Lab 08 21 27 19 DS

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[1]: import numpy as np
     import matplotlib.pyplot as plt
     import cv2
[2]: img1 = cv2.imread(r"C:\Users\saura\Desktop\Ongoing\Notes\01.
     →LAB_ass\Computer_vision_basics\Images\pic1_SIFT.jpg")
     img2 = cv2.imread(r"C:\Users\saura\Desktop\Ongoing\Notes\01.
     →LAB_ass\Computer_vision_basics\Images\pic2_SIFT.jpg")
     img1 = cv2.cvtColor(img1, cv2.COLOR BGR2RGB)
     img2 = cv2.cvtColor(img2, cv2.COLOR_BGR2RGB)
     # plt.figure(figsize = (5,10))
     # plt.imshow(img2)
    SIFT
[3]: # SIFT object
     SIFT = cv2.SIFT_create()
     keypoint_1, descriptor_1 = SIFT.detectAndCompute(img1, None)
     keypoint_2, descriptor_2 = SIFT.detectAndCompute(img2, None)
[4]: # Create Feature matcher
     bf = cv2.BFMatcher(cv2.NORM L2, crossCheck = True)
     # Match descriptors of both images
     matches = bf.match(descriptor_1, descriptor_2)
     # Sort matches by distances
     matches = sorted(matches, key = lambda y : y.distance)
     # Draw first 1000 matches
     matched_img = cv2.drawMatches(img1, keypoint_1, img2, keypoint_2, matches[:
     \hookrightarrow1000], img2, flags = 2)
     plt.figure(figsize = (15,10))
     plt.imshow(matched_img)
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[4]: <matplotlib.image.AxesImage at 0x1f8bf78fac0>

