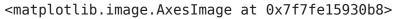
## ▼ Homework 4

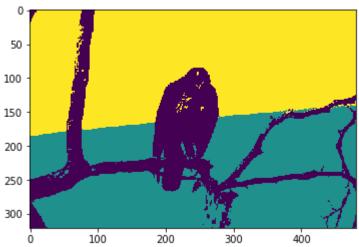
```
import numpy as np
import matplotlib.pyplot as plt
import pandas as pd
import numpy.matlib
from sklearn.cluster import KMeans
from sklearn import mixture
from sklearn.svm import SVC
from mpl_toolkits.mplot3d import Axes3D
```

#### ▼ Functions

```
def normalize(image, stack = False):
  im = np.zeros(image.shape)
  for plane in range(3):
    im[:,:,plane] = (image[:,:,plane] - np.min(image[:,:,plane]))/(np.max(image[:,:,plane]) - np.min(image[:,:,plane])
  if stack:
    x = np.linspace(0,image.shape[0] - 1,image.shape[0])
    x = np.expand dims(x, axis = 1)
    x = np.matlib.repmat(x, 1, image.shape[1])
    y = np.linspace(0,image.shape[1] - 1,image.shape[1])
    y = np.expand dims(y, axis = 1).T
    y = np.matlib.repmat(y, image.shape[0], 1)
    x = (x - np.min(x))/(np.max(x) - np.min(x))
    y = (y - np.min(y))/(np.max(y) - np.min(y))
    # print(x.shape, y.shape, im.shape)
    im = np.dstack((x,y,im))
  return im
```

```
def kmeans(vector, k):
  labels = np.zeros(vector.shape[0])
  mu guess idx = np.random.randint(0, vector.shape[0], k)
  mu guess = vector[mu guess idx]
  print(vector.shape)
  count = 0
  while (count < 10):
    for i in range(vector.shape[0]):
      labels[i] = np.argmin(np.array([np.linalg.norm(vector[i,:] - mu guess[ki,:]) for ki in range(k)]))
    # labels = np.argmin(np.array([np.linalg.norm(vector - mu guess[i,:]) for i in range(k)]))
    # print(vector - mu guess[1,:])
    for j in range(k):
      mu guess[j,:] = np.mean(vector[np.where(labels == j)[0]], axis = 0)
    count += 1
    print(count)
  return labels
test = kmeans(norm bird.reshape(321*481,-1), 3)
    NameError
                                               Traceback (most recent call last)
    <ipython-input-4-25cdb8143727> in <module>()
     ---> 1 test = kmeans(norm bird.reshape(321*481,-1), 3)
    NameError: name 'norm bird' is not defined
      SEARCH STACK OVERFLOW
plt.imshow(test.reshape(321,481))
 С→
```





