



# Support Vector Machines

# Lagrangian dual formulation

Formulation of Dual problem

$$\begin{aligned} &\text{Maximize } \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^T x_j \\ &\text{subject to } \sum_{i=1}^n \alpha_i y_i = 0, \quad \alpha_i \geq 0 \quad \forall i \end{aligned}$$

This a Quadratic Programming problem (QP)

This means that the parameters form a paraboloidal surface, and an optimal can be found(since it is convex function).

## SVM training phase

Maximize  $L_D$  w.r.t.  $\alpha_i$  such that  $\alpha_i \geq 0$  with the solution  $w = \sum_{i=1}^n \alpha_i y_i x_i$

In the solution those points for which  $\alpha_i > 0$  are support vectors and they lie on Hyperplanes  $H_1$  or  $H_2$ .

For other points  $\alpha_i = 0$  and lie on the either sides of  $H_1$  or  $H_2$  such that

$$y_i (w^T x_i + b) > 1, \forall i$$

## SVM test phase

In order to classify a new instance  $z$  we just have to compute.

$$\text{sign}(w^T z + b) = \text{sign}\left(\sum_{\forall i \in SV} \alpha_i y_i x_i^T z + b\right)$$

This means that  $w$  does not need to be explicitly computed

# SVM:Example

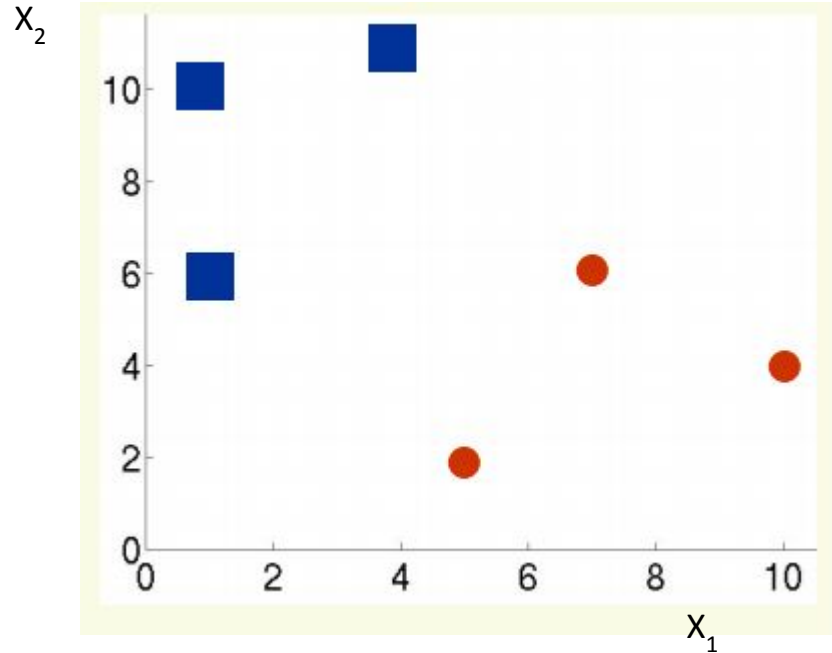
Given data :

Class-1 :  $[1,6]$  ,  $[1,10]$  ,  $[4,11]$

Label  $y_i = 1$

Class-2 :  $[5,2]$  ,  $[7,6]$  ,  $[10,4]$

Label  $y_i = -1$



# SVM:Example

To represent all inputs consider array X

$$X = \begin{pmatrix} 1 & 6 \\ 1 & 10 \\ 4 & 11 \\ 5 & 2 \\ 7 & 6 \\ 10 & 4 \end{pmatrix} \quad \text{and labels } Y = \begin{pmatrix} 1 \\ 1 \\ 1 \\ -1 \\ -1 \\ -1 \end{pmatrix}$$

# SVM:Example

$$Y^T.Y = \begin{pmatrix} 1 & 1 & 1 & -1 & -1 & -1 \\ 1 & 1 & 1 & -1 & -1 & -1 \\ 1 & 1 & 1 & -1 & -1 & -1 \\ -1 & -1 & -1 & 1 & 1 & 1 \\ -1 & -1 & -1 & 1 & 1 & 1 \\ -1 & -1 & -1 & 1 & 1 & 1 \end{pmatrix}$$

$$X.X^T =$$

$$\begin{pmatrix} 37 & 61 & 70 & 17 & 43 & 34 \\ 61 & 101 & 114 & 25 & 67 & 50 \\ 70 & 114 & 137 & 42 & 94 & 84 \\ 17 & 25 & 42 & 29 & 47 & 58 \\ 43 & 67 & 94 & 47 & 85 & 94 \\ 34 & 50 & 84 & 58 & 94 & 116 \end{pmatrix}$$

