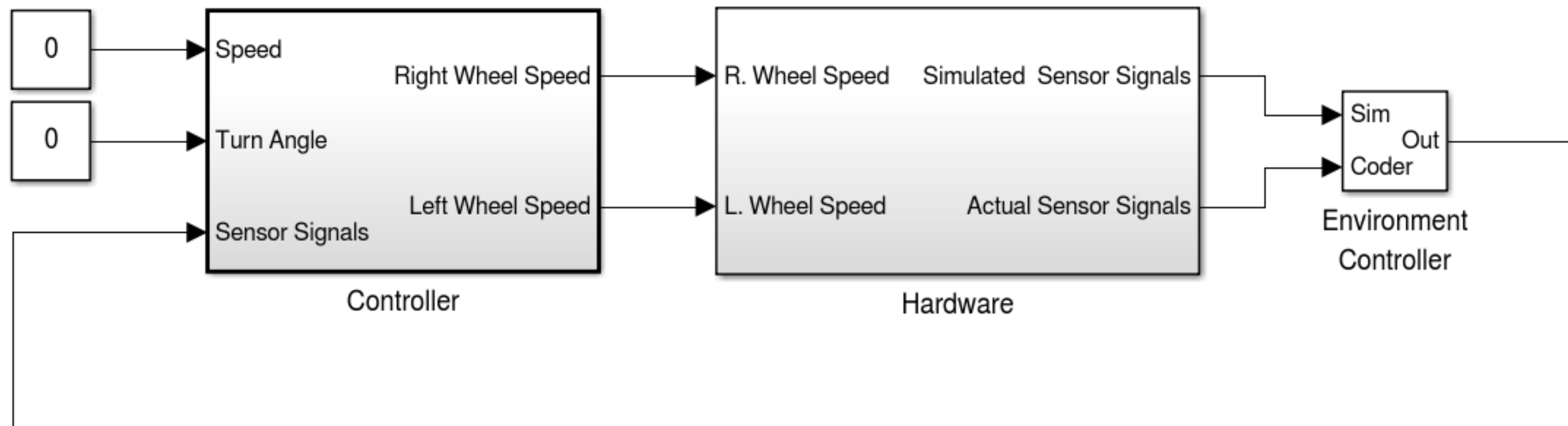


Self-Balancing Two-Wheel Robot

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To run this model on hardware, on the Simulink Editor toolbar, click the "Deploy To Hardware" button. The model runs as a standalone application, independently of Simulink.