

# EC5.102: Information and Communication

(Lec-6)

## Channel coding-2

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# Vector spaces

# Preliminaries: Basics of vector spaces

- Vector space spanned by the given set of vectors
- A subspace of a vector space
- Linearly independent vectors
- Basis and dimension of a vector space
- Orthogonal subspaces

# Understanding vector space

- What is a vector space?

A space in which:

- Any two vectors can be “added”
- Or “scaled”

... **without leaving the space!**

(Note: To define a vector space, we need a few more properties.)

- Examples: Which of the following are vector spaces?

- X-Y plane

- Positive quadrant of X-Y plane

- $\mathcal{S} = \left\{ \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$

# Linear combination and vector space

- Linear combination of two vectors:

For two vectors  $v_1, v_2 \in \mathbb{R}^n$  consider the following two operations

- Multiply  $v_1$  or  $v_2$  by scalars  $a_1, a_2 \in \mathbb{R}$ :  $a_1 v_1$  and  $a_2 v_2$
- Add  $a_1 v_1$  and  $a_2 v_2$ :  $\underbrace{a_1 v_1 + a_2 v_2}$



**Linear combination of  $v_1$  and  $v_2$**

- Vector space  $V$  **spanned** by vectors  $v_1$  and  $v_2$  is defined as

$$\begin{aligned} V &:= \left\{ v \in \mathbb{R}^n \text{ such that } v = a_1 v_1 + a_2 v_2 \text{ for some } a_1, a_2 \in \mathbb{R} \right\} \\ &= \text{span}\{v_1, v_2\} \end{aligned}$$

- Vector space spanned by  $k$  vectors  $v_1, v_2, \dots, v_k$ :

$$\begin{aligned} V &:= \left\{ v \in \mathbb{R}^n \text{ s. t. } v = a_1 v_1 + a_2 v_2 + \dots + a_k v_k \text{ for some } a_1, \dots, a_k \in \mathbb{R} \right\} \\ &= \text{span}\{v_1, v_2, \dots, v_k\} \end{aligned}$$

# Subspace of a vector space

- A **subspace** of a vector space is a nonempty subset that satisfies the requirements of a vector space: Linear combinations stay in the subspace.

- Example:

- Suppose  $V = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$  and  $W = \text{span} \left\{ \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 4 \\ 0 \end{bmatrix} \right\}$

- Is  $W$  a subspace of  $V$ ?

- Consider a set  $S = \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}$ . Is  $S$  a subspace of  $V$ ?

- Questions:

- What is the difference between a subspace and a subset?

- $V = \text{span} \left\{ \begin{bmatrix} 1 \\ 4.7 \\ -2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 33 \\ 19 \\ -1.8 \end{bmatrix} \right\}$ ,  $W = \text{span} \left\{ \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 4 \\ 0 \end{bmatrix} \right\}$ . Is  $W$  a subspace of  $V$ ?

# Linear independence

- Linear independence:

$$\left[ \begin{array}{l} \{v_1, v_2, \dots, v_n\} \text{ are said to} \\ \text{be linearly independent} \end{array} \right] \text{ if } \left[ \begin{array}{l} a_1 v_1 + a_2 v_2 + \dots + a_n v_n = 0 \text{ can happen} \\ \text{only when } a_1 = a_2 = \dots = a_n = 0 \end{array} \right]$$

- Interpretation in terms of null space:

$$\left[ \begin{array}{l} \{v_1, v_2, \dots, v_n\} \text{ are said to} \\ \text{be linearly independent} \end{array} \right] \text{ if } \left[ \begin{array}{l} \text{Nullspace of the matrix with } v_1, \dots, v_n \\ \text{as columns contains only zero vector.} \end{array} \right]$$

# Towards defining a basis of a vector space

- **Vector space**  $V$  **spanned** by vectors  $v_1, v_2, \dots, v_n$  is defined as

$$V := \left\{ v \in \mathbb{R}^n \text{ s. t. } v = a_1 v_1 + a_2 v_2 + \dots + a_n v_n \text{ for some } a_1, \dots, a_n \in \mathbb{R} \right\} \\ = \text{span}\{v_1, v_2, \dots, v_n\}$$

- Consider the following three vector spaces  $V$ ,  $W$ , and  $U$ .

$$V = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\} \quad W = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\} \quad U = \text{span} \left\{ \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \\ 0 \end{bmatrix} \right\}$$

$v_1 \quad v_2 \qquad w_1 \quad w_2 \quad w_3 \qquad u_1 \quad u_2$

Vector spaces  $V$ ,  $W$ , and  $U$  are the same!

