

# Tutorial – 2

## Intro to Processor Architecture

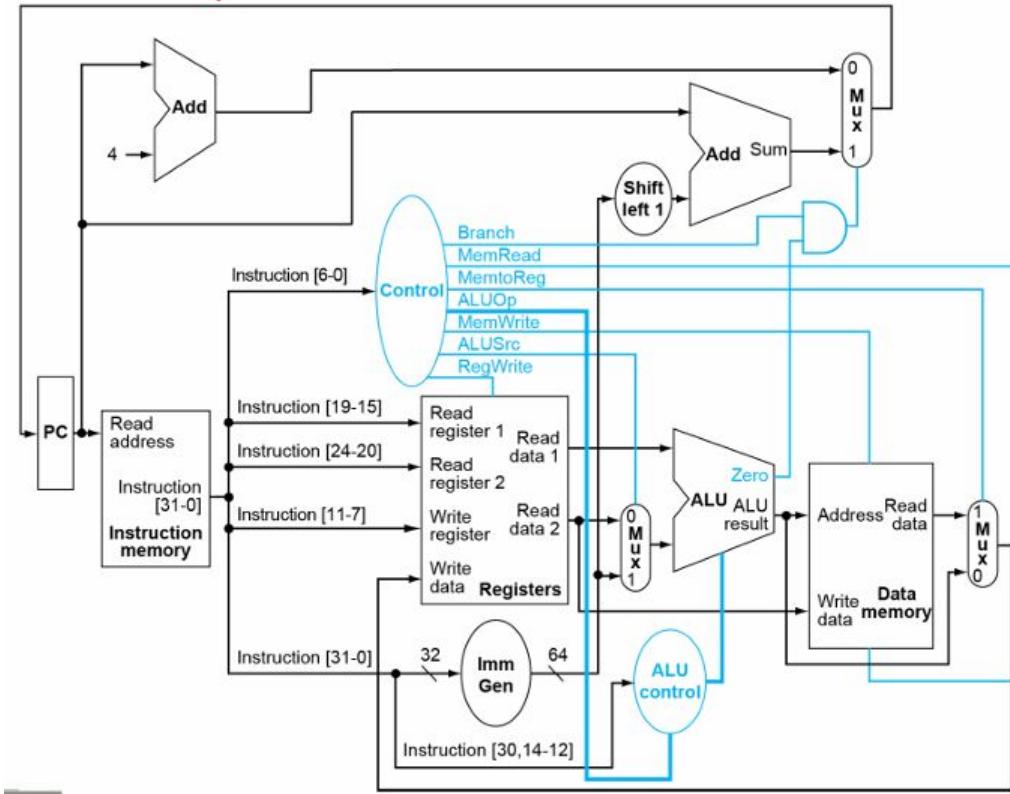
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# Overview

