

Formalizing the Edmonds-Karp Algorithm

Peter Lammich and S. Reza Sefidgar

TU München

August 2016

Maximum Flow Problem

- Network: Digraph with edge capacities and source/sink nodes
- Flow: From source to sink, not exceeding capacities
 - Kirchhoff's law: Inflow = Outflow for all nodes but source/sink
 - No inflow to source, no outflow from sink
 - Value: Flow transported from source to sink (=Outflow of source)
- Problem: Given a network, find a flow with maximal value

Ford-Fulkerson Method

- Consider network with flow
 - No antiparallel edges: $u \rightarrow v \implies v \not\rightarrow u$
- Residual graph
 - For network edge $u \xrightarrow{c,f} v$, residual graph has

$$u \xrightarrow{c-f} v \text{ and } v \xrightarrow{f} u$$

- Intuition: Flow that can be moved between nodes
 - By either increasing or decreasing flow on network edge
- Ford-Fulkerson
 - Flow is maximal iff no path from source to sink in residual graph
 - Corollary of min-cut max-flow theorem

Ford-Fulkerson Method

Flow is maximal iff no path from source to sink in residual graph.

- Greedy Algorithm

Set flow to zero

while *exists augmenting path*

augment flow along path

- Partial correctness: obvious
- Termination: Only for integer/rational capacities
- Edmonds/Karp: Choose shortest augmenting path
 - $O(VE)$ iterations for real-valued capacities
 - Using BFS to find path: $O(VE^2)$ algorithm

Our Contributions

Verified in Isabelle/HOL

- Min-Cut Max-Flow theorem
 - Human-Readable Isar proof
 - Closely following Cormen et al.
- Ford-Fulkerson and Edmonds Karp algorithms
 - Human-readable presentation of algorithms
 - Proved Correctness and Complexity
- Efficient Implementation
 - Using stepwise refinement down to Imperative/HOL
 - Isabelle's code generator exports to SML
 - Benchmark: Comparable to Java (from Sedgewick et al.)

Human-Readable Proofs

- Tried to use Isar in readable way

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Proof fragment from Cormen et al.:

$$\begin{aligned}(f \uparrow f')(u, v) &= f(u, v) + f'(u, v) - f'(v, u) && \text{(definition of } \uparrow \text{)} \\ &\leq f(u, v) + f'(u, v) && \text{(because flows are nonnegative)} \\ &\leq f(u, v) + c_f(u, v) && \text{(capacity constraint)} \\ &= f(u, v) + c(u, v) - f(u, v) && \text{(definition of } c_f \text{)} \\ &= c(u, v).\end{aligned}$$

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Our Isar version:

```
have (f↑f')(u,v) = f(u,v) + f'(u,v) - f'(v,u)
by (auto simp: augment_def)
also have ... ≤ f(u,v) + f'(u,v) using f'.capacity_const by auto
also have ... ≤ f(u,v) + cf(u,v) using f'.capacity_const by auto
also have ... = f(u,v) + c(u,v) - f(u,v)
by (auto simp: residualGraph_def)
also have ... = c(u,v) by auto
finally show (f↑f')(u, v) ≤ c(u, v) .
```


And Automatic Proofs

- Cormen et al. also give more complicated proofs

First part of proof that $|f \uparrow f'| = |f| + |f'|$:

$$\begin{aligned} & |f \uparrow f'| \\ &= \sum_{v \in V_1} (f(s, v) + f'(s, v) - f'(v, s)) - \sum_{v \in V_2} (f(v, s) + f'(v, s) - f'(s, v)) \\ &= \sum_{v \in V_1} f(s, v) + \sum_{v \in V_1} f'(s, v) - \sum_{v \in V_1} f'(v, s) \\ &\quad - \sum_{v \in V_2} f(v, s) - \sum_{v \in V_2} f'(v, s) + \sum_{v \in V_2} f'(s, v) \\ &= \sum_{v \in V_1} f(s, v) - \sum_{v \in V_2} f(v, s) \\ &\quad + \sum_{v \in V_1} f'(s, v) + \sum_{v \in V_2} f'(s, v) - \sum_{v \in V_1} f'(v, s) - \sum_{v \in V_2} f'(v, s) \\ &= \sum_{v \in V_1} f(s, v) - \sum_{v \in V_2} f(v, s) + \sum_{v \in V_1 \cup V_2} f'(s, v) - \sum_{v \in V_1 \cup V_2} f'(v, s). \quad (26.6) \end{aligned}$$

