Adding AD to existing projects

Laurent Hascoët Paul Hovland Jan Hückelheim Sri Hari Krishna Narayanan

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What we usually start with

- Existing code spread over many files
- ► Non trivial build system
- Multiple build time configuration options
- ► Multiple top level routines and drivers
- ► Calls to libraries
- ► Extensive I/O, initialization
- Parallelism
- Many users and use cases not needing AD

Code Preparation

Analyze the code . . .

- Start with a small case first
- ▶ Identify portion(s) and top level function(s) that need to be differentiated
- ► Identify independent and dependent variables
- ▶ Identify initialization code and I/O
- ▶ Identify portions that cannot be differentiated

Code Modification and Maintenance

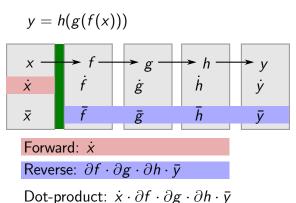
Prepare the code . . .

- Rewrite portions the cannot be differentiated
 - ► Special handling for solvers
 - ► Stubs for library calls
 - Code changes may need to guarded using preprocessor directives
- Write preprocessing scripts
- Add AD to existing build system
- Regression tests to ensure that changes for AD do not change primal output

Validation and Debug

- Original Primal vs. AD Primal
- ► Finite Differences vs Forward mode¹
- ► Forward mode vs Reverse mode
- ► Many tools provide feedback on problems.
- Start always with the simplest case possible

¹See https://fluids.ac.uk/files/resources/Farrell_adjoint_slides.pdf p.6 for a more accurate method



$$y = h(g(f(x)))$$

$$x \longrightarrow f \longrightarrow g \longrightarrow h \longrightarrow y$$

$$\dot{x} \qquad \dot{f} \qquad \dot{g} \qquad \dot{h} \qquad \dot{y}$$

$$\bar{x} \qquad \bar{f} \qquad \bar{g} \qquad \bar{h} \qquad \bar{y}$$
Forward: $\dot{x} \cdot \partial f$
Reverse: $\partial g \cdot \partial h \cdot \bar{y}$
Dot-product: $\dot{x} \cdot \partial f \cdot \partial g \cdot \partial h \cdot \bar{y}$

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Forward: $\dot{x} \cdot \partial f \cdot \partial g$
Reverse: $\partial h \cdot \bar{y}$
Dot-product: $\dot{x} \cdot \partial f \cdot \partial g \cdot \partial h \cdot \bar{y}$

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$$\bar{x} \qquad \bar{f} \qquad \bar{g} \qquad \bar{h} \qquad \bar{y}$$
Forward: $\dot{x} \cdot \partial f \cdot \partial g \cdot \partial h$
Reverse: \bar{y}
Dot-product: $\dot{x} \cdot \partial f \cdot \partial g \cdot \partial h \cdot \bar{y}$

Limitations of the dot-product test

- 1. **It only checks for a given seed.** The dot-product may look good if some errors cancel each other out. (Given some correct tangent-linear vector and a dot-product result, there's an infinite number of adjoint vectors with the same dot-product result).
 - Dot-product is a necessary, but not a sufficient condition for correctness (except for scalar functions). Sufficient condition for consistency: Dot-product test holds for a complete set of basis vectors.
- 2. **Results will differ by some small amount.** Is it roundoff, or a bug?
- It only checks for a given primal input. If the dot-product works at some point, it may not work somewhere else.
- 4. It only finds discrepancies between forward and reverse, assuming that forward is correct