

## Objective

M.Tech student in Artificial Intelligence Engineering with demonstrated expertise in machine learning, deep learning, and scalable system design. Proficient in Python, advanced algorithms, and distributed computing with hands-on experience building AI-powered applications, recommendation systems, and computer vision solutions. Passionate about leveraging artificial intelligence and data-driven approaches to solve complex engineering problems and build high-performance, scalable software systems.

## Education

<b>Amrita School of Engineering</b> <i>M.Tech - Artificial Intelligence Engineering</i>	<b>2025-Present</b> <i>Coimbatore, Tamil Nadu</i>
<b>Amrita School of Engineering</b> <i>B.Tech - Automation and Robotics Engineering</i>	<b>2021-2025</b> <i>Coimbatore, Tamil Nadu</i>
• CGPA: 7.48/10	
<b>Amrita Vidyalayam</b> <i>Higher Secondary Education - CBSE</i>	<b>2019-2021</b> <i>Coimbatore, Tamil Nadu</i>
• Stream: Physics, Chemistry, Mathematics, Computer Science • Score: 415/500 (83%)	
<b>Amrita Vidyalayam</b> <i>Secondary Education - CBSE</i>	<b>2018-2019</b> <i>Coimbatore, Tamil Nadu</i>
• Score: 457/500 (91.4%) • Leadership: School Pupil Leader	

## Area of Technical Interest

- Machine Learning
- Computer Vision and Perception
- Intelligent Robotics

## Technical Skills

- Programming Languages:** Python, C++, MATLAB  
**AI/ML Frameworks:** TensorFlow, Scikit-learn, OpenCV, PyTorch  
**Development Tools:** ROS2, Gazebo, Git, Flask, Docker, Linux  
**Cloud & Infrastructure:** AWS (EC2, Lambda, S3, SageMaker), Microservices  
**Technical Domains:** Machine Learning, Computer Vision, SLAM, Autonomous Systems  
**Hardware & Integration:** Pixhawk Flight Controllers, Raspberry Pi, Jetson Orin Nano  
**Leadership Skills:** Team Management, Project Coordination, Problem Solving

## Experience

<b>Moto Amrita - MotoStudent Competition Team</b> <i>Powertrain Lead</i>	<b>Dec 2023 – Feb 2025</b> <i>Coimbatore, Tamil Nadu</i>
• Led powertrain system design and development for FMAE MotoStudent India competition vehicles, managing both electric and internal combustion engine categories • Engineered a custom 5-liter fuel tank optimizing weight distribution and aerodynamics, achieving 5% performance improvement in fuel efficiency and lap times • Developed battery cooling solutions and test bench systems for performance validation, enhancing efficiency and reliability testing capabilities	
<b>Amrita School of Engineering</b> <i>Research Intern - Autonomous Systems</i>	<b>Summer 2024</b> <i>Coimbatore, Tamil Nadu</i>
• Designed autonomous UAV system for SAE Aerothon 2024 competition with real-time navigation algorithms and precision target detection capabilities • Integrated Pixhawk 6X flight controller with Raspberry Pi 4, implementing computer vision algorithms for object detection and tracking • Achieved successful autonomous navigation and target acquisition with 95% accuracy through extensive simulation and testing	

## Projects

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### Multi-Agent AgriTech Platform for Indian Farmers | AWS, Python, Flask

- Architected cloud-native multi-agent system on AWS integrating weather forecasting, crop advisory, market intelligence, and pest detection agents serving Indian farmers
- Deployed scalable microservices architecture using AWS EC2, Lambda, and S3 with ML models achieving 92% accuracy in crop disease identification

### 3D Object Classification using ShapeNet | PyTorch, PointNet, Deep Learning

- Implemented deep learning architecture for 3D point cloud classification using ShapeNet dataset with multiple object categories
- Developed PointNet-based neural network achieving high classification accuracy on 3D geometric data for object recognition tasks

### Car Collision Avoidance System | Arduino Uno, HR-SR04 Sensor

- Designed an innovative collision avoidance system for automobiles, incorporating cutting-edge sensor technologies to detect obstacles and prevent collisions

### Autonomous Drone for Cotton Crop Health Monitoring | Pixhawk 6X, Jetson Orin Nano

- Developed an autonomous drone system capable of detecting and localizing nutrient deficiencies in cotton crops
- Utilized advanced sensors and image processing techniques to provide farmers with real-time insights for enhanced crop management and improved yield

### Li-Ion Battery RUL Prediction Model | Python, SciPy, NumPy

- Built a model to predict the Remaining Useful Life (RUL) of lithium-ion batteries using machine learning algorithms

### 2D SDF SLAM in ROS 2 | ROS2, Gazebo, Extended Kalman Filter, C++

- Architected robust SLAM system using Signed Distance Field representation with Extended Kalman Filter for sensor fusion
- Integrated multi-sensor data (LiDAR, IMU, odometry) reducing memory footprint by 60% vs traditional occupancy grids

### PLC-Based Smart Conveyor Sorting System | PLC, Sensors, Actuators, Ladder Logic

- Developed an automated conveyor system utilizing Programmable Logic Controllers (PLC) to sort products based on predefined criteria such as size, weight, or color
- Integrated sensors to detect product attributes and actuators to divert items accordingly, enhancing sorting efficiency and accuracy

## Publications

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**Real-Time Vibration Isolation Strategies for Vision-Based Agricultural Drones Using Optical Flow and Spectral Analysis** - Developed two-stage vibration dampers achieving 88% reduction in peak vibration amplitude and improving YOLOv10s detection accuracy from 35.5% to 88.5% mAP@50 for nutrient deficiency identification in cotton crops. Evaluated five mounting configurations using Lucas-Kanade optical flow and FFT spectral analysis through real-world flight testing. DOI: [10.55041/IJSREM53258](https://doi.org/10.55041/IJSREM53258)

**Drone-Based Cotton Plant Health Dataset** - Contributed annotated aerial imagery dataset to IEEE DataPort for binary classification of cotton plant health status, supporting machine learning research in precision agriculture and computer vision applications. Available at: [IEEE DataPort](https://data.ieee.org/dataset/10.55041/IJSREM53258)

## Achievements and Contributions

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AIR 01 in FMAE MotoStudent 2024 (EV category)

AIR 7747 in GATE DA 2025

Member, SAE India

Pre-finalist, ThingQbator Cohort 6 (Innovation Program)

Second runner-up, Amrita National Science Olympiad 2019

Runner-up, Glider and Bridge Building, Tempestas 2023

Captain, Amrita Aquatics; Individual Champion, Inter-University Swimming Meet 2023

Member, Tamil Nadu State Junior Water Polo Team (2019); Participant, All India Inter-University Games 2023