Reg. No	

B.Tech DEGREE EXAMINATION, DECEMBER 2023

Fifth, Sixth and Seventh Semester

18ECO108J - EMBEDDED SYSTEM DESIGN USING ARDUINO

(For the candidates admitted during the academic year 2020 - 2021 & 2021 - 2022)

Note:

i. Part - A should be answered in OMR sheet within first 40 minutes and OMR sheet should be handed over to hall invigilator at the end of 40th minute.
ii. Part - B and Part - C should be answered in answer booklet.

Fime: 3 Hours		Max.	Max. Marks: 100			
		× 1 = 20 Marks) Il Questions	· Mar	ks BL	СО	
1.	A program written with the IDE for A (A) IDE source (C) Cryptography	Arduino is called (B) Sketch (D) Source code	.1	1	1	
2.	How many analog pins are used in A (A) 6 (C) 8	rduino UNO board? (B) 7 (D) 9	1	1	1	
3.	The sign flag 's' in status register will complement overflow flag') (A) 'N' OR 'V' (C) 'N' XOR 'V'	Il set to one when ('N'> negative flag, 'v'> (B) 'N' AND 'V' (D) 'N' NOR 'V'	2's 1	-2	1	
4.	Which area in Arduino IDE shows the (A) Menu bar (C) Button bar	ne notification of the process? (B) Edit bar (D) Status bar	1	2	1	
5.	j = 6 + k * 3; where $k = 5$ and the asterisk (*) is the j is (A) 21 (C) 26	e multiplication operator. The correct answer (B) 33 (D) 36	for	3	2	
6.	A data item is declared if it in (A) does not exist, does not have (C) exists, has	the symbol table, but an assigned <i>l value</i> . (B) does not exist, has (D) exists, does not have	1	2	2	
7.	Consider the following code fragment int c = 7; int k; k = ++c; What is the value of k? (A) 8 (C) 6	(B) 7 (D) 9		= 3	2	
	(0)0	(D))	2020			

8.	if $(ptr1 < ptr2)$ {		1	2	2
	}				
	if (ptr1 > 10) {				
	}				
	(A) Both are acceptable.	(B) First form is acceptable. The second form is unacceptable.			
	(C) Both are unacceptable.	(D) First form is unacceptable. The second form is acceptable.			
9.	This function sets the serial communication	ns speed.	1	1	3
	(A) Serial.begin(speed)	(B) Serial.read()			
	(C) Serial.write(val)	(D) Serial.printIn(val, format)			
10.	The is used to measure the persystems.		1	3	3
	(A) SNR (Signal to Noise ratio)				
	(C) Output voltage	(D) Output current			
11.	The Arduino software treats the PWI	M channels the, limiting them to	1	2	3
	- bit resolution and hard wiring them to a r (A) Few of, in different way, eight, slow				
	(C) All, same, eight, slow	(D) All, same, eight, fast			
12.	For Arduino Uno boards, dedicated pins and pin is the SCL pin.		1	1	3
	(A) A1 and A2; A1; A2	(B) A1 and A2; A2; A1			
	(C) A4 and A5; A4; A5	(D) A4 and A5; A5; A4			
13.	To read a signal on an external pin, we will bit .	ll need to write a to the data direction	1	2	4
	(A) logic high, DDxn	(B) logic low, DDxn			
	(C) logic low, PORTxn	(D) logic high, PORTxn			
14.		1-0 are that yields internal 1.1 volt	1	2	4
	(A) 00	(B) 01			
	(C) 10	(D) 11			
15.	The ADPS2-0 are bits in .		1	2	4
	(A) Prescaler, ADCSRB	(B) Prescaler, ADCSRA			
	(C) Trigger Source, ADCSRA	(D) Trigger Source, ADCSRB			
16.	For CTC mode, the Waveform Generation	Mode (WGM) bits are .	1	1	4
	(A) 010	(B) 011			
	(C) 101	(D) 110			
17.	ZigBee is based on		1.	1	5
	(A) IEEE 802.15.4	(B) IEEE 804.15.2			
	(C) IEEE 805.12.4	(D) IEIA 802.15.4			
18.	The IR signals are mainly used for transful distances.	mitting commands over the on	1	2	5
	(A) air, short	(B) air, long			
	(C) cable, short	(D) cable, long			

