assignment2_srinath

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Srinath Madhwa Prasad (600264)

1 Exercise on Convolutional Neural Networks

In this exercise you will extend and improve the accuracy of the Convolution Neural Network discussed in the demonstration by doing the following things:

Creating a deep Convolutional Neural Network.

Tweaking the hyper-parameters such as the number of channels in each layer, activation functions, mini batch size, etc;

The architecture of the network that we will create is similar to the figure below (This figure will not be displayed when exported to .pdf):

We will begin by first importing the necessary python libraries:

```
In [1]: import os
        import six.moves.cPickle as pickle
        import gzip
        import numpy
        import theano
        import theano.tensor as T
        import matplotlib.pyplot as plt
        import random as rd
        from theano.tensor.signal import pool
        from theano.tensor.nnet import conv2d
        from exercise_helper import load_data, pooling, convLayer
        from exercise_helper import fullyConnectedLayer
        from exercise_helper import negative_log_lik, errors
        from exercise_helper import generate_plot
        %matplotlib inline
        # Setting the random number generator
        rng = numpy.random.RandomState(23455)
        rd.seed(23455)
        print('***** Import complete *****')
***** Import complete ****
```

Note: If the import of 'exercise_helper' fails, ensure that 'exercise_helper.py' is in the same folder as this notebook.

Now we can create the Theano Computation Graph. We shall partition the data into minibatches and then create a computation graph for training, validation and testing. The overall logic is very similar to the demonstration. Refer to the demonstration for more details.

```
for e.g. 2 layers - [20, 50].
#.
               layer1 = 20, layer2 = 50
# mini_batch_size - Mini-batch size to be used
# activation - Activation function to use
# Outputs:
# Plot of the cost, prediction errors on validation set and
# visualisation of weights of the first convolutional layer
# Partitioning into mini- batches
n_train_batches = train_set_x.get_value(borrow=True).shape[0]
n_valid_batches = valid_set_x.get_value(borrow=True).shape[0]
n_test_batches = test_set_x.get_value(borrow=True).shape[0]
n_train_batches //= mini_batch_size
n_valid_batches //= mini_batch_size
n_test_batches //= mini_batch_size
print('train: %d batches, test: %d batches,'
     ' validation: %d batches'
     % (n_train_batches, n_test_batches, n_valid_batches))
mb_index = T.lscalar() # mini-batch index
x = T.matrix('x') # rasterised images
y = T.ivector('y') # image labels
layer_weights = [];
print('***** Constructing model ***** ')
# Reshaping matrix of mini_batch_size set of images into a
layer0_input = x.reshape((mini_batch_size, 1, 28, 28))
# Construct first convolution and pooling layer
# Hint: Use the convLayer function. See demonstration.
[layer0_output, layer0_params] = convLayer(
rng,
data_input=layer0_input,
image_spec=(mini_batch_size, 1, 28, 28),
filter_spec=(num_filters[0], 1, 5, 5),
pool_size=(2, 2),
activation=T.tanh)
#layer1_input = layer0_output.reshape((mini_batch_size, 9, 24, 24))
```

```
# Construct second convolution and pooling layer
# Hint: Use the convLayer function. See demonstration.
[layer1_output, layer1_params] = convLayer(
   data_input=layer0_output,
   image_spec=(mini_batch_size, num_filters[0], 12, 12),
   filter_spec=(num_filters[1], num_filters[0], 5, 5),
   pool_size=(2, 2),
   activation=T.tanh)
# Classify the values using the fully-connected
# activation layer.
# Hint: Remember to flatten the output from the
# convolutional layer. Use the fullyConnectedLayer function.
# See demonstration.
fc_layer_input = layer1_output.flatten(2)
[p_y_given_x, y_pred, fc_layer_params] = fullyConnectedLayer(
data_input=fc_layer_input,
num_in=num_filters[1]*4*4,
num_out=10)
# Cost that is minimised during stochastic descent.
cost = negative_log_lik(y=y, p_y_given_x=p_y_given_x)
# Creating a function that computes the mistakes on the test set
# mb_index is the mini_batch_index
test_model = theano.function(
    [mb_index],
   errors(y, y_pred),
   givens={
       x: test set x[
           mb_index * mini_batch_size:
           (mb_index + 1) * mini_batch_size],
```

```
y: test_set_y[
           mb_index * mini_batch_size:
           (mb_index + 1) * mini_batch_size]})
# Creating a function that computes the mistakes on the validation
valid_model = theano.function(
   [mb_index],
   errors(y, y_pred),
   givens={
       x: valid_set_x[
           mb_index * mini_batch_size:
           (mb_index + 1) * mini_batch_size],
       y: valid_set_y[
           mb_index * mini_batch_size:
           (mb index + 1) * mini batch size]})
# Create list of parameters to fit during training.
# Hint: Include the parameters from the two convolution layers
# and activation layer
params = fc_layer_params + layer0_params + layer1_params
# Creating a list of gradients
grads = T.grad(cost, params)
# Creating a function that updates the model parameters by SGD.
# The updates list is created by looping over all
# params[i], grads[i]) pairs.
updates = [(param_i, param_i - learning_rate * grad_i)
          for param_i, grad_i in zip(params, grads)]
train_model = theano.function(
   [mb_index],
   cost,
   updates=updates,
   givens={
       x: train_set_x[
           mb_index * mini_batch_size:
           (mb_index + 1) * mini_batch_size],
       y: train_set_y[
           mb_index * mini_batch_size:
           (mb_index + 1) * mini_batch_size]})
```

```
epoch = 0
cost_arr = numpy.array([])
valid_score_arr = numpy.array([])
valid_score_arr = numpy.append(valid_score_arr, 1)
print('***** Training model *****')
if (num_epochs < 1):</pre>
    print("Too few epochs!")
    return
while (epoch < num_epochs):
    epoch = epoch + 1
    print("Training in epoch: %d / %d" % (epoch, num_epochs),
          end=' \r'
    for minibatch_index in range(n_train_batches):
        # Computing number of iterations performed or total number
        # of mini-batches executed.
        iter = (epoch - 1) * n_train_batches + minibatch_index
        # cost of each minibatch
        cost_ij = train_model(minibatch_index)
        cost_arr = numpy.append(cost_arr, cost_ij)
    # Computing loss on each validation mini-batch after each epoch
    valid_losses = [valid_model(i) for i in range(n_valid_batches)]
    valid_score_arr = numpy.append(
                                   valid_score_arr,
                                    numpy.mean(valid_losses))
print('***** Training Complete *****')
# Computing mean error rate on test set
test_losses = [test_model(i) for i in range(n_test_batches)]
test_score = numpy.mean(test_losses)
print('Prediction error: %f %%' % (test_score * 100.))
# Generating the plots
generate_plot(cost_arr, range(1, iter+2),
              valid_score_arr,
              range(0, epoch+1),
              layer0_params[0].get_value())
```