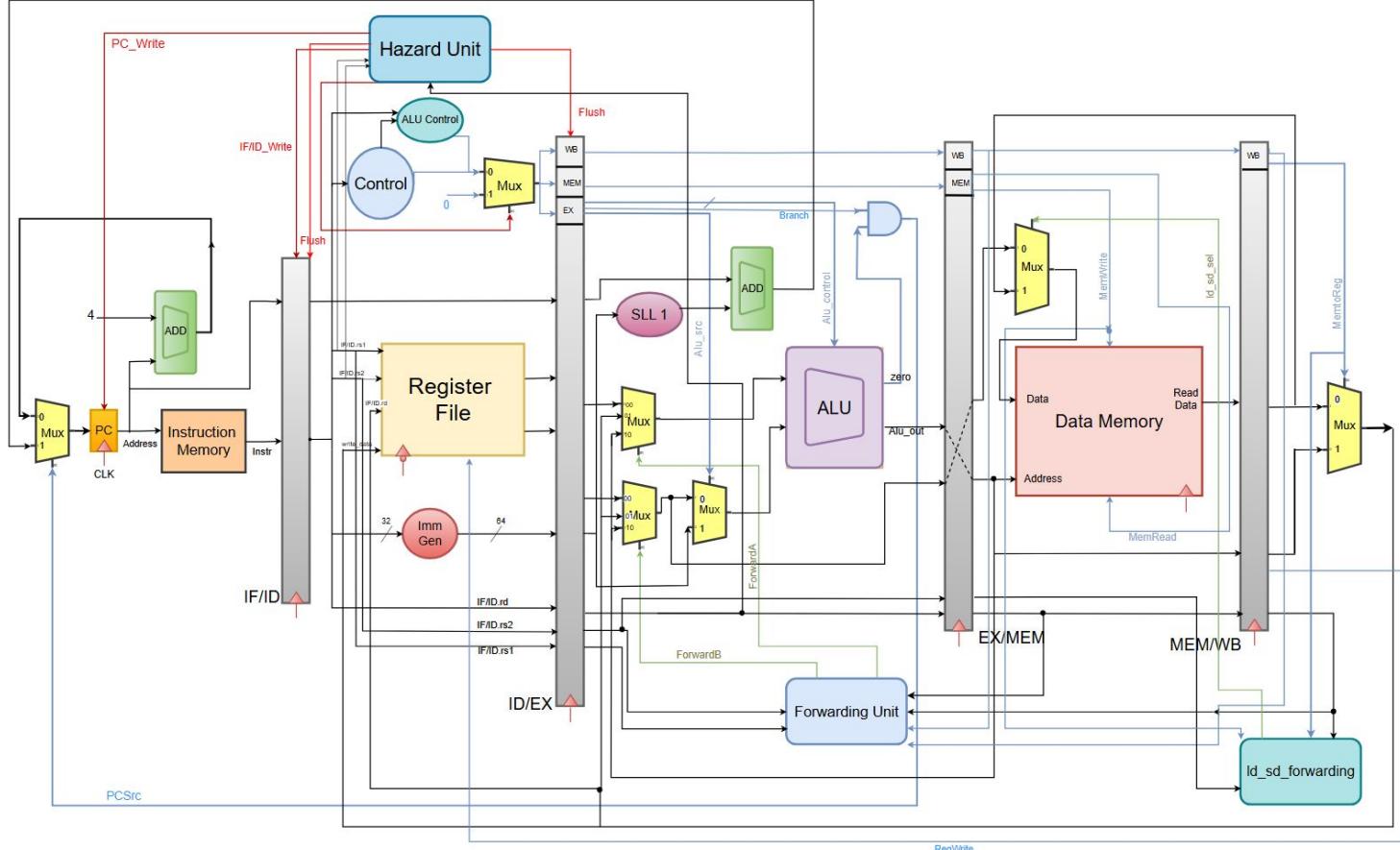
- In the previous tut..
- RISC vs CISC
- Instructions and various formats
- ALU implementation
- Carry vs Overflow flags
- Assembly language

In the previous tut..

# Sequential Design



# Pipelined Processor



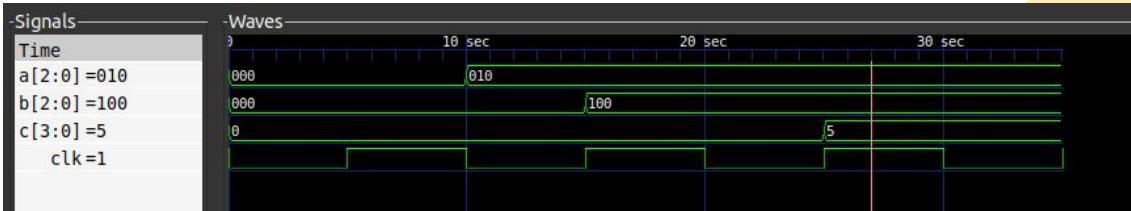
# Blocking vs Non-blocking statement {Example}

## 1. Blocking

```
initial begin
    a = 3'b000; // Default initial value for a
    b = 3'b000; // Default initial value for b
    c = 4'b0000; // Default initial value for c

    #5;
    // NOTE : Remember the delays in here -> check gtkwave !
    a = #5 3'b010;
    b = #5 3'b100;
    c = #10 4'b0101;

    #10;
    $finish;
end
```

