

Section 2

①

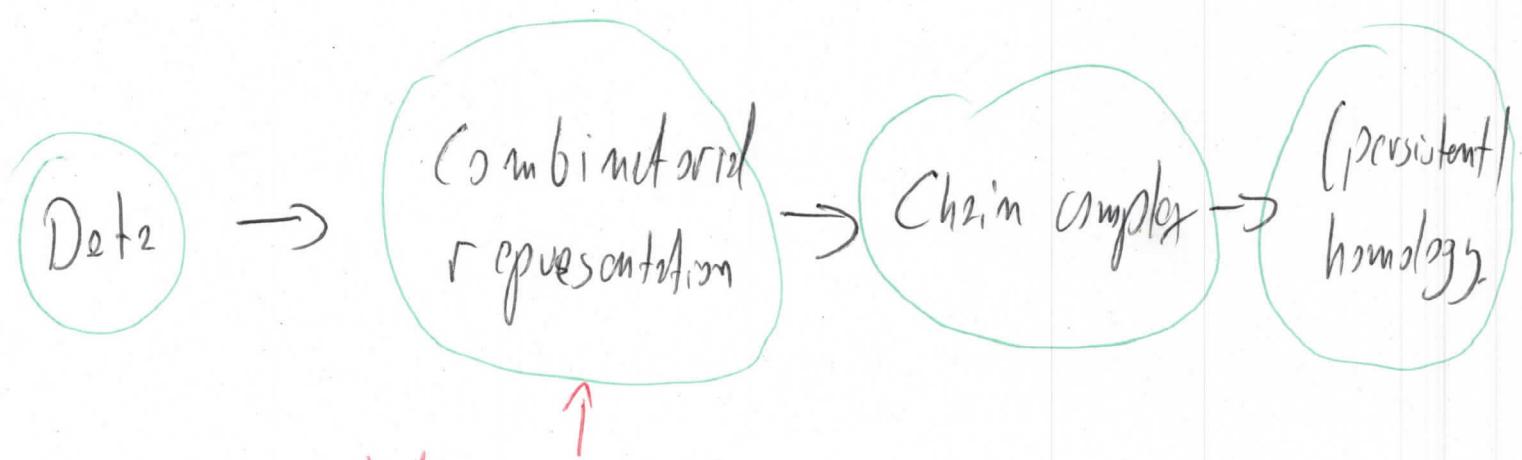
From data_2 to topological representation

There are many instances of real data that can be described using topology. The basic examples are:

- ① 2,3, higher dimensional images, (pictures, static or dynamic CT scans...)
- ② Point clouds - e.g. characteristics of patients with Covid 19.
- ③ Time series

④ ...

We need to represent all those data in the way that allows to compute their topology



Let us quickly discuss what this is for various type of data.

Images naturally correspond to so called
② cubical complexes.

What is a cubical complex? Let us start by asking a more fundamental question: What is a cube?

"Before the time began, there was the Cube. We do not know where it comes from, only that it holds the power..."

