

UNIT-III

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Electrostatic Fields

- Electrostatics is a branch of science that deals with the static (or at rest) electric charges.
- It is a branch that studies the time invariant electric fields in a space (or) vacuum produced by various types of static charge distributions i.e line/surface/volume configurations.

Coulomb's Law:

It deals with the force that one point charge exerts on another point charge. The polarity of charges may be positive (or) negative.

Statement:- It states that the force (F) between the

2 point charges Q_1 and Q_2 ,

(i) lies along the line joining the charges

(ii) directly proportional to product of the charges

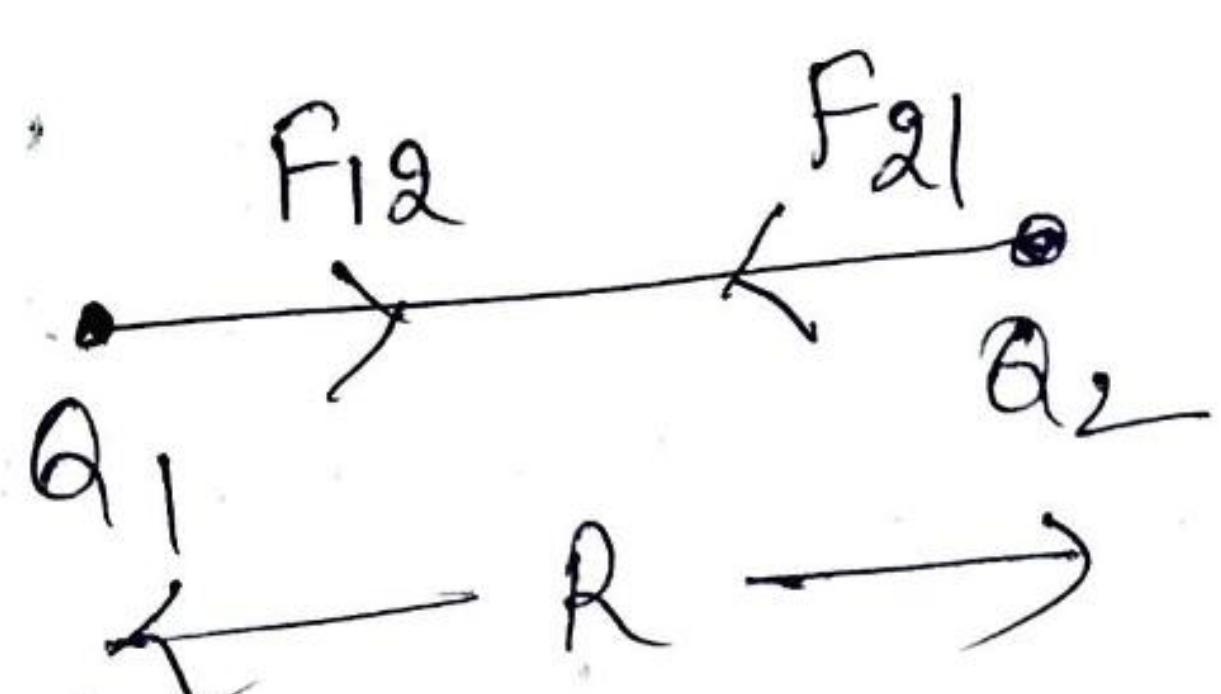
(iii) Inversely proportional to square of the distance

(R) between them.

$$\text{Mathematically, } F = \frac{k Q_1 Q_2}{R^2}$$

where $k = \frac{1}{4\pi\epsilon}$ - proportionality constant

where $\epsilon = \epsilon_0 \epsilon_r$; ϵ_0 - permittivity in free space
 ϵ_r - permittivity in any medium.



$$\therefore F = \frac{1}{4\pi\epsilon_0} \frac{Q_1 Q_2}{R^2}$$

Newton (since $\epsilon_0 = 1$
for freespace
(or) vacuum)

Note:-

$\epsilon_0 = 8.854 \times 10^{-12} \text{ F/m} = \frac{1}{36\pi} \times 10^{-9} \text{ F/m}$

$k = \frac{1}{4\pi\epsilon_0} = 9 \times 10^9 \text{ m/F}$

$1 \text{ C.} = 6 \times 10^{18} \text{ e}^-$

$1 \text{ e}^- = 1.602 \times 10^{-19} \text{ C}$

$\left. \begin{array}{l} \text{Typical} \\ \text{values for} \\ \text{problems.} \end{array} \right\}$

Force in vector form:-

→ If 2 point charges Q_1 and Q_2 are located at points having position vectors \vec{r}_1 and \vec{r}_2 from origin as shown below:

The position vectors are given as:

$$\vec{r}_1 = x_1 \hat{a}_x + y_1 \hat{a}_y + z_1 \hat{a}_z$$

$$\vec{r}_2 = x_2 \hat{a}_x + y_2 \hat{a}_y + z_2 \hat{a}_z$$

∴ Radial distance $\vec{R}_{12} = (\vec{r}_2 - \vec{r}_1)$

$$= (x_2 - x_1) \hat{a}_x + (y_2 - y_1) \hat{a}_y + (z_2 - z_1) \hat{a}_z$$

Also, $F_{12} = -F_{21}$

→ The force F_{12} on Q_2 due to Q_1 is:

$$F_{12} = + \frac{Q_1 Q_2}{4\pi\epsilon_0 |R_{12}|^2} \hat{a}_{R_{12}}$$

where, $\vec{R}_{12} = \vec{r}_2 - \vec{r}_1$ and unit vector $\hat{a}_{R_{12}} = \frac{\vec{R}_{12}}{|R_{12}|}$

$$\therefore F_{12} = \pm \frac{Q_1 Q_2}{4\pi\epsilon_0 |R_{12}|^2} \cdot \frac{\vec{R}_{12}}{|R_{12}|}$$

$$= \pm \frac{Q_1 Q_2 (r_2 - r_1)}{4\pi\epsilon_0 |R_{12}|^3} = \pm \frac{Q_1 Q_2 (r_2 - r_1)}{4\pi\epsilon_0 |r_2 - r_1|^3}$$

Newton

Note:- unit vector always indicates the direction of forces.

- if Force \rightarrow positive value \rightarrow Force of repulsion
- if Force \rightarrow negative value \rightarrow force of attraction.

Force for N-charges:-

\rightarrow If there are more than 2 points, we use principle of superposition (since force is linear quantity)

to determine force on a particular charge.

Note:- coulomb's law is linear, obeys superposition theorem

\rightarrow Let Q_1, Q_2, \dots, Q_N be n-charges located at points

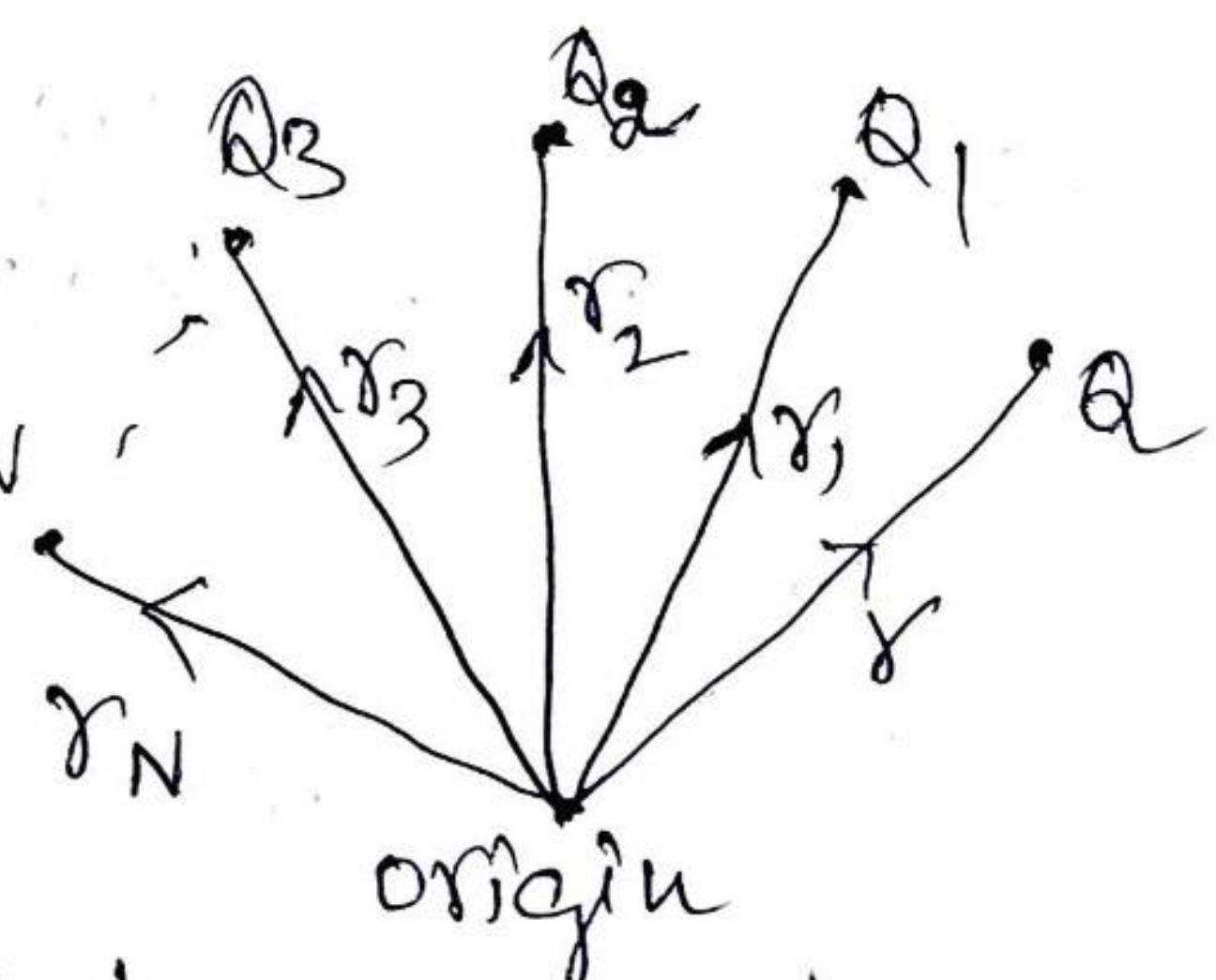
with position vectors r_1, r_2, \dots, r_N as shown in fig.

. Then the resultant force is

$$F_T = F_1 + F_2 + F_3 + \dots + F_N$$

$$\therefore F = \frac{Q}{4\pi\epsilon_0 m=1} \sum_{m=1}^N \frac{Q_m (r - r_m)}{|r - r_m|^3}$$

Newton

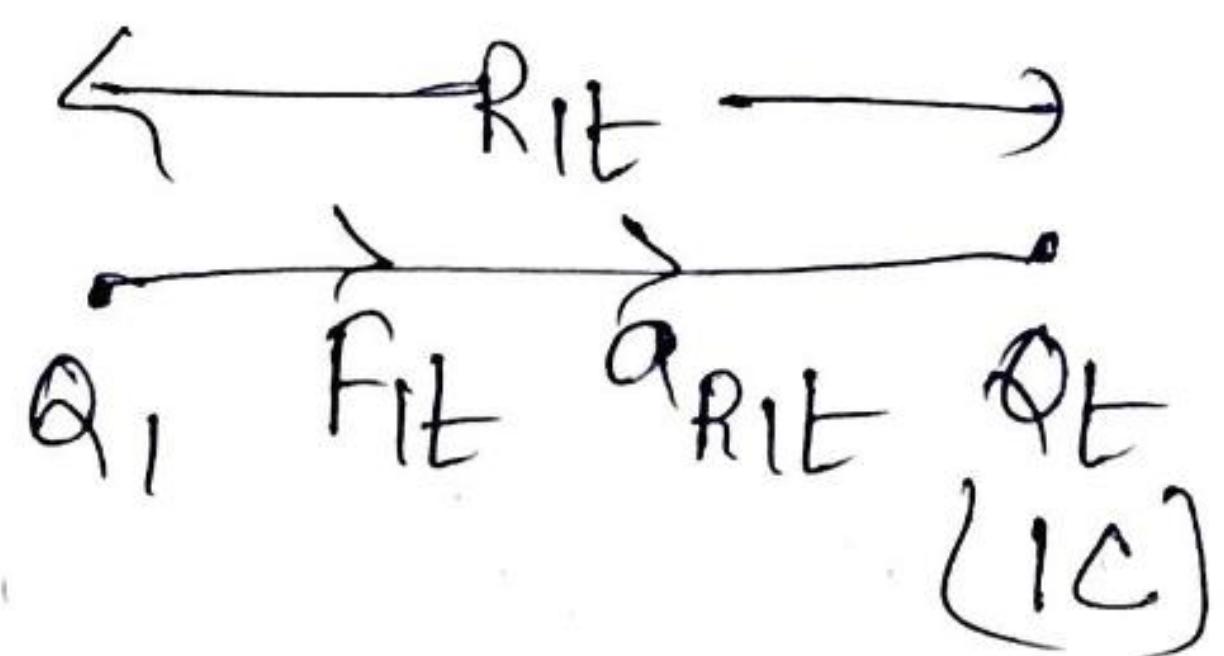


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Electric Field Intensity (\vec{E}):

→ The electrostatic force acting on a unit charge placed at that point.

$$F_{IT} = \frac{1}{4\pi\epsilon_0} \frac{Q_1 Q_T}{|R_{IT}|^2} a_{R_{IT}}$$



$$\Rightarrow \frac{F_{IT}}{Q_T} = \frac{1}{4\pi\epsilon_0} \frac{Q_1}{|R_{IT}|^2} a_{R_{IT}}$$

$$\Rightarrow \boxed{\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{Q}{|r|^2} a_r} \text{ V/m} \quad \text{for point charge}$$

