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| Process Creation | • A process (sometimes called a task) can create another process<br>  ○ Parent process – the creating process<br>  ○ Child process – the process created<br>• Tree – parent and its children |
| | • Child process can be:<br>  ○ Duplicate of the parent process (same program/data)<br>  ○ New program loaded into it (using exec)<br>  ▪ Replaces process memory space with the new program<br>• How many children can you fork from a process?<br>  ○ Limited based on the amount of memory, maximum value for pid<br>  ○ On a 64-bit system could be ~4 million, but typically related to resources |
| Process Termination | • A process terminates when it finishes executing its final statement and asks the OS to delete it by using the exit() system call<br>• A return value can be sent to its parent via the wait() system call<br>• All system resources are deallocated |
| | • Parent typically is the only one that can terminate a child process<br>• Parent users from terminating other users' processes |
| | • Possible reasons for child termination:<br>  ○ Child has exceeded usage of resources allocated<br>  ○ Task assigned to the child is no longer required<br>  ▪ Multiple children processes -> one finishes<br>  ▪ Child process -> downloading file<br>  ○ The parent is exiting and the OS does not allow the child to continue if its parent is terminated<br>  ▪ Cascading termination |
| | • A process who has terminated, but the parent has not yet called wait() is called a **zombie process**<br>• Once the parent calls wait(), the process identifier and zombie process and its entry in the process table is released<br>• If the parent did not invoke wait and instead terminates, the child then becomes an **orphan** |
| Interprocess Communication | • Cooperating – any process that can be affected by another process. Any process that shares data with another process is a cooperating process<br>• Independent – any process that cannot affect or be affect by another process |
| | • Why cooperate?<br>  ○ Information sharing (e.g., shared file)<br>  ○ Computation speedup (e.g., run in parallel)<br>  ○ Modularity (e.g., system functions in separate processes)<br>  ○ Convenience (e.g., work on multiple tasks at the same time) |
| | • Two fundamental models for interprocess communication<br>  ○ Shared Memory |

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| | ▪ Reading/writing data to a shared region of memory<br>o Message passing<br>▪ Useful for exchanging smaller amounts of data |
| Shared-Memory Systems | • Producer/consumer: one process produces, the other process consumes<br>o What are some examples of a Producer/Consumer scenario |
| | • Unbounded buffer – no practical limit on the size of the buffer<br>o Producer can always produce new items<br>• Bounded buffer – fixed buffer size<br>o Producer waits if buffer is full<br>o Consumer waits if buffer is empty |
| Message-Passing Systems | • Symmetry – sender and receiver name each other to communicate<br>• Asymmetry – sender names the recipient but not vice versa<br>o Send(P, message) – send a message to P<br>o Receive(id, message) – receive a message from any process, the variable id is set to the name of the process communicated with |
| Lab Questions<br><br>• Parent process runs<br>• Accepts input from user<br>• Forks a child process<br>• When the child process is forked, exec() is used to replace the child process with the command given by the user<br>o Exec(ls, [argument passed to ls]) | |