28. a.i.	Identify the characteristics of analog to digital converter (MCP 3008).	5	4	3	3
ii.	Construct a method using photoresistor and MCP3008 ADC to find light intensity in terms of voltage. (Hint: Code not required).	5	4	3	3
hi	(OR)  Develop a code to detect 'tilt direction' detection.	6	3	3	3
	Illustrate the working of accelerometer.	4	3	3	3
	Direct a ultrasonic range finder and bring out the working behind it.	5	4	4	3
ii.	Illustrate the characteristics of ultrasonic range finder (SR-04).	5	3	4	3
b.i.	(OR) Show the steps to display on a four digit LED matrix with I2C interface.	5	3	4	3
ii.	Use colour eight by eight () function in the code to display different colours in 8×8 LED matrix.	5	3	4	3
30. a.i.	Sketch the MQTT publish/subscribe architecture and explain the key points.	5	3	5	3
ii.	Assume Pi camera is connected to Raspberery Pi through CSI camera port. Write a code to take a photo.	5	4	5	3
b.	(OR) Use Raspberry Pi board and Node.js to make a LED to blink. Write a program and draw a relevant diagram.	10	3	5	4

Reg. No.

## **B.Tech. DEGREE EXAMINATION, MAY 2022**

Sixth Semester

## 18ECO109J – EMBEDDED SYSTEM DESIGN USING RASPBERRY PI

Note:		(For the	candia	iates aan	nittea jro	m the ac	aaemic year 20	018-2019 to 201	9-2020)	-			
(i)	over	to hall inv	igilato	r at the en	nd of 40 <sup>th</sup>	minute		ninutes and OM	R sheet	shoul	d be	han	ded
(ii)	Par	t - B should	d be an	swered in	n answer	booklet							
ime: 2	½ Ho	urs					The second			Max.	Ma	rks:	75
		, · ·	PA		(25 × 1					Marks	BL	со	PO
1	W/h	ot will be t	the our		er ALL			if $x = 56.233$ ?	)	1	2	1	5
1.		t ("% <i>d</i> "%		ւքա	OHOWIH	g pyulo	in expression	11 % - 50.255					
	(A)	56.238				(B)	56.23						
	(C)	56.2				(D)	56						
2.	What $x * *$		of out	put of th	ne follov	ving py	thon code sni	ppet if x=5?	2	1	2	1	5
	(A)					(B)	2						
	(C)	5				(D)	125					ž.	
3.		ich of the	e follo	owing f	unction	conve	t a string to	a real num	ber in	1	2	1	5
	(A)	int(k)				(B)	char(y)						
		float(x)	)			(D)	reel(x)						
1	То	control a h	nigh n	ower los	ad sav I	FD nar	el, one has to	use		1	1	1	1
т.		BJT	ngn p	3 44 61 100	ad bay 12		MOSFET						
	(C)					(D)	Tetrode						
5.	. Wh		the ou	tput of t	the follo	wing p	ython code sr	nippet if $x = 1$ ?	?	1	2	1	5
	(A)	- 4				(B)	2						
	(C)	1					7						
6.	. The	e following	g code	snippet	t belong	s to $< h$	$_{1} > GPIO con$	$atrol < /h_1 >$		1	1	2	2
		http		- 11			Python						
	(C)					` '	SML						
7	Fin	d out the r	າດກະກະ	ermissih	le paran	neter in	GPIO.add-ev	vent-detect()	is	1	1	2	1
,		Pin num			Paran	(B)	GPIO.fallin	g					
	(C)					(D)	Import						
	(0)					( )	*						