- Observations:
  - $w_3$  can be written as linear combination of  $w_1$  and  $w_2$ .
  - $v_1$  and  $v_2$  are linearly independent, similarly  $u_1$  and  $u_2$ .
- Is there any unique way of representing a given vector space? **No!**
- What could be unique? **Minimum number of vectors spanning vector space**



# Definition: Basis for a vector space $V$

- (Definition) A basis of  $V$  is a set of vectors having the following properties:
  - Vectors are linearly independent
  - They span the space  $V$

- **Examples:**

- $\left\{ \underbrace{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}}_{e_1}, \underbrace{\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}}_{e_2}, \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{e_3} \right\}$  is a basis for the vector space  $\mathbb{R}^3$ .

coordinate vectors: columns of identity matrix

- Is  $\left\{ \underbrace{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}}_{e_1}, \underbrace{\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}}_{e_2}, \underbrace{\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}}_{v_3} \right\}$  a basis for  $\mathbb{R}^3$ ? No! Why?  $e_1, e_2$ , and  $v_3$  are not independent.

- Is  $\left\{ \underbrace{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}}_{e_1}, \underbrace{\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}}_{e_2} \right\}$  a basis for  $\mathbb{R}^3$ ? No! Why?  $e_1$  and  $e_2$  do not span  $\mathbb{R}^3$ .

# Orthogonal subspaces

- (Definition) Orthogonal subspaces:

Suppose  $V$  and  $W$  are subspaces of a vector space  $U$ . Then  $V$  and  $W$  are said to be orthogonal if

$$v^T w = 0 \text{ for all } v \in V \text{ and } w \in W.$$

- Example:  $V = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} \right\}$  and  $W = \text{span} \left\{ \begin{bmatrix} 0 \\ 0 \\ 4 \\ 5 \end{bmatrix} \right\}$ .

Are  $V$  and  $W$  orthogonal subspaces?

- Do we need to check condition  $v^T w = 0$  for all  $v \in V$  and  $w \in W$ ? Justify.

# Preliminaries: Basics of vector spaces

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# Our focus

# Our focus

- Our focus: Vector space spanned by vectors over  $\mathbb{F}_2 = \{0, 1\}$ .
- Scalars can be either 0 or 1.
- Vector space  $V$  spanned by  $k$  vectors  $v_1, v_2, \dots, v_k$  where each  $v_i \in \mathbb{F}_2^n$ :

$$V := \left\{ v \in \mathbb{F}_2^n \text{ s. t. } v = a_1 v_1 + a_2 v_2 + \dots + a_k v_k \text{ for some } a_1, \dots, a_k \in \mathbb{F}_2 \right\}$$

- Questions:
  - ▶ Consider the following vector space.

$$V = \left\{ \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$$

- ▶ Can you write  $V$  as a span of some vectors?

# Self quiz

## Self-quiz

- When do we say the set of  $k$  vectors  $v_1, v_2, \dots, v_k$ , where each  $v_i \in \mathbb{R}^n$  for  $i = 1, 2, \dots, k$ , are linearly independent?
- Are the following set of vectors linearly independent?

$$v_1 = \begin{bmatrix} 1 \\ 0 \\ -3 \\ 2 \end{bmatrix} \quad v_2 = \begin{bmatrix} 0 \\ 1 \\ -5 \\ 4 \end{bmatrix} \quad v_3 = \begin{bmatrix} 3 \\ -2 \\ 1 \\ -2 \end{bmatrix} \quad v_4 = \begin{bmatrix} -4 \\ -6 \\ 1 \\ 5.2 \end{bmatrix} \quad v_5 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- Set of  $m$  vectors in  $\mathbb{R}^n$  must be linearly dependent if  $m > n$ .  
True/False?

# Self-quiz

- Write down the set of all possible vectors in the vector space  $V$  spanned the following set of vectors over  $\mathbb{F}_2$ .

$$V = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right\}$$

Are these vectors linearly independent? Justify your answer.

- What is the dimension of the following vector space? Write down a basis.

$$W = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}$$

- Is  $\mathbb{F}_2^3$  a vector space? Yes/No?
- Is there any connection between  $W$  and  $\mathbb{F}_2^3$ ? Yes/No? If yes, what is the connection?



# Introduction to binary linear block codes

# What are channel codes?



Alice



Channel



Bob

Can Alice do “something” so that Bob is able to interpret her message possibly after doing “some processing”?

