Curriculum Vitae Sri Muthu Narayanan Balasubramanian

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EDUCATION

B.E, Electrical and Electronics Engineering

2009-2013

College of Engineering Guindy, Anna University, Chennai First Class with CGPA - 8.2

Higher Secondary Education

2007-2009

Tamil Nadu Board of Higher Secondary Education SRV Boys Higher Secondary School, Namakkal **First Class** with **Distinction** (Aggregate of 97.58%)

WORK EXPERIENCE

Associate Engineer, Electronics and Systems Integration,

July '13 till date

Caterpillar Inc.

Summer Internship at Insystronics Technologies

May '12

TEST SCORES

Graduate Records Examination (GRE)

Aug '14

Quantitative Reasoning: 167 Verbal Reasoning: 162 Analytical Writing: 5.0

TOEFL (iBT) Aug '14

Reading: 29 Listening: 30 Speaking: 28 Writing: 30 Total: 117

PROJECTS

Primary Display Module Application development (Caterpillar)

Aug '13 till date

- Working on Application source code development in Embedded C for Primary Display ECU (Electronic Control Unit) for Articulated Trucks and Motor graders.
- Currently working on implementation of calibration protocol for Motor Graders.

Data Link simulator for Hardware-In-Loop (HIL) simulations (Caterpillar) Jan '14 till date

- Currently working on the research project in developing customized data link simulator with multiple protocol support (including CAN/J1939 public and proprietary protocols) for HIL simulations during development and testing of ECUs.
- Working on the implementation using Zero Message Queue (ZMQ) high performance asynchronous messaging library.

Display ECU Test automation (Caterpillar)

Dec '13

- Spearheaded the project for automation of the HIL testing of Display ECUs.
- Onscreen data capture and validation implemented using customized OCR software.
- Test scripts were implemented in Python.

Condition monitoring and fault diagnosis of Induction motors

May '13

(Undergraduate final year project)

- Sensor data acquisition, Feature extraction, trend analysis and characterization for fault prediction in industrial induction motors.
- Cost effective monitoring and proactive warning system to minimize downtime.
- Secured "S" grade (10/10 points) for the project.

Rubik's cube solver Dec '12

(Winter vacation project)

- An autonomous solver that can mechanically solve a 3x3 Rubik's cube.
- Designed and built the setup using three individual 2-DOF servo manipulators.
- The algorithm was implemented using OpenCV on the RaspberryPi board.

Self adjusting podium microphone

Nov '12

(Winter vacation project)

- Designed and built a low-cost self adjusting podium microphone.
- Implemented the face detection and tracking using Haar cascade filters in OpenCV on the RaspberryPi processor board.

Automated 3-DOF Robotic Arm

Sep '12

- Dynamic model was created using SIMULINK and the position data for the servo motors were wirelessly transmitted to the Arduino controlled robotic arm.
- The fully automated arm can draw basic shapes and alphabets.

Tire Pressure Monitoring System

May '12

(Insystronics Technologies, Embedded systems design company)

- Involved in the development of cost effective prototype Tire Pressure Monitoring System for budget cars.
- Worked on sensor data acquisition and indication system design.

Automated Guided Vehicle

Feb '11

(Funded by CEG Tech forum - the Mega project during Kurukshetra 2011)

- A fully autonomous, self-guided industrial robot for industrial applications.
- Worked on the design of electronics and path planning algorithm.

Line Follower with vision based obstacle avoidance

Oct '10

(University Grants Commission sponsored project)

- An autonomous line follower robot with camera module for obstacle avoidance.
- Image processing for obstacle avoidance was implemented using MATLAB.

TECHNICAL SKILLS

Simulation and modeling : MATLAB, Vector tools (CANalyzer/CANoe) Programming : Python, C, C++, Java, VBA, Embedded C

Platforms : Windows, Linux (Ubuntu), WinCE

Miscellaneous : Pspice, DesignSpark PCB, OpenCV, NI Vision

AREAS OF INTEREST

- Intelligent Transport systems
- Embedded systems and software
- Robotics, Automation and Computer Vision
- Control systems

ORGANIZATIONAL ROLES

- Co-founder of Illuminati, a tech hub for spreading technical knowledge through workshops.
- President of The Robotics Club of CEG.
- Student Director at the CEG Tech Forum.
- Secretary of Sruthilaya, the light music orchestra of CEG.

AWARDS AND ACHIEVEMENTS

- Recipient of Government of India Scholarship throughout under graduate course for ranking among the top 0.1% in the state's high school board exam.
- Ranked in the top 0.02% of TamilNadu Engineering admission applicants in 2009.
- Competitively awarded the sponsorship for a project during second year by The University Grants Commission (UGC).
- Winner of various robotics and circuit debugging contests at National level technical symposiums around the country.

OTHER SKILLS AND ACTIVITIES

- Holder of **Performer's Certificate**(Grade 7) in **Digital Keyboard**, Trinity College of music, London.
- Trained 6 Sigma Green Belt.
- Trained in AGILE Mindset and Practices.
- Volunteer at Chinmaya Mission, an international socio-cultural non-profit organization.

CONTACT INFORMATION

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