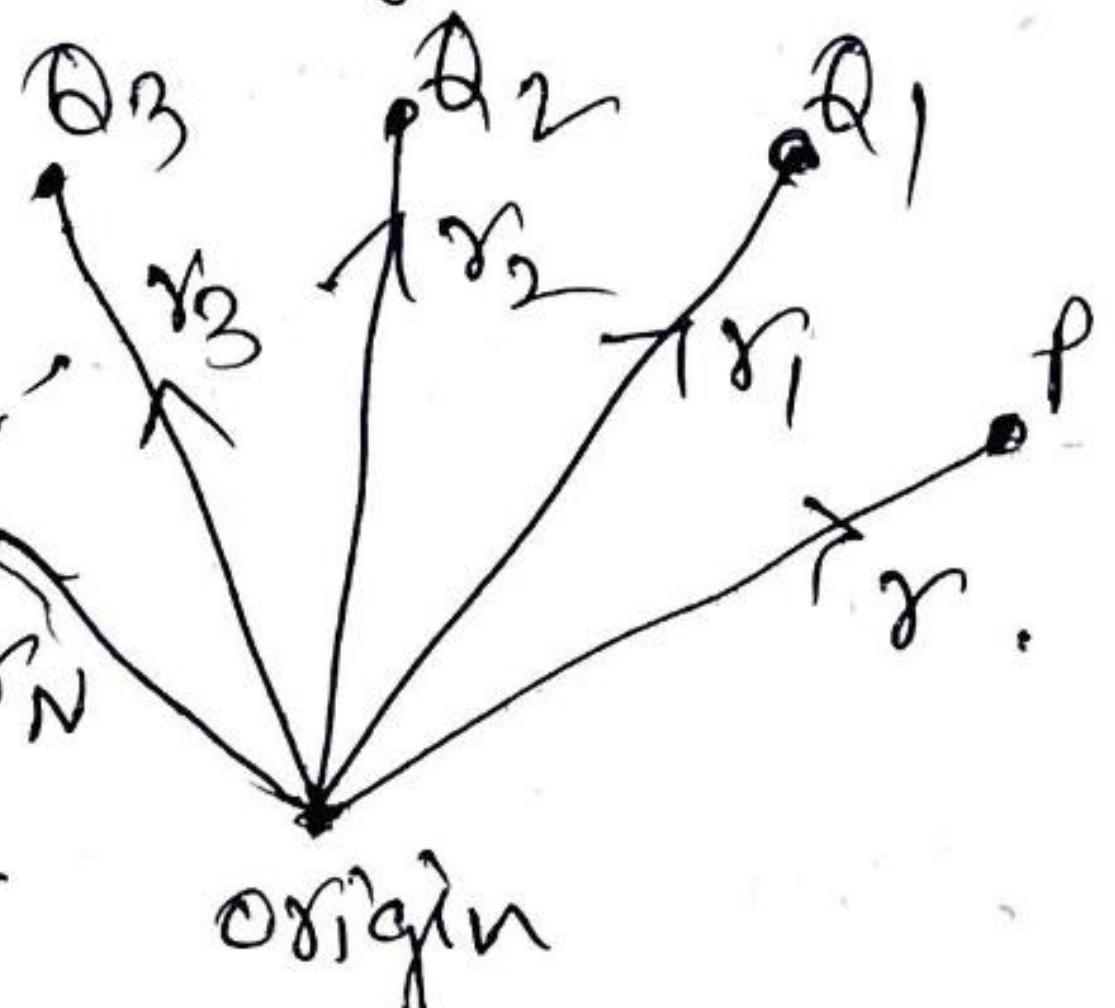
where $\vec{E} = \frac{F_{IT}}{Q_T} = \frac{F}{Q} \text{ N/C}$. (standard definition)

\vec{E} for N -charges:-

→ Electric field intensity (\vec{E}) is linear, obeys the law of superposition.

$$\therefore \vec{E}_T = \vec{E}_1 + \vec{E}_2 + \vec{E}_3 + \dots + \vec{E}_N$$

$$\vec{E}_T = \frac{Q_1}{4\pi\epsilon_0 |r-r_1|^2} \frac{a_1 + Q_2}{4\pi\epsilon_0 |r-r_2|^2} \frac{a_2 + \dots + Q_N}{4\pi\epsilon_0 |r-r_N|^2} a_N$$



$$\therefore \boxed{\vec{E} = \frac{1}{4\pi\epsilon_0} \sum_{m=1}^N \frac{Q_m}{|r-r_m|^2} a_m} \text{ V/m}$$

z.

Electric Field Intensity due to Infinite Line charge: (3)

- Consider, a line charge (sequence of point charges) as a placed on \vec{z} -axis, having charge density ρ_h (C/m).
 • Also, consider a small differential length dl carrying a charge dq along \vec{z} -axis, hence $dl = dz'$

$$(i) \therefore dq = \rho_h \cdot dz'$$

(ii) Let P - observation point

& R - distance b/w source & point P .

$$\therefore R = r - r'$$

$$\bar{R} = \rho_{ap} - z' \hat{z}$$

$$|\bar{R}| = \sqrt{\rho^2 + z'^2}$$

$$\text{direction } \bar{a}_{\bar{R}} = \frac{\bar{R}}{|\bar{R}|} = \frac{\rho_{ap} - z' \hat{z}}{\sqrt{\rho^2 + z'^2}} \quad \text{--- (1)}$$

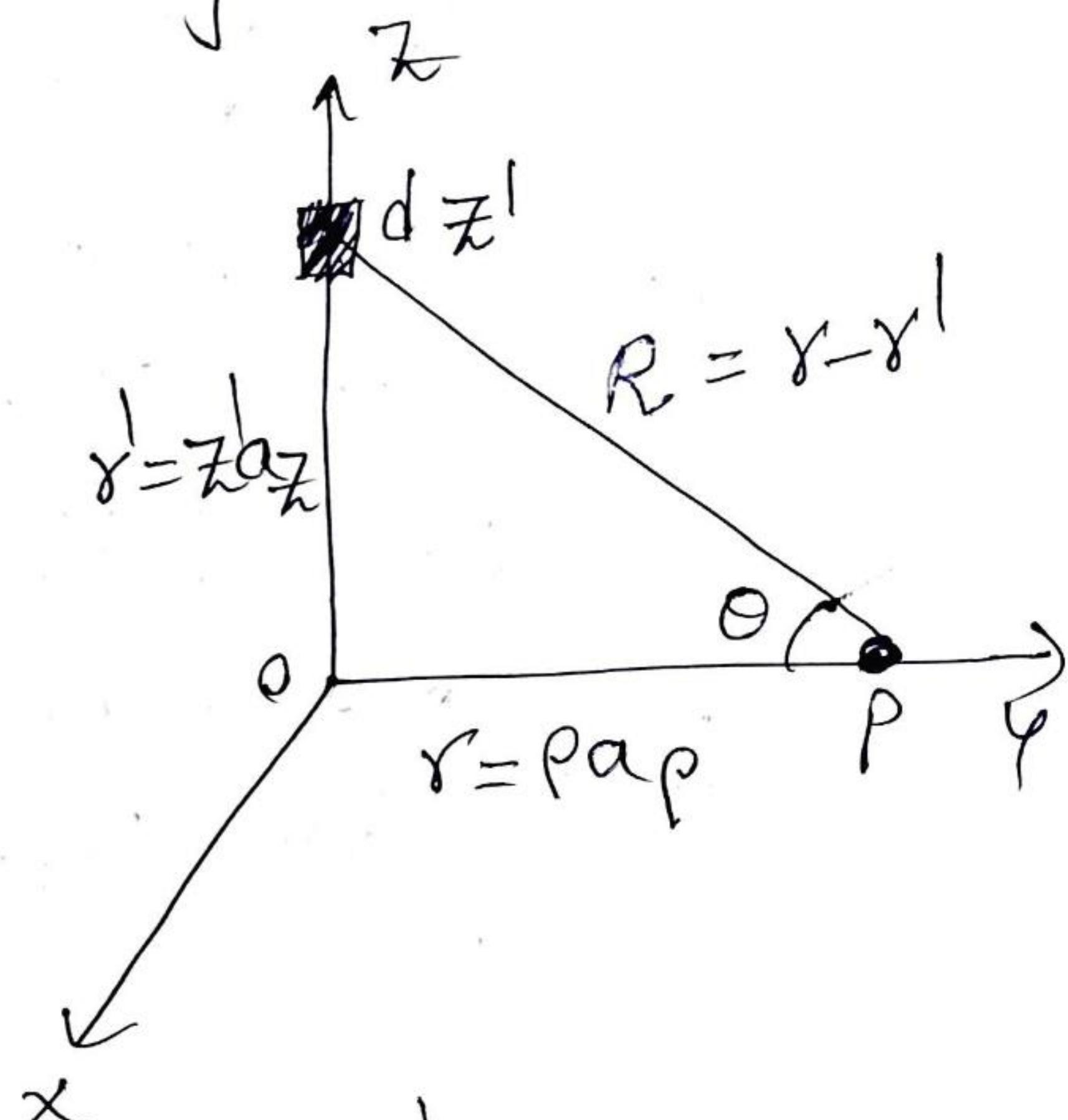
- For every charge on +ve \vec{z} -axis, there is equal charge present on -ve \vec{z} -axis.

$\therefore \bar{E}$ cancel each other in \vec{z} -direction.

$$\therefore E_z = 0 \Rightarrow \text{no } \vec{z}\text{-component of } \bar{E}$$

Eq (1) becomes,

$$\therefore \bar{a}_{\bar{R}} = \frac{\rho_{ap}}{\sqrt{\rho^2 + z'^2}} \quad (\text{since } a_z = 0)$$



→ We know that: $\vec{E} = \frac{Q}{4\pi\epsilon_0 R^2} \hat{a}_R$ (for point charge)

$$dE = \frac{dq}{4\pi\epsilon_0 |R|^2} \hat{a}_R \\ = \frac{\rho_h \cdot dz'}{4\pi\epsilon_0 \sqrt{\rho^2 + z'^2}} \cdot \left(\frac{\rho a_p}{\sqrt{\rho^2 + z'^2}} \right).$$

$$dE = \frac{\rho_h \cdot dz' \rho a_p}{4\pi\epsilon_0 (\rho^2 + z'^2)^{3/2}}$$

Integrating on both sides

$$\int_{-\infty}^{\infty} dE = \int_{-\infty}^{\infty} \frac{\rho_h \cdot \rho a_p}{4\pi\epsilon_0 (\rho^2 + z'^2)^{3/2}} dz'$$

$$\Rightarrow \bar{E} = -\frac{\rho_h}{4\pi\epsilon_0} \int_{-\infty}^{\infty} \frac{\rho a_p}{(\rho^2 + z'^2)^{3/2}} dz'$$

$$\text{Let } z' = \rho \tan\theta \Rightarrow dz' = \rho \sec^2 \theta d\theta$$

$$-\infty = \rho \tan\theta \Rightarrow \theta = -\frac{\pi}{2} \quad \} \text{ limits.}$$

$$+\infty = \rho \tan\theta \Rightarrow \theta = \frac{\pi}{2}$$

$$\therefore \bar{E} = -\frac{\rho_h}{4\pi\epsilon_0} \int_{-\pi/2}^{\pi/2} \frac{\rho a_p}{(\rho^2 + \rho^2 \tan^2 \theta)^{3/2}} \rho \sec^2 \theta d\theta$$

$$= -\frac{\rho_h}{4\pi\epsilon_0} \int_{-\pi/2}^{\pi/2} \frac{\rho^2 \sec^2 \theta d\theta}{\rho^3 \sec^3 \theta} a_p$$

$$\begin{cases} \text{since } \frac{\rho^2}{\rho^3} = \frac{1}{\rho} \\ = \frac{1}{\rho} \sec^2 \theta \end{cases}$$

$$\Rightarrow \bar{E} = \frac{\rho_h a_p}{4\pi \epsilon_0 P} \int_{-\pi/2}^{\pi/2} \cos \theta d\theta$$

$$= \frac{\rho_h a_p}{4\pi \epsilon_0 P} [+\sin \theta]_{-\pi/2}^{\pi/2}$$

$$= \frac{\rho_h a_p}{4\pi \epsilon_0 P} (2) = \frac{\rho_h}{2\pi \epsilon_0 P} a_p$$

$\therefore \boxed{\bar{E} = \frac{\rho_h}{2\pi \epsilon_0 P} a_p V_m}$ for line charg.