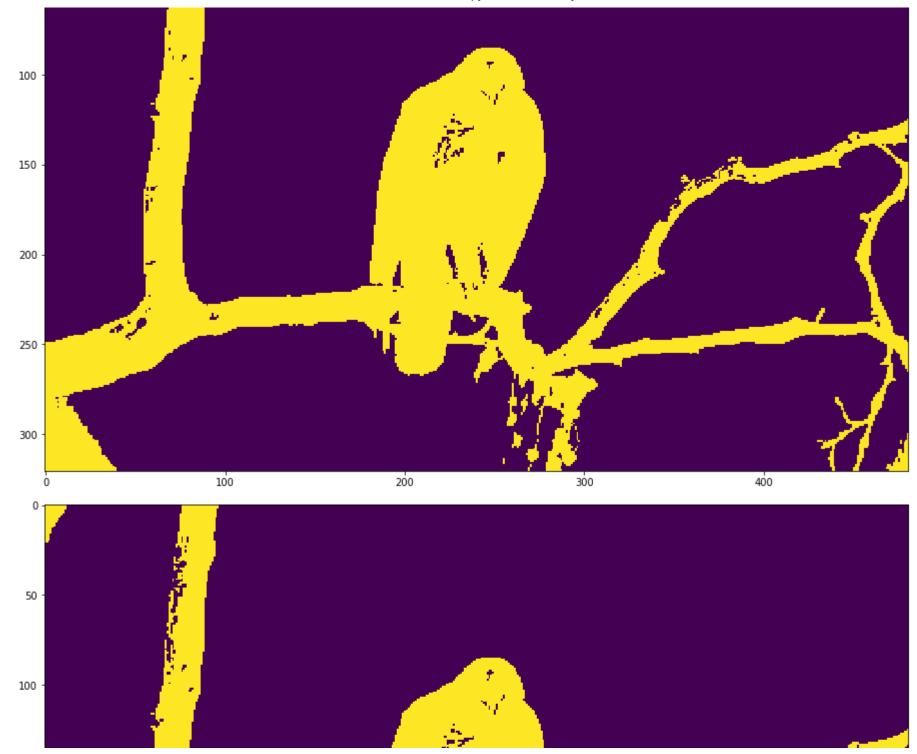
## ▼ Answer 1

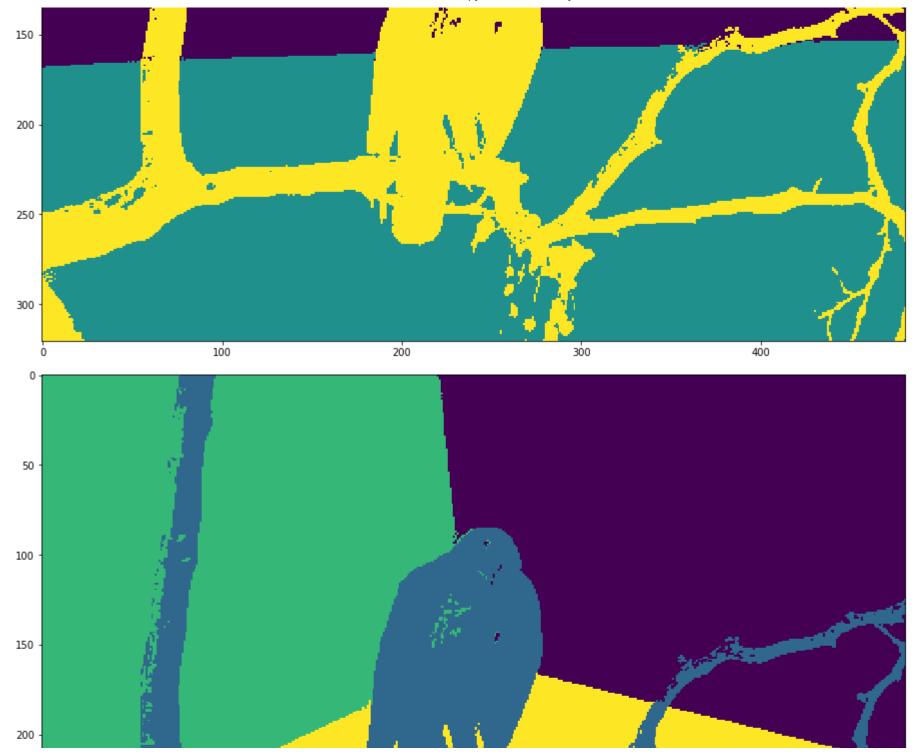
## ▼ K-Means

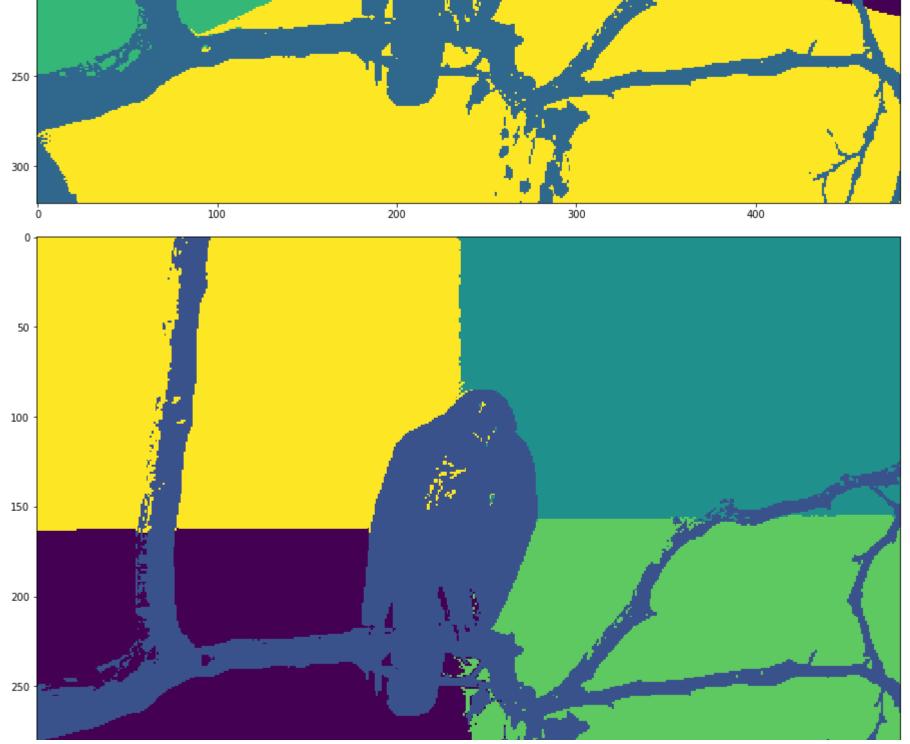
```
bird = plt.imread('bird.jpg')
norm_bird = normalize(bird, True)

k = [2, 3, 4, 5]
plt.axes([1,1,2,2])
plt.imshow(bird)
for i in k:
    cluster = KMeans(i)
    cluster.fit(norm_bird.reshape(bird.shape[0]*bird.shape[1],-1))
    labs = cluster.labels_
    plt.figure()
    plt.axes([1,1,2,2])
    plt.imshow(labs.reshape(bird.shape[0], bird.shape[1]))
```











