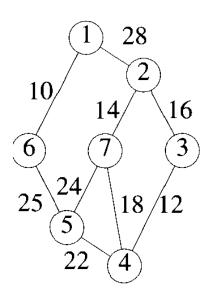
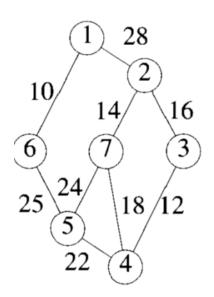
Minimum Spanning Tree

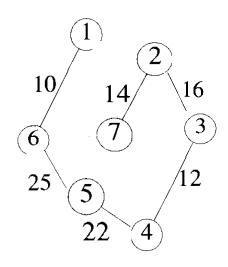


 Kruskal's approach to the construction of minimum spanning tree starts with an empty spanning tree and adds the minimum cost edge to the tree if it does not form a cycle.



- Greedy Principle/Criterion
- Selection: Minimum Cost Edge
- Feasibility: Does not form a cycle, if added to the spanning tree.

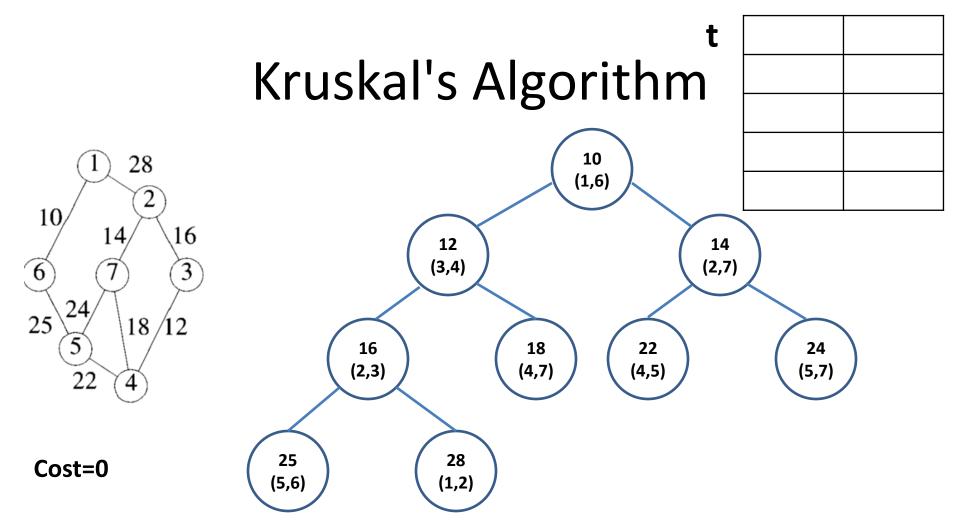




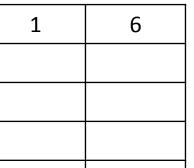
Minimum Cost Spanning Tree

- A min-heap of edges and their costs is maintained for obtaining the next least cost edge in log|E| time.
- To find out whether a cycle is formed by adding an edge, we maintain Disjoint set ADT of vertices.
- Initially, each vertex is in its own set.

- An edge is discarded if both of its vertices are in the same set.
- Whenever an edge is added, the sets containing its vertices are merged.
- A matrix with two columns is used to store the edges selected.

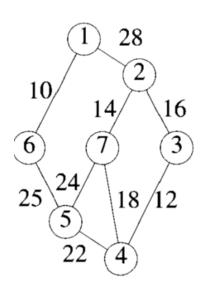


{1}, {2}, {3}, {4}, {5}, {6}, {7}



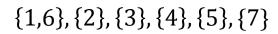
24

(5,7)



Cost=10







18

(4,7)

10

16

(2,3)

25

(5,6)



12

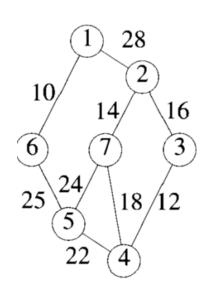
(3,4)

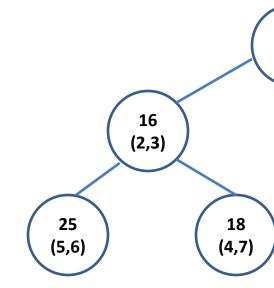


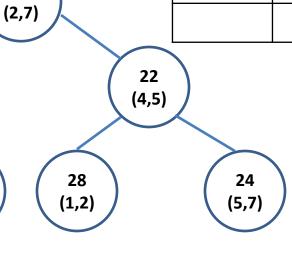
14

(2,7)