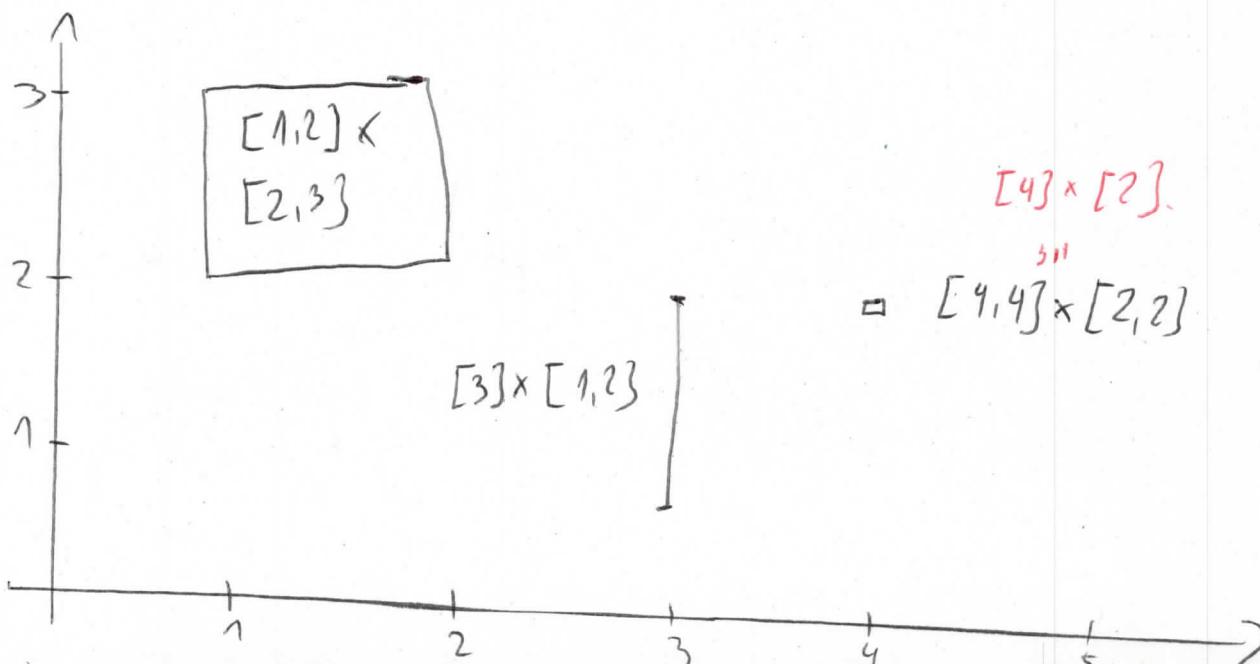
Optimus Prime-
Transformers

More seriously,

Elementary interval is an interval of a form:

$$\begin{cases} [m, m+1] \\ [m, n] \end{cases} \quad \text{for } m \in \mathbb{N}.$$

A cube is a Cartesian product of elementary intervals



Cubes, especially those that decompose a rectangle in the ③ ambient space, can be very effectively stored in a computer in a form of **bitmap**.

That include:

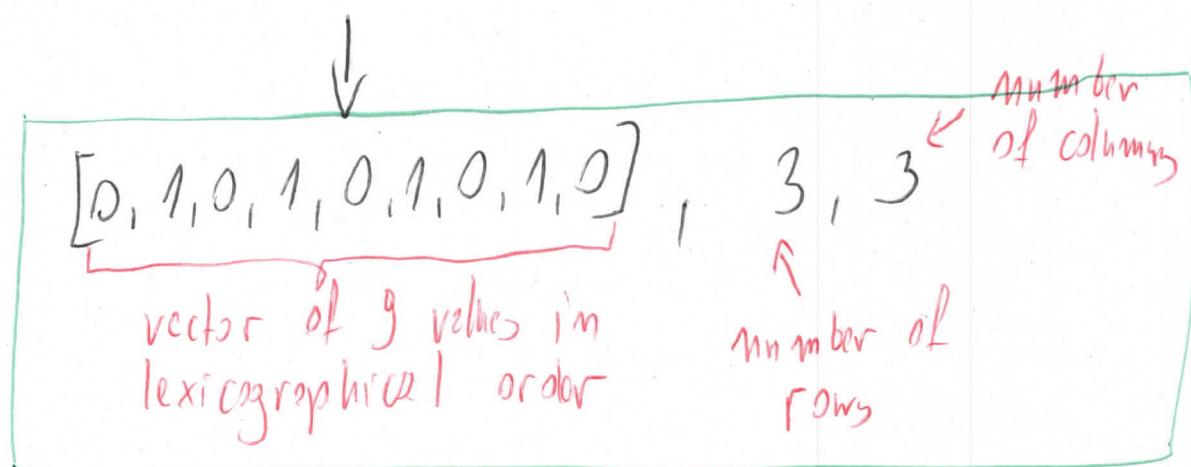
- ① For black & white, (thresholded) images:

B&W
image

| | | |
|---|---|---|
| 0 | 1 | 0 |
| 1 | 0 | 1 |
| 0 | 1 | 0 |

black = 1
white = 0

Bitmap



One bit (not byte) per cube

- ② For grayscale or RGB images similarly, but we need to store more...

(4)

| | | |
|-----|-----|-----|
| 8 | 239 | 11 |
| 251 | 242 | 228 |
| 9 | 236 | 3 |

Grayscale values, integers between
0 & 255



$[9, 236, 3, 251, 242, 228, 8, 239, 11] + \text{sizes of picture}$

One integer per cube

For RGB we will store three integers per cube.