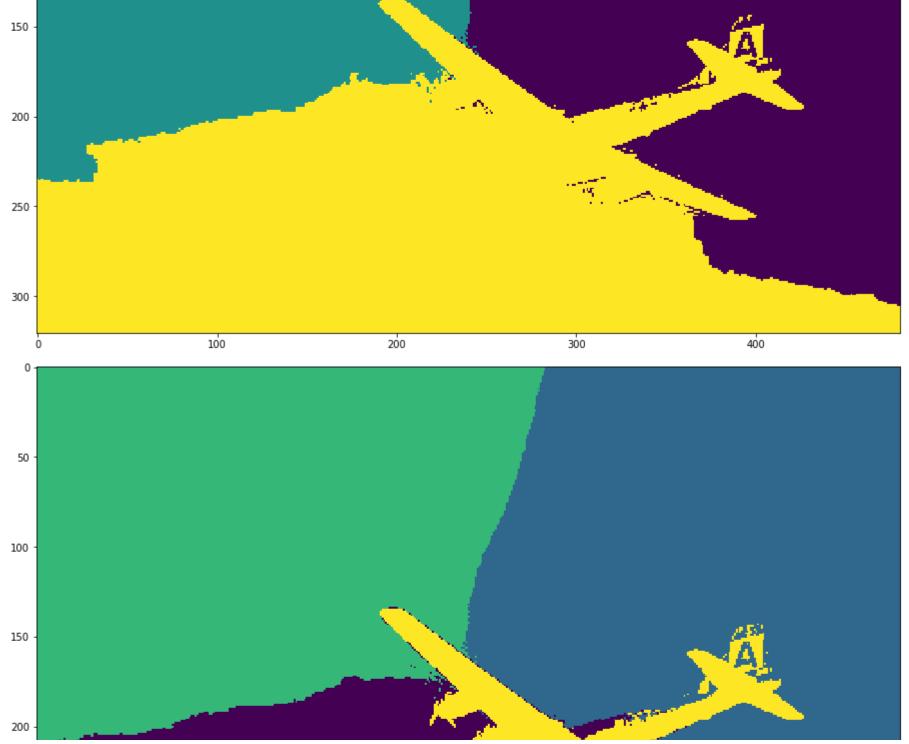
Double-click (or enter) to edit

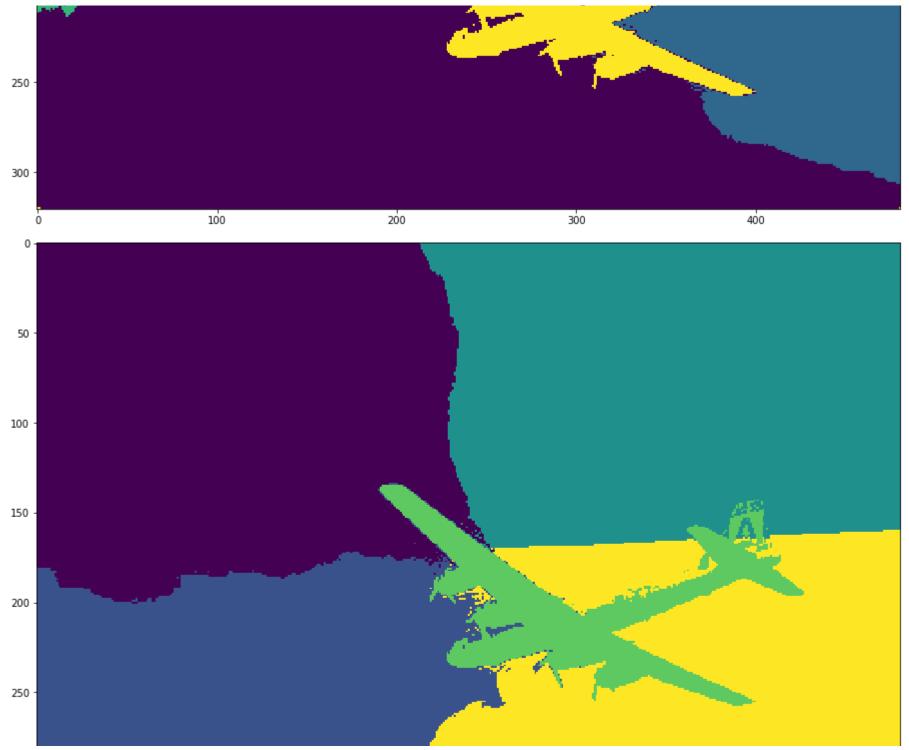
```
plane = plt.imread('plane.jpg')
norm_plane = normalize(plane, True)

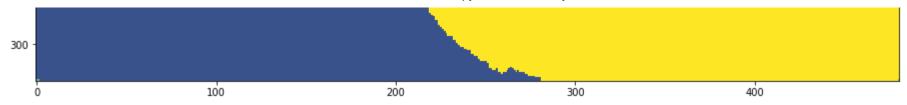
k = [2, 3, 4, 5]
plt.axes([1,1,2,2])
plt.imshow(plane)
for i in k:
    cluster = KMeans(i)
    cluster.fit(norm_plane.reshape(plane.shape[0]*plane.shape[1],-1))
    labs = cluster.labels_
    plt.figure()
    plt.axes([1,1,2,2])
    plt.imshow(labs.reshape(plane.shape[0], plane.shape[1]))
```