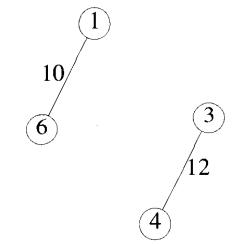
1	6
3	4





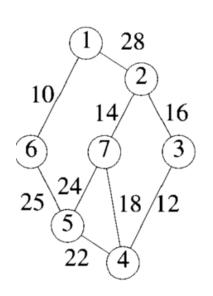


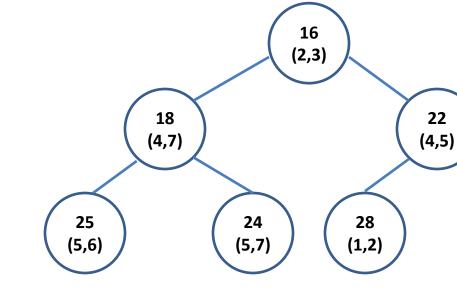
Cost=22



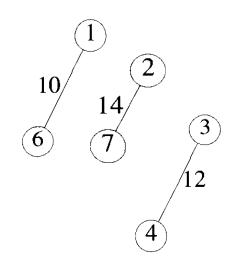
14

1	6
3	4
2	7





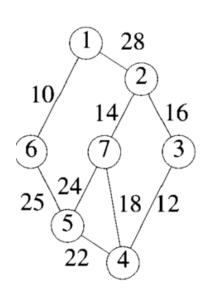
Cost=36

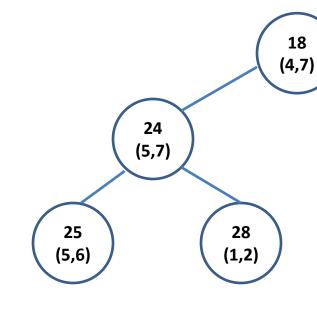


1	6
3	4
2	7
2	3

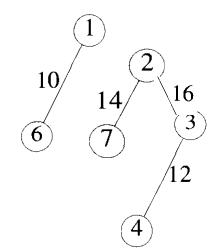
22

(4,5)

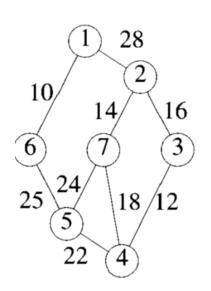


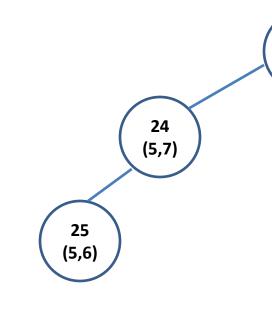


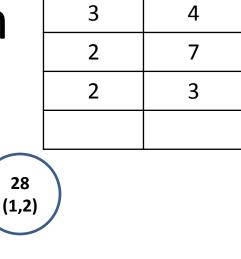




1	6
3	4
2	7
2	3

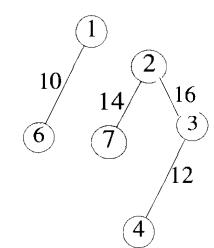






Cost=52

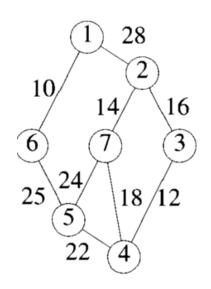
{1,6}, {2,7,3,4}, {5}

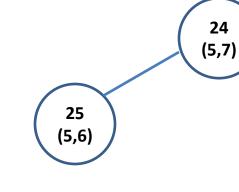


22

(4,5)

1	6
3	4
2	7
3	4
4	5

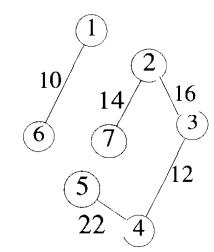


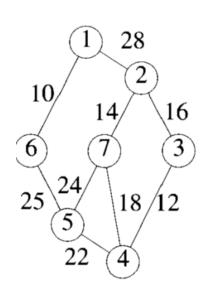


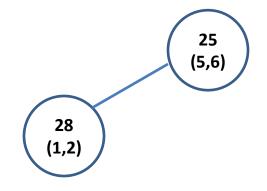
	\
28	1
(1,2)	

Cost=74

{1,6}, {2,7,3,4,5}

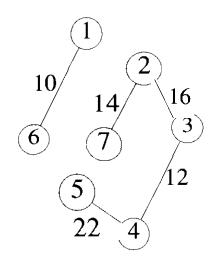






Cost=74

{1,6}, {2,7,3,4,5}





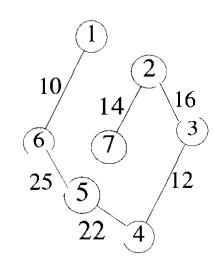
1	6
3	4
2	7
3	4
4	5
5	6

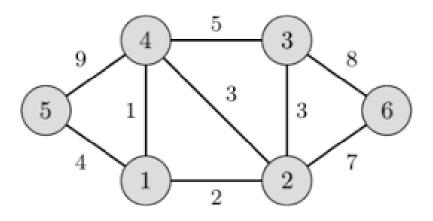
Cost=89

10

{1,6,2,7,3,4,5}

18





```
Algorithm Kruskal(E,cost,n,t)

//E is the set of edges in G

//n is the number of vertices

//cost is a matrix such that cost[u,v] is the cost of the

//edge(u,v)

//t is the array of edges included in the MST.
```

```
construct the min heap of edges in E based on cost;
i:=1;mincost:=0;
while (i < n and heap not empty) do
   Delete minimum cost edge (u,v) from the heap
   j:=Find(u);k:=Find(v);
   if (j \neq k) then
       t[i,1]:=u;t[i,2]:=v;
       mincost:=mincost+cost[u,v];
       Union(j,k);
       i:=i+1;
if (i \neq n) then write ("No Spanning Tree");
return mincost;
```

- The complexity of the algorithm is determined by the Heap operations.
- Every time a delete-min is performed, the complexity is $\log |E|$
- We delete and inspect at most |E| edges.
- Hence $|E| \log |E|$