And Automatic Proofs

- Cormen et al. also give more complicated proofs
- We sometimes chose to use more automatic proofs

lemma augment_flow_value: Flow.val c s ($f \uparrow f'$) = val + Flow.val cf s f'
proof -

interpret f'': Flow c s t $f \uparrow f'$ **using** augment_flow_presv[OF assms] .

And Automatic Proofs

- Cormen et al. also give more complicated proofs
- We sometimes chose to use more automatic proofs
 - Using some simplifier setup

```
note setsum_simp_setup[simp] =  
  sum_outgoing_alt[OF capacity_const] s_node  
  sum_incoming_alt[OF capacity_const]  
  cf.sum_outgoing_alt[OF f'.capacity_const]  
  cf.sum_incoming_alt[OF f'.capacity_const]  
  sum_outgoing_alt[OF f''.capacity_const]  
  sum_incoming_alt[OF f''.capacity_const]  
  setsum_subtractf setsum.distrib
```

And Automatic Proofs

- Cormen et al. also give more complicated proofs
- We sometimes chose to use more automatic proofs
 - Using some simplifier setup
 - And auxiliary statements

```
have aux1:  $f'(u,v) = 0$  if  $(u,v) \notin E$   $(v,u) \notin E$  for  $u\ v$   
proof -  
  from that cfE_ss_invE have  $(u,v) \notin cf.E$  by auto  
  thus  $f'(u,v) = 0$  by auto  
qed
```

And Automatic Proofs

- Cormen et al. also give more complicated proofs
- We sometimes chose to use more automatic proofs
 - Using some simplifier setup
 - And auxiliary statements
 - We reduce the displayed proof's complexity

have $f''.val = (\sum_{u \in V}. \text{augment } f' (s, u) - \text{augment } f' (u, s))$

unfolding $f''.val_def$ **by** simp

also have $\dots = (\sum_{u \in V}. f (s, u) - f (u, s) + (f' (s, u) - f' (u, s)))$

— Note that this is the crucial step of the proof, which Cormen et al. leave as an exercise.

by (rule setsum.cong) (auto simp: augment_def no_parallel_edge aux1)

also have $\dots = val + \text{Flow.val cf } s \ f'$

unfolding $val_def \ f'.val_def$ **by** simp

finally show $f''.val = val + f'.val$.

qed

Main Result

- Finally, we arrive at

context NFlow **begin**

...

theorem ford_fulkerson: **shows**

$\text{isMaxFlow } f \longleftrightarrow \neg \text{Ex isAugmentingPath}$

Ford-Fulkerson Method

- We use the Isabelle Refinement Framework

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 - Based on nondeterminism monad + refinement calculus
 - Provides proof tools + Isabelle Collection Framework

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```
definition ford_fulkerson_method  $\equiv$  do {  
  let f = ( $\lambda(u,v).$  0);  
  
  (f,brk)  $\leftarrow$  while ( $\lambda(f,brk).$   $\neg$ brk)  
  ( $\lambda(f,brk).$  do {  
    p  $\leftarrow$  selectp p. is_augmenting_path f p;  
    case p of  
      None  $\Rightarrow$  return (f,True)  
    | Some p  $\Rightarrow$  return (augment c f p, False)  
  })  
  (f,False);  
  return f  
}
```

Correctness Proof

- First, we add some assertions and invariant annotations

```
definition fofu  $\equiv$  do {  
  let f = ( $\lambda$ _. 0);  
  