# SVM:Example

Therefore Matrix  $H$  with  $H_{ij} = y_i y_j x_i^T x_j$  can be written as

$$H = Y^T Y . X^T X =$$

37	61	70	-17	-43	-34
61	101	114	-25	-67	-50
70	114	137	-42	-94	-84
-17	-25	-42	29	47	58
-43	-67	-94	47	85	94
-34	-50	-84	58	94	116



# SVM:Example in Matlab

Matlab expects quadratic programming to be stated in the canonical (standard) form which is

minimize  $L_D(\alpha) = \mathbf{f}^T \alpha + \frac{1}{2} \alpha^T \mathbf{H} \alpha$  constrained to  $\mathbf{A}\alpha \leq \mathbf{a}$  and  $\mathbf{B}\alpha = \mathbf{b}$ .

where A,B,H are n by n matrices and f, a, b are vectors

Need to convert our optimization problem to canonical form

Maximize 
$$L_D(\alpha) = \sum_{i=1}^n \alpha_i - \frac{1}{2} \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}^T \mathbf{H} \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}$$
 constrained to 
$$\sum_{i=1}^n \alpha_i y_i = 0, \quad \alpha_i \geq 0 \quad \forall i$$

## SVM:Example in Matlab

Multiply by  $-1$  to convert to minimization:  $L_D(\alpha) = - \sum_{i=1}^n \alpha_i + \frac{1}{2} \alpha^T H \alpha$

Let  $f = \begin{bmatrix} -1 \\ \vdots \\ -1 \end{bmatrix} = \text{-ones}(6,1)$ , then we can write

$$\text{Minimize } L_D(\alpha) = f^T \alpha + \frac{1}{2} \alpha^T H \alpha$$

First constraint is  $\alpha_i \geq 0 \quad \forall i$

$$A = \begin{bmatrix} -1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & -1 \end{bmatrix} = -\text{eye}(6), \quad a = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} = \text{zeros}(6,1)$$

Rewrite the first constraint in canonical form :  $A\alpha \leq a$

## SVM:Example in Matlab

Our Second constraint is  $\sum_{i=1}^n \alpha_i y_i = 0, \quad \alpha_i \geq 0 \quad \forall i$

Let  $B = [[Y] ; [\text{zeros}(5,6)]]$

and  $b = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} = \text{zeros}(6,1)$

Second constraint in canonical form is  $B\alpha = b$ .

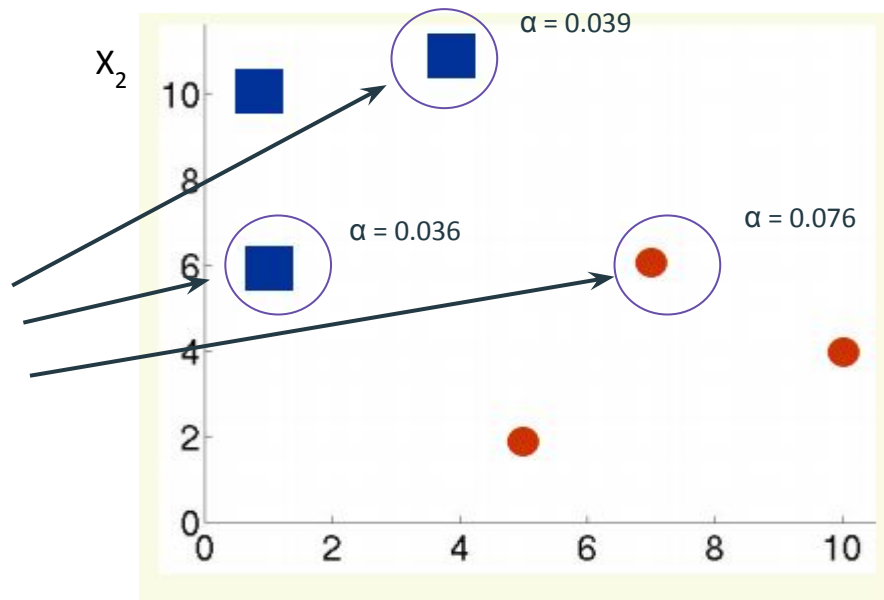
$\alpha = \text{quadprog}(H, f, A, a, B, b)$  %%in matlab

