

Solution of linear systems

Given $\underline{A} = \underline{L}\underline{U}$, we may now solve

$$\underline{A}\underline{x} = \underline{b} \Leftrightarrow \underline{L}\underline{U}\underline{x} = \underline{b}$$

Define $\underline{y} = \underline{U}\underline{x}$, so that

$$\underline{L}\underline{y} = \underline{b}, \quad \underline{U}\underline{x} = \underline{y}$$

This leads to a simple approach: first solve for \underline{y} via forward substitution, then given \underline{y} , solve for \underline{x} via back substitution.

Computational work

Q: How much effort (floating point operations) to compute $\underline{A} = \underline{L}\underline{U}$? How does it scale w/ n for $\underline{A} \in \mathbb{R}^{n \times n}$?

Recall:

$$\begin{cases} l_{ji} = \frac{1}{u_{ii}} \left[a_{ji} - \sum_{k=1}^{j-1} l_{jk} u_{ki} \right], & \begin{matrix} j=2, \dots, n \\ i=1, \dots, j-1 \end{matrix} \\ u_{ji} = a_{ji} - \sum_{k=1}^{j-1} l_{jk} u_{ki}, & \begin{matrix} j=1, \dots, n \\ i=j, \dots, n \end{matrix} \end{cases}$$

$$l_{ji}: \begin{matrix} j-1 & \times & 1 & - \\ j-2 & + & 1 & \cdot \end{matrix}$$

$$u_{ji}: \begin{matrix} j-1 & \times & 1 & - \\ j-2 & + & 0 & \cdot \end{matrix}$$

Recall:

$$\sum_{l=1}^K l = \frac{K \cdot (K+1)}{2},$$

$$\sum_{l=1}^K l^2 = \frac{K(K+1)(2K+1)}{6}$$

So in total, work is:

$$\text{work} = \underbrace{\sum_{i=2}^n \sum_{j=1}^{i-1} (2j-1)}_{L} + \underbrace{\sum_{i=1}^n \sum_{j=2}^n 2 \cdot (j-1)}_{U}$$

$$= \sum_{i=1}^n \left[\sum_{j=1}^{i-1} (2j-1) + \sum_{j=2}^n 2 \cdot (j-1) \right]$$

$$= \sum_{i=1}^n \left[2 \cdot \frac{1}{2} \cdot i \cdot (i-1) - (i-1) + 2 \cdot (i-1) \cdot (n-i+1) \right]$$

$$= \sum_{i=1}^n \left[(i-1)^2 + 2(i-1) \cdot (n-i+1) \right]$$

$$= \sum_{i=1}^n \left[(i-1)^2 - 2(i-1)^2 + 2 \cdot (i-1) \cdot n \right]$$

$$= \sum_{i=0}^{n-1} (2in - i^2)$$

$$= 2 \cdot \frac{1}{2} \cdot n \cdot n \cdot (n-1) - \frac{1}{6} (n-1) \cdot n \cdot (2(n-1)+1)$$

$$= n \cdot (n-1) \left(n - \frac{1}{6} [2n-1] \right)$$

$$= \frac{1}{6} n(n-1) (6n - 2n + 1) = \frac{1}{6} n(n-1)(4n+1)$$

$$\sim \frac{2}{3} n^3 - \frac{1}{2} n^2 \text{ for } n \text{ large.}$$

Q: How much work to solve for x?

$$\underline{L} \underline{y} = \underline{b} \Rightarrow y_1 = b_1, \quad y_i = b_i - \sum_{j=1}^{i-1} L_{ij} y_j, \quad i \geq 2.$$

$$\begin{matrix} 2^{i-1} & \times \\ 2^{i-1} & + \\ 1 & - \end{matrix} \Rightarrow 2^{i-2} \text{ ops}$$

$$\underline{UX} = \underline{y} \Rightarrow X_n = y_n, \quad X_j = \frac{1}{u_{jj}} \left(y_j - \sum_{i=j+1}^n a_{ji} X_i \right), \quad j \leq n-1$$

$$\begin{matrix} n-j & \times \\ n-j-1 & + \\ 1 & - \end{matrix} \Rightarrow 2(n-j)+1 \text{ ops}$$

So, the total work is:

$$\begin{aligned} \sum_{j=2}^n (2j-2) + \sum_{j=n-1}^1 (2(n-j)+1) &= \sum_{j=1}^n (2j-2) + \sum_{j=n}^1 2(n-j) + (n-1) \\ &= (n-1) + \sum_{j=1}^n 2(j-1) + \sum_{j=1}^n 2(j-1) \\ &= (n-1) + 4 \sum_{j=1}^n (j-1) = (n-1) + \frac{4}{2} n(n+1) - 4n \\ &= 2n^2 + 2n + (n-1) - 4n = 2n^2 - n - 1 \end{aligned}$$

Overall Cost: $\approx \frac{2}{3}n^3 + \frac{3}{2}n^2$

Note: Multiple systems w/ same A ?

Factorize $\underline{A} = \underline{L}\underline{U}$ once

Pivoting

Ex: $\underline{A} = \begin{pmatrix} 0 & 1 & 1 \\ 2 & 4 & 2 \\ -1 & 5 & -4 \end{pmatrix}$ will fail, because $A_{11} = 0$!

