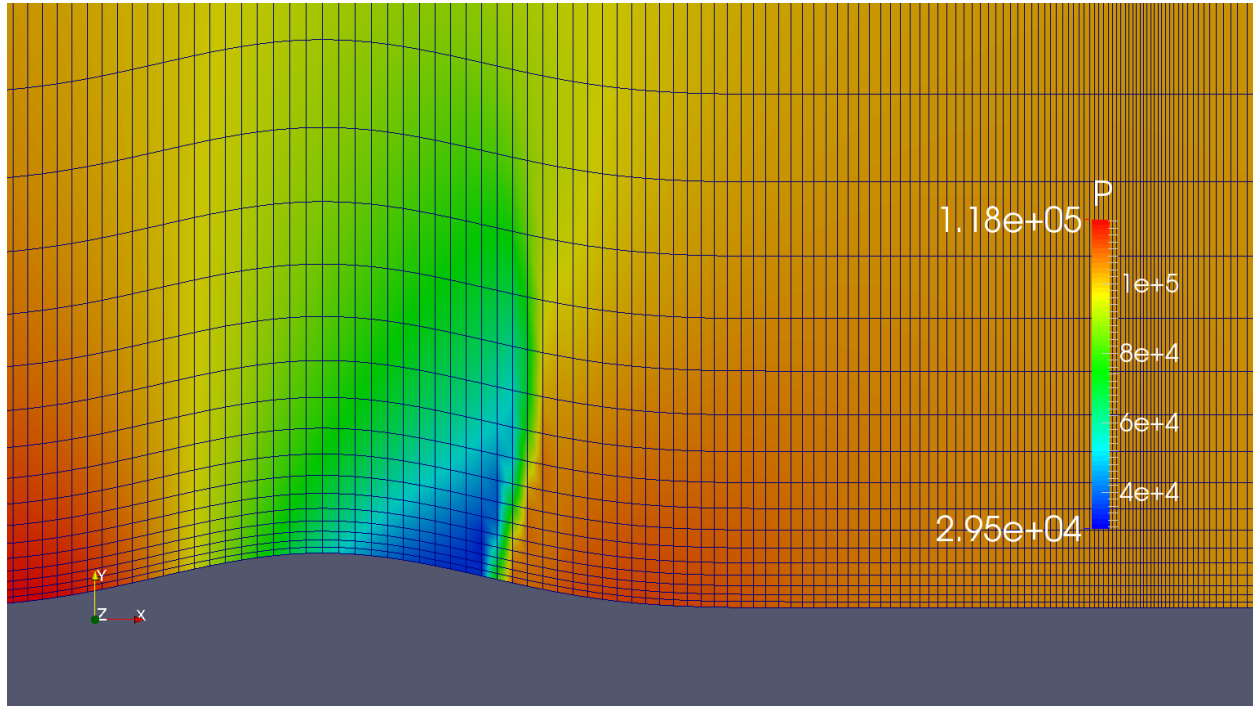


Figure 4. Inviscid transonic bump case at Mach 0.8

## IV. Conclusions

Strand2dFC is awesome... not only can it do 2,2 scheme, but it can also do 3,4 scheme! Cool!

## References

- [1] Barth, T. J., “Numerical Aspects of Computing Viscous High Reynolds Number Flows on Unstructured Meshes,” *American Institute of Aeronautics and Astronautics*, 1991.
- [2] Diskin, B. and Thomas, J., “Accuracy of Gradient Reconstruction on Grids with High Aspect Ratio,” Tech. rep., National Institute of Aerospace, December 2008.
- [3] Barth, T. J., Barth, T. J., and Linton, S. W., “An Unstructured Mesh Newton Solver for Compressible Fluid Flow and Its Parallel Implementation,” *American Institute of Aeronautics and Astronautics*, 1995.

## V. Appendix

Limit.C file is displayed below.

```
#include "Strand2dFCBlockSolver.h"
```

```
void Strand2dFCBlockSolver::limit(const int& j)
{
    /* this calculates the limiter value for Strand2dFC
     * written by Shaun Harris at Utah State University
     * email: shaun.r.harris@gmail.com
     * Sept. 16, 2014
     *
     *
     */

    // standard limiter=0 from input.namelist
    if (limiter == 0) {
        for(int n=0; n<nSurfNode; n++){
            for (int k=0; k<nq; k++) {
                lim(n,j,k) = 1.;
            }
        }
    }

    // limiter to be used limiter=1 from input.namelist
    else if (limiter == 1){ //calculate using gradient
        double a;
        double b;
        int n0;
        int n1;
        double limE;
        //initially set all lim values of j to 1
        for(int n=0; n<nSurfNode; n++){
            for (int k=0; k<nq; k++) {
                lim(n,j,k) = 1.;
            }
        }
        //find limiter value at each surfEdge
        for(int n=0; n<nSurfEdge; n++){
            for (int k=0; k<nq; k++) {
                n0=surfEdge(n,0);
                n1=surfEdge(n,1);
                a=deltaS*qx(n1,j,k,0);
                b=deltaS*qx(n0,j,k,0);
                //~ a = q(surfEdge(n,3),j,k)-q(n1,j,k); // original a
                //and b, can use this instead of a and b above
                //~ b = q(n0,j,k)-q(surfEdge(n,2),j,k);
                limE = 1. - ((fabs((a-b)/max((fabs(a)+fabs(b)),dlim(k))))
                    ) *
                    (fabs((a-b)/max((fabs(a)+fabs(b)),dlim(k)))) *
                    (fabs((a-b)/max((fabs(a)+fabs(b)),dlim(k)))));
                //output warning and exit if bad limiter
                if (limE>1 | limE<0){
                    cout<<"WARNING: _Bad_Limiter_value"<<endl;
                    cout<<"limE ("<<n<<","<<j<<","<<k<<") _=_ "<<limE<<" _
                        "<<"limiter _"<<limiter<<endl;
                    exit(0);
                }
            }
        }
        //convert limiter value from Edge to Node using the
        //minimum of 2 neighboring edges of each node
        lim(n0,j,k)=min(lim(n0,j,k),limE);
    }
}
```

```

lim(n1,j,k)=min(lim(n1,j,k),limE);
// ~ cout<<"lim("<<n0<<","<<j<<","<<k<<")= "<<lim(n0,j,
    k)<<endl;
// ~ cout<<"lim("<<n1<<","<<j<<","<<k<<")= "<<lim(n1,j,
    k)<<endl<<endl;
    }
}
}
else {
    cout << "WARNING: \input \value \for \limiter \is \incorrect \format \Limiter
        \="<<limiter<<endl;
    exit(0);
}
}

```