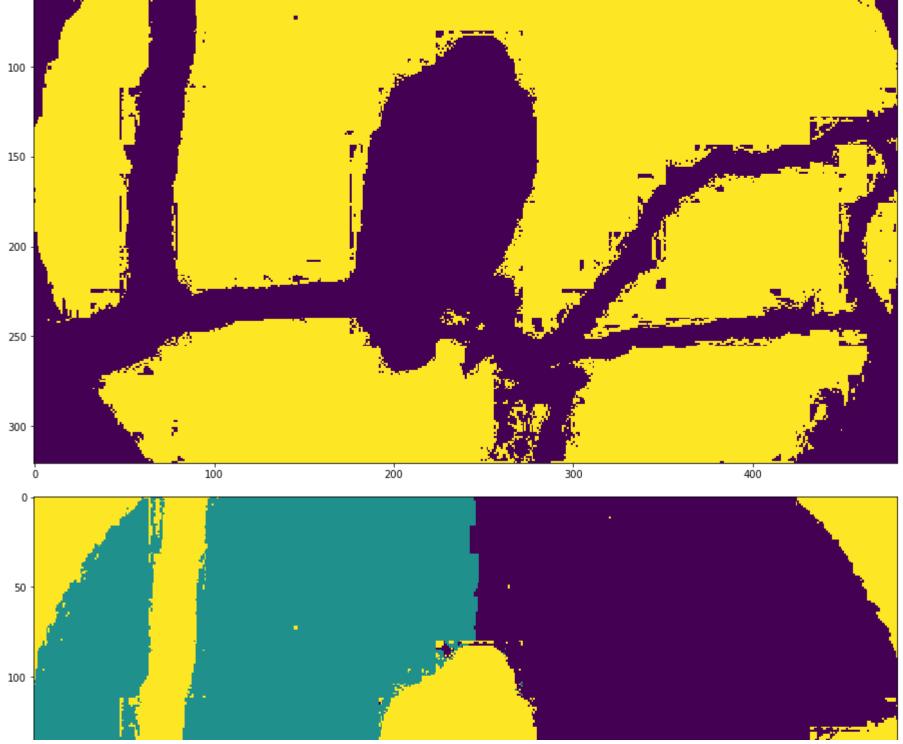


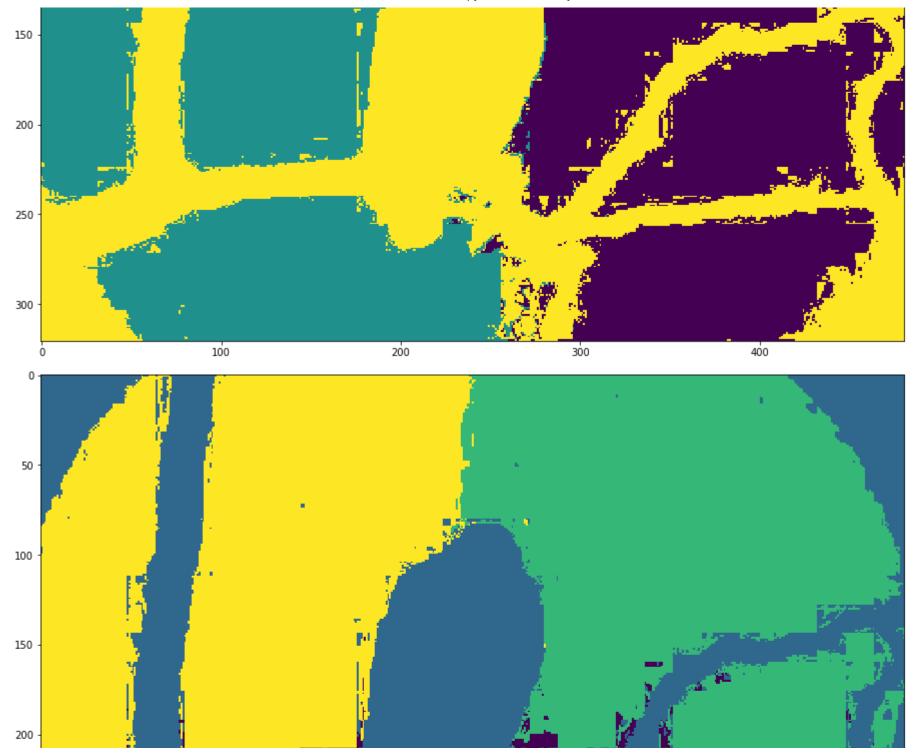


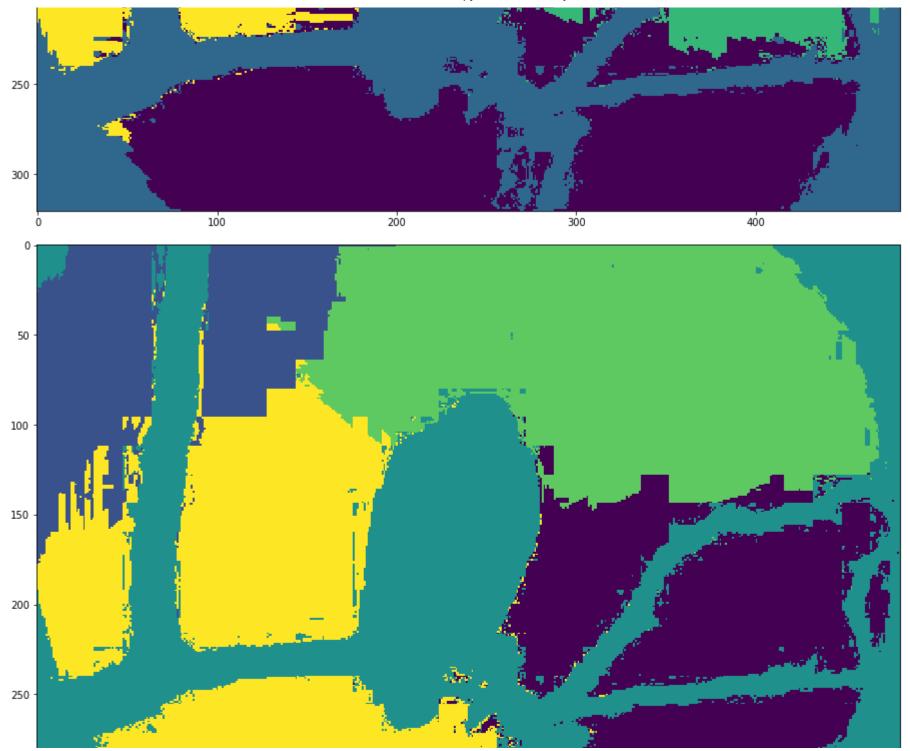
## **▼** GMM

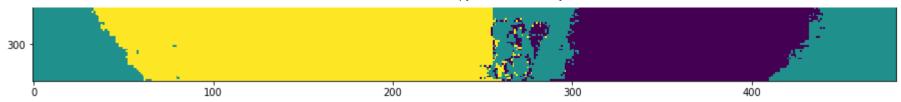
```
plt.axes([1,1,2,2])
plt.imshow(bird)
for i in k:
    gmm = mixture.GaussianMixture(i)
    gmm.fit(norm_bird.reshape(bird.shape[0]*bird.shape[1],-1))
    labs1 = gmm.predict(norm_bird.reshape(bird.shape[0]*bird.shape[1],-1))
    plt.figure()
    plt.axes([1,1,2,2])
