a) Duré à stepper motor interface to rotate the motor in anti-dockwise by N steps. Introduce mitable delay between mccessive steps. #include < stdio. h> (人・「でゆく) ぬいないがん ther xdata port-at_0xe803; to day odelar char xdata porta at_0xe800; to day odelar addata acc_at_0x30; char adata acc_at_0230; ma port [20] : 20x14, 0x1 delay () 3; 1, [28x0, 7A xo, Dxo, Foxo P() Halso int 1 for (j=0; j< 800; j++) { tong u; for P u= 0; u= 4000; u+4); 23 void main() { usid main() port = 0280; inted, b.f.m; while (1) 2 unalgred class K. acc = 0x11; convolution = 0x80; portazacc; cho f. delay (); acc = 01883 5(4) de (1) de (1) de (1) de porta=acc; 1(--1:050:61:61:4) delay (); () projects 以此一个 本人共1998年1978年