- Other applications of the technique include verifying polynomial identities.
- For instance, let P₁(x), P₂(x) be two polynomials in a field F.
- The polynomial product verification problem is to check whether $P_1(x) \cdot P_2(x) = P_3(x)$ for a given $P_3(x)$.
- It holds that there exists an O(n log n) time algorithm to multiply two polynomials, where n is themaximum degree of P₁ and P₂.
- We design a verification algorithm that is faster than O(n log n).

- Let S ⊂ F be a subset of size at least 2n + 1.
- The main idea of the verification procedure is that if indeed P₃(x) equals P₁(x) · P₂(x), then, also P₃(r) = P₁(r) · P₂(r) for r chosen uniformly at random from S.
- Further, evaluating a polynomial at a given input can be done in O(n) time.
- So, we can declare that P₃(x) equals P₁(x) · P₂(x) unless P₃(r) ≠ P₁(r) · P₂(r).
- The algorithm makes a mistake only when indeed P₃(x)
 ≠ P₁(x) · P₂(x) but the choice of r fails to detect this.

- To estimate the probability that the algorithm makes a mistake, let $Q(x) := P_3(x) P_1(x) \cdot P_2(x)$.
- The degree of Q(x) is at most 2n.
- Suppose that $P_3(x) \neq P_1(x) \cdot P_2(x)$.
- Then, Q(x) is a nonzero polynomial.
- So the test fails if Q(r) = 0 (but $P_3(x) \neq P_1(x) \cdot P_2(x)$).
- However, the polynomial Q(x) of degree at most 2n can have at most 2n roots.
- So, the probability that Q(r) = 0 is at most 2n/|S|, which
 is also the probability of error.
- As earlier, the probability of failure can be made polynomially small in n by using repeated trails or choosing a larger S, or both.

- One may wonder whether it is at all worthwhile to have elaborate verification algorithms for things as simple as polynomial product verification.
- Such techniques however are more applicable when polynomials are not available explicitly.

Finger-Printing

- The two algorithms that we considered today have the property that for inputs that are identical, the algorithm does not make any error.
- But in inputs that are not identical, the algorithm makes an error that is upper bounded by at least a constant.
 - Repeated runs of the same algorithm can catch the error, hence the error can be made arbitrarily small.

Finger-Printing

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- Repeated runs of the same algorithm can catch the error, hence the error can be made arbitrarily small.
- Consider A to be a finger-printing algorithm.
- Let us run A on input x, y for t iterations.
- The t outputs are, say, o₁, o₂, ..., o_t.
- If any of these t outputs are NO, then we can return NO as the answer.
- If all t are YES, then we return YES as the answer.
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- If any of these t outputs are NO, then we can return NO as the answer.
- If all t are YES, then we return YES as the answer.
- Given that x = y, Pr(A(x,y) = YES) = 1.
- Given that $x \neq y$, $Pr(A(x,y) = YES) \leq (1/2)^t$.
- So, if $t = O(\log n)$, then the error probability is $O(1/n^c)$.

- The above algorithms are called as co-RP algorithms.
- RP stands for Randomized Polynomial.
- Definition: The class RP consists of languages L such that there exists a randomized algorithm running in worst case polynomial time such that for any input x:
 - $x \in L \Rightarrow Pr(A \text{ accepts } x) \ge 1/2$.
 - $x \notin L \Rightarrow Pr(A \text{ accepts } x) = 0$
- The complement of the class RP is the class co-RP.
- Note that any RP or co-RP algorithm can err only on one side, either for x in L, or for x not in L.

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What about Randomized QuickSort

- The randomized quick sort algorithm does not make any errors in its output.
- So, clearly, it does not fit into either of RP or co-RP.
- While there are no errors in its output, we recall that its run time may vary.
- Such algorithms are called ZP algorithms.
 - Stands for Zero Error Expected Polynomial, time
- The class ZP consists of languages L such that there is a randomized algorithm A that always outputs the correct answer while running in expected polynomial time.
- Another name for ZP algorithms is Las Vegas algorithms.

- Many times you want to show that a particular combinatorial object exists.
- May be very inefficient to build possibly because of a huge space and a small target of interest.
 - Like finding a needle in a haystack.
- This is where randomization can come to the resuce.

- Two useful statements:
- If a random variable has a finite expected value E[X] =

 a, then certainly there exists a realisation of X with
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- Each of these statements looks simple on their own, but they are remarkably powerful in Computer Science.

- We will start with a simple example.
- Consider an undirected graph G = (V, E).
- We want to find a subgraph G' of G that:
 - 1) has the largest number of edges of G, and
 - 2) G' is bipartite.
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- The random experiment we perform is to assign a bit 0 or 1, denoted b(v), to each vertex v of G ind. and uar.
- Put all vertices in G'.
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- In other words, $G' = (V_0 \cup V_1, V_0 \times V_1 \text{ int. } E(G)).$
- Let us now bound |E(G')|.
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- By Statement (1) earlier, there must exist an assignment of b() to vertices such that G' has at least half the edges of G.