

rosjet

ROS nodes and arduino libraries for the NVIDIA Robot Teaching Kit with Jet.

installation

For installing and configuring your Jetson board for the Jet robot, see the [INSTALLATION.md](#) file.

Running rosjet

For Gazebo Simulation:

```
roslaunch jet_bringup jet_gazebo.launch
```

For Real Robot:

```
roslaunch jet_bringup jet_real.launch
```