28. a.	Derive the scalar equations of motion for restricted three-body problem.	10	1	3	1
	(OR)		Ay.		
b.	The geocentric position vectors of a space object at three successive times are $\vec{r_1} = -294.32\hat{i} + 4265.1\hat{j} + 5986.7\hat{k}(km)$	10	3	3	1
	$\vec{r}_2 = -1365.5\hat{i} + 3637.6\hat{j} + 6346.8\hat{k}(km)$				
	$\vec{r}_3 = -2940.3\hat{i} + 2473.7\hat{j} + 6555.8\hat{k}(km)$				
	Determine the velocity vector $\overrightarrow{V_3}$ using Gibbs method.				
9. a.i.	Explain orbit deviation due to injection errors.	5	2	4	
ii.	Describe the general aspects of satellite injection.	5	2	4	1
	(OR)	10	2	4	
Ъ.	Explain the types of space vehicle entry mechanics.	10	L	7	
30. a.	Estimate the radius of a planet's gravitational sphere of influence of three-body system.	10	3	5	
	(OR)				
b.	A spacecraft is launched on a mission to Mars starting from a 300 km circular parking orbit.	10	3	5	
	Calculate (i) The delta-v required, (ii) The location of perigee of the departure hyperbola, and				
	(iii) The amount of propellant required as a percentage of the spacecraft mass before the delta-v burn, assuming a specific impulse of 300 s.				
	* * * *				

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B.Tech. DEGREE EXAMINATION, MAY 2022

Seventh Semester

18ASE304T – SPACE MISSION DESIGN AND ANALYSIS

(For the candidat	tes admitted during the academic year 2018-2019)
	$R_{\text{Sun}} = 1.327 \times 10^{11} \text{km}^3 / \text{s}^2 \text{ and } R_{\text{Sun}} = 57.91 \times 10^6 \text{ km}$
	200,000 13 /-2 and D = 140,6×106 1

 $m_{Earth} = 5.974 \times 10^{24} \text{ kg}, r_{Earth} = 6378 \text{ km}, \mu_{Earth} = 398600 \text{ km}^3 / \text{s}^2 \text{ and } R_{Earth} = 149.6 \times 10^6 \text{ km}$ $m_{Mars} = 6.419 \times 10^{23}$ kg, $r_{Mars} = 3396$ km, $\mu_{Mars} = 42828$ km³ /s² and $R_{Mars} = 227.9 \times 10^6$ km

 $m_{Mercury} = 3.302 \times 10^{23} \text{ kg}, r_{Mercury} = 2440 \text{ km}, \mu_{Mercury} = 22930 \text{ km}^3/\text{s}^2 \text{ and } R_{Mercury} = 57.91 \times 10^6 \text{ km}$ $m_{Jupiter} = 1.899 \times 10^{27} \text{ kg}, r_{Jupiter} = 71490 \text{ km}, \ \mu_{Jupiter} = 1.26686 \times 10^8 \text{ km}^3 \text{ /s}^2 \text{ and } R_{Jupiter} = 778.6 \times 10^6 \text{ km}$ Note:

- (i)
- (ii)

(i)		Part - A should be answered in OMR sheet within first 40 minutes and OMR sheet shoul to hall invigilator at the end of 40 th minute.							ver
(ii)			t - B should be answered in an						
Time:	21/	4 Ho	ırs			Max	. Ma	ırks:	75
			nang a	(25 \ 1 - 25	Mowles	Marks	BL	со	PO
			PART - A	ALL Quest					
	1.	At 1			barded by the atmosphere at orbital	1	1	1	1
	•		cities on the order of						
		(A)	7 km/s	(B)	8 km/s				
		(C)	9 km/s	(D)	10 km/s				
	^	TT 71 .	1 0.4 0.11 1	4 CC4- 41 ₀	a Dandam Access Moment (DAM)	1	1	1	1
	2.			is affects in	e Random-Access Memory (RAM)				
			microprocessors? Trapped radiation	(B)	Solar particle events				
		(C)	Galactic cosmic rays		Magnetosphere				
	- 6	(0)	Galactic cosmic rays						
	3.		are principal mission	on paramete	rs or characteristics which influence	1	1	1	1
		perf	ormance, cost and schedul						
		(A)	Mission architectures	` '	System drivers				
		(C)	Mission evaluation	(D)	Mission objectives				
	1	W/hi	ch of the following are	the princip	al design variable for constellation	1	1	1	° 1
	т.	desi		the princip	ar dough variable to remove and				
			Inclination	(B)	Eccentricity				
		` '	Declination	(D)	Altitude				
							2		
	5.	Whi	ch of the following is also	called as IC	CO?	1	, I	1	1
		(A)	LEO	(B)	MEO				-
		(C)	GEO	(D)	GSO				
	6	The	attitude determination and	d control sul	osystem determine its attitude using	1	1	- 2	1
	υ.	(A)	Sensor		Actuator				
		(C)	Controller	` '	Amplifier				
			COMMONIO	(2)	r				

