

# Computational Physics: Assignment 4

Sarah Roberts

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**Part 1: Integration.** Functions were written in python to implement the Trapezoid method and Simpson's method. The included code first tests the methods on

$$\int_{-1}^1 x^2 + 2x + 2 = 4.666...$$

The trapezoid method converges to 4.663 for  $n = 1532$  steps, which has a percent error of 0.065% while Simpson's method converges to 4.665 for  $n = 521$ , which has a percent error of 0.027%. As expected, Simpson's method converges much more quickly than the Euler method.

After testing with a simple integral, the same functions were applied to approximating

$$\int_{-100}^{100} \frac{1}{\sqrt{2\pi}} e^{-\frac{(x-1)^2}{2}} = 1.0$$

The trapezoid method approximated an integral of 0.9986 for  $n = 712$ , which has percent error of 0.1404%. Simpson's rule approximated the integral as 0.9962 after  $n = 253$  iterations, with a percent error of 0.3773%. The following two plots show the error as a function of number of steps  $n$  for each of the two methods, when evaluating the latter integral.

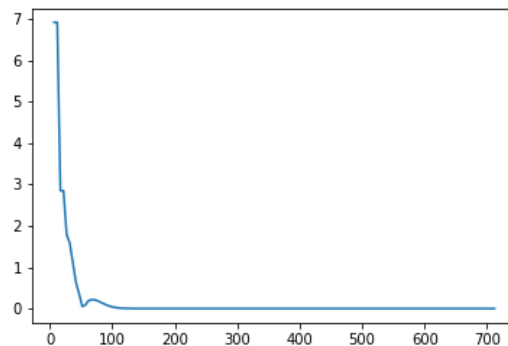


FIGURE 1. `trap.png` Percent error as a function of  $n$  when approximating the integral with trapezoid method.

**Part 2: Ordinary Differential Equations (ODEs).** Functions to approximate the solution for an ordinary differential equation were written in Python. They were applied to the ODE:

$$\frac{dx}{dt} = 4x - t + 1$$

where  $x(0) = 1$

First, Euler's method is called for  $n = 1000$ , so the method is applied to 1000 evenly spaced steps on the domain  $t = [0, 1]$ . A plot of this solution and the analytic solution is shown below. Then, the Runge-Kutta function is called for  $n = 500$ . A plot with this solution is shown below and also includes the analytic solution and the Euler approximation.

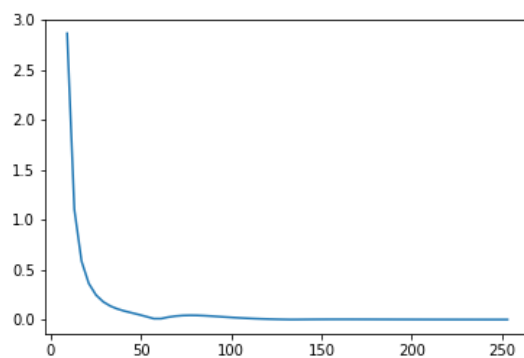


FIGURE 2. `simpson.png` Percent error as a function of  $n$  when approximating the integral with Simpson's method. Note the different scale on the  $x$  axis, compared to Figure 1. Simpson's method converges much more quickly than the trapezoid method.

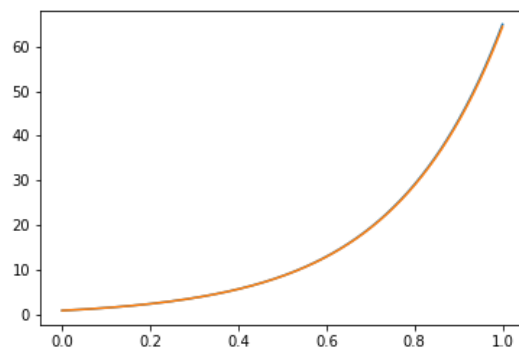


FIGURE 3. `euler.png` This figure shows the analytic solution in blue and the Euler approximation in orange.

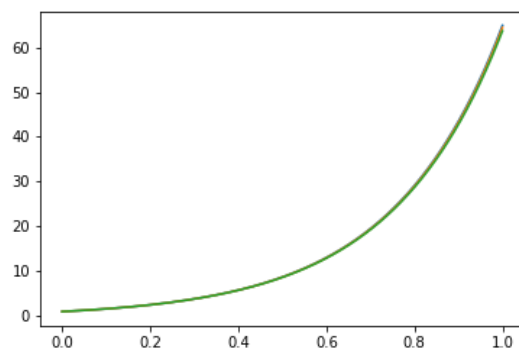


FIGURE 4. `rungekutta.png` This figure shows the analytic solution in blue, the Euler approximation in orange, and the Runge-Kutta approximation in green.

Finally, the error in the final step ( $t = 1.0$ ) was compared between the Euler and Runge Kutta methods for varying step size. The error was calculated as a fraction of the correct value, according to the analytic solution

$$x(t) = \frac{1}{16}(4t + 19e^{4t} - 3)$$

$$\text{err} = \frac{|x(t) - x_{\text{approx}}(t)|}{x(t)}$$

where  $x_{\text{approx}}(t)$  is the numerical approximation of  $x$  at  $t$ .

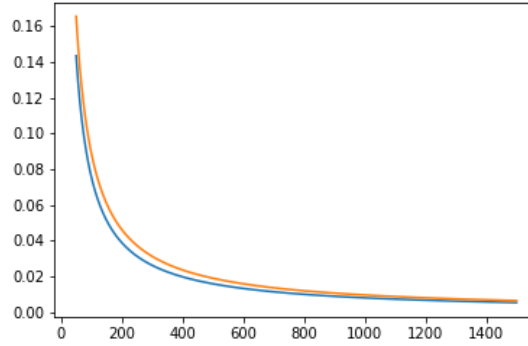


FIGURE 5. `eulerRKErrors.png` The relative error in the approximation of  $x(t = 1.0)$  was compared between the Euler and Runge-Kutta methods for varying step size. The Euler method is shown in orange and Runge-Kutta in blue. The  $x$  axis is number of steps (more steps is a smaller step size) and  $y$  axis is the error (smaller is better).