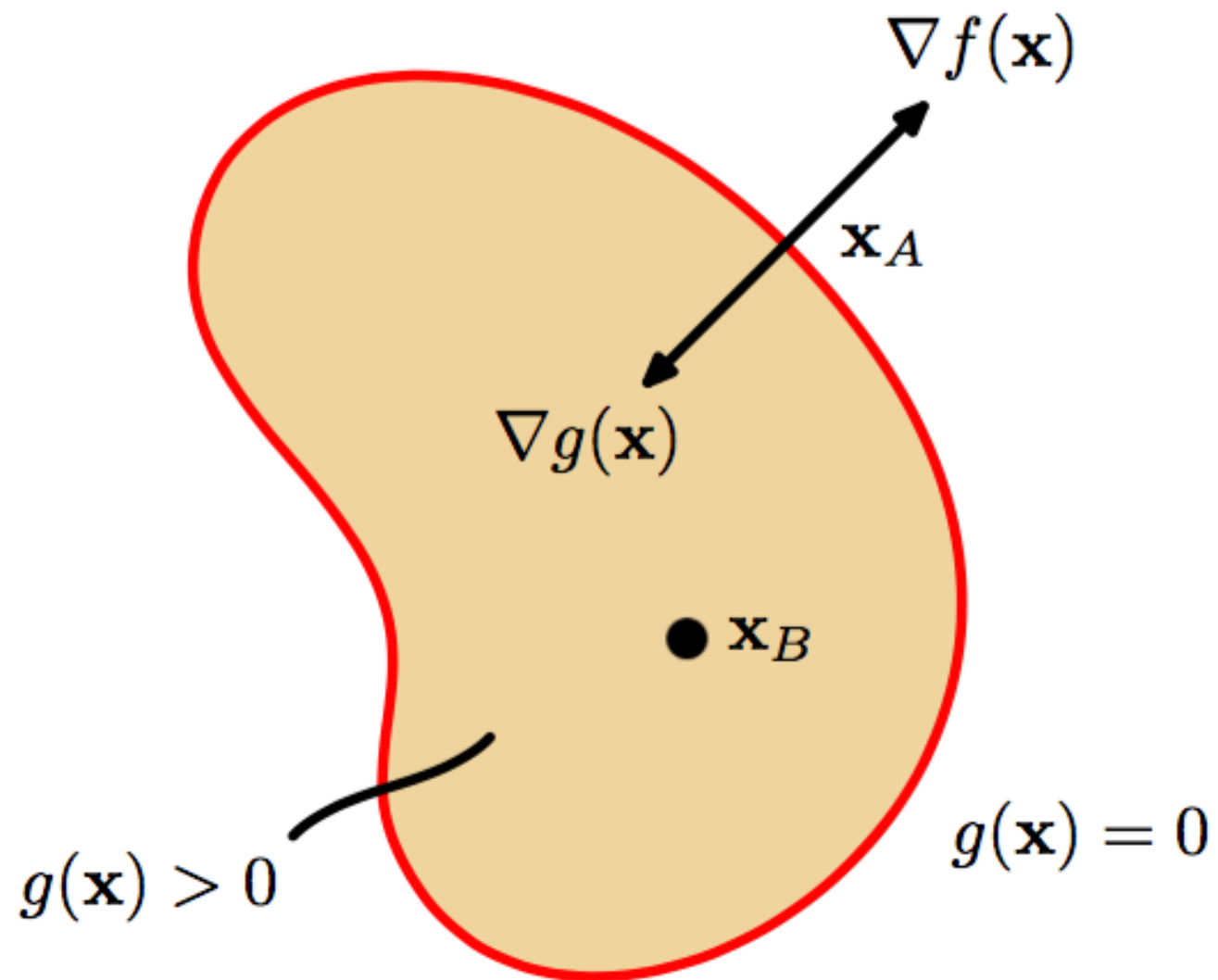


# Support Vectors Continued

Kernels, Slack variables and SMO

with help from A. Zisserman, A. Ng & S. Haykin

# Inequality constraints



$$\max f(x) \text{ stc } g(x) \geq 0$$

$$\text{KKT: } g(x) \geq 0$$

$$\lambda \geq 0$$

$$\lambda g(x) = 0$$

## KERNEL FUNCTIONS

Now the big bonus occurs because all the machinery we have developed will work if we map the points  $\mathbf{x}_i$  to a higher dimensional space, provided we observe certain conventions.

Let  $\phi(\mathbf{x}_i)$  be a function that does the mapping. So the new hyperplane is

$$\sum_{i=1}^N w_i \phi_i(\mathbf{x}) + b = 0$$

For simplicity in notation define

$$\phi(\mathbf{x}) = (\phi_0(\mathbf{x}), \phi_1(\mathbf{x}), \phi_2(\mathbf{x}), \dots, \phi_{m_1}(\mathbf{x}))$$

where  $m_1$  is the new dimension size and by convention  $\phi_0(\mathbf{x}) = 1$ .

Then all the work we did with  $\mathbf{x}$  works with  $\phi(\mathbf{x})$ . The only issue is that instead of  $\mathbf{x}_i^T \mathbf{x}_j$  we have a *Kernel function*,  $K(\mathbf{x}_i, \mathbf{x}_j)$  where

$$K(\mathbf{x}_i, \mathbf{x}_j) = \phi_i(\mathbf{x})^T \phi_j(\mathbf{x})$$

and Kernel functions need to have certain nice properties. : )

### Examples

Polynomials

$$(\mathbf{x}_i^T \mathbf{x}_j + 1)^p$$

Radial Basis Functions

$$\exp\left(-\frac{\|\mathbf{x}_i - \mathbf{x}_j\|^2}{2\sigma^2}\right)$$

Lets see an example. Suppose  $x, z \in \mathbb{R}^n$ , and consider

$$K(x, z) = (x^T z)^2.$$

We can also write this as

$$\begin{aligned} K(x, z) &= \left( \sum_{i=1}^n x_i z_i \right) \left( \sum_{j=1}^n x_j z_j \right) \\ &= \sum_{i=1}^n \sum_{j=1}^n x_i x_j z_i z_j \\ &= \sum_{i,j=1}^n (x_i x_j) (z_i z_j) \end{aligned}$$

