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# **Embedded Linux**

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## **Part I**

# **Embedded Linux & Open hardware**



# EMBEDDED LINUX(EL)

## 1.1 What is Embedded Linux ?

Embedded Linux is the use of Linux in embedded computer systems such as mobile phones, personal digital assistants (PDA), media players, set-top boxes, and other consumer electronics devices, networking equipment, machine control, industrial automation, navigation equipment and medical instruments. (Wiki)

Practically *EL* devices are no different from any regular desktop Linux, except the fact that most of the input/output, sound/video/graphics components are embedded in one IC(integrated circuit), also known as System on Chip(SoC).

## 1.2 Why Embedded Linux ?

- Linux is a free software(free as freedom), it supports large variants of embedded processors.
- Linux can be optimized to run on any low profile hardware(with 5MB ROM/RAM), as resources can be easily configured using userspace scripts.
- The kernel device drivers are modular, and can be loaded at runtime without restarting OS.
- The most of the core kernel code is architecture independent, so it is easy to add support for new processor.
- There is no fee, no renewals, no hidden clauses

The production cost per *SoC* has now become as low as 10\$, which enables low cost embedded Linux devices. Android is also an embedded Linux device.

## 1.3 ARM based Embedded Linux

**ARM (Advanced RISC Machines)** is the most actively developed, low cost, low power embedded processor available in both 32bit & 64bit versions. ARM based SoCs are manufactured by Samsung, Texas Instruments, ATMEL, NVIDIA, Apple, Qualcomm and more.

Beyond ARM, the other notable embedded processors are SUN-SPARC, MIPS, PowerPC, Zilog, AVR, and more.

We will install toolchain and perform development for ARM processors only. Similar approach can be adopted for any other architectures too.

**Layman comparison of ARM & x86 (2013 approximate price)**

Entity	x86(i3)	ARM(Cortex-A8)
Processor/SoC	107\$	11\$
RAM(1GB/DDR3)	15\$	5\$
ROM(SSD/NAND)	60\$(60G)	4\$(4G)
Graphics	20\$	NA
Power usage	high	low
Size(Board)	10"x10"	4"x2"

Today, it is cheaper to deploy a quad core ARM based web-server than its x86 counterpart. With better speed, small size & low power consumption, ARM boards are turning out to be real threat for desktop processors.

**ARM architecture based Open hardware Embedded Linux boards**

Board name	Company / ARM type / Core(s)	Approximate Price
Raspberry-Pi	Broadcom BCM2835, ARM11, 1	25\$
BeagleBone(B)	TI OMAP 3, Cortex-A8, 1	45\$
PandaBoard	TI OMAP 4, Cortex-A9, 2	182\$
WandBoard	Freescall, Cortex-A9, 1,2,4	79\$ (1 core)
Cubieboard2	Allwinner A-20, Cortex-A7, 2	59\$
A13-OLINUXINO	Allwinner A-13(Aakash), Cortex-A8, 1	47\$

**Companies using ARM architecture**

Company	SoC Name	Notable products	ARM type / Core(s)
Apple	A4	iPhone4, iPad(1G), AppleTV(2G)	Cortex-A8, 1
Apple	A5	iPhone4S, iPad2, AppleTV(3G)	Cortex-A9, 2
Apple	A7	iPhone5s	Cortex-A7, 64bit
Samsung	Exynos 3 Single	Samsung Galaxy S, Galaxy Nexus S	Cortex-A8, 1
Samsung	Exynos 4 Dual	Samsung Galaxy SII, Samsung Galaxy Note	Cortex-A9, 2
Samsung	Exynos 4 Quad	Samsung Galaxy SIII	Cortex-A9. 4
Nvidia	Tegra	Microsoft Zune HD	ARM11, 1
Nvidia	Tegra 2	ASUS Transformer, GalaxyTab 10.1	Cortex-A9, 2
Nvidia	Tegra 3	ASUS Nexus 7, HTC One X	Cortex-A9, 4
Qualcomm	Snapdragon S2	Nokia Lumia 900	NA, 1
Qualcomm	Snapdragon S3	HP TouchPad	NA, 2
Qualcomm	Snapdragon S4	HTC EVO 4G LTE	NA, 2
TI	Omap 3	Barnes and Noble Nook Color	Cortex-A8, 1
TI	Omap 4	KindleFire, GalaxyTab 2, Blackberry Playbook	Cortex-A9, 2
TI	Omap 5	NA	Cortex-A15, 2



# BOOT SEQUENCE IN LINUX

**The steps involved in Linux boot process (x86 and ARM) :**

1. **BIOS (assembly & C)** - is the first program run by x86 based motherboard. ARM boards do not have BIOS, but each SoC has its own program to verify the on-board peripherals after power on.