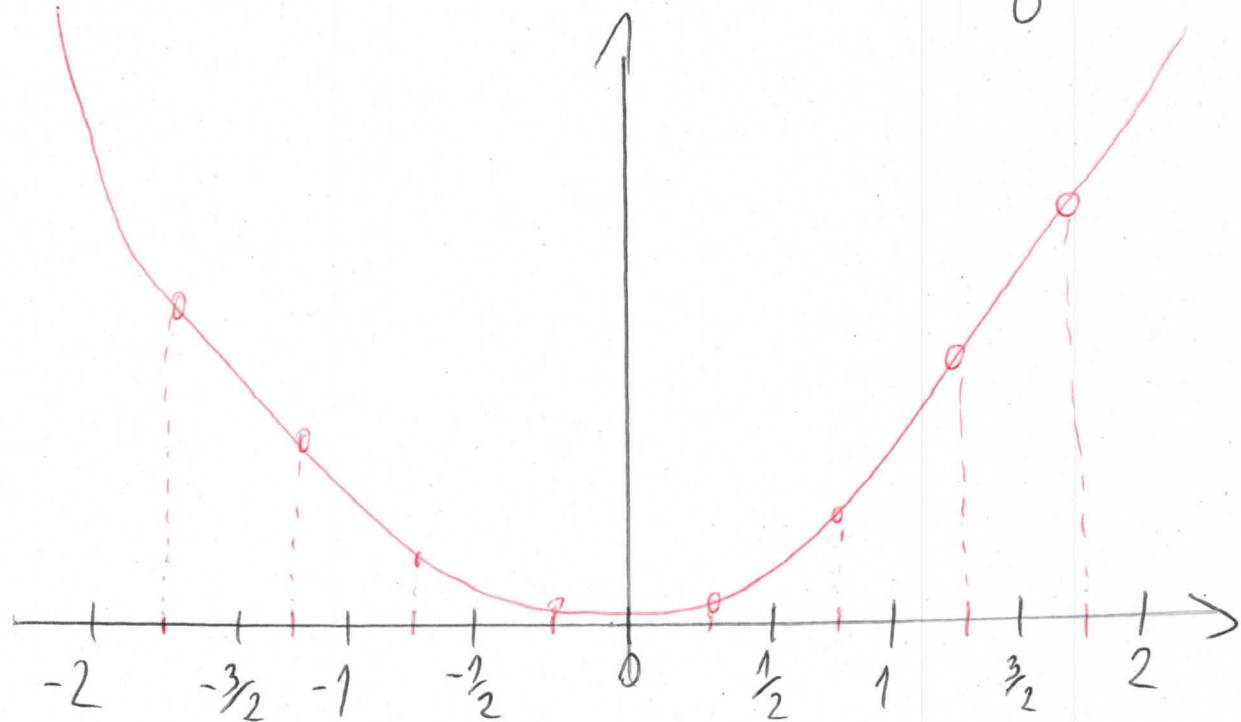
Cubical complexes were introduced & promoted (in oppose to simplicial complexes) by Jean-Paul Serre in the middle of 20'th century. Later they were made popular with so called interval arithmetic.

But, we will not get too deep to this topic in this tutorial. Let me just say that the cubical complexes allow to approximate functions on rectangular domains.

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Let us consider a simple example:

$y = x^2$, domain = $[-2, 2]$, number of cubes = 8 :



| | | | | | | | |
|--------------------|--------------------|--------------------|--------------------|-------------------|-------------------|-------------------|-------------------|
| $(-\frac{3}{4})^2$ | $(-\frac{5}{4})^2$ | $(-\frac{3}{4})^2$ | $(-\frac{1}{4})^2$ | $(\frac{1}{4})^2$ | $(\frac{3}{4})^2$ | $(\frac{5}{4})^2$ | $(\frac{7}{4})^2$ |
|--------------------|--------------------|--------------------|--------------------|-------------------|-------------------|-------------------|-------------------|

Let us now play with two dimensional images & their persistence.

Let us do it on the google colab file i will share with you now

(Let us play with python)

ssss...



(6)

Having the 2d example of a cubical complex we can play & observe the concept of stability of persistence.

Formally, in this context:

Let $\Omega \subseteq \mathbb{R}^n$ and $f, g : \Omega \rightarrow \mathbb{R}$.

Let $P = \text{persistent homology of } \Omega$ with a filtration
 $Q = \text{persistent homology of } \Omega$ with filtration

Then $d_B(P, Q) \leq \|f - g\|_\infty$

\nearrow

Bottleneck distance
between diagrams P & Q

\nearrow
 L^∞ distance between functions
at Ω , i.e.
 $\max_{x \in \Omega} |f(x) - g(x)|$

We will explain soon what the Bottleneck distance is, but first let us perturb the bitmap we get & see if the stability theorem can be observed in practice.

Cubical complexes can also be used to
approximate values of function. (7)

In our 3rd numerical experiment let us see
how one can infer topology of a point cloud
(in low dimensional space) by using Kernel Density
Estimator. For that let us:

- ① Sample a collection of points from our favorite set (in my case, I will be boring & will sample from a unit circle). (KDE)
- ② Compute a Kernel Density Estimator of those points (for more information, consult statistic courses - in general this technique allows for to obtain a possible density function from which the possible distribution)
input collection of points is sampled.
- ③ Approximate KDE on a fixed size grid.