Thus, we see that  $K(x, z) = \phi(x)^T \phi(z)$ , where the feature mapping  $\phi$  is given (shown here for the case of  $n = 3$ ) by

$$\phi(x) = \begin{bmatrix} x_1 x_1 \\ x_1 x_2 \\ x_1 x_3 \\ x_2 x_1 \\ x_2 x_2 \\ x_2 x_3 \\ x_3 x_1 \\ x_3 x_2 \\ x_3 x_3 \end{bmatrix}.$$

Note that whereas calculating the high-dimensional  $\phi(x)$  requires  $O(n^2)$  time, finding  $K(x, z)$  takes only  $O(n)$  time—linear in the dimension of the input attributes.

This is known as the ‘Kernel Trick’

When is a Kernel a Kernel?

K being **symmetric** and **positive definite** is necessary and sufficient

A reprise of last time ...

**The problem statement**

Given a set of training data  $\{(\mathbf{x}_i, d_i), i = 1, \dots, N\}$ , minimize

$$\Phi(\mathbf{w}) = \frac{1}{2} \mathbf{w}^T \mathbf{w}$$

subject to the constraint that

$$d_i(\mathbf{w}^T \mathbf{x}_i + b) \geq 1, i = 1, \dots, N$$

### The problem statement

Given a set of training data  $\{(\mathbf{x}_i, d_i), i = 1, \dots, N\}$ , minimize

$$\Phi(\mathbf{w}) = \frac{1}{2} \mathbf{w}^T \mathbf{w}$$

subject to the constraint that

$$d_i(\mathbf{w}^T \mathbf{x}_i + b) \geq 1, i = 1, \dots, N$$

**Looks like a job for LAGRANGE MULTIPLIERS!**

$$J(\mathbf{w}, b, \lambda) = \frac{1}{2} \mathbf{w}^T \mathbf{w} - \sum_{i=1}^N \lambda_i (d_i(\mathbf{w}^T \mathbf{x}_i + b) - 1)$$

So that

$$J_{\mathbf{w}} = \mathbf{0} = \mathbf{w} - \sum_{i=1}^N \lambda_i d_i \mathbf{x}_i \quad (3)$$

and

$$J_b = 0 = \sum_{i=1}^N \lambda_i d_i \quad (4)$$

**Now for the DUAL PROBLEM**

$$J(\mathbf{w}, b, \lambda) = \frac{1}{2} \mathbf{w}^T \mathbf{w} - \sum_{i=1}^N \lambda_i d_i \mathbf{w}^T \mathbf{x}_i + b \sum_{i=1}^N \lambda_i d_i + \sum_{i=1}^N \lambda_i$$

Note that from (4) third term is zero. **Using Eq. (3):**

$$Q(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j d_i d_j \mathbf{x}_i^T \mathbf{x}_j$$

## DUAL PROBLEM

$$\max Q(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j d_i d_j \mathbf{x}_i^T \mathbf{x}_j$$

Subject to constraints

$$\sum_{i=1}^N \lambda_i d_i = 0$$

$$\lambda_i \geq 0, \quad i = 1, \dots, N$$

This is *easier to solve* than the original. Furthermore it only depends on the training samples  $\{(\mathbf{x}_i, d_i), i = 1, \dots, N\}$ .

Once you have the  $\lambda_i$ s, get the  $\mathbf{w}$  from

$$\mathbf{w} = \sum_{i=1}^N \lambda_i d_i \mathbf{x}_i$$

and the  $b$  from a support vector that has  $d_i = 1$ ,

$$b = 1 - \mathbf{w}^T \mathbf{x}_s$$



*Given the training sample  $\{(\mathbf{x}_i, d_i)\}_{i=1}^N$ , find the optimum values of the weight vector  $\mathbf{w}$  and bias  $b$  such that they satisfy the constraint*

$$d_i(\mathbf{w}^T \mathbf{x}_i + b) \geq 1 - \xi_i \quad \text{for } i = 1, 2, \dots, N \quad (6.24)$$

$$\xi_i \geq 0 \quad \text{for all } i \quad (6.25)$$

*and such that the weight vector  $\mathbf{w}$  and the slack variables  $\xi_i$  minimize the cost functional*

$$\Phi(\mathbf{w}, \xi) = \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^N \xi_i \quad (6.26)$$

*where  $C$  is a user-specified positive parameter.*

*Given the training sample  $\{(\mathbf{x}_i, d_i)\}_{i=1}^N$ , find the Lagrange multipliers  $\{\alpha_i\}_{i=1}^N$  that maximize the objective function*

$$Q(\alpha) = \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j d_i d_j \mathbf{x}_i^T \mathbf{x}_j \quad (6.27)$$