8.	For proper functioning, the coils in t	he stepper motor should be energized	1	1	2	1	2.0	0.	The spreadsheet used in raspberry		- 1	1	4	4
	(A) Persistently	(B) Randomly								(B) Gnumeric				
	(C) In a sequence	(D) Based on availability of power					-		`	(D) Tensor flow	W			
9.	Quadrature encoder behaves like a p		1	1	2	2	21	1.	The language that can turn a HTM	L web page into a fully functioning	1	2	5	5
	(A) Amplifiers	(B) Oscillators	9						desktop equivalent application					
	(C) Switches	(D) Regulators								(B) MQ++				
1.0	A 1.:1	11 11	,		2	2			(C) Ada fruit	(D) Javascript				
10.	A bipolar stepper motor can be contr		1	1	2	3	_						= =	
	(A) Sparkify board	(B) Applying pressure					22		Eclipse paho is a	T) T	1	1	5	5
	(C) $I^2C$ communication	(D) Raspirobot board								(B) Java script client library				
11.	The MQ-4 can detect natural gas con	centrations anywhere from	1	1	3	5			(C) Javabyte peer	(D) Raspberry Pi library				
	(A) 200 ppm-10000 ppm	(B) 2 ppm-10 ppm					23	3	Following is a front-end frame work f	or faster and earier web development	1-	_ 1	-5	-5
	(C) 500 ppb-1000ppb	(D) 200ppb-400ppb					23			(B) Dbase				
		(-)								(D) Bootstrap				
12.	The number of channels in MCP300	8 analog to digital converter is	1	1	3	5				(b) Beetsaup				
	(A) 2	(B) 22					24	1.	Which is not true for MQTT is		1	2	1	2
	(C) 8	(D) 40							(A) It is Bi-directional	(B) It is a reliable message delivery				
									communication protocol	protocol				
13.	Which of the following represents IR		1	1	3	3				(D) Supports high data rate with				
	(A) 10 nm to 150 nm	(B) 700 nm to 2500 nm							protocol	maximum bandwidth				
	(C) 4000 A° to 7000 A°	(D) Greater than 25 mm					2.5		Class P. C		1	1	_	E i
14.	Following code snippet is associated	with	1	2	3	5	23		Cherry Pi is a	(D) Java conint with frame week	1	1	3	3
	print(" $lat = \% f \setminus t \ lon = \% f \setminus t \ time$								<ul><li>(A) Python based web frame work</li><li>(C) C++ library</li></ul>	<ul><li>(B) Java script web frame work</li><li>(D) MQTT dashboard module</li></ul>				
	%(lat,lon,report['time']))								(c) C. Holdry	(D) WQ11 dashooard module				
	(A) Temperature sensor	(B) Ultrasonic range finder												
	(C) Display module	(D) GPS device							$PART - B (5 \times 10 =$		Marks	BL	СО	PO
									Answer ALL Qu	estions				
15.	In the temperature sensor TM	P36is proportional to	1	1	3	3	26 0 3		Change the right function in nythen	So as to some out number to string	5	3	1	5
	temperature						20. a.i		and to replace one string with other.	So as to carry out number to string	3	,	ì	3
	(A) Power	(B) Current							and to replace one string with other.					
	(C) Voltage	(D) Resistance					ii	i.	Create a list with five items in pythor	n. Use the code to access the list and	5	4	1	5
16	Large scale database analytics service	a biognam ie availabla in	1	1	4	3			add new entry in different ways.					
10.	(A) Linux azure	(B) Windows apache												
	(C) Google cloud platform	(D) IBM code developer							(OR)					
		( ) ===================================					b.i	i.	Solve the celcius to Fahrenheit conver	sion with python's function feature.	5	4	1	5
17.	Find the non-available column and	row combination for a alphanumeric	1	1	4	4					ç			
	LCD						11			ython's dictionary facility. Write the	5	4	<u>.</u> I	5
	(A) 8×1	(B) 16×2							code to iterate over the dictionary.					
	(C) 20×2	(D) 23×11					27. a	ì, .	Illustrate the method to control the ser	vo motor.	10	3	2	1
18	Popular LCD module controller deve	loned by hitachi is	1	1	4	4	10							
10.	(A) 8085	(B) HD44780							(OR)					
	(C) Hita87	(D) 80486					b.i	1.	Demonstrate the operation of H-bridge	е.	5	3	2	3
10	The leading Themper's		1			2	ii	i. ]	Plan to produce a simple robot rov	ver. Give the hardware and nython	5	3	2	3
19.	The device TMP36 is a	(D) Hoot sink	1	]	4	3			programming tips to build the robot. (					
	<ul><li>(A) Temperature sensor</li><li>(C) Ultrasonic range finder</li></ul>	<ul><li>(B) Heat sink</li><li>(D) LED controller</li></ul>								,				
Page 2 of 4	(c) or asome range infact	(D) LED COMMUNICI	2.7MF	F618EC	0109	J	Page 3 of	4			143 4T	(100)	2010	O.T.
<i>J</i>			2/1VII	UIOEC	.0103		rage 3 01	4			27MF	618EC	.O109	73