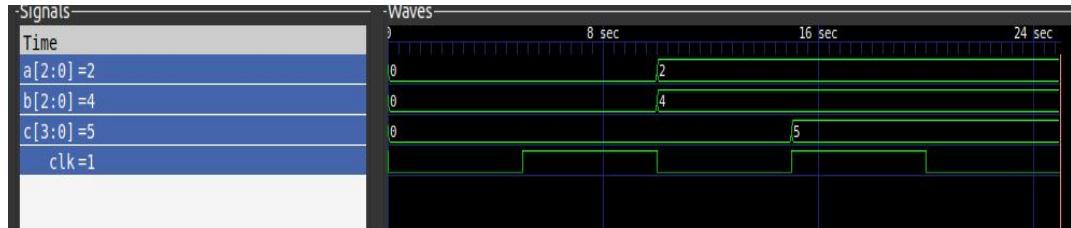


## 2. Non blocking

```
initial begin
    a = 3'b000; // Default initial value for a
    b = 3'b000; // Default initial value for b
    c = 4'b0000; // Default initial value for c

    #5;
    // NOTE : Remember the delays in here -> check gtkwave !
    a <= #5 3'b010;
    b <= #5 3'b100;
    c <= #10 4'b0101;

    #10;
    $finish;
end
```



# Behavioural vs Structural Code

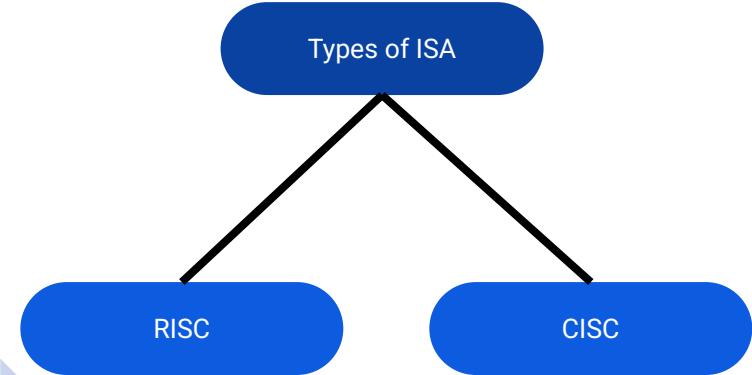
## Behavioral Verilog:

- Abstraction Level: Behavioral Verilog focuses on describing the functionality or behavior of a digital circuit without specifying its physical structure. It emphasizes what the module or system does rather than how it is implemented.
- Constructs: Common constructs include procedural blocks such as always and initial, and high-level constructs like if-else statements and loops. Register transfer level (RTL) modeling is often used to describe data flow and control flow within the design.

## Structural Verilog:

- Abstraction Level: Structural Verilog, on the other hand, is concerned with specifying the physical components and interconnections of a digital design. It provides a detailed representation of the hardware components, such as gates, multiplexers, and flip-flops, and how they are interconnected.
- Constructs: Modules and instances of these modules are used to represent different hardware components. Connectivity between these instances is established using wires and buses. Structural Verilog is closer to the actual hardware implementation.

# Instruction Set Architecture (ISA)



## What is an ISA?

Just an interface between hardware and software defining a set of instructions a processor can execute

## Components:

Operations, data types, registers, addressing modes and memory access mechanisms used by the CPU

# Reduced Instruction Set Computer (RISC)



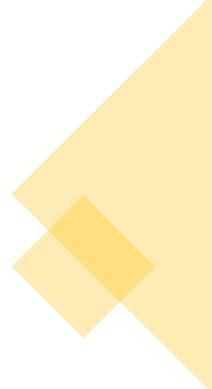
- **Fixed-length instructions:** Instruction fetching and decoding simpler and faster.
- **Load/store architecture:** Only load/store instructions access memory, arithmetic operations occur only between registers.
- **Compiler is simpler:** Since fewer instruction types and a more straightforward design, the compiler can be simpler and more efficient

# Complex Instruction Set Computer (CISC)



- **Variable-length instructions:** More flexibility but complex instruction decoding process.
- **Memory-to-memory operations:** Instructions can directly access memory locations, reducing the number of instructions required for complex operations.
- **Compiler is complex:** The compiler for CISC architectures tends to be more complex compared to RISC.