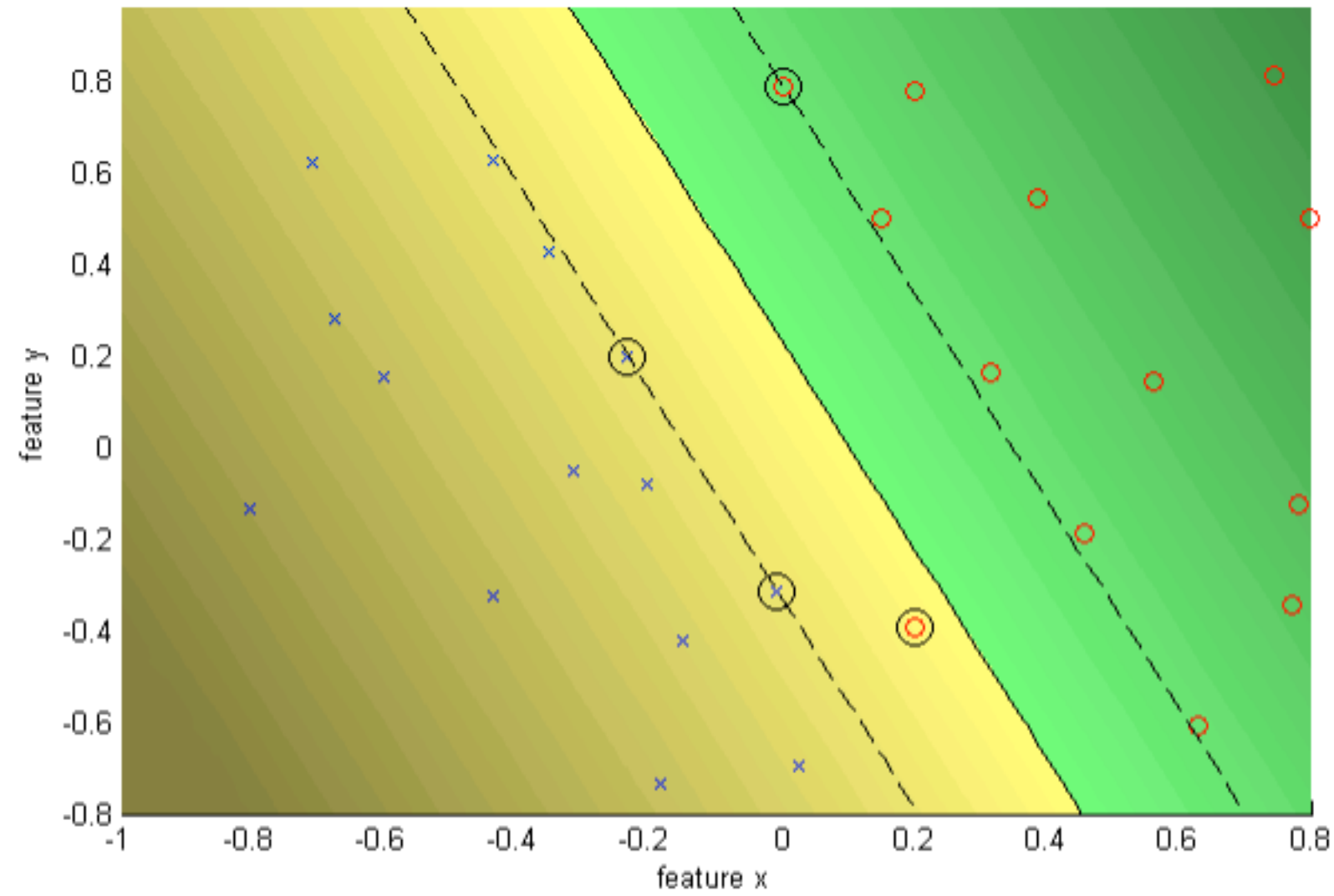
*subject to the constraints*

$$(1) \quad \sum_{i=1}^N \alpha_i d_i = 0$$

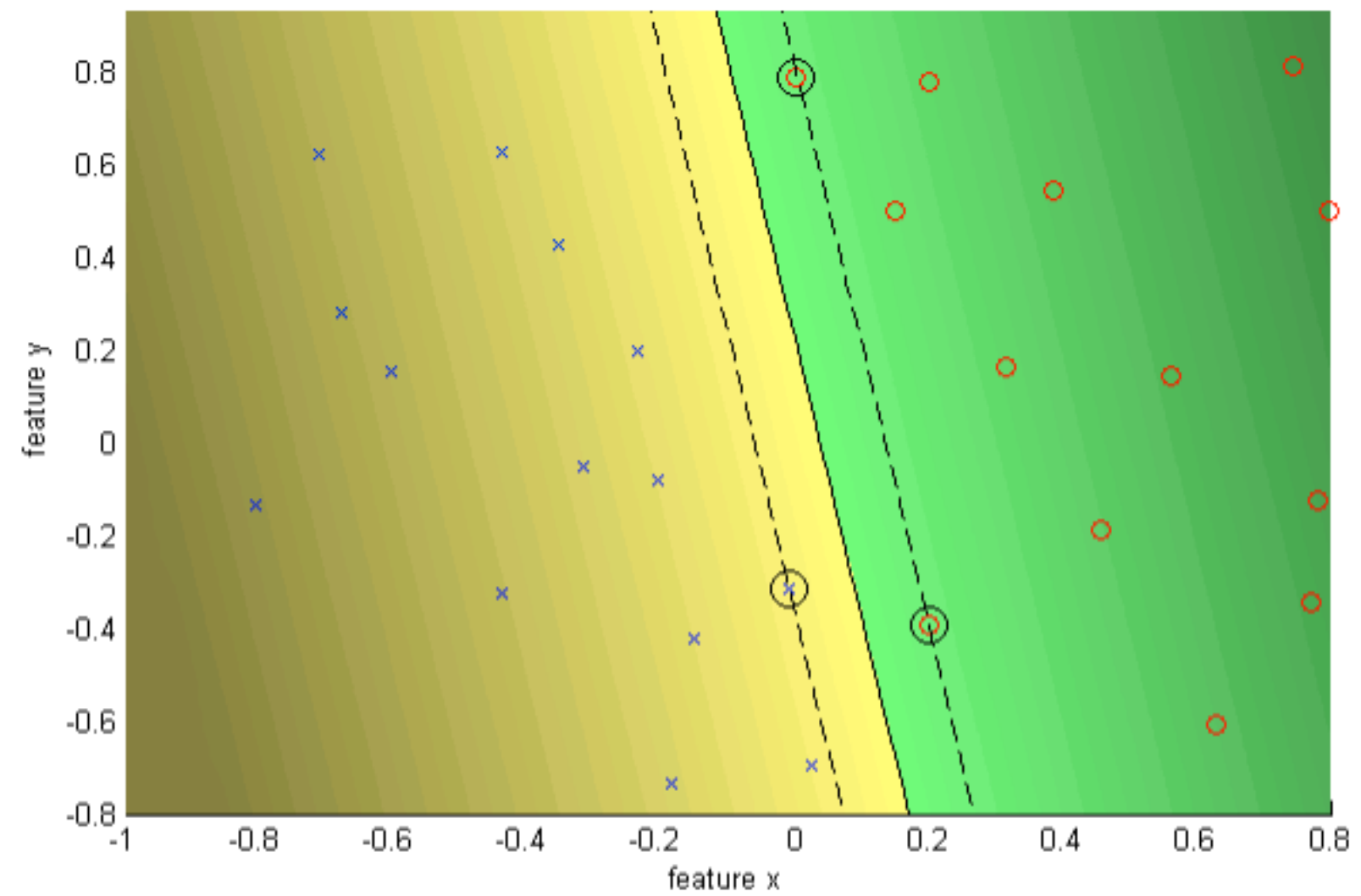
$$(2) \quad 0 \leq \alpha_i \leq C \quad \text{for } i = 1, 2, \dots, N$$