This BIOS equivalent program in EL is mostly hardcoded in SoCs, hence updating them is usually not possible in case of embedded devices.

The purpose of this stage is to check the integrity of peripherals connected, if found OK, it will look for *bootloader* application in first boot-able device.

2. **Bootloader (C & assembly)** - is used to copy and uncompress *kernel* to RAM from a given location. GRUB(Grand Unified Bootloader) is the popular bootloader for desktop Linux machines.

Embedded Linux uses **U-Boot** bootloader.

3. **Kernel (C & assembly)** - again probes all connected hardware and initializes them systematically. At the end of the kernel stage, it calls *init* process from filesystem to initialize user space scripts and startup jobs.
4. **Initrd (initial ramdisk)** - is an optional scheme for loading a temporary root file system containing device drivers into memory in the boot process of the Linux kernel.
5. **File-system** - is the last stage of boot process, it contains *glibc* and other architecture specific shared libraries to run user space applications.

Filesystem optionally may contain X-server which provides graphical desktop environment such as GNOME, KDE etc.



# SETTING UP DEVELOPMENT ENVIRONMENT

## 3.1 Software requirements

1. In Ubuntu 12.04+, issue the below command to install cross compiler

```
sudo apt-get install gcc-arm-linux-gnueabi
```

2. Install dependencies for kernel and u-boot compilation

```
sudo apt-get install build-essential dpkg-dev kernel-wedge make automake\
checkinstall git u-boot-tools
```

3. Install `qemu-user-static` for setting up chroot based ARM virtualization to install packages in ARM-fileystem

```
sudo apt-get install qemu-user-static
```

4. If you have serial console (Rx, Tx) lines from the board/tablet, then to view console output install *minicom* (optional)

```
sudo apt-get install minicom
```

## 3.2 Hardware requirements

1. A development board such as R-pi, beagleboard, cubieboard or Aakash tablet
2. An sdcard of 2 GB or above
3. USB hub, keyboard and mouse (optional)
4. Serial(Rx,Tx) cable, and USB to serial convertor (optional, for debugging)



# PREPARING U-BOOT, KERNEL & FILESYSTEM

At the end of this stage you will have a bootable sdcard with your custom embedded Linux.

For those who want to try Linux on Aakash now, can download this [sdcard image](#)

Insert the sdcard and umount

```
umount /dev/sdX
```

Untar the file and dd it to sdcard

```
sudo dd if=13.10_2GB_24_09_2013.img of=/dev/sdX bs=1M count=2048
```

## 4.1 U-Boot

### 4.1.1 Compiling U-boot

1. Clone the repository by

```
git clone -b sunxi https://github.com/androportal/uboot-allwinner.git \
--depth=1
```

2. cd into uboot-allwinner

```
cd uboot-allwinner
```

3. To compile uboot issue

```
make a13_olinuxino CROSS_COMPILE=arm-linux-gnueabi-
```

4. After successful compilation u-boot.bin will be available at root of the directory and sunxi-spl.bin will be in spl directory

### 4.1.2 Writing U-boot on sdcard

**SDCARD layout**

Start	size	usage
0	8KB	Unused
8	24KB	Initial SPL loader
32	512KB	u-boot
544	128KB	environment
672	352KB	reserved
1024	–	free for partitions

1. Insert `sdcard` in card reader or MMC reader available in laptops/netbooks
2. Backup all your `sdcard` data, and issue the following commands carefully, replace `X` in `/dev/sdX` with suitable letter(a lower case alphabet) allotted for your `sdcard`, remember `X` will never be `a` if you have a hard disk installed, so keep in mind it must be something like `/dev/sdb` or `/dev/sdc` etc. Please check twice and if you are still unsure then do not perform these steps

```
sudo fdisk -u=sectors /dev/sdX
```