# Instructions & its formats



# Registers in RISC V

x0: the constant value 0

x1: return address

x2: stack pointer

x3: global pointer

x4: thread pointer

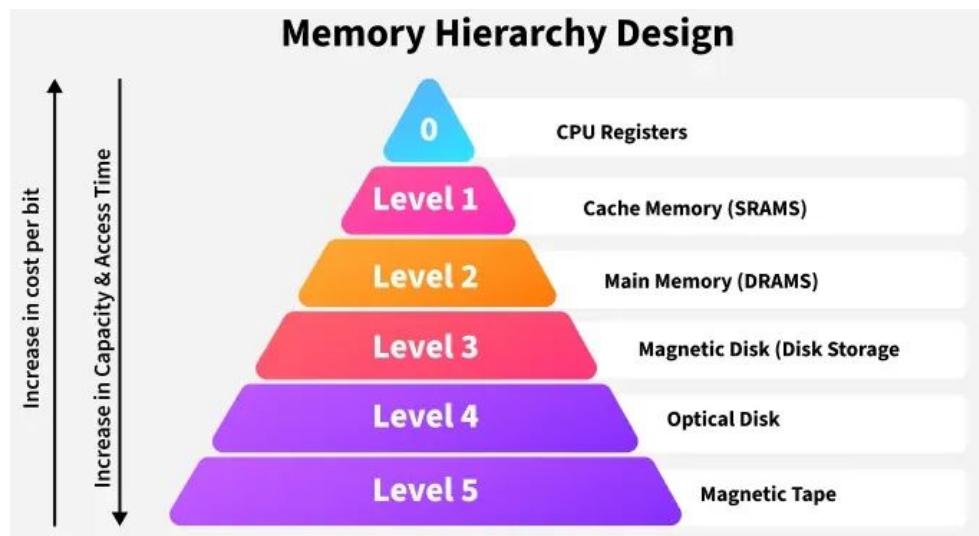
x5 – x7, x28 – x31: temporaries

x8: frame pointer

x9, x18 – x27: saved registers

x10 – x11: function arguments/results

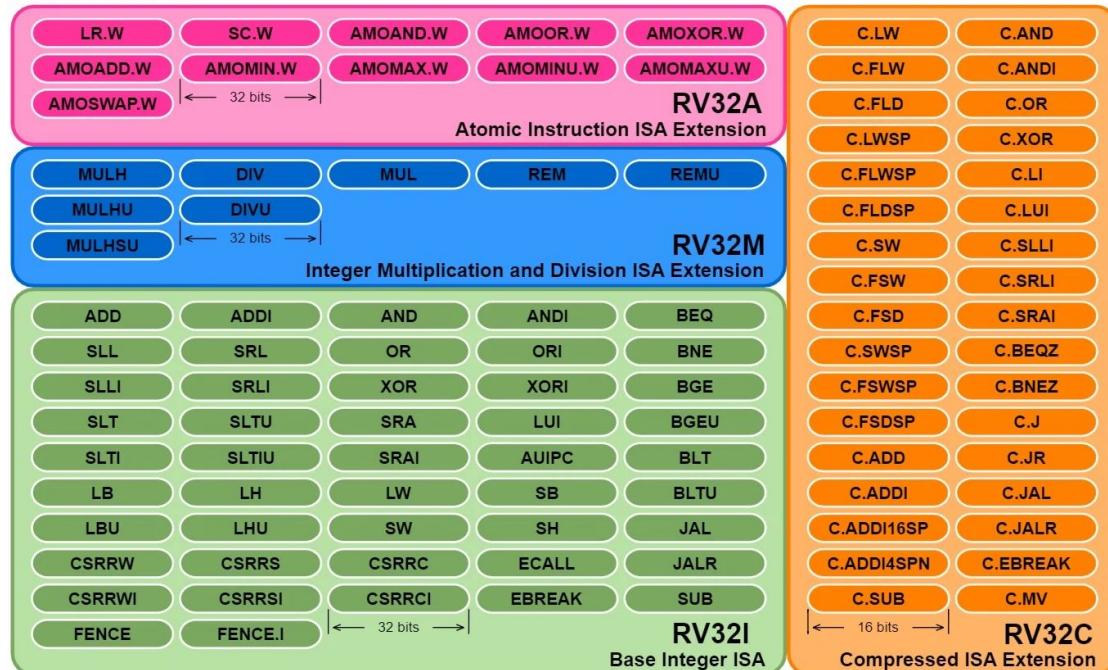
x12 – x17: function arguments



- Registers are faster to access than memory.
- For operating in memory we need load and stores but between registers, we don't need to (less instructions to be executed)
- Better to include more frequently used variables inside registers

# Instruction field

## RV32IMAC



**opcode:** operation code

**rd:** destination register

**funct3:** 3-bit function code

**rs1:** the first source register

**rs2:** the second source register

**funct7:** 7-bit function code

# R format instructions

funct7	rs2	rs1	funct3	rd	opcode
7 bits	5 bits	5 bits	3 bits	5 bits	7 bits

Inst	Name	FMT	Opcode	funct3	funct7	Description (C)	Note
add	ADD	R	0110011	0x0	0x00	$rd = rs1 + rs2$	
sub	SUB	R	0110011	0x0	0x20	$rd = rs1 - rs2$	
xor	XOR	R	0110011	0x4	0x00	$rd = rs1 \wedge rs2$	
or	OR	R	0110011	0x6	0x00	$rd = rs1 \mid rs2$	
and	AND	R	0110011	0x7	0x00	$rd = rs1 \& rs2$	
sll	Shift Left Logical	R	0110011	0x1	0x00	$rd = rs1 << rs2$	
srl	Shift Right Logical	R	0110011	0x5	0x00	$rd = rs1 >> rs2$	
sra	Shift Right Arith*	R	0110011	0x5	0x20	$rd = rs1 >> rs2$	msb-extends
slt	Set Less Than	R	0110011	0x2	0x00	$rd = (rs1 < rs2)?1:0$	