to maximum. (A) 2.7 V, 5.5 V (B) 0 V, 5.5 V (C) 0 V, 2.7 V (D) 2.0 V, 5.0 V Match the following: 1. An RFID tag 2. An RFID tag a. that carries object identifying data 3. A bag-end data base b. that reads and writes tag data 3. A bag-end data base c. that stores records associated with tag contents	1	3	5
(C) 0 V, 2.7 V Match the following: 1. An RFID tag 2. An RFID tag reader a. that carries object identifying data b. that reads and writes tag data	1	3	5
 An RFID tag An RFID tag reader a. that carries object identifying data b. that reads and writes tag data 	1	3	5
 An RFID tag An RFID tag reader a. that carries object identifying data b. that reads and writes tag data 			
2 A hog and data hace a first stores records associated with the Continue			
3. A bag-end data base c. that stores records associated with tag contents (A) 1-b, 2-c, 3-a (B) 1-c, 2-a, 3-b			
(C) $1-a$, $2-b$, $3-c$ (D) $1-a$, $2-c$, $3-b$			(%2
	Marl	cs BL	CO
	4	2	1
1. List the power saving modes of ATmega328p. Explain them.			
Define duty cycle. When the duty cycle of a pulse is 80% and the total time period is 250 microseconds. Calculate the ON time and OFF time.		3	1
3. What makes a Good function?		2	2
4. Explain the Right-Left Rule.		3	2
•		4	3
		2	4
		3	5
	Mar	ks BL	CO
PART - C (5 × 12 = 60 Marks) Answer all Questions	,		
(a) With suitable waveform diagram and formula for duty cycle explain the operation of PWM. And write a simple Arduino sketch to glow a LED connected at Pin13 at 60% duty cycle.	12	3	1
	12	3	2
(OR)			
(b) Write short notes on the following: (i) Structures (ii) Unions and (iii) Data storage			
explain.	12	4	3
(b) Write a code to control LEDs using an IR sensor and a remote (Arduino) and explain with circuit arrangement.			
(a) How timer is used in Fast PWM mode? Explain with code. (OR) (b) What are external interrupt? With code explain.	12	3	4
	250 microseconds. Calculate the ON time and OFF time. What makes a Good function? Explain the Right-Left Rule. Draw an RS-232-to-TTL receiver circuit and explain. With various options explain analogReference () function. How PWM is used to control the Servo Motor? PART - C (5 × 12 = 60 Marks) Answer all Questions (a) With suitable waveform diagram and formula for duty cycle explain the operation of PWM. And write a simple Arduino sketch to glow a LED connected at Pin13 at 60% duty cycle. (OR) (b) With neat diagram explain the architecture of ATmega 328P. (a) (i) List the pointer rules. (ii) Shows the use of pointers with a short program. (OR) (b) Write short notes on the following: (i) Structures (ii) Unions and (iii) Data storage (a) Write a sketch for the Arduino master device in I ² C communication and explain. (OR) (b) Write a code to control LEDs using an IR sensor and a remote (Arduino) and	Answer any 5 Questions List the power saving modes of ATmega328p. Explain them. Define duty cycle. When the duty cycle of a pulse is 80% and the total time period is 250 microseconds. Calculate the ON time and OFF time. What makes a Good function? Explain the Right-Left Rule. Draw an RS-232-to-TTL receiver circuit and explain. With various options explain analogReference () function. How PWM is used to control the Servo Motor? PART - C (5 × 12 = 60 Marks) Answer all Questions (a) With suitable waveform diagram and formula for duty cycle explain the operation of PWM. And write a simple Arduino sketch to glow a LED connected at Pin13 at 60% duty cycle. (OR) (b) With neat diagram explain the architecture of ATmega 328P. (a) (i) List the pointer rules. (ii) Shows the use of pointers with a short program. (OR) (b) Write short notes on the following: (i) Structures (ii) Unions and (iii) Data storage (a) Write a sketch for the Arduino master device in I ² C communication and explain. (OR) (b) Write a code to control LEDs using an IR sensor and a remote (Arduino) and	Answer any 5 Questions List the power saving modes of ATmega328p. Explain them. Define duty cycle. When the duty cycle of a pulse is 80% and the total time period is 250 microseconds. Calculate the ON time and OFF time. What makes a Good function? Explain the Right-Left Rule. Draw an RS-232-to-TTL receiver circuit and explain. With various options explain analogReference () function. How PWM is used to control the Servo Motor? PART - C (5 × 12 = 60 Marks) Answer all Questions (a) With suitable waveform diagram and formula for duty cycle explain the operation of PWM. And write a simple Arduino sketch to glow a LED connected at Pin13 at 60% duty cycle. (OR) (b) With neat diagram explain the architecture of ATmega 328P. (a) (i) List the pointer rules. (ii) Shows the use of pointers with a short program. (OR) (b) Write short notes on the following: (i) Structures (ii) Unions and (iii) Data storage (a) Write a sketch for the Arduino master device in I ² C communication and explain. (OR) (b) Write a code to control LEDs using an IR sensor and a remote (Arduino) and

32. (a) Write a code to indicate the temperature in "Red", "Yellow", "Green" LEDs 12 and also send the value to terminal in PC via serial port. Red LED should glow when temperature is greater than 100 degree Celsius Yellow LED should glow when temperature is greater than 51 degree Celsius and less than 100 degree Celsius Green LED should glow when temperature is Less than 50 degree Celsius

(OR)

(b) How a DC Motor is interfaced using H-Bridge and controlled by a slide switch? With a code explain