Reg. No.								
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B.Tech. DEGREE EXAMINATION, MAY 2024

Sixth Semester

18ECE204J - ARM - BASED EMBEDDED SYSTEM DESIGN

,		(For the candidates admitted from the academic year 2018-2019 to 2021-2022)				
Note: (i)		Part - A should be answered in OMR sheet within first 40 minutes and OMR sheet shover to hall invigilator at the end of 40 th minute.	noul	d be	hano	led
(ii) Time:	3 1	Part - B & Part - C should be answered in answer booklet. Ma	x. N	1ark	s: 10	00
I IIIIC.		$PART - A (20 \times 1 = 20 Marks)$	arks	BL	CO	PO
		Answer ALL Questions		_		
	1.	ARM is a type ofprocessor.	1	1	1	1
		(A) CISC (B) RISC (C) 64 bit (D) HPC				
			1	2	1	1
	2.	input is R5=5 and R7=8 is	1	2	1	1
		(A) R7=28 (B) R7=23				
		(C) R7=24 (D) R7=25	1	1	1	1
	3.	The ARM cortex M series forapplications.	1	1	1	1
		(A) High performance(B) Low power(C) Fast response(D) High power				1
		X	1	2	1	1
	4.	The instruction RSC R0, R1, R2 will produce which of the following execution	1	2	1	1
		(A) $R_0 = R_2 - R_1 + C - 1$ (B) $R_0 = R_1 - R_2 + C - 1$ (C) $R_0 = R_0 + carry$ (D) $R_0 = R_2 + R_1 + carry$				
	5.	In ARM processor peripheral interfacing which register is commonly used to configure a GPIO pin as an input or output? (A) General purpose control (B) Digital input/output register register (GPCR) (DIOR) (C) GPIO direction register (D) Peripheral configuration (GPIODIR) register (PCR)	1	2	2	3
	6	Which of the following ADC modes in LPC2148 continuously converts	1	2`	2	3
	0.	and updates the result in the result register?	5			
		(A) Single conversion mode (B) Burst mode				
		(C) Continuous conversion mode (D) Sequential conversion mode				_
	7.	How is the PWM frequency calculated in LPC2148 microcontroller? (A) PWM frequency = clock (B) PWM frequency = clock frequency/(prescaler *(match - frequency/ (match register register +1)) (C) PWM frequency = clock (D) PWM frequency = clock	1	3	2	3
		(C) PWM frequency = clock (D) PWM frequency = clock frequency*(prescaler *(match frequency *(match register register value+1)) value+1))				
	8.	In LPC 2148 microcontroller, if the PWM resolution is 2047 and the PWM counter width is 11 bits, how many duty cycle steps are possible? (A) 2048 (B) 1024 (C) 2047 (D) 4096	1	3	2	3

9.	Which of the following synchronous serial communication protocols commonly used in LPC2148 microcontroller? (A) UART (B) SPI (C) I2C (D) USART	is	1	1	3	1
10.	How does the I2C protocol handle communication collisions in LPC21 microcontroller? (A) By ignoring collisions and (B) By pausing transmission a continuing transmission retying after a random delay (C) By using arbitration to (D) By terminating transmissidetermine which device can and restarting to continue transmission communication process	nd	1	2	3	3
11.	Which interrupt is commonly used to handle time overflow events in LI 2148 microcontroller interfacing? (A) Timer 0 interrupt (B) Timer 1 interrupt (C) Timer 2 interrupt (D) Timer 3 interrupt	PC.	1	2	3	3
12.	In SPI communication, if the clock frequency (SCK) is 1 MHz and the S prescaler value is set to A, what is the resulting SPI clock frequency? (A) 250 kHz (B) 500 kHz (C) 1 MHz (D) 4 MHz	PI	1	3	3	3
13.	What is the role of the memory control unit (MCU) in the LPC214 microcontroller? (A) To manage access to external (B) To provide direct access memory devices flash memory (C) To control the execution flow (D) To interface with peripher of program instructions devices	to	1	2	4	1
14.	What is the role of the ethernet controller in the LPC2148 microcontroller (A) To generate clock signals for (B) To interface with extern ethernet communications ethernet transceivers (C) To manage data transmission (D) To handling routing and pack and reception over the ethernet forwarding in the network interface	al	1	2	4	1
15.	Which of the following communication interfaces is commonly used for LAN communication with the LPC2148 microcontroller? (A) UART (B) SPI (C) Ethernet (D) 12C	or	1	2	4	1
16.	 In LPC 2148 microcontroller has 64 kB of on-chip flash memory and 16 kB of on-chip RAM. If an external memory chip with 512 kB of flash memory and 128 kB of RAM is connected to the LPC2148 Via EM1, who is the total available flash memory and RAM for the μC system? (A) 576 kB of flash memory and (B) 576 kB of flash memory and 144 kB of RAM (C) 576 kB of flash memory and (D) 576 kB of flash memory and 64 kB of RAM (D) 576 kB of flash memory and 128 kB of RAM 	sh at ıd	1	3	4	3