sltu	Set Less Than (U)	R	0110011	0x3	0x00	$rd = (rs1 < rs2)?1:0$	zero-extends

Also called register type instruction because all the operands involved are in registers.

These instructions perform arithmetic and logical operations entirely within the CPU without direct memory access.

# I format instructions

immediate	rs1	funct3	rd	opcode
12 bits	5 bits	3 bits	5 bits	7 bits

addi	ADD Immediate	I	0010011	0x0		rd = rs1 + imm	
xori	XOR Immediate	I	0010011	0x4		rd = rs1 ^ imm	
ori	OR Immediate	I	0010011	0x6		rd = rs1   imm	
andi	AND Immediate	I	0010011	0x7		rd = rs1 & imm	
slli	Shift Left Logical Imm	I	0010011	0x1	imm[5:11]=0x00	rd = rs1 << imm[0:4]	
srali	Shift Right Logical Imm	I	0010011	0x5	imm[5:11]=0x00	rd = rs1 >> imm[0:4]	
srai	Shift Right Arith Imm	I	0010011	0x5	imm[5:11]=0x20	rd = rs1 >> imm[0:4]	
slti	Set Less Than Imm	I	0010011	0x2		rd = (rs1 < imm)?1:0	msb-extends
sltiu	Set Less Than Imm (U)	I	0010011	0x3		rd = (rs1 < imm)?1:0	zero-extends
lb	Load Byte	I	0000011	0x0		rd = M[rs1+imm][0:7]	
lh	Load Half	I	0000011	0x1		rd = M[rs1+imm][0:15]	
lw	Load Word	I	0000011	0x2		rd = M[rs1+imm][0:31]	
lbu	Load Byte (U)	I	0000011	0x4		rd = M[rs1+imm][0:7]	zero-extends
lhu	Load Half (U)	I	0000011	0x5		rd = M[rs1+imm][0:15]	zero-extends

# I format instructions

immediate	rs1	funct3	rd	opcode
12 bits	5 bits	3 bits	5 bits	7 bits

I format instructions are called immediate type instructions because one of the operand is just an immediate constant.