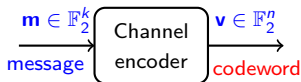
# Recap

- Two channel models:
  - ▶ Binary erasure channel ( $\text{BEC}(\epsilon)$ )
  - ▶ Binary symmetric channel ( $\text{BSC}(p)$ )
- Two channel codes:
  - ▶ Repetition codes ( $\text{REP-}n$ )
  - ▶ Single parity check codes ( $\text{SPC-}n$ )

# Binary linear block codes

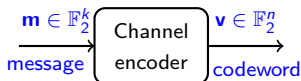
- Write down the set of codewords of REP-3 and SPC-3 codes.
- Is there any connection between  $\mathbb{F}_2^3$  and codewords of REP-3/SPC-3 codes?
- Definition of a binary linear block code
- Basics of a binary linear block code  $\mathcal{C}(n, k)$ :
  - ▶ Definition
  - ▶ Length of a code:  $n$
  - ▶ Size of a code:  $M$
  - ▶ Dimension of a code:  $k$
  - ▶ Rate of a code:  $R$
- Block diagram of a channel encoder

## Example of a channel code: Repetition code



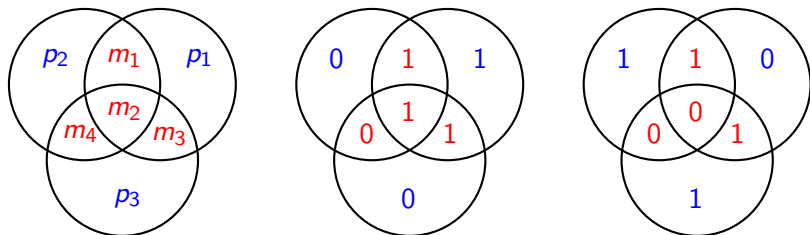
- $k$  : Dimension of the code
- $n$  : Length of the code
- For repetition code we have  $k = 1$
- When  $\mathbf{m} = 0$ , codeword is  $\mathbf{v} = [0, 0, \dots, 0]$ . Thus 0 is repeated  $n$  times for  $n$ -repetition code.
- When  $\mathbf{m} = 1$ , codeword is  $\mathbf{v} = [1, 1, \dots, 1]$ .
- Rate  $R = k/n$ .

# Example of a channel code: Single parity check code (SPC)



- For SPC code we have  $n = k + 1$ .
- SPC for  $k = 2$  is given by
  - ▶ When  $\mathbf{m} = [0 \ 0]$ , codeword is  $\mathbf{v} = [0 \ 0 \ 0]$ .
  - ▶ When  $\mathbf{m} = [0 \ 1]$ , codeword is  $\mathbf{v} = [0 \ 1 \ 1]$ .
  - ▶ When  $\mathbf{m} = [1 \ 0]$ , codeword is  $\mathbf{v} = [1 \ 0 \ 1]$ .
  - ▶ When  $\mathbf{m} = [1 \ 1]$ , codeword is  $\mathbf{v} = [1 \ 1 \ 0]$ .
- Observe:  $n$ -th bit of  $\mathbf{m}$  is modulo-2 sum of previous  $(n - 1)$ -bits.
- Codeword  $[v_0 \ v_1 \ \dots \ v_{n-1}]$  is said to satisfy **one parity check equation** given by  $v_0 + v_1 + \dots + v_{n-1} = 0$ . Hence the name **single parity check code**.
- Rate  $R = (n - 1)/n$ . Codewords of an arbitrary linear block code satisfy many parity check equations. We shall study this in detail later.

## Example of a channel code: Hamming code



- Suppose  $m_1$   $m_2$   $m_3$   $m_4$  are message bits.
- Parity  $p_1$  is obtained using  $m_1$   $m_2$   $m_3$  such that  $m_1 + m_2 + m_3 + p_1 = 0$ .  
Parity  $p_2$  is obtained using  $m_1$   $m_2$   $m_4$  such that  $m_1 + m_2 + m_4 + p_2 = 0$ .  
Parity  $p_3$  is obtained using  $m_2$   $m_3$   $m_4$  such that  $m_2 + m_3 + m_4 + p_3 = 0$ .
- Codeword is given by  $[m_1 \ m_2 \ m_3 \ m_4 \ p_1 \ p_2 \ p_3]$
- Codeword-1:  $[1 \ 1 \ 1 \ 0 \ 1 \ 0 \ 0]$   
Codeword-2:  $[1 \ 0 \ 1 \ 0 \ 0 \ 1 \ 1]$

# Designing binary linear block codes

- Do I always have to add parity bits at the end of message bits to get a codeword?
- Any subspace of  $\mathbb{F}_2^n$  gives us a binary linear block code. What about any arbitrary code?
- For the given  $n$  and  $k$ , how many distinct linear block codes are possible?
- Why the name “binary” “linear” “block” codes?
- Is there any systematic method to represent a code?
- How to do encoding?