Electric Field intensity due to infinite sheet charge:-

→ Consider, a sheet charge is placed in yz -plane & point of observation (P) on x -axis, then

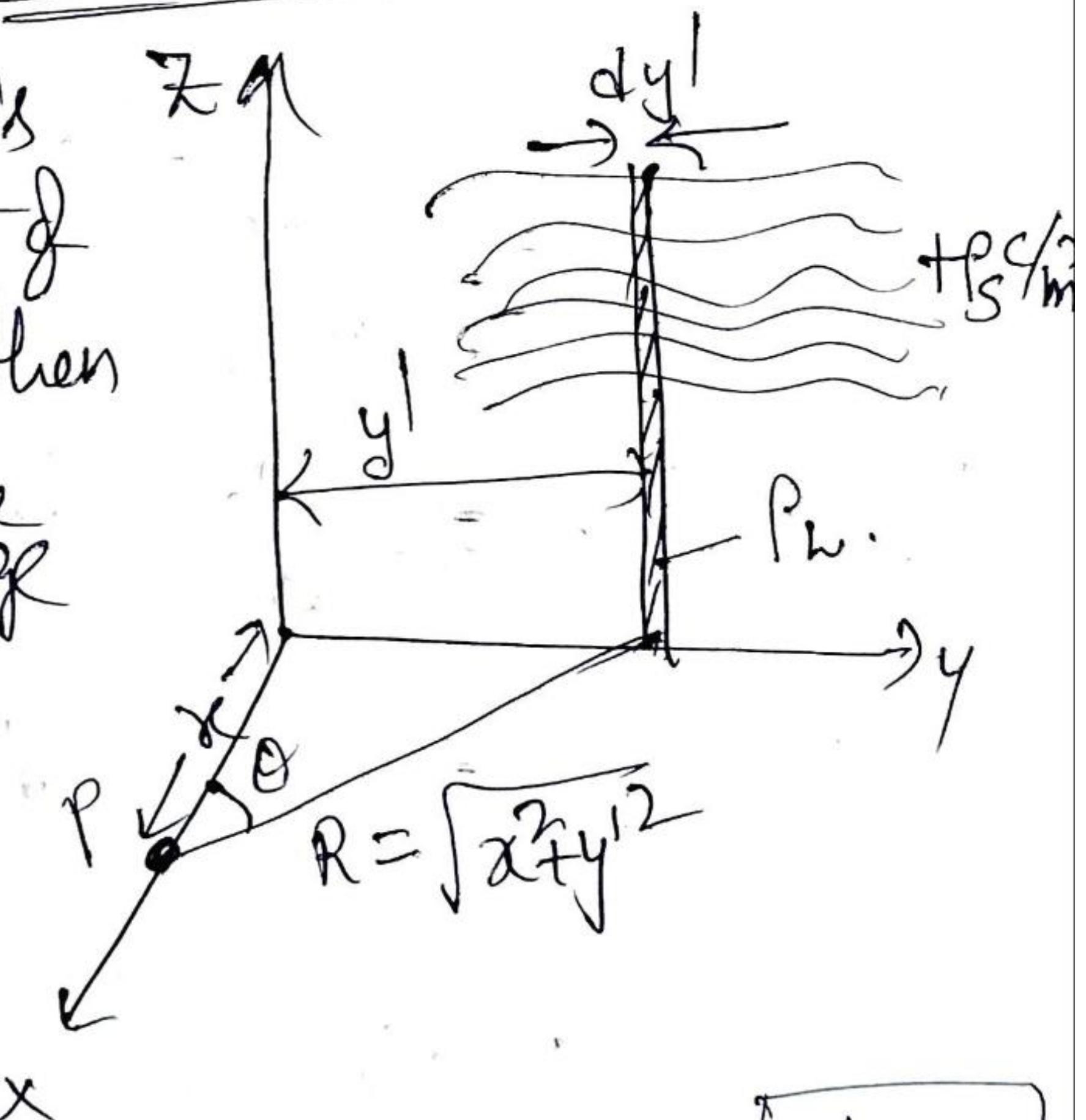
i) $\rho_h = \rho_s dy' \text{ - charge}$

ii) $R = \sqrt{x^2 + y'^2} \text{ - distance}$

→ Let \bar{E} due to line charge is

$$\bar{E} = \frac{\rho_h}{2\pi \epsilon_0 P} a_p = \frac{\rho_s dy'}{2\pi \epsilon_0 \sqrt{x^2 + y'^2}} \cos \theta$$

here,
 $P = R$



here, $\cos\theta$ — it can give the contribution of 'P' in any direction.

$$\therefore d\bar{E} = \frac{\rho_s dy' \cos\theta}{2\pi\epsilon_0 \sqrt{x^2+y'^2}}$$

$$= \frac{\rho_s dy'}{2\pi\epsilon_0 \sqrt{x^2+y'^2}} \cdot \frac{x}{\sqrt{x^2+y'^2}} \quad (\text{since } \cos\theta = \frac{x}{\sqrt{x^2+y'^2}}$$

from figure).

$$d\bar{E} = \frac{\rho_s dy' x}{2\pi\epsilon_0 (x^2+y'^2)}$$

Integrate on both sides.

$$\begin{aligned}\bar{E} &= \frac{\rho_s}{2\pi\epsilon_0} \int_{-\infty}^{\infty} \frac{x}{x^2+y'^2} dy' \\ &= \frac{\rho_s}{2\pi\epsilon_0} \left(\tan^{-1} \frac{y'}{x} \right) \Big|_{-\infty}^{\infty} \\ &= \frac{\rho_s}{2\pi\epsilon_0} \left(\frac{\pi}{2} - \left(-\frac{\pi}{2}\right) \right) \\ &= \frac{\rho_s}{2\pi\epsilon_0} (\pi) \quad = \frac{\rho_s}{2\epsilon_0} \quad (\text{in } x\text{-direction}) \\ \therefore \boxed{\bar{E}_x = \frac{\rho_s}{2\epsilon_0}} \quad &\text{V/m}\end{aligned}$$

Note:- \bar{E} due to surface charge ρ_s is independent of distance.

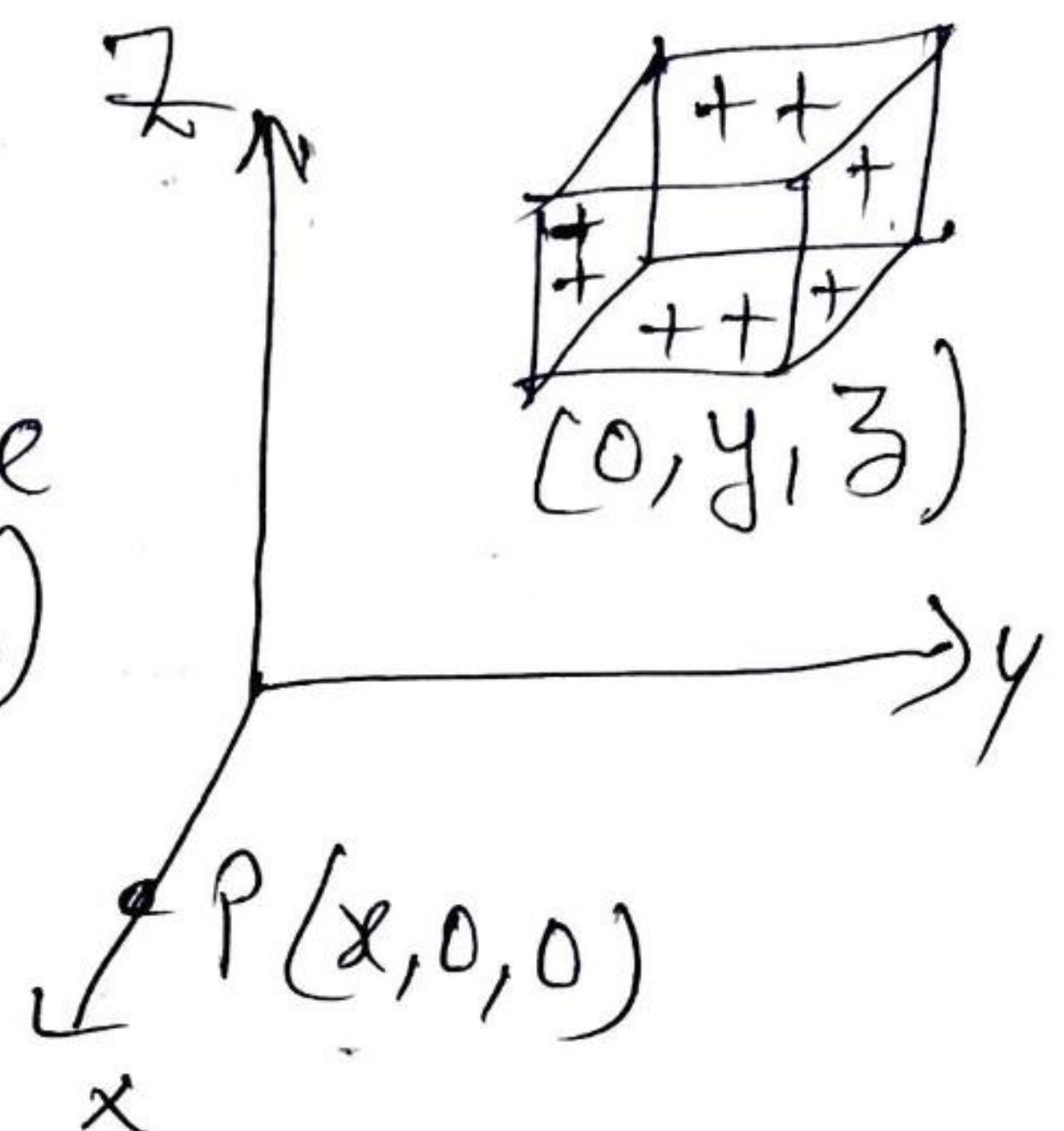
Electric field intensity due to infinite volume charge.

→ Consider infinite volume charge cube in yz -plane and P (point of observation) on x -axis, where \vec{E} is to be found.

here, $\rho_v = \frac{dQ}{dv} \rightarrow$ volume charge density (C/m^3)

$$\Rightarrow dQ = \rho_v dv$$

$$\Rightarrow Q = \int_V \rho_v dv.$$



ii) distance b/w source & point (P) is

$$\bar{R} = x\hat{a}_x - y\hat{a}_y - z\hat{a}_z$$

$$|\bar{R}| = \sqrt{x^2 + y^2 + z^2}$$

Let $\vec{E} = \frac{Q}{4\pi\epsilon_0 |\bar{R}|^2} \hat{a}_R$ (for point charge)

$$= \frac{\int_V \rho_v dv}{4\pi\epsilon_0 |\bar{R}|^2} \cdot \frac{\bar{R}}{|\bar{R}|} = \int_V \frac{\rho_v dv \cdot \bar{R}}{4\pi\epsilon_0 |\bar{R}|^3}$$

$$\vec{E} = \int_V \frac{\rho_v dv (x\hat{a}_x - y\hat{a}_y - z\hat{a}_z)}{4\pi\epsilon_0 |\bar{R}|^3}$$

Eliminating y and z -components of \vec{E}

$$\vec{E} = \int_V \frac{\rho_v dv x\hat{a}_x}{4\pi\epsilon_0 |\bar{R}|^3}$$

$$\Rightarrow \vec{E} = \int_0^\infty \int_0^\pi \int_0^{\pi/2} \frac{\rho_v (r \sin \theta dr d\theta d\phi) \hat{x} a_x}{4\pi \epsilon_0 r^3}$$

since $dr = r^2 \sin \theta dr d\theta d\phi$ (For spherical coordinate system)

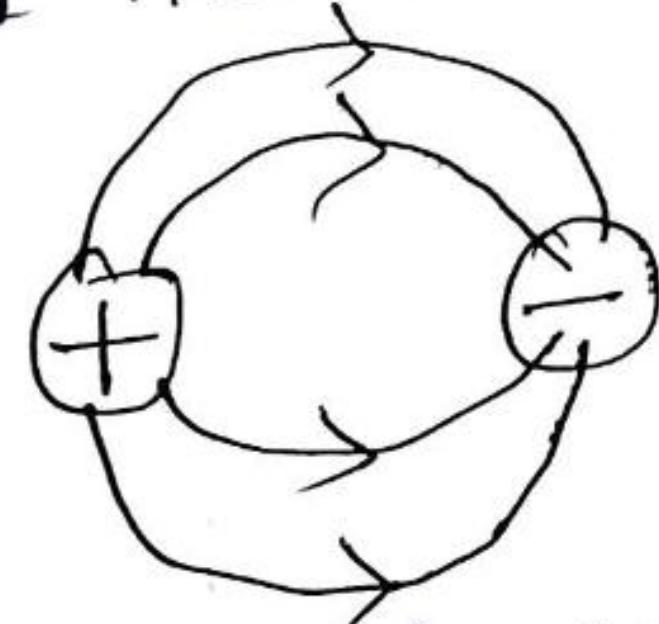
& Let $R = r$

$$\begin{aligned} \Rightarrow \vec{E} &= \frac{\rho_v}{4\pi \epsilon_0} \left[\int_0^R \frac{1}{r} dr \cdot \int_0^\pi \sin \theta d\theta \cdot \int_0^{2\pi} d\phi \hat{x} a_x \right] \\ &= \frac{\rho_v}{4\pi \epsilon_0} \left(\ln R \Big|_0^R \right) \left(-\cos \theta \Big|_0^\pi \right) \left(\phi \Big|_0^{2\pi} \right) \hat{x} a_x \\ &= \frac{\rho_v}{4\pi \epsilon_0} \cdot (\ln R - 1) \cdot 2 \cdot 2\pi \cdot \hat{x} a_x \\ \therefore \boxed{\vec{E} = \frac{\rho_v}{\epsilon_0} (\ln R - 1) \hat{x} a_x} \quad &\text{V/m.} \end{aligned}$$

Electric flux: It is the total number of lines of force in any direction, denoted by Φ , measured in coulomb (c). (6)

→ The flux lines start from positive charge and terminate on negative charge.

- The flux lines are parallel and never cross each other.



Electric flux density:

→ The number of flux lines passing through the unit surface area is called electric flux density, denoted by D . Units are C/m^2 . $D = \frac{\text{Flux}}{\text{Unit surface area}} = \frac{d\Phi}{ds}$

- This is also called displacement flux density (or) displacement density.

Gauss's Law: It constitutes one of the fundamental laws of electromagnetism.

