Project Purpose

• The primary purpose of this project is to control a servo motor using Blynk application.

Experiment

Control Servo SG90 along with two LEDs using Blynk Application:

• In this experiment, two buttons are used to control the LEDs on the esp8266 as well a slider for controlling the servo position (Angle).

Screen Grab of the Implementation

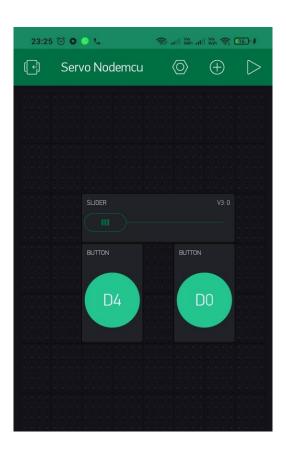


Figure 1 Blynk Application with 2 buttons and 1 slider

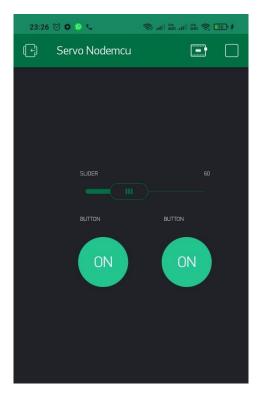


Figure 2 Blynk App with servo angle set at 60 degrees.

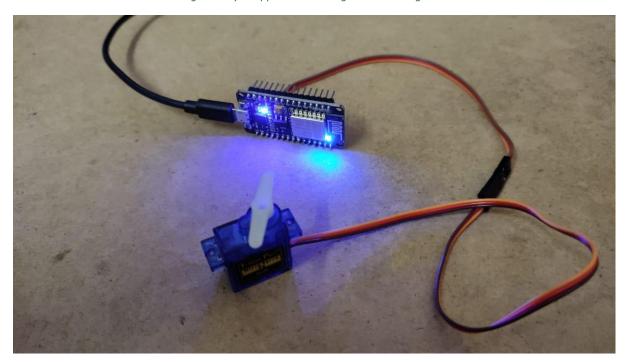


Figure 3 Hardware connections and Interfacing

GitHub upload: <u>GitHub - sriharshakns/IIITH-Research-Internship-2021-K-N-S-Sri-Harsha</u>

This contains my Video Implementation, Documentation & Code for all goals.