## EE3025 Assignment-1

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Download all python codes from

https://github.com/srikanth2001/EE3025-DSP/tree/main/Assignment-01/codes

and latex-tikz codes from

https://github.com/srikanth2001/EE3025-DSP/blob/main/Assignment-01/ee18btech11023.tex

## 1 Problem

1.1. Let

$$x(n) = \left\{ \frac{1}{2}, 2, 3, 4, 2, 1 \right\} \quad (1.1.1)$$

$$h(n) = \left( -\frac{1}{2} \right)^n u(n) + \left( -\frac{1}{2} \right)^{n-2} u(n-2) \quad (1.1.2)$$

1.2. Compute X(k), H(k) and y(n) using FFT and IFFT

## 2 Solution

2.1. input signal x(n)

$$x(n) = \left\{ 1, 2, 3, 4, 2, 1 \right\} \tag{2.1.1}$$

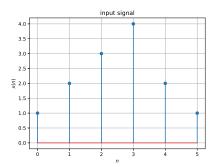


Fig. 2.1: Input Signal y(n)

2.2. Impulse Response of the System is

$$h(n) = \left(-\frac{1}{2}\right)^n u(n) + \left(-\frac{1}{2}\right)^{n-2} u(n-2) \quad (2.2.1)$$

2.3. FFT of a Input Signal x(n) is

$$X(k) = \sum_{n=0}^{N-1} x(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1$$
(2.3.1)

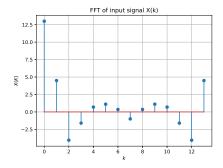


Fig. 2.3: FFT of input signal X(k)

2.4. FFT of a Impulse Response h(n) is

$$H(k) = \sum_{n=0}^{N-1} h(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1$$
(2.4.1)

2.5. then FFT of output Signal y(n) can be computed by

$$Y(k) = X(k)H(k)$$
 (2.5.1)

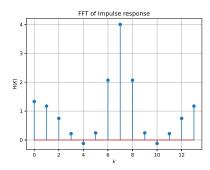


Fig. 2.4: FFT of Impulse response H(k)

2.6. y(n) can be computed by doing IFFT for Y(k)

$$y(n) = \frac{1}{N} \sum_{n=0}^{N-1} Y(k) e^{j2\pi nk/N}, \quad k = 0, 1, \dots, N-1$$
(2.6.1)

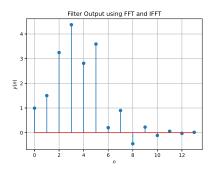


Fig. 2.6: output signal y(n)