3. First clear the previous `u-boot` and its configurations, if any:

```
sudo dd if=/dev/zero of=/dev/sdX bs=1024 seek=544 count=128
```

4. Now from same `uboot-allwinner` directory issue these commands, again replace `X` with suitable value, now to write `sunxi-spl.bin` to `sdcard` issue:

```
sudo dd if=spl/sunxi-spl.bin of=/dev/sdX bs=1024 seek=8
```

Similarly to burn `u-boot.bin` issue

```
sudo dd if=u-boot.bin of=/dev/sdX bs=1024 seek=32
```

At this point we have a bootable `sdcard` ready. Get kernel and rootfs to make a usable Linux for your tablet.

## 4.2 Kernel

### 4.2.1 Compiling Kernel

Kernel compilation steps are same for

1. Clone the repository by

```
git clone https://github.com/androportal/linux-sunxi.git
```

2. `cd` into `linux-sunxi`

```
cd linux-sunxi
```

3. Checkout to desired branch, in this case `sunxi-3.0`:

```
git checkout sunxi-3.0
```

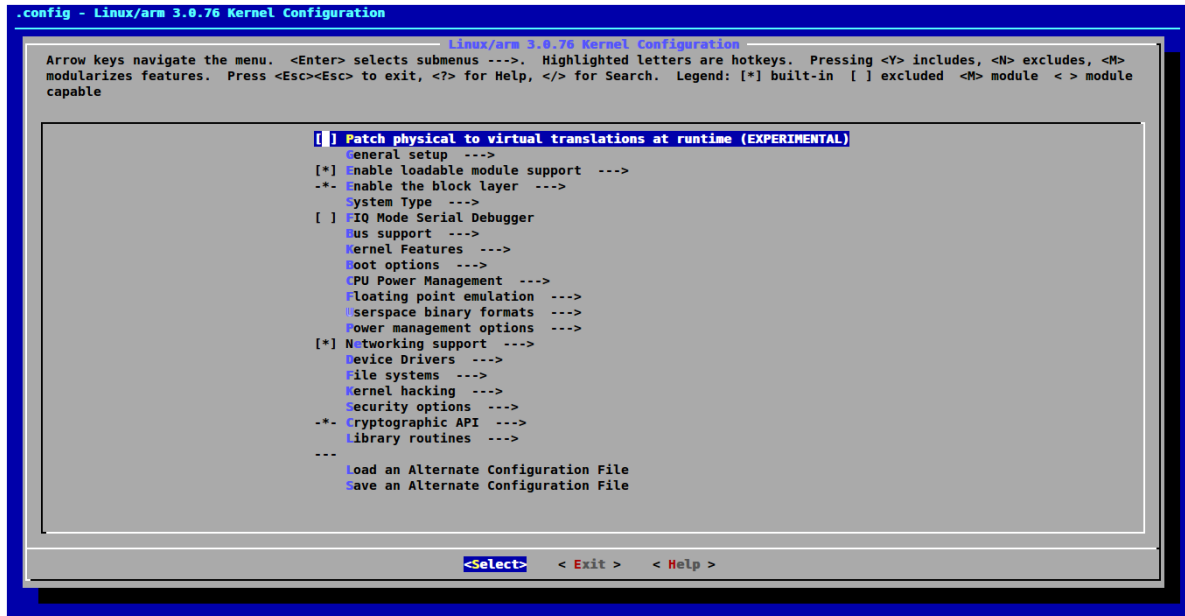
4. You may use the existing `.config` file to compile the kernel for Aakash, or customize it using standard procedures.

`.config` contains all settings and modules information set by user for specific hardware. This will differ from board to board. A `.config` file is autogenerated and can be customized later by following commands. The next command will create a default `.config` for A13(Aakash) board, do not run the next command if you have already downloaded the `.config` file from above link, otherwise it will overwrite without any warning