    plt.imshow(labs1.reshape(bird.shape[0], bird.shape[1]))
```







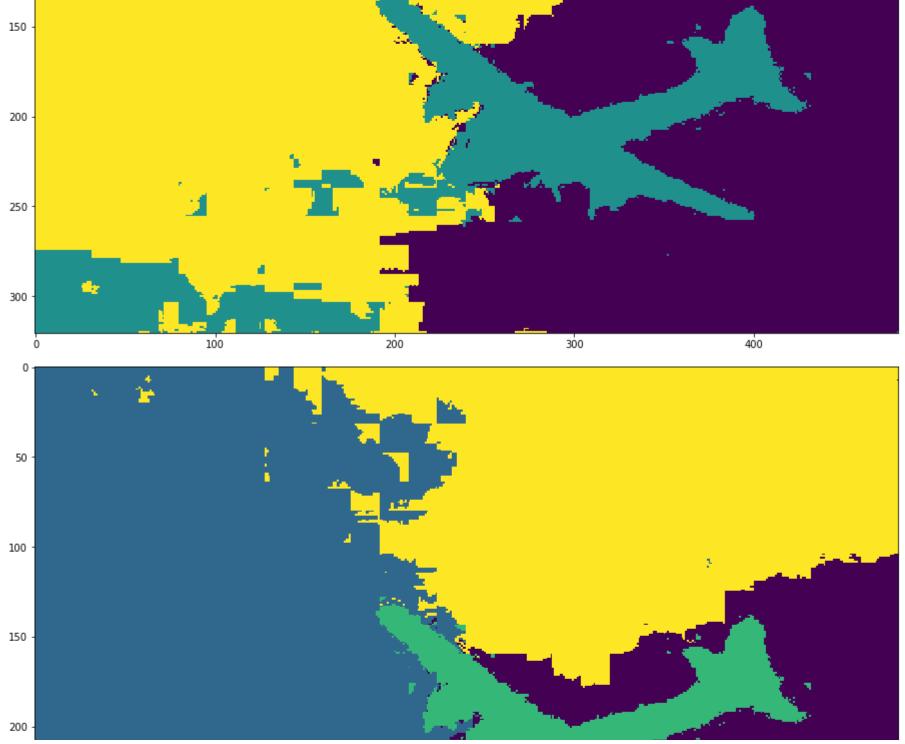


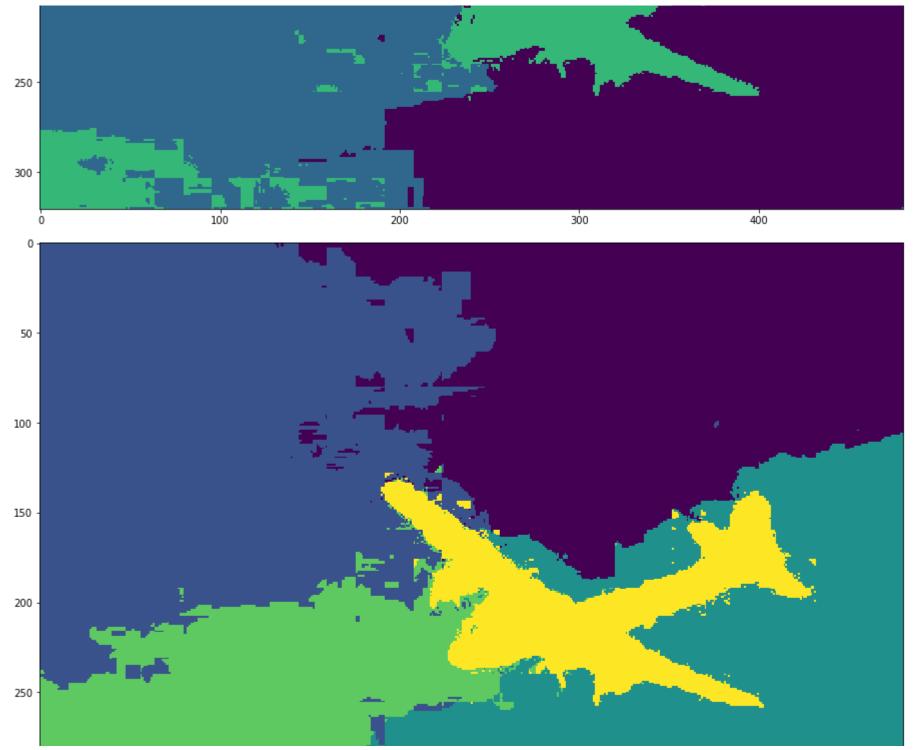


```
plt.axes([1,1,2,2])
plt.imshow(plane)
for i in k:
    gmm = mixture.GaussianMixture(i)
    gmm.fit(norm_plane.reshape(plane.shape[0]*plane.shape[1],-1))
    labs1 = gmm.predict(norm_plane.reshape(plane.shape[0]*plane.shape[1],-1))
    plt.figure()
    plt.axes([1,1,2,2])
    plt.imshow(labs1.reshape(plane.shape[0], plane.shape[1]))
```