→ It states that the total electric flux (Φ) through any closed surface is equal to the total charge enclosed by that surface.

i.e
$$\boxed{\Phi = Q}$$

Relation between \vec{E} and \vec{D} :

→ We know that : $\vec{D} = \frac{d\psi}{ds}$

$$\Rightarrow d\psi = \vec{D} \cdot ds \Rightarrow \psi = \int \vec{D} \cdot ds$$

From Gauss law $\psi = Q \Rightarrow Q = \boxed{\int \vec{D} \cdot ds}$

$$\Rightarrow Q = \vec{D} \int ds \quad (\text{since } \vec{D} \text{ - same at all points of Gaussian surface}). \\ \therefore \vec{D} \text{ - constant}$$

$$= D \int_{\phi=0}^{2\pi} \int_{\theta=0}^{\pi} r^2 \sin\theta d\theta d\phi \quad (\because ds = r \sin\theta d\theta d\phi)$$

$$= D r^2 \int_{\theta=0}^{\pi} \sin\theta d\theta \cdot \int_{\phi=0}^{2\pi} d\phi$$

$$\therefore Q = D r^2 (2)(2\pi) = 4\pi D r^2$$

$$\Rightarrow \boxed{\vec{D} = \frac{Q}{4\pi r^2} \hat{r}} \text{ C/m}^2 \text{ — for point charge.}$$

we know: $\vec{E} = \frac{Q}{4\pi \epsilon_0 r^2} \hat{r} \text{ N/C} \text{ — for point charge.}$

∴ Relating these 2 equations:

$$\boxed{\vec{D} = \epsilon_0 \vec{E}} \quad (\text{or}) \quad \boxed{\vec{D} = \epsilon \vec{E}}$$

$$\text{since } \epsilon = \epsilon_0 \epsilon_r$$

Proof of Gauss Law:-

(7)

$$\begin{aligned} \Psi &= \int D \cdot dS = \int \frac{Q}{4\pi r^2} dS \quad \left(\therefore D = \frac{Q}{4\pi r^2} \right) \\ &= \int_0^{2\pi} \int_0^{\pi} \frac{Q}{4\pi r^2} \sin\theta d\theta d\phi \\ &= \frac{Q}{4\pi} \int_0^{\pi} \sin\theta d\theta \int_0^{2\pi} d\phi \\ &= \frac{Q}{4\pi} (2)(2\pi) = Q. \\ \therefore \boxed{\Psi = Q} \end{aligned}$$

Gauss Law Applications:-

(i) Electric Flux density due to infinite line charge:-

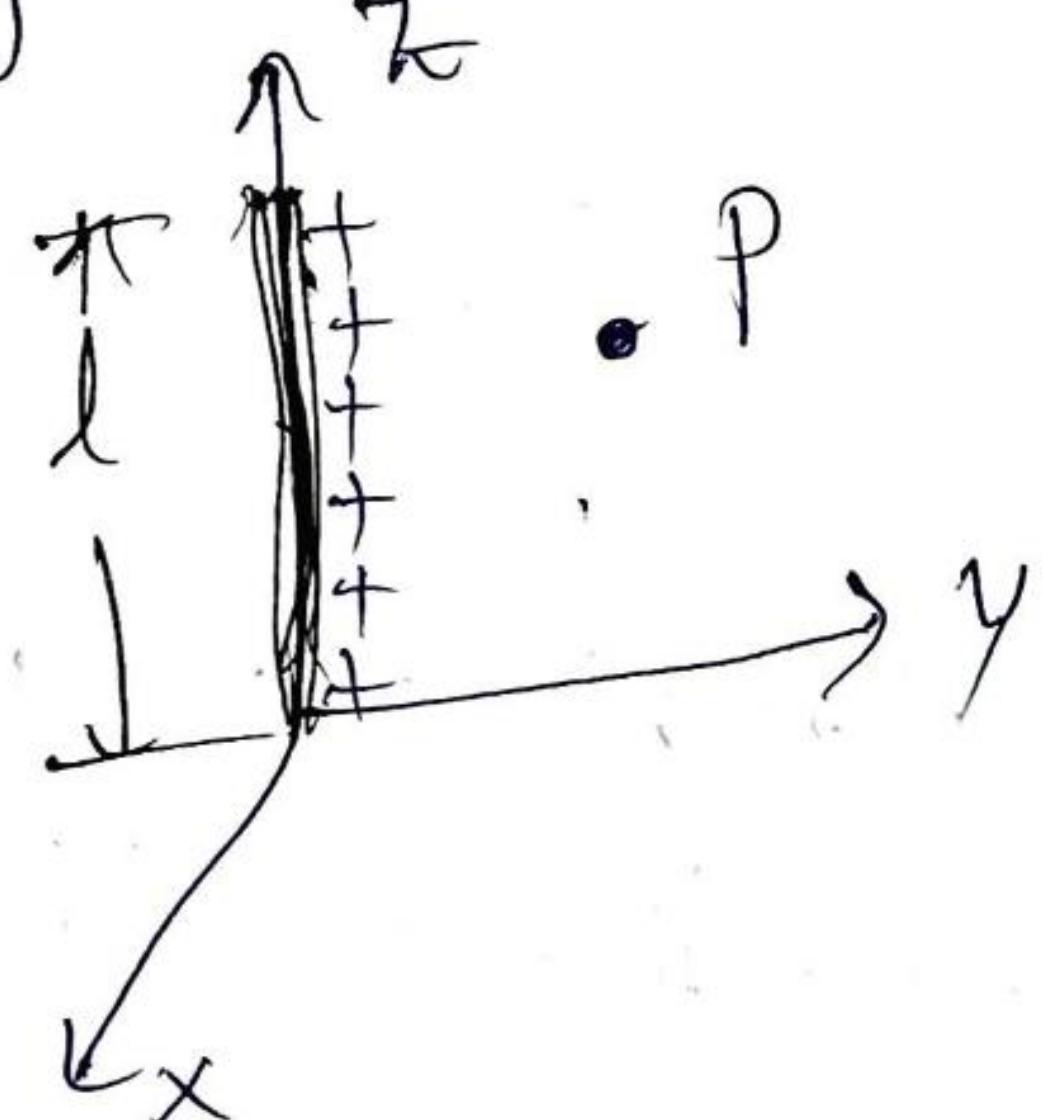
Consider, infinite line charge along z -axis as shown.
Find the electric flux density at a point (P).

→ According to Gauss law:

$$Q = \int D \cdot dS$$

$$\int \rho_l dz = \int D \cdot dS$$

$$\begin{aligned} \rho_l \cdot l &= D \int_{-\infty}^{\infty} dS \\ &= D \int_0^{2\pi} \int_{-\infty}^{\infty} d\phi dz \rho \end{aligned}$$



$$\Rightarrow \rho_h \cdot l = D\rho \int_0^{2\pi} d\phi \int_{-\infty}^{\infty} dz$$

$$\Rightarrow \rho_h \cdot l = D\rho (2\pi) (l)$$

$$\Rightarrow \boxed{D = \frac{\rho_h}{2\pi\rho} a_p} \text{ C/m}^2$$

(ii) Electric flux density due to sheet charge:

Consider the sheet in XY plane as shown:

→ According to Gauss law:

$$Q = \int \overline{D} \cdot ds$$

$$\int \rho_s ds = \int \overline{D} \cdot ds$$

$$\rho_s \int ds = \int_{\text{top}} \overline{D} \cdot ds + \int_{\text{bottom}} \overline{D} \cdot ds$$

$$\Rightarrow \rho_s \int ds = 2 \overline{D} \int ds$$

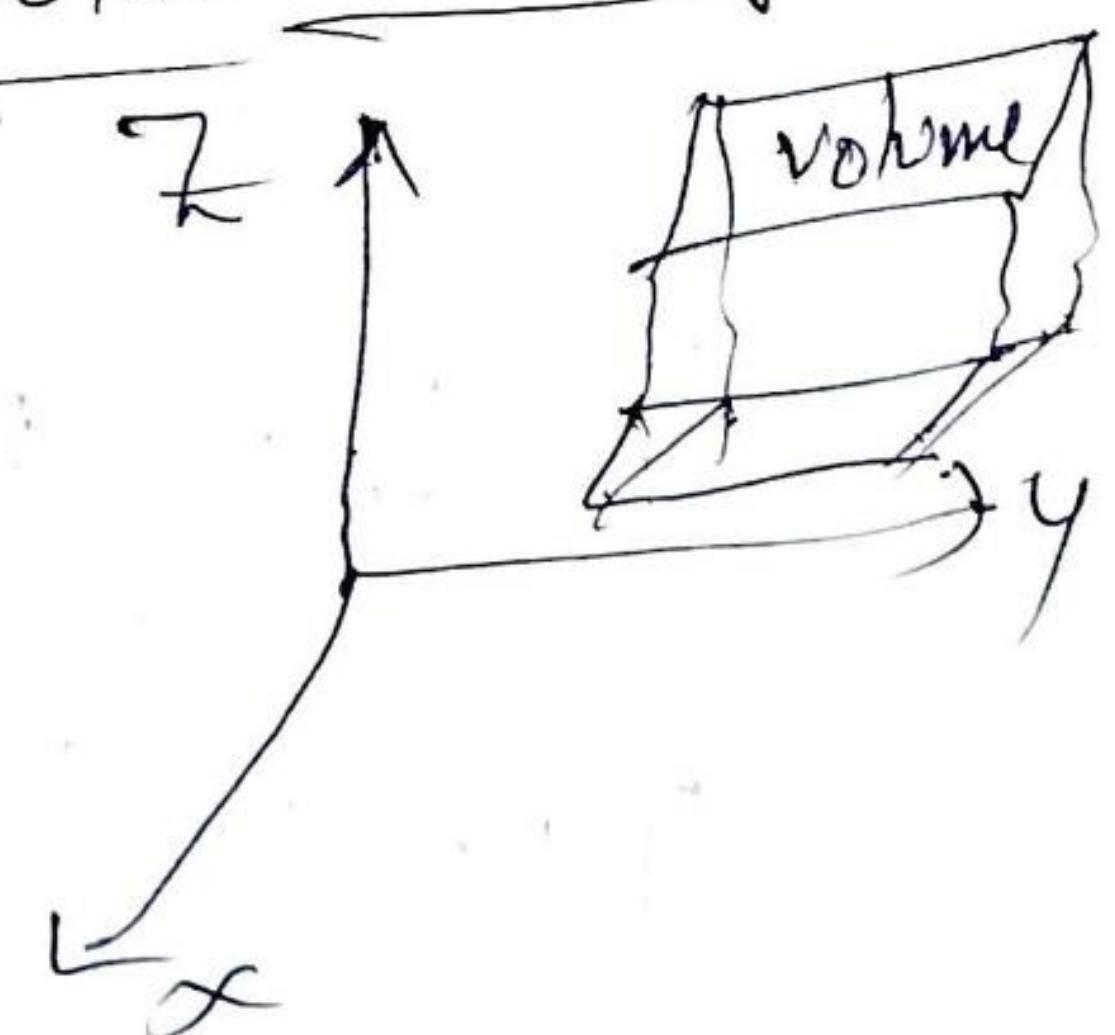
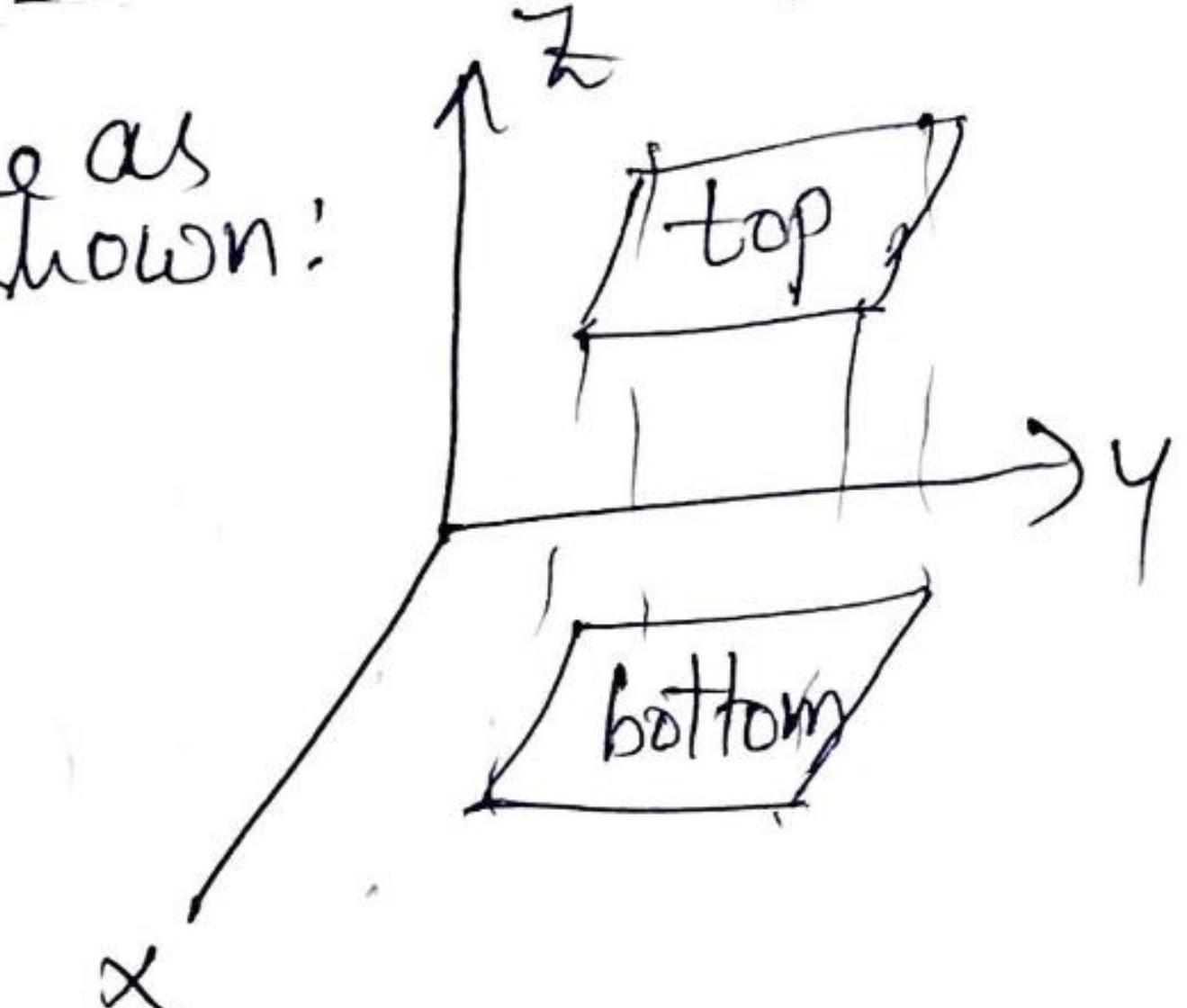
$$\Rightarrow \boxed{\overline{D} = \frac{\rho_s}{2}} \text{ C/m}^2$$

(iii) Electric flux density due to volume charge's

According to Gauss law:

$$Q = \int \overline{D} \cdot ds$$

$$\int \rho_v dv = \int \overline{D} \cdot ds$$



$$\rho_v \int_0^\infty \int_0^{2\pi} \int_0^\pi r^2 \sin\theta dr d\theta d\phi = \bar{D} \int_0^\infty \int_0^\pi r dr d\theta \quad (8)$$

$$\rho_v \int_0^\infty r^2 dr \int_0^\pi \sin\theta d\theta \int_0^{2\pi} d\phi = \bar{D} \int_0^\infty r dr \int_0^\pi d\theta$$

$$\rho_v \cdot \frac{r^3}{3} \times 2 \times 2\pi = \bar{D} \frac{a^2}{2} \times \pi$$

$$\therefore \boxed{\bar{D} = \frac{8 \rho_v r^3}{3 a^2}} \text{ C/m}^2.$$

Statement of Gauss's law (Integral Form):
 The integral of the normal component of the flux density evaluated over a closed surface must be equal to the charge enclosed by the closed surface.

$$Q_{en} = \oint_S \bar{D}_n \cdot dS$$

Limitations of Gauss's Law:

- ① charges should be uniformly distributed.
- ② It can be applied to closed surface (Gaussian surface).

