Algebraic and Semi-Algebraic Reasoning For Formal Methods

Lecture 5 - Sum of Squares Programming.

Sriram Sankaranarayanan

Sum of Squares (SOS)

A polynomial p is sum of squares (SOS) iff

$$p = \sigma_1^2 + \dots + \sigma_k^2$$

for some $k \geq 0$.

$$\quad \bullet \quad \sigma_1, \dots, \sigma_k \in \mathbb{R}[x_1, \dots, x_n].$$

Positive Polynomials vs. Sum-Of-Squares

If p is SOS then p is a positive semi-definite.

- Is the converse true?
 - Theorem # 1 Any univariate polynomial is positive semi-definite iff it is SOS.
- Theorem # 2 Any quadratic polynomial is positive semi-definite iff it is SOS.

TODO: Prove these in lecture.

There exists a polynomial that is positive semidefinite but cannot be written as a sum of squares.

Motzkin Polynomial:

$$p = x^4y^2 + x^2y^4 + 1 - 3x^2y^2 \succeq 0$$

- Prove that p is positive semi-definite.
- ullet Prove that p cannot be expressed as SOS.

Quadratic Forms and Sum of Squares

Quadratic polynomial $p(x_1, \dots, x_n)$ can be written:

$$\begin{pmatrix} 1 \\ x_1 \\ x_2 \\ \dots \\ x_n \end{pmatrix}^\top \begin{pmatrix} Q_{11} & Q_{12} & \cdots & Q_{1,n+1} \\ Q_{21} & Q_{22} & \cdots & Q_{2,n+1} \\ \vdots & & \ddots & \vdots \\ Q_{n+1,1} & Q_{n+1,2} & \cdots & Q_{n+1,n+1} \end{pmatrix} \begin{pmatrix} 1 \\ x_1 \\ x_2 \\ \dots \\ x_n \end{pmatrix}$$

SOS and **PSD** for Quadratic Forms

A quadratic form $p(\vec{x}) = \vec{x}^\top Q \vec{x}$ is positive semidefinite iff all eigenvalues of Q are non-negative.

Proof: Suppose $Q\vec{v}=\lambda\vec{v}$, λ must be real and furthermore, $\vec{v}^{\top}Q\vec{v}=\lambda\vec{v}^{\top}\vec{v}$.

- (\Rightarrow) Let p be a positive semi-definite polynomial, but Q have a negative eigenvalue $\lambda < 0$. Then $p(\vec{v}) = \lambda \vec{v}^\top \vec{v} < 0$. This is a contradiction.
- (\Leftarrow) Suppose all eigen values of Q are non-negative. Since Q is a symmetric matrix, we can write its spectral decomposition: $Q = \sum_{j=1}^n \lambda_j \vec{v}_j \vec{v}_j^\top \text{, wherein } \lambda_j \geq 0 \text{ are the eigenvalues. Therefore, } p = \vec{x}^\top Q \vec{x} \text{ can be written as}$

$$p = \sum_{j=1}^{n} \lambda_j \vec{x}^t \vec{v}_j \vec{v}_j^\top \vec{x} = \sum_{j=1}^{n} (\sqrt{\lambda_j} \vec{v}_j^\top \vec{x})^2$$

Hilbert's Seventeenth Problem

Hilbert's Seventeenth Problem: Can any positive semi-definite polynomial be written as a sum of squares of rational functions:

$$p = \sum_{j=1}^{k} \frac{\sigma_j^2}{\xi_j^2}?$$

- Hilbert showed in 1888 that not all PSD polynomials are SOS.
 - His proof did not construct an explicit counterexample.
 - Cf. Bruce Reznick, Some Concrete Aspects of the Hilbert's 17th Problem.
- Artin and Schreier'1927: Theory of real-closed fields.

Why SOS?

- Checking if a polynomial is SOS can be made efficient.
 - Reduction to semi-definite programming (convex optimization).
- Positivstellensatz using Sum of Squares.
 - Lasserre Hierarchy.

Checking SOS

Input: $p \in \mathbb{R}[x_1, \dots, x_n]$.