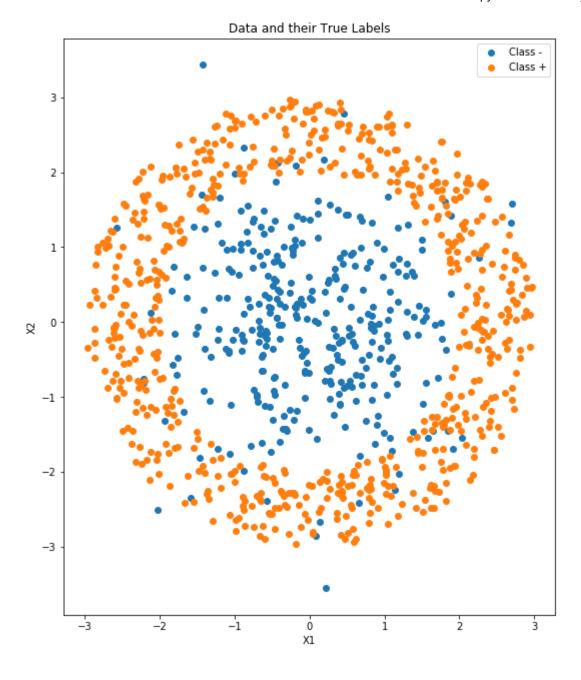


### ▼ Answer 2

```
N = 1000
mean = np.array([0, 0])
sigma = np.array([1, 0, 0, 1]).reshape(2,2)
prior = [0.35, 0.65]
data = np.zeros([2, 1000])
temp = np.random.rand(1,1000)
idx1 = np.where(temp <= prior[0])[1]
idx2 = np.where(temp > prior[0])[1]
data[:, idx1] = np.random.multivariate normal(mean, sigma, idx1.shape[0]).T
radius = np.random.uniform(2,3,idx2.shape[0])
angle = np.random.uniform(-np.pi, np.pi, idx2.shape[0])
data[:,idx2] = np.array([radius*np.cos(angle), radius*np.sin(angle)])
Y = np.zeros([1, N])
Y[:, idx1] = np.zeros(idx1.shape[0])
Y[:, idx2] = np.ones(idx2.shape[0])
plt.axes([1,1,2,2])
plt.scatter(data[0,idx1], data[1,idx1])
```

```
plt.scatter(data[0,idx2], data[1,idx2])
plt.xlabel('X1')
plt.ylabel('X2')
plt.title('Data and their True Labels')
plt.legend(('Class -', 'Class +'))
plt.gca().set_aspect('equal', 'box')

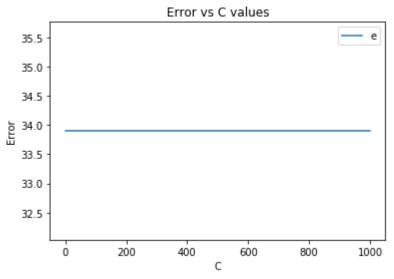
□→
```



## ▼ Linear SVM

```
k = 10
N = 1000
C = [0.001, 0.01, 0.1, 1, 10, 100, 1000]
best = []
for c in C:
  svm lin = SVC(c, kernel='linear')
  err = []
  for fold in range(k):
    val data = data[:,fold*(N//k):(fold+1)*(N//k)] # split data into val and train
    y val = Y[:,fold*(N//k):(fold+1)*(N//k)]
    train data = np.concatenate((data[:,:fold*(N//k)], data[:,(fold+1)*(N//k):]), axis = 1)
    y train = np.concatenate((Y[:,:fold*(N//k)], Y[:,(fold+1)*(N//k):]), axis = 1)
    svm lin.fit(train data.T, y train.reshape(y train.shape[1],))
    label = svm lin.predict(val data.T)
    err.append(np.sum(np.abs(label - y val)))
  best.append(np.mean(err))
plt.plot(C,best)
plt.title('Error vs C values')
plt.xlabel('C')
plt.ylabel('Error')
plt.legend('error')
C→
```

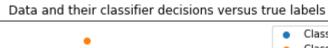
<matplotlib.legend.Legend at 0x7f5e30a5d2b0>

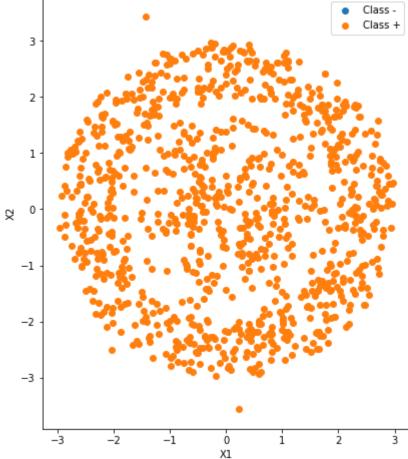


```
best_c = best.index(min(best))

svm_lin = SVC(C[best_c], kernel='linear')
svm_lin.fit(data.T, Y.reshape(Y.shape[1],))
labs1 = svm_lin.predict(data.T)
boundary1 = svm_lin.decision_function(data.T)

plt.axes([1,1,1.5,1.5])
plt.scatter(data[0,np.where(labs1 == 0)[0]], data[1,np.where(labs1 == 0)[0]])
plt.scatter(data[0,np.where(labs1 == 1)[0]], data[1,np.where(labs1 == 1)[0]])
plt.xlabel('X1')
plt.ylabel('X2')
plt.title('Data and their classifier decisions versus true labels')
plt.legend(('Class -', 'Class +'))
plt.gca().set_aspect('equal', 'box')
```