Gaussian surface:- An imaginary closed surface of arbitrary shape used to find \bar{E} .

- ③ For line charge distribution — cylindrical
 - Spherical charge distribution — concentric sphere.
 - Surface charge distribution — cylindrical.
- ④ Field point must lies on gaussian surface.
 - ⑤ charge must be inside gaussian surface.
 - ⑥ It satisfies only when all charges are symmetrical

Σ .

Gauss Divergence Theorem:

①

Divergence: It converts the integral form of Gauss law into point form.

• Gauss law integral form:
$$Q_{\text{en}} = \int_S \vec{D} \cdot d\vec{s} = \int_V \rho_v dv$$

• Divergence is of 3 types:-

- ① positive divergence:- The flow of flux from inside to outside & the volume becomes zero. ex: balloon.
- ② Negative divergence:- The flow of flux from outside to inside is negative divergence. ex: vacuum created room.
- ③ zero divergence:- The net flow of flux is zero when the inward flux = outward flux. ex: water tank

→ Mathematically, divergence can be expressed as:

$$\text{div } \vec{D} = \lim_{\Delta V \rightarrow 0} \frac{\int_S \vec{D} \cdot d\vec{s}}{\Delta V} = \lim_{\Delta V \rightarrow 0} \frac{Q_{\text{en}}}{\Delta V} = \rho_v \text{ C/m}^3 \quad ①$$

• Also, it can be expressed using mathematical operators.

$$\nabla = \frac{\partial}{\partial x} a_x + \frac{\partial}{\partial y} a_y + \frac{\partial}{\partial z} a_z$$

Let $\vec{D} = D_x a_x + D_y a_y + D_z a_z$ (component form of vector)

$$\nabla \cdot \vec{D} = \frac{\partial D_x}{\partial x} + \frac{\partial D_y}{\partial y} + \frac{\partial D_z}{\partial z} \quad ②$$

Equating equations ① & ②,

$$\nabla \cdot \vec{D} = \rho_v \quad \begin{array}{l} \text{Point form} \\ \text{of Gauss law.} \end{array}$$

↳ Maxwell's 1st equation

Note:- Unit of divergence:- C/m^3 . (and ∇ unit $-1/\text{m}$)

Statement of divergence Theorem:-

→ The integral of normal component of the flux density evaluated over a closed surface must be equal to the integral of the divergence of flux density throughout the volume enclosed by the closed surface.

We know from Gauss law: Maxwell's 1st equation.

$$\boxed{Q_{\text{en}} = \oint_S \vec{D} \cdot d\vec{s} = \int_V \rho_v dv \quad \begin{matrix} \text{(Integral form)} \\ \rightarrow ① \end{matrix}}$$

$$\nabla \cdot \vec{D} = \rho_v \quad \begin{matrix} \text{(point form)} \\ \rightarrow ② \end{matrix}$$

substituting ② in ①,

$$\boxed{\oint_S \vec{D} \cdot d\vec{s} = \int_V (\nabla \cdot \vec{D}) dv} \quad \begin{matrix} \text{Gauss divergence} \\ \text{Theorem} \end{matrix}$$

i.e. surface integral converted into volume integral.

Note:- $\nabla \cdot \vec{D} = \frac{\partial D_x}{\partial x} + \frac{\partial D_y}{\partial y} + \frac{\partial D_z}{\partial z}$ (Cartesian)

Divergence formulae

$$\left. \begin{aligned} \nabla \cdot \vec{D} &= \frac{1}{r} \frac{\partial}{\partial r} (r D_r) + \frac{1}{r \sin \theta} \frac{\partial D_\theta}{\partial \theta} + \frac{\partial D_\phi}{\partial \phi} \quad (\text{cylindrical}) \\ \nabla \cdot \vec{D} &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 D_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta D_\theta) + \frac{1}{r \sin \theta} \frac{\partial D_\phi}{\partial \phi} \quad (\text{spherical}) \end{aligned} \right\}$$

Electric potential:

(10)

- It is defined as the amount of work done required to bring/move a unit of electric charge from a reference point to the specific point against an electric field. i.e $V = \frac{W}{Q_t}$
- It is a scalar used to develop vector (\vec{E}).
- Consider a positive charge (Q_m) placed in an external electric field, let a test charge (Q_t) is placed at a point A.

- Due to \vec{E} around Q_m , Q_t will experience an electrostatic force F_e directed away from the charge.
- Since both charges are same, repulsive force exerted i.e $F_{ext} = -F_e$

- As per coulomb's law :

$$F_e = \vec{E} Q_t \quad (\text{since } \vec{E} = \frac{\vec{F}}{Q_t})$$

As we know: workdone = force \times distance

$$dw = E Q_t \times dh$$

$$\int dw = - \int_{\text{initial}}^{\text{final}} E Q_t \cdot dh \quad (\text{since -ve sign is due to workdone by test charge).}$$

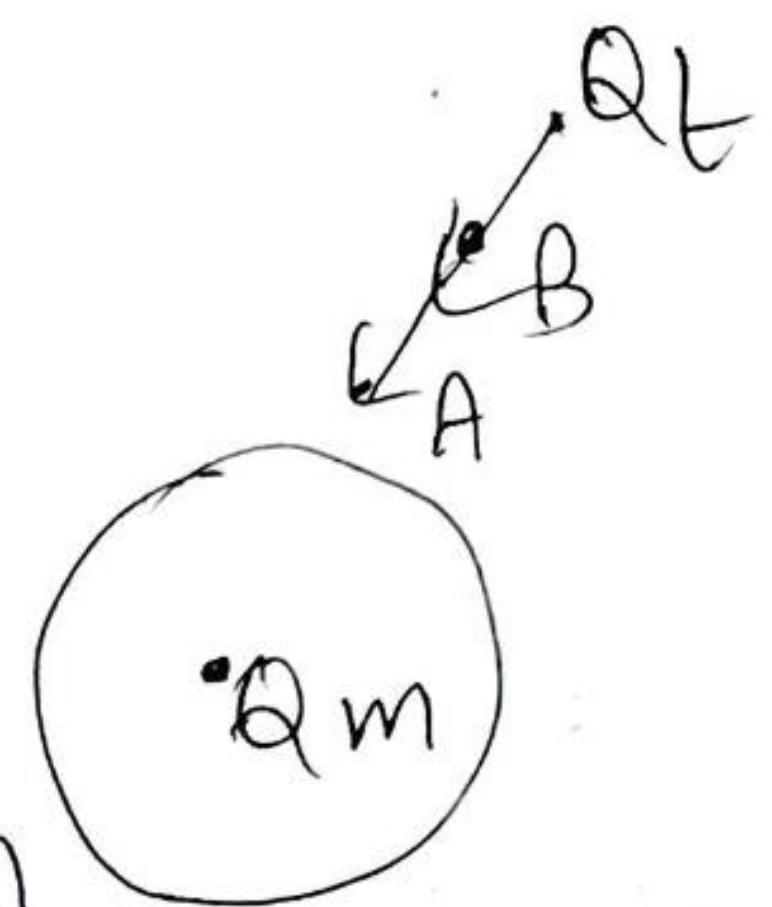
$$w = - Q_t \int_{\text{initial}}^{\text{final}} \vec{E} \cdot dh$$

Now, potential $V = \frac{w}{Q_t} = - \int_{\text{initial}}^{\text{final}} \vec{E} \cdot dh$ J/C (or) volts.

(i) Potential at any (single) point:

At point (B), potential is

$$V_B = - \int_{\infty}^B \vec{E} \cdot d\vec{r}$$



whereas ∞ — reference point where potential is zero (i.e. $V_{\infty} = 0$).

(ii) Potential difference between 2 points:-

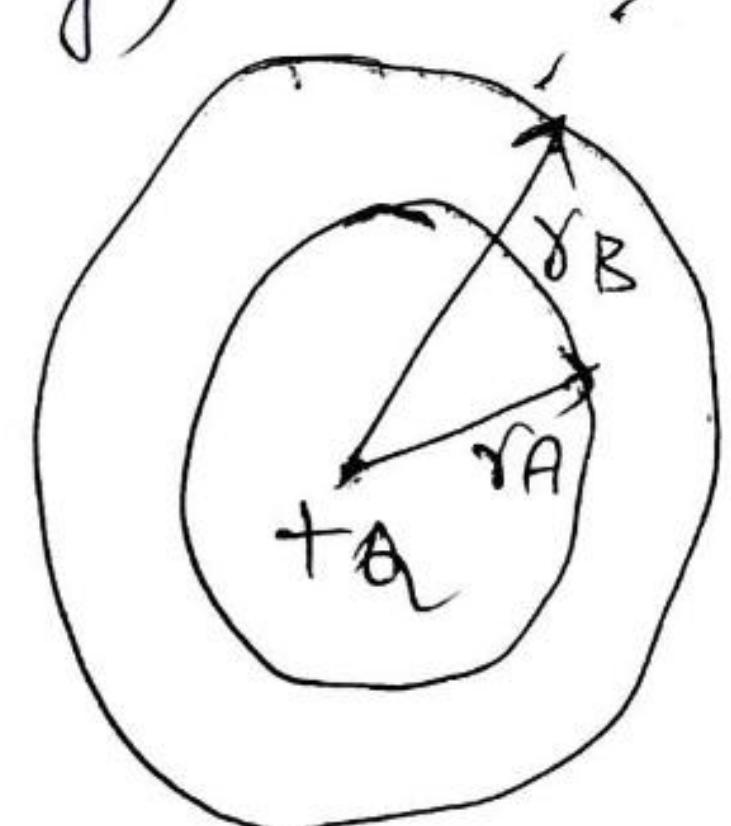
Potential difference between A & B is given as

$$V_{AB} = - \int_{B}^{A} \vec{E} \cdot d\vec{r} = V_A - V_B$$

① Potential of a point charge: In general,

$$V = - \int_{\text{initial}}^{\text{final}} \vec{E} \cdot d\vec{r}$$

where $\vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{a}_r$ (for point charge)



$$\begin{aligned} \therefore V &= - \int_{r_B}^{r_A} \frac{Q}{4\pi\epsilon_0 r^2} \hat{a}_r \cdot d\vec{r} \\ &= - \frac{Q}{4\pi\epsilon_0} \int_{r_B}^{r_A} \frac{1}{r^2} dr \quad (\hat{a}_r \cdot \hat{a}_r = 1) \\ &= \frac{-Q}{4\pi\epsilon_0} \left[\left(\frac{1}{r} \right) \right]_{r_B}^{r_A} \\ &= \frac{-Q}{4\pi\epsilon_0} \left[\left(\frac{1}{r_A} \right) - \left(\frac{1}{r_B} \right) \right] \\ &= \frac{Q}{4\pi\epsilon_0} \left[\frac{1}{r_B} - \frac{1}{r_A} \right] \end{aligned}$$

* $dr = d\vec{r}$
moving in radial direction

if $r_B \rightarrow \infty$, In general
 $V = \frac{Q}{4\pi\epsilon_0 r_A}$ $\Rightarrow V = \frac{Q}{4\pi\epsilon_0 r}$ volts.

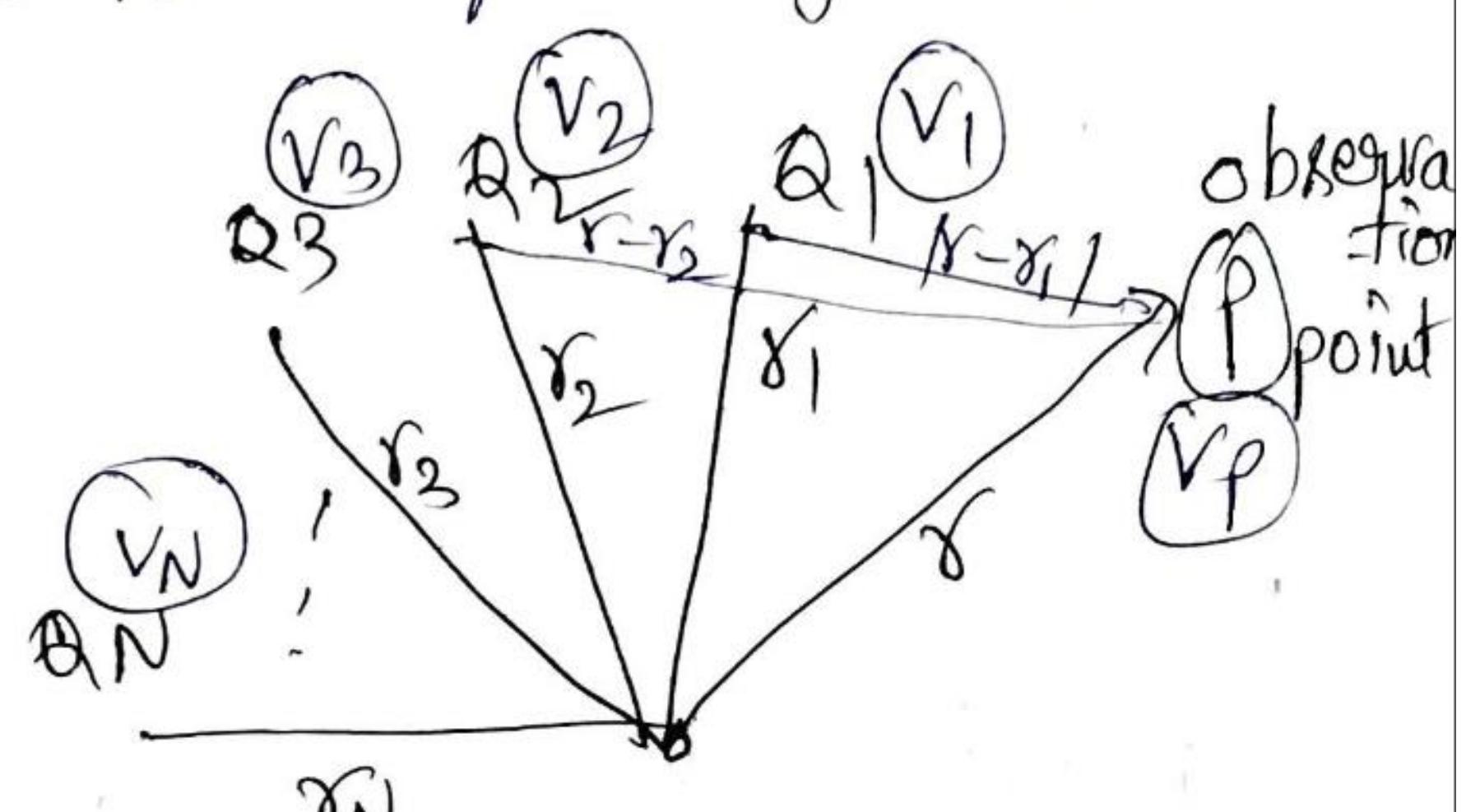
- Potential of a system comprising N-point charges: ⑪
- As potential is linear, it obeys superposition theorem.
 - hence, it can be apply for N-no. of charges system.
 - ∴ According to superposition theorem:

$$V_p = V_1 + V_2 + \dots + V_N$$

i.e

$$V_p = \frac{Q_1}{4\pi\epsilon_0|x-x_1|} + \frac{Q_2}{4\pi\epsilon_0|x-x_2|} + \dots$$

$$\therefore V_p = \frac{1}{4\pi\epsilon_0} \sum_{m=1}^N \frac{Q_m}{|x-x_m|} \text{ volts.}$$