  (f,_)  $\leftarrow$  whilefofu_invar  
    ( $\lambda$ (f,brk).  $\neg$ brk)  
    ( $\lambda$ (f,_). do {  
      p  $\leftarrow$  find_augmenting_spec f;  
      case p of  
        None  $\Rightarrow$  return (f,True)  
      | Some p  $\Rightarrow$  do {  
        assert (p $\neq$ []);  
        assert (NFlow.isAugmentingPath c s t f p);  
        let f' = NFlow.augmentingFlow c f p;  
        let f = NFlow.augment c f f';  
        assert (NFlow c s t f);  
        return (f, False)  
      }  
    })  
  (f,False);  
  assert (NFlow c s t f);  
  return f  
}
```

Correctness Proof

- First, we add some assertions and invariant annotations
- Then, we use the VCG to prove partial correctness

theorem fofu_partial_correct: fofu \leq (**spec** f. isMaxFlow f)

unfolding fofu_def find_augmenting_spec_def

apply (refine_vcg)

apply (vc_solve simp:

zero_flow

NFlow.augment_pres_nflow

NFlow.augmenting_path_not_empty

NFlow.noAugPath_iff_maxFlow[symmetric])

done

Correctness Proof

- First, we add some assertions and invariant annotations
- Then, we use the VCG to prove partial correctness
- This also yields correctness of the unannotated version

theorem (in Network) ford_fulkerson_method \leq (**spec** f. isMaxFlow f)

Edmonds-Karp Algorithm

- Specify shortest augmenting path

definition `find_shortest_augmenting_spec f` \equiv **assert** (NFlow c s t f) \gg
(**selectp** p. Graph.isShortestPath (residualGraph c f) s p t)

Edmonds-Karp Algorithm

- Specify shortest augmenting path
- This is a refinement of augmenting path

lemma find_shortest_augmenting_refine[refine]:

$(f', f) \in \text{Id} \implies \text{find_shortest_augmenting_spec } f' \leq \Downarrow \text{Id } (\text{find_augmenting_spec } f)$

Note: This is verbose boilerplate for

$\text{find_shortest_augmenting_spec} \leq \text{find_augmenting_spec}$

Edmonds-Karp Algorithm

- Specify shortest augmenting path
- This is a refinement of augmenting path
- Replace in algorithm

definition $\text{fofu} \equiv \text{do}$ {

...

$p \leftarrow \text{find_augmenting_spec } f;$

...

Edmonds-Karp Algorithm

- Specify shortest augmenting path
- This is a refinement of augmenting path
- Replace in algorithm

definition edka_partial \equiv **do** {

...

p \leftarrow find_shortest_augmenting_spec f;

...

Edmonds-Karp Algorithm

- Specify shortest augmenting path
- This is a refinement of augmenting path
- Replace in algorithm
- New algorithm refines original one

lemma edka_partial_refine[refine]: edka_partial \leq \Downarrow Id fofu

unfolding find_shortest_augmenting_spec_def find_augmenting_spec_def
apply (refine_vcg)
apply (auto
 simp: NFlow.shortest_is_augmenting
 dest: NFlow.augmenting_path_imp_shortest)
done

Total Correctness and Complexity

- Next, we define a total correct version

definition $\text{edka_partial} \equiv \mathbf{do} \{$

...

$(f, _) \leftarrow \mathbf{while}^{f \text{ of } u \text{ } \textit{invar}}$

...

Total Correctness and Complexity

- Next, we define a total correct version

definition $\text{edka} \equiv \mathbf{do} \{$

...

$(f, _) \leftarrow \mathbf{while}_T^{f \text{ of } u_invar}$

...

Total Correctness and Complexity

- Next, we define a total correct version
- And show refinement

theorem `edka_refine[refine]`: $\text{edka} \leq \Downarrow \text{Id edka_partial}$

Total Correctness and Complexity

- Next, we define a total correct version
- And show refinement
- We also show $O(VE)$ bound on loop iterations
 - Instrumenting the loop with a counter

Towards Efficient Implementation