*where  $C$  is a user-specified positive parameter.*

$C = 10$  soft margin



$C = \text{Infinity}$     hard margin



# SMO: Sequential Minimization Optimization

Let's go back to the dual formulation.  
Note the soft constraint formulation

$$\max_{\alpha} \quad W(\alpha) = \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m y^{(i)} y^{(j)} \alpha_i \alpha_j \langle x^{(i)}, x^{(j)} \rangle. \quad (17)$$

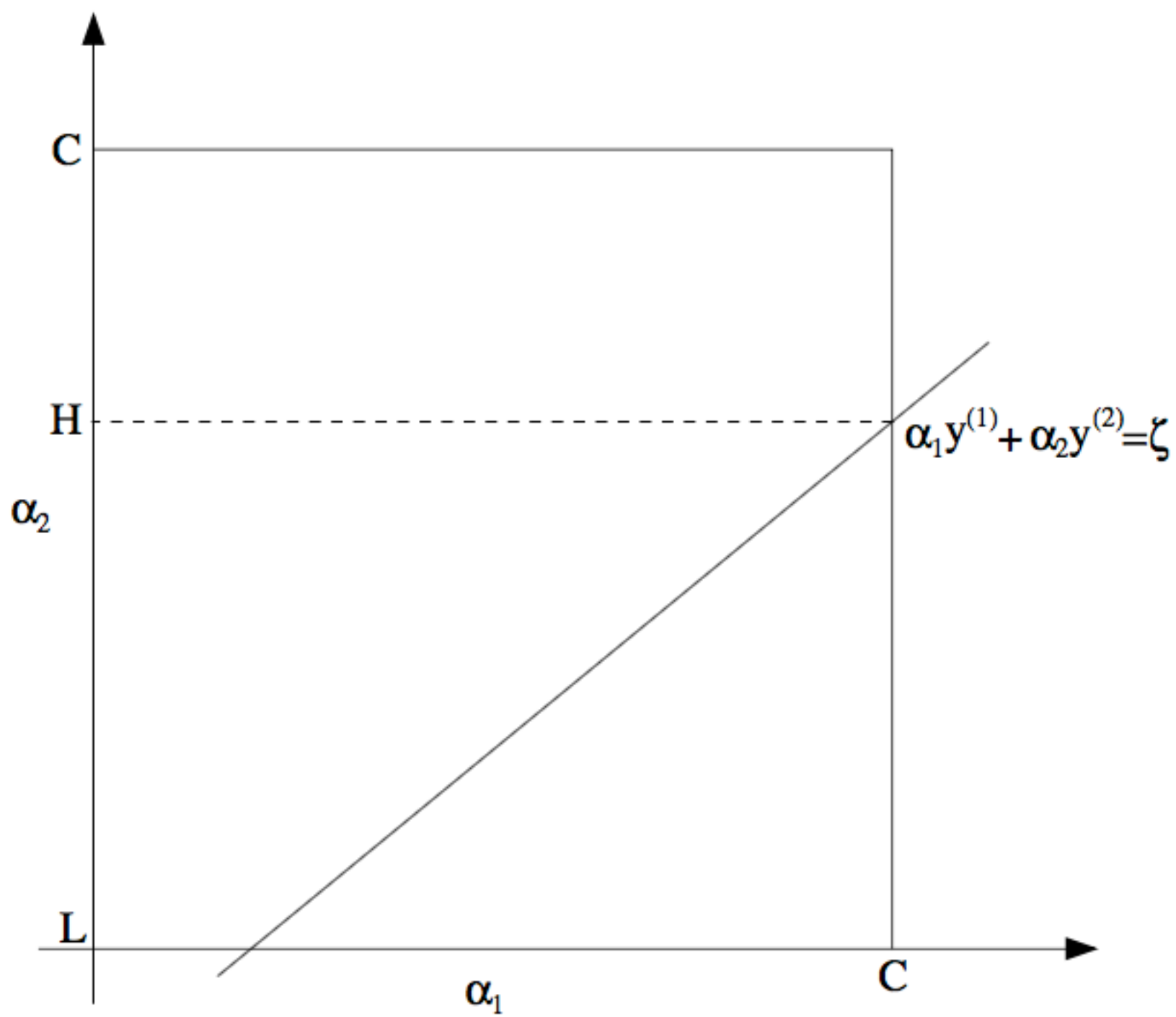
$$\text{s.t.} \quad 0 \leq \alpha_i \leq C, \quad i = 1, \dots, m \quad (18)$$