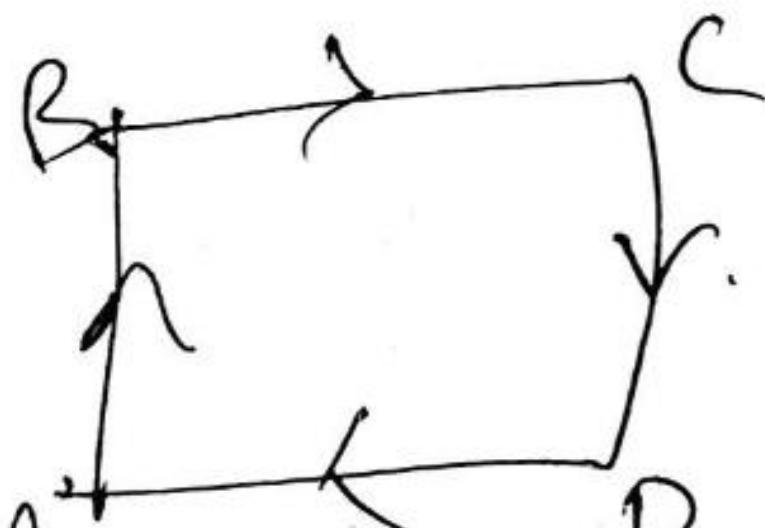


Law of Conservative Field: (KVL in EMF Theory)

- The algebraic sum of all the potentials around a closed loop must be zero.

$$\text{i.e } V = - \int \vec{E} \cdot d\vec{l} = 0$$

Let:



v. fig: closed path (or loop)

$$\text{if } \left(\int_A^B \vec{E} \cdot d\vec{l} + \int_B^C \vec{E} \cdot d\vec{l} + \int_C^D \vec{E} \cdot d\vec{l} + \int_D^A \vec{E} \cdot d\vec{l} \right) = 0.$$

$$\text{i.e. if } \int_h \vec{E} \cdot d\vec{l} = 0 \rightarrow \begin{array}{l} \text{conservative law in} \\ \text{electrostatics} \\ \text{Maxwell's 2nd equation.} \end{array}$$

Curling: cross-product

→ $\nabla \times \vec{E}$ denotes how much vect^l E curls around the point.

→ The curl of E is an axial vector whose magnitude is the maximum circulation of E per unit area tends to zero whose direction is the normal direction of area when the area is oriented, so as to make circulation maximum.

$$\nabla \times \vec{E} = \text{curl } E = \left[\lim_{AS \rightarrow 0} \frac{\oint_L \vec{E} \cdot d\vec{l}}{AS} \right]_{an \max}$$

where AS — area bounded by the curve L .

a_n — unit vector normal to surface AS
— determined by right hand rule.

→ By using curling, the integral form of law of conservative field is converted to point form (or) differential form as:

$$\boxed{\nabla \times \vec{E} = 0} \rightarrow \text{point form of Maxwell's 2nd Equation.}$$

Maxwell's Equations for electrostatic fields:

	<u>Integral Form</u>	<u>Point Form</u>
① Maxwell's 1st Equation: (Gauss law).	$\oint_S \vec{D} \cdot d\vec{S} = \int_V \rho_v dv$	$\nabla \cdot \vec{D} = \rho_v$
② Maxwell's 2nd Equation: (law of conservation of electrostatic field).	$\oint_L \vec{E} \cdot d\vec{l} = 0$	$\nabla \times \vec{E} = 0$

Potential Gradient:

- * The gradient of a scalar quantity (v) gives a vector that represents both magnitude & direction of a maximum rate of change of potential (v).

$$\boxed{\bar{E} = -\nabla v}$$

where $\text{grad } v = \nabla v = \frac{dv}{dh}$

Proof: we know that:

$$v = - \int \bar{E} \cdot dh$$



$$dv = -\bar{E} \cdot dh$$

$$dv = -E dh \cos \theta$$

(using dot product)

$$\Rightarrow \frac{dv}{dh} = -E \cos \theta$$

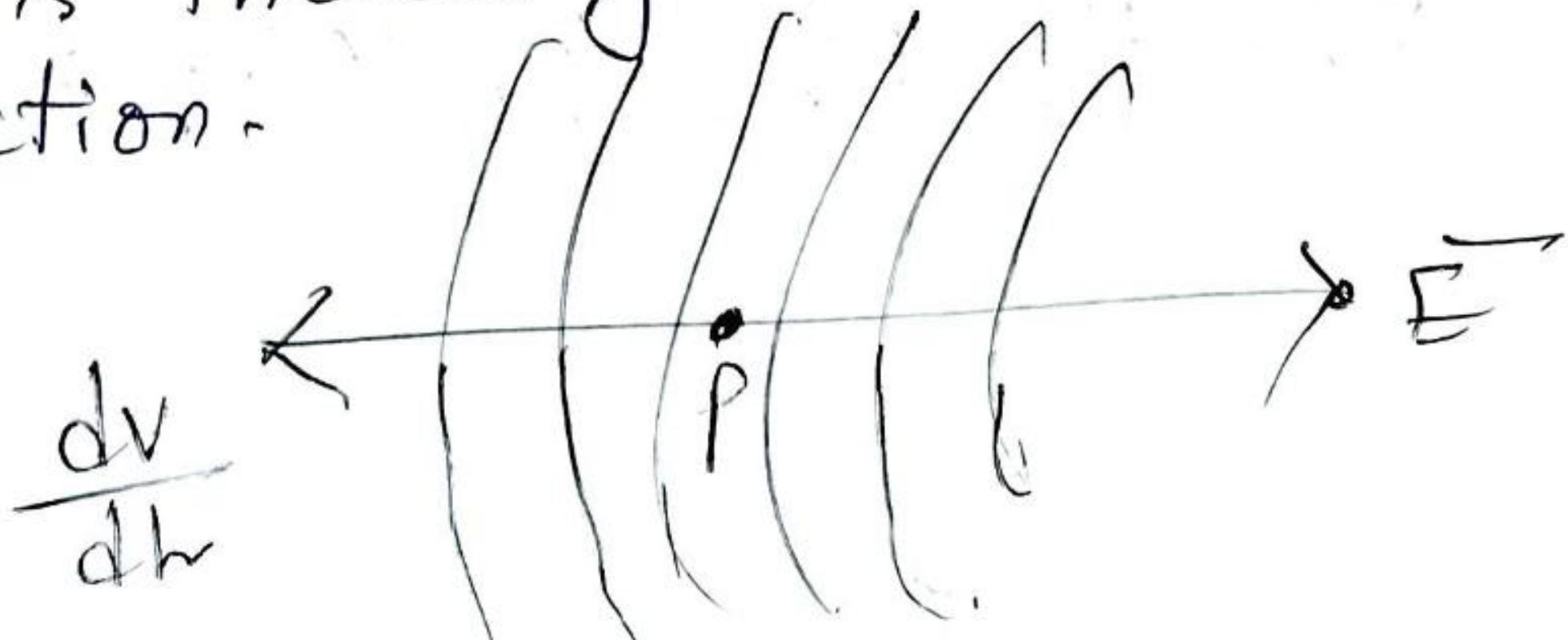
(i) If $\theta = 90^\circ \Rightarrow \frac{dv}{dh} = 0 \Rightarrow$ no work done
 \Rightarrow equipotential surface

$$(ii) \text{ If } \theta = 180^\circ \Rightarrow \frac{dv}{dh} = \bar{E} \Rightarrow \left. \frac{dv}{dh} \right|_{\max} = \bar{E}_{\max}$$

This indicates maximum rate of change of potential with distance gives maximum electric field intensity.

$$\therefore \boxed{\bar{E} = -\text{grad } v = -\nabla v}$$

i.e Maximum value is obtained for \bar{E} when potential is increasing most rapidly in opposite direction.



Mathematical proof:

→ Let v is a function of (x, y, z) then

$$dv = \frac{\partial v}{\partial x} dx + \frac{\partial v}{\partial y} dy + \frac{\partial v}{\partial z} dz \quad \text{--- (1)}$$

we know: $V = - \int E \cdot dl$

$$\Rightarrow dv = -E \cdot dl$$

$$= - [E_x ax + E_y ay + E_z az] \cdot [dx a_x + dy a_y + dz a_z]$$

$$\Rightarrow dv = - [E_x dx + E_y dy + E_z dz] \quad \text{--- (2)}$$

equating (1) & (2) $\Rightarrow E_x = \frac{-\partial v}{\partial x}; E_y = \frac{-\partial v}{\partial y}; E_z = \frac{-\partial v}{\partial z}$

$$\begin{aligned} \therefore \bar{E} &= - \left[\frac{\partial v}{\partial x} a_x + \frac{\partial v}{\partial y} a_y + \frac{\partial v}{\partial z} a_z \right] \\ &= - \left[\frac{\partial}{\partial x} a_x + \frac{\partial}{\partial y} a_y + \frac{\partial}{\partial z} a_z \right] V \end{aligned}$$

$$\therefore \boxed{\bar{E} = -\nabla V}$$

Note:- Formulae for Gradient in 3 coordinate systems

(1) $\nabla V = \frac{\partial V}{\partial x} a_x + \frac{\partial V}{\partial y} a_y + \frac{\partial V}{\partial z} a_z$ (Cartesian coordinate system)

(2) $\nabla V = \frac{\partial V}{\partial \rho} a_\rho + \frac{1}{\rho} \frac{\partial V}{\partial \phi} a_\phi + \frac{\partial V}{\partial z} a_z$ (cylindrical ")

(3) $\nabla V = \frac{\partial V}{\partial r} a_r + \frac{1}{r} \frac{\partial V}{\partial \theta} a_\theta + \frac{1}{r \sin \theta} \frac{\partial V}{\partial \phi} a_\phi$ (spherical)

* Energy & Energy Density:-

(13)

- Energy density is the amount of energy stored in a given system (or) region of space per unit volume.
- Consider,
- (i) a point charge Q_1 transferred from infinity to position r_1 in the system.
 - It takes no work to bring the first charge since there is no electric field against (as the system is initially empty i.e. charge free).
 - ∴ $W_1 = 0 \text{ J}$.
- (ii) another point charge Q_2 , to bring it to position r_2 from infinity.
 - Do some work against the electric field generated by Q_1 .
 - ∴ $W_2 = Q_2 V_{21} \text{ J}$
where V_{21} — electrostatic potential at position r_2 due to Q_1 .
- (iii) Similarly, the work required to bring Q_3 to r_3

$$W_3 = Q_3 V_{31} + Q_3 V_{32} = Q_3 (V_{31} + V_{32}) \text{ J}$$
 - where V_{31} & V_{32} — potentials at r_3 due to Q_1 & Q_2 .

→ Thus, the total work done in assembling the 3 charges is given as $W_E = W_1 + W_2 + W_3$

$$= 0 + Q_2 V_{21} + Q_3 (V_{31} + V_{32}) \quad \text{--- (1)}$$

→ if the charges were positioned in reverse order such as: let

$$\left. \begin{aligned} Q_2 V_{21} &= Q_2 \frac{Q_1}{4\pi\epsilon_0 R_{21}} = Q_1 \frac{Q_2}{4\pi\epsilon_0 R_{12}} \\ \therefore Q_2 V_{21} &= Q_1 V_{12} \end{aligned} \right]$$

substituting this reverse logic, eqn (1) becomes,

$$W_E = Q_1 V_{12} + Q_1 V_{13} + Q_2 V_{23} \quad \text{--- (2)}$$

→ Adding eqn (1) & (2) $\Rightarrow 2W_E = Q_1 (V_{12} + V_{13}) + Q_2 (V_{21} + V_{23}) + Q_3 (V_{31} + V_{32})$

$$\therefore 2W_E = Q_1 V_1 + Q_2 V_2 + Q_3 V_3$$

$$\Rightarrow W_E = \frac{1}{2} [Q_1 V_1 + Q_2 V_2 + Q_3 V_3] \text{ where}$$

V_1, V_2, V_3 — potentials at r_1, r_2 & r_3 .

for N-point charges:-

$$W_E = \frac{1}{2} \sum_{m=1}^N Q_m V_m \quad \text{Joules}$$

for single charge:-

$$W_E = \frac{1}{2} Q V \quad \text{J}$$

Ex: energy storage in capacitor is

$$W_E = \frac{1}{2} C V^2 \quad \text{J}$$

$$\text{since } C = \frac{Q}{V}$$

- Note: (i) Energy equation represents potential energy of the system. (14)
- (ii) This is the workdone in bringing static charges from infinity & assembling them in the system.
- (iii) when charges return back to $\infty \Rightarrow$ system gets dissolved \Rightarrow kinetic energy released.