(8)

Comment 1

This approximation is not rigorous i.e. we do not know how far away (in, say, L^p or L^∞ norm) the function is from its partially constant approximation.

But - we can make it rigorous using rigorous arithmetic, for instance interval arithmetic.

[Dobts, Wanner, Rigorous cubical approximation and persistent homology of continuous functions]

Comment 2

The number of cubes in a cubical complex meshing a square $\underbrace{m \times m \times \dots \times m}_k$ grows exponentially with k .

It is therefore no possible to use these techniques in higher dimensions.

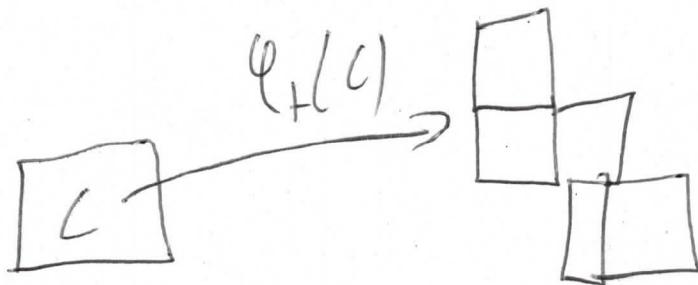
Bonus Section

Topology met Dynamics



Using rigorous arithmetic, like interval arithmetic, it is possible to approximate dynamics.

To be precise, we know where the point, after time T , may be mapped:



More precisely, given a space X and a function

$$\bar{\Phi} : \mathbb{R} \times X \rightarrow X$$

↑ continuous dynamical system

We require that:

① $\bar{\Phi}(0, x) = x$ ← we do not move in zero time

② $\bar{\Phi}(t_2, \bar{\Phi}(t_1, x)) = \bar{\Phi}(t_1 + t_2, x)$ ie

$\bar{\Phi}(t_1, x)$
 $\bar{\Phi}(t_2, \bar{\Phi}(t_1, x))$
 $\bar{\Phi}(t_1 + t_2, x)$

Using a computational technique called **Rigorous Arithmetic**, having interval arithmetic as the most popular, we can estimate (over estimate) where an image of a cube is. In some cases however that allows to detect invariant sets of dynamics.

A set $M \subseteq X$ is **invariant with respect to Φ** if $\Phi(t, M) \subseteq X$ for every t (we can speak about forward/backward invariant set, but will skip it here).

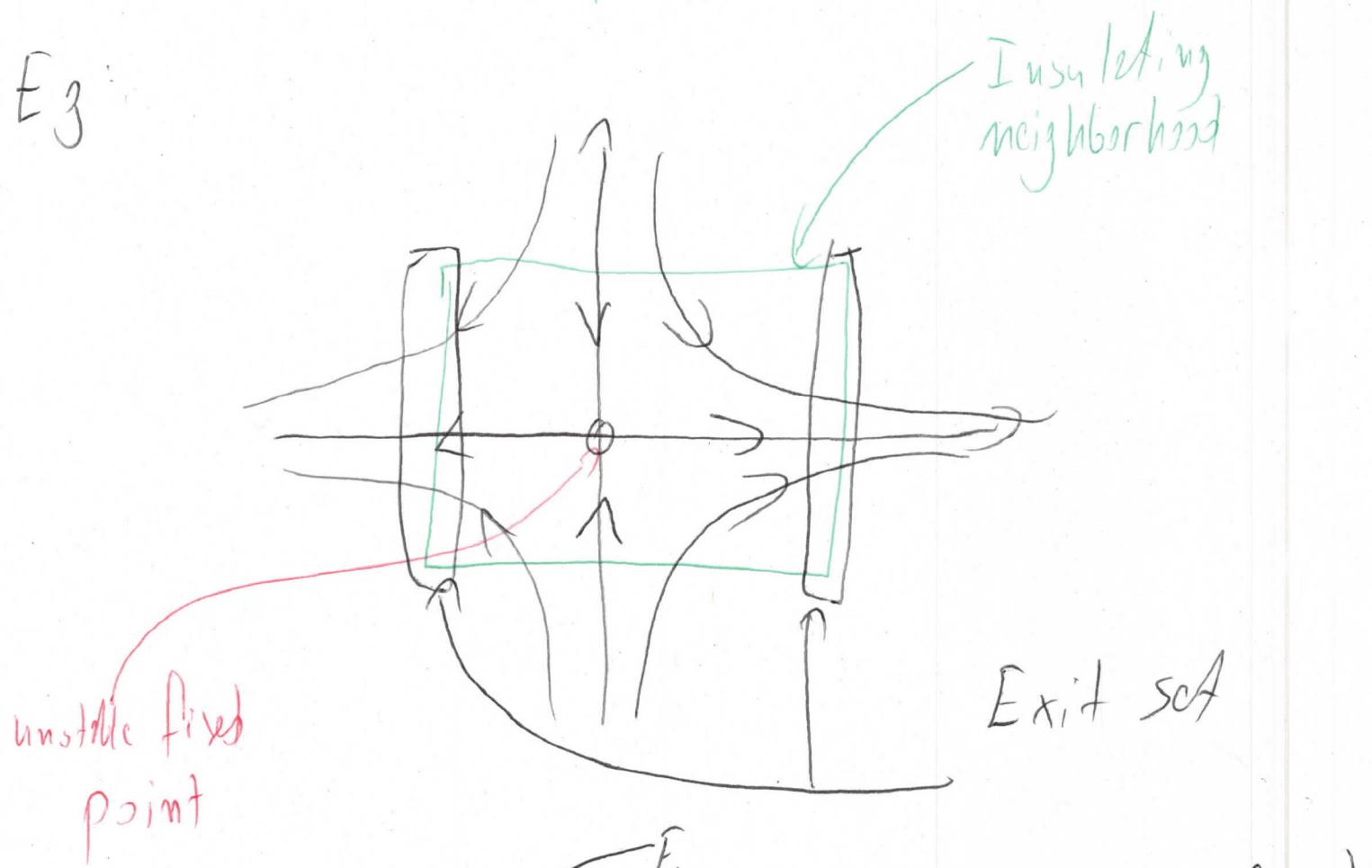
Examples of invariant sets: fixed points, periodic orbits, ...