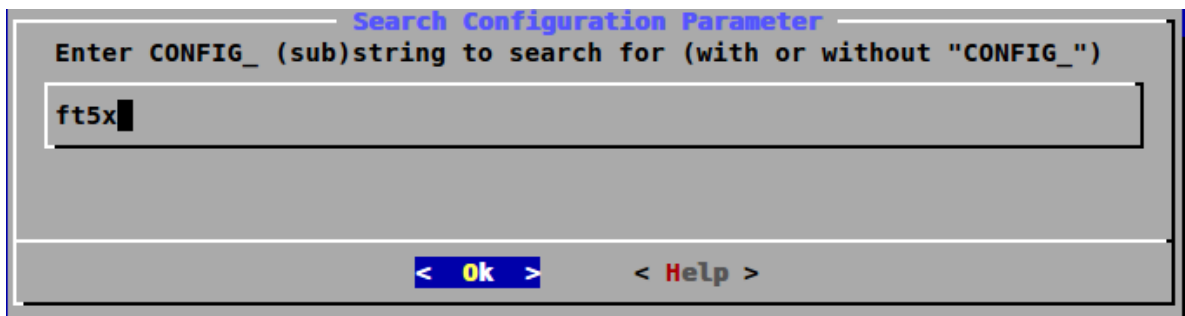
```
make ARCH=arm a13_defconfig
```

5. To customize or view the settings you may run the following command(optional)

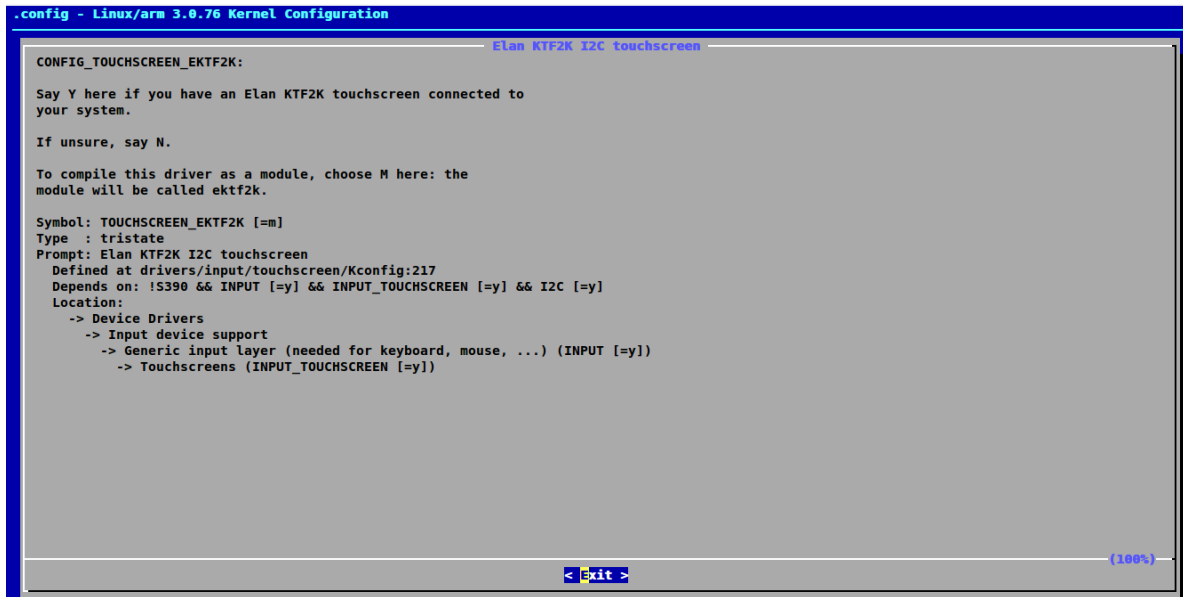
```
make ARCH=arm menuconfig
```



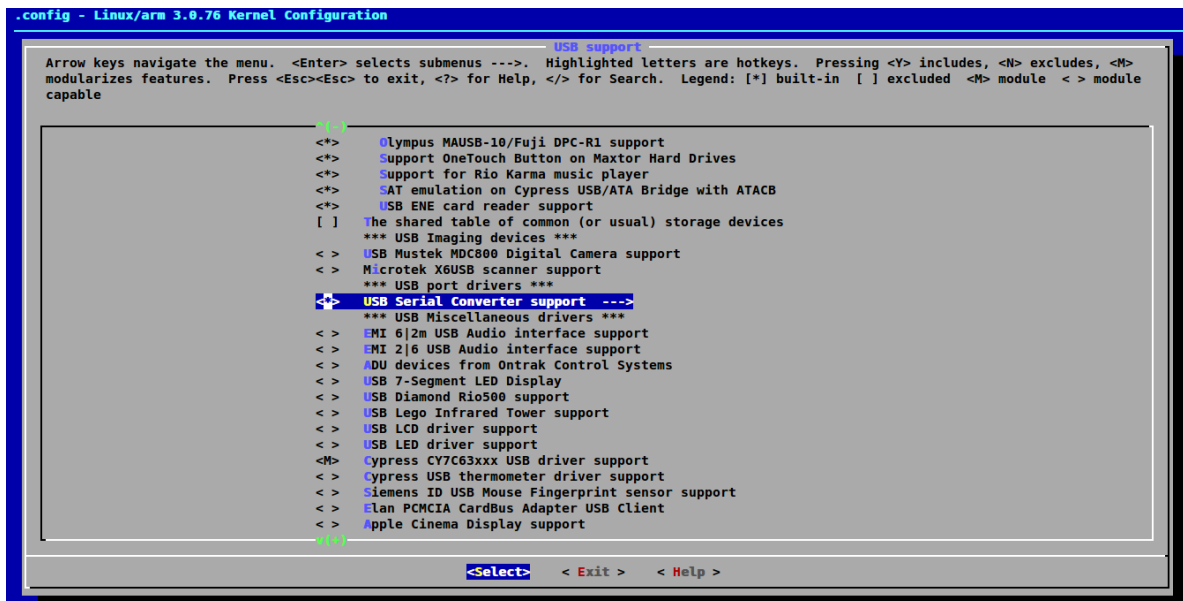
To search any module or setting use `' / '`



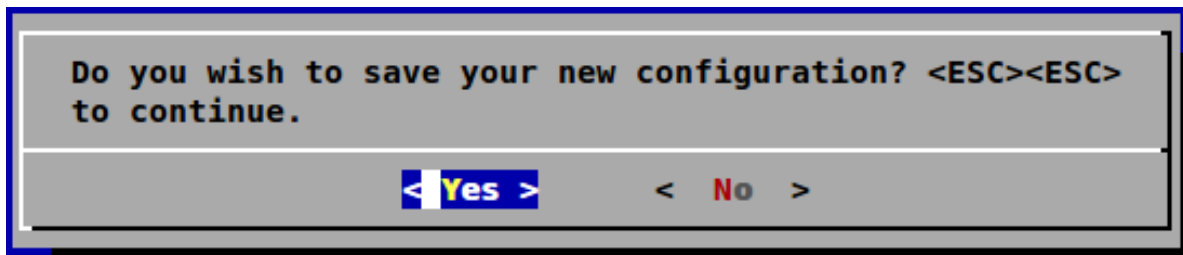
To get module help use `' ? '` when selected



Use space-bar to toggle 'M' (as module) or '\*' (build in kernel)



Use arrow keys to select exit, and choose yes to save the new .config file



6. Now to compile kernel issue



```
make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi- uImage
```

#### 7. To make kernel modules

```
make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi- \
INSTALL_MOD_PATH=out modules
```

#### 8. To install modules in right path

```
make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi- INSTALL_MOD_PATH=out \
modules_install
```

9. After successful compilation uImage will be available at arch/arm/boot/uImage and also find script.bin in the root of the directory(This section is subject to change), the kernel modules are available at out/lib/modules/3.0.76+/

## 4.2.2 Copying kernel to sdcard

1. Insert sdcard in card reader or MMC reader available in laptops/netbooks
2. Backup all your sdcard data, and issue the following commands carefully, replace X in /dev/sdX with suitable letter(a lower case alphabet) allotted for your sdcard, remember X will never be *a* if you have a hard disk installed, so keep in mind it must be something like /dev/sdb or /dev/sdc etc. Please check twice and if you are still unsure leave this README right now otherwise you may end up with non bootable machine:

```
sudo fdisk -u=sectors /dev/sdX
```

3. Then create partition for kernel and filesystem in your sdcard, from inside fdisk prompt type p to list all partitions

```
Command (m for help): p
```

4. Now press d to delete your partition. If you have multiple partitions use partition number to delete each partition as shown by fdisk utility:

```
Command (m for help): d
```