Several refinement steps lead to final implementation:

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- 1 Update residual graphs instead of flows

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Several refinement steps lead to final implementation:

- 1 Update residual graphs instead of flows
- 2 Implement augmentation (iterate over path twice)
- 3 Use BFS to determine shortest augmenting path

Towards Efficient Implementation

Several refinement steps lead to final implementation:

- ① Update residual graphs instead of flows
- ② Implement augmentation (iterate over path twice)
- ③ Use BFS to determine shortest augmenting path
- ④ Implement successor function on residual graph
 - Using pre-computed map of adjacent nodes in network

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 - Using pre-computed map of adjacent nodes in network
- ⑤ Imperative Data Structures
 - Tabulate capacity matrix and adjacency map to array
 - Maintain residual graph in array

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Several refinement steps lead to final implementation:

- ① Update residual graphs instead of flows
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- ⑤ Imperative Data Structures
 - Tabulate capacity matrix and adjacency map to array
 - Maintain residual graph in array
- ⑥ Export to SML code

Assembling Overall Correctness proof

- Correctness statement
 - As Hoare-Triple using Separation Logic

context Network_Impl **begin**

theorem edka_imp_correct:

assumes VN: Graph.V $c \subseteq \{0..<N\}$

assumes ABS_PS: is_adj_map am

shows

<emp>

edka_imp c s t N am

< $\lambda fi. \exists_A f. \text{is_rflow } N \ f \ fi \ * \ \uparrow(\text{isMaxFlow } f)$ >_t

Assembling Overall Correctness proof

- Correctness statement
 - As Hoare-Triple using Separation Logic
- Proof by transitivity

proof -

interpret Edka_Impl **by** unfold_locales fact

note edka5_refine[OF ABS_PS]

also note edka4_refine

also note edka3_refine

also note edka2_refine

also note edka_refine

also note edka_partial_refine

also note fofu_partial_correct

finally have edka5 am \leq SPEC isMaxFlow .

from hn_refine_ref[OF this edka_imp_refine]

show ?thesis

by (simp add: hn_refine_def)

qed

Assembling Overall Correctness proof

- Correctness statement
 - As Hoare-Triple using Separation Logic
- Proof by transitivity
- Also integrated with check for valid network
 - Input is list of edges, source, and sink

theorem

fixes el **defines** $c \equiv \text{In_}\alpha \text{ el}$

shows $\langle \text{emp} \rangle \text{edmonds_karp el s t} \langle \lambda$

None $\Rightarrow \uparrow(\neg \text{In_invar el} \vee \neg \text{Network c s t})$

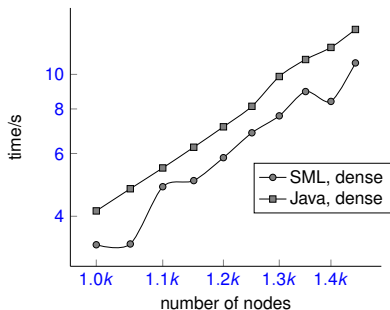
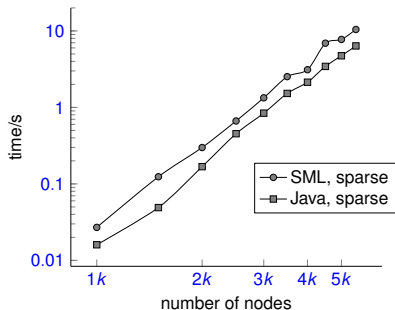
| Some (N,cf) \Rightarrow

$\uparrow(\text{In_invar el} \wedge \text{Network c s t} \wedge \text{Graph.V c} \subseteq \{0..<N\})$

* $(\exists_A f. \text{is_rflow c N f cf} * \uparrow(\text{Network.isMaxFlow c s t f})) \rangle_t$

Benchmarking

- Against Java version of Sedgewick et al., on random networks
 - Sparse graphs (density=0.02): Java is (slightly) faster
 - Dense graphs (density=0.25): We are (slightly) faster
 - Supposed reason: Different 2-dimensional array implementations



Conclusion

- Proof of Min-Cut/Max-Flow theorem
 - Human readable proofs following textbook presentation
 - Showing off Isar proof language
- Verified Edmonds-Karp algorithm
 - From abstract pseudo-code like version ...
 - ... down to imperative implementation
 - Showing off Isabelle Refinement Framework
- Our implementation is pretty efficient