$$\sum_{i=1}^m \alpha_i y^{(i)} = 0. \quad (19)$$

$$\alpha_1 y^{(1)} = - \sum_{i=2}^m \alpha_i y^{(i)}.$$

$$\alpha_1 = -y^{(1)} \sum_{i=2}^m \alpha_i y^{(i)}$$

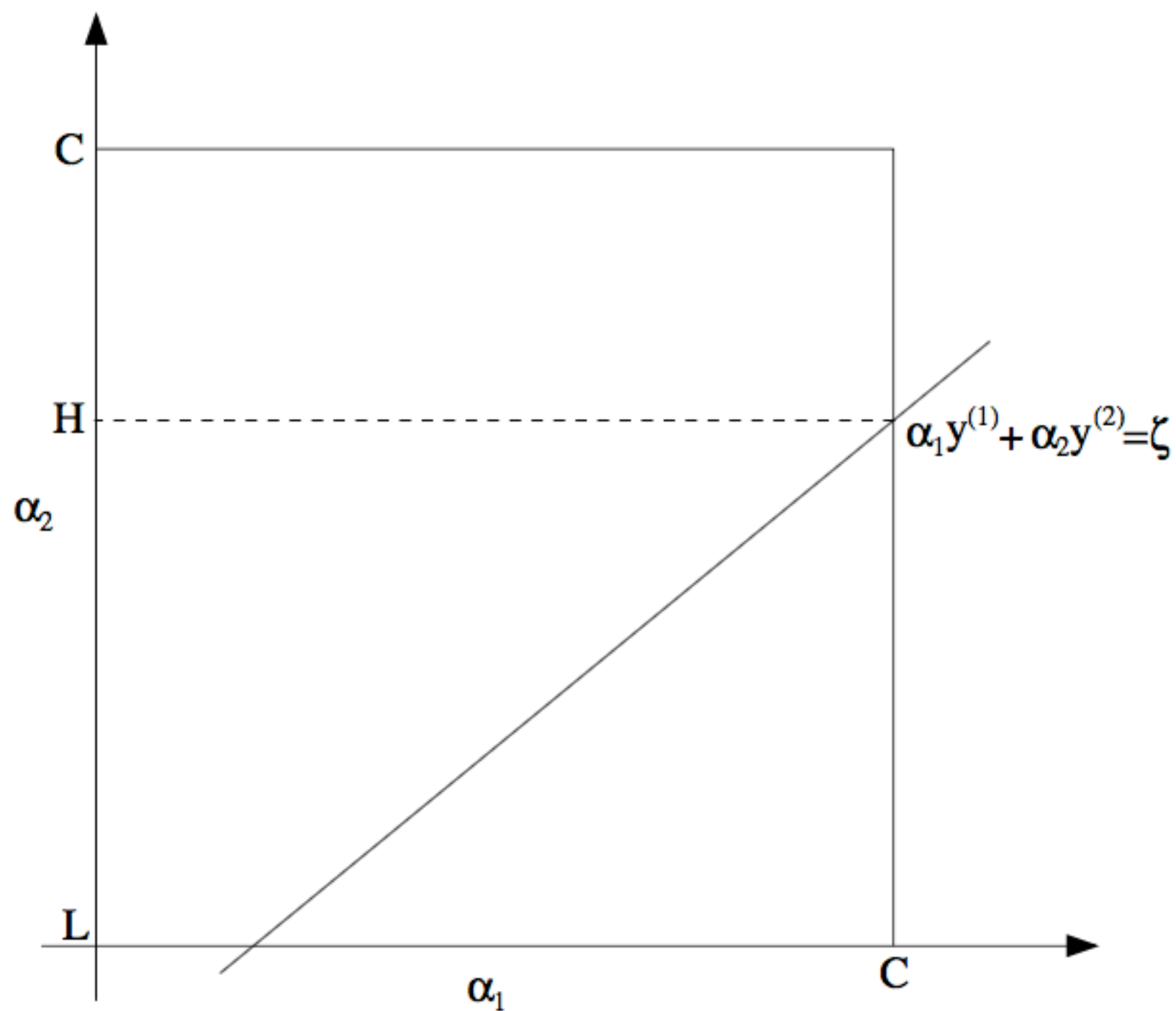
$$\alpha_1 y^{(1)} + \alpha_2 y^{(2)} = - \sum_{i=3}^m \alpha_i y^{(i)}$$