5. Type n for new partion(hit enter) and then mention p for primary partition, hit enter to continue with default starting sector(2048), enter again for last sector and mention +16M, this partition will be later formatted with vfat for kernel:

```
Command (m for help): n
Partition type:
   p   primary (0 primary, 0 extended, 4 free)
   e   extended
Select (default p): p
Partition number (1-4, default 1):
Using default value 1
First sector (2048-7744511, default 2048):
Using default value 2048
Last sector, +sectors or +size{K,M,G} (2048-7744511, default 7744511): +16M
```

6. The sdcard is assumed to be 4gb size, similarly create 2nd primary partition using remaining disk space which will serve as filesystem:

```
Command (m for help): n
Partition type:
   p   primary (1 primary, 0 extended, 3 free)
   e   extended
```

```
Select (default p): p
Partition number (1-4, default 2):
Using default value 2
First sector (34816-7744511, default 34816):
Using default value 34816
Last sector, +sectors or +size{K,M,G} (34816-7744511, default 7744511):
Using default value 7744511
```

7. (Optional) If you intend to use swap partition, leave atleast ~300MB in previous step and create a 3rd primary partition.

8. Now as we have created 2 primary partitions now let's write(w) the changes to disk. For that issue:

```
Command (m for help): w
```

9. As partition is completed, we need to format them respectively, the first partition must be vfat so that uboot can read kernel:

```
sudo mkfs.vfat /dev/sdX1
```

For rootfs, create ext4 partition:

```
sudo mkfs.ext4 /dev/sdX2
```

10. Now mount vfat partition to some mount point(directory):

```
sudo mount -t vfat /dev/sdX1 /mnt/boot
```

copy kernel to /mnt/boot, assuming that you are still in linux-sunxi directory:

```
sudo cp arch/arm/boot/uImage /mnt/boot
```

Also copy script.bin to same directory(script.bin must be extracted from android partition)

```
sudo cp script.bin /mnt/boot
```

Now, umount /mnt/boot, before that you may want to sync so that any remaining buffers are written to disks:

```
sudo sync
```

Finally unmount:

```
sudo umount /mnt/boot
```

At this point we have a sdcard ready with kernel. Copy rootfs to make a usable Linux for your hardware.

## 4.3 Filesystem

As of now we have uboot and kernel ready, the next step is to run applications, to do so we need Linux file system. One can use any distribution from here after. For this session we will use ubuntu 13.10 daily build. You can upgrade to stable 13.10 later.

We will use LXDE, as it is almost 50% lighter & twice as faster than any other desktop environment.

### 4.3.1 Setting up ARM chroot

1. Insert sdcard again, download the core ubuntu 13.10 image from this [link](#) and save it in say */tmp* directory. Extract the tar file in your sdcard's ext4 partition

```
cd /media/<ext4 partition of sdcard>
```

Now extract core ubuntu file system

```
sudo tar -xvpzhf /tmp/saucy-core-armhf.tar.gz
```

2. Copy the static qemu binary to mount arm fs in x86 architecture without invoking actual qemu emulator

```
sudo cp /usr/bin/qemu-arm-static /media/<ext4 partition of sdcard>/usr/bin/
```

3. Now set up chroot environment manually or use the *ch-mount.sh* bash script given two steps below

```
sudo mount -t proc /proc /media/<ext4 partition of sdcard>/proc
```

```
sudo mount -t sysfs /sys /media/<ext4 partition of sdcard>/sys
```

```
sudo mount -o bind /dev /media/<ext4 partition of sdcard>/dev
```

```
sudo mount -o bind /dev/pts /media/<ext4 partition of sdcard>/dev/pts
```

4. chroot into the file system

```
sudo chroot /media/<ext4 partition of sdcard>/
```

5. The above two steps can be combined together using a simple bash *ch-mount.sh*. From here onwards we will use this script to mount and un-mount fs. Please read this script to get any further help

```
sudo bash ch-mount.sh -m /media/<ext4 partition of sdcard>/
```

### 4.3.2 Updating and installing packages

1. Now we have a chroot environment with all *proc*, *dev*, *sys*, *dev/pts* mounted, so run update to fetch repository informations (as chroot has root prompt so no need to write sudo anymore)

```
apt-get update
```