Unlike R type instructions here we only use 1 source register, one destination register and a 12 bit immediate value

The advantage of i type instruction is that they reduce the need of an extra register and therefore additional instructions are not required.

# S format instructions

imm[11:5]	rs2	rs1	funct3	imm[4:0]	opcode
-----------	-----	-----	--------	----------	--------

7 bits

5 bits

5 bits

3 bits

5 bits

7 bits

sb	Store Byte	S	0100011	0x0		M[rs1+imm][0:7] = rs2[0:7]
sh	Store Half	S	0100011	0x1		M[rs1+imm][0:15] = rs2[0:15]
sw	Store Word	S	0100011	0x2		M[rs1+imm][0:31] = rs2[0:31]

S type instructions are also called store type because they are used to store the data from register into the memory.

They don't write the result to rd. They just specify rs1(base mem address) rs2 (data to be stored) and the 12 bit immediate value that holds the offset that has to be added to the base address.

# B type instructions

imm[11:5]	rs2	rs1	funct3	imm[4:0]	opcode
7 bits	5 bits	5 bits	3 bits	5 bits	7 bits

beq	Branch ==	B	1100011	0x0		if(rs1 == rs2) PC += imm	
bne	Branch !=	B	1100011	0x1		if(rs1 != rs2) PC += imm	
blt	Branch <	B	1100011	0x4		if(rs1 < rs2) PC += imm	
bge	Branch ≥	B	1100011	0x5		if(rs1 ≥ rs2) PC += imm	
bltu	Branch < (U)	B	1100011	0x6		if(rs1 < rs2) PC += imm	zero-extends
bgeu	Branch ≥ (U)	B	1100011	0x7		if(rs1 ≥ rs2) PC += imm	zero-extends

B type instructions are called branch type instructions because they are used to change the flow of the program based on a condition

Takes rs1 and rs2 and depending on the condition they branch to a target instruction

We specify the target instruction based on the immediate offset

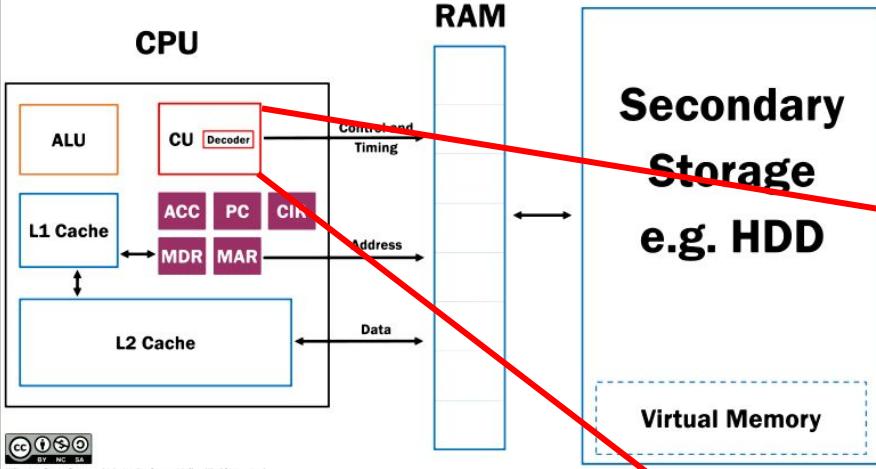
# J type instructions

imm[20 10:1 11 19:12]				rd	opcode
jal	Jump And Link	J	1101111		rd = PC+4; PC += imm