Output: Is
$$p=\sigma_1^2+\cdots+\sigma_k^2$$
 for $\sigma_1,\ldots,\sigma_k\in\mathbb{R}[x_1,\ldots,x_n]$?

Idea: quadratic forms but lift to a higher dimensional space.

- Originally proposed by N. Shor, 1987 (In Russian).
- Rediscovered by Lasserre'2001 and Parrilo'2003.
 - Global Optimization with Polynomials and the Problem of Moments, Jean B. Lasserre, SIAM J. Opt., 2001.
 - Semidefinite programming relaxations for semialgebraic problems, Pablo Parrilo, Math. Prog. Ser. B, 2003.

Checking Sum of Squares: Idea

Idea Write a non-quadratic polynomial as a quadratic form.

Example
$$x^4y^2 - 2x^2y^2 + 2y^2 - 2xy + x^2 + 9$$

Let
$$\mu(x,y) = \begin{pmatrix} x^2y \\ xy \\ x \\ y \\ 1 \end{pmatrix}$$
, Write $p = \mu^\top Q \mu$.

Example (Continued)

$$p = x^4y^2 - 2x^2y^2 + 2y^2 - 2xy + x^2 + 9$$

	x^2y	xy	\boldsymbol{x}	y	1
x^2y	1	0	0	-1	0
xy	0	0	0	0	0
x	0	0	1	-1	0
y	-1	0	-1	2	0
1	0	0	0	0	9

Problem: Q is not unique.

Example: Non-Uniqueness

$$p = x^4y^2 - 2x^2y^2 + 2y^2 - 2xy + x^2 + 9$$

	x^2y	xy	x	y	1
x^2y	1	0	0	0	0
xy	0	-2	0	0	0
x	0	0	1	-1	0
y	0	0	-1	2	0
1	0	0	0	0	9

 ${\cal Q}$ is not a psd matrix.

Basic Idea.

- $\quad \hbox{Fix a vector of monomials } \mu(x_1,\dots,x_n).$
- lacktriangle Try to write polynomial p as
 - $p = \mu^\top Q \mu$
 - ullet Q is a positive semidefinite matrix.
- However, there are infinitely many ways of doing so.
 - We need to discover one way to do it!

Constraint Problem

Let
$$p = \sum_{\alpha \in \mathbb{N}^n} c_{\alpha} \vec{x}^{\alpha}$$
.

- M(p): set of monomials in p.
- Choose a monomial basis $\mu(\vec{x}) = [\beta_1, \dots, \beta_k]$.
 - Every $\alpha \in M(p)$ can be written as the sum of two monomials in the basis.
- Let Q be an unknown positive semi-definite matrix that we seek.
- Question: What are the constraints on Q?

Constraint Problem (continued)

For every monomial $\alpha \in M(p)$, let

$$C(\alpha) = \{(i, j) \mid \beta_i + \beta_j = \alpha\}$$

Each monomial imposes a constraint on the entries of Q:

$$\sum_{(i,j) \in C(\alpha)} Q_{i,j} = c_\alpha$$

- Linear equality involving entries of ${\cal Q}.$

Constraint Problem (continued)

find
$$Q \in \mathbb{R}^{|\mu| \times |\mu|}$$
 s.t.
$$\vdots \\ (C_{\alpha},Q) = c_{\alpha} \leftarrow \text{ linear equations over entries of } Q \\ \vdots \\ Q \succeq 0 \leftarrow \text{PSD constraint}$$

This is called a semi-definite programming problem (SDP).

Semi-Definite Programming

Trace inner product:

$$\qquad (A,B) = \operatorname{tr}(A \times B) = \textstyle \sum_i \sum_j A_{i,j} B_{i,j}.$$

SDP Problem: Decision Variable $X \in \mathbb{R}^{n \times n}$.

$$\begin{aligned} & \min & (C,X) \\ & (A_1,X) = b_1 \\ & \vdots \\ & (A_m,X) = b_m \\ & X \succeq 0 \end{aligned}$$

Semi-Definite Programming

Semidefinite Programming, S. Boyd and L. Vandenberghe, SIAM REVIEW Vol. 38, No. 1, pp. 49-95, March 1996.