# SVM:Example

Solution

$$\alpha = \begin{pmatrix} 0.036 \\ 0 \\ 0.039 \\ 0 \\ 0.076 \\ 0 \end{pmatrix}$$

Support  
Vectors



Find  $W$  using  $w = \sum_{\forall i \in SV} \alpha_i y_i x_i = (\alpha \cdot Y)^T \cdot X$

## SVM:Example

$$\alpha .Y = [0.036 , 0 , 0.04 , -0 , -0.076 , -0]$$

$$W = (\alpha .Y)^T .X = [-0.33 , 0.20] \Rightarrow w_1 = -0.33 \quad w_2 = 0.20$$

We can find b using  $w^T x_i + b = 1$  for positive support vector  $i = 1$

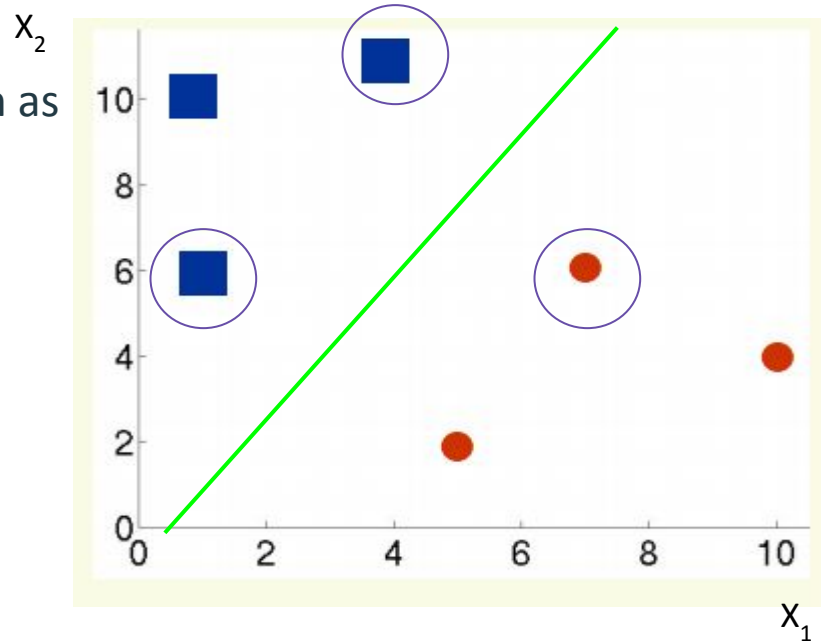
$$\begin{aligned} b &= 1 - w^T x_1 = 1 - (-0.33 \times 1 + 0.20 \times 6) = 1 - (-0.33 + 1.20) \\ &= 0.13 \end{aligned}$$

# SVM:Example

Equation of the line can be written as

$$-0.33 X_1 + 0.20 X_2 + 0.13 = 0$$

(since  $w^T x_i + b = 0$ )



# SVM:Example

## Testing Phase:

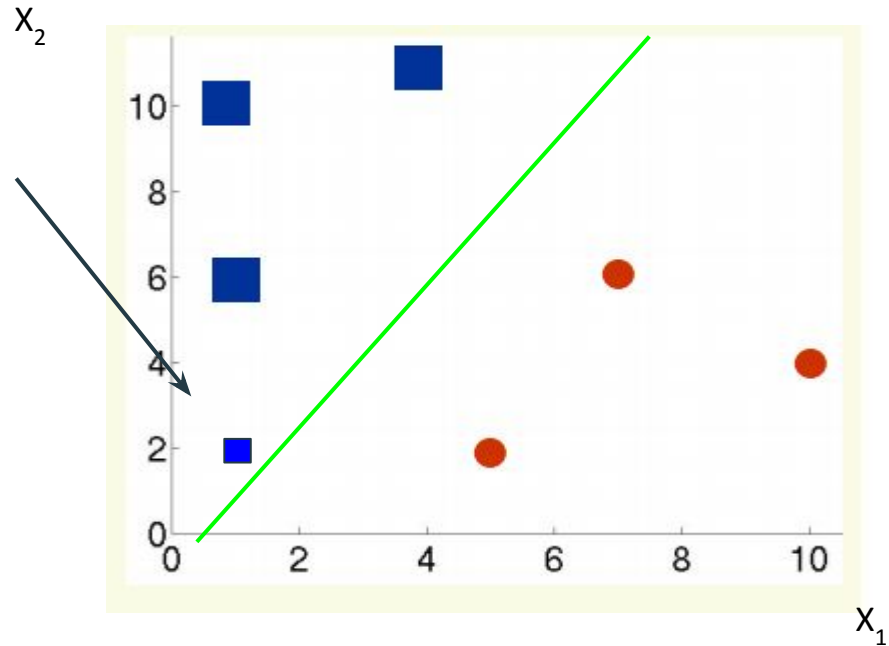
Suppose give a new point  $z = [1,2]$

Find  $\text{sign}(w^T z + b)$  :