1.0.1 Experiment

Now we shall define some hyper-parameters and evaluate the model. We will compute the final Prediction Error on the test set. To complete this assignment, you must do the following things:

Set your parameters in the cell below

Run the experiment. Then, describe and discuss it in the 'Conclusions' cell below. You must do this for each experiment that you run.

Especially in CSC notebooks, do not forget to restart the kernel after each experiment.

Repeat from step 1 and perform at least 4 experiments.

Run the experiment with the best result again to display the plots in the final submission.

Download the completed assignment as PDF and submit as usual. The final PDF will contain

the plots from only your best experiment as well as the discussion of all your experiments in the 'Conclusions' cell.

```
# Description and examples of parameters to train_test_conv_net()
       # learning_rate - Sets the learning rate for Stochastic Gradient
                        Descent. e.g.: 0.1
       # num_epochs - Sets the number of training epochs. E.g.: 10
       # num_filters - Sets the number of kernels for each
                      convolution layer. for e.g. 2 layers: [4, 8]
                      implies layer1 = 4, layer2 = 8
       # mini_batch_size - Sets the mini-batch size to be used in
                          the experiment. E.g: 50
       # activation - Sets the activation function to be used.
                     E.q.: T.tanh
       # train_size - Sets the number of training samples to be used.
       #
                     E.q. 6000.
       # Note: The Kernel may crash on too large values of the
       # num_epochs, num_filters, mini_batch_size and train_size due to
       # memory limitations. This may happen especially on CSC notebooks
       # as it is a shared resource.
       # If that happens use smaller values!
       learning_rate = 0.1
       num_epochs
                      = 20
       num_filters = [32, 64]
       mini_batch_size = 50
       activation = T.nnet.sigmoid
       train_size = 30000
       *************************************
       # Loading dataset
       # We use only a subset of the full dataset.
       # Validation and test sets will be 1/3 of train
       # set size
       datasets = load_data('mnist.pkl.gz', train_size)
       train_set_x, train_set_y = datasets[0]
       valid_set_x, valid_set_y = datasets[1]
       test_set_x, test_set_y = datasets[2]
       print('Training set: %d samples'
             %(train_set_x.get_value(borrow=True).shape[0]))
       print('Test set: %d samples'
             %(test_set_x.get_value(borrow=True).shape[0]))
       print('Validation set: %d samples'
```

```
%(valid_set_x.get_value(borrow=True).shape[0]))
```