- Lots of applications of SDPs,
 - Engineering design problems
 - Data Analysis Problems
 - Approximation Algorithms
- Properties of SDPs,
- Techniques for Efficient Solution.

Semi-Definite Programming: Primal vs. Dual Forms

$$\begin{array}{lll} \min & (C,X) \\ \text{s.t.} & (A_1,X) = b_1 \\ & \vdots \\ & (A_m,X) = b_m \\ & X \succeq 0 \end{array} \qquad \begin{array}{ll} \min & \sum_{j=1}^m b_j x_j \\ \text{s.t.} & C + \sum_{j=1}^m x_i A_i \ \succeq \ 0 \end{array}$$

Note: both forms are interchangable.

SDP: Solution

$$\begin{aligned} & \min & & (C,X) \\ & \text{s.t.} & & (A_1,X) = b_1 \\ & & & \vdots \\ & & & (A_m,X) = b_m \\ & & & X \succeq 0 \end{aligned}$$

- Infeasible
- Unbounded
- Feasible and Optimal
 - Symmetric PSD matrix X.
 - X satisfies the constraints.
 - Minimizes the objective.

Solving SDPs

- Interior point methods.
- Basic Idea: Use a barrier function.
- TODO Illustrate what barrier functions are and how interior point methods work.

Solving SDPs: Convergence

- Requires strict feasibility.
 - There exists a solution $X \succ 0$ satisfying constraints.
- Guaranteed to get a solution that is within $\epsilon>0$ distance of optimal solution.
 - Time complexity in problem size and $\log(\frac{1}{\epsilon})$.
 - $\qquad \hbox{ Arithmetic operations are typically } O(1). \\$

SDP Numerics

SDPs are typically solved using floating point arithmetic.

• Some extended precision solvers such as SDPA.

Optimal solution need not be rational.

$$\begin{array}{ll} \max & X_{1,2} \\ \text{s.t.} & X_{1,1} = 1 \\ & X_{2,2} = 2 \\ & X \succeq 0 \end{array}$$

• Optimal solution is $\sqrt{2}$.

SDP Numerics (continued)

- SDP solution verification.
 - Check that matrix X is a PSD.
 - Can use Cholesky decomposition.
 - Check that the equality constraints are satisfied.

Cf. Roux, Voronin and Sank. Validating Numerical Semidefinite Programming Solvers for Polynomial Invariants, SAS 2016 and STTT 2018.

Sum of Squares Checking

Given $p \in \mathbb{R}[x_1, \dots, x_n]$, how do we find the monomials needed for μ ?

• Hint: consider maximum degree in each variable.

Newton Polytope: Consider $p = \sum_{\alpha \in \mathbb{N}^n} c_{\alpha} \vec{x}^{\alpha}$.

- Collect all monomials as vectors $\alpha \in \mathbb{N}^n$ such that $c_{\alpha} \neq 0$.
- Compute the convex hull P of the vectors in \mathbb{N}^n corresponding to the monomials.
- Compute all the points in $\frac{1}{2}P$.
- Any monomial \vec{x}^{β} appears in the SOS decomposition of p iff $\beta \in \frac{1}{2}P.$

Proving Entailments

$$(\forall x, y \in \mathbb{R}) \quad x^2 + y^2 \le 1 \ \land \ x + y \le 0 \ \Rightarrow \ y \le 1.423$$

Why?

$$(1.423-y) = \left(\begin{array}{c} 0.765134 \ \, (1-x^2-y^2) \ + \\ 0.4 \ \, -(x+y) \ + \\ 0.6574-0.6x+0.4y+0.765134(x^2+y^2) \end{array} \right)$$

Positivstellensatz

Consider entailment over \mathbb{R}^n :

$$p_1 \geq 0 \ \land \ \cdots \ \land \ p_m \geq 0 \ \models \ p \geq 0$$

One approach is to try to convert to real Nullstellensatz.

Inequalities to Equalities

Consider polynomials over $p \in \mathbb{R}[x_1, \dots, x_n]$.