7	W71-1-1 C /1 C 11		1		,								
/.		ction of telemetry, tracking and command	1	1 2	1	18		mber for air at standard con	ndition is	1	2	4	1
	subsystem?						(A) 0.70		(B) 0.71				
	(A) Receive	(B) Oscillate					(C) 0.80		(D) 0.81				
	(C) Modulate	(D) Transmit							THE PERSON NAMED IN COLUMN				
						19	9. The heat f	lux of the wall is proportion	nal to	1	1	4	_1
8.	A telemetry channel with information	n encoded as a resistance is called as	1 1	2	1			1 free steam temperature	(B) Local stagnation temperature				
	(A) High-level analog	(B) Low-level analog						l temperature gradient	(D) Local velocity gradient				
	(C) Passive analog	(D) Active analog					(0) 2000	ir temperature gradient	(D) Local velocity gradient				
		(=) 1101110 unitalog				20	00 Athunara	ania anaoda tha tatal anthal	larr domanda on the	1	1	4	1
9	The spacecraft average density is		1	2	1	20		onic speeds, the total enthal		•	ı, İ	7	•
٠.	(A) 59 kg/m ³	(B) 69 kg/m^3							(B) Velocity alone				
	(C) 79 kg/m^3								(D) Both static enthalpy and pressure				
	(C) /9 kg/III	(D) 89 kg/m^3					veloc	city					
10	The	- t	1 1	2	1	2	1 Far manne	ed mission which one of th	ne following orbital maneuver has a large	1	1	5	1
10.		e transmitter from receiver.	- n		1	2.		neliocentric orbits?	ic following ofolial maneuver has a large				-
	(A) Actuator	(B) Sensor					_		(D) C:1-:1		8		
	(C) Domain decomposer	(D) Diplexer							(B) Simple impulse maneuver				
							(C) Phasi	ing maneuver	(D) Bi-elliptic Hohmann maneuver				
11.	Which of the following trajectory can	lled as escape trajectory?	1 1	3	1								
	(A) Circular trajectory	(B) Parabolic trajectory				-22		the following is the gravitat		1	2	5	1
	(C) Elliptic trajectory	(D) Hyperbolic trajectory					' '		(B) $42828 \text{ km}^3/\text{s}^2$				
	. , , , , , , , , , , , , , , , , , , ,						(C) 2293	$0 \text{ km}^3/\text{s}^2$	(D) $1.26686 \times 10^8 \text{ km}^3/\text{s}^2$				
12.	Which is the measure of energy requ	ired for interplanetary mission?	1 1	. 3	1								
	(A) Escape velocity	(B) Parabolic excess speed				23	23. In order to	escape the gravitational pu	all of a planet, the spacecraft must travel	1	1	5	1
	(C) Elliptic excess speed	(D) Characteristic energy					in		1 ,				
	(c) Emptie excess speed	(B) Characteristic energy							(B) Circular trajectory				
13	The geocentric position vector is give	000 00	1 3	3	1			tic trajectory	(D) Hyperbolic trajectory				
13.			1 3	, ,	1		(c) Linp	no hajoetory	(b) Tryperbone trajectory				
). What is the corresponding magnitude?				2/	4 Which or	ne of the following out	ronomical object has relatively large	1	1	5	1
	(A) 7356.5 km	(B) 7441.7 km				2-	eccentricit		follomical object has relatively large		•		
	(C) 7456.8 km	(D) 7556.9 km						•	(D) M				
		The second secon					(A) Jupite		(B) Venus				
14.	In perifocal coordinate system, the	unit vector \hat{w} lies in the direction of	1 1	3	1		(C) Satur	n	(D) Pluto				
							5 77 11 1 0				·		
	(A) Eccentricity	(B) Angular momentum				25	5. Which of t	the following are the veloci	ty of an orbiting satellite at an altitude of	1	3	5	1
	(C) Ture anomaly	(D) Eccentric anomaly							$0 \text{ km}^3/\text{s}^2$ and R_{Earth} –6378 km)				
	(c) Tare unomary	(D) Lecentric anomary					(A) 7.5 kg		(B) 8.5 km/s				
15.	is called equilibrium	or liberation point	1 1	3	1		(C) 9.5 kg	m/s	(D) 10.5 km/s				
15.	(A) Lagrange point												
	(C) Gaussian point	(B) Jacobi point											
	(C) Gaussian point	(D) Euler point						$PART - B (5 \times 10)$	= 50 Marks)	Marks	RI.	CO	PO _
1.0	Which of the Call is a second		1 .	,				Answer ALL (
16.		hmetic sum of all the velocity changes	1 1	4	1								
	required to perform a specified missi					26.2	a Define sna	ice mission and explain the	classifications of space mission.	10	1,2	1	1
	(A) Mission characteristic velocity	(B) Launch vehicle characteristic				20.0	a. Define spa	nee mission and explain the	classifications of space mission.		-,-		
-		velocity						(OB)					
	(C) Mission azimuthal velocity	(D) Launch vehicle azimuthal velocity				1.	h E1	(OR)	4.14. 41.	10	2	1	1
						C	o. Explain the	e step by step procedure for	r ordit design.	10	2	1	1
17.	The time of separation is called as		1 1	4	1	0.7	г	1 , 11 1		1.0	_	_	
	(A) Injection parameter	(B) Injection anomaly				27. 8	a. Explain in	detail about attitude determ	nination and control subsystem.	10	2	2	2
	(C) Injection epoch	(D) Injection unit											
	. ,	()J				2		(OR)					
						L b	b. Describe in	n detail about electrical pov	ver subsystem.	10	2	2	1
								× ×					

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