





Decision Analytics

Lecture 3: Mathematical Optimisation

Given a domain D and an objective function

$$f:D\to\mathbb{R}$$

find $\hat{x} \in D$ that minimises f, i.e. $\forall x \in D : f(\hat{x}) \leq f(x)$

(for maximisation problems replace f with -f)

- Different optimisation techniques are applicable depending on
 - The properties of the domain *D*
 - The shape of the objective function f

- Special case 1:
 - Domain is $D = \mathbb{R}^n$
 - Objective function f is differentiable
- Then a necessary condition for a local minimum/maximum of the objective function f is

$$\frac{\partial}{\partial x}f = 0$$

• This condition can be either solved directly or by neighbourhood search algorithms (gradient descent, simulated annealing)

- Special case 2:
 - Domain D = $\{x \in \mathbb{R}^n | g(x) = 0\}$ is a manifold
 - Objective function f and implicit constraint g is differentiable
- Then a necessary condition for a local minimum/maximum of f is

$$\frac{\partial}{\partial x}(f + \lambda^T g) = 0$$
$$\frac{\partial}{\partial \lambda}(f + \lambda^T g) = 0$$

• This conditions essentially add the Lagrange parameter λ to the search domain and reduce the problem to the previous case

- Special case 3:
 - Domain D = $\{x, y \in \mathbb{R}^{n+m} | Ax + By = c\}$
 - Objective function $f = (y \bar{y})^2$
- This is a special case of the previous problem with a quadratic objective function and a linear manifold as domain
- The Lagrange function in this case is

$$L(x, y, \lambda) = (y - \overline{y})^2 + \lambda^T (Ax + By - c)$$

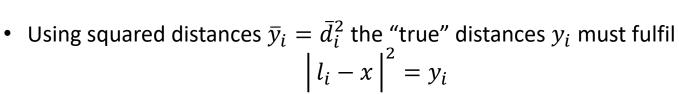
• Its derivatives form a system of linear equations, that can be solved for (x, y, λ)

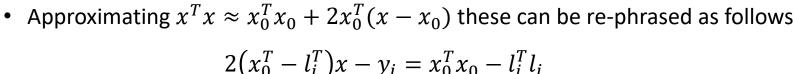
$$\frac{\partial}{\partial x}L(x,y,\lambda) = \lambda^T A = 0$$

$$\frac{\partial}{\partial y}L(x,y,\lambda) = 2(y-\bar{y}) + \lambda^T B = 0$$

$$\frac{\partial}{\partial \lambda}L(x,y,\lambda) = Ax + By - c = 0$$

- Special case 3:
 - Domain D = $\{x, y \in \mathbb{R}^{n+m} | Ax + By = c\}$
 - Objective function $f = (y \bar{y})^2$
- Example: Radio location
 - Given the cell-tower locations l_1, \dots, l_n
 - and distance measurements $ar{d}_1$, ..., $ar{d}_n$
 - Where is the mobile device *x*?





• Minimising the residual between measured distances and "true" distances $(y - \bar{y})^2$ has the structure of the optimisation problem stated above

- Special case 4:
 - Domain $D = \{x \in \mathbb{R}^n | x \ge 0 \land Ax \le b\}$ is bound by linear constraints
 - The objective function is linear $f = c^T x$
- This can be solved by Linear Programming (LP)
- Very efficient algorithms exist to solve LP problems, the Google OR Tools provide a front-end for various solvers, e.g.:

```
from ortools.linear_solver import pywraplp

solver = pywraplp.Solver('LP',

pywraplp.Solver.GLOP_LINEAR_PROGRAMMING)
```

- Special case 4:
 - Domain $D = \{x \in \mathbb{R}^n | x \ge 0 \land Ax \le b\}$ is bound by linear constraints
 - The objective function is linear $f = c^T x$
- Example: Combined Heat and Power (CHP) optimisation
 - A CHP can be set to run at $0 \le p_i \le 1$ percent of its total capacity
 - Its maximum thermal output is T_i and its maximum electrical output is E_i
 - The goal is to satisfy thermal demand $\sum_i p_i T_i \geq D_T$ as well as electrical demand $\sum_i p_i E_i \geq D_E$ while minimising fuel cost $\sum_i p_i c_i$
 - Excess thermal energy can be easily dumped, however the grid imposes a maximum amount of electrical energy it can take, i.e. $\sum_i p_i E_i D_E \leq M_E$



- Special case 5:
 - Domain $D = \{x \in \mathbb{N}^n | Ax \le b\}$ is integer only and bound by linear constraints
 - The objective function is linear $f = c^T x$
- Despite its similarity to case 4 (LP), mixed integer linear programs (MIP) are NP-hard
- MIP algorithms are available, the Google OR Tools provide a unified front-end for various solvers, e.g.:

- Special case 5:
 - Domain $D = \{x \in \mathbb{N}^n | Ax \le b\}$ is integer only and bound by linear constraints
 - The objective function is linear $f = c^T x$
- Examples: Combined Heat and Power (CHP) optimisation
 - Same as before, but what happens if the CHP output cannot be adjusted from 0-100%, but only has an ON/OFF switch?
 - More important, if this is integrated into a bigger grid management problem, where some generators and/or consumers can only be switched on and off altogether



- Special case 6:
 - Domain $D \subset \mathbb{N}^n$ is integer only and subject to constraints
 - The objective function f=1 is constant, i.e. all feasible solutions are equally valid
- In general, Constraint Satisfaction Problems (CSP) are also NP-hard
- The goal is (only) to find a feasible solution, not to find the best (e.g. n-queens problems)
- Constraint Programming (CP) can be used to find a solution
- The Google OR Tools provide the CP-SAT solver for these problems:

from ortools.sat.python import cp_model

- Special case 7:
 - Domain $D \subset \mathbb{N}^n$ is integer only and subject to constraints
 - A generic objective function f is defined to quantify the cost of each feasible solution
- Even more generic than case 6, hence also NP-hard
- Can be used to solve Combinatorial Optimisation Problems, but be aware that sometimes more efficient solutions exist (e.g. Max-Flow)
- Again, Constraint Programming can often be used for finding a good solution
- The Google OR Tools provide the CP-SAT solver for these problems:

from ortools.sat.python import cp_model

- Special case 7:
 - Domain $D \subset \mathbb{N}^n$ is integer only and subject to constraints
 - A generic objective function f is defined to quantify the cost of each feasible solution
- Example: Renewable integration into the energy grid
 - Issues: Wind turbines can be switched on and off, solar panels often cannot, backup power generation is expensive
 - Depending on the weather conditions and energy demand, different combinations of renewables need to be integrated into the grid in order to maximise profit while keeping the grid stable



- Direct solutions exist for some (important) special cases, including
 - Gauss-Helmert model (special case 3)
 - Linear Programming (special case 4)
- Integer domain problems tend to be more difficult than real domain problems
- Constraint Programming (special cases 6 & 7) is a very versatile tool for solving many difficult integer optimisation problems
- However: CP is <u>NOT</u> the method of choice for every problem, in particular if the problem can be solved more efficiently using one of the other specialised approaches
- Neighbourhood search algorithms can be used where a meaningful neighbourhood relation in the parameter space can be established (special cases 1 & 2)

Thank you for your attention!