

## FINAL EXAM

**DUE: BLACKBOARD FOR DUE DATE AND TIME.**

SHOW ALL YOUR WORK IN A NEAT AND CLEAR MANNER TO GET MAXIMUM POINTS.  
USE ONLY THE FRONT SIDE OF EACH SHEET OF PAPER.  
WRITE YOUR NAME ON EACH PAGE, AND NUMBER YOUR PAGES.

I, \_\_\_\_\_ (PRINT) HAVE COMPLETED THE FOLLOWING TASKS ON MY OWN, WITHOUT THE ASSISTANCE OR GUIDANCE OF ANYONE ELSE, EITHER IN OR OUTSIDE OF MY CLASS.

SIGNATURE: \_\_\_\_\_, DATE: \_\_\_\_\_

## PROBLEMS

### 1.) WORTH 50 POINTS

A PMAC motor has the following specifications: 2 pole; Balanced 3 phase;  $K_t = K_e = 0.75$  in MKS units;  $L_s = 25$  [mH];  $R_s = 0.25 \Omega$ ;  $J_m = 0.03$  [kg\*m<sup>2</sup>].

This motor is driving a load of inertia  $J_L = 0.05$  [kg\*m<sup>2</sup>], and a load torque  $T_L = 2$  [Nm] to bring the system from rest to a speed of 2,000 [RPM] in  $t_1$  [sec.]; assume  $T_{em} = 7$  [NM].

- Calculate (*by hand*) and plot (*using matlab or equivalent*) the speed  $\omega_m(t)$  and position  $\theta_{is}(t)$  as functions of time during this interval of  $0 < t < t_1$  [sec.].
- Calculate (*by hand*) and plot (*using matlab or equivalent*) the voltage  $v_a(t)$  and current  $i_a(t)$  as functions of time during this interval of  $0 < t < t_1$  [sec.].

### 2.) WORTH 40 POINTS

A permanent-magnet dc motor is to be started under a loaded condition. The load-torque  $T_L$  is linearly proportional to the speed and equals 3 [Nm] at a speed of 2850 [RPM] and  $J_L = 0.05$  [kg\*m<sup>2</sup>]. We can neglecting  $L_a$  and friction. The motor current must not exceed  $\pm 12.5$  [A]. Calculate and plot the voltage  $v_a(t)$ , which is to be applied such the motor follow the following speed profile.

Motor Specifications:  $J_m = 0.03$  [kg\*m<sup>2</sup>];  $K_t = K_e = 0.35$  in MKS units;  $R_a = 0.25 \Omega$ ;

- Interval #1: From rest to 2850 [RPM] as quickly as possible,  $0 < t \leq t_1$ .
- Interval #2: Maintain the 2850 [RPM] for 5 seconds,  $t_1 < t \leq t_1 + 5$  [sec.].

- Interval #3: From 2850 [RPM] back to rest as quickly as possible,  $t_1 + 5 < t \leq t_2$  [sec.]. You do not need to consider  $t > t_2$ .

### **3.) WORTH 10 POINTS**

Validate your results for Problem 2 using Matlab/Simulink, or an equivalent simulation tool. Provide narrative explaining how your results validate your analysis. Include the “code,” and plot. Remember that the scopes in Simulink have a history tab, in that tab you should uncheck that box that limits the data to the last 5000 elements.