## ▼ Gaussian SVM

$$k = 10$$

$$N = 1000$$

$$C = [0.1, 1, 10, 100]$$

$$G = [0.1, 1, 10, 100]$$

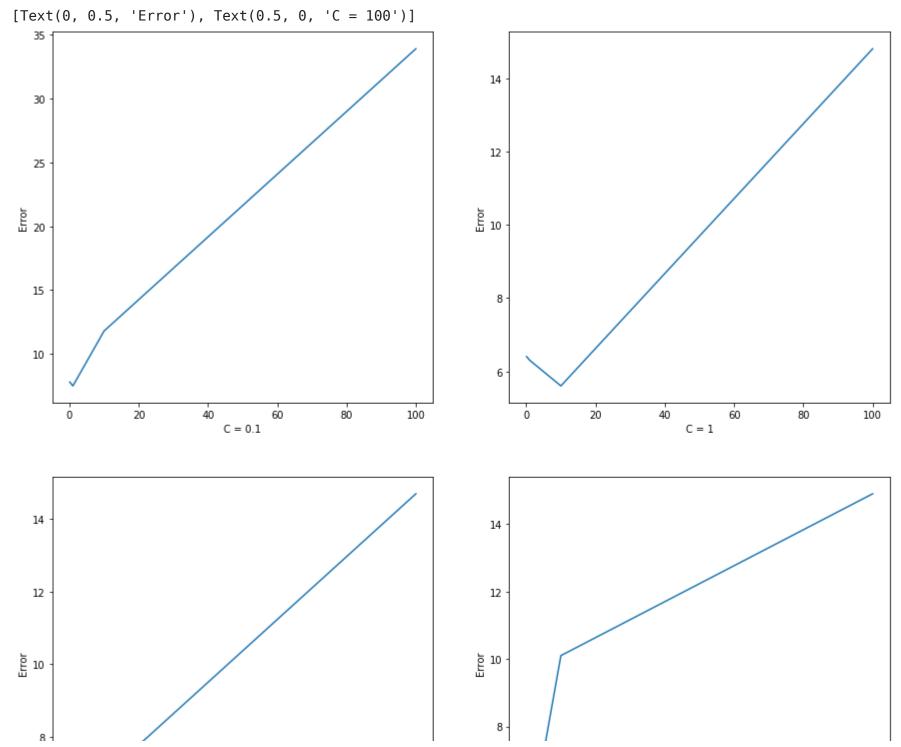
$$best = []$$

 $https://colab.research.google.com/drive/1DHabM8mIRiTLdKmgtnfTQTPT91BNgYH1\\ \#scrollTo=XOkEgfJS0iRt&printMode=true$ 

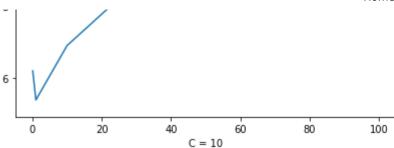
best

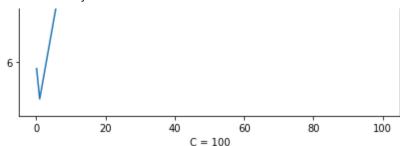
С→

```
[7.8,
     7.5,
     11.8,
      33.9,
     6.4,
     6.3,
     5.6,
      14.8,
     6.2,
     5.4,
     6.9,
      14.7,
     5.8,
     4.9,
      10.1,
     14.91
np.array(best).reshape(4,4)
\Gamma array([[ 7.8, 7.5, 11.8, 33.9],
           [ 6.4, 6.3, 5.6, 14.8],
           [ 6.2, 5.4, 6.9, 14.7],
           [ 5.8, 4.9, 10.1, 14.9]])
fig, ax = plt.subplots(2,2, figsize=(15,15))
ax[0,0].plot([0.1,1,10,100], best[:4])
# ax[0,0].plot(best.index(min(best[:4])), min(best[:4]), 'o')
# ax[0,0].text(i, v+25, "%d" %v, ha="center")
ax[0,1].plot([0.1,1,10,100], best[4:8])
ax[1,0].plot([0.1,1,10,100], best[8:12])
ax[1,1].plot([0.1,1,10,100], best[12:16])
ax[0,0].set(xlabel='C = 0.1', ylabel='Error')
ax[0,1].set(xlabel='C = 1', ylabel='Error')
ax[1,0].set(xlabel='C = 10', ylabel='Error')
ax[1,1].set(xlabel='C = 100', ylabel='Error')
С
```