Continuous charge configurations:-

\rightarrow If the system has continuous charge distribution (in place of point charge) then energy equation becomes:

$$\textcircled{1} \quad Q = \int_h \rho_h dh ; \quad W_E = \frac{1}{2} \int_h \rho_h \cdot V dh \quad \text{J} \quad \begin{matrix} \text{line} \\ \text{charge} \end{matrix}$$

$$\textcircled{2} \quad Q = \int_S \rho_S ds ; \quad W_E = \frac{1}{2} \int_S \rho_S \cdot V ds \quad \text{J} \quad \begin{matrix} \text{surface} \\ \text{charge} \end{matrix}$$

$$\textcircled{3} \quad Q = \int_V \rho_V dv ; \quad W_E = \frac{1}{2} \int_V \rho_V \cdot V dv \quad \text{J} \quad \begin{matrix} \text{volume} \\ \text{charge} \end{matrix}$$

For most practical configuration (volume):-

$$Q = \int_V \rho_V dv \Rightarrow W_E = \frac{1}{2} \int_V \rho_V \cdot V dv.$$

Energy density in terms of D & E :

$$W = \frac{1}{2} \int_V (\nabla \cdot D) V dv \quad \text{since } \rho_V = \nabla \cdot D$$

From vector identity:
$$\boxed{\nabla \cdot V \bar{D} \equiv V(\nabla \cdot D) + \bar{D} \cdot (\nabla V)}$$

$$\therefore W_E = \frac{1}{2} \int_V (\nabla \cdot \bar{D}) dV - \frac{1}{2} \int_V (\bar{D} \cdot \nabla V) dV$$

• As per divergence theorem:

$$\int_S \bar{V} \bar{D} \cdot d\bar{s} = \int_V (\nabla \cdot \bar{D}) dV$$

$$\therefore W_E = \frac{1}{2} \int_S \bar{V} \bar{D} \cdot d\bar{s} - \frac{1}{2} \int_V (\bar{D} \cdot \nabla V) dV$$

$$= 0 - \frac{1}{2} \int_V (\bar{D} \cdot \nabla V) dV$$

$$= -\frac{1}{2} \int_V \bar{D} \cdot (-\bar{E}) dV \quad (\text{since } \bar{E} = -\nabla V)$$

$$W_E = \frac{1}{2} \int_V \bar{D} \cdot \bar{E} dV$$

Joules.

Also

$$W_E = \frac{1}{2} \int_V \epsilon_0 \bar{E}^2 dV$$

 Joules (since $\bar{D} = \epsilon_0 \bar{E}$)

Energy Density: Energy density = $\frac{\text{energy}}{\text{unit volume}}$

$$\therefore W_E = \frac{1}{2} \int_V \bar{D} \cdot \bar{E} dV$$

$$\Rightarrow \boxed{\frac{dW_E}{dV} = \frac{1}{2} (\bar{D} \cdot \bar{E}) = \frac{1}{2} (\epsilon_0 \bar{E}^2) = \frac{1}{2} \frac{\bar{D}^2}{\epsilon_0} \left| \frac{J}{m^3} \right.}$$

Energy density ($\frac{dW_E}{dV}$), measured in J/m^3 .

Equation of continuity (Electrostatic fields):

(15)

→ We know that:

i) current — rate of change of charge. $I = \frac{dQ}{dt}$ A

ii) current density — current per unit area.

iii) $J = \frac{I}{A}$ A/m² (valid for uniform current on the surface)

iv) $J = \frac{dI}{dS}$ A/m² (practically, current is non-uniform throughout the surface).

$$\therefore dI = J \cdot ds$$

$$\Rightarrow \boxed{\int_S J \cdot ds} A$$

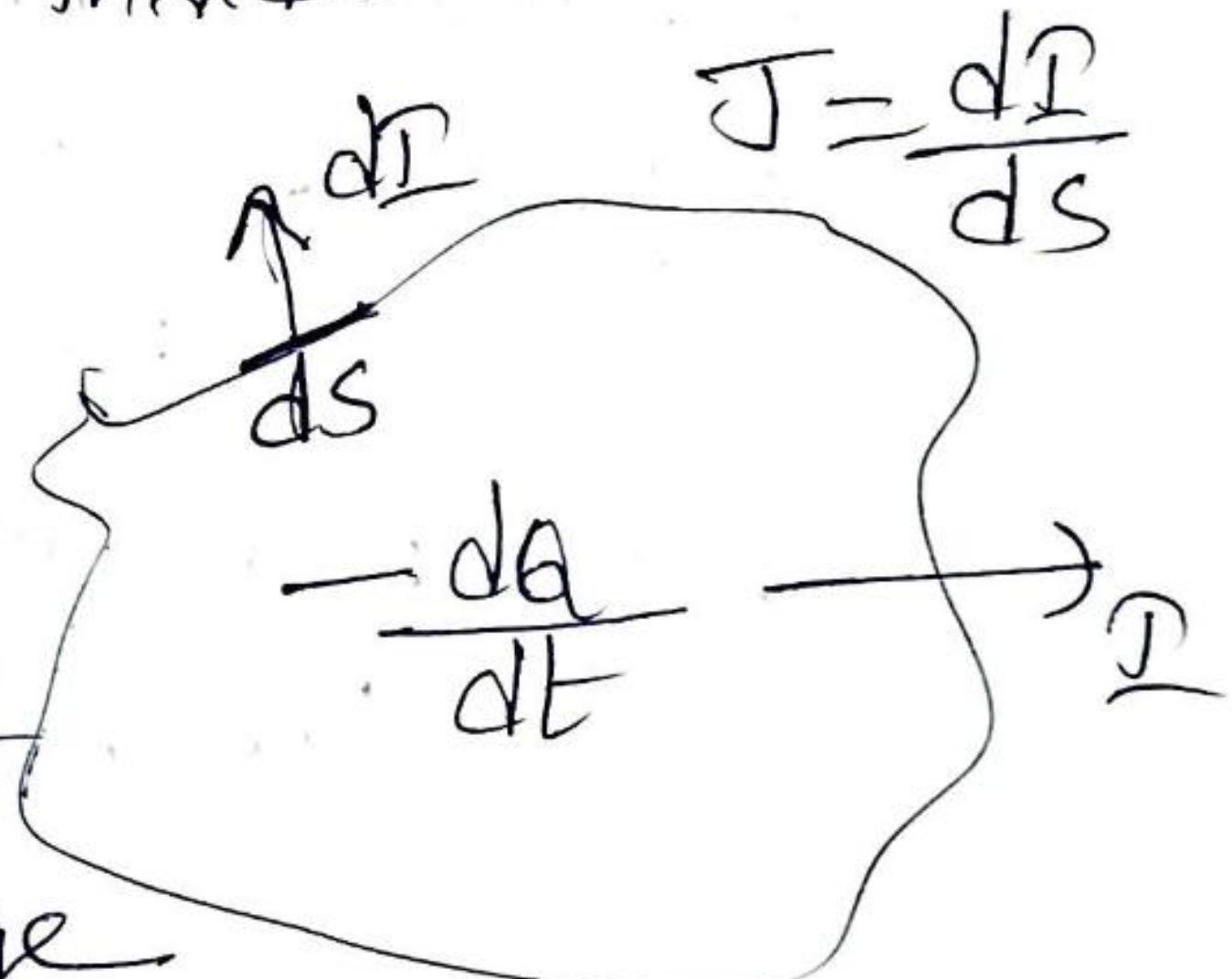
Statement for equation of continuity:

The net outward flow of charges must be equal to continuous decrease of positive charges inside the closed

surface.

$$\text{i.e. } I = -\frac{dQ}{dt}$$

$$\int_S J \cdot ds = -\frac{dQ}{dt}; \text{ a-point charge}$$



For most practical configuration i.e. volume:

$$Q = \int_V \rho_v dv$$

$$\therefore \int_S J \cdot ds = - \int_V \frac{\partial \rho_v}{\partial t} dv$$

$$\text{Use divergence theorem: } \int_S \vec{D} \cdot ds = \int_V (\nabla \cdot \vec{D}) dv$$

$$\therefore \int_V (\nabla \cdot \vec{J}) dV = - \int_V \frac{\partial \rho_v}{\partial t} dV$$

$$\therefore \boxed{\nabla \cdot \vec{J} = -\frac{\partial \rho_v}{\partial t}} \rightarrow \text{for time-varying fields}$$

• But, for static fields : ρ_v - constant $\therefore \frac{\partial \rho_v}{\partial t} = 0$

$$\therefore \boxed{\nabla \cdot \vec{J} = 0} \rightarrow \text{for static fields.}$$

Conduction Current Density:

- If the current flows through the conductors, it is called as conduction current.
- A conductor is characterized by large amount of free electrons that provide conduction current due to an impressed electric field.

$$\therefore F = -e\vec{E}$$

• An electron having mass m , \vec{E} , mobility μ .

$$\text{Thus, } \frac{m\mu}{\gamma} = -e\vec{E} \quad \textcircled{2}$$

$$\mu = \frac{-e\gamma}{m}\vec{E} \quad \textcircled{3}$$

where γ - average time interval b/w the collisions.

• if there are ' n ' no. of electrons per unit volume,

$$\rho_v = -ne \quad \textcircled{4}$$

$$\therefore \text{current density } (\vec{J}) = \rho_v \mu = (-ne) \left(\frac{-e\gamma}{m} \vec{E} \right)$$

$$\Rightarrow J = \frac{n e \bar{v}}{m} \bar{E} \quad (16)$$

$\therefore [J = \sigma \bar{E}]$ — ohm's law for electrostatic fields. (point form of ohm's law).

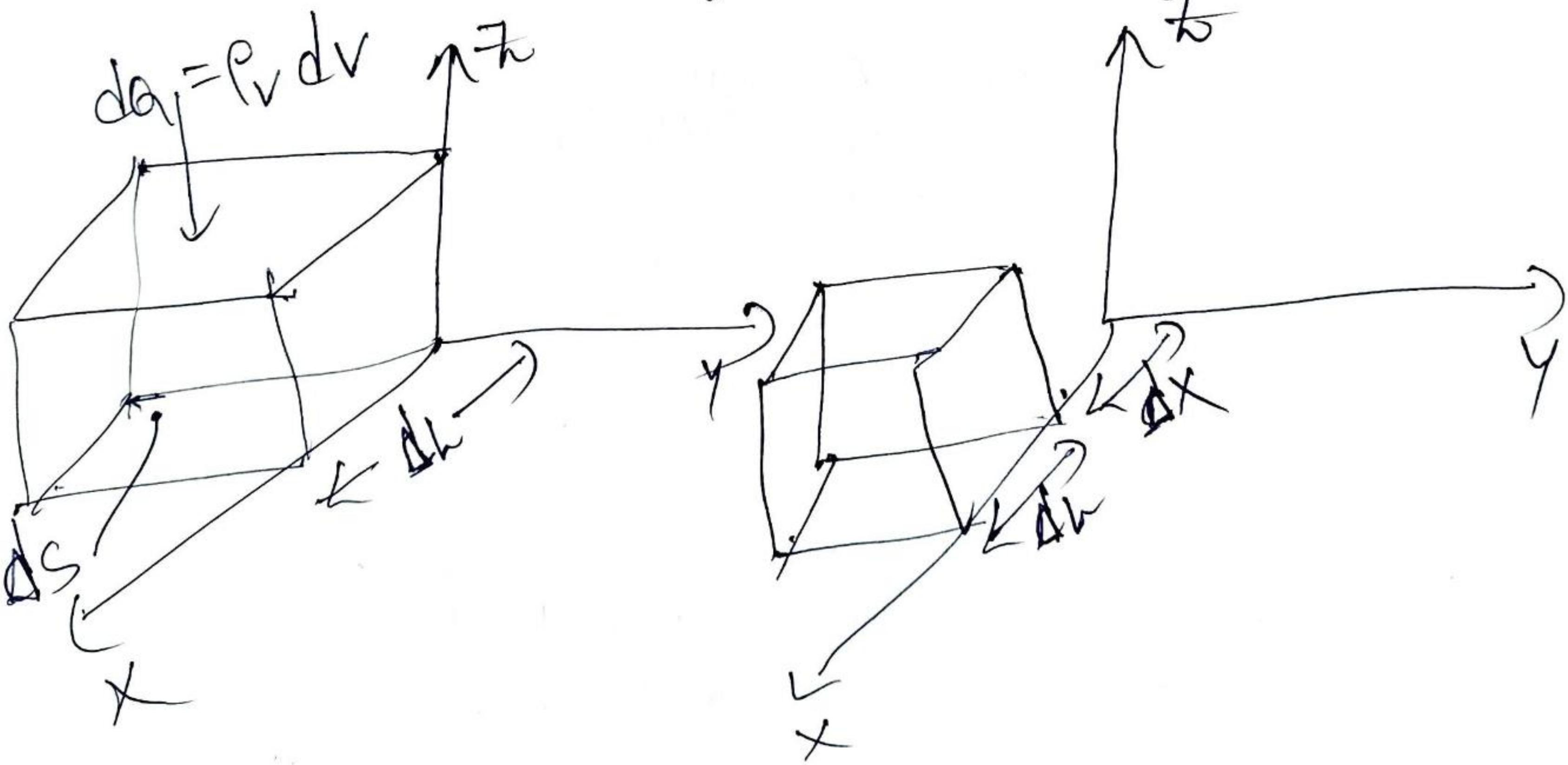
where $\sigma = \frac{n e \bar{v}}{m}$ (conductivity of the material)

J — conduction current density (A/m^2).

$\therefore [J = \sigma \bar{E}]$ — Equation of conduction current density.