2. Open */media/<ext4 partition of sdcard>/etc/apt/sources.list* in texteditor and replace the content with following

```
deb http://ports.ubuntu.com/ubuntu-ports/ saucy main universe
deb http://ports.ubuntu.com/ubuntu-ports/ saucy multiverse restricted
deb-src http://ports.ubuntu.com/ubuntu-ports/ saucy main universe
deb-src http://ports.ubuntu.com/ubuntu-ports/ saucy multiverse restricted
```

3. Now install english language pack to avoid locale related errors

```
apt-get install language-pack-en-base
```

4. Now install minimal X environment to test our setup

```
apt-get install vim.tiny sudo ssh net-tools ethtool wireless-tools lxde \
xfce4-power-manager xinit xorg network-manager iputils-ping \
florence rsyslog alsa-utils gnome-mplayer \
```

5. Few optional recommended packages for system utilities(lxtask, lxproxy and htop)

```
apt-get install bash-completion lxtask htop \
python-central python-object-2 python-gtk2 synaptic\
```

Download [lxproxy](#) and install using dpkg:

```
dpkg -i lxproxy_0.1ubuntu3_all.deb
```

6. Few more optional packages for office suite, arduino development and pcb designing (testing purpose):

```
apt-get install libreoffice python-gnome2 python-gconf python-serial\
python-gtksourceview2 gcc-avr binutils-avr avr-libc avrdude python-xdg
```

Download [gnoduino](#) and install using dpkg:

```
dpkg -i gnoduino_0.4.0-0pmjdebruijn4~precise_all.deb
```

### 4.3.3 User permissions and startup jobs

1. Add user and set permissions

```
adduser aakash && addgroup aakash adm && addgroup aakash sudo && \
addgroup aakash audio
```

2. Open /etc/hostname file in vim.tiny editor and give a hostname, for example write aakash-arm

3. Similarly open /etc/hosts and remove its content and add these two lines:

```
127.0.0.1    localhost
127.0.1.1    aakash-arm
```

4. Open /etc/modules file and append these two lines

```
gt811_ts
ft5x_ts
ektf2k
8192cu
```

5. Add these lines in /etc/rc.local to activate swap at boot time(if using):

```
# Added for Aakash, assuming the last partition will be swap
mkswap /dev/mmcblk0p3
swapon /dev/mmcblk0p3
```

6. To allow non root user to edit networking, change this file

```
/usr/share/polkit-1/actions/org.freedesktop.NetworkManager.policy
```

look for this section:

```
<action id="org.freedesktop.NetworkManager.settings.modify.system">
```

```
change <allow_active> to 'yes':
```

```
<defaults>
```

```
<allow_inactive>no</allow_inactive>
```

```
<allow_active>yes</allow_active>
```

```
</defaults>
```

```
</action>
```

7. Open /etc/lxdm/lxdm.conf and modify it for autologin. Change the autologin section in the top of the file to this

```
## uncomment and set autologin username to enable autologin
autologin=aakash
```

8. Now open a new tab in your host Linux machine's terminal and copy /<path to linux kernel>/linux-sunxi/out/lib/modules/3.0.76+/ to your arm ubuntu setup

```
sudo cp -r /<path to linux kernel>/linux-sunxi/out/lib/modules/3.0.76+/ \
/media/<ext4 partition of sdcard>/lib/modules/
```

9. Download rtl8192cufw.bin from this [page](#), and create a directory as /lib/firmware/rtlwifi in ubuntu chroot, copy rtl8192cufw.bin inside rtlwifi directory
10. By now we have basic elements set to give a trial run to our OS. Type `exit` in chroot environment to get back to Ubuntu x86 host prompt, now run un-mount script

```
sudo bash ch-mount.sh -u /media/<ext4 partition of sdcard>/
```

unmount both the partitions (fat32 and ext4) from your machine, confirm with `mount` command to check nothing from sdcard is mounted

Remove the sdcard and insert it in your tablet, power on to get ubuntu 13.10 lxde desktop.

The default login is aakash. If you unable to *logout* or *shutdown*, then you must set the following as root

```
chmod u+s /usr/bin/lxsession-logout
```



# DEBUGGING

## 5.1 U-boot access using minicom

Minicom is a serial communication program, its used to access serial console at certain baudrate us Rx & Tx lines. The serial console redirects the output of embedded Linux device to minicom. Mostly embedded devices do not have display units, hence serial debugging is one of the widely used practice.