Beginning the training process

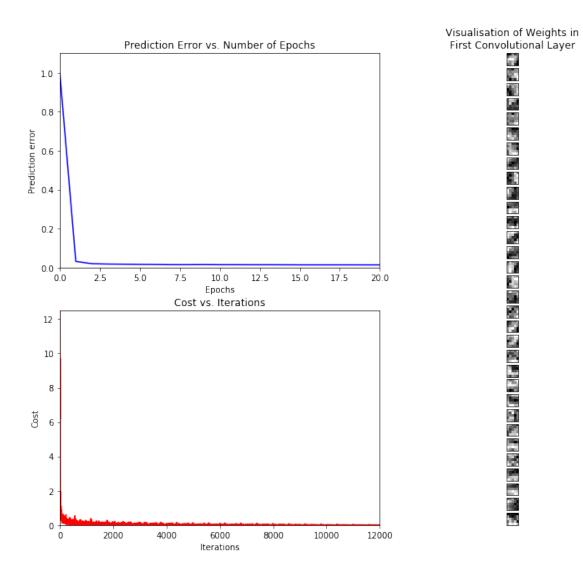
train_test_conv_net(learning_rate, num_epochs, num_filters, mini_batch_size, activation)

**** Loading data **** Training set: 30000 samples Test set: 10000 samples

Validation set: 10000 samples

train: 600 batches, test: 200 batches, validation: 200 batches

**** Constructing model **** **** Training model **** **** Training Complete **** Prediction error: 1.390000 %



Now go ahead and experiment with different hyper-parameters such as different number of filters, different number of convolution layers, activation functions etc;. Try to find out which configuration gives the best accuracy.

1.0.2 Conclusions

The choice of activation function plays an important role in prediction error and accuracy.

As seen from the below results , the sigmoid activation function with higher number of channels gives the least prediction error then sigmoid function with lesser number of channels. The best result was obtained with least number of epochs (20) and a learning rate of 0.1. The cost reduced in lesser iterations. Apparently, the training size was high which is also main reason to reduce the prediction error.

relu function didn't perform well with higher number of channels and gave high error but with lesser number of channels it gave lesser error.

But generally we can see, with higher number of channels, the error tends to decrease.

learning_rate = 0.1 num_epochs = 10 num_filters = [9, 16] mini_batch_size = 50 activation = T.tanh train_size = 6000

Prediction error: 3.000000 %

learning_rate = 0.2 num_epochs = 12 num_filters = [9, 14] mini_batch_size = 50 activation = T.nnet.sigmoid train_size = 6000

Prediction error: 2.900000 %

num_epochs = 14 num_filters = [16, 16] mini_batch_size = 64 activation = T.nnet.relu train_size = 20000

Prediction error: 1.832933 %

learning_rate = 0.2 num_epochs = 16 num_filters = [24, 24] mini_batch_size = 80 activation = T.nnet.relu train_size = 6000

Prediction error: 4.950000 %

learning_rate = 0.1 num_epochs = 20 num_filters = [32, 64] mini_batch_size = 50 activation = T.nnet.sigmoid train_size = 30000

Prediction error: 1.390000 %

learning_rate = 0.05 num_epochs = 15 num_filters = [64, 64] mini_batch_size = 50 activation = T.tanh train_size = 20000

Prediction error: 1.759398 %

learning_rate = 0.1 num_epochs = 35 num_filters = [32, 32] mini_batch_size = 50 activation = T.nnet.relu train size = 2000

Prediction error: 4.153846 %