$\text{sign}(-0.33x_1 + 0.20x_2 + 0.13)$

$\text{sign}(-0.07 + 0.13) = \text{positive}$

**Therefore  $z$  is in class 1**

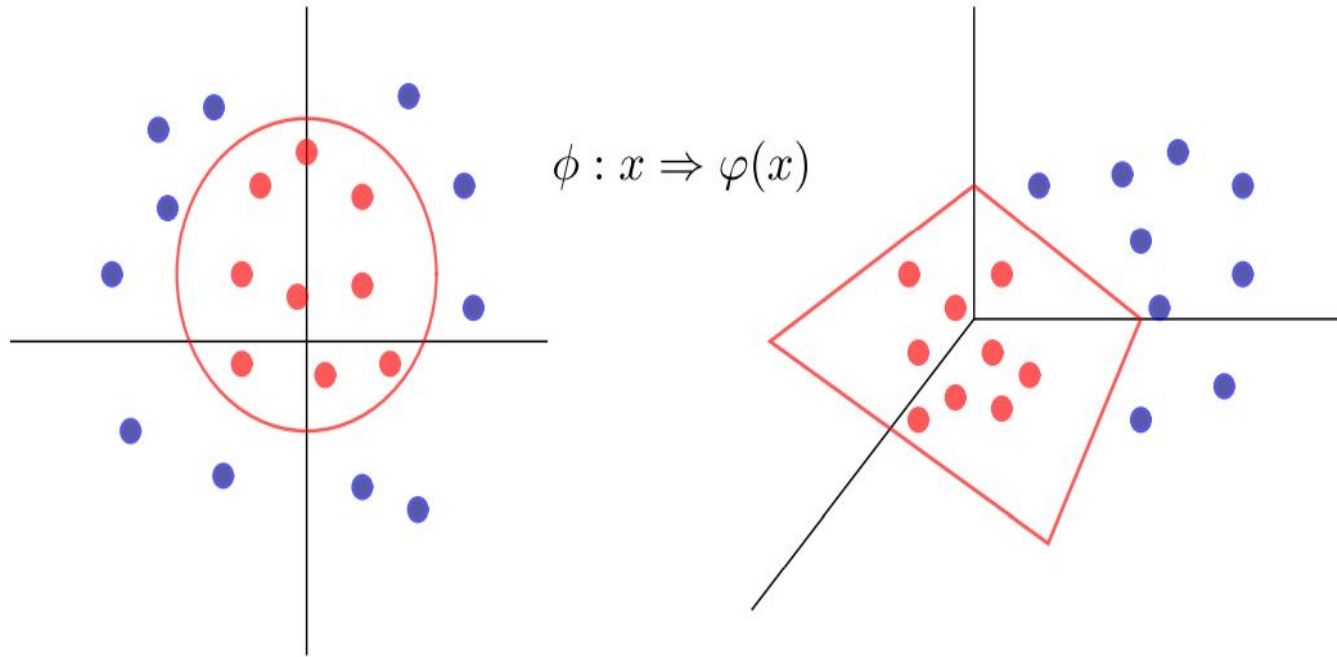


# SVM: Non-linear classification

- So far we have only considered large margin classifiers that use a linear boundary.
- In order to have better performance we have to be able to obtain non-linear boundaries.
- The idea is to transform the data from the input space (the original attributes of the examples) to a higher dimensional space using a function  $\varphi(x)$ .
- This new space is called the feature space .
- The advantage of the transformation is that linear operations in the feature space are equivalent to non-linear operations in the input space.



# Feature Space transformation



## XOR - Problem

The XOR problem is not linearly separable in its original definition, but we can make it linearly separable if we add a new feature  $x_1 \cdot x_2$

$x_1$	$x_2$	$x_1 \cdot x_2$	$x_1 \text{ XOR } x_2$
0	0	0	1
0	1	0	0
1	0	0	0
1	1	1	1

The linear function  $h(x) = 2x_1x_2 - x_1 - x_2 + 1$  classifies correctly all the examples.

Thank you