Convection current density:

- if the current flows in insulators like liquids, rarefied gases etc.
- It does not require any conductors
- It does not obey the ohm's law.
- ex: current flow in vacuum tube by using beam of electrons (electron bunches).



→ consider the bunch of charge element

$$dQ = \rho_v dv = \rho_v ds dh$$

if the block moves dx in time dt

$$dI = \frac{da}{dt} = \frac{\rho_v ds dx}{dt} \quad (\text{since } dh = dx)$$

$$dI = \rho_v ds \cdot v_x \quad (\text{where velocity in } x\text{-direction})$$

$$\Rightarrow \frac{dI}{ds} = \rho_v \cdot v_x \quad \left(v_x = \frac{dx}{dt} \right).$$

$$\therefore \boxed{J_v = \rho_v \cdot v_x} \rightarrow \text{convection current density}$$

Dielectric constant: (or) Relative permittivity:

(i) If two charges q_1 and q_2 , separated by a distance r , in vacuum, then electrostatic force between them is:

$$F_v = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r^2} \rightarrow ① \quad (\text{since Coulomb's law}).$$

(ii) Now, when the same charges with same separation placed in a medium of absolute permittivity (ϵ), then electrostatic force between them is:

$$F_m = \frac{1}{4\pi\epsilon} \frac{q_1 q_2}{r^2} = \frac{1}{4\pi\epsilon_0\epsilon_r} \frac{q_1 q_2}{r^2} \rightarrow ②.$$

∴ let $\frac{F_v}{F_m} = \frac{\left(\frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r^2}\right)}{\left(\frac{1}{4\pi\epsilon_0\epsilon_r} \frac{q_1 q_2}{r^2}\right)} = \epsilon_r \quad \left[\because \epsilon_r = \frac{F_v}{F_m} \right]$

definition: dielectric constant of a medium is defined as the ratio of electrostatic force between 2 point charges when placed in vacuum to the force between the same charges placed in a medium.

Poisson's & Laplace Equations:

(17)

$$\rightarrow \text{point form: } \nabla \cdot \vec{D} = \rho_v \quad \text{--- (1)}$$

$$\vec{D} = \epsilon \vec{E} \quad \text{--- (2)}$$

$$\vec{E} = -\nabla V \quad \text{--- (3)}$$

substituting (2) & (3) in (1)

$$\nabla \cdot \epsilon \vec{E} = \rho_v$$

$$\nabla \cdot \epsilon (-\nabla V) = \rho_v$$

$$\nabla \cdot \nabla V = -\frac{\rho_v}{\epsilon}$$

$$\boxed{\nabla^2 V = -\frac{\rho_v}{\epsilon}} \rightarrow \text{poisson's equation.}$$

$$\text{if } \rho_v = 0 \Rightarrow \boxed{\nabla^2 V = 0} \rightarrow \text{laplace's equation.}$$

Note:- (1) $\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2}$ (Cartesian)

(2) $\nabla^2 V = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial V}{\partial r} \right) + \frac{1}{r^2} \left(\frac{\partial^2 V}{\partial \theta^2} \right) + \frac{\partial^2 V}{\partial z^2}$ (cylindrical)

(3) $\nabla^2 V = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2}$ (spherical)

Note:- (1) $\nabla \cdot \vec{D} = \rho_v$ — Maxwell's 1st equation

(2) $\nabla \times \vec{E} = 0$ — Maxwell's 2nd equation

(3) $\nabla V = -E$ — potential gradient.

(4) $\nabla^2 V = -\frac{\rho_v}{\epsilon_0} \Rightarrow \text{laplace's equation}$
 $(\rho_v = 0)$.

Capacitors & its types:-

→ Capacitance: It is the charge required to develop the potential between the two oppositely charged surfaces/plates. i.e $C = \frac{Q}{V}$ mF/μF/nF. since $1F = \frac{1C}{1V}$.

(B) parallel-plate capacitor:

→ It consists of 2 parallel plates separated by a distance (d).
 • The space between plates is filled with dielectric of permittivity (ϵ).

• Let A — area of cross section of plates.

$$\rightarrow As \ C = \frac{Q_{enc}}{V} \quad \text{--- (1)}$$

i) Q_{en} (charge enclosed):

$$\cdot \text{Using Gauss's law: } Q_{en} = \int_S D \cdot dS$$

$$Q_{en} = P_s \cdot A \quad \text{--- (2)}$$

where P_s — surface charge density of plate (C/m^2)

ii) potential: we know: $V = \int_{\text{initial}}^{\text{final}} E \cdot dL$

$$\text{where } \bar{E} = \bar{E}_{\text{plate 1}} + \bar{E}_{\text{plate 2}} = \frac{P_s}{2\epsilon_0} + \frac{P_s}{2\epsilon_0} = \frac{P_s}{\epsilon_0} \text{ V/m}$$

(since \vec{E} for surface charge configuration = $\frac{\rho_s}{2\epsilon_0} \hat{y}$)

$$\therefore \text{potential } V = - \int_d^0 \frac{\rho_s}{\epsilon_0} a_z \cdot dz a_z \quad (\text{since } dh = dz a_z)$$

$$= - \frac{\rho_s}{\epsilon_0} (0-d) = \frac{\rho_s d}{\epsilon_0} \quad \text{--- (3)}$$

• substitute (2) & (3) in (1) gives,

$$\text{capacitance } C = \frac{\rho_s \cdot A}{\frac{\rho_s d}{\epsilon_0}} = \frac{\epsilon_0 A}{d}$$

$$\therefore \boxed{C = \frac{\epsilon_0 A}{d} \text{ Farads}} \quad \text{or} \quad \boxed{C = \frac{\epsilon A}{d} \text{ Farads}}$$

where $\epsilon = \epsilon_0 \epsilon_r$.

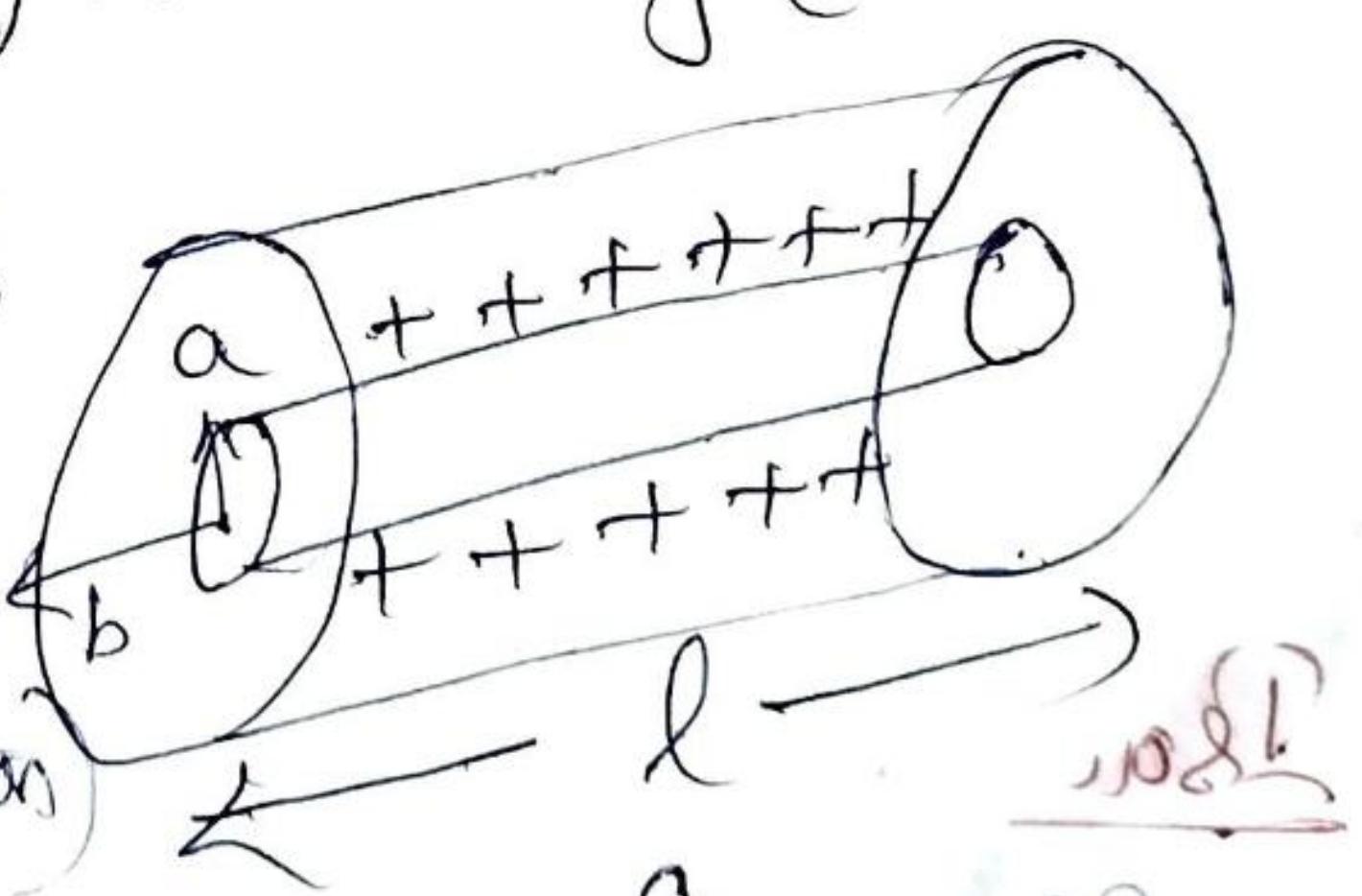
(ii) Coaxial Cable Capacitor:

→ Consider length (l) of two coaxial conductors of inner radius (a) and outer radius (b).
 • The space between the conductors is filled with homogeneous dielectric with permittivity (ϵ).

$$(i) Q = \int_{\text{line}} \rho_h dh \quad (\text{Since, it's of line})$$

$$= \rho_h \cdot h \quad \text{--- (2)}$$

charge configuration



$$(ii) V = - \int_{\text{initial}}^{\text{final}} \vec{E} \cdot d\vec{l}$$

$$= - \int_{l_1}^{l_2} \frac{\rho_h}{2\pi\epsilon_0 \rho} a_p \cdot d\theta a_p = - \frac{\rho_h}{2\pi\epsilon_0} \int_{l_1}^{l_2} \frac{1}{\rho} d\rho \quad \text{--- (3)}$$

$$= -\frac{\rho_h}{2\pi\epsilon_0} \left[\ln \frac{a}{b} \right]$$

(consider E for line charge)

$$= -\frac{\rho_h}{2\pi\epsilon_0} \left(\ln \left(\frac{a}{b} \right) \right) = \frac{\rho_h}{2\pi\epsilon_0} \ln \left(\frac{b}{a} \right) \quad \text{--- (3)}$$

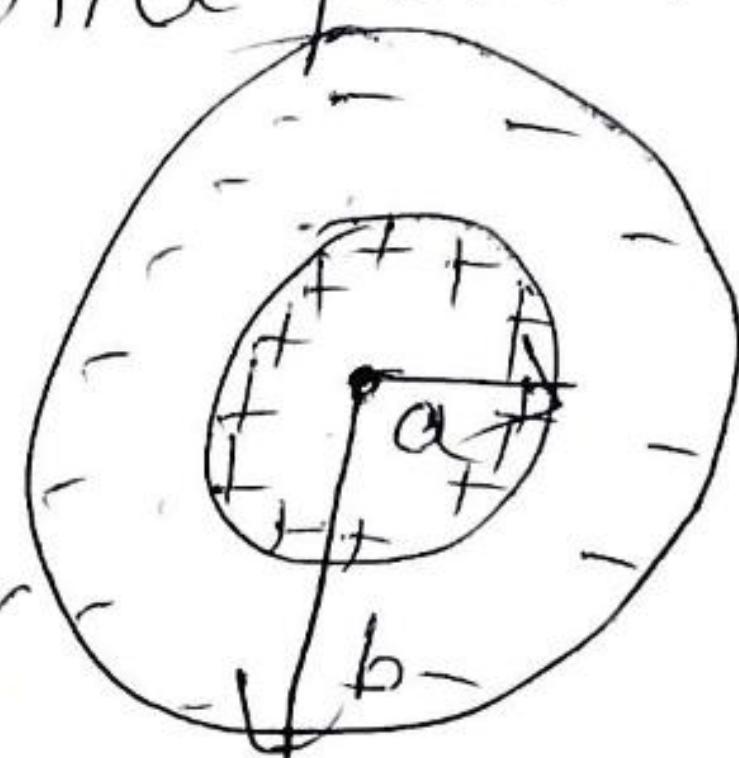
Substitute (2) & (3) in (1)

$$C = \frac{Q}{V} = \frac{\rho_h \cdot h}{\frac{\rho_h}{2\pi\epsilon_0} \ln \left(\frac{b}{a} \right)} = \frac{2\pi\epsilon_0 h}{\ln \left(\frac{b}{a} \right)} \text{ Farad}$$

Spherical Capacitor:

Consider, 2 concentric spherical conductors with inner sphere radius (a) & outer sphere radius (b), separated by dielectric medium with permittivity ϵ .

$$\text{Let } C = \frac{Q_{en}}{V} = \frac{Q}{-\int_{\text{initial}}^{\text{final}} E \cdot dL} = \frac{Q}{\int_a^b \frac{Q}{4\pi\epsilon_0 r^2} dr}$$



(E — for point charge)

$$= \frac{Q}{\frac{4\pi\epsilon_0}{a} \int_a^b \frac{1}{r^2} dr}$$

$$= \frac{4\pi\epsilon_0}{\left(\frac{1}{a} - \frac{1}{b} \right)} = \frac{4\pi\epsilon_0}{\left(\frac{1}{a} - \frac{1}{b} \right)} = \frac{4\pi\epsilon_0 ab}{b-a} \text{ Farad}$$

Isolated Capacitor:

For an isolated capacitor i.e. $b \rightarrow \infty$ (Subcase of spherical capacitor)

$$\therefore [C = 4\pi\epsilon_0 a] \text{ Farad}$$