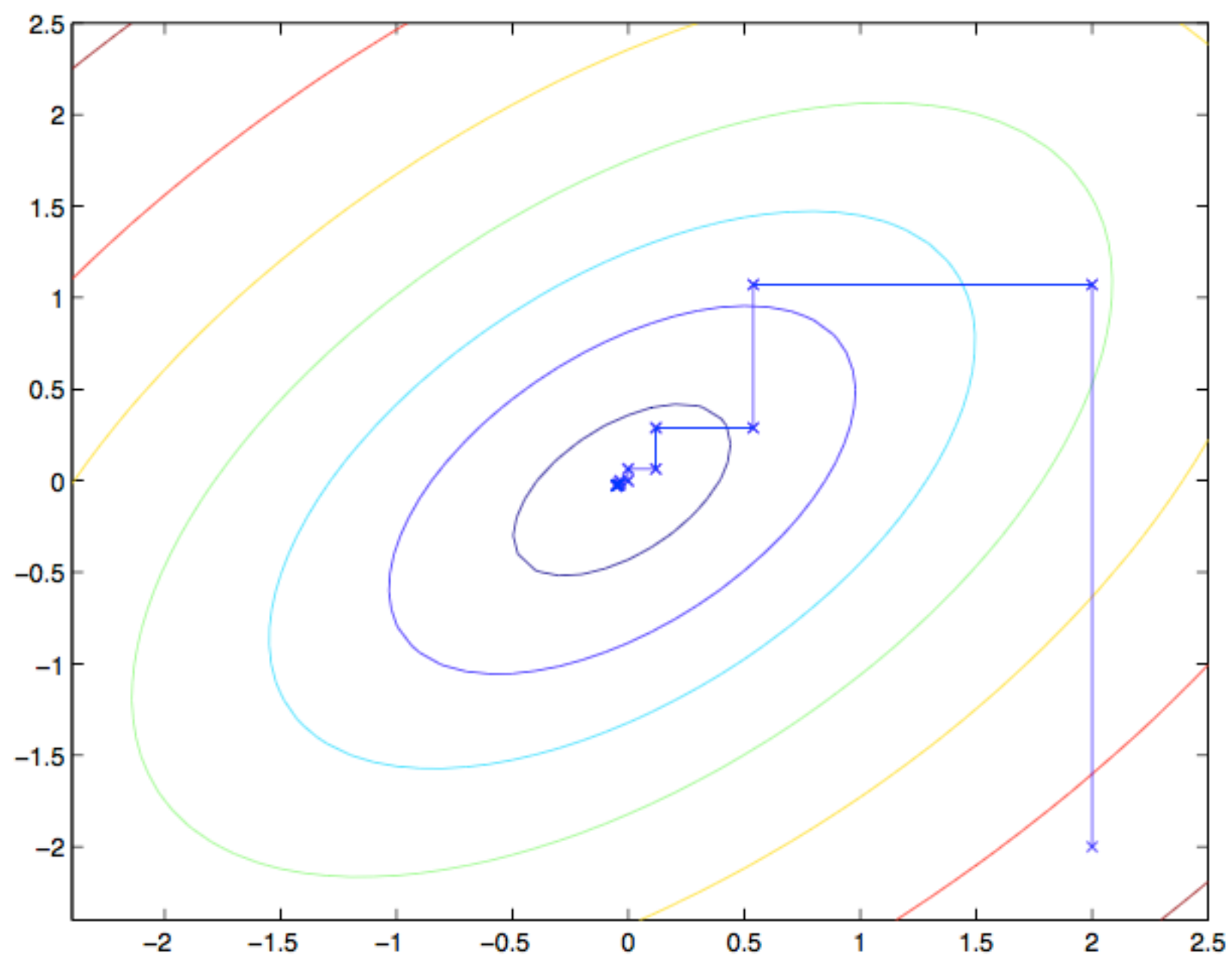


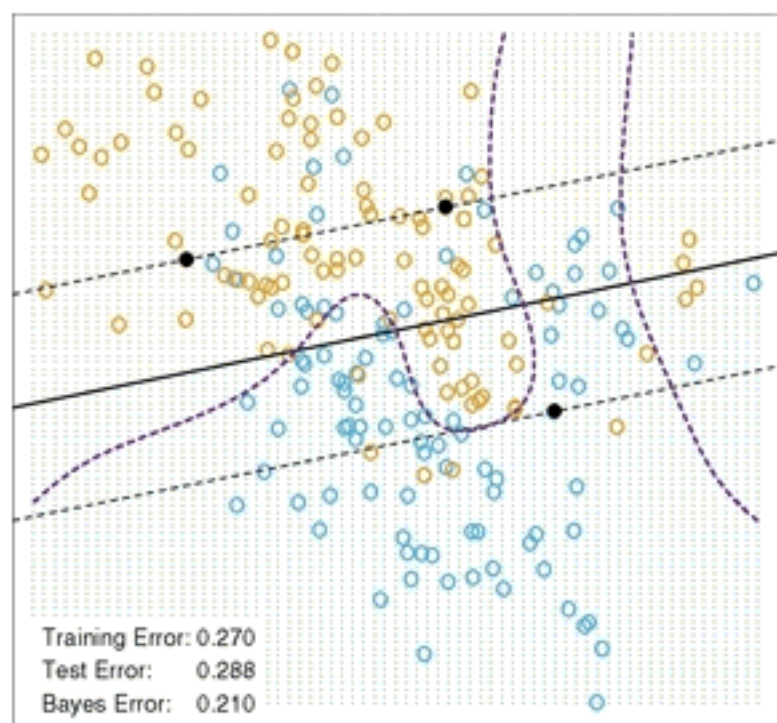


$$\alpha_1 = (\zeta - \alpha_2 y^{(2)})y^{(1)}$$

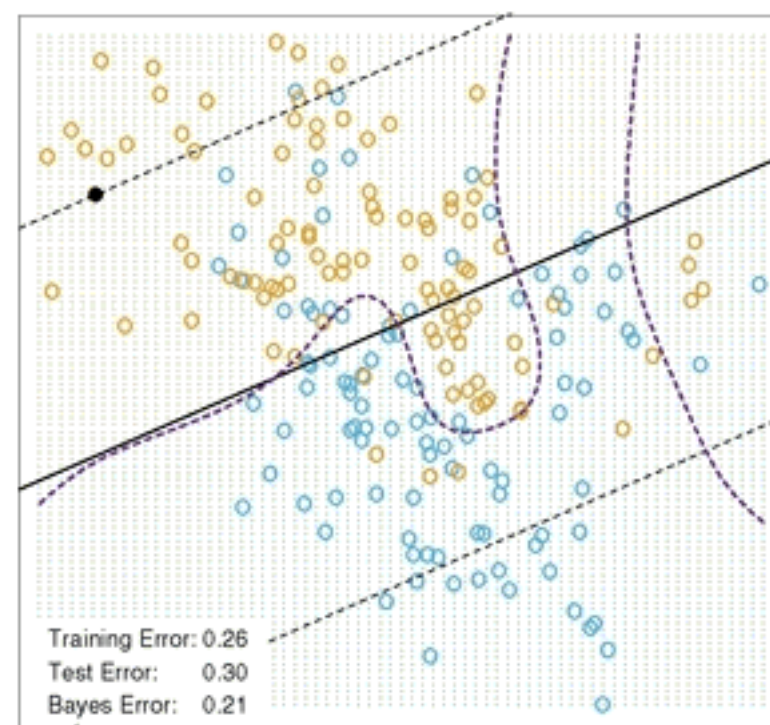
$$\alpha_2^{new} = \begin{cases} H & \text{if } \alpha_2^{new,unclipped} > H \\ \alpha_2^{new,unclipped} & \text{if } L \leq \alpha_2^{new,unclipped} \leq H \\ L & \text{if } \alpha_2^{new,unclipped} < L \end{cases}$$