- Let t be a fresh variable.
- $p \ge 0 \Leftrightarrow p = t^2$
- $p>0 \Leftrightarrow t^2p=1$
- $p \neq 0 \Leftrightarrow tp = 1$

Convert entailment back to equalities.

Real Varieties

Given $p_1,\dots,p_m\in\mathbb{R}[x_1,\dots,x_n]$, define the $\mathit{real\ variety}$ as

$$V = \{\vec{x} \in \mathbb{R}^n \mid \bigwedge_{j=1}^m p_j = 0\}$$

- We already saw the importance of algebraic closure.
 - Real variety of $1 + x^2 = 0$.

Theorem $V=\emptyset$ if and only if $1+\sigma\in\langle p_1,\dots,p_m\rangle$, where σ is SOS.

Positivestellensatz

Let
$$S=\{\vec{x}\in\mathbb{R}^n\ |\ p_1(\vec{x})\geq 0\ \wedge\ \cdots\ \wedge\ p_m(\vec{x})\geq 0\}.$$

- We wish to show that $p \ge 0$ on S for given p.
- **Important:** We will need S to be compact.

Schmugden's Positivstellensatz

Enrich the set of polynomials

$$Q(S) = \{p_1^{e_1} \cdots p_m^{e_m} \ | \ e_i \in \{0,1\}\}$$

Note: $|Q(S)| = 2^m$.

Theorem (Schmugden'1991)

- $\begin{array}{l} \bullet \quad \text{If } p = \sum_{q \in Q(S)} \sigma_q q \text{ for } \sigma_q \text{ SOS then} \\ p_1(\vec{x}) \geq 0 \ \land \ \cdots \ \land \ p_m(\vec{x}) \geq 0 \models p \geq 0. \end{array}$
- $\begin{array}{l} \bullet \quad \text{Conversely, if } p_1(\vec{x}) \geq 0 \ \, \wedge \, \, \cdots \, \, \wedge \, \, p_m(\vec{x}) \geq 0 \models p > 0 \\ \text{then } p = \sum_{q \in Q(S)} \sigma_q q \text{ for } \sigma_q \text{ SOS.} \end{array}$

Putinar's Positivstellensatz

Let
$$M = \{\sum_{j=1}^m \sigma_j p_j + \sigma_0 \mid \sigma_0, \dots, \sigma_m \text{ SOS}\}.$$

• Archimedean Property: There exists a K such that

$$K-(x_1^2+\cdots+x_n^2)\in M$$

If time permits, explain connection to Archimedes.

Theorem (Putinar'1993)

- $\quad \quad \text{If } p \in M \text{ then } p_1 \geq 0 \ \land \ \cdots \land \ p_m \geq 0 \ \models \ p \geq 0.$
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Positivstellensatz to Semi-Definite Programming

Problem: prove the following entailment.

$$p_1 \geq 0 \ \land \ \cdots \ \land \ p_m \geq 0 \ \models \ p \geq 0$$

Strategy: Find, $\sigma_0, \dots, \sigma_m$ such that

$$p = \sigma_0 + \sum_{j=1}^m \sigma_j p_j, \text{ and } \sigma_j \text{ SOS}$$

- Bound the degrees of $\sigma_0,\ldots,\sigma_m\in\mathbb{R}_{2d}[\vec{x}].$

Reduction to SDP

- Fix a basis of monomials $\mu(\vec{x})$.
- $\bullet \quad \sigma_i = \mu^t X_i \mu$
- $p = \sigma_0 + \sum_{j=1}^m \sigma_j p_j$
 - Equate monomials on LHS and RHS.

• Place X_1, \dots, X_n in a block diagonal form.

$$X = \left[\begin{array}{cccc} X_1 & 0 & \cdots & 0 \\ 0 & X_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & 0 \\ 0 & 0 & \cdots & X_n \end{array} \right]$$

Next Lecture

- Demonstrate using Sum Of Squares Programming in JuMP.
- Connections to combinatorial optimization.
- Applications:
 - Barriers for differential equations.
- Discussion of Open Challenges.
 - Proofs and Floating Point Numbers.
 - Dealing with non-polynomial functions.