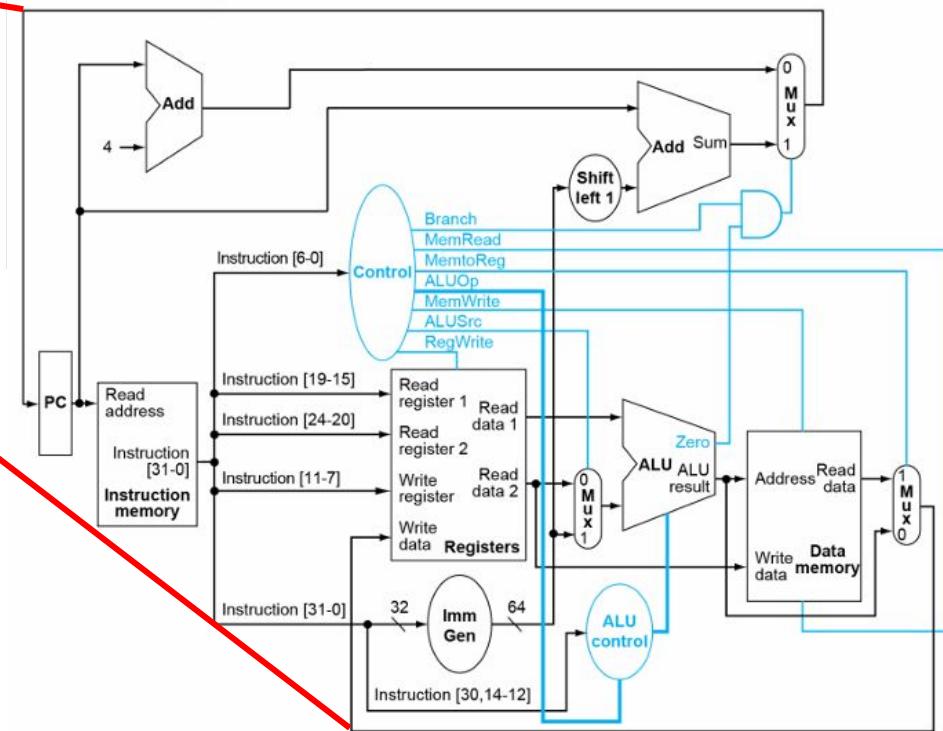
- Only jal uses J-type format (Jump And Link)
- Purpose: unconditional PC-relative jump + optionally save return address ( $rd = PC + 4$ )
- Immediate size: 20-bit signed immediate
- Common usage: “*jal ra, label*” for function calls, and “*jal x0, label*” for plain jump (no link)

# **ALU Implementation**

# Computer Systems - Von Neumann Architecture



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Carry	Overflow
<ul style="list-style-type: none"> <li>Only relevant for unsigned arithmetic.</li> <li>Broadly two cases where this flag is set -           <ol style="list-style-type: none"> <li>Carry when numbers are added :  <math>&gt;&gt;1111 + 0001 = 1 \text{ (carry)} + 0000</math> </li> <li>Carry when numbers are subtracted :  <math>&gt;&gt;0000 - 0001 = 1 \text{ (borrow)} + 1111</math> </li> </ol> </li> <li>Otherwise, the carry flag is turned off -  <math>0111 + 0001 = 1000</math>  <math>1000 - 0001 = 0111</math> </li> <li>Is irrelevant for signed arithmetic.</li> <li><b>How do you determine carry flag?</b></li> </ul>	<ul style="list-style-type: none"> <li>Only relevant for signed arithmetic.</li> <li>Broadly two cases where this flag is set -           <ol style="list-style-type: none"> <li>Addition of two positive numbers resulted in a negative number :  <math>&gt;&gt;0100 + 0100 = 1000</math> </li> <li>Addition of two negative numbers resulted in a positive number :  <math>&gt;&gt;1000 + 1000 = 0000</math> </li> </ol> </li> <li>Otherwise the overflow flag is turned off. Equivalently, irrelevant for unsigned arithmetic.</li> <li><b>How do you determine overflow flag?</b></li> </ul>