Suppose we find a set I such that for every $x \in \partial I$ the trajectory at x either enters I , or exits I . Such a set is called **insulating neighborhood**.

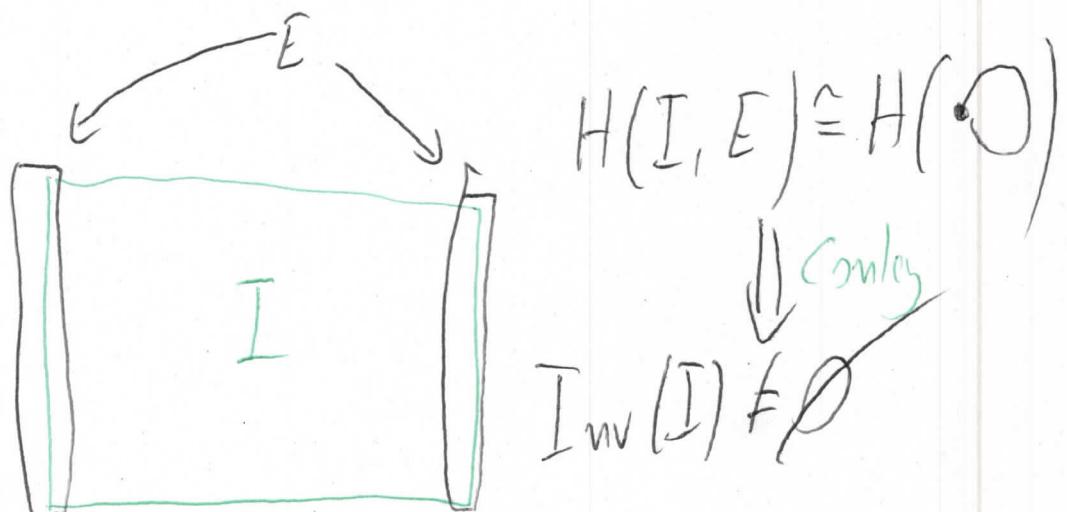
Let $E = \{x \in \partial I \mid \text{trajectory of } x \text{ leaves } I\}$
↑ this is an exit set.

Then the celebrated result of homological
 Conley Index states that if
 $H_*(I, E)$ is nontrivial, then $\text{Inv}(I) \neq \emptyset$
 meaning that there is something
 invariant in I . It can be fixed
 point, periodic orbit, ...

Eg:



Therefore



It is a very nice example how topology
and dynamics go pair-to-pair (or, should
I write homoty-to-homoty?)

(12)

Topology help dynamics to find invariant sets.
Soon we will see that dynamics help topology
to find, for instance and among others, Betti
numbers.