17.	Which transmi externa		2	5	1			
	(A) I2		(B)	SPI				
	(C) U.	ART	(D)	I2S				
18.	this can (A) Ra	a be specified as signed and ur ange (- 48768 to 32767) and nge (0 to 125535)	nsigne (B)	Range(0 to 32767) and range (0 to 65535)		3	5	3
		ange (0 to 32767) and range -65535 to 65535)	(D)	Range (- 32768 to 32767) and range (0 to 65535)				
19.	bytes. corresponding for the factor (A) 0.0	What will be the correct c	is outained is outained in the contract of the	value given by two consecutive ponding voltage output, if this atput through the MBED's DAC, imal) 3.293 volts 0.2114 volts	1	3	5	3
2.0	FF1 0	,			,	0	_	2
20.	(A) 20 (C) 40		(B)	10% 67%	1	2	5	3
		PART – B (5 > Answer ANY I			Marks	BL	CO	PO
21.		e a block diagram representing acteristics and applications.	ıg an	embedded system, and elucidate	4	2	1	3
22.								
	Identify processe		ign c	onstraints associated with ARM	4	2	1	3
	Generat PWM n have a	ors. ing a PWM signal with a d nodule of the LPC 2148 mic	luty of rocon ate the	cycle of 75% using the internal troller. The PWM signal should be required values for the PWM	4	2	2	3
23.	Generat PWM n have a period a	ors. ing a PWM signal with a d nodule of the LPC 2148 mic frequency of 10 kHz. Calcul and the match register to achie	luty of rocon ate the ve the	cycle of 75% using the internal troller. The PWM signal should be required values for the PWM				
23.24.	Generat PWM in have a period a Draw th special in	ring a PWM signal with a demodule of the LPC 2148 microfrequency of 10 kHz. Calculand the match register to achieve onchip LPC2148 internal Afunction registers. The the UART data transmission is transmitted a synchronous	luty of rocon ate the ve the DC n	cycle of 75% using the internal troller. The PWM signal should be required values for the PWM e desired duty cycle.	4	2	2	3
23.24.25.	Generat PWM in have a period a Draw th special in Illustrat how dat stop bits	cing a PWM signal with a demodule of the LPC 2148 microfrequency of 10 kHz. Calculand the match register to achieve onchip LPC2148 internal Afunction registers. The the UART data transmission is transmitted a synchronous.	uty or rocon ate the ve the DC n on ar usly a	eycle of 75% using the internal troller. The PWM signal should be required values for the PWM to desired duty cycle. Include and explains its necessary and reception process, explaining	4	2	2	3

CO $PART - C (5 \times 12 = 60 Marks)$ Answer ALL Ouestions 12 28. a. Examine and illustrate the architectural design of the ARM core in LPC 1768, providing a detailed explanation of its features. (OR) 12 3 1 b. Write assembly language program for bitwise logical operations (AND, OR and XOR only)(using ARM processor instruction and its represent in binary mode with 8 bit. Consider at least 3 inputs whose are last six digits of your register number (Ex.103301 means, 10 is first number, 33 is second number and 01 is third number) and executes its output through manual representation. 3 2 12 29. a. Describe the process of configuring GPIO pins on the LPC2148 microcontroller for input and output operations. Include the necessary register settings and programming steps required to configure a GPIO pin as an output and toggle its state. (OR) b. Write embedded C program to flash LEDs using parallel GPIO ports and explain the pin selection register associated with GPIO ports. 12 2 30, a. Discuss the architectures of the RTC module in the LPC2148 microcontroller, including its registers and operational modes. (OR) 3 b. Define timer. Elucidate its characteristics and explain the architecture of timer in LPC 2148 ARM processor with its associated control and timer/ counters register. 12 3 31. a. Compare and contrast the different wireless communication technologies such as Wi-Fi, Bluetooth and cellular networks interms of range, data rate and application scenarios. (OR) b. Discuss the steps involved in making an RPC from the client's request to the server's response, highlighting any necessary marshalling and unmarshalling process. 2 32. a. Define digital signal processing and explain its significance in various fields such as tele-communications, audio processing and image processing. (OR)

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b. Discuss the factors that contribute to achieving high fidelity in digital audio playback such as sampling rate, bit depth, signal to noise ratio and

3

5

12

frequency response.