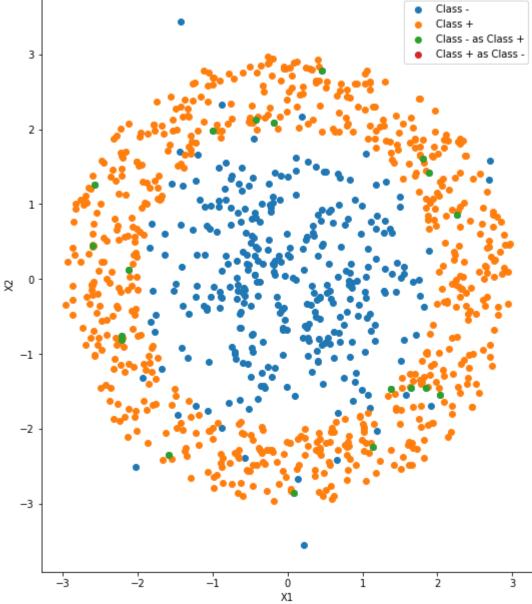
C→





```
svm gaus = SVC(best c, kernel='rbf', gamma = best g)
svm gaus.fit(data.T, Y.reshape(Y.shape[1],))
labs2 = svm_gaus.predict(data.T)
boundary2 = svm gaus.decision_function(data.T)
a = np.where((labs2 == 1) & (Y == 0))[1]
b = np.where((labs2 == 0) & (Y == 1))[1]
plt.axes([1,1,2,2])
plt.scatter(data[0,idx1], data[1,idx1])
plt.scatter(data[0,idx2], data[1,idx2])
plt.scatter(data[0, a], data[1, a])
plt.scatter(data[0, b], data[1, b])
plt.xlabel('X1')
plt.ylabel('X2')
plt.title('Data and their classifier decisions versus true labels')
plt.legend(('Class -', 'Class +', 'Class - as Class +', 'Class + as Class -'))
plt.gca().set aspect('equal', 'box')
```

## Data and their classifier decisions versus true labels • Classifier decisions versus true labels

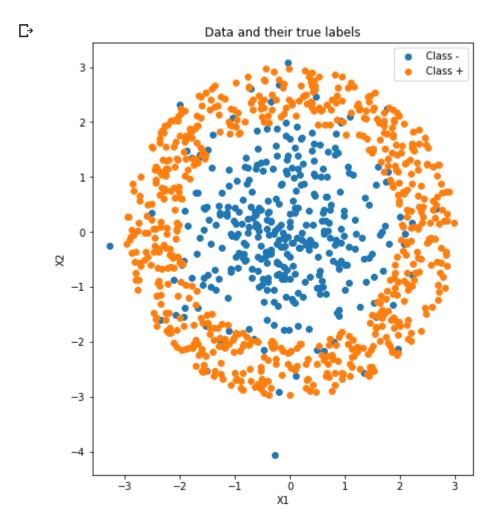


print(idx1.shape, idx2.shape, a.shape, b.shape)

▼ Test Data Set

```
data tst = np.zeros([2, 1000])
temp tst = np.random.rand(1,1000)
idx1 tst = np.where(temp_tst <= prior[0])[1]</pre>
idx2 tst = np.where(temp_tst > prior[0])[1]
data_tst[:, idx1_tst] = np.random.multivariate_normal(mean, sigma, idx1_tst.shape[0]).T
radius_tst = np.random.uniform(2,3,idx2_tst.shape[0])
angle tst = np.random.uniform(-np.pi, np.pi, idx2_tst.shape[0])
data_tst[:,idx2_tst] = np.array([radius_tst*np.cos(angle_tst), radius_tst*np.sin(angle_tst)])
Y_{tst} = np.zeros([1, N])
Y_tst[:, idx1_tst] = np.zeros(idx1_tst.shape[0])
Y tst[:, idx2 tst] = np.ones(idx2 tst.shape[0])
print(idx1_tst.shape, idx2_tst.shape)
r→ (347,) (653,)
labels tst lin = svm lin.predict(data tst.T)
labels tst gaus = svm gaus.predict(data tst.T)
np.sum(abs(labels_tst_lin - Y_tst))
┌→ 347.0
np.sum(abs(labels tst gaus - Y tst))
   150.0
 Гэ
```

```
plt.axes([1,1,1.5,1.5])
plt.scatter(data_tst[0,idx1_tst], data_tst[1,idx1_tst])
plt.scatter(data_tst[0,idx2_tst], data_tst[1,idx2_tst])
plt.xlabel('X1')
plt.ylabel('X2')
plt.title('Data and their true labels')
plt.legend(('Class -', 'Class +'))
plt.gca().set_aspect('equal', 'box')
```



```
plt.scatter(data_tst[0,np.where(labels_tst_lin == 1)[0]], data_tst[1,np.where(labels_tst_lin == 1)[0]])
plt.xlabel('X1')
plt.ylabel('X2')
plt.title('Data and their classifier decisions versus true labels')
plt.legend(('Class -', 'Class +'))
plt.gca().set_aspect('equal', 'box')
```

# С→ Data and their classifier decisions versus true labels 3 Class + 1 $\simeq$ $^{-1}$ -2 -3 -3 X1

```
al = np.where((labels_tst_gaus == 1) & (Y_tst == 0))[1] bl = np.where((labels_tst_gaus == 0) & (Y_tst == 1))[1] plt.axes([1,1,2,2]) plt.scatter(data_tst[0,idx1_tst], data_tst[1,idx1_tst])
```

## Data and their classifier decisions versus true labels Class -Class + 3 Class - as Class + Class + as Class -2 0 $\aleph$ $^{-1}$ -2 -3 -3 -2 -1 Ó Х1

print(idx1\_tst.shape[0] - a1.shape[0],idx2\_tst.shape[0] -b1.shape[0])

**□**→ 211 639