Permute row 1 w/ row 2: $\hat{\underline{A}} = \begin{pmatrix} 2 & 4 & 2 \\ 0 & 1 & 1 \\ -1 & 5 & -4 \end{pmatrix}$

$$\tilde{A}^{(1)} = 2 \checkmark, \quad \tilde{A}^{(2)} = \begin{pmatrix} 2 & 4 \\ 0 & 1 \end{pmatrix} \checkmark \quad \underline{\text{fine!}} \quad \Delta$$

The above interchange of rows is called a Pivot.

In addition, even if $\det A^{(k)} \neq 0$ for all k , rounding errors stemming from multiplication by large or division by small #'s can be problematic. Pivoting can help w/ this.

Def: Let $n \geq 2$, $P \in \mathbb{R}^{n \times n}$. We call P a permutation matrix if $P_{ji} \in \{0, 1\}$ for all j, i and each row and column contain exactly one 1.

Ex: $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \quad \Delta$

Permutation matrices have some useful properties:

Lemma: Let $n \geq 2$ and let P be a permutation matrix. Then,

(i) P can be obtained from I by permuting rows.

(ii) If $Q \in \mathbb{R}^{n \times n}$ is another permutation, so are QP and PQ .

(iii) Let $P^{(rs)}$ be the interchange matrix obtained from I by swapping rows r and s . Then $P^{(rs)}$ is a permutation and every permutation can be obtained as a product of interchange matrices.

(iv) $\det(P) = \pm 1$

We now state a positive result about pivoting.

Thm: Let $n \geq 2$, $A \in \mathbb{R}^{n \times n}$. There exists a permutation matrix $P \in \mathbb{R}^{n \times n}$ a unit lower triangular matrix $L \in \mathbb{R}^{n \times n}$ and an upper triangular matrix $U \in \mathbb{R}^{n \times n}$ so that

$$\underline{P} \underline{A} = \underline{L} \underline{U}$$

pf: $n=2$ Induction!

$$\underline{A} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad a \neq 0 \Rightarrow \underline{P} = \underline{I} \text{ from } \underline{L} \underline{U} \text{ fact.}$$

$$a=0, c \neq 0: \underline{P} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \Rightarrow \underline{P} \underline{A} = \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}}_L \underbrace{\begin{pmatrix} c & d \\ 0 & b \end{pmatrix}}_U$$

$$a=0, c=0: \underline{A} = \begin{pmatrix} 0 & b \\ 0 & d \end{pmatrix} = \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}}_L \underbrace{\begin{pmatrix} 0 & b \\ 0 & d \end{pmatrix}}_U \quad (\underline{P} = \underline{I})$$

$n=k+1$

Say that $\max_i |a_{i1}|$ occurs in row k . Call this element γ , and permute row 1 w/ row k .

$$\underline{P}^{(1,k)} \underline{A} = \begin{pmatrix} \gamma & \underline{\omega}^T \\ \underline{p} & \underline{B} \end{pmatrix} = \begin{pmatrix} 1 & \underline{0}^T \\ \underline{0} & \underline{I} \end{pmatrix} \begin{pmatrix} \gamma & \underline{v}^T \\ \underline{0} & \underline{C} \end{pmatrix} \quad \begin{matrix} \underline{B}, \underline{C} \in \mathbb{R}^{k \times k} \\ \underline{p}, \underline{m}, \underline{v}, \underline{\omega} \in \mathbb{R}^k \end{matrix}$$

By induction, $\underline{P}^* \underline{C} = \underline{L}^* \underline{U}^*$ for some $\underline{P}^*, \underline{L}^*, \underline{U}^* \in \mathbb{R}^{k \times k}$.

Define $\underline{P} = \begin{pmatrix} \underline{I} & \underline{0}^T \\ \underline{0} & (\underline{P}^*)^{-1} \end{pmatrix} \underline{P}^{(1,k)}$. Then,

$$\underline{P} \underline{A} = \begin{pmatrix} \underline{I} & \underline{0}^T \\ \underline{0} & (\underline{P}^*)^{-1} \end{pmatrix} \begin{pmatrix} 1 & \underline{0}^T \\ \underline{0} & \underline{I} \end{pmatrix} \begin{pmatrix} \gamma & \underline{v}^T \\ \underline{0} & \underline{C} \end{pmatrix}$$

$$= \begin{pmatrix} \mathbf{I} & \mathbf{0}^T \\ (\mathbf{P}^*)^{-1} \mathbf{M} & (\mathbf{P}^*)^{-1} \end{pmatrix} \begin{pmatrix} \mathbf{q} & \mathbf{v}^T \\ \mathbf{0} & \mathbf{c} \end{pmatrix}$$

$$= \begin{pmatrix} \mathbf{I} & \mathbf{0}^T \\ (\mathbf{P}^*)^{-1} \mathbf{M} & (\mathbf{P}^*)^{-1} \end{pmatrix} \begin{pmatrix} \mathbf{q} & \mathbf{v}^T \\ \mathbf{0} & \mathbf{P}^* \mathbf{L}^* \mathbf{v}^* \end{pmatrix}$$

$$= \underbrace{\begin{pmatrix} \mathbf{I} & \mathbf{0}^T \\ (\mathbf{P}^*)^{-1} \mathbf{M} & \mathbf{L}^* \end{pmatrix}}_{\mathbf{L}} \underbrace{\begin{pmatrix} \mathbf{q} & \mathbf{v}^T \\ \mathbf{0} & \mathbf{v}^* \end{pmatrix}}_{\mathbf{U}} \quad \square$$