### 5.1.1 Minicom setup

Set the proper baud rate and port. The baud rate could be 115200 in most cases, if not check the manual of the SoC.

Run

```
sudo minicom -s
```

and then navigate to `Serial port setup` and change settings to match as shown below, hit enter to exit, then Save setup as dfl.

```
+-----+
| A -   Serial Device       : /dev/ttyUSB0
| B - Lockfile Location    : /var/lock
| C -   Callin Program     :
| D -   Callout Program    :
| E -   Bps/Par/Bits       : 115200 8N1
| F - Hardware Flow Control : No
| G - Software Flow Control : No
|
| Change which setting? █
+-----+
| Screen and keyboard
| Save setup as dfl
| Save setup as..
| Exit
| Exit from Minicom
+-----+
```

Connect Rx, Tx lines to your embedded board and other end to your host laptop/desktop.



Now run

```
minicom
```

and you should see scrolling U-boot and kernel logs. By default U-boot waits for user interrupt for 3 seconds. If interrupted it will drop into U-boot prompt, similar to this

```
U-Boot SPL 2012.10-rc3 (Sep 23 2013 - 16:25:21)
SUNXI SD/MMC: 0
```

```
U-Boot 2012.10-rc3 (Sep 23 2013 - 16:25:21) Allwinner Technology
```

```
CPU:   SUNXI Family
Board: A13-OLinuXino
I2C:   ready
DRAM:  512 MiB
MMC:   SUNXI SD/MMC: 0
*** Warning - bad CRC, using default environment
```

```
In:    serial
Out:    serial
Err:    serial
Hit any key to stop autoboot:  0
sun5i#
```

```
CTRL-A Z for help |115200 8N1 | NOR | Minicom 2.6.2 | VT102 | Offline
```



You can type `help` to see all *U-boot* commands.

To print default U-boot environment variables

```
printenv
```

```
Environment size: 1028/131068 bytes
sun5i#printenv
baudrate=115200
boot_mmc=fatload mmc 0 0x43000000 script.bin && fatload mmc 0 0x48000000 ${kernel} && watchdog 0 && bootm 0x48000000
bootcmd=if run loadbootenv; then echo Loaded environment from ${bootenv};env import -t ${scriptaddr} ${filesize};fi;if test -n ${uenvcmd}; then echo ;
bootdelay=3
bootenv=uEnv.txt
bootscr=boot.scr
console=ttyS0,115200
kernel=uImage
loadbootenv=fatload mmc 0 $scriptaddr ${bootenv} || ext2load mmc 0 $scriptaddr ${bootenv} || ext2load mmc 0 $scriptaddr boot/${bootenv}
loadbootscr=fatload mmc 0 $scriptaddr ${bootscr} || ext2load mmc 0 $scriptaddr ${bootscr} || ext2load mmc 0 $scriptaddr boot/${bootscr}
loglevel=8
panicarg=panic=10
root=/dev/mmcblk0p2 rootwait
scriptaddr=0x44000000
setargs=setenv bootargs console=${console} root=${root} loglevel=${loglevel} ${panicarg} ${extraargs}
stderr=serial
stdin=serial
stdout=serial
```

U-boot prompt can allow user to update kernel, load alternate kernel images, change the environment variables and lot more.

Now to `boot` the kernel from U-boot prompt just run

```
boot
```

This will boot the default kernel set in U-boot environment.

## 5.2 Kernel debugging

The kernel logs can be viewed in same minicom serial console. The logs provide important information about services and drivers. One can set `loglevel` to control the extent of debug info on screen.

Developers usually insert `printk` statements in device drivers and check values of variables in kernel log. The better and efficient way to debug kernel is by using `kdb`. More on `kdb` can be found [here](#)



# **ADDITIONAL TOOLS TO MAKE LIFE EASY**

## **6.1 ssh & scp**

Setup an ssh server in your embedded Linux box and add your public key to have password less login (helps to load kernel images and modules faster)

## **6.2 tftp server**

If your board supports ethernet cable then use this setup to transfer test builds.