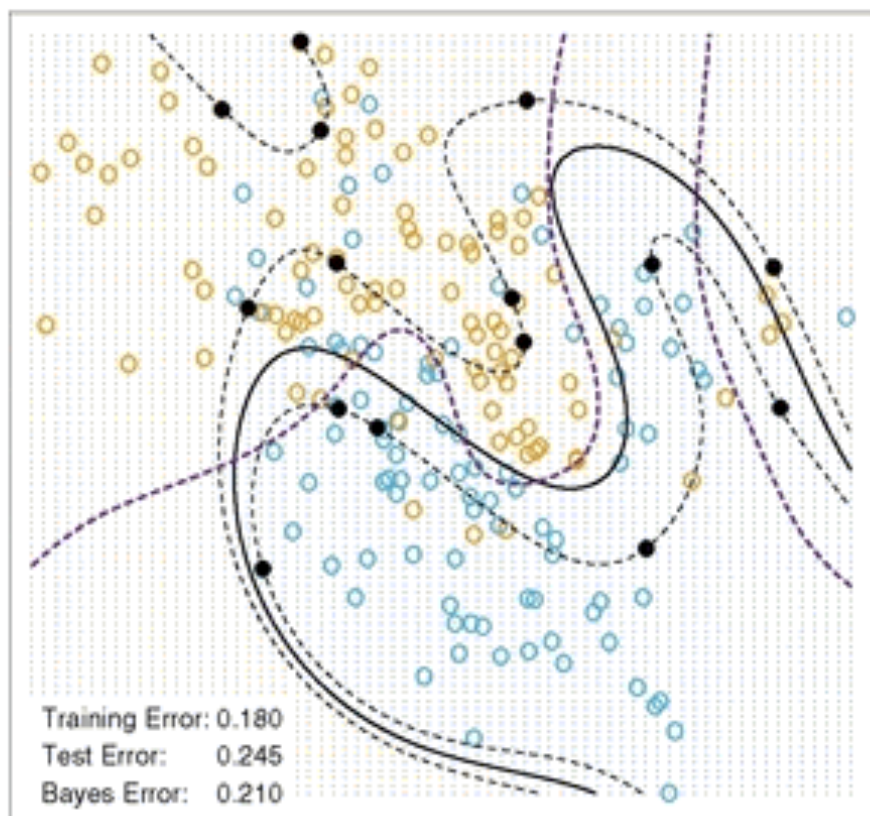


$C = 10000$

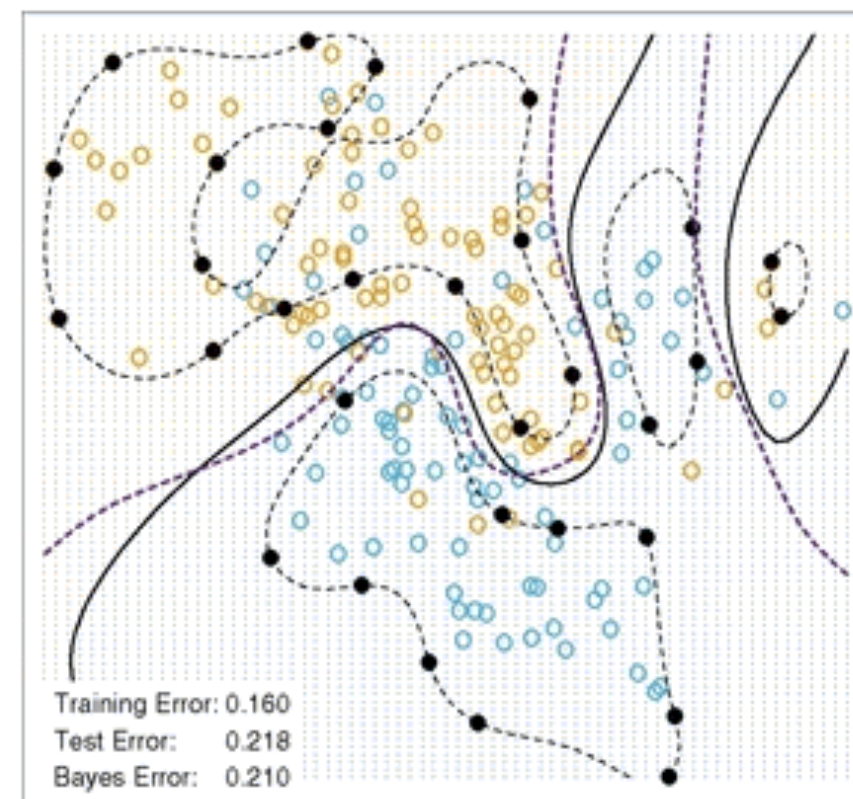


$C = 0.01$

SVM - Degree-4 Polynomial in Feature Space



SVM - Radial Kernel in Feature Space



# Soft constraints

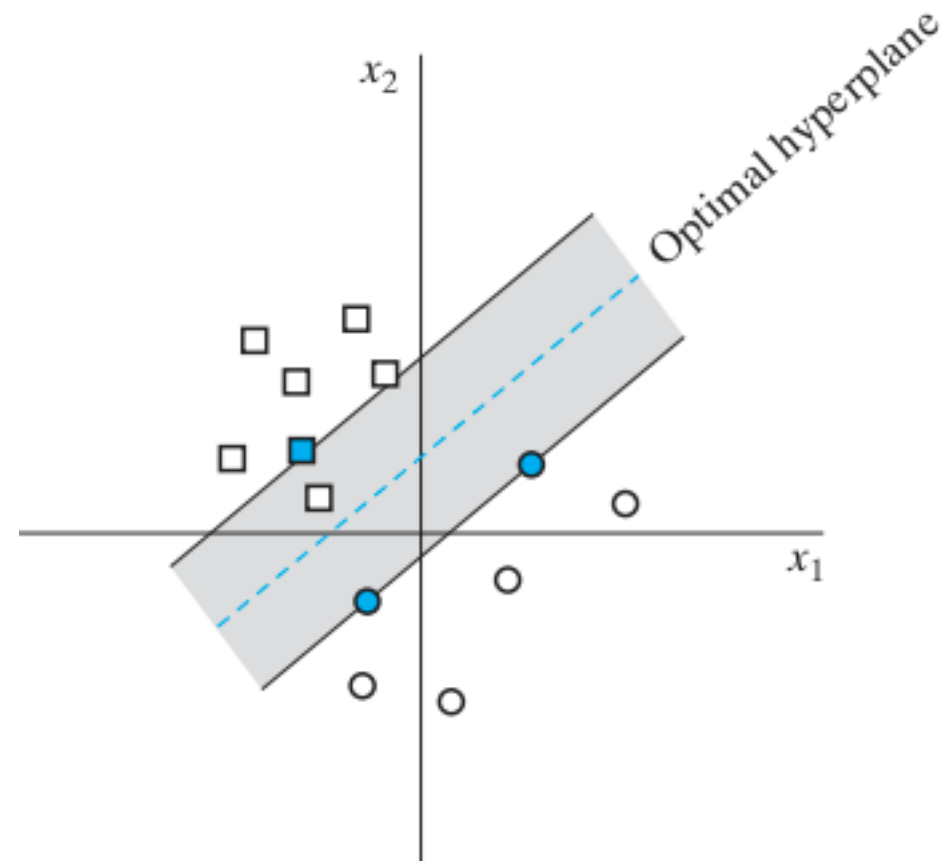
The margin of separation between classes is said to be *soft* if a data point  $(\mathbf{x}_i, d_i)$  violates the following condition (see Eq. (6.10)):

$$d_i(\mathbf{w}^T \mathbf{x}_i + b) \geq +1, \quad i = 1, 2, \dots, N$$

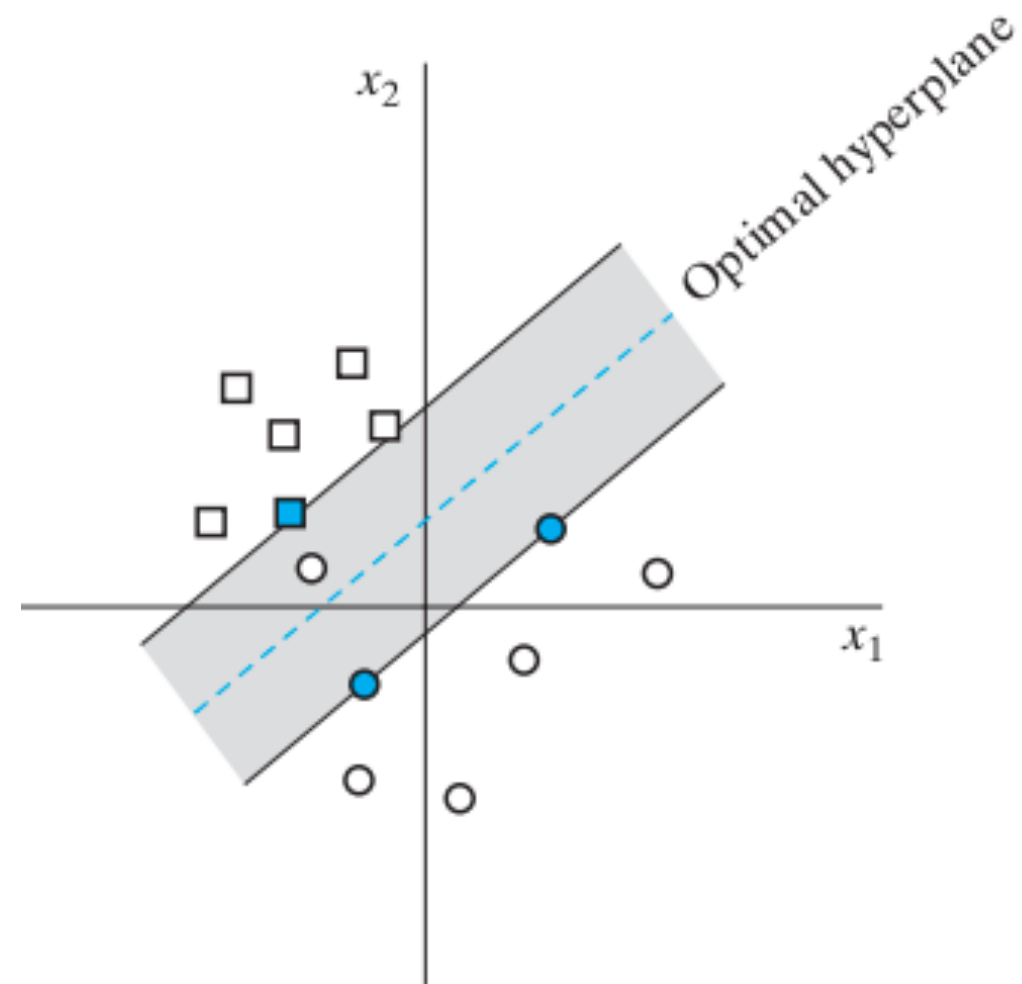
- The data point  $(\mathbf{x}_i, d_i)$  falls on the wrong side of the decision surface, as illustrated in Fig. 6.3b.

This violation can arise in one of two ways:

- The data point  $(\mathbf{x}_i, d_i)$  falls inside the region of separation, but on the correct side of the decision surface, as illustrated in Fig. 6.3a.



- The data point  $(\mathbf{x}_i, d_i)$  falls on the wrong side of the decision surface, as illustrated in Fig. 6.3b.





To make the optimization problem mathematically tractable, we approximate the functional  $\Phi(\xi)$  by writing

$$\Phi(\xi) = \sum_{i=1}^N \xi_i$$

Moreover, we simplify the computation by formulating the functional to be minimized with respect to the weight vector  $\mathbf{w}$  as follows:

$$\Phi(\mathbf{w}, \xi) = \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^N \xi_i \quad (6.23)$$