# Assembly language

# 1. Sum of first N natural numbers

```
1      addi x1, x0, 30    // n = 30
2      addi x2, x0, 0    // sum = 0
3      addi x3, x0, 1    // i = 1 (Loop variable)
4      add x10, x3, x0   // x10 = 1 (temp)
5 Loop: add x2, x2, x3   // sum += i
6      addi x3, x3, 1    // i++
7      sub x4, x3, x1    // i - n
8      beq x4, x10, 4    // if i == n, branch to Exit
9      beq x0, x0, -8    // branch to Loop (unconditional branch)
10 Exit:
```



## 2. Fibonacci Seq.

```
1      addi x1, x0, 10          // Calculate 8 Fibonacci numbers
2      addi x2, x0, 0           // Address for storing results
3      addi x3, x0, 0           // Fib(0) = 0
4      addi x4, x0, 1           // Fib(1) = 1
5      sd x3, 0(x2)            // Store Fib(0)
6      addi x2, x2, 1           // Increment address (changed from 8)
7      sd x4, 0(x2)            // Store Fib(1)
8      addi x2, x2, 1           // Increment address (changed from 8)
9      addi x5, x0, 2           // i = 2
10     fib_loop: beq x5, x1, 16 // If i==n, done
11     add x6, x3, x4          // Calculate next Fibonacci number
12     sd x6, 0(x2)            // Store result
13     addi x2, x2, 1           // Increment address (changed from 8)
14     addi x5, x5, 1           // i++
15     add x3, x0, x4          // a = b
16     add x4, x0, x6          // b = result
17     beq x0, x0, -14         // Loop back
18     fib_done: add x2, x0, x0 //iterating address for Loading
19     ld x10, 0(x2)            //put the series onto the registers (x10-x19)
20     ld x11, 1(x2)
21     ld x12, 2(x2)
22     ld x13, 3(x2)
23     ld x14, 4(x2)
24     ld x15, 5(x2)
25     ld x16, 6(x2)
26     ld x17, 7(x2)
27     ld x18, 8(x2)
28     ld x19, 9(x2)
```

### 3. Vector Addition

$N = 5$

$A = [1, 2, 3, 0, 0] @ 10$

$B = [7, 8, 9, 0, 0] @ 20$

$\text{Sum} = [8, 10, 12, 0, 0] @ 40$

```
1      addi x4, x0, 5      // x4 = 5
2      add x5, x4, x4      // x5 = 10
3      add x6, x5, x5      // x6 = 20
4      add x7, x6, x6      // x7 = 40
5      addi x10, x10, 1     // x10 = 1
6      addi x11, x0, 7      // x11 = 7
7      sd x10, 0(x5)       // store 1 at mem[10]
8      sd x11, 0(x6)       // store 7 at mem[20]
9      add x11, x11, x10    // x11 = 8
10     add x10, x10, x10    // x10 = 2
11     sd x10, 1(x5)       // store 2 at mem[11]
12     sd x11, 1(x6)       // store 8 at mem[21]
13     addi x10, x0, 3      // x10 = 3
14     addi x11, x0, 9      // x11 = 9
15     sd x10, 2(x5)       // store 3 at mem[12]
16     sd x11, 2(x6)       // store 9 at mem[22]
17 Loop: add x20, x5, x3    // calculate address to be accessed of A
18     add x21, x6, x3    // calculate address to be accessed of B
19     ld x22, 0(x20)      // Load A[i]
20     ld x23, 0(x21)      // Load B[i]
21     add x24, x22, x23    // compute sum
22     add x25, x7, x3    // calculate address to be accessed of C
23     sd x24, 0(x25)      // store the sum
24     addi x3, x3, 1      // increment Loop var
25     beq x4, x3, 4       // jump to Exit if loop var == 5
26     beq x0, x0, -18     // jump to Loop (unconditional)
27 Exit:  ld x15, 0(x7)     // Load C[0]
28     ld x16, 1(x7)       // Load C[1]
29     ld x17, 2(x7)       // Load C[2]
```

# References

1. Computer Architecture: A Quantitative Approach by Patterson, Hennessy and Kozyrakis 7th edition
2. [Carry vs Overflow](#)
3. [Immediate format in instructions](#)

# **Any Questions ?**